

# SymPol™ Transceiver

Check for Samples: SN65HVD96

### **FEATURES**

- Communicate Without Errors on Normal or Reversed-Wire Bus Lines
- Up to 5 Mbps Signaling
- Industrial Temperature Range: –40°C to 85°C
- Symmetric Polarity Receiver
- Receiver Hysteresis > 100 mV
- Connect up to 32 Nodes Plus Parallel Terminators on one Bus, or Connect up to 200 Nodes on an Unterminated Bus

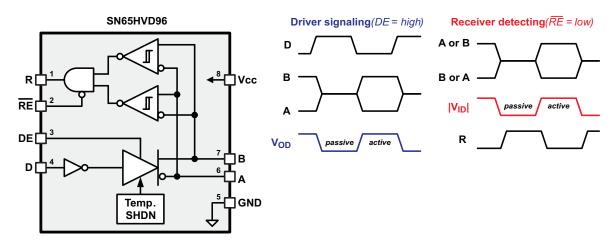
- Transient Protection
  - ±12 kV Human Body Model on Bus Pins
  - ±25 V Repetitive Transient Pulse on Bus Pins
- Additional Reliability Features:
  - Bus Standoff From –35 V to 40 V
  - Driver Output Short-Circuit Current Limit
  - Automatic Thermal Shutdown and Recovery
- Complies with ANSI/TIA-4963 Standard

### DESCRIPTION

The SN65HVD96 is specifically designed to meet the requirements for a transceiver which operates with no errors if the twisted-pair signal wires are connected normally or reversed. This allows for error free operation in applications where the signal wires may become inadvertently reversed during installation or maintenance. This feature is corrected internally so no intervention from the controller or operator is required. The SN65HVD96 complies with the requirements of ANSI/TIA-4963, *Electrical Characteristics of Reversible Balanced Voltage Digital Interface Circuits*.

Similar to RS-485, these transceivers can be used for point-to-point, multi-drop, or multi-point networks. Sympol™ devices are not backwards compatible with, but are an upgrade to, existing RS-485 networks. The pin-out is identical to the industry-standard SN75176 transceiver, allowing direct upgrade from RS-485 to SymPol. Current-limited differential outputs protect in case of driver contention on a party-line bus. High receiver input impedance allows connection of at least 32 nodes. Several fault tolerant features are integrated into the device to protect from operational hazards. Current limiting on the driver outputs protects against short-circuit faults, and operates independently on each driver output. An automatic thermal shutdown protects the driver circuits against over temperature conditions. The receiver output enters a deterministic failsafe state if the bus connection is left disconnected or if the bus wires are shorted together.

The small outline integrated circuit (SOIC) package saves board space compared to equivalent discrete implementations. These devices are fully characterized for operation over the industrial temperature range of  $-40^{\circ}$ C to  $85^{\circ}$ C.



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Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

Sympol is a trademark of Texas Instruments.



### ABSOLUTE MAXIMUM RATINGS(1)

|   | VALUE                        | UNIT |  |  |  |
|---|------------------------------|------|--|--|--|
| Supply voltage, V <sub>CC</sub>   | -0.5 to 6                    | V    |  |  |  |
| Voltage range at A or B   | -35 to 40                    | V    |  |  |  |
| Voltage range at logic pins (D, DE, RE)   | -0.3 to V <sub>CC</sub> +0.3 | V    |  |  |  |
| Voltage input range, transient pulse, A and B, through $100\Omega$              | ±25                          | V    |  |  |  |
| Voltage input transient pulse, A and B, per ISO 7637                            | ±200                         | V    |  |  |  |
| Differential voltage, $V_A - V_B$   | -75 to +75                   | V    |  |  |  |
| Electro-static discharge per JEDEC Std. 22 A114, A and B pins, Human Body Model | ±12                          | kV   |  |  |  |
| Electro-static discharge per JEDEC Std. 22 A114, all pins, Human Body Model     | ±5                           | kV   |  |  |  |
| Electro-static discharge per JEDEC Std. 22 C101, all pins, Charged Device Model | ±2                           | kV   |  |  |  |
| Electro-static discharge per JEDEC Std. 22 A115, all pins, Machine Model        | ±200                         | V    |  |  |  |
| Receiver output current   | ±20                          | mA   |  |  |  |
| Junction temperature, T <sub>J</sub>  | 170                          | °C   |  |  |  |
| Continuous total power dissipation (see Dissipation Rating Ta                   |                              |      |  |  |  |

<sup>(1)</sup> Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

### THERMAL INFORMATION

|                       | <b>T</b> 1                          | IERMAL METRIC <sup>(1)</sup>  | SN65HVD96   | LINUTC |
|-----------------------|-------------------------------------|---|-------------|--------|
|                       | ır                                  | TERMAL METRIC   | 8 PINS SOIC | UNITS  |
| $\theta_{JA}$         | Junction-to-ambient thermal resista | ance <sup>(2)</sup>   | 124.5       |        |
| $\theta_{JC(top)}$    | Junction-to-case(top) thermal resis | 55.9  |             |        |
| $\theta_{JB}$         | Junction-to-board thermal resistan  | 50.2  | °C 111      |        |
| ΨЈТ                   | Junction-to-top characterization pa | 4.9   | °C/W        |        |
| ΨЈВ                   | Junction-to-board characterization  | 46.0  |             |        |
| $\theta_{JC(bottom)}$ | Junction-to-case(bottom) thermal r  | n/a   |             |        |
|                       |                                     | TEST CONDITIONS   |             |        |
|                       |                                     | VCC = 5.25 V, TJ = 150°C, RL = 300 $\Omega$ , CL = 50 pF (driver), CL = 15 pF (receiver), unterminated <sup>(8)</sup> | 188         |        |
| $P_d$                 | Power Dissipation                   | VCC = 5.25 V, TJ = 150°C, RL = 100 Ω, CL = 50 pF (driver), CL = 15 pF (receiver), RS-422 load <sup>(8)</sup>          | 251         | mW     |
|                       |                                     | VCC = 5.25 V, TJ = 150°C, RL = 54 $\Omega$ , CL = 50 pF (driver), CL = 15 pF (receiver), RS-485 load <sup>(8)</sup>   | 319         |        |

- (1) For more information about traditional and new thermal metrics, see the IC Package Thermal Metrics application report, SPRA953.
- (2) The junction-to-ambient thermal resistance under natural convection is obtained in a simulation on a JEDEC-standard, high-K board, as specified in JESD51-7, in an environment described in JESD51-2a.
- (3) The junction-to-case (top) thermal resistance is obtained by simulating a cold plate test on the package top. No specific JEDEC-standard test exists, but a close description can be found in the ANSI SEMI standard G30-88.
- (4) The junction-to-board thermal resistance is obtained by simulating in an environment with a ring cold plate fixture to control the PCB temperature, as described in JESD51-8.
- (5) The junction-to-top characterization parameter, ψ<sub>JT</sub>, estimates the junction temperature of a device in a real system and is extracted from the simulation data for obtaining θ<sub>JA</sub>, using a procedure described in JESD51-2a (sections 6 and 7).
- (6) The junction-to-board characterization parameter, ψ<sub>JB</sub>, estimates the junction temperature of a device in a real system and is extracted from the simulation data for obtaining θ<sub>JA</sub>, using a procedure described in JESD51-2a (sections 6 and 7).
- (7) The junction-to-case (bottom) thermal resistance is obtained by simulating a cold plate test on the exposed (power) pad. No specific JEDEC standard test exists, but a close description can be found in the ANSI SEMI standard G30-88.
- (8) Driver and receiver enabled, 50% duty cycle square-wave signal at 5 Mbps.



### **RECOMMENDED OPERATING CONDITIONS**

|                   |  | MIN  | NOM | MAX             | UNIT |
|-------------------|--|------|-----|-----------------|------|
| $V_{CC}$          | Supply voltage   | 4.75 | 5   | 5.25            | V    |
| VI                | Input voltage at any bus terminal (separately or common mode) <sup>(1)</sup> | -7   |     | 12              | V    |
| V <sub>IH</sub>   | High-level input voltage (Driver, driver enable, and receiver enable inputs) | 2    |     | V <sub>CC</sub> | V    |
| V <sub>IL</sub>   | Low-level input voltage (Driver, driver enable, and receiver enable inputs)  | 0    |     | 0.8             | V    |
| V <sub>ID</sub>   | Differential input voltage   | -12  |     | 12              | V    |
| Io                | Output current, Driver   | -70  |     | 70              | mA   |
| Io                | Output current, Receiver   | -2   |     | 2               | mA   |
| $R_L$             | Differential load resistance   | 54   | 60  |                 | Ω    |
| 1/t <sub>UI</sub> | Signaling rate   | 0    |     | 5               | Mbps |
| T <sub>A</sub>    | Operating free-air temperature   | -40  |     | 85              | °C   |

<sup>(1)</sup> The algebraic convention, in which the least positive (most negative) limit is designated as minimum is used in this data sheet.

### **ELECTRICAL CHARACTERISTICS**

over recommended operating conditions (unless otherwise noted)

|                       | PARAMETER   | TEST CONDIT  | TONS                  | MIN   | TYP | MAX | UNIT  |
|-----------------------|---|--|-----------------------|-------|-----|-----|-------|
|                       |   | RS-485 common-mode loa   | d, see Figure 2       | 1.5   |     |     | 1     |
| V <sub>OD(ACT)</sub>  | Driver differential output voltage magnitude (active)                   | RS-485 differential load R <sub>L</sub><br>C <sub>L</sub> = Open, see Figure 3 | = 54 Ω,               | 1.5   |     |     | V     |
|                       | magnitude (active)  | RS-422 differential load R <sub>L</sub><br>C <sub>L</sub> = Open, see Figure 3 | 2                     |       |     | ľ   |       |
|                       |   | RS-485 common-mode loa   | d, See Figure 2       |       |     | 50  |       |
| D. ( )                | Driver differential output voltage                                      | RS-485 differential load R <sub>L</sub><br>C <sub>L</sub> = Open, see Figure 3 | = 54 Ω,               |       |     | 20  | ,     |
| V <sub>OD(PAS)</sub>  | magnitude (passive)   | RS-422 differential load R <sub>L</sub><br>C <sub>L</sub> = Open, see Figure 3 | = 100 Ω,              |       |     | 25  | 25 mV |
|                       |   | No Load  |                       |       | 50  |     |       |
| V <sub>OC(SS)</sub>   | Steady-state common-mode output voltage                                 | $Voc = (V_A + V_B) / 2$ $R_L = 54\Omega$                                       | 1                     | Vcc/2 | 3   | V   |       |
| ΔV <sub>OC</sub>      | Change in differential driver output common-mode voltage                | $Voc_{(D=High)} - Voc_{(D=Low)}$<br>$R_L = 54\Omega$                           | -0.2                  |       | 0.2 | V   |       |
| V <sub>IT(ACT)</sub>  | Active-going receiver differential input threshold                      | $V_{ID} = V_A - V_B$ or $V_{ID} = V_B - V_B$                                   |                       | 775   | 900 | mV  |       |
| V <sub>IT(PASS)</sub> | Passive-going receiver differential input threshold                     |  |                       | 500   | 625 |     | mV    |
| V <sub>HYS</sub>      | Receiver differential input threshold hysteresis (VIT(ACT) - VIT(PASS)) |  |                       | 100   | 150 |     | mV    |
| V <sub>OH</sub>       | Receiver high-level output voltage                                      | $-20 \mu A \ge I_O \ge -2 mA$  |                       | 2.4   |     | 3.7 | V     |
| V <sub>OL</sub>       | Receiver low-level output voltage                                       | 20 μA ≤ I <sub>O</sub> ≤ 2 mA  |                       |       |     | 0.4 | V     |
| I <sub>I</sub>        | Logic pins input current  |  |                       | -100  |     | 100 | μΑ    |
| l <sub>OZ</sub>       | Receiver output high-impedance current                                  | $V_O = 0 \text{ V or Vcc, } \overline{RE} \text{ at Vcc}$                      | ;                     | -10   |     | 10  | uA    |
| I <sub>OS</sub>       | Driver short-circuit output current                                     | _7 V < Vo < +12 V  |                       | -350  |     | 350 | mA    |
|                       |   | Vcc = 4.75 to 5.25 V or  | V <sub>I</sub> = 12 V |       |     | 1   | mA    |
| l <sub>l</sub>        | Bus input current (passive driver)                                      | Vcc=0V, DE at 0V, other bus pin at 0V  | V <sub>I</sub> = -7 V | -0.8  |     |     | mA    |
| I <sub>CC</sub>       | Supply current (quiescent), no load                                     |  |                       |       |     | 20  | mA    |
| R <sub>ID</sub>       | Differential input resistance   | DE at OV, Vcm = Vcc/2  |                       | 24    | 40  | 57  | kΩ    |



### **SWITCHING CHARACTERISTICS**

over recommended operating conditions (unless otherwise noted)

|  | PARAMETER  | TEST CONDITIONS  | MIN | TYP | MAX | UNIT |
|--|--|--|-----|-----|-----|------|
| DRIVER   |  |  |     |     |     |      |
| t <sub>rise</sub> , t <sub>fall</sub>  | Driver differential output rise/fall time  |  |     | 15  | 30  | ns   |
| t <sub>pAP</sub> , t <sub>pPA</sub>  | Driver propagation delay   | $R_1 = 54 \Omega$ , $C_1 = 50 pF$ , See Figure 3           |     | 40  | 80  | ns   |
| t <sub>SK(P)</sub>   | Driver differential output pulse skew, $ \mathbf{t}_{\text{pAP}} - \mathbf{t}_{\text{pPA}} $ |  |     | 1   | 10  | ns   |
| t <sub>pZA</sub> , t <sub>pAZ</sub>  | Driver enable/disable time   | D = GND, $R_L$ = 54 $\Omega$ , $C_L$ = 50 pF, See Figure 4 |     | 50  | 80  | ns   |
| RECEIVER   |  |  |     |     | ,   |      |
| t <sub>rise</sub> , t <sub>fall</sub>  | Receiver output rise/fall time   |  |     | 8   | 15  | ns   |
| t <sub>PHL</sub> , t <sub>PLH</sub>  | Receiver propagation delay time  | C <sub>L</sub> = 15 pF, See Figure 5                       |     | 70  | 90  | ns   |
| t <sub>SK(P)</sub>   | Receiver output pulse skew, t <sub>PHL</sub> - t <sub>PLH</sub>                              |  |     | 5   | 15  | ns   |
| t <sub>PZL</sub> , t <sub>PZH</sub> ,<br>t <sub>PLZ</sub> , t <sub>PHZ</sub> | Receiver enable/disable time   | See Figure 6   |     | 20  | 100 | ns   |

### **FUNCTION TABLE**

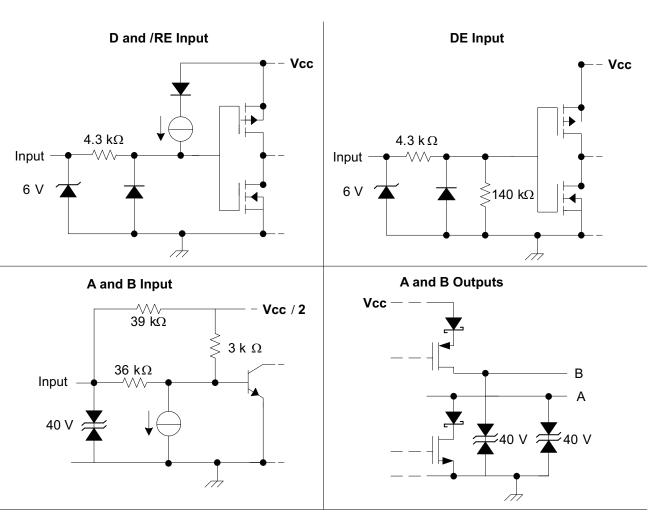
| DRIVER   | DE        | D                                | $V_{OD}$ |                           |
|----------|-----------|----------------------------------|----------|---------------------------|
|          | L or OPEN | X                                | Z        | Driver Disabled (Passive) |
|          | Н         | L                                | Н        | Driver Active             |
|          | п         | H or Open                        | Z        | Driver Passive            |
| RECEIVER | RE        | V <sub>ID</sub>                  | R        |                           |
|          | H or OPEN | X                                | Z        | Receiver Disabled         |
|          |           | V <sub>ID</sub> < -0.9 V         | L        | Active Bit Received       |
|          |           | -0.9 V < V <sub>ID</sub> < -0.5  | ?        | Indeterminate bus         |
|          | ,         | -0.5 V < V <sub>ID</sub> < 0.5 V | Н        | Passive Bit Received      |
|          | L         | 0.5 V < V <sub>ID</sub> < 0.9 V  | ?        | Indeterminate bus         |
|          |           | 0.9 V < V <sub>ID</sub>          | L        | Active Bit Received       |
|          |           | Open, Short, Idle                | Н        | Failsafe Condition        |

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### **DEVICE INFORMATION**



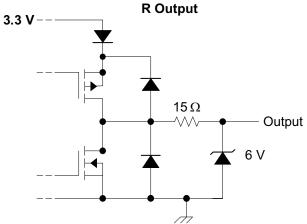


Figure 1. Equivalent Input and Output Schematic Diagrams

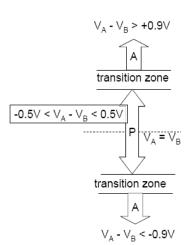


### APPLICATION INFORMATION

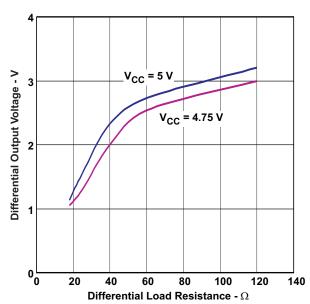
### Sympol™ States

# Sym-Pol\* States

- If the differential voltage is positive (V<sub>A</sub> > V<sub>B</sub>) the state is called ACTIVE
- If the differential voltage is near zero (V<sub>A</sub> ≈ V<sub>B</sub>) the state is called PASSIVE
- If the differential voltage is negative (V<sub>A</sub> < V<sub>B</sub>) the state is called ACTIVE



\*Symmetric polarity



### Using Sympol to Achieve Immunity to Crossed Bus Wire

Many applications which use RS-422 or RS-485 are wired on-site by third-party installers. This opens the door to the possibility of miss-wiring, especially for far-flung networks with many stations (or nodes). Neither RS-422 nor RS-485 allows correct communications when the bus wires (typically a twisted-pair) are swapped.

The existing solutions for this case require active intervention, either by the installer or maintenance technician, or by an automated controller. Sympol offers a way to replace RS-422 or RS-485 networks with communication over the same bus lines. Due to the innovative nature of Sympol signaling levels, a Sympol network is immune to communication errors caused by crossed bus wires.

Signaling levels are similar to RS-422 and RS-485, so signaling rates, cable lengths, and noise immunity will be comparable.

Sympol is NOT interoperable with RS-422 or RS-485; that is, designers may not mix Sympol nodes with existing RS-485 nodes.

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### **Number of Nodes**

The SN65HV96 specifications for bus-pin impedance are similar to a standard one unit-load (1 UL) RS-485 device. This allows designers to attach up to 32 nodes plus two parallel termination resistors on a single bus segment. In applications where the standard trunk-and-stub arrangement of RS-485 is not practical, or if mis-termination may occur during installation, it may be desirable to not use parallel termination on the bus lines. In these applications, the number of nodes allowed can be up to about 200, while still maintaining high driver output amplitude. The bus pin impedance is approximated as 12 k $\Omega$ , therefore 200 devices in parallel present differential loading similar to the 60  $\Omega$  termination resistance.

### PARAMETER MEASUREMENT INFORMATION

Input generator rate is 100kbps, 50% duty-cycle, transition times less than 6 ns for all figures.

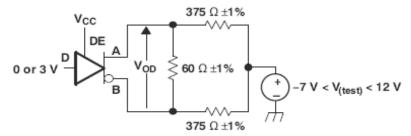


Figure 2. Measurement of Driver Differential Output Voltage With Common-Mode Load

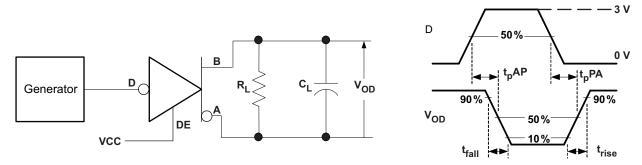


Figure 3. Measurements of Driver Differential Output Rise and Fall Times and Propagation delays

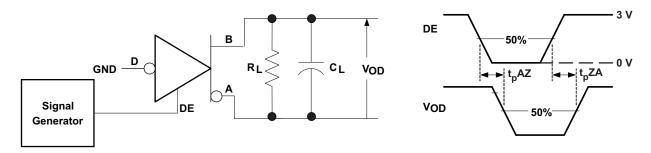


Figure 4. Measurements of Driver Enable and Disable Times With Active Output



### PARAMETER MEASUREMENT INFORMATION (continued)

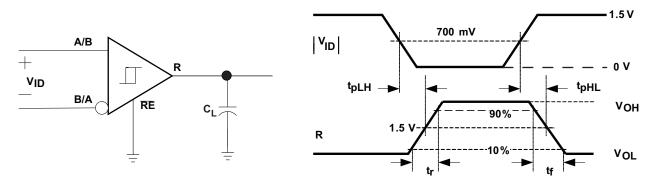


Figure 5. Measurement of Receiver Output Rise and Fall Times and Propagation Delays

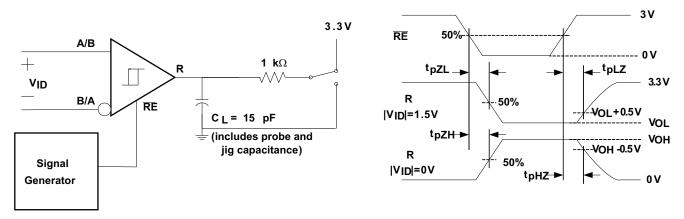


Figure 6. Measurement of Receiver Enable Times With Driver Disabled



### **REVISION HISTORY**

| Cŀ | nanges from Original (June 2010) to Revision A  | Page         | е |
|----|---|--------------|---|
| •  | Changed the 4th bullet in Features to 2 bulleted items  | 1            | 1 |
| •  | Changed the 6th bullet in Features to read "Connect up to 32 Nodes Plus Parallel Terminators on one Bus, or Connect up to 200 Nodes on an Unterminated Bus" | <i>'</i>     | 1 |
| •  | Deleted italics from party line and failsafe in second paragraph  |              | 1 |
| •  | Added to protect after Several faultinto the device sentence, second paragraph  | 1            | 1 |
| •  | Changed in abs max table from 7V to 6V  | 2            | 2 |
| •  | Deleted deleted 'dc' from the VALUE column in 2nd and 4th parameter   | 2            | 2 |
| •  | Added commas after the name of the test specification, A224, 2 places, C101 and A115. Added the word pins after A and B in the first Human Body Model row   |              | 2 |
| •  | Deleted 290 in the THERMAL Table from the first cell under TEST Conditions. Deleted 5V supply from all three cells.   | 2            | 2 |
| •  | Added typical characteristics graph to Application Information Section  | <del>(</del> | 6 |
| •  | Added section to Application Information titled Number of Nodes   | 7            | 7 |
|    |   |              |   |
| Cr | nanges from Revision A (December 2010) to Revision B  | Page         | 9 |
| •  | Changed revision A, December 2010 to Rev B, October 2011  |              | 1 |
| •  | Added new ListItem to the FEATURES: 'CompliesStandard'  | ′            | 1 |
| •  | Added last sentence to the first paragraph of DESCRIPTION   |              | 1 |
|    | Added Differential voltageV row to the ABS MAX RATINGS table  |              |   |
|    | Added differential input resistance specification to Electrical Characteristics table.  |              |   |

Product Folder Link(s): SN65HVD96



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### **PACKAGING INFORMATION**

| Orderable Device | Status  | Package Type | Package<br>Drawing | Pins | Package<br>Qty | Eco Plan     | Lead finish/<br>Ball material | MSL Peak Temp      | Op Temp (°C) | Device Marking<br>(4/5) | Samples |
|------------------|---------|--------------|--------------------|------|----------------|--------------|-------------------------------|--------------------|--------------|-------------------------|---------|
| P82B96PW         | LIFEBUY | TSSOP        | PW                 | 8    | 150            | RoHS & Green | NIPDAU                        | Level-1-260C-UNLIM | -40 to 85    | PG96                    |         |
| SN65HVD96DR      | ACTIVE  | SOIC         | D                  | 8    | 2500           | RoHS & Green | NIPDAU                        | Level-1-260C-UNLIM | -40 to 85    | HVD96                   | Samples |

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

- (3) MSL, Peak Temp. The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.
- (4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.
- (5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.
- (6) Lead finish/Ball material Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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### TAPE AND REEL INFORMATION

# REEL DIMENSIONS Reel Diameter Reel Width (W1)

# TAPE DIMENSIONS WHO SHOPE THE STATE OF THE

| A0 | Dimension designed to accommodate the component width     |
|----|---|
| В0 | Dimension designed to accommodate the component length    |
| K0 | Dimension designed to accommodate the component thickness |
| W  | Overall width of the carrier tape                         |
| P1 | Pitch between successive cavity centers                   |

### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



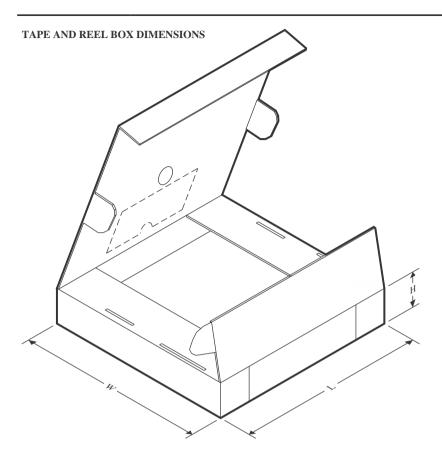
### \*All dimensions are nominal

|   | Device      | Package<br>Type | Package<br>Drawing |   | SPQ  | Reel<br>Diameter<br>(mm) | Reel<br>Width<br>W1 (mm) | A0<br>(mm) | B0<br>(mm) | K0<br>(mm) | P1<br>(mm) | W<br>(mm) | Pin1<br>Quadrant |
|---|-------------|-----------------|--------------------|---|------|--------------------------|--------------------------|------------|------------|------------|------------|-----------|------------------|
| ١ | SN65HVD96DR | SOIC            | D                  | 8 | 2500 | 330.0                    | 12.4                     | 6.4        | 5.2        | 2.1        | 8.0        | 12.0      | Q1               |



## **PACKAGE MATERIALS INFORMATION**

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### \*All dimensions are nominal

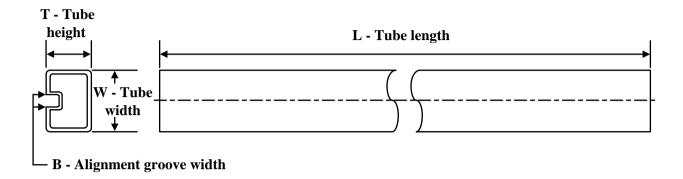
| Device      | Package Type | Package Drawing | Pins | SPQ  | Length (mm) | Width (mm) | Height (mm) |  |
|-------------|--------------|-----------------|------|------|-------------|------------|-------------|--|
| SN65HVD96DR | SOIC         | D               | 8    | 2500 | 356.0       | 356.0      | 35.0        |  |





www.ti.com 7-Apr-2023

### **TUBE**

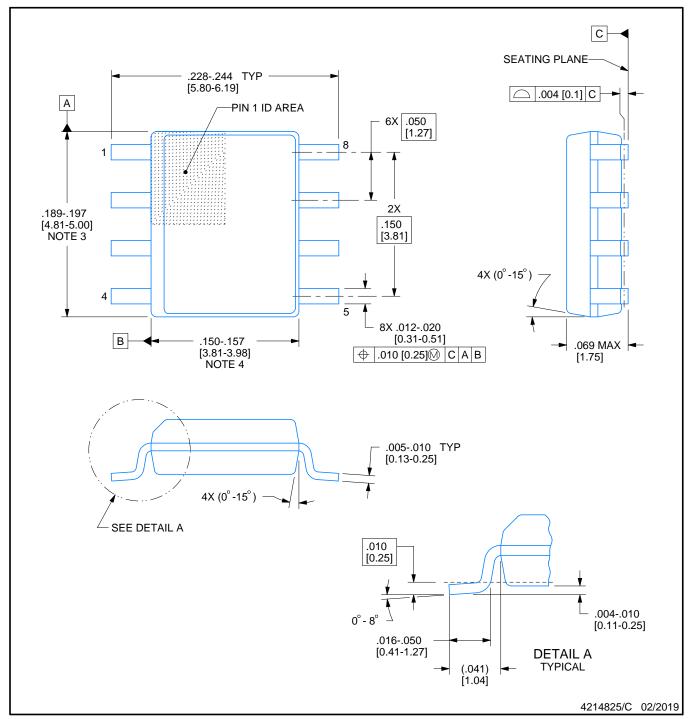


### \*All dimensions are nominal

| Device   | Package Name | Package Type | Pins | SPQ | L (mm) | W (mm) | T (µm) | B (mm) |  |
|----------|--------------|--------------|------|-----|--------|--------|--------|--------|--|
| P82B96PW | PW           | TSSOP        | 8    | 150 | 530    | 10.2   | 3600   | 3.5    |  |



SMALL OUTLINE INTEGRATED CIRCUIT

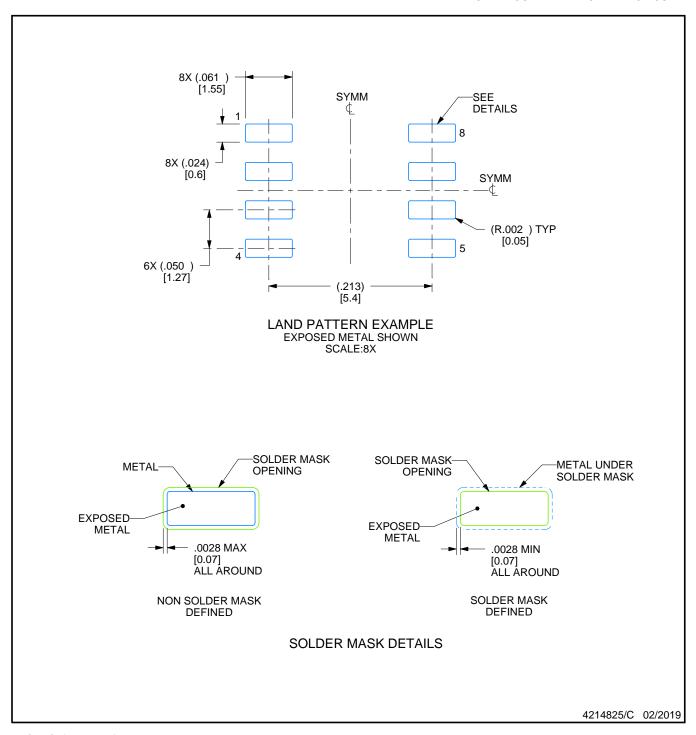


### NOTES:

- 1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.
- 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 [0.15] per side.
- 4. This dimension does not include interlead flash.
- 5. Reference JEDEC registration MS-012, variation AA.



SMALL OUTLINE INTEGRATED CIRCUIT

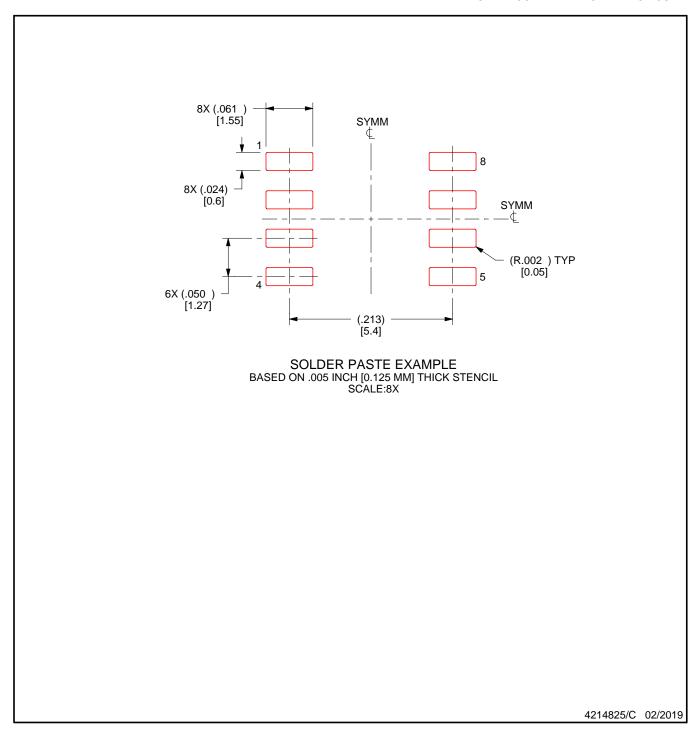


NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

SMALL OUTLINE INTEGRATED CIRCUIT



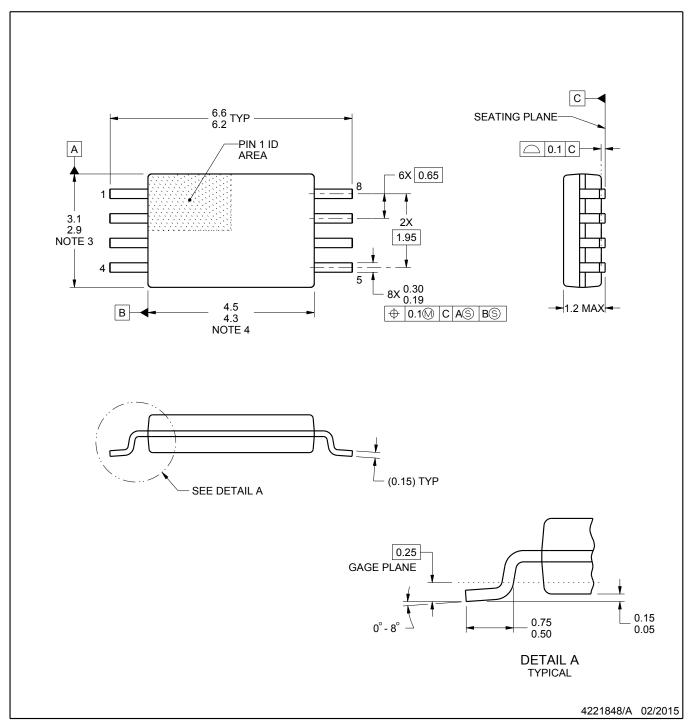
NOTES: (continued)

- 8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 9. Board assembly site may have different recommendations for stencil design.





SMALL OUTLINE PACKAGE



### NOTES:

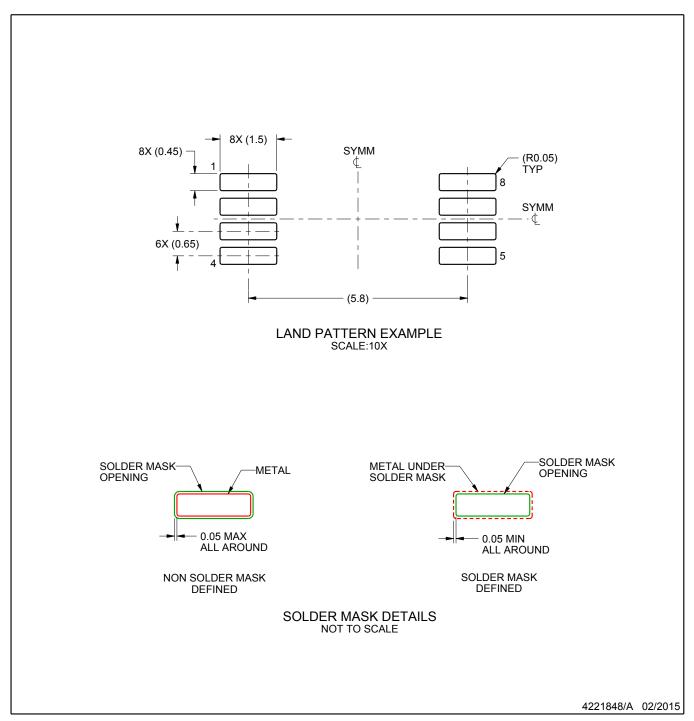
- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.

  2. This drawing is subject to change without notice.

  3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not
- exceed 0.15 mm per side.
- 4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.25 mm per side.
- 5. Reference JEDEC registration MO-153, variation AA.



SMALL OUTLINE PACKAGE

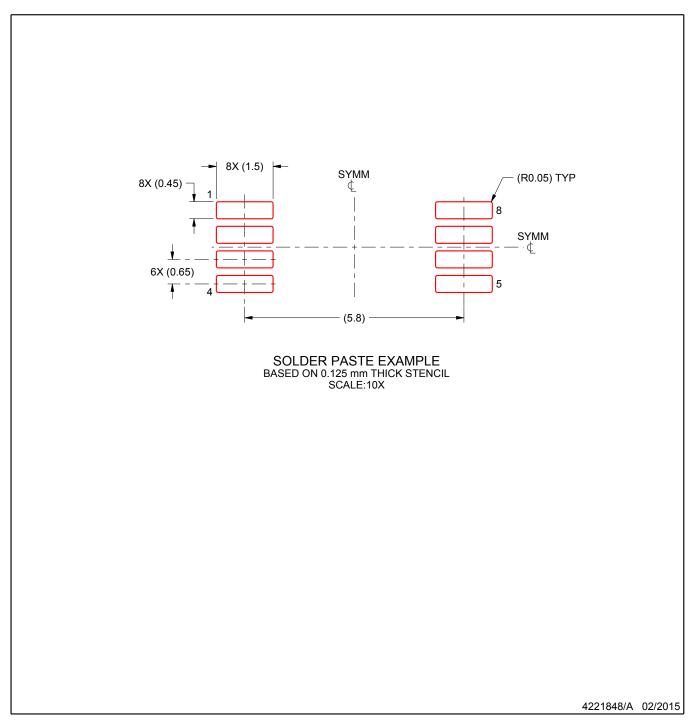


NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

SMALL OUTLINE PACKAGE



NOTES: (continued)

- 8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 9. Board assembly site may have different recommendations for stencil design.



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