

Description

The ZXLD1350Q is a hysteretic mode inductive step-down converter with integrated switch and high side current sense.

It operates from an input supply from 7V to 30V driving single or multiple series connected LEDs efficiently external adjustable output current up to 350mA.

The output current can be adjusted by applying a DC voltage or a PWM waveform. 100:1 adjustment of output current is possible using PWM control. Applying a voltage of 0.2V or lower to the ADJ pin turns the output off and switches the device into a low current standby state.

The ZXLD1350Q has been qualified to AEC-Q100 grade 2 and is Automotive Compliant supporting PPAPs.

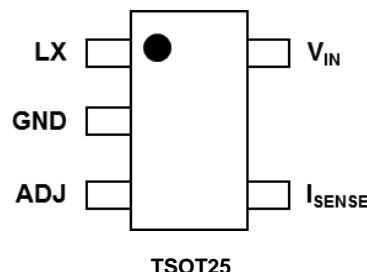
Features

- Simple Low Parts Count
- Internal 30V NDMOS Switch
- Internal PWM Filter
- High Efficiency (Up to 95%)
- Wide Input Voltage Range: 7V to 30V
- 40V Transient Capability
- Up to 1MHz Switching Frequency
- Typical 4% Output Current Accuracy
- Green Molding (No Br, Sb) in TSOT25
- **Totally Lead-Free & Fully RoHS Compliant (Notes 1 & 2)**
- **Halogen and Antimony Free. "Green" Device (Note 3)**
- Automotive Compliant
- **Qualified to AEC-Q100 Standards for High Reliability**
- **PPAP Capable (Note 4)**

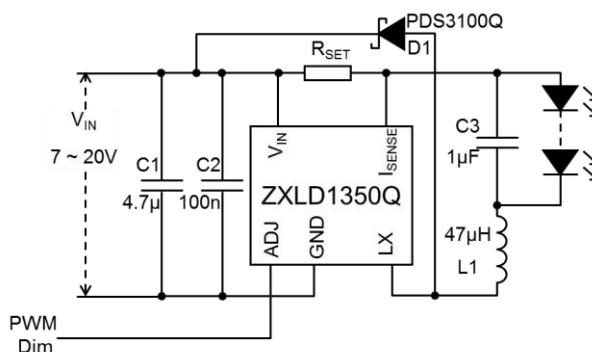
Notes: 1. No purposely added lead. Fully EU Directive 2002/95/EC (RoHS) & 2011/65/EU (RoHS 2) compliant.
 2. See http://www.diodes.com/quality/lead_free.html for more information about Diodes Incorporated's definitions of Halogen- and Antimony-free, "Green" and Lead-free.
 3. Halogen- and Antimony-free "Green" products are defined as those which contain <900ppm bromine, <900ppm chlorine (<1500ppm total Br + Cl) and <1000ppm antimony compounds.
 4. Automotive products are AEC-Q100 qualified and are PPAP capable. Refer to <https://www.diodes.com/quality/product-compliance-definitions/>.

Pin Assignments

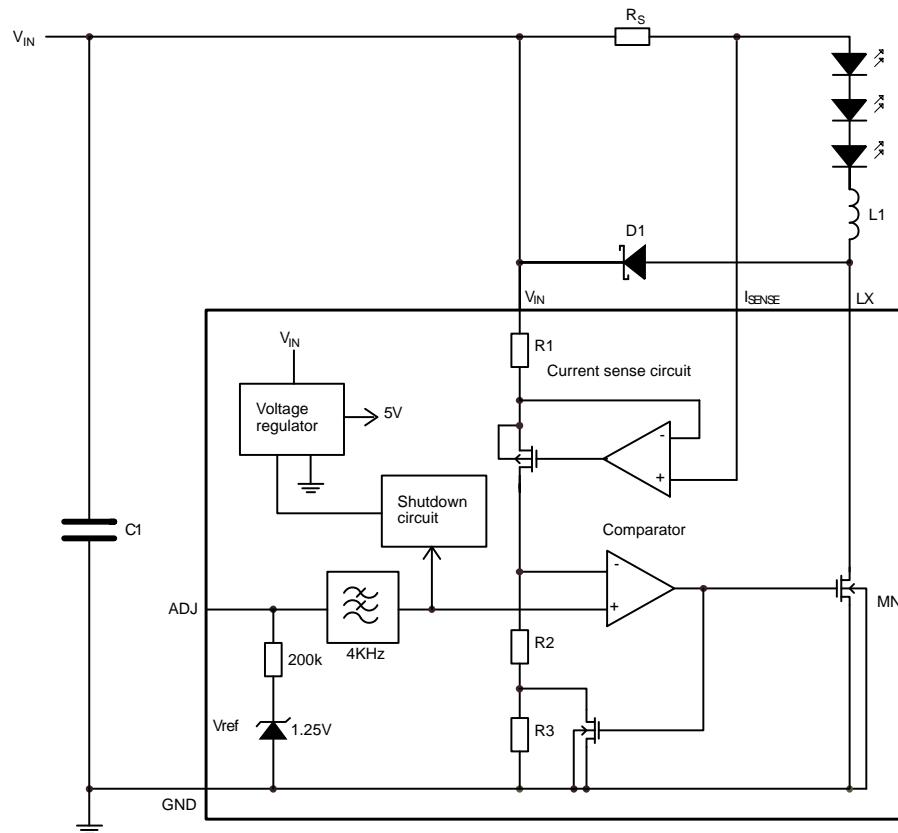
(Top View)



Typical Application Circuit



Block Diagram



Block Diagram – Pin Connection

Pin Description

Pin Number	Pin Name	Description
1	LX	Drain of NDMOS switch
2	GND	Ground (0V)
3	ADJ	Multi-function On/Off and brightness control pin: <ul style="list-style-type: none"> Leave floating for normal operation <ul style="list-style-type: none"> $V_{ADJ} = V_{REF} = 1.25V \rightarrow$ giving nominal average output current $\rightarrow I_{OUTnom} = 0.1/R_S$ Drive to voltage below 0.2V to turn off output current. Drive with Analog voltage: <ul style="list-style-type: none"> $0.3V < V_{ADJ} < 2.5V \rightarrow$ adjusts output current from 25% to 200%^(†) of I_{OUTnom} Drive with PWM signal from open-collector or open-drain transistor, to adjust output current. <ul style="list-style-type: none"> Adjustment range 25% to 100% of I_{OUTnom} for $f > 10kHz$ and 1% to 100% of I_{OUTnom} for $f < 500Hz$ Connect a capacitor from this pin to ground to increase soft-start time. (Default soft-start time = 0.5ms. <ul style="list-style-type: none"> Additional soft-start time is approx.0.5ms/nF)
4	I_SENSE	Connect resistor R_S from this pin to V_{IN} to define nominal average output current $I_{OUTnom} = 0.1/R_S$ (Note: $R_{SMIN} = 0.27\Omega$ with ADJ pin open circuit)
5	V _{IN}	Input voltage (7V to 30V). Decouple to ground with 1 μ F of higher X7R ceramic capacitor close to device

Absolute Maximum Ratings (Voltages to GND Unless Otherwise Stated)

Symbol	Parameter	Rating	Unit
V_{IN}	Input Voltage	-0.3 to +30 (40V for 0.5 sec)	V
V_{SENSE}	I_{SENSE} Voltage	+0.3 to -5 (measured with respect to V_{IN})	V
V_{LX}	LX Output Voltage	-0.3 to +30 (40V for 0.5 sec)	V
V_{ADJ}	Adjust Pin Input Voltage	-0.3 to +6	V
I_{LX}	Switch Output Current	500	mA
P_{TOT}	Power Dissipation (Refer to Package Thermal De-rating Curve on Page 17)	450	mW
T_{ST}	Storage Temperature	-55 to +150	°C
$T_{J\ MAX}$	Junction Temperature	+150	°C
ESD Susceptibility			
HBM	Human Body Model	500	V
CDM	Charged Device Model	1000	V
MM	Machine Model	75	V

Caution: Stresses greater than the 'Absolute Maximum Ratings' specified above, may cause permanent damage to the device. These are stress ratings only; functional operation of the device at conditions between maximum recommended operating conditions and absolute maximum ratings is not implied. Device reliability may be affected by exposure to absolute maximum rating conditions for extended periods of time.

(Semiconductor devices are ESD sensitive and may be damaged by exposure to ESD events. Suitable ESD precautions should be taken when handling and transporting these devices.)

Thermal Resistance

Symbol	Parameter	Rating	Unit
θ_{JA}	Junction to Ambient	200	°C/W

Recommended Operating Conditions

Symbol	Parameter	Min	Typ.	Max	Units
V_{IN}	Input Voltage	7	—	30	V
t_{OFFMIN}	Minimum Switch Off-time	—	—	800	ns
t_{ONMIN}	Minimum Switch On-time	—	—	800	ns
D_{LX}	Duty Cycle Range	0.01	—	0.99	—
T_A	Ambient Operating Temperature Range	-40	—	+105	°C
$I_{LX\ CONT}$	Average/RMS LX Switch Current	—	—	0.37	A
$f_{Lx\ max}$	Recommended Maximum Operating Frequency	—	—	1	MHz
t_{PD}	Internal Comparator Propagation Delay	—	50	—	ns

Electrical Characteristics

(Test conditions: $V_{IN} = 12V$, $T_{amb} = +25^{\circ}C$, unless otherwise specified.)

Symbol	Parameter	Condition	Min.	Typ.	Max.	Unit
V_{SU}	Internal Regulator Start-up Threshold	V_{IN} rising	—	4.8	—	V
I_{INQoff}	Quiescent Supply Current with Output Off	ADJ pin grounded	—	15	20	μA
I_{INQon}	Quiescent Supply Current with Output Switching	ADJ pin floating, $f = 250kHz$	—	250	500	μA
V_{SENSE}	Mean Current Sense Threshold Voltage (Defines LED Current Setting Accuracy)	Measured on I_{SENSE} pin with respect to V_{IN} $V_{ADJ} = 1.25V$	95	100	105	mV
$V_{SENSEHYS}$	Sense Threshold Hysteresis	—	—	± 15	—	%
I_{SENSE}	I_{SENSE} Pin Input Current	$V_{SENSE} = V_{IN} - 0.1$	—	1.25	10	μA
V_{REF}	Internal Reference Voltage	Measured on ADJ pin with pin floating	1.21	1.25	1.29	V
$\Delta V_{REF}/\Delta T$	Temperature Coefficient of V_{REF}	—	—	50	—	ppm/ $^{\circ}C$
V_{ADJ}	External Control Voltage Range on ADJ Pin for DC Brightness Control (Note 5)	—	0.3	—	2.5	V
V_{ADJoff}	DC Voltage on ADJ Pin to Switch Device from Active (On) State to Quiescent (Off) State	V_{ADJ} falling	0.15	0.2	0.25	V
V_{ADJon}	DC Voltage on ADJ Pin to Switch Device from Quiescent (Off) State to Active (On) State	V_{ADJ} rising	0.2	0.25	0.3	V
R_{ADJ}	Resistance between ADJ Pin and V_{REF}	—	135	—	250	$k\Omega$
I_{Lxmean}	Continuous LX Switch Current	—	—	—	0.37	A
R_{LX}	LX Switch 'On' Resistance	—	—	1.5	2	Ω
$I_{LX(leak)}$	LX Switch Leakage Current	—	—	—	1	μA
$D_{PWM(LF)}$	Duty Cycle Range of PWM Signal Applied to ADJ Pin during Low Frequency PWM Dimming Mode	PWM frequency <500Hz PWM amplitude = V_{REF} Measured on ADJ pin	0.01	—	1	—
	Brightness Control Range		—	100:1	—	—
$D_{PWM(HF)}$	Duty Cycle Range of PWM Signal Applied to ADJ Pin during High Frequency PWM Dimming Mode	PWM frequency <10kHz PWM amplitude = V_{REF} Measured on ADJ pin	0.16	—	1	—
	Brightness Control Range		—	5:1	—	—
f_{LX}	Operating Frequency (See Graphs for More Details)	ADJ pin floating $L = 100H$ (0.82V) $I_{OUT} = 350mA$ @ $V_{LED} = 3.4V$ Driving 1 LED	—	250	—	kHz
t_{ss}	Start Up Time (See Graphs for More Details)	Time taken for output current to reach 90% of final value after voltage on ADJ pin has risen above 0.3V.	—	500	—	μs

Note: 5. 100% brightness corresponds to $V_{ADJ} = V_{ADJ(nom)} = V_{REF}$. Driving the ADJ pin above V_{REF} will increase the V_{SENSE} threshold and output current proportionally.

Device Description

The device, in conjunction with the coil (L1) and current sense resistor (R_S), forms a self-oscillating continuous-mode buck converter.

Device Operation (Refer to block diagram and Figure 1 - Operating waveforms)

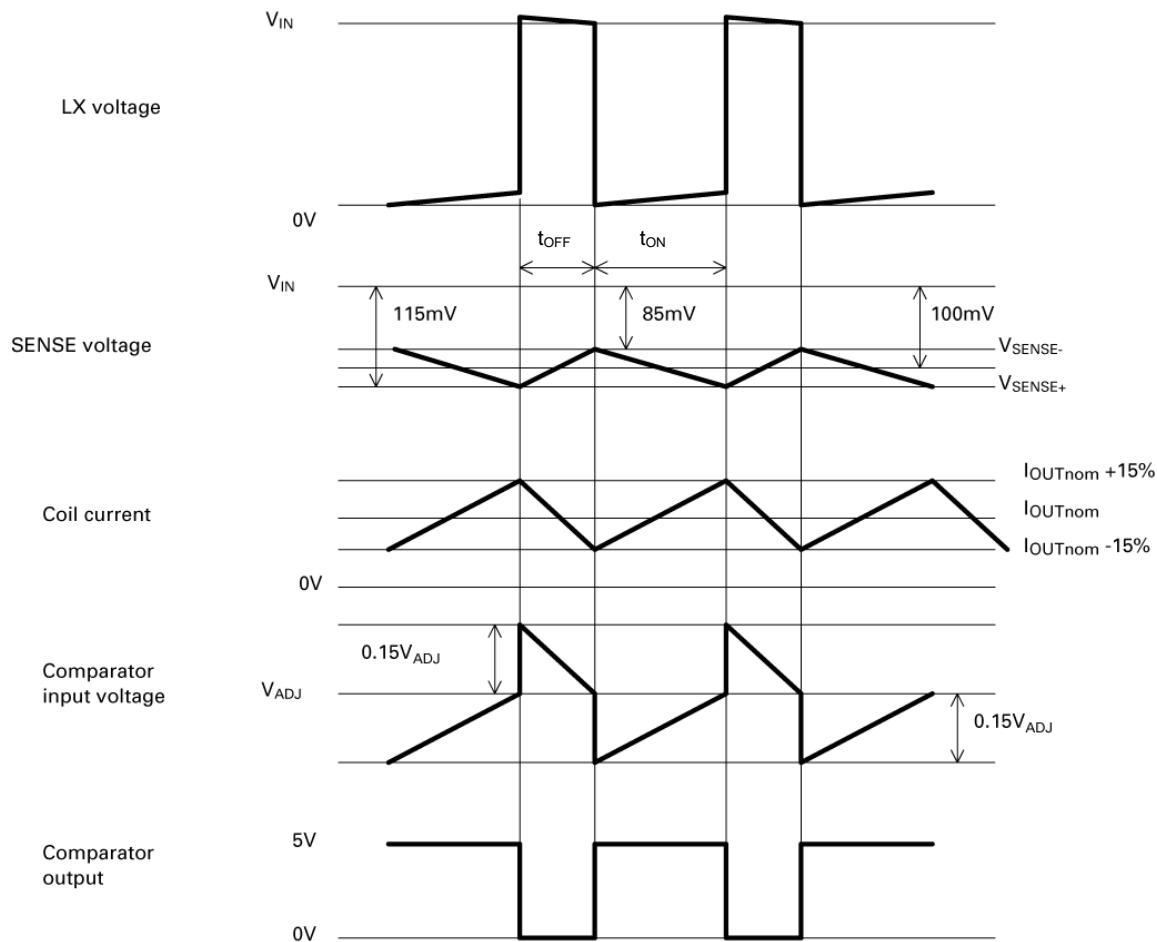


Figure 1. Theoretical Operating Waveforms

Operation can be best understood by assuming that the ADJ pin of the device is unconnected and the voltage on this pin (V_{ADJ}) appears directly at the (+) input of the comparator.

When input voltage V_{IN} is first applied, the initial current in L1 and R_S is zero and there is no output from the current sense circuit. Under this condition, the (-) input to the comparator is at ground and its output is high. This turns MN on and switches the LX pin low, causing current to flow from V_{IN} to ground, via R_S, L1 and the LED(s). The current rises at a rate determined by V_{IN} and L1 to produce a voltage ramp (V_{SENSE}) across R_S. The supply referred voltage V_{SENSE} is forced across internal resistor R1 by the current sense circuit and produces a proportional current in internal resistors R2 and R3. This produces a ground referred rising voltage at the (-) input of the comparator. When this reaches the threshold voltage (V_{ADJ}), the comparator output switches low and MN turns off. The comparator output also drives another NMOS switch, which bypasses internal resistor R3 to provide a controlled amount of hysteresis. The hysteresis is set by R3 to be nominally 15% of V_{ADJ}.

When MN is off, the current in L1 continues to flow via D1 and the LED(s) back to V_{IN}. The current decays at a rate determined by the LED and diode forward voltages to produce a falling voltage at the input of the comparator. When this voltage returns to V_{ADJ}, the comparator output switches high again. This cycle of events repeats, with the comparator input ramping between limits of V_{ADJ} ± 15%.

Device Description (Cont.)

Switching Thresholds

With $V_{ADJ} = V_{REF}$, the ratios of $R1$, $R2$ and $R3$, define an average V_{SENSE} switching threshold of 100mV (measured on the I_{SENSE} pin with respect to V_{IN}). The average output current I_{OUTnom} is then defined by this voltage and R_S according to:

$$I_{OUTnom} = 100\text{mV}/R_S$$

Nominal ripple current is $\pm 15\text{mV}/R_S$.

Adjusting Output Current

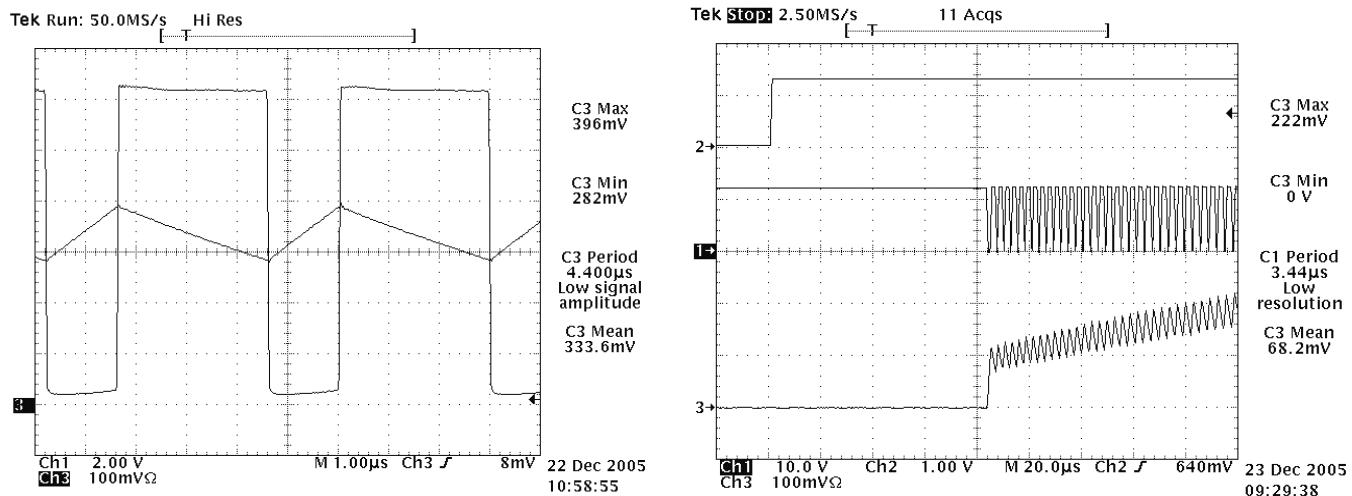
The device contains a low pass filter between the ADJ pin and the threshold comparator and an internal current limiting resistor (200k Ω nom) between ADJ and the internal reference voltage. This allows the ADJ pin to be overdriven with either DC or pulse signals to change the V_{SENSE} switching threshold and adjust the output current. The filter is third order, comprising three sections, each with a cut-off frequency of nominally 4kHz.

Details of the different modes of adjusting output current are given in the applications section.

Output Shutdown

The output of the low pass filter drives the shutdown circuit. When the input voltage to this circuit falls below the threshold (0.2V nom), the internal regulator and the output switch are turned off. The voltage reference remains powered during shutdown to provide the bias current for the shutdown circuit. Quiescent supply current during shutdown is nominally 15mA and switch leakage is below 1mA.

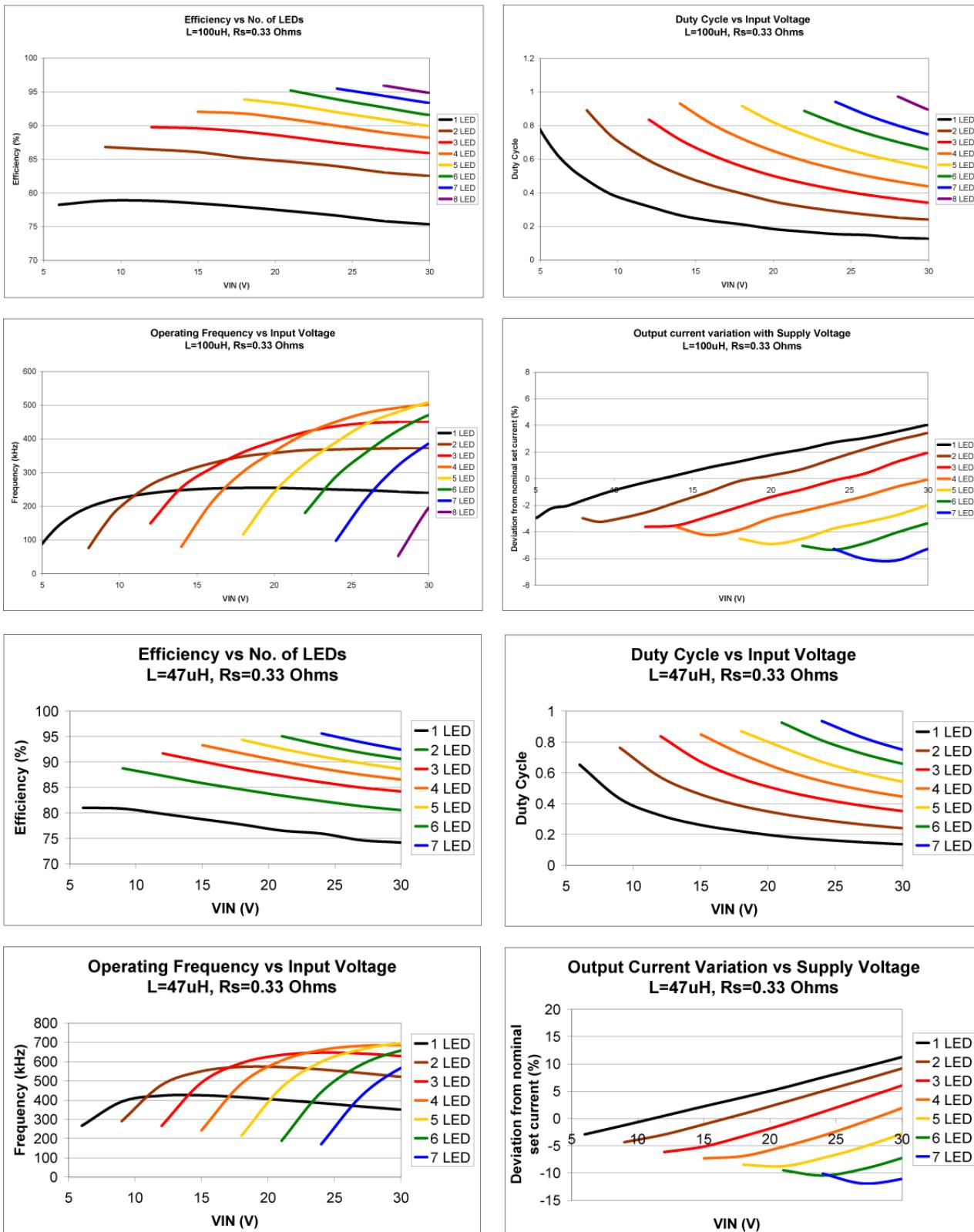
Typical Operating Waveforms [$V_{IN} = 12\text{V}$, $R_S = 0.3\Omega$, $L = 100\mu\text{H}$]



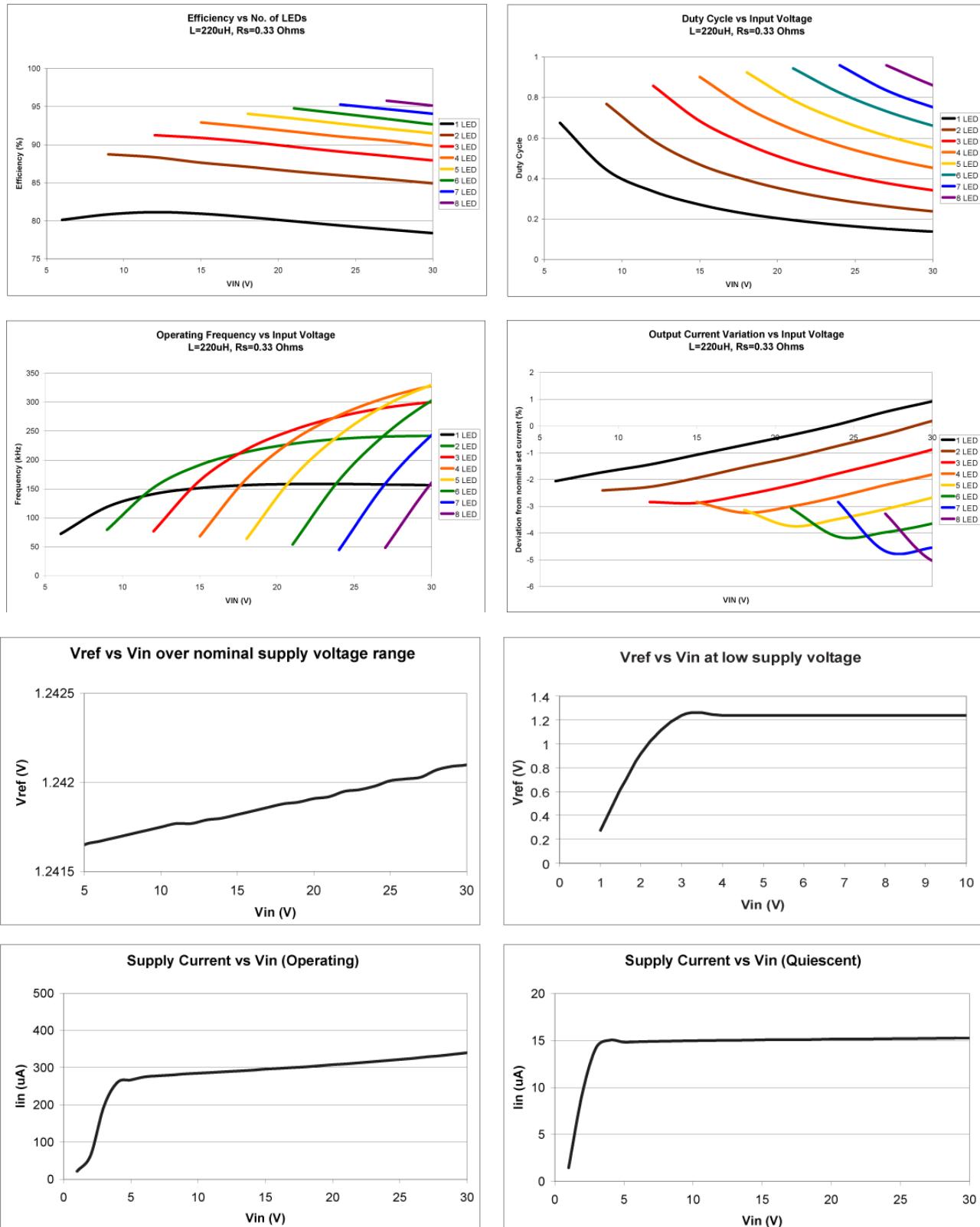
Normal Operation. Output Current (Ch3) and LX Voltage (Ch1)

Start-up Waveforms. Output Current (Ch3), LX Voltage (Ch1) and V_{ADJ} (Ch2)

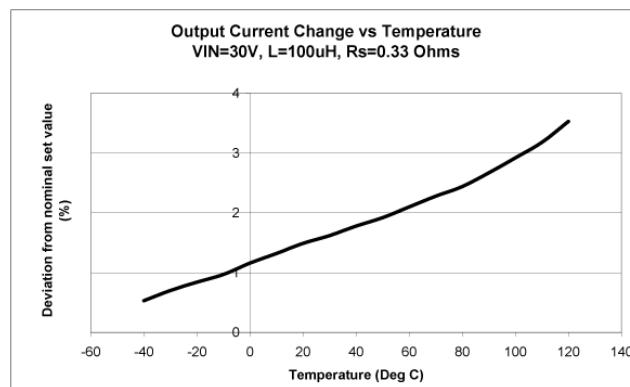
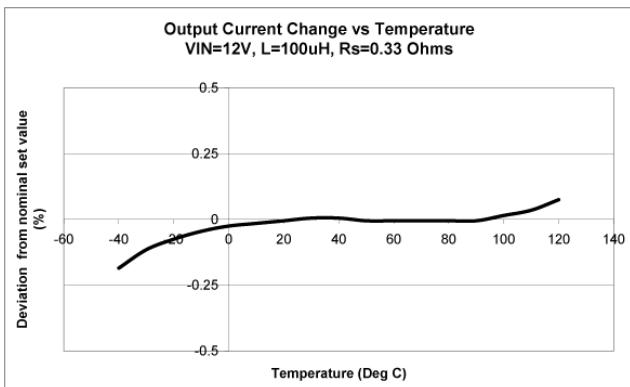
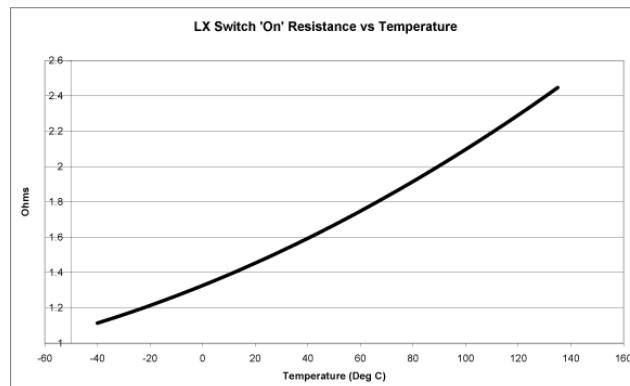
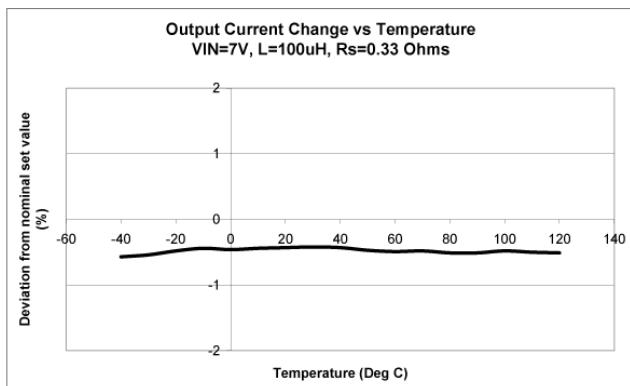
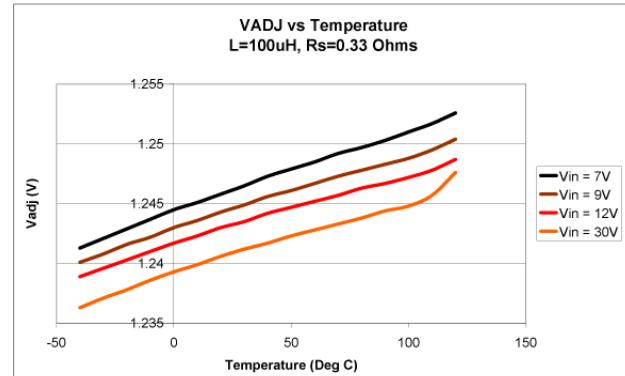
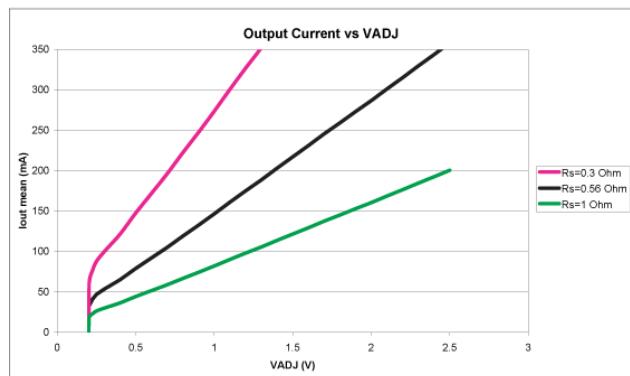
Typical Operating Conditions



Typical Characteristics (Cont.)



Typical Characteristics (Cont.)



Application Information

Setting Nominal Average Output Current with External Resistor R_S

The nominal average output current in the LED(s) is determined by the value of the external current sense resistor (R_S) connected between V_{IN} and I_{SENSE} and is given by:

$$I_{OUTnom} = 0.1/R_S \text{ [for } R_S > 0.27\Omega\text{]}$$

The table below gives values of nominal average output current for several preferred values of current setting resistor (R_S) in the typical application circuit shown on page 1:

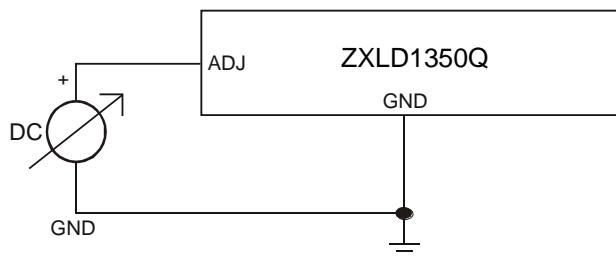
$R_S (\Omega)$	Nominal Average Output Current (mA)
0.27	370
0.30	333
0.33	300
0.39	256

The above values assume that the ADJ pin is floating and at a nominal voltage of V_{REF} (=1.25V). Note that $R_S = 0.27\Omega$ is the minimum allowed value of sense resistor under these conditions to maintain switch current below the specified maximum value.

It is possible to use different values of R_S if the ADJ pin is driven from an external voltage. (See next section).

Output Current Adjustment by External DC Control Voltage

The ADJ pin can be driven by an external dc voltage (V_{ADJ}), as shown, to adjust the output current to a value above or below the nominal average value defined by R_S .



The nominal average output current in this case is given by:

$$I_{OUTdc} = 0.08*V_{ADJ}/R_S \quad \text{for } 0.3 < V_{ADJ} < 2.5V$$

Note that 100% brightness setting corresponds to $V_{ADJ} = V_{REF}$. When driving the ADJ pin above 1.25V, R_S must be increased in proportion to prevent I_{OUTdc} exceeding 370mA maximum.

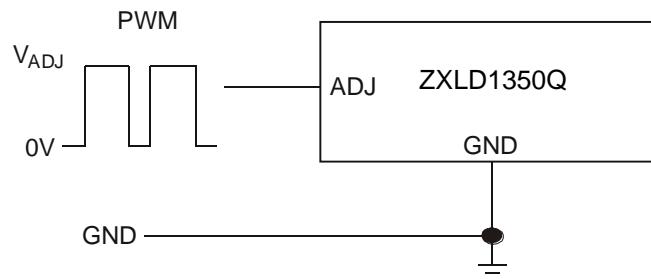
The input impedance of the ADJ pin is $200k\Omega \pm 25\%$.

Application Information (Cont.)

Output Current Adjustment by PWM Control

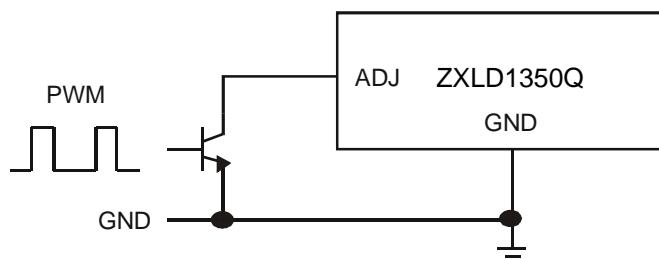
Directly Driving ADJ Input

A Pulse Width Modulated (PWM) signal with duty cycle D_{PWM} can be applied to the ADJ pin, as shown below, to adjust the output current to a value above or below the nominal average value set by resistor R_S :



Driving the ADJ Input via Open Collector Transistor

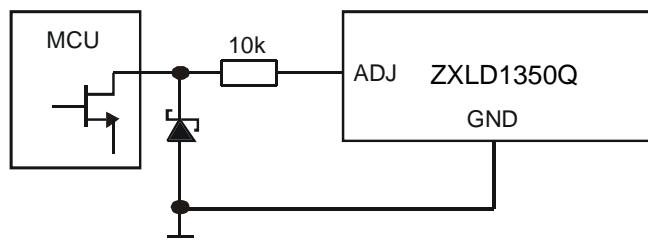
The recommended method of driving the ADJ pin and controlling the amplitude of the PWM waveform is to use a small NPN switching transistor as shown below:



This scheme uses the $200\text{k}\Omega$ resistor between the ADJ pin and the internal voltage reference as a pull-up resistor for the external transistor.

Driving the ADJ Input from a Microcontroller

Another possibility is to drive the device from the open drain output of a microcontroller. The diagram below shows one method of doing this:



The diode and resistor suppress possible high amplitude negative spikes on the ADJ input resulting from the drain-source capacitance of the FET. Negative spikes at the input to the device should be avoided as they may cause errors in output current, or erratic device operation.

PWM dimming can be further split into high frequency and low frequency PWM dimming and how the device responds to these.

Application Information (Cont.)

Low Frequency PWM Mode

When the ADJ pin is driven with a low frequency PWM signal (eg 100Hz), with a high level voltage V_{ADJ} and a low level of zero, the output of the internal low pass filter will swing between 0V and V_{ADJ} , causing the input to the shutdown circuit to fall below its turn-off threshold (200mV nom) when the ADJ pin is low. This will cause the output current to be switched on and off at the PWM frequency, resulting in an average output current I_{OUTavg} proportional to the PWM duty cycle. (See Figure 2 - Low frequency PWM operating waveforms).

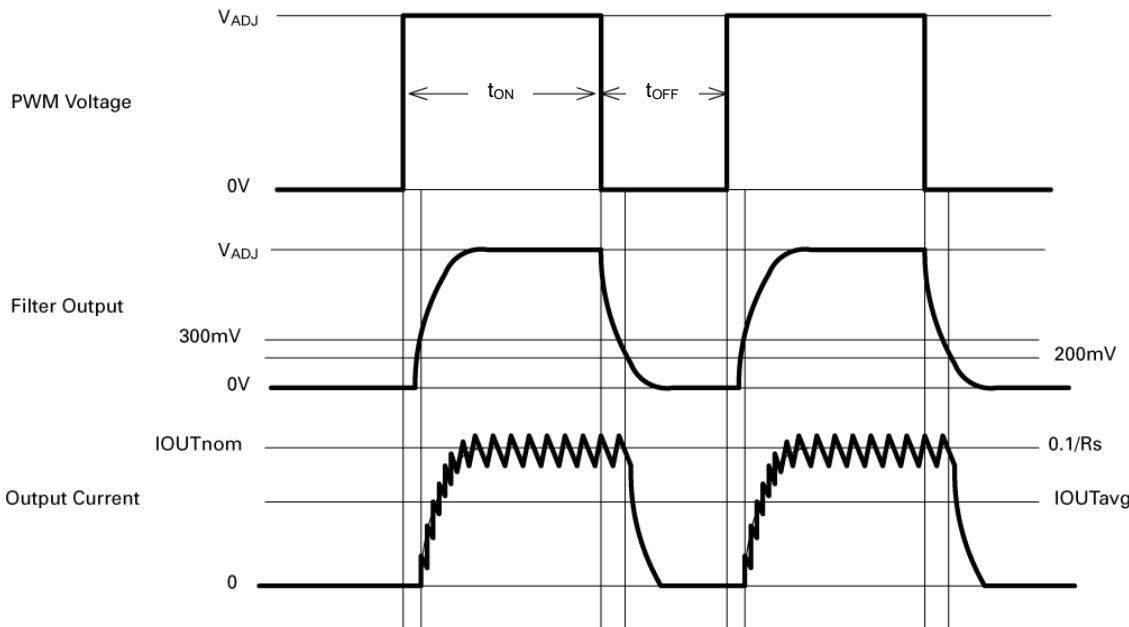


Figure 2. Low Frequency PWM Operating Waveforms

The average value of output current in this mode is given by:

$$I_{OUTavg} = 0.1D_{PWM}/R_S \quad \text{for } D_{PWM} > 0.01$$

This mode is preferable if optimum LED 'whiteness' is required. It will also provide the widest possible dimming range (approx. 100:1) and higher efficiency at the expense of greater output ripple.

Note that the low pass filter introduces a small error in the output duty cycle due to the difference between the start-up and shut-down time. This time difference is a result of the 200mV shutdown threshold and the rise and fall times at the output of the filter. To minimize this error, the PWM duty cycle should be as low as possible consistent with avoiding flicker in the LED.

Application Information (Cont.)

High Frequency PWM Mode

At PWM frequencies above 10kHz and for duty cycles above 0.16, the output of the internal low pass filter will contain a DC component that is always above the shutdown threshold. This will maintain continuous device operation and the nominal average output current will be proportional to the average voltage at the output of the filter, which is directly proportional to the duty cycle. (See Figure 3 – High frequency PWM operating waveforms). For best results, the PWM frequency should be maintained above the minimum specified value of 10kHz, in order to minimize ripple at the output of the filter. The shutdown comparator has approximately 50mV of hysteresis, to minimize erratic switching due to this ripple. An upper PWM frequency limit of approximately one tenth of the operating frequency is recommended, to avoid excessive output modulation and to avoid injecting excessive noise into the internal reference.

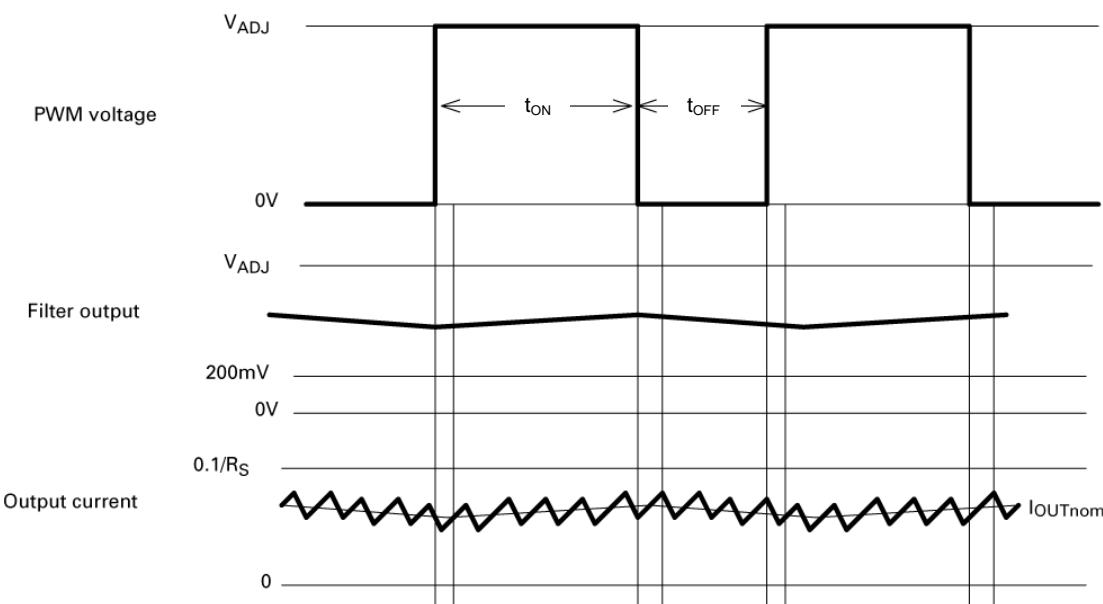


Figure 3. High Frequency PWM Operating Waveforms

The nominal average value of output current in this mode is given by:

$$I_{OUTnom} \approx 0.1D_{PWM}/R_S \text{ for } D_{PWM} > 0.16$$

This mode will give minimum output ripple and reduced radiated emission, but with a reduced dimming range (approx.5:1). The restricted dimming range is a result of the device being turned off when the DC component on the filter output falls below 200mV.

Shutdown Mode

Taking the ADJ pin to a voltage below 0.2V for more than approximately 100 μ s, will turn off the output and supply current will fall to a low standby level of 15 μ A nominal.

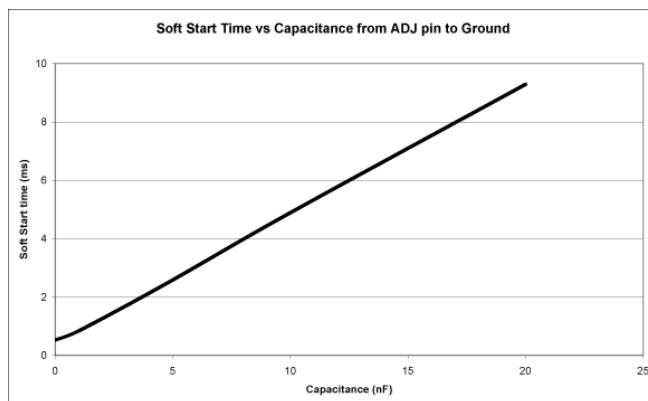
Note that the ADJ pin is not a logic input. Taking the ADJ pin to a voltage above V_{REF} will increase output current above the 100% nominal average value. (See graphs for details).

Application Information (Cont.)

Soft-start

The device has inbuilt soft-start action due to the delay through the PWM filter. An external capacitor from the ADJ pin to ground will provide additional soft-start delay, by increasing the time taken for the voltage on this pin to rise to the turn-on threshold and by slowing down the rate of rise of the control voltage at the input of the comparator. With no external capacitor, the time taken for the output to reach 90% of its final value is approximately 500 μ s. Adding capacitance increases this delay by approximately 0.5ms/nF.

The graph below shows the variation of soft-start time for different values of capacitor.



Inherent Open-circuit LED Protection

If the connection to the LED(s) is open-circuited, the coil is isolated from the LX pin of the chip, so the device will not be damaged, unlike in many boost converters, where the back EMF may damage the internal switch by forcing the drain above its breakdown voltage.

Capacitor Selection

A low ESR capacitor should be used for input decoupling, as the ESR of this capacitor appears in series with the supply source impedance and lowers overall efficiency. This capacitor has to supply the relatively high peak current to the coil and smooth the current ripple on the input supply. A minimum value of 1 μ F is acceptable if the input source is close to the device, but higher values will improve performance at lower input voltages, especially when the source impedance is high. The input capacitor should be placed as close as possible to the IC.

For maximum stability over temperature and voltage, capacitors with X7R, X5R, or better dielectric are recommended. Capacitors with Y5V dielectric are not suitable for decoupling in this application and should NOT be used.

A table of recommended manufacturers is provided below:

Manufacturer	Website
Murata	www.murata.com
Taiyo Yuden	www.t-yuden.com
Kemet	www.kemet.com
AVX	www.avxcorp.com

Inductor Selection

Recommended inductor values for the ZXLD1350Q are in the range 47 μ H to 220 μ H.

Higher values of inductance are recommended at higher supply voltages in order to minimize errors due to switching delays, which result in increased ripple and lower efficiency. Higher values of inductance also result in a smaller change in output current over the supply voltage range. (See graphs). The inductor should be mounted as close to the device as possible with low resistance connections to the LX and V_{IN} pins.

The chosen coil should have a saturation current higher than the peak output current and a continuous current rating above the required mean output current.

Application Information (Cont.)

Suitable coils for use with the ZXLD1350Q are listed in the table below:

Part Number	L (μH)	DCR (V)	I _{SAT} (A)	Manufacturer
DO1608C	47	0.64	0.5	CoilCraft
MSS6132ML	47	0.38	0.56	
	68	0.58	0.47	
	100	0.82	0.39	
CD104-MC	220	0.55	0.53	Sumida
NP04SB470M	47	0.27	0.38	Taiyo Yuden

The inductor value should be chosen to maintain operating duty cycle and switch 'on'/off' time within the specified limits over the supply voltage and load current range.

The following equations can be used as a guide, with reference to Figure 1 - Operating waveforms.

LX Switch 'On' Time

$$t_{ON} = \frac{L \Delta I}{V_{IN} - V_{LED} - I_{avg} \times (R_S + r_L + R_{LX})}$$

Note: $t_{ONmin} > 200\text{ns}$

LX Switch 'Off' Time

$$t_{OFF} = \frac{L \Delta I}{V_{LED} + V_D + I_{avg} \times (R_S + r_L)}$$

Note: $t_{OFFmin} > 200\text{ns}$

Where:

L is the coil inductance (H)

r_L is the coil resistance (Ω)

I_{avg} is the required LED current (A)

ΔI is the coil peak-peak ripple current (A) {Internally set to $0.3 \times I_{avg}$ }

V_{IN} is the supply voltage (V)

V_{LED} is the total LED forward voltage (V)

R_{LX} is the switch resistance (Ω)

V_D is the rectifier diode forward voltage at the required load current (V)

Example:

For $V_{IN} = 12\text{V}$, $L = 47\mu\text{H}$, $r_L = 0.64\Omega$, $V_{LED} = 3.4\text{V}$, $I_{avg} = 350\text{mA}$ and $V_D = 0.36\text{V}$

$$t_{ON} = (47 \times 10^{-6} \times 0.105) / (12 - 3.4 - 0.672) = 0.622\mu\text{s}$$

$$t_{OFF} = (47 \times 10^{-6} \times 0.105) / (3.4 + 0.36 + 0.322) = 1.21\mu\text{s}$$

This gives an operating frequency of 546kHz and a duty cycle of 0.34.

These and other equations are available as a spreadsheet calculator from the Diodes website.

Note that in practice, the duty cycle and operating frequency will deviate from the calculated values due to dynamic switching delays, switch rise/fall times and losses in the external components.

Optimum performance will be achieved by setting the duty cycle close to 0.5 at the nominal supply voltage. This helps to equalize the undershoot and overshoot and improves temperature stability of the output current.

Application Information (Cont.)

Diode Selection

For maximum efficiency and performance, the rectifier (D1) should be a fast low capacitance Schottky diode with low reverse leakage at the maximum operating voltage and temperature. The recommended diode for use with this part is the DFSL140Q. This has approximately ten times lower leakage than standard Schottky diodes, which are unsuitable for use above +85°C. It also provides better efficiency than silicon diodes, due to a combination of lower forward voltage and reduced recovery time.

The table below gives the typical characteristics for the DFSL140Q:

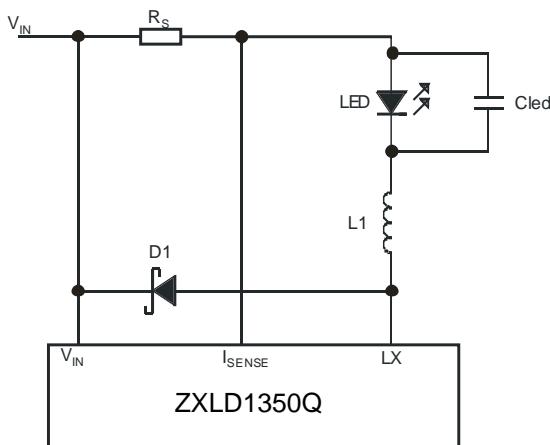
Diode	Forward Voltage @ 300mA (mV)	Continuous Current (mA)	Reverse Leakage @ 30V +85°C (µA)	Package
DFSL140Q	410	1000	100	PowerDI®123

If alternative diodes are used, it is important to select parts with a peak current rating above the peak coil current and a continuous current rating higher than the maximum output load current. It is very important to consider the reverse leakage of the diode when operating above +85°C. Excess leakage will increase the power dissipation in the device.

The higher forward voltage and overshoot due to reverse recovery time in silicon diodes will increase the peak voltage on the LX output. If a silicon diode is used, care should be taken to ensure that the total voltage appearing on the LX pin including supply ripple, does not exceed the specified maximum value.

Reducing Output Ripple

Peak to peak ripple current in the LED(s) can be reduced, if required, by shunting a capacitor Cled across the LED(s) as shown below:



A value of 1µF will reduce nominal ripple current by a factor three (approx.). Proportionally lower ripple can be achieved with higher capacitor values. Note that the capacitor will not affect operating frequency or efficiency, but it will increase start-up delay, by reducing the rate of rise of LED voltage.

Operation at low supply voltage

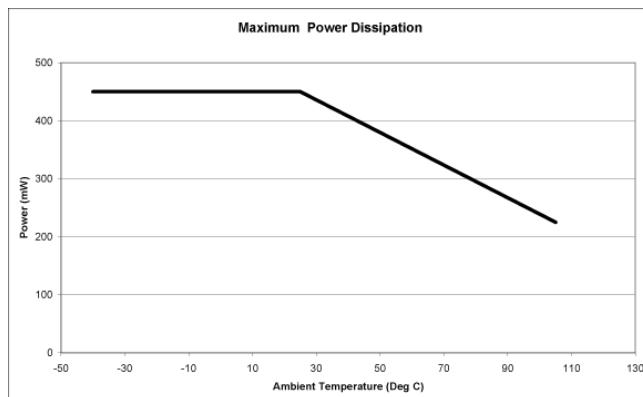
The internal regulator disables the drive to the switch until the supply has risen above the start-up threshold (VSU). Above this threshold, the device will start to operate. However, with the supply voltage below the specified minimum value, the switch duty cycle will be high and the device power dissipation will be at a maximum. Care should be taken to avoid operating the device under such conditions in the application, in order to minimize the risk of exceeding the maximum allowed die temperature. (See next section on thermal considerations).

Note that when driving loads of two or more LEDs, the forward drop will normally be sufficient to prevent the device from switching below approximately 6V. This will minimize the risk of damage to the device.

Application Information (Cont.)

Thermal Considerations

When operating the device at high ambient temperatures, or when driving maximum load current, care must be taken to avoid exceeding the package power dissipation limits. The graph below gives details for power derating. This assumes the device to be mounted on a $(25\text{mm})^2$ PCB with 1oz copper standing in still air.



Note that the device power dissipation will most often be a maximum at minimum supply voltage. It will also increase if the efficiency of the circuit is low. This may result from the use of unsuitable coils, or excessive parasitic output capacitance on the switch output.

Thermal Compensation of Output Current

High luminance LEDs often need to be supplied with a temperature compensated current in order to maintain stable and reliable operation at all drive levels. The LEDs are usually mounted remotely from the device, so for this reason, the temperature coefficients of the internal circuits for the ZXLD1350Q have been optimized to minimize the change in output current when no compensation is employed. If output current compensation is required, it is possible to use an external temperature sensing network - normally using Negative Temperature Coefficient (NTC) thermistors and/or diodes, mounted very close to the LED(s). The output of the sensing network can be used to drive the ADJ pin in order to reduce output current with increasing temperature.

Layout Considerations

LX Pin

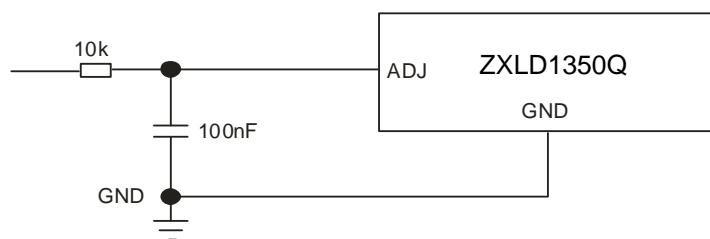
The LX pin of the device is a fast switching node, so PCB tracks should be kept as short as possible. To minimize ground 'bounce', the ground pin of the device should be soldered directly to the ground plane.

Coil and Decoupling Capacitors

It is particularly important to mount the coil and the input decoupling capacitor close to the device to minimize parasitic resistance and inductance, which will degrade efficiency. It is also important to take account of any track resistance in series with current sense resistor R_S .

ADJ Pin

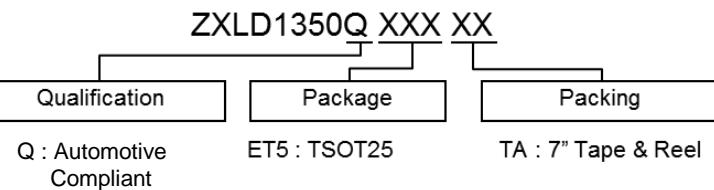
The ADJ pin is a high impedance input, so when left floating, PCB tracks to this pin should be as short as possible to reduce noise pickup. A 100nF capacitor from the ADJ pin to ground will reduce frequency modulation of the output under these conditions. An additional series 10k Ω resistor can also be used when driving the ADJ pin from an external circuit (see below). This resistor will provide filtering for low frequency noise and provide protection against high voltage transients.



High Voltage Tracks

Avoid running any high voltage tracks close to the ADJ pin, to reduce the risk of leakage due to board contamination. Any such leakage may raise the ADJ pin voltage and cause excessive output current. A ground ring placed around the ADJ pin will minimize changes in output current under these conditions.

Ordering Information

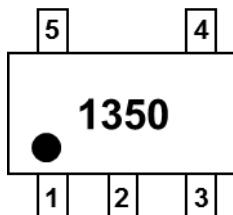


Device	Package Code	Package (Note 6)	Part Mark	Packing: 7" Tape and Reel			Qualification Grade (Note 7)
				Quantity Per Reel	Tape Width	Part Number Suffix	
ZXLD1350QET5TA	ET5	TSOT25	1350	3000	8mm	TA	Automotive Compliant

Note: 6. Pad layout as shown in Diodes Incorporated's package outline PDFs, which can be found on our website at <http://www.diodes.com/package-outlines.html>.
 7. ZXLD1350Q has been qualified to AEC-Q100 grade 2 and is classified as "Automotive Compliant" supporting PPAP documentation.
 See ZXLD1350 datasheet for commercial qualified versions.

Marking Information

TSOT25

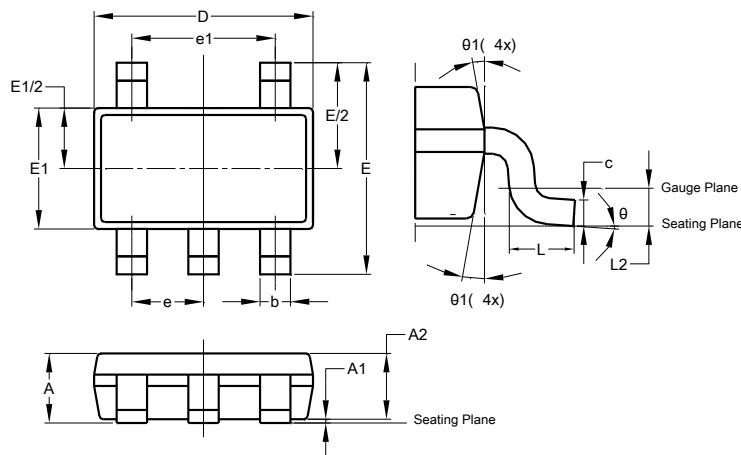


XXXX : Identification Code : 1350

Package Outline Dimensions

Please see <http://www.diodes.com/package-outlines.html> for the latest version.

TSOT25



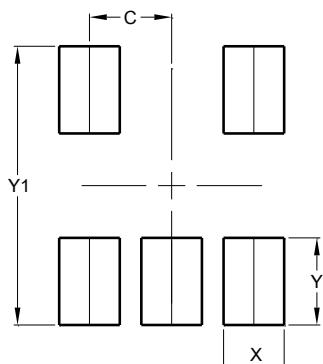
TSOT25			
Dim	Min	Max	Typ
A	-	1.00	-
A1	0.01	0.10	-
A2	0.84	0.90	-
b	0.30	0.45	-
c	0.12	0.20	-
D	-	-	2.90
E	-	-	2.80
E1	-	-	1.60
e	0.95 BSC		
e1	1.90 BSC		
L	0.30	0.50	-
L2	0.25 BSC		
θ	0°	8°	4°
θ1	4°	12°	-

All Dimensions in mm

Suggested Pad Layout

Please see <http://www.diodes.com/package-outlines.html> for the latest version.

TSOT25



Dimensions	Value (in mm)
C	0.950
X	0.700
Y	1.000
Y1	3.199

Revision History

Date	Revision	Changes																
December 2014	1-2	<p>Initial release</p>																
January 2017	2-2	<p>Added further clarification of Automotive Compliance and reference to Diodes' definition (Page 1, Note 4 and page 18, Note 7)</p> <p>Corrected device part mark to include pin 1 identifier (Pages 1 and 18)</p> <p>Correction of ESD ratings (Page 3) (Note 8):</p> <table border="1"> <thead> <tr> <th>ESD Rating</th> <th>Incorrect revision 1-2 specification</th> <th>Corrected revision 2-2 specification</th> <th>Unit</th> </tr> </thead> <tbody> <tr> <td>HBM Human Body Model</td> <td>500</td> <td>500</td> <td>V</td> </tr> <tr> <td>MM Machine Model</td> <td>100</td> <td>75</td> <td>V</td> </tr> <tr> <td>CDM Charged Device Model</td> <td>1000</td> <td>1000</td> <td>V</td> </tr> </tbody> </table> <p>Note 8. The actual physical ESD withstand capability is unaltered.</p>	ESD Rating	Incorrect revision 1-2 specification	Corrected revision 2-2 specification	Unit	HBM Human Body Model	500	500	V	MM Machine Model	100	75	V	CDM Charged Device Model	1000	1000	V
ESD Rating	Incorrect revision 1-2 specification	Corrected revision 2-2 specification	Unit															
HBM Human Body Model	500	500	V															
MM Machine Model	100	75	V															
CDM Charged Device Model	1000	1000	V															

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