

**TIBPAL16L8-10C, TIBPAL16R4-10C, TIBPAL16R6-10C, TIBPAL16R8-10C  
TIBPAL16L8-12M, TIBPAL16R4-12M, TIBPAL16R6-12M, TIBPAL16R8-12M  
HIGH-PERFORMANCE IMPACT-X™ PAL® CIRCUITS**

SRPS017A - D3023, MAY 1987 - REVISED DECEMBER 2010

- **High-Performance Operation:**
  - $f_{max}$  (w/o feedback)
    - TIBPAL16R'-10C Series . . . 62.5 MHz Min
    - TIBPAL16R'-12M Series . . . 56 MHz Min
  - $f_{max}$  (with feedback)
    - TIBPAL16R'-10C Series . . . 55.5 MHz Min
    - TIBPAL16R'-12M Series . . . 48 MHz Min
- **Functionally Equivalent, but Faster than, Existing 20-Pin PLDs**
- **Preload Capability on Output Registers**  
Simplifies Testing
- **Power-Up Clear on Registered Devices (All Register Outputs are Set Low, but Voltage Levels at the Output Pins Go High)**
- **Package Options Include Both Plastic and Ceramic Chip Carriers in Addition to Plastic and Ceramic DIPs**
- **Security Fuse Prevents Duplication**
- **Dependable Texas Instruments Quality and Reliability**

DEVICE	I INPUTS	3-STATE O OUTPUTS	REGISTERED Q OUTPUTS	I/O PORTS
PAL16L8	10	2	0	6
PAL16R4	8	0	4 (3-state buffers)	4
PAL16R6	8	0	6 (3-state buffers)	2
PAL16R8	8	0	8 (3-state buffers)	0

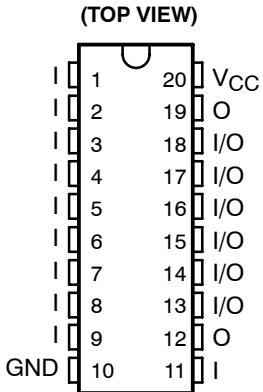
## description

These programmable array logic devices feature high speed and functional equivalency when compared with currently available devices. These IMPACT-X™ circuits combine the latest Advanced Low-Power Schottky technology with proven titanium-tungsten fuses to provide reliable, high-performance substitutes for conventional TTL logic. Their easy programmability allows for quick design of custom functions and typically results in a more compact circuit board. In addition, chip carriers are available for further reduction in board space.

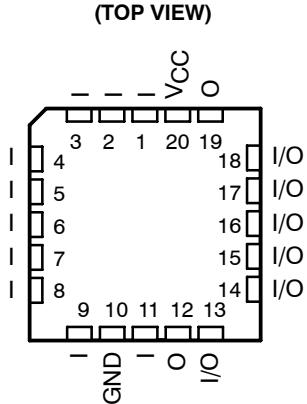
All of the register outputs are set to a low level during power up. Extra circuitry has been provided to allow loading of each register asynchronously to either a high or low state. This feature simplifies testing because the registers can be set to an initial state prior to executing the test sequence.

The TIBPAL16' C series is characterized from 0°C to 75°C. The TIBPAL16' M series is characterized for operation over the full military temperature range of -55°C to 125°C.

**TIBPAL16L8'**  
C SUFFIX . . . J OR N PACKAGE  
M SUFFIX . . . J PACKAGE



**TIBPAL16L8'**  
C SUFFIX . . . FN PACKAGE  
M SUFFIX . . . FK PACKAGE



Pin assignments in operating mode

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PAL is a registered trademark of Advanced Micro Devices Inc.

PRODUCTION DATA information is current as of publication date.  
Products conform to specifications per the terms of Texas Instruments standard warranty. Production processing does not necessarily include testing of all parameters.

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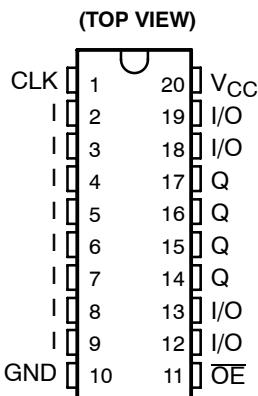
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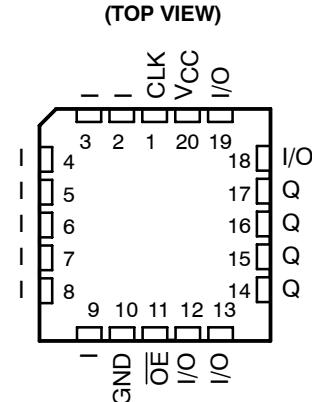
# **TIBPAL16R4-10C, TIBPAL16R6-10C, TIBPAL16R8-10C TIBPAL16R4-12M, TIBPAL16R6-12M, TIBPAL16R8-12M HIGH-PERFORMANCE *IMPACT-X*™ PAL® CIRCUITS**

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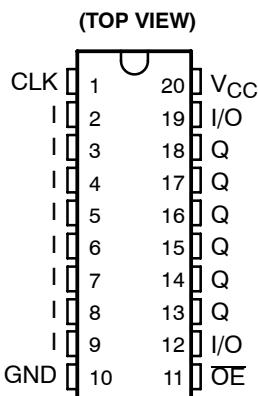
**TIBPAL16R4'**  
**C SUFFIX . . . J OR N PACKAGE**  
**M SUFFIX . . . J PACKAGE**



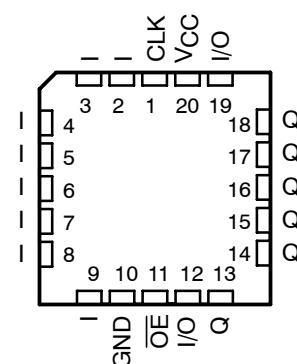
TIBPAL16R4'  
C SUFFIX . . . FN PACKAGE  
M SUFFIX . . . FK PACKAGE



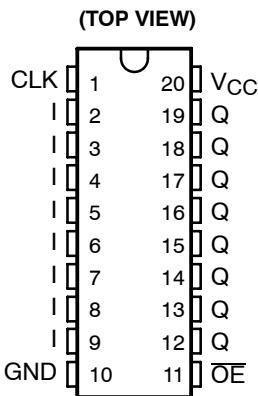
TIBPAL16R6'  
C SUFFIX . . . J OR N PACKAGE  
M SUFFIX . . . J PACKAGE



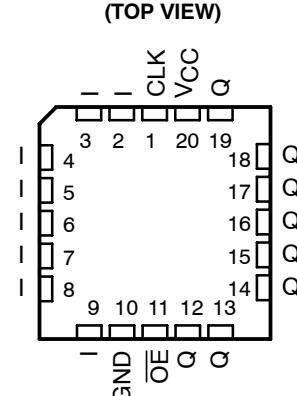
TIBPAL16R6'  
C SUFFIX . . . FN PACKAGE  
M SUFFIX . . . FK PACKAGE



TIBPAL16R8'  
C SUFFIX . . . J OR N PACKAGE  
M SUFFIX . . . J PACKAGE



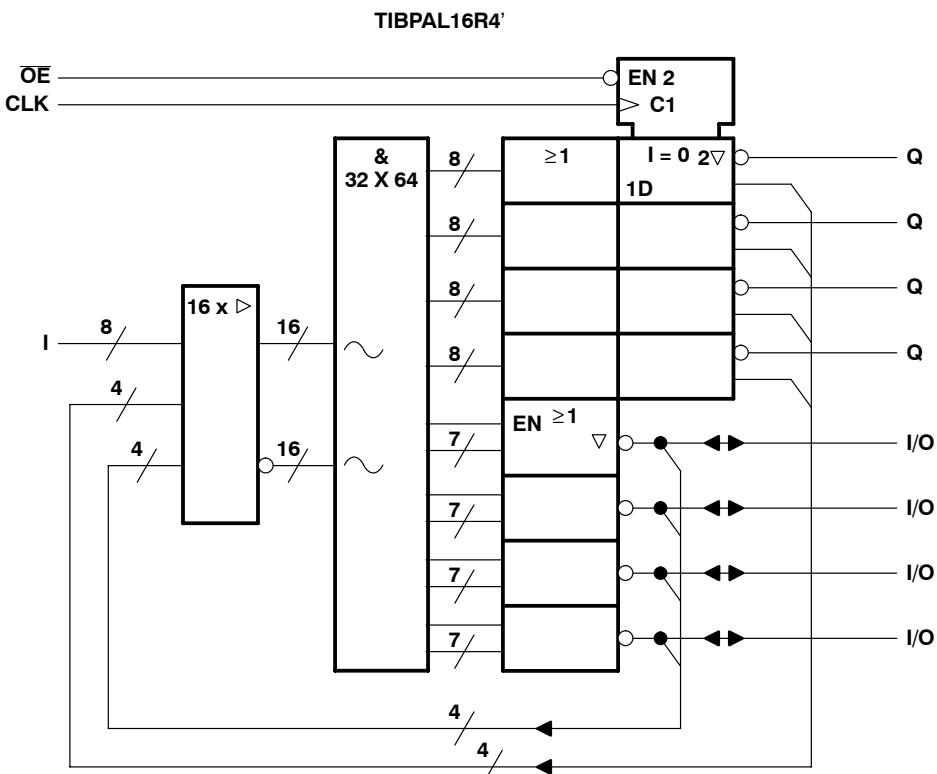
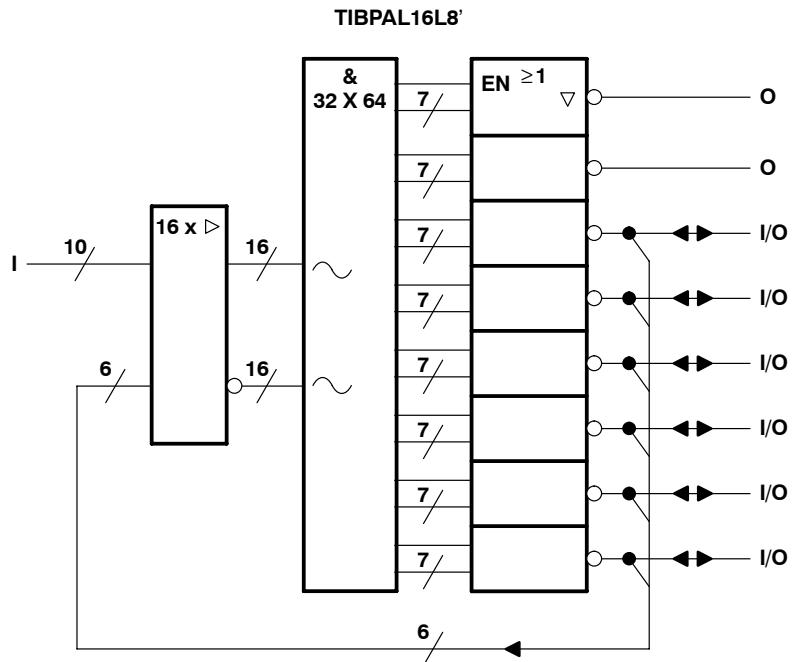
TIBPAL16R8'  
C SUFFIX . . . FN PACKAGE  
M SUFFIX . . . FK PACKAGE



### Pin assignments in operating mode



**functional block diagrams (positive logic)**



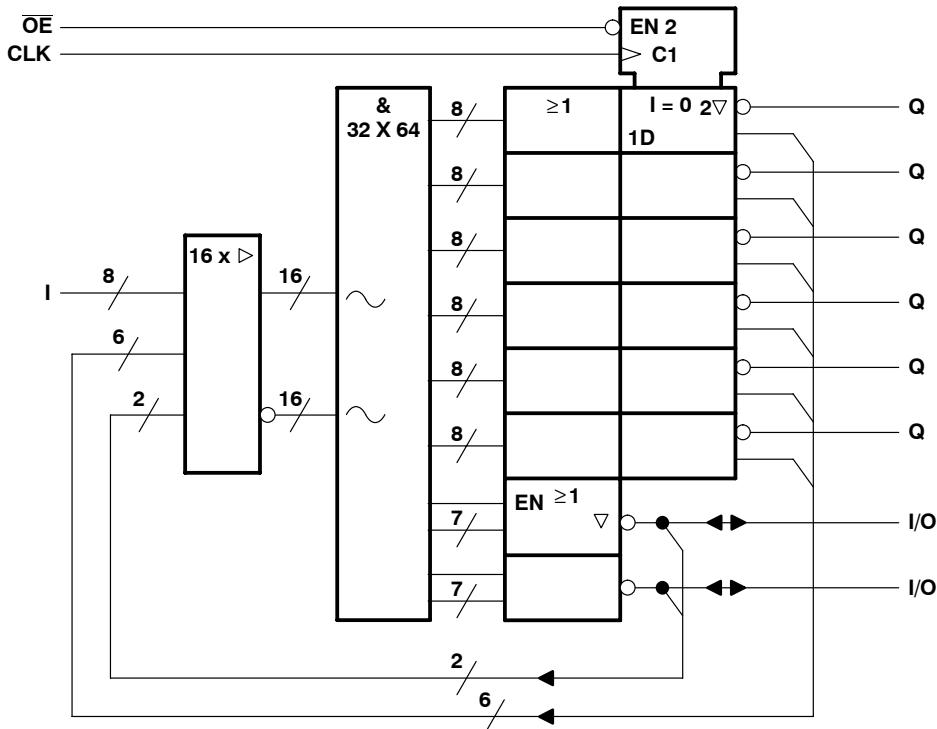
~ denotes fused inputs

**TIBPAL16R6-10C, TIBPAL16R8-10C****TIBPAL16R6-12M, TIBPAL16R8-12M****HIGH-PERFORMANCE IMPACT-X™ PAL® CIRCUITS**

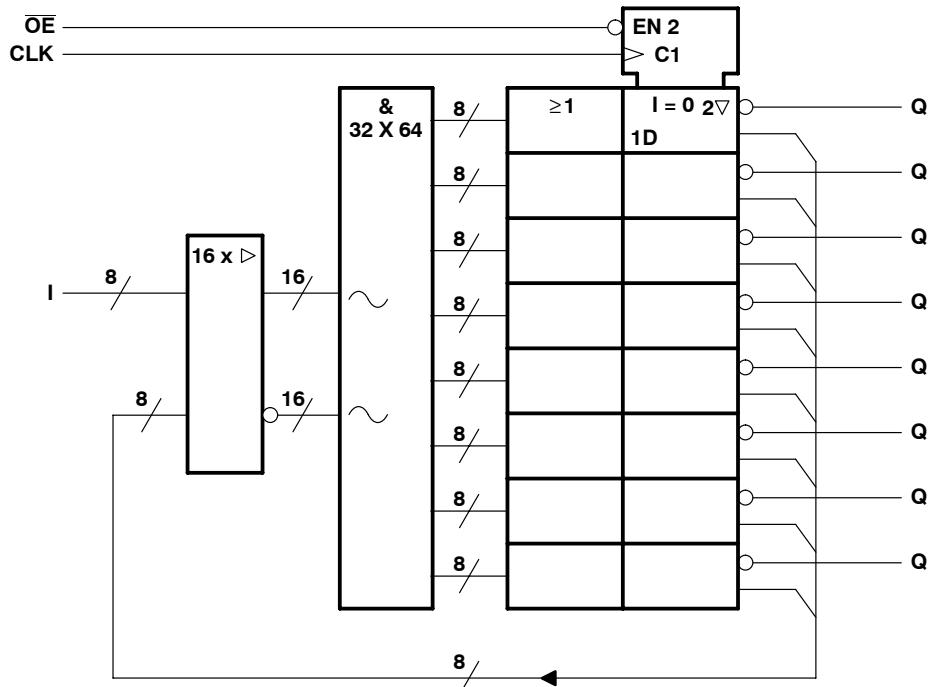
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**functional block diagrams (positive logic)**

TIBPAL16R6'



TIBPAL16R8'

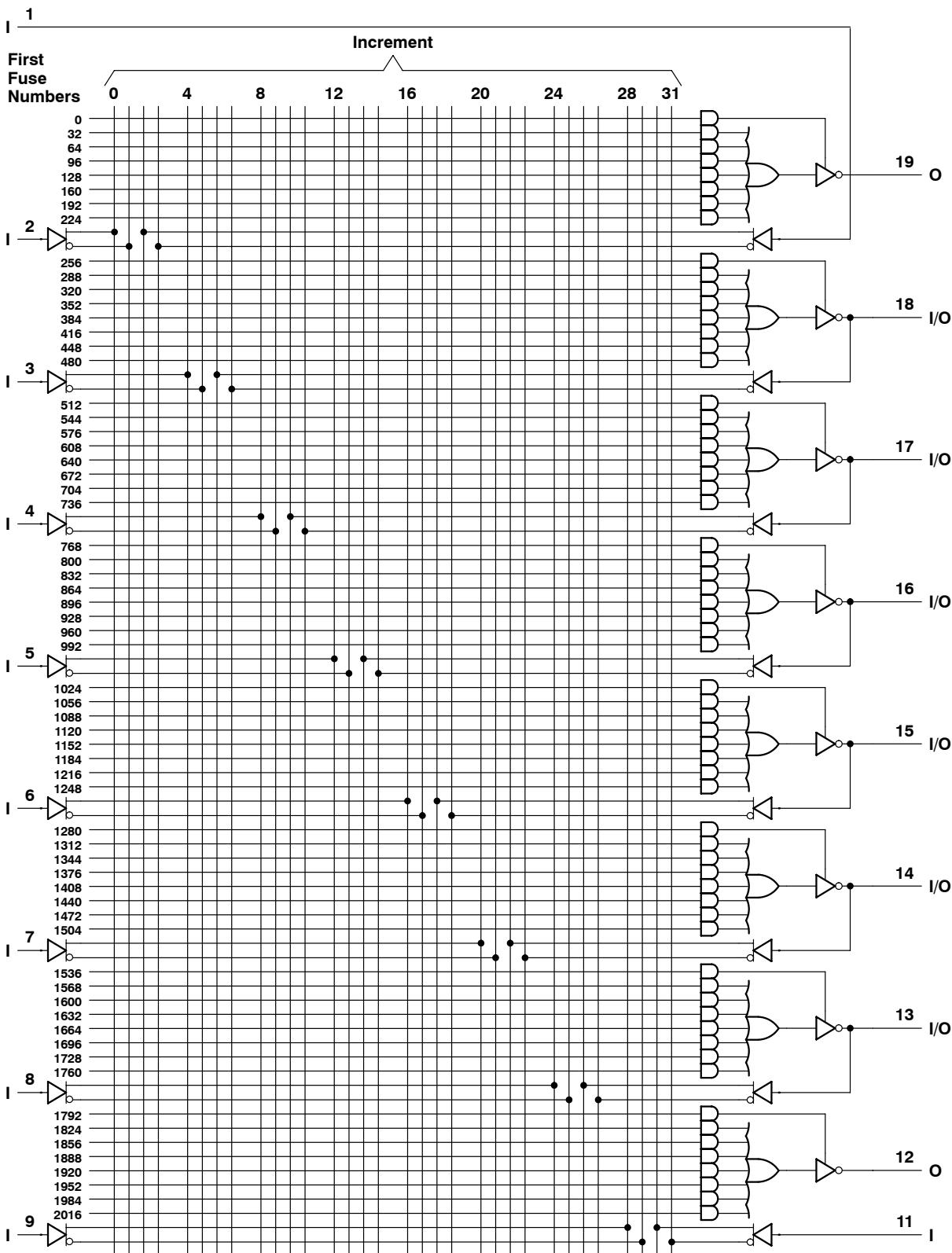


~ denotes fused inputs

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## logic diagram (positive logic)

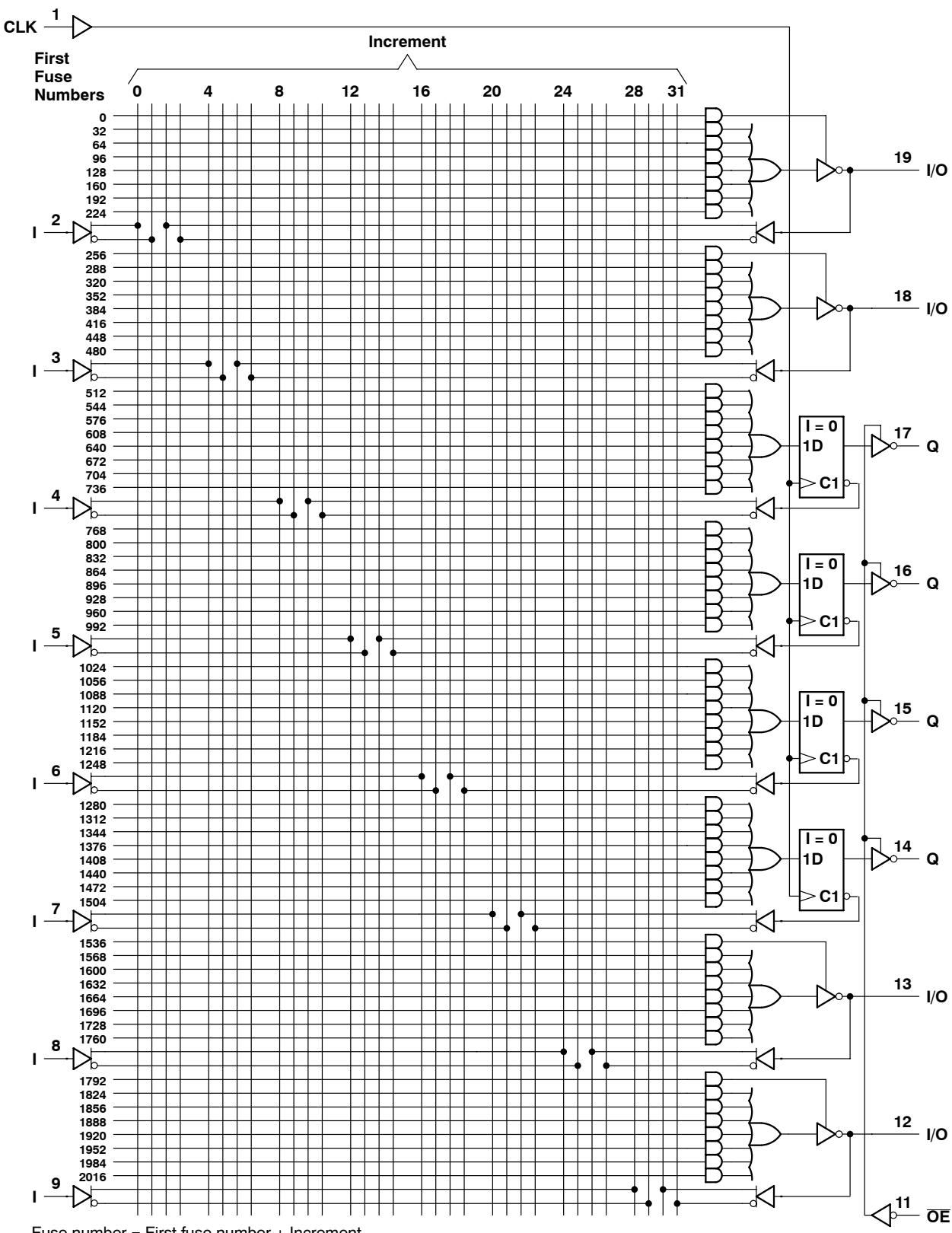


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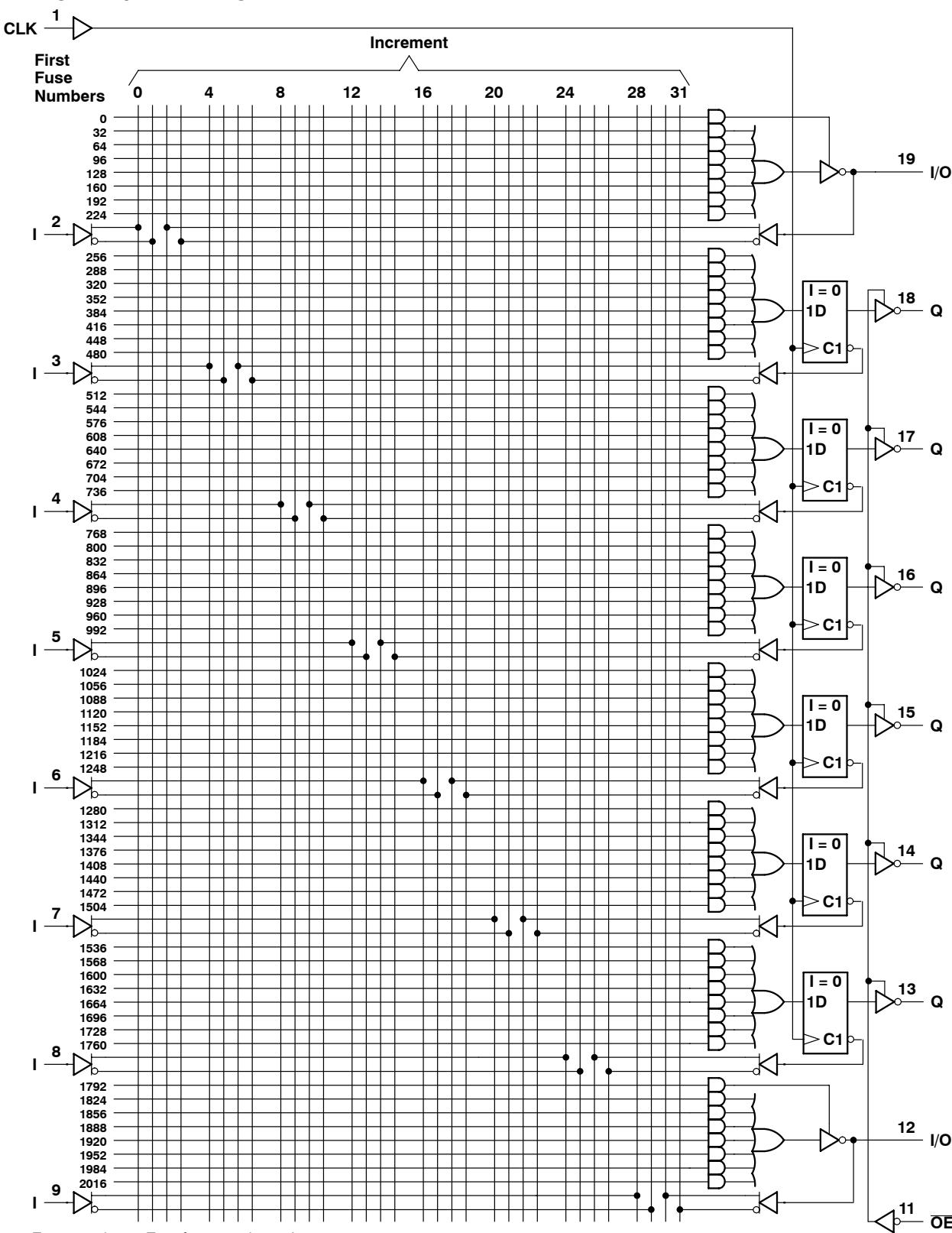
**TIBPAL16R4-10C****TIBPAL16R4-12M****HIGH-PERFORMANCE IMPACT-X™ PAL® CIRCUITS**

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**logic diagram (positive logic)**
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## logic diagram (positive logic)



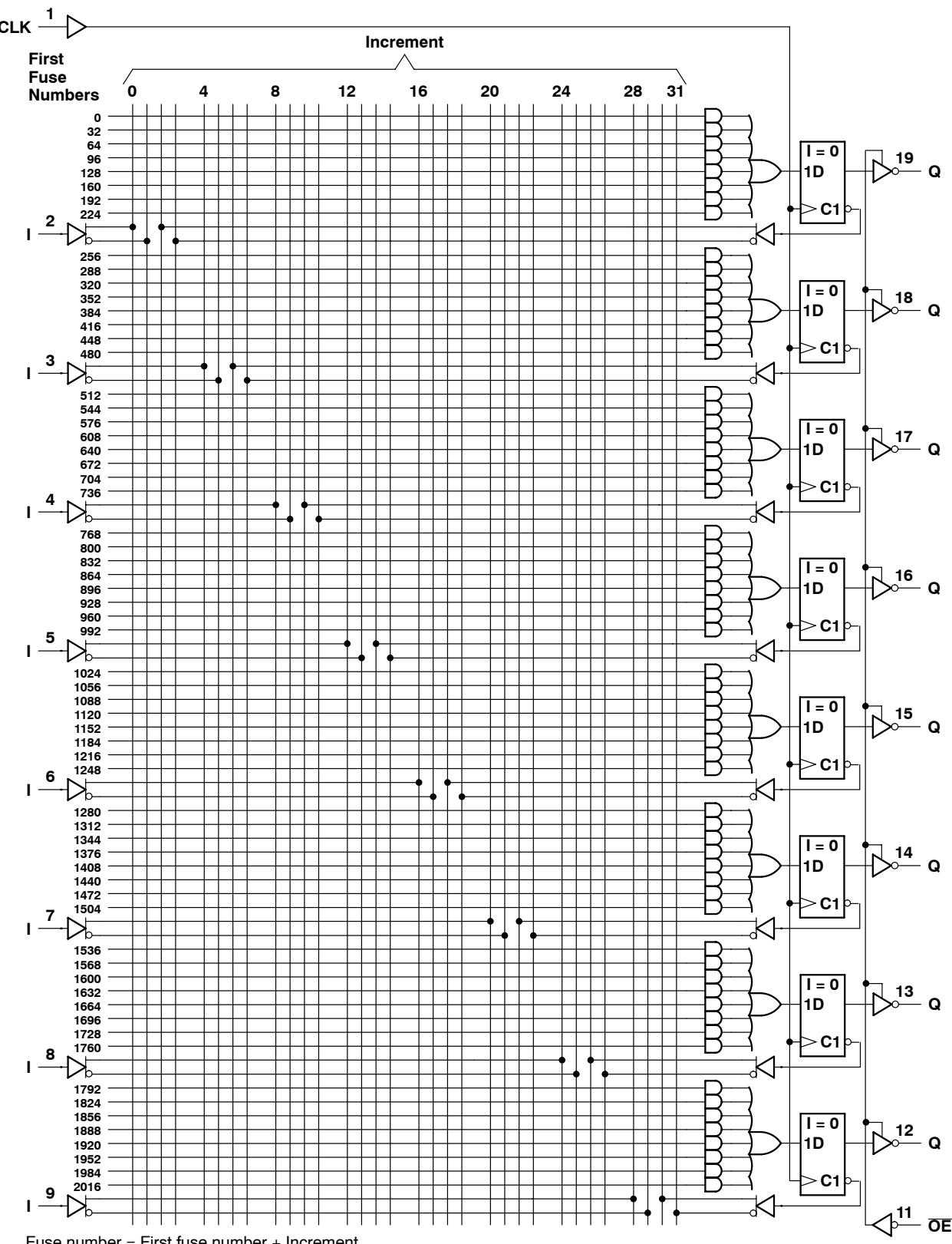
Fuse number = First fuse number + Increment

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**TIBPAL16R8-10C****TIBPAL16R8-12M****HIGH-PERFORMANCE IMPACT-X™ PAL® CIRCUITS**

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**logic diagram (positive logic)**
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# TIBPAL16L8-10C, TIBPAL16R4-10C, TIBPAL16R6-10C, TIBPAL16R8-10C

## HIGH-PERFORMANCE *IMPACT-X*™ *PAL*® CIRCUITS

SRPS017A – D3023, MAY 1987 – REVISED DECEMBER 2010

### absolute maximum ratings over operating free-air temperature range (unless otherwise noted)

Supply voltage, $V_{CC}$ (see Note 1) .....	7 V
Input voltage (see Note 1) .....	5.5 V
Voltage applied to disabled output (see Note 1) .....	5.5 V
Operating free-air temperature range .....	0°C to 75°C
Storage temperature range .....	-65°C to 150°C

NOTE 1: These ratings apply except for programming pins during a programming cycle.

### recommended operating conditions

		MIN	NOM	MAX	UNIT
$V_{CC}$	Supply voltage	4.75	5	5.25	V
$V_{IH}$	High-level input voltage (see Note 2)	2	5.5	5.5	V
$V_{IL}$	Low-level input voltage (see Note 2)		0.8	0.8	V
$I_{OH}$	High-level output current		-3.2	-3.2	mA
$I_{OL}$	Low-level output current		24	24	mA
$f_{clock}$	Clock frequency	0	62.5	62.5	MHz
$t_w$	Pulse duration, clock (see Note 2)	High	8	8	ns
		Low	8	8	
$t_{su}$	Setup time, input or feedback before clock↑	10		10	ns
$t_h$	Hold time, input or feedback after clock↑	0		0	ns
$T_A$	Operating free-air temperature	0	25	75	°C

NOTE 2: These are absolute voltage levels with respect to the ground pin of the device and include all overshoots due to system and/or tester noise. Testing these parameters should not be attempted without suitable equipment.

### electrical characteristics over recommended operating free-air temperature range

PARAMETER	TEST CONDITIONS	MIN	TYP <sup>†</sup>	MAX	UNIT
$V_{IK}$	$V_{CC} = 4.75$ V, $I_I = -18$ mA		-0.8	-1.5	V
$V_{OH}$	$V_{CC} = 4.75$ V, $I_{OH} = -3.2$ mA	2.4	3.2	3.2	V
$V_{OL}$	$V_{CC} = 4.75$ V, $I_{OL} = 24$ mA		0.3	0.5	V
$I_{OZH}^{\ddagger}$	$V_{CC} = 5.25$ V, $V_O = 2.4$ V		100	100	μA
$I_{OZL}^{\ddagger}$	$V_{CC} = 5.25$ V, $V_O = 0.4$ V		-100	-100	μA
$I_I$	$V_{CC} = 5.25$ V, $V_I = 5.5$ V		0.2	0.2	mA
$I_{IH}^{\ddagger}$	$V_{CC} = 5.25$ V, $V_I = 2.4$ V		25	25	μA
$I_{IL}^{\ddagger}$	$V_{CC} = 5.25$ V, $V_I = 0.4$ V	-0.08	-0.25	-0.25	mA
$I_{OS}^{\$}$	$V_{CC} = 5.25$ V, $V_O = 0$	-30	-70	-130	mA
$I_{CC}$	$V_{CC} = 5.25$ V, $V_I = 0$ , Outputs open	140	180	180	mA
$C_i$	$f = 1$ MHz, $V_I = 2$ V	5		5	pF
$C_o$	$f = 1$ MHz, $V_O = 2$ V	6		6	pF
$C_{i/o}$	$f = 1$ MHz, $V_{I/O} = 2$ V	7.5		7.5	pF
$C_{clk}$	$f = 1$ MHz, $V_{CLK} = 2$ V	6		6	pF

<sup>†</sup> All typical values are at  $V_{CC} = 5$  V,  $T_A = 25^\circ\text{C}$ .

<sup>‡</sup> I/O leakage is the worst case of  $I_{OZL}$  and  $I_{IL}$  or  $I_{OZH}$  and  $I_{IH}$  respectively.

<sup>§</sup> Not more than one output should be shorted at a time, and the duration of the short circuit should not exceed one second.



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**TIBPAL16L8-10C, TIBPAL16R4-10C, TIBPAL16R6-10C, TIBPAL16R8-10C**  
**HIGH-PERFORMANCE *IMPACT-X*™ PAL® CIRCUITS**

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**switching characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)**

PARAMETER	FROM (INPUT)	TO (OUTPUT)	TEST CONDITION	MIN	TYP <sup>†</sup>	MAX	UNIT
$f_{max}$	With feedback		R1 = 200 $\Omega$ , R2 = 390 $\Omega$ , See Figure 3	55.5	80		MHz
	Without feedback			62.5	85		
$t_{pd}$	I, I/O	O, I/O		3	7	10	ns
$t_{pd}$	CLK $\uparrow$	Q		2	5	8	ns
$t_{en}$	OE $\downarrow$	Q		1	4	10	ns
$t_{dis}$	OE $\uparrow$	Q		1	4	10	ns
$t_{en}$	I, I/O	O, I/O		3	8	10	ns
$t_{dis}$	I, I/O	O, I/O		3	8	10	ns

<sup>†</sup> All typical values are at  $V_{CC} = 5$  V,  $T_A = 25^\circ\text{C}$ .

<sup>‡</sup>  $f_{max}(\text{with feedback}) = \frac{1}{t_{su} + t_{pd}(\text{CLK to Q})}$ ,  $f_{max}(\text{without feedback}) = \frac{1}{t_w \text{ high} + t_w \text{ low}}$



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# TIBPAL16L8-12M, TIBPAL16R4-12M, TIBPAL16R6-12M, TIBPAL16R8-12M

## HIGH-PERFORMANCE *IMPACT-X*™ *PAL*® CIRCUITS

SRPS017D – D3023, MAY 1987 – REVISED DECEMBER 2010

### absolute maximum ratings over operating free-air temperature range (unless otherwise noted)

Supply voltage, $V_{CC}$ (see Note 1) .....	7 V
Input voltage (see Note 1) .....	5.5 V
Voltage applied to disabled output (see Note 1) .....	5.5 V
Operating free-air temperature range .....	-55°C to 125°C
Storage temperature range .....	-65°C to 150°C

NOTE 1: These ratings apply except for programming pins during a programming cycle.

### recommended operating conditions

		MIN	NOM	MAX	UNIT
$V_{CC}$	Supply voltage	4.5	5	5.5	V
$V_{IH}$	High-level input voltage	2	5.5	5.5	V
$V_{IL}$	Low-level input voltage		0.8	0.8	V
$I_{OH}$	High-level output current		-2	-2	mA
$I_{OL}$	Low-level output current		12	12	mA
$f_{clock}^{\dagger}$	Clock frequency	0	56	56	MHz
$t_w$	Pulse duration, clock (see Note 2)	High	9	9	ns
		Low	9	9	
$t_{su}^{\dagger}$	Setup time, input or feedback before clock↑	11	11	11	ns
$t_h^{\dagger}$	Hold time, input or feedback after clock↑	0	0	0	ns
$T_A$	Operating free-air temperature	-55	25	125	°C

NOTE 2: These are absolute voltage levels with respect to the ground pin of the device and include all overshoots due to system and/or tester noise. Testing these parameters should not be attempted without suitable equipment.

### electrical characteristics over recommended operating free-air temperature range

PARAMETER	TEST CONDITIONS	MIN	TYP <sup>†</sup>	MAX	UNIT
$V_{IK}$	$V_{CC} = 4.5$ V, $I_I = -18$ mA		-0.8	-1.5	V
$V_{OH}$	$V_{CC} = 4.5$ V, $I_{OH} = -2$ mA	2.4	3.2	3.2	V
$V_{OL}$	$V_{CC} = 4.5$ V, $I_{OL} = 12$ mA		0.3	0.5	V
$I_{OZH}^{\ddagger}$	$V_{CC} = 5.5$ V, $V_O = 2.4$ V		100	100	µA
$I_{OZL}^{\ddagger}$	$V_{CC} = 5.5$ V, $V_O = 0.4$ V		-100	-100	µA
$I_I$	$V_{CC} = 5.5$ V, $V_I = 5.5$ V		0.2	0.2	mA
$I_{IH}^{\ddagger}$	$V_{CC} = 5.5$ V, $V_I = 2.4$ V		25	25	µA
$I_{IL}^{\ddagger}$	$V_{CC} = 5.5$ V, $V_I = 0.4$ V		-0.08	-0.25	mA
$I_{OS}^{\$}$	$V_{CC} = 5.5$ V, $V_O = 0.5$ V	-30	-70	-250	mA
$I_{CC}$	$V_{CC} = 5.5$ V, $V_I = GND$ , Outputs open	140	140	220	mA
$C_I$	$f = 1$ MHz, $V_I = 2$ V		5	5	pF
$C_O$	$f = 1$ MHz, $V_O = 2$ V		6	6	pF
$C_{i/o}$	$f = 1$ MHz, $V_{I/O} = 2$ V		7.5	7.5	pF
$C_{clk}$	$f = 1$ MHz, $V_{CLK} = 2$ V		6	6	pF

<sup>†</sup> All typical values are at  $V_{CC} = 5$  V,  $T_A = 25^{\circ}\text{C}$ .

<sup>‡</sup> I/O leakage is the worst case of  $I_{OZL}$  and  $I_{IL}$  or  $I_{OZH}$  and  $I_{IH}$  respectively.

<sup>\$</sup> Not more than one output should be shorted at a time, and the duration of the short circuit should not exceed one second.  $V_O$  is set at 0.5 V to avoid test problems caused by test equipment ground degradation.



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**TIBPAL16L8-12M, TIBPAL16R4-12M, TIBPAL16R6-12M, TIBPAL16R8-12M**  
**HIGH-PERFORMANCE *IMPACT-X*™ PAL® CIRCUITS**

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**switching characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)**

PARAMETER	FROM (INPUT)	TO (OUTPUT)	TEST CONDITION	MIN	TYP <sup>†</sup>	MAX	UNIT
$f_{max}$	With feedback		R1 = 390 $\Omega$ , R2 = 750 $\Omega$ , See Figure 3	48	80		MHz
	Without feedback			56	85		
$t_{pd}$	I, I/O	O, I/O		3	7	12	ns
$t_{pd}$	CLK $\uparrow$	Q		2	5	10	ns
$t_{en}$	OE $\downarrow$	Q		1	4	10	ns
$t_{dis}$	OE $\uparrow$	Q		1	4	10	ns
$t_{en}$	I, I/O	O, I/O		3	8	14	ns
$t_{dis}$	I, I/O	O, I/O		2	8	12	ns

<sup>†</sup> All typical values are at  $V_{CC} = 5$  V,  $T_A = 25^\circ\text{C}$ .

$$^{\ddagger} f_{max}(\text{with feedback}) = \frac{1}{t_{su} + t_{pd} \text{ (CLK to Q)}}, f_{max}(\text{without feedback}) = \frac{1}{t_w \text{ high} + t_w \text{ low}}$$



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## programming information

Texas Instruments programmable logic devices can be programmed using widely available software and inexpensive device programmers.

Complete programming specifications, algorithms, and the latest information on hardware, software, and firmware are available upon request. Information on programmers capable of programming Texas Instruments programmable logic is also available, upon request, from the nearest TI field sales office, local authorized TI distributor, or by calling Texas Instruments at (214) 997-5666.

### preload procedure for registered outputs (see Figure 1 and Note 3)

The output registers can be preloaded to any desired state during device testing. This permits any state to be tested without having to step through the entire state-machine sequence. Each register is preloaded individually by following the steps given below.

- Step 1. With  $V_{CC}$  at 5 volts and Pin 1 at  $V_{IL}$ , raise Pin 11 to  $V_{IHH}$ .
- Step 2. Apply either  $V_{IL}$  or  $V_{IH}$  to the output corresponding to the register to be preloaded.
- Step 3. Pulse Pin 1, clocking in preload data.
- Step 4. Remove output voltage, then lower Pin 11 to  $V_{IL}$ . Preload can be verified by observing the voltage level at the output pin.

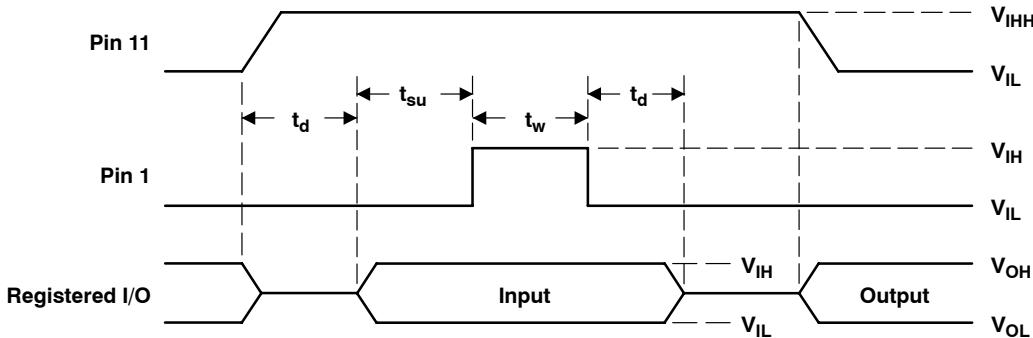


Figure 1. Preload Waveforms

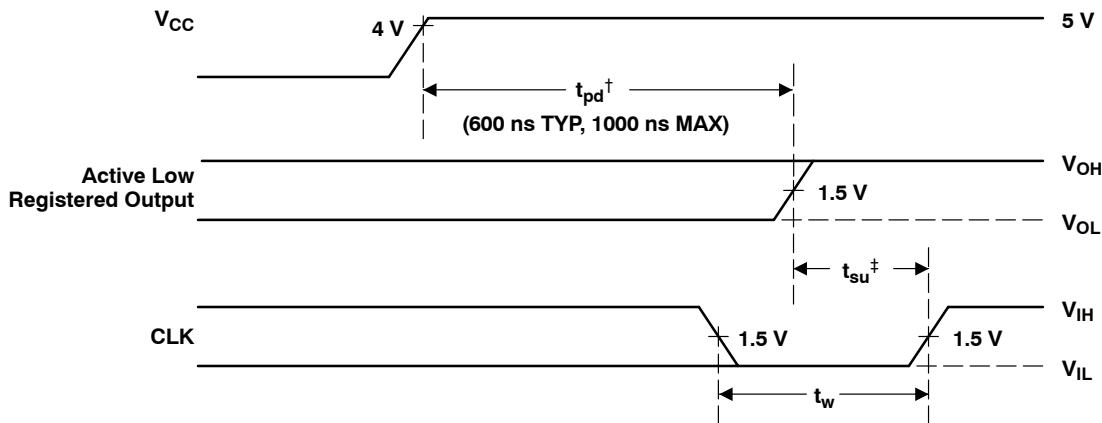
NOTE 3:  $t_d = t_{su} = t_h = 100$  ns to 1000 ns  $V_{IHH} = 10.25$  V to 10.75 v

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HIGH-PERFORMANCE IMPACT-X™ PAL® CIRCUITS**

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**power-up reset (see Figure 2)**

Following power up, all registers are reset to zero. This feature provides extra flexibility to the system designer and is especially valuable in simplifying state-machine initialization. To ensure a valid power-up reset, it is important that the rise of  $V_{CC}$  be monotonic. Following power-up reset, a low-to-high clock transition must not occur until all applicable input and feedback setup times are met.

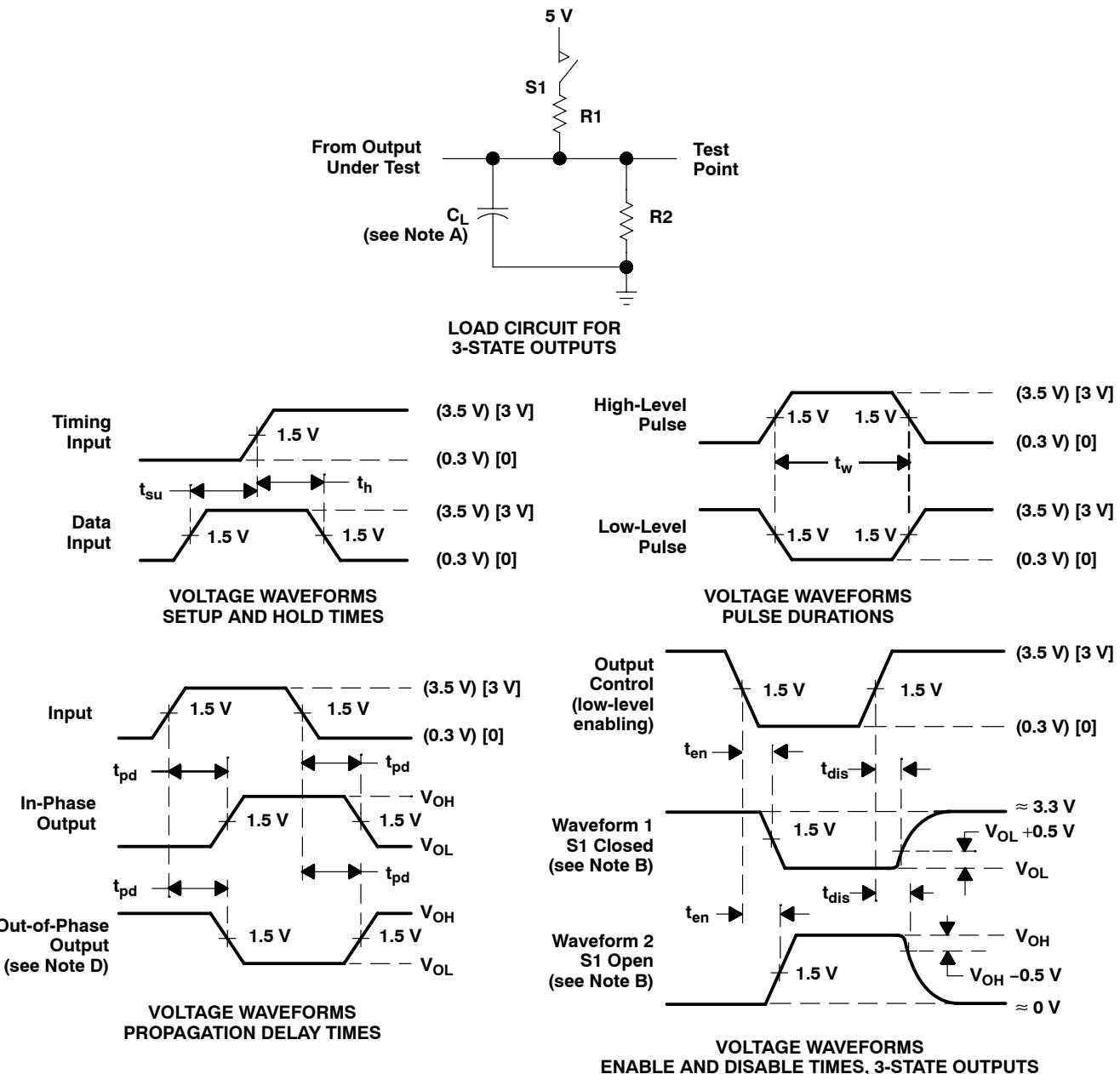


† This is the power-up reset time and applies to registered outputs only. The values shown are from characterization data.

‡ This is the setup time for input or feedback.

**Figure 2. Power-Up Reset Waveforms**

## PARAMETER MEASUREMENT INFORMATION



NOTES:

- A.  $C_L$  includes probe and jig capacitance and is 50 pF for  $t_{pd}$  and  $t_{en}$ , 5 pF for  $t_{dis}$ .
- B. Waveform 1 is for an output with internal conditions such that the output is low except when disabled by the output control. Waveform 2 is for an output with internal conditions such that the output is high except when disabled by the output control.
- C. All input pulses have the following characteristics: For C suffix, use the voltage levels indicated in parentheses ( ), PRR  $\leq$  1 MHz,  $t_r = t_f = 2$  ns, duty cycle = 50%; For M suffix, use the voltage levels indicated in brackets [ ], PRR  $\leq$  10 MHz,  $t_r$  and  $t_f \leq 2$  ns, duty cycle = 50%
- D. When measuring propagation delay times of 3-state outputs, switch S1 is closed.
- E. Equivalent loads may be used for testing.

**Figure 3. Load Circuit and Voltage Waveforms**

# TIBPAL16R4-10C, TIBPAL16R6-10C, TIBPAL16R8-10C

## HIGH-PERFORMANCE *IMPACT-X*™ PAL® CIRCUITS

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### metastable characteristics of TIBPAL16R4-10C, TIBPAL16R6-10C, and TIBPAL16R8-10C

At some point a system designer is faced with the problem of synchronizing two digital signals operating at two different frequencies. This problem is typically overcome by synchronizing one of the signals to the local clock through use of a flip-flop. However, this solution presents an awkward dilemma since the setup and hold time specifications associated with the flip-flop are sure to be violated. The metastable characteristics of the flip-flop can influence overall system reliability.

Whenever the setup and hold times of a flip-flop are violated, its output response becomes uncertain and is said to be in the metastable state if the output hangs up in the region between  $V_{IL}$  and  $V_{IH}$ . This metastable condition lasts until the flip-flop falls into one of its two stable states, which takes longer than the specified maximum propagation delay time (CLK to Q max).

From a system engineering standpoint, a designer cannot use the specified data sheet maximum for propagation delay time when using the flip-flop as a data synchronizer – how long to wait after the specified data sheet maximum must be known before using the data in order to guarantee reliable system operation.

The circuit shown in Figure 4 can be used to evaluate MTBF (Mean Time Between Failure) and  $\Delta t$  for a selected flip-flop. Whenever the Q output of the DUT is between 0.8 V and 2 V, the comparators are in opposite states. When the Q output of the DUT is higher than 2 V or lower than 0.8 V, the comparators are at the same logic level. The outputs of the two comparators are sampled a selected time ( $\Delta t$ ) after SCLK. The exclusive OR gate detects the occurrence of a failure and increments the failure counter.

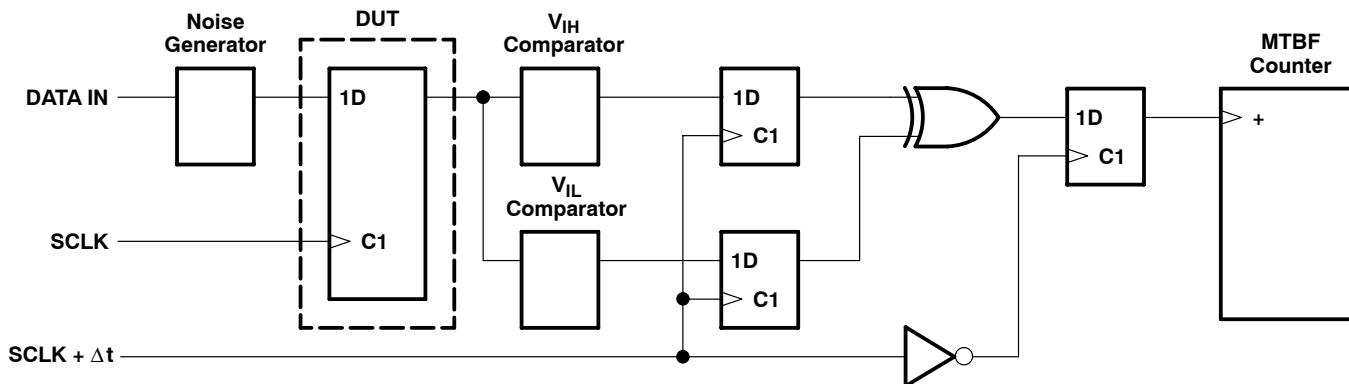


Figure 4. Metastable Evaluation Test Circuit

In order to maximize the possibility of forcing the DUT into a metastable state, the input data signal is applied so that it always violates the setup and hold time. This condition is illustrated in the timing diagram in Figure 5. Any other relationship of SCLK to data will provide less chance for the device to enter into the metastable state.

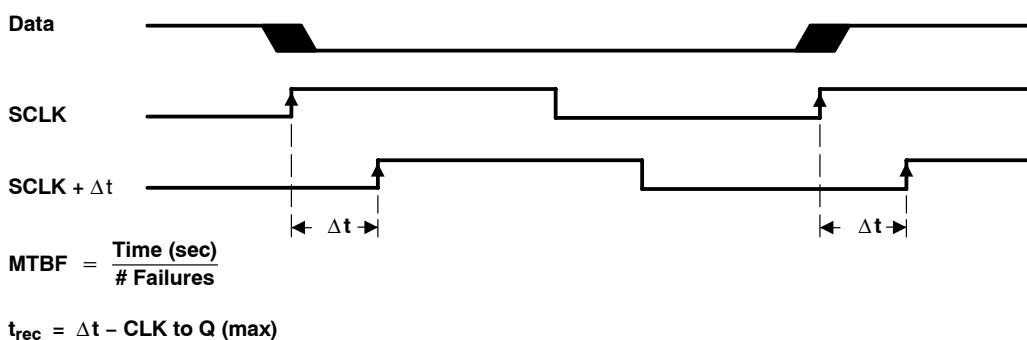
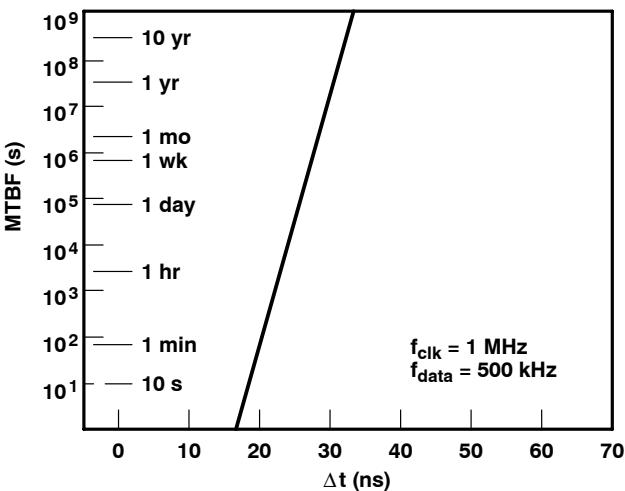


Figure 5. Timing Diagram

By using the described test circuit, MTBF can be determined for several different values of  $\Delta t$  (see Figure 4). Plotting this information on semilog scale demonstrates the metastable characteristics of the selected flip-flop. Figure 6 shows the results for the TIBPAL16'-10C operating at 1 MHz.



**Figure 6. Metastable Characteristics**

From the data taken in the above experiment, an equation can be derived for the metastable characteristics at other clock frequencies.

The metastable equation:  $\frac{1}{MTBF} = f_{SCLK} \times f_{data} \times C1 e^{-C2 \times \Delta t}$

The constants C1 and C2 describe the metastable characteristics of the device. From the experimental data, these constants can be solved for:  $C1 = 9.15 \times 10^{-7}$  and  $C2 = 0.959$

Therefore

$$\frac{1}{MTBF} = f_{SCLK} \times f_{data} \times 9.15 \times 10^{-7} e^{-0.959 \times \Delta t}$$

### definition of variables

DUT (Device Under Test): The DUT is a 10-ns registered PLD programmed with the equation  $Q := D$ .

MTBF (Mean Time Between Failures): The average time (s) between metastable occurrences that cause a violation of the device specifications.

$f_{SCLK}$  (system clock frequency): Actual clock frequency for the DUT.

$f_{data}$  (data frequency): Actual data frequency for a specified input to the DUT.

C1: Calculated constant that defines the magnitude of the curve.

C2: Calculated constant that defines the slope of the curve.

$t_{rec}$  (metastability recovery time): Minimum time required to guarantee recovery from metastability, at a given MTBF failure rate.  $t_{rec} = \Delta t - t_{pd}$  (CLK to Q, max)

$\Delta t$ : The time difference (ns) from when the synchronizing flip-flop is clocked to when its output is sampled.

The test described above has shown the metastable characteristics of the TIBPAL16R4/R6/R8-10C series. For additional information on metastable characteristics of Texas Instruments logic circuits, please refer to TI Applications publication SDAA004, "Metastable Characteristics, Design Considerations for ALS, AS, and LS Circuits."

**TIBPAL16L8-10C, TIBPAL16R4-10C, TIBPAL16R6-10C, TIBPAL16R8-10C  
 TIBPAL16L8-12M, TIBPAL16R4-12M, TIBPAL16R6-12M, TIBPAL16R8-12M  
 HIGH-PERFORMANCE IMPACT-X™ PAL® CIRCUITS**

SRPS017A - D3023, MAY 1987 - REVISED DECEMBER 2010

**TYPICAL CHARACTERISTICS**

**PROPAGATION DELAY TIME  
 vs  
 FREE-AIR TEMPERATURE**

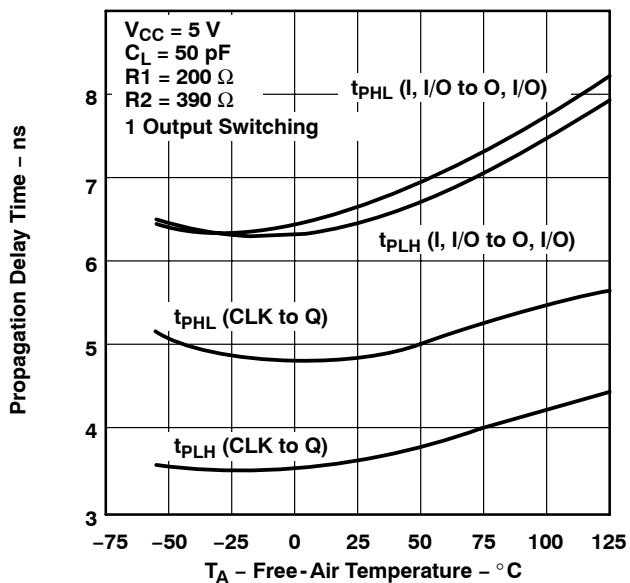


Figure 7

**PROPAGATION DELAY TIME  
 vs  
 SUPPLY VOLTAGE**

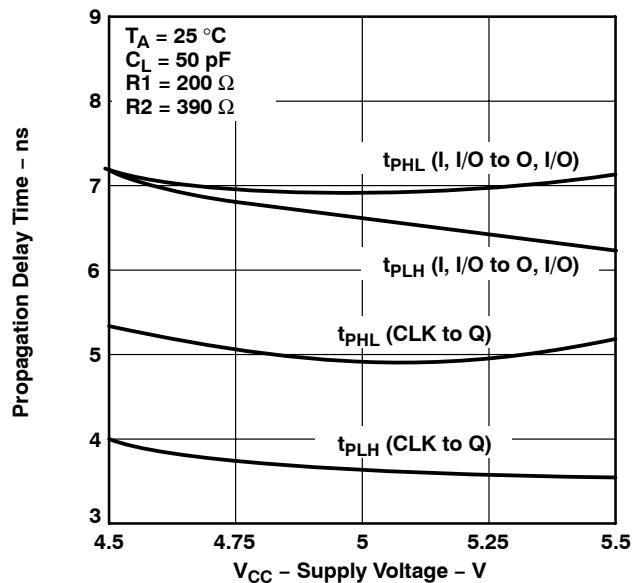


Figure 8

**PROPAGATION DELAY TIME  
 vs  
 NUMBER OF OUTPUTS SWITCHING**

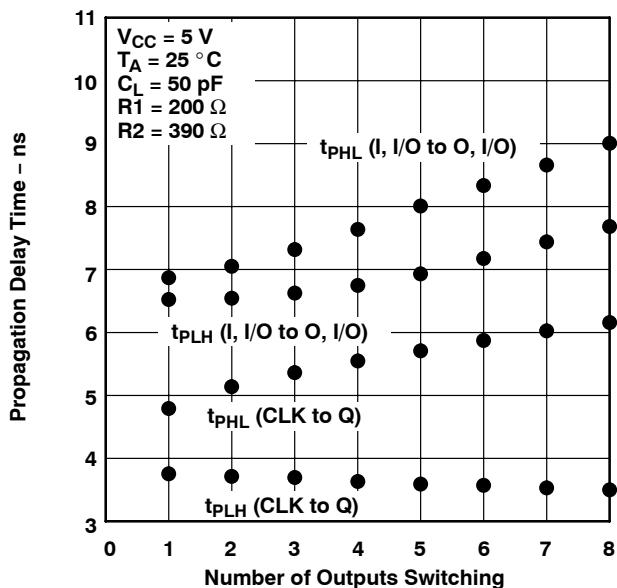


Figure 9

### TYPICAL CHARACTERISTICS

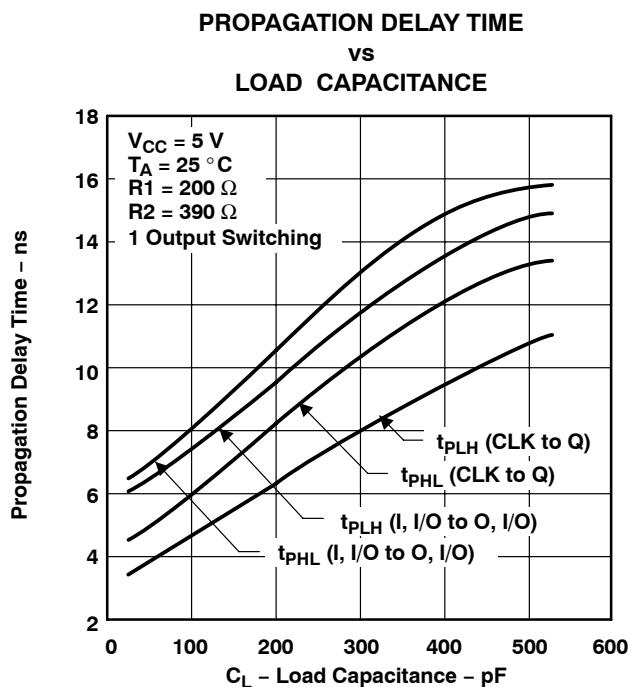


Figure 10

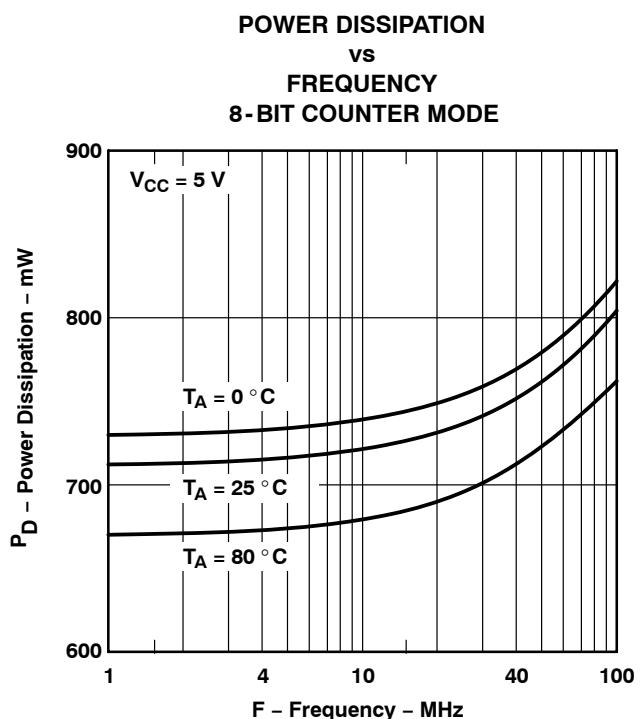


Figure 11

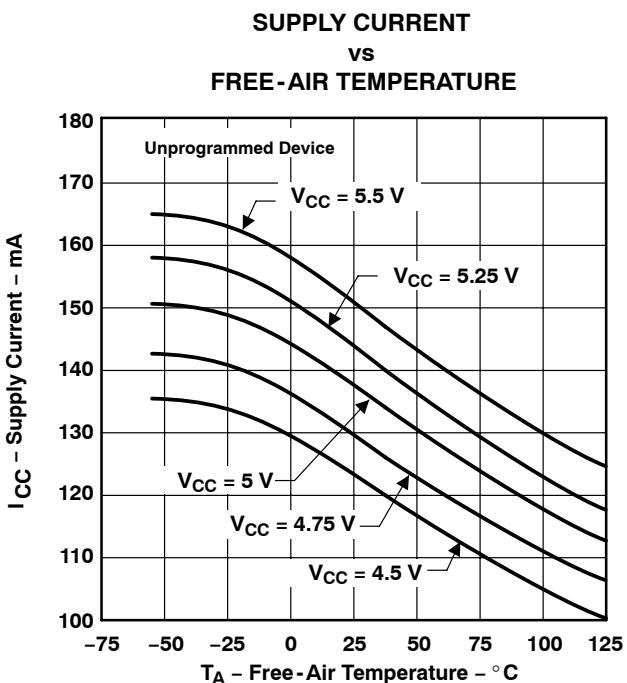


Figure 12

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D0892

SRPS017

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5962-85155152A	NRND	LCCC	FK	20	55	Non-RoHS & Green	SNPB	N / A for Pkg Type	-55 to 125	5962- 85155152A TIBPAL16 R6-12MFKB	
5962-8515515RA	NRND	CDIP	J	20	20	Non-RoHS & Green	SNPB	N / A for Pkg Type	-55 to 125	5962-8515515RA TIBPAL16R6-12M JB	
5962-85155162A	NRND	LCCC	FK	20	55	Non-RoHS & Green	SNPB	N / A for Pkg Type	-55 to 125	5962- 85155162A TIBPAL16 R4-12MFKB	
5962-8515516RA	NRND	CDIP	J	20	20	Non-RoHS & Green	SNPB	N / A for Pkg Type	-55 to 125	5962-8515516RA TIBPAL16R4-12M JB	
TIBPAL16R4-12MFKB	NRND	LCCC	FK	20	55	Non-RoHS & Green	SNPB	N / A for Pkg Type	-55 to 125	5962- 85155162A TIBPAL16 R4-12MFKB	
TIBPAL16R4-12MJ	NRND	CDIP	J	20	20	Non-RoHS & Green	SNPB	N / A for Pkg Type	-55 to 125	TIBPAL16R4-12M J	
TIBPAL16R4-12MJB	NRND	CDIP	J	20	20	Non-RoHS & Green	SNPB	N / A for Pkg Type	-55 to 125	5962-8515516RA TIBPAL16R4-12M JB	
TIBPAL16R6-12MFKB	NRND	LCCC	FK	20	55	Non-RoHS & Green	SNPB	N / A for Pkg Type	-55 to 125	5962- 85155152A TIBPAL16 R6-12MFKB	
TIBPAL16R6-12MJB	NRND	CDIP	J	20	20	Non-RoHS & Green	SNPB	N / A for Pkg Type	-55 to 125	5962-8515515RA TIBPAL16R6-12M JB	

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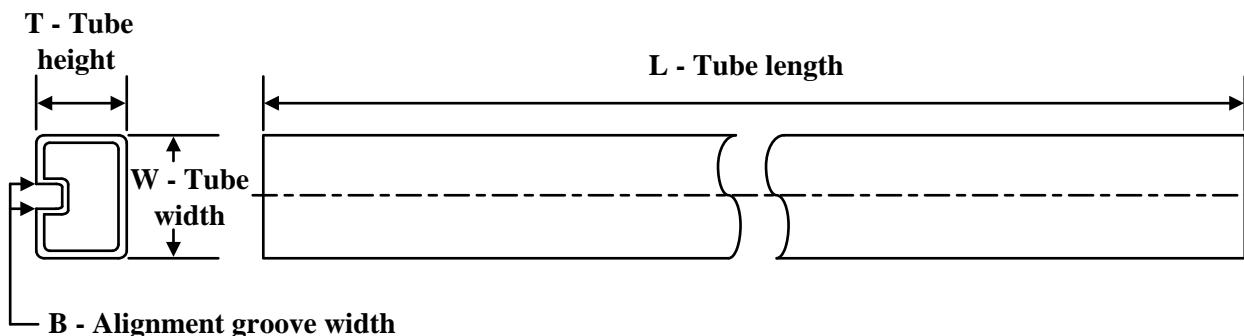
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\*All dimensions are nominal

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5962-85155152A	FK	LCCC	20	55	506.98	12.06	2030	NA
5962-85155162A	FK	LCCC	20	55	506.98	12.06	2030	NA
TIBPAL16R4-12MFKB	FK	LCCC	20	55	506.98	12.06	2030	NA
TIBPAL16R6-12MFKB	FK	LCCC	20	55	506.98	12.06	2030	NA

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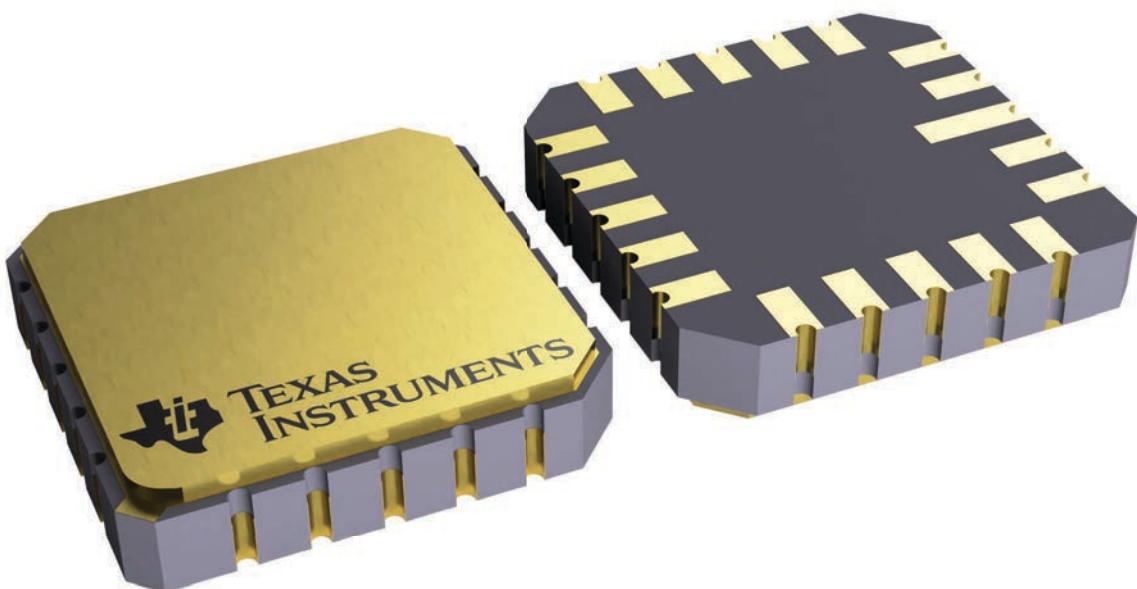
**FK 20**

**LCCC - 2.03 mm max height**

**8.89 x 8.89, 1.27 mm pitch**

**LEADLESS CERAMIC CHIP CARRIER**

This image is a representation of the package family, actual package may vary.  
Refer to the product data sheet for package details.

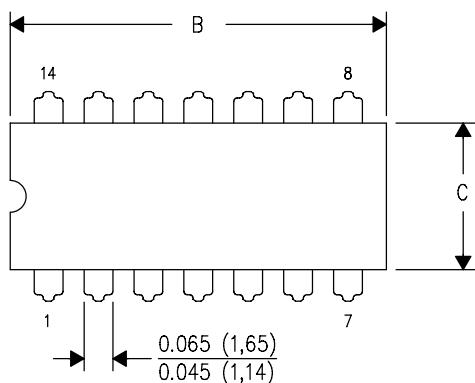


4229370VA\

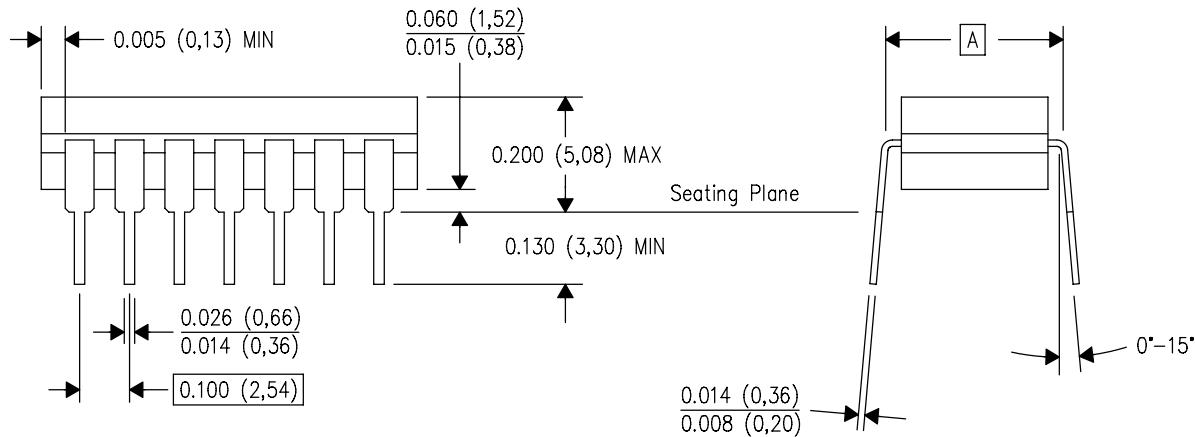
J (R-GDIP-T\*\*)

14 LEADS SHOWN

CERAMIC DUAL IN-LINE PACKAGE



PINS ** DIM	14	16	18	20
A	0.300 (7,62) BSC	0.300 (7,62) BSC	0.300 (7,62) BSC	0.300 (7,62) BSC
B MAX	0.785 (19,94)	.840 (21,34)	0.960 (24,38)	1.060 (26,92)
B MIN	—	—	—	—
C MAX	0.300 (7,62)	0.300 (7,62)	0.310 (7,87)	0.300 (7,62)
C MIN	0.245 (6,22)	0.245 (6,22)	0.220 (5,59)	0.245 (6,22)



4040083/F 03/03

NOTES: A. All linear dimensions are in inches (millimeters).  
B. This drawing is subject to change without notice.  
C. This package is hermetically sealed with a ceramic lid using glass frit.  
D. Index point is provided on cap for terminal identification only on press ceramic glass frit seal only.  
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