

ADATA Technology Corp.

SATA 6Gb/s M.2 2280 SSD Datasheet

2280-S3-B-M

2280-D2-B-M

IM2S3328E

MLC: 32GB, 64GB, 128GB, 256GB, 512GB, 1TB

Preliminary Version 1.0S

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Key Features:

- Capacity:
 - MLC : 32GB, 64GB, 128GB,
 256GB,512GB,1TB
- Form Factor: M.2 2280-S3-B-M
- Compatibility:
 - Serial ATA 6Gb/s interface
 - Complies with ATA-8 Standard
 - Complies ATA Revision 3.1
 - S.M.A.R.T feature supported
 - NCQ Command set supported

Performance

- Sequential Read: Up to 561MB/s
- Sequential Write: Up to 451MB/s
- Random 4K Read: Up to 71K
- Random 4K Write: Up to 79K

- Power Consumption:
 - Slumber : 0.02W- Typical
 - Idle: 0.04W-Typical
 - Sequential Read : 1.5W-Typical
 - Sequential Write : 3W-Typical

• Temperature:

- Operation: -10°C ~ 80°C(Normal)
- Operation: -40°C ~ 90°C(Wide)
- Non-operation: -55°C ~ 95°C
- Shock
 - 1500G/0.5ms
- Vibration
 - 20G Peak, 10~2000Hz
- Reliability
 - MTBF: 1,000,000 hours

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Revision History

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0	Preliminary Version	Dec.2015		Terry_Chu
1	Preliminary Version	May.2016	Add 1TB	Terry_Chu

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1.0 General Description

Taking the advantages of NAND flash memory, Solid State Drive (SSD) provides better solutions on durability, performance, and power efficiency over traditional hard disk drives. Employing static wear-leveling technology to maximize SSD lifetime, the SSD solutions are your best choice on wide-ranged mobile computing devices and industrial electronic products. With standard SATA form factor or customized module form factor, The ADATA M.2 2280 SSD IM2S3328E offers capacities up to 512GB using Synchronous MLC NAND type flash memories.





2.0 Mechanical Specification

"All product specifications not covered in this document (electrical performance, appearance, etc.) are in accordance with ADATA's defined norms and standards. "

2.1 Physical dimensions and Weight

[Table 2-1] Dimensions and Weight

Length(mm)	Width(mm)	Height(mm)	Weight(gram)
80.00+/-0.15	22.00+/-0.15	Max 3.5	Max 10

2.2 PCBA Dimensions



[Figure 2-1] Physical Dimensions

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3.0 Product Specification

3.1 Interface and configuration

- Burst read/write rate is 600 MB/sec (6.0 Gb/sec).
- Supports 1-port 1.5/3.0/6.0 Gbps SATA I/II/III interface.
- Compliant with Serial ATA International Organization: Serial ATA Revision 3.1.
- Compliant SSD Alliance compliance program

Model		IMS3328E		
Capacity	Cylinder	Head	Sector	Total Sectors
32GB	16383	16	63	62,533,296
64GB	16383	16	63	125,045,424
128GB	16383	16	63	250,069,680
256GB	16383	16	63	500,118,192
512GB	16383	16	63	1,000,215,216
1TB	16383	16	63	2,000,409,264

3.2 Capacity

[Table 3-1] User Addressable Sectors

Total useable capacity may be less (duo to formatting, flash management, and other functions).

1GB=1,000,000,000 bytes; 1sector = 512bytes.

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3.3 Performance

3.3.1 Read/Write & IOPS Performance

MLC	32GB	64GB	128GB	256GB	512GB	1TB	Unit
4K Random Read	26K	50K	70K	71K	70K	70K	IOPS
4K Random Write	11K	24K	46K	79K	73K	73K	IOPS

[Table 3-2] Read/Write & IOPS Performance

- IOPS Test Utility: IOmeter 2010 (Queue depth of 32; Measurements are performed on 10% capacity of LBA range. Write cache enable)

- The system conditions and test environment may affect test result

MLC	32GB	64GB	128GB	256GB	512GB	1TB	Unit
Sequential Read	277	512	520	509	523	523	MB/s
Sequential Write	48	97	191	373	448	448	MB/s

[Table 3-3] Read/Write Performance (Crystal Disk Mark)

- Seq. Read & Write speed test by Crystal Disk Mark

- The system conditions and test environment may affect test result

MLC	32GB	64GB	128GB	256GB	512GB	1TB	Unit
Sequential Read	281	550	560	562	561	561	MB/s
Sequential Write	49	97	192	375	451	451	MB/s

[Table 3-4] Read/Write Performance (ATTO)

- Seq. Read & Write speed test by ATTO

- The system conditions and test environment may affect test result

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3.4 Electrical

3.4.1 Operating Voltage

Operating Voltage			
Input Power	DC 3.3V ± 5%		
Maximum Ripple	100Mv p-p or less		

[Table 3-5] Operating Voltage

3.4.2 Power Consumption (Typical)

MLC	Slumber	Partial	Idle	Read	Write	Unit
32GB	0.02	0.08	0.28	0.95	0.88	
64GB	0.02	0.07	0.28	1.09	1.45	
128GB	0.02	0.17	0.27	1.29	1.6	۱۸/
256GB	0.02	0.17	0.29	1.45	2.55	VV
512GB	0.04	0.08	0.32	1.51	3.00	
1TB	0.04	0.08	0.32	1.51	3.00	

[Table 3-6] Power Consumption

- To measure consumption in /Slumber/ Idle mode and Sequential Read/Sequential Write

3.5 Environmental Conditions

Feature	Operating	Non-Operating			
Normal Temperature	-10°C to 80°C	-55°C to 95°C			
Wide Temperature	-40°C to 90°C	-55°C to 95°C			
Humidity	$0^\circ C$ to $55^\circ C$ / 5%~95% RH, non-condensing				
Vibration	20G Peak, 10~2000Hz				
Shock	1500G, duration 0.5ms, Half Sine Wave				

[Table 3-7] Temperature, Humidity, Shock, Vibration

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3.6 Reliability

Parameter	Value
Mean Time Between Failures (MTBF)	
The MTBF statistics were calculated by Part Count	1,000,000 hours
Method, not relevant to individual units	

[Table 3-8] Reliability Specification

3.7 Endurance

Endurance for the SSD can be predicted based on the operating workload .The tables as below shows the drive lifetime for each SSD capacity based JESD219A Client workload.

MLC	32GB	64GB	128GB	256GB	512GB	1TB	Unit
TBW	43	86	172	345	690	1381	ТВ

[Table 3-9] Tera Byte Written

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4.0 Supported Command Sets

4.1 ATA Feature Command Sets

ADATA IM2S3328E supports all the mandatory ATA commands defined in ATA-8 specification. The supported command sets are listed as below.

Command Name	Code	Protocol
General Feature Set		
Execute Device Diagnostic	90h	Execute device diagnostic
Flush Cache	E7h	Non-data
Identify Device	ECh	PIO data-in
Initialize Drive Parameters	91h	Non-data
Read DMA	C8h	DMA
Read Log Ext	2Fh	PIO data-in
Read Multiple	C4h	PIO data-in
Read Sector(s)	20h	PIO data-in
Read Verify Sector(s)	40h or 41h	Non-data
Set Feature	EFh	Non-data
Set Multiple Mode	C6h	Non-data
Write DMA	CAh	DMA
Write Multiple	C5h	PIO data-out
Write Sector(s)	30h	PIO data-out
NOP	00h	Non-data
Read Buffer	E4h	PIO data-in
Write Buffer	E8h	PIO data-out
Power Management Feature Set		
Check Power Mode	E5h or 98h	Non-data
Idle	E3h or 97h	Non-data
Idle Immediate	E1h or 95h	Non-data
Sleep	E6h or 99h	Non-data
Standby	E2h or 96h	Non-data

[Table 4-1] Supported ATA Command Table

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Standby Immediate	E0h or 94h	Non-data						
Security Mode Feature Set								
Security Set Password	F1h	PIO data-out						
Security Unlock	F2h	PIO data-out						
Security Erase Prepare	F3h	Non-data						
Security Erase Unit	F4h	PIO data-out						
Security Freeze Lock	F5h	Non-data						
Security Disable Password	F6h	PIO data-out						
SMART Feature Set								
SMART Disable Operations	B0h	Non-data						
SMART Enable/Disable Autosave	B0h	Non-data						
SMART Enable Operations	B0h	Non-data						
SMART Execute OFF-LINE Immediate	B0h	Non-data						
SMART Read Log	B0h	PIO data-in						
SMART Read Data	B0h	PIO data-in						
SMART Read Threshold	B0h	PIO data-in						
SMART Return Status	B0h	Non-data						
SMART Save Attribute Values	B0h	Non-data						
SMART Write Log	B0h	PIO data-out						
Host Protected Area Feature Set								
Read Native Max Address	F8h	Non-data						
Set Max Address	F9h	Non-data						
Set Max Set Password	F9h	PIO data-out						
Set Max Lock	F9h	Non-data						
Set Max Freeze Lock	F9h	Non-data						
Set Max Unlock	F9h	PIO data-out						
48-bit Address Feature Set								
Flush Cache Ext	EAh	Non-data						
Read Sector(s) Ext	24h	PIO data-in						
Read DMA Ext	25h	DMA						
Read Multiple Ext	29h	PIO data-in						
Read Native Max Address Ext	27h	Non-data						

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Read Verify Sector(s) Ext	42h	Non-data
Set Max Address Ext	37h	Non-data
Write DMA Ext	35h	DMA
Write Multiple Ext	39h	PIO data-out
Write Sector(s) Ext	34h	PIO data-out
NCQ Feature Set		
Read FPDMA Queued	60h	DMA Queued
Write FPDMA Queued	61h	DMA Queued
Others		
Data Set Management	06h	DMA
Seek	70h	Non-data

4.2 Identify Device

ADATA IM2S3328E responds to ATA IDENTIFY DEVICE command with a pre-defined string of information on features, hardware and firmware revision information.

4.2.1 Identify device information

[Table 4-2] IDENTIFY DEVICE Table

Word	F/V	Default Value	Description
0	F	044Ah	General configuration
1	Х	XXXXh	Default number of cylinders
2	V	0000h	Reserved
3	Х	00XXh	Default number of heads
4	Х	0000h	Obsolete
5	Х	0240h	Obsolete
6	F	XXXXh	Default number of sectors per track
7 - 8	V	XXXXh	Number of sectors per card
			(Word 7 = MSW, Word 8 = LSW)
9	Х	0000h	Obsolete
10 - 19	F	XXXXh	Serial number in ASCII (Right justified)
20	Х	0002h	Obsolete

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21	Х	0002h	Obsolete			
22	Х	0000h	Obsolete			
23 - 26	6 F XXXXh		Firmware revision in ASCII			
			Big Endian Byte Order in Word			
27 - 46	F	XXXXh	Model number in ASCII (Left justified)			
			Big Endian Byte Order in Word			
47	F	8001h	Maximum number of sectors on Read/Write Multiple			
			command			
48	F	0000h	Reserved			
49	F	0300h	Capabilities			
50	F	0400h	Capabilities			
51	F	0200h	PIO data transfer cycle timing mode			
52	Х	0000h	Obsolete			
53	F	0007h	Field validity			
54	Х	XXXXh	Current numbers of cylinders			
55	Х	XXXXh	Current numbers of heads			
56	Х	XXXXh	Current sectors per track			
57 - 58	Х	XXXXh	Current capacity in sectors (LBAs)			
			(Word 57 = LSW , Word 58 = MSW)			
59	F	0101h	Multiple sector setting			
60 - 61	F	XXXXh	Total number of user addressable logical sectors for			
			28-bit commands (DWord)			
62	Х	0000h	Reserved			
63	F	0207h	Multiword DMA transfer			
			Supports MDMA mode 0, 1 and 2			
64	F	0003h	Advanced PIO modes supported			
65	F	0078h	Minimum Multiword DMA transfer cycle time per word			
66	F	0078h	Recommended Multiword DMA transfer cycle time			
67	F	0078h	Minimum PIO transfer cycle time without flow control			
68	F	0078h	Minimum PIO transfer cycle time with IORDY flow			
			control			
69	F	4000h	Additional supported			

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70 - 74	F	0000h	Reserved		
75	F	001Fh	Queue depth		
76	F	030Eh	Serial ATA capabilities		
			Supports Serial ATA Gen3		
			Supports Serial ATA Gen2		
			Supports Serial ATA Gen1		
			Supports Phy event counters log		
			Supports receipt of host initiated power management		
			requests		
			Supports Native Command Queuing		
77	F	0080h	Serial ATA additional capability		
			DevSleep_to_ReducedPwerState		
78	F	0148h	Serial ATA features supported		
			Supports Device Sleep		
			Supports software settings preservation		
			Device supports initiating power management		
79	V	0040h	Reserved		
80	F	03FCh	Major version number (ACS-2)		
81	F	0000h	Minor version number		
82	F	702Bh	Command sets supported 0		
83	F	7500h	Command sets supported 1		
84	F	4002h	Command sets supported 2		
85 - 87	V	XXXXh	Command set/feature enabled		
88	V	007Fh	Ultra DMA mode supported and selected		
89	F	0003h	Time required for a Normal Erase mode Security Erase		
			Unit command		
90	F	0001h	Time required for an Enhanced Erase mode Security		
			Erase Unit command		
91	V	0000h	Current advanced power management value		
92	V	FFFEh	Master password identifier		
93 - 99	V	0000h	Reserved		
100 - 103	V	XXXXh	Maximum user LBA for 48-bit address feature set		

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104	V	0000h	Reserved
105	F	0100h	Maximum number of 512-byte blocks per Data Set
			Management command
106 - 127	V	0000h	Reserved
128	V	0009h	Security status
129 - 159	Х	XXXXh	Vendor specific
160	F	0000h	Power requirement description
161	Х	0000h	Reserved
162	F	0000h	Key management schemes supported
163	F	0000h	CF Advanced True IDE Timing mode capability and
			setting
164 - 168	V	0000h	Reserved
169	F	0001h	Data Set Management supported
170 - 216	V	XXXXh	Reserved
217	F	0001h	Non-rotating media (SSD)
218 - 221	Х	0000h	Reserved
222	F	107Fh	Transport major revision (SATA Rev 3.1)
223 - 254	Х	0000h	Reserved
255	Х	XXXXh	Integrity word

Notes:

1. F = content (byte) is fixed and does not change.

2. V = content (byte) is variable and may change depending on the state of the device or the commands executed by the device.

3. X = content (byte) is vendor specific and may be fixed or variable.

4.3 S.M.A.R.T. Feature Set

S.M.A.R.T. (Self-Monitoring, Analysis and Reporting Technology; often written as SMART) is a monitoring system for HDDs and SSDs to detect and report on various indicators of reliability and drive status. Host can monitor the healthy condition of SSD drive by analyzing S.M.A.R.T. data and inform user to take action if necessary. IM2S3328E supports specific S.M.A.R.T. for industrial and server application including drive life monitoring, wear leveling, total data read/write on host/flash interface. By leveraging S.M.A.R.T., user can easily not only monitor drive status but also understand the workload to help evaluating the reliability.

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Value	Command	Value	Command
D0h	Read Data	D5h	Read Log
D1h	Read Attribute Threshold	D6h	Write Log
D2h	Enable/Disable Autosave	D8h	Enable SMART operations
D3h	Save Attribute Values	D9h	Disable SMART operations
D4h	Execute Off-Line Immediate	DAh	Return Status

[Table 4-3] S.M.A.R.T. Feature Register Values

If the reserved size is below the threshold, the status can be read from the Cylinder Register using **Return Status** command (DAh).

4.3.1 SMART Data Structure

The following 512byte make up the device SMART data structure. Users can obtain the data using **Read Data** command (D0h).

Byte	F/V	Description
0 – 1	Х	Revision code
2 – 361	Х	SMART attribute & value [Table 4-3.3]
362	V	Off-line data collection status
363	Х	Self-test execution status byte
364 - 365	V	Total time in seconds to complete off-line data collection activity
366	Х	Vendor specific
367	F	Off-line data collection capability
368 – 369	F	SMART capability
370	F	Error logging capability Bit 7-1 : Reserved Bit 0 = 1 : Device error logging supported
371	Х	Vendor specific
372	F	Short self-test routine recommended polling time (in minutes)
373	F	Extended self-test routine recommended polling time (in minutes)
374	F	Conveyance self-test routine recommended polling time (in minutes)
375 – 385	R	Reserved
386 – 395	F	Firmware version
396 – 399	F	Reserved

[Table 4-4] S.M.A.R.T. Data Structure

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Byte	F/V	Description
400 – 405	F	"SM2246"
406 – 510	Х	Vendor specific
511	V	Data structure checksum

Notes:

F = content (byte) is fixed and does not change.

V = content (byte) is variable and may change depending on the state of the device or commands executed by the device.

X = content (byte) is vendor specific and may be fixed or variable.

R = content (byte) is reserved and shall be zero.

4.3.2 SMART Attribute

The following table defines the vendor specific data in byte 2 to 361 of the 512-byte SMART data.

Attribute ID (hex)		Ra	aw Attrik	oute Val	ue		Attribute Name
01	MSB	00	00	00	00	00	Read error rate
05	LSB	MSB	00	00	00	00	Reallocated sectors count
09	LSB	-	-	MSB	00	00	Reserved
0C	LSB	-	-	MSB	00	00	Power cycle count
A0	LSB	-	-	MSB	00	00	Uncorrectable sector count when read/write
A1	LSB	MSB	00	00	00	00	Number of valid spare block
A3	LSB	MSB	00	00	00	00	Number of initial invalid block
A4	LSB	-	-	MSB	00	00	Total erase count
A5	LSB	-	-	MSB	00	00	Maximum erase count
A6	LSB	-	-	MSB	00	00	Minimum erase count
A7	LSB	-	-	MSB	00	00	Average erase count
A8	LSB	-	-	MSB	00	00	Max. erase count of Spec.
A9	LSB	-	-	MSB	00	00	Remain Life(percentage)
AF	LSB	-	-	MSB	00	00	Program fail count in worst die
B0	LSB	MSB	00	00	00	00	Erase fail count in worst die
B1	LSB	-	-	MSB	00	00	Total wear level count
B2	LSB	MSB	00	00	00	00	Runtime invalid block count
B5	LSB	-	-	MSB	00	00	Total program fail count

[Table 4-3.3]S.M.A.R.T. Atribute

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Attribute ID (hex)		Ra	aw Attrik	oute Val	ue		Attribute Name
B6	LSB	MSB	00	00	00	00	Total erase fail count
C0	LSB	MSB	00	00	00	00	Power-off retract count
C2	MSB	00	00	00	00	00	Controlled temperature
C3	LSB	-	-	MSB	00	00	Hardware ECC recovered
C4	LSB	-	-	MSB	00	00	Reallocation event count
C5	LSB	-	-	MSB	00	00	Current pending sector count
C6	LSB	-	-	MSB	00	00	Uncorrectable error count off-line
C7	LSB	MSB	00	00	00	00	Ultra DMA CRC error count
E8	LSB	MSB	00	00	00	00	Available reserved space
F1	LSB	-	-	-	-	MSB	Host written LBAs (each write unit = 32MB)
F2	LSB	-	-	-	-	MSB	Host read LBAs (each read unit = 32MB)
F5	LSB	-	-	-	-	MSB	Total data written to flash (each write unit = 32MB)

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5.0 Pin assignment and descriptions

5.1 SATA Interface



TOP



BOTTOM [Figure 5-1] SATA Interface

Pin	Туре	Description
1	CONFIG_3	Ground
2	3.3 V	Supply pin, 3.3 V
3	GND	Ground
4	3.3 V	Supply pin, 3.3 V
5	No connect	No connect
6	No connect	No connect
7	No connect	No connect
8	No connect	No connect
9	No connect	No connect
10	DAS/DSS	Device Activity Signal / Disable Staggered Spinup
11	No connect	No connect
12	(removed for key)	Mechanical notch B
13	(removed for key)	Mechanical notch B
14	(removed for key)	Mechanical notch B
15	(removed for key)	Mechanical notch B

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16	(removed for key)	Mechanical notch B
17	(removed for key)	Mechanical notch B
18	(removed for key)	Mechanical notch B
19	(removed for key)	Mechanical notch B
20	No connect	No connect
21	CONFIG_0	Ground
22	No connect	No connect
23	No connect	No connect
24	No connect	No connect
25	No connect	No connect
26	No connect	No connect
27	GND	Ground
28	No connect	No connect
29	No connect	No connect
30	No connect	No connect
21	No connect	No connect
51		
32	No connect	No connect
32 33	No connect GND	No connect Ground
32 33 34	No connect GND No connect	No connect Ground No connect
32 33 34 35	No connect GND No connect No connect	No connect Ground No connect No connect
32 33 34 35 36	No connect GND No connect No connect No connect No connect	No connect No connect Ground No connect No connect No connect No connect
31 32 33 34 35 36 37	No connect GND No connect No connect No connect No connect	No connect Ground No connect No connect No connect No connect No connect No connect
32 33 34 35 36 37 38	No connect GND No connect No connect No connect No connect DEVSLP	No connect Ground No connect No connect No connect No connect No connect Device Sleep, Input. If driven high the host is informing the SSD to enter a low
32 33 34 35 36 37 38	No connect GND No connect No connect No connect No connect DEVSLP	No connect Ground No connect No connect No connect No connect No connect Device Sleep, Input. If driven high the host is informing the SSD to enter a low power state.
32 33 34 35 36 37 38 39	No connect GND No connect No connect No connect No connect DEVSLP GND	No connect Ground No connect No connect No connect No connect No connect Device Sleep, Input. If driven high the host is informing the SSD to enter a low power state. Ground
31 32 33 34 35 36 37 38 39 40	No connect GND No connect No connect No connect No connect DEVSLP GND No connect	No connect Ground No connect No connect No connect No connect No connect Device Sleep, Input. If driven high the host is informing the SSD to enter a low power state. Ground No connect
31 32 33 34 35 36 37 38 39 40 41	No connect GND No connect No connect No connect No connect DEVSLP GND No connect SATA-B+	No connect Ground No connect No connect No connect No connect No connect Device Sleep, Input. If driven high the host is informing the SSD to enter a low power state. Ground No connect Host receiver differential signal pair.
32 32 33 34 35 36 37 38 39 40 40 41 42	No connect GND No connect No connect No connect No connect DEVSLP GND No connect SATA-B+ No connect	No connect Ground No connect No connect No connect No connect No connect Device Sleep, Input. If driven high the host is informing the SSD to enter a low power state. Ground No connect Host receiver differential signal pair. No connect
31 32 33 34 35 36 37 38 39 40 40 41 42 43	No connect GND No connect No connect No connect No connect DEVSLP GND No connect SATA-B+ No connect SATA-B-	No connect Ground No connect No connect No connect No connect No connect Device Sleep, Input. If driven high the host is informing the SSD to enter a low power state. Ground No connect No connect No connect Device Sleep, Input. If driven high the host is informing the SSD to enter a low power state. Ground No connect Host receiver differential signal pair. No connect
31 32 33 34 35 36 37 38 39 40 41 42 43 44	No connect No connect GND No connect No connect No connect DEVSLP GND No connect SATA-B+ No connect SATA-B- No connect	No connect Ground No connect No connect No connect No connect No connect Device Sleep, Input. If driven high the host is informing the SSD to enter a low power state. Ground No connect No connect Host receiver differential signal pair. No connect No connect
31 32 33 34 35 36 37 38 39 40 41 42 43 44 45	No connect GND No connect No connect No connect No connect DEVSLP GND No connect SATA-B+ No connect SATA-B- No connect GND	No connect Ground No connect No connect No connect No connect No connect Device Sleep, Input. If driven high the host is informing the SSD to enter a low power state. Ground No connect Host receiver differential signal pair. No connect Host receiver differential signal pair. No connect Ground

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47	SATA-A-	Host transmitter differential pair.
48	No connect	No connect
49	SATA-A+	Host transmitter differential pair.
50	No connect	No connect
51	GND	Ground
52	No connect	No connect
53	No connect	No connect
54	No connect	No connect
55	No connect	No connect
56	No connect	No connect
57	GND	Ground
58	No connect	No connect
59	(removed for key)	Mechanical notch M
60	(removed for key)	Mechanical notch M
61	(removed for key)	Mechanical notch M
62	(removed for key)	Mechanical notch M
63	(removed for key)	Mechanical notch M
64	(removed for key)	Mechanical notch M
65	(removed for key)	Mechanical notch M
66	(removed for key)	Mechanical notch M
67	No connect	No connect
68	No connect	No connect
69	CONFIG_1	Ground
70	3.3 V	Supply pin, 3.3 V
71	GND	Ground
72	3.3 V	Supply pin, 3.3 V
73	GND	Ground
74	3.3 V	Supply pin, 3.3 V
75	CONFIG_2	Ground

[Table 5-2] SATA Pin Assignment

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6.0 SATA Interface

6.1 Out of bank signaling

The shall be tree Out Of Band (OOB) signals used/ detected by the Phy: COMRESET, COMINIT, and COMWAKE. Each burst is followed by idle periods (at common-mode levels), having durations as depicted in following Figure and Table. The COMWAKE OOB signaling is used to bring the Phy out of a power-down state (Partial or Slumber).

There shall be three Out Of Band (OOB) signals used/detected by the Phy: COMRESET, COMINIT, and COMWAKE. COMINIT, COMRESET and COMWAKE OOB signaling shall be achieved by transmission of either a burst of four Gen1 ALIGNP primitives or a burst composed of four Gen1 Dwords with each Dword composed of four D24.3 characters, each burst having duration of 160 UIOOB. Each burst is followed by idle periods (at common-mode levels), having durations as depicted in Figure 6-1 and Table 6-1.



[Figure 6-1] OOB signals

Time	Value	
T1	160 Uloob (106.7 ns nominal)	
T2	480 Uloob (320 ns nominal)	
Table C 41 COD Ginnel Times		

[Table 6-1] OOB Signal Times

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6.2 COMRESET sequence state diagram

COMRESET always originates from the host controller, and forces a hardware reset in the device. It is indicated by transmitting bursts of data separated by an idle bus condition. The OOB COMRESET signal shall consist of no less than six data bursts, including inter-burst temporal spacing. The COMRESET signal shall be:

1) Sustained/continued uninterrupted as long as the system hard reset is asserted, or 2) Started during the system hardware reset and ended sometime after the negation of system hardware reset, or 3) Transmitted immediately following the negation of the system hardware reset signal.

The host controller shall ignore any signal received from the device from the assertion of the hardware reset signal until the COMRESET signal is transmitted. Each burst shall be 160 Gen1 UI's long (106.7 ns) and each inter-burst idle state shall be 480 Gen1 UI's long (320 ns). A COMRESET detector looks for four consecutive bursts with 320 ns spacing (nominal). Any spacing less than 175 ns or greater than 525 ns shall invalidate the COMRESET detector output. The COMRESET interface signal to the PHY layer shall initiate the Reset sequence shown in Figure 6-2 below. The interface shall be held inactive for at least 525 ns after the last burst to ensure far-end detector detects the negation properly.



[Figure 6-2] COMRESET Sequence

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Description:

- 1. Host/device is powered and operating normally with some form of active communication.
- 2. Some condition in the host causes the host to issue COMRESET.
- 3. Host releases COMRESET. Once the condition causing the COMRESET is released, the host releases the COMRESET signal and puts the bus in a quiescent condition.
- 4. Device issues COMINIT –When the device detects the release of COMRESET, it responds with a COMINIT. This is also the entry point if the device is late starting. The device may initiate communications at any time by issuing a COMINIT.
- 5. Host calibrates and issues a COMWAKE.
- 6. Device responds –The device detects the COMWAKE sequence on its RX pair and calibrates its transmitter (optional). Following calibration the device sends a six burst COMWAKE sequence and then sends a continuous stream of the ALIGN sequence starting at the device's highest supported speed. After ALIGNP Dwords have been sent for 54.6us (2048 nominal Gen1 Dword times) without a response from the host as determined by detection of ALIGNP primitives received from the host, the device assumes that the host cannot communicate at that speed. If additional speeds are available the device tries the next lower supported speed by sending ALIGNP Dwords at that rate for 54.6 us (2048 nominal Gen1 Dword times.) This step is repeated for as many slower speeds as are supported. Once the lowest speed has been reached without response from the host, the device enters an error state.
- 7. Host locks –after detecting the COMWAKE, the host starts transmitting D10.2 characters (see 7.6) at its lowest supported rate. Meanwhile, the host receiver locks to the ALIGN sequence and, when ready, returns the ALIGN sequence to the device at the same speed as received. A host shall be designed such that it acquires lock in 54.6us (2048 nominal Gen1 Dword times) at any given speed. The host should allow for at least 873.8 us (32768 nominal Gen1 Dword times) after detecting the release of COMWAKE to receive the first ALIGNP. This ensures interoperability with multi-generational and synchronous designs. If no ALIGNP is received within 873.8 us (32768 nominal Gen1 Dword times) the host restarts the power-on sequence –repeating indefinitely until told to stop by the Application layer.
- 8. Device locks –the device locks to the ALIGN sequence and, when ready, sends SYNCP indicating it is ready to start normal operation.

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9. Upon receipt of three back-to-back non-ALIGNP primitives, the communication link is established and normal operation may begin.

6.3 COMINIT

COMINIT always originates from the drive and requests a communication initialization. It is electrically identical to the COMRESET signal except that it originates from the device and is sent to the host. It is used by the device to request a reset from the host in accordance to the sequence shown in Figure 6-3, below.



[Figure 6-3] COMINIT Sequence

Description:

- 1. Host/device is powered and operating normally with some form of active communication.
- 2. Some condition in the device causes the device to issues a COMINIT
- 3. Host calibrates and issues a COMWAKE.
- 4. Device responds –The device detects the COMWAKE sequence on its RX pair and calibrates its transmitter (optional). Following calibration the device sends a six burst COMWAKE sequence and then sends a continuous stream of the ALIGN sequence starting at the device's highest supported speed. After ALIGNP Dwords have been sent for 54.6 us (2048 nominal Gen1 Dword times) without a response from the host as determined by

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detection of ALIGNP primitives received from the host, the device assumes that the host cannot communicate at that speed. If additional speeds are available the device tries the next lower supported speed by sending ALIGNP Dwords at that rate for 54.6 us (2048 nominal Gen1 Dword times.) This step is repeated for as many slower speeds as are supported. Once the lowest speed has been reached without response from the host, the device enters an error state.

- 5. Host locks –after detecting the COMWAKE, the host starts transmitting D10.2 characters (see section 7.6) at its lowest supported rate. Meanwhile, the host receiver locks to the ALIGN sequence and, when ready, returns the ALIGN sequence to the device at the same speed as received. A host shall be designed such that it acquires lock in 54.6 us (2048 nominal Gen1 Dword times) at any given speed. The host should allow for at least 873.8 us (32768 nominal Gen1 Dword times) after detecting the release of COMWAKE to receive the first ALIGNP. This ensures interoperability with multi-generational and synchronous designs. If no ALIGNP is received within 873.8 us (32768 nominal Gen1 Dword times) the host restarts the power-on sequence -repeating indefinitely until told to stop by the Application layer.
- 6. Device locks -the device locks to the ALIGN sequence and, when ready, sends SYNCP indicating it is ready to start normal operation.
- 7. Upon receipt of three back-to-back non-ALIGNP primitives, the communication link is established and normal operation may begin.

6.4 Power on sequence timing diagram

The following timing diagrams and descriptions are provided for clarity and are informative. The state diagrams provided in section 7.4 comprise the normative behavior specification and is the ultimate reference.



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[Figure 6-4] Power on sequence

Description:

- 1. Host/device power-off -Host and device power-off.
- 2. Power is applied -Host side signal conditioning pulls TX and RX pairs to neutral state(common mode voltage).
- 3. Host issues COMRESET
- 4. Host releases COMRESET. Once the power-on reset is released, the host releases the COMRESET signal and puts the bus in a quiescent condition.
- 5. Device issues COMINIT –When the device detects the release of COMRESET, it responds with a COMINIT. This is also the entry point if the device is late starting. The device may initiate communications at any time by issuing a COMINIT.
- 6. Host calibrates and issues a COMWAKE.
- 7. Device responds –The device detects the COMWAKE sequence on its RX pair and calibrates its transmitter (optional). Following calibration the device sends a six burst COMWAKE sequence and then sends a continuous stream of the ALIGN sequence starting at the device's highest supported speed. After ALIGNP primitives have been sent for 54.6 us (2048 nominal Gen1 Dword times) without a response from the host as

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determined by detection of ALIGNP primitives received from the host, the device assumes that the host cannot communicate at that speed. If additional speeds are available the device tries the next lower supported speed by sending ALIGNP primitives at that rate for 54.6 us (2048 nominal Gen1 Dword times.) This step is repeated for as many slower speeds as are supported. Once the lowest speed has been reached without response from the host, the device shall enter an error state.

- 8. Host locks –after detecting the COMWAKE, the host starts transmitting D10.2characters (see 7.6) at its lowest supported rate. Meanwhile, the host receiver locks to the ALIGN sequence and, when ready, returns the ALIGN sequence to the device at the same speed as received. A host shall be designed such that it acquires lock in 54.6us (2048 nominal Gen1 Dword times) at any given speed. The host should allow for at least 873.8 us (32768 nominal Gen1 Dword times) after detecting the release of COMWAKE to receive the first ALIGNP. This insures interoperability with multi-generational and synchronous designs. If no ALIGNP is received within 873.8 us(32768 nominal Gen1 Dword times) the host restarts the power-on sequence –repeating indefinitely until told to stop by the Application layer.
- 9. Device locks –the device locks to the ALIGN sequence and, when ready, sends the SYNCP primitive indicating it is ready to start normal operation.
- 10. Upon receipt of three back-to-back non-ALIGNP primitives, the communication link is established and normal operation may begin.







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8.0 Label & Package Specifications **ADATA** IM2S3328E-128GM Capacity: 128GB FW Version: O1026A S/N: 2G1720062789 Made in China Rated Voltage/Current:3.3V --- 1.6A [Figure 8-1] Label 11pcs / Tray (PS) Anti-Static PE BAG The red areas can turn directly 200pcs msata/ 1Box (B Flute) 2 Box / Carton 400pcs msata / Carton (AB Flute) [Figure 8-2] Package ADATA Technology Co., Ltd. | www.adata-group.com T: +886-2-8228-0886 F: +886-2-8228-0887 2F, No. 258, Lian Cheng Rd., Chung Ho Dist., New Taipei City 235, Taiwan (R.O.C.)