

## **Key Features**

- RoHS lead-free solder and lead-solder-exempted products are available
- Delivers up to 16 A (53 W)
- · Industry-standard footprint and pinout
- Single-in-Line Package (SIP): 2.0" x 0.575" x 0.315"
- (50.8 x 14.59 x 8.00 mm)
- Weight: 0.26 oz [7.28 q]
- Synchronous buck converter topology
- Start-up into pre-biased output
- No minimum load required
- Programmable output voltage via external resistor
- Operating ambient temperature: -40 °C to 85 °C
- Remote output sense
- Remote ON/OFF (Positive or Negative)
- Fixed-frequency operation
- Auto-reset output overcurrent protection
- Auto-reset overtemperature protection
- High reliability, MTBF = TBD Million Hours
- All materials meet UL94, V-0 flammability rating
- Safety approved to UL/CSA 62368-1 and EN/IEC 62368-1



3.0 - 5.5 VDC Input; 0.7525 - 3.63 VDC Programmable @ 16 A

Bel Power Solutions point-of-load converters are recommended for use with regulated bus converters in an Intermediate Bus Architecture (IBA). The YNV05T16 non-isolated DC-DC converter delivers up to 16 A of output current in an industry-standard through hole SIP package. Operating from a 3.0 – 5.5 V input, this converter is an ideal choice for Intermediate Bus Architectures where point-of-load power delivery is generally a requirement. It provides an extremely-tight regulated programmable output voltage from 0.7525 V to 3.63 V.

The YNV05T16 converter provides exceptional thermal performance, even in high temperature environments with minimal airflow. This is accomplished through the use of circuitry, packaging, and processing techniques to achieve ultra-high efficiency, excellent thermal management, and a very sleek body profile.

The sleek body profile and the preclusion of heat sinks minimize impedance to system airflow, thus enhancing cooling for both upstream and downstream devices. The use of 100% automation for assembly, coupled with advanced power electronics and thermal design, results in a product with extremely high reliability.

## **Applications**

- Intermediate Bus Architectures
- Telecommunications
- Data Communications
- Distributed Power Architectures
- Servers, Workstations

#### **Benefits**

- High efficiency no heat sink required
- Reduces Total Solution Board Area
- Minimizes Part Numbers in Inventory



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## **ELECTRICAL SPECIFICATIONS**

Conditions:  $T_A = 25$  °C, Airflow = 200 LFM (1 m/s),  $V_{A} = 5$  VDC,  $V_{A} = 0.7525 - 3.63$  V, unless otherwise specified.

PARAMETER	NOTES	MIN	TYP	MAX	UNITS
ABSOLUTE MAXIMUM RATINGS					
Input Voltage	Continuous	-0.3		6	VDC
Operating Ambient Temperature		-40		85	°C
Storage Temperature		-55		125	°C
FEATURE CHARACTERISTICS					
Switching Frequency			300		kHz
Output Voltage Programming Range <sup>1</sup>	By external resistor, See Trim Table 1	0.7525		3.63	VDC
Remote Sense Compensation <sup>1</sup>				0.5	VDC
Turn-On Delay Time <sup>2</sup>	Full resistive load				
With Vin = (Converter Enabled, then Vin applied)	From Vin = Vin(min) to Vo=0.1* Vo(nom)		3.5		ms
With Enable (Vin = Vin(nom) applied, then enabled)	From enable to Vo= 0.1*Vo(nom)		3.5		ms
Rise time <sup>2</sup> (Full resistive load)	From 0.1*Vo(nom) to 0.9*Vo (nom)		3.5		ms
ON/OFF Control (Positive Logic) <sup>3</sup>	Converter Off	-5		0.8	VDC
Civer i Control (i Caltive Logic)	Converter On	2.4		5.5	VDC
ON/OFF Control (Negative Logic) <sup>3</sup>	Converter Off Converter On	2.4 -5		5.5 0.8	VDC VDC
INPUT CHARACTERISTICS	Converter On	-5		0.0	VDC
	For Vout > 2.5 V	4.5	5.0	5.5	VDC
Operating Input Voltage Range	For Vout ≤ 2.5 V	3.0	5.0	5.5	VDC
Input Under Voltage Lockout	Turn-on Threshold		2.05	2.15	VDC
	Turn-off Threshold	1.75	1.9		VDC
Maximum Input Current					
Vin = 4.5V, lout = 16A	$V_{OUT} = 3.3 \text{ VDC}$			12.7	ADC
Vin = 3.0V, lout = 16A	V <sub>OUT</sub> = 2.5 VDC			14.7	ADC
Vin = 3.0V, lout = 16A	$V_{OUT} = 2.0 \text{ VDC}$			11.9	ADC
Vin = 3.0V, lout = 16A	V <sub>OUT</sub> = 1.8 VDC			10.8	ADC
Vin = 3.0V, lout = 16A	$V_{OUT} = 1.5 \text{ VDC}$			9.5	ADC
Vin = 3.0V, lout = 16A	V <sub>OUT</sub> = 1.2 VDC			7.8	ADC
Vin = 3.0V, lout = 16A	V <sub>OUT</sub> = 1.0 VDC			6.5	ADC
Vin = 3.0V, lout = 16A	V <sub>OUT</sub> = 0.7525 VDC			5.1	ADC
Input Stand-by Current (Converter disabled)	Vin = 5.0 VDC		10		mA
Input No Load Current (Converter enabled)	Vin = 5.5 VDC				
	$V_{OUT} = 3.3 \text{ VDC}$		90		mA
	$V_{OUT} = 2.5 \text{ VDC}$		85		mA
	V <sub>OUT</sub> = 2.0 VDC		80		mA
	V <sub>OUT</sub> = 1.8 VDC		75		mA
	V <sub>OUT</sub> = 1.5 VDC		70		mA
	V <sub>OUT</sub> = 1.2 VDC		65		mA
	V <sub>OUT</sub> = 1.0 VDC		60		mA
	$V_{\text{OUT}} = 0.7525 \text{ VDC}$		50		mA
Input Reflected-Ripple Current - is	See Fig. G for setup. (BW = 20 MHz)		15		$mA_{P-P}$



OUTPUT CHARACTERISTICS					
Output Voltage Set Point (no load)		-1.5	Vout	+1.5	%Vout
Output Regulation <sup>4</sup>	Over Line - Full resistive load		0.2		%Vout
	Over Load - From no load to full load		0.5		%Vout
Output Voltage Tolerance	(Overall operating input voltage, resistive load and temperature conditions until end of life)	-3		+3	%Vout
Output Ripple and Noise - 20MHz bandwidth (Fig. G) Over line, load and temperature	Vout = 3.3V Full load, Peak-to-Peak		30	60	$mV_{\text{P-P}}$
	Vout = 0.7525V Full load, Peak-to-Peak		15	30	$mV_{\text{P-P}}$
External Load Capacitance	Min ESR $> 1m\Omega$			1000	μF
Plus full load (resistive)	Min ESR $> 10 \text{ m}\Omega$			5000	μF
Output Current Range		0		16	Α
Output Current Limit Inception (Iout)			20	28	Α
Output Short- Circuit Current (Hiccup mode)	Short=10 mΩ, continuous		6		Arms
DYNAMIC RESPONSE					
Load current change from 8A – 16A, di/dt = 5 A/ $\mu$ S	Co = 100 $\mu$ F ceramic + 1 $\mu$ F ceramic		160 <sup>5</sup>		mV
Settling Time (V <sub>OUT</sub> < 10% peak deviation)			40		μs
Unloading current change $16A - 8A$ , $di/dt = -5 A/\mu S$	Co = 100 $\mu$ F ceramic + 1 $\mu$ F ceramic	= 100 μF ceramic + 1 μF ceramic			mV
Settling Time (V <sub>OUT</sub> < 10% peak deviation)			40		μs
EFFICIENCY	Full load (16A)				
	$V_{\text{OUT}} = 3.3 \text{ VDC}$		93.5		%
	V <sub>OUT</sub> = 2.5 VDC		92.0		%
	$V_{OUT} = 2.0 \text{ VDC}$		90.5		%
	V <sub>OUT</sub> = 1.8 VDC		89.5		%
	V <sub>OUT</sub> = 1.5 VDC		88.0		%
	V <sub>OUT</sub> = 1.2 VDC		85.5		%
	V <sub>OUT</sub> = 1.0 VDC		83.5		%
	V <sub>OUT</sub> = 0.7525 VDC		79.5		%

### Notes:

- The output voltage should not exceed 3.63V (taking into account both the programming and remote sense compensation).
- Note that start-up time is the sum of turn-on delay time and rise time.
- The converter is on if ON/OFF pin is left open.
- <sup>4</sup> Trim resistor connected across the GND (pin 5) and TRIM pins of the converter.
- <sup>5</sup> See waveforms for dynamic response and settling time for different output voltages.



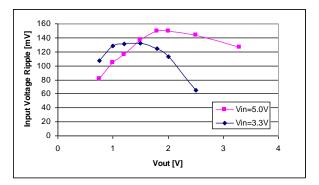
#### **OPERATIONS**

#### Input and Output Impedance

The YNV05T16 converter should be connected via a low impedance to the DC power source. In many applications, the inductance associated with the distribution from the power source to the input of the converter can affect the stability of the converter. It is recommended to use decoupling capacitors in order to ensure stability of the converter and reduce input ripple voltage. Internally, the converter has  $52~\mu F$  (low ESR ceramics) of input capacitance. In a typical application, low - ESR tantalum or POS capacitors will be sufficient to provide adequate ripple voltage filtering at the input of the converter. However, very low ESR ceramic capacitors of  $47~\mu F$  to  $100~\mu F$  are recommended at the input of the converter in order to minimize the input ripple voltage. They should be placed as close as possible to the input pins of the converter.

The YNV05T16 has been designed for stable operation with or without external output capacitance. Low ESR ceramic capacitors (minimum  $47\mu$ F) placed as close as possible to the load are recommended for improved transient performance and lower output voltage ripple.

It is important to keep low resistance and low inductance PCB traces when the connecting load to the output pins of the converter in order to maintain good load regulation.



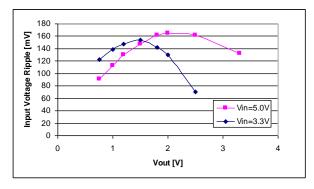


Fig. A: Input Voltage Ripple, CIN = 4 x 47 μF ceramic.

Fig. B: Input Voltage Ripple, CIN = 470 μF polymer + 2 x 47 μF ceramic.

Fig. A shows input voltage ripple for various output voltages using four  $47\mu F$  input ceramic capacitors. The same plot is shown in Fig. B with one 470  $\mu F$  polymer capacitor (6TPB470M from Sanyo) in parallel with two 47  $\mu F$  ceramic capacitors at full load.

#### ON/OFF (Pin 10)

The ON/OFF pin is used to turn the converter on or off remotely via a system signal. There are two remote control options available, positive logic (standard option) and negative logic, and both are referenced to GND. Typical connections are shown in Fig. C.

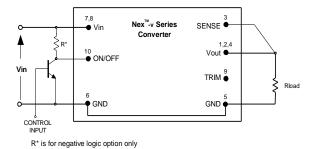


Fig. C: Circuit configuration for ON/OFF function.

The positive logic version turns the converter on when the ON/OFF pin is at a logic high or left open, and turns converter off when at a logic low or shorted to GND.



The negative logic version turns the converter on when the ON/OFF pin is at a logic low or left open, and turns the converter off when the ON/OFF pin is at a logic high or connected to Vin.

The ON/OFF pin is internally pulled-up to Vin for a positive logic version, and pulled-down for a negative logic version. A TTL or CMOS logic gate, open collector (open drain) transistor can be used to drive ON/OFF pin. When using an open collector (open drain) transistor with a negative logic option, add a pull-up resistor (R\*) of  $10k\Omega$  to Vin as shown in Fig. C. The external pull-up resistor (R\*) can be increased to  $20k\Omega$  if minimum input voltage is more than 4.5V. This device must be capable of:

- sinking up to 0.6 mA at a low level voltage of ≤ 0.8 V
- sourcing up to 0.25 mA at a high logic level of 2.3V 5.5V

#### Remote Sense (Pin 3)

The remote sense feature of the converter compensates for voltage drops occurring only between Vout of the converter and the load. The SENSE (Pin 3) pin should be connected at the load or at the point where regulation is required (see Fig. D). There is no sense feature on the output GND return pin, where a solid ground plane is recommended to provide a low voltage drop.

If remote sensing is not required, the SENSE pin must be connected to the Vout to ensure the converter will regulate at the specified output voltage. If these connections are not made, the converter will deliver an output voltage that is slightly higher than the specified value.

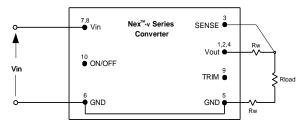


Fig. D: Remote sense circuit configuration.

Because the sense lead carries minimal current, large trace on the end-user board is not required. However, the sense trace should be located close to a ground plane to minimize system noise and ensure optimum performance.

When utilizing the remote sense feature, care must be taken not to exceed the maximum allowable output power capability of the converter, equal to the product of the nominal output voltage and the allowable output current for the given conditions.

When using remote sense, the output voltage of the converter can be increased up to 0.5V above the sense point voltage in order to maintain the required voltage across the load. Therefore, the designer must, if necessary, decrease the maximum current (originally obtained from the derating curves) by the same percentage to ensure the converter's actual output power remains at or below the maximum allowable output power.

### **Output Voltage Programming (Pin 9)**

The output voltage can be programmed from 0.7525 V to 3.63 V by connecting an external resistor between the TRIM pin (Pin 9) and the GND pin (Pin 5); see Fig. E. Note that when a trim resistor is not connected, the output voltage of the converter is 0.7525 V.

A trim resistor, RTRIM, for a desired output voltage can be calculated using the following equation:

$$R_{\text{TRIM}} = \frac{21.07}{\left(\text{V}_{\text{O-REQ}} - 0.7525\right)} - 5.11 \qquad [k\Omega]$$

where,

 $\mathbf{R}_{\mathsf{TRIM}} = \mathsf{Required}$  value of trim resistor  $[\mathsf{k}\Omega]$ 

**Vo-REQ** = Desired (trimmed) output voltage [V]



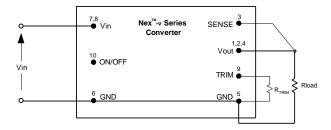


Fig. E: Configuration for programming output voltage.

Note that the tolerance of a trim resistor directly affects the output voltage tolerance. It is recommended to use standard 1% or 0.5% resistors. For tighter tolerance, two resistors in parallel are recommended rather than one standard value from Table 1.

The ground pin of the trim resistor should be connected directly to the converter GND pin (Pin 5) with no voltage drop in between. Table 1 provides the trim resistor values for popular output voltages.

V <sub>0-REG</sub> [V]	R <sub>TRIM</sub> [kΩ]	The Closest Standard Value [kΩ]
0.7525	open	
1.0	80.0	80.6
1.2	41.97	42.2
1.5	23.1	23.2
1.8	15	15
2.0	11.78	11.8
2.5	6.95	6.98
3.3	3.16	3.16
3.63	2.21	2.21

Table 1: Trim Resistor Value

The output voltage can also be programmed by external voltage source. To make trimming less sensitive, a series external resistor (Rext) is recommended between the Trim pin (pin 9) and the programming voltage source. Control Voltage can be calculated by the formula:

$$V_{\text{CTRL}} = 0.7 - \frac{(5.11 + R_{\text{EXT}})(V_{\text{O-REQ}} - 0.7525)}{30.1}$$
 [V]

Where,

**V**CTRL = Control voltage [V]

 $\mathbf{R}_{\text{EXT}}$  = External resistor between TRIM pin and voltage source; the value can be chosen depending on the required output voltage range [k $\Omega$ ]

Control voltages with  $\mathbf{R}\mathbf{E}\mathbf{x}\mathbf{T}=0$  and  $\mathbf{R}\mathbf{E}\mathbf{x}\mathbf{T}=15k\Omega$  are shown in Table 2.

<b>V</b> <sub>0-REG</sub> [V]	R <sub>EXT</sub> = 0	$R_{EXT} = 15 k\Omega$
0.7525	0.700	0.700
1.0	0.658	0.535
1.2	0.624	0.401
1.5	0.573	0.201
1.8	0.522	-0.000
2.0	0.488	-0.133
2.5	0.403	-0.468
3.3	0.268	-1.002
3.63	0.257	-1.044

Table 2: Control Voltage [VDC]



#### **PROTECTION FEATURES**

### Input Undervoltage Lockout

Input undervoltage lockout is standard with this converter. The converter will shut down when the input voltage drops below a pre-determined voltage; it will start automatically when Vin returns to a specified range.

The input voltage must be typically 2.05V for the converter to turn on. Once the converter has been turned on, it will shut off when the input voltage drops below typically 1.9V.

## **Output Overcurrent Protection (OCP)**

The converter is protected against overcurrent and short-circuit conditions. Upon sensing an over-current condition, the converter will enter hiccup mode. Once the overload or short-circuit condition is removed, Vout will return to nominal value.

### **Overtemperature Protection (OTP)**

The converter will shut down under an overtemperature condition to protect itself from overheating caused by operation outside the thermal derating curves, or operation in abnormal conditions such as system fan failure. After the converter has cooled to a safe operating temperature, it will automatically restart.

## **Safety Requirements**

Approved to the latest edition and amendment of ITE Safety standards, UL/CSA 62368-1 and EN/IEC 62368-1.

The maximum DC voltage between any two pins is Vin under all operating conditions. Therefore, the unit has ELV (extra low voltage) output; it meets ES1 requirements under the condition that all input voltages are ELV.

The converter is not internally fused. To comply with safety agencies requirements, a recognized fuse with a maximum rating of 25 Amps must be used in series with the input line.

#### **CHARACTERIZATION**

#### **General Information**

The converter has been characterized for many operational aspects, to include thermal derating (maximum load current as a function of ambient temperature and airflow) for vertical mounting, efficiency, start-up parameters, output ripple and noise, and transient response to load step-change.

The figures are numbered as Fig. x.y, where x indicates the different output voltages, and y associates with specific plots (y = 1 for the vertical thermal derating, ...). For example, Fig. x.1 will refer to the vertical thermal derating for all the output voltages in general.

The following pages contain specific plots or waveforms associated with the converter. Additional comments for specific data are provided below.

#### **Test Conditions**

All thermal and efficiency data presented were taken with the converter soldered to a test board, specifically a 0.060" thick printed wiring board (PWB) with four layers. The top and bottom layers were not metalized. The two inner layers, comprising two-ounce copper, were used to provide traces for connectivity to the converter.

The lack of metalization on the outer layers as well as the limited thermal connection ensured that heat transfer from the converter to the PWB was minimized. This provides a worst-case but consistent scenario for thermal derating purposes.

All measurements requiring airflow were made in vertical and horizontal wind tunnel facilities using Infrared (IR) thermography and thermocouples for thermometry.

Ensuring components on the converter do not exceed their ratings is important to maintaining high reliability. If one anticipates operating the converter at or close to the maximum loads specified in the derating curves, it is prudent to check actual operating temperatures in the application. Thermographic imaging is preferable; if this capability is not



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available, then thermocouples may be used. Bel Power Solutions recommends the use of AWG #40 gauge thermocouples to ensure measurement accuracy. Careful routing of the thermocouple leads will further minimize measurement error. Refer to Fig. F for optimum measuring thermocouple location.

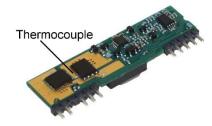


Fig. F: Location of the thermocouple for thermal testing.

### **Thermal Derating**

Load current vs. ambient temperature and airflow rates are given in Fig. x.1 for maximum temperature of 120 °C. Ambient temperature was varied between 25 °C and 85 °C, with airflow rates from 30 to 500 LFM (0.15 m/s to 2.5 m/s), and vertical converter mounting. The airflow during the testing is parallel to the long axis of the converter, going from ON/OFF pin to output pins.

For each set of conditions, the maximum load current was defined as the lowest of:

- The output current at which any MOSFET temperature does not exceed a maximum specified temperature (120 °C) as indicated by the thermographic image, or
- ii. The maximum current rating of the converter (16 A)

During normal operation, derating curves with maximum FET temperature less than or equal to 120 °C should not be exceeded. Temperature on the PCB at the thermocouple location shown in Fig. F should not exceed 120 °C in order to operate inside the derating curves.

#### **Efficiency**

Fig. x.2 show the efficiency vs. load current plot for ambient temperature of 25 °C, airflow rate of 200 LFM (1 m/s) and input voltages of 4.5 V, 5.0 V, and 5.5 V.

Fig. x.3 show the efficiency vs. load current plot for ambient temperature of 25 °C, airflow rate of 200 LFM (1 m/s) and input voltages of 3.0 V, 3.3 V, and 3.6 V for output voltages 2.5V.

#### **Power Dissipation**

Fig. 3.3V.3 shows the power dissipation vs. load current plot for Ta = 25 °C, airflow rate of 200 LFM (1 m/s) with vertical mounting and input voltages of 4.5 V, 5.0 V, and 5.5 V for 3.3 V output voltage.

#### Start-up

Output voltage waveforms, during the turn-on transient with application of Vin at full rated load current (resistive load) are shown with  $47\mu F$  external load capacitance at Vin = 5 V in Fig. x.4.

#### **Ripple and Noise**

The output voltage ripple waveform is measured at full rated load current. Note that all output voltage waveforms are measured across a  $1\mu$ F ceramic capacitor. The output voltage ripple and input reflected ripple current waveforms are obtained using the test setup shown in Fig. G.

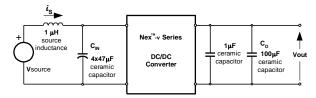


Fig. G: Test setup for measuring input reflected ripple current is and output voltage ripple



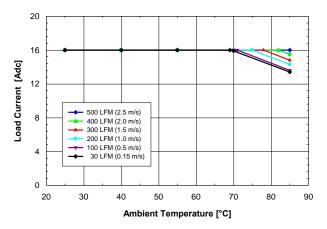


Fig. 3.3V.1: Available load current vs. ambient temperature and airflow rates for Vout = 3.3 V converter mounted vertically with Vin = 5 V, air flowing from pin 10 to pin 1, and maximum MOSFET temperature  $\leq 120 \text{ }^{\circ}\text{C}$ .

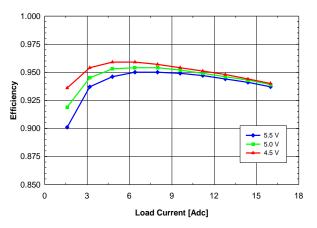


Fig. 3.3V.2: Efficiency vs. load current and input voltage for Vout = 3.3 V converter mounted vertically with air flowing from pin 10 to pin 1 at a rate of 200 LFM (1 m/s) and Ta = 25 °C.

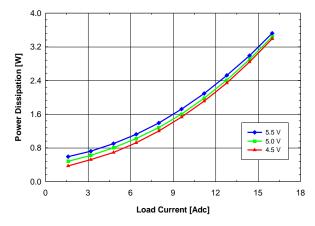


Fig. 3.3V.3: Power loss vs. load current and input voltage for Vout = 3.3 V converter mounted vertically with air flowing from pin 10 to pin 1 at a rate of 200 LFM (1 m/s) and Ta = 25 °C.

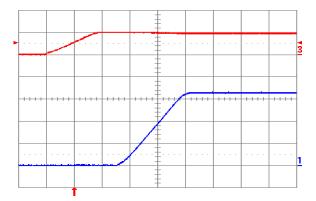


Fig. 3.3V.4: Turn-on transient for Vout = 3.3 V with application of Vin at full rated load current (resistive) and 100 μF external capacitance at Vin = 5 V. Top trace: Vin (5 V/div.); Bottom trace: output voltage (1 V/div.); Time scale: 2 ms/div.

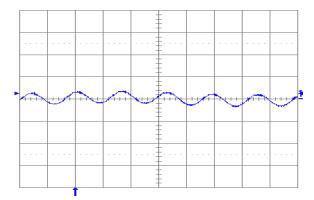


Fig. 3.3V.5: Output voltage ripple (20 mV/div.) at full rated load current into a resistive load with external capacitance  $100\,\mu F$  ceramic +  $1\,\mu F$  ceramic and Vin =  $5\,V$  for Vout =  $3.3\,V$ . Time scale:  $2\,\mu s/div$ .



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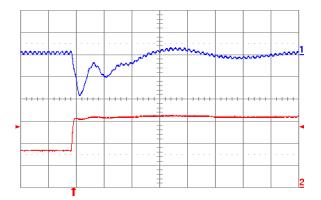


Fig. 3.3V.6: Output voltage response for Vout = 3.3 V to positive load current step change from 8 A to 16 A with slew rate of 5 A/μs at Vin = 5 V. Top trace: output voltage (100 mV/div.); Bottom trace: load current (5 A/div.). Co = 100 μF ceramic + 1 μF ceramic. Time scale: 20 μs/div.

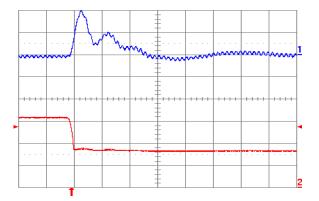


Fig. 3.3V.7: Output voltage response for Vout = 3.3 V to negative load current step change from 16 A to 8 A with slew rate of -5 A/μs at Vin = 5 V. Top trace: output voltage (100 mV/div.); Bottom trace: load current (5 A/div.). Co = 100 μF ceramic + 1 μF cera-mic. Time scale: 20 μs/div.

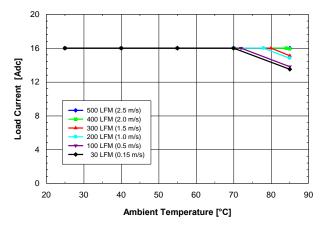


Fig. 2.5V.1: Available load current vs. ambient temperature and airflow rates for Vout = 2.5 V converter mounted vertically with Vin = 5 V, air flowing from pin 10 to pin 1, and maximum MOSFET temperature  $\leq 120 \text{ °C}$ .

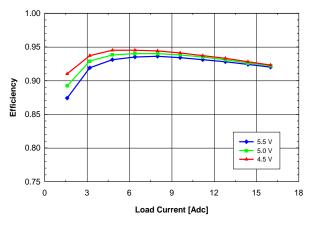


Fig. 2.5V.2: Efficiency vs. load current and input voltage for Vout = 2.5 V converter mounted vertically with air flowing from pin 10 to pin 1 at a rate of 200 LFM (1 m/s) and Ta = 25 °C.

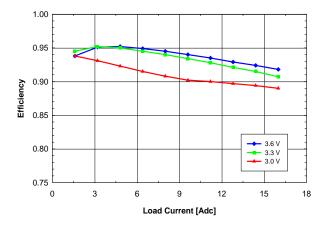


Fig. 2.5V.3: Efficiency vs. load current and input voltage for Vout = 2.5 V converter mounted vertically with air flowing from pin 10 to pin 1 at a rate of 200 LFM (1 m/s) and Ta = 25 °C.



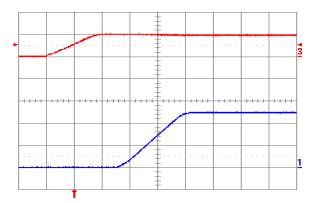


Fig. 2.5V.4: Turn-on transient for Vout = 2.5 V with application of Vin at full rated load current (resistive) and 100  $\mu$ F external capacitance at Vin = 5 V. Top trace: Vin (5 V/div.); Bottom trace: output voltage (1 V/div.); Time scale: 2 ms/div.

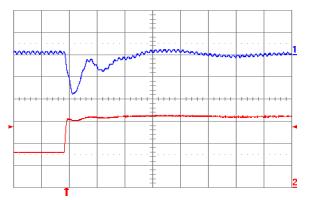


Fig. 2.5V.6: Output voltage response for Vout = 2.5 V to positive load current step change from 8 A to 16 A with slew rate of 5 A/μs at Vin = 5 V. Top trace: output voltage (100 mV/div.); Bottom trace: load current (5 A/div.). Co = 100 μF ceramic + 1 μF ceramic. Time scale: 20 μs/div.

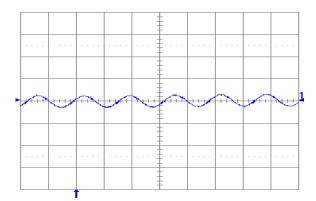


Fig. 2.5V.5: Output voltage ripple (20 mV/div.) at full rated load current into a resistive load with external capacitance 100  $\mu$ F ceramic + 1  $\mu$ F ceramic and Vin = 5 V for Vout = 2.5 V. Time scale: 2  $\mu$ s/div.

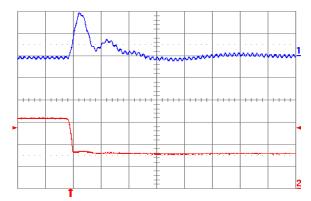


Fig. 2.5V.7: Output voltage response for Vout = 2.5 V to negative load current step change from 16 A to 8 A with slew rate of -5 A/μs at Vin = 5 V. Top trace: output voltage (100 mV/div.); Bottom trace: load current (5 A/div.). Co = 100 μF ceramic + 1 μF ceramic. Time scale: 20 μs/div.

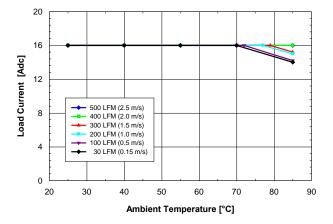


Fig. 2.0V.1: Available load current vs. ambient temperature and airflow rates for Vout = 2.0 V converter mounted vertically with Vin = 5 V, air flowing from pin 10 to pin 1, and maximum MOSFET temperature  $\leq 120 \text{ °C}$ .



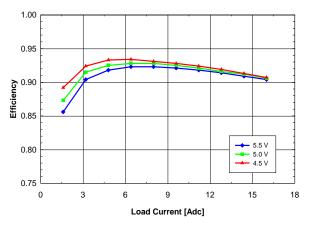


Fig. 2.0V.2: Efficiency vs. load current and input voltage for Vout = 2.0 V converter mounted vertically with air flowing from pin 10 to pin 1 at a rate of 200 LFM (1 m/s) and Ta = 25

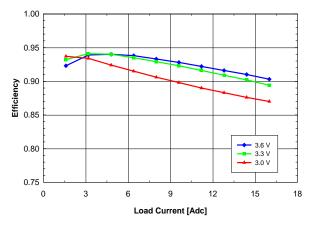


Fig. 2.0V.3: Efficiency vs. load current and input voltage for Vout = 2.0 V converter mounted vertically with air flowing from pin 10 to pin 1 at a rate of 200 LFM (1 m/s) and Ta = 25 °C.

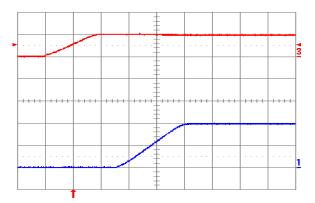


Fig. 2.0V.4: Turn-on transient for Vout = 2.0 V with application of Vin at full rated load current (resistive) and 100 μF external capacitance at Vin = 5 V. Top trace: Vin (5 V/div.); Bottom trace: output voltage (1 V/div.); Time scale: 2 ms/div.

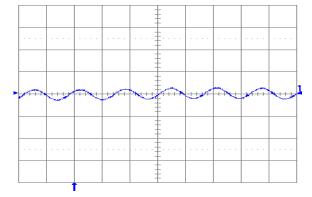


Fig. 2.0V.5: Output voltage ripple (20 mV/div.) at full rated load current into a resistive load with external capacitance  $100 \, \mu F$  ceramic +  $1 \, \mu F$  ceramic and Vin =  $5 \, V$  for Vout =  $2.0 \, V$ . Time scale:  $2 \, \mu s/div$ .

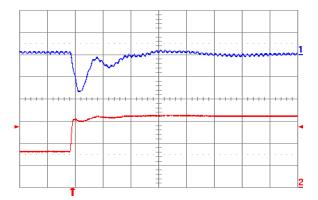


Fig. 2.0V.6: Output voltage response for Vout = 2.0 V to positive load current step change from 8 A to 16 A with slew rate of 5 A/μs at Vin = 5 V. Top trace: output voltage (100 mV/div.); Bottom trace: load current (5 A/div.). Co = 100 μF ceramic + 1 μF ceramic. Time scale: 20 μs/div.

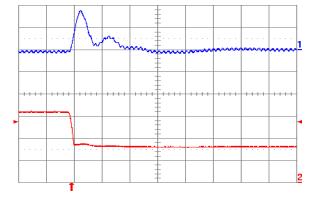


Fig. 2.0V.7: Output voltage response for Vout = 2.0 V to negative load current step change from 16 A to 8 A with slew rate of -5 A/μs at Vin = 5 V. Top trace: output voltage (100 mV/div.); Bottom trace: load current (5 A/div.). Co = 100 μF ceramic + 1 μF ceramic. Time scale: 20 μs/div.

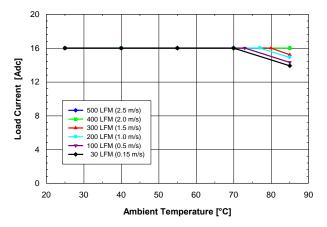


Fig. 1.8V.1: Available load current vs. ambient temperature and airflow rates for Vout = 1.8 V converter mounted vertically with Vin = 5 V, air flowing from pin 10 to pin 1, and maximum MOSFET temperature  $\leq$  120 °C.

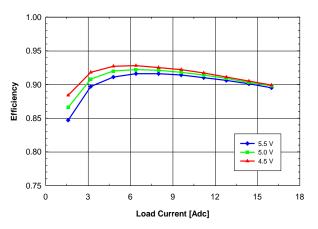


Fig. 1.8V.2: Efficiency vs. load current and input voltage for Vout = 1.8 V converter mounted vertically with air flowing from pin 10 to pin 1 at a rate of 200 LFM (1 m/s) and Ta = 25 °C.

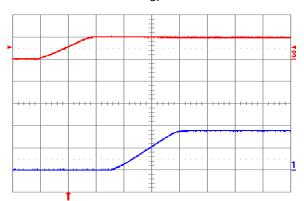


Fig. 1.8V.4: Turn-on transient for Vout = 1.8 V with application of Vin at full rated load current (resistive) and 100 μF external capacitance at Vin = 5 V. Top trace: Vin (5 V/div.); Bottom trace: output voltage (1 V/div.); Time scale: 2 ms/div.

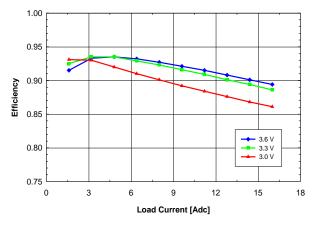


Fig. 1.8V.3: Efficiency vs. load current and input voltage for Vout = 1.8 V converter mounted vertically with air flowing from pin 10 to pin 1 at a rate of 200 LFM (1 m/s) and Ta = 25 °C.

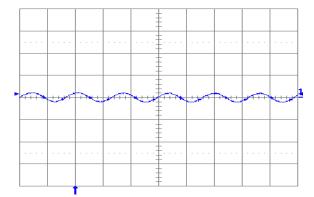


Fig. 1.8V.5: Output voltage ripple (20 mV/div.) at full rated load current into a resistive load with external capacitance 100 μF ceramic + 1 μF ceramic and Vin = 5 V for Vout = 1.8 V. Time scale: 2 μs/div.



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North America +1 408 785 5200

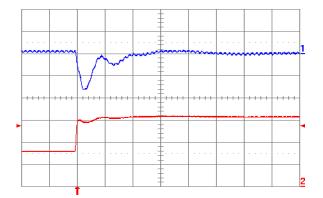


Fig. 1.8V.6: Output voltage response for Vout = 1.8 V to positive load current step change from 8 A to 16 A with slew rate of 5 A/μs at Vin = 5 V. Top trace: output voltage (100 mV/div.); Bottom trace: load current (5 A/div.). Co = 100 μF ceramic + 1 μF ceramic. Time scale: 20 μs/div.

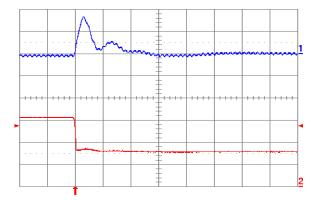


Fig. 1.8V.7: Output voltage response for Vout = 1.8 V to negative load current step change from 16 A to 8 A with slew rate of -5 A/μs at Vin = 5 V. Top trace: output voltage (100 mV/div.); Bottom trace: load current (5 A/div.). Co = 100 μF ceramic + 1 μF ceramic. Time scale: 20 μs/div.

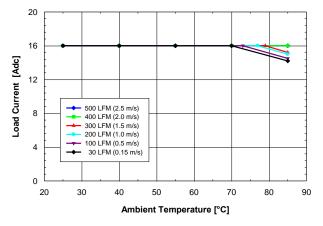


Fig. 1.5V.1: Available load current vs. ambient temperature and airflow rates for Vout = 1.5 V converter mounted vertically with Vin = 5 V, air flowing from pin 10 to pin 1, and maximum MOSFET temperature  $\leq$  120 °C.

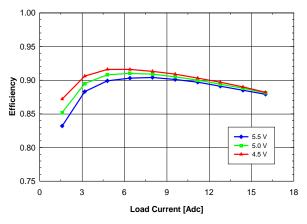


Fig. 1.5V.2: Efficiency vs. load current and input voltage for Vout = 1.5 V converter mounted vertically with air flowing from pin 10 to pin 1 at a rate of 200 LFM (1 m/s) and Ta = 25 °C.

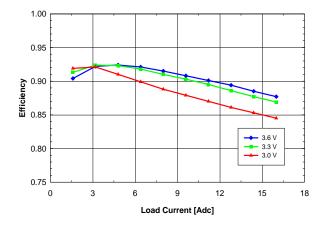


Fig. 1.5V.3: Efficiency vs. load current and input voltage for Vout = 1.5 V converter mounted vertically with air flowing from pin 10 to pin 1 at a rate of 200 LFM (1 m/s) and Ta = 25

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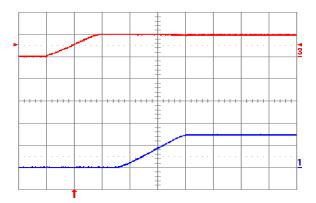


Fig. 1.5V.4: Turn-on transient for Vout = 1.5 V with application of Vin at full rated load current (resistive) and 100 μF external capacitance at Vin = 5 V. Top trace: Vin (5 V/div.); Bottom trace: output voltage (1 V/div.); Time scale: 2 ms/div.

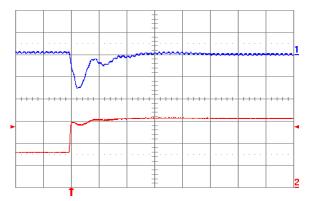


Fig. 1.5V.6: Output voltage response for Vout = 1.5 V to positive load current step change from 8 A to 16 A with slew rate of 5 A/μs at Vin = 5 V. Top trace: output voltage (100 mV/div.); Bottom trace: load current (5 A/div.). Co = 100 μF ceramic + 1 μF ceramic. Time scale: 20 μs/div.

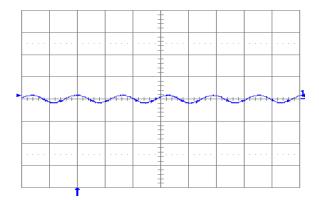


Fig. 1.5V.5: Output voltage ripple (20 mV/div.) at full rated load current into a resistive load with external capacitance 100 μF ceramic + 1 μF ceramic and Vin = 5 V for Vout = 1.5 V. Time scale: 2 μs/div.

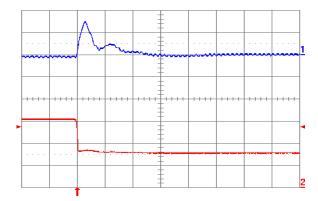


Fig. 1.5V.7: Output voltage response for Vout = 1.5 V to negative load current step change from 16 A to 8 A with slew rate of -5 A/μs at Vin = 5 V. Top trace: output voltage (100 mV/div.); Bottom trace: load current (5 A/div.). Co = 100 μF ceramic + 1 μF ceramic. Time scale: 20 μs/div.

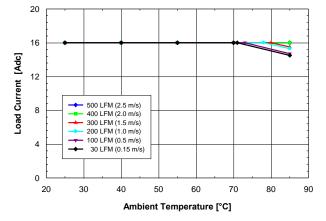


Fig. 1.2V.1: Available load current vs. ambient temperature and airflow rates for Vout = 1.2 V converter mounted vertically with Vin = 5 V, air flowing from pin 10 to pin 1, and maximum MOSFET temperature  $\leq$  120 °C.



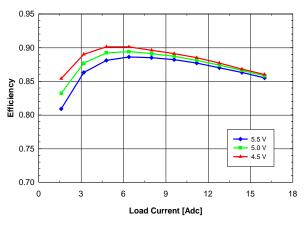


Fig. 1.2V.2: Efficiency vs. load current and input voltage for Vout = 1.2 V converter mounted vertically with air flowing from pin 10 to pin 1 at a rate of 200 LFM (1 m/s) and Ta = 25

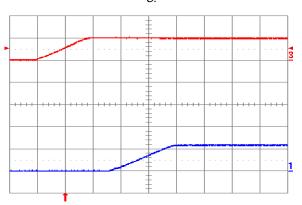


Fig. 1.2V.4: Turn-on transient for Vout = 1.2 V with application of Vin at full rated load current (resistive) and 100 μF external capacitance at Vin = 5 V. Top trace: Vin (5 V/div.); Bottom trace: output voltage (1 V/div.); Time scale: 2 ms/div.

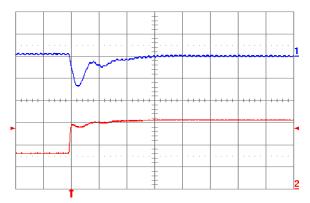


Fig. 1.2V.6: Output voltage response for Vout = 1.2 V to positive load current step change from 8 A to 16 A with slew rate of 5 A/μs at Vin = 5 V. Top trace: output voltage (100 mV/div.); Bottom trace: load current (5 A/div.). Co = 100 μF ceramic + 1 μF ceramic. Time scale: 20 μs/div.

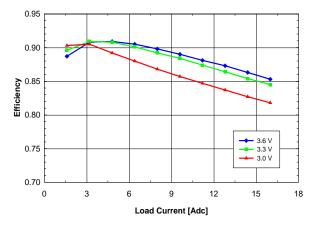


Fig. 1.2V.3: Efficiency vs. load current and input voltage for Vout = 1.2 V converter mounted vertically with air flowing from pin 10 to pin 1 at a rate of 200 LFM (1 m/s) and Ta = 25 °C.

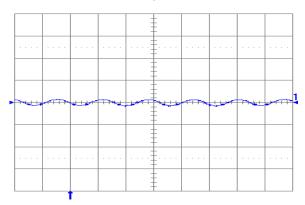


Fig. 1.2V.5: Output voltage ripple (20 mV/div.) at full rated load current into a resistive load with external capacitance  $100 \, \mu F$  ceramic +  $1 \, \mu F$  ceramic and Vin =  $5 \, V$  for Vout =  $1.2 \, V$ . Time scale:  $2 \, \mu s$ /div.

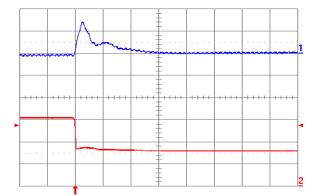


Fig. 1.2V.7: Output voltage response for Vout = 1.2 V to negative load current step change from 16 A to 8 A with slew rate of -5 A/μs at Vin = 5 V. Top trace: output voltage (100 mV/div.); Bottom trace: load current (5 A/div.). Co = 100 μF ceramic + 1 μF ceramic. Time scale: 20 μs/div.



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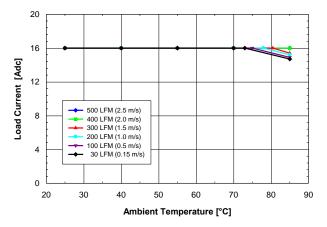


Fig. 1.0V.1: Available load current vs. ambient temperature and airflow rates for Vout = 1.0 V converter mounted vertically with Vin = 5 V, air flowing from pin 10 to pin 1, and maximum MOSFET temperature  $\leq 120 \text{ }^{\circ}\text{C}$ .

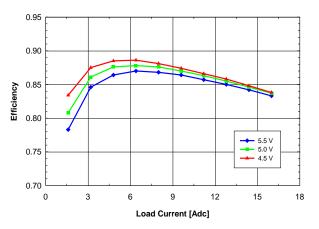


Fig. 1.0V.2: Efficiency vs. load current and input voltage for Vout = 1.0 V converter mounted vertically with air flowing from pin 10 to pin 1 at a rate of 200 LFM (1 m/s) and Ta = 25 °C.

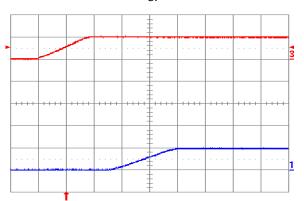


Fig. 1.0V.4: Turn-on transient for Vout = 1.0 V with application of Vin at full rated load current (resistive) and 100 μF external capacitance at Vin = 5 V. Top trace: Vin (5 V/div.); Bottom trace: output voltage (0.5 V/div.); Time scale: 2 ms/div.

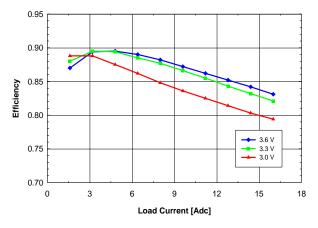


Fig. 1.0V.3: Power loss vs. load current and input voltage for Vout = 1.0 V converter mounted vertically with air flowing from pin 10 to pin 1 at a rate of 200 LFM (1 m/s) and Ta = 25 °C.

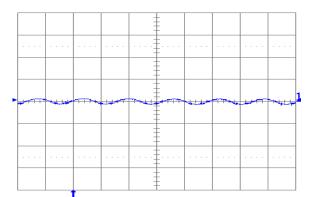


Fig. 1.0V.5: Output voltage ripple (20 mV/div.) at full rated load current into a resistive load with external capacitance 100 μF ceramic + 1 μF ceramic and Vin = 5 V for Vout = 1.0 V. Time scale: 2 μs/div.



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North America +1 408 785 5200

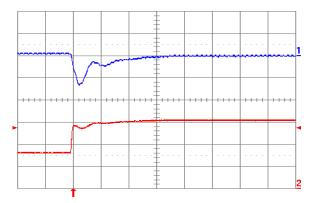


Fig. 1.0V.6: Output voltage response for Vout = 1.0 V to positive load current step change from 8 A to 16 A with slew rate of 5 A/μs at Vin = 5 V. Top trace: output voltage (100 mV/div.); Bottom trace: load current (5 A/div.). Co = 100 μF ceramic + 1 μF ceramic. Time scale: 20 μs/div.

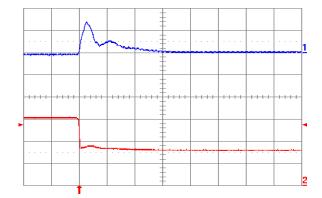


Fig. 1.0V.7: Output voltage response for Vout = 1.0 V to negative load current step change from 16 A to 8 A with slew rate of -5 A/μs at Vin = 5 V. Top trace: output voltage (100 mV/div.); Bottom trace: load current (5 A/div.). Co = 100 μF ceramic + 1 μF ceramic. Time scale: 20 μs/div.

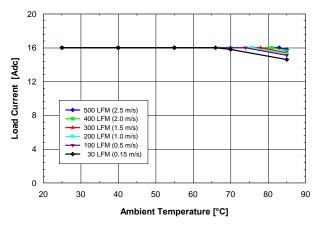


Fig. 0.7525V.1: Available load current vs. ambient temperature and airflow rates for Vout = 1.0 V converter mounted vertically with Vin = 5 V, air flowing from pin 10 to pin 1, and maximum MOSFET temperature  $\leq$  120 °C.

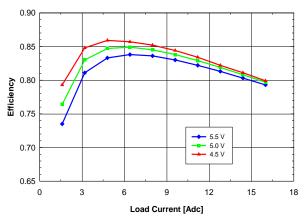


Fig. 0.7525V.2: Efficiency vs. load current and input voltage for Vout = 0.7525 V converter mounted vertically with air flowing from pin 10 to pin 1 at a rate of 200 LFM (1 m/s) and  $Ta = 25 \, ^{\circ}C$ .

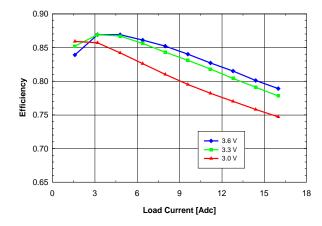


Fig. 0.7525V.3: Efficiency vs. load current and input voltage for Vout = 0.7525 V converter mounted vertically with air flowing from pin 10 to pin 1 at a rate of 200 LFM (1 m/s) and Ta = 25 °C.

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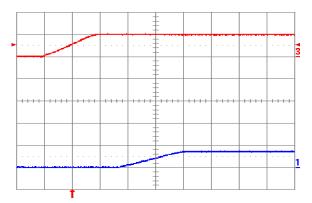


Fig. 0.7525V.4: Turn-on transient for Vout = 0.7525V with application of Vin at full rated load current (resistive) and 100 μF external capacitance at Vin = 5 V. Top trace: Vin (5 V/div.); Bottom trace: output voltage (1 V/div.); Time scale: 2 ms/div.

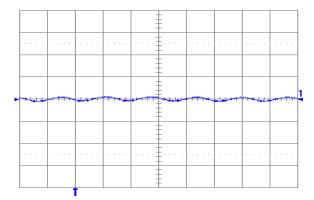


Fig. 0.7525V.5: Output voltage ripple (20 mV/div.) at full rated load current into a resistive load with external capacitance 100 μF ceramic + 1 μF ceramic and Vin = 5 V for Vout = 0.7525 V. Time scale: 2 μs/div.

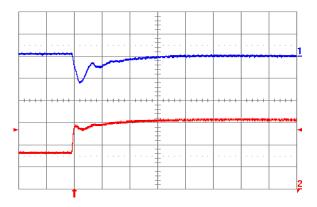


Fig. 0.7525V.6: Output voltage response for Vout = 0.7525 V to positive load current step change from 8 A to 16 A with slew rate of 5 A/μs at Vin = 5 V. Top trace: output voltage (100 mV/div.); Bottom trace: load current (5 A/div.). Co = 100 μF ceramic + 1 μF ceramic. Time scale: 20 μs/div.

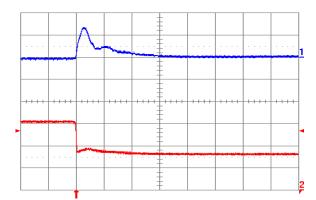
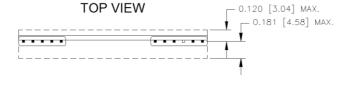
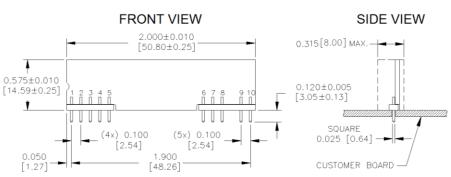


Fig. 0.7525V.7: Output voltage response for Vout = 0.7525 V to negative load current step change from 16 A to 8 A with slew rate of -5 A/μs at Vin = 5 V. Top trace: output voltage (100 mV/div.); Bottom trace: load current (5 A/div.). Co = 100 μF ceramic + 1 μF ceramic. Time scale: 20 μs/div.



### **PHYSICAL INFORMATION**





PAD/PIN CONNECTIONS				
Pad/Pin #	Function			
1	Vout			
2	Vout			
3	Vout SENSE			
4	Vout			
5	GND			
6	GND			
7	Vin			
8	Vin			
9	TRIM			
10	ON/OFF			

YNV05T16 Pinout (Through-Hole - SIP)

#### YNV05T16 Platform Notes

- All dimensions are in inches [mm]
- Connector Material: Phosphor Bronze/ Brass Alloy 360
- Connector Finish: Gold over Nickel
- Converter Weight: 0.26 oz [7.28 g]
- Converter Height: 0.585" Max.
- Recommended Through Hole Via/Pad:
   Min. 0.043" X 0.064" [1.09 x 1.63 mm]

### **ORDERING INFORMATION**

Product Series	Input Voltage	Mounting Scheme	Rated Load Current		Enable Logic	Environmental
YNV	05	Т	16	-	0	
V Sorios	Y-Series $3.0 - 5.5 \text{ V}$ $T \Rightarrow \text{Through-Hole}$ (SIP)	, T⇒Through-Hole 16 A	ough-Hole 16 A		0 ⇒ Standard (Positive Logic)	No Suffix ⇒ RoHS lead- solder-exempt compliant
r-Series		(0.7525 V to 3.63 V)		D ⇒ Opposite of Standard (Negative Logic)	$ G \qquad \Rightarrow \text{RoHS compliant} \\ \text{for all six substances} $	

The example above describes P/N YNV05T16-0: 3.0V – 5.5V input, thru-hole (SIP), 16A at 0.7525V to 3.63V output, standard enable logic, and RoHS lead solder exemption compliant. Please consult factory regarding availability of a specific version.

### For more information on these products consult: tech.support@psbel.com

**NUCLEAR AND MEDICAL APPLICATIONS** - Products are not designed or intended for use as critical components in life support systems, equipment used in hazardous environments, or nuclear control systems.

**TECHNICAL REVISIONS** - The appearance of products, including safety agency certifications pictured on labels, may change depending on the date manufactured. Specifications are subject to change without notice.

