AC Servo System
1S Series

OMRON

Optimized installation and setup
Increased machine productivity



EtherCAT®

SYSMAC
always in control

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State of the art technology applied to general purpose servo

Improved machine design. Increased machine productivity

Designed to meet the machine requirements, the 1S servo technology optimizes the full cycle, through the machine design, installation and commissioning tasks and finally to the maintenance once in production. In addition to the traditional motion solution, the 1S servo offers high resolution multi-turn encoder without battery backup, safety network built-in and improved loop control allowing accurate and higher machine productivity.

Capacity range is expanded, but 1S concept can be maintained.



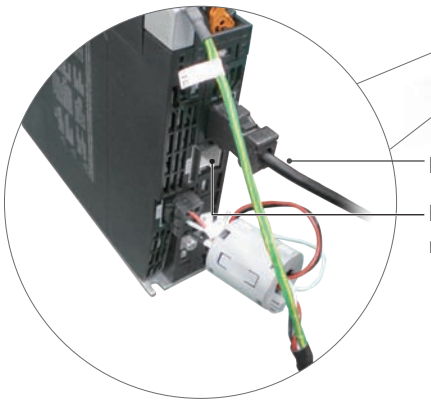
Direct wiring of I/O signals. No need for terminal block units

NO WIRING

Optimized installation and commissioning tasks

Cabinet size reduction *1

- Compact servo drive with same height throughout the power range from 0.1 to 7.5 kW



Pre-assembled motor cables

Embedded relay for direct motor brake control

- Fast and secure screw-less push-in in all connectors
- Pluggable connectors for easy pre-wiring and system maintenance *2

Servo features

- Power range from 50 W to 15 kW
- 23 bit high resolution encoder
- Battery-free absolute multi-turn encoder
- Improved loop control for low overshoot and quick settling time
- Safety function built-in:
  - Hardwired Safe Torque Off :
    EN ISO 13849-1(Cat.3 PLe), EN61508(SIL3), EN62061(SIL3), EN61800-5-2(STO)
  - Safety over EtherCAT(FSoE) :
    EN ISO 13849-1(Cat.3 PLd), EN61508(SIL2), EN62061(SIL2), EN61800-5-2(STO)

*1 Side-by-side Installation
For servo drivers of 3 kW or less, limit the operating ambient temperature of Servo Drive from 0 to 45°C when the distance is less than 10 mm.
For servo drivers of 4 kW or more, the distance between servo drivers must be 40 mm or more.
*2 Except 15 kW (200 V)

Expanded with High Capacity Range: 4 - 15 kW



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Simplified machine design and maintenance

- No battery, no maintenance
- No need for homing sequence improving machine uptime
- 23 bit high resolution encoder as standard
- Absolute multi-turn encoder design without mechanics: 16 bits, 65536 turns
- Compact and smaller motor size

50% setup time reduction*

Servo sizing

- Servo sizing tool for the entire machine
- Graphical environment of the kinematic chain
- Electronic CAM import from Sysmac Studio

Save 40% *

System configuration

- NJ project auto-builder from servo sizing file
- Quick setup wizard for key parameters
- Parameters transfer in less than 400 ms

Save 60% *

Gain tuning & test run

PATENT PENDING

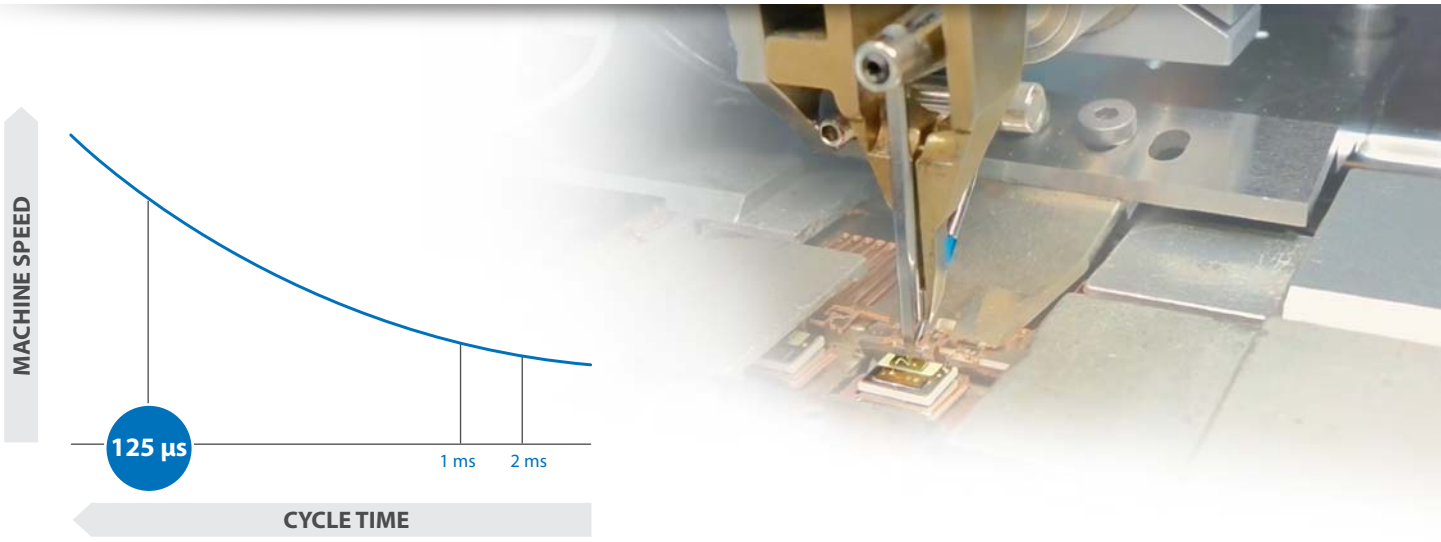
- "Best effort" feature for quick stabilization time
- Easy tuning with intelligent gain search in less than 2 minutes
- Wizard for tuning, test run & monitoring
- Advanced tuning simulation to reduce testing effort and prevent machine damage

Save 50% *

* Performance comparison with previous Omron products based on Omron investigation in July 2019.

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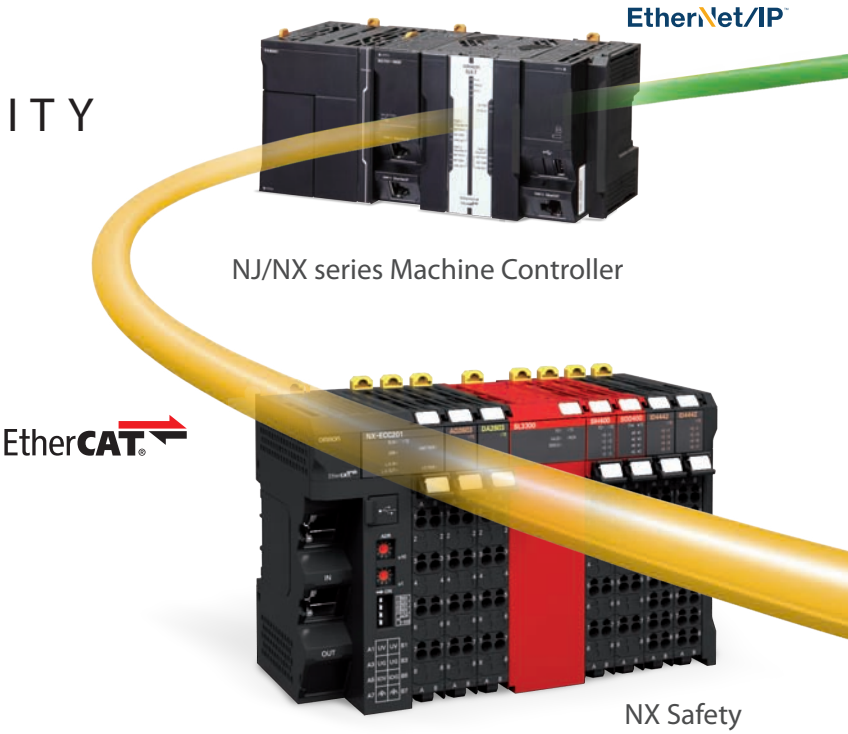
Totally integrated, totally in control



HIGHER PRODUCTIVITY

125 µs system cycle

- Faster machine speed keeping same accuracy
- Accurate profile generation in the controller
- The 23 bit high resolution encoder in combination with the improved loop control provide an accurate following profile



NJ/NX series Machine Controller

NX Safety

INTEGRATED SAFETY

Safety control via EtherCAT

- Simplified safety installation
- Reduction of safety devices
- Safety function built-in: Fail Safe over EtherCAT (FSoE) Safe Torque Off
- Safety approval: EN ISO 13849-1(Cat.3 PLd), EN61508(SIL2), EN62061(SIL2), EN61800-5-2(STO)
- Troubleshooter integrated with Sysmac Studio

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Servo sizing | Setup | Logic, Motion & Safety programming | Simulation | Commissioning

TOTALLY IN CONTROL



Sysmac Studio

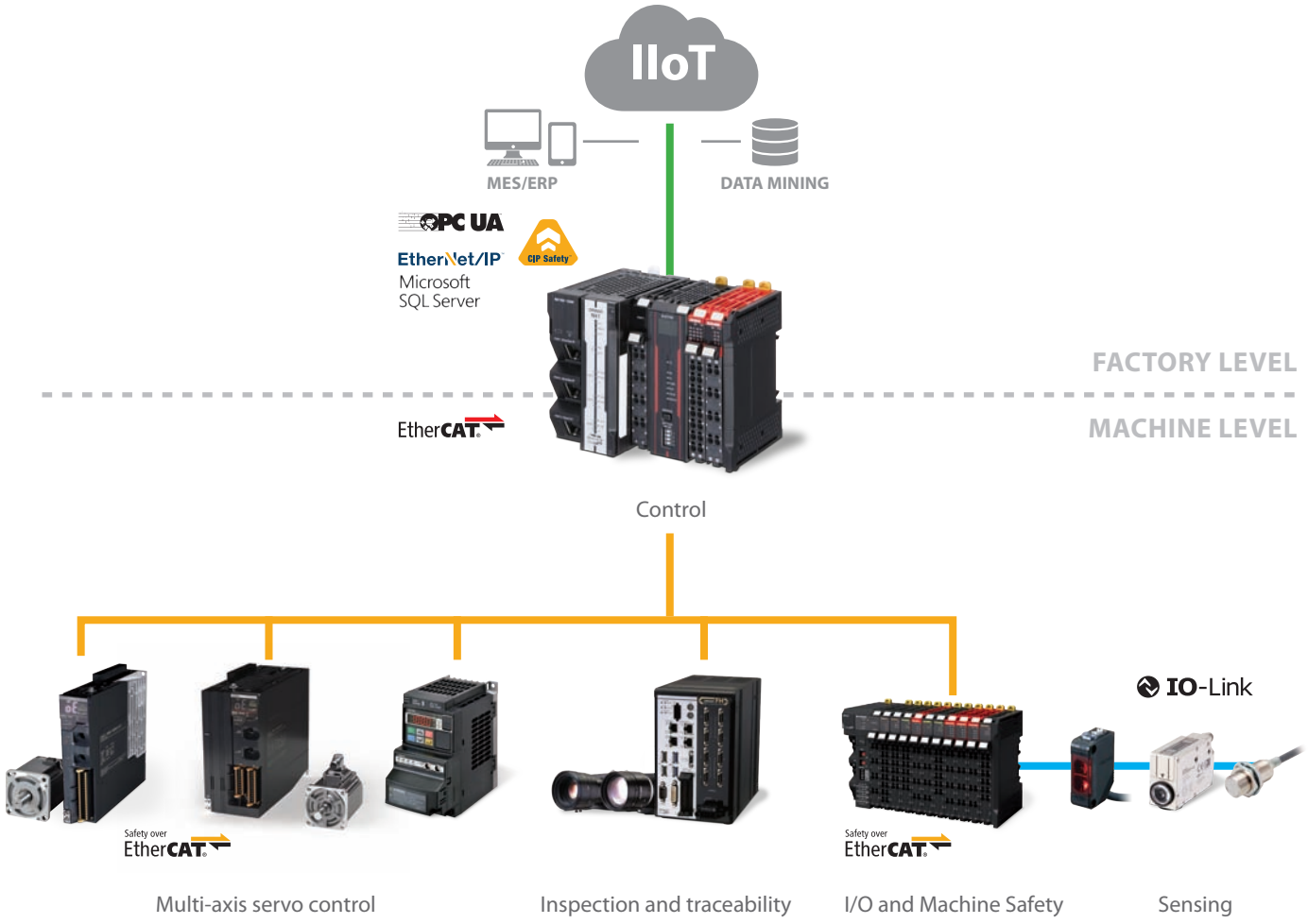
- Simplified servo setup: Direct use of servo sizing calculation
- Open standard IEC 61131-3 programming
- Standard PLCopen Function Blocks for Motion and Safety
- Sysmac Library for fast engineering and optimized machine availability
  - Application libraries
  - Optimized productivity
  - Predictive maintenance
  - Reduced downtime

Sysmac Library



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Sysmac Automation Platform



Software



Microsoft SQL Server

Sysmac Studio, the integrated software

- One single tool for logic sequence, motion, safety, robotics, vision and HMI
- Fully compliant with open standard IEC 61131-3
- PLCopen Function Blocks for Motion and Safety
- Supports Ladder, Structured Text and In-Line ST programming with a rich instruction set
- CAM editor for easy programming of complex motion profiles
- Database Connectivity Function Block library

Sysmac Library

- The Sysmac Library is a collection of software functional components that can be used in programs for the NJ/NX Machine Automation Controllers. Sample programs and HMI screen samples are also available.

Please download it from following URL and install to Sysmac Studio. http://www.ia.omron.com/sysmac_library/

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Sysmac servo family

Machine Controller

OPC UA
Microsoft SQL Server
EtherNet/IP
EtherCAT



CIP Safety
Safety over EtherCAT

The NX-series Safety Network Controller connected with the NX1 Machine Controller enables the use of both EtherNet/IP + CIP Safety and EtherCAT + FSoE at the same time.

NJ/NX series

- Logic sequence, Motion, Safety, Robotics and Database connection functionality
- Scalable motion control: CPUs from 2 up to 256 axes
- IEC 61131-3 controller
- PLCopen Function Blocks for Motion Control and Safety
- Advanced motion with Robotics functionality
- Built-in EtherCAT and EtherNet/IP ports

Motion

EtherCAT



Safety over EtherCAT
SIL3 PLe

EtherCAT



Safety over EtherCAT

EtherCAT



1S Motion Safety servo

- Servo drive for rotary motors
- Up to 3kW
- Battery-free absolute multi-turn encoder
- Advanced safety functions: STO/SS1/SS2/SOS/SLS/SLP/SDI/SBC
- Servo drive for rotary motors with one cable connection

1S Servo System - General purpose servo

- Servo drive for rotary motors
- Up to 15kW
- Battery-free absolute multi-turn encoder
- Safety function: R88D-1SN□-ECT : STO
  R88D-1SN□-ECT-51: STO/SS1/SLS

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GOLDEN MOUSETRAP AWARDS

G5 Servo System

- Servo drive for rotary or linear motors
- Rotary motor: Up to 15 kW
- Iron- core and Ironless linear motor models: Up to 2100 N peak force
- Safety function: STO (Hardwired Safe Torque Off only)
- Full closed loop control

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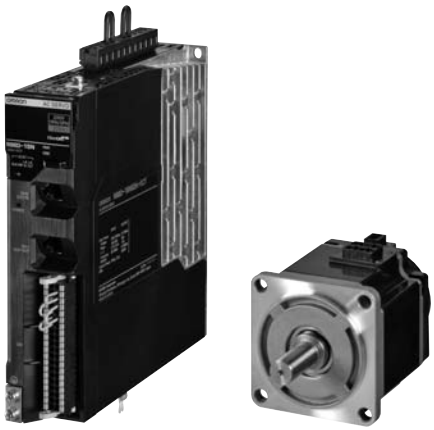
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AC Servo System 1S-series

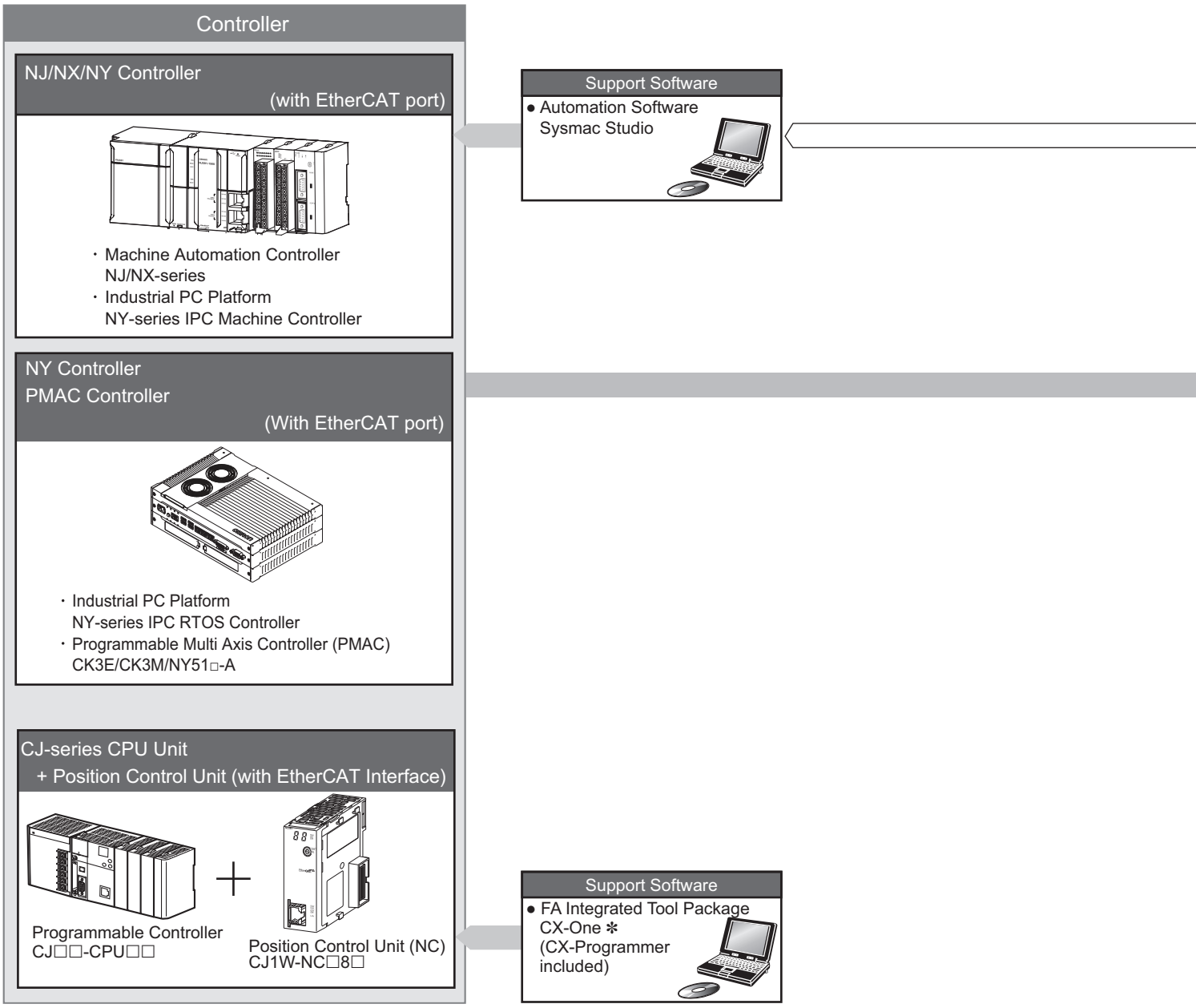
R88M-1□/R88D-1SN□-ECT

Best Machine Architecture

- Simple installation and wiring contributes to board design efficiency
- EtherCAT Communications Cycle of 125 µs
- Achievement of Safety on EtherCAT Network
- Supports two-degree-of-freedom control
- Battery-free system reduces maintenance and space
- Comes equipped with a 23-bit ABS encoder
- 350% momentary maximum torque (200 V, 750 W max.)



System Configuration



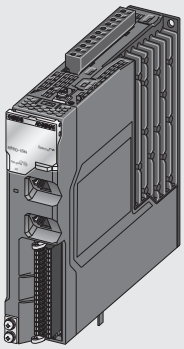
✻ You cannot use the CX-One to make the settings of 1S-series Servo Drives. Obtain the Sysmac Studio.
Note: PMAC is an abbreviation for Programmable Multi Axis Controller.

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USB communications

EtherCAT communications

Servo Drive



- 1S-series Servo Drive
  R88D-1SN□-ECT
  100 VAC
  200 VAC
  400 VAC

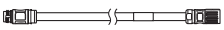
Power signal

Power cable

- Standard cable
  - Without brake wire
    R88A-CA1□□□□S
  - With brake wire
    R88A-CA1□□□□B
- Flexible cable
  - Without brake wire
    R88A-CA1□□□□SF
    R88A-CA1A□□□SFR
  - With brake wire
    R88A-CA1□□□□BF



- Extension Cable (Flexible)
  R88A-CA1□E□□BF



Brake cable for 750 W max.

- Standard cable
  R88A-CA1A□□□B
- Flexible cable
  R88A-CA1A□□□BF
  R88A-CA1A□□□BFR

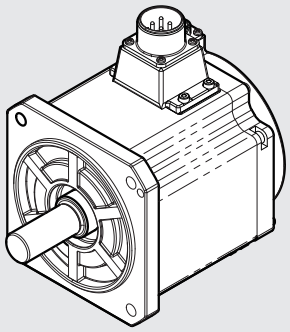
Feedback signal

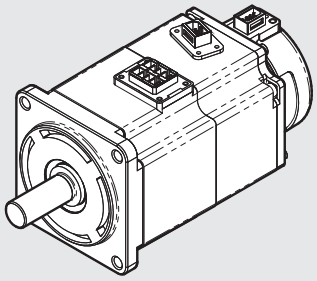
Encoder cable

- Standard cable
  R88A-CR1A□□□C
  R88A-CR1B□□□N
  R88A-CR1B□□□V
- Flexible cable
  R88A-CR1A□□□CF
  R88A-CR1B□□□NF
  R88A-CR1B□□□VF



Servomotor



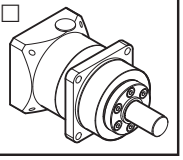


- 1S-series Servomotor
  R88M-1L□/-1M□
  3,000 r/min
  2,000 r/min
  1,500 r/min
  1,000 r/min

ABS

Decelerator

- Backlash: 3 Arcminutes Max.
  R88G-HPG□
- Backlash: 15 Arcminutes Max.
  R88G-VRXF□



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AC Servo Drives with Built-in EtherCAT Communications [1S-series]

R88D-1SN□-ECT

Contents

- Ordering Information
- Specifications
- EtherCAT Communication Specifications
- Version Information
- Names and Functions
- Dimensions



Ordering Information

Refer to the Ordering Information.

Specifications

General Specifications

Item			Specifications
Operating ambient temperature and humidity			0 to 55°C, 90% max. (with no condensation)
Storage ambient temperature and humidity			-20 to 65°C, 90% max. (with no condensation)
Operating and storage atmosphere			No corrosive gases
Operating altitude			1,000 m max.
Vibration resistance			10 to 60 Hz and at an acceleration of 5.88 m/s^2 or less (Not to be run continuously at the resonance frequency)
Insulation resistance			Between power supply terminals/power terminals and PE terminals: 0.5 MΩ min. (at 500 VDC)
Dielectric strength			Between power supply terminals/power terminals and PE terminals: 1,500 VAC for 1 min (at 50/60 Hz)
Protective structure			IP20 (Built into IP54 panel)
International standard	**EU Directives and UK legislation**	**EMC**	EN 61800-3 second environment, C3 category (EN61326-3-1 *1; Functional Safety)
		Low Voltage	EN 61800-5-1
		Machinery	EN ISO 13849-1 (Cat.3), EN 61508, EN 62061, EN 61800-5-2
	UL standards		UL 61800-5-1
	CSA standards		CSA C22.2 No. 274
	Korean Radio Regulations (KC)		Compliant
	Australian EMC Labelling Requirements (RCM)		Compliant
	SEMI standards		Can conform to the standard for momentary power interruptions (for no-load operation).
	Ship standards (NK/LR)		Not compliant

✻ The following product models are applicable to EN61000-6-7.
Applicable models: R88D-1SN55□-ECT, R88D-1SN75□-ECT, R88D-1SN150□-ECT

Note: The above items reflect individual evaluation testing. The results may differ under compound conditions.

The detail of Machinery Directive is as follows:
The STO function via safety input signals: EN ISO 13849-1 (Cat3 PLe), EN 61508 (SIL3), EN 62061 (SIL3), EN 61800-5-2 (STO)
The STO function via EtherCAT communications: EN ISO 13849-1 (Cat.3 PLd), EN 61508 (SIL2), EN 62061 (SIL2), EN 61800-5-2 (STO)

Precautions for Correct Use

Disconnect all connections to the Servo Drive before attempting a megger test (insulation resistance measurement) on a Servo Drive. Not doing so may result in the Servo Drive failure.
Do not perform a dielectric strength test on the Servo Drive. Internal elements may be damaged.

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Characteristics

100-VAC Input Models

Servo Drive model (R88D-)			1SN01L-ECT	1SN02L-ECT	1SN04L-ECT
Item			100 W	200 W	400 W
Input	Main circuit	Power supply voltage	Single-phase 100 to 120 VAC (85 to 132 V) ✻1 Rise time 500 ms max. ✻2		
		Frequency	50/60 Hz (47.5 to 63 Hz) ✻1		
	Control circuit	Power supply voltage	24 VDC (21.6 to 26.4 V)		
		Current consumption ✻3	600 mA		
	Rated input current [A (rms)] (Main circuit power supply voltage: 120 VAC)	Single-phase	2.9	4.9	8.4
		3-phase	---	---	---
Output	Rated current [A (rms)]		1.5	2.5	4.8
	Maximum current [A (rms)]		4.7	8.4	14.7
Heat value [W]		Main circuit ✻4	14.8	23.4	33.1
		Control circuit	11	11	13.2
Applicable Servomotor rated output [W]			100	200	400
3,000-r/min Servomotor (R88M-)		Batteryless 23-bit ABS	1M05030S 1M10030S	1M20030S	1M40030S
Hold time at momentary power interruption (Main circuit power supply voltage: 100 VAC)			10 ms (Load condition: rated output) ✻5		
SCCR [A (rms)]			5000		
Weight [kg]			1.2	1.5	1.9

✻1. The values outside parentheses indicate the rated value, and the values inside parentheses indicate the range of acceptable variation.
✻2. If the power supply is turned ON slowly, a Regeneration Circuit Error Detected during Power ON (Error No. 14.02) may occur. Check that the power supply has a capacity sufficiently greater than the total capacity of the Servo Drive and the peripheral devices.
✻3. Select a DC power supply in consideration of the current values that are specified in the current consumption.
The rated current value that is printed on the product nameplate is a condition to apply the 1S-series product for the UL/Low Voltage Directive. Therefore, you do not need to consider it when you select a DC power supply for each model.
✻4. This is the maximum heating value in applicable Servomotors.
Refer to the table on the page 14 for the Heating Values of Applicable Servomotors.
✻5. This hold time at momentary power interruption is that of the main circuit. In order to maintain power supply to the control circuit at momentary power interruption, use a DC power supply, which meets the following conditions, for the control power supply:
Reinforced insulation or double insulation, and the output hold time of 10 ms or more.

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200-VAC Input Models

Servo Drive model (R88D-)			1SN01H-ECT	1SN02H-ECT	1SN04H-ECT	1SN08H-ECT
Item			100 W	200 W	400 W	750 W
Input	Main circuit	Power supply voltage	Single-phase and 3-phase 200 to 240 VAC (170 to 252 V) ✻1 Rise time 500 ms max. ✻2			
		Frequency	50/60 Hz (47.5 to 63 Hz) ✻1			
	Control circuit	Power supply voltage	24 VDC (21.6 to 26.4 V)			
		Current consumption ✻3	600 mA			
	Rated current [A (rms)] (Main circuit power supply voltage: 240 VAC)	Single-phase	1.8	2.7	4.6	7.3
		3-phase	1.0	1.5	2.7	4.0
Output	Rated current [A (rms)]		0.8	1.5	2.5	4.6
	Maximum current [A (rms)]		3.1	5.6	9.1	16.9
Heat value [W]		Main circuit ✻4	15.7/15.3 ✻5	15.2/14.6 ✻5	22.4/22.4 ✻5	40/39.7 ✻5
		Control circuit	11	11	11	13.2
Applicable Servomotor rated output [W]			100	200	400	750
3,000-r/min Servomotor (R88M-)		Batteryless 23-bit ABS	1M05030T 1M10030T	1M20030T	1M40030T	1M75030T
2,000-r/min Servomotor (R88M-)		Batteryless 23-bit ABS	---	---	---	---
1,000-r/min Servomotor (R88M-)		Batteryless 23-bit ABS	---	---	---	---
Hold time at momentary power interruption (Main circuit power supply voltage: 200 VAC)			10 ms (Load condition: rated output) ✻6			
SCCR [A (rms)]			5000			
Weight [kg]			1.2	1.2	1.5	2.0

Servo Drive model (R88D-)			1SN10H-ECT	1SN15H-ECT	1SN20H-ECT	1SN30H-ECT
Item			1 kW	1.5 kW	2 kW	3 kW
Input	Main circuit	Power supply voltage	3-phase 200 to 240 VAC (170 to 252 V) ✻1	Single-phase and 3-phase 200 to 240 VAC (170 to 252 V) ✻1	3-phase 200 to 240 VAC (170 to 252 V) ✻1	
			Rise time 500 ms max. ✻2			
		Frequency	50/60 Hz (47.5 to 63 Hz) ✻1			
	Control circuit	Power supply voltage	24 VDC (21.6 to 26.4 V)			
		Current consumption ✻3	600 mA	900 mA		
	Rated current [A (rms)] (Main circuit power supply voltage: 240 VAC)	Single-phase	---	15.7	---	---
		3-phase	5.8	9.0	13.0	15.9
Output	Rated current [A (rms)]		7.7	9.7	16.2	22.3
	Maximum current [A (rms)]		16.9	28.4	41.0	54.7
Heat value [W]		Main circuit ✻4	46.5	85.5/85.5 ✻5	128.9	167.5
		Control circuit	13.2	20.4	20.4	20.4
Applicable Servomotor rated output [W]			1,000	1,500	2,000	3,000
3,000-r/min Servomotor (R88M-)		Batteryless 23-bit ABS	1L1K030T	1L1K530T	1L2K030T	1L3K030T
2,000-r/min Servomotor (R88M-)		Batteryless 23-bit ABS	1M1K020T	1M1K520T	1M2K020T	1M3K020T
1,000-r/min Servomotor (R88M-)		Batteryless 23-bit ABS	1M90010T	---	1M2K010T	1M3K010T
Hold time at momentary power interruption (Main circuit power supply voltage: 200 VAC)			10 ms (Load condition: rated output) ✻6			
SCCR [A (rms)]			5000			
Weight [kg]			2.0	3.4	3.4	3.4

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Servo Drive model (R88D-)			1SN55H-ECT	1SN75H-ECT	1SN150H-ECT
Item			5.5 kW	7.5 kW	15 kW
Input	Main circuit	Power supply voltage	3-phase 200 to 240 VAC (170 to 252 V) ✻1 Rise time 500 ms max. ✻2		
		Frequency	50/60 Hz (47.5 to 63 Hz) ✻1		
	Control circuit	Power supply voltage	24 VDC (21.6 to 26.4 V)		
		Current consumption ✻3	900 mA		1,200 mA
	Rated current [A (rms)] (Main circuit power supply voltage: 240 VAC)	3-phase	27.0	38.0	77.0
Output	Rated current [A (rms)]		28.6	42.0	70.0
	Maximum current [A (rms)]		84.8	113	169.7
Heat value [W]		Main circuit ✻4	290	360	610
		Control circuit	19.9		29.7
Applicable Servomotor rated output [W]			5,500	7,500	15,000
3,000-r/min Servomotor (R88M-)		Batteryless 23-bit ABS	1L4K030T 1L4K730T	---	---
2,000-r/min Servomotor (R88M-)		Batteryless 23-bit ABS	---	---	---
1,500-r/min Servomotor (R88M-)		Batteryless 23-bit ABS	1M4K015T 1M5K015T	1M7K515T	1M11K015T 1M15K015T
1,000-r/min Servomotor (R88M-)		Batteryless 23-bit ABS	---	---	---
Hold time at momentary power interruption (Main circuit power supply voltage: 200 VAC)			10 ms (Load condition: rated output) ✻6		
SCCR [A (rms)]			5000		
Weight [kg]			9.4	9.4	21

✻1. The values outside parentheses indicate the rated value, and the values inside parentheses indicate the range of acceptable variation.
✻2. If the power supply is turned ON slowly, a Regeneration Circuit Error Detected during Power ON (Error No. 14.02) may occur. Check that the power supply has a capacity sufficiently greater than the total capacity of the Servo Drive and the peripheral devices.
✻3. Select a DC power supply in consideration of the current values that are specified in the current consumption.
The rated current value that is printed on the product nameplate is a condition to apply the 1S-series product for the UL/Low Voltage Directive. Therefore, you do not need to consider it when you select a DC power supply for each model.
✻4. This is the maximum heating value in applicable Servomotors.
Refer to the table on the next page for the heating value of each applicable Servomotor.
✻5. The first value is for single-phase input power and the second value is for 3-phase input power.
✻6. This hold time at momentary power interruption is that of the main circuit. In order to maintain power supply to the control circuit at momentary power interruption, use a DC power supply, which meets the following conditions, for the control power supply:
Reinforced insulation or double insulation, and the output hold time of 10 ms or more.

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400-VAC Input Models

Use a neutral grounded 400 VAC 3-phase power supply for the 400 VAC input models.

Servo Drive model (R88D-)			1SN06F-ECT	1SN10F-ECT	1SN15F-ECT	1SN20F-ECT
Item			600 W	1 kW	1.5 kW	2 kW
Input	Main circuit	Power supply voltage	3-phase 380 to 480 VAC (323 to 504 V) ✻1 Rise time 500 ms max. ✻2			
		Frequency	50/60 Hz (47.5 to 63 Hz) ✻1			
	Control circuit	Power supply voltage	24 VDC (21.6 to 26.4 V)			
		Current consumption ✻3	900 mA			
	Rated current [A (rms)] (Main circuit power supply voltage: 480 VAC)	3-phase	2.4	3.1	4.3	6.5
Output	Rated current [A (rms)]		1.8	4.1	4.7	7.8
	Maximum current [A (rms)]		5.5	9.6	14.1	19.8
Heat value [W]		Main circuit ✻4	20.2	52.1	77.5	106.8
		Control circuit	20.4	20.4	20.4	20.4
Applicable Servomotor rated output [W]			600	1,000	1,500	2,000
3,000-r/min Servomotor (R88M-)		Batteryless 23-bit ABS	---	1L75030C 1L1K030C	1L1K530C	1L2K030C
2,000-r/min Servomotor (R88M-)		Batteryless 23-bit ABS	1M40020C 1M60020C	1M1K020C	1M1K520C	1M2K020C
1,000-r/min Servomotor (R88M-)		Batteryless 23-bit ABS	---	1M90010C	---	1M2K010C
Hold time at momentary power interruption (Main circuit power supply voltage: 400 VAC)			10 ms (Load condition: rated output) ✻5			
SCCR [A (rms)]			5000			
Weight [kg]			3.4	3.4	3.4	3.4

Servo Drive model (R88D-)			1SN30F-ECT	1SN55F-ECT	1SN75F-ECT	1SN150F-ECT
Item			3kW	5.5kW	7.5kW	15kW
Input	Main circuit	Power supply voltage	3-phase 380 to 480 VAC (323 to 504 V) ✻1 Rise time 500 ms max. ✻2			
		Frequency	50/60 Hz (47.5 to 63 Hz) ✻1			
	Control circuit	Power supply voltage	24 VDC (21.6 to 26.4 V)			
		Current consumption ✻3	900 mA			1,200 mA
	Rated current [A (rms)] (Main circuit power supply voltage: 480 VAC)	3-phase	8.4	16.0	23.0	40.0
Output	Rated current [A (rms)]		11.3	14.5	22.6	33.9
	Maximum current [A (rms)]		28.3	42.4	56.5	84.8
Heat value [W]		Main circuit ✻4	143.3	280.0	280.0	440.0
		Control circuit	20.4	19.9		29.7
Applicable Servomotor rated output [W]			3,000	5,500	7,500	15,000
3,000-r/min Servomotor (R88M-)		Batteryless 23-bit ABS	1L3K030C	1L4K030C 1L5K030C	---	---
2,000-r/min Servomotor (R88M-)		Batteryless 23-bit ABS	1M3K020C	---	---	---
1,500-r/min Servomotor (R88M-)		Batteryless 23-bit ABS	---	1M4K015C 1M5K515C	1M7K515C	1M11K015C 1M15K015C
1,000-r/min Servomotor (R88M-)		Batteryless 23-bit ABS	1M3K010C	---	---	---
Hold time at momentary power interruption (Main circuit power supply voltage: 400 VAC)			10 ms (Load condition: rated output) ✻5			
SCCR [A (rms)]			5000			
Weight [kg]			3.4	9.4	9.4	21

✻1. The values outside parentheses indicate the rated value, and the values inside parentheses indicate the range of acceptable variation.
✻2. If the power supply is turned ON slowly, a Regeneration Circuit Error Detected during Power ON (Error No. 14.02) may occur. Check that the power supply has a capacity sufficiently greater than the total capacity of the Servo Drive and the peripheral devices.
✻3. Select a DC power supply in consideration of the current values that are specified in the current consumption.
The rated current value that is printed on the product nameplate is a condition to apply the 1S-series product for the UL/Low Voltage Directive. Therefore, you do not need to consider it when you select a DC power supply for each model.
✻4. This is the maximum heating value in applicable Servomotors.
Refer to the table below for the heating value of each applicable Servomotor.
✻5. This hold time at momentary power interruption is that of the main circuit. In order to maintain power supply to the control circuit at momentary power interruption, use a DC power supply, which meets the following conditions, for the control power supply:
Reinforced insulation or double insulation, and the output hold time of 10 ms or more.

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Relationship between Servo Drive, Servomotors and the Main Circuit Heating Value

Servo Drive model	Servomotor model	Main circuit heat value [W]
R88D-1SN01L-ECT	R88M-1M05030S-☐	11.2
	R88M-1M10030S-☐	14.8
R88D-1SN01H-ECT	R88M-1M05030T-☐	13.2/13.2 ✻
	R88M-1M10030T-☐	15.7/15.3 ✻
R88D-1SN10H-ECT	R88M-1L1K030T-☐	46.5
	R88M-1M1K020T-☐	37.7
	R88M-1M90010T-☐	42.9
R88D-1SN15H-ECT	R88M-1L1K530T-☐	85.5/85.5 ✻
	R88M-1M1K520T-☐	84/84 ✻
R88D-1SN20H-ECT	R88M-1L2K030T-☐	128.9
	R88M-1M2K020T-☐	91.3
	R88M-1M2K010T-☐	109.1
R88D-1SN30H-ECT	R88M-1L3K030T-☐	167.5
	R88M-1M3K020T-☐	125.5
	R88M-1M3K010T-☐	156.7
R88D-1SN55H-ECT	R88M-1L4K030T-☐	250
	R88M-1M4K015T-☐	270
	R88M-1L4K730T-☐	290
	R88M-1M5K015T-☐	290
R88D-1SN75H-ECT	R88M-1M7K515T-☐	360
R88D-1SN150H-ECT	R88M-1M11K015T-☐	490
	R88M-1M15K015T-☐	610
R88D-1SN06F-ECT	R88M-1M40020C-☐	14.4
	R88M-1M60020C-☐	20.2
R88D-1SN10F-ECT	R88M-1L75030C-☐	51.1
	R88M-1L1K030C-☐	52.1
	R88M-1M1K020C-☐	33.4
	R88M-1M90010C-☐	40.2
R88D-1SN15F-ECT	R88M-1L1K530C-☐	77.5
	R88M-1M1K520C-☐	47.9
R88D-1SN20F-ECT	R88M-1L2K030C-☐	106.8
	R88M-1M2K020C-☐	65.7
	R88M-1M2K010C-☐	79.6
R88D-1SN30F-ECT	R88M-1L3K030C-☐	143.3
	R88M-1M3K020C-☐	96.5
	R88M-1M3K010C-☐	115.5
R88D-1SN55F-ECT	R88M-1L4K030C-☐	250
	R88M-1M4K015C-☐	280
	R88M-1L5K030C-☐	250
	R88M-1M5K515C-☐	280
R88D-1SN75F-ECT	R88M-1M7K515C-☐	280
R88D-1SN150F-ECT	R88M-1M11K015C-☐	390
	R88M-1M15K015C-☐	440

✻ The first value is for single-phase input power and the second value is for 3-phase input power.

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EtherCAT Communications Specifications

Item	Specifications
Communications standard	IEC 61158 Type 12, IEC 61800-7 CiA 402 Drive Profile
Physical layer	100BASE-TX (IEEE802.3)
Connectors	RJ45 × 2 (shielded) ECAT IN: EtherCAT input ECAT OUT: EtherCAT output
Communications media	Recommended media: Twisted-pair cable, which is doubly shielded by the aluminum tape and braid, with Ethernet Category 5 (100BASE-TX) or higher
Communications distance	Distance between nodes: 100 m max.
Process data	Fixed PDO mapping Variable PDO mapping
Mailbox (CoE)	Emergency messages, SDO requests, SDO responses, and SDO information
Synchronization mode and communications cycle	DC Mode (Synchronous with Sync0 Event) Communications cycle: 125 µs, 250 µs, 500 µs, 750 µs, 1 to 10 ms (in 0.25 ms increments) Free Run Mode
Indicators	ECAT-L/A IN (Link/Activity IN) × 1 ECAT-L/A OUT (Link/Activity OUT) × 1 ECAT-RUN × 1 ECAT-ERR × 1
CiA 402 Drive Profile	• Cyclic synchronous position mode • Cyclic synchronous velocity mode • Cyclic synchronous torque mode • Profile position mode • Profile velocity mode • Homing mode • Touch probe function • Torque limit function

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Version Information

1S-series Servo Drive		Corresponding version
Model	Unit version	Sysmac Studio
R88D-1SN□-ECT	Version 1.0	Version 1.16 or higher
	Version 1.1	Version 1.18 or higher
	Version 1.2	Version 1.22 or higher
	Version 1.3 ∗1	Version 1.27 or higher
	Version 1.4 ∗1	Version 1.43 or higher

∗1. Sysmac Studio version 1.44 or higher enables you to use the cable redundancy function and configure a ring topology.

Functions That Were Added or Changed for Each Unit Version

Functions That Were Added or Changed

Function		Addition/change	Unit version
EtherCAT Communications	Cable Redundancy Function	Addition	Ver.1.3
Adjustment Function	Multiple Drives Tuning Function	Addition	Ver.1.1
Object	Basic Functions - Control Method Selection (3000-03 hex)	Change	Ver.1.4
	Machine - Inertia Ratio (3001-01 hex)	Change	Ver.1.1
	Position Command - Following Error After Interpolation (3010-92 hex)	Addition	Ver.1.4
	Command Dividing Function - Interpolation Method Selection in csp (3041-10 hex)	Addition	Ver.1.2
	TDF Position Control - Command Following Gain Selection (3120-10 hex)	Addition	Ver.1.1
	TDF Position Control - Command Following Gain 2 (3120-11 hex)	Addition	Ver.1.1
	TDF Velocity Control - Command Following Gain Selection (3121-10 hex)	Addition	Ver.1.1
	TDF Velocity Control - Command Following Gain 2 (3121-11 hex)	Addition	Ver.1.1
	Runaway Detection (3B71 hex)	Addition	Ver.1.1
	Motor Advanced Setting (4412 hex)	Addition	Ver.1.4
	Function Output - Bit Mask (4602-01 hex)	Change	Ver.1.4
	Function Output - Physical Outputs (4602-F1 hex)	Change	Ver.1.2
		Change	Ver.1.4
	Brake Interlock Output - Threshold Speed at Servo OFF (4610-03 hex) ∗1	Change	Ver.1.4
	External Brake Interlock Output (4663 hex)	Addition	Ver.1.2
	Digital outputs - Physical Outputs (60FE - 01 hex)	Change	Ver.1.2
		Change	Ver.1.4
	Digital outputs - Bit mask (60FE-02 hex)	Change	Ver.1.4
Error detection function	Runaway Detection	Addition	Ver.1.1
	Synchronization Error	Change	Ver.1.1
	Regeneration Circuit Error Detected during Power ON	Addition	Ver.1.2
		Delete	Ver.1.3
	Inrush Current Prevention Circuit Error	Addition	Ver.1.3
	Regeneration Circuit Error	Addition	Ver.1.3
Applied Functions	Brake Interlock	Addition	Ver.1.2
		Change	Ver.1.4

∗1. With the unit version Ver.1.4 or later, the default setting is changed. Refer to the *AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications User's Manual* (Cat.No.I586) for details.

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Combinations of Unit Versions and Motor Power Cables

Motor power cables have two cable versions (version 1.0 and version 1.1) and are available in the following lengths: 3 m, 5 m, 10 m, 15 m, 20 m, 30 m, 40 m, and 50 m. Use a Servo Drive unit version 1.2 or earlier with 20 m or less of motor power cable.

Power Cables				Combination table			
				Unit version 1.2 or earlier		Unit version 1.3 or later	
Power Cable model (R88A-)	Cable length	Cable version		Cable version		Cable version	
		Ver.1.0	Ver.1.1	Ver.1.0	Ver.1.1	Ver.1.0	Ver.1.1
CA1A□□□S CA1A□□□SF CA1A□□□SFR CA1A□□□B CA1A□□□BF	3 m, 5 m, 10 m, 15 m, 20 m	Yes	Yes	Available	Available	Available	Available
	30 m, 40 m, 50 m	---	Yes	---	Unavailable	---	Available
CA1B□□□S CA1B□□□SF CA1B□□□B CA1B□□□BF	3 m, 5 m, 10 m, 15 m, 20 m	Yes	Yes	Available	Available	Available	Available
	30 m, 40 m, 50 m	---	Yes	---	Unavailable	---	Available
CA1C□□□S CA1C□□□SF CA1C□□□B CA1C□□□BF	3 m, 5 m, 10 m, 15 m, 20 m	Yes	Yes	Available	Available	Available	Available
	30 m, 40 m, 50 m	---	Yes	---	Unavailable	---	Available
CA1D□□□B CA1D□□□BF	3 m, 5 m, 10 m, 15 m, 20 m	Yes	---	Available	---	Available	---
	30 m, 40 m, 50 m	Yes	---	Unavailable	---	Available	---
CA1E□□□S CA1E□□□SF CA1E□□□B CA1E□□□BF	3 m, 5 m, 10 m, 15 m, 20 m	Yes	Yes	Available	Available	Available	Available
	30 m, 40 m, 50 m	---	Yes	---	Unavailable	---	Available
CA1F□□□S CA1F□□□SF CA1F□□□B CA1F□□□BF	3 m, 5 m, 10 m, 15 m, 20 m	Yes	---	Available	---	Available	---
	30 m, 40 m, 50 m	Yes	---	Unavailable	---	Available	---
CA1H0□□SF CA1H0□□BF	3 m, 5 m, 10 m, 15 m, 20 m	Yes	---	Available	---	Available	---
CA1HE□□BF	10 m, 20 m	Yes	---	Unavailable ✻1	---	Available ✻2	---
CA1J0□□SF CA1J0□□BF	3 m, 5 m, 10 m, 15 m, 20 m	Yes	---	Available	---	Available	---
CA1JE□□BF	10 m, 20 m	Yes	---	Unavailable ✻1	---	Available ✻2	---
CA1K0□□SF CA1K0□□BF	3 m, 5 m, 10 m, 15 m, 20 m	Yes	---	Available	---	Available	---
CA1KE□□BF	10 m, 20 m	Yes	---	Unavailable ✻1	---	Available ✻2	---

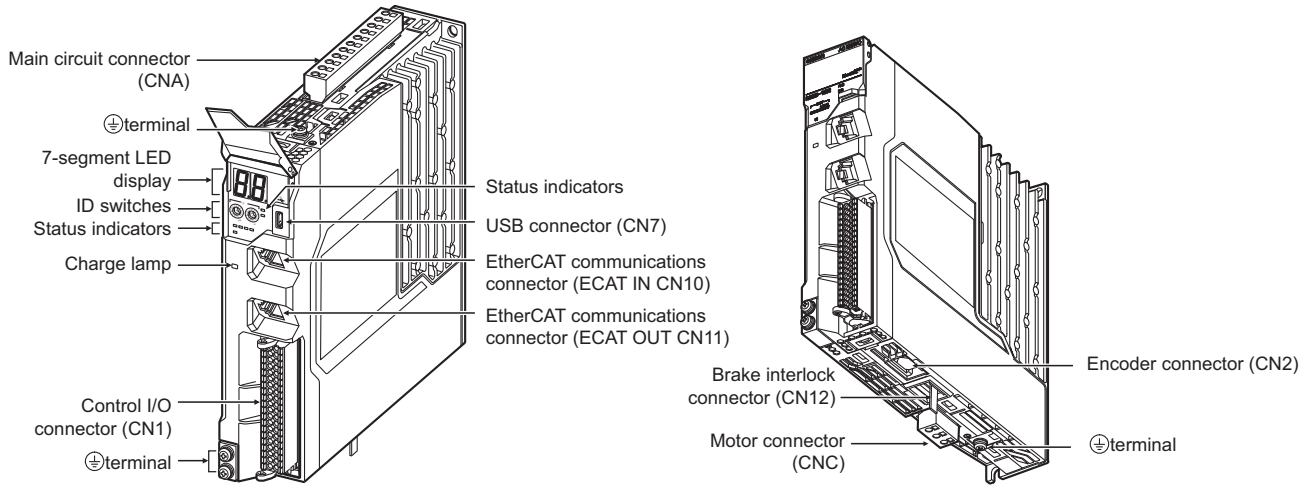
✻1. The Servo Drive unit version 1.2 or earlier cannot be used with extension cables.
✻2. The total length of motor power cables for a Servo Drive must not exceed 50 m. See *Combinations of Motor Power Cables and Extension Power Cables* on page 120 for details.

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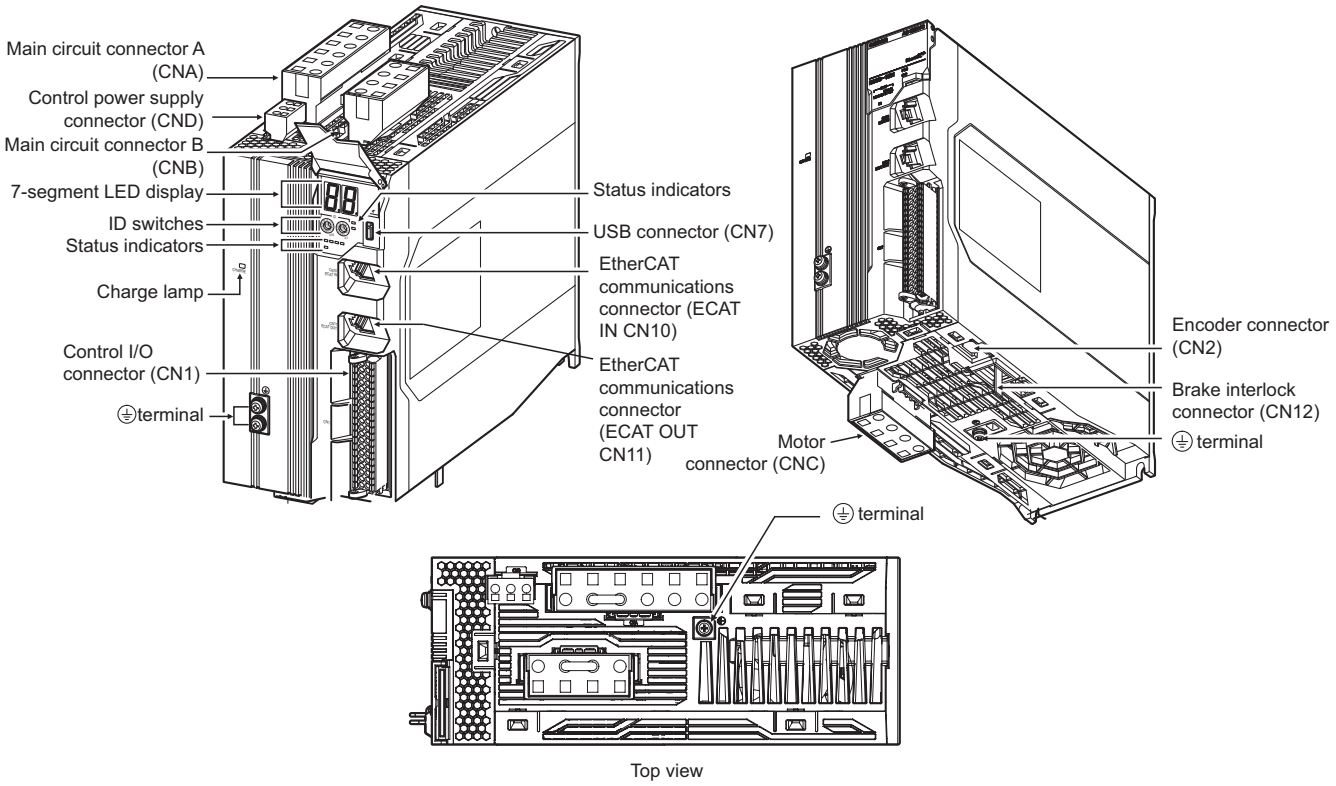
Part Names

Servo Drive Part Names

R88D-1SN01L-ECT/-1SN02L-ECT/-1SN04L-ECT/-1SN01H-ECT/ -1SN02H-ECT/-1SN04H-ECT/-1SN08H-ECT/-1SN10H-ECT

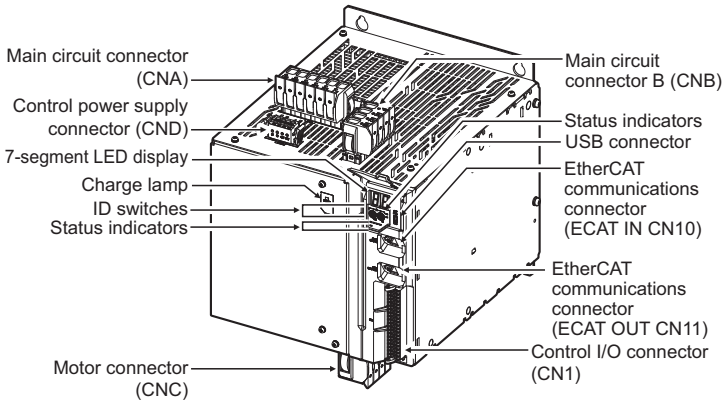


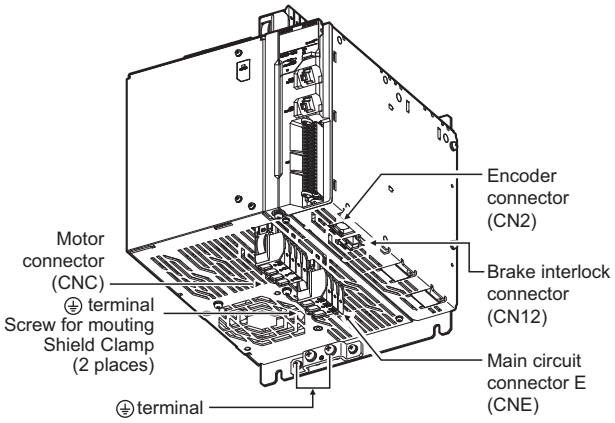
R88D-1SN15H-ECT/-1SN20H-ECT/-1SN30H-ECT/-1SN06F-ECT/ -1SN10F-ECT/-1SN15F-ECT/-1SN20F-ECT/-1SN30F-ECT



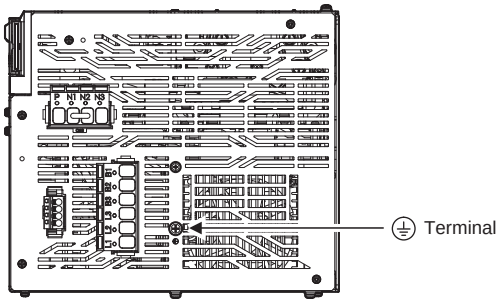
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R88D-1SN55H-ECT/-1SN75H-ECT/-1SN55F-ECT/-1SN75F-ECT

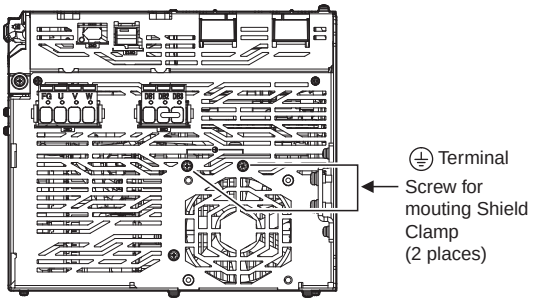




Top view

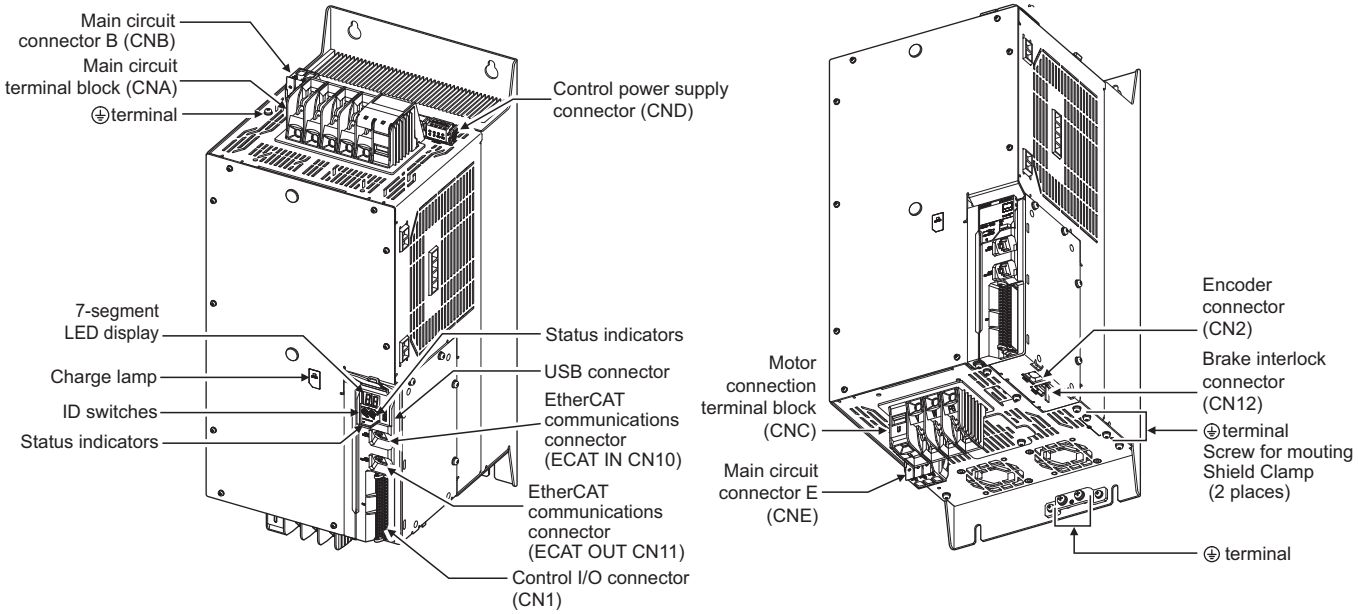


Bottom view

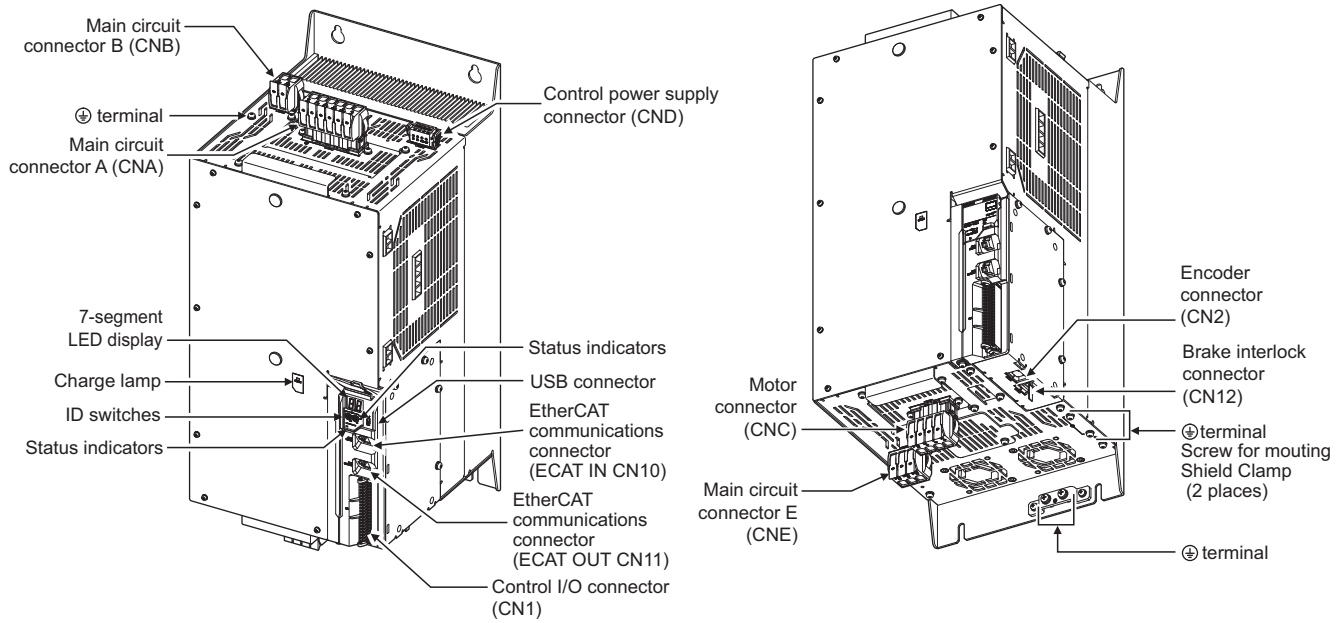


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R88D-1SN150H-ECT



R88D-1SN150F-ECT

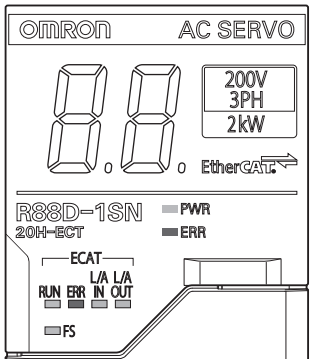


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Servo Drive Functions

Status Indicators

The following seven indicators are mounted.



Name	Color	Description
PWR	Green	Displays the status of control power supply.
ERR	Red	Gives the Servo Drive error status.
ECAT-RUN	Green	Displays the EtherCAT communications status.
ECAT-ERR	Red	
ECAT-L/A IN, ECAT-L/A OUT	Green	Lights or flashes according to the status of a link in the EtherCAT physical layer.
FS	Red/green	Displays the safety communications status.

7-segment LED Display

A 2-digit 7-segment LED display shows error numbers, the Servo Drive status, and other information.

ID Switches

Two rotary switches (0 to F hex) are used to set the EtherCAT node address.

Charge Lamp

Lights when the main circuit power supply carries electric charge.

Control I/O Connector (CN1)

Used for command input signals, I/O signals, and as the safety device connector. The short-circuit wire is installed on the safety signals before shipment.

Encoder Connector (CN2)

Connector for the encoder installed in the Servomotor.

EtherCAT Communications Connectors (ECAT IN CN10, ECAT OUT CN11)

These connectors are for EtherCAT communications.

USB Connector (CN7)

USB-Micro B Communications connector for the computer. This connector enables USB 2.0 Full Speed (12 Mbps) communications.

Brake Interlock Connector (CN12)

Used for brake interlock signals.

Main Circuit Connector (CNA)

Connector for the main circuit power supply input, control power supply input, external regeneration resistor, and DC reactor.
Applicable models: R88D-1SN01L-ECT/-1SN02L-ECT/-1SN04L-ECT/-1SN01H-ECT/-1SN02H-ECT/-1SN04H-ECT/-1SN08H-ECT/-1SN10H-ECT

Main Circuit Connector A (CNA)

Connector for the main circuit power supply input and external regeneration resistor. The connector differs depending on the model.
Applicable models: R88D-1SN15H-ECT/-1SN20H-ECT/-1SN30H-ECT/-1SN55H-ECT/-1SN75H-ECT/-1SN06F-ECT/-1SN10F-ECT/
-1SN15F-ECT/ -1SN20F-ECT/-1SN30F-ECT/-1SN55F-ECT/-1SN75F-ECT

Main Circuit Terminal Block (CNA)

Connector for the main circuit power supply input.
Applicable models: R88D-1SN150H-ECT

Main Circuit Connector A (CNA)

Connector for the main circuit power supply input and AC reactor.
Applicable models: R88D-1SN150F-ECT

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Main Circuit Connector B (CNB)

Connector for a DC reactor. The connector differs depending on the model.
Applicable models: R88D-1SN15H-ECT/-1SN20H-ECT/-1SN30H-ECT/-1SN55H-ECT/-1SN75H-ECT/-1SN06F-ECT/-1SN10F-ECT/
-1SN15F-ECT/ -1SN20F-ECT/-1SN30F-ECT/-1SN55F-ECT/-1SN75F-ECT

Main Circuit Connector B (CNB)

Connector for a external regeneration resistor.
Applicable models: R88D-1SN150H-ECT/ -1SN150F-ECT

Control Power Supply Connector (CND)

Connector for control power supply input. The connector differs depending on the model.
Applicable models: R88D-1SN15H-ECT/-1SN20H-ECT/-1SN30H-ECT/-1SN55H-ECT/-1SN75H-ECT/-1SN150H-ECT/-1SN06F-ECT/
-1SN10F-ECT/-1SN15F-ECT/-1SN20F-ECT/-1SN30F-ECT/-1SN55F-ECT/-1SN75F-ECT/-1SN150F-ECT

Motor Connector (CNC)

Connector for the power line to the phase U, V, and W of the Servomotor. The connector differs depending on the model.

Motor Connection Terminal Block (CNC)

Connector for the power line to the phase U, V, and W of the Servomotor.
Applicable models: R88D-1SN150H-ECT

Main Circuit Connector E (CNE)

Connector for a External Dynamic Brake Resistor.
Applicable models: R88D-1SN55H-ECT/-1SN75H-ECT/-1SN150H-ECT/-1SN55F-ECT/-1SN75F-ECT/-1SN150F-ECT

⏚ Terminal

The number of ⏚ terminals of the Servo Drives and their connection targets are as follows.

Model	Number of ⏚ terminals	Connection to
R88D-1SN01L-ECT/-1SN02L-ECT/-1SN04L-ECT/ -1SN01H-ECT/-1SN02H-ECT/-1SN04H-ECT/ -1SN08H-ECT/-1SN10H-ECT	1 on top	PE wire of the main circuit power supply cable. FG wire inside the control panel, and FG wire for the motor cable and shielded wire.
	2 on front	
	1 on bottom	
R88D-1SN15H-ECT/-1SN20H-ECT/-1SN30H-ECT/ -1SN06F-ECT/-1SN10F-ECT/-1SN15F-ECT/ -1SN20F-ECT/-1SN30F-ECT	1 on top	PE wire of the main circuit power supply cable. FG wire inside the control panel and the motor cable shielded wire.
	2 on front	
	1 on bottom	
R88D-1SN55H-ECT/-1SN75H-ECT/ -1SN150H-ECT/ -1SN55F-ECT/ -1SN75F-ECT/-1SN150F-ECT	1 on top	PE wire of the main circuit power supply cable. FG wire inside the control panel and the motor cable shielded wire.
	2 on front	
	2 on bottom	

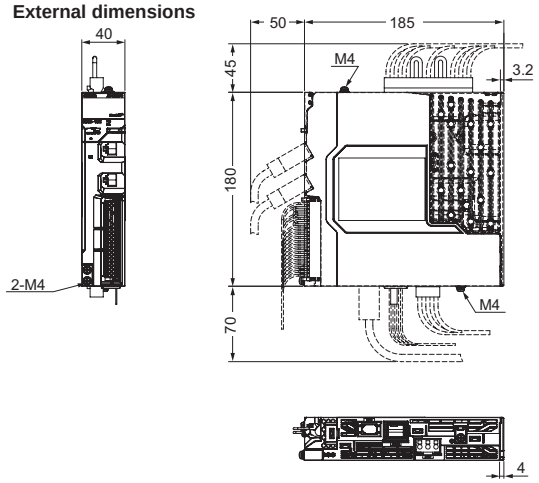
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Dimensions

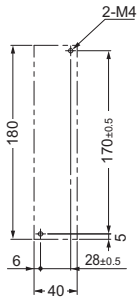
(Unit: mm)

Single-phase 100 VAC: R88D-1SN01L-ECT (100 W)
Single-phase/3-phase 200 VAC: R88D-1SN01H-ECT/-1SN02H-ECT (100 to 200 W)

External dimensions

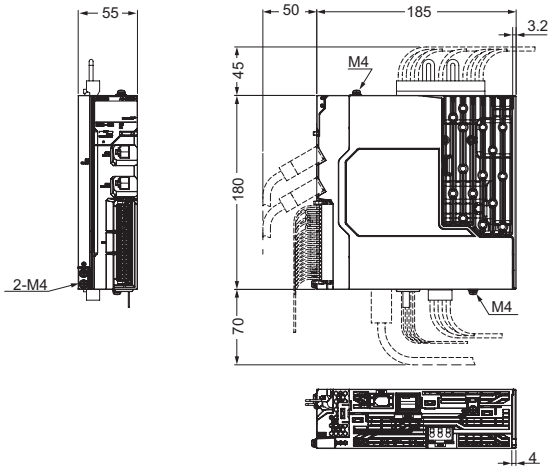


Mounting dimensions

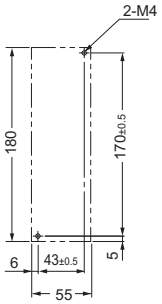


Single-phase 100 VAC: R88D-1SN02L-ECT (200 W)
Single-phase/3-phase 200 VAC: R88D-1SN04H-ECT (400 W)

External dimensions

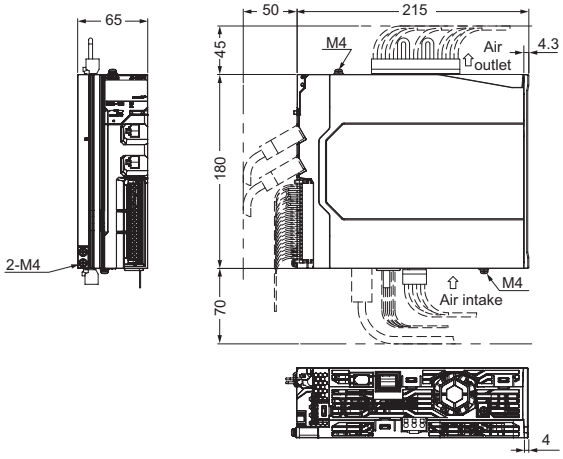


Mounting dimensions

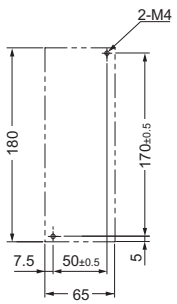


Single-phase 100 VAC: R88D-1SN04L-ECT (400 W)
Single-phase/3-phase 200 VAC: R88D-1SN08H-ECT (750 W)
3-phase 200 VAC: R88D-1SN10H-ECT (1 kW)

External dimensions



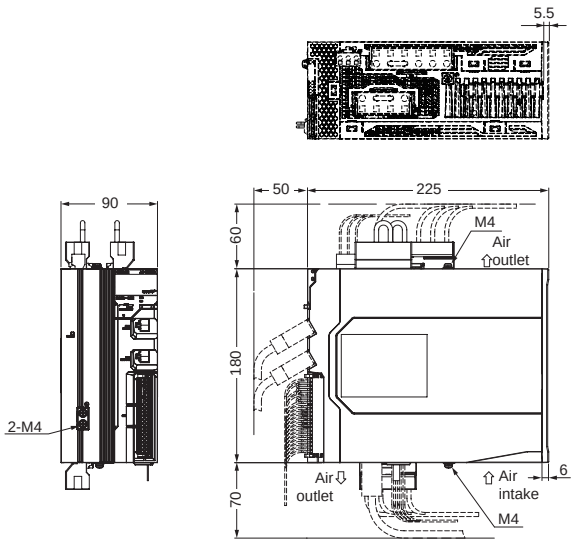
Mounting dimensions



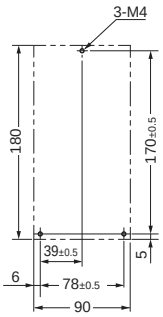
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Single-phase/3-phase 200 VAC: R88D-1SN15H-ECT (1.5 kW)
3-phase 200 VAC: R88D-1SN20H-ECT/-1SN30H-ECT (2 to 3 kW)
3-phase 400 VAC: R88D-1SN06F-ECT/-1SN10F-ECT/-1SN15F-ECT/-1SN20F-ECT/-1SN30F-ECT (600 W to 3 kW)

External dimensions

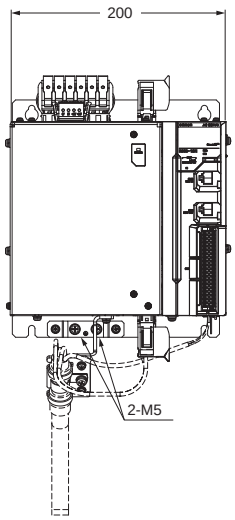


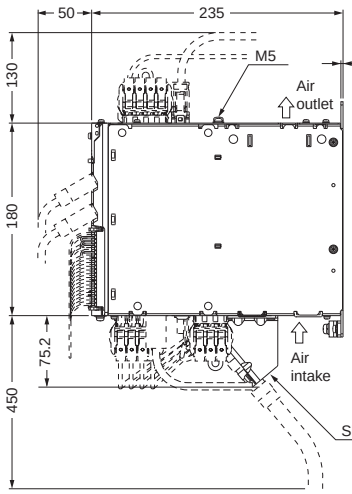
Mounting dimensions



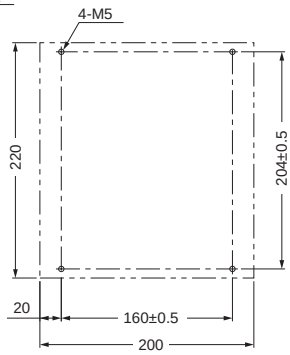
3-phase 200 VAC: R88D-1SN55H-ECT/-1SN75H-ECT (5.5 to 7.5 kW)
3-phase 400 VAC: R88D-1SN55F-ECT/-1SN75F-ECT (5.5 to 7.5kW)

External dimensions





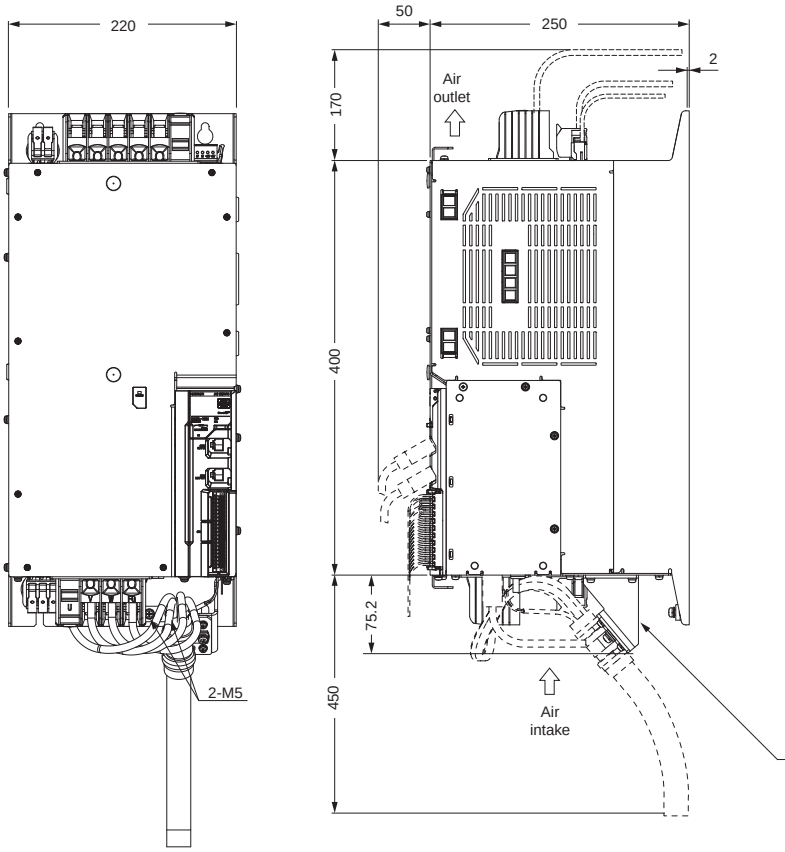
Mounting dimensions



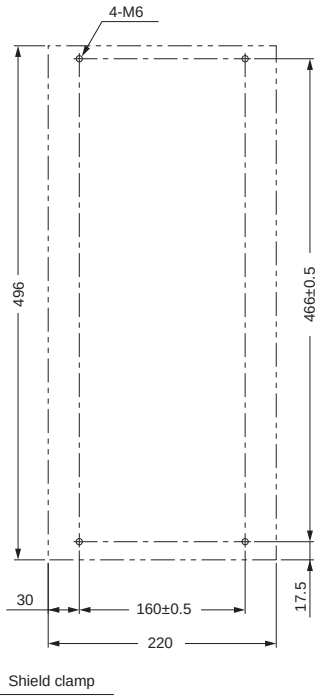
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3-phase 200 VAC: R88D-1SN150H-ECT (15 kW)

External dimensions

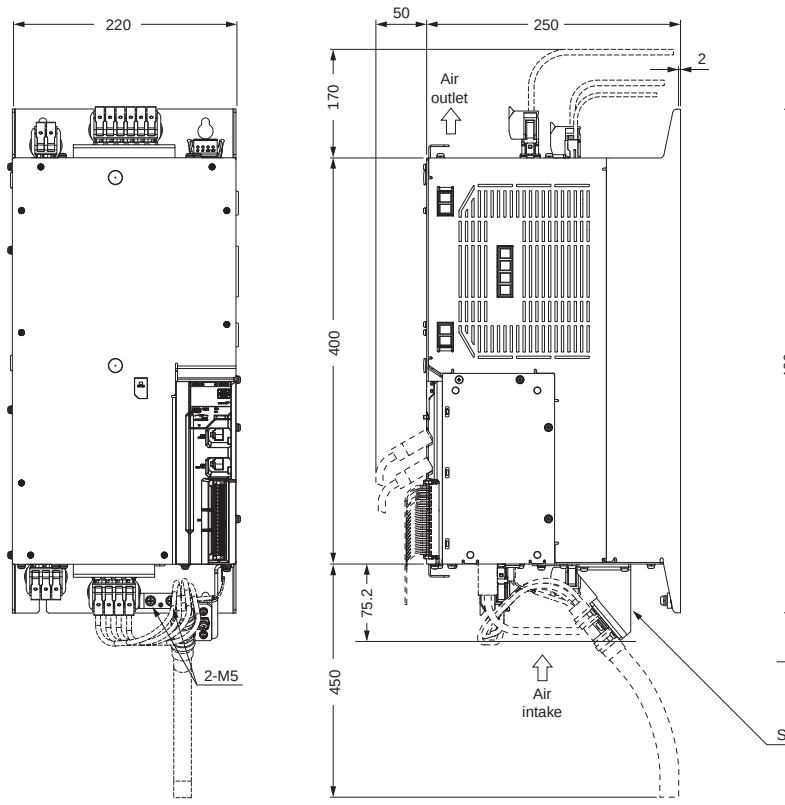


Mounting dimensions

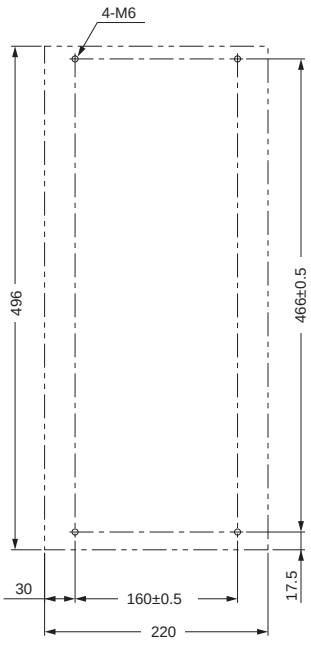


3-phase 400 VAC: R88D-1SN150F-ECT (15 kW)

External dimensions



Mounting dimensions



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R88M-1L□/-1M□

Contents

- Ordering Information
- Specifications
- Names and Functions
- External Dimensions



Ordering Information

Refer to the Ordering Information.

Specifications

General Specifications

Item			Specifications
Operating ambient temperature and humidity			0 to 40°C 20% to 90% (with no condensation)
Storage ambient temperature and humidity			-20 to 65°C 20% to 90% (with no condensation)
Operating and storage atmosphere			No corrosive gases
Vibration resistance ✻1			Acceleration of 49 m/s^2 ✻2 24.5 m/s^2 max. in X, Y, and Z directions when the motor is stopped
Impact resistance			Acceleration of 98 m/s^2 max. 3 times each in X, Y, and Z directions
Insulation resistance			Between power terminals and FG terminals: 10 MΩ min. (at 500 VDC Megger)
Dielectric strength			Between power terminals and FG terminals: 1,500 VAC for 1 min (voltage 100 V, 200 V) Between power terminals and FG terminals: 1,800 VAC for 1 min (voltage 400 V) Between brake terminal and FG terminals: 1,000 VAC for 1 min
Insulation class			Class F
Protective structure			IP67 (except for the through-shaft part and connector pins) IP20 if you use a 30-meter or longer encoder cable.
International standard	**EU Directives and UK legislation**	**Low Voltage**	EN 60034-1/-5
	UL standards		UL 1004-1/-6
	CSA standards		CSA C22.2 No.100 (with cUR mark)

✻1. The amplitude may be increased by machine resonance. As a guideline, 80% of the specified value must not be exceeded.
✻2. 24.5 m/s^2 for servomotors of 7.5 kW or more.
Note: 1. Do not use the cable when it is laying in oil or water.
2. Do not expose the cable outlet or connections to stress due to bending or its own weight.

Encoder Specifications

Item	Specifications
Encoder system	Optical batteryless absolute encoder
Resolution per rotation	23 bits
Multi-rotation data hold	16 bits
Power supply voltage	5 VDC±10%
Current consumption	230 mA max.
Output signal	Serial communications
Output interface	RS485 compliant

Note: It is possible to use an absolute encoder as an incremental encoder.
Refer to the *AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications User's Manual* (Cat.No.I586) for details.

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Characteristics

3,000-r/min Servomotors

Item		Model (R88M-) / Unit	100 VAC			
			1M05030S	1M10030S	1M20030S	1M40030S
Rated output ✻1 ✻2		W	50	100	200	400
Rated torque ✻1 ✻2		N·m	0.159	0.318	0.637	1.27
Rated rotation speed ✻1 ✻2		r/min	3,000			
Maximum rotation speed		r/min	6,000			
Momentary maximum torque ✻1 ✻3		N·m	0.48	0.95	1.91	3.8
Rated current ✻1 ✻2		A (rms)	1.20	1.50	2.50	4.8
Momentary maximum current ✻1		A (rms)	4.00	4.70	8.40	14.7
Rotor inertia	Without brake	× 10^{-4} kg·m^2	0.0418	0.0890	0.2232	0.4452
	With brake	× 10^{-4} kg·m^2	0.0496	0.0968	0.2832	0.5052
Applicable load inertia		× 10^{-4} kg·m^2	0.810	1.62	4.80	8.40
Torque constant ✻1		N·m/ A (rms)	0.14	0.24	0.28	0.30
Power rate ✻1 ✻5		kW/s	6.7	11.9	18.5	36.6
Mechanical time constant ✻5		ms	1.7	1.1	0.76	0.61
Electrical time constant		ms	0.67	0.84	2.4	2.4
Allowable radial load ✻6		N	68	68	245	245
Allowable thrust load ✻6		N	58	58	88	88
Weight	Without brake	kg	0.35	0.52	1.0	1.4
	With brake	kg	0.59	0.77	1.3	1.9
Radiator plate dimensions (material)		mm	250 × 250 × t6 (aluminum)			
Brake specifications ✻7	Excitation voltage ✻8	V	24 VDC±10%			
	Current consumption (at 20°C)	A	0.27	0.27	0.32	0.32
	Static friction torque	N·m	0.32 min.	0.32 min.	1.37 min.	1.37 min.
	Attraction time	ms	25 max.	25 max.	30 max.	30 max.
	Release time ✻9	ms	15 max.	15 max.	20 max.	20 max.
	Backlash	°	1.2 max.	1.2 max.	1.2 max.	1.2 max.
	Allowable braking work	J	9	9	60	60
	Allowable total work	J	9000	9,000	60,000	60,000
	Allowable angular acceleration	rad/s^2	10,000 max.			
	Brake lifetime (acceleration/ deceleration)	---	10 million times min.			
	Insulation class	---	Class F			

For models with an oil seal, the following derating is used due to increase in friction torque.

Item	Unit	Model (R88M-) 1M05030S-O/ -OS2/ -BO/ -BOS2	1M10030S-O/ -OS2/ -BO/ -BOS2	1M20030S-O/ -OS2/ -BO/ -BOS2	1M40030S-O/ -OS2/ -BO/ -BOS2
Derating rate	%	90	95	95	80
Rated output	W	45	95	190	320
Rated current	A (rms)	1.20	1.50	2.50	4.0

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Item		Model (R88M-) / Unit	200 VAC				
			1M05030T	1M10030T	1M20030T	1M40030T	1M75030T
Rated output ✻1 ✻2		W	50	100	200	400	750
Rated torque ✻1 ✻2		N·m	0.159	0.318	0.637	1.27	2.39
Rated rotation speed ✻1 ✻2		r/min	3,000				
Maximum rotation speed		r/min	6,000				
Momentary maximum torque ✻1 ✻3		N·m	0.56 ✻4	1.11 ✻4	2.2 ✻4	4.5 ✻4	8.4 ✻4
Rated current ✻1 ✻2		A (rms)	0.67	0.84	1.5	2.5	4.6
Momentary maximum current ✻1		A (rms)	2.60	3.10	5.6	9.1	16.9
Rotor inertia	Without brake	× 10^{-4} kg·m^2	0.0418	0.0890	0.2232	0.4452	1.8242
	With brake	× 10^{-4} kg·m^2	0.0496	0.0968	0.2832	0.5052	2.0742
Applicable load inertia		× 10^{-4} kg·m^2	0.810	1.62	4.80	8.40	19.4
Torque constant ✻1		N·m/ A (rms)	0.25	0.42	0.48	0.56	0.59
Power rate ✻1 ✻5		kW/s	6.7	11.9	18.5	36.6	31.4
Mechanical time constant ✻5		ms	1.7	1.2	0.78	0.56	0.66
Electrical time constant		ms	0.67	0.83	2.4	2.6	3.3
Allowable radial load ✻6		N	68	68	245	245	490
Allowable thrust load ✻6		N	58	58	88	88	196
Weight	Without brake	kg	0.35	0.52	1.0	1.4	2.9
	With brake	kg	0.59	0.77	1.3	1.9	3.9
Radiator plate dimensions (material)		mm	250 × 250 × t6 (aluminum)				
Brake specifications ✻7	Excitation voltage ✻8	V	24 VDC±10%				
	Current consumption (at 20°C)	A	0.27	0.27	0.32	0.32	0.37
	Static friction torque	N·m	0.32 min.	0.32 min.	1.37 min.	1.37 min.	2.55 min.
	Attraction time	ms	25 max.	25 max.	30 max.	30 max.	40 max.
	Release time ✻9	ms	15 max.	15 max.	20 max.	20 max.	35 max.
	Backlash	°	1.2 max.	1.2 max.	1.2 max.	1.2 max.	1.0 max.
	Allowable braking work	J	9	9	60	60	250
	Allowable total work	J	9000	9,000	60,000	60,000	250,000
	Allowable angular acceleration	rad/s^2	10,000 max.				
	Brake lifetime (acceleration/ deceleration)	---	10 million times min.				
	Insulation class	---	Class F				

For models with an oil seal, the following derating is used due to increase in friction torque.

Item	Model (R88M-) / Unit	1M05030T-O/ -OS2/ -BO/ -BOS2	1M10030T-O/ -OS2/ -BO/ -BOS2	1M20030T-O/ -OS2/ -BO/ -BOS2	1M40030T-O/ -OS2/ -BO/ -BOS2	1M75030T-O/ -OS2/ -BO/ -BOS2
Derating rate	%	90	95	95	80	90
Rated output	W	45	95	190	320	675
Rated current	A (rms)	0.67	0.84	1.5	2.1	4.2

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Item		Model (R88M-) / Unit	200 VAC					
			1L1K030T	1L1K530T	1L2K030T	1L3K030T	1L4K030T	1L4K730T
Rated output ✻1 ✻2		W	1,000	1,500	2,000	3,000	4,000	4,700
Rated torque ✻1 ✻2		N·m	3.18	4.77	6.37	9.55	12.7	15.0
Rated rotation speed ✻1 ✻2		r/min	3,000					
Maximum rotation speed		r/min	5,000					
Momentary maximum torque ✻1 ✻3		N·m	9.55	14.3	19.1	28.7	38.2	47.7
Rated current ✻1 ✻2		A (rms)	5.2	8.8	12.5	17.1	22.8	25.7
Momentary maximum current ✻1		A (rms)	16.9	28.4	41.0	54.7	74	84.8
Rotor inertia	Without brake	× 10^{-4} kg·m^2	2.1042	2.1042	2.4042	6.8122	8.8122	10.6122
	With brake	× 10^{-4} kg·m^2	2.5542	2.5542	2.8542	7.3122	11.3122	13.1122
Applicable load inertia		× 10^{-4} kg·m^2	35.3	47.6	60.2	118	213	279
Torque constant ✻1		N·m/ A (rms)	0.67	0.58	0.56	0.64	0.63	0.65
Power rate ✻1 ✻5		kW/s	48	108	169	134	183	209
Mechanical time constant ✻5		ms	0.58	0.58	0.50	0.47	0.37	0.37
Electrical time constant		ms	5.9	6.1	6.4	11	12	12
Allowable radial load ✻6		N	490				880	
Allowable thrust load ✻6		N	196				343	
Weight	Without brake	kg	5.7	5.7	6.4	11.5	13.5	16
	With brake	kg	7.4	7.4	8.1	12.5	16	18.5
Radiator plate dimensions (material)		mm	400 × 400 × t20 (aluminum)		470 × 470 × t20 (aluminum)			540 × 540 × t20 (aluminum)
Brake specifications ✻7	Excitation voltage ✻8	V	24 VDC±10%					
	Current consumption (at 20°C)	A	0.70	0.70	0.70	0.66	0.6	0.6
	Static friction torque	N·m	9.3 min.	9.3 min.	9.3 min.	12.0 min.	16 min.	16 min.
	Attraction time	ms	100 max.	100 max.	100 max.	100 max.	150 max.	150 max.
	Release time ✻9	ms	30 max.	30 max.	30 max.	30 max.	50 max.	50 max.
	Backlash	°	1.0 max.	1.0 max.	1.0 max.	0.8 max.	0.6 max.	0.6 max.
	Allowable braking work	J	500	500	500	1,000	350	350
	Allowable total work	J	900,000	900,000	900,000	3,000,000	1,000,000	1,000,000
	Allowable angular acceleration	rad/s^2	10,000 max.					
	Brake lifetime (acceleration/ deceleration)	---	10 million times min.					
	Insulation class	---	Class F					

Note: 1. For the models listed in the table above, there is no derating for models with an oil seal.

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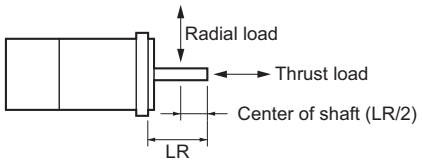
Item		Model (R88M-) / Unit	400 VAC		
			1L75030C	1L1K030C	1L1K530C
Rated output ✻1 ✻2		W	750	1,000	1,500
Rated torque ✻1 ✻2		N·m	2.39	3.18	4.77
Rated rotation speed ✻1 ✻2		r/min	3,000		
Maximum rotation speed		r/min	5,000		
Momentary maximum torque ✻1 ✻3		N·m	7.16	9.55	14.3
Rated current ✻1 ✻2		A (rms)	3.0	3.0	4.5
Momentary maximum current ✻1		A (rms)	9.6	9.6	14.1
Rotor inertia	Without brake	× 10^{-4} kg·m^2	1.3042	2.1042	2.1042
	With brake	× 10^{-4} kg·m^2	1.7542	2.5542	2.5542
Applicable load inertia		× 10^{-4} kg·m^2	38.6	35.3	47.6
Torque constant ✻1		N·m/ A (rms)	0.91	1.17	1.17
Power rate ✻1 ✻5		kW/s	44	48	108
Mechanical time constant ✻5		ms	1.09	0.6	0.58
Electrical time constant		ms	4.3	5.9	5.9
Allowable radial load ✻6		N	490		
Allowable thrust load ✻6		N	196		
Weight	Without brake	kg	4.1	5.7	5.7
	With brake	kg	5.8	7.4	7.4
Radiator plate dimensions (material)		mm	305 × 305 × t20 (aluminum)	400 × 400 × t20 (aluminum)	
Brake specifications ✻7	Excitation voltage ✻8	V	24 VDC±10%		
	Current consumption (at 20°C)	A	0.70	0.70	0.70
	Static friction torque	N·m	9.3 min.	9.3 min.	9.3 min.
	Attraction time	ms	100 max.	100 max.	100 max.
	Release time ✻9	ms	30 max.	30 max.	30 max.
	Backlash	°	1.0 max.	1.0 max.	1.0 max.
	Allowable braking work	J	500	500	500
	Allowable total work	J	900,000	900,000	900,000
	Allowable angular acceleration	rad/s^2	10,000 max.		
	Brake lifetime (acceleration/ deceleration)	---	10 million times min.		
	Insulation class	---	Class F		

Note: 1. For the models listed in the table above, there is no derating for models with an oil seal.

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Item		Model (R88M-) Unit	400 VAC 1L2K030C	1L3K030C	1L4K030C	1L5K030C
Rated output ✻1 ✻2		W	2,000	3,000	4,000	5,000
Rated torque ✻1 ✻2		N·m	6.37	9.55	12.7	15.9
Rated rotation speed ✻1 ✻2		r/min	3,000			
Maximum rotation speed		r/min	5,000			
Momentary maximum torque ✻1 ✻3		N·m	19.1	28.7	38.2	47.7
Rated current ✻1 ✻2		A (rms)	6.3	8.7	12.8	13.6
Momentary maximum current ✻1		A (rms)	19.8	27.7	42.4	42.4
Rotor inertia	Without brake	× 10^{-4} kg·m^2	2.4042	6.8122	8.8122	10.6122
	With brake	× 10^{-4} kg·m^2	2.8542	7.3122	11.3122	13.1122
Applicable load inertia		× 10^{-4} kg·m^2	60.2	118	213	279
Torque constant ✻1		N·m/ A (rms)	1.15	1.23	1.11	1.32
Power rate ✻1 ✻5		kW/s	169	134	183	238
Mechanical time constant ✻5		ms	0.52	0.49	0.36	0.35
Electrical time constant		ms	6.3	11	12	13
Allowable radial load ✻6		N	490		880	
Allowable thrust load ✻6		N	196		343	
Weight	Without brake	kg	6.4	11.5	13.5	16
	With brake	kg	8.1	12.5	16	18.5
Radiator plate dimensions (material)		mm	470 × 470 × t20 (aluminum)			540 × 540 × t20 (aluminum)
Brake specifications ✻7	Excitation voltage ✻8	V	24 VDC±10%			
	Current consumption (at 20°C)	A	0.70	0.66	0.6	0.6
	Static friction torque	N·m	9.3 min.	12 min.	16 min.	16 min.
	Attraction time	ms	100 max.	100 max.	150 max.	150 max.
	Release time ✻9	ms	30 max.	30 max.	50 max.	50 max.
	Backlash	°	1.0 max.	0.8 max.	0.6 max.	0.6 max.
	Allowable braking work	J	500	1,000	350	350
	Allowable total work	J	900,000	3,000,000	1,000,000	1,000,000
	Allowable angular acceleration	rad/s^2	10,000 max.			
	Brake lifetime (acceleration/ deceleration)	---	10 million times min.			
	Insulation class	---	Class F			

✻1. This is a typical value for when the Servomotor is used at a normal temperature (20°C, 65%) in combination with a Servo Drive.
✻2. The rated values are the values with which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.
✻3. The momentary maximum torque is approximately 300% of the rated torque, except for some models.
✻4. The momentary maximum torque is approximately 350% of the rated torque. Output at the momentary maximum torque shortens detection time of the overload protection function. Refer to Electronic Thermal Function in the *AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications User's Manual* (Cat.No.I586) for details.
✻5. This value is for models without options.
✻6. The allowable radial and thrust loads are the values determined for a limit of 20,000 hours at normal operating temperatures.
The allowable radial loads are applied as shown in the following diagram.



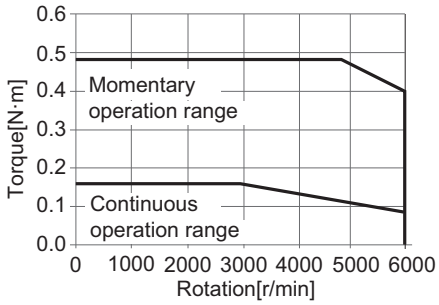
✻7. When the brake is released for a vertical axis, refer to the *AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications User's Manual* (Cat.No.I586) to set an appropriate value for Brake Interlock Output (4610 hex).
✻8. This is a non-excitation brake. It is released when excitation voltage is applied.
✻9. This value is a reference value.
Note: 1. For the models listed in the table above, there is no derating for models with an oil seal.

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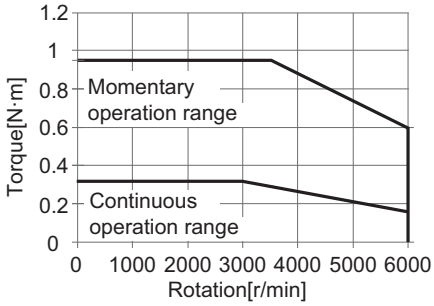
Torque-Rotation Speed Characteristics for 3,000-r/min Servomotors (100 VAC)

The following graphs show the characteristics with a 3-m standard cable and a 100 VAC input.

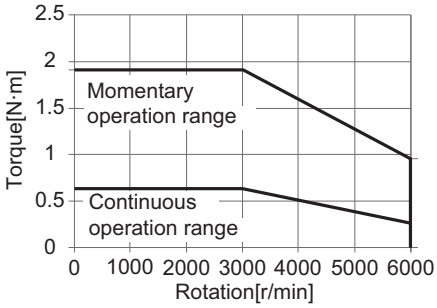
• R88M-1M05030S



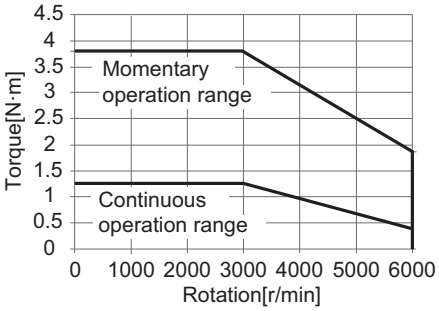
• R88M-1M10030S



• R88M-1M20030S



• R88M-1M40030S



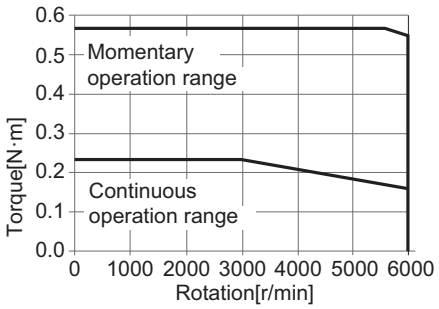
Note: The continuous operation range is the range in which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.
Continuous operation at the maximum speed is also possible. However, doing so will reduce the output torque.

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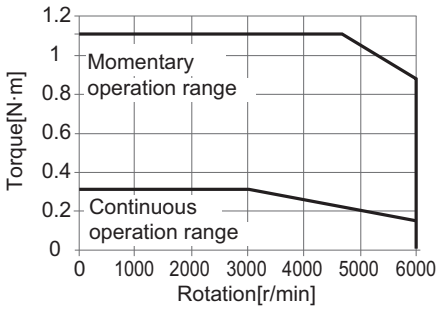
Torque-Rotation Speed Characteristics for 3,000-r/min Servomotors (200 VAC)

The following graphs show the characteristics with a 3-m standard cable and a 3-phase 200-VAC or single-phase 220-VAC input.

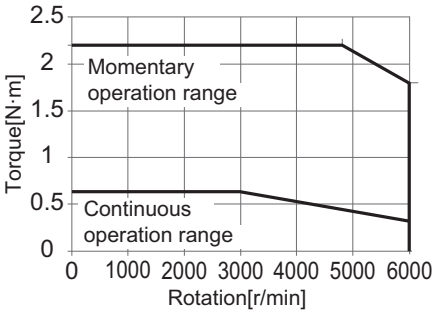
• R88M-1M05030T



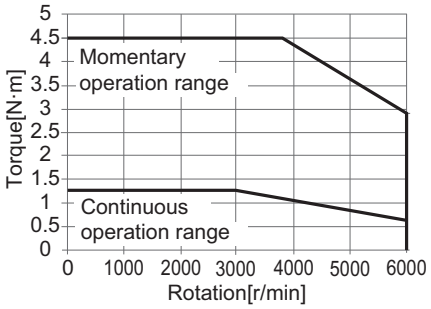
• R88M-1M10030T



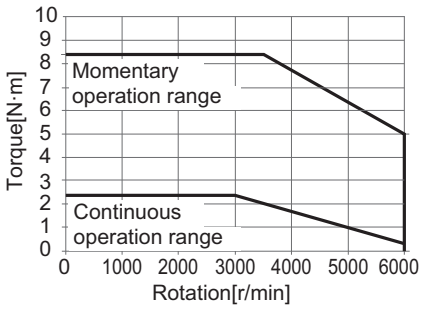
• R88M-1M20030T



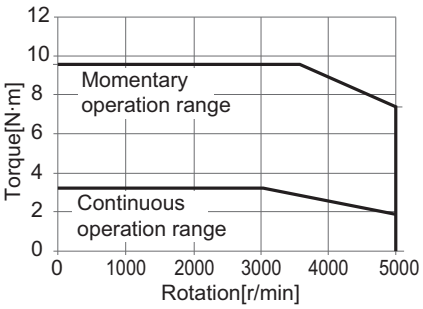
• R88M-1M40030T



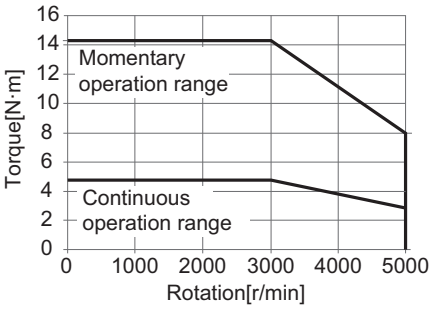
• R88M-1M75030T



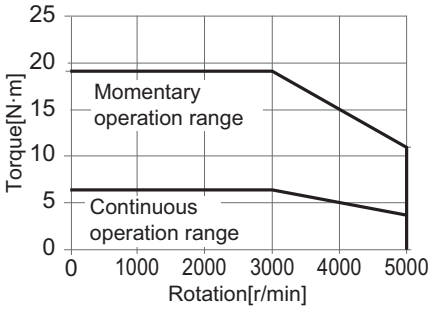
• R88M-1L1K030T



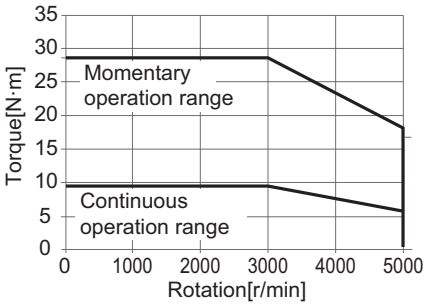
• R88M-1L1K530T



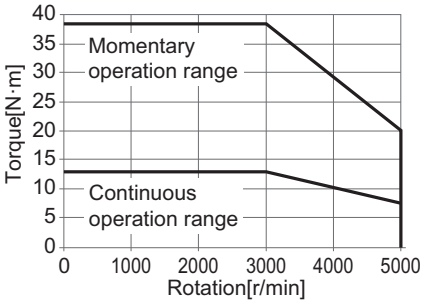
• R88M-1L2K030T



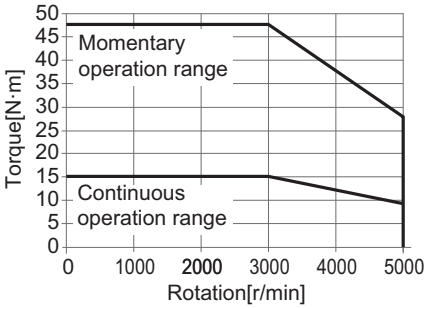
• R88M-1L3K030T



• R88M-1L4K030T



• R88M-1L4K730T



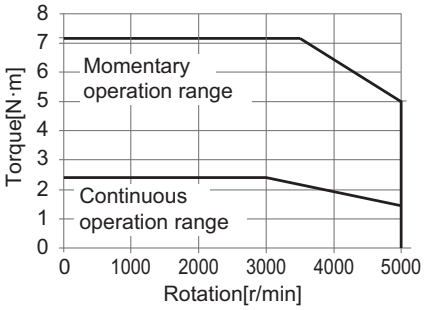
Note: The continuous operation range is the range in which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.
Continuous operation at the maximum speed is also possible. However, doing so will reduce the output torque.

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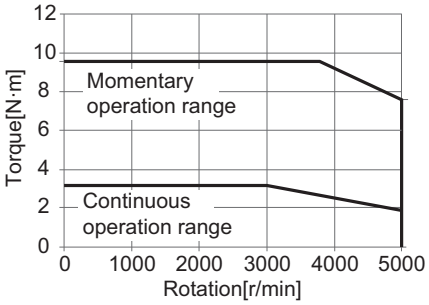
Torque-Rotation Speed Characteristics for 3,000-r/min Servomotors (400 VAC)

The following graphs show the characteristics with a 3-m standard cable and a 3-phase 400 VAC input.

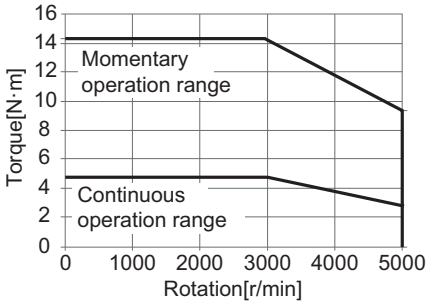
• R88M-1L75030C



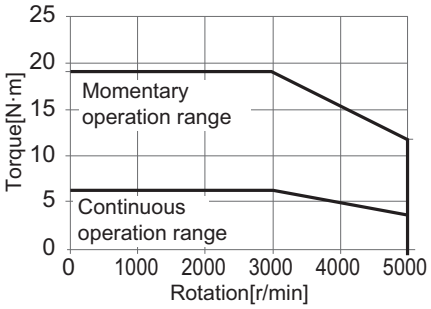
• R88M-1L1K030C



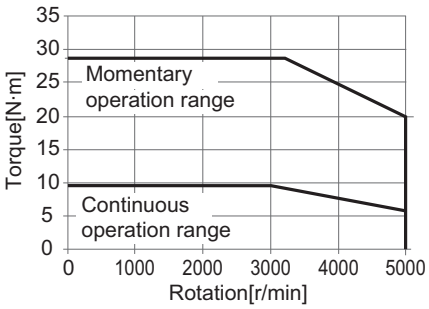
• R88M-1L1K530C



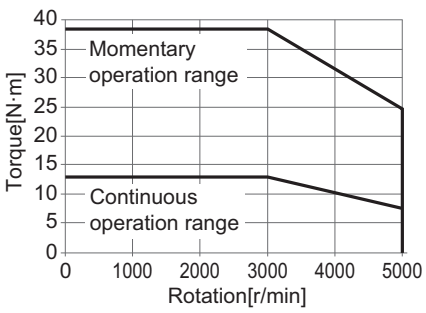
• R88M-1L2K030C



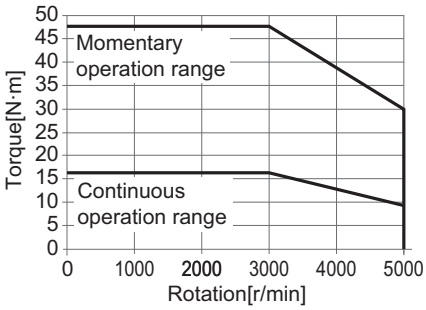
• R88M-1L3K030C



• R88M-1L4K030C



• R88M-1L5K030C



Note: The continuous operation range is the range in which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.
Continuous operation at the maximum speed is also possible. However, doing so will reduce the output torque.

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2,000-r/min Servomotors

Item		Model (R88M-) / Unit	200 VAC			
			1M1K020T	1M1K520T	1M2K020T	1M3K020T
Rated output ✻1 ✻2		W	1,000	1,500	2,000	3,000
Rated torque ✻1 ✻2		N·m	4.77	7.16	9.55	14.3
Rated rotation speed ✻1 ✻2		r/min	2,000			
Maximum rotation speed		r/min	3,000			
Momentary maximum torque ✻1		N·m	14.3	21.5	28.7	43.0
Rated current ✻1 ✻2		A (rms)	5.2	8.6	11.3	15.7
Momentary maximum current ✻1		A (rms)	16.9	28.4	40.6	54.7
Rotor inertia	Without brake	× 10^{-4} kg·m^2	6.0042	9.0042	12.2042	15.3122
	With brake	× 10^{-4} kg·m^2	6.5042	9.5042	12.7042	17.4122
Applicable load inertia		× 10^{-4} kg·m^2	59.0	79.9	100	142
Torque constant ✻1		N·m/ A (rms)	0.93	0.83	0.85	0.93
Power rate ✻1 ✻3		kW/s	38	57	75	134
Mechanical time constant ✻3		ms	0.94	0.78	0.81	0.80
Electrical time constant		ms	13	15	14	19
Allowable radial load ✻4		N	490			784
Allowable thrust load ✻4		N	196			343
Weight	Without brake	kg	6.6	8.5	10	12
	With brake	kg	8.6	10.5	12	15
Radiator plate dimensions (material)		mm	400 × 400 × t20 (aluminum)	470 × 470 × t20 (aluminum)		
Brake specifications ✻5	Excitation voltage ✻6	V	24 VDC±10%			
	Current consumption (at 20°C)	A	0.51	0.51	0.66	0.60
	Static friction torque	N·m	9.0 min.	9.0 min.	12 min.	16 min.
	Attraction time	ms	100 max.	100 max.	100 max.	150 max.
	Release time ✻7	ms	30 max.	30 max.	30 max.	50 max.
	Backlash	°	0.6 max.	0.6 max.	0.6 max.	0.6 max.
	Allowable braking work	J	1,000	1,000	1,000	350
	Allowable total work	J	3,000,000	3,000,000	3,000,000	1,000,000
	Allowable angular acceleration	rad/s^2	10,000 max.			
	Brake lifetime (acceleration/ deceleration)	---	10 million times min.			
	Insulation class	---	Class F			

Note: 1. For the models listed in the table above, there is no derating for models with an oil seal.

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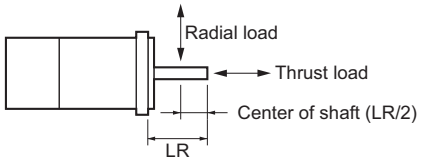
Item		Model (R88M-) / Unit	400 VAC		
			1M40020C	1M60020C	1M1K020C
Rated output ✻1 ✻2		W	400	600	1,000
Rated torque ✻1 ✻2		N·m	1.91	2.86	4.77
Rated rotation speed ✻1 ✻2		r/min	2,000		
Maximum rotation speed		r/min	3,000		
Momentary maximum torque ✻1		N·m	5.73	8.59	14.3
Rated current ✻1 ✻2		A (rms)	1.1	1.6	2.9
Momentary maximum current ✻1		A (rms)	3.9	5.5	9.4
Rotor inertia	Without brake	× 10^{-4} kg·m^2	2.5042	3.9042	6.0042
	With brake	× 10^{-4} kg·m^2	2.8472	4.2472	6.5042
Applicable load inertia		× 10^{-4} kg·m^2	19.0	23.5	59.0
Torque constant ✻1		N·m/ A (rms)	1.75	1.84	1.69
Power rate ✻1 ✻3		kW/s	14.6	21.0	38
Mechanical time constant ✻3		ms	1.57	1.21	0.94
Electrical time constant		ms	6.8	7.8	13
Allowable radial load ✻4		N	490		
Allowable thrust load ✻4		N	196		
Weight	Without brake	kg	3.9	4.7	6.6
	With brake	kg	4.8	5.8	8.6
Radiator plate dimensions (material)		mm	305 × 305 × t12 (aluminum)		400 × 400 × t20 (aluminum)
Brake specifications ✻5	Excitation voltage ✻6	V	24 VDC±10%		
	Current consumption (at 20°C)	A	0.30	0.30	0.51
	Static friction torque	N·m	3.92 min.	3.92 min.	9.0 min.
	Attraction time	ms	40 max.	40 max.	100 max.
	Release time ✻7	ms	25 max.	25 max.	30 max.
	Backlash	°	1.0 max.	1.0 max.	0.6 max.
	Allowable braking work	J	330	330	1,000
	Allowable total work	J	330,000	330,000	3,000,000
	Allowable angular acceleration	rad/s^2	10,000 max.		
	Brake lifetime (acceleration/ deceleration)	---	10 million times min.		
	Insulation class	---	Class F		

Note: 1. For the models listed in the table above, there is no derating for models with an oil seal.

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Item		Model (R88M-) / Unit	400 VAC		
			1M1K520C	1M2K020C	1M3K020C
Rated output ✻1 ✻2		W	1,500	2,000	3,000
Rated torque ✻1 ✻2		N·m	7.16	9.55	14.3
Rated rotation speed ✻1 ✻2		r/min	2,000		
Maximum rotation speed		r/min	3,000		
Momentary maximum torque ✻1		N·m	21.5	28.7	43.0
Rated current ✻1 ✻2		A (rms)	4.1	5.7	8.6
Momentary maximum current ✻1		A (rms)	13.5	19.8	28.3
Rotor inertia	Without brake	× 10^{-4} kg·m^2	9.0042	12.2042	15.3122
	With brake	× 10^{-4} kg·m^2	9.5042	12.7042	17.4122
Applicable load inertia		× 10^{-4} kg·m^2	79.9	100	142
Torque constant ✻1		N·m/ A (rms)	1.75	1.75	1.74
Power rate ✻1 ✻3		kW/s	57	75	134
Mechanical time constant ✻3		ms	0.85	0.80	0.76
Electrical time constant		ms	13	14	20
Allowable radial load ✻4		N	490		784
Allowable thrust load ✻4		N	196		343
Weight	Without brake	kg	8.5	10	12
	With brake	kg	10.5	12	15
Radiator plate dimensions (material)		mm	470 × 470 × t20 (aluminum)		
Brake specifications ✻5	Excitation voltage ✻6	V	24 VDC±10%		
	Current consumption (at 20°C)	A	0.51	0.66	0.60
	Static friction torque	N·m	9.0 min.	12 min.	16 min.
	Attraction time	ms	100 max.	100 max.	150 max.
	Release time ✻7	ms	30 max.	30 max.	50 max.
	Backlash	°	0.6 max.	0.6 max.	0.6 max.
	Allowable braking work	J	1,000	1,000	350
	Allowable total work	J	3,000,000	3,000,000	1,000,000
	Allowable angular acceleration	rad/s^2	10,000 max.		
	Brake lifetime (acceleration/ deceleration)	---	10 million times min.		
	Insulation class	---	Class F		

✻1. This is a typical value for when the Servomotor is used at a normal temperature (20°C, 65%) in combination with a Servo Drive.
✻2. The rated values are the values with which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.
✻3. This value is for models without options.
✻4. The allowable radial and thrust loads are the values determined for a limit of 20,000 hours at normal operating temperatures. The allowable radial loads are applied as shown in the following diagram.



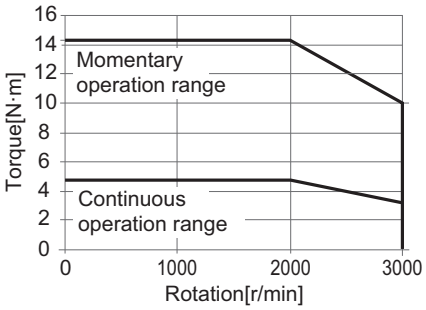
✻5. When the brake is released for a vertical axis, refer to the *AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications User's Manual* (Cat.No.I586) to set an appropriate value for Brake Interlock Output (4610 hex).
✻6. This is a non-excitation brake. It is released when excitation voltage is applied.
✻7. This value is a reference value.
Note: 1. For the models listed in the table above, there is no derating for models with an oil seal.

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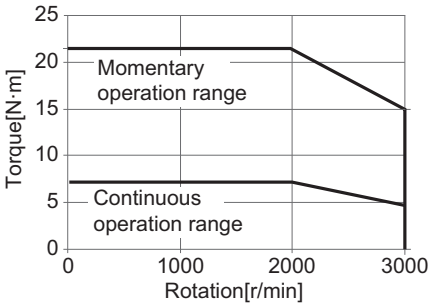
Torque-Rotation Speed Characteristics for 2,000-r/min Servomotors (200 VAC)

The following graphs show the characteristics with a 3-m standard cable and a 3-phase 200-VAC or single-phase 220-VAC input.

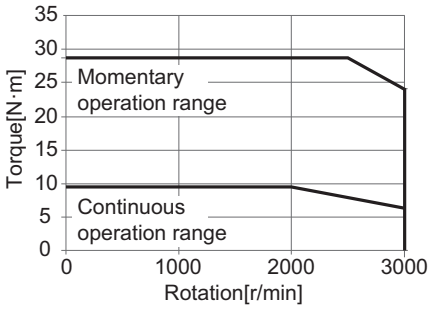
• R88M-1M1K020T



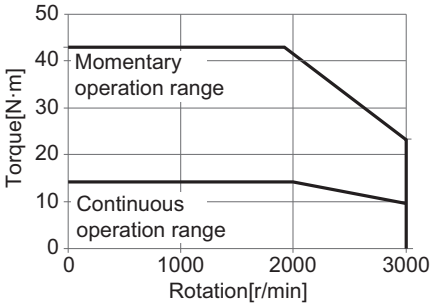
• R88M-1M1K520T



• R88M-1M2K020T



• R88M-1M3K020T

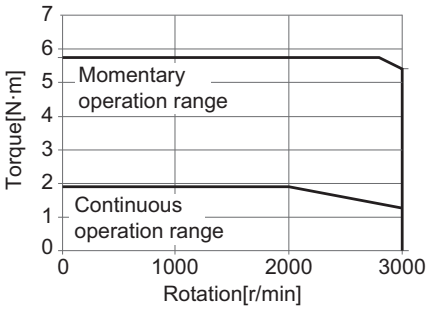


Note: The continuous operation range is the range in which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.
Continuous operation at the maximum speed is also possible. However, doing so will reduce the output torque.

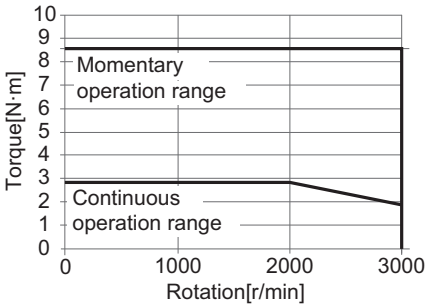
Torque-Rotation Speed Characteristics for 2,000-r/min Servomotors (400 VAC)

The following graphs show the characteristics with a 3-m standard cable and a 400 VAC input.

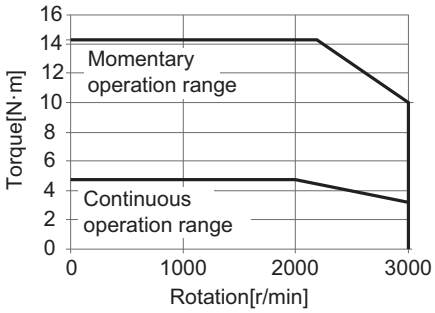
• R88M-1M40020C



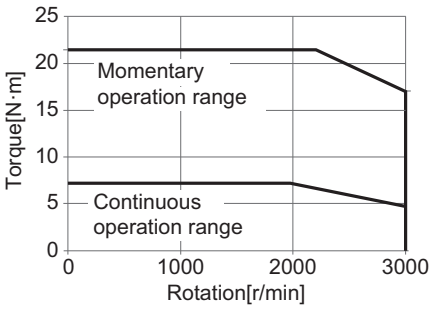
• R88M-1M60020C



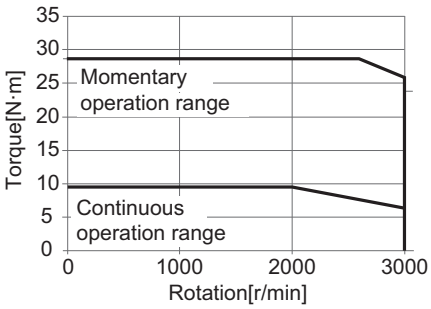
• R88M-1M1K020C



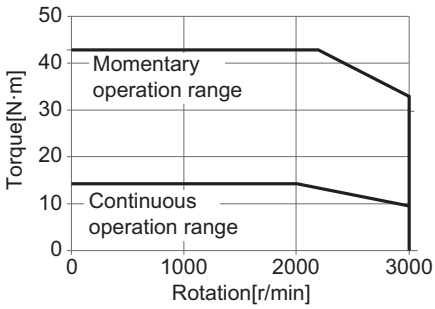
• R88M-1M1K520C



• R88M-1M2K020C



• R88M-1M3K020C



Note: The continuous operation range is the range in which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.
Continuous operation at the maximum speed is also possible. However, doing so will reduce the output torque.

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1,500-r/min Servomotors

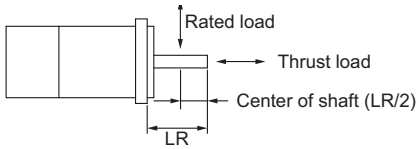
Item		Model (R88M-) / Unit	200 VAC				
			1M4K015T	1M5K015T	1M7K515T	1M11K015T	1M15K015T
Rated output ✻1 ✻2		W	4,000	5,000	7,500	11,000	15,000
Rated torque ✻1 ✻2		N·m	25.5	31.8	47.8	70.0	95.5
Rated rotation speed ✻1 ✻2		r/min	1,500				
Maximum rotation speed		r/min	3,000			2,000	
Momentary maximum torque ✻1		N·m	75	95	119	175	224
Rated current ✻1 ✻2		A (rms)	25.7	25.8	41.2	57	60.7
Momentary maximum current ✻1		A (rms)	84.8	84.8	113.0	150.0	150.0
Rotor inertia	Without brake	× 10^{-4} kg·m^2	54.0122	77.0122	113.0122	229.0122	340.0122
	With brake	× 10^{-4} kg·m^2	60.0122	83.0122	118.0122	253.0122	365.0122
Applicable load inertia		× 10^{-4} kg·m^2	687	955	1,070	2,200	3,110
Torque constant ✻1		N·m/ A (rms)	1.08	1.36	1.29	1.40	1.79
Power rate ✻1 ✻3		kW/s	120	131	202	214	268
Mechanical time constant ✻3		ms	1	1.1	0.75	0.61	0.56
Electrical time constant		ms	19	19	24	32	32
Allowable radial load ✻4		N	1,200	1,470	1,470	2,500	2,500
Allowable thrust load ✻4		N	343	490	490	686	686
Weight	Without brake	kg	21	29	39	63	85
	With brake	kg	26	34	45	73	99
Radiator plate dimensions (material)		mm	470 × 470 × t20 (aluminum)	540 × 540 × t20 (aluminum)		670 × 630 × t35 (aluminum)	
Brake specifications ✻5	Excitation voltage ✻6	V	24 VDC±10%				
	Current consumption (at 20°C)	A	1.0	1.0	1.4	1.7	0.92
	Static friction torque	N·m	32 min.	42 min.	54.9 min.	90 min.	100 min.
	Attraction time	ms	150 max.	150 max.	300 max.	300 max.	600 max.
	Release time ✻7	ms	60 max.	60 max.	140 max.	140 max.	215 max.
	Backlash	°	0.8 max.	0.8 max.	0.2 max.	0.2 max.	0.2 max.
	Allowable braking work	J	1,400	1,400	830	1,400	1,400
	Allowable total work	J	4,600,000	4,600,000	2,500,000	4,600,000	6,100,000
	Allowable angular acceleration	rad/s^2	10,000 max.		5,000 max.	3,000 max.	
	Brake lifetime (acceleration/ deceleration)	---	10 million times min.				
	Insulation class	---	Class F				

Note: 1. For the models listed in the table above, there is no derating for models with an oil seal.

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Item		Unit	Model (R88M-) 1M4K015C	1M5K515C	1M7K515C	1M11K015C	1M15K015C
			400 VAC				
Rated output ✻1 ✻2		W	4,000	5,500	7,500	11,000	15,000
Rated torque ✻1 ✻2		N·m	25.5	35.0	47.8	70	95.5
Rated rotation speed ✻1 ✻2		r/min	1,500				
Maximum rotation speed		r/min	3,000			2,000	
Momentary maximum torque ✻1		N·m	75	95	119	175	224
Rated current ✻1 ✻2		A (rms)	12.8	14.0	22.0	31.4	33.3
Momentary maximum current ✻1		A (rms)	42.4	42.4	56.5	80.7	81.2
Rotor inertia	Without brake	× 10^{-4} kg·m^2	54.0122	77.0122	113.0122	229.0122	340.0122
	With brake	× 10^{-4} kg·m^2	60.0122	83.0122	118.0122	253.0122	365.0122
Applicable load inertia		× 10^{-4} kg·m^2	687	955	1070	2200	3110
Torque constant ✻1		N·m/ A (rms)	2.07	2.68	2.49	2.6	3.27
Power rate ✻1 ✻3		kW/s	120	159	202	214	268
Mechanical time constant ✻3		ms	1.2	1	0.78	0.63	0.62
Electrical time constant		ms	18	19	23	29	29
Allowable radial load ✻4		N	1,200	1,470	1470	2,500	2,500
Allowable thrust load ✻4		N	343	490	490	686	686
Weight	Without brake	kg	21	29	39	63	85
	With brake	kg	26	34	45	73	99
Radiator plate dimensions (material)		mm	470 × 470 × t20	540 x 540x t20 (aluminum)		670 × 630 × t35 (aluminum)	
Brake specifications ✻5	Excitation voltage ✻6	V	24 VDC ± 10%				
	Current consumption (at 20°C)	A	1.0	1.0	1.4	1.7	0.92
	Static friction torque	N·m	32 min.	42 min.	54.9 min.	90 min.	100 min.
	Attraction time	ms	150 max.	150 max.	300 max.	300 max.	600 max.
	Release time ✻7	ms	60 max.	60 max.	140 max.	140 max.	215 max.
	Backlash	°	0.8 max.	0.8 max.	0.2 max.	0.2 max.	0.2 max.
	Allowable braking work	J	1,400	1,400	830	1,400	1,400
	Allowable total work	J	4,600,000	4,600,000	2,500,000	4,600,000	6,100,000
	Allowable angular acceleration	rad/s^2	10,000 max.		5,000 max.	3,000 max.	
	Brake lifetime (acceleration/ deceleration)	---	10 million times min.				
	Insulation class	---	Class F				

✻1. This is a typical value for when the Servomotor is used at a normal temperature (20°C, 65%) in combination with a Servo Drive.
✻2. The rated values are the values with which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.
✻3. This value is for models without options.
✻4. The allowable radial and thrust loads are the values determined for a limit of 20,000 hours at normal operating temperatures.
The allowable radial loads are applied as shown in the following diagram.



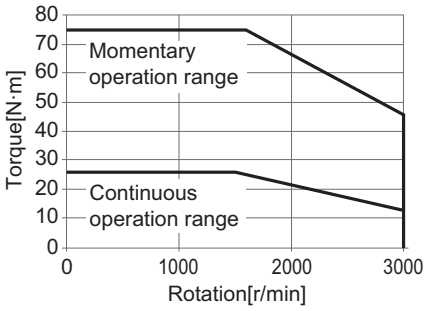
✻5. When the brake is released for a vertical axis, refer to the *AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications User's Manual* (Cat.No.I586) to set an appropriate value for Brake Interlock Output (4610 hex).
✻6. This is a non-excitation brake. It is released when excitation voltage is applied.
✻7. This value is a reference value.
Note: 1. For the models listed in the table above, there is no derating for models with an oil seal.

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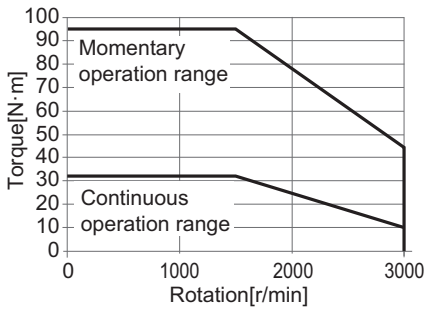
Torque-Rotation Speed Characteristics for 1,500-r/min Servomotors (200 VAC)

The following graphs show the characteristics with a 3-m standard cable and a 3-phase 200-VAC input.

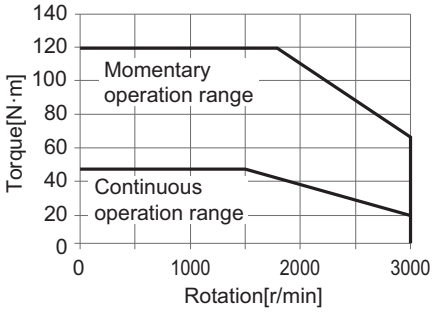
• R88M-1M4K015T



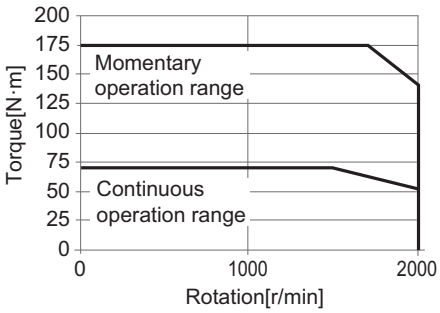
• R88M-1M5K015T



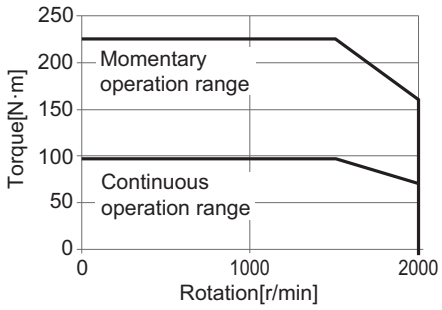
• R88M-1M7K515T



• R88M-1M11K015T



• R88M-1M15K015T

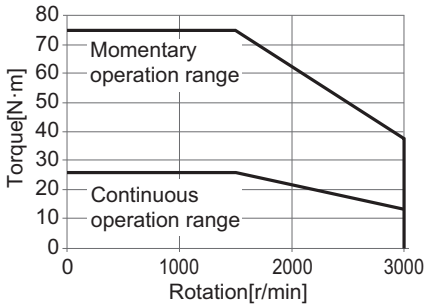


Note: The continuous operation range is the range in which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.
Continuous operation at the maximum speed is also possible. However, doing so will reduce the output torque.

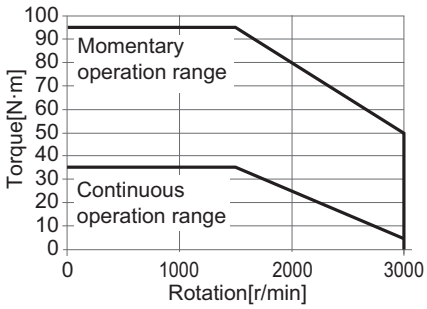
Torque-Rotation Speed Characteristics for 1,500-r/min Servomotors (400 VAC)

The following graphs show the characteristics with a 3-m standard cable and a 400 VAC input.

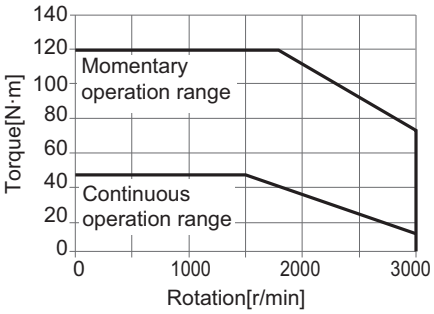
• R88M-1M4K015C



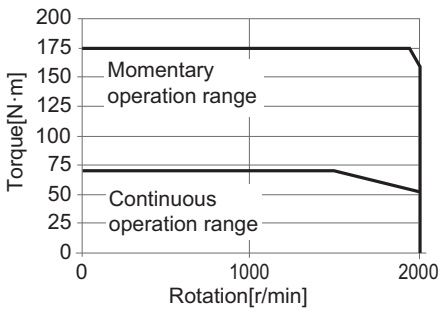
• R88M-1M5K515C



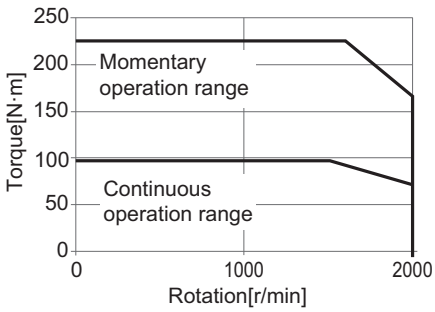
• R88M-1M7K515C



• R88M-1M11K015C



• R88M-1M15K015C



Note: The continuous operation range is the range in which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.
Continuous operation at the maximum speed is also possible. However, doing so will reduce the output torque.

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1,000-r/min Servomotors

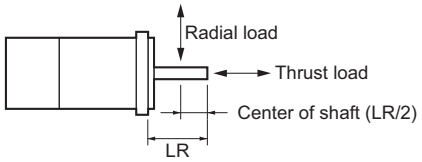
Item		Model (R88M-) / Unit	200 VAC		
			1M90010T	1M2K010T	1M3K010T
Rated output ✻1 ✻2		W	900	2,000	3,000
Rated torque ✻1 ✻2		N·m	8.59	19.1	28.7
Rated rotation speed ✻1 ✻2		r/min	1,000		
Maximum rotation speed		r/min	2,000		
Momentary maximum torque ✻1		N·m	19.3	47.7	71.7
Rated current ✻1 ✻2		A (rms)	6.7	14.4	21.2
Momentary maximum current ✻1		A (rms)	16.9	40.6	54.7
Rotor inertia	Without brake	× 10^{-4} kg·m^2	9.0042	40.0122	68.0122
	With brake	× 10^{-4} kg·m^2	9.5042	45.1122	73.1122
Applicable load inertia		× 10^{-4} kg·m^2	79.9	314	492
Torque constant ✻1		N·m/ A (rms)	1.28	1.45	1.51
Power rate ✻1 ✻3		kW/s	82	91	121
Mechanical time constant ✻3		ms	0.77	1.0	0.83
Electrical time constant		ms	15	18	22
Allowable radial load ✻4		N	686	1,176	1,470
Allowable thrust load ✻4		N	196	490	
Weight	Without brake	kg	8.5	18	28
	With brake	kg	10.5	22	33
Radiator plate dimensions (material)		mm	470 × 470 × t20 (aluminum)		540 × 540 × t20 (aluminum)
Brake specifications ✻5	Excitation voltage ✻6	V	24 VDC±10%		
	Current consumption (at 20°C)	A	0.51	1.2	1.0
	Static friction torque	N·m	9.0 min.	22 min.	42 min.
	Attraction time	ms	100 max.	120 max.	150 max.
	Release time ✻7	ms	30 max.	50 max.	60 max.
	Backlash	°	0.6 max.	0.8 max.	0.8 max.
	Allowable braking work	J	1,000	1,400	1,400
	Allowable total work	J	3,000,000	4,600,000	4,600,000
	Allowable angular acceleration	rad/s^2	10,000 max.		
	Brake lifetime (acceleration/ deceleration)	---	10 million times min.		
	Insulation class	---	Class F		

Note: 1. For the models listed in the table above, there is no derating for models with an oil seal.

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Item		Model (R88M-) / Unit	400 VAC		
			1M90010C	1M2K010C	1M3K010C
Rated output ✻1 ✻2		W	900	2,000	3,000
Rated torque ✻1 ✻2		N·m	8.59	19.1	28.7
Rated rotation speed ✻1 ✻2		r/min	1,000		
Maximum rotation speed		r/min	2,000		
Momentary maximum torque ✻1		N·m	19.3	47.7	71.7
Rated current ✻1 ✻2		A (rms)	3.6	7.1	10.6
Momentary maximum current ✻1		A (rms)	9.0	19.5	27.7
Rotor inertia	Without brake	× 10^{-4} kg·m^2	9.0042	40.0122	68.0122
	With brake	× 10^{-4} kg·m^2	9.5042	45.1122	73.1122
Applicable load inertia		× 10^{-4} kg·m^2	79.9	314	492
Torque constant ✻1		N·m/ A (rms)	2.41	3.00	2.97
Power rate ✻1 ✻3		kW/s	82	91	121
Mechanical time constant ✻3		ms	0.88	1.2	0.92
Electrical time constant		ms	13	16	19
Allowable radial load ✻4		N	686	1,176	1,470
Allowable thrust load ✻4		N	196	490	
Weight	Without brake	kg	8.5	18	28
	With brake	kg	10.5	22	33
Radiator plate dimensions (material)		mm	470 × 470 × t20 (aluminum)		540 × 540 × t20 (aluminum)
Brake specifications ✻5	Excitation voltage ✻6	V	24 VDC±10%		
	Current consumption (at 20°C)	A	0.51	1.2	1.0
	Static friction torque	N·m	9.0 min.	22 min.	42 min.
	Attraction time	ms	100 max.	120 max.	150 max.
	Release time ✻7	ms	30 max.	50 max.	60 max.
	Backlash	°	0.6 max.	0.8 max.	0.8 max.
	Allowable braking work	J	1,000	1,400	1,400
	Allowable total work	J	3,000,000	4,600,000	4,600,000
	Allowable angular acceleration	rad/s^2	10,000 max.		
	Brake lifetime (acceleration/ deceleration)	---	10 million times min.		
	Insulation class	---	Class F		

✻1. This is a typical value for when the Servomotor is used at a normal temperature (20°C, 65%) in combination with a Servo Drive.
✻2. The rated values are the values with which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.
✻3. This value is for models without options.
✻4. The allowable radial and thrust loads are the values determined for a limit of 20,000 hours at normal operating temperatures. The allowable radial loads are applied as shown in the following diagram.



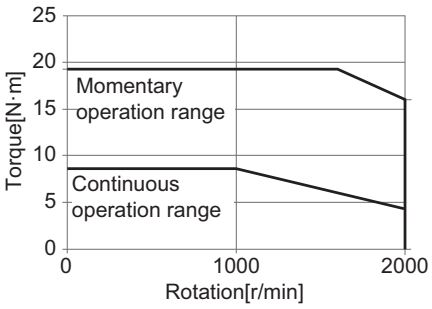
✻5. When the brake is released for a vertical axis, refer to the *AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications User's Manual* (Cat.No.I586) to set an appropriate value for Brake Interlock Output (4610 hex).
✻6. This is a non-excitation brake. It is released when excitation voltage is applied.
✻7. This value is a reference value.
Note: 1. For the models listed in the table above, there is no derating for models with an oil seal.

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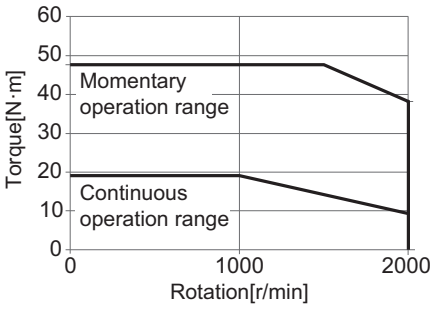
Torque-Rotation Speed Characteristics for 1,000-r/min Servomotors (200 V/400 VAC)

The following graphs show the characteristics with a 3-m standard cable and a single-phase 220-VAC or 3-phase 400-VAC input.

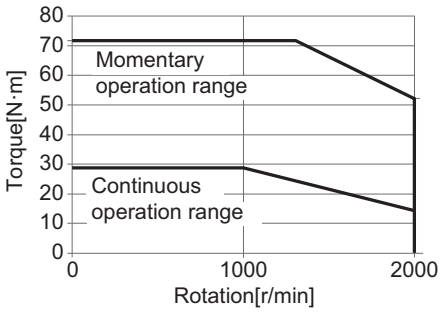
• R88M-1M90010T



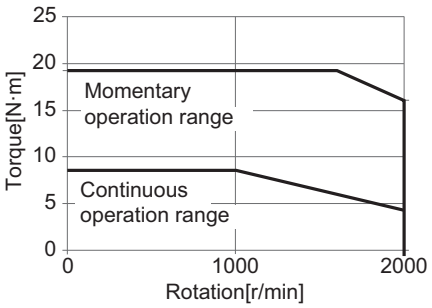
• R88M-1M2K010T



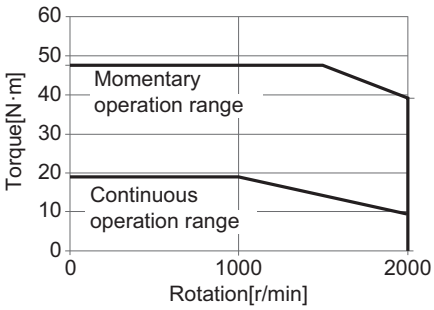
• R88M-1M3K010T



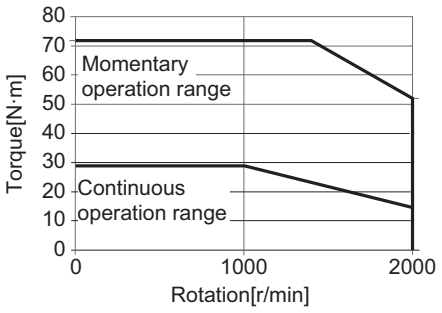
• R88M-1M90010C



• R88M-1M2K010C



• R88M-1M3K010C



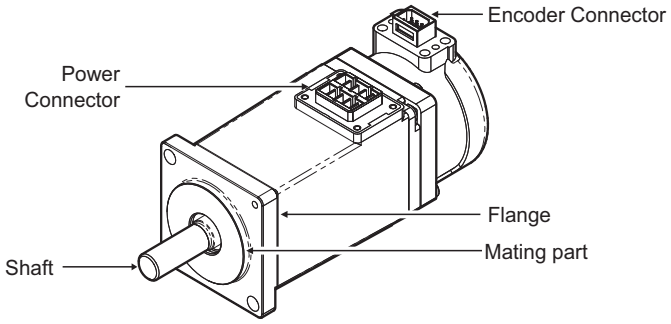
Note: The continuous operation range is the range in which continuous operation is possible at an ambient temperature of 40°C when the Servomotor is horizontally installed on a specified radiator plate.
Continuous operation at the maximum speed is also possible. However, doing so will reduce the output torque.

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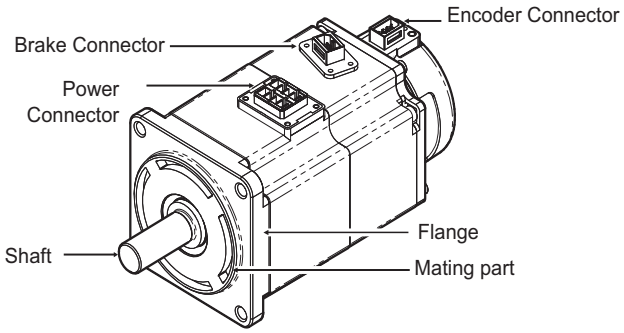
Part Names

Servomotor Part Names

Flange Size of 80 × 80 or less

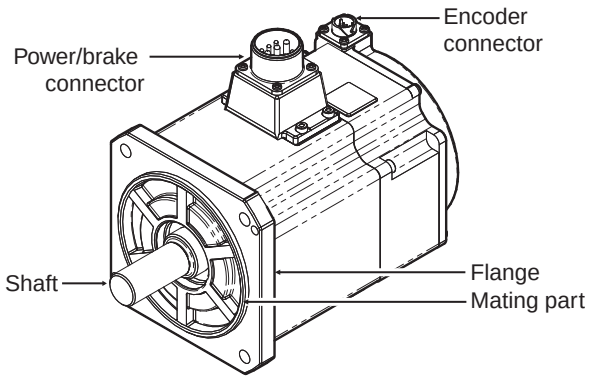


100 VAC 100 W Servomotors (without Brake)



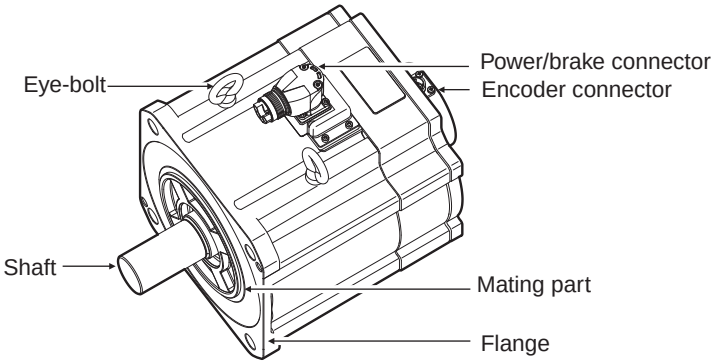
200 VAC 200 W Servomotors (with Brake)

Flange Size of 100 × 100 or more



200 VAC 1.5 kW Servomotors (with Brake)

Flange Size of 130 × 130 or more (4 kW or more)



200VAC 4kW Servomotors (with Brake)

Servomotor Functions

Shaft

The load is mounted on this shaft.
The direction which is in parallel with the shaft is called the thrust direction, and the direction which is perpendicular to the shaft is called the radial direction.

Flange

Used for mounting the Servomotor on the equipment.
Fit the mating part into the equipment and use the mounting holes to screw the Servomotor.

Power Connector

Used for supplying power to the phase U, V, and W of the Servomotor.
For Servomotors with a brake and flange size of 100 × 100 or more, the pins for power and brake are set on the same connector.
In the case of a Servomotor with its flange size □130 or more, the cable outlet direction can be selected. The change of the cable outlet direction shall be up to five times.

Encoder Connector

Used for supplying power to the encoder of the Servomotor and communicating with the Servo Drive.
When a Servomotor at 3000 r/min 4 kW or more and a Servomotor at 1500 r/min are selected, use encoder cables with metal shell type (for applicable Servomotor type B at 4 kw or more).

Brake Connector

Used for supplying power to the brake coil of the Servomotor.
This part is attached only to the Servomotors with a brake and flange size of 80 × 80 or less.

Eye-bolt

Used for lifting and moving the motor by putting a wire rope, for example, through the shaft.

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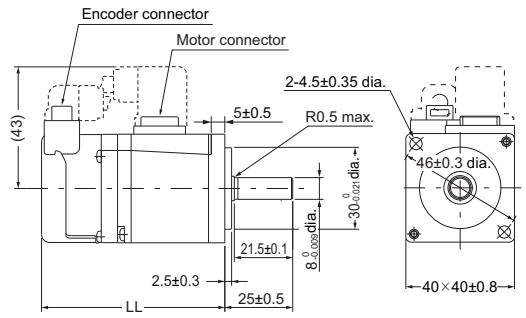
External Dimensions

(Unit: mm)

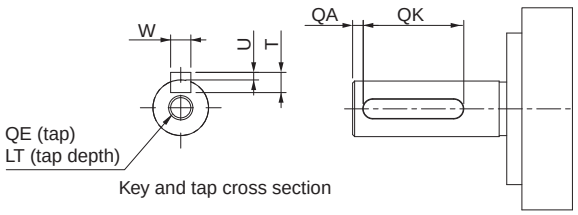
3,000-r/min Servomotors (100 V and 200 V)

50 W (without Brake)

R88M-1M05030S(-O/-S2/-OS2)
R88M-1M05030T(-O/-S2/-OS2)



Shaft-end with key and tap



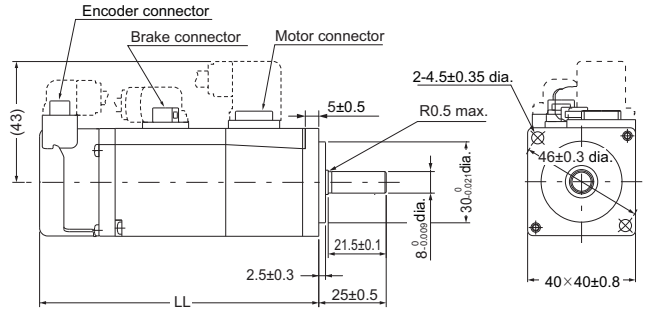
Model	Dimensions [mm]
	LL
R88M-1M05030S(-S2) R88M-1M05030T(-S2)	67.5±1
R88M-1M05030S-O(S2) R88M-1M05030T-O(S2)	72.5±1

Model	Dimensions [mm]						
	QA	QK	W	T	U	QE	LT
R88M-1M05030S (-S2/-OS2)	2	12	$3^{0}_{-0.025}$	3	$1.2^{0}_{-0.2}$	M3	8
R88M-1M05030T (-S2/-OS2)	2	12	$3^{0}_{-0.025}$	3	$1.2^{0}_{-0.2}$	M3	8

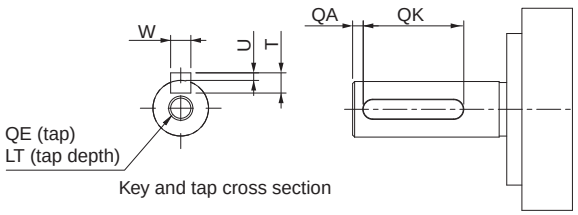
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

50 W (with Brake)

R88M-1M05030S-B(O/S2/OS2)
R88M-1M05030T-B(O/S2/OS2)



Shaft-end with key and tap



Model	Dimensions [mm]
	LL
R88M-1M05030S-B(S2) R88M-1M05030T-B(S2)	103.5±1
R88M-1M05030S-BO(S2) R88M-1M05030T-BO(S2)	108.5±1

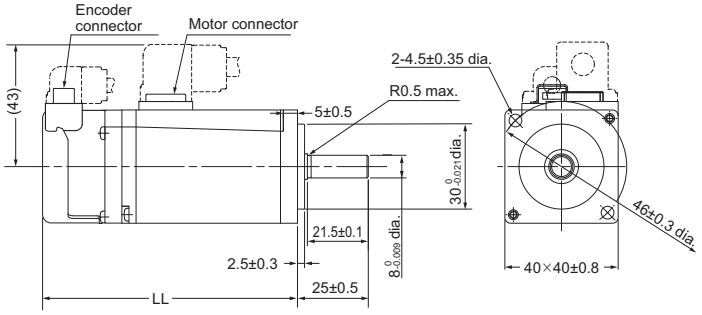
Model	Dimensions [mm]						
	QA	QK	W	T	U	QE	LT
R88M-1M05030S-B (S2/OS2)	2	12	$3^{0}_{-0.025}$	3	$1.2^{0}_{-0.2}$	M3	8
R88M-1M05030T-B (S2/OS2)	2	12	$3^{0}_{-0.025}$	3	$1.2^{0}_{-0.2}$	M3	8

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

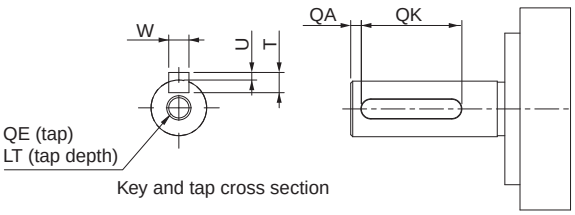
Downloaded from Arrow.com.

100 W (without Brake)

R88M-1M10030S(-O/-S2/-OS2)
R88M-1M10030T(-O/-S2/-OS2)



Shaft-end with key and tap



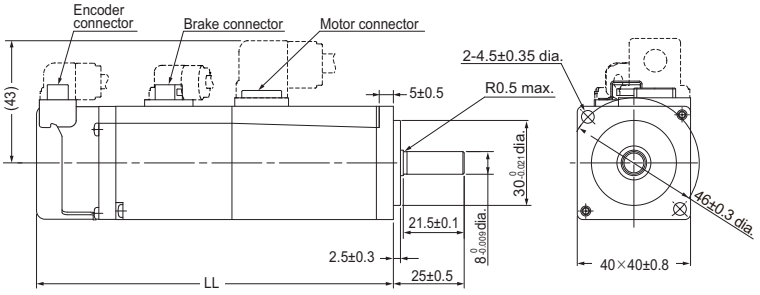
Model	Dimensions [mm]
	LL
R88M-1M10030S(-S2) R88M-1M10030T(-S2)	90±1
R88M-1M10030S-O(S2) R88M-1M10030T-O(S2)	95±1

Model	Dimensions [mm]						
	QA	QK	W	T	U	QE	LT
R88M-1M10030S(-S2/-OS2)	2	12	$3^{0}_{-0.025}$	3	$1.2^{0}_{-0.2}$	M3	8
R88M-1M10030T(-S2/-OS2)	2	12	$3^{0}_{-0.025}$	3	$1.2^{0}_{-0.2}$	M3	8

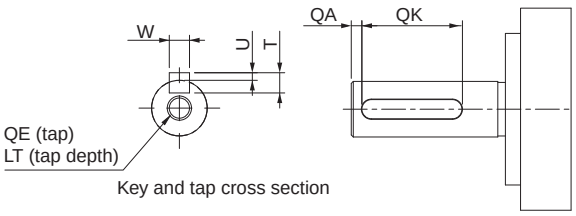
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

100 W (with Brake)

R88M-1M10030S-B(O/S2/OS2)
R88M-1M10030T-B(O/S2/OS2)



Shaft-end with key and tap



Model	Dimensions [mm]
	LL
R88M-1M10030S-B(S2) R88M-1M10030T-BS2)	126±1
R88M-1M10030S-BO(S2) R88M-1M10030T-BO(S2)	131±1

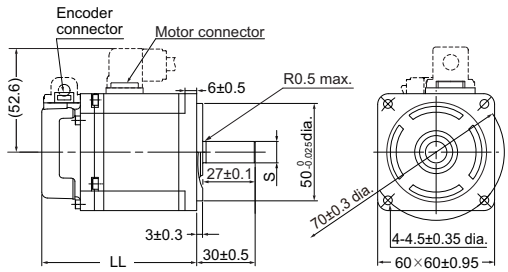
Model	Dimensions [mm]						
	QA	QK	W	T	U	QE	LT
R88M-1M10030S-B(S2/OS2)	2	12	$3^{0}_{-0.025}$	3	$1.2^{0}_{-0.2}$	M3	8
R88M-1M10030T-B(S2/OS2)	2	12	$3^{0}_{-0.025}$	3	$1.2^{0}_{-0.2}$	M3	8

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

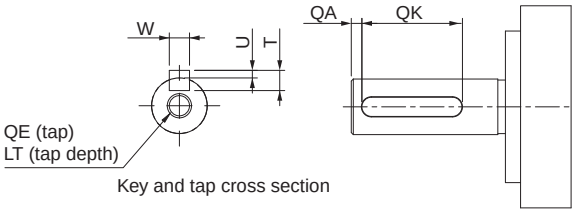
OMRON
Downloaded from Arrow.com.

200 W/400 W (without Brake)

R88M-1M20030S(-O/-S2/-OS2)/R88M-1M20030T(-O/-S2/-OS2)
R88M-1M40030S(-O/-S2/-OS2)/R88M-1M40030T(-O/-S2/-OS2)



Shaft-end with key and tap



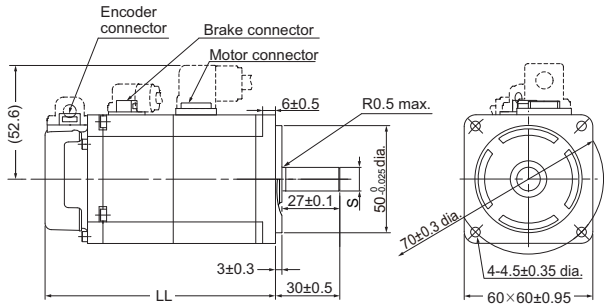
Model	Dimensions [mm]	
	S	LL
R88M-1M20030S(-S2) R88M-1M20030T(-S2)	$11^{0}_{-0.011}$ dia.	79.5±1
R88M-1M40030S(-S2) R88M-1M40030T(-S2)	$14^{0}_{-0.011}$ dia.	105.5±1
R88M-1M20030S-O(S2) R88M-1M20030T-O(S2)	$11^{0}_{-0.011}$ dia.	86.5±1
R88M-1M40030S-O(S2) R88M-1M40030T-O(S2)	$14^{0}_{-0.011}$ dia.	112.5±1

Model	Dimensions [mm]						
	QA	QK	W	T	U	QE	LT
R88M-1M20030S(-S2/-OS2)	2	20	$4^{0}_{-0.03}$	4	$1.5^{0}_{-0.2}$	M4	10
R88M-1M20030T(-S2/-OS2)	2	20	$4^{0}_{-0.03}$	4	$1.5^{0}_{-0.2}$	M4	10
R88M-1M40030S(-S2/-OS2)	2	20	$5^{0}_{-0.03}$	5	$2^{0}_{-0.2}$	M5	12
R88M-1M40030T(-S2/-OS2)	2	20	$5^{0}_{-0.03}$	5	$2^{0}_{-0.2}$	M5	12

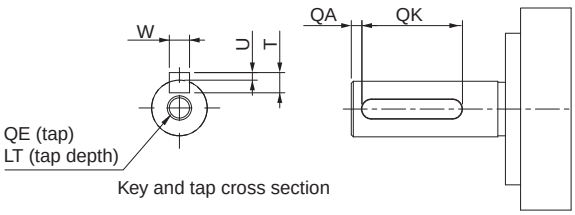
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

200 W/400 W (with Brake)

R88M-1M20030S-B(O/S2/OS2)/R88M-1M20030T-B(O/S2/OS2)
R88M-1M40030S-B(O/S2/OS2)/R88M-1M40030T-B(O/S2/OS2)



Shaft-end with key and tap



Model	Dimensions [mm]	
	S	LL
R88M-1M20030S-B(S2) R88M-1M20030T-B(S2)	$11^{0}_{-0.011}$ dia.	107.5±1
R88M-1M40030S-B(S2) R88M-1M40030T-B(S2)	$14^{0}_{-0.011}$ dia.	133.5±1
R88M-1M20030S-BO(S2) R88M-1M20030T-BO(S2)	$11^{0}_{-0.011}$ dia.	114.5±1
R88M-1M40030S-BO(S2) R88M-1M40030T-BO(S2)	$14^{0}_{-0.011}$ dia.	140.5±1

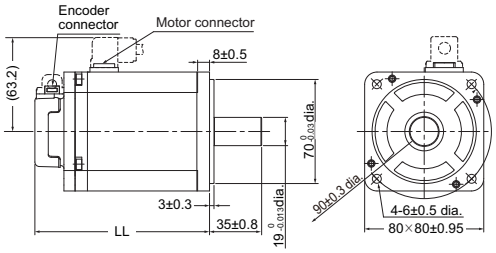
Model	Dimensions [mm]						
	QA	QK	W	T	U	QE	LT
R88M-1M20030S-B(S2/OS2)	2	20	$4^{0}_{-0.03}$	4	$1.5^{0}_{-0.2}$	M4	10
R88M-1M20030T-B(S2/OS2)	2	20	$4^{0}_{-0.03}$	4	$1.5^{0}_{-0.2}$	M4	10
R88M-1M40030S-B(S2/OS2)	2	20	$5^{0}_{-0.03}$	5	$2^{0}_{-0.2}$	M5	12
R88M-1M40030T-B(S2/OS2)	2	20	$5^{0}_{-0.03}$	5	$2^{0}_{-0.2}$	M5	12

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

Downloaded from Arrow.com.

750 W (without Brake)

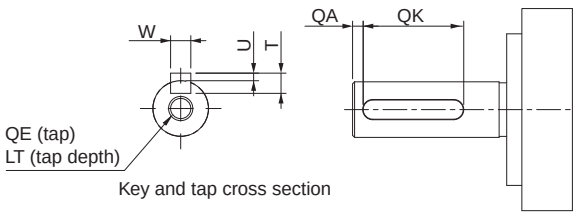
R88M-1M75030T(-O/-S2/-OS2)



Model	Dimensions [mm]
	LL
R88M-1M75030T(-S2)	117.3±1
R88M-1M75030T-O(S2)	124.3±1

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

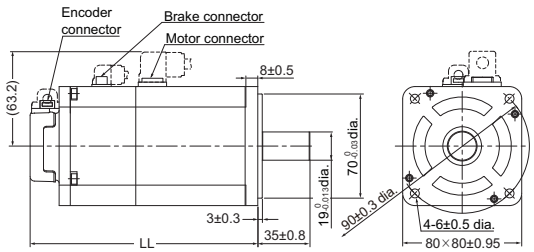
Shaft-end with key and tap



Model	Dimensions [mm]						
	QA	QK	W	T	U	QE	LT
R88M-1M75030T(-S2/-OS2)	3	24	$6^{0}_{-0.03}$	6	$2.5^{0}_{-0.2}$	M5	12

750 W (with Brake)

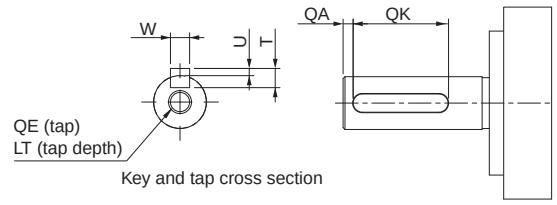
R88M-1M75030T-B(O/S2/OS2)



Model	Dimensions [mm]
	LL
R88M-1M75030T-B(S2)	153±1
R88M-1M75030T-BO(S2)	160±1

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

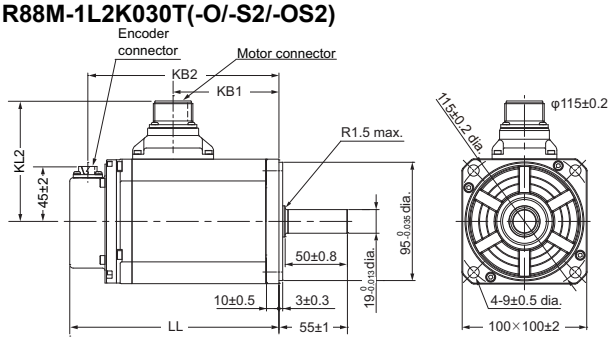
Shaft-end with key and tap



Model	Dimensions [mm]						
	QA	QK	W	T	U	QE	LT
R88M-1M75030T-B(S2/OS2)	3	24	$6^{0}_{-0.03}$	6	$2.5^{0}_{-0.2}$	M5	12

1 kW/1.5 kW/2 kW (without Brake)

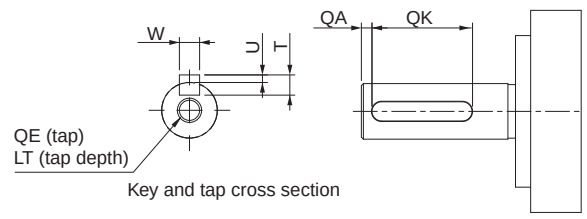
R88M-1L1K030T(-O/-S2/-OS2)/R88M-1L1K530T(-O/-S2/-OS2)/ R88M-1L2K030T(-O/-S2/-OS2)



Model	Dimensions [mm]			
	LL	KB1	KB2	KL2
R88M-1L1K030T(-O/-S2/-OS2)	168±2	85±1	153±2	97±2
R88M-1L1K530T(-O/-S2/-OS2)	168±2	85±1	153±2	97±2
R88M-1L2K030T(-O/-S2/-OS2)	179±2	96±1	164±2	102±2

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

Shaft-end with key and tap

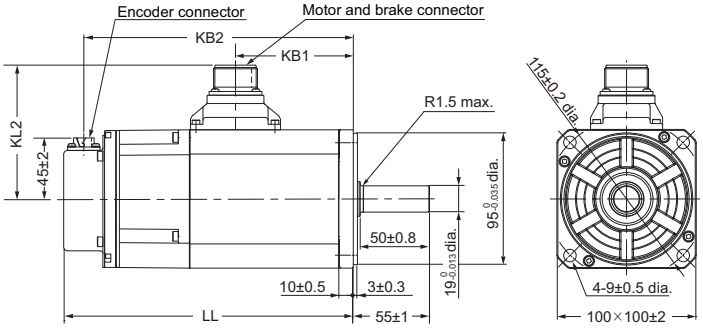


Model	Dimensions [mm]						
	QA	QK	W	T	U	QE	LT
R88M-1L1K030T(-S2/-OS2)	3	42	$6^{0}_{-0.03}$	6	$2.5^{0}_{-0.2}$	M5	12
R88M-1L1K530T(-S2/-OS2)	3	42	$6^{0}_{-0.03}$	6	$2.5^{0}_{-0.2}$	M5	12
R88M-1L2K030T(-S2/OS2)	3	42	$6^{0}_{-0.03}$	6	$2.5^{0}_{-0.2}$	M5	12

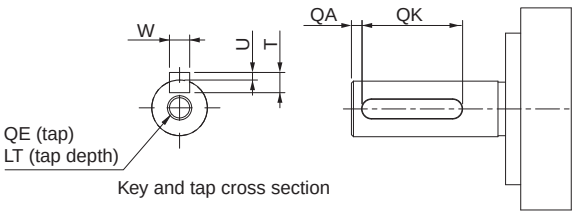
Downloaded from Arrow.com.

1 kW/1.5 kW/2 kW (with Brake)

R88M-1L1K030T-B(O/S2/OS2)/R88M-1L1K530T-B(O/S2/OS2)/ R88M-1L2K030T-B(O/S2/OS2)



Shaft-end with key and tap



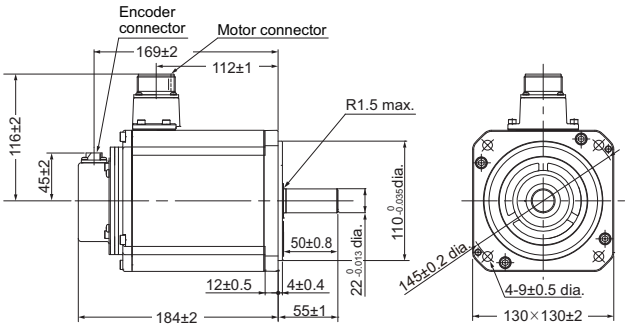
Model	Dimensions [mm]			
	LL	KB1	KB2	KL2
R88M-1L1K030T-B(O/S2/OS2)	209±3	85±1	194±2	97±2
R88M-1L1K530T-B(O/S2/OS2)	209±3	85±1	194±2	97±2
R88M-1L2K030T-B(O/S2/OS)	220±3	96±1	205±2	104±2

Model	Dimensions [mm]						
	QA	QK	W	T	U	QE	LT
R88M-1L1K030T-B(S2/OS2)	3	42	$6^{0}_{-0.03}$	6	$2.5^{0}_{-0.2}$	M5	12
R88M-1L1K530T-B(S2/OS2)	3	42	$6^{0}_{-0.03}$	6	$2.5^{0}_{-0.2}$	M5	12
R88M-1L2K030T-B(S2/OS2)	3	42	$6^{0}_{-0.03}$	6	$2.5^{0}_{-0.2}$	M5	12

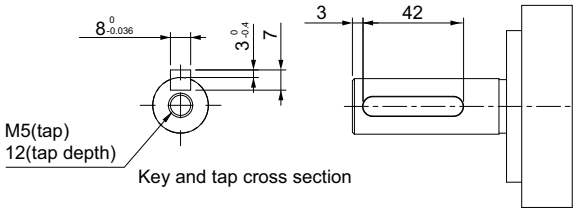
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

3 kW (without Brake)

R88M-1L3K030T(-O/-S2/-OS2)



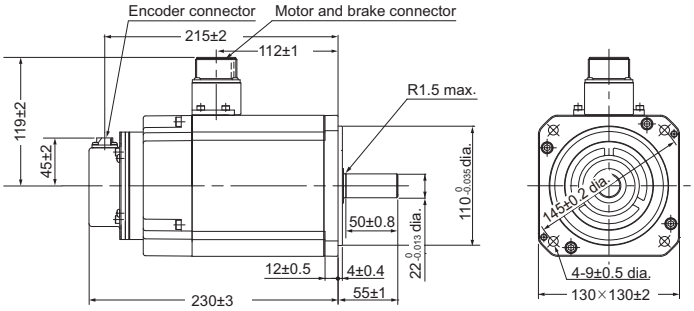
Shaft-end with key and tap



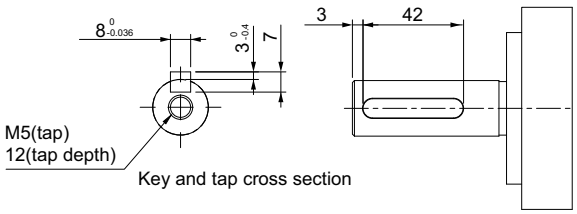
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

3 kW (with Brake)

R88M-1L3K030T-B(O/S2/OS2)



Shaft-end with key and tap

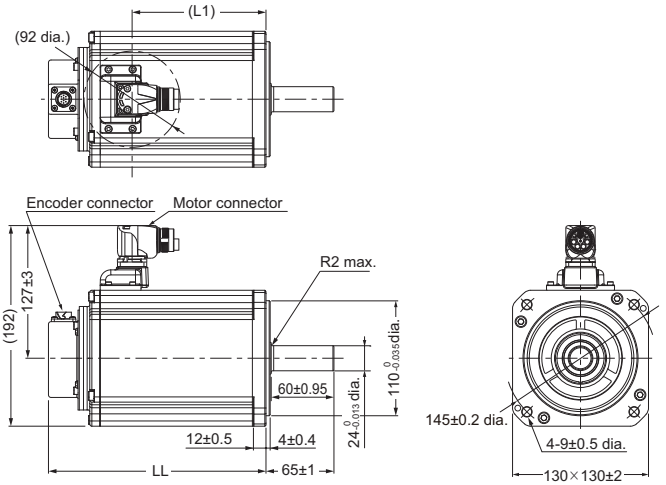


Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

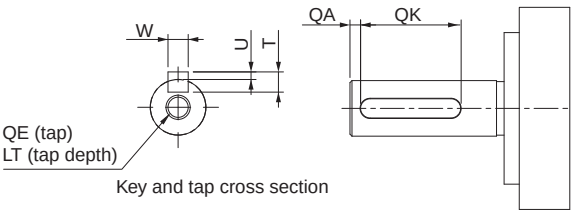
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4 kW, 4.7 kW (without Brake)

R88M-1L4K030T(-O/-S2/-OS2)
R88M-1L4K730T(-O/-S2/-OS2)



Shaft-end with key and tap



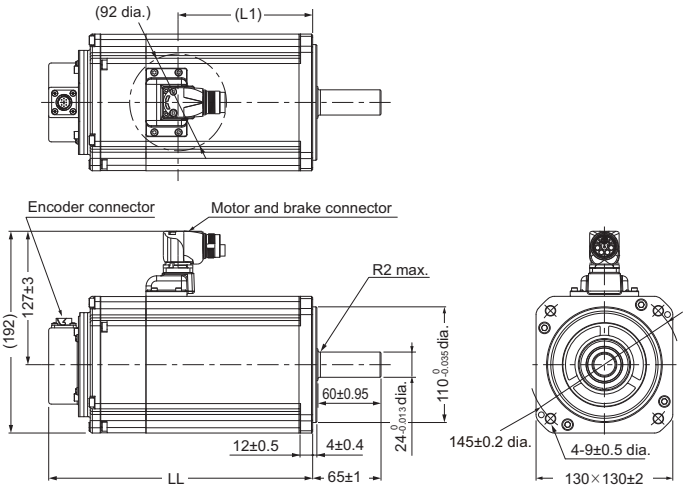
Model	Dimensions [mm]	
	LL	L1
R88M-1L4K030T(-O/-S2/-OS2)	208±3	128
R88M-1L4K730T(-O/-S2/-OS2)	232±3	152

Model	Dimensions [mm]						
	QA	QK	W	T	U	QE	LT
R88M-1L4K030T(-S2/-OS2)	3	52	$8^{0}_{-0.036}$	7	$3^{0}_{-0.4}$	M8	20
R88M-1L4K730T(-S2/-OS2)	3	52	$8^{0}_{-0.036}$	7	$3^{0}_{-0.4}$	M8	20

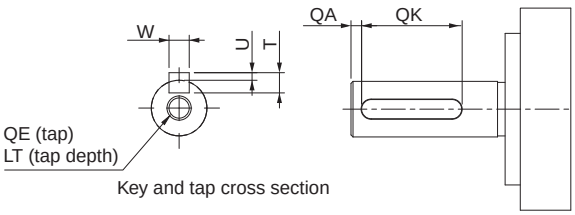
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

4 kW, 4.7 kW (with Brake)

R88M-1L4K030T-B(O/S2/OS2)
R88M-1L4K730T-B(O/S2/OS2)



Shaft-end with key and tap



Model	Dimensions [mm]	
	LL	L1
R88M-1L4K030T-B(O/S2/OS2)	251±3	128
R88M-1L4K730T-B(O/S2/OS2)	275±3	152

Model	Dimensions [mm]						
	QA	QK	W	T	U	QE	LT
R88M-1L4K030T-B(S2/OS2)	3	52	$8^{0}_{-0.036}$	7	$3^{0}_{-0.4}$	M8	20
R88M-1L4K730T-B(S2/OS2)	3	52	$8^{0}_{-0.036}$	7	$3^{0}_{-0.4}$	M8	20

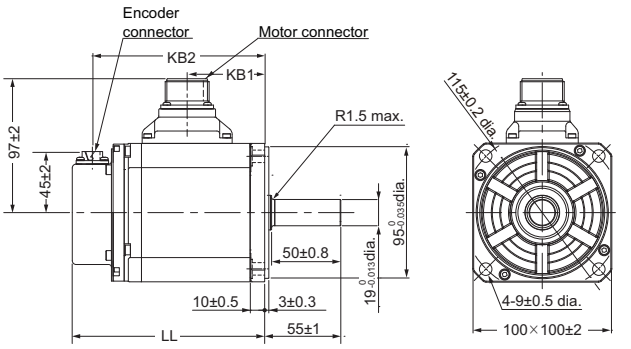
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

OMRON
Downloaded from Arrow.com.

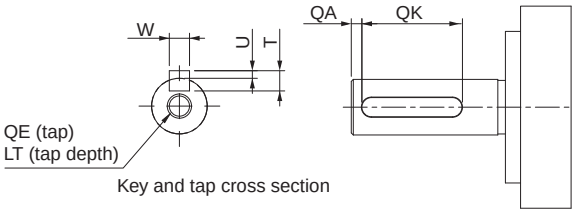
3,000-r/min Servomotors (400 V)

750 W/1 kW/1.5 kW/2 kW (without Brake)

R88M-1L75030C(-O/-S2/-OS2)/R88M-1L1K030C(-O/-S2/-OS2)
R88M-1L1K530C(-O/-S2/-OS2)/R88M-1L2K030C(-O/-S2/-OS2)



Shaft-end with key and tap



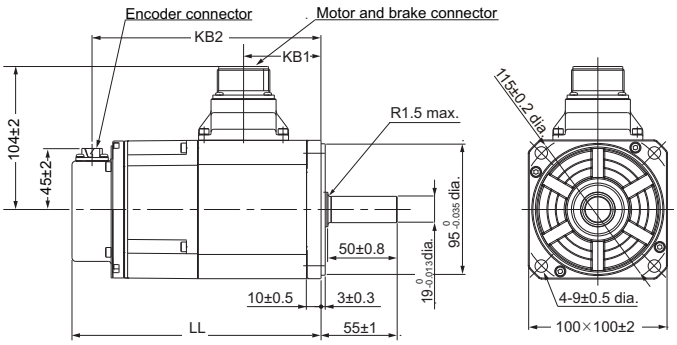
Model	Dimensions [mm]		
	LL	KB1	KB
R88M-1L75030C(-O/-S2/-OS2)	139±2	56±1	124±2
R88M-1L1K030C(-O/-S2/-OS2)	168±2	85±1	153±2
R88M-1L1K530C(-O/-S2/-OS2)	168±2	85±1	153±2
R88M-1L2K030C(-O/-S2/-OS2)	179±2	96±1	164±2

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number.
Models with an oil seal are indicated with “O” at the end of the model number.

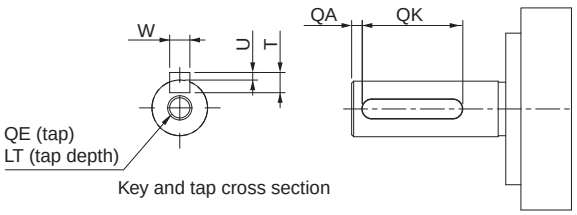
Model	Dimensions [mm]						
	QA	QK	W	T	U	QE	LT
R88M-1L75030C(-S2/-OS2)	3	42	$6^{0}_{-0.03}$	6	$2.5^{0}_{-0.2}$	M5	12
R88M-1L1K030C(-S2/-OS2)	3	42	$6^{0}_{-0.03}$	6	$2.5^{0}_{-0.2}$	M5	12
R88M-1L1K530C(-S2/-OS2)	3	42	$6^{0}_{-0.03}$	6	$2.5^{0}_{-0.2}$	M5	12
R88M-1L2K030C(-S2/-OS2)	3	42	$6^{0}_{-0.03}$	6	$2.5^{0}_{-0.2}$	M5	12

750 W/1 kW/1.5 kW/2 kW (with Brake)

R88M-1L75030C-B(O/S2/OS2)/R88M-1L1K030C-B(O/S2/OS2)
R88M-1L1K530C-B(O/S2/OS2)/R88M-1L2K030C-B(O/S2/OS2)



Shaft-end with key and tap



Model	Dimensions [mm]		
	LL	KB1	KB
R88M-1L75030C-B(O/S2/OS2)	180±2	56±1	165±2
R88M-1L1K030C-B(O/S2/OS2)	209±3	85±1	194±2
R88M-1L1K530C-B(O/S2/OS2)	209±3	85±1	194±2
R88M-1L2K030C-B(O/S2/OS2)	220±3	96±1	205±2

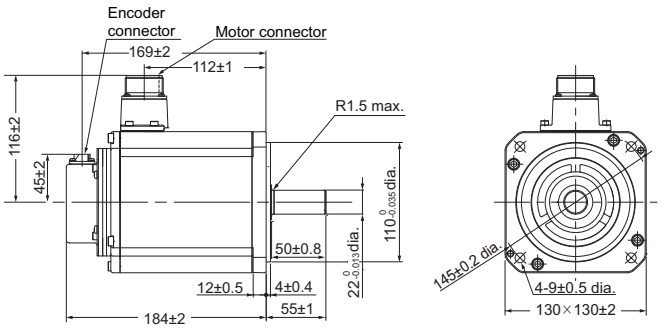
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number.
Models with an oil seal are indicated with “O” at the end of the model number.

Model	Dimensions [mm]						
	QA	QK	W	T	U	QE	LT
R88M-1L75030C-B(S2/OS2)	3	42	$6^{0}_{-0.03}$	6	$2.5^{0}_{-0.2}$	M5	12
R88M-1L1K030C-B(S2/OS2)	3	42	$6^{0}_{-0.03}$	6	$2.5^{0}_{-0.2}$	M5	12
R88M-1L1K530C-B(S2/OS2)	3	42	$6^{0}_{-0.03}$	6	$2.5^{0}_{-0.2}$	M5	12
R88M-1L2K030C-B(S2/OS2)	3	42	$6^{0}_{-0.03}$	6	$2.5^{0}_{-0.2}$	M5	12

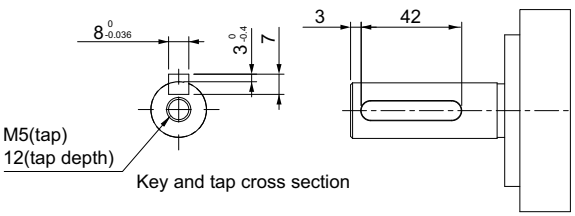
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3 kW (without Brake)

R88M-1L3K030C(-O/-S2/-OS2)



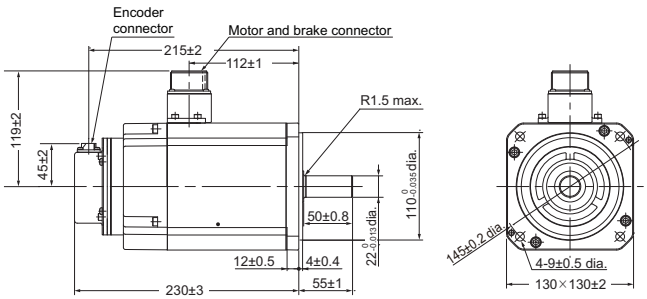
Shaft-end with key and tap



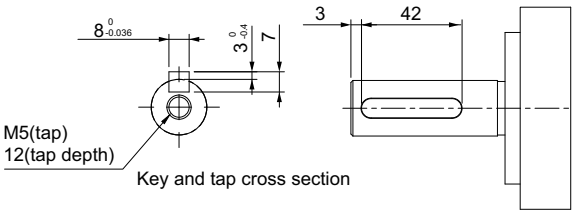
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

3 kW (with Brake)

R88M-1L3K030C-B(O/S2/OS2)



Shaft-end with key and tap

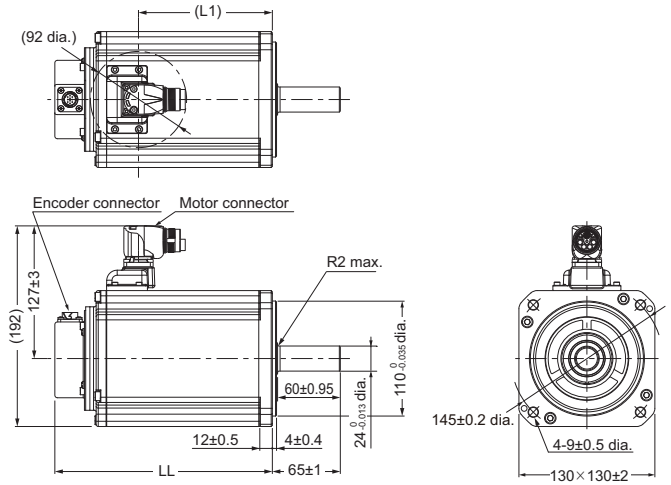


Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

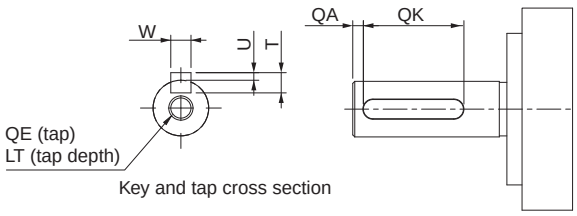
Downloaded from Arrow.com.

4 kW, 5 kW (without Brake)

R88M-1L4K030C(-O/-S2/-OS2)
R88M-1L5K030C(-O/-S2/-OS2)



Shaft-end with key and tap



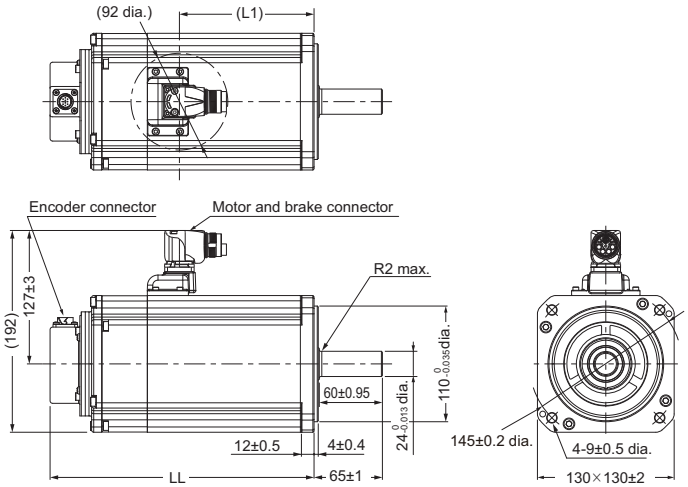
Model	Dimensions [mm]	
	LL	L1
R88M-1L4K030C(-O/-S2/-OS2)	208±3	128
R88M-1L5K030C(-O/-S2/-OS2)	232±3	152

Model	Dimensions [mm]						
	QA	QK	W	T	U	QE	LT
R88M-1L4K030C(-S2/-OS2)	3	52	$8^{0}_{-0.036}$	7	$3^{0}_{-0.4}$	M8	20
R88M-1L5K030C(-S2/-OS2)	3	52	$8^{0}_{-0.036}$	7	$3^{0}_{-0.4}$	M8	20

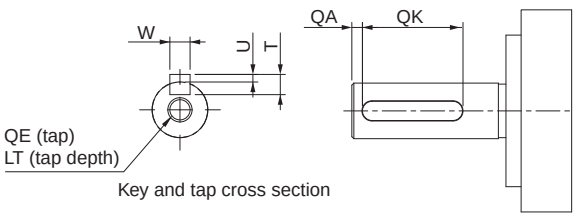
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

4 kW, 5 kW (with Brake)

R88M-1L4K030C-B(O/S2/OS2)
R88M-1L5K030C-B(O/S2/OS2)



Shaft-end with key and tap



Model	Dimensions [mm]	
	LL	L1
R88M-1L4K030C-B(O/S2/OS2)	251±3	128
R88M-1L5K030C-B(O/S2/OS2)	275±3	152

Model	Dimensions [mm]						
	QA	QK	W	T	U	QE	LT
R88M-1L4K030C-B(S2/OS2)	3	52	$8^{0}_{-0.036}$	7	$3^{0}_{-0.4}$	M8	20
R88M-1L5K030C-B(S2/OS2)	3	52	$8^{0}_{-0.036}$	7	$3^{0}_{-0.4}$	M8	20

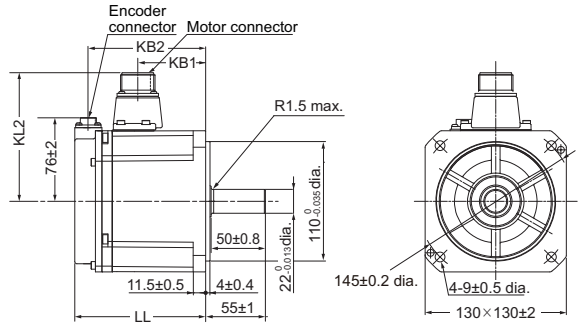
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

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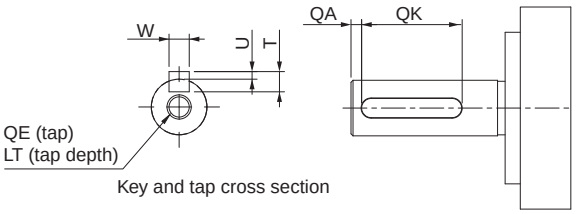
2,000-r/min Servomotors (200 V)

1 kW/1.5 kW/2 kW (without Brake)

R88M-1M1K020T(-O/-S2/-OS2)
R88M-1M1K520T(-O/-S2/-OS2)
R88M-1M2K020T(-O/-S2/-OS2)



Shaft-end with key and tap



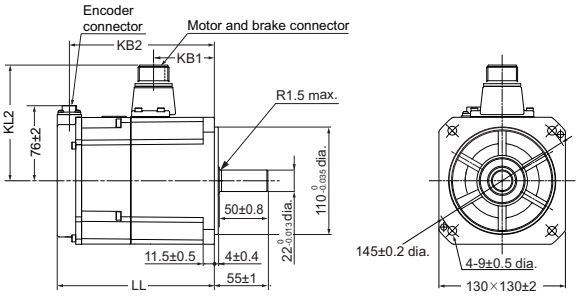
Model	Dimensions [mm]			
	LL	KB1	KB2	KL2
R88M-1M1K020T(-O/-S2/-OS2)	120.5±2	63±1	109±2	118±2
R88M-1M1K520T(-O/-S2/-OS2)	138±2	79±1	125±2	118±2
R88M-1M2K020T(-O/-S2/-OS2)	160±2	99±1	147±2	116±2

Model	Dimensions [mm]						
	QA	QK	W	T	U	QE	LT
R88M-1M1K020T(-S2/-OS2)	3	42	$8^{0}_{-0.036}$	7	$3^{0}_{-0.4}$	M5	12
R88M-1M1K520T(-S2/-OS2)	3	42	$8^{0}_{-0.036}$	7	$3^{0}_{-0.4}$	M5	12
R88M-1M2K020T(-S2/-OS2)	3	42	$8^{0}_{-0.036}$	7	$3^{0}_{-0.4}$	M5	12

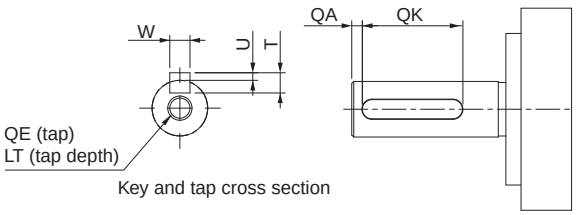
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

1 kW/1.5 kW/2 kW (with Brake)

R88M-1M1K020T-B (O/S2/OS2)
R88M-1M1K520T-B(O/S2/OS2)
R88M-1M2K020T-B(O/S2/OS2)



Shaft-end with key and tap



Model	Dimensions [mm]			
	LL	KB1	KB2	KL2
R88M-1M1K020T-B(O/S2/OS2)	162±2	63±1	149±2	118±2
R88M-1M1K520T-B(O/S2/OS2)	179±2	79±1	166±2	118±2
R88M-1M2K020T-B(O/S2/OS2)	201±3	99±1	189±2	119±2

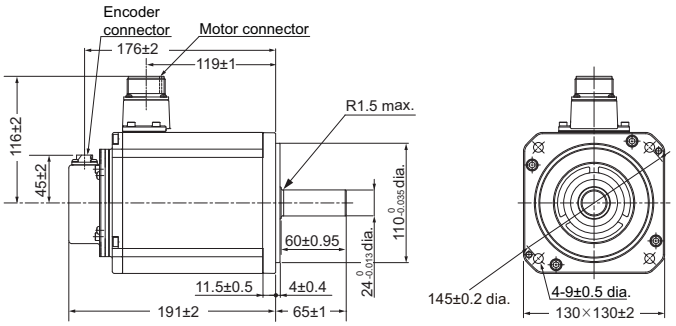
Model	Dimensions [mm]						
	QA	QK	W	T	U	QE	LT
R88M-1M1K020T-B(S2/OS2)	3	42	$8^{0}_{-0.036}$	7	$3^{0}_{-0.4}$	M5	12
R88M-1M1K520T-B(S2/OS2)	3	42	$8^{0}_{-0.036}$	7	$3^{0}_{-0.4}$	M5	12
R88M-1M2K020T-B(S2/OS2)	3	42	$8^{0}_{-0.036}$	7	$3^{0}_{-0.4}$	M5	12

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

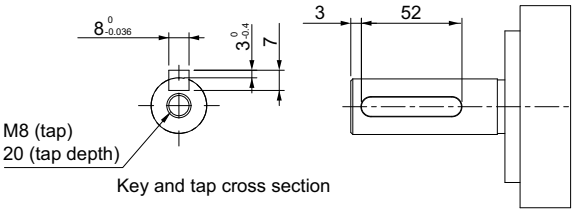
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3 kW (without Brake)

R88M-1M3K020T(-O/-S2/-OS2)



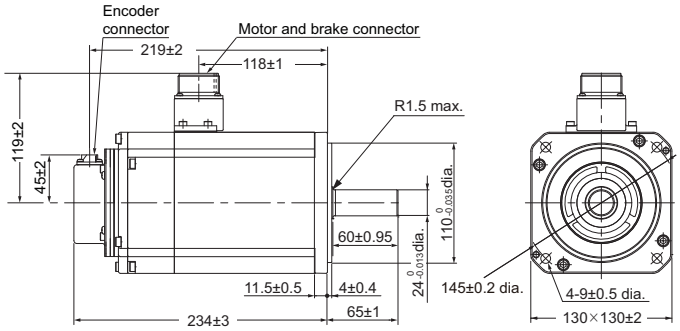
Shaft-end with key and tap



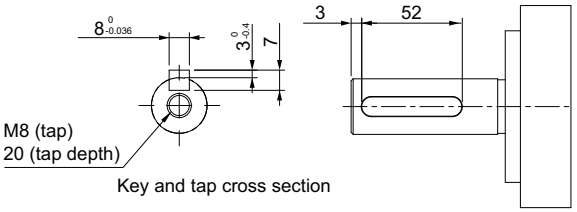
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

3 kW (with Brake)

R88M-1M3K020T-B(O/S2/OS2)



Shaft-end with key and tap



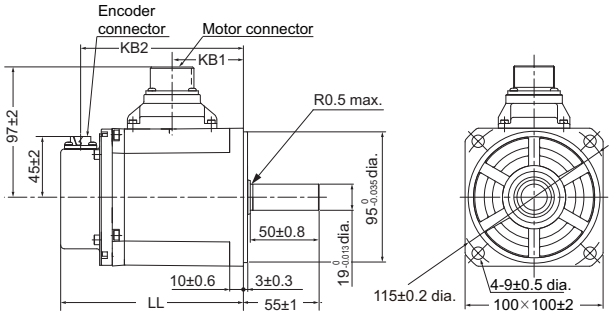
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

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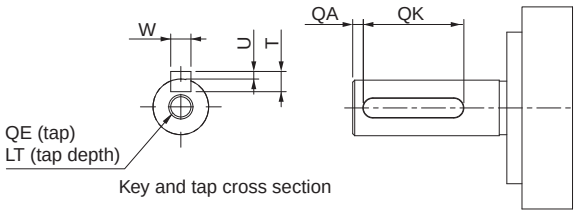
2,000-r/min Servomotors (400 V)

400 W/600 W (without Brake)

R88M-1M40020C(-O/-S2/-OS2)/R88M-1M60020C(-O/-S2/-OS2)



Shaft-end with key and tap



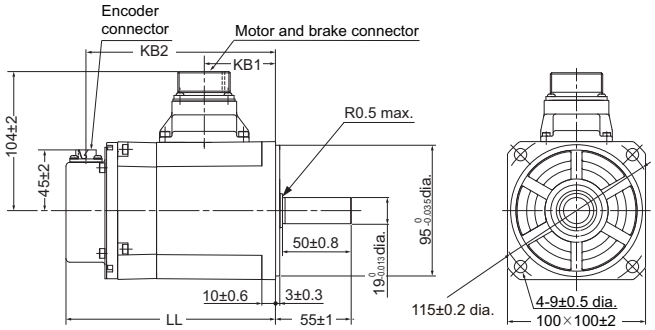
Model	Dimensions [mm]		
	LL	KB1	KB2
R88M-1M40020C(-O/-S2/-OS2)	134.8±1	52±1	120.5±2
R88M-1M60020C(-O/-S2/-OS2)	151.8±1	69±1	137.5±2

Model	Dimensions [mm]						
	QA	QK	W	T	U	QE	LT
R88M-1M40020C(-S2/-OS2)	3	42	$6^{0}_{-0.03}$	6	$2.5^{0}_{-0.2}$	M5	12
R88M-1M60020C(-S2/-OS2)	3	42	$6^{0}_{-0.03}$	6	$2.5^{0}_{-0.2}$	M5	12

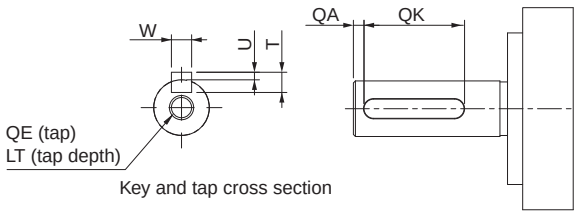
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

400 W/600 W (with Brake)

R88M-1M40020C-B(O/S2/OS2)/R88M-1M60020C-B(O/S2/OS2)



Shaft-end with key and tap



Model	Dimensions [mm]		
	LL	KB1	KB2
R88M-1M40020C-B(O/S2/OS2)	152.3±1	52±1	138±2
R88M-1M60020C-B(O/S2/OS2)	169.3±1	69±1	155±2

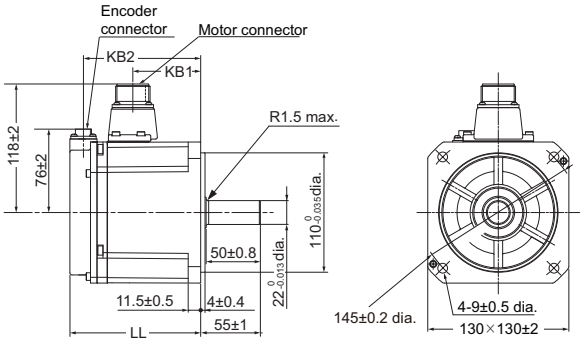
Model	Dimensions [mm]						
	QA	QK	W	T	U	QE	LT
R88M-1M40020C-B(S2/OS2)	3	42	$6^{0}_{-0.03}$	6	$2.5^{0}_{-0.2}$	M5	12
R88M-1M60020C-B(S2/OS2)	3	42	$6^{0}_{-0.03}$	6	$2.5^{0}_{-0.2}$	M5	12

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

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1 kW/1.5 kW/2 kW (without Brake)

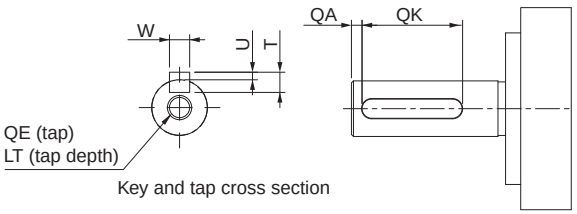
R88M-1M1K020C(-O/-S2/-OS2)
R88M-1M1K520C(-O/-S2/-OS2)
R88M-1M2K020C(-O/-S2/-OS2)



Model	Dimensions [mm]		
	LL	KB1	KB2
R88M-1M1K020C(-O/-S2/-OS2)	120.5±2	63±1	109±2
R88M-1M1K520C(-O/-S2/-OS2)	138±2	79±1	125±2
R88M-1M2K020C(-O/-S2/-OS2)	160±2	98±1	148±2

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.
Models with an oil seal are indicated with "O" at the end of the model number.

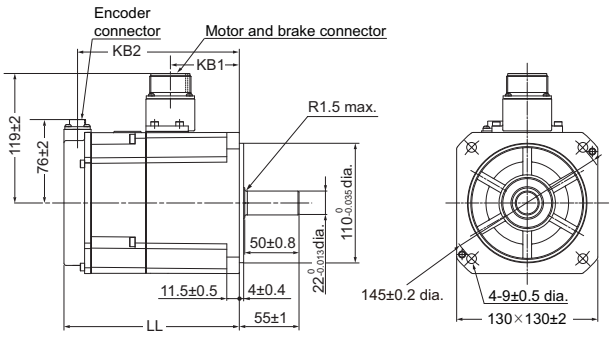
Shaft-end with key and tap



Model	Dimensions [mm]						
	QA	QK	W	T	U	QE	LT
R88M-1M1K020C(-S2/-OS2)	3	42	$8^{0}_{-0.036}$	7	$3^{0}_{-0.4}$	M5	12
R88M-1M1K520C(-S2/-OS2)	3	42	$8^{0}_{-0.036}$	7	$3^{0}_{-0.4}$	M5	12
R88M-1M2K020C(-S2/-OS2)	3	42	$8^{0}_{-0.036}$	7	$3^{0}_{-0.4}$	M5	12

1 kW/1.5 kW/2 kW (with Brake)

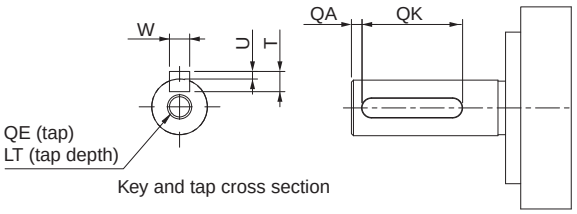
R88M-1M1K020C-B(O/S2/OS2)
R88M-1M1K520C-B(O/S2/OS2)
R88M-1M2K020C-B(O/S2/OS2)



Model	Dimensions [mm]		
	LL	KB1	KB2
R88M-1M1K020C-B(O/S2/OS2)	162±2	64±1	150±2
R88M-1M1K520C-B(O/S2/OS2)	179±2	81±1	167±2
R88M-1M2K020C-B(O/S2/OS2)	201±3	99±1	189±2

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with "S2" at the end of the model number.
Models with an oil seal are indicated with "O" at the end of the model number.

Shaft-end with key and tap

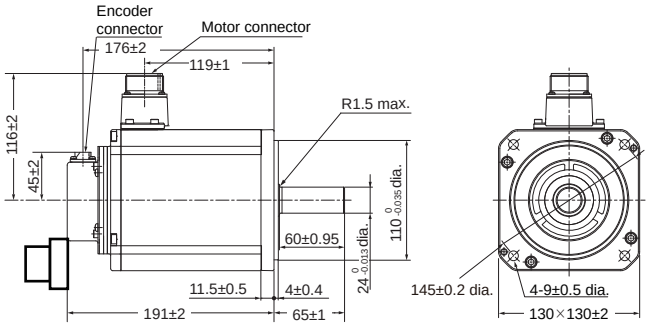


Model	Dimensions [mm]						
	QA	QK	W	T	U	QE	LT
R88M-1M1K020C-B(S2/OS2)	3	42	$8^{0}_{-0.036}$	7	$3^{0}_{-0.4}$	M5	12
R88M-1M1K520C-B(S2/OS2)	3	42	$8^{0}_{-0.036}$	7	$3^{0}_{-0.4}$	M5	12
R88M-1M2K020C-B(S2/OS2)	3	42	$8^{0}_{-0.036}$	7	$3^{0}_{-0.4}$	M5	12

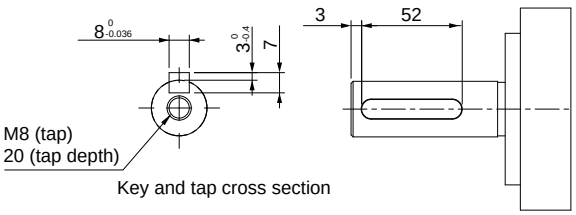
Downloaded from Arrow.com.

3 kW (without Brake)

R88M-1M3K020C(-O/-S2/-OS2)



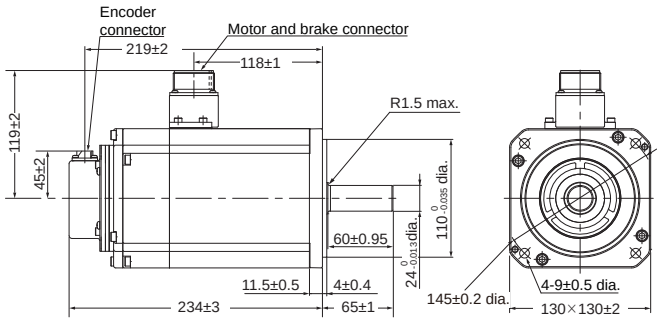
Shaft-end with key and tap



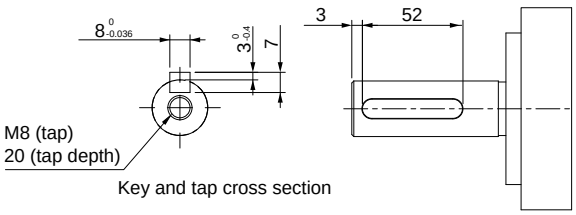
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

3 kW (with Brake)

R88M-1M3K020C-B(O/S2/OS2)



Shaft-end with key and tap



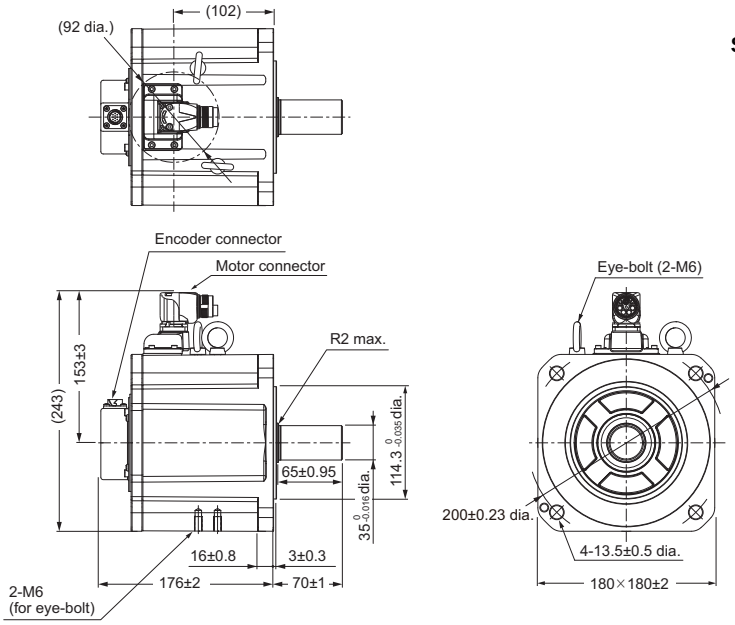
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

Downloaded from Arrow.com.

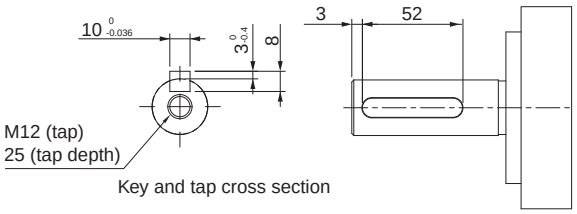
1,500-r/min Servomotors (200 V)

4 kW (without Brake)

R88M-1M4K015T(-O/-S2/-OS2)



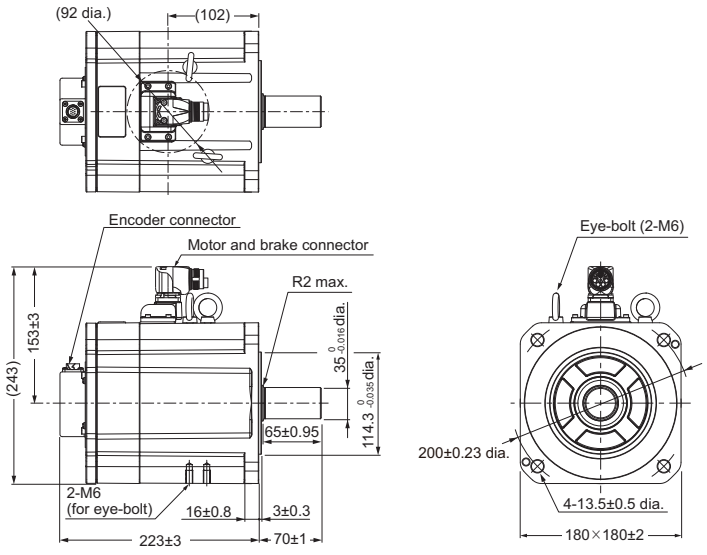
Shaft-end with key and tap



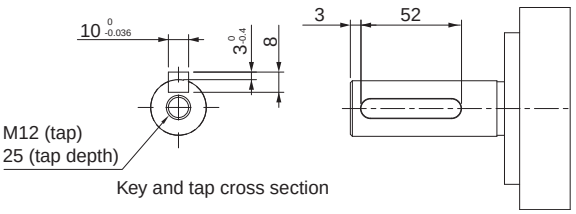
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

4 kW (with Brake)

R88M-1M4K015T-B(O/S2/OS2)



Shaft-end with key and tap

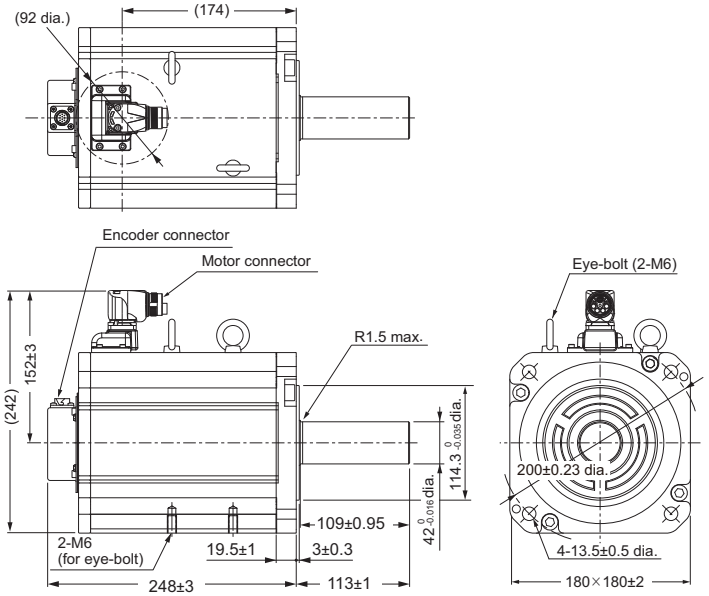


Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

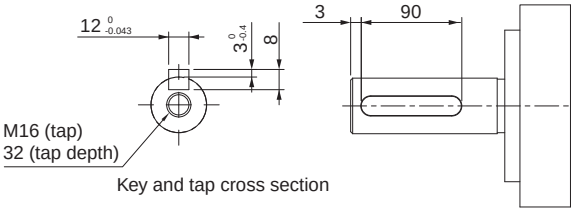
Downloaded from Arrow.com.

5 kW (without Brake)

R88M-1M5K015T(-O/-S2/-OS2)



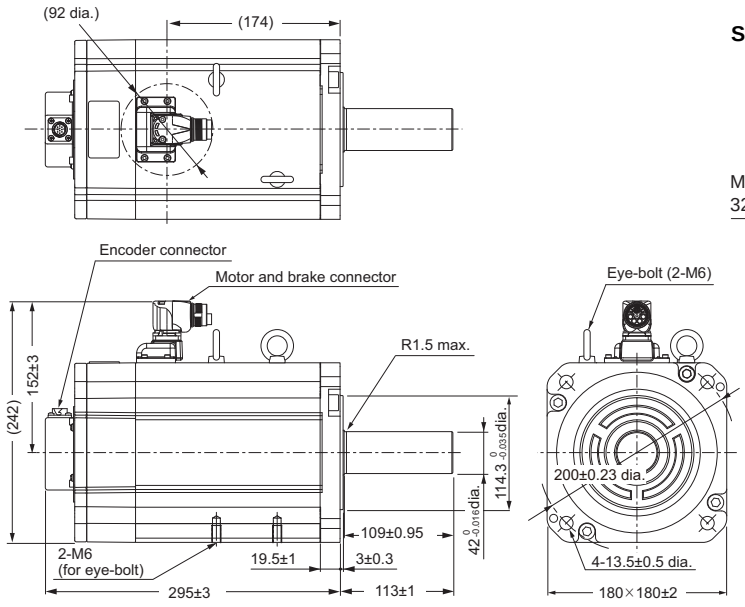
Shaft-end with key and tap



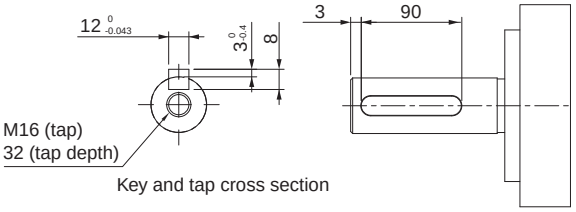
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

5 kW (with Brake)

R88M-1M5K015T-B(O/S2/OS2)



Shaft-end with key and tap

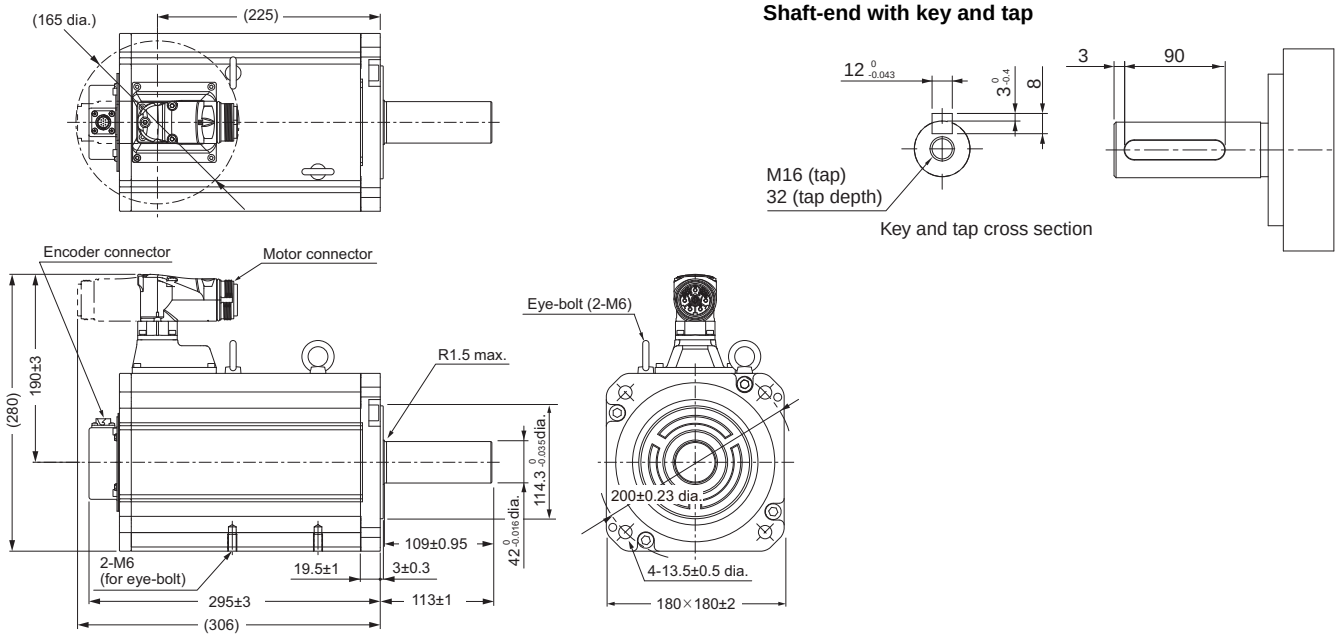


Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

Downloaded from Arrow.com.

7.5 kW (without Brake)

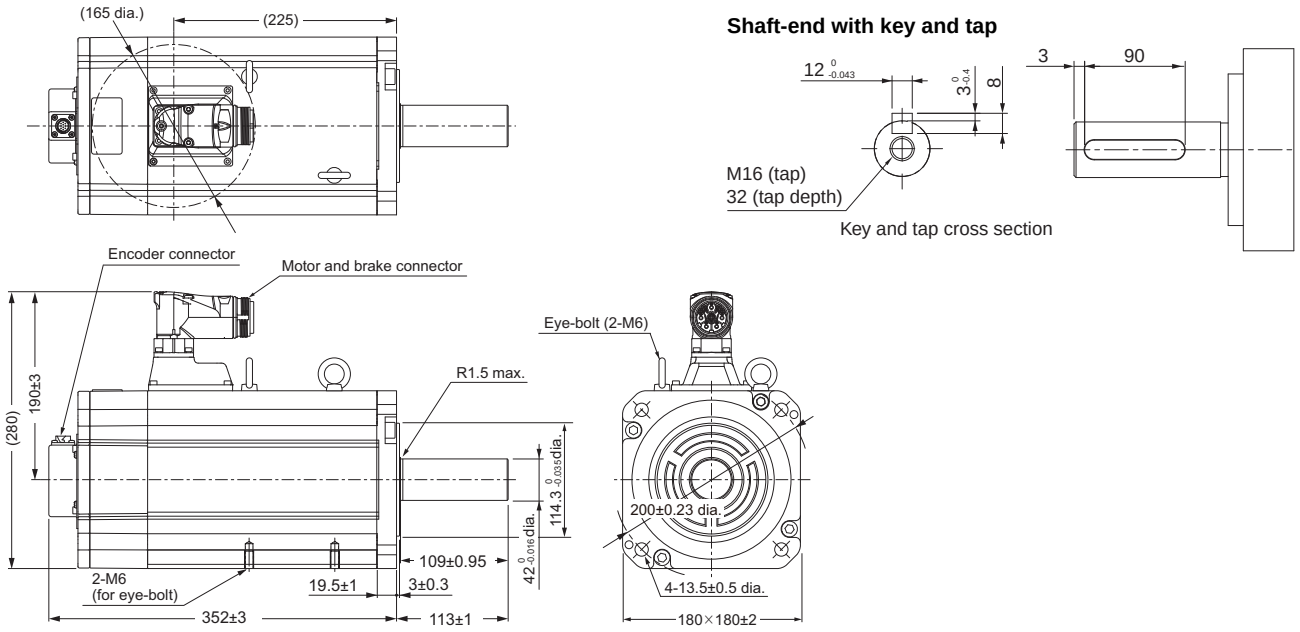
R88M-1M7K515T(-O/-S2/-OS2)



Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

7.5 kW (with Brake)

R88M-1M7K515T-B(O/S2/OS2)

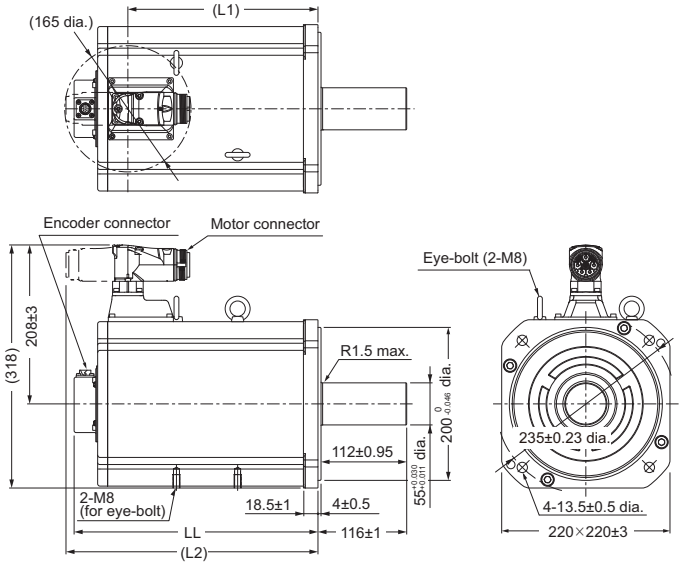


Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

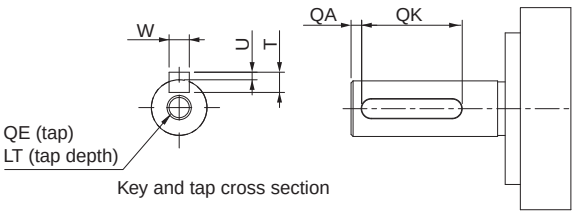
Downloaded from Arrow.com.

11 kW/15 kW (without Brake)

R88M-1M11K015T(-O/-S2/-OS2)
R88M-1M15K015T(-O/-S2/-OS2)



Shaft-end with key and tap



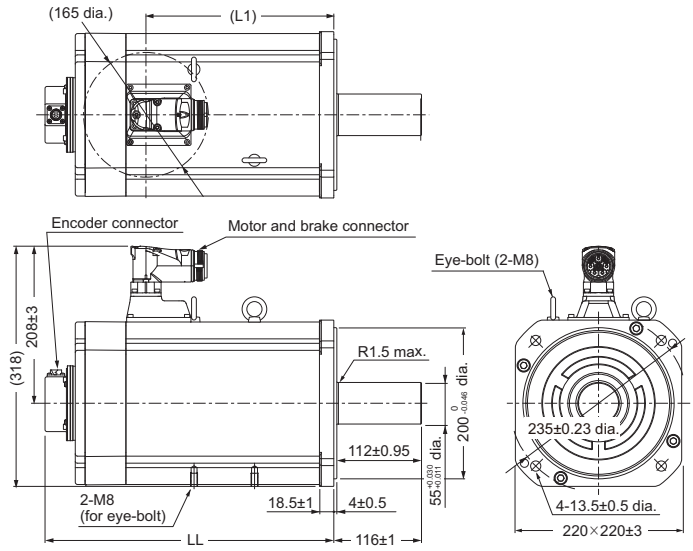
Model	Dimensions [mm]		
	LL	L1	L2
R88M-1M11K015T(-O/-S2/-OS2)	319±3	249	330
R88M-1M15K015T(-O/-S2/-OS2)	397±3	327	408

Model	Dimensions [mm]						
	QA	QK	W	T	U	QE	LT
R88M-1M11K015T(-S2/-OS2)	3	93	$16^{0}_{-0.043}$	10	$4^{0}_{-0.4}$	M20	40
R88M-1M15K015T(-S2/-OS2)	3	93	$16^{0}_{-0.043}$	10	$4^{0}_{-0.4}$	M20	40

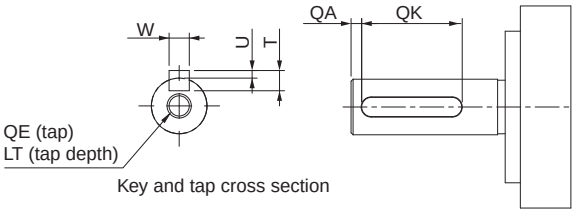
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

11 kW/15 kW (with Brake)

R88M-1M11K015T-B(O/S2/OS2)
R88M-1M15K015T-B(O/S2/OS2)



Shaft-end with key and tap



Model	Dimensions [mm]	
	LL	L1
R88M-1M11K015T-B(O/S2/OS2)	382±3	249
R88M-1M15K015T-B(O/S2/OS2)	493±3	327

Model	Dimensions [mm]						
	QA	QK	W	T	U	QE	LT
R88M-1M11K015T-B(S2/OS2)	3	93	$16^{0}_{-0.043}$	10	$4^{0}_{-0.4}$	M20	40
R88M-1M15K015T-B(S2/OS2)	3	93	$16^{0}_{-0.043}$	10	$4^{0}_{-0.4}$	M20	40

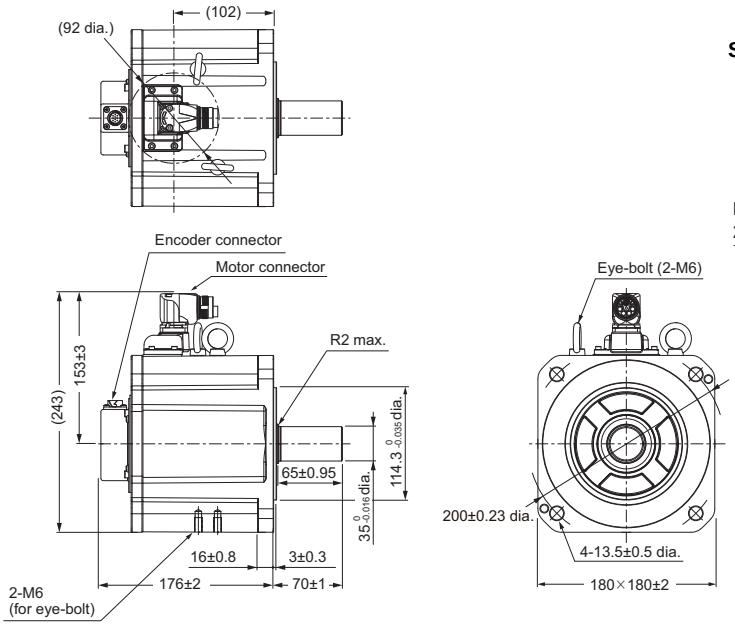
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

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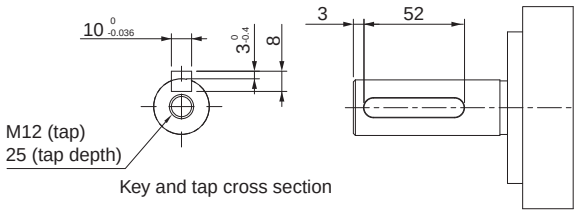
1,500-r/min Servomotors (400 V)

4 kW (without Brake)

R88M-1M4K015C(-O/-S2/-OS2)



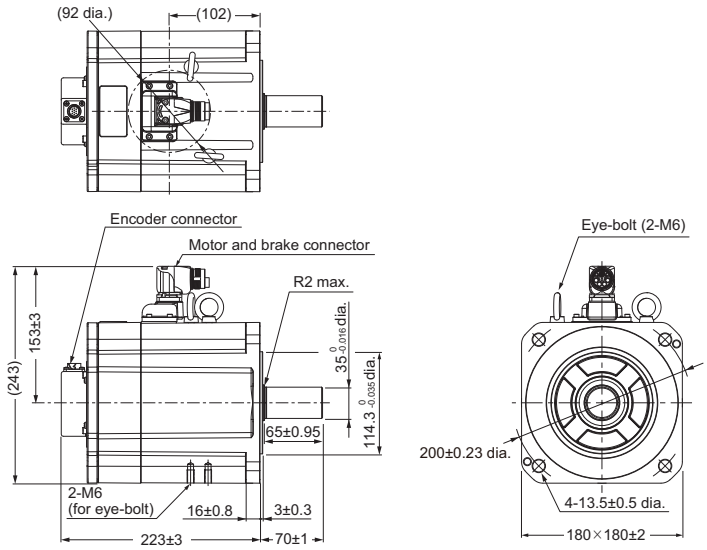
Shaft-end with key and tap



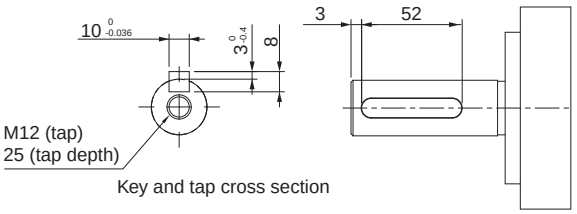
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

4 kW (with Brake)

R88M-1M4K015C-B(O/S2/OS2)



Shaft-end with key and tap

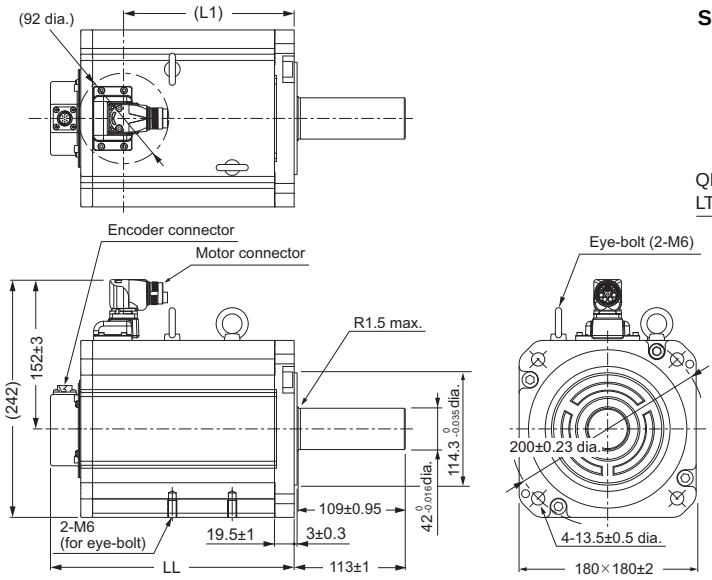


Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

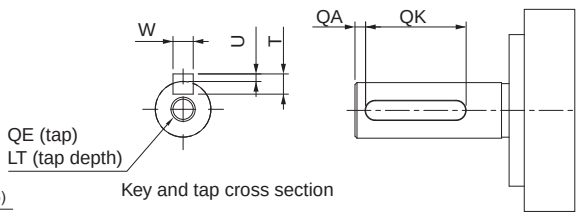
Downloaded from Arrow.com.

5.5 kW/7.5 kW (without Brake)

R88M-1M5K515C(-O/-S2/-OS2)
R88M-1M7K515C(-O/-S2/-OS2)



Shaft-end with key and tap



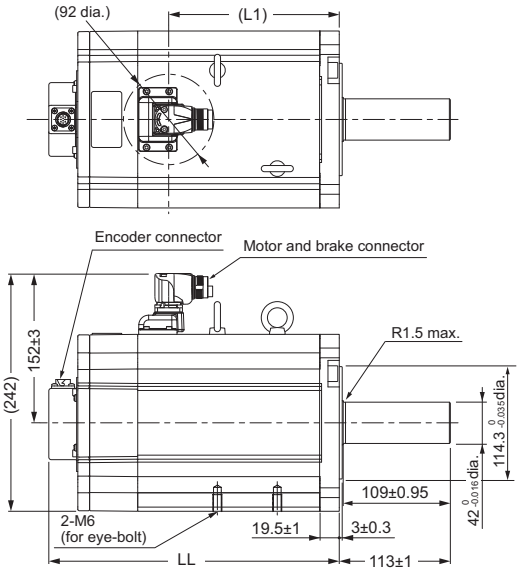
Model	Dimensions [mm]	
	LL	L1
R88M-1M5K515C(-O/-S2/-OS2)	248±3	174
R88M-1M7K515C(-O/-S2/-OS2)	295±3	221

Model	Dimensions [mm]						
	QA	QK	W	T	U	QE	LT
R88M-1M5K515C (-S2/-OS2)	3	90	$12^{0}_{-0.043}$	8	$3^{0}_{-0.4}$	M16	32
R88M-1M7K515C (-S2/-OS2)	3	90	$12^{0}_{-0.043}$	8	$3^{0}_{-0.4}$	M16	32

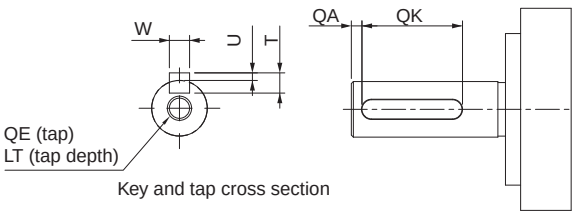
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

5.5 kW/7.5 kW (with Brake)

R88M-1M5K515C-B(O/S2/OS2)
R88M-1M7K515C-B(O/S2/OS2)



Shaft-end with key and tap



Model	Dimensions [mm]	
	LL	L1
R88M-1M5K515C-B(O/S2/OS2)	295±3	174
R88M-1M7K515C-B(O/S2/OS2)	352±3	221

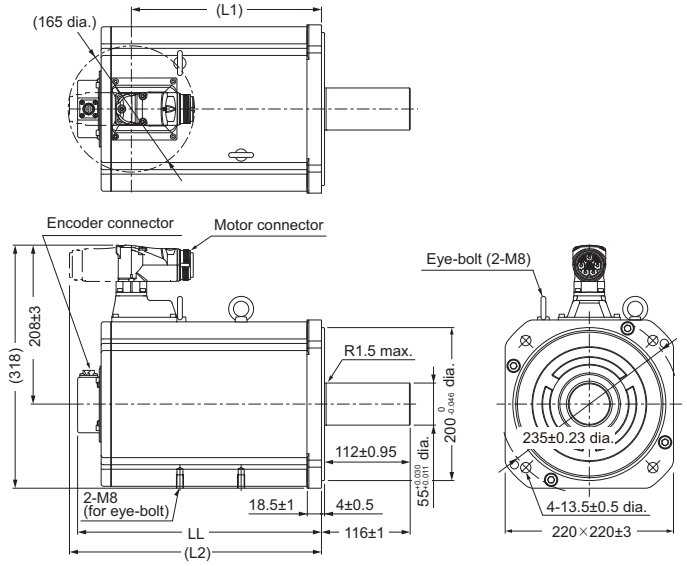
Model	Dimensions [mm]						
	QA	QK	W	T	U	QE	LT
R88M-1M5K515C-B (S2/OS2)	3	90	$12^{0}_{-0.043}$	8	$3^{0}_{-0.4}$	M16	32
R88M-1M7K515C-B (S2/OS2)	3	90	$12^{0}_{-0.043}$	8	$3^{0}_{-0.4}$	M16	32

Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

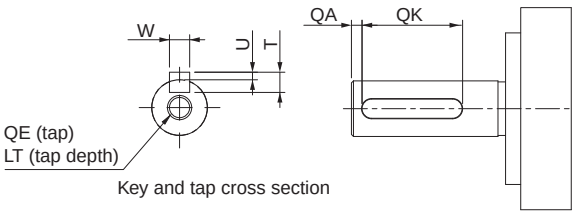
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11 kW/15 kW (without Brake)

R88M-1M11K015C(-O/-S2/-OS2)
R88M-1M15K015C(-O/-S2/-OS2)



Shaft-end with key and tap



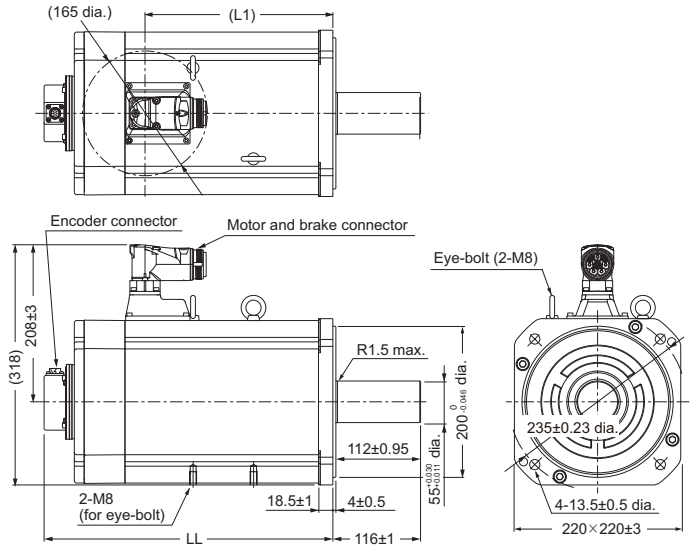
Model	Dimensions [mm]		
	LL	L1	L2
R88M-1M11K015C(-O/-S2/-OS2)	319±3	249	330
R88M-1M15K015C(-O/-S2/-OS2)	397±3	327	408

Model	Dimensions [mm]						
	QA	QK	W	T	U	QE	LT
R88M-1M11K015C(-S2/-OS2)	3	93	$16^{0}_{-0.043}$	10	$4^{0}_{-0.4}$	M20	40
R88M-1M15K015C(-S2/-OS2)	3	93	$16^{0}_{-0.043}$	10	$4^{0}_{-0.4}$	M20	40

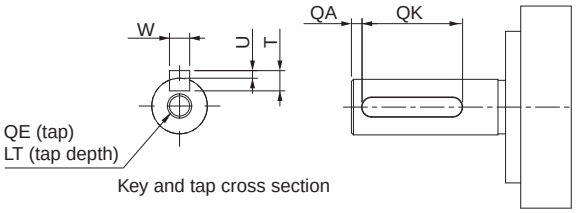
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

11 kW/15 kW (with Brake)

R88M-1M11K015C-B(O/S2/OS2)
R88M-1M15K015C-B(O/S2/OS2)



Shaft-end with key and tap



Model	Dimensions [mm]	
	LL	L1
R88M-1M11K015C-B(O/S2/OS2)	382±3	249
R88M-1M15K015C-B(O/S2/OS2)	493±3	327

Model	Dimensions [mm]						
	QA	QK	W	T	U	QE	LT
R88M-1M11K015C-B(S2/OS2)	3	93	$16^{0}_{-0.043}$	10	$4^{0}_{-0.4}$	M20	40
R88M-1M15K015C-B(S2/OS2)	3	93	$16^{0}_{-0.043}$	10	$4^{0}_{-0.4}$	M20	40

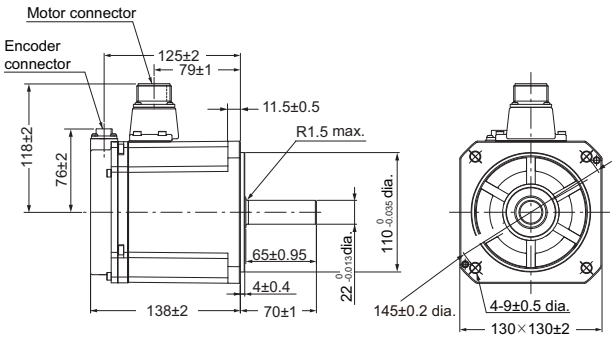
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

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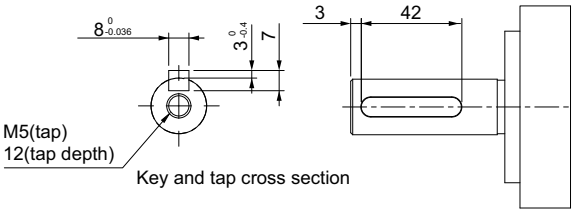
1,000-r/min Servomotors (200 V)

900 W (without Brake)

R88M-1M90010T(-O/-S2/-OS2)



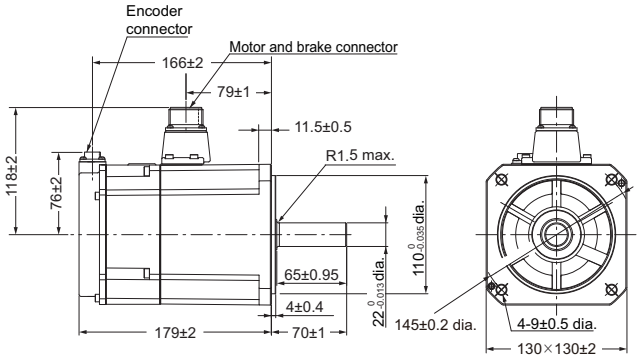
Shaft-end with key and tap



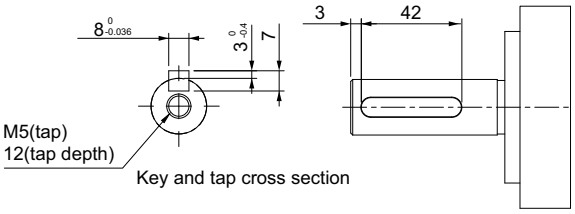
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

900 W (with Brake)

R88M-1M90010T-B(O/S2/OS2)



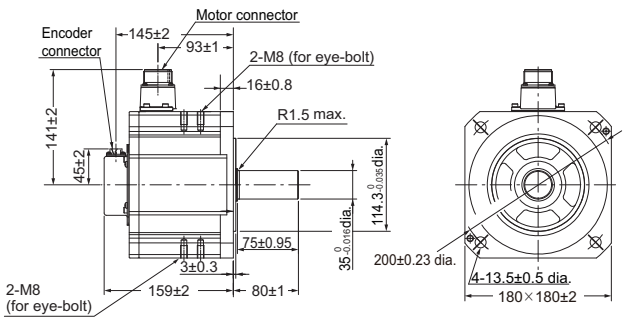
Shaft-end with key and tap



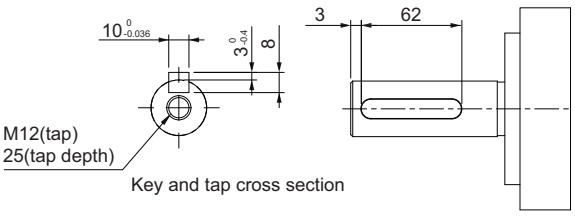
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

2 kW (without Brake)

R88M-1M2K010T(-O/-S2/-OS2)



Shaft-end with key and tap

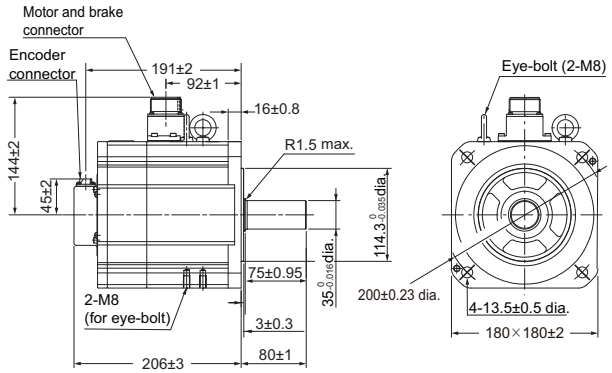


Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

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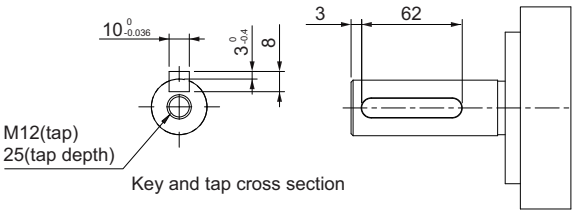
2 kW (with Brake)

R88M-1M2K010T-B(O/S2/OS2)



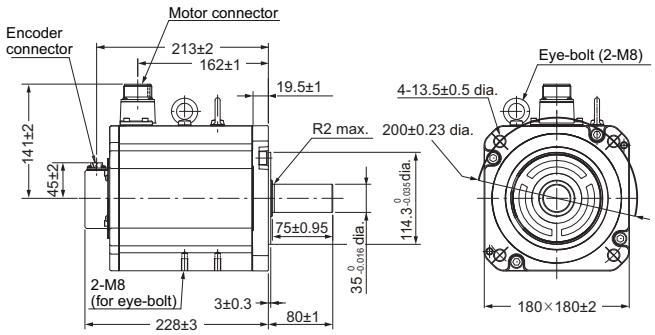
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

Shaft-end with key and tap



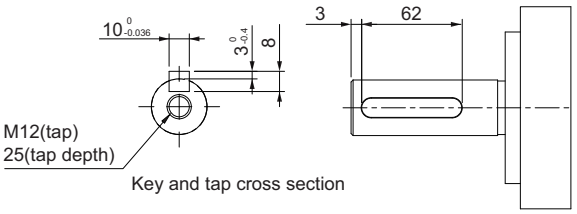
3 kW (without Brake)

R88M-1M3K010T(-O/-S2/-OS2)



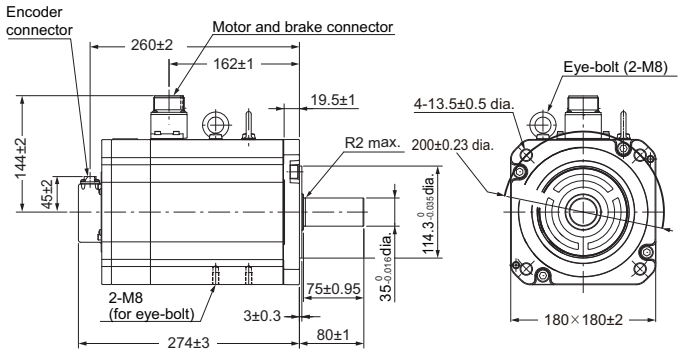
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

Shaft-end with key and tap



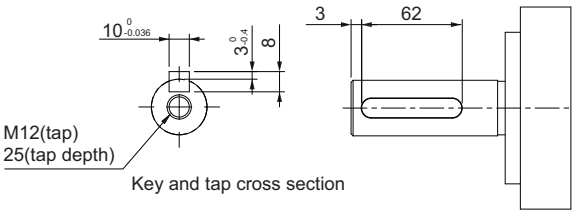
3 kW (with Brake)

R88M-1M3K010T-B(O/S2/OS2)



Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

Shaft-end with key and tap

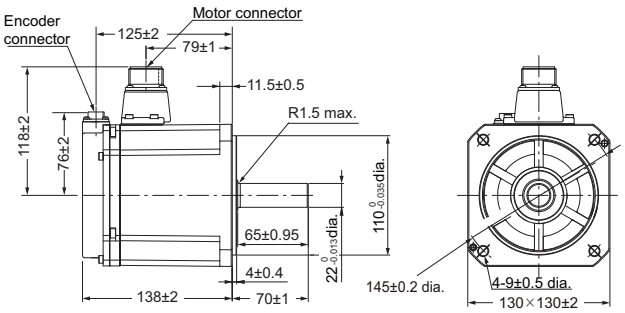


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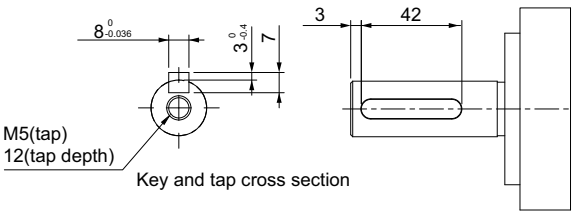
1,000-r/min Servomotors (400 V)

900 W (without Brake)

R88M-1M90010C(-O/-S2/-OS2)



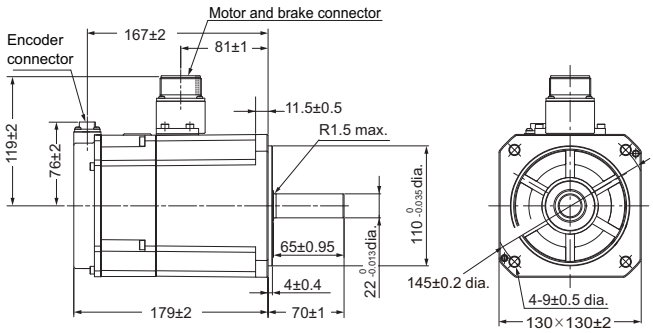
Shaft-end with key and tap



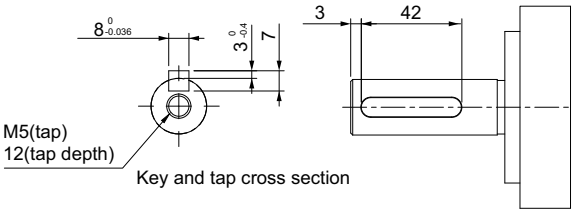
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

900 W (with Brake)

R88M-1M90010C-B(O/S2/OS2)



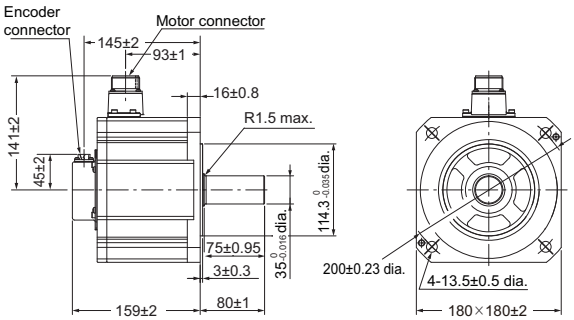
Shaft-end with key and tap



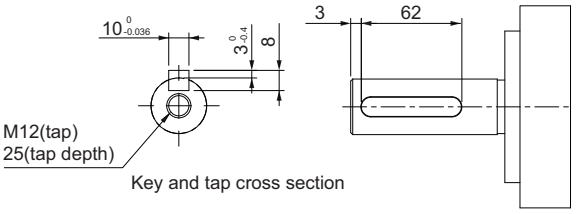
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

2 kW (without Brake)

R88M-1M2K010C(-O/-S2/-OS2)



Shaft-end with key and tap

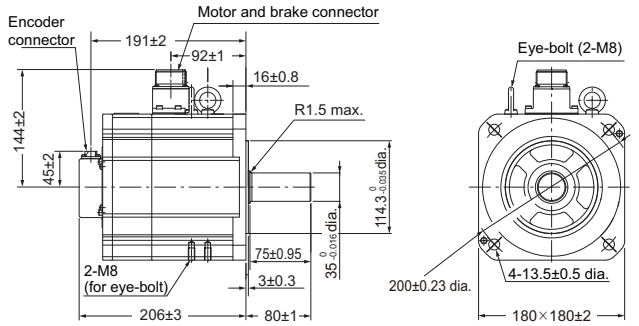


Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

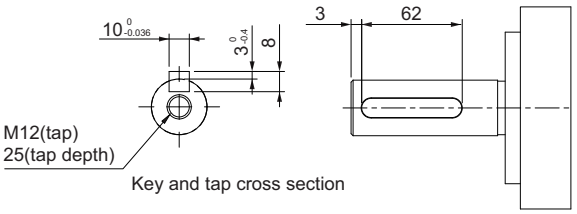
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2 kW (with Brake)

R88M-1M2K010C-B(O/S2/OS2)



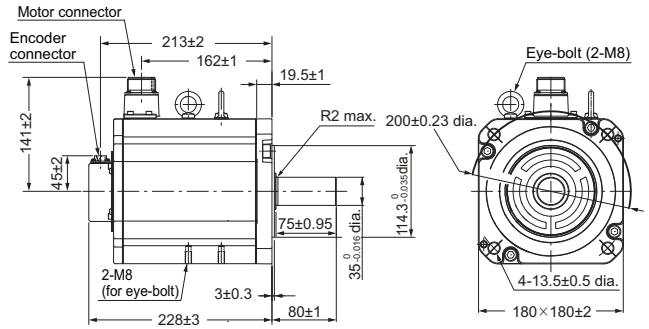
Shaft-end with key and tap



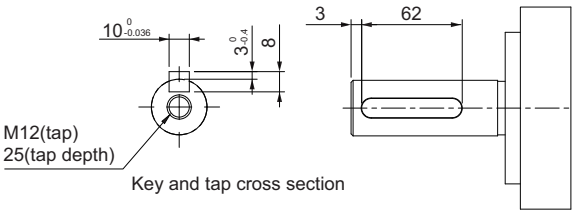
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

3 kW (without Brake)

R88M-1M3K010C(-O/-S2/-OS2)



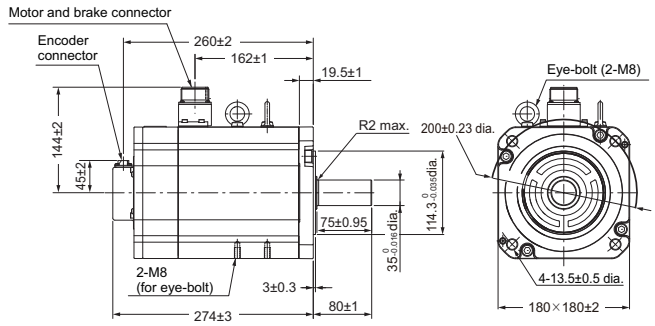
Shaft-end with key and tap



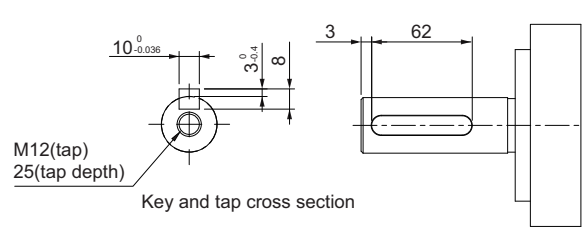
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

3 kW (with Brake)

R88M-1M3K010C-B(O/S2/OS2)



Shaft-end with key and tap



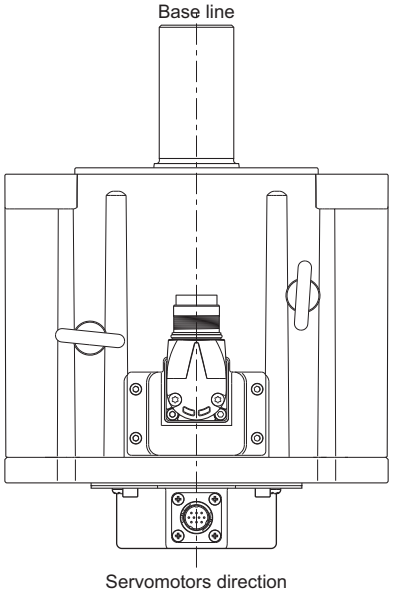
Note: The standard shaft type is a straight shaft. Models with a key and tap are indicated with “S2” at the end of the model number. Models with an oil seal are indicated with “O” at the end of the model number.

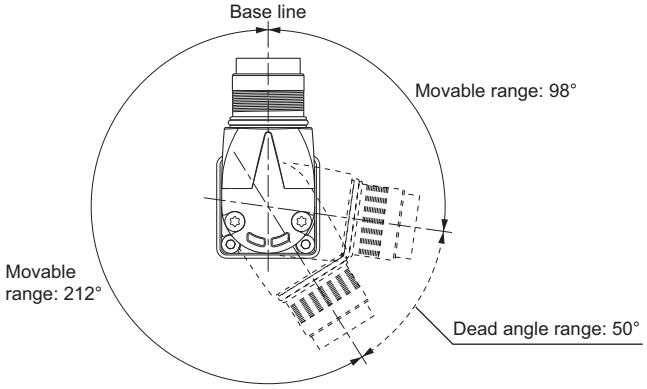
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Cable Outlet Direction of Connector

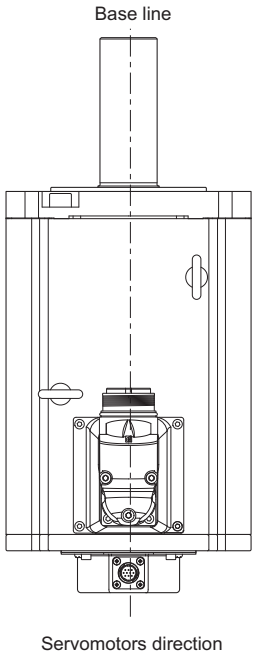
The cable outlet direction of the servomotor for connector type M23 or M40 can be selected. The below shows the selectable range.
The change of the cable outlet direction shall be up to five times. For a procedure of the change of the cable outlet direction, refer to the *AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications User's Manual* (Cat.No.I586).

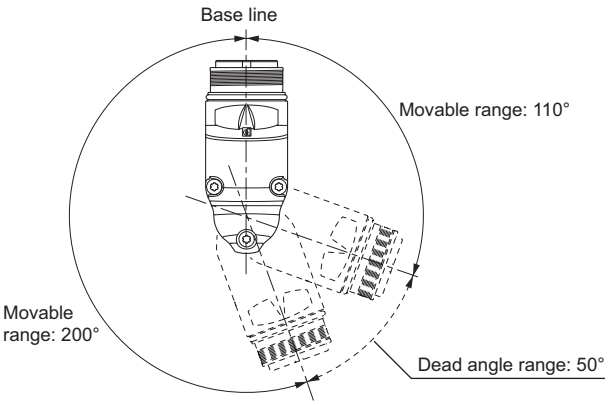
Cable Outlet Direction of Connector Type M23





Cable Outlet Direction of Connector Type M40



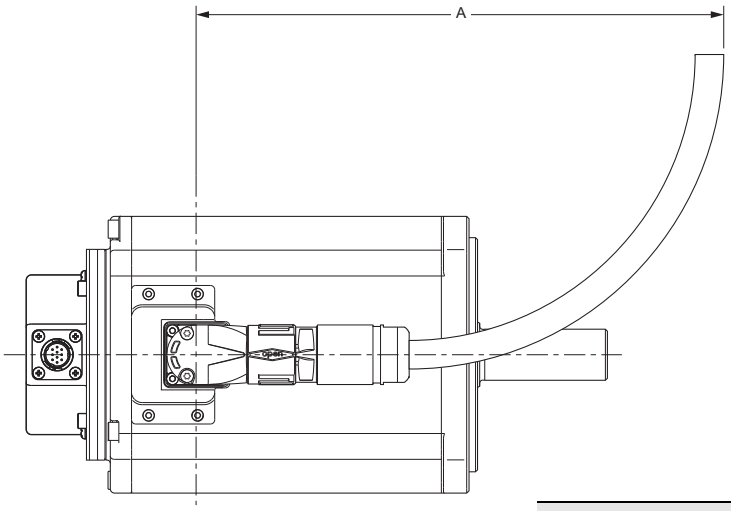


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Cable Wiring Dimension for a Case of Servo Motor Installing

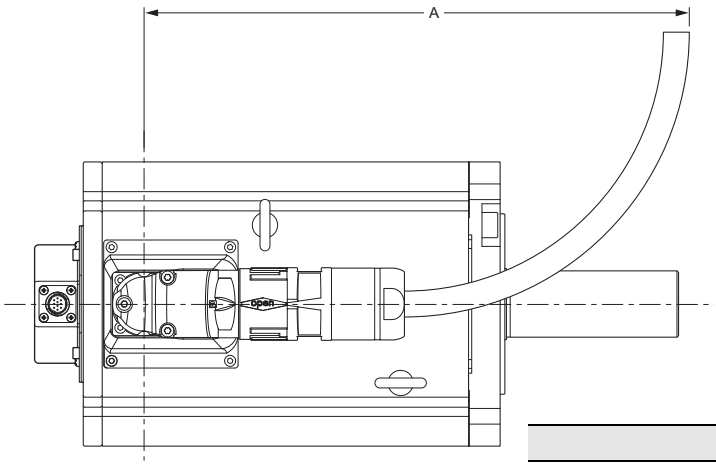
Cable wiring dimensions are shown below the table when you install a Servomotor with connector type M23 or connector type M40.
The dimensions from the rotation center of the connector to the cable surrounding are indicated as A.

Servo Motor for Connector Type M23



Model	A (mm)
R88M-1L4K030T(-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	265
R88M-1L4K030C(-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	
R88M-1L4K730T(-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	
R88M-1L5K030C(-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	
R88M-1M4K015T(-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	
R88M-1M4K015C(-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	
R88M-1M5K015T(-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	
R88M-1M5K515C(-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	
R88M-1M7K515C(-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	

Servo Motor for Connector Type M40



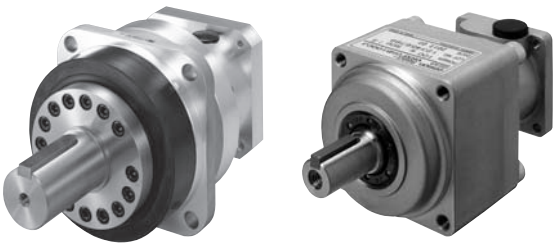
Model	A (mm)
R88M-1M7K515T (-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	421
R88M-1M11K015T (-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	421
R88M-1M11K015C (-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	356
R88M-1M15K015T (-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	421
R88M-1M15K015C (-S2/-O/-OS2/-B/-BS2/-BO/-BOS2)	356

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R88G-HPG/VRXF

Contents

- Ordering Information
- Specifications
- External Dimensions



Ordering Information

Refer to the Ordering Information.

Specifications

Backlash: 3 Arcminutes Max.

● For 3,000-r/min Servomotors

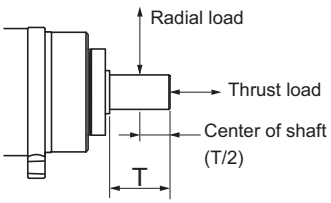
Servomotor rated output	Reduction ratio	Model	Rated rotation speed	Rated torque	Efficiency	Momentary maximum rotation speed	Momentary maximum torque	Decelerator inertia	Allowable radial load	Allowable thrust load	Weight
			r/min	N·m	%	r/min	N·m	× 10^{-4} kg·m^2	N	N	kg
50 W (100 V)	1/21	R88G-HPG14A21100B☐	142	2.1	62.6	285	8.4	0.05	340	1358	1.0
	1/33	R88G-HPG14A33050B☐	90	3.6	68.4	181	13.4	0.044	389	1555	1.0
	1/45	R88G-HPG14A45050B☐	66	4.9	68.4	133	18.3	0.044	427	1707	1.0
50 W (200 V)	1/21	R88G-HPG14A21100B☐	142	2.1	62.6	285	9.9	0.05	340	1358	1.0
	1/33	R88G-HPG14A33050B☐	90	3.6	68.4	181	15.9	0.044	389	1555	1.0
	1/45	R88G-HPG14A45050B☐	66	4.9	68.4	133	21.7	0.044	427	1707	1.0
100 W (100 V)	1/5	R88G-HPG11B05100B☐	600	1.2	77.0	1200	4.2	0.005	135	538	0.3
	1/11	R88G-HPG14A11100B☐	272	2.5	72.1	545	9.0	0.06	280	1119	1.0
	1/21	R88G-HPG14A21100B☐	142	5.2	77.8	285	17.5	0.05	340	1358	1.0
	1/33	R88G-HPG20A33100B☐	90	6.8	65.2	181	26.9	0.065	916	3226	2.4
	1/45	R88G-HPG20A45100B☐	66	9.8	68.2	133	37.1	0.063	1006	3541	2.4
100 W (200 V)	1/5	R88G-HPG11B05100B☐	600	1.2	77.0	1200	4.9	0.005	135	538	0.3
	1/11	R88G-HPG14A11100B☐	272	2.5	72.1	545	10.6	0.06	280	1119	1.0
	1/21	R88G-HPG14A21100B☐	142	5.2	77.8	285	20.7	0.05	340	1358	1.0
	1/33	R88G-HPG20A33100B☐	90	6.8	65.2	181	31.9	0.065	916	3226	2.4
	1/45	R88G-HPG20A45100B☐	66	9.8	68.2	133	44.0	0.063	1006	3541	2.4
200 W (100 V)	1/5	R88G-HPG14A05200B☐	600	2.4	75.4	1200	8.3	0.207	221	883	1.0
	1/11	R88G-HPG14A11200B☐	272	5.8	82.6	545	18.8	0.197	280	1119	1.1
	1/21	R88G-HPG20A21200B☐	142	10.2	76.2	285	35.9	0.49	800	2817	2.9
	1/33	R88G-HPG20A33200B☐	90	17.0	80.6	181	57.3	0.45	916	3226	2.9
	1/45	R88G-HPG20A45200B☐	66	23.5	82.1	133	78.5	0.45	1006	3541	2.9
200 W (200 V)	1/5	R88G-HPG14A05200B☐	600	2.4	75.4	1200	9.7	0.207	221	883	1.0
	1/11	R88G-HPG14A11200B☐	272	5.8	82.6	545	21.8	0.197	280	1119	1.1
	1/21	R88G-HPG20A21200B☐	142	10.2	76.2	285	41.7	0.49	800	2817	2.9
	1/33	R88G-HPG20A33200B☐	90	17.0	80.6	181	66.5	0.45	916	3226	2.9
	1/45	R88G-HPG20A45200B☐	66	23.5	82.1	133	91.1	0.45	1006	3541	2.9
400 W (100 V)	1/5	R88G-HPG14A05400B☐	600	5.3	84.2	1200	17.1	0.207	221	883	1.1
	1/11	R88G-HPG20A11400B☐	272	11.4	81.6	545	38.1	0.57	659	2320	2.9
	1/21	R88G-HPG20A21400B☐	142	23.0	86.1	285	74.0	0.49	800	2817	2.9
	1/33	R88G-HPG32A33400B☐	90	33.8	80.7	181	114.0	0.62	1565	6240	7.5
	1/45	R88G-HPG32A45400B☐	66	46.6	81.5	133	155.9	0.61	1718	6848	7.5

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Servomotor rated output	Reduction ratio	Model	Rated rotation speed	Rated torque	Efficiency	Momentary maximum rotation speed	Momentary maximum torque	Decelerator inertia	Allowable radial load	Allowable thrust load	Weight
			r/min	N·m	%	r/min	N·m	× 10^{-4} kg·m^2	N	N	kg
400 W (200 V)	1/5	R88G-HPG14A05400B☐	600	5.3	84.2	1200	20.4	0.207	221	883	1.1
	1/11	R88G-HPG20A11400B☐	272	11.4	81.6	545	45.5	0.57	659	2320	2.9
	1/21	R88G-HPG20A21400B☐	142	23.0	86.1	285	88.1	0.49	800	2817	2.9
	1/33	R88G-HPG32A33400B☐	90	33.8	80.7	181	136.2	0.62	1565	6240	7.5
	1/45	R88G-HPG32A45400B☐	66	46.6	81.5	133	186.1	0.61	1718	6848	7.5
750 W (200 V)	1/5	R88G-HPG20A05750B☐	600	9.9	82.9	1200	38.7	0.68	520	1832	2.9
	1/11	R88G-HPG20A11750B☐	272	20.0 ✻1	87.2	545	86.7	0.6	659	2320	3.1
	1/21	R88G-HPG32A21750B☐	142	42.1	84.0	285	163.3	3.0	1367	5448	7.8
	1/33	R88G-HPG32A33750B☐	90	69.3	87.9	181	259.7	2.7	1565	6240	7.8
	1/45	R88G-HPG32A45750B☐	66	94.9	88.3	133	299.0 ✻2	2.7	1718	6848	7.8
750 W (400 V)	1/5	R88G-HPG32A052K0B☐	600	7.7	64.3	1000	30.6	3.8	889	3542	7.4
	1/11	R88G-HPG32A112K0B☐	272	20.5	78.0	454	70.9	3.4	1126	4488	7.9
	1/21	R88G-HPG32A211K5B☐	142	42.1	84.0	238	138.3	3.0	1367	5448	7.9
	1/33	R88G-HPG32A33600SB☐	90	69.3	87.9	151	220.4	2.7	1565	6240	7.9
	1/45	R88G-HPG50A451K5B☐	66	92.0	85.5	111	298.0	4.7	4538	15694	19.0
1 kW	1/5	R88G-HPG32A052K0B☐	600	11.5	72.2	1000	42.0	3.8	889	3542	7.4
	1/11	R88G-HPG32A112K0B☐	272	28.9	82.5	454	96.1	3.4	1126	4488	7.9
	1/21	R88G-HPG32A211K5B☐	142	58.1	86.9	238	186.5	3.0	1367	5448	7.9
	1/33	R88G-HPG50A332K0B☐	90	90.9	86.7	151	292.7	4.8	4135	14300	19.0
	1/45	R88G-HPG50A451K5B☐	66	126.1	88.1	111	401.3	4.7	4538	15694	19.0
1.5 kW	1/5	R88G-HPG32A052K0B☐	600	19.1	80.1	1000	64.8	3.8	889	3542	7.4
	1/11	R88G-HPG32A112K0B☐	272	45.7	87.0	454	146.3	3.4	1126	4488	7.9
	1/21	R88G-HPG32A211K5B☐	142	90.1	90.0	238	282.2	3.0	1367	5448	7.9
	1/33	R88G-HPG50A332K0B☐	90	141.3	89.8	151	443.2	4.8	4135	14300	19.0
	1/45	R88G-HPG50A451K5B☐	66	194.8	90.8	111	606.5	4.7	4538	15694	19.0
2 kW	1/5	R88G-HPG32A052K0B☐	600	26.8	84.1	1000	87.9	3.8	889	3542	7.4
	1/11	R88G-HPG32A112K0B☐	272	62.5	89.3	454	197.0	3.4	1126	4488	7.9
	1/21	R88G-HPG50A212K0B☐	142	119.0	89.0	238	375.7	5.8	3611	12486	19.0
	1/33	R88G-HPG50A332K0B☐	90	192.0	91.3	151	595.3	4.8	4135	14300	19.0
3 kW	1/5	R88G-HPG32A053K0B☐	600	42.0	88.1	1000	134.0	3.8	889	3542	7.3
	1/11	R88G-HPG50A113K0B☐	272	93.9	89.3	454	296.1	7.7	2974	10285	19.0
	1/21	R88G-HPG50A213K0B☐	142	183.1	91.3	238	569.2	5.8	3611	12486	19.0
4 kW	1/5	R88G-HPG32A054K0B☐	600	57.2	90.0	1000	179.6	3.8	889	3542	7.9
	1/11	R88G-HPG50A115K0B☐	272	127.1	91.0	454	396.4	8.8	2974	10285	19.1
4.7 kW	1/5	R88G-HPG50A055K0B☐	600	65.6	87.4	1000	222.5	12.0	2347	8118	18.6
	1/11	R88G-HPG50A115K0B☐	272	151.4	91.8	454	496.7	8.8	2974	10285	19.1
5 kW	1/5	R88G-HPG50A055K0B☐	600	69.9	87.9	1000	222.5	12.0	2347	8118	18.6
	1/11	R88G-HPG50A115K0B☐	272	160.9	92.0	454	496.7	8.8	2974	10285	19.1

✻1. The value is the allowable continuous output torque of the Decelerator. Take care so that this value is not exceeded.
✻2. The value is the maximum allowable torque of the Decelerator. Take care so that this value is not exceeded.

Note: 1. The Decelerator inertia is the Servomotor shaft conversion value.
2. The protective structure rating of the Servomotor with the Decelerator is IP44.
3. The Allowable radial load column shows the values obtained at the center of the shaft (T/2).



4. The standard shaft type is a straight shaft. A model with a key and tap is indicated with “J” at ☐ of the model number.
5. Take care so that the surface temperature of the Decelerator does not exceed 70°C.

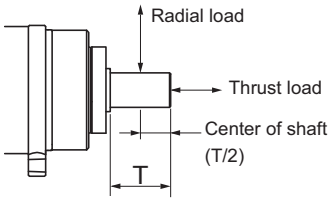
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● For 2,000-r/min Servomotors

Servomotor rated output	Reduction ratio	Model	Rated rotation speed	Rated torque	Efficiency	Momentary maximum rotation speed	Momentary maximum torque	Decelerator inertia	Allowable radial load	Allowable thrust load	Weight
			r/min	N·m	%	r/min	N·m	× 10^{-4} kg·m^2	N	N	kg
400 W	1/5	R88G-HPG32A052K0B☐	400	6.5	68.4	600	24.9	3.8	889	3542	7.4
	1/11	R88G-HPG32A112K0B☐	181	16.8	79.9	272	57.1	3.4	1126	4488	7.9
	1/21	R88G-HPG32A211K5B☐	95	34.0	84.9	142	111.1	3.0	1367	5448	7.9
	1/33	R88G-HPG32A33600SB☐	60	55.6	88.2	90	176.6	2.7	1565	6240	7.9
	1/45	R88G-HPG32A45400SB☐	44	76.0	88.5	66	241.1	2.7	1718	6848	7.9
600 W	1/5	R88G-HPG32A052K0B☐	400	11.1	77.6	600	38.6	3.8	889	3542	7.4
	1/11	R88G-HPG32A112K0B☐	181	26.8	85.3	272	87.3	3.4	1126	4488	7.9
	1/21	R88G-HPG32A211K5B☐	95	53.2	88.6	142	168.7	3.0	1367	5448	7.9
	1/33	R88G-HPG32A33600SB☐	60	85.7	90.8	90	267.2	2.7	1565	6240	7.9
	1/45	R88G-HPG50A451K5B☐	44	115.1	89.4	66	362.6	4.7	4538	15694	19.0
1 kW	1/5	R88G-HPG32A053K0B☐	400	20.3	85.0	600	66.0	3.8	889	3542	7.3
	1/11	R88G-HPG32A112K0SB☐	181	47.0	89.6	272	147.6	3.4	1126	4488	7.8
	1/21	R88G-HPG32A211K0SB☐	95	91.7	91.5	142	283.8	2.9	1367	5448	7.8
	1/33	R88G-HPG50A332K0SB☐	60	143.9	91.4	90	445.8	4.7	4135	14300	19.0
	1/45	R88G-HPG50A451K0SB☐	44	197.6	92.1	66	609.3	4.7	4538	15694	19.0
1.5 kW	1/5	R88G-HPG32A053K0B☐	400	31.7	88.7	600	100.6	3.8	889	3542	7.3
	1/11	R88G-HPG32A112K0SB☐	181	72.2	91.7	272	223.7	3.4	1126	4488	7.8
	1/21	R88G-HPG50A213K0B☐	95	137.6	91.5	142	426.7	5.8	3611	12486	19.0
	1/33	R88G-HPG50A332K0SB☐	60	219.6	92.9	90	673.9	4.7	4135	14300	19.0
2 kW	1/5	R88G-HPG32A053K0B☐	400	43.2	90.5	600	135.1	3.8	889	3542	7.3
	1/11	R88G-HPG32A112K0SB☐	181	97.5	92.8	272	299.7	3.4	1126	4488	7.8
	1/21	R88G-HPG50A213K0B☐	95	185.8	92.7	142	571.9	5.8	3611	12486	19.0
	1/33	R88G-HPG50A332K0SB☐	60	270.0 ✻1	93.5	90	849.0 ✻2	4.7	4135	14300	19.0
3 kW	1/5	R88G-HPG32A054K0B☐	400	66.0	92.3	600	203.8	3.8	889	3542	7.9
	1/11	R88G-HPG50A115K0B☐	181	146.1	92.9	272	449.2	8.8	2974	10285	19.1
	1/21	R88G-HPG50A213K0SB☐	95	260.0 ✻1	93.6	142	849.0 ✻2	6.9	3611	12486	19.1
	1/25	R88G-HPG65A253K0SB☐	80	322.9	90.3	120	1011.7	14	7846	28654	52.0

✻**1.** The value is the allowable continuous output torque of the Decelerator. Take care so that this value is not exceeded.
✻**2.** The value is the maximum allowable torque of the Decelerator. Take care so that this value is not exceeded.

Note: 1. The Decelerator inertia is the Servomotor shaft conversion value.
2. The protective structure rating of the Servomotor with the Decelerator is IP44.
3. The Allowable radial load column shows the values obtained at the center of the shaft (T/2).



4. The standard shaft type is a straight shaft. A model with a key and tap is indicated with “J” at ☐ of the model number.
5. Take care so that the surface temperature of the Decelerator does not exceed 70°C.

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● For 1,500-r/min Servomotors

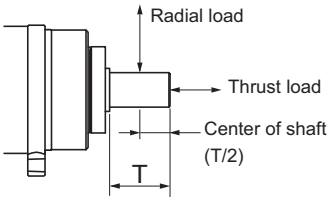
Servomotor rated output	Reduction ratio	Model	Rated rotation speed	Rated torque	Efficiency	Momentary maximum rotation speed	Momentary maximum torque	Decelerator inertia	Allowable radial load	Allowable thrust load	Weight
			r/min	N·m	%	r/min	N·m	× 10^{-4} kg·m^2	N	N	kg
4 kW	1/5	R88G-HPG50A055K0SB☐	300	119.0	93.4	600	356.6	11	2347	8118	22.0
	1/11	R88G-HPG50A115K0SB☐	136	217.9 ✻	94.3	272	788.2	8.4	2974	10285	23.5
	1/20	R88G-HPG65A205K0SB☐	75	474.9	93.1	150	1425.3	14	7338	26799	55.4
	1/25	R88G-HPG65A255K0SB☐	60	596.0	93.5	120	1784.0	14	7846	28654	55.4
5 kW	1/5	R88G-HPG50A054K5TB☐	300	149.3	93.9	600	452.6	12	2347	8118	22.0
	1/12	R88G-HPG65A127K5SB☐	125	354.1	92.8	250	1082.2	66	6295	22991	52.0
	1/20	R88G-HPG65A204K5TB☐	75	595.9	93.7	150	1809.3	53	7338	26799	52.0
5.5 kW	1/5	R88G-HPG50A054K5TB☐	300	164.6	94.1	600	452.6	12	2347	8118	22.0
	1/12	R88G-HPG65A127K5SB☐	125	391.0	93.1	250	1082.2	66	6295	22991	52.0
	1/20	R88G-HPG65A204K5TB☐	75	657.3	93.9	150	1809.3	53	7338	26799	52.0

✻ The value is the allowable continuous output torque of the Decelerator. Take care so that this value is not exceeded.

Note: 1. The Decelerator inertia is the Servomotor shaft conversion value.

2. The protective structure rating of the Servomotor with the Decelerator is IP44.

3. The Allowable radial load column shows the values obtained at the center of the shaft (T/2).



4. The standard shaft type is a straight shaft. A model with a key and tap is indicated with "J" at ☐ of the model number.

5. Take care so that the surface temperature of the Decelerator does not exceed 70°C.

● For 1,000-r/min Servomotors

Servomotor rated output	Reduction ratio	Model	Rated rotation speed	Rated torque	Efficiency	Momentary maximum rotation speed	Momentary maximum torque	Decelerator inertia	Allowable radial load	Allowable thrust load	Weight
			r/min	N·m	%	r/min	N·m	× 10^{-4} kg·m^2	N	N	kg
900 W	1/5	R88G-HPG32A05900TB☐	200	39.8	92.6	400	91.2	3.8	889	3542	7.9
	1/11	R88G-HPG32A11900TB☐	90	88.7	93.9	181	201.8	3.4	1126	4488	8.4
	1/21	R88G-HPG50A21900TB☐	47	169.2	93.8	95	385.1	7.0	3611	12486	19.1
	1/33	R88G-HPG50A33900TB☐	30	267.5	94.4	60	606.8	5.9	4135	14300	19.1
2 kW	1/5	R88G-HPG32A052K0TB☐	200	90.2	94.5	400	227.5	5.2	889	3542	8.90
	1/11	R88G-HPG50A112K0TB☐	90	198.9	94.7	181	500.9	8.4	2974	10285	20.1
	1/21	R88G-HPG50A212K0TB☐	47	320.1 ✻1	94.8	95	849.0 ✻2	6.5	3611	12486	20.1
	1/25	R88G-HPG65A255K0SB☐	40	446.7	93.6	80	1133.1	14	7846	28654	55.4
3 kW	1/5	R88G-HPG50A055K0SB☐	200	135.4	94.4	400	341.8	11	2347	8118	22.0
	1/11	R88G-HPG50A115K0SB☐	90	246.2 ✻1	94.9	181	754.4	8.4	2974	10285	23.5
	1/20	R88G-HPG65A205K0SB☐	50	540.4	94.2	100	1366.0	14	7338	26799	55.4
	1/25	R88G-HPG65A255K0SB☐	40	677.1	94.4	80	1709.1	14	7846	28654	55.4

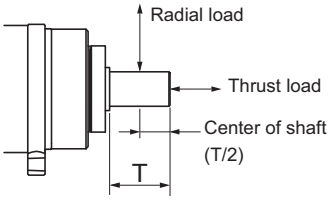
✻**1.** The value is the allowable continuous output torque of the Decelerator. Take care so that this value is not exceeded.

✻**2.** The value is the maximum allowable torque of the Decelerator. Take care so that this value is not exceeded.

Note: 1. The Decelerator inertia is the Servomotor shaft conversion value.

2. The protective structure rating of the Servomotor with the Decelerator is IP44.

3. The Allowable radial load column shows the values obtained at the center of the shaft (T/2).



4. The standard shaft type is a straight shaft. A model with a key and tap is indicated with "J" at ☐ of the model number.

5. Take care so that the surface temperature of the Decelerator does not exceed 70°C.

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Backlash: 15 Arcminutes Max.

● For 3,000-r/min Servomotors

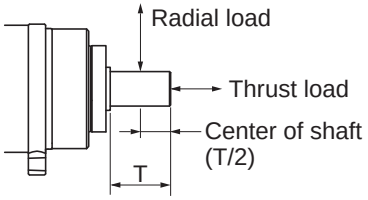
Servomotor rated output	Reduction ratio	Model	Rated rotation speed	Rated torque	Efficiency	Momentary maximum rotation speed	Momentary maximum torque	Decelerator inertia	Allowable radial load	Allowable thrust load	Weight
			r/min	N·m	%	r/min	N·m	× 10^{-4} kg·m^2	N	N	kg
50 W (100 V)	1/5	R88G-VRXF05B100CJ	600	0.65	82	1200	1.97	0.060	392	196	0.55
	1/9	R88G-VRXF09B100CJ	333	1.17	82	667	3.54	0.050	441	220	0.55
	1/15	R88G-VRXF15B100CJ	200	1.84	77	400	5.54	0.053	588	294	0.70
	1/25	R88G-VRXF25B100CJ	120	3.06	77	240	9.24	0.051	686	343	0.70
50 W (200 V)	1/5	R88G-VRXF05B100CJ	600	0.65	82	1200	2.30	0.060	392	196	0.55
	1/9	R88G-VRXF09B100CJ	333	1.17	82	667	4.13	0.050	441	220	0.55
	1/15	R88G-VRXF15B100CJ	200	1.84	77	400	6.47	0.053	588	294	0.70
	1/25	R88G-VRXF25B100CJ	120	3.06	77	240	10.78	0.051	686	343	0.70
100 W (100 V)	1/5	R88G-VRXF05B100CJ	600	1.43	90	1200	4.28	0.060	392	196	0.55
	1/9	R88G-VRXF09B100CJ	333	2.58	90	667	7.70	0.050	441	220	0.55
	1/15	R88G-VRXF15B100CJ	200	4.10	86	400	12.26	0.053	588	294	0.70
	1/25	R88G-VRXF25B100CJ	120	6.84	86	240	20.43	0.051	686	343	0.70
100 W (200 V)	1/5	R88G-VRXF05B100CJ	600	1.43	90	1200	5.00	0.060	392	196	0.55
	1/9	R88G-VRXF09B100CJ	333	2.58	90	667	8.23 ✻	0.050	441	220	0.55
	1/15	R88G-VRXF15B100CJ	200	4.10	86	400	14.10 ✻	0.053	588	294	0.70
	1/25	R88G-VRXF25B100CJ	120	6.84	86	240	21.90 ✻	0.051	686	343	0.70
200 W (100 V)	1/5	R88G-VRXF05B200CJ	600	2.93	92	1200	8.79	0.147	392	196	0.72
	1/9	R88G-VRXF09C200CJ	333	4.76	83	667	14.27	0.273	931	465	1.70
	1/15	R88G-VRXF15C200CJ	200	8.22	86	400	24.64	0.302	1176	588	2.10
	1/25	R88G-VRXF25C200CJ	120	13.70	86	240	41.07	0.293	1323	661	2.10
200 W (200 V)	1/5	R88G-VRXF05B200CJ	600	2.93	92	1200	9.94 ✻	0.147	392	196	0.72
	1/9	R88G-VRXF09C200CJ	333	4.76	83	667	16.43	0.273	931	465	1.70
	1/15	R88G-VRXF15C200CJ	200	8.22	86	400	28.38	0.302	1176	588	2.10
	1/25	R88G-VRXF25C200CJ	120	13.70	86	240	47.30	0.293	1323	661	2.10
400 W (100 V)	1/5	R88G-VRXF05C400CJ	600	5.59	88	1200	16.72	0.370	784	392	1.70
	1/9	R88G-VRXF09C400CJ	333	10.06	88	667	30.10	0.273	931	465	1.70
	1/15	R88G-VRXF15C400CJ	200	16.95	89	400	50.73	0.302	1176	588	2.10
	1/25	R88G-VRXF25C400CJ	120	28.26	89	240	84.55	0.293	1323	661	2.10
400 W (200 V)	1/5	R88G-VRXF05C400CJ	600	5.59	88	1200	19.80	0.370	784	392	1.70
	1/9	R88G-VRXF09C400CJ	333	10.06	88	667	34.00 ✻	0.273	931	465	1.70
	1/15	R88G-VRXF15C400CJ	200	16.95	89	400	56.70 ✻	0.302	1176	588	2.10
	1/25	R88G-VRXF25C400CJ	120	28.26	89	240	92.40 ✻	0.293	1323	661	2.10
750 W (200 V)	1/5	R88G-VRXF05C750CJ	600	10.99	92	1200	38.64	0.817	784	392	2.10
	1/9	R88G-VRXF09D750CJ	333	19.57	91	667	63.70 ✻	0.755	1176	588	3.40
	1/15	R88G-VRXF15D750CJ	200	31.91	89	400	106.00 ✻	0.685	1372	686	3.80
	1/25	R88G-VRXF25D750CJ	120	53.18	89	240	177.00 ✻	0.658	1617	808	3.80

✻ The value is the maximum allowable torque of the Decelerator. Take care so that this value is not exceeded.

Note: 1. The Decelerator inertia is the Servomotor shaft conversion value.

2. The protective structure rating of the Servomotor combined with the Decelerator is IP44. (Excluding decelerator and servo motor connecting parts.)

3. The Allowable radial load column shows the values obtained at the center of the shaft (T/2).



4. The standard shaft type is a shaft with key and tap. (The key is temporarily assembled to the shaft.)

5. Take care so that the surface temperature of the Decelerator does not exceed 90°C.

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External Dimensions

(Unit: mm)

Backlash: 3 Arcminutes Max.

● For 3,000-r/min Servomotors (50 to 200 W)

Servomotor rated output	Reduction ratio	Model	Outline drawing	Dimensions [mm]												
				LM	LR	C1	C2	D1	D2	D3	D4	D5	D6 ✻2	E	F1	F2
50 W	1/21	R88G-HPG14A21100B☐	1	64.0	58	60	60 × 60	70	46	56	55.5	40	---	37	2.5	21
	1/33	R88G-HPG14A33050B☐	1	64.0	58	60	60 × 60	70	46	56	55.5	40	---	37	2.5	21
	1/45	R88G-HPG14A45050B☐	1	64.0	58	60	60 × 60	70	46	56	55.5	40	---	37	2.5	21
100 W	1/5	R88G-HPG11B05100B☐	1 ✻1	39.5	42	40	40 × 40	46	46	40	39.5	29	---	27	2.2	15
	1/11	R88G-HPG14A11100B☐	1	64.0	58	60	60 × 60	70	46	56	55.5	40	---	37	2.5	21
	1/21	R88G-HPG14A21100B☐	1	64.0	58	60	60 × 60	70	46	56	55.5	40	---	37	2.5	21
	1/33	R88G-HPG20A33100B☐	2	66.5	80	90	55 dia.	105	46	85	84	59	89	53	7.5	27
	1/45	R88G-HPG20A45100B☐	2	66.5	80	90	55 dia.	105	46	85	84	59	89	53	7.5	27
200 W	1/5	R88G-HPG14A05200B☐	1	64.0	58	60	60 × 60	70	70	56	55.5	40	---	37	2.5	21
	1/11	R88G-HPG14A11200B☐	1	64.0	58	60	60 × 60	70	70	56	55.5	40	---	37	2.5	21
	1/21	R88G-HPG20A21200B☐	2	71.0	80	90	89 dia.	105	70	85	84	59	---	53	7.5	27
	1/33	R88G-HPG20A33200B☐	2	71.0	80	90	89 dia.	105	70	85	84	59	---	53	7.5	27
	1/45	R88G-HPG20A45200B☐	2	71.0	80	90	89 dia.	105	70	85	84	59	---	53	7.5	27

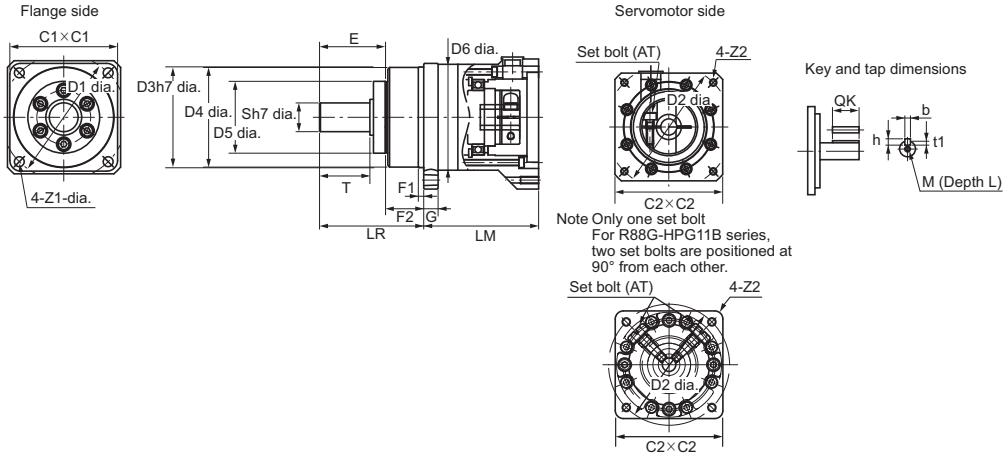
Servomotor rated output	Reduction ratio	Model	Dimensions [mm]											
			G	S	T	Z1	Z2	AT ✻3	Key				Tap	
									QK	b	h	t1	M	L
50 W	1/21	R88G-HPG14A21100B☐	8	16	28	5.5	M4 × 10	M3	25	5	5	3	M4	8
	1/33	R88G-HPG14A33050B☐	8	16	28	5.5	M4 × 10	M3	25	5	5	3	M4	8
	1/45	R88G-HPG14A45050B☐	8	16	28	5.5	M4 × 10	M3	25	5	5	3	M4	8
100 W	1/5	R88G-HPG11B05100B☐	5	8	20	3.4	M4 × 9	M3	15	3	3	1.8	M3	6
	1/11	R88G-HPG14A11100B☐	8	16	28	5.5	M4 × 10	M3	25	5	5	3	M4	8
	1/21	R88G-HPG14A21100B☐	8	16	28	5.5	M4 × 10	M3	25	5	5	3	M4	8
	1/33	R88G-HPG20A33100B☐	10	25	42	9	M4 × 10	M4	36	8	7	4	M6	12
	1/45	R88G-HPG20A45100B☐	10	25	42	9	M4 × 10	M4	36	8	7	4	M6	12
200 W	1/5	R88G-HPG14A05200B☐	8	16	28	5.5	M4 × 10	M4	25	5	5	3	M4	8
	1/11	R88G-HPG14A11200B☐	8	16	28	5.5	M4 × 10	M4	25	5	5	3	M4	8
	1/21	R88G-HPG20A21200B☐	10	25	42	9	M4 × 10	M4	36	8	7	4	M6	12
	1/33	R88G-HPG20A33200B☐	10	25	42	9	M4 × 10	M4	36	8	7	4	M6	12
	1/45	R88G-HPG20A45200B☐	10	25	42	9	M4 × 10	M4	36	8	7	4	M6	12

✻1. Two set bolts are positioned at 90° from each other.
✻2. D6 is the maximum diameter of the decelerator body between the flange side and Servomotor side. (See Outline Drawing) The value is given only when the diameter is larger than the diameters of these two sides. Take heed of this when you mount the decelerator to the machine.
✻3. Indicates set bolt.

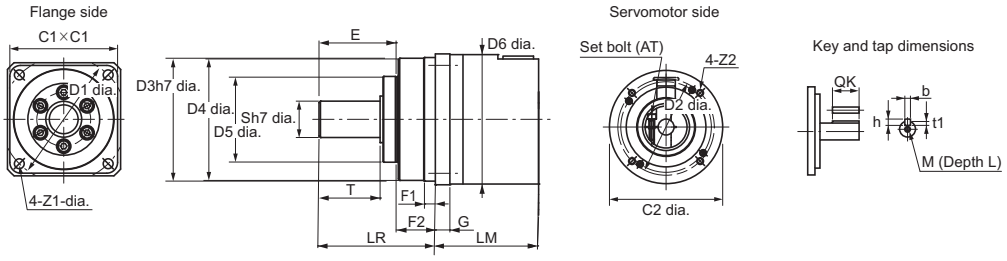
Note: 1. The standard shaft type is a straight shaft.
2. A model with a key and tap is indicated with "J" at ☐ of the model number.
(Example: R88G-HPG11B05100BJ)
3. The diameter of the motor shaft insertion hole is the same as the shaft diameter of the corresponding Servomotor.
4. You cannot use this type of Decelerator for the Servomotor with key.
5. The dimensional drawings in this document are for showing main dimensions only, and they do not give the details of the product shape.

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Outline Drawing 1



Outline Drawing 2



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● For 3,000-r/min Servomotors (400 to 750 W)

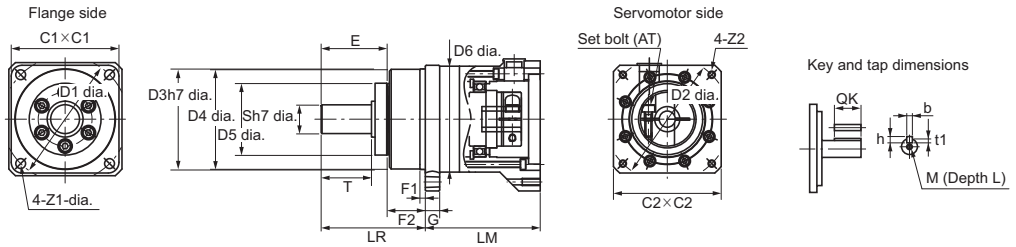
Servomotor rated output	Reduction ratio	Model	Outline drawing	Dimensions [mm]												
				LM	LR	C1	C2	D1	D2	D3	D4	D5	D6 ✻1	E	F1	F2
400 W	1/5	R88G-HPG14A05400B☐	1	64	58	60	60 × 60	70	70	56	55.5	40	---	37	2.5	21
	1/11	R88G-HPG20A11400B☐	2	71	80	90	89 dia.	105	70	85	84	59	---	53	7.5	27
	1/21	R88G-HPG20A21400B☐	2	71	80	90	89 dia.	105	70	85	84	59	---	53	7.5	27
	1/33	R88G-HPG32A33400B☐	2	104	133	120	122 dia.	135	70	115	114	84	---	98	12.5	35
	1/45	R88G-HPG32A45400B☐	2	104	133	120	122 dia.	135	70	115	114	84	---	98	12.5	35
750 W (200 V)	1/5	R88G-HPG20A05750B☐	1	78	80	90	80 × 80	105	90	85	84	59	89	53	7.5	27
	1/11	R88G-HPG20A11750B☐	1	78	80	90	80 × 80	105	90	85	84	59	89	53	7.5	27
	1/21	R88G-HPG32A21750B☐	2	104	133	120	122 dia.	135	90	115	114	84	---	98	12.5	35
	1/33	R88G-HPG32A33750B☐	2	104	133	120	122 dia.	135	90	115	114	84	---	98	12.5	35
	1/45	R88G-HPG32A45750B☐	2	104	133	120	122 dia.	135	90	115	114	84	---	98	12.5	35
750 W (400 V)	1/5	R88G-HPG32A052K0B☐	2	110	133	120	135 dia.	135	115	115	114	84	---	98	12.5	35
	1/11	R88G-HPG32A112K0B☐	2	110	133	120	135 dia.	135	115	115	114	84	---	98	12.5	35
	1/21	R88G-HPG32A211K5B☐	2	110	133	120	135 dia.	135	115	115	114	84	---	98	12.5	35
	1/33	R88G-HPG32A33600SB☐	2	110	133	120	135 dia.	135	115	115	114	84	---	98	12.5	35
	1/45	R88G-HPG50A451K5B☐	2	123	156	170	170 dia.	190	115	165	163	122	---	103	12	53

Servomotor rated output	Reduction ratio	Model	Dimensions [mm]											
			G	S	T	Z1	Z2	AT ✻2	Key				Tap	
									QK	b	h	t1	M	L
400 W	1/5	R88G-HPG14A05400B☐	8	16	28	5.5	M4 × 10	M4	25	5	5	3	M4	8
	1/11	R88G-HPG20A11400B☐	10	25	42	9	M4 × 10	M4	36	8	7	4	M6	12
	1/21	R88G-HPG20A21400B☐	10	25	42	9	M4 × 10	M4	36	8	7	4	M6	12
	1/33	R88G-HPG32A33400B☐	13	40	82	11	M4 × 10	M4	70	12	8	5	M10	20
	1/45	R88G-HPG32A45400B☐	13	40	82	11	M4 × 10	M4	70	12	8	5	M10	20
750 W (200 V)	1/5	R88G-HPG20A05750B☐	10	25	42	9	M5 × 12	M4	36	8	7	4	M6	12
	1/11	R88G-HPG20A11750B☐	10	25	42	9	M5 × 12	M4	36	8	7	4	M6	12
	1/21	R88G-HPG32A21750B☐	13	40	82	11	M5 × 12	M6	70	12	8	5	M10	20
	1/33	R88G-HPG32A33750B☐	13	40	82	11	M5 × 12	M6	70	12	8	5	M10	20
	1/45	R88G-HPG32A45750B☐	13	40	82	11	M5 × 12	M6	70	12	8	5	M10	20
750 W (400 V)	1/5	R88G-HPG32A052K0B☐	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/11	R88G-HPG32A112K0B☐	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/21	R88G-HPG32A211K5B☐	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/33	R88G-HPG32A33600SB☐	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/45	R88G-HPG50A451K5B☐	16	50	82	14	M8 × 10	M6	70	14	9	5.5	M10	20

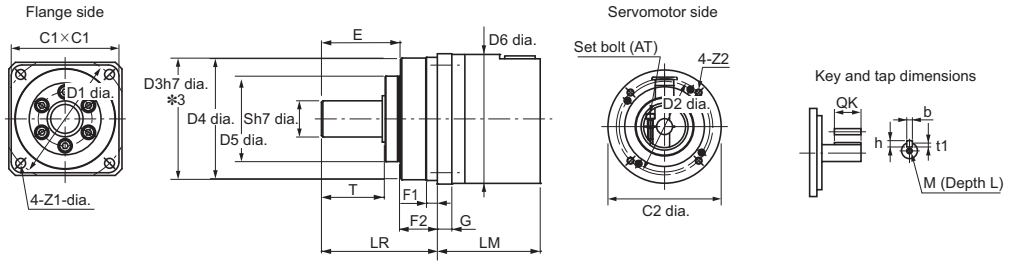
✻1. D6 is the maximum diameter of the decelerator body between the flange side and Servomotor side. (See Outline Drawing) The value is given only when the diameter is larger than the diameters of these two sides. Take heed of this when you mount the decelerator to the machine.
✻2. Indicates set bolt.

Note: 1. The standard shaft type is a straight shaft.
2. A model with a key and tap is indicated with "J" at ☐ of the model number.
(Example: R88G-HPG14A05400BJ)
3. The diameter of the motor shaft insertion hole is the same as the shaft diameter of the corresponding Servomotor.
4. You cannot use this type of Decelerator for the Servomotor with key.
5. The dimensional drawings in this document are for showing main dimensions only, and they do not give the details of the product shape.

Outline Drawing 1



Outline Drawing 2



✻3. The tolerance is "h8" for R88G-HPG50☐.

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● For 3,000-r/min Servomotors (1 to 5 kW)

Servomotor rated output	Reduction ratio	Model	Outline drawing	Dimensions [mm]												
				LM	LR	C1	C2	D1	D2	D3	D4	D5	D6※1	E	F1	F2
1 kW	1/5	R88G-HPG32A052K0B☐	2	110	133	120	135 dia.	135	115	115	114	84	---	98	12.5	35
	1/11	R88G-HPG32A112K0B☐	2	110	133	120	135 dia.	135	115	115	114	84	---	98	12.5	35
	1/21	R88G-HPG32A211K5B☐	2	110	133	120	135 dia.	135	115	115	114	84	---	98	12.5	35
	1/33	R88G-HPG50A332K0B☐	2	123	156	170	170 dia.	190	115	165	163	122	---	103	12	53
	1/45	R88G-HPG50A451K5B☐	2	123	156	170	170 dia.	190	115	165	163	122	---	103	12	53
1.5 kW	1/5	R88G-HPG32A052K0B☐	2	110	133	120	135 dia.	135	115	115	114	84	---	98	12.5	35
	1/11	R88G-HPG32A112K0B☐	2	110	133	120	135 dia.	135	115	115	114	84	---	98	12.5	35
	1/21	R88G-HPG32A211K5B☐	2	110	133	120	135 dia.	135	115	115	114	84	---	98	12.5	35
	1/33	R88G-HPG50A332K0B☐	2	123	156	170	170 dia.	190	115	165	163	122	---	103	12	53
	1/45	R88G-HPG50A451K5B☐	2	123	156	170	170 dia.	190	115	165	163	122	---	103	12	53
2 kW	1/5	R88G-HPG32A052K0B☐	2	110	133	120	135 dia.	135	115	115	114	84	---	98	12.5	35
	1/11	R88G-HPG32A112K0B☐	2	110	133	120	135 dia.	135	115	115	114	84	---	98	12.5	35
	1/21	R88G-HPG50A212K0B☐	2	123	156	170	170 dia.	190	115	165	163	122	---	103	12	53
	1/33	R88G-HPG50A332K0B☐	2	123	156	170	170 dia.	190	115	165	163	122	---	103	12	53
3 kW	1/5	R88G-HPG32A053K0B☐	1	107	133	120	130 × 130	135	145	115	114	84	---	98	12.5	35
	1/11	R88G-HPG50A113K0B☐	2	123	156	170	170 dia.	190	145	165	163	122	---	103	12	53
	1/21	R88G-HPG50A213K0B☐	2	123	156	170	170 dia.	190	145	165	163	122	---	103	12	53
4 kW	1/5	R88G-HPG32A054K0B☐	1	129	133	120	130 × 130	135	145	115	114	84	---	98	12.5	35
	1/11	R88G-HPG50A115K0B☐	1	149	156	170	130 × 130	190	145	165	163	122	170	103	12	53
4.7 kW 5 kW	1/5	R88G-HPG50A055K0B☐	1	149	156	170	130 × 130	190	145	165	163	122	170	103	12	53
	1/11	R88G-HPG50A115K0B☐	1	149	156	170	130 × 130	190	145	165	163	122	170	103	12	53

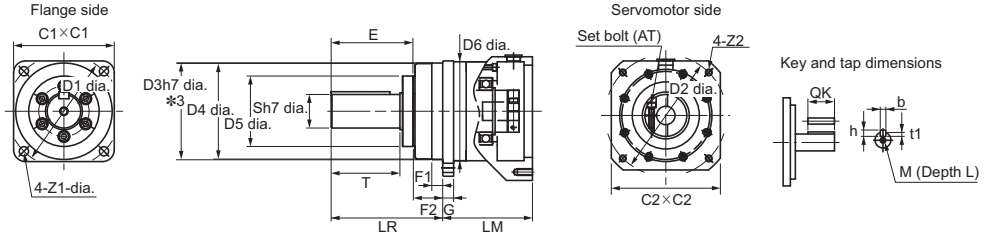
Servomotor rated output	Reduction ratio	Model	Dimensions [mm]											
			G	S	T	Z1	Z2	AT ※2	Key				Tap	
									QK	b	h	t1	M	L
1 kW	1/5	R88G-HPG32A052K0B☐	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/11	R88G-HPG32A112K0B☐	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/21	R88G-HPG32A211K5B☐	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/33	R88G-HPG50A332K0B☐	16	50	82	14	M8 × 10	M6	70	14	9	5.5	M10	20
	1/45	R88G-HPG50A451K5B☐	16	50	82	14	M8 × 10	M6	70	14	9	5.5	M10	20
1.5 kW	1/5	R88G-HPG32A052K0B☐	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/11	R88G-HPG32A112K0B☐	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/21	R88G-HPG32A211K5B☐	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/33	R88G-HPG50A332K0B☐	16	50	82	14	M8 × 10	M6	70	14	9	5.5	M10	20
	1/45	R88G-HPG50A451K5B☐	16	50	82	14	M8 × 10	M6	70	14	9	5.5	M10	20
2 kW	1/5	R88G-HPG32A052K0B☐	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/11	R88G-HPG32A112K0B☐	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/21	R88G-HPG50A212K0B☐	16	50	82	14	M8 × 10	M6	70	14	9	5.5	M10	20
	1/33	R88G-HPG50A332K0B☐	16	50	82	14	M8 × 10	M6	70	14	9	5.5	M10	20
3 kW	1/5	R88G-HPG32A053K0B☐	13	40	82	11	M8 × 18	M6	70	12	8	5	M10	20
	1/11	R88G-HPG50A113K0B☐	16	50	82	14	M8 × 16	M6	70	14	9	5.5	M10	20
	1/21	R88G-HPG50A213K0B☐	16	50	82	14	M8 × 16	M6	70	14	9	5.5	M10	20
4 kW	1/5	R88G-HPG32A054K0B☐	13	40	82	11	M8 × 25	M6	70	12	8	5	M10	20
	1/11	R88G-HPG50A115K0B☐	16	50	82	14	M8 × 25	M6	70	14	9	5.5	M10	20
4.7 kW 5 kW	1/5	R88G-HPG50A055K0B☐	16	50	82	14	M8 × 25	M6	70	14	9	5.5	M10	20
	1/11	R88G-HPG50A115K0B☐	16	50	82	14	M8 × 25	M6	70	14	9	5.5	M10	20

※1. D6 is the maximum diameter of the decelerator body between the flange side and Servomotor side. (See Outline Drawing) The value is given only when the diameter is larger than the diameters of these two sides. Take heed of this when you mount the decelerator to the machine.
※2. Indicates set bolt.

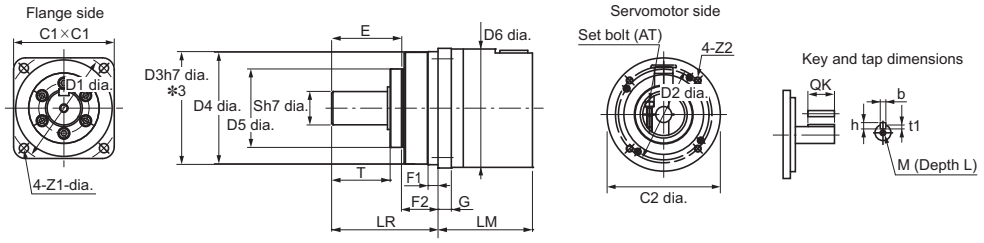
Note: 1. The standard shaft type is a straight shaft.
2. A model with a key and tap is indicated with "J" at ☐ of the model number. (Example: R88G-HPG32A052K0BJ)
3. The diameter of the motor shaft insertion hole is the same as the shaft diameter of the corresponding Servomotor.
4. You cannot use this type of Decelerator for the Servomotor with key.
5. The dimensional drawings in this document are for showing main dimensions only, and they do not give the details of the product shape.

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Outline Drawing 1



Outline Drawing 2



✻3. The tolerance is “h8” for R88G-HPG50□.

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● For 2,000-r/min Servomotors (400 W to 1 kW)

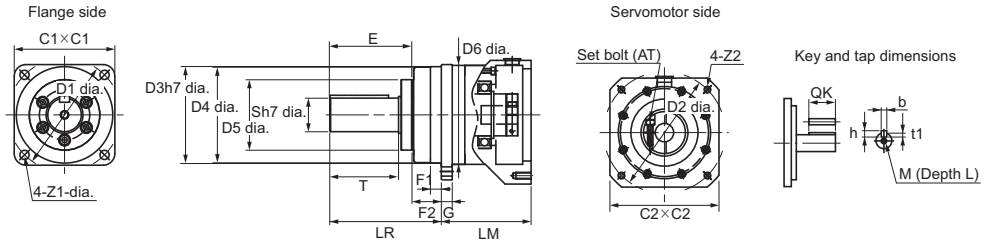
Servomotor rated output	Reduction ratio	Model	Outline drawing	Dimensions [mm]												
				LM	LR	C1	C2	D1	D2	D3	D4	D5	D6 ✻1	E	F1	F2
400 W (400 V)	1/5	R88G-HPG32A052K0B☐	2	110	133	120	135 dia.	135	115	115	114	84	---	98	12.5	35
	1/11	R88G-HPG32A112K0B☐	2	110	133	120	135 dia.	135	115	115	114	84	---	98	12.5	35
	1/21	R88G-HPG32A211K5B☐	2	110	133	120	135 dia.	135	115	115	114	84	---	98	12.5	35
	1/33	R88G-HPG32A33600SB☐	2	110	133	120	135 dia.	135	115	115	114	84	---	98	12.5	35
	1/45	R88G-HPG32A45400SB☐	2	110	133	120	135 dia.	135	115	115	114	84	---	98	12.5	35
600 W (400 V)	1/5	R88G-HPG32A052K0B☐	2	110	133	120	135 dia.	135	115	115	114	84	---	98	12.5	35
	1/11	R88G-HPG32A112K0B☐	2	110	133	120	135 dia.	135	115	115	114	84	---	98	12.5	35
	1/21	R88G-HPG32A211K5B☐	2	110	133	120	135 dia.	135	115	115	114	84	---	98	12.5	35
	1/33	R88G-HPG32A33600SB☐	2	110	133	120	135 dia.	135	115	115	114	84	---	98	12.5	35
	1/45	R88G-HPG50A451K5B☐	2	123	156	170	170 dia.	190	115	165	163	122	---	103	12	53
1 kW	1/5	R88G-HPG32A053K0B☐	1	107	133	120	130 × 130	135	145	115	114	84	---	98	12.5	35
	1/11	R88G-HPG32A112K0SB☐	1	107	133	120	130 × 130	135	145	115	114	84	---	98	12.5	35
	1/21	R88G-HPG32A211K0SB☐	1	107	133	120	130 × 130	135	145	115	114	84	---	98	12.5	35
	1/33	R88G-HPG50A332K0SB☐	2	123	156	170	170 dia.	190	145	165	163	122	---	103	12	53
	1/45	R88G-HPG50A451K0SB☐	2	123	156	170	170 dia.	190	145	165	163	122	---	103	12	53

Servomotor rated output	Reduction ratio	Model	Dimensions [mm]										
			G	S	T	Z1	Z2	AT ✻2	Key				Tap	
									QK	b	h	t1	M	L
400 W (400 V)	1/5	R88G-HPG32A052K0B☐	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/11	R88G-HPG32A112K0B☐	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/21	R88G-HPG32A211K5B☐	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/33	R88G-HPG32A33600SB☐	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/45	R88G-HPG32A45400SB☐	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
600 W (400 V)	1/5	R88G-HPG32A052K0B☐	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/11	R88G-HPG32A112K0B☐	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/21	R88G-HPG32A211K5B☐	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/33	R88G-HPG32A33600SB☐	13	40	82	11	M8 × 10	M6	70	12	8	5	M10	20
	1/45	R88G-HPG50A451K5B☐	16	50	82	14	M8 × 10	M6	70	14	9	5.5	M10	20
1 kW	1/5	R88G-HPG32A053K0B☐	13	40	82	11	M8 × 18	M6	70	12	8	5	M10	20
	1/11	R88G-HPG32A112K0SB☐	13	40	82	11	M8 × 18	M6	70	12	8	5	M10	20
	1/21	R88G-HPG32A211K0SB☐	13	40	82	11	M8 × 18	M6	70	12	8	5	M10	20
	1/33	R88G-HPG50A332K0SB☐	16	50	82	14	M8 × 16	M6	70	14	9	5.5	M10	20
	1/45	R88G-HPG50A451K0SB☐	16	50	82	14	M8 × 16	M6	70	14	9	5.5	M10	20

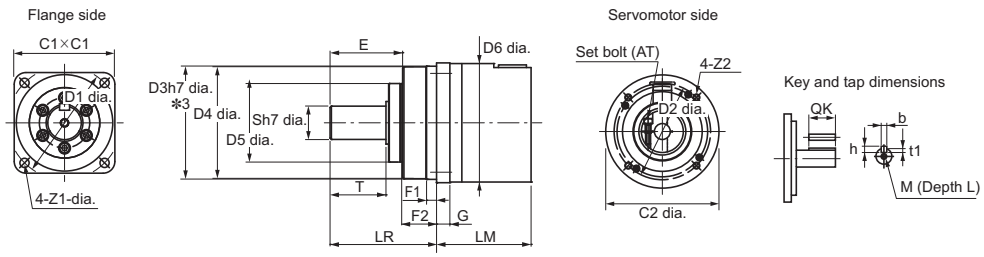
✻1. D6 is the maximum diameter of the decelerator body between the flange side and Servomotor side. (See Outline Drawing) The value is given only when the diameter is larger than the diameters of these two sides. Take heed of this when you mount the decelerator to the machine.
✻2. Indicates set bolt.

Note: 1. The standard shaft type is a straight shaft.
2. A model with a key and tap is indicated with "J" at ☐ of the model number.
(Example: R88G-HPG32A053K0BJ)
3. The diameter of the motor shaft insertion hole is the same as the shaft diameter of the corresponding Servomotor.
4. You cannot use this type of Decelerator for the Servomotor with key.
5. The dimensional drawings in this document are for showing main dimensions only, and they do not give the details of the product shape.

Outline Drawing 1



Outline Drawing 2



✻3. The tolerance is "h8" for R88G-HPG50☐.

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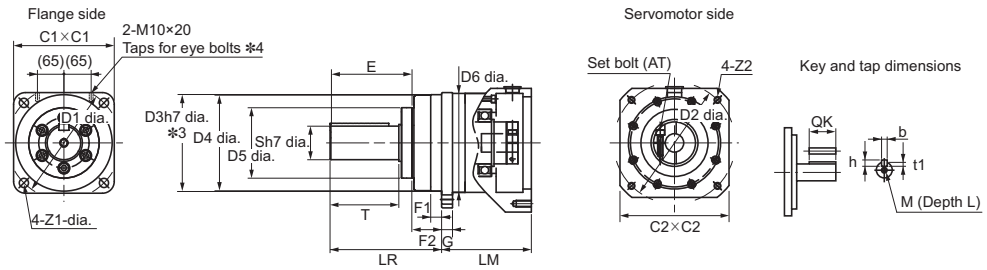
● For 2,000-r/min Servomotors (1.5 to 3 kW)

Servomotor rated output	Reduction ratio	Model	Outline drawing	Dimensions [mm]												
				LM	LR	C1	C2	D1	D2	D3	D4	D5	D6 ✻1	E	F1	F2
1.5 kW	1/5	R88G-HPG32A053K0B□	1	107	133	120	130 × 130	135	145	115	114	84	---	98	12.5	35
	1/11	R88G-HPG32A112K0SB□	1	107	133	120	130 × 130	135	145	115	114	84	---	98	12.5	35
	1/21	R88G-HPG50A213K0B□	2	123	156	170	170 dia.	190	145	165	163	122	---	103	12	53
	1/33	R88G-HPG50A332K0SB□	2	123	156	170	170 dia.	190	145	165	163	122	---	103	12	53
2 kW	1/5	R88G-HPG32A053K0B□	1	107	133	120	130 × 130	135	145	115	114	84	---	98	12.5	35
	1/11	R88G-HPG32A112K0SB□	1	107	133	120	130 × 130	135	145	115	114	84	---	98	12.5	35
	1/21	R88G-HPG50A213K0B□	2	123	156	170	170 dia.	190	145	165	163	122	---	103	12	53
	1/33	R88G-HPG50A332K0SB□	2	123	156	170	170 dia.	190	145	165	163	122	---	103	12	53
3 kW	1/5	R88G-HPG32A054K0B□	1	129	133	120	130 × 130	135	145	115	114	84	---	98	12.5	35
	1/11	R88G-HPG50A115K0B□	1	149	156	170	130 × 130	190	145	165	163	122	170	103	12	53
	1/21	R88G-HPG50A213K0SB□	1	149	156	170	130 × 130	190	145	165	163	122	170	103	12	53
	1/25	R88G-HPG65A253K0SB□	1	231	222	230	130 × 130	260	145	220	214	168	220	165	12	57

Servomotor rated output	Reduction ratio	Model	Dimensions [mm]										
			G	S	T	Z1	Z2	AT ✻2	Key				Tap	
									QK	b	h	t1	M	L
1.5 kW	1/5	R88G-HPG32A053K0B□	13	40	82	11	M8 × 18	M6	70	12	8	5	M10	20
	1/11	R88G-HPG32A112K0SB□	13	40	82	11	M8 × 18	M6	70	12	8	5	M10	20
	1/21	R88G-HPG50A213K0B□	16	50	82	14	M8 × 16	M6	70	14	9	5.5	M10	20
	1/33	R88G-HPG50A332K0SB□	16	50	82	14	M8 × 16	M6	70	14	9	5.5	M10	20
2 kW	1/5	R88G-HPG32A053K0B□	13	40	82	11	M8 × 18	M6	70	12	8	5	M10	20
	1/11	R88G-HPG32A112K0SB□	13	40	82	11	M8 × 18	M6	70	12	8	5	M10	20
	1/21	R88G-HPG50A213K0B□	16	50	82	14	M8 × 16	M6	70	14	9	5.5	M10	20
	1/33	R88G-HPG50A332K0SB□	16	50	82	14	M8 × 16	M6	70	14	9	5.5	M10	20
3 kW	1/5	R88G-HPG32A054K0B□	13	40	82	11	M8 × 25	M6	70	12	8	5	M10	20
	1/11	R88G-HPG50A115K0B□	16	50	82	14	M8 × 25	M6	70	14	9	5.5	M10	20
	1/21	R88G-HPG50A213K0SB□	16	50	82	14	M8 × 25	M6	70	14	9	5.5	M10	20
	1/25	R88G-HPG65A253K0SB□	25	80	130	18	M8 × 25	M8	110	22	14	9	M16	35

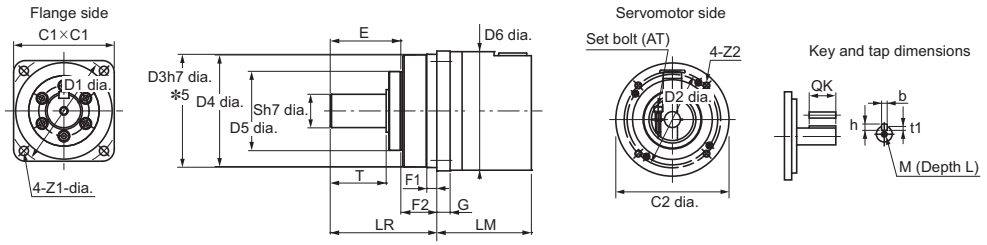
✻1. D6 is the maximum diameter of the decelerator body between the flange side and Servomotor side. (See Outline Drawing) The value is given only when the diameter is larger than the diameters of these two sides. Take heed of this when you mount the decelerator to the machine.
✻2. Indicates set bolt.
Note: 1. The standard shaft type is a straight shaft.
2. A model with a key and tap is indicated with "J" at □ of the model number.
(Example: R88G-HPG32A05900TBJ)
3. The diameter of the motor shaft insertion hole is the same as the shaft diameter of the corresponding Servomotor.
4. You cannot use this type of Decelerator for the Servomotor with key.
5. The dimensional drawings in this document are for showing main dimensions only, and they do not give the details of the product shape.

Outline Drawing 1



✻3. The tolerance is "h8" for R88G-HPG50□ and R88G-HPG65□.
✻4. The model R88G-HPG65□ has the taps for eye bolts.

Outline Drawing 2



✻5. The tolerance is "h8" for R88G-HPG50□.

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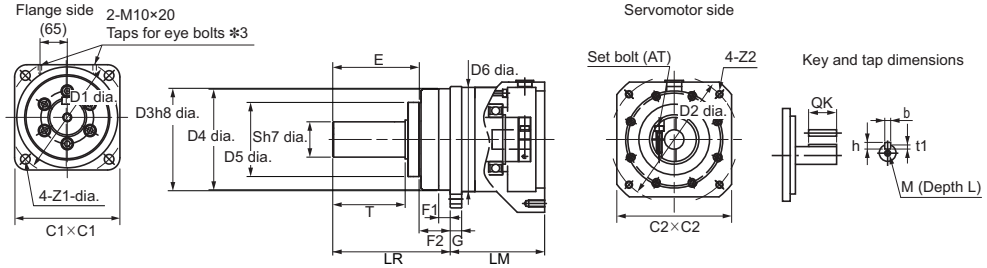
● For 1,500-r/min Servomotors (4 kW to 5.5 kW)

Servomotor rated output	Reduction ratio	Model	Outline drawing	Dimensions [mm]												
				LM	LR	C1	C2	D1	D2	D3	D4	D5	D6 ✻1	E	F1	F2
4 kW	1/5	R88G-HPG50A055K0SB□	1	149	156	170	180 × 180	190	200	165	163	122	---	103	12	53
	1/11	R88G-HPG50A115K0SB□	1	149	156	170	180 × 180	190	200	165	163	122	---	103	12	53
	1/21	R88G-HPG65A205K0SB□	1	231	222	230	180 × 180	260	200	220	214	168	220	165	12	57
	1/33	R88G-HPG65A255K0SB□	1	231	222	230	180 × 180	260	200	220	214	168	220	165	12	57
5 kW 5.5 kW	1/5	R88G-HPG50A054K5TB□	1	149	156	170	180 × 180	190	200	165	163	122	---	103	12	53
	1/12	R88G-HPG65A127K5SB□	1	254.5	222	230	180 × 180	260	200	220	214	168	220	165	12	57
	1/20	R88G-HPG65A204K5TB□	1	254.5	222	230	180 × 180	260	200	220	214	168	220	165	12	57

Servomotor rated output	Reduction ratio	Model	Dimensions [mm]											
			G	S	T	Z1	Z2	AT ✻2	Key				Tap	
									QK	b	h	t1	M	L
4 kW	1/5	R88G-HPG50A055K0SB□	16	50	82	14	M12 × 25	M6	70	14	9	5.5	M10	20
	1/11	R88G-HPG50A115K0SB□	16	50	82	14	M12 × 25	M6	70	14	9	5.5	M10	20
	1/21	R88G-HPG65A205K0SB□	25	80	130	18	M12 × 25	M8	110	22	14	9	M16	35
	1/33	R88G-HPG65A255K0SB□	25	80	130	18	M12 × 25	M8	110	22	14	9	M16	35
5 kW 5.5 kW	1/5	R88G-HPG50A054K5TB□	16	50	82	14	M12 × 25	M6	70	14	9	5.5	M10	20
	1/12	R88G-HPG65A127K5SB□	25	80	130	18	M12 × 25	M8	110	22	14	9	M16	35
	1/20	R88G-HPG65A204K5TB□	25	80	130	18	M12 × 25	M8	110	22	14	9	M16	35

✻1. D6 is the maximum diameter of the decelerator body between the flange side and Servomotor side. (See Outline Drawing) The value is given only when the diameter is larger than the diameters of these two sides. Take heed of this when you mount the decelerator to the machine.
✻2. Indicates set bolt.
Note: 1. The standard shaft type is a straight shaft.
2. A model with a key and tap is indicated with "J" at □ of the model number. (Example: R88G-HPG11B05100BJ)
3. The diameter of the motor shaft insertion hole is the same as the shaft diameter of the corresponding Servomotor.
4. You cannot use this type of Decelerator for the Servomotor with key.
5. The dimensional drawings in this document are for showing main dimensions only, and they do not give the details of the product shape.

Outline Drawing 1



✻3. The model R88G-HPG65□ has the taps for eye bolts.

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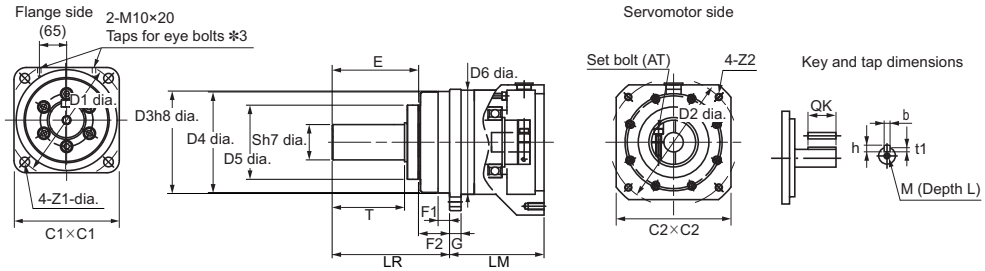
● For 1,000-r/min Servomotors (900 W to 3 kW)

Servomotor rated output	Reduction ratio	Model	Outline drawing	Dimensions [mm]												
				LM	LR	C1	C2	D1	D2	D3	D4	D5	D6 ✻1	E	F1	F2
900 W	1/5	R88G-HPG32A05900TB□	1	129	133	120	130 × 130	135	145	115	114	84	---	98	12.5	35
	1/11	R88G-HPG32A11900TB□	1	129	133	120	130 × 130	135	145	115	114	84	---	98	12.5	35
	1/21	R88G-HPG50A21900TB□	1	149	156	170	130 × 130	190	145	165	163	122	170	103	12	53
	1/33	R88G-HPG50A33900TB□	1	149	156	170	130 × 130	190	145	165	163	122	170	103	12	53
2 kW	1/5	R88G-HPG32A052K0TB□	1	129	133	120	180 × 180	135	200	115	114	84	---	98	12.5	35
	1/11	R88G-HPG50A112K0TB□	1	149	156	170	180 × 180	190	200	165	163	122	---	103	12	53
	1/21	R88G-HPG50A212K0TB□	1	149	156	170	180 × 180	190	200	165	163	122	---	103	12	53
	1/25	R88G-HPG65A255K0SB□	1	231	222	230	180 × 180	260	200	220	214	168	220	165	12	57
3 kW	1/5	R88G-HPG50A055K0SB□	1	149	156	170	180 × 180	190	200	165	163	122	---	103	12	53
	1/11	R88G-HPG50A115K0SB□	1	149	156	170	180 × 180	190	200	165	163	122	---	103	12	53
	1/20	R88G-HPG65A205K0SB□	1	231	222	230	180 × 180	260	200	220	214	168	220	165	12	57
	1/25	R88G-HPG65A255K0SB□	1	231	222	230	180 × 180	260	200	220	214	168	220	165	12	57

Servomotor rated output	Reduction ratio	Model	Dimensions [mm]										
			G	S	T	Z1	Z2	AT ✻2	Key				Tap	
									QK	b	h	t1	M	L
900 W	1/5	R88G-HPG32A05900TB□	13	40	82	11	M8 × 25	M6	70	12	8	5	M10	20
	1/11	R88G-HPG32A11900TB□	13	40	82	11	M8 × 25	M6	70	12	8	5	M10	20
	1/21	R88G-HPG50A21900TB□	16	50	82	14	M8 × 25	M6	70	14	9	5.5	M10	20
	1/33	R88G-HPG50A33900TB□	16	50	82	14	M8 × 25	M6	70	14	9	5.5	M10	20
2 kW	1/5	R88G-HPG32A052K0TB□	13	40	82	11	M12 × 25	M6	70	12	8	5	M10	20
	1/11	R88G-HPG50A112K0TB□	16	50	82	14	M12 × 25	M6	70	14	9	5.5	M10	20
	1/21	R88G-HPG50A212K0TB□	16	50	82	14	M12 × 25	M6	70	14	9	5.5	M10	20
	1/25	R88G-HPG65A255K0SB□	25	80	130	18	M12 × 25	M8	110	22	14	9	M16	35
3 kW	1/5	R88G-HPG50A055K0SB□	16	50	82	14	M12 × 25	M6	70	14	9	5.5	M10	20
	1/11	R88G-HPG50A115K0SB□	16	50	82	14	M12 × 25	M6	70	14	9	5.5	M10	20
	1/20	R88G-HPG65A205K0SB□	25	80	130	18	M12 × 25	M8	110	22	14	9	M16	35
	1/25	R88G-HPG65A255K0SB□	25	80	130	18	M12 × 25	M8	110	22	14	9	M16	35

✻1. D6 is the maximum diameter of the decelerator body between the flange side and Servomotor side. (See Outline Drawing) The value is given only when the diameter is larger than the diameters of these two sides. Take heed of this when you mount the decelerator to the machine.
✻2. Indicates set bolt.
Note: 1. The standard shaft type is a straight shaft.
2. A model with a key and tap is indicated with "J" at □ of the model number.
(Example: R88G-HPG32A05900TBJ)
3. The diameter of the motor shaft insertion hole is the same as the shaft diameter of the corresponding Servomotor.
4. You cannot use this type of Decelerator for the Servomotor with key.
5. The dimensional drawings in this document are for showing main dimensions only, and they do not give the details of the product shape.

Outline Drawing 1



✻3. The tolerance is "h8" for R88G-HPG50□ and R88G-HPG65□.
✻4. The model R88G-HPG65□ has the taps for eye bolts.

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Backlash: 15 Arcminutes Max.

● For 3,000-r/min Servomotors

Model			Dimensions [mm]										
			LM	LR	C1	C2	D1	D2	D3	F	G	S	T
50 W	1/5	R88G-VRXF05B100CJ	67.5	32	40	52	46	60	50	3	6	12	20
	1/9	R88G-VRXF09B100CJ	67.5	32	40	52	46	60	50	3	6	12	20
	1/15	R88G-VRXF15B100CJ	78.0	32	40	52	46	60	50	3	6	12	20
	1/25	R88G-VRXF25B100CJ	78.0	32	40	52	46	60	50	3	6	12	20
100 W	1/5	R88G-VRXF05B100CJ	67.5	32	40	52	46	60	50	3	6	12	20
	1/9	R88G-VRXF09B100CJ	67.5	32	40	52	46	60	50	3	6	12	20
	1/15	R88G-VRXF15B100CJ	78.0	32	40	52	46	60	50	3	6	12	20
	1/25	R88G-VRXF25B100CJ	78.0	32	40	52	46	60	50	3	6	12	20
200 W	1/5	R88G-VRXF05B200CJ	72.5	32	60	52	70	60	50	3	10	12	20
	1/9	R88G-VRXF09C200CJ	89.5	50	60	78	70	90	70	3	8	19	30
	1/15	R88G-VRXF15C200CJ	100.0	50	60	78	70	90	70	3	8	19	30
	1/25	R88G-VRXF25C200CJ	100.0	50	60	78	70	90	70	3	8	19	30
400 W	1/5	R88G-VRXF05C400CJ	89.5	50	60	78	70	90	70	3	8	19	30
	1/9	R88G-VRXF09C400CJ	89.5	50	60	78	70	90	70	3	8	19	30
	1/15	R88G-VRXF15C400CJ	100.0	50	60	78	70	90	70	3	8	19	30
	1/25	R88G-VRXF25C400CJ	100.0	50	60	78	70	90	70	3	8	19	30
750 W (200 V)	1/5	R88G-VRXF05C750CJ	93.5	50	80	78	90	90	70	3	10	19	30
	1/9	R88G-VRXF09D750CJ	97.5	61	80	98	90	115	90	5	10	24	40
	1/15	R88G-VRXF15D750CJ	110.0	61	80	98	90	115	90	5	10	24	40
	1/25	R88G-VRXF25D750CJ	110.0	61	80	98	90	115	90	5	10	24	40

Model			Dimensions [mm]									
			Z1	Z2	AT ✻	L	Key				Tap	
							QK	b	h	t1	m	l
50 W	1/5	R88G-VRXF05B100CJ	M4	M5	M4	12	16	4	4	2.5	M5	10
	1/9	R88G-VRXF09B100CJ	M4	M5	M4	12	16	4	4	2.5	M5	10
	1/15	R88G-VRXF15B100CJ	M4	M5	M4	12	16	4	4	2.5	M5	10
	1/25	R88G-VRXF25B100CJ	M4	M5	M4	12	16	4	4	2.5	M5	10
100 W	1/5	R88G-VRXF05B100CJ	M4	M5	M4	12	16	4	4	2.5	M5	10
	1/9	R88G-VRXF09B100CJ	M4	M5	M4	12	16	4	4	2.5	M5	10
	1/15	R88G-VRXF15B100CJ	M4	M5	M4	12	16	4	4	2.5	M5	10
	1/25	R88G-VRXF25B100CJ	M4	M5	M4	12	16	4	4	2.5	M5	10
200 W	1/5	R88G-VRXF05B200CJ	M4	M5	M4	12	16	4	4	2.5	M5	10
	1/9	R88G-VRXF09C200CJ	M4	M6	M5	20	22	6	6	3.5	M6	12
	1/15	R88G-VRXF15C200CJ	M4	M6	M5	20	22	6	6	3.5	M6	12
	1/25	R88G-VRXF25C200CJ	M4	M6	M5	20	22	6	6	3.5	M6	12
400 W	1/5	R88G-VRXF05C400CJ	M4	M6	M5	20	22	6	6	3.5	M6	12
	1/9	R88G-VRXF09C400CJ	M4	M6	M5	20	22	6	6	3.5	M6	12
	1/15	R88G-VRXF15C400CJ	M4	M6	M5	20	22	6	6	3.5	M6	12
	1/25	R88G-VRXF25C400CJ	M4	M6	M5	20	22	6	6	3.5	M6	12
750 W (200 V)	1/5	R88G-VRXF05C750CJ	M5	M6	M6	20	22	6	6	3.5	M6	12
	1/9	R88G-VRXF09D750CJ	M5	M8	M6	20	30	8	7	4	M8	16
	1/15	R88G-VRXF15D750CJ	M5	M8	M6	20	30	8	7	4	M8	16
	1/25	R88G-VRXF25D750CJ	M5	M8	M6	20	30	8	7	4	M8	16

✻ Indicates set bolt.

Note: 1. The standard shaft type is a shaft with key and tap.

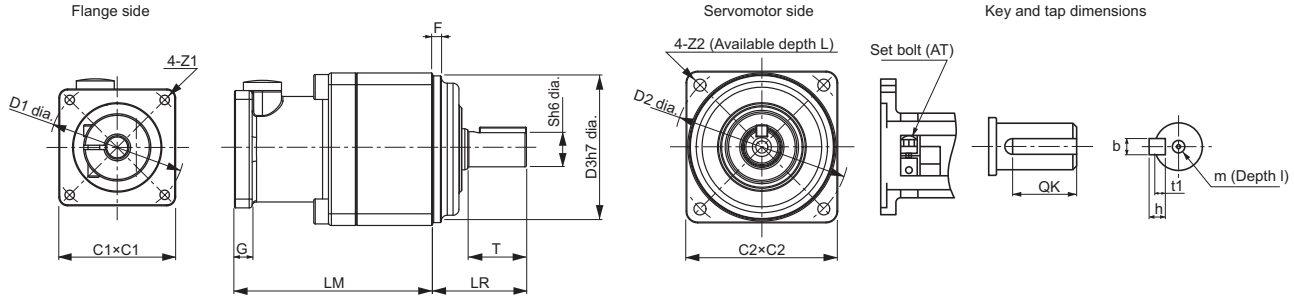
2. The diameter of the motor shaft insertion hole is the same as the shaft diameter of the corresponding Servomotor.

3. You cannot use this type of Decelerator for the Servomotor with key.

4. The dimensional drawings in this document are for showing main dimensions only, and they do not give the details of the product shape.

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Outline Drawing



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Ordering Information

Interpreting Model Numbers 92
AC Servo Drives with Built-in EtherCAT Communications 92
AC Servomotor 92
Decelerator 93
Table of AC Servomotor Variations 94
Ordering Information 95
AC Servo Drives with Built-in EtherCAT Communications 95
AC Servomotors 96
Decelerator (Backlash: 3 Arcminutes Max./15 Arcminutes Max.) 101
Cables and Peripheral Devices 102
Software 111
Combination table 112
Cable Connection Configuration 115
Related Manuals 121
Sizing Tool for AC Servo Motors 122

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Interpreting Model Numbers

AC Servo Drives with Built-in EtherCAT Communications

R88D-1S N 01 H -ECT
(1) (2) (3) (4) (5)

No	Item	Symbol	Specifications
(1)	1S-series Servo Drive		
(2)	Servo Drive Type	N	Standard / Communication type
(3)	Applicable Servomotor rated output	01	100 W
		02	200 W
		04	400 W
		06	600 W
		08	750 W
		10	1 kW
		15	1.5 kW
		20	2 kW
		30	3 kW
		55	5.5 kW
		75	7.5 kW
		150	15 kW
(4)	Power Supply Voltage	L	100 VAC
		H	200 VAC
		F	400 VAC
(5)	Communications type	ECT	EtherCAT Communications

AC Servomotor

R88M-1 M 100 30 S -BOS2
(1) (2) (3) (4) (5) (6)

No	Item	Symbol	Specifications
(1)	1S-series Servomotor		
(2)	Servomotor Type	L	Standard / Low-inertia type
		M	Standard / Middle-inertia type
(3)	Rated output	050	50 W
		100	100 W
		200	200 W
		400	400 W
		600	600 W
		750	750 W
		900	900 W
		1K0	1 kW
		1K5	1.5 kW
		2K0	2 kW
		3K0	3 kW
		4K0	4 kW
		4K7	4.7 kW
		5K0	5 kW
		5K5	5.5 kW
		7K0	7.5 kW
		11K0	11 kW
		15K0	15 kW
(4)	Rated rotation speed	10	1,000 r/min
		15	1,500 r/min
		20	2,000 r/min
		30	3,000 r/min
(5)	Servo Drive main power supply voltage and encoder type	S	100 VAC absolute encoder
		T	200 VAC absolute encoder
		C	400 VAC absolute encoder
(6)	Options		
	Brake	None	Without brake
		B	With 24-VDC brake
	Oil seal	None	Without oil seal
		O	With oil seal
	Key and tap	None	Straight shaft
		S2	With key and tap

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Decelerator
Backlash: 3 Arcminutes Max.

R88G-HPG 14A 05 100 S B J
(1) (2) (3) (4) (5) (6) (7)

No	Item	Symbol	Specifications
(1)	Decelerator for Servomotor Backlash: 3 Arcminutes max.		
(2)	Flange size number	11B	40 × 40
		14A	60 × 60
		20A	90 × 90
		32A	120 × 120
		50A	170 × 170
		65A	230 × 230
(3)	Reduction ratio	05	1/5
		11	1/11
		12	1/12
		20	1/20
		21	1/21
		25	1/25
		33	1/33
		45	1/45
(4)	Applicable Servomotor rated output ✻	050	50 W
		100	100 W
		200	200 W
		400	400 W
		600	600 W
		750	750 W
		900	900 W
		1K0	1 kW
		1K5	1.5 kW
		2K0	2 kW
		3K0	3 kW
		4K0	4 kW
		4K5	4.5 kW
		5K0	5 kW
		7K5	7.5 kW
(5)	Servomotor type ✻	None	3,000-r/min Servomotors
		S	2,000-r/min Servomotors
		T	1,000-r/min Servomotors
(6)	Backlash	B	Backlash: 3 Arcminutes max.
(7)	Option	None	Straight shaft
		J	With key and tap

✻ This is a standard model number of servo motor; this model number structure can be applied to other motors. Confirm decelerator and servomotor combination table when you select a Servomotor.

Backlash: 15 Arcminutes Max.

R88G-VRXF 09 B 100 C J
(1) (2) (3) (4) (5) (6)

No	Item	Symbol	Specifications
(1)	Decelerator for Servomotor Backlash: 15 Arcminutes max.		
(2)	Gear Ratio	05	1/5
		09	1/9
		15	1/15
		25	1/25
(3)	Flange Size Number	B	□52
		C	□78
		D	□98
(4)	Applicable Servomotor rated output	100	50 W, 100 W
		200	200 W
		400	400 W
		750	750 W
(5)	Backlash	C	Backlash: 15 Arcminutes Max
(6)	Option	J	With key and tap

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Table of AC Servomotor Variations

R88M-1□ □□□ □□ □ - □ □ □□

(2) (3) (4) (5) (6) (7) (8)

(2)	(3)	(4)	Model	(5)			(6)		(7)		(8)	
Type	Rated output	Rotation speed		Power supply specifications			Brake		Oil seal		Shaft type	
				ABS 400	ABS 200	ABS 100						
				C	T	S	None	B	None	O	None	S2
M	50 W	3,000 r/min	R88M-1M05030		✓	✓	✓	✓	✓	✓	✓	✓
	100 W		R88M-1M10030		✓	✓	✓	✓	✓	✓	✓	✓
	200 W		R88M-1M20030		✓	✓	✓	✓	✓	✓	✓	✓
	400 W		R88M-1M40030		✓	✓	✓	✓	✓	✓	✓	✓
	750 W		R88M-1M75030		✓		✓	✓	✓	✓	✓	✓
L	750 W		R88M-1L75030	✓			✓	✓	✓	✓	✓	✓
	1 kW		R88M-1L1K030	✓	✓		✓	✓	✓	✓	✓	✓
	1.5 kW		R88M-1L1K530	✓	✓		✓	✓	✓	✓	✓	✓
	2 kW		R88M-1L2K030	✓	✓		✓	✓	✓	✓	✓	✓
	3 kW		R88M-1L3K030	✓	✓		✓	✓	✓	✓	✓	✓
	4 kW		R88M-1L4K030	✓	✓		✓	✓	✓	✓	✓	✓
	4.7 kW		R88M-1L4K730		✓							
	5 kW		R88M-1L5K030	✓			✓	✓	✓	✓	✓	✓
M	400 W	2,000 r/min	R88M-1M40020	✓			✓	✓	✓	✓	✓	✓
	600 W		R88M-1M60020	✓			✓	✓	✓	✓	✓	✓
	1 kW		R88M-1M1K020	✓	✓		✓	✓	✓	✓	✓	✓
	1.5 kW		R88M-1M1K520	✓	✓		✓	✓	✓	✓	✓	✓
	2 kW		R88M-1M2K020	✓	✓		✓	✓	✓	✓	✓	✓
	3 kW		R88M-1M3K020	✓	✓		✓	✓	✓	✓	✓	✓
M	4 kW	1,500 r/min	R88M-1M4K015	✓	✓		✓	✓	✓	✓	✓	✓
	5 kW		R88M-1M5K015		✓							
	5.5 kW		R88M-1M5K515	✓			✓	✓	✓	✓	✓	✓
	7.5 kW		R88M-1M7K515	✓	✓		✓	✓	✓	✓	✓	✓
	11 kW		R88M-1M11K015	✓	✓		✓	✓	✓	✓	✓	✓
	15 kW		R88M-1M15K015	✓	✓		✓	✓	✓	✓	✓	✓
M	900 W	1,000 r/min	R88M-1M90010	✓	✓		✓	✓	✓	✓	✓	✓
	2 kW		R88M-1M2K010	✓	✓		✓	✓	✓	✓	✓	✓
	3 kW		R88M-1M3K010	✓	✓		✓	✓	✓	✓	✓	✓
M:Middle inertia L:Low inertia	100: 100 W 1K0: 1 kW 3K0: 3 kW	10: 1,000 r/min 15: 1,500 r/min 20: 2,000 r/min 30: 3,000 r/min		C: 400 VAC (with absolute encoder) ABS/INC T: 200 VAC (with absolute encoder) ABS/INC S: 100 VAC (with absolute encoder) ABS/INC			None: Without brake B: With 24-VDC brake		None: Without oil seal O: With oil seal		None: Straight shaft S2: With key and tap	

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Ordering Information

AC Servo Drives with Built-in EtherCAT Communications

Power supply voltage	Rated output	Model
Single-phase 100 VAC	100 W	R88D-1SN01L-ECT
	200 W	R88D-1SN02L-ECT
	400 W	R88D-1SN04L-ECT
Single-phase/3-phase 200 VAC	100 W	R88D-1SN01H-ECT
	200 W	R88D-1SN02H-ECT
	400 W	R88D-1SN04H-ECT
	750 W	R88D-1SN08H-ECT
	1.5 kW	R88D-1SN15H-ECT
3-phase 200 VAC	1 kW	R88D-1SN10H-ECT
	2 kW	R88D-1SN20H-ECT
	3 kW	R88D-1SN30H-ECT
	5.5 kW	R88D-1SN55H-ECT
	7.5 kW	R88D-1SN75H-ECT
	15 kW	R88D-1SN150H-ECT
3-phase 400 VAC	600 W	R88D-1SN06F-ECT
	1 kW	R88D-1SN10F-ECT
	1.5 kW	R88D-1SN15F-ECT
	2 kW	R88D-1SN20F-ECT
	3 kW	R88D-1SN30F-ECT
	5.5 kW	R88D-1SN55F-ECT
	7.5 kW	R88D-1SN75F-ECT
	15 kW	R88D-1SN150F-ECT

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AC Servomotors

● 3,000-r/min Servomotors

Specifications			Model	
			Without oil seal	
			Straight shaft	With key and tap
Without brake	100 VAC	50 W	R88M-1M05030S	R88M-1M05030S-S2
		100 W	R88M-1M10030S	R88M-1M10030S-S2
		200 W	R88M-1M20030S	R88M-1M20030S-S2
		400 W	R88M-1M40030S	R88M-1M40030S-S2
	200 VAC	50 W	R88M-1M05030T	R88M-1M05030T-S2
		100 W	R88M-1M10030T	R88M-1M10030T-S2
		200 W	R88M-1M20030T	R88M-1M20030T-S2
		400 W	R88M-1M40030T	R88M-1M40030T-S2
		750 W	R88M-1M75030T	R88M-1M75030T-S2
		1 kW	R88M-1L1K030T	R88M-1L1K030T-S2
		1.5 kW	R88M-1L1K530T	R88M-1L1K530T-S2
		2 kW	R88M-1L2K030T	R88M-1L2K030T-S2
		3 kW	R88M-1L3K030T	R88M-1L3K030T-S2
		4 kW	R88M-1L4K030T	R88M-1L4K030T-S2
		4.7 kW	R88M-1L4K730T	R88M-1L4K730T-S2
	400 VAC	750 W	R88M-1L75030C	R88M-1L75030C-S2
		1 kW	R88M-1L1K030C	R88M-1L1K030C-S2
		1.5 kW	R88M-1L1K530C	R88M-1L1K530C-S2
		2 kW	R88M-1L2K030C	R88M-1L2K030C-S2
		3 kW	R88M-1L3K030C	R88M-1L3K030C-S2
		4 kW	R88M-1L4K030C	R88M-1L4K030C-S2
		5 kW	R88M-1L5K030C	R88M-1L5K030C-S2
With brake	100 VAC	50 W	R88M-1M05030S-B	R88M-1M05030S-BS2
		100 W	R88M-1M10030S-B	R88M-1M10030S-BS2
		200 W	R88M-1M20030S-B	R88M-1M20030S-BS2
		400 W	R88M-1M40030S-B	R88M-1M40030S-BS2
	200 VAC	50 W	R88M-1M05030T-B	R88M-1M05030T-BS2
		100 W	R88M-1M10030T-B	R88M-1M10030T-BS2
		200 W	R88M-1M20030T-B	R88M-1M20030T-BS2
		400 W	R88M-1M40030T-B	R88M-1M40030T-BS2
		750 W	R88M-1M75030T-B	R88M-1M75030T-BS2
		1 kW	R88M-1L1K030T-B	R88M-1L1K030T-BS2
		1.5 kW	R88M-1L1K530T-B	R88M-1L1K530T-BS2
		2 kW	R88M-1L2K030T-B	R88M-1L2K030T-BS2
		3 kW	R88M-1L3K030T-B	R88M-1L3K030T-BS2
		4 kW	R88M-1L4K030T-B	R88M-1L4K030T-BS2
		4.7 kW	R88M-1L4K730T-B	R88M-1L4K730T-BS2
	400 VAC	750 W	R88M-1L75030C-B	R88M-1L75030C-BS2
		1 kW	R88M-1L1K030C-B	R88M-1L1K030C-BS2
		1.5 kW	R88M-1L1K530C-B	R88M-1L1K530C-BS2
		2 kW	R88M-1L2K030C-B	R88M-1L2K030C-BS2
		3 kW	R88M-1L3K030C-B	R88M-1L3K030C-BS2
		4 kW	R88M-1L4K030C-B	R88M-1L4K030C-BS2
		5 kW	R88M-1L5K030C-B	R88M-1L5K030C-BS2

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Specifications			Model	
			With oil seal	
			Straight shaft	With key and tap
Without brake	100 VAC	50 W	R88M-1M05030S-O	R88M-1M05030S-OS2
		100 W	R88M-1M10030S-O	R88M-1M10030S-OS2
		200 W	R88M-1M20030S-O	R88M-1M20030S-OS2
		400 W	R88M-1M40030S-O	R88M-1M40030S-OS2
	200 VAC	50 W	R88M-1M05030T-O	R88M-1M05030T-OS2
		100 W	R88M-1M10030T-O	R88M-1M10030T-OS2
		200 W	R88M-1M20030T-O	R88M-1M20030T-OS2
		400 W	R88M-1M40030T-O	R88M-1M40030T-OS2
		750 W	R88M-1M75030T-O	R88M-1M75030T-OS2
		1 kW	R88M-1L1K030T-O	R88M-1L1K030T-OS2
		1.5 kW	R88M-1L1K530T-O	R88M-1L1K530T-OS2
		2 kW	R88M-1L2K030T-O	R88M-1L2K030T-OS2
		3 kW	R88M-1L3K030T-O	R88M-1L3K030T-OS2
		4 kW	R88M-1L4K030T-O	R88M-1L4K030T-OS2
		4.7 kW	R88M-1L4K730T-O	R88M-1L4K730T-OS2
	400 VAC	750 W	R88M-1L75030C-O	R88M-1L75030C-OS2
		1 kW	R88M-1L1K030C-O	R88M-1L1K030C-OS2
		1.5 kW	R88M-1L1K530C-O	R88M-1L1K530C-OS2
		2 kW	R88M-1L2K030C-O	R88M-1L2K030C-OS2
		3 kW	R88M-1L3K030C-O	R88M-1L3K030C-OS2
		4 kW	R88M-1L4K030C-O	R88M-1L4K030C-OS2
		5 kW	R88M-1L5K030C-O	R88M-1L5K030C-OS2
With brake	100 VAC	50 W	R88M-1M05030S-BO	R88M-1M05030S-BOS2
		100 W	R88M-1M10030S-BO	R88M-1M10030S-BOS2
		200 W	R88M-1M20030S-BO	R88M-1M20030S-BOS2
		400 W	R88M-1M40030S-BO	R88M-1M40030S-BOS2
	200 VAC	50 W	R88M-1M05030T-BO	R88M-1M05030T-BOS2
		100 W	R88M-1M10030T-BO	R88M-1M10030T-BOS2
		200W	R88M-1M20030T-BO	R88M-1M20030T-BOS2
		400 W	R88M-1M40030T-BO	R88M-1M40030T-BOS2
		750 W	R88M-1M75030T-BO	R88M-1M75030T-BOS2
		1 kW	R88M-1L1K030T-BO	R88M-1L1K030T-BOS2
		1.5 kW	R88M-1L1K530T-BO	R88M-1L1K530T-BOS2
		2 kW	R88M-1L2K030T-BO	R88M-1L2K030T-BOS2
		3 kW	R88M-1L3K030T-BO	R88M-1L3K030T-BOS2
		4 kW	R88M-1L4K030T-BO	R88M-1L4K030T-BOS2
		4.7 kW	R88M-1L4K730T-BO	R88M-1L4K730T-BOS2
	400 VAC	750 W	R88M-1L75030C-BO	R88M-1L75030C-BOS2
		1 kW	R88M-1L1K030C-BO	R88M-1L1K030C-BOS2
		1.5 kW	R88M-1L1K530C-BO	R88M-1L1K530C-BOS2
		2 kW	R88M-1L2K030C-BO	R88M-1L2K030C-BOS2
		3 kW	R88M-1L3K030C-BO	R88M-1L3K030C-BOS2
		4 kW	R88M-1L4K030C-BO	R88M-1L4K030C-BOS2
		5 kW	R88M-1L5K030C-BO	R88M-1L5K030C-BOS2

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● 2,000-r/min Servomotors

Specifications			Model	
			Without oil seal	
			Straight shaft	With key and tap
Without brake	200 VAC	1 kW	R88M-1M1K020T	R88M-1M1K020T-S2
		1.5 kW	R88M-1M1K520T	R88M-1M1K520T-S2
		2 kW	R88M-1M2K020T	R88M-1M2K020T-S2
		3 kW	R88M-1M3K020T	R88M-1M3K020T-S2
	400 VAC	400 W	R88M-1M40020C	R88M-1M40020C-S2
		600 W	R88M-1M60020C	R88M-1M60020C-S2
		1 kW	R88M-1M1K020C	R88M-1M1K020C-S2
		1.5 kW	R88M-1M1K520C	R88M-1M1K520C-S2
		2 kW	R88M-1M2K020C	R88M-1M2K020C-S2
		3 kW	R88M-1M3K020C	R88M-1M3K020C-S2
With brake	200 VAC	1 kW	R88M-1M1K020T-B	R88M-1M1K020T-BS2
		1.5 kW	R88M-1M1K520T-B	R88M-1M1K520T-BS2
		2 kW	R88M-1M2K020T-B	R88M-1M2K020T-BS2
		3 kW	R88M-1M3K020T-B	R88M-1M3K020T-BS2
	400 VAC	400 W	R88M-1M40020C-B	R88M-1M40020C-BS2
		600 W	R88M-1M60020C-B	R88M-1M60020C-BS2
		1 kW	R88M-1M1K020C-B	R88M-1M1K020C-BS2
		1.5 kW	R88M-1M1K520C-B	R88M-1M1K520C-BS2
		2 kW	R88M-1M2K020C-B	R88M-1M2K020C-BS2
		3 kW	R88M-1M3K020C-B	R88M-1M3K020C-BS2

Specifications			Model	
			With oil seal	
			Straight shaft	With key and tap
Without brake	200 VAC	1 kW	R88M-1M1K020T-O	R88M-1M1K020T-OS2
		1.5 kW	R88M-1M1K520T-O	R88M-1M1K520T-OS2
		2 kW	R88M-1M2K020T-O	R88M-1M2K020T-OS2
		3 kW	R88M-1M3K020T-O	R88M-1M3K020T-OS2
	400 VAC	400 W	R88M-1M40020C-O	R88M-1M40020C-OS2
		600 W	R88M-1M60020C-O	R88M-1M60020C-OS2
		1 kW	R88M-1M1K020C-O	R88M-1M1K020C-OS2
		1.5 kW	R88M-1M1K520C-O	R88M-1M1K520C-OS2
		2 kW	R88M-1M2K020C-O	R88M-1M2K020C-OS2
		3 kW	R88M-1M3K020C-O	R88M-1M3K020C-OS2
With brake	200 VAC	1 kW	R88M-1M1K020T-BO	R88M-1M1K020T-BOS2
		1.5 kW	R88M-1M1K520T-BO	R88M-1M1K520T-BOS2
		2 kW	R88M-1M2K020T-BO	R88M-1M2K020T-BOS2
		3 kW	R88M-1M3K020T-BO	R88M-1M3K020T-BOS2
	400 VAC	400 W	R88M-1M40020C-BO	R88M-1M40020C-BOS2
		600 W	R88M-1M60020C-BO	R88M-1M60020C-BOS2
		1 kW	R88M-1M1K020C-BO	R88M-1M1K020C-BOS2
		1.5 kW	R88M-1M1K520C-BO	R88M-1M1K520C-BOS2
		2 kW	R88M-1M2K020C-BO	R88M-1M2K020C-BOS2
		3 kW	R88M-1M3K020C-BO	R88M-1M3K020C-BOS2

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● 1500-r/min Servomotors

Specifications			Model	
			Without oil seal	
			Straight shaft	With key and tap
Without brake	200 VAC	4 kW	R88M-1M4K015T	R88M-1M4K015T-S2
		5 kW	R88M-1M5K015T	R88M-1M5K015T-S2
		7.5 kW	R88M-1M7K515T	R88M-1M7K515T-S2
		11 kW	R88M-1M11K015T	R88M-1M11K015T-S2
		15 kW	R88M-1M15K015T	R88M-1M15K015T-S2
	AC400V	4 kW	R88M-1M4K015C	R88M-1M4K015C-S2
		5.5 kW	R88M-1M5K515C	R88M-1M5K515C-S2
		7.5 kW	R88M-1M7K515C	R88M-1M7K515C-S2
		11 kW	R88M-1M11K015C	R88M-1M11K015C-S2
		15 kW	R88M-1M15K015C	R88M-1M15K015C-S2
With brake	200 VAC	4 kW	R88M-1M4K015T-B	R88M-1M4K015T-BS2
		5 kW	R88M-1M5K015T-B	R88M-1M5K015T-BS2
		7.5 kW	R88M-1M7K515T-B	R88M-1M7K515T-BS2
		11 kW	R88M-1M11K015T-B	R88M-1M11K015T-BS2
		15 kW	R88M-1M15K015T-B	R88M-1M15K015T-BS2
	AC400V	4 kW	R88M-1M4K015C-B	R88M-1M4K015C-BS2
		5.5 kW	R88M-1M5K515C-B	R88M-1M5K515C-BS2
		7.5 kW	R88M-1M7K515C-B	R88M-1M7K515C-BS2
		11 kW	R88M-1M11K015C-B	R88M-1M11K015C-BS2
		15 kW	R88M-1M15K015C-B	R88M-1M15K015C-BS2

Specifications			Model	
			With oil seal	
			Straight shaft	With key and tap
Without brake	200 VAC	4 kW	R88M-1M4K015T-O	R88M-1M4K015T-OS2
		5 kW	R88M-1M5K015T-O	R88M-1M5K015T-OS2
		7.5 kW	R88M-1M7K515T-O	R88M-1M7K515T-OS2
		11 kW	R88M-1M11K015T-O	R88M-1M11K015T-OS2
		15 kW	R88M-1M15K015T-O	R88M-1M15K015T-OS2
	AC400V	4 kW	R88M-1M4K015C-O	R88M-1M4K015C-OS2
		5.5 kW	R88M-1M5K515C-O	R88M-1M5K515C-OS2
		7.5 kW	R88M-1M7K515C-O	R88M-1M7K515C-OS2
		11 kW	R88M-1M11K015C-O	R88M-1M11K015C-OS2
		15 kW	R88M-1M15K015C-O	R88M-1M15K015C-OS2
With brake	200 VAC	4 kW	R88M-1M4K015T-BO	R88M-1M4K015T-BOS2
		5 kW	R88M-1M5K015T-BO	R88M-1M5K015T-BOS2
		7.5 kW	R88M-1M7K515T-BO	R88M-1M7K515T-BOS2
		11 kW	R88M-1M11K015T-BO	R88M-1M11K015T-BOS2
		15 kW	R88M-1M15K015T-BO	R88M-1M15K015T-BOS2
	AC400V	4 kW	R88M-1M4K015C-BO	R88M-1M4K015C-BOS2
		5.5 kW	R88M-1M5K515C-BO	R88M-1M5K515C-BOS2
		7.5 kW	R88M-1M7K515C-BO	R88M-1M7K515C-BOS2
		11 kW	R88M-1M11K015C-BO	R88M-1M11K015C-BOS2
		15 kW	R88M-1M15K015C-BO	R88M-1M15K015C-BOS2

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● 1,000-r/min Servomotors

Specifications			Model	
			Without oil seal	
			Straight shaft	With key and tap
Without brake	200 VAC	900 W	R88M-1M90010T	R88M-1M90010T-S2
		2 kW	R88M-1M2K010T	R88M-1M2K010T-S2
		3 kW	R88M-1M3K010T	R88M-1M3K010T-S2
	400 VAC	900 W	R88M-1M90010C	R88M-1M90010C-S2
		2 kW	R88M-1M2K010C	R88M-1M2K010C-S2
		3 kW	R88M-1M3K010C	R88M-1M3K010C-S2
With brake	200 VAC	900 W	R88M-1M90010T-B	R88M-1M90010T-BS2
		2 kW	R88M-1M2K010T-B	R88M-1M2K010T-BS2
		3 kW	R88M-1M3K010T-B	R88M-1M3K010T-BS2
	400 VAC	900 W	R88M-1M90010C-B	R88M-1M90010C-BS2
		2 kW	R88M-1M2K010C-B	R88M-1M2K010C-BS2
		3 kW	R88M-1M3K010C-B	R88M-1M3K010C-BS2

Specifications			Model	
			With oil seal	
			Straight shaft	With key and tap
Without brake	200 VAC	900 W	R88M-1M90010T-O	R88M-1M90010T-OS2
		2 kW	R88M-1M2K010T-O	R88M-1M2K010T-OS2
		3 kW	R88M-1M3K010T-O	R88M-1M3K010T-OS2
	400 VAC	900 W	R88M-1M90010C-O	R88M-1M90010C-OS2
		2 kW	R88M-1M2K010C-O	R88M-1M2K010C-OS2
		3 kW	R88M-1M3K010C-O	R88M-1M3K010C-OS2
With brake	200 VAC	900 W	R88M-1M90010T-BO	R88M-1M90010T-BOS2
		2 kW	R88M-1M2K010T-BO	R88M-1M2K010T-BOS2
		3 kW	R88M-1M3K010T-BO	R88M-1M3K010T-BOS2
	400 VAC	900 W	R88M-1M90010C-BO	R88M-1M90010C-BOS2
		2 kW	R88M-1M2K010C-BO	R88M-1M2K010C-BOS2
		3 kW	R88M-1M3K010C-BO	R88M-1M3K010C-BOS2

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Decelerator (Backlash: 3 Arcminutes Max.)

● For 3,000-r/min Servomotors

Servomotor rated output	Reduction ratio	Model (Straight shaft) ✻
50 W	1/21	R88G-HPG14A21100B□
	1/33	R88G-HPG14A33050B□
	1/45	R88G-HPG14A45050B□
100 W	1/5	R88G-HPG11B05100B□
	1/11	R88G-HPG14A11100B□
	1/21	R88G-HPG14A21100B□
	1/33	R88G-HPG20A33100B□
	1/45	R88G-HPG20A45100B□
200 W	1/5	R88G-HPG14A05200B□
	1/11	R88G-HPG14A11200B□
	1/21	R88G-HPG20A21200B□
	1/33	R88G-HPG20A33200B□
	1/45	R88G-HPG20A45200B□
400 W	1/5	R88G-HPG14A05400B□
	1/11	R88G-HPG20A11400B□
	1/21	R88G-HPG20A21400B□
	1/33	R88G-HPG32A33400B□
	1/45	R88G-HPG32A45400B□
750 W (200 V)	1/5	R88G-HPG20A05750B□
	1/11	R88G-HPG20A11750B□
	1/21	R88G-HPG32A21750B□
	1/33	R88G-HPG32A33750B□
	1/45	R88G-HPG32A45750B□
750 W (400 V)	1/5	R88G-HPG32A052K0B□
	1/11	R88G-HPG32A112K0B□
	1/21	R88G-HPG32A211K5B□
	1/33	R88G-HPG32A33600SB□
	1/45	R88G-HPG50A451K5B□
1 kW	1/5	R88G-HPG32A052K0B□
	1/11	R88G-HPG32A112K0B□
	1/21	R88G-HPG32A211K5B□
	1/33	R88G-HPG50A332K0B□
	1/45	R88G-HPG50A451K5B□
1.5 kW	1/5	R88G-HPG32A052K0B□
	1/11	R88G-HPG32A112K0B□
	1/21	R88G-HPG32A211K5B□
	1/33	R88G-HPG50A332K0B□
	1/45	R88G-HPG50A451K5B□
2 kW	1/5	R88G-HPG32A052K0B□
	1/11	R88G-HPG32A112K0B□
	1/21	R88G-HPG50A212K0B□
	1/33	R88G-HPG50A332K0B□
3 kW	1/5	R88G-HPG32A053K0B□
	1/11	R88G-HPG50A113K0B□
	1/21	R88G-HPG50A213K0B□
4 kW	1/5	R88G-HPG32A054K0B□
	1/11	R88G-HPG50A115K0B□
4.7 kW 5 kW	1/5	R88G-HPG50A055K0B□
	1/11	R88G-HPG50A115K0B□

✻ The standard shaft type is a straight shaft. A model with a key and tap is indicated with "J" at □ of the Decelerator model number.
e.g. R88G-HPG11B05100BJ

● For 2,000-r/min Servomotors

Servomotor rated output	Reduction ratio	Model (Straight shaft) ✻
400 W	1/5	R88G-HPG32A052K0B□
	1/11	R88G-HPG32A112K0B□
	1/21	R88G-HPG32A211K5B□
	1/33	R88G-HPG32A33600SB□
	1/45	R88G-HPG32A45400SB□
600 W	1/5	R88G-HPG32A052K0B□
	1/11	R88G-HPG32A112K0B□
	1/21	R88G-HPG32A211K5B□
	1/33	R88G-HPG32A33600SB□
	1/45	R88G-HPG50A451K5B□
1 kW	1/5	R88G-HPG32A053K0B□
	1/11	R88G-HPG32A112K0SB□
	1/21	R88G-HPG32A211K0SB□
	1/33	R88G-HPG50A332K0SB□
	1/45	R88G-HPG50A451K0SB□
1.5 kW	1/5	R88G-HPG32A053K0B□
	1/11	R88G-HPG32A112K0SB□
	1/21	R88G-HPG50A213K0B□
	1/33	R88G-HPG50A332K0SB□
2 kW	1/5	R88G-HPG32A053K0B□
	1/11	R88G-HPG32A112K0SB□
	1/21	R88G-HPG50A213K0B□
	1/33	R88G-HPG50A332K0SB□
3 kW	1/5	R88G-HPG32A054K0B□
	1/11	R88G-HPG50A115K0B□
	1/21	R88G-HPG50A213K0SB□
	1/25	R88G-HPG65A253K0SB□

✻ The standard shaft type is a straight shaft. A model with a key and tap is indicated with "J" at □ of the Decelerator model number.
e.g. R88G-HPG11B05100BJ

● For 1,500-r/min Servomotors

Servomotor rated output	Reduction ratio	Model (Straight shaft) ✻
4 kW	1/5	R88G-HPG50A055K0SB□
	1/11	R88G-HPG50A115K0SB□
	1/21	R88G-HPG65A205K0SB□
	1/25	R88G-HPG65A255K0SB□
5 kW 5.5 kW	1/5	R88G-HPG50A054K5TB□
	1/12	R88G-HPG65A127K5SB□
	1/20	R88G-HPG65A204K5TB□

✻ The standard shaft type is a straight shaft. A model with a key and tap is indicated with "J" at □ of the Decelerator model number.
e.g. R88G-HPG11B05100BJ

● For 1,000-r/min Servomotors

Servomotor rated output	Reduction ratio	Model (Straight shaft) ✻
900 W	1/5	R88G-HPG32A05900TB□
	1/11	R88G-HPG32A11900TB□
	1/21	R88G-HPG50A21900TB□
	1/33	R88G-HPG50A33900TB□
2 kW	1/5	R88G-HPG32A052K0TB□
	1/11	R88G-HPG50A112K0TB□
	1/21	R88G-HPG50A212K0TB□
	1/25	R88G-HPG65A255K0SB□
3 kW	1/5	R88G-HPG50A055K0SB□
	1/11	R88G-HPG50A115K0SB□
	1/20	R88G-HPG65A205K0SB□
	1/25	R88G-HPG65A255K0SB□

✻ The standard shaft type is a straight shaft. A model with a key and tap is indicated with "J" at □ of the Decelerator model number.
e.g. R88G-HPG11B05100BJ

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Decelerator (Backlash: 15 Arcminutes Max.)

● For 3,000-r/min Servomotors

Servomotor rated output	Reduction ratio	Model
50 W	1/5	R88G-VRXF05B100CJ
	1/9	R88G-VRXF09B100CJ
	1/15	R88G-VRXF15B100CJ
	1/25	R88G-VRXF25B100CJ
100 W	1/5	R88G-VRXF05B100CJ
	1/9	R88G-VRXF09B100CJ
	1/15	R88G-VRXF15B100CJ
	1/25	R88G-VRXF25B100CJ
200 W	1/5	R88G-VRXF05B200CJ
	1/9	R88G-VRXF09C200CJ
	1/15	R88G-VRXF15C200CJ
	1/25	R88G-VRXF25C200CJ
400 W	1/5	R88G-VRXF05C400CJ
	1/9	R88G-VRXF09C400CJ
	1/15	R88G-VRXF15C400CJ
	1/25	R88G-VRXF25C400CJ
750 W (200 V)	1/5	R88G-VRXF05C750CJ
	1/9	R88G-VRXF09D750CJ
	1/15	R88G-VRXF15D750CJ
	1/25	R88G-VRXF25D750CJ

Cables and Peripheral Devices

Encoder Cables (Standard Cable)

Applicable Servomotor			Model
100 V 200 V	3,000-r/min Servomotors of 50W, 100 W, 200 W, 400 W, and 750 W	3 m	R88A-CR1A003C
		5 m	R88A-CR1A005C
		10 m	R88A-CR1A010C
		15 m	R88A-CR1A015C
		20 m	R88A-CR1A020C
		30 m	R88A-CR1A030C
		40 m	R88A-CR1A040C
		50 m	R88A-CR1A050C
200 V 400 V	200 V: 3000-r/min Servomotors of 1 to 3 kW 2000-r/min Servomotors 1000-r/min Servomotors 400 V: 3000-r/min Servomotors of 3 kW or less 2000-r/min Servomotors 1000-r/min Servomotors	3 m	R88A-CR1B003N
		5 m	R88A-CR1B005N
		10 m	R88A-CR1B010N
		15 m	R88A-CR1B015N
		20 m	R88A-CR1B020N
		30 m	R88A-CR1B030N
		40 m	R88A-CR1B040N
		50 m	R88A-CR1B050N
200 V 400 V	3000-r/min Servomotors of 4 kW or more 1500-r/min Servomotors	3 m	R88A-CR1B003V
		5 m	R88A-CR1B005V
		10 m	R88A-CR1B010V
		15 m	R88A-CR1B015V
		20 m	R88A-CR1B020V
		30 m	R88A-CR1B030V
		40 m	R88A-CR1B040V
		50 m	R88A-CR1B050V

Brake Cables (Standard Cable)

Applicable Servomotor			Model
100 V 200 V	3,000-r/min Servomotors of 100 W, 200 W, 400 W, and 750 W ✻	3 m	R88A-CA1A003B
		5 m	R88A-CA1A005B
		10 m	R88A-CA1A010B
		15 m	R88A-CA1A015B
		20 m	R88A-CA1A020B
		30 m	R88A-CA1A030B
		40 m	R88A-CA1A040B
		50 m	R88A-CA1A050B

✻ The Servomotors of 50 W are exempt from the applicable Servomotors. Use these combinations with caution.

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Motor Power Cables (Standard Cable)

Applicable Servomotor			Without brake wire	With brake wire
			Model	Model
100 V 200 V	3,000-r/min Servomotors of 100 W, 200 W, 400 W, and 750 W ✻	3 m	R88A-CA1A003S	---
		5 m	R88A-CA1A005S	---
		10 m	R88A-CA1A010S	---
		15 m	R88A-CA1A015S	---
		20 m	R88A-CA1A020S	---
		30 m	R88A-CA1A030S	---
		40 m	R88A-CA1A040S	---
		50 m	R88A-CA1A050S	---
200 V	3,000-r/min Servomotors of 1 kW 2,000-r/min Servomotors of 1 kW 1,000-r/min Servomotors of 900 W	3 m	R88A-CA1B003S	R88A-CA1B003B
		5 m	R88A-CA1B005S	R88A-CA1B005B
		10 m	R88A-CA1B010S	R88A-CA1B010B
		15 m	R88A-CA1B015S	R88A-CA1B015B
		20 m	R88A-CA1B020S	R88A-CA1B020B
		30 m	R88A-CA1B030S	R88A-CA1B030B
		40 m	R88A-CA1B040S	R88A-CA1B040B
		50 m	R88A-CA1B050S	R88A-CA1B050B
200 V	3,000-r/min Servomotors of 1.5 kW 2,000-r/min Servomotors of 1.5 kW	3 m	R88A-CA1C003S	R88A-CA1C003B
		5 m	R88A-CA1C005S	R88A-CA1C005B
		10 m	R88A-CA1C010S	R88A-CA1C010B
		15 m	R88A-CA1C015S	R88A-CA1C015B
		20 m	R88A-CA1C020S	R88A-CA1C020B
		30 m	R88A-CA1C030S	R88A-CA1C030B
		40 m	R88A-CA1C040S	R88A-CA1C040B
		50 m	R88A-CA1C050S	R88A-CA1C050B
400 V	3,000-r/min Servomotors of 750 W, 1 kW, 1.5 kW, and 2 kW 2,000-r/min Servomotors of 400 W, 600 W, 1 kW, 1.5 kW, and 2 kW 1,000-r/min Servomotors of 900 W	3 m	R88A-CA1C003S	R88A-CA1D003B
		5 m	R88A-CA1C005S	R88A-CA1D005B
		10 m	R88A-CA1C010S	R88A-CA1D010B
		15 m	R88A-CA1C015S	R88A-CA1D015B
		20 m	R88A-CA1C020S	R88A-CA1D020B
		30 m	R88A-CA1C030S	R88A-CA1D030B
		40 m	R88A-CA1C040S	R88A-CA1D040B
		50 m	R88A-CA1C050S	R88A-CA1D050B
200 V 400 V	3,000-r/min Servomotors of 2 kW (200 V) and 3 kW (200 V/400 V) 2,000-r/min Servomotors of 2 kW (200 V) and 3 kW (200 V/400 V) 1,000-r/min Servomotors of 2 kW (200 V/400 V) and 3 kW (400 V)	3 m	R88A-CA1E003S	R88A-CA1E003B
		5 m	R88A-CA1E005S	R88A-CA1E005B
		10 m	R88A-CA1E010S	R88A-CA1E010B
		15 m	R88A-CA1E015S	R88A-CA1E015B
		20 m	R88A-CA1E020S	R88A-CA1E020B
		30 m	R88A-CA1E030S	R88A-CA1E030B
		40 m	R88A-CA1E040S	R88A-CA1E040B
		50 m	R88A-CA1E050S	R88A-CA1E050B
200 V	1,000-r/min Servomotors of 3 kW	3 m	R88A-CA1F003S	R88A-CA1F003B
		5 m	R88A-CA1F005S	R88A-CA1F005B
		10 m	R88A-CA1F010S	R88A-CA1F010B
		15 m	R88A-CA1F015S	R88A-CA1F015B
		20 m	R88A-CA1F020S	R88A-CA1F020B
		30 m	R88A-CA1F030S	R88A-CA1F030B
		40 m	R88A-CA1F040S	R88A-CA1F040B
		50 m	R88A-CA1F050S	R88A-CA1F050B

✻ The Servomotors of 50 W are exempt from the applicable Servomotors. Use these combinations with caution.

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Encoder Cables (Flexible Cable)

Applicable Servomotor			Model
100 V 200 V	3,000-r/min Servomotors of 50W, 100 W, 200 W, 400 W, and 750 W	3 m	R88A-CR1A003CF
		5 m	R88A-CR1A005CF
		10 m	R88A-CR1A010CF
		15 m	R88A-CR1A015CF
		20 m	R88A-CR1A020CF
		30 m	R88A-CR1A030CF
		40 m	R88A-CR1A040CF
		50 m	R88A-CR1A050CF
200 V 400 V	200 V: 3000-r/min Servomotors of 1 to 3 kW 2000-r/min Servomotors 1000-r/min Servomotors 400V: 3000-r/min Servomotors of 3 kW or less 2000-r/min Servomotors 1000-r/min Servomotors	3 m	R88A-CR1B003NF
		5 m	R88A-CR1B005NF
		10 m	R88A-CR1B010NF
		15 m	R88A-CR1B015NF
		20 m	R88A-CR1B020NF
		30 m	R88A-CR1B030NF
		40 m	R88A-CR1B040NF
		50 m	R88A-CR1B050NF
200 V 400 V	3000-r/min Servomotors of 4 kW or more 1500-r/min Servomotors	3 m	R88A-CR1B003VF
		5 m	R88A-CR1B005VF
		10 m	R88A-CR1B010VF
		15 m	R88A-CR1B015VF
		20 m	R88A-CR1B020VF
		30 m	R88A-CR1B030VF
		40 m	R88A-CR1B040VF
		50 m	R88A-CR1B050VF

Brake Cables (Flexible Cable)

Applicable Servomotor			Model
100 V 200 V	3,000-r/min Servomotors of 100 W, 200 W, 400 W, and 750 W ✻	3 m	R88A-CA1A003BF
		5 m	R88A-CA1A005BF
		10 m	R88A-CA1A010BF
		15 m	R88A-CA1A015BF
		20 m	R88A-CA1A020BF
		30 m	R88A-CA1A030BF
		40 m	R88A-CA1A040BF
		50 m	R88A-CA1A050BF

✻ The Servomotors of 50 W are exempt from the applicable Servomotors. Use these combinations with caution.

Motor Power Cables (Flexible Cable)

Applicable Servomotor			Without brake wire	With brake wire
			Model	Model
100 V 200 V	3,000-r/min Servomotors of 100 W, 200 W, 400 W, and 750 W ✻	3 m	R88A-CA1A003SF	---
		5 m	R88A-CA1A005SF	---
		10 m	R88A-CA1A010SF	---
		15 m	R88A-CA1A015SF	---
		20 m	R88A-CA1A020SF	---
		30 m	R88A-CA1A030SF	---
		40 m	R88A-CA1A040SF	---
		50 m	R88A-CA1A050SF	---
200 V	3,000-r/min Servomotors of 1 kW 2,000-r/min Servomotors of 1 kW 1,000-r/min Servomotors of 900 W	3 m	R88A-CA1B003SF	R88A-CA1B003BF
		5 m	R88A-CA1B005SF	R88A-CA1B005BF
		10 m	R88A-CA1B010SF	R88A-CA1B010BF
		15 m	R88A-CA1B015SF	R88A-CA1B015BF
		20 m	R88A-CA1B020SF	R88A-CA1B020BF
		30 m	R88A-CA1B030SF	R88A-CA1B030BF
		40 m	R88A-CA1B040SF	R88A-CA1B040BF
		50 m	R88A-CA1B050SF	R88A-CA1B050BF
200 V	3,000-r/min Servomotors of 1.5 kW 2,000-r/min Servomotors of 1.5 kW	3 m	R88A-CA1C003SF	R88A-CA1C003BF
		5 m	R88A-CA1C005SF	R88A-CA1C005BF
		10 m	R88A-CA1C010SF	R88A-CA1C010BF
		15 m	R88A-CA1C015SF	R88A-CA1C015BF
		20 m	R88A-CA1C020SF	R88A-CA1C020BF
		30 m	R88A-CA1C030SF	R88A-CA1C030BF
		40 m	R88A-CA1C040SF	R88A-CA1C040BF
		50 m	R88A-CA1C050SF	R88A-CA1C050BF

✻ The Servomotors of 50 W are exempt from the applicable Servomotors. Use these combinations with caution.

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Applicable Servomotor			Without brake wire	With brake wire
			Model	Model
400 V	3,000-r/min Servomotors of 750 W, 1 kW, 1.5 kW, and 2 kW 2,000-r/min Servomotors of 400 W, 600 W, 1 kW, 1.5 kW, and 2 kW 1,000-r/min Servomotors of 900 W	3 m	R88A-CA1C003SF	R88A-CA1D003BF
		5 m	R88A-CA1C005SF	R88A-CA1D005BF
		10 m	R88A-CA1C010SF	R88A-CA1D010BF
		15 m	R88A-CA1C015SF	R88A-CA1D015BF
		20 m	R88A-CA1C020SF	R88A-CA1D020BF
		30 m	R88A-CA1C030SF	R88A-CA1D030BF
		40 m	R88A-CA1C040SF	R88A-CA1D040BF
		50 m	R88A-CA1C050SF	R88A-CA1D050BF
200 V 400 V	3,000-r/min Servomotors of 2 kW (200 V) and 3 kW (200 V/400 V) 2,000-r/min Servomotors of 2 kW (200 V) and 3 kW (200 V/400 V) 1,000-r/min Servomotors of 2 kW (200 V/400 V) and 3 kW (400 V)	3 m	R88A-CA1E003SF	R88A-CA1E003BF
		5 m	R88A-CA1E005SF	R88A-CA1E005BF
		10 m	R88A-CA1E010SF	R88A-CA1E010BF
		15 m	R88A-CA1E015SF	R88A-CA1E015BF
		20 m	R88A-CA1E020SF	R88A-CA1E020BF
		30 m	R88A-CA1E030SF	R88A-CA1E030BF
		40 m	R88A-CA1E040SF	R88A-CA1E040BF
		50 m	R88A-CA1E050SF	R88A-CA1E050BF
200 V	The Servomotors of 50 W are exempt from the applicable Servomotors. Use these combination	3 m	R88A-CA1F003SF	R88A-CA1F003BF
		5 m	R88A-CA1F005SF	R88A-CA1F005BF
		10 m	R88A-CA1F010SF	R88A-CA1F010BF
		15 m	R88A-CA1F015SF	R88A-CA1F015BF
		20 m	R88A-CA1F020SF	R88A-CA1F020BF
		30 m	R88A-CA1F030SF	R88A-CA1F030BF
		40 m	R88A-CA1F040SF	R88A-CA1F040BF
		50 m	R88A-CA1F050SF	R88A-CA1F050BF
200 V 400 V	200 V: 3000 r/min Servomotors of 4 kW, 4.7 kW 1500 r/min Servomotors of 4 kW, 5 kW 400 V: 3000 r/min Servomotors of 4 kW, 5 kW 1500 r/min Servomotors of 4 kW, 5.5 kW, 7.5 kW	3 m	R88A-CA1H003SF	R88A-CA1H003BF
		5 m	R88A-CA1H005SF	R88A-CA1H005BF
		10 m	R88A-CA1H010SF	R88A-CA1H010BF
		15 m	R88A-CA1H015SF	R88A-CA1H015BF
		20 m	R88A-CA1H020SF	R88A-CA1H020BF
400 V	1500 r/min Servomotors of 11 kW, 15 kW	3 m	R88A-CA1J003SF	R88A-CA1J003BF
		5 m	R88A-CA1J005SF	R88A-CA1J005BF
		10 m	R88A-CA1J010SF	R88A-CA1J010BF
		15 m	R88A-CA1J015SF	R88A-CA1J015BF
		20 m	R88A-CA1J020SF	R88A-CA1J020BF
200 V	1500 r/min Servomotors of 7.5 kW, 11 kW, 15 kW	3 m	R88A-CA1K003SF	R88A-CA1K003BF
		5 m	R88A-CA1K005SF	R88A-CA1K005BF
		10 m	R88A-CA1K010SF	R88A-CA1K010BF
		15 m	R88A-CA1K015SF	R88A-CA1K015BF
		20 m	R88A-CA1K020SF	R88A-CA1K020BF

Brake Cables (Non-load side, Flexible Cable)

When you use the brake cable with cable on non-load side such as R88A-CA1A□□□BFR, use it in combination with the motor power cable with cable on non-load side such as R88A-CA1A□□□SFR.

Applicable Servomotor			Model
100 V 200 V	3000-r/min Servomotors of 50 W, 200 W, 400 W, 750 W ✻	3 m	R88A-CA1A003BFR
		5 m	R88A-CA1A005BFR
		10 m	R88A-CA1A010BFR
		15 m	R88A-CA1A015BFR
		20 m	R88A-CA1A020BFR
		30 m	R88A-CA1A030BFR
		40 m	R88A-CA1A040BFR
		50 m	R88A-CA1A050BFR

✻ The Servomotors of 100 W are exempt from the applicable Servomotors. Use these combinations with caution.

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Motor Power Cables (Non-load side, Flexible Cable)

When you use the motor power cable with cable on non-load side such as R88A-CA1A□□□SFR and the brake cable together, use the brake cable with cable on non-load side such as R88A-CA1A□□□BFR.

Applicable Servomotor			Without brake wire	With brake wire
			Model	Model
100 V 200 V	3000-r/min Servomotors of 50 W, 200 W, 400 W, 750 W ✻	3 m	R88A-CA1A003SFR	---
		5 m	R88A-CA1A005SFR	---
		10 m	R88A-CA1A010SFR	---
		15 m	R88A-CA1A015SFR	---
		20 m	R88A-CA1A020SFR	---
		30 m	R88A-CA1A030SFR	---
		40 m	R88A-CA1A040SFR	---
		50 m	R88A-CA1A050SFR	---

✻ The Servomotors of 100 W are exempt from the applicable Servomotors. Use these combinations with caution.

Extension Power Cable

Use the cables listed below to extend the motor power cable either with or without brake wire for a servomotor of 4 kW or more.

Applicable Servomotor			Model
200 V 400 V	200 V: 3000 r/min Servomotors of 4 kW, 4.7 kW 1500 r/min Servomotors of 4 kW, 5 kW 400 V: 3000 r/min Servomotors of 4 kW, 5 kW 1500 r/min Servomotors of 4 kW, 5.5 kW, 7.5 kW	10 m	R88A-CA1HE10BF
		20 m	R88A-CA1HE20BF
400 V	1500r/min Servomotors of 11kW, 15kW	10 m	R88A-CA1JE10BF
		20 m	R88A-CA1JE20BF
200 V	1500r/min Servomotors of 7.5kW, 11kW, 15kW	10 m	R88A-CA1KE10BF
		20 m	R88A-CA1KE20BF

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Recommended EtherCAT Communications Cable

Use a straight STP (shielded twisted-pair) cable of category 5 or higher with double shielding (braiding and aluminum foil tape) for EtherCAT.

Cabel with Connectors

Item	Appearance	Recommended manufacturer	Cable length [m]	Model
Cable with Connectors on Both Ends (RJ45/RJ45) Standard RJ45 plugs type ✻1 Wire gauge and number of pairs: AWG26, 4-pair cable Cable sheath material: PUR Cable color: Yellow ✻2		OMRON	0.3	XS6W-6PUR8SS30CM-YF
			0.5	XS6W-6PUR8SS50CM-YF
			1	XS6W-6PUR8SS100CM-YF
			2	XS6W-6PUR8SS200CM-YF
			3	XS6W-6PUR8SS300CM-YF
			5	XS6W-6PUR8SS500CM-YF
Cable with Connectors on Both Ends (RJ45/RJ45) Rugged RJ45 plugs type ✻1 Wire gauge and number of pairs: AWG22, 2-pair cable Cable color: Light blue		OMRON	0.3	XS5W-T421-AMD-K
			0.5	XS5W-T421-BMD-K
			1	XS5W-T421-CMD-K
			2	XS5W-T421-DMD-K
			5	XS5W-T421-GMD-K
			10	XS5W-T421-JMD-K
Cable with Connectors on Both Ends (M12 Straight/RJ45) Shield Strengthening Connector cable ✻3 M12/Smartclick Connectors Rugged RJ45 plugs type Wire Gauge and Number of Pairs: AWG22, 2-pair cable Cable color: Black		OMRON	0.5	XS5W-T421-BMC-SS
			1	XS5W-T421-CMC-SS
			2	XS5W-T421-DMC-SS
			3	XS5W-T421-EMC-SS
			5	XS5W-T421-GMC-SS
			10	XS5W-T421-JMC-SS

✻1. Standard type cables length 0.2, 0.3, 0.5, 1, 1.5, 2, 3, 5, 7.5, 10, 15 and 20 m are available.
Rugged type cables length 0.3, 0.5, 1, 2, 3, 5, 10 and 15 m are available.
For details, refer to Cat.No.G019.
✻2. Cables colors are available in blue, yellow, or Green.
✻3. For details, contact your OMRON representative.

Cables/Connectors
Wire Gauge and Number of Pairs: AWG24, 4-pair Cable

Item	Appearance	Recommended manufacturer	Model
Cables	---	Kuramo Electric Co.	KETH-SB ✻
RJ45 Connectors	---	Panduit Corporation	MPS588-C ✻

✻ We recommend you to use above cable and connector together.

Wire Gauge and Number of Pairs: AWG22, 2-pair Cable

Item	Appearance	Recommended manufacturer	Model
Cables	---	Kuramo Electric Co.	KETH-PSB-OMR ✻
	---	JMACS Japan Co., Ltd.	PNET/B ✻
RJ45 Assembly Connector		OMRON	XS6G-T421-1 ✻

✻ We recommend you to use above cable and connector together.

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Peripheral Connector

Servo Drive Side Connectors

One of each of servo drive side connectors (except the encoder connector) are included with the R88D-1SN□-ECT AC Servo Drive.
All connecters are also available separately for maintenance.

Name and applications	Model
Main circuit connector (CNA) ✻1 For R88D-1SN01L-ECT/-1SN02L-ECT/-1SN04L-ECT/-1SN01H-ECT/-1SN02H-ECT/-1SN04H-ECT/-1SN08H-ECT/-1SN10H-ECT	R88A-CN102P ✻4
Main circuit connector A (CNA) ✻2 For R88D-1SN15H-ECT/-1SN20H-ECT/-1SN30H-ECT/-1SN06F-ECT/-1SN10F-ECT/-1SN15F-ECT/-1SN20F-ECT/-1SN30F-ECT	R88A-CN103P ✻4
Main circuit connector A (CNA) ✻2 For R88D-1SN55H-ECT/-1SN75H-ECT/-1SN55F-ECT/-1SN75F-ECT	R88A-CN106P
Main circuit connector A (CNA) For R88D-1SN150F-ECT	R88A-CN108P
Main circuit connector B (CNB) ✻2 For R88D-1SN15H-ECT/-1SN20H-ECT/-1SN30H-ECT/-1SN06F-ECT/-1SN10F-ECT/-1SN15F-ECT/-1SN20F-ECT/-1SN30F-ECT	R88A-CN104P ✻4
Main circuit connector B (CNB) ✻2 For R88D-1SN55H-ECT/-1SN75H-ECT/-1SN55F-ECT/-1SN75F-ECT	R88A-CN107P
Main circuit connector B (CNB) For R88D-1SN150H-ECT/-1SN150F-ECT	R88A-CN101E
Motor connector (CNC) For R88D-1SN01L-ECT/-1SN02L-ECT/-1SN04L-ECT/-1SN01H-ECT/-1SN02H-ECT/-1SN04H-ECT/-1SN08H-ECT/-1SN10H-ECT	R88A-CN101A ✻4
Motor connector (CNC) For R88D-1SN15H-ECT/-1SN20H-ECT/-1SN30H-ECT/-1SN06F-ECT/-1SN10F-ECT/-1SN15F-ECT/-1SN20F-ECT/-1SN30F-ECT	R88A-CN102A ✻4
Motor connector (CNC) For R88D-1SN55H-ECT/-1SN75H-ECT/-1SN55F-ECT/-1SN75F-ECT/-1SN150F-ECT	R88A-CN103A
Control power supply connector (CND) For R88D-1SN15H-ECT/-1SN20H-ECT/-1SN30H-ECT/-1SN06F-ECT/-1SN10F-ECT/-1SN15F-ECT/-1SN20F-ECT/-1SN30F-ECT	R88A-CN101P ✻4
Control power supply connector (CND) For R88D-1SN55H-ECT/-1SN75H-ECT/-1SN150H-ECT/-1SN55F-ECT/-1SN75F-ECT/-1SN150F-ECT	R88A-CN105P
Main circuit connector E (CNE) ✻2 For R88D-1SN55H-ECT/-1SN75H-ECT/-1SN150H-ECT/-1SN55F-ECT/-1SN75F-ECT/-1SN150F-ECT	R88A-CN101D
Control I/O connector (CN1) ✻3	R88A-CN101C
Encoder connector (CN2)	R88A-CN101R
Brake interlock connector (CN12)	R88A-CN101B

✻1. Two short-circuit wires are connected to the connector.
✻2. One short-circuit wire is connected to the connector.
✻3. Four short-circuit wires are connected to the connector.
✻4. One opener is included.

Servomotor Side Connector

Applicable Servo Drive and Power Cables			Model
Encoder connector	100 V, 200 V	For 3,000 r/min (50 to 750 W)	R88A-CNK02R
	200 V	For 3000 r/min (1 kW to 3 kW), 2000 r/min, 1000 r/min	R88A-CN104R
	400 V	For 3000 r/min (750 kW to 3 kW), 2000 r/min, 1000 r/min	
	200 V, 400 V	For 3000 r/min (4 kW to 5 kW), 1500 r/min	R88A-CN105R
Power connector (For 750 W max.) ✻			R88A-CN111A
Brake connector (For 750 W max.)			R88A-CN111B

✻ This connector is used for power cables with cable on load side such as R88A-CA1A□□□S and R88A-CA1A□SF. This connector cannot be used for power cables with cable on non-load side such as R88A-CA1A□SFR.

External Regeneration Resistance Unit Connector

Name and applications	Model
External Regeneration Resistance Unit Connector For R88A-RR550□	R88A-CN101E ✻

✻ Same connector as main circuit connector B (CNB) for R88D-1SN150H-ECT/-1SN150F-ECT.

Shield Clamp Bracket

A shield clamp is used for fixing a power cable and connecting a shield wire of the power cable with FG in Servo Drives.
The shield clamp consists of the shield clamp bracket and shield clamp plate.

Name	Applicable Servo Drive and Power Cables		Model
Shield Clamp Bracket	R88D-1SN55□-ECT R88D-1SN75F-ECT	R88A-CA1H□□□□F	R88A-SC10CA
	R88D-1SN150F-ECT	R88A-CA1J□□□□F	
	R88D-1SN75H-ECT R88D-1SN150H-ECT	R88A-CA1K□□□□F	

Note: An applicable power cable comes with a shield clamp bracket.
An extension cable does not come with a shield clamp bracket.

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External Regeneration Resistors

Applicable Servo Drive	Specifications	Model
R88D-1SN01L-ECT/-1SN02L-ECT	Regeneration process capacity: 24 W, 15 Ω	R88A-RR12015
R88D-1SN01H-ECT/-1SN02H-ECT	Regeneration process capacity: 24 W, 25 Ω	R88A-RR12025
R88D-1SN150H-ECT	Regeneration process capacity: 60 W, 2.5 Ω	R88A-RR30002R5
R88D-1SN75H-ECT	Regeneration process capacity: 60 W, 4 Ω	R88A-RR30004
R88D-1SN55H-ECT	Regeneration process capacity: 60 W, 5.4 Ω	R88A-RR30005R4
R88D-1SN20H-ECT/-1SN30H-ECT/-1SN150F-ECT	Regeneration process capacity: 60 W, 10 Ω	R88A-RR30010
R88D-1SN01L-ECT/-1SN02L-ECT	Regeneration process capacity: 60 W, 15 Ω	R88A-RR30015
R88D-1SN55F-ECT/-1SN75F-ECT	Regeneration process capacity: 60 W, 16 Ω	R88A-RR30016
R88D-1SN15H-ECT	Regeneration process capacity: 60 W, 17 Ω	R88A-RR30017
R88D-1SN04L-ECT/-1SN08H-ECT/-1SN10H-ECT/ -1SN20F-ECT ✻/-1SN30F-ECT ✻	Regeneration process capacity: 60 W, 20 Ω	R88A-RR30020
R88D-1SN01H-ECT/-1SN02H-ECT/-1SN04H-ECT	Regeneration process capacity: 60 W, 25 Ω	R88A-RR30025
R88D-1SN06F-ECT ✻/-1SN10F-ECT ✻/-1SN15F-ECT ✻	Regeneration process capacity: 60 W, 33 Ω	R88A-RR30033

✻ Use two series-connected External Regeneration Resistors for this model.

External Regeneration Resistance Unit

Applicable Servo Drive	Specifications	Model
R88D-1SN150H-ECT	Regeneration process capacity: 120 W, 2.5 Ω	R88A-RR55002R5
R88D-1SN75H-ECT	Regeneration process capacity: 120W, 4 Ω	R88A-RR55004
R88D-1SN55H-ECT	Regeneration process capacity: 120W, 5.4 Ω	R88A-RR55005R4
R88D-1SN150F-ECT	Regeneration process capacity: 120W, 10 Ω	R88A-RR55010
R88D-1SN55F-ECT/-1SN75F-ECT	Regeneration process capacity: 120W, 16 Ω	R88A-RR55016
R88D-1SN150H-ECT	Regeneration process capacity: 640W, 2.5 Ω (with fan)	R88A-RR1K602R5
R88D-1SN75H-ECT	Regeneration process capacity: 640W, 4 Ω (with fan)	R88A-RR1K604
R88D-1SN55H-ECT	Regeneration process capacity: 640W, 5.4 Ω (with fan)	R88A-RR1K605R4
R88D-1SN20H-ECT/-1SN30H-ECT	Regeneration process capacity: 640 W, 10 Ω (with fan)	R88A-RR1K610
R88D-1SN55F-ECT/-1SN75F-ECT/-1SN150F-ECT	Regeneration process capacity: 640 W, 16 Ω (with fan)	R88A-RR1K616
R88D-1SN15H-ECT	Regeneration process capacity: 640 W, 17 Ω (with fan)	R88A-RR1K617
R88D-1SN08H-ECT/-1SN10H-ECT/-1SN20F-ECT ✻/ -1SN30F-ECT ✻/-1SN55F-ECT ✻	Regeneration process capacity: 640 W, 20 Ω (with fan)	R88A-RR1K620
R88D-1SN20F-ECT/-1SN30F-ECT	Regeneration process capacity: 640 W, 40 Ω (with fan)	R88A-RR1K640
R88D-1SN06F-ECT/-1SN10F-ECT/-1SN15F-ECT	Regeneration process capacity: 640 W, 66 Ω (with fan)	R88A-RR1K666

✻ Use two series-connected External Regeneration Resistance Units for this model.

External Dynamic Brake Resistors

Applicable Servomotor	Specifications	Model
R88D-1SN150H-ECT	Resistance value: 1.25 Ω	R88A-DBR30001R2
R88D-1SN55H-ECT/-1SN75H-ECT	Resistance value: 1.5 Ω	R88A-DBR30001R5
R88D-1SN55F-ECT/-1SN75F-ECT	Resistance value: 4 Ω	R88A-DBR30004
R88D-1SN150F-ECT	Resistance value: 5 Ω	R88A-DBR30005

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DC Reactor

For a recommended reactor for applicable Servomotor at 5.5 kW or more, refer to the *AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications User's Manual* (Cat. No. I586).

Applicable Servomotor	Model
R88D-1SN01L-ECT/-1SN01H-ECT/-1SN02H-ECT	R88A-PD2002
R88D-1SN02L-ECT/-1SN04H-ECT	R88A-PD2004
R88D-1SN04L-ECT/-1SN08H-ECT	R88A-PD2007
R88D-1SN10H-ECT/-1SN15H-ECT	R88A-PD2015
R88D-1SN20H-ECT	R88A-PD2022
R88D-1SN30H-ECT	R88A-PD2037
R88D-1SN06F-ECT	R88A-PD4007
R88D-1SN10F-ECT/-1SN15F-ECT	R88A-PD4015
R88D-1SN20F-ECT	R88A-PD4022
R88D-1SN30F-ECT	R88A-PD4037

Footprint-type Noise Filter

For a recommended noise filter for applicable Servomotor at 5.5 kW or more, refer to the *AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications User's Manual* (Cat. No. I586).

Applicable Servo Drive	Model
R88D-1SN01L-ECT/-1SN01H-ECT/-1SN02H-ECT (Single-phase input)	R88A-FI1S103
R88D-1SN02L-ECT/-1SN04H-ECT (Single-phase input)	R88A-FI1S105
R88D-1SN04L-ECT/-1SN08H-ECT (Single-phase input)	R88A-FI1S109
R88D-1SN15H-ECT (Single-phase input)	R88A-FI1S116
R88D-1SN01H-ECT/-1SN02H-ECT (3-phase input)	R88A-FI1S202
	R88A-FI1S203
R88D-1SN04H-ECT (3-phase input)	R88A-FI1S203
R88D-1SN08H-ECT (3-phase input)/-1SN10H-ECT	R88A-FI1S208
R88D-1SN15H-ECT (3-phase input)/-1SN20H-ECT/-1SN30H-ECT	R88A-FI1S216
R88D-1SN06F-ECT/-1SN10F-ECT-1SN15F-ECT/-1SN20F-ECT/-1SN30F-ECT	R88A-FI1S309

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Software

Automation Software Sysmac Studio

The Sysmac Studio is the software that provides an integrated environment for setting, programming, debugging and maintenance of machine automation controllers including the NJ/NX-series CPU Units, NY-series Industrial PC, EtherCAT Slave, and the HMI.

For details, refer to your local OMRON website and Sysmac Studio Catalog (Cat. No. P138).
Note: The 1S-series Servo Drive unit version 1.3 or later is supported by Sysmac Studio version 1.27 or higher.

Collections of software functional components

Sysmac Library

Sysmac Library is POU Libraries (Function Block and Function) provided for NJ/NX-series Controller.
Please download it from following URL and install to Sysmac Studio.
http://www.ia.omron.com/sysmac_library/

Product	Features	Model
EtherCAT 1S Series Library	The EtherCAT 1S Series Library is used to initialize the absolute encoder, back up and restore the parameters for an OMRON 1S-series Servo Drive with built-in EtherCAT communications. You can use this library to reduce manpower of programming when implementing the processing for a Servo Drive.	SYSMAC-XR011

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Combination table

Servo Drive and Servomotor Combinations

The following tables show the possible combinations of 1S-series Servo Drives and Servomotors.
The Servomotors and Servo Drives can only be used in the listed combinations. "☐"at the end of the motor model number is for options, such as the shaft type and brake.

3,000-r/min Servomotors and Servo Drives

Main circuit power supply voltage	Servomotor rated output	Servomotor	Servo Drive
Single-phase 100 VAC	50 W	R88M-1M05030S-☐	R88D-1SN01L-ECT
	100 W	R88M-1M10030S-☐	R88D-1SN01L-ECT
	200 W	R88M-1M20030S-☐	R88D-1SN02L-ECT
	400 W	R88M-1M40030S-☐	R88D-1SN04L-ECT
Single-phase/3-phase 200 VAC	50 W	R88M-1M05030T-☐	R88D-1SN01H-ECT
	100 W	R88M-1M10030T-☐	R88D-1SN01H-ECT
	200 W	R88M-1M20030T-☐	R88D-1SN02H-ECT
	400 W	R88M-1M40030T-☐	R88D-1SN04H-ECT
	750 W	R88M-1M75030T-☐	R88D-1SN08H-ECT
	1.5 kW	R88M-1L1K530T-☐	R88D-1SN15H-ECT
3-phase 200 VAC	1 kW	R88M-1L1K030T-☐	R88D-1SN10H-ECT
	2 kW	R88M-1L2K030T-☐	R88D-1SN20H-ECT
	3 kW	R88M-1L3K030T-☐	R88D-1SN30H-ECT
	4 kW	R88M-1L4K030T-☐	R88D-1SN55H-ECT
	4.7 kW	R88M-1L4K730T-☐	
3-phase 400 VAC	750 W	R88M-1L75030C-☐	R88D-1SN10F-ECT
	1 kW	R88M-1L1K030C-☐	R88D-1SN10F-ECT
	1.5 kW	R88M-1L1K530C-☐	R88D-1SN15F-ECT
	2 kW	R88M-1L2K030C-☐	R88D-1SN20F-ECT
	3 kW	R88M-1L3K030C-☐	R88D-1SN30F-ECT
	4 kW	R88M-1L4K030C-☐	R88D-1SN55F-ECT
	5 kW	R88M-1L5K030C-☐	

2,000-r/min Servomotors and Servo Drives

Main circuit power supply voltage	Servomotor rated output	Servomotor	Servo Drive
Single-phase/3-phase 200 VAC	1.5 kW	R88M-1M1K520T-☐	R88D-1SN15H-ECT
3-phase 200 VAC	1 kW	R88M-1M1K020T-☐	R88D-1SN10H-ECT
	2 kW	R88M-1M2K020T-☐	R88D-1SN20H-ECT
	3 kW	R88M-1M3K020T-☐	R88D-1SN30H-ECT
3-phase 400 VAC	400 W	R88M-1M40020C-☐	R88D-1SN06F-ECT
	600 W	R88M-1M60020C-☐	R88D-1SN06F-ECT
	1 kW	R88M-1M1K020C-☐	R88D-1SN10F-ECT
	1.5 kW	R88M-1M1K520C-☐	R88D-1SN15F-ECT
	2 kW	R88M-1M2K020C-☐	R88D-1SN20F-ECT
	3 kW	R88M-1M3K020C-☐	R88D-1SN30F-ECT

1,500-r/min Servomotors and Servo Drives

Main circuit power supply voltage	Servomotor rated output	Servomotor	Servo Drive
3-phase 200 VAC	4 kW	R88M-1M4K015T-☐	R88D-1SN55H-ECT
	5 kW	R88M-1M5K015T-☐	
	7.5 kW	R88M-1M7K515T-☐	R88D-1SN75H-ECT
	11 kW	R88M-1M11K015T-☐	R88D-1SN150H-ECT
	15 kW	R88M-1M15K015T-☐	
3-phase 400 VAC	4 kW	R88M-1M4K015C-☐	R88D-1SN55F-ECT
	5.5 kW	R88M-1M5K515C-☐	
	7.5 kW	R88M-1M7K515C-☐	R88D-1SN75F-ECT
	11 kW	R88M-1M11K015C-☐	R88D-1SN150F-ECT
	15 kW	R88M-1M15K015C-☐	

1,000-r/min Servomotors and Servo Drives

Main circuit power supply voltage	Servomotor rated output	Servomotor	Servo Drive
3-phase 200 VAC	900 W	R88M-1M90010T-☐	R88D-1SN10H-ECT
	2 kW	R88M-1M2K010T-☐	R88D-1SN20H-ECT
	3 kW	R88M-1M3K010T-☐	R88D-1SN30H-ECT
3-phase 400 VAC	900 W	R88M-1M90010C-☐	R88D-1SN10F-ECT
	2 kW	R88M-1M2K010C-☐	R88D-1SN20F-ECT
	3 kW	R88M-1M3K010C-☐	R88D-1SN30F-ECT

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Servomotor and Decelerator Combinations

Backlash:3 Arcminutes Max.

3,000-r/min Servomotors and Decelerators

Servomotor models ✻	Reduction ratio				
	1/5	1/11	1/21	1/33	1/45
R88M-1M05030☐	---	---	R88G-HPG 14A21100B☐	R88G-HPG 14A33050B☐	R88G-HPG 14A45050B☐
R88M-1M10030☐	R88G-HPG 11B05100B☐	R88G-HPG 14A11100B☐		R88G-HPG 20A33100B☐	R88G-HPG 20A45100B☐
R88M-1M20030☐	R88G-HPG 14A05200B☐	R88G-HPG 14A11200B☐	R88G-HPG 20A21200B☐	R88G-HPG 20A33200B☐	R88G-HPG 20A45200B☐
R88M-1M40030☐	R88G-HPG 14A05400B☐	R88G-HPG 20A11400B☐	R88G-HPG 20A21400B☐	R88G-HPG 32A33400B☐	R88G-HPG 32A45400B☐
R88M-1M75030☐ (200 VAC)	R88G-HPG 20A05750B☐	R88G-HPG 20A11750B☐	R88G-HPG 32A21750B☐	R88G-HPG 32A33750B☐	R88G-HPG 32A45750B☐
R88M-1L75030☐ (400 VAC)	R88G-HPG 32A052K0B☐	R88G-HPG 32A112K0B☐	R88G-HPG 32A211K5B☐	R88G-HPG 32A33600SB☐	R88G-HPG 50A451K5B☐
R88M-1L1K030☐				R88G-HPG 50A332K0B☐	
R88M-1L1K530☐					
R88M-1L2K030☐			R88G-HPG 50A212K0B☐		---
R88M-1L3K030☐	R88G-HPG 32A053K0B☐	R88G-HPG 50A113K0B☐	R88G-HPG 50A213K0B☐	---	---
R88M-1L4K030☐	R88G-HPG 32A054K0B☐	R88G-HPG 50A115K0B☐	---	---	---
R88M-1L4K730☐ R88M-1L5K030☐	R88G-HPG 32A054K0B☐		---	---	---

✻You cannot use a Servomotor with a key and tap (model numbers with -S2 at the end) in combination with a Decelerator.

2,000-r/min Servomotors and Decelerators

Servomotor models ✻	Reduction ratio					
	1/5	1/11	1/21	1/25	1/33	1/45
R88M-1M40020☐ (400 VAC)	R88G-HPG 32A052K0B☐	R88G-HPG 32A112K0B☐	R88G-HPG 32A211K5B☐	---	R88G-HPG 32A33600SB☐	R88G-HPG 32A45400SB☐
R88M-1M60020☐ (400 VAC)				---		R88G-HPG 50A451K5B☐
R88M-1M1K020☐	R88G-HPG 32A053K0B☐	R88G-HPG 32A112K0SB☐	R88G-HPG 32A211K0SB☐	---	R88G-HPG 50A332K0SB☐	R88G-HPG 50A451K0SB☐
R88M-1M1K520☐			R88G-HPG 50A213K0B☐	---		---
R88M-1M2K020☐				---		---
R88M-1M3K020☐	R88G-HPG 32A054K0B☐	R88G-HPG 50A115K0B☐	R88G-HPG 50A213K0SB☐	R88G-HPG 65A253K0SB☐	---	---

✻You cannot use a Servomotor with a key and tap (model numbers with -S2 at the end) in combination with a Decelerator.

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1,500-r/min Servomotors and Decelerators

Servomotor models ✻	Reduction ratio				
	1/5	1/11	1/12	1/21	1/25
R88M-1M4K015□	R88G-HPG 50A055K0SB□	R88G-HPG 50A115K0SB□	---	R88G-HPG 65A205K0SB□	R88G-HPG 65A255K0SB□
R88M-1M5K□15□	R88G-HPG 50A054K5TB□	---	R88G-HPG 65A127K5SB□	R88G-HPG 65A204K5TB□	---

1,000-r/min Servomotors and Decelerators

Servomotor models ✻	Reduction ratio					
	1/5	1/11	1/21	1/25	1/33	1/45
R88M-1M90010□	R88G-HPG 32A05900TB□	R88G-HPG 32A11900TB□	---	R88G-HPG 50A21900TB□	---	R88G-HPG 50A33900TB□
R88M-1M2K010□	R88G-HPG 32A052K0TB□	R88G-HPG 50A112K0TB□	---	R88G-HPG 50A212K0TB□	R88G-HPG 65A255K0SB□	---
R88M-1M3K020□	R88G-HPG 50A055K0SB□	R88G-HPG 50A115K0SB□	R88G-HPG 65A205K0SB□	---		---

✻ You cannot use a Servomotor with a key and tap (model numbers with -S2 at the end) in combination with a Decelerator.

Backlash:15 Arcminutes Max.

3,000-r/min Servomotors and Decelerators

Servomotor models ✻	Reduction ratio			
	1/5	1/9	1/15	1/25
R88M-1M05030□	R88G-VRXF05B100CJ	R88G-VRXF09B100CJ	R88G-VRXF15B100CJ	R88G-VRXF25B100CJ
R88M-1M10030□				
R88M-1M20030□	R88G-VRXF05B200CJ	R88G-VRXF09C200CJ	R88G-VRXF15C200CJ	R88G-VRXF25C200CJ
R88M-1M40030□	R88G-VRXF05C400CJ	R88G-VRXF09C400CJ	R88G-VRXF15C400CJ	R88G-VRXF25C400CJ
R88M-1M75030□ (200 VAC)	R88G-VRXF05C750CJ	R88G-VRXF09D750CJ	R88G-VRXF15D750CJ	R88G-VRXF25D750CJ

✻ You cannot use a Servomotor with a key and tap (model numbers with -S2 at the end) in combination with a Decelerator.

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Cable Connection Configuration

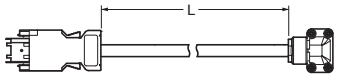
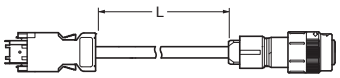
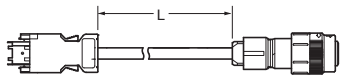
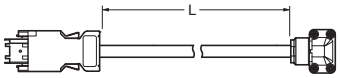
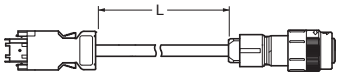
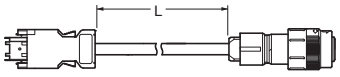
- Select an appropriate cable for the Servomotor.
- Some motor power cables have two cable versions: version 1.0 and version 1.1.
  The cable version can be checked on the model number label.
  Version 1.0: There is no version indicated on the model number label.
  Version 1.1: “Ver. 1.1” is indicated on the model number label.
- Use a Servo Drive unit version 1.2 or earlier with 20 m or less of motor power cable. For the combination of a Servo Drive and a motor power cable, see *Combinations of Unit Versions and Motor Power Cables* on page 18.

Refer to the *AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications User’s Manual* (Cat.No.I586) for details.

Precautions for Correct Use

The regulations for cables differ according to the country in use. (The regulations can also be different in the same country according to the region or where the Servomotors are installed.) Therefore, be sure to check to the respective certificate institution for a cable that conforms to the regulations of each country.

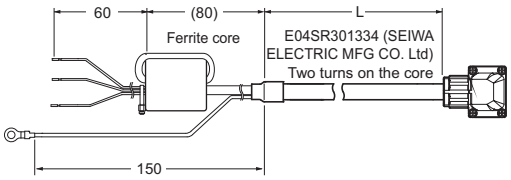
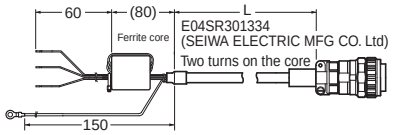
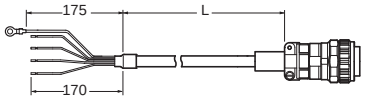
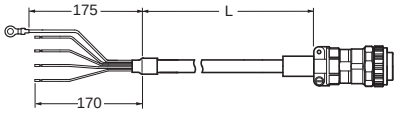
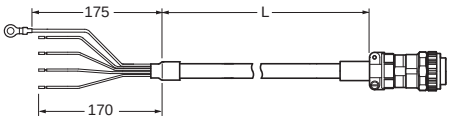
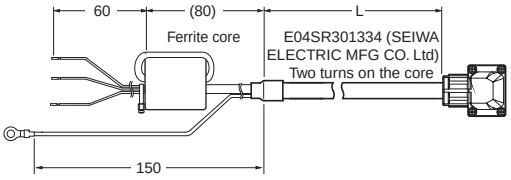
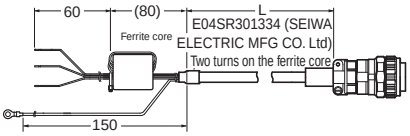
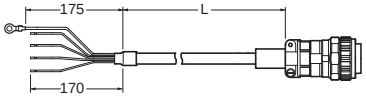
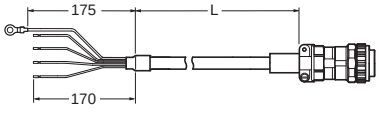
Encoder Cables

Connected to	Model	Connection configuration and external dimensions [mm]		
100 V and 200 V: 3,000-r/min Servomotors of 50 W, 100 W, 200 W, 400 W, and 750 W	Standard Cable R88A-CR1A□□□C The empty boxes in the model number are for the cable length. (3 to 20 m: 5.3 mm dia. 30 to 50 m: 6.0 mm dia.)	Servo Drive side connector Connector model Receptacle: 3E206-0100KV (3M) Shell kit: 3E306-3200-008 (3M)		Servomotor side connector Angle clamp model JN6FR07SM1 (Japan Aviation Electronics) Connector pin model LY10-C1-A1-10000 (Japan Aviation Electronics)
200 V: 3,000-r/min Servomotors of 1 kW to 3 kW, 2,000-r/min Servomotors, and 1,000-r/min Servomotors 400 V: 3,000-r/min Servomotors of 3 kW or less, 2,000-r/min Servomotors, and 1,000-r/min Servomotors	Standard Cable R88A-CR1B□□□N The empty boxes in the model number are for the cable length. (6.0 mm dia.)	Servo Drive side connector Connector model Receptacle: 3E206-0100KV (3M) Shell kit: 3E306-3200-008 (3M)		Servomotor side connector Straight plug model JN2DS10SL1-R (Japan Aviation Electronics) Contact model JN1-22-22S-10000 (Japan Aviation Electronics)
200 V and 400 V: 3000-r/min Servomotors of 4 kW or more 1500-r/min Servomotors	Standard Cable R88A-CR1B□□□V The empty boxes in the model number are for the cable length. (6.0 mm dia.)	Servo Drive side connector Connector model Receptacle: 3E206-0100KV (3M) Shell kit: 3E306-3200-008 (3M)		Servomotor side connector Straight plug model JN2VDS10SL1 (Japan Aviation Electronics) Contact model JN2V-22-22S-10000 (Japan Aviation Electronics)
100 V and 200 V: 3,000-r/min Servomotors of 50 W, 100 W, 200 W, 400 W and 750 W	Flexible Cable R88A-CR1A□□□CF The empty boxes in the model number are for the cable length. (3 to 20 m: 5.3 mm dia. 30 to 50 m: 6.0 mm dia.)	Servo Drive side connector Connector model Receptacle: 3E206-0100KV (3M) Shell kit: 3E306-3200-008 (3M)		Servomotor side connector Angle clamp model JN6FR07SM1 Connector pin model LY10-C1-A1-10000 (Japan Aviation Electronics)
200 V: 3,000-r/min Servomotors of 1 kW to 3 kW, 2,000-r/min Servomotors, and 1,000-r/min Servomotors 400 V: 3,000-r/min Servomotors of 3 kW or less, 2,000-r/min Servomotors, and 1,000-r/min Servomotors	Flexible Cable R88A-CR1B□□□NF The empty boxes in the model number are for the cable length. (6.0 mm dia.)	Servo Drive side connector Connector model Receptacle: 3E206-0100KV (3M) Shell kit: 3E306-3200-008 (3M)		Servomotor side connector Straight plug model JN2DS10SL1-R (Japan Aviation Electronics) Contact model JN1-22-22S-10000 (Japan Aviation Electronics)
200 V and 400 V: 3000-r/min Servomotors of 4 kW or more 1500-r/min Servomotors	Flexible Cable R88A-CR1B□□□VF The empty boxes in the model number are for the cable length. (6.0 mm dia.)	Servo Drive side connector Connector model Receptacle: 3E206-0100KV (3M) Shell kit: 3E306-3200-008 (3M)		Servomotor side connector Straight plug model JN2VDS10SL1 (Japan Aviation Electronics) Contact model JN2V-22-22S-10000 (Japan Aviation Electronics)

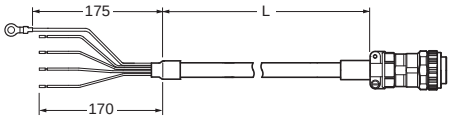
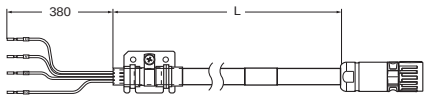
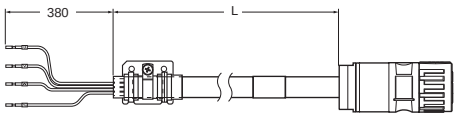
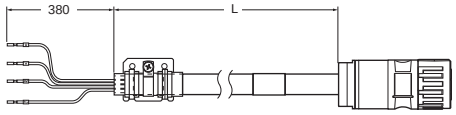
Note: Cable length: 3 m, 5 m, 10 m, 15 m, 20 m, 30 m, 40 m, 50 m
The empty boxes in the model number are put as follows: 3 m = 003, 5 m = 005, 10 m = 010.

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Power Cables without Brake Wire

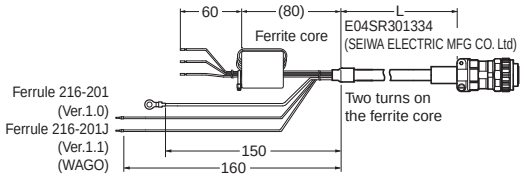
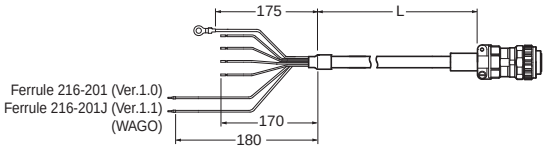
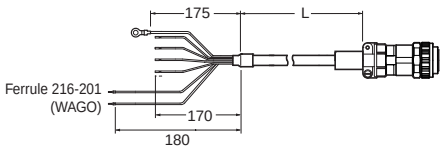
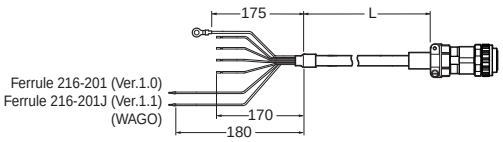
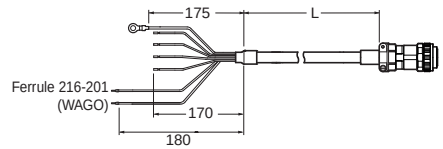
Connected to	Model	Connection configuration and external dimensions [mm]
100 V and 200 V: 3,000-r/min Servomotors of 100 W, 200 W, 400 W, and 750 W	Standard Cable R88A-CA1A□□□S The empty boxes in the model number are for the cable length. ✻1 (Ver.1.0: 6.8 mm dia.) (Ver.1.1: 7.2 mm dia.)		**Note: 1.** Use the R88A-CN111A Power Connector/Socket Contact (Omron) for this cable. **Note: 2.** This drawing shows the cable version 1.1. For the drawing of the cable version 1.0, refer to the *AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications User's Manual* (Cat. No. I586).
200 V: 3,000-r/min Servomotors of 1 kW, 2,000-r/min Servomotors of 1 kW, and 1,000-r/min Servomotors of 900 W	Standard Cable R88A-CA1B□□□S The empty boxes in the model number are for the cable length. ✻1 (Ver.1.0: 10.8 mm dia.) (Ver.1.1: 13.3 mm dia.)		Servomotor side connector Connector JL10-6A20-4SE-EB (Japan Aviation Electronics) Clamp JL04-2022CK(12)-R (Ver.1.0) JL04-2022CK(14)-R (Ver.1.1) (Japan Aviation Electronics)
200 V: 3,000-r/min Servomotors of 1.5 kW and 2,000-r/min Servomotors of 1.5 kW 400 V: 3,000-r/min Servomotors of 750 W, 1 kW, 1.5 kW, and 2 kW 2,000-r/min Servomotors of 400 W, 600 W, 1 kW, 1.5 kW, and 2 kW 1,000-r/min Servomotors of 900 W	Standard Cable R88A-CA1C□□□S The empty boxes in the model number are for the cable length. ✻1 (Ver.1.0: 10.8 mm dia.) (Ver.1.1: 13.3 mm dia.)		Servomotor side connector Connector JL10-6A20-4SE-EB (Japan Aviation Electronics) Clamp JL04-2022CK(12)-R (Ver.1.0) JL04-2022CK(14)-R (Ver.1.1) (Japan Aviation Electronics)
200 V: 3,000-r/min Servomotors of 2 kW and 3 kW 2,000-r/min Servomotors of 2 kW and 3 kW 1,000-r/min Servomotors of 2 kW 400 V: 3,000-r/min Servomotors of 3 kW 2,000-r/min Servomotors of 3 kW 1,000-r/min Servomotors of 2 kW and 3 kW	Standard Cable R88A-CA1E□□□S The empty boxes in the model number are for the cable length. ✻1 (Ver.1.0: 12.0 mm dia.) (Ver.1.1: 15.0 mm dia.)		Servomotor side connector Connector JL10-6A22-22SE-EB (Japan Aviation Electronics) Clamp JL04-2022CK(12)-R (Ver.1.0) JL04-2022CK(14)-R (Ver.1.1) (Japan Aviation Electronics)
200 V: 1,000-r/min Servomotors of 3 kW	Standard Cable R88A-CA1F□□□S The empty boxes in the model number are for the cable length. ✻1 (14.5 mm dia.)		Servomotor side connector Connector JL10-6A22-22SE-EB (Japan Aviation Electronics) Clamp JL04-2022CK(14)-R (Japan Aviation Electronics)
100 V and 200 V: 3,000-r/min Servomotors of 100 W, 200 W, 400 W, and 750 W	Flexible Cable R88A-CA1A□□□SF The empty boxes in the model number are for the cable length. ✻1 (Ver.1.0: 6.8 mm dia.) (Ver.1.1: 7.2 mm dia.)		**Note: 1.** Use the R88A-CN111A Power Connector/Socket Contact (Omron) for this cable. **Note: 2.** This drawing shows the cable version 1.1. For the drawing of the cable version 1.0, refer to the *AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications User's Manual* (Cat. No. I586).
200 V: 3,000-r/min Servomotors of 1 kW, 2,000-r/min Servomotors of 1 kW, and 1,000-r/min Servomotors of 900 W	Flexible Cable R88A-CA1B□□□SF The empty boxes in the model number are for the cable length. ✻1 (Ver.1.0: 10.8 mm dia.) (Ver.1.1: 15.3 mm dia.)		Servomotor side connector Connector JL10-6A20-4SE-EB (Japan Aviation Electronics) Clamp JL04-2022CK(12)-R (Ver.1.0) JL04-2022CK(14)-R (Ver.1.1) (Japan Aviation Electronics)
200 V: 3,000-r/min Servomotors of 1.5 kW 2,000-r/min Servomotors of 1.5 kW 400 V: 3,000-r/min Servomotors of 750 W, 1 kW, 1.5 kW, and 2 kW 2,000-r/min Servomotors of 400 W, 600 W, 1 kW, 1.5 kW, and 2 kW 1,000-r/min Servomotors of 900 W	Flexible Cable R88A-CA1C□□□SF The empty boxes in the model number are for the cable length. ✻1 (Ver.1.0: 10.8 mm dia.) (Ver.1.1: 15.3 mm dia.)		Servomotor side connector Connector JJL10-6A20-4SE-EB (Japan Aviation Electronics) Clamp JL04-2022CK(12)-R (Ver.1.0) JL04-2022CK(14)-R (Ver.1.1) (Japan Aviation Electronics)
200 V: 3,000-r/min Servomotors of 2 kW and 3 kW 2,000-r/min Servomotors of 2 kW and 3 kW 1,000-r/min Servomotors of 2 kW 400 V: 3,000-r/min Servomotors of 3 kW 2,000-r/min Servomotors of 3 kW 1,000-r/min Servomotors of 2 kW and 3 kW	Flexible Cable R88A-CA1E□□□SF The empty boxes in the model number are for the cable length. ✻1 (Ver.1.0: 12.0 mm dia.) (Ver.1.1: 15.5 mm dia.)		Servomotor side connector Connector JL10-6A22-22SE-EB (Japan Aviation Electronics) Clamp JL04-2022CK(12)-R (Ver.1.0) JL04-2022CK(14)-R (Ver.1.1) (Japan Aviation Electronics)

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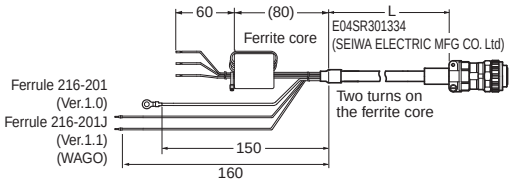
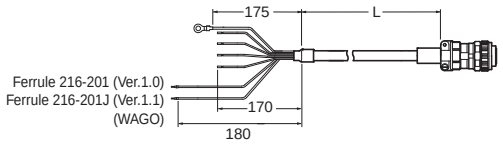
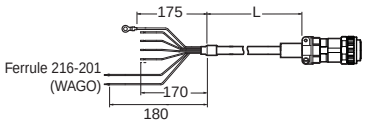
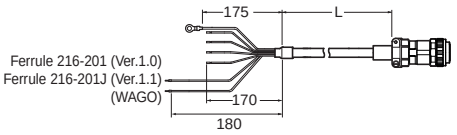
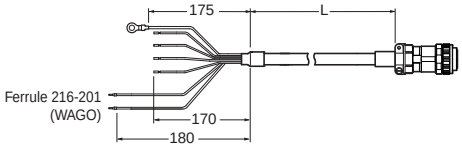
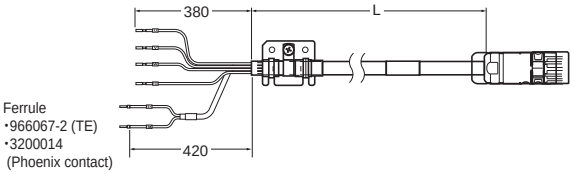
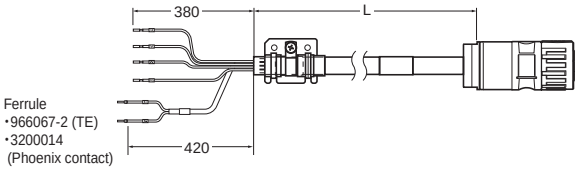
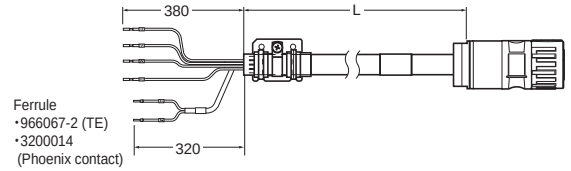
Connected to	Model	Connection configuration and external dimensions [mm]	
200 V: 1,000-r/min Servomotors of 3 kW	Flexible Cable R88A-CA1F□□□SF The empty boxes in the model number are for the cable length. ✻1 (14.5 mm dia.)		Servomotor side connector Connector JL10-6A22-22SE-EB (Japan Aviation Electronics) Clamp JL04-2022CK(14)-R (Japan Aviation Electronics)
200V: 3000 r/min Servomotors of 4 kW, 4.7 kW 1500 r/min Servomotors of 4 kW, 5 kW 400V: 3000 r/min Servomotors of 4 kW, 5 kW 1500 r/min Servomotors of 4 kW, 5.5 kW and 7.5 kW	Flexible Cable R88A-CA1H□□□SF The empty boxes in the model number are for the cable length. ✻2 (15 mm dia.)		Servomotor side connector M23 Series (Phoenix Contact) Connector 1621517 Contact Power: 1621578
400 V: 1500-r/min Servomotors of 11 kW and 15 kW	Flexible Cable R88A-CA1J□□□SF The empty boxes in the model number are for the cable length. ✻2 (17.3 mm dia.)		Servomotor side connector M40 Series (Phoenix Contact) Connector 1623327 Contact Power: 1623379
200 V: 1500-r/min Servomotors of 7.5 kW,11 kW and 15 kW	Flexible Cable R88A-CA1K□□□SF The empty boxes in the model number are for the cable length. ✻2 (23.2 mm dia.)		Servomotor side connector M40 Series (Phoenix Contact) Connector 1623328 Contact Power: 1623381

Note: The empty boxes in the model number are put as follows: 3 m = 003, 5 m = 005, 10 m = 010.
✻1. Cable length: 3 m, 5 m, 10 m, 15 m, 20 m, 30 m, 40 m, 50 m
✻2. Cable length: 3 m, 5 m, 10 m, 15 m, 20 m

Power Cables with Brake Wire

Connected to	Model	Connection configuration and external dimensions [mm]	
200 V: 3,000-r/min Servomotors of 1 kW 2,000-r/min Servomotors of 1 kW 1,000-r/min Servomotors of 900 W	Standard Cable R88A-CA1B□□□B The empty boxes in the model number are for the cable length. ✻1 (Ver.1.0: 12.5 mm dia.) (Ver.1.1: 13.3 mm dia.)		Servomotor side connector Connector JL10-6A20-18SE-EB (Japan Aviation Electronics) Clamp JL04-2022CK(12)-R (Ver.1.0) JL04-2022CK(14)-R (Ver.1.1) (Japan Aviation Electronics)
200 V: 3,000-r/min Servomotors of 1.5 kW 2,000-r/min Servomotors of 1.5 kW	Standard Cable R88A-CA1C□□□B The empty boxes in the model number are for the cable length. ✻1 (Ver.1.0: 12.5 mm dia.) (Ver.1.1: 13.3 mm dia.)		Servomotor side connector Connector JL10-6A20-18SE-EB (Japan Aviation Electronics) Clamp JL04-2022CK(12)-R (Ver.1.0) JL04-2022CK(14)-R (Ver.1.1) (Japan Aviation Electronics)
400 V: 3,000-r/min Servomotors of 750 W, 1 kW, 1.5 kW, and 2 kW 2,000-r/min Servomotors of 400 W, 600 W, 1 kW, 1.5 kW, and 2 kW 1,000-r/min Servomotors of 900 W	Standard Cable R88A-CA1D□□□B The empty boxes in the model number are for the cable length. ✻1 (12.5 mm dia.)		Servomotor side connector Connector JL10-6A24-11SE-EB (Japan Aviation Electronics) Clamp JL04-2428CK(14)-R (Japan Aviation Electronics)
200 V: 3,000-r/min Servomotors of 2 kW and 3 kW 2,000-r/min Servomotors of 2 kW and 3 kW 1,000-r/min Servomotors of 2 kW 400 V: 3,000-r/min Servomotors of 3 kW 2,000-r/min Servomotors of 3 kW 1,000-r/min Servomotors of 2 kW and 3 kW	Standard Cable R88A-CA1E□□□B The empty boxes in the model number are for the cable length. ✻1 (Ver.1.0: 14.0 mm dia.) (Ver.1.1: 15.0 mm dia.)		Servomotor side connector Connector JL10-6A24-11SE-EB (Japan Aviation Electronics) Clamp JL04-2428CK(14)-R (Ver.1.0) JL04-2428CK(17)-R (Ver.1.1) (Japan Aviation Electronics)
200 V: 1,000-r/min Servomotors of 3 kW	Standard Cable R88A-CA1F□□□B The empty boxes in the model number are for the cable length. ✻1 (17.0 mm dia.)		Servomotor side connector Connector JN6FS05SJ2 (Japan Aviation Electronics) Socket contact ST-JN5-S-C1B-2500 (Japan Aviation Electronics)

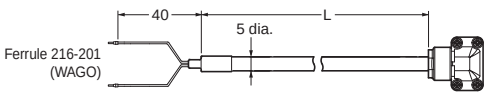
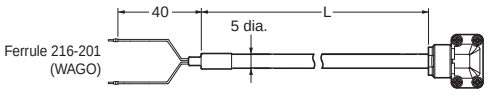
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Connected to	Model	Connection configuration and external dimensions [mm]	
200 V: 3,000-r/min Servomotors of 1 kW 2,000-r/min Servomotors of 1 kW 1,000-r/min Servomotors of 900 W	Flexible Cable R88A-CA1B□□□BF The empty boxes in the model number are for the cable length. ✻1 (Ver.1.0: 12.5 mm dia.) (Ver.1.1: 14.7 mm dia.)		Servomotor side connector Connector JL10-6A20-18SE-EB (Japan Aviation Electronics) Clamp JL04-2022CK(12)-R (Ver.1.0) JL04-2022CK(14)-R (Ver.1.1) (Japan Aviation Electronics)
200 V: 3,000-r/min Servomotors of 1.5 kW 2,000-r/min Servomotors of 1.5 kW	Flexible Cable R88A-CA1C□□□BF The empty boxes in the model number are for the cable length. ✻1 (Ver.1.0: 12.5 mm dia.) (Ver.1.1: 14.7 mm dia.)		Servomotor side connector Connector JL10-6A20-18SE-EB (Japan Aviation Electronics) Clamp JL04-2022CK(12)-R (Ver.1.0) JL04-2022CK(14)-R (Ver.1.1) (Japan Aviation Electronics)
400 V: 3,000-r/min Servomotors of 750 W, 1 kW, 1.5 kW, and 2 kW 2,000-r/min Servomotors of 400 W, 600 W, 1 kW, 1.5 kW, and 2 kW 1,000-r/min Servomotors of 900 W	Flexible Cable R88A-CA1D□□□BF The empty boxes in the model number are for the cable length. ✻1 (12.5 mm dia.)		Servomotor side connector Connector JL10-6A24-11SE-EB (Japan Aviation Electronics) Clamp JL04-2428CK(14)-R (Japan Aviation Electronics)
200 V: 3,000-r/min Servomotors of 2 kW and 3 kW 2,000-r/min Servomotors of 2 kW and 3 kW 1,000-r/min Servomotors of 2 kW 400 V: 3,000-r/min Servomotors of 3 kW 2,000-r/min Servomotors of 3 kW 1,000-r/min Servomotors of 2 kW and 3 kW	Flexible Cable R88A-CA1E□□□BF The empty boxes in the model number are for the cable length. ✻1 (Ver.1.0: 14.2 mm dia.) (Ver.1.1: 15.0 mm dia.)		Servomotor side connector Connector JL10-6A24-11SE-EB (Japan Aviation Electronics) Clamp JL04-2428CK(14)-R (Ver.1.0) JL04-2428CK(17)-R (Ver.1.1) (Japan Aviation Electronics)
200 V: 1,000-r/min Servomotors of 3 kW	Flexible Cable R88A-CA1F□□□BF The empty boxes in the model number are for the cable length. ✻1 (17.0 mm dia.)		Servomotor side connector Connector JL10-6A24-11SE-EB (Japan Aviation Electronics) Clamp JL04-2428CK(17)-R (Japan Aviation Electronics)
200 V: 3000 r/min Servomotors of 4 kW, 4.7 kW 1500 r/min Servomotors of 4 kW, 5 kW 400 V: 3000 r/min Servomotors of 4 kW, 5 kW 1500 r/min Servomotors of 4 kW, 5.5 kW and 7.5 kW	Flexible Cable R88A-CA1H□□□BF The empty boxes in the model number are for the cable length. ✻2 (15 mm dia.)		Servomotor side connector M23 Series (Phoenix Contact) Connector 1621517 Contact Power: 1621578 Brake: 1618251
400 V: 1500-r/min Servomotors of 11 kW and 15 kW	Flexible Cable R88A-CA1J□□□BF The empty boxes in the model number are for the cable length. ✻2 (17.3 mm dia.)		Servomotor side connector M40 Series (Phoenix Contact) Connector 1623327 Contact Power: 1623379 Brake: 1623604
200 V: 1500-r/min Servomotors of 7.5 kW, 11 kW and 15 kW	Flexible Cable R88A-CA1K□□□BF The empty boxes in the model number are for the cable length. ✻2 (23.2 mm dia.)		Servomotor side connector M40 Series (Phoenix Contact) Connector 1623328 Contact Power: 1623381 Brake: 1623604

Note: The empty boxes in the model number are put as follows: 3 m = 003, 5 m = 005, 10 m = 010.
✻1. Cable length: 3 m, 5 m, 10 m, 15 m, 20 m, 30 m, 40 m, 50 m
✻2. Cable length: 3 m, 5 m, 10 m, 15 m, 20 m

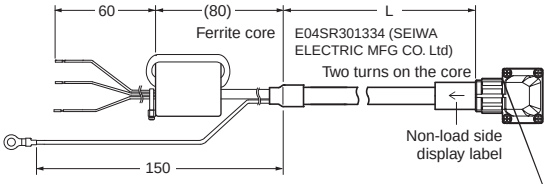
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Brake Cables

Connected to	Model	Connection configuration and external dimensions [mm]	
100 V and 200 V: 3,000-r/min Servomotors of 100 W, 200 W, 400 W, and 750 W	Standard Cable R88A-CA1A□□□B The empty boxes in the model number are for the cable length. (5.0 mm dia.)		Servomotor side connector Connector JN6FR02SM1 (Japan Aviation Electronics) Socket contact LY10-C1-A1-10000 (Japan Aviation Electronics)
100 V and 200 V: 3,000-r/min Servomotors of 100 W, 200 W, 400 W, and 750 W	Flexible Cable R88A-CA1A□□□BF The empty boxes in the model number are for the cable length. (5.0 mm dia.)		Servomotor side connector Connector JN6FR02SM1 (Japan Aviation Electronics) Socket contact LY10-C1-A1-10000 (Japan Aviation Electronics)

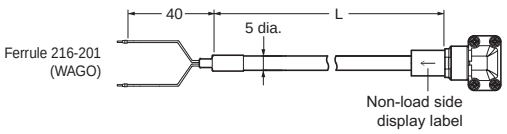
Note: Cable length: 3 m, 5 m, 10 m, 15 m, 20 m, 30 m, 40 m, 50 m
The empty boxes in the model number are put as follows: 3 m = 003, 5 m = 005, 10 m = 010.

Power Cables without Brake Wire (Non-load side, Flexible Cable)

Connected to	Model	Connection configuration and external dimensions [mm]	
100 V, 200 V: 3,000-r/min Servomotors of 50 W, 200 W, 400 W and 750 W	Non-load side, Flexible Cable R88A-CA1A□□□SFR The empty boxes in the model number are for the cable length. (Ver.1.0: 6.8 mm dia.) (Ver.1.1: 7.2 mm dia.)		Servomotor side connector Connector JN6FS05SJ1 (Japan Aviation Electronics) Socket contact ST-JN6-S-C1B-2500 (Japan Aviation Electronics)

Note: 1. Cable length: 3 m, 5 m, 10 m, 15 m, 20 m, 30 m, 40 m, 50 m
The empty boxes in the model number are put as follows: 3 m = 003, 5 m = 005, 10 m = 010.
2. This drawing shows the cable version 1.1. For the drawing of the cable version 1.0, refer to the *AC Servomotors/Servo Drives 1S-series with Built-in EtherCAT® Communications User's Manual* (Cat. No. I586).

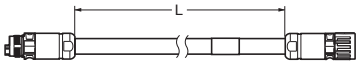
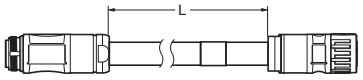
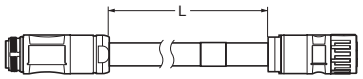
Brake Cables (Non-load side, Flexible Cable)

Connected to	Model	Connection configuration and external dimensions [mm]	
100 V, 200 V: 3,000-r/min Servomotors of 50 W, 200 W, 400 W and 750 W	Non-load side, Flexible Cable R88A-CA1A□□□BFR The empty boxes in the model number are for the cable length. (5.0 mm dia.)		Servomotor side connector Connector JN6FR02SM1 (Japan Aviation Electronics) Socket contact LY10-C1-A1-10000 (Japan Aviation Electronics)

Note: Cable length: 3 m, 5 m, 10 m, 15 m, 20 m, 30 m, 40 m, 50 m
The empty boxes in the model number are put as follows: 3 m = 003, 5 m = 005, 10 m = 010.

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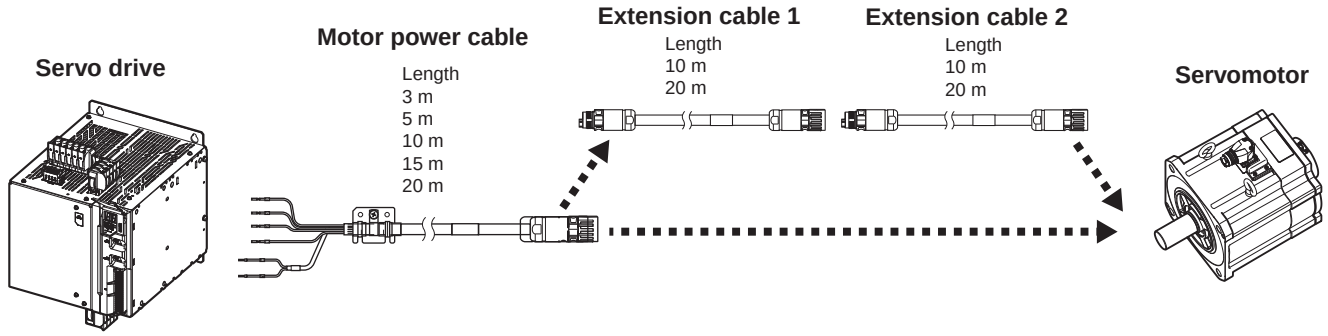
Extension Power Cable

Connected to	Model	Connection configuration and external dimensions [mm]		
200 V: 3000 r/min Servomotors of 4 kW, 4.7 kW 1500 r/min Servomotors of 4 kW, 5 kW 400 V: 3000 r/min Servomotors of 4 kW, 5 kW 1500 r/min Servomotors of 4 kW, 5.5 kW and 7.5 kW	Flexible Cable R88A-CA1HE□□BF The empty boxes in the model number are for the cable length. (15 mm dia.)	Servo Drive side connector M23 Series (Phoenix Contact) Connector 1621549 Contact Power: 1621581 Brake: 1618256		Servomotor side connector M23 Series (Phoenix Contact) Connector 1621517 Contact Power: 1621578 Brake: 1618251
400 V: 1500-r/min Servomotors of 11 kW and 15 kW	Flexible Cable R88A-CA1JE□□BF The empty boxes in the model number are for the cable length. (17.3 mm dia.)	Servo Drive side connector M40 Series (Phoenix Contact) Connector 1623357 Contact Power: 1623384 Brake: 1623611		Servomotor side connector M40 Series (Phoenix Contact) Connector 1623327 Contact Power: 1623379 Brake: 1623604
200 V: 1500-r/min Servomotors of 7.5 kW, 11 kW and 15kW	Flexible Cable R88A-CA1KE□□BF The empty boxes in the model number are for the cable length. (23.2 mm dia.)	Servo Drive side connector M40 Series (Phoenix Contact) Connector 1623358 Contact Power: 1623386 Brake: 1623611		Servomotor side connector M40 Series (Phoenix Contact) Connector 1623328 Contact Power: 1623381 Brake: 1623604

Note: Cable length: 10 m, 20 m
The empty boxes in the model number are put as follows: 10 m = 10, 20 m = 20.

Combinations of Motor Power Cables and Extension Power Cables

The table below lists the combinations of cables that can be used to extend the motor power cable for a servomotor of 4 kW or more to more than 20 m.



Length (m)				Combination
Total	Motor power cable	Extension cable 1	Extension cable 2	
3	3	---	---	Motor power cable only
5	5	---	---	Motor power cable only
10	10	---	---	Motor power cable only
15	15	---	---	Motor power cable only
20	20	---	---	Motor power cable only
30	20	10	---	Motor power cable + extension cable 1
40	20	20	---	Motor power cable + extension cable 1
50	20	10	20	Motor power cable + extension cable 1 + extension cable 2 ✻

✻ A 20 m extension cable 1 and a 10 m extension cable 2 can also be used.

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Related Manuals

English Man.No.	Japanese Man.No.	Model	Manual name
I586	SBCE-377	R88M-1□/R88D-1SN□-ECT	AC Servomotors/Servo Drives 1S-Series with EtherCAT Communications User's Manual
W535	SBCA-418	NX701-□□□□	NX-series CPU Unit User's Manual (Hardware)
W629	SBCA-497	NX502-□□□□	NX-series NX502 CPU Unit Hardware User's Manual
W593	SBCA-462	NX102-□□□□	NX-series NX102 CPU Unit Hardware User's Manual
W578	SBCA-448	NX1P2-□□□□□□ NX1P2-□□□□□□1	NX-series NX1P2 CPU Unit User's Manual (Hardware)
W500	SBCA-466	NJ501-□□□□ NJ301-□□□□ NJ101-□□□□	NJ-series CPU Unit User's Manual (Hardware)
W501	SBCA-467	NX701-□□□□ NX502-□□□□ NX102-□□□□ NX1P2-□□□□ NJ501-□□□□ NJ301-□□□□ NJ101-□□□□	NJ-series / NX-series CPU Unit User's Manual (Software)
W507	SBCE-433	NX701-□□□□ NX502-□□□□ NX102-□□□□ NX1P2-□□□□ NJ501-□□□□ NJ301-□□□□ NJ101-□□□□	NJ-series / NX-series CPU Unit User's Manual (Motion Control)
W556	SBCA-434	NY512-□□□□	NY-series IPC Machine Controller Industrial Box PC Hardware User's Manual
W557	SBCA-435	NY532-□□□□	NY-series IPC Machine Controller Industrial Panel PC Hardware User's Manual
W558	SBCA-436	NY532-□□□□ NY512-□□□□	NY-series IPC Machine Controller Industrial Panel PC / Industrial Box PC Software User's Manual
W559	SBCE-379	NY532-□□□□ NY512-□□□□	NY-series IPC Machine Controller Industrial Panel PC / Industrial Box PC Motion Control User's Manual
Z930	SGFM-710	NX-SL□□□□ NX-SI□□□□ NX-SO□□□□	NX-series Safety Control Unit User's Manual
Z931	SGFM-711	NX-SL□□□□	NX-series Safety Control Unit Instructions Reference Manual
W504	SBCA-470	SYSMAC-SE2□□□	Sysmac Studio Version 1 Operation Manual
I589	SBCE-401	SYSMAC-SE2□□□	Sysmac Studio Drive Function Operation Manual
W487	SBCE-359	CJ1W-NC281 CJ1W-NC481 CJ1W-NC881 CJ1W-NCF81 CJ1W-NC482 CJ1W-NC882 CJ1W-NCF82	CJ-series Position Control Unit Operation Manual
Z922	SJLB-306	G9SP-N10S G9SP-N10D G9SP-N20S	G9SP Series Safety Controller Operation Manual

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AC Servo System 1S-series

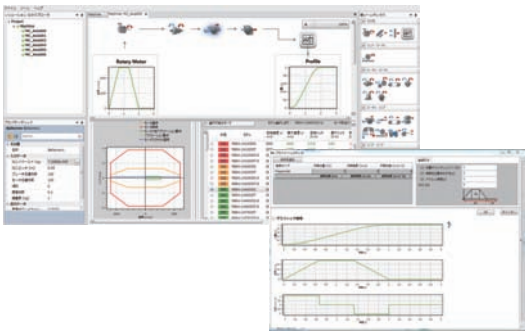
Sizing Tool for AC Servo Motors

AC Servo motors selection for the entire machine

- User can size all axes in one project with the corresponded Sysmac controller.
- Pre-defined system can be used for common applications.
- Selection of optimized drive, motor and gearbox combination.
- Multiple views are not required: design, adjust and validate at a glance.
- Import sizing file directly to Sysmac Studio for reducing the machine development time.

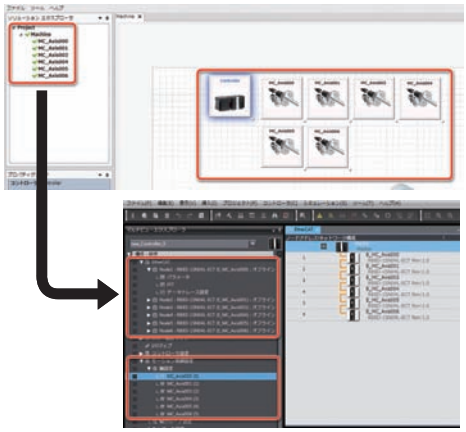
Quick sizing and selection of AC servo motors

- High variety of mechanical system
- Import CAM from Sysmac Studio
- Kinematics chain architecture includes motor, reducer, loads and motion profile.
- Adjustments can be done in one view and results auto-refreshed.



Re-use work done during design phase

- Export sizing file result.
- Import sizing file result in Sysmac Studio.
- EtherCAT configuration, axes settings and drives parameters will be created automatically



Compatible models

1S series	EtherCAT Communications and Safety Functionality	R88D-1SAN□-ECT
1S series	EtherCAT Communications and SS1/SLS Safety Functionality	R88D-1SN□-ECT-51
1S series	EtherCAT Communications	R88D-1SN□-ECT
G5 series	EtherCAT Communications for Position Control	R88D-KN□-ECT
G5 series	EtherCAT Communications (Linear Motor Type)	R88D-KN□-ECT-L
G5 series	MECHATROLINK-II Communications	R88D-KN□-ML2
G5 series	General-purpose Pulse Train or Analog Inputs	R88D-KT

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