CY7C1440AV25
CY7C1446AV25

36-Mbit (1 M × 36/512 K × 72) Pipelined Sync SRAM

Features

- Supports bus operation up to 250 MHz
- Available speed grades are 250 and 167 MHz
- Registered inputs and outputs for pipelined operation
- 2.5 V core power supply
- 2.5 V power supply
- Fast clock-to-output times
  - 2.6 ns (for 250-MHz device)
- Provide high-performance 3-1-1-1 access rate
- User-selectable burst counter supporting Intel® Pentium® interleaved or linear burst sequences
- Separate processor and controller address strobes
- Synchronous self-timed writes
- Asynchronous output enable
- Single-cycle Chip Deselect
- CY7C1440AV25 available in Pb-free and non-Pb-free 165-ball FBGA package. CY7C1446AV25 available in non-Pb-free 209-ball FBGA package
- IEEE 1149.1 JTAG-Compatible Boundary Scan
- “ZZ” Sleep Mode Option

Functional Description

The CY7C1440AV25/CY7C1446AV25 SRAM integrates 1 M × 36/512 K × 72 SRAM cells with advanced synchronous peripheral circuitry and a two-bit counter for internal burst operation. All synchronous inputs are gated by registers controlled by a positive-edge-triggered Clock Input (CLK). The synchronous inputs include all addresses, all data inputs, address-pipelining Chip Enable ($\overline{CE_1}$), depth-expansion Chip Enables (CE_2 and $\overline{CE_3}$), Burst Control inputs (ADSC, ADSP, and ADV), Write Enables ($\overline{BW_X}$, and $\overline{BWE}$), and Global Write ($\overline{GW}$). Asynchronous inputs include the Output Enable ($\overline{OE}$) and the ZZ pin.

Addresses and chip enables are registered at rising edge of clock when either Address Strobe Processor (ADSP) or Address Strobe Controller ($\overline{ADSC}$) are active. Subsequent burst addresses can be internally generated as controlled by the Advance pin ($\overline{ADV}$).

Address, data inputs, and write controls are registered on-chip to initiate a self-timed Write cycle.This part supports Byte Write operations (see Pin Descriptions and Truth Table for further details). Write cycles can be one to two or four bytes wide as controlled by the byte write control inputs. $\overline{GW}$ when active LOW causes all bytes to be written.

The CY7C1440AV25/CY7C1446AV25 operates from a +2.5 V core power supply while all outputs may operate with a +2.5 V supply. All inputs and outputs are JEDEC-standard JESD8-5-compatible.

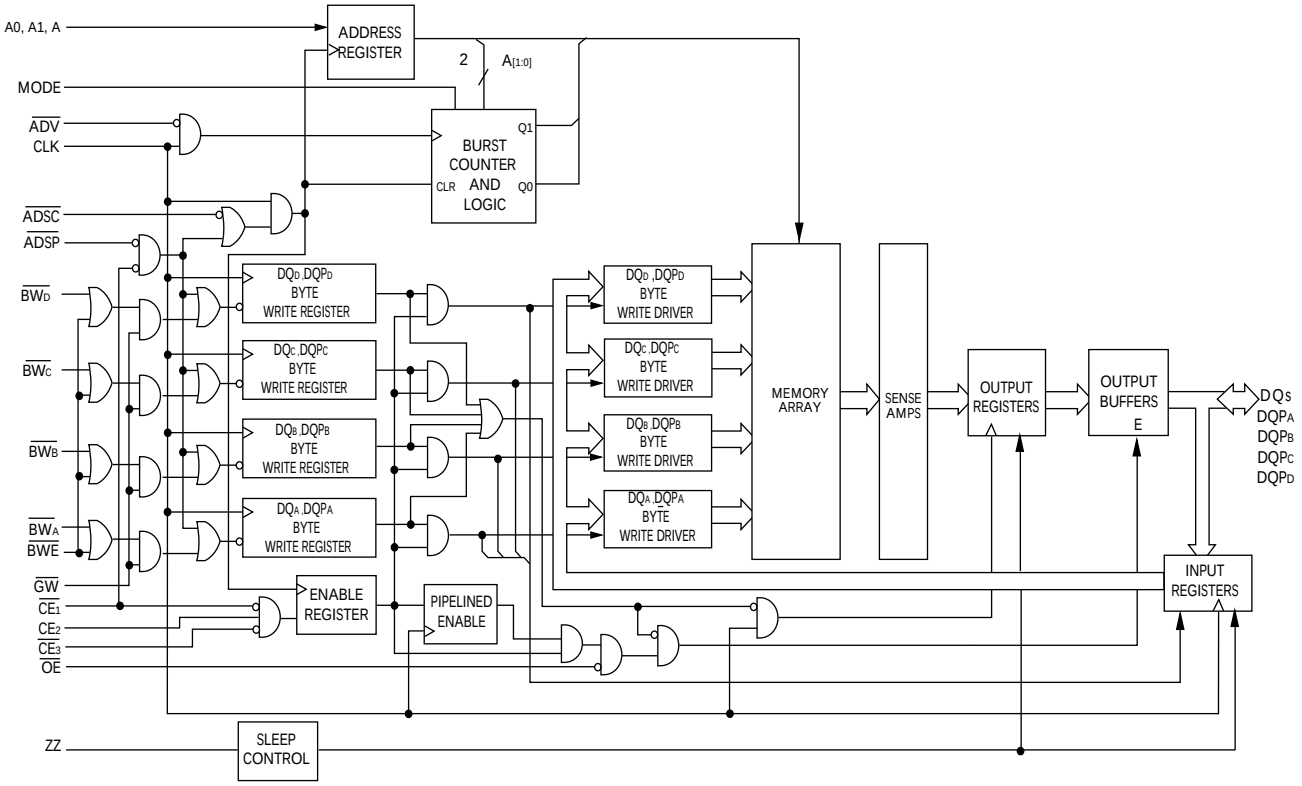
For a complete list of related documentation, click here.

Selection Guide

Description	250 MHz	167 MHz	Unit
Maximum Access Time	2.6	3.4	ns
Maximum Operating Current	435	335	mA
Maximum CMOS Standby Current	120	120	mA

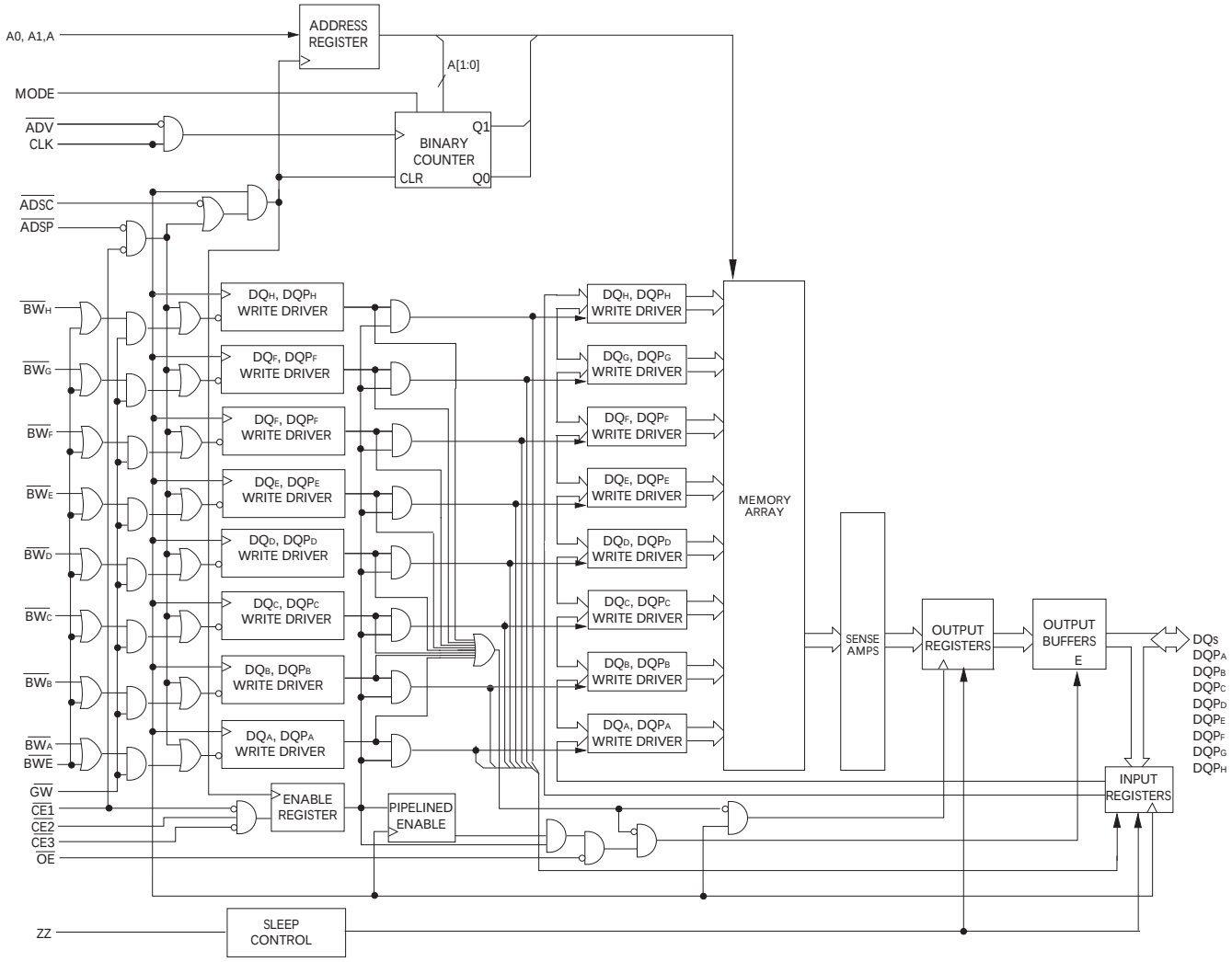
Downloaded from Arrow.com.

Logic Block Diagram – CY7C1440AV25



Downloaded from Arrow.com.

Logic Block Diagram – CY7C1446AV25



Downloaded from Arrow.com.

Contents

Pin Configurations **5**
Pin Definitions **7**
Functional Overview **8**
Single Read Accesses 8
Single Write Accesses Initiated by ADSP 8
Single Write Accesses Initiated by ADSC 9
Burst Sequences 9
Sleep Mode 9
Interleaved Burst Address Table 9
Linear Burst Address Table 9
ZZ Mode Electrical Characteristics 9
Truth Table **10**
Truth Table for Read/Write **11**
Truth Table for Read/Write **11**
IEEE 1149.1 Serial Boundary Scan (JTAG) **12**
Disabling the JTAG Feature 12
Test Access Port (TAP) 12
PERFORMING A TAP RESET 12
TAP REGISTERS 12
TAP Instruction Set 12
TAP Controller State Diagram **14**
TAP Controller Block Diagram **15**
TAP Timing **15**
TAP AC Switching Characteristics **16**
2.5 V TAP AC Test Conditions **17**
2.5 V TAP AC Output Load Equivalent **17**
TAP DC Electrical Characteristics and Operating Conditions **17**
Identification Register Definitions **18**
Scan Register Sizes **18**
Instruction Codes **18**
Boundary Scan Order **19**
Boundary Scan Order **20**
Maximum Ratings **21**
Operating Range **21**
Electrical Characteristics **21**
DC Electrical Characteristics 21
Capacitance **22**
Thermal Resistance **22**
AC Test Loads and Waveforms **22**
Switching Characteristics **23**
Switching Waveforms **24**
Ordering Information **28**
Ordering Code Definitions 28
Package Diagrams **29**
Acronyms **31**
Document Conventions **31**
Units of Measure 31
Document History Page **32**
Sales, Solutions, and Legal Information **33**
Worldwide Sales and Design Support 33
Products 33
PSoC® Solutions 33
Cypress Developer Community 33
Technical Support 33

Downloaded from Arrow.com.

Pin Configurations

Figure 1. 165-ball FBGA (15 × 17 × 1.4 mm) pinout

CY7C1440AV25 (1 M × 36)

	1	2	3	4	5	6	7	8	9	10	11
A	NC/288M	A	$\overline{CE}_1$	$\overline{BW}_C$	$\overline{BW}_B$	$\overline{CE}_3$	$\overline{BWE}$	$\overline{ADSC}$	$\overline{ADV}$	A	NC
B	NC/144M	A	CE2	$\overline{BW}_D$	$\overline{BW}_A$	CLK	$\overline{GW}$	$\overline{OE}$	$\overline{ADSP}$	A	NC/576M
C	DQP_C	NC	V_{DDQ}	V_{SS}	V_{SS}	V_{SS}	V_{SS}	V_{SS}	V_{DDQ}	NC/1G	DQP_B
D	DQ_C	DQ_C	V_{DDQ}	V_{DD}	V_{SS}	V_{SS}	V_{SS}	V_{DD}	V_{DDQ}	DQ_B	DQ_B
E	DQ_C	DQ_C	V_{DDQ}	V_{DD}	V_{SS}	V_{SS}	V_{SS}	V_{DD}	V_{DDQ}	DQ_B	DQ_B
F	DQ_C	DQ_C	V_{DDQ}	V_{DD}	V_{SS}	V_{SS}	V_{SS}	V_{DD}	V_{DDQ}	DQ_B	DQ_B
G	DQ_C	DQ_C	V_{DDQ}	V_{DD}	V_{SS}	V_{SS}	V_{SS}	V_{DD}	V_{DDQ}	DQ_B	DQ_B
H	NC	NC	NC	V_{DD}	V_{SS}	V_{SS}	V_{SS}	V_{DD}	NC	NC	ZZ
J	DQ_D	DQ_D	V_{DDQ}	V_{DD}	V_{SS}	V_{SS}	V_{SS}	V_{DD}	V_{DDQ}	DQ_A	DQ_A
K	DQ_D	DQ_D	V_{DDQ}	V_{DD}	V_{SS}	V_{SS}	V_{SS}	V_{DD}	V_{DDQ}	DQ_A	DQ_A
L	DQ_D	DQ_D	V_{DDQ}	V_{DD}	V_{SS}	V_{SS}	V_{SS}	V_{DD}	V_{DDQ}	DQ_A	DQ_A
M	DQ_D	DQ_D	V_{DDQ}	V_{DD}	V_{SS}	V_{SS}	V_{SS}	V_{DD}	V_{DDQ}	DQ_A	DQ_A
N	DQP_D	NC	V_{DDQ}	V_{SS}	NC	A	NC	V_{SS}	V_{DDQ}	NC	DQP_A
P	NC	NC/72M	A	A	TDI	A1	TDO	A	A	A	A
R	MODE	A	A	A	TMS	A0	TCK	A	A	A	A

Downloaded from Arrow.com.

Pin Configurations (continued)

Figure 2. 209-ball FBGA (14 × 22 × 1.76 mm) pinout

CY7C1446AV25 (512 K × 72)

	1	2	3	4	5	6	7	8	9	10	11
A	DQ_G	DQ_G	A	CE_2	$\overline{ADSP}$	$\overline{ADSC}$	$\overline{ADV}$	$\overline{CE}_3$	A	DQ_B	DQ_B
B	DQ_G	DQ_G	$\overline{BWS}_C$	$\overline{BWS}_G$	NC/288M	$\overline{BW}$	A	$\overline{BWS}_B$	$\overline{BWS}_F$	DQ_B	DQ_B
C	DQ_G	DQ_G	$\overline{BWS}_H$	$\overline{BWS}_D$	NC/144M	$\overline{CE}_1$	NC/576M	$\overline{BWS}_E$	$\overline{BWS}_A$	DQ_B	DQ_B
D	DQ_G	DQ_G	V_{SS}	NC	NC/1G	$\overline{OE}$	$\overline{GW}$	NC	V_{SS}	DQ_B	DQ_B
E	DQP_G	DQP_C	V_{DDQ}	V_{DDQ}	V_{DD}	V_{DD}	V_{DD}	V_{DDQ}	V_{DDQ}	DQP_F	DQP_B
F	DQ_C	DQ_C	V_{SS}	V_{SS}	V_{SS}	NC	V_{SS}	V_{SS}	V_{SS}	DQ_F	DQ_F
G	DQ_C	DQ_C	V_{DDQ}	V_{DDQ}	V_{DD}	NC	V_{DD}	V_{DDQ}	V_{DDQ}	DQ_F	DQ_F
H	DQ_C	DQ_C	V_{SS}	V_{SS}	V_{SS}	NC	V_{SS}	V_{SS}	V_{SS}	DQ_F	DQ_F
J	DQ_C	DQ_C	V_{DDQ}	V_{DDQ}	V_{DD}	NC	V_{DD}	V_{DDQ}	V_{DDQ}	DQ_F	DQ_F
K	NC	NC	CLK	NC	V_{SS}	V_{SS}	V_{SS}	NC	NC	NC	NC
L	DQ_H	DQ_H	V_{DDQ}	V_{DDQ}	V_{DD}	NC	V_{DD}	V_{DDQ}	V_{DDQ}	DQ_A	DQ_A
M	DQ_H	DQ_H	V_{SS}	V_{SS}	V_{SS}	NC	V_{SS}	V_{SS}	V_{SS}	DQ_A	DQ_A
N	DQ_H	DQ_H	V_{DDQ}	V_{DDQ}	V_{DD}	NC	V_{DD}	V_{DDQ}	V_{DDQ}	DQ_A	DQ_A
P	DQ_H	DQ_H	V_{SS}	V_{SS}	V_{SS}	ZZ	V_{SS}	V_{SS}	V_{SS}	DQ_A	DQ_A
R	DQP_D	DQP_H	V_{DDQ}	V_{DDQ}	V_{DD}	V_{DD}	V_{DD}	V_{DDQ}	V_{DDQ}	DQP_A	DQP_E
T	DQ_D	DQ_D	V_{SS}	NC	NC	MODE	NC	NC	V_{SS}	DQ_E	DQ_E
U	DQ_D	DQ_D	NC/72M	A	A	A	A	A	A	DQ_E	DQ_E
V	DQ_D	DQ_D	A	A	A	A1	A	A	A	DQ_E	DQ_E
W	DQ_D	DQ_D	TMS	TDI	A	A0	A	TDO	TCK	DQ_E	DQ_E

Downloaded from Arrow.com.

Pin Definitions

Name	I/O	Description
A_0, A_1, A	Input-Synchronous	**Address Inputs used to select one of the address locations**. Sampled at the rising edge of the CLK if ADSP or ADSC is active LOW, and $\overline{CE}_1$, CE_2, and $\overline{CE}_3$ are sampled active. A1:A0 are fed to the two-bit counter.
$\overline{BW}_A$, $\overline{BW}_B$, $\overline{BW}_C$, $\overline{BW}_D$, $\overline{BW}_E$, $\overline{BW}_F$, $\overline{BW}_G$, $\overline{BW}_H$	Input-Synchronous	**Byte Write Select Inputs, active LOW**. Qualified with $\overline{BWE}$ to conduct byte writes to the SRAM. Sampled on the rising edge of CLK.
$\overline{GW}$	Input-Synchronous	**Global Write Enable Input, active LOW**. When asserted LOW on the rising edge of CLK, a global write is conducted (ALL bytes are written, regardless of the values on BW_X and BWE).
$\overline{BWE}$	Input-Synchronous	**Byte Write Enable Input, active LOW**. Sampled on the rising edge of CLK. This signal must be asserted LOW to conduct a byte write.
CLK	Input-Clock	**Clock Input**. Used to capture all synchronous inputs to the device. Also used to increment the burst counter when $\overline{ADV}$ is asserted LOW, during a burst operation.
$\overline{CE}_1$	Input-Synchronous	**Chip Enable 1 Input, active LOW**. Sampled on the rising edge of CLK. Used in conjunction with CE_2 and $\overline{CE}_3$ to select/deselect the device. ADSP is ignored if $\overline{CE}_1$ is HIGH. $\overline{CE}_1$ is sampled only when a new external address is loaded.
CE_2	Input-Synchronous	**Chip Enable 2 Input, active HIGH**. Sampled on the rising edge of CLK. Used in conjunction with $\overline{CE}_1$ and $\overline{CE}_3$ to select/deselect the device. CE_2 is sampled only when a new external address is loaded.
$\overline{CE}_3$	Input-Synchronous	**Chip Enable 3 Input, active LOW**. Sampled on the rising edge of CLK. Used in conjunction with $\overline{CE}_1$ and CE_2 to select/deselect the device. Not connected for BGA. Where referenced, $\overline{CE}_3$ is assumed active throughout this document for BGA. $\overline{CE}_3$ is sampled only when a new external address is loaded.
$\overline{OE}$	Input-Asynchronous	**Output Enable, asynchronous input, active LOW**. Controls the direction of the I/O pins. When LOW, the I/O pins behave as outputs. When deasserted HIGH, I/O pins are tri-stated, and act as input data pins. $\overline{OE}$ is masked during the first clock of a read cycle when emerging from a deselected state.
$\overline{ADV}$	Input-Synchronous	**Advance Input signal, sampled on the rising edge of CLK, active LOW**. When asserted, it automatically increments the address in a burst cycle.
$\overline{ADSP}$	Input-Synchronous	**Address Strobe from Processor, sampled on the rising edge of CLK, active LOW**. When asserted LOW, addresses presented to the device are captured in the address registers. A1:A0 are also loaded into the burst counter. When $\overline{ADSP}$ and $\overline{ADSC}$ are both asserted, only $\overline{ADSP}$ is recognized. $\overline{ASDP}$ is ignored when $\overline{CE}_1$ is deasserted HIGH.
$\overline{ADSC}$	Input-Synchronous	**Address Strobe from Controller, sampled on the rising edge of CLK, active LOW**. When asserted LOW, addresses presented to the device are captured in the address registers. A1:A0 are also loaded into the burst counter. When $\overline{ADSP}$ and $\overline{ADSC}$ are both asserted, only $\overline{ADSP}$ is recognized.
ZZ	Input-Asynchronous	**ZZ "sleep" Input, active HIGH**. When asserted HIGH places the device in a non-time-critical "sleep" condition with data integrity preserved. For normal operation, this pin has to be LOW or left floating. ZZ pin has an internal pull-down.
DQs, DQPs	I/O-Synchronous	**Bidirectional Data I/O lines**. As inputs, they feed into an on-chip data register that is triggered by the rising edge of CLK. As outputs, they deliver the data contained in the memory location specified by the addresses presented during the previous clock rise of the read cycle. The direction of the pins is controlled by $\overline{OE}$. When $\overline{OE}$ is asserted LOW, the pins behave as outputs. When HIGH, DQs and DQP_X are placed in a tri-state condition.
V_{DD}	Power Supply	**Power supply inputs to the core of the device**.
V_{SS}	Ground	**Ground for the core of the device**.
V_{SSQ}	I/O Ground	**Ground for the I/O circuitry**.
V_{DDQ}	I/O Power Supply	**Power supply for the I/O circuitry**.

Downloaded from Arrow.com.

Pin Definitions (continued)

Name	I/O	Description
MODE	Input-Static	**Selects Burst Order**. When tied to GND selects linear burst sequence. When tied to V_{DD} or left floating selects interleaved burst sequence. This is a strap pin and should remain static during device operation. Mode Pin has an internal pull-up.
TDO	JTAG serial output Synchronous	**Serial data-out to the JTAG circuit**. Delivers data on the negative edge of TCK. If the JTAG feature is not being utilized, this pin should be disconnected.
TDI	JTAG serial input Synchronous	**Serial data-In to the JTAG circuit**. Sampled on the rising edge of TCK. If the JTAG feature is not being utilized, this pin can be disconnected or connected to V_{DD}.
TMS	JTAG serial input Synchronous	**Serial data-In to the JTAG circuit**. Sampled on the rising edge of TCK. If the JTAG feature is not being utilized, this pin can be disconnected or connected to V_{DD}.
TCK	JTAG-Clock	**Clock input to the JTAG circuitry**. If the JTAG feature is not being utilized, this pin must be connected to V_{SS}.
NC	–	**No Connects**. Not internally connected to the die
NC/72M, NC/144M, NC/288M, NC/576, NC/1G	–	**No Connects**. Not internally connected to the die. 72M, 144M, 288M, 576M and 1G are address expansion pins are not internally connected to the die.

Functional Overview

All synchronous inputs pass through input registers controlled by the rising edge of the clock. All data outputs pass through output registers controlled by the rising edge of the clock. Maximum access delay from the clock rise (t_{CO}) is 2.6 ns (250-MHz device).

The CY7C1440AV25/CY7C1446AV25 supports secondary cache in systems utilizing either a linear or interleaved burst sequence. The interleaved burst order supports Pentium and i486™ processors. The linear burst sequence is suited for processors that utilize a linear burst sequence. The burst order is user selectable, and is determined by sampling the MODE input. Accesses can be initiated with either the Processor Address Strobe (ADSP) or the Controller Address Strobe (ADSC). Address advancement through the burst sequence is controlled by the ADV input. A two-bit on-chip wraparound burst counter captures the first address in a burst sequence and automatically increments the address for the rest of the burst access.

Byte Write operations are qualified with the Byte Write Enable ($\overline{BWE}$) and Byte Write Select ($\overline{BW_X}$) inputs. A Global Write Enable ($\overline{GW}$) overrides all Byte Write inputs and writes data to all four bytes. All writes are simplified with on-chip synchronous self-timed Write circuitry.

Three synchronous Chip Selects ($\overline{CE_1}$, CE_2, $\overline{CE_3}$) and an asynchronous Output Enable ($\overline{OE}$) provide for easy bank selection and output tri-state control. $\overline{ADSP}$ is ignored if $\overline{CE_1}$ is HIGH.

Single Read Accesses

This access is initiated when the following conditions are satisfied at clock rise: (1) $\overline{ADSP}$ or $\overline{ADSC}$ is asserted LOW, (2) $\overline{CE_1}$, CE_2, $\overline{CE_3}$ are all asserted active, and (3) the Write signals ($\overline{GW}$, $\overline{BWE}$) are all deserted HIGH. $\overline{ADSP}$ is ignored if $\overline{CE_1}$ is HIGH. The address presented to the address inputs (A) is stored into the address advancement logic and the Address Register while being presented to the memory array. The corresponding data is allowed to propagate to the input of the Output Registers. At the rising edge of the next clock the data is allowed to propagate through the output register and onto the data bus within 2.6 ns (250-MHz device) if $\overline{OE}$ is active LOW. The only exception occurs when the SRAM is emerging from a deselected state to a selected state, its outputs are always tri-stated during the first cycle of the access. After the first cycle of the access, the outputs are controlled by the $\overline{OE}$ signal. Consecutive single Read cycles are supported. Once the SRAM is deselected at clock rise by the chip select and either $\overline{ADSP}$ or $\overline{ADSC}$ signals, its output will tri-state immediately.

Single Write Accesses Initiated by $\overline{ADSP}$

This access is initiated when both of the following conditions are satisfied at clock rise: (1) $\overline{ADSP}$ is asserted LOW, and (2) $\overline{CE_1}$, CE_2, $\overline{CE_3}$ are all asserted active. The address presented to A is loaded into the address register and the address advancement logic while being delivered to the memory array. The Write signals ($\overline{GW}$, $\overline{BWE}$, and $\overline{BW_X}$) and ADV inputs are ignored during this first cycle.

$\overline{ADSP}$-triggered Write accesses require two clock cycles to complete. If $\overline{GW}$ is asserted LOW on the second clock rise, the data presented to the DQs inputs is written into the corresponding address location in the memory array. If $\overline{GW}$ is HIGH, then the Write operation is controlled by $\overline{BWE}$ and $\overline{BW_X}$ signals.

The CY7C1440AV25/CY7C1446AV25 provides Byte Write capability that is described in the Write Cycle Descriptions table. Asserting the Byte Write Enable input ($\overline{BWE}$) with the selected Byte Write ($\overline{BW_X}$) input, will selectively write to only the desired bytes. Bytes not selected during a Byte Write operation will

Downloaded from Arrow.com.

remain unaltered. A synchronous self-timed Write mechanism has been provided to simplify the Write operations.

Because CY7C1440AV25/CY7C1446AV25 is a common I/O device, the Output Enable (OE) must be deasserted HIGH before presenting data to the DQs inputs. Doing so will tri-state the output drivers. As a safety precaution, DQs are automatically tri-stated whenever a Write cycle is detected, regardless of the state of OE.

Single Write Accesses Initiated by ADSC

ADSC Write accesses are initiated when the following conditions are satisfied: (1) ADSC is asserted LOW, (2) ADSP is deserted HIGH, (3) CE_1, CE_2, CE_3 are all asserted active, and (4) the appropriate combination of the Write inputs (GW, BWE, and BW_X) are asserted active to conduct a Write to the desired byte(s). ADSC-triggered Write accesses require a single clock cycle to complete. The address presented to A is loaded into the address register and the address advancement logic while being delivered to the memory array. The ADV input is ignored during this cycle. If a global Write is conducted, the data presented to the DQs is written into the corresponding address location in the memory core. If a Byte Write is conducted, only the selected bytes are written. Bytes not selected during a Byte Write operation will remain unaltered. A synchronous self-timed Write mechanism has been provided to simplify the Write operations.

Because CY7C1440AV25/CY7C1446AV25 is a common I/O device, the Output Enable (OE) must be deasserted HIGH before presenting data to the DQs inputs. Doing so will tri-state the output drivers. As a safety precaution, DQs are automatically tri-stated whenever a Write cycle is detected, regardless of the state of OE.

Burst Sequences

The CY7C1440AV25/CY7C1446AV25 provides a two-bit wraparound counter, fed by A1:A0, that implements either an interleaved or linear burst sequence. The interleaved burst sequence is designed specifically to support Intel Pentium applications. The linear burst sequence is designed to support processors that follow a linear burst sequence. The burst sequence is user selectable through the MODE input.

Asserting ADV LOW at clock rise will automatically increment the burst counter to the next address in the burst sequence. Both Read and Write burst operations are supported.

Sleep Mode

The ZZ input pin is an asynchronous input. Asserting ZZ places the SRAM in a power conservation “sleep” mode. Two clock cycles are required to enter into or exit from this “sleep” mode. While in this mode, data integrity is guaranteed. Accesses pending when entering the “sleep” mode are not considered valid nor is the completion of the operation guaranteed. The device must be deselected prior to entering the “sleep” mode. CE_1, CE_2, CE_3, ADSP, and ADSC must remain inactive for the duration of t_{ZZREC} after the ZZ input returns LOW.

Interleaved Burst Address Table

(MODE = Floating or V_{DD})

First Address A1:A0	Second Address A1:A0	Third Address A1:A0	Fourth Address A1:A0
00	01	10	11
01	00	11	10
10	11	00	01
11	10	01	00

Linear Burst Address Table

(MODE = GND)

First Address A1:A0	Second Address A1:A0	Third Address A1:A0	Fourth Address A1:A0
00	01	10	11
01	10	11	00
10	11	00	01
11	00	01	10

ZZ Mode Electrical Characteristics

Parameter	Description	Test Conditions	Min	Max	Unit
I_{DDZZ}	Sleep mode standby current	ZZ ≥ V_{DD} – 0.2 V	–	100	mA
t_{ZZS}	Device operation to ZZ	ZZ ≥ V_{DD} – 0.2 V	–	$2t_{CYC}$	ns
t_{ZZREC}	ZZ recovery time	ZZ ≤ 0.2 V	$2t_{CYC}$	–	ns
t_{ZZI}	ZZ Active to sleep current	This parameter is sampled	–	$2t_{CYC}$	ns
t_{RZZI}	ZZ Inactive to exit sleep current	This parameter is sampled	0	–	ns

Downloaded from Arrow.com.

Truth Table

The truth table for CY7C1440AV25/CY7C1446AV25 follows. [1, 2, 3, 4, 5, 6]

Operation	Address Used	$\overline{CE_1}$	CE_2	$\overline{CE_3}$	ZZ	$\overline{ADSP}$	$\overline{ADSC}$	$\overline{ADV}$	$\overline{WRITE}$	$\overline{OE}$	CLK	DQ
Deselect Cycle, Power Down	None	H	X	X	L	X	L	X	X	X	L–H	Tri-State
Deselect Cycle, Power Down	None	L	L	X	L	L	X	X	X	X	L–H	Tri-State
Deselect Cycle, Power Down	None	L	X	H	L	L	X	X	X	X	L–H	Tri-State
Deselect Cycle, Power Down	None	L	L	X	L	H	L	X	X	X	L–H	Tri-State
Deselect Cycle, Power Down	None	L	X	H	L	H	L	X	X	X	L–H	Tri-State
Sleep Mode, Power Down	None	X	X	X	H	X	X	X	X	X	X	Tri-State
READ Cycle, Begin Burst	External	L	H	L	L	L	X	X	X	L	L–H	Q
READ Cycle, Begin Burst	External	L	H	L	L	L	X	X	X	H	L–H	Tri-State
WRITE Cycle, Begin Burst	External	L	H	L	L	H	L	X	L	X	L–H	D
READ Cycle, Begin Burst	External	L	H	L	L	H	L	X	H	L	L–H	Q
READ Cycle, Begin Burst	External	L	H	L	L	H	L	X	H	H	L–H	Tri-State
READ Cycle, Continue Burst	Next	X	X	X	L	H	H	L	H	L	L–H	Q
READ Cycle, Continue Burst	Next	X	X	X	L	H	H	L	H	H	L–H	Tri-State
READ Cycle, Continue Burst	Next	H	X	X	L	X	H	L	H	L	L–H	Q
READ Cycle, Continue Burst	Next	H	X	X	L	X	H	L	H	H	L–H	Tri-State
WRITE Cycle, Continue Burst	Next	X	X	X	L	H	H	L	L	X	L–H	D
WRITE Cycle, Continue Burst	Next	H	X	X	L	X	H	L	L	X	L–H	D
READ Cycle, Suspend Burst	Current	X	X	X	L	H	H	H	H	L	L–H	Q
READ Cycle, Suspend Burst	Current	X	X	X	L	H	H	H	H	H	L–H	Tri-State
READ Cycle, Suspend Burst	Current	H	X	X	L	X	H	H	H	L	L–H	Q
READ Cycle, Suspend Burst	Current	H	X	X	L	X	H	H	H	H	L–H	Tri-State
WRITE Cycle, Suspend Burst	Current	X	X	X	L	H	H	H	L	X	L–H	D
WRITE Cycle, Suspend Burst	Current	H	X	X	L	X	H	H	L	X	L–H	D

Notes
1. X = "Don't Care." H = Logic HIGH, L = Logic LOW.
2. $\overline{WRITE}$ = L when any one or more Byte Write enable signals and $\overline{BWE}$ = L or $\overline{GW}$ = L. $\overline{WRITE}$ = H when all Byte write enable signals, $\overline{BWE}$, $\overline{GW}$ = H.
3. The DQ pins are controlled by the current cycle and the $\overline{OE}$ signal. $\overline{OE}$ is asynchronous and is not sampled with the clock.
4. BGA package has only two chip selects $\overline{CE_1}$ and CE_2.
5. The SRAM always initiates a read cycle when $\overline{ADSP}$ is asserted, regardless of the state of $\overline{GW}$, $\overline{BWE}$, or $\overline{BW_X}$. Writes may occur only on subsequent clocks after the $\overline{ADSP}$ or with the assertion of $\overline{ADSC}$. As a result, OE must be driven HIGH prior to the start of the write cycle to allow the outputs to tri-state. $\overline{OE}$ is a don't care for the remainder of the write cycle.
6. $\overline{OE}$ is asynchronous and is not sampled with the clock rise. It is masked internally during write cycles. During a read cycle all data bits are Tri-State when $\overline{OE}$ is inactive or when the device is deselected, and all data bits behave as output when OE is active (LOW).

Downloaded from Arrow.com.

Truth Table for Read/Write

The Truth Table for Read/Write for CY7C1440AV25 follows. [7, 8, 9]

Function (CY7C1440AV25)	$\overline{GW}$	$\overline{BWE}$	$\overline{BW_D}$	$\overline{BW_C}$	$\overline{BW_B}$	$\overline{BW_A}$
Read	H	H	X	X	X	X
Read	H	L	H	H	H	H
Write Byte A – (DQ_A and DQP_A)	H	L	H	H	H	L
Write Byte B – (DQ_B and DQP_B)	H	L	H	H	L	H
Write Bytes B, A	H	L	H	H	L	L
Write Byte C – (DQ_C and DQP_C)	H	L	H	L	H	H
Write Bytes C, A	H	L	H	L	H	L
Write Bytes C, B	H	L	H	L	L	H
Write Bytes C, B, A	H	L	H	L	L	L
Write Byte D – (DQ_D and DQP_D)	H	L	L	H	H	H
Write Bytes D, A	H	L	L	H	H	L
Write Bytes D, B	H	L	L	H	L	H
Write Bytes D, B, A	H	L	L	H	L	L
Write Bytes D, C	H	L	L	L	H	H
Write Bytes D, C, A	H	L	L	L	H	L
Write Bytes D, C, B	H	L	L	L	L	H
Write All Bytes	H	L	L	L	L	L
Write All Bytes	L	X	X	X	X	X

Truth Table for Read/Write

The Truth Table for Read/Write for CY7C1446AV25 follows. [7, 8, 9]

Function (CY7C1446AV25)	$\overline{GW}$	$\overline{BWE}$	$\overline{BW_x}$
Read	H	H	X
Read	H	L	All $\overline{BW}$ = H
Write Byte x – (DQ_x and DQP_x)	H	L	L
Write All Bytes	H	L	All $\overline{BW}$ = L

Notes
7. The DQ pins are controlled by the current cycle and the $\overline{OE}$ signal. $\overline{OE}$ is asynchronous and is not sampled with the clock.
8. $\overline{BW}$x represents any byte write signal. To enable any byte write $\overline{BW_x}$, a Logic LOW signal should be applied at clock rise. Any number of bye writes can be enabled at the same time for any given write.
9. Table only lists a partial listing of the byte write combinations. Any combination of $\overline{BW_X}$ is valid. Appropriate write will be done based on which byte write is active.

Downloaded from Arrow.com.

IEEE 1149.1 Serial Boundary Scan (JTAG)

The CY7C1440AV25/CY7C1446AV25 incorporates a serial boundary scan test access port (TAP). This part is fully compliant with IEEE Standard 1149.1.The TAP operates using JEDEC-standard 2.5 V I/O logic level.

The CY7C1440AV25/CY7C1446AV25 contains a TAP controller, instruction register, boundary scan register, bypass register, and ID register.

Disabling the JTAG Feature

It is possible to operate the SRAM without using the JTAG feature. To disable the TAP controller, TCK must be tied LOW(V_{SS}) to prevent clocking of the device. TDI and TMS are internally pulled up and may be unconnected. They may alternately be connected to V_{DD} through a pull-up resistor. TDO should be left unconnected. Upon power-up, the device will come up in a reset state which will not interfere with the operation of the device.

Test Access Port (TAP)

Test Clock (TCK)

The test clock is used only with the TAP controller. All inputs are captured on the rising edge of TCK. All outputs are driven from the falling edge of TCK.

Test Mode Select (TMS)

The TMS input is used to give commands to the TAP controller and is sampled on the rising edge of TCK. It is allowable to leave this ball unconnected if the TAP is not used. The ball is pulled up internally, resulting in a logic HIGH level.

Test Data-In (TDI)

The TDI ball is used to serially input information into the registers and can be connected to the input of any of the registers. The register between TDI and TDO is chosen by the instruction that is loaded into the TAP instruction register. For information on loading the instruction register, see TAP Controller State Diagram on page 14. TDI is internally pulled up and can be unconnected if the TAP is unused in an application. TDI is connected to the most significant bit (MSB) of any register.

Test Data-Out (TDO)

The TDO output ball is used to serially clock data-out from the registers. The output is active depending upon the current state of the TAP state machine (see Instruction Codes on page 18). The output changes on the falling edge of TCK. TDO is connected to the least significant bit (LSB) of any register.

Performing a TAP Reset

A RESET is performed by forcing TMS HIGH (VDD) for five rising edges of TCK. This RESET does not affect the operation of the SRAM and may be performed while the SRAM is operating.

At power-up, the TAP is reset internally to ensure that TDO comes up in a High Z state.

TAP Registers

Registers are connected between the TDI and TDO balls and allow data to be scanned into and out of the SRAM test circuitry. Only one register can be selected at a time through the instruction register. Data is serially loaded into the TDI ball on the rising edge of TCK. Data is output on the TDO ball on the falling edge of TCK.

Instruction Register

Three-bit instructions can be serially loaded into the instruction register. This register is loaded when it is placed between the TDI and TDO balls as shown in the TAP Controller Block Diagram on page 15. Upon power-up, the instruction register is loaded with the IDCODE instruction. It is also loaded with the IDCODE instruction if the controller is placed in a reset state as described in the previous section.

When the TAP controller is in the Capture-IR state, the two least significant bits are loaded with a binary “01” pattern to allow for fault isolation of the board-level serial test data path.

Bypass Register

To save time when serially shifting data through registers, it is sometimes advantageous to skip certain chips. The bypass register is a single-bit register that can be placed between the TDI and TDO balls. This allows data to be shifted through the SRAM with minimal delay. The bypass register is set LOW (V_{SS}) when the BYPASS instruction is executed.

Boundary Scan Register

The boundary scan register is connected to all the input and bidirectional balls on the SRAM.

The boundary scan register is loaded with the contents of the RAM I/O ring when the TAP controller is in the Capture-DR state and is then placed between the TDI and TDO balls when the controller is moved to the Shift-DR state. The EXTEST, SAMPLE/PRELOAD and SAMPLE Z instructions can be used to capture the contents of the I/O ring.

The Boundary Scan Order on page 19 and Boundary Scan Order on page 20 show the order in which the bits are connected. Each bit corresponds to one of the bumps on the SRAM package. The MSB of the register is connected to TDI, and the LSB is connected to TDO.

Identification (ID) Register

The ID register is loaded with a vendor-specific, 32-bit code during the Capture-DR state when the IDCODE command is loaded in the instruction register. The IDCODE is hardwired into the SRAM and can be shifted out when the TAP controller is in the Shift-DR state. The ID register has a vendor code and other information described in the Identification Register Definitions on page 18.

TAP Instruction Set

Overview

Eight different instructions are possible with the three bit instruction register. All combinations are listed in the Instruction Codes on page 18. Three of these instructions are listed as RESERVED and should not be used. The other five instructions are described in detail below.

Instructions are loaded into the TAP controller during the Shift-IR state when the instruction register is placed between TDI and TDO. During this state, instructions are shifted through the

Downloaded from Arrow.com.

instruction register through the TDI and TDO balls. To execute the instruction once it is shifted in, the TAP controller needs to be moved into the Update-IR state.

IDCODE

The IDCODE instruction causes a vendor-specific, 32-bit code to be loaded into the instruction register. It also places the instruction register between the TDI and TDO balls and allows the IDCODE to be shifted out of the device when the TAP controller enters the Shift-DR state.

The IDCODE instruction is loaded into the instruction register upon power-up or whenever the TAP controller is given a test logic reset state.

SAMPLE Z

The SAMPLE Z instruction causes the boundary scan register to be connected between the TDI and TDO pins when the TAP controller is in a Shift-DR state. The SAMPLE Z command puts the output bus into a High Z state until the next command is given during the “Update IR” state.

SAMPLE/PRELOAD

SAMPLE/PRELOAD is a 1149.1 mandatory instruction. When the SAMPLE/PRELOAD instructions are loaded into the instruction register and the TAP controller is in the Capture-DR state, a snapshot of data on the inputs and output pins is captured in the boundary scan register.

The user must be aware that the TAP controller clock can only operate at a frequency up to 20 MHz, while the SRAM clock operates more than an order of magnitude faster. Because there is a large difference in the clock frequencies, it is possible that during the Capture-DR state, an input or output will undergo a transition. The TAP may then try to capture a signal while in transition (metastable state). This will not harm the device, but there is no guarantee as to the value that will be captured. Repeatable results may not be possible.

To guarantee that the boundary scan register will capture the correct value of a signal, the SRAM signal must be stabilized long enough to meet the TAP controller’s capture set-up plus hold times (t_{CS} and t_{CH}). The SRAM clock input might not be captured correctly if there is no way in a design to stop (or slow) the clock during a SAMPLE/PRELOAD instruction. If this is an issue, it is still possible to capture all other signals and simply ignore the value of the CK and CK# captured in the boundary scan register.

Once the data is captured, it is possible to shift out the data by putting the TAP into the Shift-DR state. This places the boundary scan register between the TDI and TDO pins.

PRELOAD allows an initial data pattern to be placed at the latched parallel outputs of the boundary scan register cells prior to the selection of another boundary scan test operation.

The shifting of data for the SAMPLE and PRELOAD phases can occur concurrently when required — that is, while data captured is shifted out, the preloaded data can be shifted in.

BYPASS

When the BYPASS instruction is loaded in the instruction register and the TAP is placed in a Shift-DR state, the bypass register is placed between the TDI and TDO pins. The advantage of the BYPASS instruction is that it shortens the boundary scan path when multiple devices are connected together on a board.

EXTEST

The EXTEST instruction enables the preloaded data to be driven out through the system output pins. This instruction also selects the boundary scan register to be connected for serial access between the TDI and TDO in the shift-DR controller state.

EXTEST OUTPUT BUS TRI-STATE

IEEE Standard 1149.1 mandates that the TAP controller be able to put the output bus into a tri-state mode.

The boundary scan register has a special bit located at bit #89 (for 165-ball FBGA package) or bit #138 (for 209-ball FBGA package). When this scan cell, called the “extest output bus tri-state”, is latched into the preload register during the “Update-DR” state in the TAP controller, it will directly control the state of the output (Q-bus) pins, when the EXTEST is entered as the current instruction. When HIGH, it will enable the output buffers to drive the output bus. When LOW, this bit will place the output bus into a High Z condition.

This bit can be set by entering the SAMPLE/PRELOAD or EXTEST command, and then shifting the desired bit into that cell, during the “Shift-DR” state. During “Update-DR”, the value loaded into that shift-register cell will latch into the preload register. When the EXTEST instruction is entered, this bit will directly control the output Q-bus pins. Note that this bit is pre-set HIGH to enable the output when the device is powered-up, and also when the TAP controller is in the “Test-Logic-Reset” state.

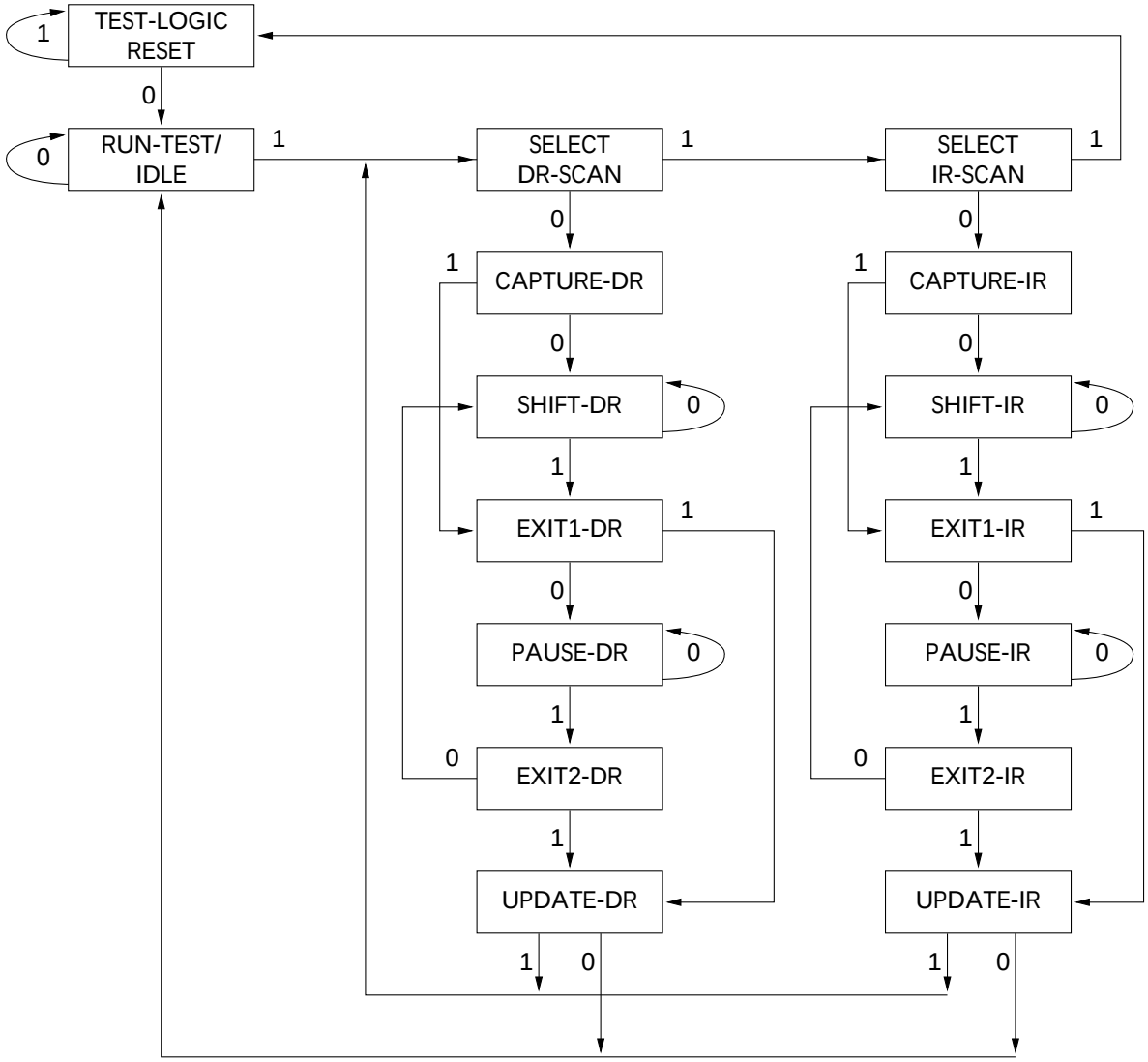
Reserved

These instructions are not implemented but are reserved for future use. Do not use these instructions.

Downloaded from Arrow.com.

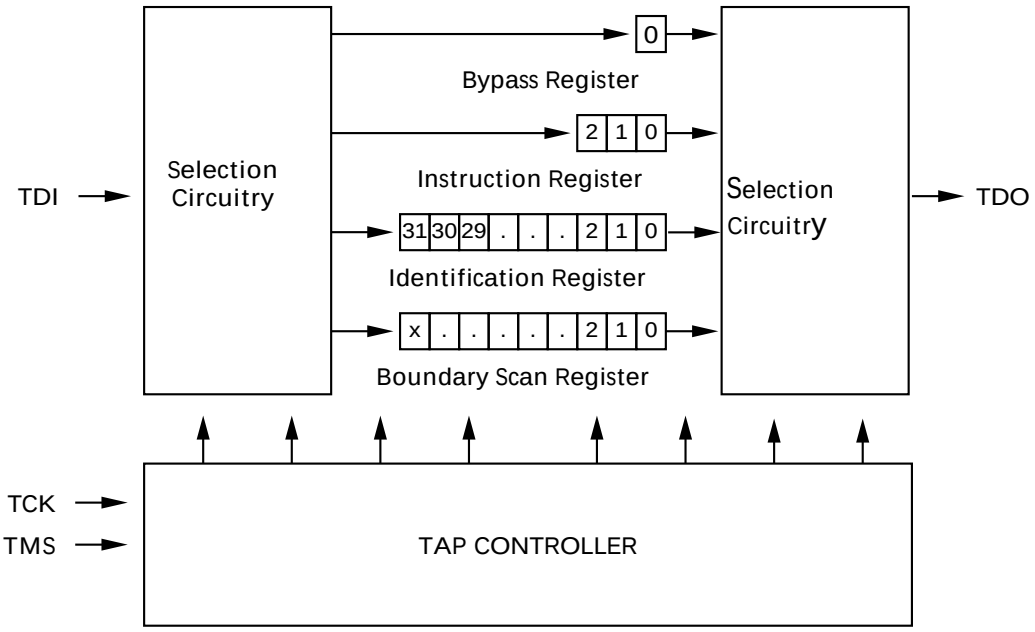
TAP Controller State Diagram

The 0/1 next to each state represents the value of TMS at the rising edge of TCK.



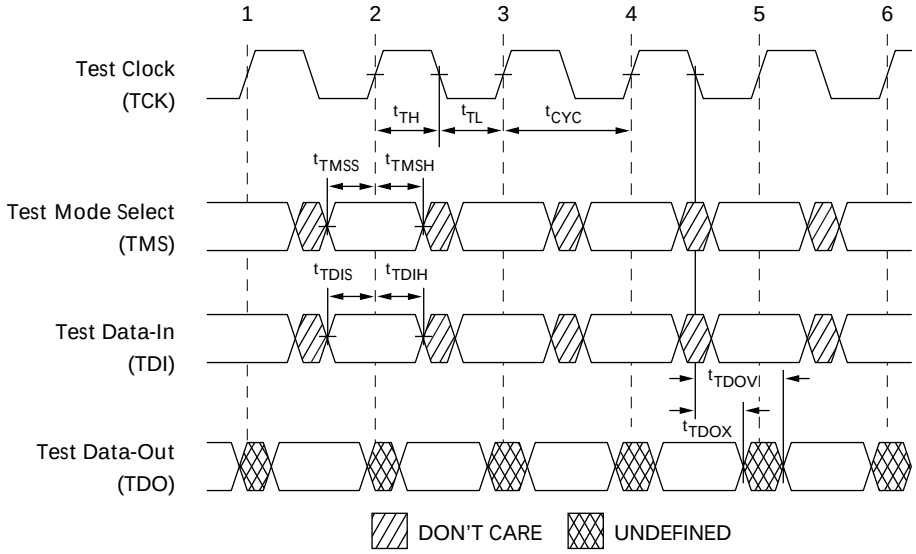
Downloaded from Arrow.com.

TAP Controller Block Diagram



TAP Timing

Figure 3. TAP Timing



Downloaded from Arrow.com.

TAP AC Switching Characteristics

Over the Operating Range

Parameter [10, 11]	Description	Min	Max	Unit
Clock				
t_{TCYC}	TCK Clock Cycle Time	50	–	ns
t_{TF}	TCK Clock Frequency	–	20	MHz
t_{TH}	TCK Clock HIGH time	20	–	ns
t_{TL}	TCK Clock LOW time	20	–	ns
Output Times				
t_{TDOV}	TCK Clock LOW to TDO Valid	–	10	ns
t_{TDOX}	TCK Clock LOW to TDO Invalid	0	–	ns
Set-up Times				
t_{TMSS}	TMS Set-up to TCK Clock Rise	5	–	ns
t_{TDIS}	TDI Set-up to TCK Clock Rise	5	–	ns
t_{CS}	Capture Set-up to TCK Rise	5		ns
Hold Times				
t_{TMSH}	TMS Hold after TCK Clock Rise	5	–	ns
t_{TDIH}	TDI Hold after Clock Rise	5	–	ns
t_{CH}	Capture Hold after Clock Rise	5	–	ns

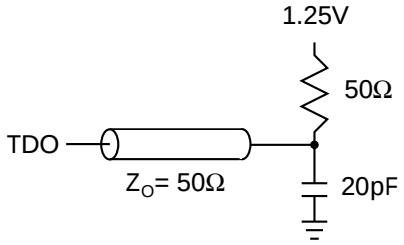
Notes
10. t_{CS} and t_{CH} refer to the set-up and hold time requirements of latching data from the boundary scan register.
11. Test conditions are specified using the load in TAP AC test Conditions. t_R/t_F = 1 ns.

Downloaded from Arrow.com.

2.5 V TAP AC Test Conditions

Input pulse levels ..... V_{SS} to 2.5 V
Input rise and fall time ..... 1 ns
Input timing reference levels ..... 1.25 V
Output reference levels ..... 1.25 V
Test load termination supply voltage ..... 1.25 V

2.5 V TAP AC Output Load Equivalent



TAP DC Electrical Characteristics and Operating Conditions

(0 °C < T_A < +70 °C; V_{DD} = 2.5 V ± 0.125 V unless otherwise noted)

Parameter [12]	Description	Test Conditions		Min	Max	Unit
V_{OH1}	Output HIGH Voltage	I_{OH} = –1.0 mA	V_{DDQ} = 2.5 V	2.0	–	V
V_{OH2}	Output HIGH Voltage	I_{OH} = –100 µA	V_{DDQ} = 2.5 V	2.1	–	V
V_{OL1}	Output LOW Voltage	I_{OL} = 1.0 mA	V_{DDQ} = 2.5 V	–	0.4	V
V_{OL2}	Output LOW Voltage	I_{OL} = 100 µA	V_{DDQ} = 2.5 V	–	0.2	V
V_{IH}	Input HIGH Voltage		V_{DDQ} = 2.5 V	1.7	V_{DD} + 0.3	V
V_{IL}	Input LOW Voltage		V_{DDQ} = 2.5 V	–0.3	0.7	V
I_X	Input Load Current	GND ≤ V_{IN} ≤ V_{DDQ}		–5	5	µA

Note
12. All voltages referenced to V_{SS} (GND).

Downloaded from Arrow.com.

Identification Register Definitions

Instruction Field	CY7C1440AV25 (1 M × 36)	CY7C1446AV25 (512 K × 72)	Description
Revision Number (31:29)	000	000	Describes the version number.
Device Depth (28:24)	01011	01011	Reserved for Internal Use
Architecture/Memory Type (23:18)	000000	000000	Defines memory type and architecture
Bus Width/Density (17:12)	100111	110111	Defines width and density
Cypress JEDEC ID Code (11:1)	00000110100	00000110100	Allows unique identification of SRAM vendor.
ID Register Presence Indicator (0)	1	1	Indicates the presence of an ID register.

Scan Register Sizes

Register Name	Bit Size (× 36)	Bit Size (× 72)
Instruction	3	3
Bypass	1	1
ID	32	32
Boundary Scan Order (165-ball FBGA package)	89	–
Boundary Scan Order (209-ball FBGA package)	–	138

Instruction Codes

Instruction	Code	Description
EXTEST	000	Captures I/O ring contents.
IDCODE	001	Loads the ID register with the vendor ID code and places the register between TDI and TDO. This operation does not affect SRAM operations.
SAMPLE Z	010	Captures I/O ring contents. Places the boundary scan register between TDI and TDO. Forces all SRAM output drivers to a High Z state.
RESERVED	011	Do Not Use: This instruction is reserved for future use.
SAMPLE/PRELOAD	100	Captures I/O ring contents. Places the boundary scan register between TDI and TDO. Does not affect SRAM operation.
RESERVED	101	Do Not Use: This instruction is reserved for future use.
RESERVED	110	Do Not Use: This instruction is reserved for future use.
BYPASS	111	Places the bypass register between TDI and TDO. This operation does not affect SRAM operations.

Downloaded from Arrow.com.

Boundary Scan Order

165-ball FBGA [13, 14]

CY7C1440AV25 (1 M × 36)

Bit #	Ball ID	Bit #	Ball ID	Bit #	Ball ID	Bit #	Ball ID
1	N6	26	E11	51	A3	76	N1
2	N7	27	D11	52	A2	77	N2
3	N10	28	G10	53	B2	78	P1
4	P11	29	F10	54	C2	79	R1
5	P8	30	E10	55	B1	80	R2
6	R8	31	D10	56	A1	81	P3
7	R9	32	C11	57	C1	82	R3
8	P9	33	A11	58	D1	83	P2
9	P10	34	B11	59	E1	84	R4
10	R10	35	A10	60	F1	85	P4
11	R11	36	B10	61	G1	86	N5
12	H11	37	A9	62	D2	87	P6
13	N11	38	B9	63	E2	88	R6
14	M11	39	C10	64	F2	89	Internal
15	L11	40	A8	65	G2		
16	K11	41	B8	66	H1		
17	J11	42	A7	67	H3		
18	M10	43	B7	68	J1		
19	L10	44	B6	69	K1		
20	K10	45	A6	70	L1		
21	J10	46	B5	71	M1		
22	H9	47	A5	72	J2		
23	H10	48	A4	73	K2		
24	G11	49	B4	74	L2		
25	F11	50	B3	75	M2		

Notes
13. Balls which are NC (No Connect) are Pre-Set LOW.
14. Bit# 89 is Pre-Set HIGH.

Downloaded from Arrow.com.

Boundary Scan Order

209-ball FBGA [15, 16]

CY7C1446AV25 (512 K × 72)

Bit #	Ball ID	Bit #	Ball ID	Bit #	Ball ID	Bit #	Ball ID
1	W6	36	F6	71	H6	106	K3
2	V6	37	K8	72	C6	107	K4
3	U6	38	K9	73	B6	108	K6
4	W7	39	K10	74	A6	109	K2
5	V7	40	J11	75	A5	110	L2
6	U7	41	J10	76	B5	111	L1
7	T7	42	H11	77	C5	112	M2
8	V8	43	H10	78	D5	113	M1
9	U8	44	G11	79	D4	114	N2
10	T8	45	G10	80	C4	115	N1
11	V9	46	F11	81	A4	116	P2
12	U9	47	F10	82	B4	117	P1
13	P6	48	E10	83	C3	118	R2
14	W11	49	E11	84	B3	119	R1
15	W10	50	D11	85	A3	120	T2
16	V11	51	D10	86	A2	121	T1
17	V10	52	C11	87	A1	122	U2
18	U11	53	C10	88	B2	123	U1
19	U10	54	B11	89	B1	124	V2
20	T11	55	B10	90	C2	125	V1
21	T10	56	A11	91	C1	126	W2
22	R11	57	A10	92	D2	127	W1
23	R10	58	C9	93	D1	128	T6
24	P11	59	B9	94	E1	129	U3
25	P10	60	A9	95	E2	130	V3
26	N11	61	D7	96	F2	131	T4
27	N10	62	C8	97	F1	132	T5
28	M11	63	B8	98	G1	133	U4
29	M10	64	A8	99	G2	134	V4
30	L11	65	D8	100	H2	135	5W
31	L10	66	C7	101	H1	136	5V
32	K11	67	B7	102	J2	137	5U
33	M6	68	A7	103	J1	138	Internal
34	L6	69	D6	104	K1		
35	J6	70	G6	105	N6		

Notes
15. Balls which are NC (No Connect) are Pre-Set LOW.
16. Bit# 138 is Pre-Set HIGH.

Downloaded from Arrow.com.

Maximum Ratings

Exceeding maximum ratings may impair the useful life of the device. These user guidelines are not tested.

Storage Temperature ..... –65 °C to +150 °C

Ambient Temperature with Power Applied ..... –55 °C to +125 °C

Supply Voltage on V_{DD} Relative to GND .....–0.3 V to +3.6 V

Supply Voltage on V_{DDQ} Relative to GND .... –0.3 V to +V_{DD}

DC Voltage Applied to Outputs in Tri-State .....–0.5 V to V_{DDQ} + 0.5 V

DC Input Voltage .....–0.5 V to V_{DD} + 0.5 V

Current into Outputs (LOW) ..... 20 mA

Static Discharge Voltage (per MIL-STD-883, Method 3015) ..... > 2001 V

Latch-up Current ..... > 200 mA

Operating Range

Range	Ambient Temperature	V_{DD}	V_{DDQ}
Commercial	0 °C to +70 °C	2.5 V ± 5%	1.7 V to V_{DD}
Industrial	–40 °C to +85 °C		

Electrical Characteristics

Over the Operating Range

DC Electrical Characteristics

Over the Operating Range

Parameter [17, 18]	Description	Test Conditions		Min	Max	Unit
V_{DD}	Power Supply Voltage			2.375	2.625	V
V_{DDQ}	I/O Supply Voltage	for 2.5 V I/O		2.375	2.625	V
V_{OH}	Output HIGH Voltage	for 2.5 V I/O, I_{OH} = –1.0 mA		2.0	–	V
V_{OL}	Output LOW Voltage	for 2.5 V I/O, I_{OL} = 1.0 mA		–	0.4	V
V_{IH}	Input HIGH Voltage[17]	for 2.5 V I/O		1.7	V_{DD} + 0.3	V
V_{IL}	Input LOW Voltage[17]	for 2.5 V I/O		–0.3	0.7	V
I_X	Input Leakage Current except ZZ and MODE	GND ≤ V_I ≤ V_{DDQ}		–5	5	µA
	Input Current of MODE	Input = V_{SS}		–30	–	µA
		Input = V_{DD}		–	5	µA
	Input Current of ZZ	Input = V_{SS}		–5	–	µA
		Input = V_{DD}		–	30	µA
I_{OZ}	Output Leakage Current	GND ≤ V_I ≤ V_{DDQ}, Output Disabled		–5	5	µA
I_{DD}	V_{DD} Operating Supply Current	V_{DD} = Max, I_{OUT} = 0 mA, f = f_{MAX} = 1/t_{CYC}	4-ns cycle, 250 MHz	–	435	mA
			6-ns cycle, 167 MHz		335	mA
I_{SB1}	Automatic CE Power-down Current – TTL Inputs	V_{DD} = Max, Device Deselected, V_{IN} ≥ V_{IH} or V_{IN} ≤ V_{IL}, f = f_{MAX} = 1/t_{CYC}	All speeds	–	185	mA
I_{SB2}	Automatic CE Power-down Current – CMOS Inputs	V_{DD} = Max, Device Deselected, V_{IN} ≤ 0.3 V or V_{IN} ≥ V_{DDQ} – 0.3 V, f = 0	All speeds	–	120	mA
I_{SB3}	Automatic CE Power-down Current – CMOS Inputs	V_{DD} = Max, Device Deselected, V_{IN} ≤ 0.3 V or V_{IN} ≥ V_{DDQ} – 0.3 V, f = f_{MAX} = 1/t_{CYC}	All speeds	–	160	mA
I_{SB4}	Automatic CE Power-down Current – TTL Inputs	V_{DD} = Max, Device Deselected, V_{IN} ≥ V_{IH} or V_{IN} ≤ V_{IL}, f = 0	All speeds	–	135	mA

Notes
17. Overshoot: $V_{IH(AC)}$ < V_{DD} + 1.5 V (Pulse width less than t_{CYC}/2), undershoot: $V_{IL(AC)}$ > –2 V (Pulse width less than t_{CYC}/2).
18. TPower-up: Assumes a linear ramp from 0 V to $V_{DD(min)}$ within 200 ms. During this time V_{IH} < V_{DD} and V_{DDQ} ≤ V_{DD}.

Downloaded from Arrow.com.

Capacitance

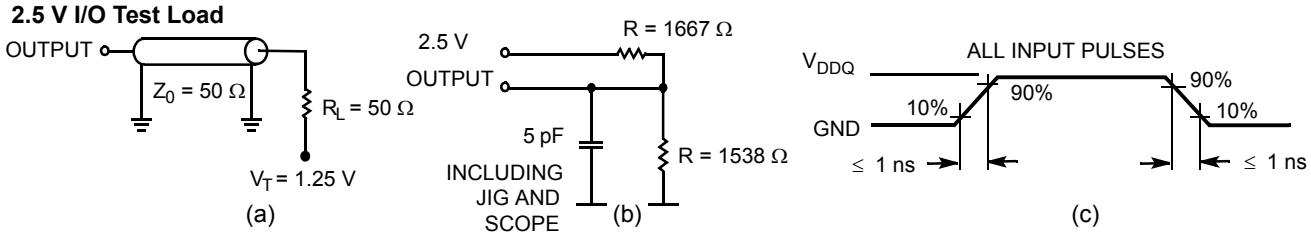
Parameter [19]	Description	Test Conditions	165-ball FBGA Max	209-ball FBGA Max	Unit
C_{IN}	Input Capacitance	T_A = 25 °C, f = 1 MHz, V_{DD}/V_{DDQ} = 2.5 V	7	5	pF
C_{CLK}	Clock Input Capacitance		7	5	pF
$C_{I/O}$	Input/Output Capacitance		6	7	pF

Thermal Resistance

Parameter [19]	Description	Test Conditions	165-ball FBGA Package	209-ball FBGA Package	Unit
Θ_{JA}	Thermal resistance (junction to ambient)	Test conditions follow standard test methods and procedures for measuring thermal impedance, per EIA/JESD51.	20.8	25.31	°C/W
Θ_{JC}	Thermal resistance (junction to case)		3.2	4.48	°C/W

AC Test Loads and Waveforms

Figure 4. AC Test Loads and Waveforms



Note
19. Tested initially and after any design or process change that may affect these parameters.

Downloaded from Arrow.com.

Switching Characteristics

Over the Operating Range

Parameter [20, 21]	Description	-250		-167		Unit
		Min	Max	Min	Max	
t_{POWER}	V_{DD}(typical) to the first Access[22]	1	–	1	–	ms
Clock						
t_{CYC}	Clock Cycle Time	4.0	–	6.0	–	ns
t_{CH}	Clock HIGH	1.5	–	2.4	–	ns
t_{CL}	Clock LOW	1.5	–	2.4	–	ns
Output Times						
t_{CO}	Data Output Valid After CLK Rise	–	2.6	–	3.4	ns
t_{DOH}	Data Output Hold After CLK Rise	1.0	–	1.5	–	ns
t_{CLZ}	Clock to Low Z [23, 24, 25]	1.0	–	1.5	–	ns
t_{CHZ}	Clock to High Z [23, 24, 25]	–	2.6	–	3.4	ns
t_{OEV}	$\overline{OE}$ LOW to Output Valid	–	2.6	–	3.4	ns
t_{OELZ}	$\overline{OE}$ LOW to Output Low Z [23, 24, 25]	0	–	0	–	ns
t_{OEHZ}	$\overline{OE}$ HIGH to Output High Z [23, 24, 25]	–	2.6	–	3.4	ns
Set-up Times						
t_{AS}	Address Set-up Before CLK Rise	1.2	–	1.5	–	ns
t_{ADS}	$\overline{ADSC}$, $\overline{ADSP}$ Set-up Before CLK Rise	1.2	–	1.5	–	ns
t_{ADVS}	$\overline{ADV}$ Set-up Before CLK Rise	1.2	–	1.5	–	ns
t_{WES}	$\overline{GW}$, $\overline{BWE}$, $\overline{BW_X}$ Set-up Before CLK Rise	1.2	–	1.5	–	ns
t_{DS}	Data Input Set-up Before CLK Rise	1.2	–	1.5	–	ns
t_{CES}	Chip Enable Set-Up Before CLK Rise	1.2	–	1.5	–	ns
Hold Times						
t_{AH}	Address Hold After CLK Rise	0.3	–	0.5	–	ns
t_{ADH}	$\overline{ADSP}$, $\overline{ADSC}$ Hold After CLK Rise	0.3	–	0.5	–	ns
t_{ADVH}	$\overline{ADV}$ Hold After CLK Rise	0.3	–	0.5	–	ns
t_{WEH}	$\overline{GW}$, $\overline{BWE}$, $\overline{BW_X}$ Hold After CLK Rise	0.3	–	0.5	–	ns
t_{DH}	Data Input Hold After CLK Rise	0.3	–	0.5	–	ns
t_{CEH}	Chip Enable Hold After CLK Rise	0.3	–	0.5	–	ns

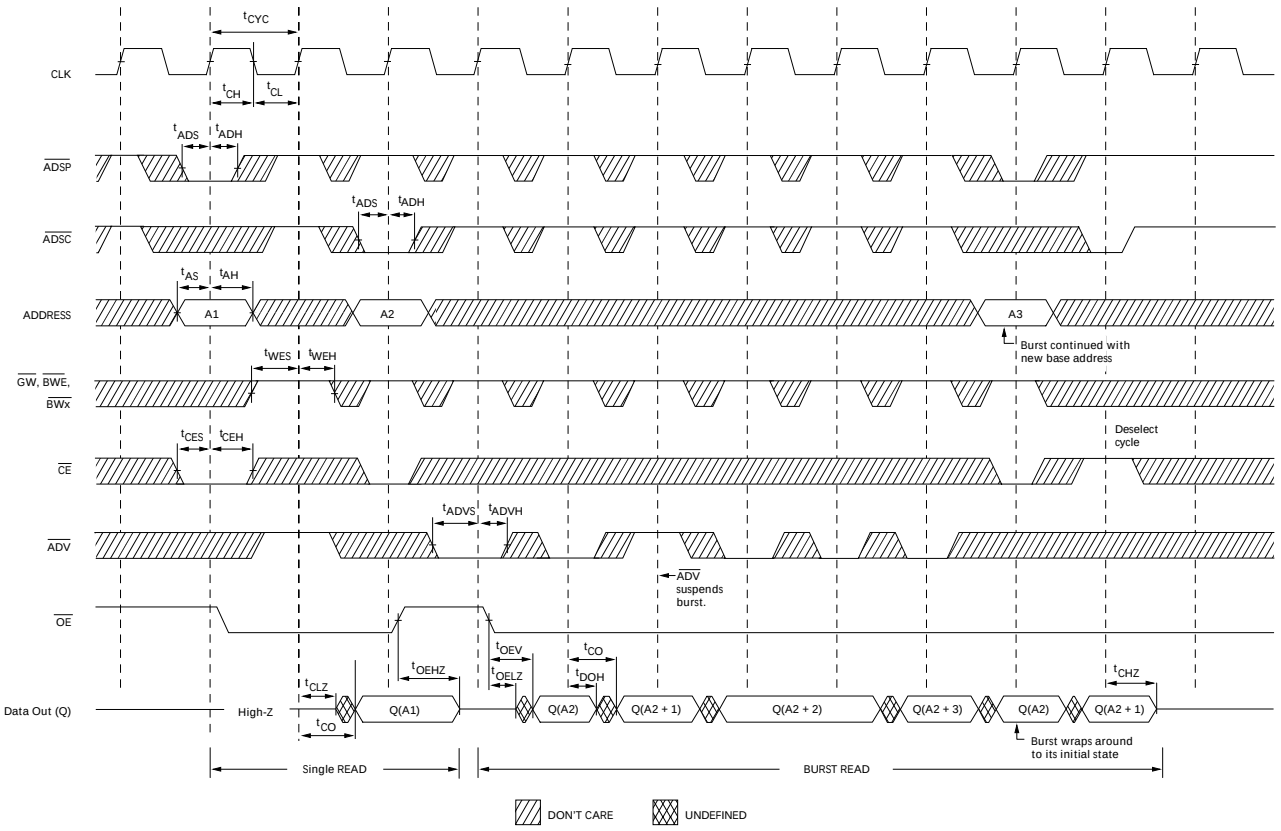
Notes

20. Timing reference level is 1.25 V when V_{DDQ} = 2.5 V.
21. Test conditions shown in (a) of Figure 4 on page 22 unless otherwise noted.
22. This part has a voltage regulator internally; t_{POWER} is the time that the power needs to be supplied above $V_{DD(minimum)}$ initially before a read or write operation can be initiated.
23. t_{CHZ}, t_{CLZ},t_{OELZ}, and t_{OEHZ} are specified with AC test conditions shown in part (b) of Figure 4 on page 22. Transition is measured ± 200 mV from steady-state voltage.
24. At any given voltage and temperature, t_{OEHZ} is less than t_{OELZ} and t_{CHZ} is less than t_{CLZ} to eliminate bus contention between SRAMs when sharing the same data bus. These specifications do not imply a bus contention condition, but reflect parameters guaranteed over worst case user conditions. Device is designed to achieve High Z prior to Low Z under the same system conditions.
25. This parameter is sampled and not 100% tested.

Downloaded from Arrow.com.

Switching Waveforms

Figure 5. Read Cycle Timing [26]

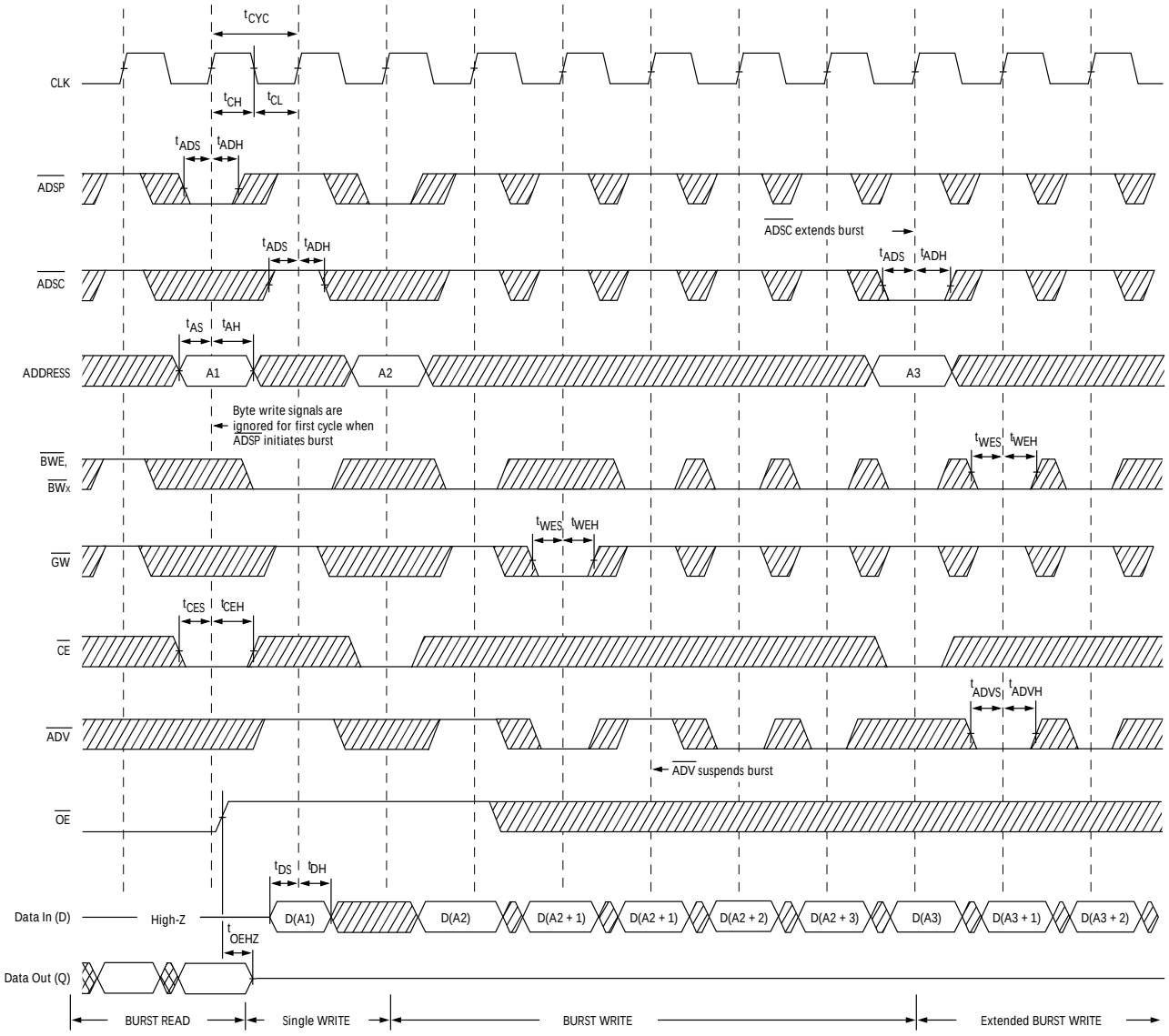


Note
26. On this diagram, when $\overline{CE}$ is LOW: $\overline{CE}_1$ is LOW, CE_2 is HIGH and $\overline{CE}_3$ is LOW. When $\overline{CE}$ is HIGH: $\overline{CE}_1$ is HIGH or CE_2 is LOW or $\overline{CE}_3$ is HIGH.

Downloaded from Arrow.com.

Switching Waveforms (continued)

Figure 6. Write Cycle Timing [27, 28]

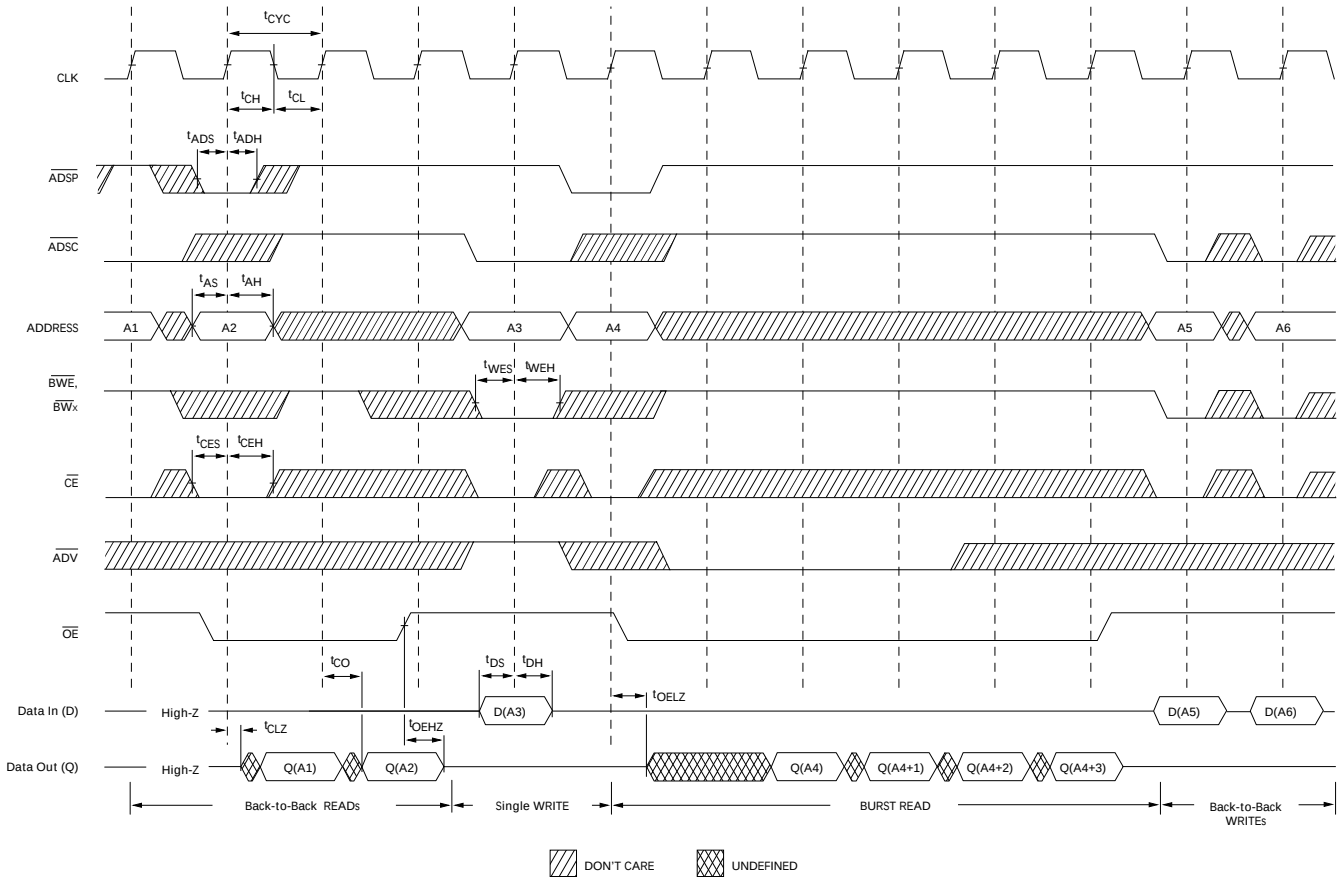


Notes
27. On this diagram, when $\overline{CE}$ is LOW: $\overline{CE}_1$ is LOW, CE_2 is HIGH and $\overline{CE}_3$ is LOW. When $\overline{CE}$ is HIGH: $\overline{CE}_1$ is HIGH or CE_2 is LOW or $\overline{CE}_3$ is HIGH.
28. Full width write can be initiated by either $\overline{GW}$ LOW; or by $\overline{GW}$ HIGH, $\overline{BWE}$ LOW and $\overline{BW}_X$ LOW.

Downloaded from Arrow.com.

Switching Waveforms (continued)

Figure 7. Read/Write Cycle Timing [29, 30, 31]

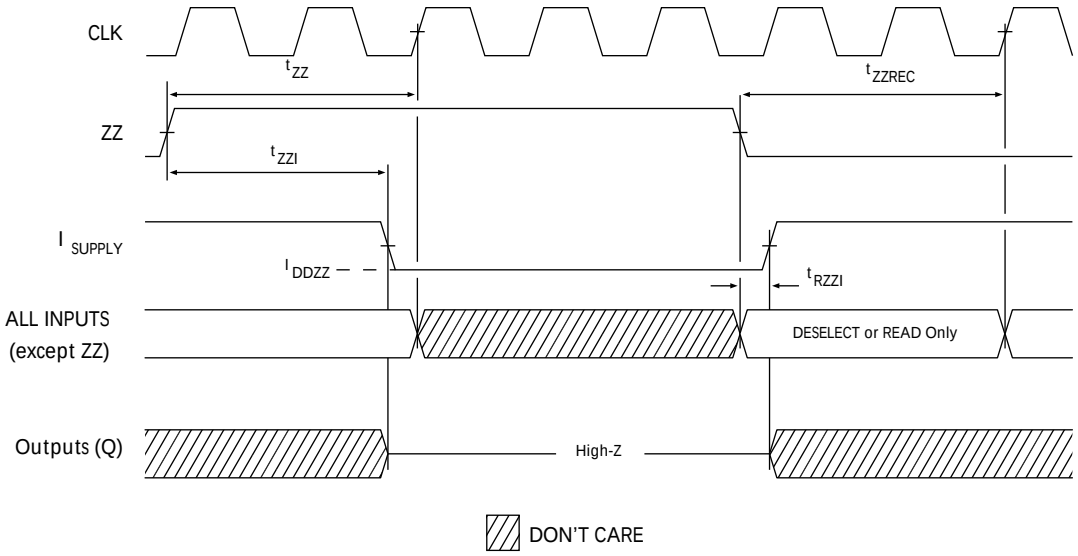


Notes
29. On this diagram, when $\overline{CE}$ is LOW: $\overline{CE}_1$ is LOW, CE_2 is HIGH and $\overline{CE}_3$ is LOW. When $\overline{CE}$ is HIGH: $\overline{CE}_1$ is HIGH or CE_2 is LOW or $\overline{CE}_3$ is HIGH.
30. The data bus (Q) remains in high Z following a WRITE cycle, unless a new read access is initiated by ADSP or ADSC.
31. GW is HIGH.

Downloaded from Arrow.com.

Switching Waveforms (continued)

Figure 8. ZZ Mode Timing [32, 33]



Notes
32. Device must be deselected when entering ZZ mode. See Cycle Descriptions table for all possible signal conditions to deselect the device.
33. DQs are in high Z when exiting ZZ sleep mode.

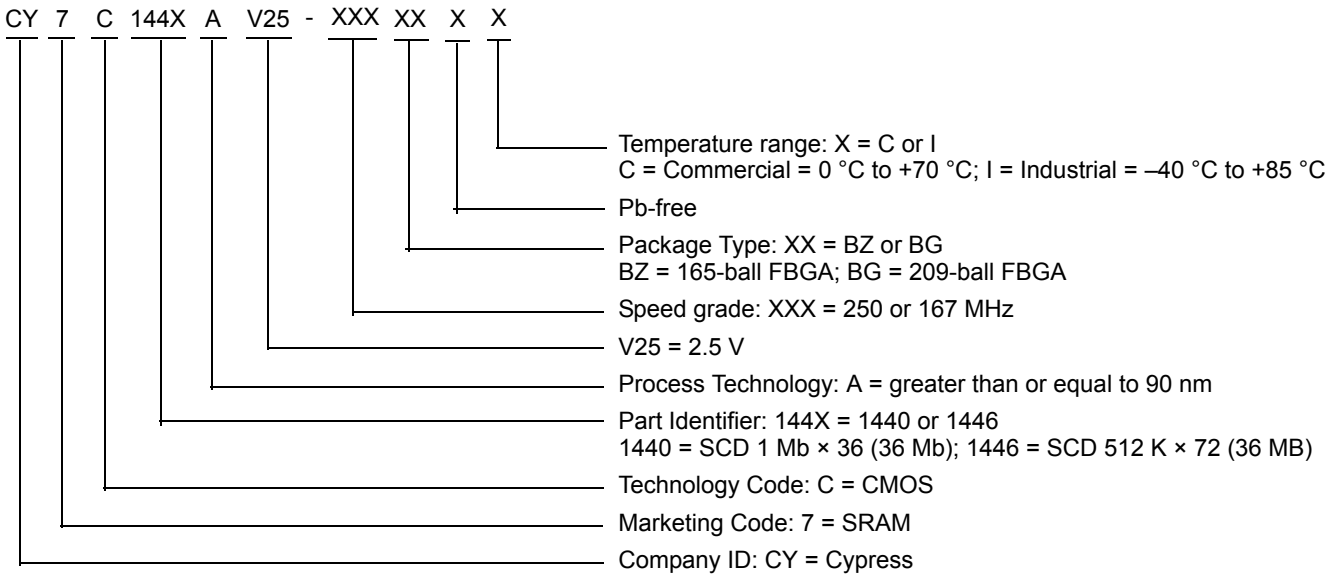
Downloaded from Arrow.com.

Ordering Information

Not all of the speed, package and temperature ranges are available. Please contact your local sales representative or visit www.cypress.com for actual products offered.

Speed (MHz)	Ordering Code	Package Diagram	Part and Package Type	Operating Range
250	CY7C1440AV25-250BZXI	51-85195	165-ball FBGA (15 × 17 × 1.4mm) Pb-free	Industrial
	CY7C1446AV25-250BGI	51-85167	209-ball FBGA (14 × 22 × 1.76mm)	
167	CY7C1440AV25-167BZXC	51-85195	165-ball FBGA (15 × 17 × 1.4mm) Pb-free	Commercial

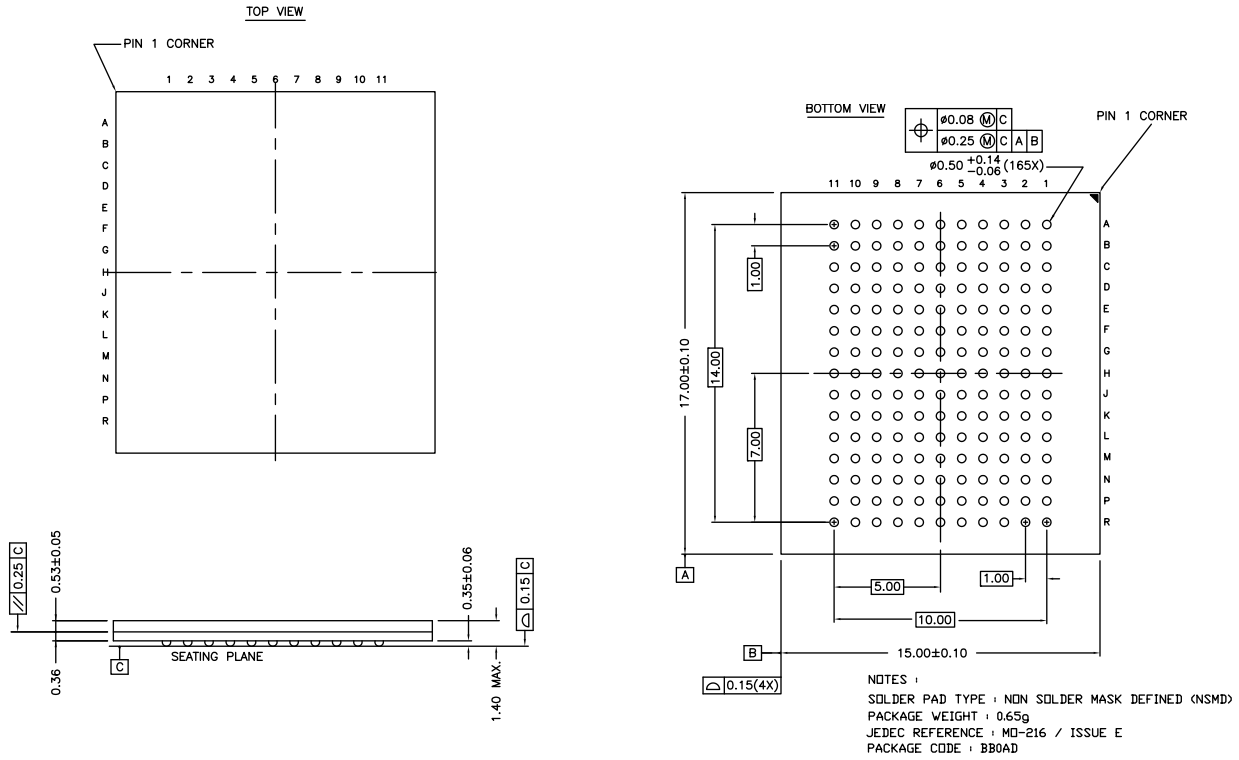
Ordering Code Definitions



Downloaded from Arrow.com.

Package Diagrams

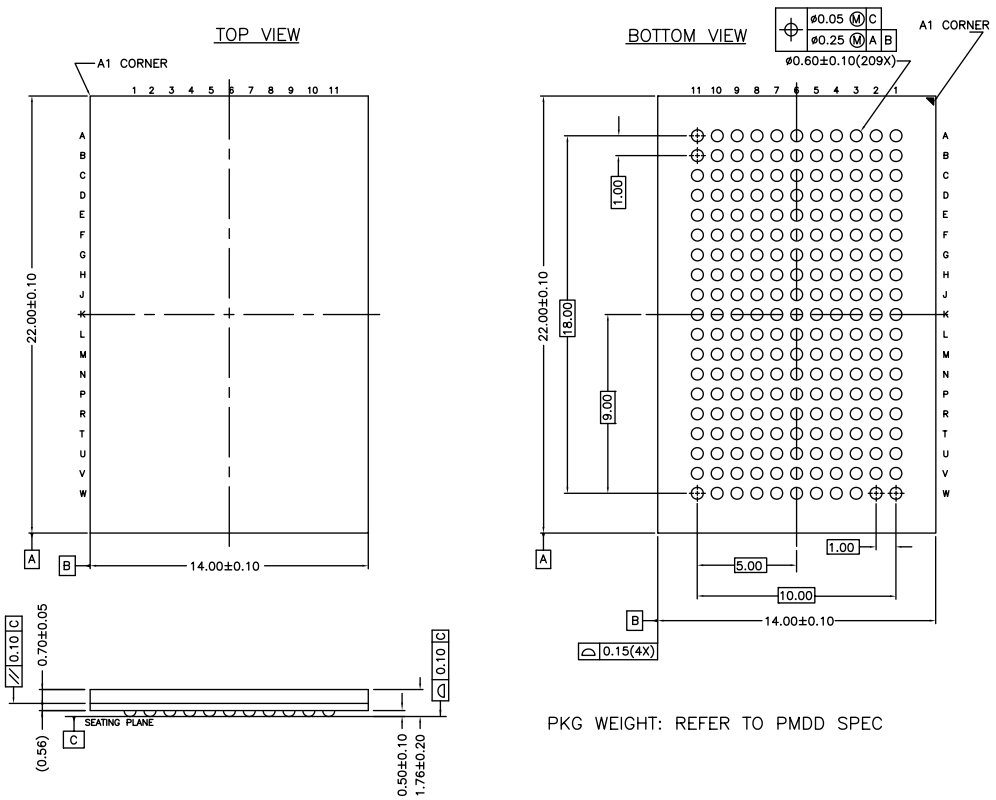
Figure 9. 165-ball FBGA (15 × 17 × 1.40 mm) (0.50 ball diameter) Package Outline, 51-85195



Downloaded from Arrow.com.

Package Diagrams (continued)

Figure 10. 209-ball FBGA (14 × 22 × 1.76 mm) BB209A Package Outline, 51-85167



51-85167 *C

Downloaded from Arrow.com.

Acronyms

Acronym	Description
CMOS	Complementary Metal Oxide Semiconductor
$\overline{CE}$	Chip Enable
FBGA	Fine-Pitch Ball Grid Array
I/O	Input/Output
JTAG	Joint Test Action Group
LSB	Least Significant Bit
MSB	Most Significant Bit
$\overline{OE}$	Output Enable
SRAM	Static Random Access Memory
TCK	Test Clock
TDI	Test Data-In
TDO	Test Data-Out
TMS	Test Mode Select
TTL	Transistor-Transistor Logic
$\overline{WE}$	Write Enable

Document Conventions

Units of Measure

Symbol	Unit of Measure
°C	degree Celsius
MHz	megahertz
µA	microampere
µs	microsecond
mA	milliampere
mm	millimeter
ms	millisecond
mV	millivolt
ns	nanosecond
%	percent
pF	picofarad
V	volt
W	watt

Downloaded from Arrow.com.

Document History Page

Document Title:CY7C1440AV25/CY7C1446AV25, 36-Mbit (1 M × 36/512 K × 72) Pipelined Sync SRAM Document Number: 001-70167				
Rev.	**ECN No.**	**Issue Date**	**Orig. of Change**	**Description of Change**
**	3281372	01/17/2012	NJY	New data sheet.
*A	3508385	01/25/2012	NJY	Changed status from Preliminary to Final.
*B	4234753	01/07/2014	PRIT	Updated Package Diagrams: Replaced spec 51-85165 with spec 51-85195. spec 51-85167 – Changed revision from *B to *C. Updated to new template. Completing Sunset Review.
*C	4575228	11/20/2014	PRIT	Updated Functional Description: Added “For a complete list of related documentation, click here.” at the end.
*D	4905904	09/02/2015	PRIT	Removed 1.8 V TAP AC Test Conditions. Removed 1.8 V TAP AC Output Load Equivalent. Updated TAP DC Electrical Characteristics and Operating Conditions: Removed details corresponding to Test Condition “V_{DDQ} = 1.8 V” for all parameters. Updated Electrical Characteristics: Removed details corresponding to Test Condition “for 1.8 V I/O” for all parameters. Updated Package Diagrams: spec 51-85195 – Changed revision from *C to *D. Updated to new template.
*E	5072691	01/05/2016	PRIT	No technical updates. Completing Sunset Review.

Downloaded from Arrow.com.

Sales, Solutions, and Legal Information

Worldwide Sales and Design Support

Cypress maintains a worldwide network of offices, solution centers, manufacturer's representatives, and distributors. To find the office closest to you, visit us at Cypress Locations.

Products

Automotive	cypress.com/go/automotive
Clocks & Buffers	cypress.com/go/clocks
Interface	cypress.com/go/interface
Lighting & Power Control	cypress.com/go/powerpsoc
Memory	cypress.com/go/memory
PSoC	cypress.com/go/psoc
Touch Sensing	cypress.com/go/touch
USB Controllers	cypress.com/go/USB
Wireless/RF	cypress.com/go/wireless

PSoC® Solutions

psoc.cypress.com/solutions

PSoC 1 | PSoC 3 | PSoC 4 | PSoC 5LP

Cypress Developer Community

Community | Forums | Blogs | Video | Training

Technical Support

cypress.com/go/support

© Cypress Semiconductor Corporation, 2012-2016. The information contained herein is subject to change without notice. Cypress Semiconductor Corporation assumes no responsibility for the use of any circuitry other than circuitry embodied in a Cypress product. Nor does it convey or imply any license under patent or other rights. Cypress products are not warranted nor intended to be used for medical, life support, life saving, critical control or safety applications, unless pursuant to an express written agreement with Cypress. Furthermore, Cypress does not authorize its products for use as critical components in life-support systems where a malfunction or failure may reasonably be expected to result in significant injury to the user. The inclusion of Cypress products in life-support systems application implies that the manufacturer assumes all risk of such use and in doing so indemnifies Cypress against all charges.

Any Source Code (software and/or firmware) is owned by Cypress Semiconductor Corporation (Cypress) and is protected by and subject to worldwide patent protection (United States and foreign), United States copyright laws and international treaty provisions. Cypress hereby grants to licensee a personal, non-exclusive, non-transferable license to copy, use, modify, create derivative works of, and compile the Cypress Source Code and derivative works for the sole purpose of creating custom software and or firmware in support of licensee product to be used only in conjunction with a Cypress integrated circuit as specified in the applicable agreement. Any reproduction, modification, translation, compilation, or representation of this Source Code except as specified above is prohibited without the express written permission of Cypress.

Disclaimer: CYPRESS MAKES NO WARRANTY OF ANY KIND, EXPRESS OR IMPLIED, WITH REGARD TO THIS MATERIAL, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE. Cypress reserves the right to make changes without further notice to the materials described herein. Cypress does not assume any liability arising out of the application or use of any product or circuit described herein. Cypress does not authorize its products for use as critical components in life-support systems where a malfunction or failure may reasonably be expected to result in significant injury to the user. The inclusion of Cypress' product in a life-support systems application implies that the manufacturer assumes all risk of such use and in doing so indemnifies Cypress against all charges.

Use may be limited by and subject to the applicable Cypress software license agreement.

i486 is a trademark, and Intel and Pentium are registered trademarks of Intel Corporation. PowerPC is a trademark of IBM Corporation. All products and company names mentioned in this document may be the trademarks of their respective holders.

Downloaded from Arrow.com.