

LogiCoA™ Power Solutions

Synchronous Buck DCDC Converter

Evaluation Board

LogiCoA001-EVK-001

(12V→5V, 5A)

Introduction

LogiCoA™ Power is a solution adopting analog-digital hybrid control to a switching power supply. This user's guide will provide the steps necessary to operate the evaluation board of LogiCoA™ Power Solution Synchronous buck DCDC converter, LogiCoA001-EVK-001. Bill of materials, operating procedures and application data are included.

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1 Overview of LogiCoA™ Power Solution

Figure 1-1 shows the overview of LogiCoA™ Power Solution. LogiCoA™ Power is a solution adopting analog-digital hybrid control to a switching power supply and consists from 3 elements, (1) Microcontroller for Power Supply Control (LogiCoA™ Microcontroller) ML62Q203x/ML62Q204x (hereinafter referred to ML62Q20xx group), (2) Operating System for Power Supply Control Microcontroller, RMOS, and (3) Power Supply Application. Refer to the explanation application note [1] for detail information of analog-digital hybrid control.

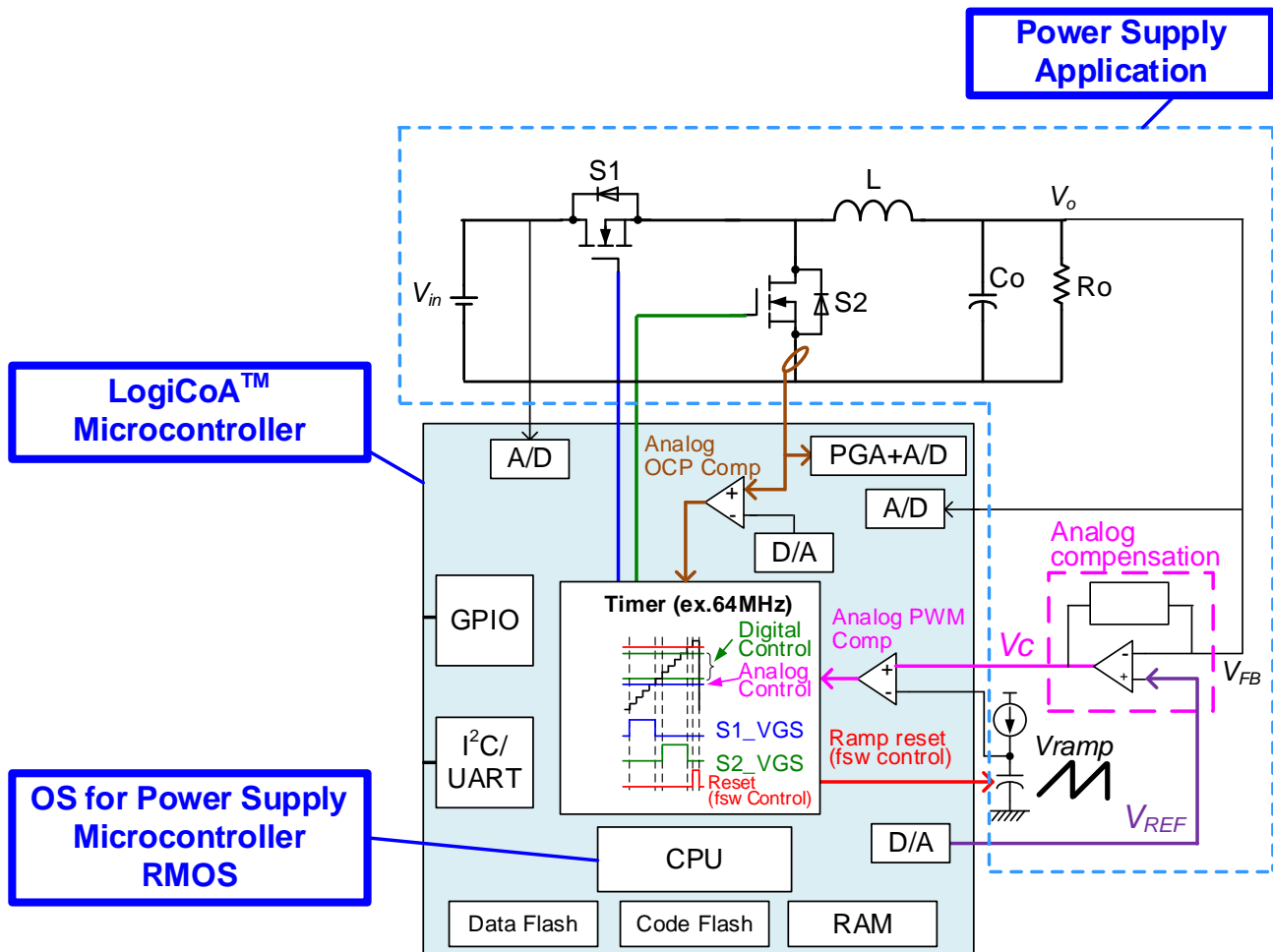


Figure 1-1. System overview of LogiCoA™ Power Solution

(1) Microcontrollers for Power Supply Control (LogiCoA™ Microcontroller)

LogiCoA™ Microcontrollers are suitable ones for power supply control with those analog-digital hybrid control is adopted and ML62Q2033/2035 and ML62Q2043/2045 are released. (at the time of this document's release) On this EVK, ML62Q2035 is mounted. Refer to 4.2 MCU, the datasheet of ML62Q2033/2035/2043/2045 [2] and the user's manual of ML62Q2033/2035/2043/2045 [3] for more detail information about ML62Q2035.

(2) Operating System for Power Supply Control Microcontroller RMOS (Real time Micro Operating System)

RMOS is a multi-task and real-time operating system developed to control switching power supplies and operates on ML62Q20xx group. Refer to the explanation application note [4] for more detail information about RMOS.

(3) Power Supply Application

Power Supply Applications are application circuits correspond to each power supply topology. On this EVK external components such as LDO, gate driver, operational amplifier, MOSFET inductor and so on are mounted as an application circuit of synchronous buck converter.

2 Operating Conditions

(Unless otherwise specified Ta=25°C, Vin=12V)

Parameter	Symbol	Min	Typ	Max	Unit	Conditions
Input Voltage	Vin	7.5	12.0	38.0	V	
Control Block Supply Voltage(LDO)	Vcc5Vldo	4.9	5.0	5.1	V	Vcc5V=LDO Output
Control Block Supply Voltage(USB)	Vcc5Vusb	4.25	5.00	5.75	V	Vin=open, Vcc5V=USB VBUS Output
Driver Block Supply Voltage	Vcc12V	11.4	12.0	12.6	V	Vin>13V
Output Voltage	Vo	-	5.0	-	V	default setting, variable with serial communication
Output Voltage Range	Vo_r	1.0	-	8.0	V	variable with serial communication
Output Current	Io	-	-	5.0	A	
Switching Frequency	fsw	-	160	-	kHz	default setting
Switching Frequency Range	fsw_r	80	-	500	kHz	
Maximum Duty	Dmax	-	80	-	%	default setting
Soft Start Time	Tsstart	-	5	-	ms	Io=0A
Efficiency	η	-	92	-	%	Vo=5V, Io=5A
Startup Voltage	Vstart	-	9.0	-	V	Vin rise, default setting, variable with serial communication
Startup Voltage Range	Vstart_r	7.5	-	38.0	V	
Stop Voltage	Vstop	-	8.0	-	V	Vin fall, default setting, variable with serial communication
Stop Voltage Range	Vstop_r	7.5	-	38.0	V	
Startup Delay Time	Tstart	-	1000	-	ms	Vin rise, default setting
Startup Delay Time Range	Tstart_r	10	-	-	ms	
Input Voltage Protection	Vivp	-	38.0	-	V	default setting
Input Voltage Protection Range	Vivp_r	7.5	-	38.0	V	
Over Current Protection	Iocp	-	6.0	-	A	default setting
Over Current Protection Range	Iocp_r	2.5	-	8.0	A	
Output Low Voltage Protection	Vlvp	-	3.0	-	V	Vo fall, default setting
Output Low Voltage Protection Range	Vlvp_r	1.0	-	7.0	V	
Output Low Voltage Protection Mask Time	Tlvp	-	500	-	ms	Vo fall, default setting
Output Low Voltage Protection Mask Time Range	Tlvp_r	10	-	-	ms	
Output Over Voltage Protection	Vovp	-	6.0	-	V	Vo rise, default setting
Output Over Voltage Protection Range	Vovp_r	1.0	-	10.0	V	

3 Firmware

For this EVK, in addition to the evaluation board, the source code of RMOS and power supply control are supplied. And those can be downloaded from the URL below.

Table 3-1. RMOS download URL and the file name

Download URL	https://www.rohm.com/reference-designs/ref66009
Reference Program Name	LogiCoA™ Solution Buck Converter Reference Program
File Name	RMOS100-PSFW001.zip

4 Block Diagram and Description

4.1 Block Diagram

Figure 4-1 shows the application block diagram of this EVK.

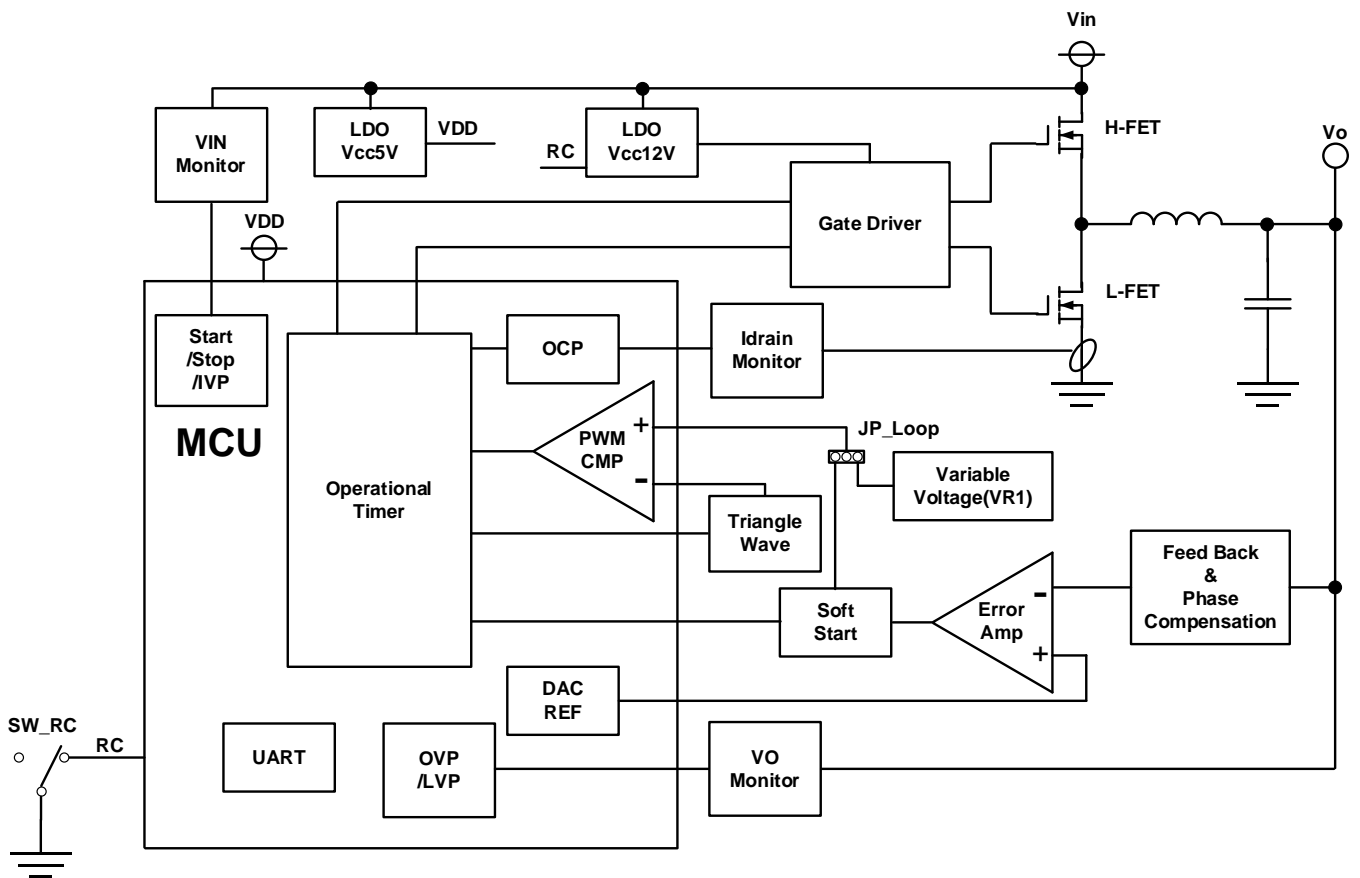


Figure 4-1. Application Block Diagram

4.2 MCU

On this EVK, MCU ML62Q2035 is mounted as a power supply controller. VDD voltage of MCU is supplied from the control block power supply Vcc5V, and after supplied voltage becomes over 4.10V (typ) of the threshold voltage of POR, the microcontroller startup and RMOS starts its operation. Each pin's function of ML62Q2035 and selected function in this EVK is listed in Table 4-1.

Table 4-1. Pin list of ML62Q2035

Pin No.	Pin Name	1 st Function	2 nd Function	3 rd Function	4 th Function	5 th Function	6 th Function	7 th Function	8 th Function
		GPI/EXI	UART	I ² C	OTM	CMP/DAC	ADC	CMP	CMP/ADC
19	VDD	—	—	—	—	—	—	—	—
18	VSS	—	—	—	—	—	—	—	—
17	VDDL	—	—	—	—	—	—	—	—
16	P01	—	—	—	—	CMP0P	—	CMP0P /CMP1P	CMP0P
15	P02	—	—	—	OTO4B	CMP0M	—	CMP0M /CMP1M	CMP0M
14	P03	EXI0	—	—	OTO0A	—	—	—	—
13	P04	EXI1	—	—	OTO0B	—	—	—	—
12	P05	EXI1	—	—	OTO1A	—	—	—	—
11	P06	EXI2	—	—	OTO2A	—	—	—	—
10	P10	EXI3	RXD1, (/TXD1)	—	OTO3A	—	—	—	—
9	P11	—	—	—	OTO4A	CMP2P	—	CMP2P	CMP2P
8	P12	—	RXD0, (/TXD0)	SDAU0	OTO1B	—	—	—	—
7	P00/TEST0	EXI3	—	—	—	—	—	—	—
6	P13	EXI2	TXD0	SCLU0	OTO5B	—	AIN4	—	—
5	RESET_N	—	—	—	—	—	—	—	—
4	P14	—	—	—	—	CMP1P	AIN0	CMP1P /CMP2P	AIN0 /CMP1P
3	P15	—	—	—	—	CMP1M	AIN1	CMP1M /CMP2M	AIN1 /CMP1M
2	P16	—	—	—	—	CMP2M	AIN2	CMP2M	AIN2 /CMP2M
1	P17	EXI0	—	—	—	—	AIN3	—	—
20	P23	—	TXD1	—	OTO5A	DACOUT0	—	—	—


 selected function in this EVK

Table 4-2 listed the typical specifications of ML62Q2035. Refer to [2] and [3] for more detail information about ML62Q2035.

Table 4-2. Typical specifications of ML62Q2035

Part Number	ML62Q2035	
CPU	16bit RISC CPU Core(nx-U16/100), Max operating frequency 16MHz	
Memory	Code Flash: 32KB, Data Flash: 4KB(Erase Unit:128B), RAM: 2KB	
Analog Comparator	3ch(asynchronous to clock), Response time: Max 100ns	
Timer	16bit timer with PWM/Capture x 6 counters, 10 outputs	
	Max 64MHz operation(Resolution 15.625ns)	
AD Converter	12bit SA-ADC: 5ch	
DA Converter	8bit, 2ch	
Programmable Gain Amplifier	1ch, Gain Setting: 4 steps (x4/x8/x16/x32)	
Serial I/F	I ² Cx1, UARTx2	
I/O Port	I: 1, I/O: 15	
External Interrupt	4	
Other	Multiplication/Division Unit, Temperature Sensor, Power ON Reset	
Clock	Low	Internal RC Oscillator: 32.768kHz ± 1.5%*
	High	PLL: 64MHz ± 1.5%*, CPU: 16MHz to 125kHz ± 1.5%* PWM/Capture: 64MHz to 500kHz ± 1.5%*
Current Consumption(CPU)	Stop: 80μA, Halt: 90μA, Active: 3.3mA@16MHz	
Operating Supply Voltage	4.5V to 5.5V	
Operating Temperature	Ta=-40°C to +105°C(Tj=115°C) (Absolute maximum ratings:Tjmax=125°C)	
Package	TSSOP20	

*: Ta=-20°C to +85°C

4.3 Control Block Power Supply

On this EVK, a fixed 5V output LDO BD950N1WG-C is mounted as a power supply (Vcc5V) for control block (MCU and analog control circuit). BD950N1WG-C has standby control function, but in this EVK, VIN pin and EN pin are shorted and so when Vin voltage is applied and VIN pin of BD950N1WG-C voltage is over UVLO rise voltage (typ 2.6V), Vcc5V turns on. Refer to the datasheet of BD9xxN1-C series [5] for more detail information about BD950N1WG-C.

4.4 Driver Block Power Supply

On this EVK, a 12V output LDO BD900N1WG-C is mounted as a power supply (Vcc12V) of the gate driver to drive output FET. BD900N1WG-C has standby control function and can be controlled turning ON/OFF by a remote control switch described later. Refer to the datasheet of BD9xxN1-C series [5] for more detail information about BD900N1WG-C.

4.5 Remote Control Switch

This EVK has RC (RC: Remote Control) function for external turning ON/OFF control. DCDC operates as the setting below by turning the mechanical switch (SW_RC) connected P10 pin of ML62Q2035 to OPEN or short to GND. To avoid a false detection by noise, there are mask time of 150μs at RC=H detection and 1.25ms at RC=L. P10 pin is set as a GPIO with internal 40kΩ(typ) pulled-up. Refer to [2] about the threshold of operating state because it depends on input/output characteristics of ML62Q2035.

Table 4-3. Operating state of Remote Control Switch

SW_RC	P10 pin	DCDC
OPEN	VDD	ON
GND SHORT	GND	OFF

4.6 Error Amplifier and Reference Voltage

Figure 4-2 shows the error amplifier and surrounding circuits. BU7481SG is mounted on as an error amplifier. As control block power supply Vcc5V is supplied, the error amplifier starts to operate but startup of the error amplifier output is controlled by the soft start circuit. Refer to the datasheet of that [6] for more detail information about BU7481SG.

The reference voltage of error amplifier Vo_REF is generated by the 8-bits DA converter built-in in the MCU (1.973V at VDD=5V). Output voltage Vo is calculated as following equation.

$$V_o = V_{O_REF} \times \frac{R_{29} + R_{30} + R_{31}}{R_{31}}$$

Ex.) When Vo_REF=1.973V, R29=51Ω, R30=3.3kΩ and R31=2.2kΩ, output voltage is as below.

$$V_o = 1.973V \times \frac{51\Omega + 3.3k\Omega + 2.2k\Omega}{2.2k\Omega} \cong 4.9782V$$

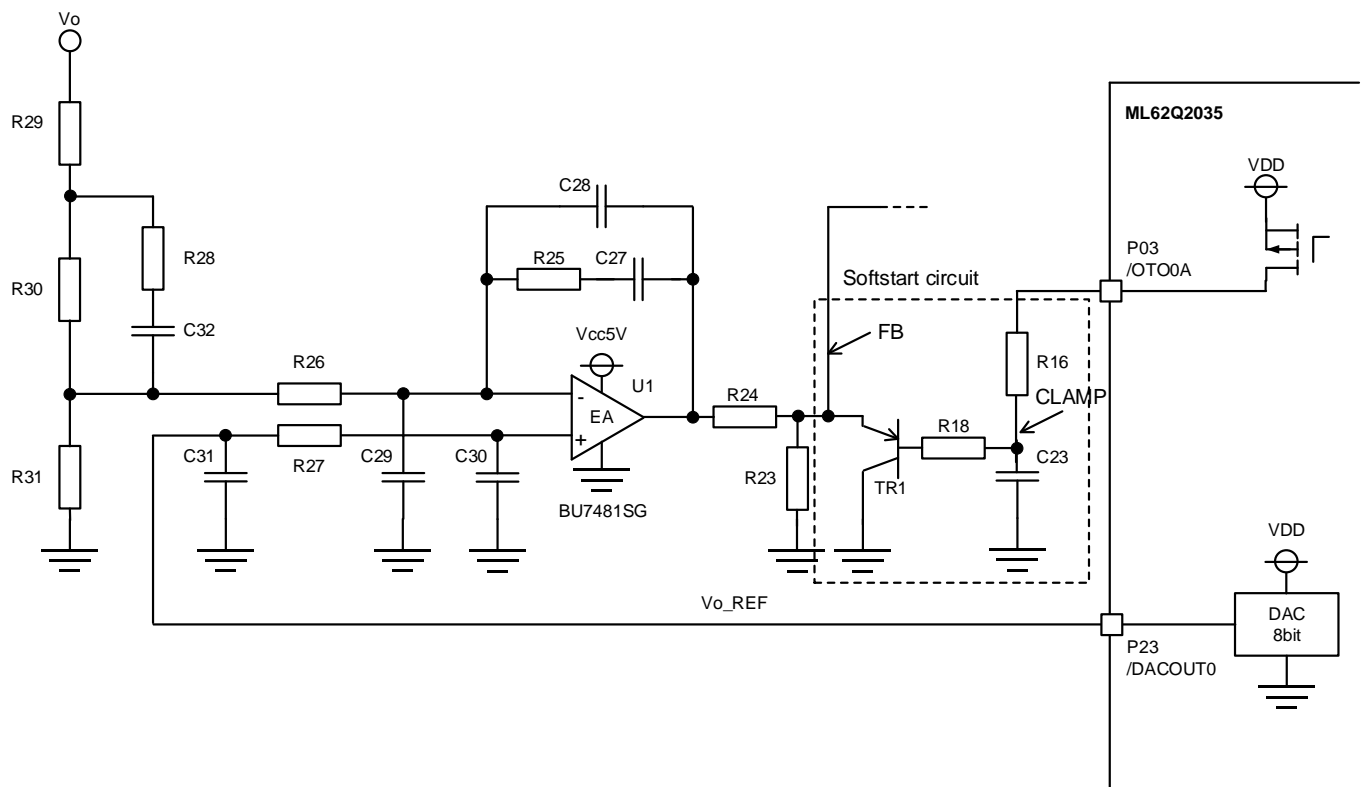


Figure 4-2. Error amplifier and surrounding circuits

4.7 Soft Start

In this EVK, to avoid an overshoot and rush current, output of the error amplifier (FB) is clamped while starting up, thus ramp up speed of DCDC output is controlled and starts softly.

The FB voltage is clamped by the CLAMP voltage + V_{BE} of TR_1 because the voltage generated at both ends of R_{18} can be considered minute due to $R_{18}=100\Omega$ and TR_1 base current. P03/OTO0A pin has been set as PMOS open drain, and while in startup, clamped voltage rise up slowly by controlling the ON duty of the PMOS. In the steady state, the CLAMP voltage is equal to VDD and thus the FB voltage is not clamped.

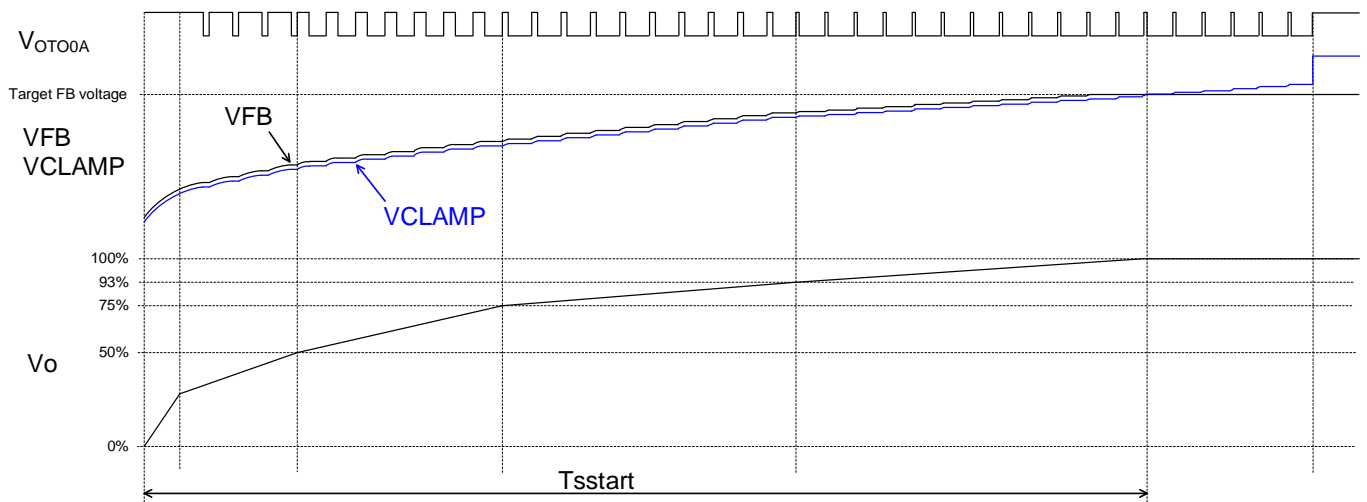


Figure 4-3. Soft start operation timing chart

4.8 Triangle Waveform Generator and PWM Comparator

Figure 4-4 and 4-5 shows the triangle waveform generator and surrounding circuits, and timing chart. Triangle waveform is generated at P02/CMP0M pin by clock pulse output from P04/OTO0B pin. P01/CMP0P pin and P02/CMP0M pin have been set as an input of analog comparator and the build-in analog comparator operate as the PWM comparator.

As shown in Figure 4-5, the frequency of clock pulse output from P04/OTO0B pin is the switching frequency of the DCDC converter fsw (160kHz). And while the output of the clock pulse is H, the voltage of TRNGL becomes also H, so the output of the PWM comparator is L. This leads that the L duty of the clock pulse is the Max Duty D_{max} (80% typ) of the DCDC converter.

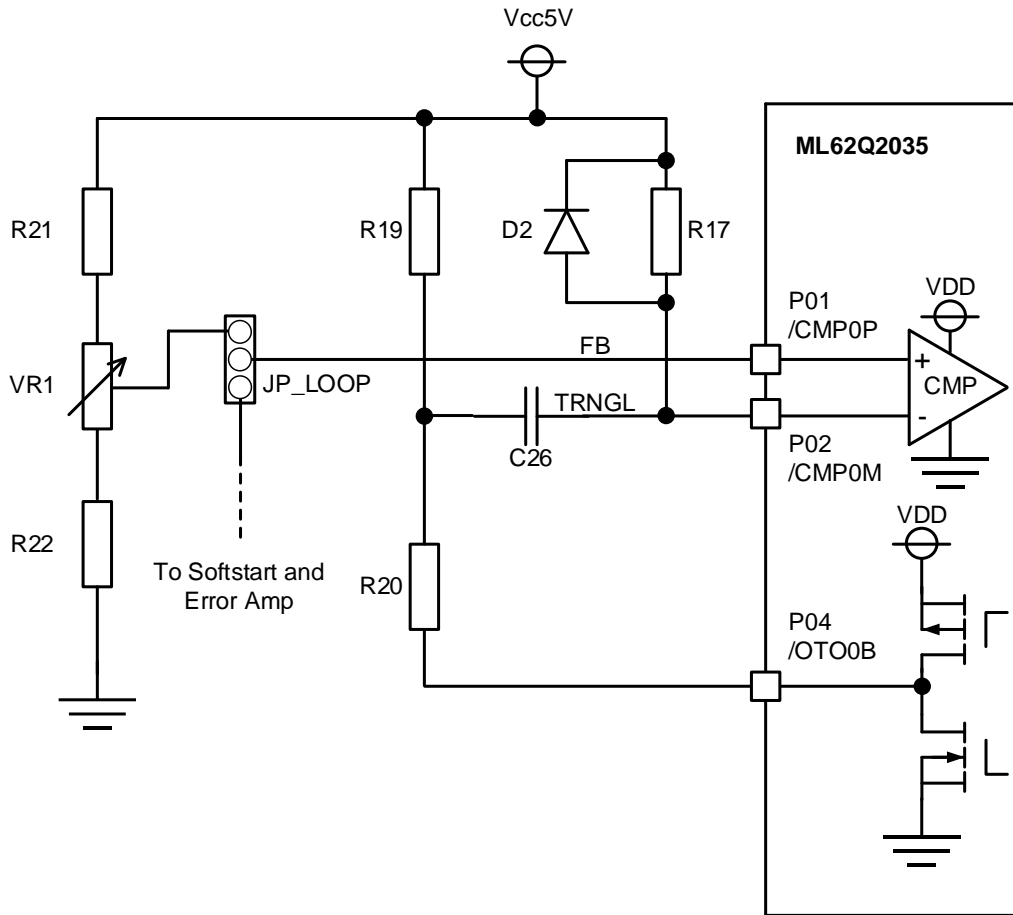


Figure 4-4. Triangle waveform generator and surrounding circuit

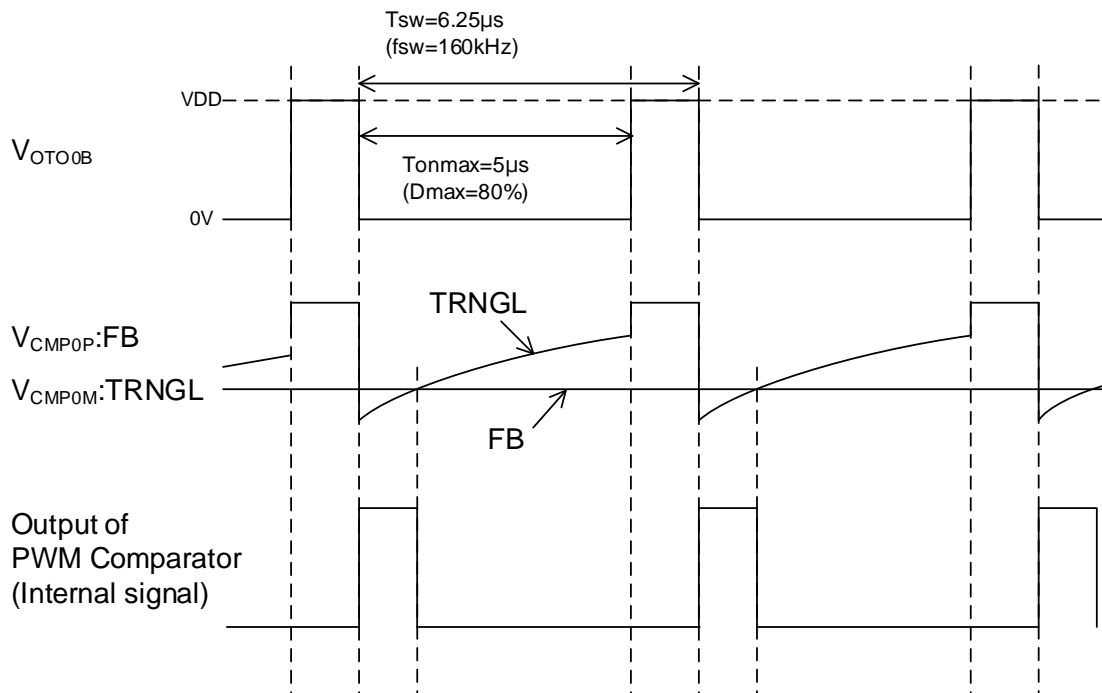


Figure 4-5. Triangle waveform generator timing chart

4.9 Volume Resistor for open loop operation (for debug)

This EVK can be operated in open loop without feedback control for debugging. Open loop and closed loop operation can be exchanged by the jumper connection of JP_Loop (refer to Figure 4-1. Application Block Diagram and Figure 4-4. Triangle waveform generator and surrounding circuit.) When open loop operation is selected, the input voltage of the PWM comparator can be tuned using volume resistor VR_1 . The divided voltage from V_{cc5V} by R_{21} and $10k\Omega$ volume resistor VR_1 will be the FB voltage (0Ω is mounted on R_{22} .)

4.10 Output Stage

In output stage, the control signals of H-side/L-side FET from the MCU level shifted by the gate driver drive output FETs, and stable voltage smoothed by the LC filter is supplied. BD2320EFJ-LA is mounted on as a gate driver. Refer to the datasheet of that [7] for more detail information of BD2320EFJ-LA.

4.11 Input Voltage Detection Block

Figure 4-6 shows the input voltage detection block. The divided V_{in} voltage by R_6 and R_7 is input to the P15/AIN1 pin of ML62Q2035, and the digital value of pin input voltage converted by the 12bits AD converter is obtained.

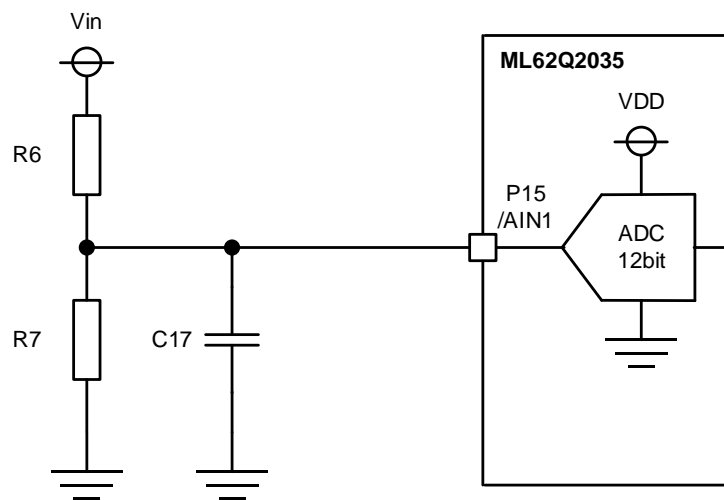


Figure 4-6. Input voltage detection block

4.11.1 Startup/Stop Voltage Check

In this EVK, V_{in} input voltage is monitored by the input voltage detection block described above and when the voltage is over the startup voltage of 9V, DCDC startups after the 1s of the startup delay time. When the input voltage is below 8V, DCDC stops. For a noise reduction, there is a $150\mu s$ of mask time in voltage detection.

4.11.2 Input Voltage Protection

This EVK has an input over voltage protection function (IVP: Input Voltage Protection). V_{in} input voltage is monitored by the input voltage detection block described above and when the voltage is over the detect voltage of 38V, the protection works and DCDC stops output switching. For a noise reduction, there is a $250\mu s$ of mask time in voltage detection. When the input voltage is below the detect voltage in the normal operation state, count of the mask time is reset. When protection works, DCDC stops latched, and restarts after turning on RC again in the condition that V_{in} input voltage is under the detection threshold voltage.

4.12 Output Voltage Detection Block

Figure 4-7 shows the output voltage detection block. The divided V_o voltage by R_{32} and R_{33} is input to the P14/AIN0 pin of ML62Q2035, and the digital value of pin input voltage converted by the 12bits AD converter is acquired.

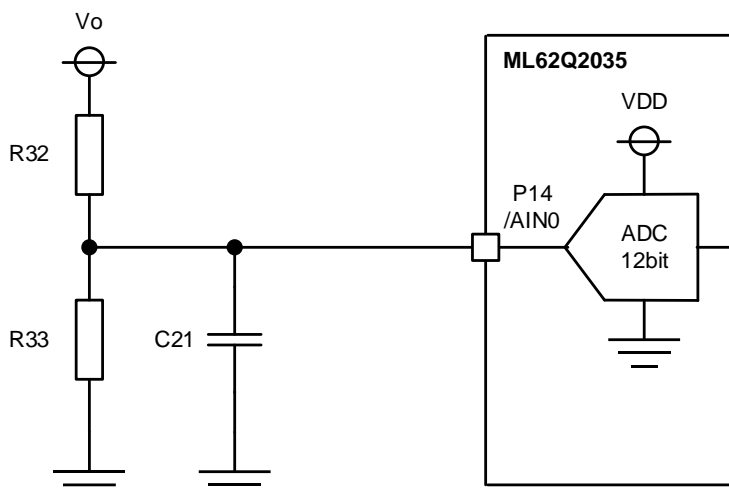


Figure 4-7. Output voltage detection block

4.12.1 Low Voltage Protection

This EVK has an output low voltage protection function (LVP: Low Voltage Protection). V_o output voltage is monitored by the output voltage detection block described above and when the voltage drops less than the detect voltage of 3.0V, timer count starts. When the output voltage remains below the detect voltage and 500ms has passed, protection works and DCDC stops output switching. The timer counter is incremented from the initial value by every 500 μ s, and when the output voltage becomes over the detect voltage while in timer counting, the counter value is decremented. When DCDC stops by the protection or RC, the timer counter is reset. When protection works, DCDC stops latched, and restart after turning on RC again.

4.12.2 Over Voltage Protection

This EVK has an output over voltage protection function (OVP: Over Voltage Protection). V_o output voltage is monitored by the output voltage detection block described above and when the voltage is over the detect voltage of 6.0V, the protection works, and DCDC stops output switching. For a noise reduction, there is a 250 μ s of mask time in voltage detection. When the output voltage drops less than the detect voltage in the normal operation state, count of the mask time is reset. When protection works the DCDC stops latched, and restart after turning on RC again.

4.13 Drain Current Detection Block

Figure 4-8 shows the drain current detection block. The drain current I_d flows through low side FET, FET2, is converted to the voltage V_{SNS} in the current sense resistor R_5 . V_{SNS} divided from V_{cc5V} by R_8, R_9 and R_{10}, R_{11} , and added certain offset voltage to meet the input voltage range of AD converter/analog comparator, are input to P16/AIN2 pin and P11/CMP2P pin of ML62Q2035 each. By the built-in AD converter in P16/AIN2 pin, the digital value of the current is acquired and the built-in comparator in P11/CMP2P pin detect the overcurrent.

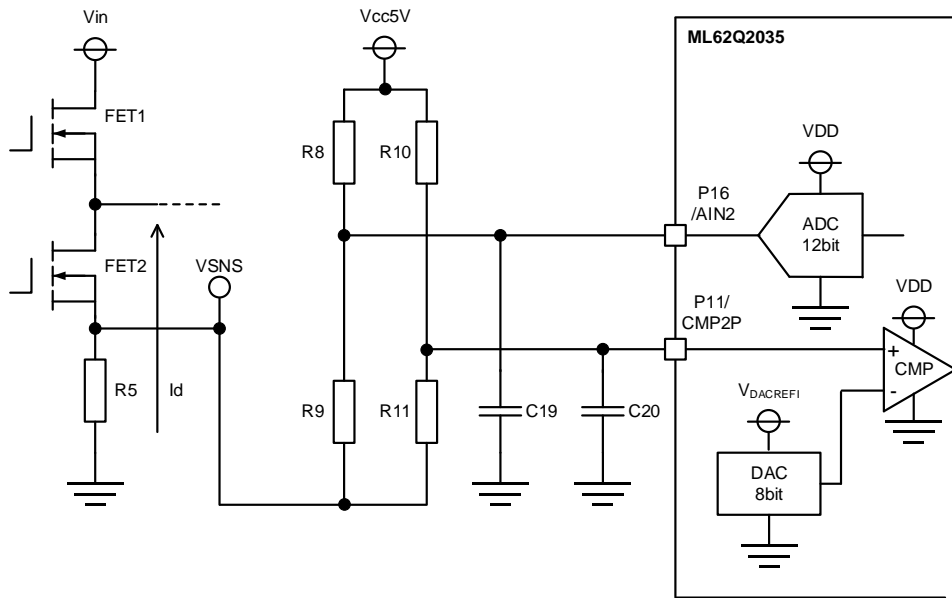


Figure 4-8. Drain current detection block

4.13.1 Over Current Protection

This EVK has a pulse-by-pulse over current protection function (OCP: Over Current Protection). The drain current of low side FET is monitored by the analog comparator in the drain current detection block described above. When the current exceeds the detect threshold value of 6.0A, protection works and turning off the FET. After the detection, DCDC restarts from protection automatically, but if the overload state continues, OCP is detected again.

4.14 LED Indicator

In this EVK, 2 LEDs of LED1(red) and LED2(green) are mounted on. And each blinking pattern indicates below operating state.

Table 4-4. LED1 Blinking pattern and operating state

LED1	State
Off	-
Blinking	Program writing/Accessing to MCU

Table 4-5. LED2 Blinking pattern and operating state

LED2	State
1 time short blink(100ms x 1) in 1.6ms period	Vin input voltage is below startup voltage(Vin stop state)
2 times short blink(100ms x 2) in 1.6ms period	Vin input voltage is over startup voltage and standby with RC control(RC standby state)
1 time blink(700ms x 1) in 1.6ms period	Normal operation state
5 times short blink(100ms x 5) in 1.6ms period	Abnormal stop state

5 Serial Communication

In this EVK, modification of power supply control parameter and recording the operating log are capable of by a serial communication via the on-board USB-UART convert module from such as an external Windows PC. (Logging function is not implemented at the time of this document's release.) Refer to the explanation application note of communication function and GUI[8] for more detail information about the serial communication and communication commands.

6 View of EVK

Figure 6-1 and Figure 6-2 shows the view of EVK.



Figure 6-1. LogiCoA001-EVK-001(Top View)

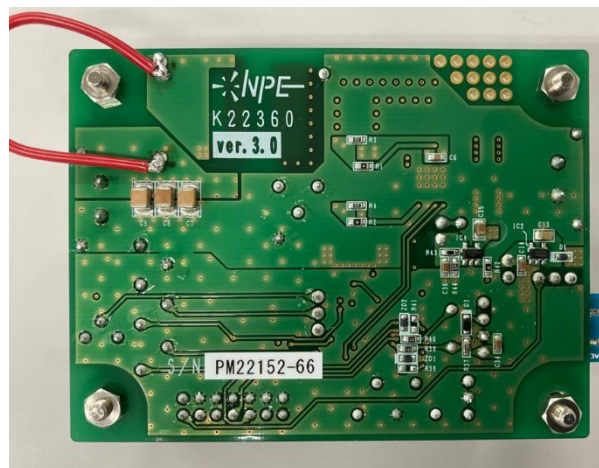


Figure 6-2. LogiCoA001-EVK-001(Bottom View)

7 Operating Procedure

1. Short 1-2 pins of the jumper JP_LDO, 1-2 pins of JP_12V, 2-3 pins of JP_Loop and open JP_REG on the EVK.
2. Turn the SW_RC to connect 1-2pins on EVK. (Turn the switch to upper side in the board direction of Figure 6-1.)
3. Turn off the DC power supply and connect it's GND pin to 2 pin of J1 on the EVK.
4. Connect DC power supply's VCC pin to 1 pin of J1 on the EVK.
5. Connect the load between 1 pin and 2 pin of J2 on the EVK. When an electric load is used, turn off the output before connecting to the board.
6. Connect the voltmeter to the mon_Vo pin and mon_GND pin on the EVK.
7. Turn on the DC power supply. Check if the measured value of the voltmeter is 5V.
8. If an electric load is used, turn on the electric load.

Notes: This EVK does not support hot plugging protection. Do not perform hot plugging on this board.

10 Bill of Materials

Table 10-1 shows the bill of materials of this EVK.

Table 10-1. Bill of Materials

Quantity	Reference Designator	Part Number	Manufacturer	Value	Description [Unit: inch(mm)]
IC					
1	IC1	BD2320EFJ-LAE2	ROHM	-	Gate Driver,14.5V,2024(4960)
1	IC2	BD950N1WG-CTR	ROHM	-	LDO, 42V, 5V/150mA,1112(2829)
1	IC3	ML62Q2035-NNNTDZWATZ	LAPIS Technology	-	MCU, 5.5V, 32kbyte,2526(6465)
1	IC4	BD900N1WG-CTR	ROHM	-	LDO, 42V, 150mA,1112(2829)
1	U1	BU7481SG-TR	ROHM	-	1ch-OPAMP,5.5V,1112(2829)
Resistor					
1	R1	-	-	4.7Ω	0.1W,±1%,0603(1608)
3	R2,R22,R42	-	-	0Ω	1A,0.1W,0603(1608)
4	R3,R4,R12,R14	-	-	10kΩ	0.1W,±1%,0603(1608)
1	R5	LTR100LJZPFSR020	ROHM	20mΩ	4W,±1%,1225(3264)
1	R6	-	-	220kΩ	0.1W,±1%,0603(1608)
1	R7	-	-	27kΩ	0.1W,±1%,0603(1608)
6	R8,R13,R15,R19,R31,R33	-	-	2.2kΩ	0.1W,±1%,0603(1608)
1	R9	-	-	330Ω	0.1W,±1%,0603(1608)
1	R10	-	-	820Ω	0.1W,±1%,0603(1608)
1	R11	-	-	150Ω	0.1W,±1%,0603(1608)
4	R16,R17,R32,R44	-	-	4.7kΩ	0.1W,±1%,0603(1608)
3	R18,R35,R36	-	-	100Ω	0.1W,±1%,0603(1608)
1	R20	-	-	470Ω	0.1W,±1%,0603(1608)
2	R21,R24	-	-	1kΩ	0.1W,±1%,0603(1608)
0	R23	No mount	-	-	-
1	R25	-	-	8.2kΩ	0.1W,±1%,0603(1608)
4	R26,R27,R38,R40	-	-	10Ω	0.1W,±1%,0603(1608)
1	R28	-	-	43Ω	0.1W,±1%,0603(1608)
1	R29	-	-	51Ω	0.1W,±1%,0603(1608)
1	R30	-	-	3.3kΩ	0.1W,±1%,0603(1608)
0	R39,R41	No mount	-	-	-
1	R43	-	-	82kΩ	0.1W,±0.5%,0603(1608)
1	R44	-	-	4.7kΩ	0.1W,±0.5%,0603(1608)
1	VR1	CT-6EP103	Nidec Copal Electronics	10kΩ	70.7V,0.5W,±10%,2828(7070)
Capacitor					
4	C1,C2,C3,C4	C3225X7S2A475K200AE	TDK	4.7μF	100V,X7S,±10%,1210(3225)
4	C5,C19,C24,C25	CGA3E1X7R1E105K080AC	TDK	1μF	25V,X7R,±10%,0603(1608)
3	C6,C18,C31	CGA3E2X7R1H104K080AA	TDK	0.1μF	50V,X7R,±10%,0603(1608)
6	C7,C8,C9,C10,C11,C12	GRM32ER71E226ME15L	Murata	22μF	25V,X7R,±20%,1210(3225)
2	C13,C35	GRM21BR61H475ME51L	Murata	4.7μF	50V,X5R,±20%,0805(2012)
2	C14,C36	GRM188R6YA475ME15D	Murata	4.7μF	35V,X5R,±20%,0603(1608)
2	C15,C22	CC0603JRNPO9BN470	Yageo	47pF	50V,COG,±5%,0603(1608)
0	C16	No mount	-	-	-
2	C17,C21	GRM188B11H103K	Murata	0.01μF	50V,B,±10%,0603(1608)
1	C20	CGA3E2C0G1H471J080AA	TDK	470pF	50V,COG,±5%,0603(1608)
1	C23	CGA3E3X7R1H224K080AB	TDK	0.22μF	50V,X7R,±10%,0603(1608)
2	C26,C33	CGA3E2X7R1H102K080AA	TDK	1000pF	50V,X7R,±10%,0603(1608)
1	C27	CGA3E2C0G1H822J080AA	TDK	8200pF	50V,COG,±5%,0603(1608)
1	C28	CGA3E2C0G1H561J080AA	TDK	560pF	50V,COG,±5%,0603(1608)
2	C29,C30	CGA3E2C0G1H101J080AA	TDK	100pF	50V,COG,±5%,0603(1608)
1	C32	CGA3E2X7R1H223M080AA	TDK	0.022μF	50V,X7R,±15%,0603(1608)
1	C34	C1608X5R1E475M080AC	TDK	4.7μF	25V,X5R,±20%,0603(1608)
1	CE1	UCDH101MCL6GS	Nichicon	100μF	50V,±20%,0.36Ωmax,Φ10
1	CE2	APXT100ARA391MF80G	Chemi-con	390μF	10V,±20%,22mΩmax,Φ6.3
Diode					
1	D1	RB510SM-40T2R	ROHM	-	40V,100mA,0603(1608)
1	D2	RB500SM-30T2R	ROHM	-	30V,100mA,0603(1608)
1	D3	1SS355VMT-17	ROHM	-	80V,100mA,1005(2513)
2	ZD1,ZD2	EDZV12R6.2B	ROHM	-	6.2V,5mA,150mW,0603(1608)
Transistor					
1	TR1	2SA2029T2LR	ROHM	-	-50V,150mA,0505(1211)
2	FET1,FET2	RS6L090BGTB1	ROHM	-	60V,90A,4.7mΩmax,2024(4960)
Inductor					
1	L1	XAL1010-153MED	Coilcraft	15μH	60V,9.9A,18.6mΩmax,±20%,(10.0 x 11.3)
LED					
1	LED1	SML-D13U8WT86	ROHM	-	RED,2.1V,20mA,52mW,0603(1608)
1	LED2	SML-D12P8WT86	ROHM	-	GRN,2.2V,20mA,54mW,0603(1608)
Others					
1	J3	HIF3FC-14PA-2.54DSA(71)	Hirose Electric	-	200V,1A,IMD14-2.54-H9.3-HIF3FC_DSA,200Vac,1A
2	JP_LDO,JP_12V	61300211121	Würth Elektronik	-	250V,3A,2.54,5.08*2.54
2	JP_Loop,JP_REG	61300311121	Würth Elektronik	-	250V,3A,2.54,7.62*2.54
1	SW_RC	ATE1E-2M3-10-Z	Nidec Copal Electronics	-	ON-OFF-ON,2.54-ATE1,60V,50mA,0.4VA
2	J1,J2	XW4E-02C1-V1	Omron	-	250V,13.5A,5.08-XW4E,250V,13.5A
1	FT234x	AE-FT234X	AKIZUKI DENSHI TUSHO	-	5V,2.54,FT234XD

11 Reference Application Data

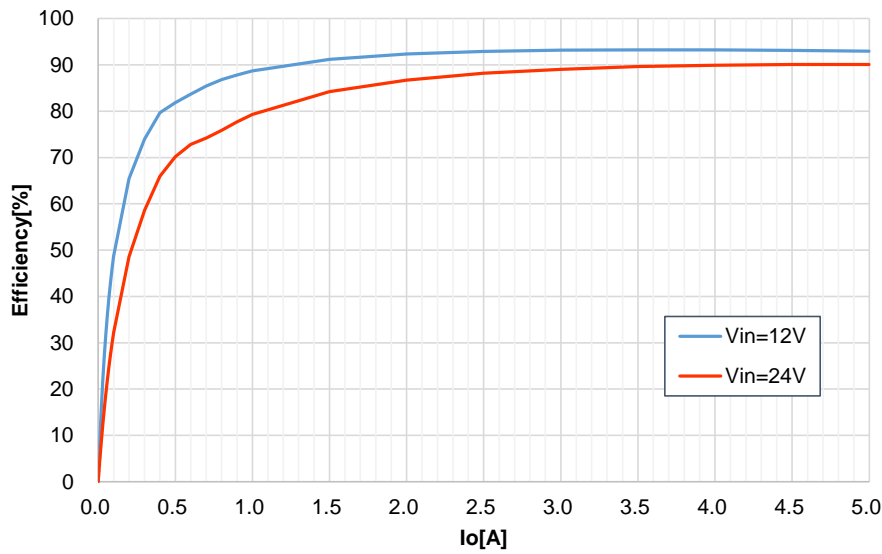


Figure 11-1. Efficiency vs Io

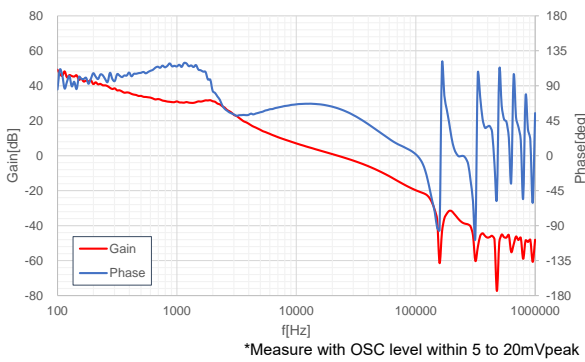


Figure 11-2. Frequency Characteristics
(Vin=12V, Vo=5V, Io=5A, OSC:20mVpeak)

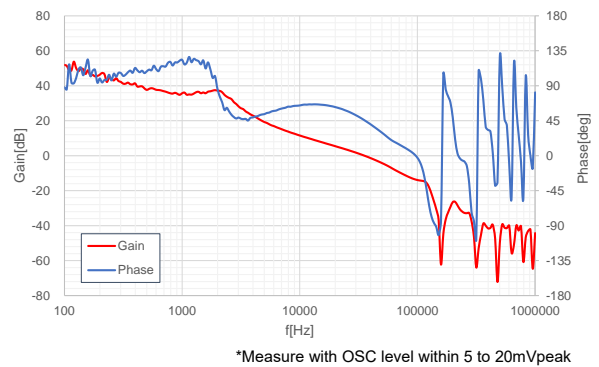


Figure 11-3. Frequency Characteristics
(Vin=24V, Vo=5V, Io=5A, OSC:20mVpeak)

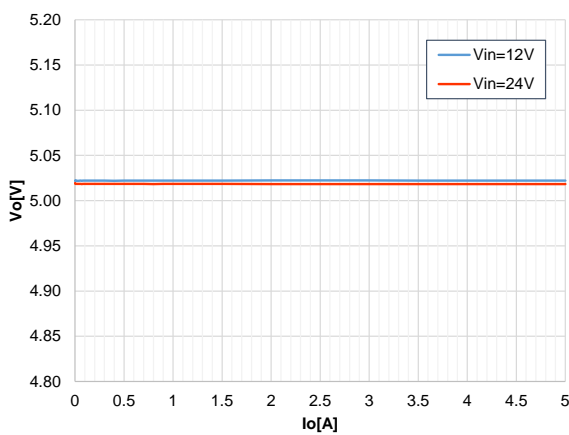


Figure 11-4. Load Regulation

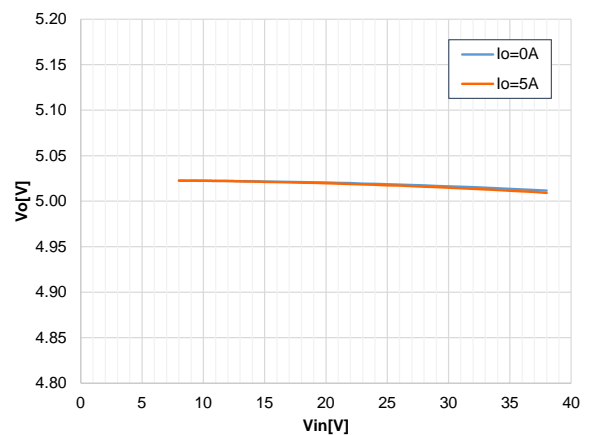


Figure 11-5. Line Regulation

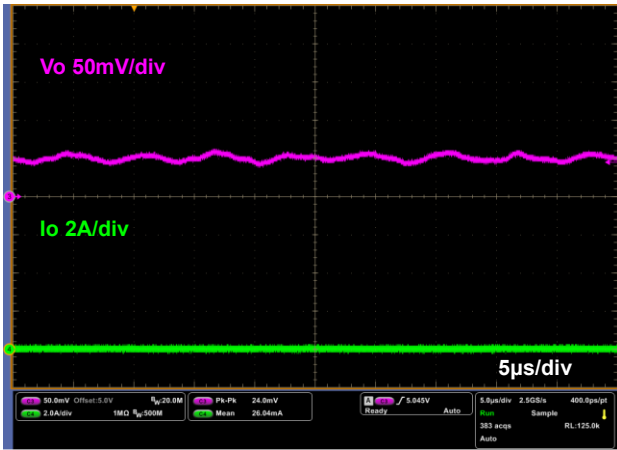


Figure 11-6. Output Ripple Voltage
($V_{in}=12V$, $V_o=5V$, $I_o=0A$)

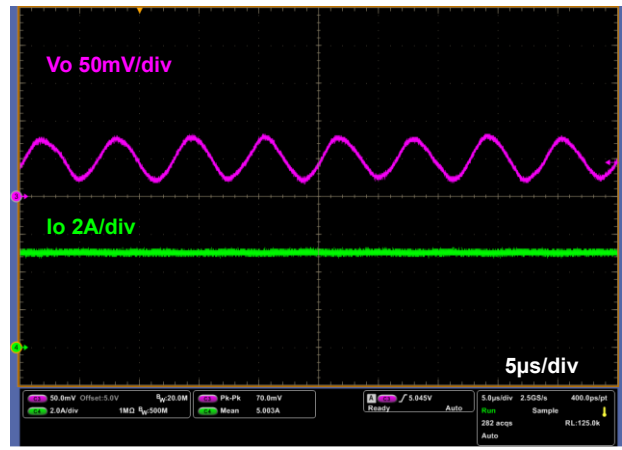


Figure 11-7. Output Ripple Voltage
($V_{in}=12V$, $V_o=5V$, $I_o=5A$)

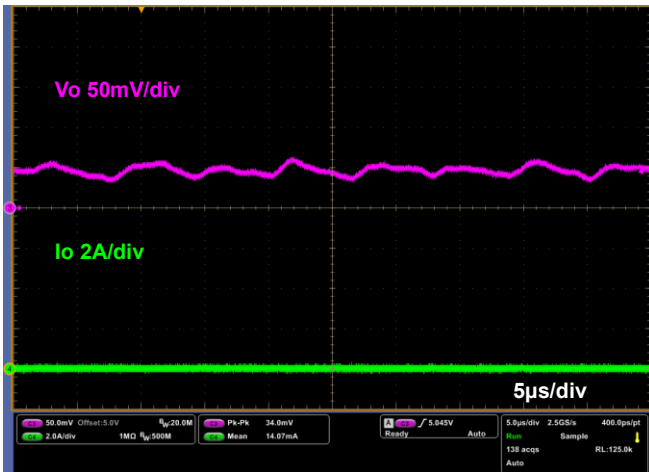


Figure 11-8. Output Ripple Voltage
($V_{in}=24V$, $V_o=5V$, $I_o=0A$)

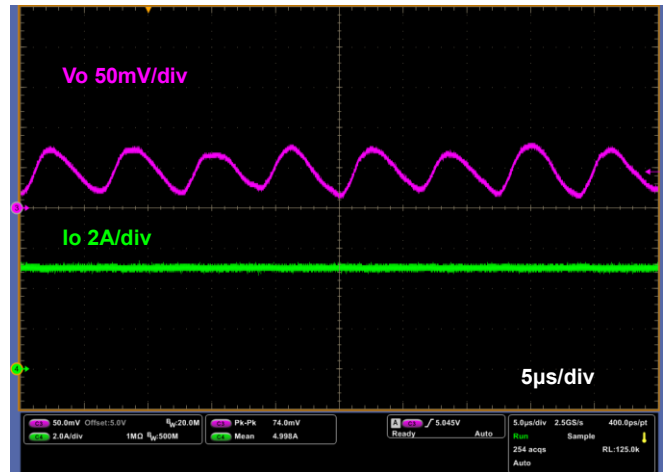


Figure 11-9. Output Ripple Voltage
($V_{in}=24V$, $V_o=5V$, $I_o=5A$)

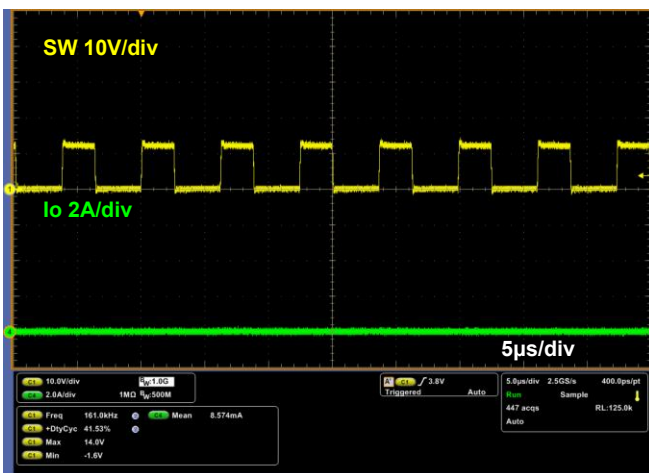


Figure 11-10. Switching Waveform
($V_{in}=12V$, $V_o=5V$, $I_o=0A$)



Figure 11-11. Switching Waveform
($V_{in}=12V$, $V_o=5V$, $I_o=5A$)

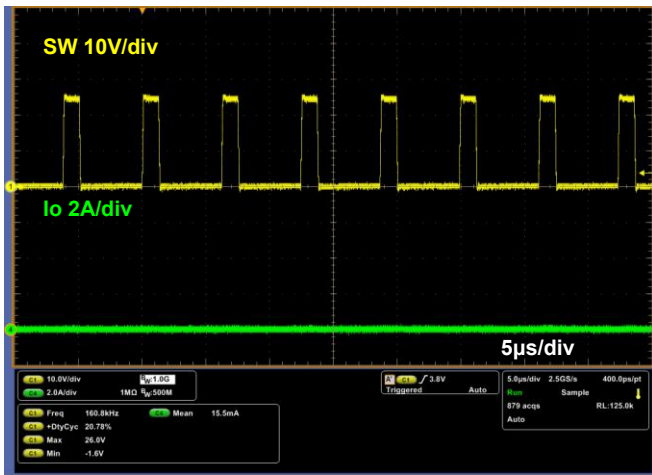


Figure 11-12. Switching Waveform
(Vin=24V, Vo=5V, Io=0A)

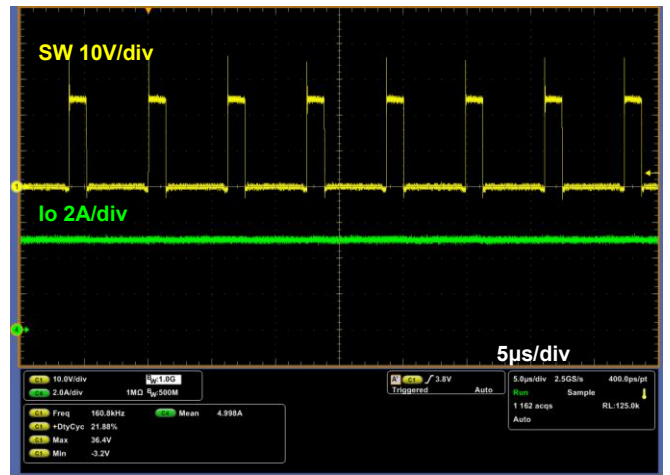


Figure 11-13. Switching Waveform
(Vin=24V, Vo=5V, Io=5A)

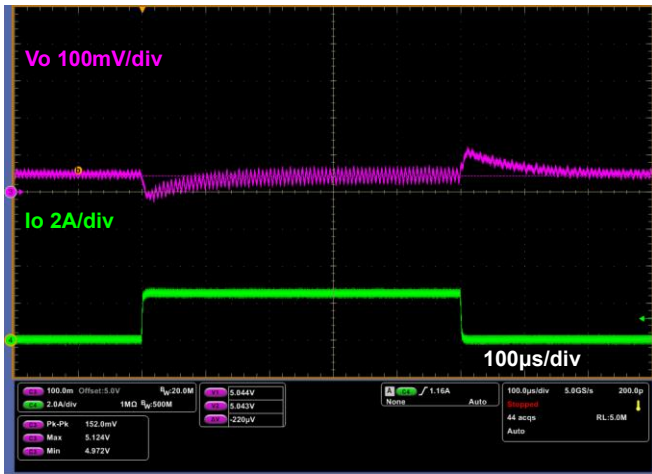


Figure 11-14. Load Transient
(Vin=12V, Vo=5V, Io=0A↔2.5A, 1A/µs)

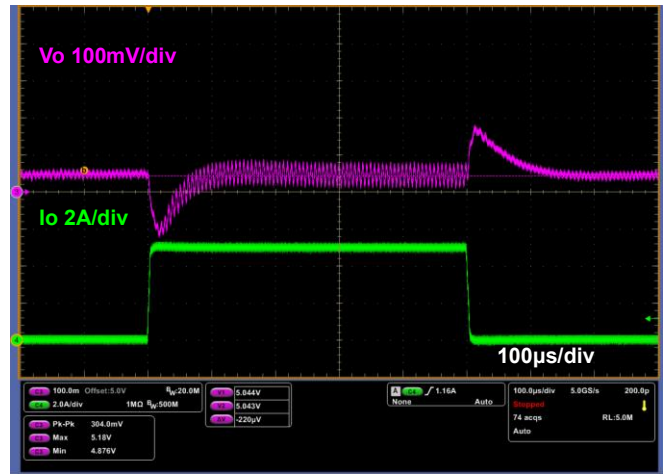


Figure 11-15. Load Transient
(Vin=12V, Vo=5V, Io=0A↔5A, 1A/µs)

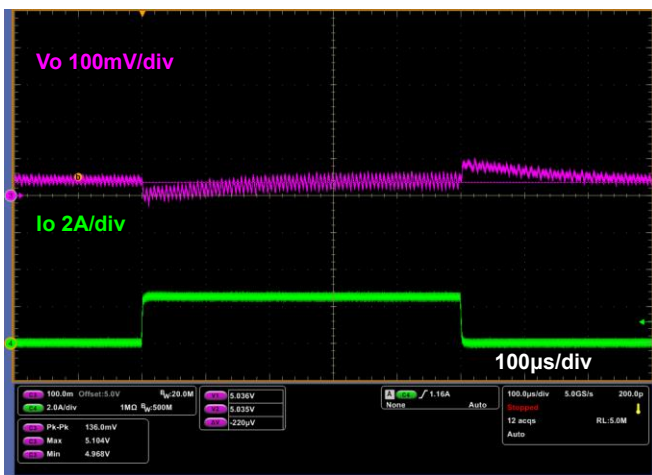


Figure 11-16. Load Transient
(Vin=24V, Vo=5V, Io=0A↔2.5A, 1A/µs)

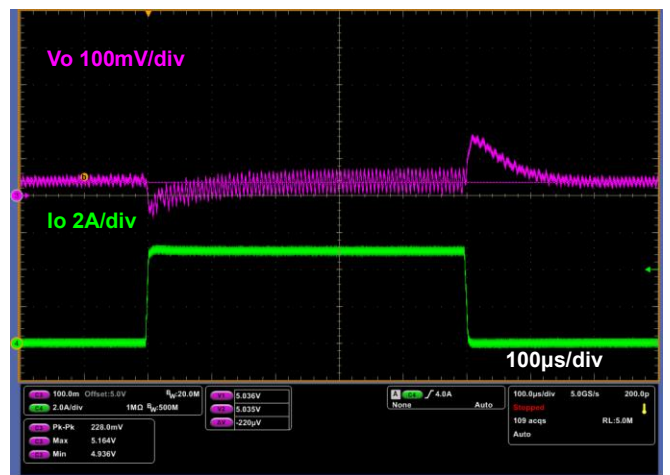


Figure 11-17. Load Transient
(Vin=24V, Vo=5V, Io=0A↔5A, 1A/µs)

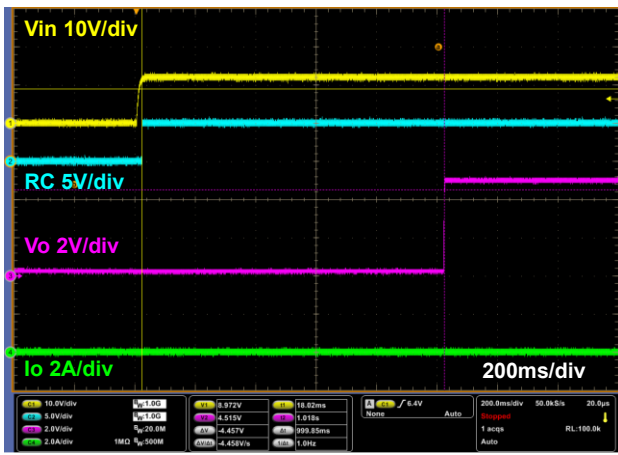


Figure 11-18. Startup Waveform
(Vin=0→12V, Vo=5V, Io=0A, RC=open)

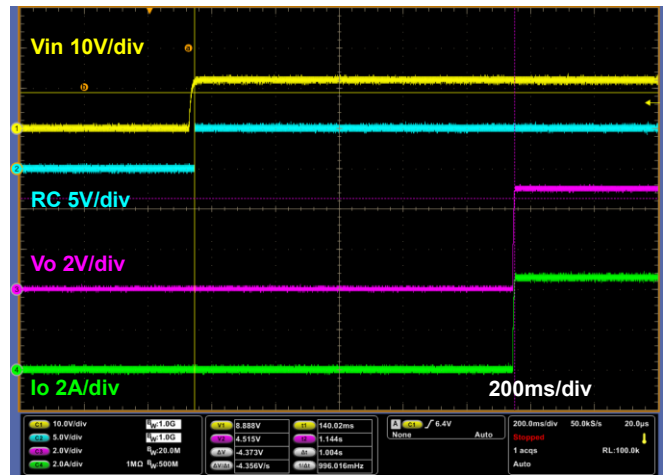


Figure 11-19. Startup Waveform
(Vin=0→12V, Vo=5V, Io=5A, RC=open)

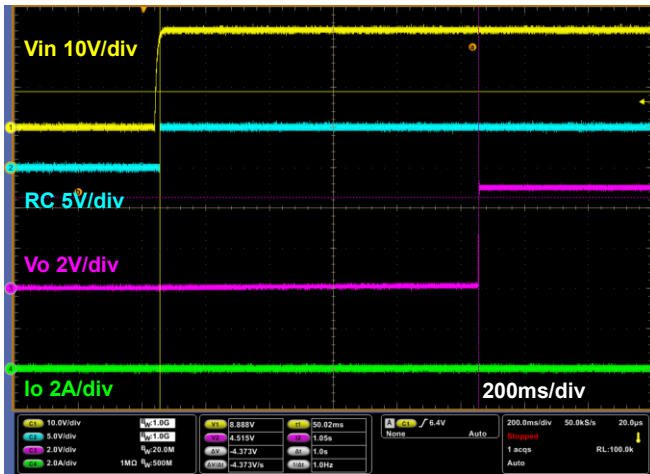


Figure 11-20. Startup Waveform
(Vin=0→24V, Vo=5V, Io=0A, RC=open)

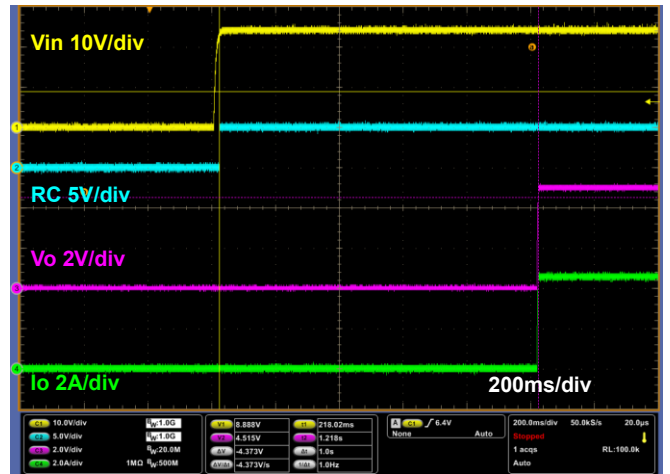


Figure 11-21. Startup Waveform
(Vin=0→24V, Vo=5V, Io=0A, RC=open)

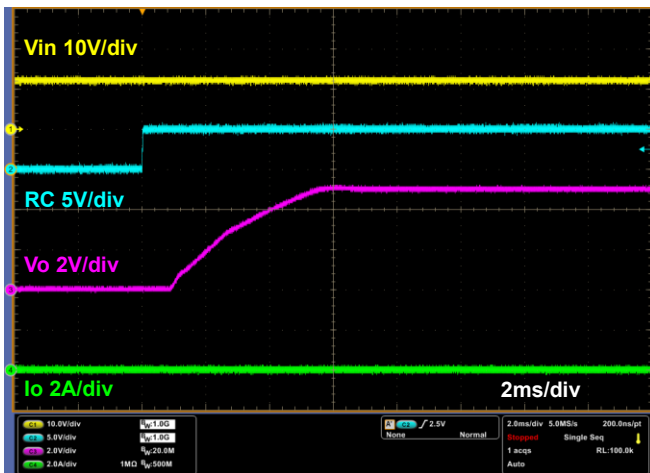


Figure 11-22. Startup Waveform
(Vin=12V, Vo=5V, Io=0A, RC=L→H)

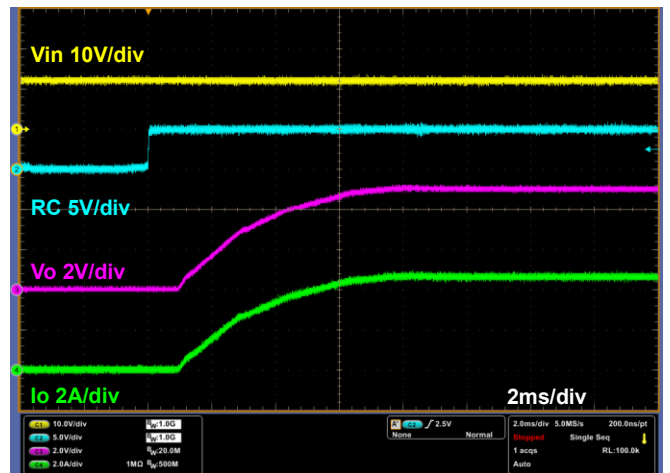


Figure 11-23. Startup Waveform
(Vin=12V, Vo=5V, Io=5A, RC=L→H)

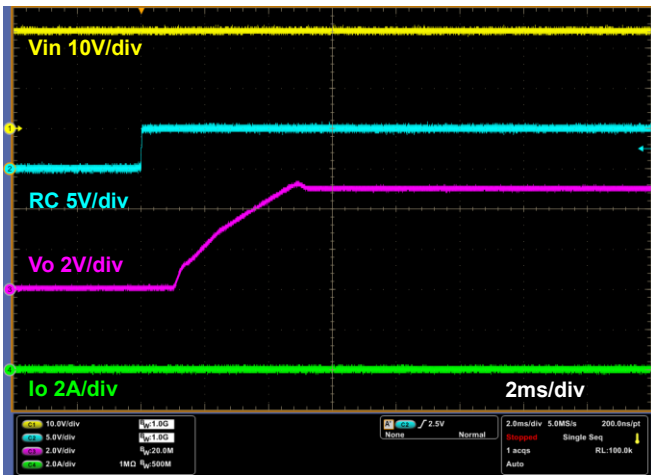


Figure 11-24. Startup Waveform
($V_{in}=24V$, $V_o=5V$, $I_o=0A$, $RC=L \rightarrow H$)

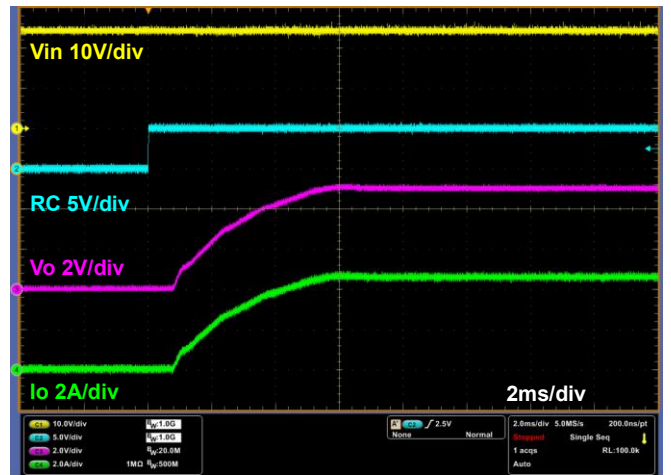


Figure 11-25. Startup Waveform
($V_{in}=24V$, $V_o=5V$, $I_o=5A$, $RC=L \rightarrow H$)

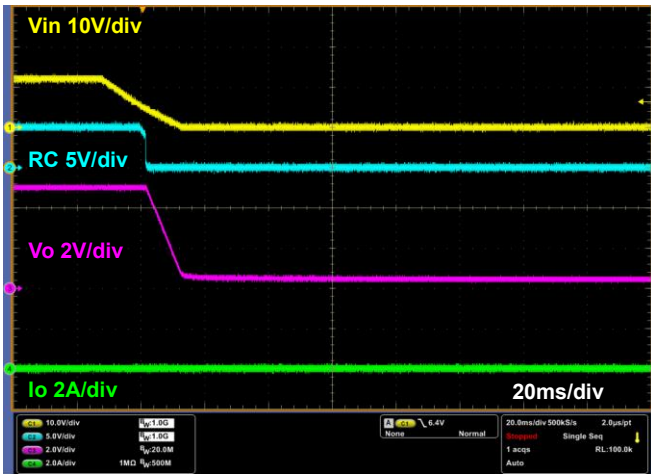


Figure 11-26. Stop Waveform
($V_{in}=12V \rightarrow 0V$, $V_o=5V$, $I_o=0A$, $RC=open$)

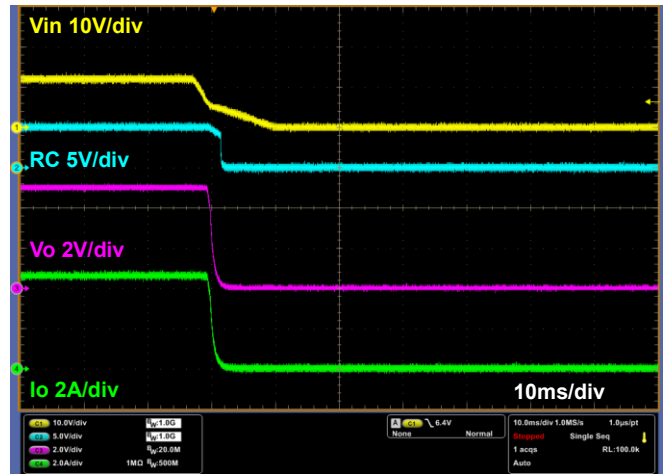


Figure 11-27. Stop Waveform
($V_{in}=12V \rightarrow 0V$, $V_o=5V$, $I_o=5A$, $RC=open$)

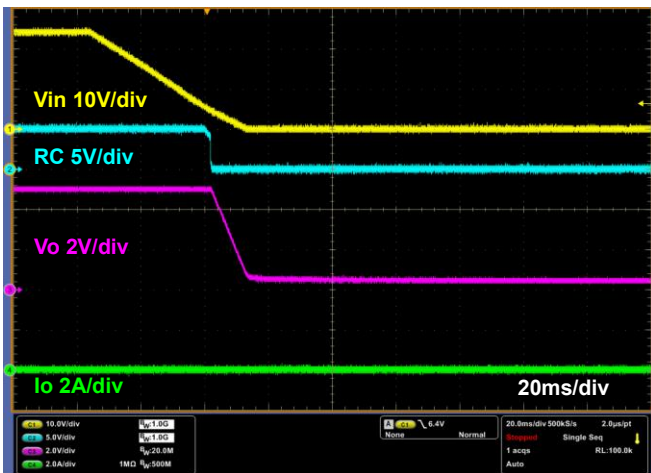


Figure 11-28. Stop Waveform
($V_{in}=24V \rightarrow 0V$, $V_o=5V$, $I_o=0A$, $RC=open$)

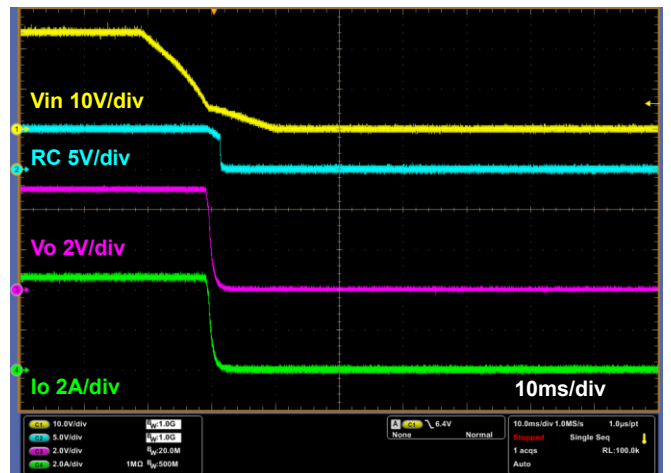


Figure 11-29. Stop Waveform
($V_{in}=24V \rightarrow 0V$, $V_o=5V$, $I_o=5A$, $RC=open$)

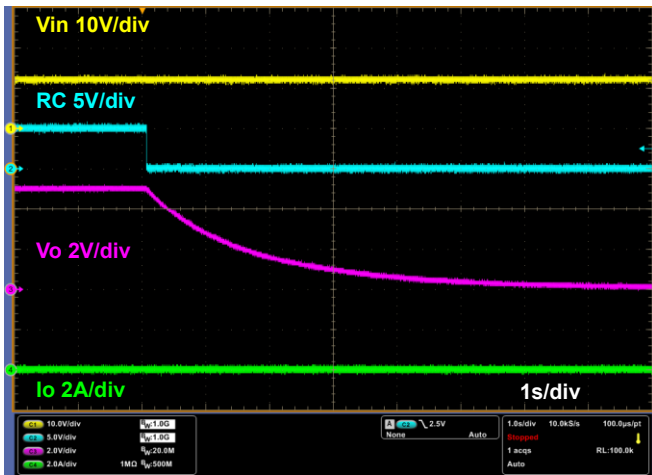


Figure 11-30. Stop Waveform
(Vin=12V, Vo=5V, Io=0A, RC=H→L)

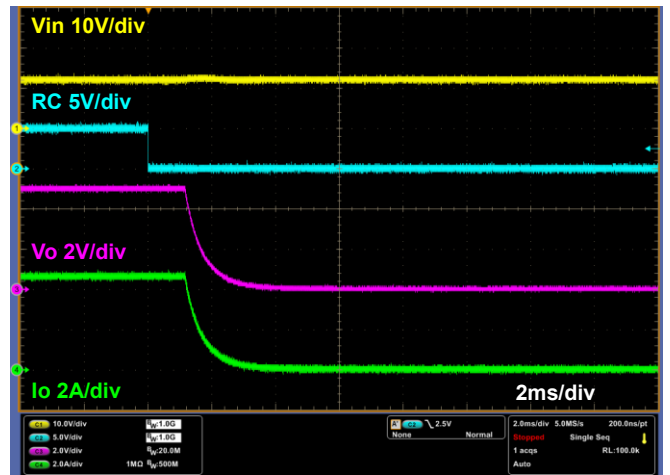


Figure 11-31. Stop Waveform
(Vin=12V, Vo=5V, Io=5A, RC=H→L)

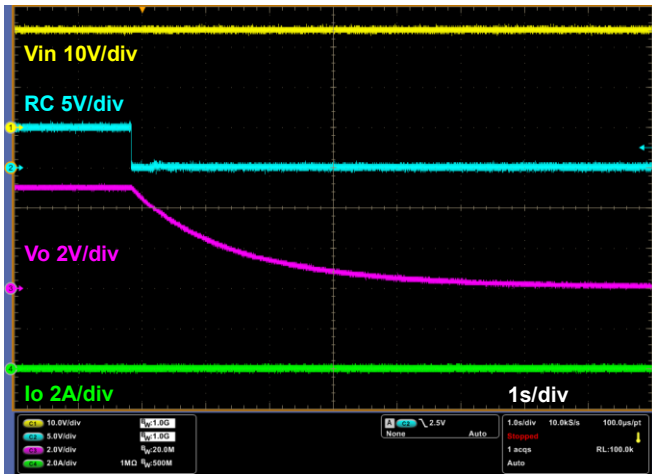


Figure 11-32. Stop Waveform
(Vin=24V, Vo=5V, Io=0A, RC=H→L)

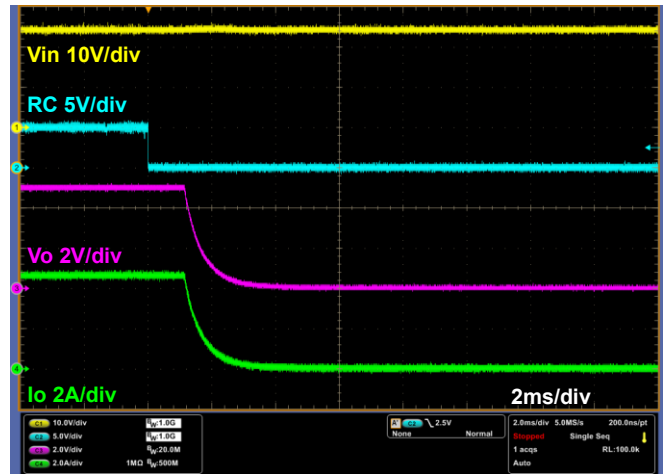


Figure 11-33. Stop Waveform
(Vin=24V, Vo=5V, Io=5A, RC=H→L)

12 References

- [1] 66AN145E, Rev001, Analog-Digital hybrid control innovating switching power design
- [2] FEDL62Q2045-01, ML62Q2033/2035/2043/2045 datasheet
- [3] FEUL62Q2045-03, ML62Q2033/2035/2043/2045 User's Manual
- [4] 66AN147E, Rev.001, Operating system for switching power control MCU "RMOS"
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- [6] TSZ02201-0RAR0G200370-1-2 Rev.001, High Speed Low Voltage Operation CMOS Operational Amplifiers BU7481G BU7481SG datasheet
- [7] TSZ02201-0Q2Q0A800840-1-2, Rev.002, High Frequency High-Side and Low-Side Driver BD2320EFJ-LA datasheet
- [8] 66AN149E, Rev.001, Serial communication of RMOS and GUI developing manual

Revision History

Date	Revision Number	Description
10. May.2024	001	Initial release.
31. Oct. 2024	002	p.12 Add description of 4.14 LED indicator. p.17 Add measurement condition and comment in Figure 11-2 and 11-3.

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