



Starter kit User Guide

SK-FM3-100PMC-MB9BF516N

Hardware V1.1 / Documentation V1.3

Warranty and Disclaimer

- The use of the deliverables (deliverables shall include, but not limited to, software, application examples, hardware, target boards, evaluation boards, starter kits, schematics, engineering samples of IC's etc.) is subject to the terms and conditions of Spansion LLC and its affiliates ("SPANSION") as set out below and in (i) the terms and conditions of the License Agreement and/or the Sale and Purchase Agreement and/or any other agreement under which deliverables have been delivered, (ii) the technical descriptions and (iii) all accompanying written materials.
- 1. Please note that the deliverables are intended for and must only be used for test applications in an evaluation laboratory environment.
- 2. The software deliverables are provided on an as-is basis without charge and are subject to alterations. It is the user's obligation to fully test the software in its environment and to ensure proper functionality, qualification and compliance with component specifications.
- 3. Regarding hardware deliverables, the following limited warranty shall apply:
 - Except as otherwise provided in the following paragraphs, for a period of one (1) year from date of shipment to customer ("Warranty Period"), SPANSION warrants the hardware deliverables (i) are free of defects in material and workmanship, and (ii) conform to SPANSION applicable data sheet specifications (available at www.spansion.com or upon request).
 - This warranty does not extend beyond the first purchaser of the deliverables. The liability of SPANSION under this warranty is limited, at SPANSION's option, solely to repair the deliverable, to send replacement deliverable, or to make an appropriate credit adjustment or refund in an amount not to exceed the original purchase price actually paid for the deliverable returned to SPANSION. SPANSION'S warranty obligations are conditioned upon the following: (a) SPANSION is promptly notified in writing by customer during the applicable warranty period of any defect or nonconformance in the deliverable, (b) customer obtains authorization from SPANSION to return the defective deliverable, (c) the defective deliverable is returned to SPANSION in accordance with SPANSION'S shipping instructions set forth below, and (d) SPANSION'S examination of such deliverable discloses to its satisfaction that any defect or nonconformance actually existed and was not caused by improper use or operation outside of the data sheet specifications for the deliverable, abuse, negligence, improper installation, accident, loss or damage in transit, or unauthorized repair or alteration by a person other than SPANSION. Customer shall ship such defective deliverable to SPANSION via SPANSION'S carrier, collect. Risk of loss will transfer to SPANSION when the defective deliverable is provided to SPANSION'S carrier. If customer fails to adhere to these warranty returns guidelines, customer shall assume all risk of loss and shall pay for all freight to SPANSION'S specified location. This warranty shall not apply to any deliverables that have been repaired or altered, except those which have been repaired or altered by SPANSION. The aforementioned provisions do not extend the original warranty period of any deliverable that has either been repaired or replaced by Seller.
 - THESE WARRANTIES ARE IN LIEU OF ALL OTHER WARRANTIES, EXPRESSED, IMPLIED OR STATUTORY, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE, NONINFRINGEMENT, AND ANY WARRANTY OTHERWISE ARISING OUT OF ANY PROPOSAL, SPECIFICATION OR SAMPLE. SPANSION NEITHER ASSUMES NOR AUTHORIZES ANY OTHER PERSON TO ASSUME FOR IT ANY OTHER LIABILITIES. THE FOREGOING CONSTITUTES CUSTOMER'S SOLE AND EXCLUSIVE REMEDY FOR THE FURNISHING OF DEFECTIVE OR NONCONFORMING DELIVERABLES.
- 4. The following limitation of liability shall apply for all deliverables
 - EXCEPT FOR DAMAGES FOR BODILY INJURY OR DEATH, SPANSION SHALL NOT BE LIABLE FOR ANY INDIRECT, INCIDENTAL, SPECIAL, RELIANCE, OR CONSEQUENTIAL DAMAGES, RELIANCE DAMAGES, AND/OR PUNITIVE, OR EXEMPLARY DAMAGES, WHETHER ANY SUCH DAMAGES ARE BASED ON CONTRACT, TORT OR ANY OTHER LEGAL THEORY, AND WHETHER OR NOT SPANSION HAS BEEN INFORMED OF THE POSSIBILITY OF SUCH DAMAGES, AND NOTWITHSTANDING ANY FAILURE OF ESSENTIAL PURPOSE OF ANY LIMITED REMEDY.
 - REGARDLESS OF THE BASIS ON WHICH CUSTOMER IS ENTITLED TO CLAIM DAMAGES FROM SPANSION (INCLUDING FUNDAMENTAL BREACH, NEGLIGENCE, MISREPRESENTATION, OR OTHER CONTRACT OR TORT CLAIM), SPANSION ENTIRE LIABILITY IN ANY CALENDAR YEAR, REGARDLESS OF THE NUMBER OF CLAIMS, SHALL NOT EXCEED FIFTY PERCENT (50%) OF THE TOTAL AMOUNT PAID BY CUSTOMER TO SPANSION FOR THE DELIVERABLES SOLD IN SUCH CALENDAR YEAR.
- 5. Should one of the above stipulations be or become invalid and/or unenforceable, the remaining stipulations shall stay in full effect.
- 6. The contents of this document are subject to change by SPANSION without a prior notice, thus contact SPANSION about the latest one.
- This board and its deliverables must only be used for test applications in an evaluation laboratory environment.

- For your convenience this user guide includes external links that simplify installing of drivers, software utilities, and quick jumps to documentation.
- Some PDF viewer do not allow access to external content by links because of security reasons.
- A viewer called “PDF XChange” is provided in the software package of this starter kit. It’s use is free of charge and no additional installation is required.
- Launching “start.bat” opens this user guide in the PDF XChange viewer.
- Please ensure you have copied the complete software package related to this starter kit in order to use and run the links and examples given on the next pages.
- Please contact the [Spancion Support](#) in case of any question.

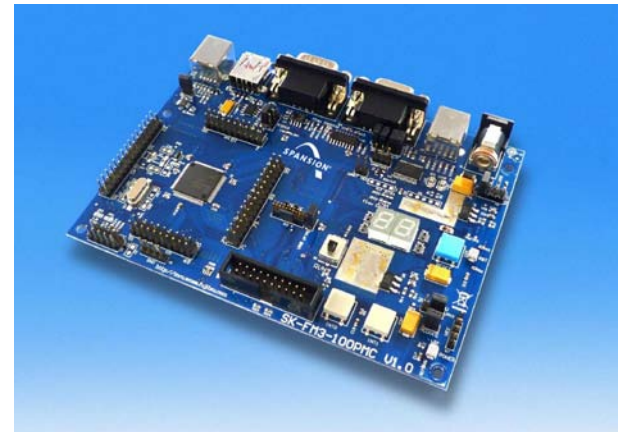
■ Introduction

- [About The SK-FM3-100PMC-MB9BF516N](#)
- [SK-FM3-100PMC-MB9BF516N content](#)
- [SK-FM3-100PMC-9BF516N-JL content](#)
- [Test it](#)
- [The Hardware](#)
- [The Software](#)

■ Try yourself

- [Software examples](#)
- [Program Download](#)
- [IAR-Embedded Workbench](#)
- [KEIL \$\mu\$ Vision](#)
- [Solutions](#)

■ [Workshops](#), [Contacts](#) & [More](#)



■ [Additional documents](#)

- [Schematic](#)
- [Factsheet](#)
- [Data sheet MB9B510R Series](#)
- [Peripheral Manual](#) and [Errata](#)
- [Peripheral Manual \(Timer Part\)](#) and [Errata](#)
- [Peripheral Manual \(Analog Part\)](#) and [Errata](#)
- [Peripheral Manual \(Communication Part\)](#) and [Errata](#)
- [Flash Programming Manual](#) and [Errata](#)

Please visit www.spansion.com to find latest releases of the above mentioned documents.

About the SK-FM3-100PMC-MB9BF516N



- The SK-FM3-100PMC-MB9BF516N is available in two versions:
 - The SK-FM3-100PMC-MB9BF516N includes a low-cost evaluation board based on the SPANSION FM3 microcontroller MB9B510 Series
 - SK-FM3-100PMC-9BF516N-JL includes a low-cost evaluation board based on the SPANSION FM3 microcontroller MB9B510 Series and the JTAG adapter J-Link
- The MB9B510 Series includes the following features:
 - Up to 512 KByte Flash Memory
 - 32 KByte Work Flash
 - Up to 64 KByte RAM
 - Up to 2 CAN controller 2.0A/B
 - Up to 8 LIN-USART-I²C interfaces
 - USB-Host/-Device interface
 - Timers (ICUs, OCUs, PPGs, others)
 - Three 12 Bit ADCs
 - External interrupts

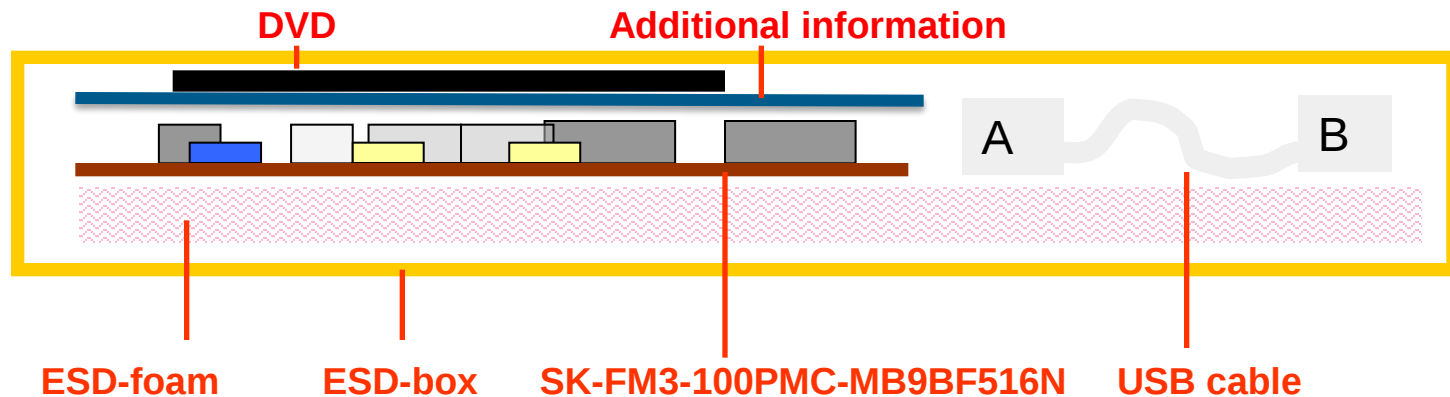
About the SK-FM3-100PMC-MB9BF516N



- Features of the SK-FM3-100PMC-MB9BF516N board:
 - Microcontroller MB9BF516N
 - 1x UART-Transceiver (SUB-D9 connector)
 - 1x USB to serial converter (Type-B connector)
 - 1x High-speed CAN-Transceiver (SUB-D9 connector)
 - 1x USB-MiniHost (Type-A connector)
 - 1x USB-Device (Type-B connector)
 - JTAG- and TRACE-Interface each on a 20 pin-header
 - TSC-Interface to connect for example the SPANSION SK-TSC-1127S-SB
 - 2x LED-Display (7-Segment)
 - 2x 'User'-button
 - 1x 'Reset'-button, 'Reset'-LED
 - All 100 pins routed to pin-header
 - On-board 5V and 3V voltage regulators, 'Power'-LED
 - Power supply via USB (UART'B'), USB-Device, JTAG or external with a 8V to 12V power connector

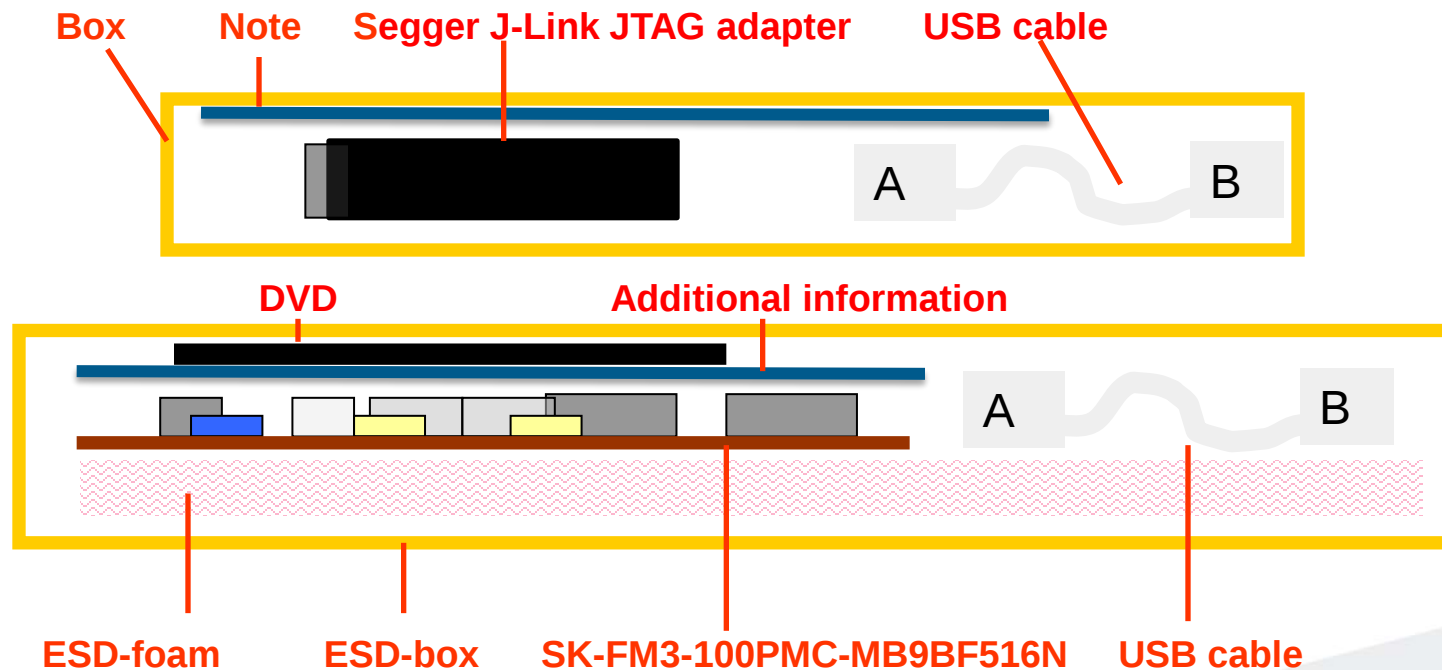
SK-FM3-100PMC-MB9BF516N content

- The SK-FM3-100PMC-MB9BF516N contains
 - SK-FM3-100PMC-MB9BF516N evaluation board with MB9BF516N
 - USB cable
 - DVD: Documentation, USB driver, Software examples, Programmer

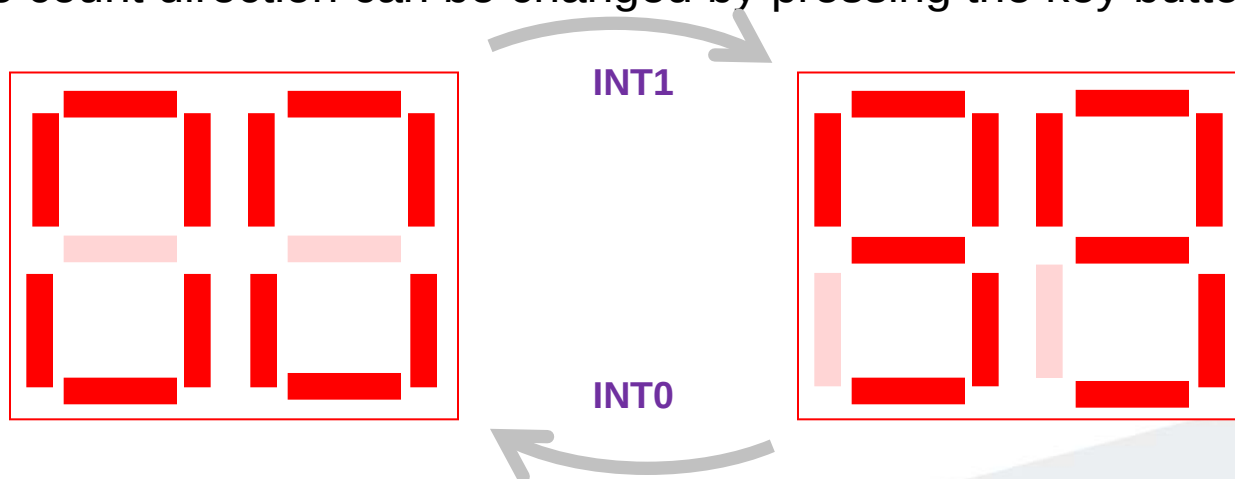


SK-FM3-100PMC-9BF516N-JL content

- The SK-FM3-100PMC-9BF516N-JL contains
 - SK-FM3-100PMC-MB9BF516N evaluation board with MB9BF516N
 - USB cable
 - DVD: Documentation, USB driver, Software examples, Programmer
 - Segger J-Link JTAG adapter incl. USB cable



- The microcontroller on the SK-FM3-100PMC-MB9BF516N is already preprogrammed with a simple application.
 - [Install the USB driver from the DVD](#)
 - Connect the SK-FM3-100PMC-MB9BF516N via USB (X5) with the PC , verify that jumper J5 is on the USBPWR position.
 - Press the ,Reset'- Button
 - The SK-FM3-100PMC-MB9BF516N will automatically start counting
 - The count direction can be changed by pressing the key buttons

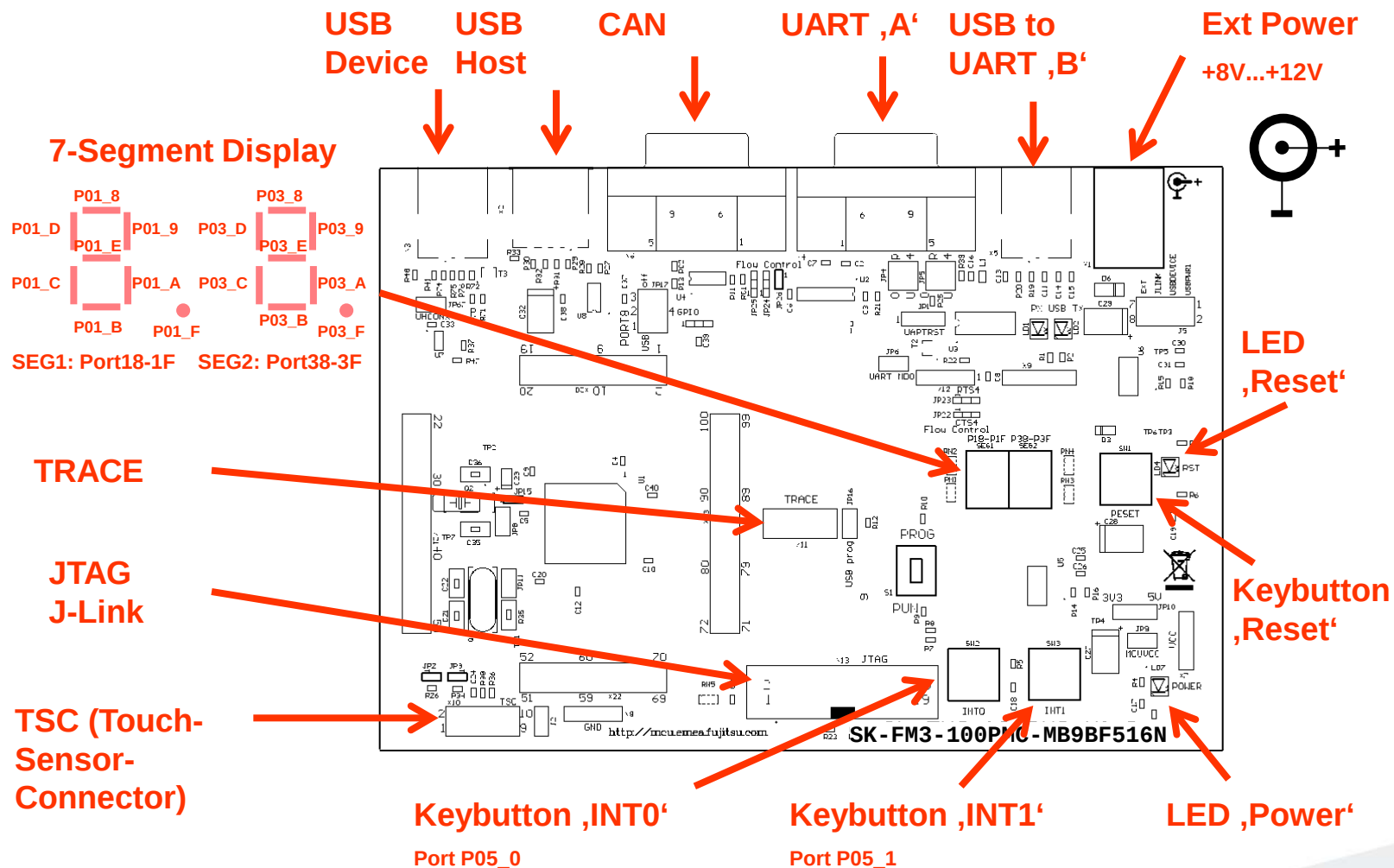


Congratulations!

- You finished successfully the first test
- Now you will get more details about the SK-FM3-100PMC-MB9BF516N board
- You will learn more about
 - The on-board features
 - How to program the Flash
 - How to start with IAR-Embedded-Workbench and KEIL μ Vision

The Hardware

■ Main features



The Hardware

■ The jumpers

JP1: DTR-Reset

1-2: DTR-Signal of the UART connector is connected to the MCU reset-pin.

2-3: DTR-Signal of the USB connector is connected to the MCU reset-pin.

Some terminal-programs, e.g. SPANSION's Skwizard, allow to reset the evaluation board by using the DTR-Signal.

JP6: MD0 selection

Close this jumper to control the MD0 level by the RTS signal of the USB interface

S1: Mode selection

PROG: Program-mode

RUN: Run-mode

JP10: 5V / 3.3V

1-2: 5V supply is used

2-3: 3.3V supply is used

JP4: UART RX select

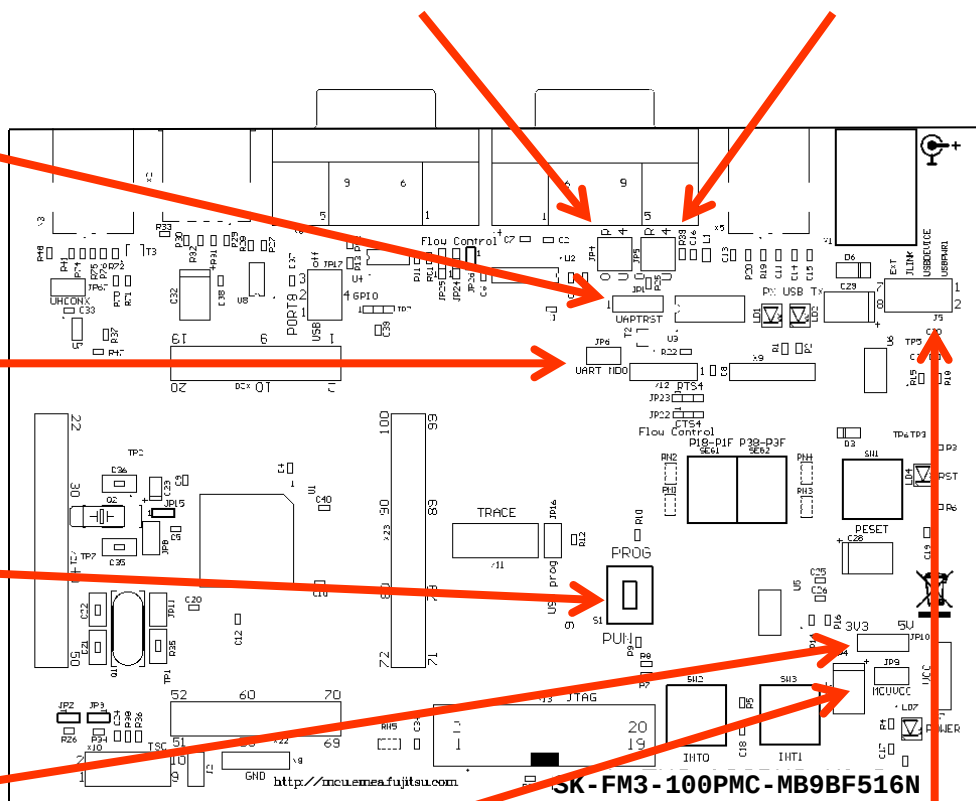
R-0: UART0=UART'A' / U-4: UART4=UART'B' (USB)

R-4: UART4=UART'A' / U-0: UART0=UART'B' (USB)

JP5: UART TX select

R-0: UART0=UART'A' / U-4: UART4=UART'B' (USB)

R-4: UART4=UART'A' / U-0: UART0=UART'B' (USB)



JP9: MCU Vcc

This jumper can be used to measure the current consumption of the MCU

J5: Power Supply

1-2: USB (UART ,B') supply

5-6: JLINK supply

3-4: USB Device supply

7-8: External supply

The Hardware

■ The jumpers

JP24-JP26: Flow Control UART4

JP24

1-2: Flow control disabled
2-3: Flow control enabled

JP25

1-2: Flow control enabled
2-3: Flow control disabled

JP26

open: Flow control disabled
closed: Flow control enabled

JP17: Port8 (USB use)

1-2: USB in use
2-3: USB not in use
2-4: Use Port 8 as digital I/O

JP67: USB Function HCONX

Open: D+ is not pulled up
Closed: HCONX controls Pullup of D+

JP16: USB prog

(for PROG-Mode S1)

Open: UART programming enabled
Closed: USB programming enabled

JP2: Pullup resistor TSC

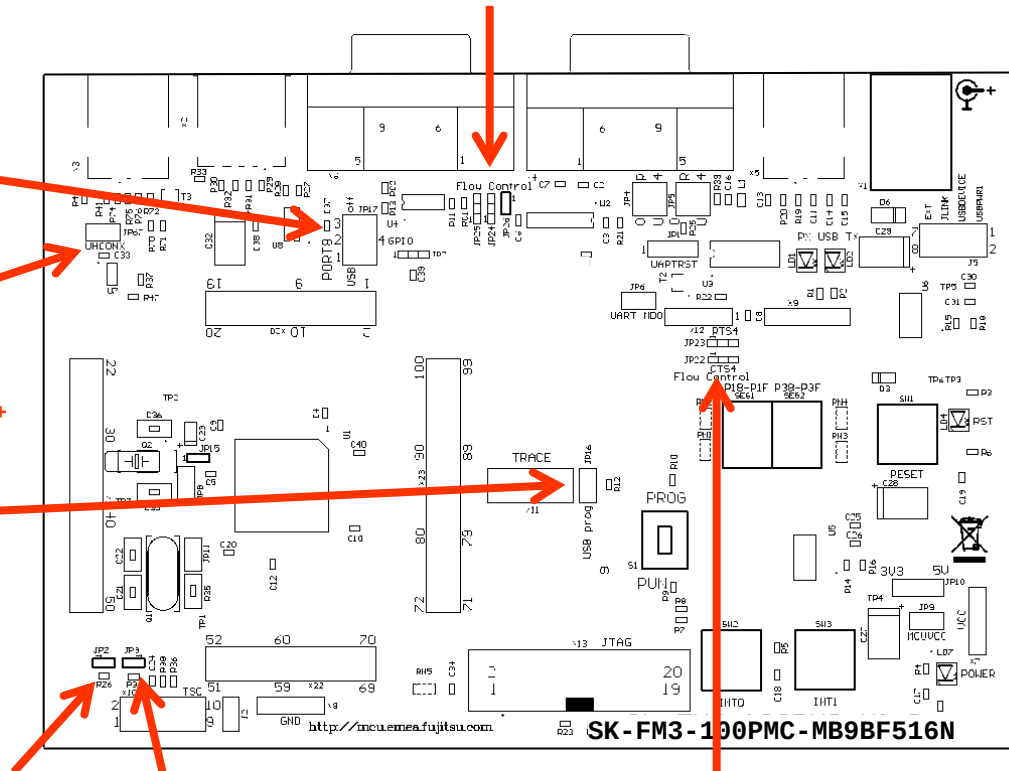
Closed: Pull up SCL3

JP3: Pullup resistor TSC

Closed: Pull up SDA3

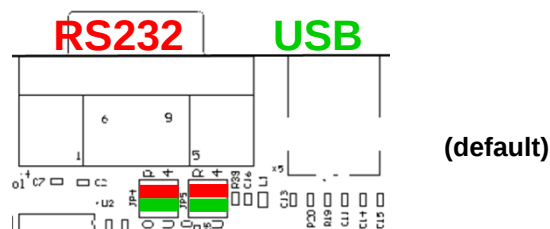
JP22,JP23: Flow Control CTS4, DTS4

JP22, JP23 1-2: Flow control on UART'A'
JP22, JP23 2-3: Flow control on UART'B'
JP22, JP23 Open: Flow control disabled

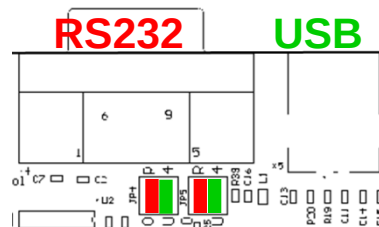


- JP4, JP5 : UART selection

- UART0 and UART4 of the microcontroller can be used together with a typical RS232 SUB-D9 connector and a serial/USB converter
- The jumpers JP4 and JP5 routes the channel to the connector
- UART0 = USB-connector (X5), UART4 = Sub-D9 (X4) (default)
 - ◆ Setting of Jumper JP4 and JP5: U-0 / R-4

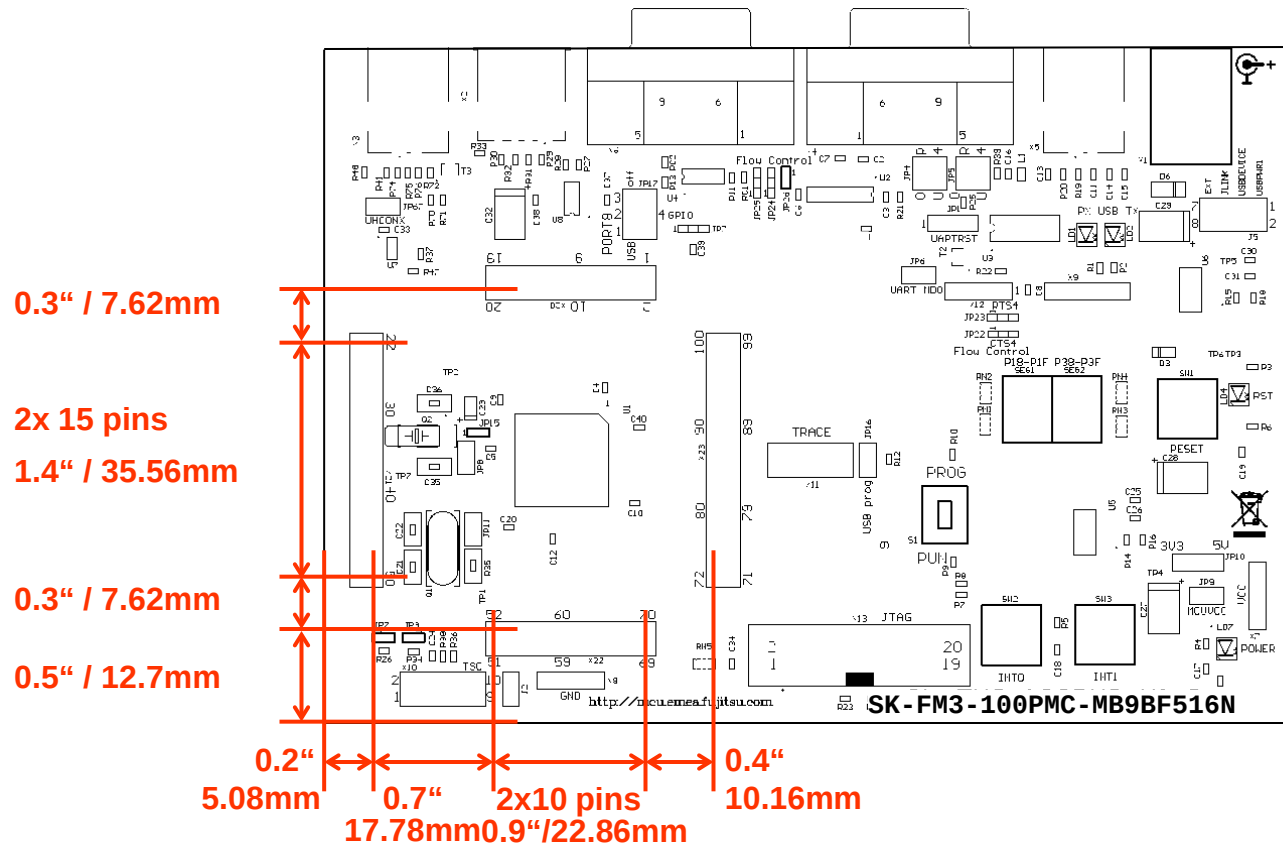


- UART0 = Sub-D9 (X4), UART4 = USB-connector (X5)
 - ◆ Setting of Jumper JP4 and JP5: U-4 / R-0



The Hardware

- Extension headers X20-X23
 - Standard 0.1" / 2.54mm grid for use with prototype boards



■ The microcontroller pins

Pin	Pin-name	Pin-Function on SK-FM-100PMC-MB9BF516N
1	VCC	MCUVCC
2	P50/INT00_0/AIN0_2/SIN3_1/RTO10_0/MADATA00_0	Key button 'INT0'
3	P51/INT01_0/BIN0_2/SOT3_1/RTO11_0/MADATA01_0	Key button 'INT1'
4	P52/INT02_0/ZIN0_2/SCK3_1/RTO12_0/MADATA02_0	USB current limitation 'INT2'
5	P53/SIN6_0/TIOA1_2/INT07_2/RTO13_0/MADATA03_0	
6	P54/SOT6_0/TIOB1_2/RTO14_0/MADAT A04_0	
7	P55/SCK6_0/ADTG_1/RTO15_0/MADAT A05_0	
8	P56/INT08_2/DTT1X_0/MADATA06_0	
9	P30/AIN0_0/TIOB0_1/INT03_2/MADATA 07_0	
10	P31/BIN0_0/TIOB1_1/SCK6_1/INT04_2/MADATA08_0	

Pin	Pin-name	Pin-Function on SK-FM-100PMC-MB9BF516N
11	P32/ZIN0_0/TIOB2_1/SOT6_1/INT05_2/MADATA09_0	
12	P33/INT04_0/TIOB3_1/SIN6_1/ADTG_6/MADATA10_0	
13	P34/FRCK0_0/TIOB4_1/TX0_1/MADAT A11_0	CAN0 TX
14	P35/IC03_0/TIOB5_1/RX0_1/INT08_1/M ADATA12_0	CAN0 RX
15	P36/IC02_0/SIN5_2/INT09_1/MADATA1 3_0	
16	P37/IC01_0/SOT5_2/INT10_1/MADATA1 4_0	
17	P38/IC00_0/SCK5_2/INT11_1/MADATA1 5_0	SEG2-A
18	P39/DTT10X_0/ADTG_2	SEG2-B
19	P3A/RTO00_0/TIOA0_1/RTCCO_2/SUB OUT_2	SEG2-C
20	P3B/RTO01_0/TIOA1_1	SEG2-D

■ The microcontroller pins (cont'd)

Pin	Pin-name	Pin-Function on SK-FM-100PMC-MB9BF516N
21	P3C/RTO02_0/TIOA2_1	SEG2-E
22	P3D/RTO03_0/TIOA3_1	SEG2-F
23	P3E/RTO04_0/TIOA4_1	SEG2-G
24	P3F/RTO05_0/TIOA5_1	SEG2-DP
25	VSS	GND
26	VCC	MCUVCC
27	P40/TIOA0_0/RTO10_1/INT12_1	TINT TSC-Connector 'INT12'
28	P41/TIOA1_0/RTO11_1/INT13_1	GINT TSC-Connector 'INT13'
29	P42/TIOA2_0/RTO12_1	
30	P43/TIOA3_0/RTO13_1/ADTG_7	

Pin	Pin-name	Pin-Function on SK-FM-100PMC-MB9BF516N
31	P44/TIOA4_0/RTO14_1/MAD00_0	
32	P45/TIOA5_0/RTO15_1/MAD01_0	
33	C	'C' capacitor
34	VSS	GND
35	VCC	MCUVCC
36	P46/X0A	Subclock (optional)
37	P47/X1A	Subclock (optional)
38	INITX	Key button ,Reset'
39	P48/DTTI1X_1/INT14_1/SIN3_2/MAD02_0	
40	P49/TIOB0_0/IC10_1/AIN0_1/SOT3_2/MAD03_0	SDA3 TSC-Connector

■ The microcontroller pins (cont'd)

Pin	Pin-name	Pin-Function on SK-FM-100PMC-MB9BF516N
41	P4A/TIOB1_0/IC11_1/BIN0_1/SCK3_2/MAD04_0	SCL3 TSC-Connector
42	P4B/TIOB2_0/IC12_1/ZIN0_1/MAD05_0	
43	P4C/TIOB3_0/IC13_1/SCK7_1/AIN1_2/MAD06_0	
44	P4D/TIOB4_0/FRCK1_1/SOT7_1/BIN1_2/MAD07_0	
45	P4E/TIOB5_0/INT06_2/SIN7_1/ZIN1_2/MAD08_0	
46	PE0/MD1	GND
47	MD0	Mode-Switch S1
48	PE2/X0	4 MHz Crystal
49	PE3/X1	4 MHz Crystal
50	VSS	GND

Pin	Pin-name	Pin-Function on SK-FM-100PMC-MB9BF516N
51	VCC	MCUVCC
52	P10/AN00	
53	P11/AN01/SIN1_1/INT02_1/RX1_2/FRC K0_2/MAD09_0	
54	P12/AN02/SOT1_1/TX1_2/IC00_2/MAD10_0	
55	P13/AN03/SCK1_1/RTCCO_1/SUBOUT_1/IC01_2/MAD11_0	
56	P14/AN04/SIN0_1/INT03_1/IC02_2/MAD12_0	
57	P15/AN05/SOT0_1/IC03_2/MAD13_0	
58	P16/AN06/SCK0_1/MAD14_0	
59	P17/AN07/SIN2_2/INT04_1/MAD15_0	
60	AVCC	MCUVCC

- The microcontroller pins (cont'd)

Pin	Pin-name	Pin-Function on SK-FM-100PMC-MB9BF516N
61	AVRH	MCUVCC
62	AVSS	GND
63	P18/AN08/SOT2_2/MAD16_0	SEG1-A
64	P19/AN09/SCK2_2/MAD17_0	SEG1-B
65	P1A/AN10/SIN4_1/INT05_1/IC00_1/MAD18_0	SEG1-C
66	P1B/AN11/SOT4_1/IC01_1/MAD19_0	SEG1-D
67	P1C/AN12/SCK4_1/IC02_1/MAD20_0	SEG1-E
68	P1D/AN13/CTS4_1/IC03_1/MAD21_0	SEG1-F
69	P1E/AN14/RTS4_1/DTTI0X_1/MAD22_0	SEG1-G
70	P1F/AN15/ADTG_5/FRCK0_1/MAD23_0	SEG1-DP

Pin	Pin-name	Pin-Function on SK-FM-100PMC-MB9BF516N
71	P23/SCK0_0/TIOA7_1	
72	P22/SOT0_0/TIOB7_1/ZIN1_1	UART0 (TXD)
73	P21/SIN0_0/INT06_1/BIN1_1	UART0 (RXD)
74	P20/INT05_0/CROUT_0/AIN1_1/MAD24_0	Reset TSC-Connector
75	VSS	GND
76	VCC	MCUVCC
77	P00/TRSTX/MCSX7_0	JTAG TRSTX
78	P01/TCK/SWCLK	JTAG/TRACE TCK
79	P02/TDI/MCSX6_0	JTAG/TRACE TDI
80	P03/TMS/SWDIO	JTAG/TRACE TMS

■ The microcontroller pins (cont'd)

Pin	Pin-name	Pin-Function on SK-FM-100PMC-MB9BF516N
81	P04/TDO/SWO	JTAG/TRACE TDO
82	P05/TRACED0/TIOA5_2/SIN4_2/INT00_1/MCSX5_0	TRACE TRACED0
83	P06/TRACED1/TIOB5_2/SOT4_2/INT01_1/AIN2_1/MCSX4_0	TRACE TRACED1
84	P07/TRACED2/ADTG_0/SCK4_2/BIN2_1/MCLKOUT_0	TRACE TRACED2
85	P08/TRACED3/TIOA0_2/CTS4_2/ZIN2_1/MCSX3_0	TRACE TRACED3
86	P09/TRACECLK/TIOB0_2/RTS4_2/RT020_1/MCSX2_0	TRACE TRACECLK
87	P0A/SIN4_0/INT00_2/FRCK1_0/FRCK2_0/RT021_1/MCSX1_0	UART4 (RXD)
88	P0B/SOT4_0/TIOB6_1/IC10_0/IC20_0/RT022_1/MCSX0_0	UART4 (TXD)
89	P0C/SCK4_0/TIOA6_1/IC11_0/IC21_0/RT023_1/MALE_0	
90	P0D/RTS4_0/TIOA3_2/IC12_0/IC22_0/RT024_1/MDQM0_0	RTS4 Flow control

Pin	Pin-name	Pin-Function on SK-FM-100PMC-MB9BF516N
91	P0E/CTS4_0/TIOB3_2/IC13_0/IC23_0/RT025_1/MDQM1_0	CTS4 Flow control
92	P0F/NMIX/CROUT_1/RTCCO_0/DTTI2X_0/DTTI2X_1/SUBOUT_0	
93	P63/INT03_0/SIN5_1/RX0_2/MWEX_0	USB-Switch Device/Host
94	P62/SCK5_0/ADTG_3/TX0_2/MOEX_0	Current limitation enable
95	P61/SOT5_0/TIOB2_2/UHCONX	USB UHCONX
96	P60/SIN5_0/TIOA2_2/INT15_1/MRDY_0	Mode-Switch S1
97	USBVCC	USB-power supply
98	P80/UDM0	USB Data-
99	P81/UDP0	USB Data+
100	VSS	GND



- The SK-FM3-100PMC-MB9BF516N DVD includes the following software:
 - MCU Flash programming tools
 - ◆ FLASH MCU Programmer for FM3
 - ◆ FLASH USB DIRECT Programmer
 - USB driver for on-board USB-to-RS232 converter
 - The terminal program ,Serial Port Viewer‘
 - The USB configuration tool ,USB Wizard‘
 - Software examples for the SK-FM3-100PMC-MB9BF516N

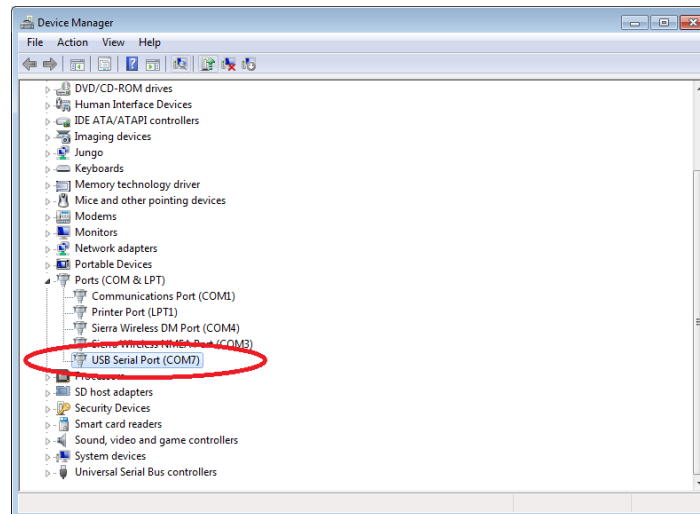
- Please check our dedicated microcontroller website:

www.spansion.com

- for updates of the Flash programmer tool, utilities and examples
- for data sheets, hardware manuals, application notes, etc.

Installation of the USB-driver

- Install the USB driver from the [DVD](#) with administrator privileges
- Start the Device Manager of the Windows Control Panel
 - START -> Settings -> Control Panel
 - Control Panel -> System -> Hardware -> Device Manager
- Check 'Ports' for the assigned virtual COM-port number
 - USB Serial Port (e.g.: COM7)



- Ready!



- Serial Port Viewer
 - Free of charge terminal program, [Start installation](#)
- USB Wizard
 - Free of charge USB configuration tool, [Start installation](#)
- Following examples are provided with SK-FM3-100PMC-MB9BF516N for IAR Embedded Workbench V6 and KEIL μ Vision4:
 - [mb9bf51xn_template](#), 'Empty' project as base for user applications
 - [mb9bf51xn_adc_dvm](#) Digital Voltage Meter based on the A/D-converter
 - [mb9bf51xn_can_uart_terminal](#) Simple CAN example (CAN0)
 - [mb9bf51xn_ioport_counter](#) Counts from 0 to 99 on the 7-segment Display
 - Further examples on [DVD](#) and on our website

Note: **Please copy the examples to your local drive!**

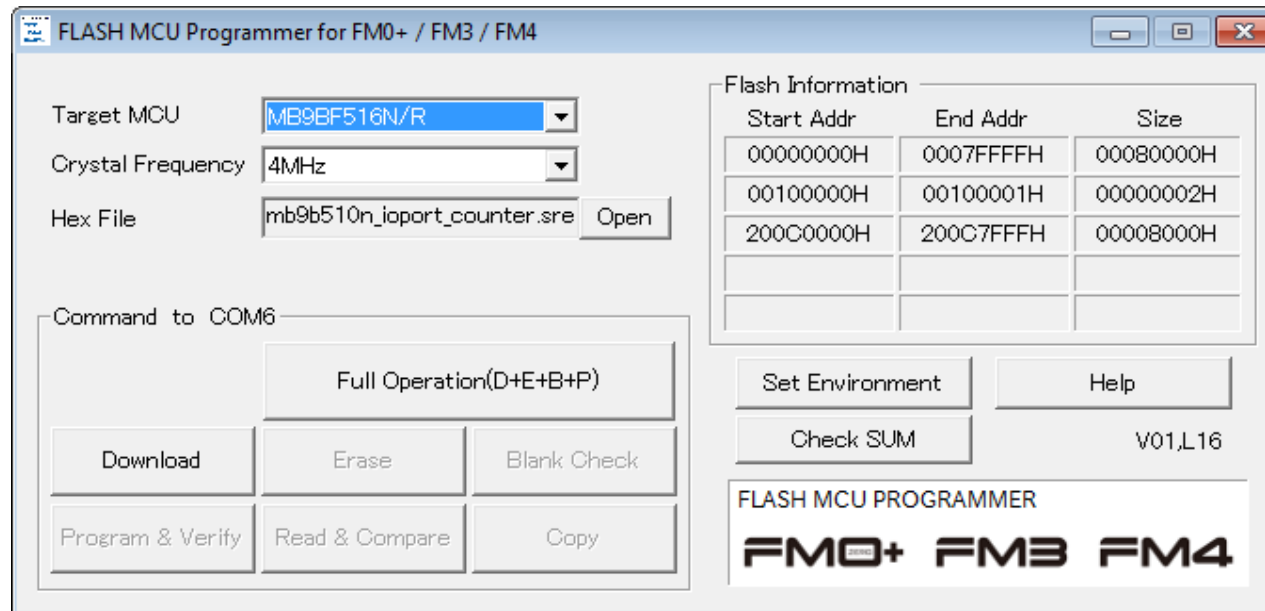


- There are two options to program the flash:
 - UART Programming (X4, X5)
 - ◆ Check jumper JP16 is opened
 - ◆ Connect UART0 of the board to the USB-Port of the PC
 - via USB (JP4,JP5: U-0, R-4)
 - via RS232 (JP4,JP5: U-4, R-0)
 - ◆ Use the [FLASH MCU Programmer](#)
 - USB Programming (X3)
 - ◆ Check jumper JP16 is closed
 - ◆ Connect the board via USB-Device (X3) to the USB-Port of the PC
 - ◆ Use the [FLASH USB DIRECT Programmer](#)

FLASH MCU Programmer for UART Programming

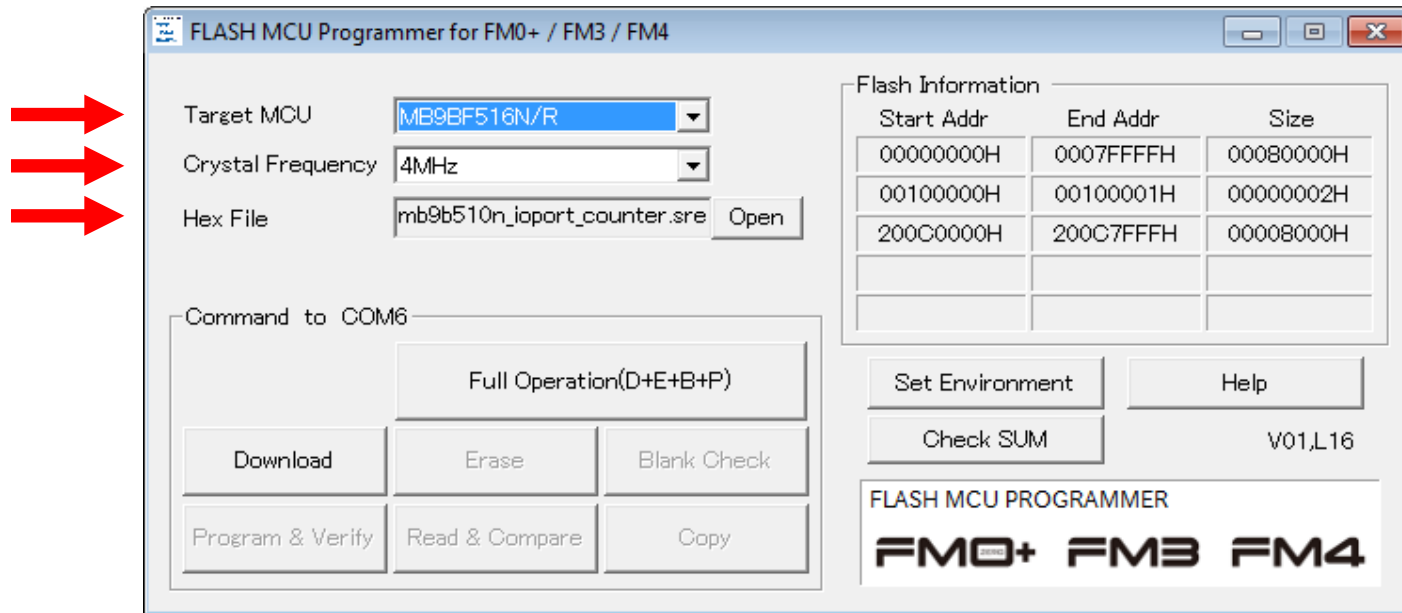
- FLASH MCU Programmer

- Free of charge, no registration required
- Windows based programming tool for FM3 microcontroller
- Uses PC serial port COMx (incl. virtual COM port: USB-to-RS232)
- [Start installation](#)



Program Download

- Start the FLASH MCU Programmer
- Select the target microcontroller (MB9BF516[N/R])
- Select the crystal frequency (4 MHz)
- Choose the software example from the example 'exe'-folder (e.g. Examples\mb9bfxxx_ioport_counter-v11\example\IAR\output\release\exe\mb9bfxxx_ioport_counter.srec)

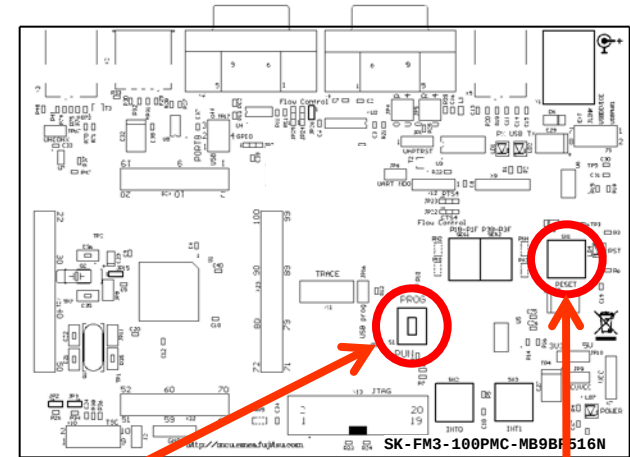


Program Download

- Connect to the PC
 - Connect UART0 with RS232 (X4) or with the USB interface X5
 - Select COM port (,Set Environment')
- Open JP16
- Set switch S1 to position ,PROG'
- Press ,Reset'
- Start ,Full Operation'

(see JP4, JP5 jumper settings)

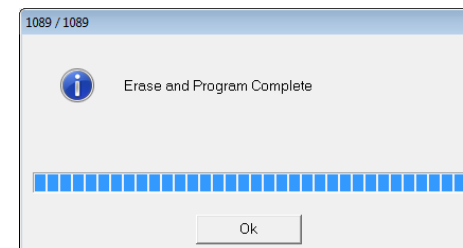
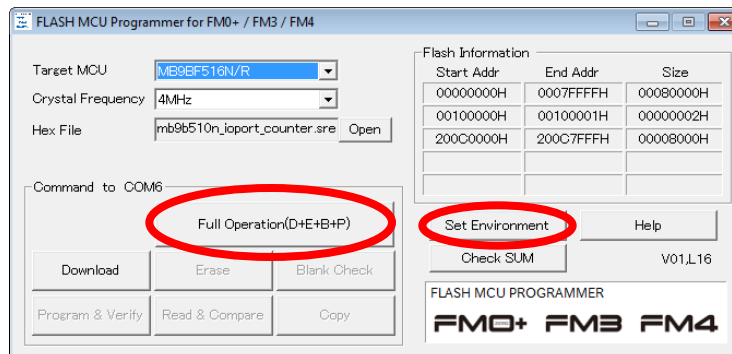
RS232 USB port



S1: Mode selection

PROG: Set switch to position ,PROG' in order to select the program-mode

Keybutton ,RESET'

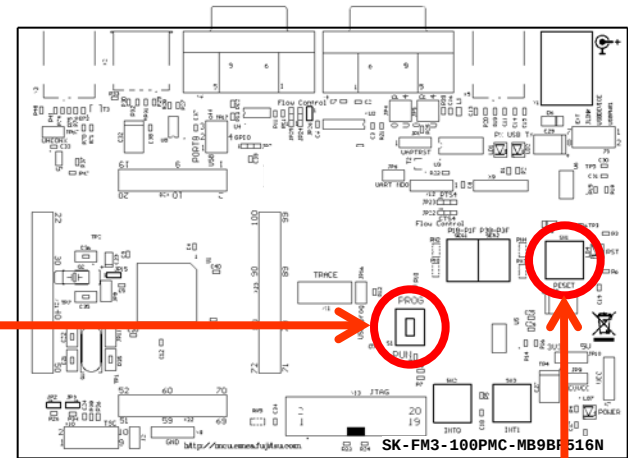


Program Download

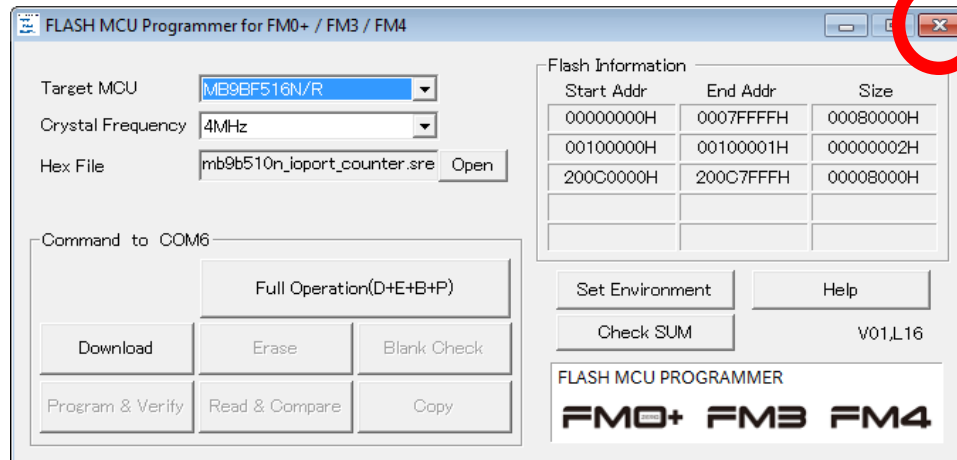
- Close the FLASH MCU Programmer
- Set switch S1 to position ,RUN‘
- Press ,Reset‘

S1: Mode selection

**RUN: Set switch to position ,RUN‘
in order to select the run-mode**



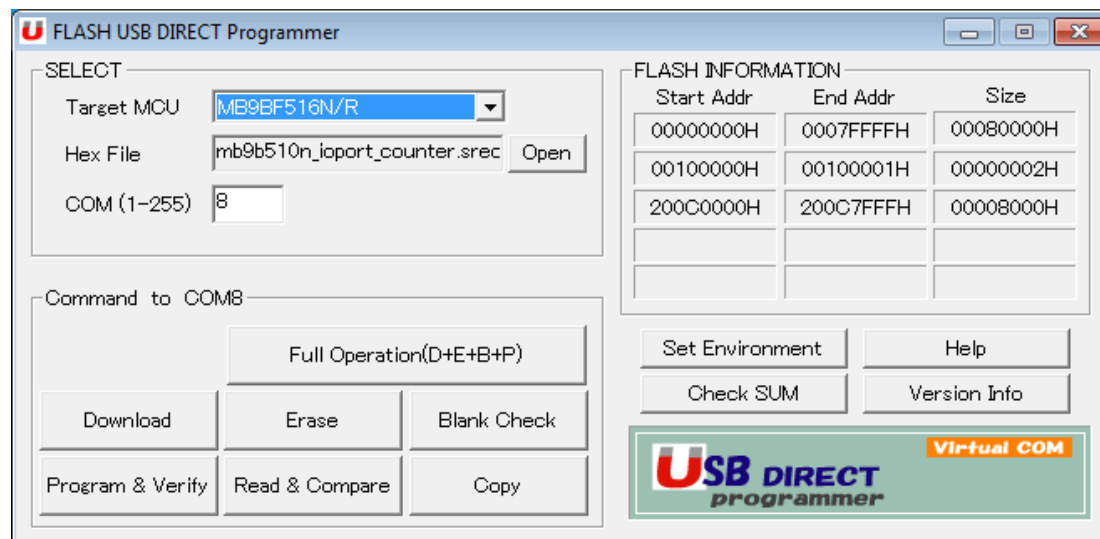
Keybutton ,RESET‘



**Close the FLASH MCU
Programmer**

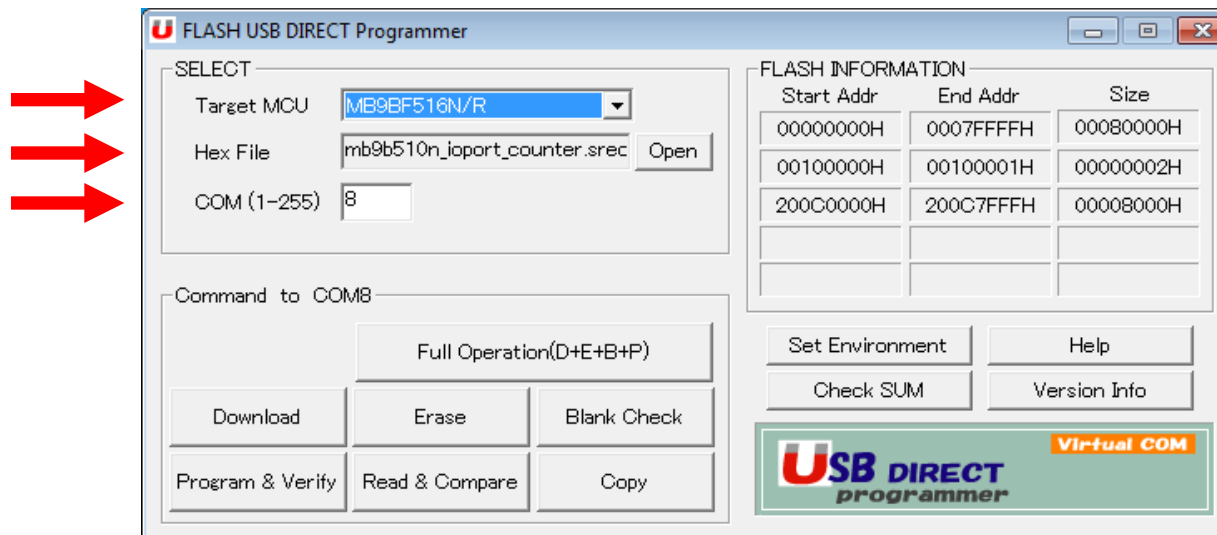
FLASH USB DIRECT Programmer for USB Direct Programming

- FLASH USB DIRECT Programmer
 - Windows based programming tool for FM3 microcontroller
 - Uses direct USB connection (via X3)
 - [Start installation](#)



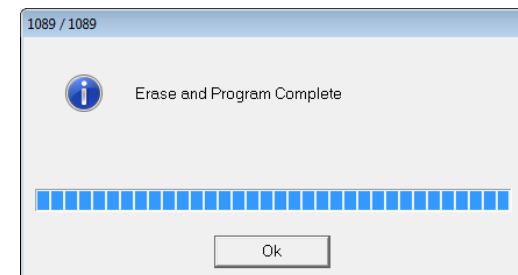
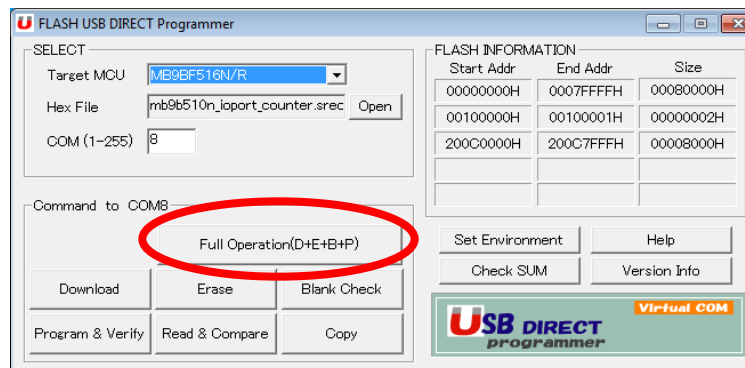
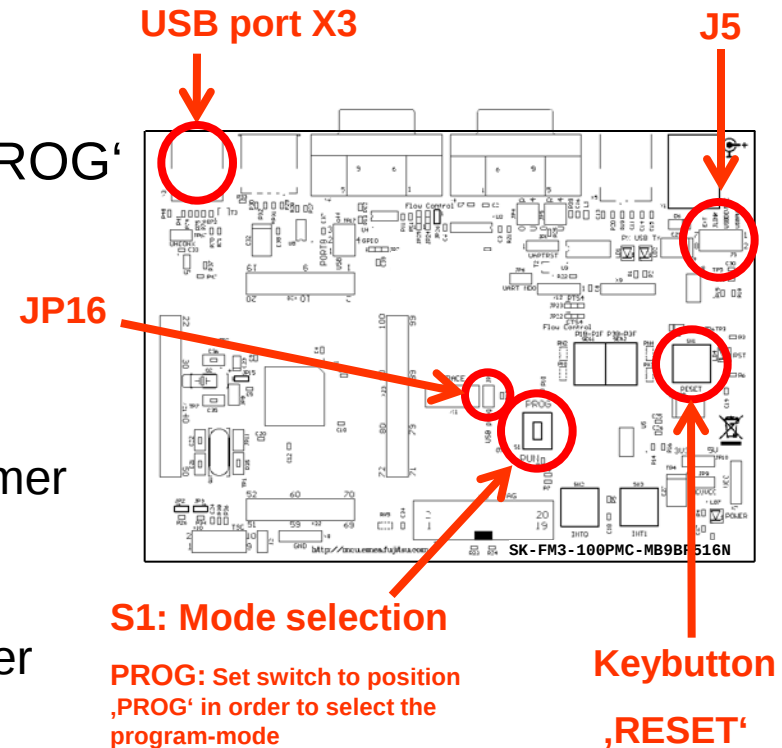
Program Download

- Start the FLASH USB DIRECT Programmer
- Select the target microcontroller (MB9BF516)
- Choose the software example from the example 'exe'-folder (e.g. Examples\mb9bfxxx_ioport_counter-v10\example\IAR\output\release\exe\mb9bfxxx_ioport_counter.srec)
- Select the COM port



Program Download

- Select the MCU power supply ([J5](#))
 - Close JP16, Set switch S1 to position 'PROG'
 - Connect USB port X3 with the PC
 - Install the USB driver
 - See subfolder 'driver' of installed programmer
 - E.g.: C:\Program Files (x86)\Spansion\..
..FLASH USB DIRECT Programmer\driver
- Press 'Reset' and Start 'Full Operation'

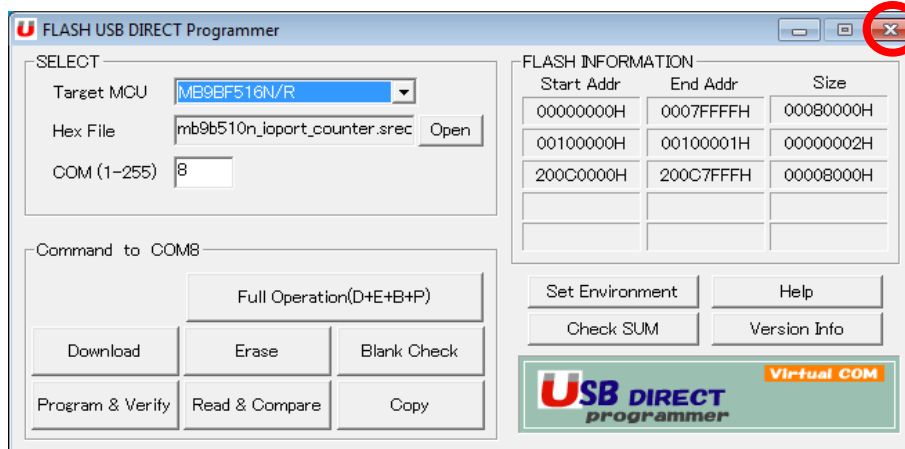
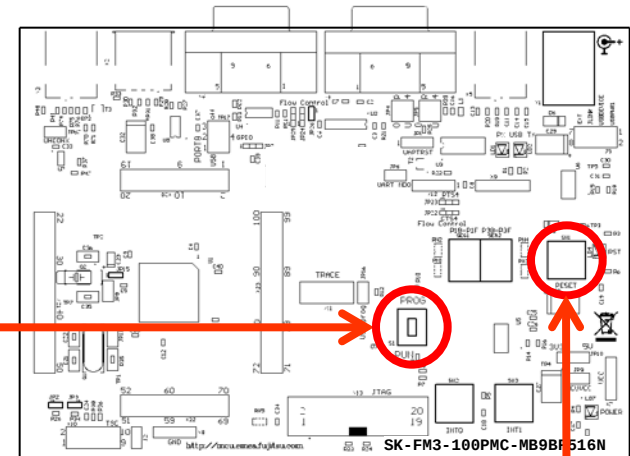


Program Download

- Close the FLASH USB DIRECT Programmer
- Set switch S1 to position ,RUN‘
- Press ,Reset‘

S1: Mode selection

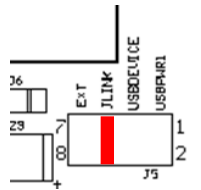
**RUN: Set switch to position ,RUN‘
in order to select the run-mode**



Keybutton ,RESET‘

**Close the FLASH USB
DIRECT Programmer**

- The MB9BF516N microcontroller offers a JTAG-Interface that is supported by SK-FM3-100PMC-MB9BF516N.
 - Debug your program with a JTAG-Adapter e.g. Segger J-Link
 - Connect the J-Link to the JTAG-Interface routed to the 20-Pin-Header on X13 and to the USB-Port of your PC
 - Use IAR-Embedded Workbench to debug your program
 - If the JTAG-Adapter allows powering the target, then jumper J5 can be set as follows:

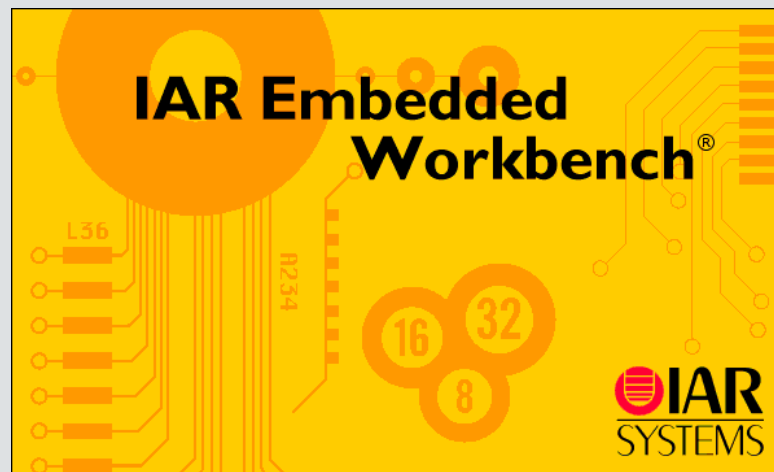


- The MB9BF516N microcontroller offers an ETM (Embedded-Trace-Macrocell) that is supported by SK-FM3-100PMC-MB9BF516N
 - An optional JTAG-Adapter supporting trace features is required e.g. ULINKpro from KEIL
 - The ETM is connected to the 20-Pin-Header X11 (TRACE)
 - Use e.g. KEIL μ Vision to trace your program



IAR Embedded Workbench

- Installation
- Getting Started
- Open Project
- Build Project
- Debug Project



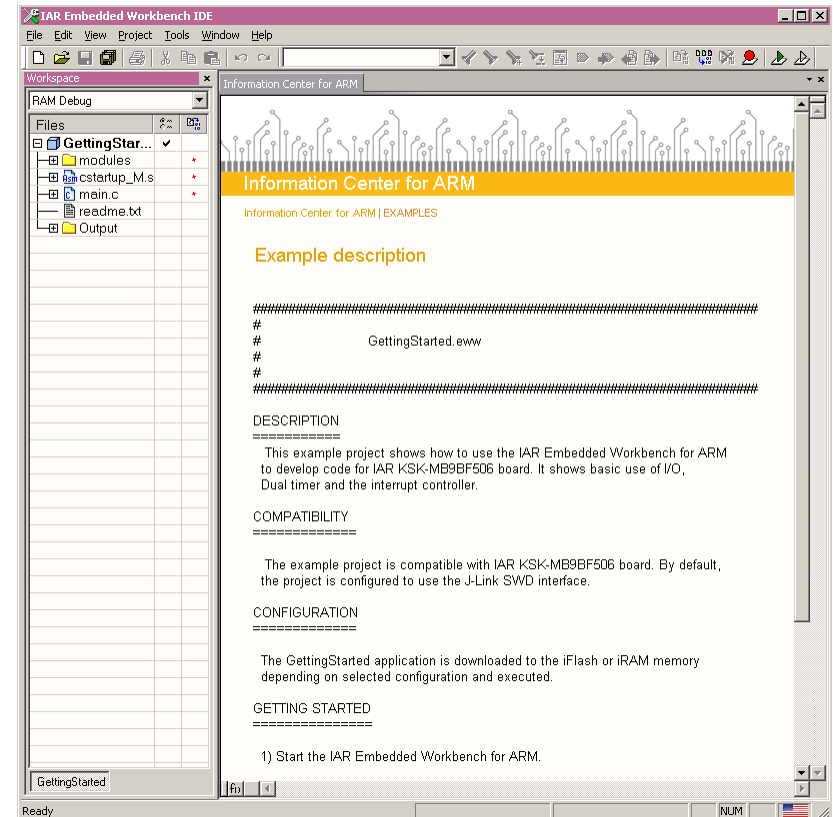
IAR Workbench Getting Started

- Install EWARM from IAR-CD or download latest version from IAR Website
 - EWARM size-limited (32k) or time-limited (full) Evaluation Version
 - ◆ <http://supp.iar.com/Download/SW/?item=EWARM-EVAL>
- Start EWARM Workbench
- Choose File → Open → Workspace
 - e.g.: <drive:>\<board>\[Examples\mb9b510n_ioport_counter_v11\example\IAR\](#)
 - Choose mb9b510n_ioport_counter.eww

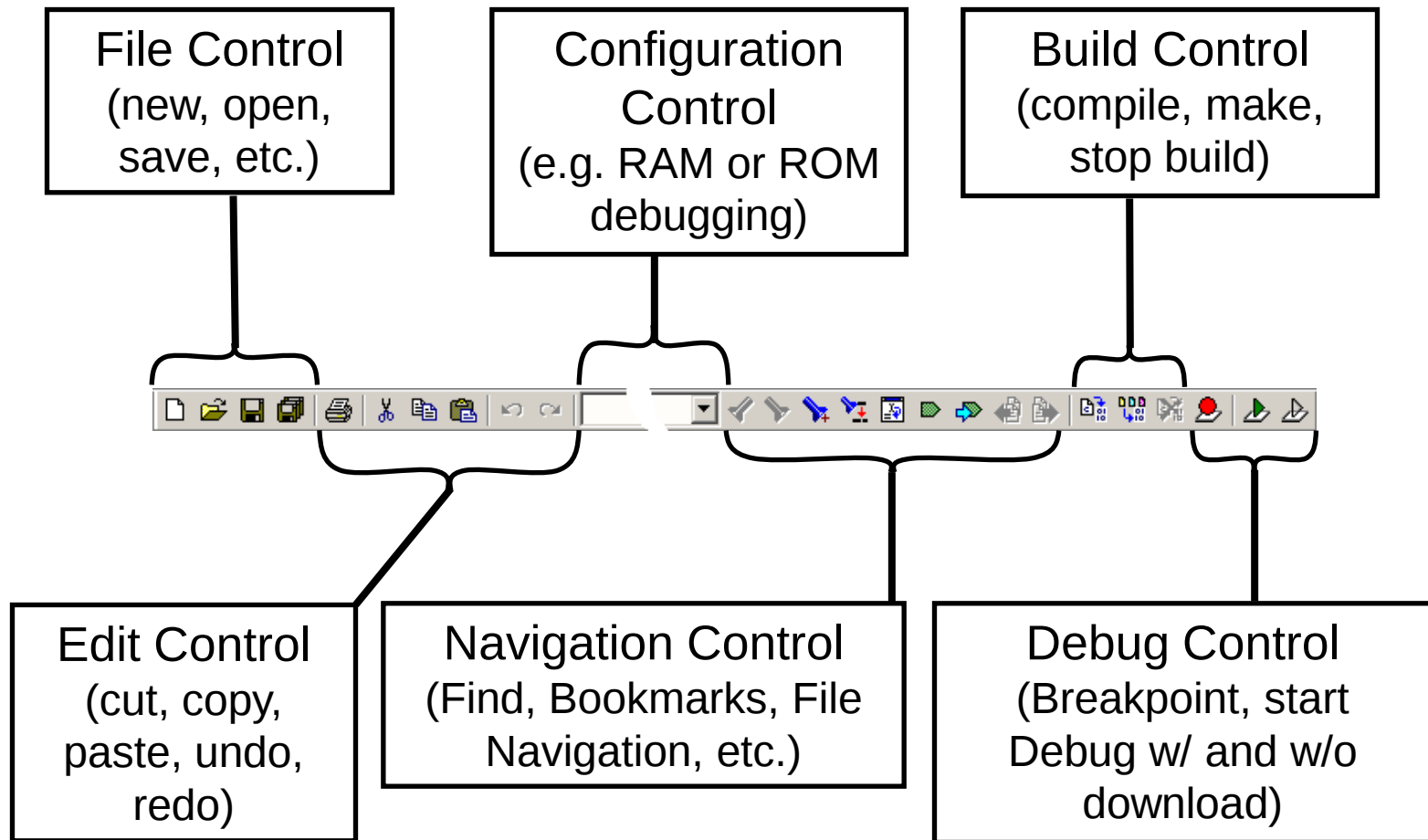


IAR Workbench – Main Window

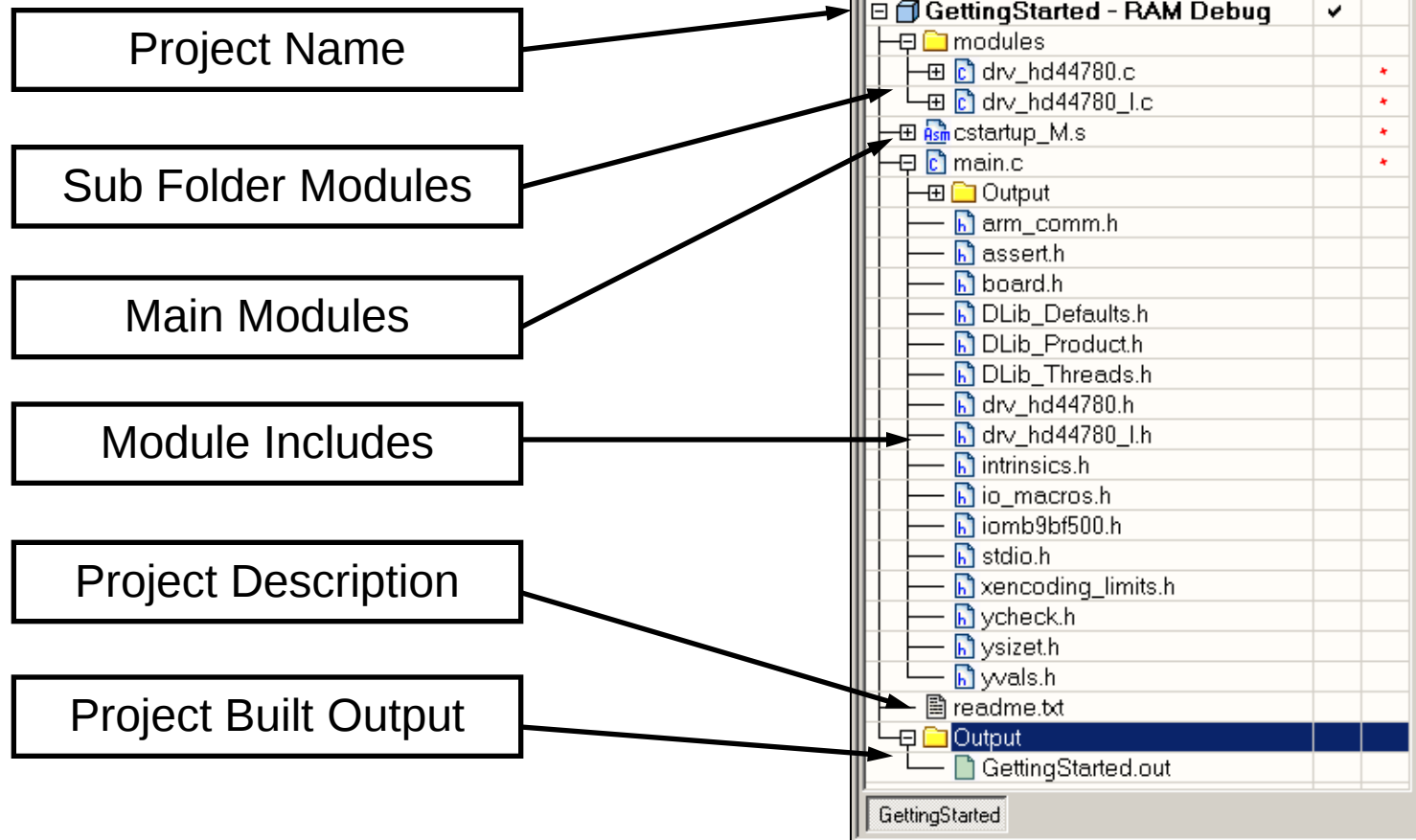
- IAR Workbench
 - Workspace on left side of Workbench window
 - ◆ If hidden then View→Workspace
 - Source files on right side of Workbench window as tabbed windows
 - Project open
File → Open → Workspace → *.eww
 - For new projects
start with ,mb9bf56xr_template'



- IAR Menu Bar

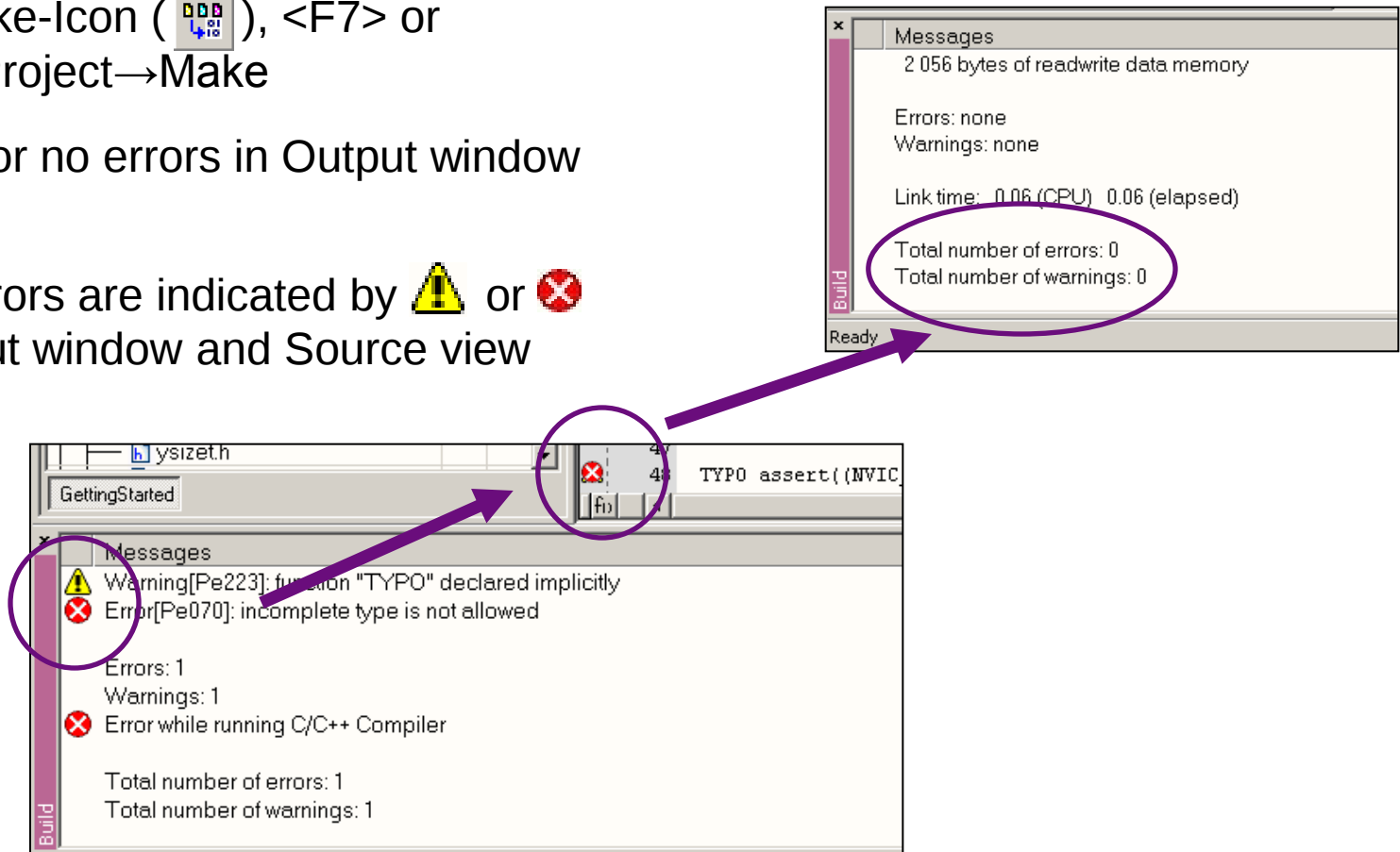


- IAR Workspace Window



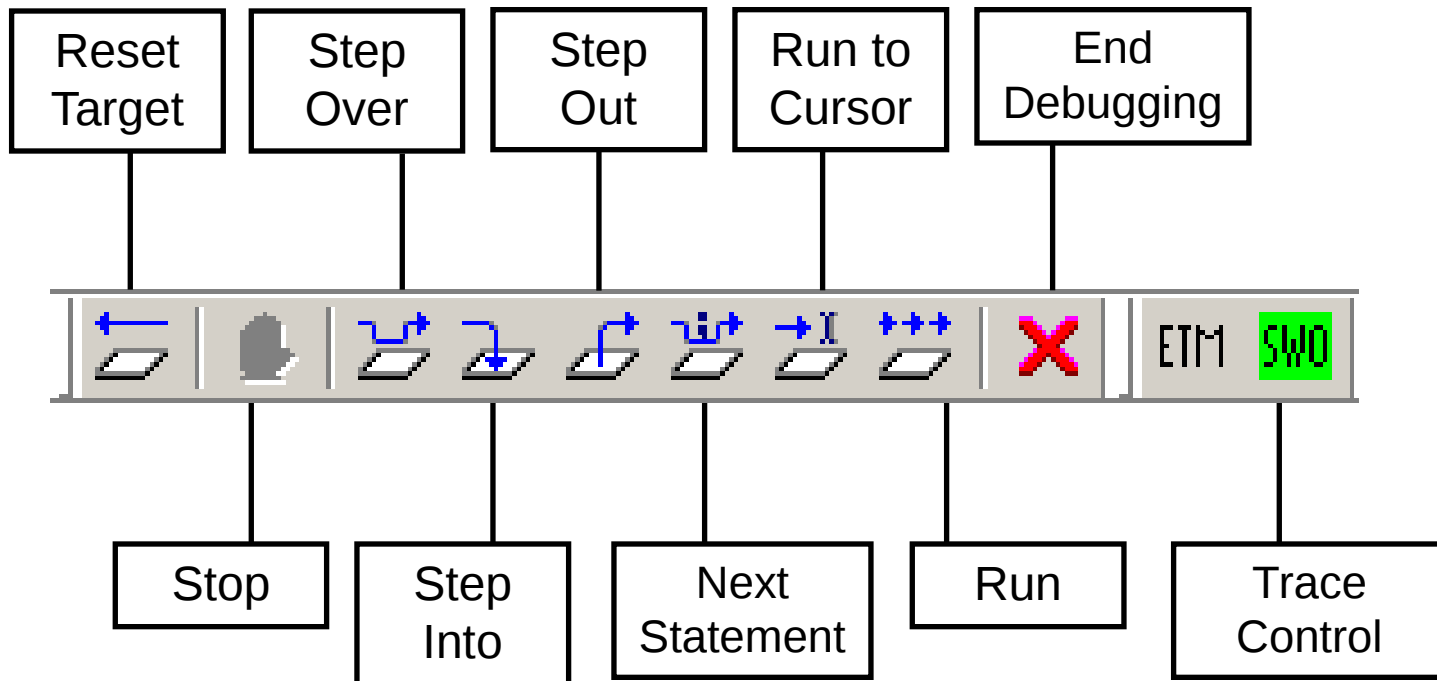
■ Making the Project

- Use Make-Icon (, <F7> or Menu: Project→Make
- Check for no errors in Output window below
- Build errors are indicated by  or 
In Output window and Source view



■ Download to Target and Start Debugging

- Use  Icon, <Ctrl>-D, or Project→Download and Debug
- A new menu bar will occur on successful connection to target



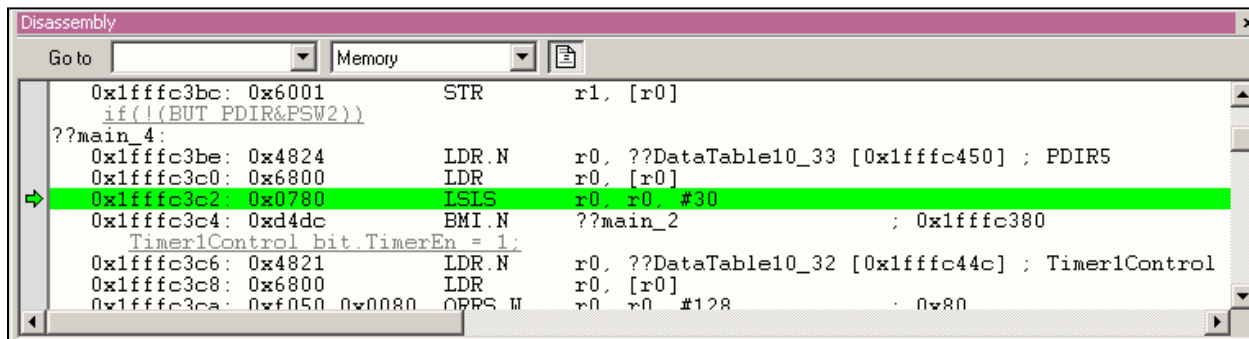
■ Source Window

- The Source windows do not change contents but get additional information
 - ◆ Current line (PC):
 - ◆ Halted on Breakpoint:
 - ◆ Halted on Data break (example):

```
165 CSW_TMR_bit.MOWT = 9;  
172 PSW_TMR_bit.POWT = 2;  
148 Timer1IntClr = 1;
```

■ Disassembly Window

- Shows 'pure' disassembly view
- Shows mixed mode view



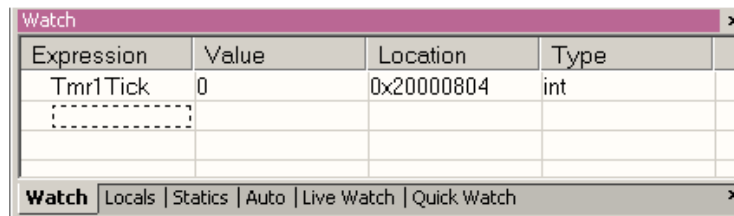
The screenshot shows the 'Disassembly' window in IAR Workbench. The window has a title bar 'Disassembly' and a menu bar with 'Goto' and 'Memory'. The main area displays assembly code with addresses, hex values, and instructions. The instruction 'LSLS r0, r0, #30' at address 0x1ffff3c2 is highlighted in green. The code includes conditional assembly directives like 'if(!(BUT_PDIR&PSW2))' and '??main_4:'. The instructions are: STR r1, [r0] at 0x1ffff3bc; LDR.N r0, ??DataTable10_33 [0x1ffff450] ; PDIR5 at 0x1ffff3be; LDR r0, [r0] at 0x1ffff3c0; LSLS r0, r0, #30 at 0x1ffff3c2; BMI.N ??main_2 ; 0x1ffff380 at 0x1ffff3c4; LDR.N r0, ??DataTable10_32 [0x1ffff44c] ; Timer1Control at 0x1ffff3c6; LDR r0, [r0] at 0x1ffff3c8; ORRS.W r0, r0, #128 at 0x1ffff3ca.

```
Disassembly  
Goto Memory  
0x1ffff3bc: 0x6001 STR r1, [r0]  
if(!(BUT_PDIR&PSW2))  
??main_4:  
0x1ffff3be: 0x4824 LDR.N r0, ??DataTable10_33 [0x1ffff450] ; PDIR5  
0x1ffff3c0: 0x6800 LDR r0, [r0]  
→ 0x1ffff3c2: 0x0780 LSLS r0, r0, #30  
0x1ffff3c4: 0xd4dc BMI.N ??main_2 ; 0x1ffff380  
Timer1Control_bit.TimerEn = 1;  
0x1ffff3c6: 0x4821 LDR.N r0, ??DataTable10_32 [0x1ffff44c] ; Timer1Control  
0x1ffff3c8: 0x6800 LDR r0, [r0]  
0x1ffff3ca: 0xf050 0x0080 ORRS.W r0, r0, #128 ; 0x80
```

■ Watch Window

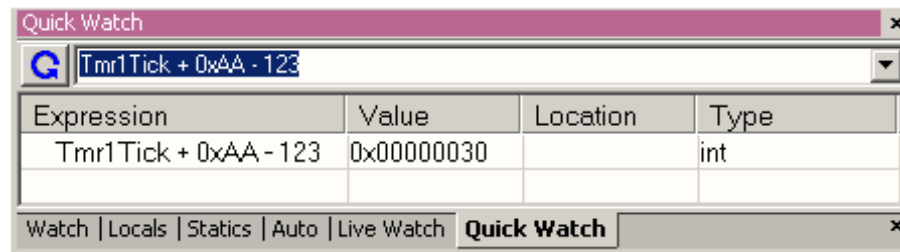
– Watch

- ◆ Expressions/Variables have to be added by user and are updated by Halt/Breakpoint



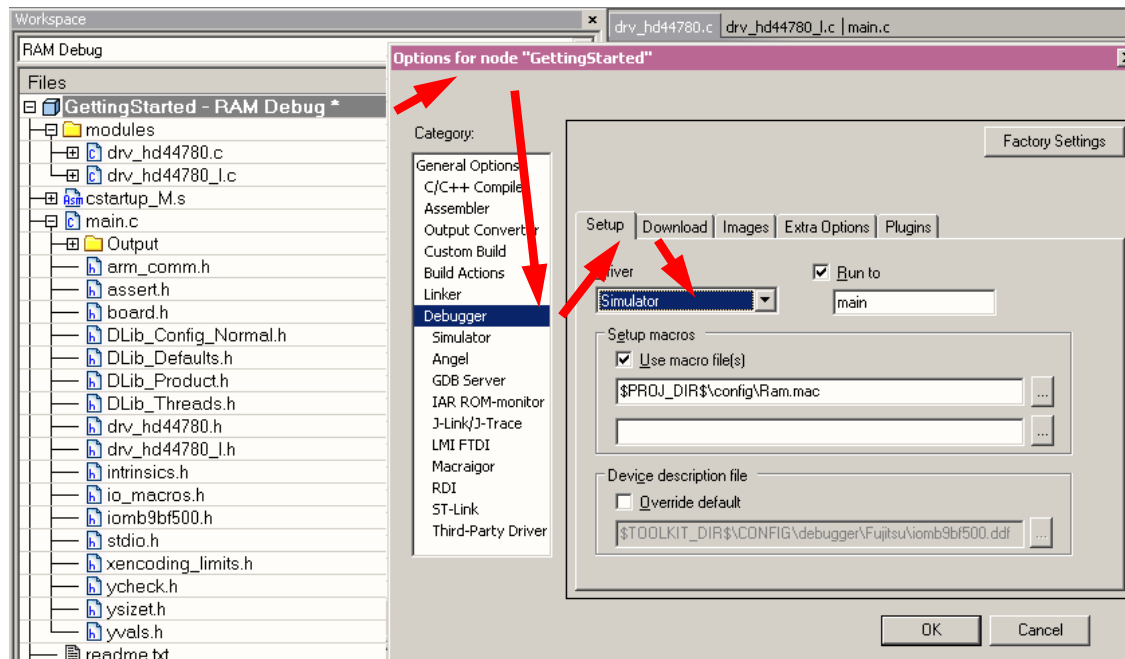
– Quick Watch

- ◆ The Quick watch allows the user to calculate and recalculate expressions even with variables



- ◆ The drop down menu memorizes the last typed contents

- Simulator
 - Mark Project File in Workspace
 - Choose Project→Options
 - Choose Simulator in Debugger Setup
 - Start Simulator with usual  Icon



KEIL μ Vision

- Installation
- Getting Started
- Open Project
- Build Project
- Debug Project

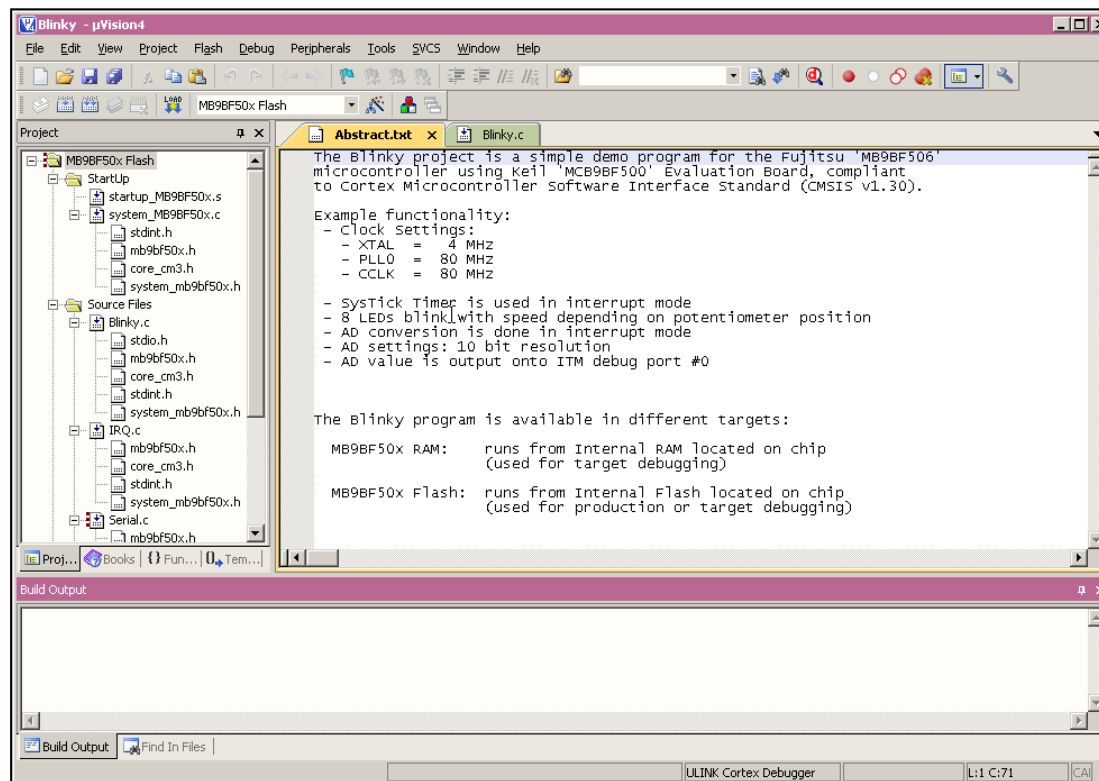




- Install μ Vision from KEIL-CD or download latest version from KEIL Website
 - Evaluation Version
 - ◆ <https://www.keil.com/demo/eval/arm.htm>
 - ◆ Registration required
- Install ULINK-ME
 - Special installation is not needed, because ULINK-ME acts as a USB Human Interface Device (HID) and thus needs no extra USB driver
- Install ULINK Pro (optional)
 - ULINK Pro needs an own dedicated USB driver located in:
<Installation Path>\KEIL\ARM\ULINK
- Start μ Vision

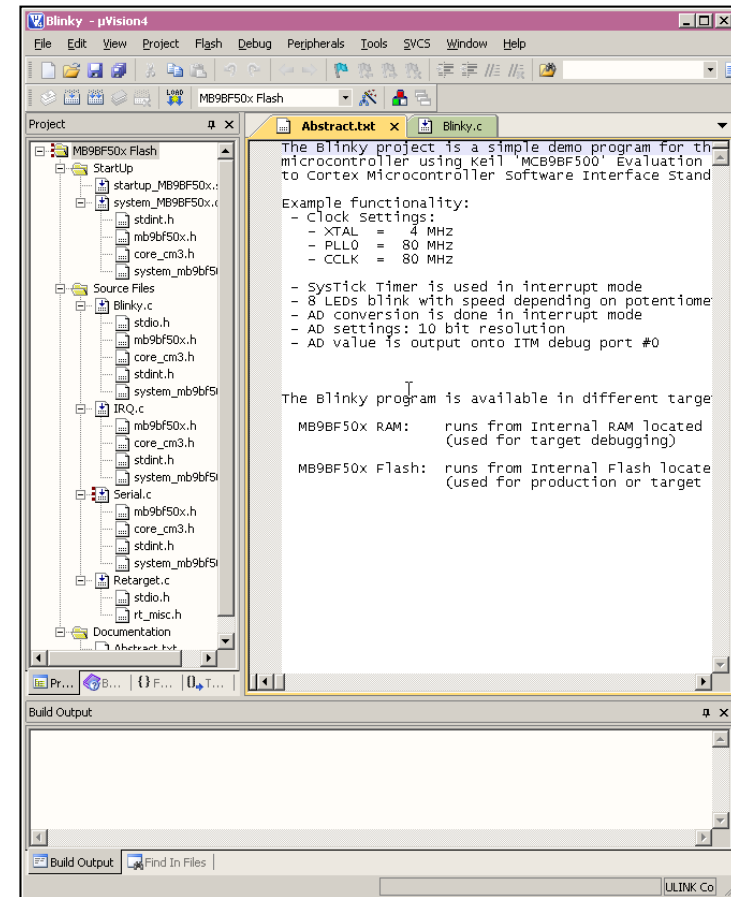
KEIL μ Vision – Getting Started

- Choose Menu: Project→Open Project...
 - Browse to: <drive:>\<board>\[Examples\mb9b510n_adc_dvm-v11\example\ARM\](#)
 - Choose mb9b510n_adc_dvm.uvproj



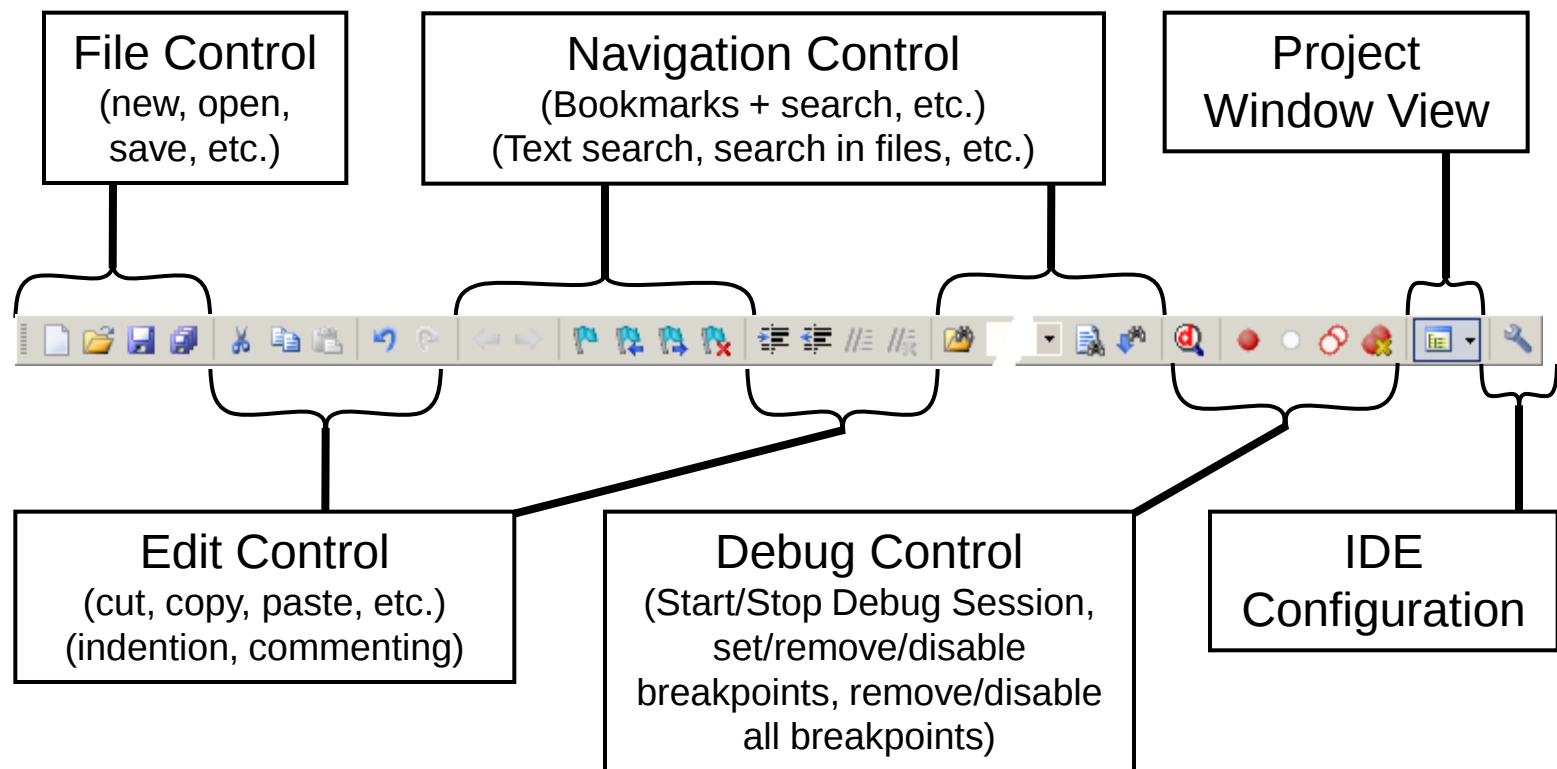
■ KEIL μ Vision

- Project window on left side of IDE window
 - ◆ Choose:
View→Project Window
if hidden
- Source files on right side of IDE window as tabbed windows
- Output window on bottom side of IDE window



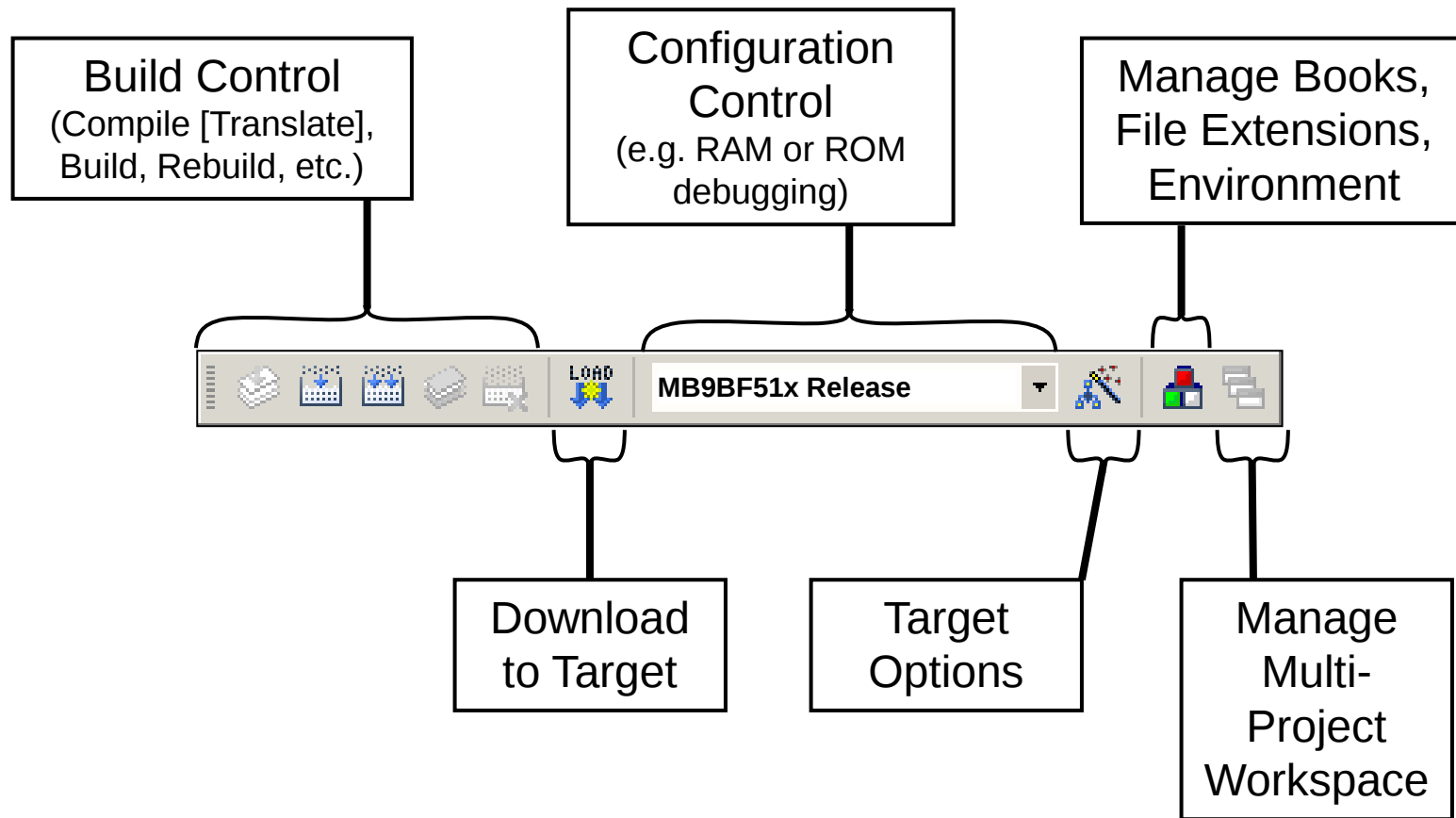
■ Menu Bar 1

- Can be moved in bar window area or set floating

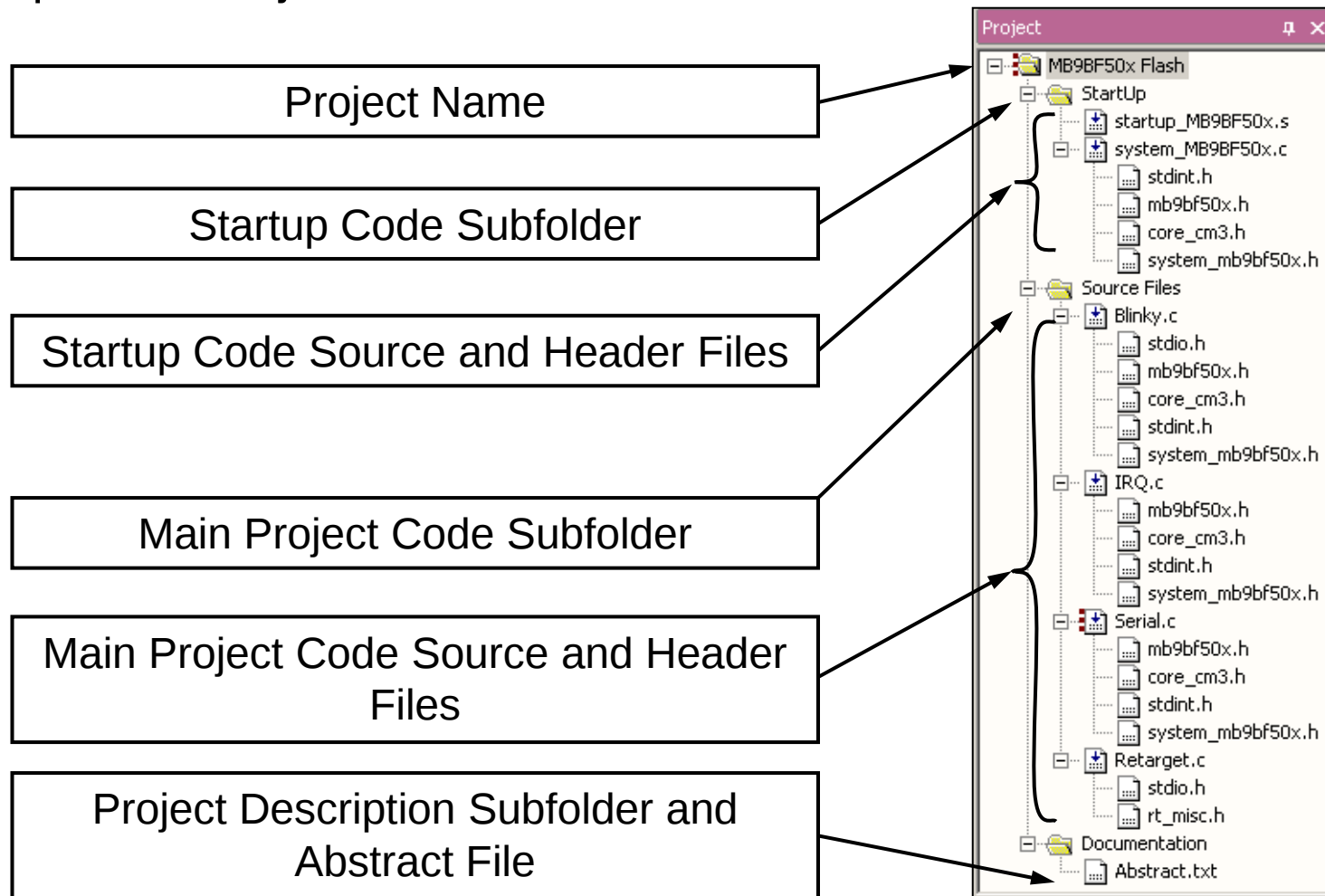


■ Menu Bar 2

- Can be moved in bar window area or set floating

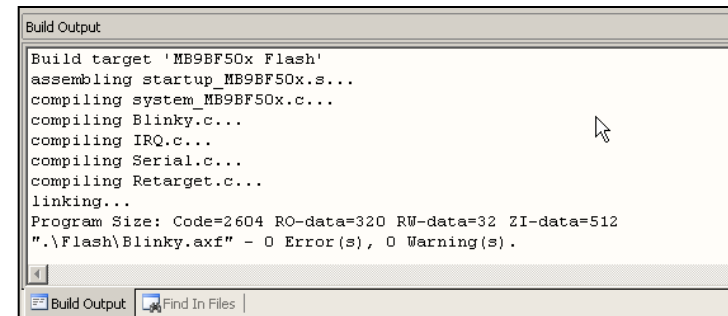


■ μ Vision Project Window



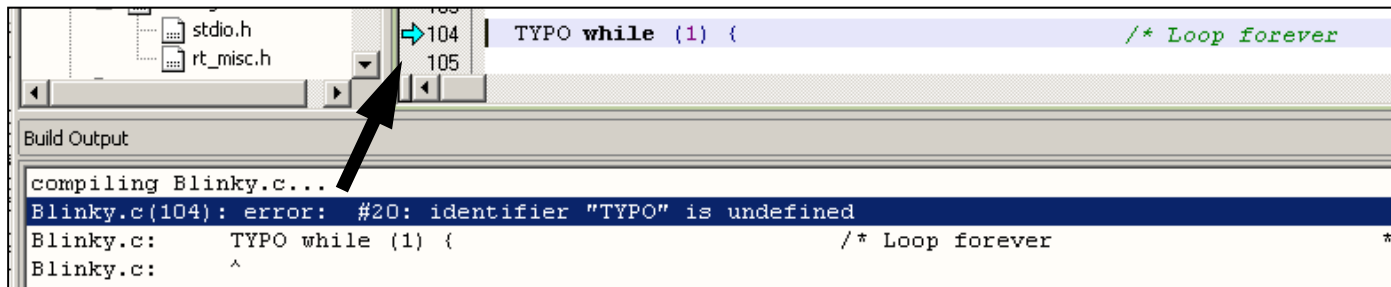
■ Making the Project

- Use Rebuild Icon
() or
Project→Rebuild all target
files
- Check for no errors in
Output window below



```
Build Output
Build target 'MB9BF50x Flash'
assembling startup_MB9BF50x.s...
compiling system_MB9BF50x.c...
compiling Blinky.c...
compiling IRQ.c...
compiling Serial.c...
compiling Retarget.c...
linking...
Program Size: Code=2604 RO-data=320 RW-data=32 ZI-data=512
".\Flash\Blinky.axf" - 0 Error(s), 0 Warning(s).
```

- Build errors are shown in Output window.
 - ◆ Can be double-clicked by showing the source line with a blue arrow

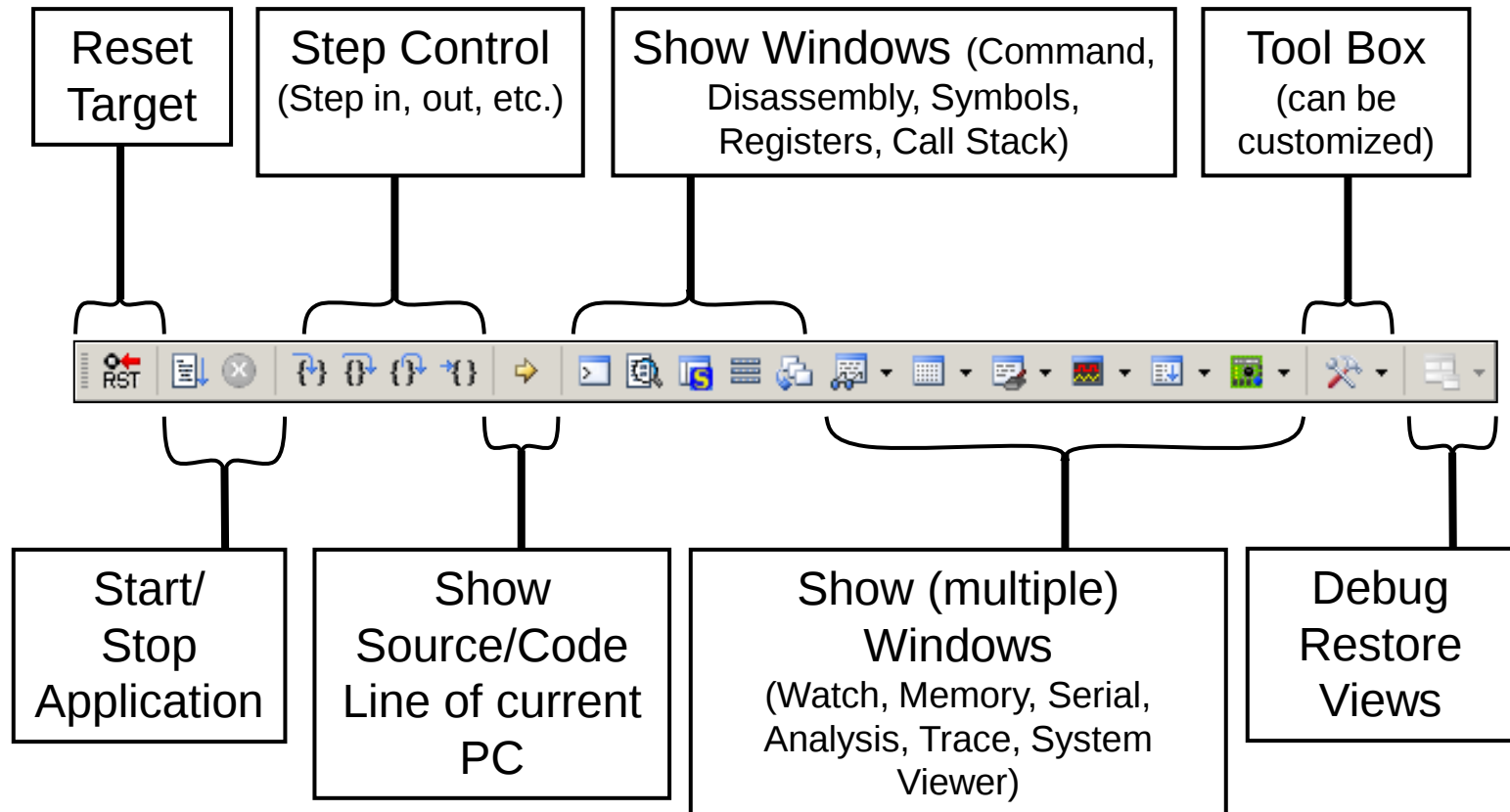


■ Start Debugging

- Download to target first, when MCU Flash does not contain the current application openend and built in the IDE
 - ◆ Use Download Icon () or Menu: Flash→Download
- Start Debug Session
 - ◆ Use Start/Stop Debug Icon () or Menu: Debug→Start/Stop Debug Session
- Ending Debug Session
 - ◆ Use same way as for starting debug session

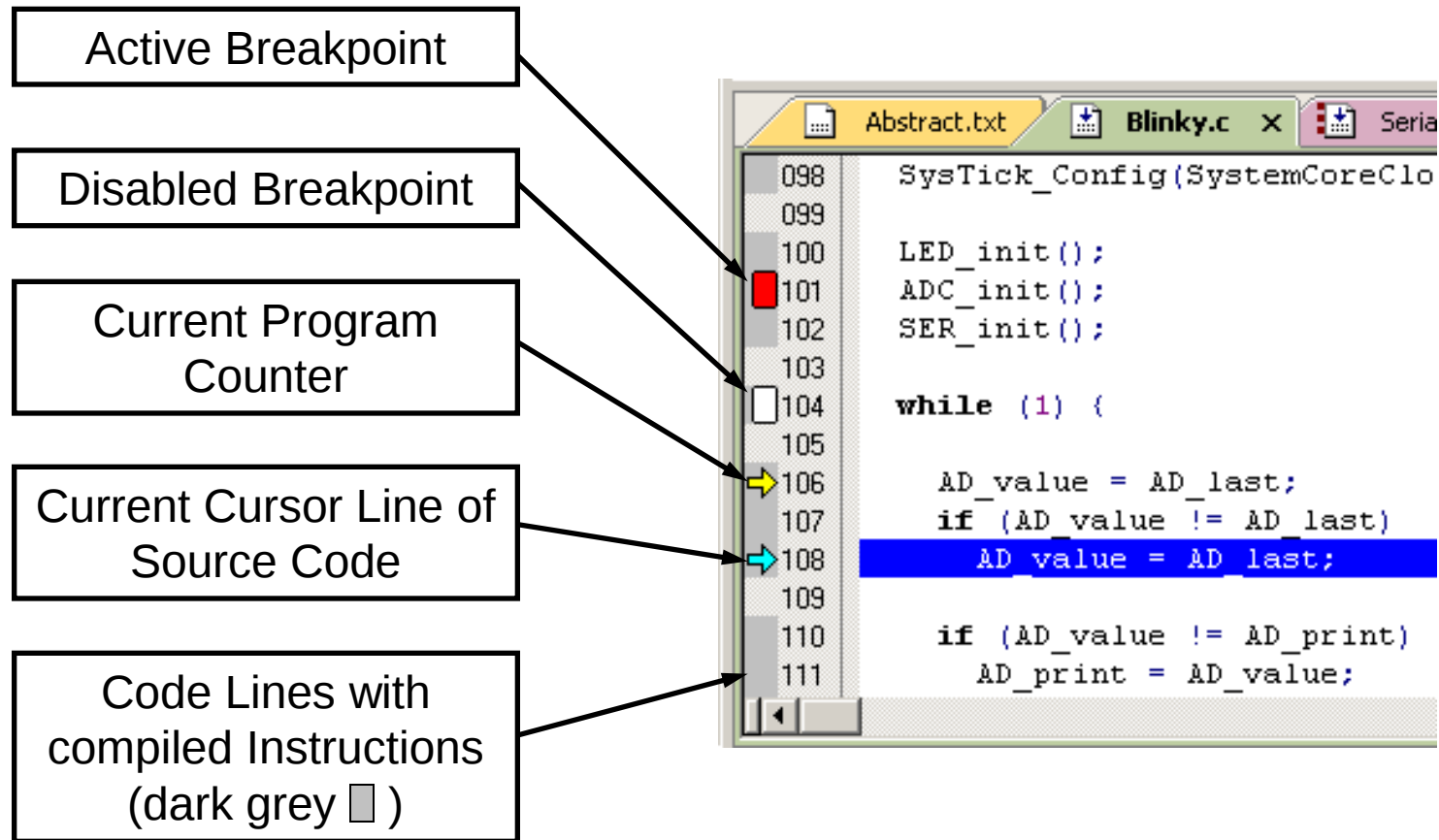
■ Debugging Icon Bar

- During a Debug Session there will be visible a new icon bar



■ Source View

- The Source windows do not change contents but get additional information



- Disassembly View
 - Mixed mode is selectable and deselectable

The screenshot shows the Disassembly View window in KEIL µVision. The window title is "Disassembly". The code is displayed in a list format with addresses, hex values, mnemonics, and comments. The current program counter is at 0x00000438, and the current cursor line is highlighted in yellow.

Annotations on the left side of the screenshot:

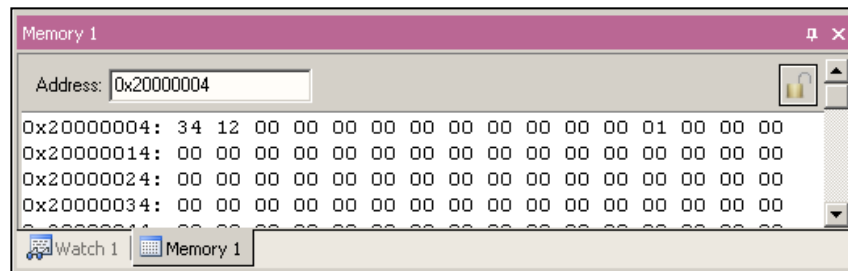
- Active Breakpoint:** Points to the red square icon next to address 0x0000042E.
- Disabled Breakpoint:** Points to the white square icon next to address 0x00000436.
- Current Program Counter:** Points to the address 0x00000438.
- Current Cursor Line of Code highlighted in yellow background (■):** Points to the line of code at address 0x00000438.

Disassembly View Content:

```
0x0000042A F7FFFA3 BL.W LED_i
101: ADC_init();
0x0000042E F7FFF67 BL.W ADC_i
102: SER_init();
103:
0x00000432 F000F8AE BL.W SER_i
104: while (1) {
105:
0x00000436 E015 B 0x0000
106: AD_value = AD_last;
0x00000438 4816 LDR r0,[p
0x0000043A 8804 LDRH r4,[r
107: if (AD_value != AD_last
```

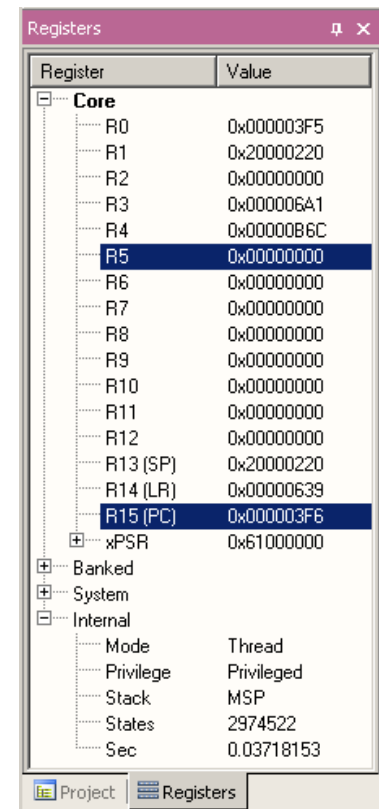
■ Memory Window

- Up to 4 Memory windows can be displayed in tabs
- Memory is updated during runtime
- Memory window tabs are shared with Watch windows



■ Register View

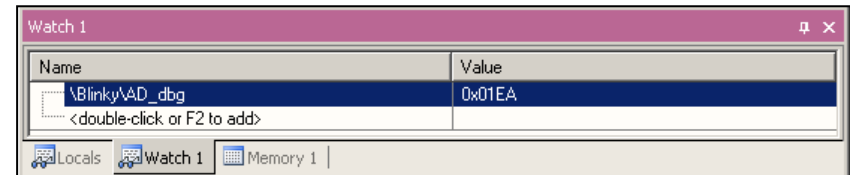
- Register view is a tab of the Project window
- Changes are highlighted in dark blue text background
- Register tree knots can be expanded



■ Variable Windows

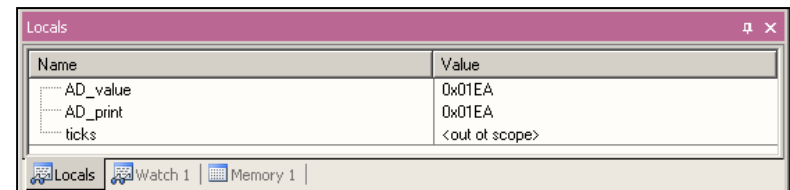
– Watch Windows

- ◆ Up to 2 Watch windows are sharing their tabs with e.g. Memory and Local views
- ◆ Updated during runtime
- ◆ Any changes are highlighted in dark blue text background color
- ◆ Displayed values can be changed by user during break



– Local View

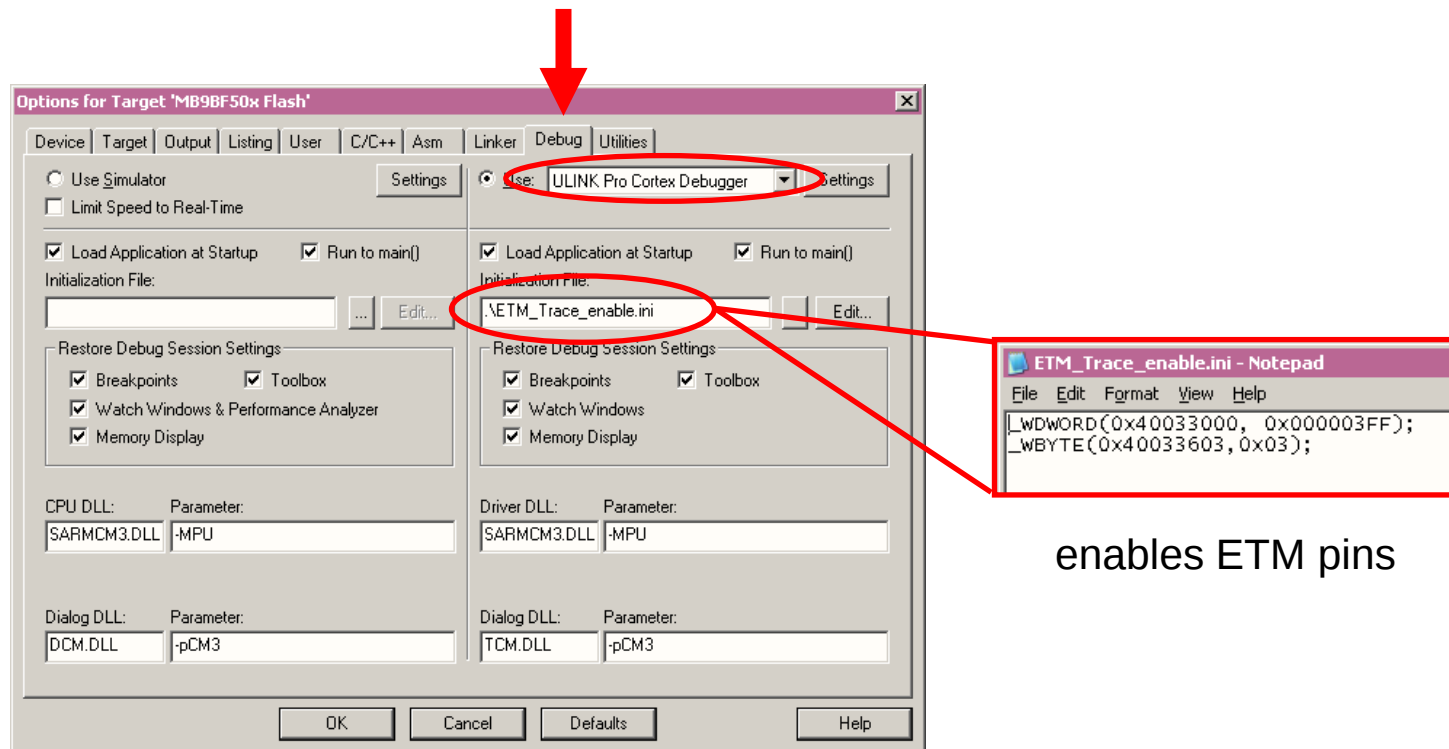
- ◆ The local view shares the tab with e.g. Memory and Watch windows
- ◆ Any changes are highlighted in dark blue text background color
- ◆ Displayed values can be changed by user during break



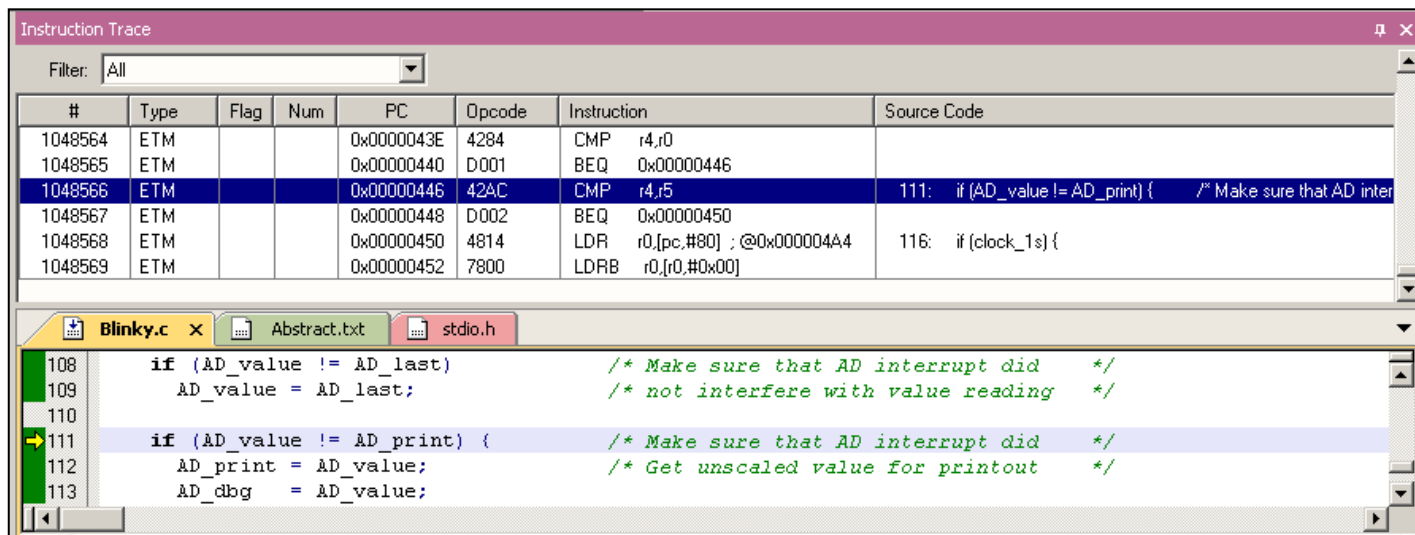
- Trace via ITM
 - Simple Trace views via Instrumentation Trace Macro is supported by μ LINK ME
 - Records
 - Exceptions
 - Counters

Type	Dly	Num	Address	Data	PC	Dly	Cycles	Time[s]
ITM		0	41H				82975148	1.03718935
ITM		0	44H				82975293	1.03719116
ITM		0	20H			X	82988592	1.03735740
ITM		0	76H			X	82988592	1.03735740
ITM		0	61H			X	82988592	1.03735740
ITM		0	6CH			X	82988592	1.03735740
ITM		0	75H			X	82988592	1.03735740
ITM		0	65H			X	82988592	1.03735740
ITM		0	20H			X	82988592	1.03735740
ITM		0	3DH			X	82988592	1.03735740
ITM		0	20H			X	82988592	1.03735740
ITM		0	30H			X	82988592	1.03735740
ITM		0	78H			X	82988592	1.03735740
ITM		0	30H				82993831	1.03742289
ITM		0	31H			X	83001392	1.03751740
ITM		0	45H			X	83001392	1.03751740
ITM		0	42H			X	83001392	1.03751740
ITM		0	0DH			X	83001392	1.03751740
ITM		0	04H			X	83001392	1.03751740
ITM		0	0DH			X	83001392	1.03751740

- Trace via ETM
 - Check settings in menu:
Flash→Configure Flash Tools... Tab:Debug

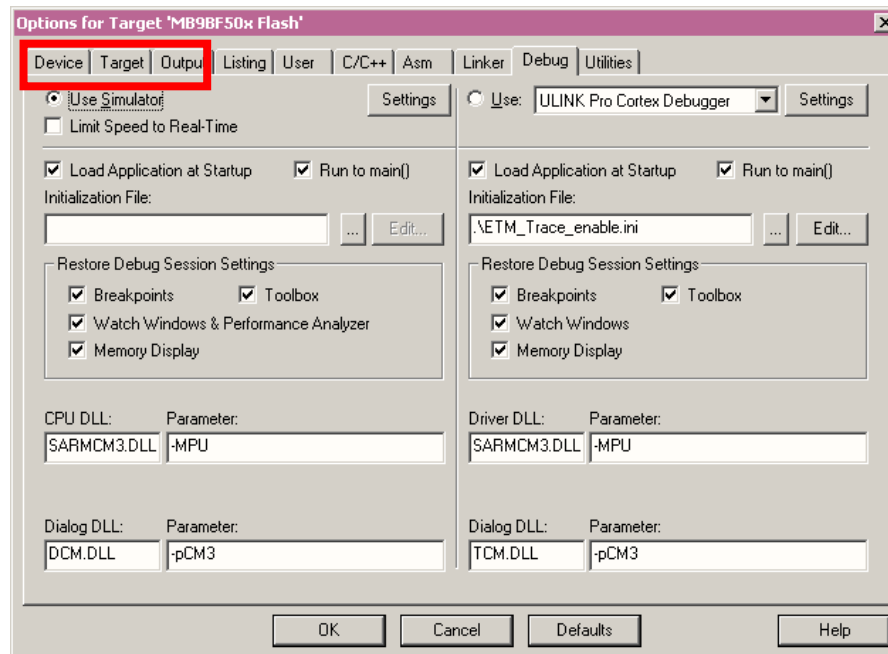


- Instruction Trace
 - Real Time Trace recording
 - Output can be filtered by several ETM and ITM events
 - Trace buffer is held in PC memory and transferred to μ Vision on break



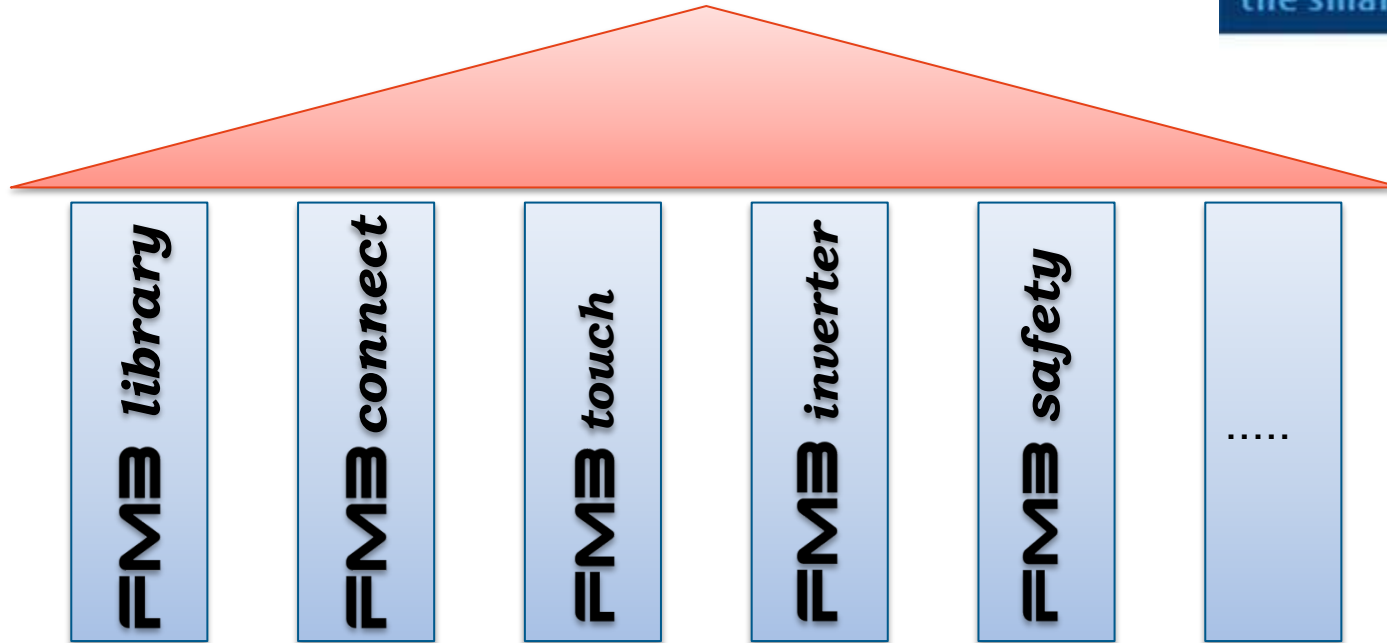
■ Simulator

- The Core Simulator can be selected by the menu:
[Flash] → [Configure Flash Tools...] → [Debug]
and then choosing [Use Simulator]
- Look & feel is like using ULINK debugger
- Controlable also with *.ini files



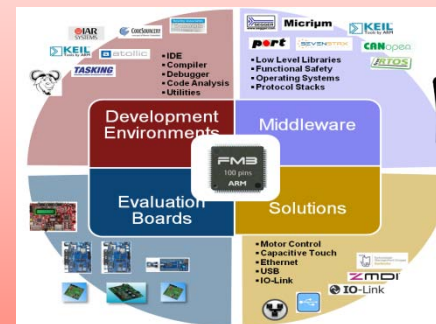
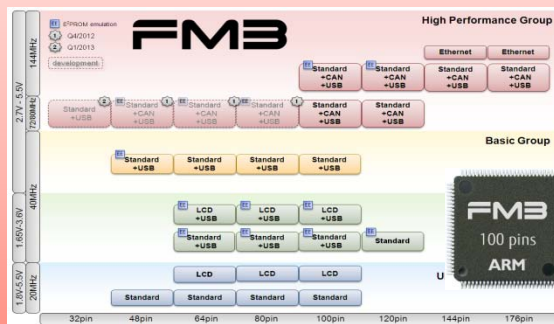


Solutions



Products

Eco system



■ FM3 Low Level Library (L3)

- CMSIS compliant header files
- Driver collection to supports MCU peripherals
- Hardware abstraction layer offers an API
- Interrupt handling supported
- Optimized memory use
 - ◆ For unused resources, no memory for library code is allocated

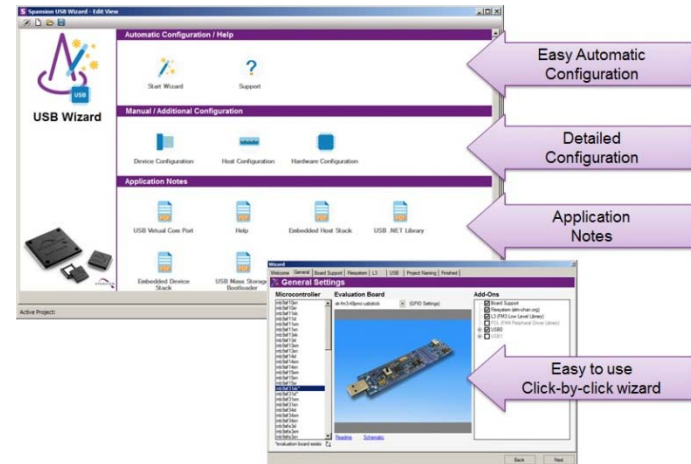


■ Supported Modules

- ADC (A/D-Converter), BT (Base Timer), CAN, CRC, CLK , CRTRIM (CR Clock Trimming), CSV (Clock Supervisor) , DAC (D/A-Converter), DMA, DSM (Deep Standby Modes), DT (Dual Timer), EXINT (External Interrupts), EXTIF (External Bus Interface), FLASH, GPIO, LVD (Low Voltage Detection), MFS (Multi Function Serial: UART, SPI, I2C, LIN), MFT (Multi Function Timer), QPRC (Quadrature Encoding), RESET (Reset Cause), RTC (Real Time Clock), USB (Host and Device) , WC (Watch Counter), WDG (Watchdog: SW, HW), ..., and more.

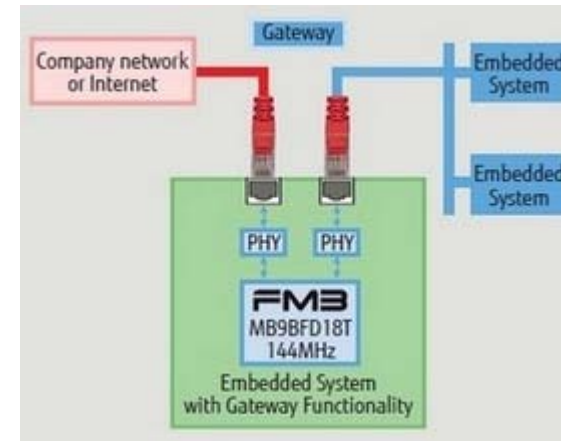
■ FMconnect USB

- Up to two USB interfaces
 - ◆ Supports Host/Device/OTG
 - ◆ Control, interrupt, bulk, isochronous
- Free software examples
- Spansion USB Wizard (PC based GUI):
 - ◆ USB driver configuration
 - ◆ Easy creation of USB descriptors
 - ◆ Code injection in existing projects



■ FMconnect Ethernet

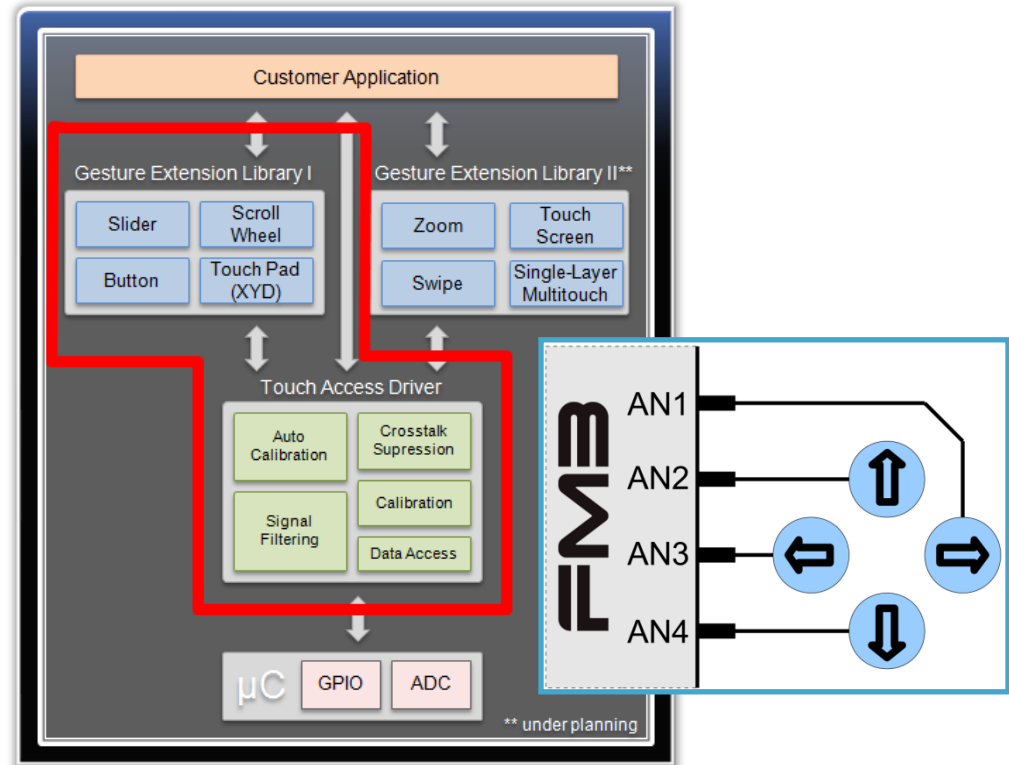
- One or two channels Ethernet MAC
- Dedicated Ethernet starter kit
- Free Ethernet software:
 - ◆ Low level driver available
 - ◆ TCP/IP stack available
 - ◆ Software examples, e.g.: web server
- Commercial products from partners



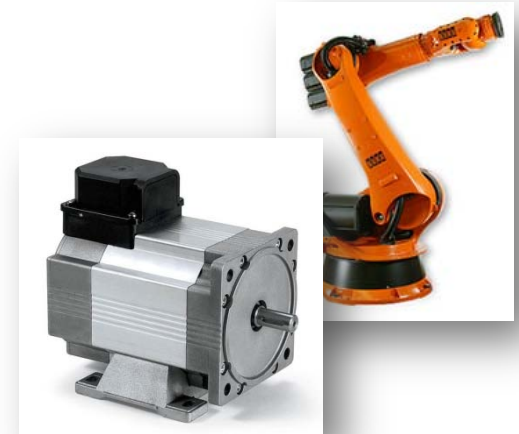
FM3 touch

- Software FM3touch library

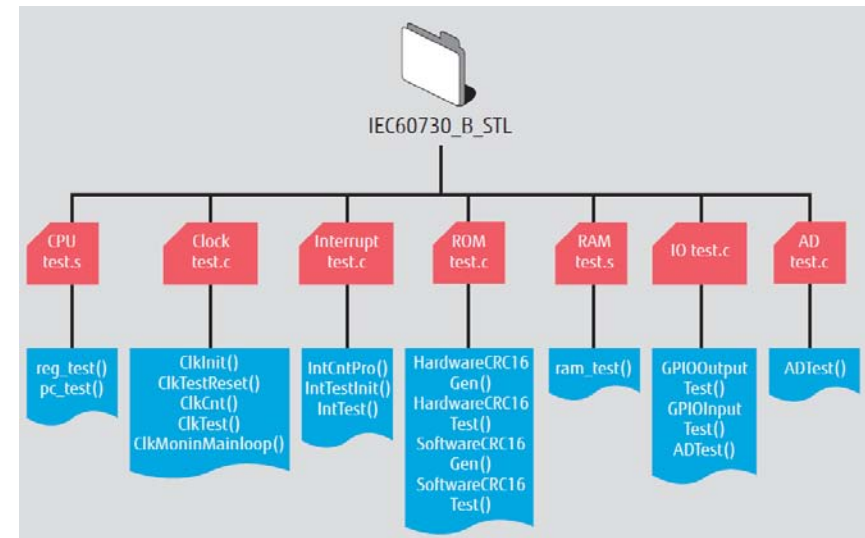
- Works on all FM3 derivatives, user can freely choose best-fitting FM3 MCU and add touch functionality
- No external components
- Only one pin (ADC channel) per touch input
- High sensitivity (<10fF)
- Low resource usage, no 'atomic' handling required
- Flexible configuration and event system for easy integration
- Configuration tool included
- Free of charge (basic variant)



- FM3 inverter drive hardware features
 - Up to 3 ch flexible 3-phase motor timers, automatic dead time insertion
 - Up to 3 ch independent 12-bit 1Msps ADCs, up to 32 ADC inputs
 - Up to 3 ch ABZ quadrature decoder units
 - DTTI input for motor emergency stop
 - 3.3V and true 5V single supply guarantees robustness
- FM3 software motor control library
 - Support for BLDC, PMSM, IPM and ACIM
 - Field oriented control
 - Support for encoder or hall sensor feedback, or sensorless application



- FM3 functional safety hardware features
 - Two stage watchdog with independent clock source
 - Clock supervisor (clock failure and abnormal frequency detection)
 - On-Chip Low Voltage Detector
 - CRC hardware module
 - MPU (Memory Protection Unit)
 - DTTI input for motor emergency stop
- IEC60730 Class B
 - Self-Test Library available
 - CPU test
 - Clock test
 - Interrupt test
 - Memory test
 - I/O test
 - A/D converter test





Finally



FM Seminar	Motor Control	USB Workshop	Ethernet Workshop
Please register here: http://news.spansion.com/seminars			
• Overview FM family • Memory • Peripheral resources • Packages • Processor architecture • Bus structure • Flash memory • Flash programming • Peripheral resources • Clock distribution • Timer • Interfaces • FM features • Development tool chains • IAR workbench / J-Link • KEIL µVision / uLink • Starter Kits • Practical exercises • Flash programming • Project setup/modification • Debugging • External interrupts	• Introduction of Spansion MCU • Line-Up of microcontrollers with motion control features • Performance • Introduction of motors types • ACIM • BLDC • PMSM • Introduction of control types • Sinusoidal commutation • Field Orientated Control • Space Vector Modulation • Peripherals of FM3/FM4 MCUs • Base Timer • Multifunction Timer • 12-bit A/D Converter • Quadrature Position and Revolution Counter • Interrupt Controller • Hands-on exercise / SW-Example • BLDC motor with hall sensor • PMSM motor with field orientated control	• Introduction of Spansion MCU • Line-op of USB MCUs • USB vs. RS232 • Historical Background • Electrical Layer • USB Protocol • Enumeration Process (Descriptors & USB Settings) • Transfer Types • Data Transfers • USB Class Concept • Software Driver Concepts • USB Host • USB Examples • Virtual COM Port • USB Descriptor Manager • Create Template Classes • Create Descriptors • PC software based on LibUSB • Special Use Cases • e.g. boot loader	• Introduction of Spansion MCU • Line-op of Ethernet MCUs • Fundamentals of Ethernet • Ethernet Microcontrollers • Hardware Design considerations • Software Design considerations • Communication layer models • The Internet Protocol suite • Web technologies in embedded systems • Developing Ethernet applications • Tools and methods • Practical hints and advice on FM3 Ethernet solutions • Hands-on training

- Please check the following website, for any available updates

www.spansion.com

www.spansion.com/starterkit

- Please contact your local support team for any technical question

America: Spansion.Solutions@Spansion.com

China: mcu-ticket-cn@spansion.com

Europe: mcu-ticket-de@spansion.com

Japan: mcu-ticket-jp@spansion.com

Other: <http://www.spansion.com/Support/SES/Pages/Ask-Spansion.aspx>

- Gültig für EU-Länder:

- Gemäß der Europäischen WEEE-Richtlinie und deren Umsetzung in landesspezifische Gesetze nehmen wir dieses Gerät wieder zurück.
- Zur Entsorgung schicken Sie das Gerät bitte an die folgende Adresse:

- Valid for European Union Countries:

- According to the European WEEE-Directive and its implementation into national laws we take this device back.
- For disposal please send the device to the following address:



CCS Express GMBH
c/o Spansion International Inc.
Frankfurter Str. 83-107
D-65479 Raunheim
Germany



- This board is compliant with China RoHS



www.spansion.com

Spancion®, the Spancion logo, MirrorBit®, MirrorBit® Eclipse™ and combinations thereof are trademarks and registered trademarks of Spancion LLC in the United States and other countries. Other names used are for informational purposes only and may be trademarks of their respective owners.

This document is for informational purposes only and subject to change without notice. Spancion does not represent that it is complete, accurate or up-to-date; it is provided "AS IS." To the maximum extent permitted by law, Spancion disclaims any liability for loss or damages arising from use of or reliance on this document.