

LPY550AL

MEMS motion sensor:

dual axis pitch and yaw ±500°/s analog output gyroscope

Features

- 2.7 V to 3.6 V single supply operation
- Very extended operating temperature range (-40°C to +85°C)
- High stability overtemperature
- Absolute analog rate output
- Two separate outputs for each axis (1x and 4x amplified)
- Integrated low-pass filters
- Low power consumption
- Embedded power-down
- Embedded self-test
- High shock and vibration survivability
- ECOPACK[®] RoHS and "Green" compliant (see *Section 5*)

Applications

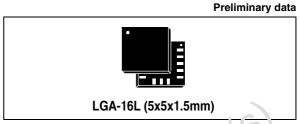
- Pointing devices, remote and veme controllers
- Gaming applications
- Motion control with use: interface
- Industrial and robotics

Description

change without notice.

The PY550AL is a low-power two-axis nic romachined gyroscope able to measure angular rate along pitch and yaw axes.

It provides excellent temperature stability and high resolution over extended operating temperature range (-40°C to +85°C).



The LPY550AL has a full scale of ± 500 % and is capable of detecting rates with a \lesssim dB bandwidth up to 140 Hz.

The gyroscope is the combination of one actuator and one acceleromater integrated in a single micromachined structure.

It includes a sensing element composed by single driving mass, kept in continuos oscillating mosement and able to react when an angular rate is applied based on the Coriolis principle.

A CMOS IC provides the measured angular rate to the external world through an analog output voltage, allowing high level of integration and production trimming to better match sensing element characteristics.

ST gyroscope family leverages on robust and mature manufacturing process already used for the production of micromachined accelerometers.

ST is already in the field with several hundreds million sensors with excellent acceptance from the market in terms of quality, reliability and performance.

LPY550AL is provided in plastic land grid array (LGA) package. Several years ago ST pioneered successfully the usage of this package for accelerometers. Today ST has the widest manufacturing capability and strongest expertise in the world for production of sensor in plastic LGA package.

Table 1. Device summary

Order code	Temperature range (°C)	Package	Packing
LPY550AL	-40 to +85	LGA-16 (5x5x1.5)	Tray
LPY550ALTR	-40 to +85	LGA-16 (5x5x1.5)	Tape and reel

July 2009 Doc ID 15808 Rev 2 1/12

This is preliminary information on a new product now in development or undergoing evaluation. Details are subject to

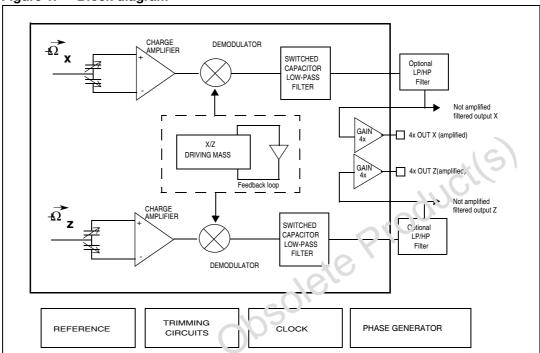
Contents

1	Bloc	Block diagram and pin description				
	1.1	Pin description				
2	Mec	hanical and electrical specifications5				
	2.1	Mechanical characteristics				
	2.2	Electrical characteristics 6				
	2.3	Absolute maximum ratings 6				
3	Tern	ninology				
	3.1	Sensitivity				
	3.2	Sensitivity				
	3.3	Self-test				
	3.4	High pass filter reset (HP)				
4	Арр	lication hints 8				
	4.1	Output response vs. rotaiion 9				
	4.2	Soldering information				
5	Pack	kage information 10				
6		is on history				
	ete					
0050						



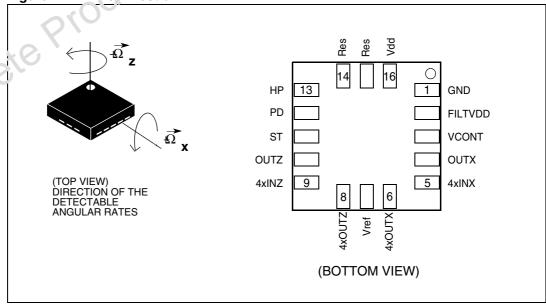
1 Block diagram and pin description

Figure 1. Block diagram



1.1 Pin description

Figure 2. Pin connection



57

Table 2. Pin description

Pin # Pin name Analog function	Table 2.	riii description	
2 FILTVDD PLL filter connection pin #2 3 VCONT PLL filter connection pin #1 4 OUTX Not amplified output 5 4xINX Input of 4x amplifier 6 4xOUTX X rate signal output voltage (amplified) 7 Vref Reference voltage 8 4xOUTZ Z rate signal output voltage (amplified) 9 4xINZ Input of 4x amplifier 10 OUTZ Not amplified output 11 ST Self-test (logic 0: normal mode, logic 1: self-test) 12 PD Power-down (logic 0: normal mode; logic 1: power-down mode) 13 HP High pass filter recet (logic 0: normal operation mode; logic1: external high pass filter is reset) 14,15 Res Secret d. Connect to Vdd	Pin #	Pin name	Analog function
3 VCONT PLL filter connection pin #1 4 OUTX Not amplified output 5 4xINX Input of 4x amplifier 6 4xOUTX X rate signal output voltage (amplified) 7 Vref Reference voltage 8 4xOUTZ Z rate signal output voltage (amplified) 9 4xINZ Input of 4x amplifier 10 OUTZ Not amplified output 11 ST Self-test (logic 0: normal mode, logic 1: self-test) 12 PD Power-down (logic 0: normal mode; logic 1: power-down mode) 13 HP High pass filter reset (logic 0: normal operation mode; logic1: external high pass filter is reset) 14,15 Res Res Connect to Vdd	1	GND	0V supply voltage
4 OUTX Not amplified output 5 4xINX Input of 4x amplifier 6 4xOUTX X rate signal output voltage (amplified) 7 Vref Reference voltage 8 4xOUTZ Z rate signal output voltage (amplified) 9 4xINZ Input of 4x amplifier 10 OUTZ Not amplified output 11 ST Self-test (logic 0: normal mode, logic 1: self-test) 12 PD Power-down (logic 0: normal mode; logic 1: power-down mode) 13 HP High pass filter recet (logic 0: normal operation mode; logic1: externer, high pass filter is reset) 14,15 Res Frederick Connect to Vdd	2	FILTVDD	PLL filter connection pin #2
Self-test (logic 0: normal mode; logic 1: power-down mode) HP High pass filter recet (logic 0: normal operation mode; logic1: externer, high pass filter is reset) He Ferved. Connect to Vdd Camplifier Hand of 4x amplifier Hand of 4x ampl	3	VCONT	PLL filter connection pin #1
6 4xOUTX X rate signal output voltage (amplified) 7 Vref Reference voltage 8 4xOUTZ Z rate signal output voltage (amplified) 9 4xINZ Input of 4x amplifier 10 OUTZ Not amplified output 11 ST Self-test (logic 0: normal mode, logic 1: self-test) 12 PD Power-down (logic 0: normal mode; logic 1: power-down mode) 13 HP High pass filter reset (logic 0: normal operation mode; logic1: extense high pass filter is reset) 14,15 Res Treceived. Connect to Vdd	4	OUTX	Not amplified output
7 Vref Reference voltage 8 4xOUTZ Z rate signal output voltage (amplified) 9 4xINZ Input of 4x amplifier 10 OUTZ Not amplified output 11 ST Self-test (logic 0: normal mode, logic 1: self-test) 12 PD Power-down (logic 0: normal mode; logic 1: power-down mode) 13 HP High pass filter reset (logic 0: normal operation mode; logic1: extense high pass filter is reset) 14,15 Res Tese ved. Connect to Vdd	5	4xINX	Input of 4x amplifier
8 4xOUTZ Z rate signal output voltage (amplified) 9 4xINZ Input of 4x amplifier 10 OUTZ Not amplified output 11 ST Self-test (logic 0: normal mode, logic 1: self-test) 12 PD Power-down (logic 0: normal mode; logic 1: power-down mode) 13 HP High pass filter recet (logic 0: normal operation mode; logic1: extense high pass filter is reset) 14,15 Res Served. Connect to Vdd	6	4xOUTX	X rate signal output voltage (amplified)
9 4xINZ Input of 4x amplifier 10 OUTZ Not amplified output 11 ST Self-test (logic 0: normal mode, logic 1: self-test) 12 PD Power-down (logic 0: normal mode; logic 1: power-down mode) 13 HP High pass filter recet (logic 0: normal operation mode; logic1: external high pass filter is reset) 14,15 Res Seeved. Connect to Vdd	7	Vref	Reference voltage
10 OUTZ Not amplified output 11 ST Self-test (logic 0: normal mode, logic 1: self-test) 12 PD Power-down (logic 0: normal mode; logic 1: power-down mode) 13 HP High pass filter recet (logic 0: normal operation mode; logic1: external high pass filter is reset) 14,15 Res Sees veld. Connect to Vdd	8	4xOUTZ	Z rate signal output voltage (amplified)
11 ST Self-test (logic 0: normal mode, logic 1: self-test) 12 PD Power-down (logic 0: normal mode; logic 1: power-down mode) 13 HP High pass filter recet (logic 0: normal operation mode; logic1: external high pass filter is reset) 14,15 Res Theorem Connect to Vdd	9	4xINZ	Input of 4x amplifier
Power-down (logic 0: normal mode; logic 1: power-down mode) High pass filter recet (logic 0: normal operation mode; logic1: external high pass filter is reset) 14,15 Res Trecerved. Connect to Vdd	10	OUTZ	Not amplified output
mode) High pass filter recet (logic 0: normal operation mode; logic1: externer high pass filter is reset) 14,15 Res Trecerved. Connect to Vdd	11	ST	Self-test (logic 0: normal moc'e, logic 1: self-test)
logic1: externer high pass filter is reset) 14,15 Res Served. Connect to Vdd	12	PD	Power-down (logic 0: norma' mode; logic 1: power-down mode)
	13	HP	
16 Vdd Fower supply	14,15	Res	⊼ecerv∉d. Connect to Vdd
Productisi	16	Vdd	Fower supply
	P'	oduci(s)	

2 Mechanical and electrical specifications

2.1 Mechanical characteristics

Table 3. Mechanical characteristics @ Vdd = 3 V, T = 25 °C unless otherwise noted⁽¹⁾

Symbol	Parameter	Test condition	Min.	Typ. ⁽²⁾	Max.	Unit
FSA	Measurement range	4x OUT (amplified)		±500		°/s
FS	weasurement range	OUT (not amplified)		±2000		°/s
SoA	Sensitivity ⁽³⁾	4x OUT (amplified)		2		mV/ °/s
So	Sensitivity ·	OUT (not amplified)		0.5		ກV/ °/s
SoDr	Sensitivity change vs temperature	Delta from 25°C		0.037	,,,C ¹	%/°C
Voff	Zero-rate level ⁽³⁾			1.23	70,0	V
Vref	Reference voltage			1.23		V
OffDr	Zero-rate level change Vs temperature	Delta from 25°C	×	0.03		°/s/°C
NL	Non linearity	Best fit straight line	7/8	±1		% FS
BW	Bandwidth ⁽⁴⁾		60,	140		Hz
Rn	Rate noise density			0.059		°/s / √Hz
Тор	Operating temperature range		-40		+85	°C

^{1.} The product is factory calibrated at 3 V. The opera ional power supply range is specified in *Table 4*.

opsolete

5/

Doc ID 15808 Rev 2

^{2.} Typical specifications are not guaranter a

^{3.} Sensitivity and Zero-rate Offset are not ratiometric to supply voltage

^{4.} The product is capable of many ring angular rates extending from DC to the selected BW.

2.2 **Electrical characteristics**

Electrical characteristics @ Vdd =3 V, T=25 °C unless otherwise noted(1) Table 4.

Symbol	Parameter	Test condition	Min.	Typ. ⁽²⁾	Max.	Unit	
Vdd	Supply voltage		2.7	3	3.6	V	
ldd	Supply current	PD pin connected to GND		6.8		mA	
IddPdn	Supply current in power-down mode	PD pin connected to Vdd		1	5	μΑ	
Vst	Colf toot input	Logic 0 level	0		0.2*Vdd	V	
VSI	Self-test input	Logic 1 level	0.8*Vdd		Vdd		
VPD	Power-down input	Logic 0 level	0		0.2*\'מני	9	
VPD	Fower-down input	Logic 1 level	0.8*Vdd		\ <u>'dc</u>		
Тор	Operating temperature range		-40	010C	+85	°C	
1. The product is factory calibrated at 3 V							
2. Typical specifications are not guaranteed							
 The product is factory calibrated at 3 V Typical specifications are not guaranteed Absolute maximum ratings 							

^{1.} The product is factory calibrated at 3 V

Absolute maximum ratings 2.3

Stresses above those listed as "Abso ute maximum ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device under these conditions is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

Table 5. Absolute maximum ratings

	Symbol	Ratings	Maximum value	Unit
	Vdd	Supply voltage	-0.3 to 6	V
	√in	Input voltage on any control pin (PD, ST)	-0.3 to Vdd +0.3	V
	T _{STG}	Storage temperature range	-40 to +125	°C
Obso	Α	Acceleration)	3000 g for 0.5 ms	
	_ ^	Acceleration)	10000 g for 0.1 ms	
	ESD	Electrostatic discharge protection	2 (HBM)	kV



This is a mechanical shock sensitive device, improper handling can cause permanent damage to the part



This is an ESD sensitive device, improper handling can cause permanent damage to the part

577 Doc ID 15808 Rev 2 6/12

^{2.} Typical specifications are not guaranteed

LPY550AL Terminology

3 Terminology

3.1 Sensitivity

An angular rate gyroscope is a device that produces a positive-going output voltage for counterclockwise rotation around the sensible axis considered. Sensitivity describes the gain of the sensor and can be determined by applying a defined angular velocity to it. This value changes very little over temperature and time.

3.2 Zero-rate level

Zero-rate level describes the actual output signal if there is no angular rate present. Zero-rate level of precise MEMS sensors is, to some extent, a result of stress to the sensor and therefore zero-rate level can slightly change after mounting the sensor onto a printed circuit board or after exposing it to extensive mechanical stress. This value changes very little over temperature and time.

3.3 Self-test

Self-test allows testing the mechanical and electrical part of the sensor, allowing the seismic mass to be moved by means of an electrostatic test-force. The self-test function is off when the ST pin is connected to GND. When the ST pin is tied to Vdd, an actuation force is applied to the sensor, emulating a definite Coriolis force. In this case the sensor output will exhibit a voltage change in its DC level which is also dependent on the supply voltage. When ST is active, the device output level is given by the algebraic sum of the signals produced by the velocity acting on the sensor and by the electrostatic test-force. If the output signals change within the amplitude specified in *Table 3*, then the mechanical element is working properly and the parameters of the interface chip are within the defined specification

3.4 Yoh pass filter reset (HP)

LPY550AL provides the possibility to reset the optional external high pass filter by applying high logic value to HP pad. This procedure ensures faster response expecially during overload conditions. Moreover, this operation is suggested each time the device is powered.

Application hints LPY550AL

4 Application hints

C2 10nF GND GND Vdd 10kOhm 470nF R1 100 nF 10 uF C1 (TOP VIEW) DIRECTION OF THE DETECTABLE ANGULAR RATES 1161 | 11141 GND <u>13</u> HP LPY550AL Not amplified Not amplified filtered output Z filtered output X (Top View) ú 5 1611 118 R1 GND GND Vref Recomended Optional Vref Low-pass filter High-pass filter Typical values: R1 = 1MOhm C1 = 4.7 uF R2 = 33kOhmC2 = 2.2nF to 2.2uF

Figure 3. LPY550AL electrical connections and external components values

Power supply decoupling capacitors (100 nF ceramic or polyester + 10 µF Aluminum) should be placed as near as possible to the device (common design practice).

The LFY 550AL allows band limiting the output rate response through the use of an external low pass filter (suggested) and/or high pass filter (optional) in addition to the embedded low pass filter ($f_t = 140 \text{ Hz}$).

*xOUTX and 4xOUTZ are respectively OUTX and OUTZ amplified outputs lines, internally buffered to ensure low output impedance.

If external high pass or low pass filtering is not applied it is mandatory to short-circuit respectively pad 4 to pad 5 and pad 9 to pad 10 when amplified outputs are used.

When only not-amplified outputs are used (OUTX/Z), it is suggested to set pads 5 and 9 to fixed reference voltage (Vref).

When high pass filter is applied to not amplified output (OUTx), it is recommended to buffer the line before entering ADC for performance optimization.

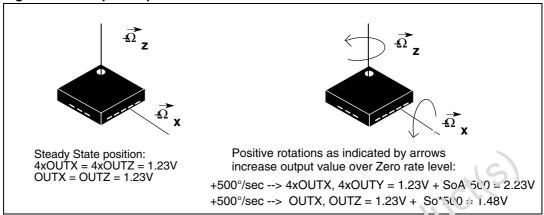
The LPY550AL IC includes a PLL (phase locked loop) circuit to synchronize driving and sensing interfaces. Capacitors and resistors must be added at **FILTVDD** and **VCONT** pins (as shown in *Figure 3*) to implement a low-pass filter.

577

LPY550AL Application hints

4.1 Output response vs. rotation

Figure 4. Output response vs. rotation



4.2 Soldering information

The LGA package is compliant with the ECOPACION TioHS and "Green" standard. It is qualified for soldering heat resistance ac profing to JEDEC J-STD-020C.

Leave "pin 1 indicator" unconnected (juri) g soldering.

Land pattern and soldering recommendations are available at www.st.com

Package information LPY550AL

5 Package information

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK[®] packages, depending on their level of environmental compliance. ECOPACK[®] specifications, grade definitions and product status are available at: www.st.com. ECOPACK[®] is an ST trademark.

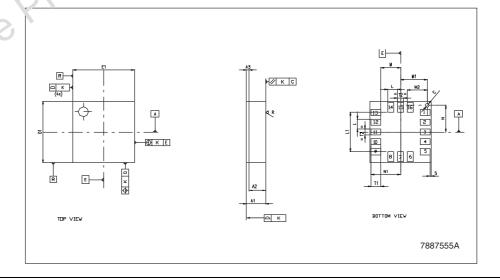
Figure 5. LGA-16: mechanical data and package dimensions

	Dimensions					
Ref.		mm	m		inch	
Kei.	Min.	Тур.	Max.	Min.	Тур.	Max.
A1	1.46	1.5	1.6	0.057	0.059	0.063
A2			1.33			0.052
А3	0.16	0.2	0.24	0.006	0.008	0.009
С		0.3			0.012	
D1	4.85	5	5.15	0.191	0.197	0.203
E1	4.85	5	5.15	0.191	0.197	0.203
L		0.8			0.031	
L1		3.2			0.126	
М		1.6			0.062	
M1	2.15	2.175	2.20	0.085	0.086	0.087
M2		1.625			0.064	
Ν		2.175			0.086	
N1		2.4			0.094	
T1		0.8			0.031	
T2	0.475	0.5	0.525	0.019	0.020	0.021
R	1.2		1.6	0 047		0.063
S		0.1			0.004	
h		0.15	5		0.006	
k		L OF			0.002	
- i		0.1			0.004	

Outline and mechanical data



LGA-16 (5x5x1.5mm) Land Grid Array Package



10/12 Doc ID 15808 Rev 2

LPY550AL Revision history

6 Revision history

Table 6. Document revision history

Date	Revision	Changes
04-Jun-2009	1	Initial release
06-Jul-2009	2	Small text changes to improve readability. Updated <i>Table 4</i>



Please Read Carefully:

Information in this document is provided solely in connection with ST products. STMicroelectronics NV and its subsidia, 'ea' ('ST") reserve the right to make changes, corrections, modifications or improvements, to this document, and the products and sen ices described herein at any time, without notice.

All ST products are sold pursuant to ST's terms and conditions of sale.

Purchasers are solely responsible for the choice, selection and use of the ST products and solvices described herein, and ST assumes no liability whatsoever relating to the choice, selection or use of the ST products and services described herein.

No license, express or implied, by estoppel or otherwise, to any intellectual property Liquis is granted under this document. If any part of this document refers to any third party products or services it shall not be deemed a license grant by ST for the use of such third party products or services, or any intellectual property contained therein or considered as a trainant covering the use in any manner whatsoever of such third party products or services or any intellectual property containe 2 to 3 in 3 in 3.

UNLESS OTHERWISE SET FORTH IN ST'S TERMS AND CONDITIONS OF SALE ST DISCLAIMS ANY EXPRESS OR IMPLIED WARRANTY WITH RESPECT TO THE USE AND OR SALE OF ST PRODUCTS INCLUDING WITHOUT LIMITATION IMPLIED WARRANTIES OF MERCHANTABILITY, FITNE'SE FOR A PARTICULAR PURPOSE (AND THEIR EQUIVALENTS UNDER THE LAWS OF ANY JURISDICTION), OR INFRINGEMENT OF ANY PATENT, COPYRIGHT OR OTHER INTELLECTUAL PROPERTY RIGHT.

UNLESS EXPRESSLY APPROVED IN VIRITING BY AN AUTHORIZED ST REPRESENTATIVE, ST PRODUCTS ARE NOT RECOMMENDED, AUTHORIZED OR WARRANTED FOR USE IN MILITARY, AIR CRAFT, SPACE, LIFE SAVING, OR LIFE SUSTAINING APPLICATIONS, NOR IN PRODUCT'S OR SYSTEMS WHERE FAILURE OR MALFUNCTION MAY RESULT IN PERSONAL INJURY, DEATH, OR SEVERE PF OP ENTY OR ENVIRONMENTAL DAMAGE. ST PRODUCTS WHICH ARE NOT SPECIFIED AS "AUTOMOTIVE GRADE" MAY ONLY BE USED IN AUTOMOTIVE APPLICATIONS AT USER'S OWN RISK.

Resale of S. p. or ucts with provisions different from the statements and/or technical features set forth in this document shall immediately void any war and granted by ST for the ST product or service described herein and shall not create or extend in any manner whatsoever, any liabi. To T.

ST and the ST logo are trademarks or registered trademarks of ST in various countries.

Information in this document supersedes and replaces all information previously supplied.

The ST logo is a registered trademark of STMicroelectronics. All other names are the property of their respective owners.

© 2009 STMicroelectronics - All rights reserved

STMicroelectronics group of companies

Australia - Belgium - Brazil - Canada - China - Czech Republic - Finland - France - Germany - Hong Kong - India - Israel - Italy - Japan - Malaysia - Malta - Morocco - Philippines - Singapore - Spain - Sweden - Switzerland - United Kingdom - United States of America

www.st.com

12/12 Doc ID 15808 Rev 2

