



# SLDN-20D1Ax Series Non-Isolated DC-DC Converter

The SLDN-20D1Ax modules are non-isolated DC-DC converters that can deliver up to 20A of output current. These modules operate over a wide range of input voltage ( $V_{\rm IN}=3$  VDC-14.4 VDC) and provide a precisely regulated output voltage from 0.6 VDC to 5.5 VDC, programmable via an external resistor and Power Management Bus control.

Features include a digital interface using the Power Management Bus protocol, remote On/Off, adjustable output voltage, over current and over temperature protection. The Power Management Bus interface supports a range of commands to both control and monitor the module. The module also includes the Tunable Loop<sup>TM</sup> feature that allows the user to optimize the dynamic response of the converter to match the load with reduced amount of output capacitance leading to savings on cost and PWB area.



# **Key Features & Benefits**

- 3 VDC 14.4 VDC Input
- 0.45 VDC 5.5 VDC / 20 A Outputs
- Power Good signal
- Remote On/Off
- Over temperature protection
- Cost efficient open frame design
- Ability to sink and source current
- DOSA based
- Compatible in a Pb-free or SnPb reflow environment
- Output voltage programmable from 0.6 VDC to 2.0 VDC via external resistor
- Tunable Loop<sup>TM</sup> to optimize dynamic output voltage response
- Flexible output voltage sequencing EZ-SEQUENCE
- Fixed switching frequency with capability of external synchronization
- Output overcurrent protection (non-latching)
- Small size: 20.32 x 11.43 x 8.5 mm (0.8 x 0.45 x 0.334 in)
- Wide operating temperature range -40°C to 85°C

# **Applications**

- Distributed power architectures
- Servers and storage applications
- Intermediate bus voltage applications
- Networking equipment
- Telecommunications equipment
- Industrial equipment



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#### 1. MODEL SELECTION

OUTPUT VOLTAGE	INPUT VOLTAGE	MAX. OUTPUT CURRENT	MAX. OUTPUT POWER	TYPICAL EFFICIENCY	MODEL NUMBER ACTIVE LOW	MODEL NUMBER ACTIVE HIGH
0.45 - 5.5 VDC	3 - 14.4 VDC	20 A	110W	95.2%	SLDN-20D1A0	SLDN-20D1AL

**NOTE:** 1. Add "R" suffix at the end of the model number to indicate tape and reel packaging (Standard). 2. Add "G" suffix at the end of the model number to indicate tray packaging (Option).

#### PART NUMBER EXPLANATION

s	LDN	-	20	D	1A	0	x
Mounting type	Series code		Output current	Wide input voltage range	Sequencing	Logic status	Package
Surface mount	SLDN series		20A	3-14.4V	With sequencing	0 – active high L – active low	G – Tray R – Tape&Reel

# 2. ABSOLUTE MAXIMUM RATINGS

PARAMETER	DESCRIPTION	MIN	TYP	UNITS
Continuous Input Voltage		-0.3	15	V
Voltage on SEQ ,SYNC,VS+		-	7	V
Voltage on CLK,DATA,SMBALERT terminal		-	3.6	V
Operating Ambient Temperature	see Thermal Considerations section	-40	85	°C
Storage Temperature		-55	125	°C
Altitude		-	2000	m

**NOTE:** Stresses in excess of the absolute maximum ratings can cause permanent damage to the device. These are absolute stress ratings only, functional operation of the device is not implied at these or any other conditions in excess of those given in the operations sections of the data sheet. Exposure to absolute maximum ratings for extended periods can adversely affect the device reliability.

#### 3. INPUT SPECIFICATIONS

PARAMETER	DESCRIPTION		MIN	TYP	MAX	UNIT
Operating Input Voltage			3	-	14.4	V
Input Current	VIN=3V to 14 V, IO=IO	, max	-	-	19	Α
Input Current (no load)	VO,set = 0.6 VDC	VIN = 12VDC, $IO = 0$ ,	-	69	-	mA
input current (no load)	VO,set = 5 VDC module	module enabled	-	134	-	IIIA
Input Stand-by Current	VIN = 12V, module dis	abled	-	16.5	-	mA
Input Reflected Ripple Current (pk-pk)	impedance	IHz, 1μH source ; VIN =0 to 14V, IO= IOmax onfigurations	-	50	-	mA
I2t Inrush Current Transient			-	-	1	A2s
Input Ripple Rejection (120Hz)			-	-64	-	dB

NOTE: Unless otherwise indicated, specifications apply overall operating input voltage, resistive load, and temperature conditions.



# 4. OUTPUT SPECIFICATIONS

PARAMETER	DESCRIPTION	MIN	TYP	MAX	UNIT
Output Voltage Set Point	with 0.1% tolerance for external resistor used to set output voltage	-1.0	-	+1.0	%Vo,set
Output Voltage	Over all operating input voltage, resistive load, and temperature conditions until end of life	-3.0	-	+3.0	%Vo,set
Power Management Bus Adjustable Output Voltage Range		-25	0	+25	%Vo,set
Power Management Bus Output Voltage Adjustment Step Size		-	0.4	-	
Adjustment Range	Selected by an external resistor     Some output voltages may not be possible depending on the input voltage – see Feature Descriptions Section	0.6	-	5.5	V
Remote Sense Range		-	-	0.5	V
Line Regulation	VO ≥ 2.5V VIN=VIN. min tO VIN. max	±0.17	±0.27	0.4	%Vo,set
Line negulation	VO < 2.5V	-	-	5	mV
Load Regulation	VO ≥ 2.5V IO=IO, min to IO, max	10 10 min to 10 may	-	10	mV
Load negulation	VO < 2.5V	-	-	10	IIIV
Temperature Regulation	Tref=TA, min to TA, max	-	-	0.4	%Vo,set
Output Current	In either sink or source mode	0	-	20	mV
Output Ripple and Noise (pk-pk)	5Hz to 20MHz BW, VIN=VIN, nom and IO=IO, min to IO,	-	50	100	mV
Output Ripple and Noise (rms)	max Co = $0.1\mu$ F // 22 $\mu$ F ceramic capacitors)	-	20	38	mV
Output Short-Circuit Current	Vo≤250mV, Hiccup Mode	1.4	2.5	3.6	Arms
Turn-On Delay and Rise Times (VIN=VIN, nom, IO=IO, max, VO	Case 1: On/Off input is enabled and then input power is applied (delay from instant at which VIN = VIN, min until Vo = 10% of Vo, set)	1.0	1.1	1.7	ms
to within ±1% of steady state.)	Case 2: Input power is applied for at least one second and then the On/Off input is enabled (delay from instant at which Von/Off is enabled until Vo = 10% of Vo, set)	600	700	1800	μs
Output voltage Rise time	Time for Vo to rise from 10% of Vo, set to 90% of Vo, set.	1.2	1.5	2.7	msec
ESR≥ 1 mΩ	Without the Tunable Loop™	2x47	-	2x47	
Capacitance ESR≥0.15 mΩ	With the Tunable $Loop^TM$	2x47	-	1000	μF
ESR≥ 10 mΩ	With the Tunable $Loop^TM$	2x47	-	10000	
Output Current Limit Inception	Current limit does not operate in sink mode	110	130	150	% lo,max

**NOTE**: Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions. External capacitors may require using the new Tunable Loop<sup>TM</sup> feature to ensure that the module is stable as well as getting the best transient response. See the Tunable Loop<sup>TM</sup> section for details.



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#### 3. GENERAL SPECIFICATIONS

PARAMETER			DESCRIPTION	MIN	TYP	MAX	UNIT
	Vo=0.	6V		76.0	79.1	-	
	Vo=1.	2V		84.3	87.1	-	
- Fffining out	Vo=1.	8V	Vin= 12VDC, TA=25°C	87.2	90.4	-	%
Efficiency	Vo=2.	5V	Io=Io, max , Vo= Vo,set	90.3	92.6	-	90
	Vo=3.	3V		91.4	93.8	-	
	Vo=5.	0V		92.8	95.2	-	
Switching Frequency	•			475	500	525	kHz
Synchronization Fred	quency Range			425	-	600	kHz
High-Level Input Volt	tage			2.0	-	-	V
Low-Level Input Volt	age			-	-	0.4	V
Input Current, SYNC				-	-	100	nA
Minimum Pulse Widtl	h, SYNC			100			ns
Maximum SYNC rise	time			100			ns
Power Management	Bus Over Temp	perature Warning Threshold		120	130	140	°C
Power Management Thresholds	Bus Adjustable	Input Under Voltage Lockout		2.5	-	14	V
Resolution of Adjusta	able Input Unde	r Voltage Threshold		-	-	500	mV
Over Temperature Dr	rotootion		Tref-Q1	123	133	143	°C
Over Temperature Pr	otection		Tref-Q4	121	131	141	
Tracking Accuracy	Power-Up: 2	PV/ms	Vin, min to Vin, max; Io, min to	-	-	100	mV
	Power-Down	n: 2V/ms	Io, max, VSEQ < Vo		-	100	IIIV
	Overvoltage	threshold for PGOOD ON		103	108	113	%Vo, set
	Overvoltage	threshold for PGOOD OFF		100	105	110	%Vo, set
PGOOD (Power Good)	Undervoltag	e threshold for PGOOD ON	Signal Interface Open Drain, Vsupply ≤ 5VDC	105	110	115	%Vo, set
	Undervoltag	e threshold for PGOOD OFF		85	90	95	%Vo, set
	Pulldown res	sistance of PGOOD pin		-	-	50	Ω
	Sink current	capability into PGOOD pin		-	-	5	mA
Weight				4.086	4.54	4.994	g
		Turn-on Threshold		2.7	-	2.95	
Input Undervoltage Lockout		Turn-off Threshold		2.4	-	2.75	V
		Hysteresis		0.05	-	0.4	
MTBF			Calculated MTBF (IO=0.8IO, max, TA=40°C) Telecordia Issue 2 Method 1 Case 3		15,455,61	4	hours
Dimension - (L. 14)	LD			0. 800 x 0.450 x 0.334		in	
Dimensions (L × W ×	н)			20.3	2 x 11.43	x 8.50	mm

NOTE: Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions.



# 4. DIGITAL INTERFACE SPECIFICATIONS

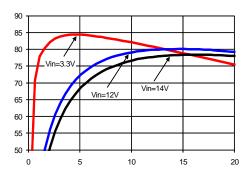
POWER MANAGEMENT BUS SIGNAL INTERFACE CHARACTERISTICS   1.1   1	PARAMETER	DESCRIPTION	MIN	TYP	MAX	UNIT
Input Low Voltage (CLK, DATA)   7.0	POWER MANAGEMENT BUS SIGNAL	INTERFACE CHARACTERISTICS				
Thight level current (CLK, DATA) (CLK, DATA, SMBALERT#) (C	Input High Voltage (CLK, DATA)		2.1	-	3.6	V
CLK, DATA    File of the part of the pa	Input Low Voltage (CLK, DATA)		-	-	8.0	V
Pout four four four four four four four four			-10	-	10	μΑ
CLCK, DATA, SMBALERT#)   Count   CLCK, DATA, SMBALERT#)   Clck   CLCK, DATA, SMBALERT#)   Clck   CLCK, DATA, SMBALERT#)   Clck   C	Input low level current		-10	-	10	μΑ
Current (DATA, SMBALERT#)         0         -         10         μA           Pin capacitance         -         0.7         -         pF           Data hold time         Receive Mode Transmit Mode         0         -         -         ns           Data setup time         250         -         -         ns           Power Management Bus Operating frequency range         10         -         400         kHz           MEASUREMENT SYSTEM CHARACTERISTICS         WEASUREMENT SYSTEM CHARACTERISTICS         153         192         231         μs           Output current measurement range         0         -         26         A           Output current measurement resolution         62.5         -         -         mA           Output current measurement offset         -         -         -         -         MA           Output current measurement offset         -		$I_{out} = 2 \text{ mA}$	-	-	0.4	V
Data hold time         Receive Mode Transmit Mode         0         -         -         ns           Data setup time         250         -         -         ns           Power Management Bus Operating frequency range         10         -         400         kHz           MEASUREMENT SYSTEM CHARACTERISTICS           Read delay time         153         192         231         μs           Output current measurement range         0         -         26         A           Output current measurement resolution         62.5         -         -         mA           Output current measurement gain accuracy         -         -         ±5         %           Output current measurement offset         -         -         -         mt           VOUT measurement range         0         -         5.5         V           VOUT measurement gain accuracy         -15         -         5.5         %           VOUT measurement gain accuracy         -15         -         5.6         %           VOUT measurement gain accuracy         -15         -         5.6         %           VOUT measurement range         0         -         14.4         V           VIN mea		V <sub>out</sub> = 3.6 V	0	-	10	μΑ
Data hold time         Transmit Mode         300         -         -         ns           Data setup time         250         -         -         ns           Power Management Bus Operating frequency range         10         -         400         kHz           MEASUREMENT SYSTEM CHARACTERISTICS           Read delay time         153         192         231         µs           Output current measurement range         0         -         26         A           Output current measurement resolution         62.5         -         -         mA           Output current measurement gain accuracy         -         -         4.5         %           Output current measurement offset         -         -         0.1         A           VOUT measurement range         0         -         5.5         V           VOUT measurement gain accuracy         -15         -         5         %           VOUT measurement offset         -3         -         3         %           VOUT measurement range         0         -         14.4         V           VOUT measurement range         0         -         14.4         V           VIN measurement resolution         -	Pin capacitance		-	0.7	-	pF
Data setup time         250         -         -           Power Management Bus Operating frequency range         10         -         400         kHz           MEASUREMENT SYSTEM CHARACTERISTICS           Read delay time         153         192         231         µs           Output current measurement range         0         -         26         A           Output current measurement resolution         62.5         -         -         mA           Output current measurement gain accuracy         -         -         ±5         %           Output current measurement offset         -         -         -         ±5         %           VOUT measurement range         0         -         5.5         V           VOUT measurement gain accuracy         -15         -         5.5         V           VOUT measurement gain accuracy         -15         -         5         %           VOUT measurement gain accuracy         -15         -         5         %           VOUT measurement range         0         -         14.4         V           VIN measurement resolution         -         32.5         -         mV           VIN measurement gain accuracy         -15	Data hold time	Receive Mode	0	-	-	ne
Power Management Bus Operating frequency range         10         -         400         kHz           MEASUREMENT SYSTEM CHARACTERISTICS           Read delay time         153         192         231         µs           Output current measurement range         0         -         26         A           Output current measurement resolution         62.5         -         -         mA           Output current measurement gain accuracy         -         -         ±5         %           Output current measurement offset         -         -         0.1         A           VOUT measurement range         0         -         5.5         V           VOUT measurement gain accuracy         -15         -         5         %           VOUT measurement gain accuracy         -15         -         5         %           VOUT measurement offset         -3         -         3         %           VIN measurement range         0         -         14.4         V           VIN measurement gain accuracy         -         32.5         -         mV           VIN measurement gain accuracy         -         32.5         -         mV	Data Hold time	Transmit Mode	300	-	-	115
frequency range         400 RFIZ           MEASUREMENT SYSTEM CHARACTERISTICS           Read delay time         153         192         231         µs           Output current measurement range         0         -         26         A           Output current measurement resolution         62.5         -         -         mA           Output current measurement gain accuracy         -         -         0.1         A           VOUT measurement range         0         -         5.5         V           VOUT measurement resolution         -         15.625         -         mV           VOUT measurement gain accuracy         -15         -         5         %           VOUT measurement offset         -3         -         3         %           VIN measurement range         0         -         14.4         V           VIN measurement gain accuracy         -         32.5         -         mV           VIN measurement gain accuracy         -         5         %	Data setup time		250	-	-	ns
MEASUREMENT SYSTEM CHARACTERISTICS           Read delay time         153         192         231         µs           Output current measurement range         0         -         26         A           Output current measurement resolution         62.5         -         -         mA           Output current measurement gain accuracy         -         -         ±5         %           Output current measurement offset         -         -         0.1         A           VOUT measurement range         0         -         5.5         V           VOUT measurement gain accuracy         -15         -         5         %           VOUT measurement offset         -3         -         3         %           VOUT measurement range         0         -         14.4         V           VIN measurement range         0         -         14.4         V           VIN measurement gain accuracy         -         32.5         -         mV           VIN measurement gain accuracy         -         32.5         -         mV			10	-	400	kHz
Output current measurement range         0         -         26         A           Output current measurement resolution         62.5         -         -         mA           Output current measurement gain accuracy         -         -         ±5         %           Output current measurement offset         -         -         0.1         A           VOUT measurement range         0         -         5.5         V           VOUT measurement gain accuracy         -15         -         5         %           VOUT measurement offset         -3         -         5         %           VOUT measurement range         0         -         14.4         V           VIN measurement resolution         -         32.5         -         mV           VIN measurement gain accuracy         -15         -         5         %		RISTICS				
Output current measurement resolution         62.5         -         -         mA           Output current measurement gain accuracy         -         -         ±5         %           Output current measurement offset         -         -         0.1         A           VOUT measurement range         0         -         5.5         V           VOUT measurement resolution         -         15.625         -         mV           VOUT measurement gain accuracy         -15         -         5         %           VOUT measurement offset         -3         -         3         %           VIN measurement range         0         -         14.4         V           VIN measurement resolution         -         32.5         -         mV           VIN measurement gain accuracy         -15         -         5         %	Read delay time		153	192	231	μs
Output current measurement gain accuracy       -       -       ±5       %         Output current measurement offset       -       -       0.1       A         VOUT measurement range       0       -       5.5       V         VOUT measurement resolution       -       15.625       -       mV         VOUT measurement gain accuracy       -15       -       5       %         VOUT measurement offset       -3       -       3       %         VIN measurement range       0       -       14.4       V         VIN measurement gain accuracy       -       32.5       -       mV         VIN measurement gain accuracy       -       5       5       %	Output current measurement range		0	-	26	Α
Output current measurement offset       -       -       0.1       A         VOUT measurement range       0       -       5.5       V         VOUT measurement resolution       -       15.625       -       mV         VOUT measurement gain accuracy       -15       -       5       %         VOUT measurement offset       -3       -       3       %         VIN measurement range       0       -       14.4       V         VIN measurement resolution       -       32.5       -       mV         VIN measurement gain accuracy       -15       -       5       %	Output current measurement resolution		62.5	-	-	mA
VOUT measurement range         0         -         5.5         V           VOUT measurement resolution         -         15.625         -         mV           VOUT measurement gain accuracy         -15         -         5         %           VOUT measurement offset         -3         -         3         %           VIN measurement range         0         -         14.4         V           VIN measurement resolution         -         32.5         -         mV           VIN measurement gain accuracy         -15         -         5         %	Output current measurement gain accur	racy	-	-	±5	%
VOUT measurement resolution         -         15.625         -         mV           VOUT measurement gain accuracy         -15         -         5         %           VOUT measurement offset         -3         -         3         %           VIN measurement range         0         -         14.4         V           VIN measurement resolution         -         32.5         -         mV           VIN measurement gain accuracy         -15         -         5         %	Output current measurement offset		-	-	0.1	Α
VOUT measurement gain accuracy         -15         -         5         %           VOUT measurement offset         -3         -         3         %           VIN measurement range         0         -         14.4         V           VIN measurement resolution         -         32.5         -         mV           VIN measurement gain accuracy         -15         -         5         %	VOUT measurement range		0	-	5.5	V
VOUT measurement offset         -3         -         3         %           VIN measurement range         0         -         14.4         V           VIN measurement resolution         -         32.5         -         mV           VIN measurement gain accuracy         -15         -         5         %	VOUT measurement resolution		-	15.625	-	mV
VIN measurement range         0         -         14.4         V           VIN measurement resolution         -         32.5         -         mV           VIN measurement gain accuracy         -15         -         5         %	VOUT measurement gain accuracy		-15	-	5	%
VIN measurement resolution - 32.5 - mV VIN measurement gain accuracy -15 - 5 %	VOUT measurement offset		-3	-	3	%
VIN measurement gain accuracy -15 - 5 %	VIN measurement range		0	-	14.4	V
,	VIN measurement resolution		-	32.5	-	mV
VIN measurement offset -5.5 -2 1.4 LSB	VIN measurement gain accuracy		-15	-	5	%
	VIN measurement offset		-5.5	-2	1.4	LSB

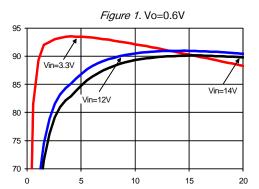
**NOTE**: Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions. See Feature Descriptions for additional information.

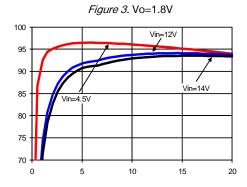


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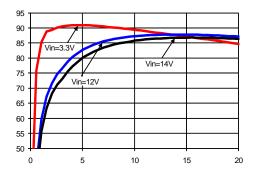
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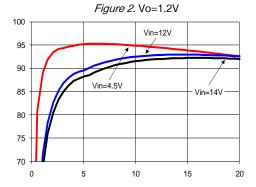












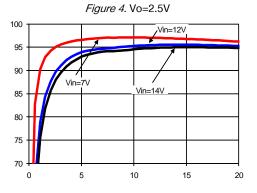


Figure 6. Vo=5.0V



#### 6. THERMAL DERATING CURVES

#### Ambient Temperature, T<sub>A</sub> °C

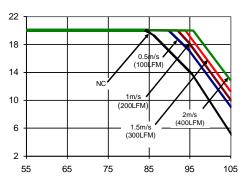


Figure 7. Vo=0.6V

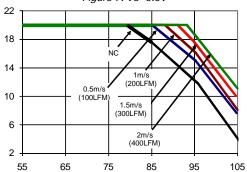


Figure 9. Vo=1.8V

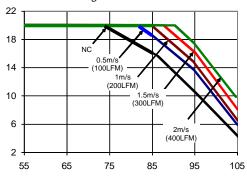


Figure 11. Vo=3.3V

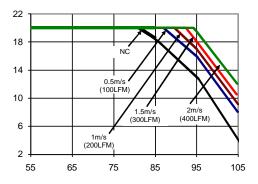


Figure 8. Vo=1.2V

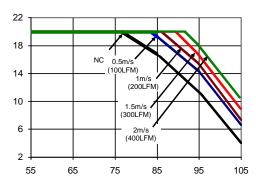


Figure 10. Vo=2.5V

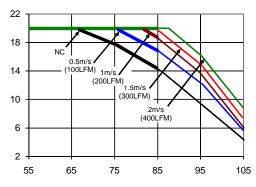


Figure 12. Vo=5.0V



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#### 7. ANALOG FEATURE DESCRIPTIONS

#### Remote On/Off

PARAMETER		DESCRIPTION	MIN	TYP	MAX	UNIT
Signal Low (Unit On)	(Unit On) Active Low	The remote on/off pin open, Unit on.	-0.2	-	0.6	V
Signal High (Unit Off)	Active Low	The remote on/on pin open, Onit on.	2.0	-	VIn,max	V
Signal Low (Unit Off)	A ativa I limb	The versate on left win ones. Unit on	-0.2	-	0.6	V
Signal High (Unit On)	Active High	The remote on/off pin open, Unit on.	2.0	-	VIn,max	V

For negative logic On/Off modules, the circuit configuration is shown in Figure. 9.

The SLDN-20D1Ax module can be turned ON and OFF either by using the ON/OFF pin (Analog interface) or through the Power Management Bus interface (Digital). The module can be configured in a number of ways through the Power Management Bus interface to react to the two ON/OFF inputs:

- Module ON/OFF can be controlled only through the analog interface (digital interface ON/OFF commands are ignored)
- Module ON/OFF can be controlled only through the Power Management Bus interface (analog interface is ignored)
- Module ON/OFF can be controlled by either the analog or digital interface.

The default state of the module (as shipped from the factory) is to be controlled by the analog interface only. If the digital interface is to be enabled, or the module is to be controlled only through the digital interface, this change must be made through the Power Management Bus. These changes can be made and written to non-volatile memory on the module so that it is remembered for subsequent use.

## **Analog On/Off**

The SLDN-20D1Ax modules feature an On/Off pin for remote On/Off operation. Two On/Off logic options are available. In the Positive Logic On/Off option, (device code suffix "0" – see Ordering Information), the module turns ON during a logic High on the On/Off pin and turns OFF during a logic Low. With the Negative Logic On/Off option, (device code suffix "L" – see Ordering Information), the module turns OFF during logic High and ON during logic Low. The On/Off signal should be always referenced to ground. For either On/Off logic option, leaving the On/Off pin disconnected will turn the module ON when input voltage is present.

For positive logic modules, the circuit configuration for using the On/Off pin is shown in Figure 39. When the external transistor Q2 is in the OFF state, the internal transistor Q7 is turned OFF, which keeps Q6 OFF and Q5 OFF. This allows the internal PWM #Enable signal to be pulled up by the internal 3.3V, thus turning the module ON. When transistor Q2 is turned ON, the On/Off pin is pulled low, which turns Q7, Q6 and Q5 ON and the internal PWM #Enable signal is pulled low and the module is OFF. A suggested value for Rpullup is  $20k\Omega$ .

For negative logic On/Off modules, the circuit configuration is shown in Fig. 40. The On/Off pin should be pulled high with an external pull-up resistor (suggested value for the 3V to 14V input range is 20Kohms). When transistor Q2 is in the OFF state, the On/Off pin is pulled high, transistor Q3 is turned ON. This turns Q6 ON, followed by Q5 turning ON which pulls the internal ENABLE low and the module is OFF. To turn the module ON, Q2 is turned ON pulling the On/Off pin low, turning transistor Q3 OFF, which keeps Q6 and Q5 OFF resulting in the PWM Enable pin going high.

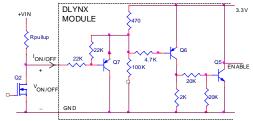


Figure 13. Circuit configuration for using positive On/Off logic

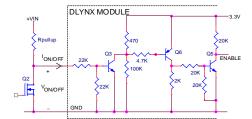


Figure 14. Circuit configuration for using positive On/Off logic



#### **Digital On/Off**

Please see the Digital Feature Descriptions section.

#### 8. MONOTONIC START-UP AND SHUTDOWN

The SLDN-20D1Ax module has monotonic start-up and shutdown behavior for any combination of rated input voltage, output current and operating temperature range.

#### 9. STARTUP INTO PRE-BIASED OUTPUT

The SLDN-20D1Ax module can start into a prebiased output as long as the prebias voltage is 0.5V less than the set output voltage.

# 10. ANALOG OUTPUT VOLTAGE PROGRAMMING

The output voltage of the module is programmable to any voltage from 0.6DC to 5.5VDC by connecting a resistor between the Trim and SIG\_GND pins of the module. Certain restrictions apply on the output voltage set point depending on the input voltage. These are shown in the Output Voltage vs. Input Voltage Set Point Area plot in Fig. 15. The Upper Limit curve shows that for output voltages lower than 1V, the input voltage must be lower than the maximum of 14.4V. The Lower Limit curve shows that for output voltages higher than 0.6V, the input voltage needs to be larger than the minimum of 3V.

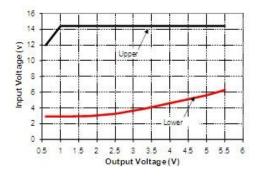


Figure 15.

**NOTE**: Output Voltage vs. Input Voltage Set Point Area plot showing limits where the output voltage can be set for different input voltages.

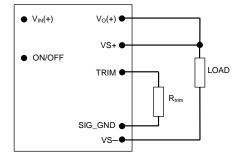


Figure 16.

CAUTION – Do not connect SIG\_GND to GND elsewhere in the layout

Circuit configuration for programming output voltage using an external resistor.



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Without an external resistor between Trim and SIG\_GND pins, the output of the module will be 0.6 VDC. To calculate the value of the trim resistor, Rtrim for a desired output voltage, should be as per the following equation:

$$Rtrim = \left[\frac{12}{(Vo - 0.6)}\right] k\Omega$$

Rtrim is the external resistor in  $k\Omega$  *Vo* is the desired output voltage.

Table 1 provides Rtrim values required for some common output voltages.

VO, set (V)	RTRIM (KΩ)
0.6	Open
0.9	40
1.0	30
1.2	20
1.5	13.33
1.8	10
2.5	6.316
3.3	4.444
5.0	2.727

Table 1.

#### 11. DIGITAL OUTPUT VOLTAGE ADJUSTMENT

Please see the Digital Feature Descriptions section.

#### 12. REMOTE SENSE

The SLDN-20D1Ax power module has a Remote Sense feature to minimize the effects of distribution losses by regulating the voltage between the sense pins (VS+ and VS-). The voltage drop between the sense pins and the VOUT and GND pins of the module should not exceed 0.5V.

#### 13. ANALOG VOLTAGE MARGINING

Output voltage margining can be implemented in the module by connecting a resistor, Rmargin-up, from the Trim pin to the ground pin for margining-up the output voltage and by connecting a resistor, Rmargin-down, from the Trim pin to output pin for margining-down. Figure 17 shows the circuit configuration for output voltage margining. Please consult your local Bel Power technical representative for additional details.

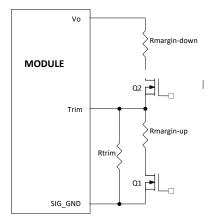


Figure 17. Circuit Configuration for margining Output voltage.



#### 14. DIGITAL OUTPUT VOLTAGE MARGINING

Please see the Digital Feature Descriptions section.

#### 15. OUTPUT VOLTAGE SEQUENCING

The SLDN-20D1Ax module includes a sequencing feature, EZ-SEQUENCE that enables users to implement various types of output voltage sequencing in their applications. This is accomplished via an additional sequencing pin. When not using the sequencing feature, leave it unconnected.

The voltage applied to the SEQ pin should be scaled down by the same ratio as used to scale the output voltage down to the reference voltage of the module. This is accomplished by an external resistive divider connected across the sequencing voltage before it is fed to the SEQ pin as shown in Fig. 18. In addition, a small capacitor (suggested value 100pF) should be connected across the lower resistor R1.

For SLDN-20D1Ax modules, the minimum recommended delay between the ON/OFF signal and the sequencing signal is 10ms to ensure that the module output is ramped up according to the sequencing signal. This ensures that the module soft-start routine is completed before the sequencing signal is allowed to ramp up.

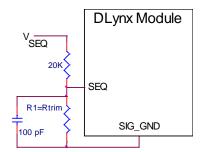


Figure 18. Circuit showing connection of the sequencing signal to the SEQ pin

When the scaled down sequencing voltage is applied to the SEQ pin, the output voltage tracks this voltage until the output reaches the set-point voltage. The final value of the sequencing voltage must be set higher than the set-point voltage of the module. The output voltage follows the sequencing voltage on a one-to-one basis. By connecting multiple modules together, multiple modules can track their output voltages to the voltage applied on the SEQ pin.

To initiate simultaneous shutdown of the modules, the SEQ pin voltage is lowered in a controlled manner. The output voltage of the modules tracks the voltages below their set-point voltages on a one-to-one basis. A valid input voltage ust be maintained until the tracking and output voltages reach ground potential.

Note that in all digital Bel series of modules, the Power Management Bus Output Undervoltage Fault will be tripped when sequencing is employed. This will be detected using the STATUS\_WORD and STATUS\_VOUT Power Management Bus commands. In addition, the SMBALERT# signal will be asserted low as occurs for all faults and warnings. To avoid the module shutting down due to the Output Undervoltage Fault, the module must be set to continue operation without interruption as the response to this fault (see the description of the Power Management Bus command VOUT\_UV\_FAULT\_RESPONSE for additional information).

#### **16. OVERCURRENT PROTECTION**

To provide protection in a fault (output overload) condition, the unit is equipped with internal current-limiting circuitry and can endure current limiting continuously. At the point of current-limit inception, the unit enters hiccup mode. The unit operates normally once the output current is brought back into its specified range.

### 17. DIGITAL ADJUSTABLE OVERCURRENT WARNING

Please see the Digital Feature Descriptions section.



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#### 18. OVERTEMPERATURE PROTECTION

To provide protection in a fault condition, the unit is equipped with a thermal shutdown circuit. The unit will shut down if the overtemperature threshold of  $128^{\circ}$ C  $\sim 130^{\circ}$ C is exceeded at the thermal reference point Tref .Once the unit goes into thermal shutdown it will then wait to cool before attempting to restart.

#### 19. INPUT UNDERVOLTAGE LOCKOUT

Please see the Digital Feature Descriptions section.

#### 20. DIGITAL TEMPERATURE STATUS VIA POWER MANAGEMENT BUS

Please see the Digital Feature Descriptions section.

#### 21. DIGITALLY ADJUSTABLE OUTPUT OVER AND UNDER VOLTAGE PROTECTION

Please see the Digital Feature Descriptions section.

#### 22. INPUT UNDERVOLTAGE LOCKOUT

At input voltages below the input undervoltage lockout limit, the module operation is disabled. The module will begin to operate at an input voltage above the undervoltage lockout turn-on threshold.

#### 23. DIGITALLY ADJUSTABLE INPUT UNDERVOLTAGE LOCKOUT

Please see the Digital Feature Descriptions section.

#### 24. DIGITALLY ADJUSTABLE POWER GOOD THRESHOLDS

Please see the Digital Feature Descriptions section.

#### 25. SYNCHRONIZATION

The SLDN-20D1Ax module switching frequency can be synchronized to a signal with an external frequency within a specified range. Synchronization can be done by using the external signal applied to the SYNC pin of the module as shown in Fig. 19, with the converter being synchronized by the rising edge of the external signal. The Electrical Specifications table specifies the requirements of the external SYNC signal. If the SYNC pin is not used, the module should free run at the default switching frequency.

If synchronization is not being used, connect the SYNC pin to GND.

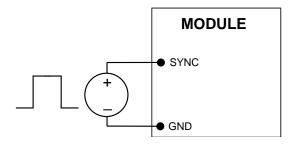


Figure 19. External source connections to synchronize switching frequency of the module.

#### 26. MEASURING OUTPUT CURRENT, OUTPUT VOLTAGE AND INPUT VOLTAGE

Please see the Digital Feature Descriptions section.



#### **27. DUAL LAYOUT**

Identical dimensions and pin layout of Analog and Digital modules permit migration from one to the other without needing to change the layout. In both cases the trim resistor is connected between trim and signal ground. The output of the analog module cannot be trimmed down to 0.45V.

#### 28. POWER GOOD

The SLDN-20D1Ax module provides a Power Good (PGOOD) signal that is implemented with an open-drain output to indicate that the output voltage is within the regulation limits of the power module. The PGOOD signal will be de-asserted to a low state if any condition such as overtemperature, overcurrent or loss of regulation occurs that would result in the output voltage going  $\pm 10\%$  outside the setpoint value. The PGOOD terminal can be connected through a pullup resistor (suggested value  $\pm 100\%$ ) to a source of 5VDC or lower.

#### 29. TUNABLE LOOPTM

The SLDN-20D1Ax has a feature that optimizes transient response of the module called Tunable Loop<sup>TM</sup> .

External capacitors are usually added to the output of the module for two reasons: to reduce output ripple and noise (see Figure 38) and to reduce output voltage deviations from the steady-state value in the presence of dynamic load current changes. Adding external capacitance however affects the voltage control loop of the module, typically causing the loop to slow down with sluggish response. Larger values of external capacitance could also cause the module to Become unstable.

The Tunable Loop<sup>™</sup> allows the user to externally adjust the voltage control loop to match the filter network connected to the output of the module. The Tunable Loop<sup>™</sup> is implemented by connecting a series R-C between the VS+ and TRIM pins of the module, as shown in Fig. 20. This R-C allows the user to externally adjust the voltage loop feedback compensation of the module.

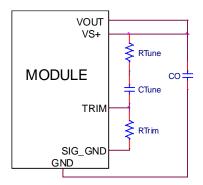


Figure 20. Circuit diagram showing connection of RTUME and CTUNE to tune the control loop of the module.

Recommended values of RTUNE and CTUNE for different output capacitor combinations are given in Tables 2 and 3. Table 3 shows the recommended values of RTUNE and CTUNE for different values of ceramic output capacitors up to 1000uF that might be needed for an application to meet output ripple and noise requirements. Selecting RTUNE and CTUNE according to Table 3 will ensure stable operation of the module. In applications with tight output voltage limits in the presence of dynamic current loading, additional output capacitance will be required. Table 3 lists recommended values of RTUNE and CTUNE in order to meet 2% output voltage deviation limits for some common output voltages in the presence of a 10A to 20A step change (50% of full load), with an input voltage of 12V.

Please contact your Bel Power technical representative to obtain more details of this feature as well as for guidelines on how to select the right value of external R-C to tune the module for best transient performance and stable operation for other output capacitance values.



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Со	2x47μF	4x47μF	6x47μF	10x47μF	20x47μF
RTUNE	330	330	270	330	180
CTUNE	47pF	560pF	1200pF	2200pF	4700pF

Table 2.

General recommended values of of RTUNE and CTUNE for Vin=12V and various external ceramic capacitor combinations.

Vo	5 <b>V</b>	3.3V	2.5V	1.8V	1.2V	0.6V
		5x47μF +	2x47μF	2x47μF	1x47μF	1x47μF
Со	8x47μF	1x330μF	+	+	+	+
	Ολ-1 μι	Polymer	2x330μF	3x330μF	5x330μF	11x330μF
		Folymer	Polymer	Polymer	Polymer	Polymer
RTUNE	220	220	220	220	180	180
CTUNE	1500pF	2200pF	3300pF	5600pF	10nF	47nF
<b>∆V</b>	100mV	64mV	49mV	36mV	24mV	12mV

Table 3.

Recommended values of RTUNE and CTUNE to obtain transient deviation of 2% of Vout for a 10A step load with Vin=12V.

**NOTE**: The capacitors used in the Tunable Loop tables are 47  $\mu$ F/3  $m\Omega$  ESR ceramic and 330  $\mu$ F/12  $m\Omega$  ESR polymer capacitors.

#### 30. DIGITAL FEATURE DESCRIPTIONS

#### **Power Management Bus Interface Capability**

The SLDN-20D1Ax modules have a Power Management Bus interface that supports both communication and control. The Power Management Bus Power Management Protocol Specification can be obtained from www.Power Management Bus.org. The modules support a subset of version 1.1 of the specification (see Table 6 for a list of the specific commands supported). Most module parameters can be programmed using Power Management Bus and stored as defaults for later use.

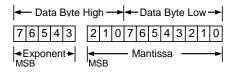
The module also supports the SMBALERT response protocol whereby the module can alert the bus master if it wants to talk. For more information on the SMBus alert response protocol, see the System Management Bus (SMBus) specification.

The module has non-volatile memory that is used to store configuration settings. Not all settings programmed into the device are automatically saved into this non-volatile memory, only those specifically identified as capable of being stored can be saved (see Table 6 for which command parameters can be saved to non-volatile storage).

The module has non-volatile memory that is used to store configuration settings. Not all settings programmed into the device are automatically saved into this non-volatile memory, only those specifically identified as capable of being stored can be saved (see Table 6 for which command parameters can be saved to non-volatile storage).

#### **Power Management Bus Data Format**

For commands that set thresholds, voltages or report such quantities, the module supports the "Linear" data format among the three data formats supported by Power Management Bus. The Linear Data Format is a two byte value with an 11-bit, two's complement mantissa and a 5-bit, two's complement exponent. The format of the two data bytes is shown below:



NOTE: The value is of the number is then given by

Value = Mantissa x 2 Exponent



#### **Power Management Bus Addressing**

The SLDN-20D1Ax module can be addressed through the Power Management Bus using a device address. The module has 64 possible addresses (0 to 63 in decimal) which can be set using resistors connected from the ADDR0 and ADDR1 pins to GND. Note that some of these addresses (0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11 12, 40, 44, 45, 55 in decimal) are reserved according to the SMBus specifications and may not be useable. The address is set in the form of two octal (0 to 7) digits, with each pin setting one digit. The ADDR1 pin sets the high order digit and ADDR0 sets the low order digit. The resistor values suggested for each digit are shown in Table 4 (1% tolerance resistors are recommended). Note that if either address resistor value is outside the range specified in Table 4, the module will respond to address 127.

DIGIT	RESISTOR VALUE (KΩ)
0	10
1	15.4
2	23.7
3	36.5
4	54.9
5	84.5
6	130
7	200

Table 4.

The user must know which I2C addresses are reserved in a system for special functions and set the address of the module to avoid interfering with other system operations. Both 100kHz and 400kHz bus speeds are supported by the module. Connection for the Power Management Bus interface should follow the High Power DC specifications given in section 3.1.3 in the SMBus specification V2.0 for the 400kHz bus speed or the Low Power DC specifications in section 3.1.2. The complete SMBus specification is available from the SMBus web site, smbus.org.

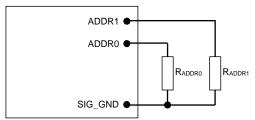


Figure 21. Circuit showing connection of resistors used to set the Power Management Bus address of the module.



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#### **Power Management Bus Enabled On/Off**

The module can also be turned on and off via the Power Management Bus interface. The OPERATION command is used to actually turn the module on and off via the Power Management Bus, while the ON\_OFF\_CONFIG command configures the combination of analog ON/OFF pin input and Power Management Bus commands needed to turn the module on and off. Bit [7] in the OPERATION command data byte enables the module, with the following functions:

- 0: Output is disabled
- 1: Output is enabled

This module uses the lower five bits of the ON\_OFF\_CONFIG data byte to set various ON/OFF options as follows:

BIT POSITION	4	3	2	1	0
ACCESS	r/w	r/w	r/w	r/w	r
FUNCTION	PU	CMD	CPR	POL	CPA
DEFAULT VALUE	1	0	1	1	1

PU: Sets the default to either operate any time input power is present or for the ON/OFF to be controlled by the analog ON/OFF input and the Power Management Bus OPERATION command. This bit is used together with the CP, CMD and ON bits to determine startup.

BIT VALUE	ACTION
0	Module powers up any time power is present regardless of state of the analog ON/OFF pin
1	Module does not power up until commanded by the analog ON/OFF pin and the OPERATION command as programmed in bits [2:0] of the ON_OFF_CONFIG register.

CMD: The CMD bit controls how the device responds to the OPERATION command.

BIT VALUE	ACTION
0	Module ignores the ON bit in the OPERATION command
1	Module responds to the ON bit in the OPERATION command

CPR: Sets the response of the analog ON/OFF pin. This bit is used together with the CMD, PU and ON bits to determine startup.

BIT VALUE	ACTION
0	Module ignores the analog ON/OFF pin, i.e. ON/OFF is only controlled through the POWER MANAGEMENT BUS via the OPERATION command
1	Module requires the analog ON/OFF pin to be asserted to start the unit

#### **Power Management Bus Adjustable Soft Start Rise Time**

The soft start rise time can be adjusted in the module via Power Management Bus. When setting this parameter, make sure that the charging current for output capacitors can be delivered by the module in addition to any load current to avoid nuisance tripping of the overcurrent protection circuitry during startup. The TON\_RISE command sets the rise time in ms, and allows choosing soft start times between 600µs and 9ms, with possible values listed in Table 5. Note that the exponent is fixed at -4 (decimal) and the upper two bits of the mantissa are also fixed at 0.



RISE TIME	EXPONENT	MANTISSA
600μs	11100	0000001010
900μs	11100	0000001110
1.2ms	11100	00000010011
1.8ms	11100	00000011101
2.7ms	11100	00000101011
4.2ms	11100	00001000011
6.0ms	11100	00001100000
9.0ms	11100	00010010000

Table 5.

#### **Output Voltage Adjustment Using the Power Management Bus**

The VOUT\_SCALE\_LOOP parameter is important for a number of Power Management Bus commands related to output voltage trimming, margining, over/under voltage protection and the PGOOD thresholds. The output voltage of the module is set as the combination of the voltage divider formed by RTrim and a  $20k\Omega$  upper divider resistor inside the module, and the internal reference voltage of the module. The reference voltage VREF is nominally set at 600mV, and the output regulation voltage is then given by

$$V_{OUT} = \left[\frac{20000 + RTrim}{RTrim}\right] \times V_{REF}$$

Hence the module output voltage is dependent on the value of RTrim which is connected external to the module. The information on the output voltage divider ratio is conveyed to the module through the VOUT\_SCALE\_LOOP parameter which is calculated as follows:

$$VOUT\_SCALE\_LOOP = \frac{RTrim}{20000 + RTrim}$$

The VOUT\_SCALE\_LOOP parameter is specified using the "Linear" format and two bytes. The upper five bits [7:3] of the high byte are used to set the exponent which is fixed at –9 (decimal). The remaining three bits of the high byte [2:0] and the eight bits of the lower byte are used for the mantissa. The default value of the mantissa is 00100000000 corresponding to 256 (decimal), corresponding to a divider ratio of 0.5. The maximum value of the mantissa is 512 corresponding to a divider ratio of 1. Note that the resolution of the VOUT\_SCALE\_LOOP command is 0.2%.

When Power Management Bus commands are used to trim or margin the output voltage, the value of VREF is what is changed inside the module, which in turn changes the regulated output voltage of the module.

The nominal output voltage of the module can be adjusted with a minimum step size of 0.4% over a  $\pm 25\%$  range from nominal using the VOUT\_TRIM command over the Power Management Bus.. The VOUT\_TRIM command is used to apply a fixed offset voltage to the output voltage command value using the "Linear" mode with the exponent fixed at -10 (decimal). The value of the offset voltage is given by

$$V_{OUT(offset)} = VOUT \_TRIM \times 2^{-10}$$

This offset voltage is added to the voltage set through the divider ratio and nominal VREF to produce the trimmed output voltage. The valid range in two's complement for this command is –4000h to 3FFFh. The high order two bits of the high byte must both be either 0 or 1. If a value outside of the +/-25% adjustment range is given with this command, the module will set it's output voltage to the nominal value (as if VOUT\_TRIM had been set to 0), assert SMBALRT#, set the CML bit in STATUS\_BYTE and the invalid data bit in STATUS\_CML.



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#### **Output Voltage Margining Using the Power Management Bus**

The module can also have its output voltage margined via Power Management Bus commands. The command VOUT\_MARGIN\_HIGH sets the margin high voltage, while the command VOUT\_MARGIN\_LOW sets the margin low voltage. Both the VOUT\_MARGIN\_HIGH and VOUT\_MARGIN\_LOW commands use the "Linear" mode with the exponent fixed at -10 (decimal). Two bytes are used for the mantissa with the upper bit [7] of the high byte fixed at 0. The actual margined output voltage is a combination of the VOUT\_MARGIN\_HIGH or VOUT\_MARGIN\_LOW and the VOUT\_TRIM values as shown below.

$$V_{OUT(MH)} =$$
 
$$(VOUT\_MARGIN\_HIGH + VOUT\_TRIM) \times 2^{-10}$$
 
$$V_{OUT(ML)} =$$
 
$$(VOUT\_MARGIN\_LOW + VOUT\_TRIM) \times 2^{-10}$$

Note that the sum of the margin and trim voltages cannot be outside the ±25% window around the nominal output voltage. The data associated with VOUT\_MARGIN\_HIGH and VOUT\_MARGIN\_LOW can be stored to non-volatile memory using the STORE\_DEFAULT\_ALL command.

The module is commanded to go to the margined high or low voltages using the OPERATION command. Bits [5:2] are used to enable margining as follows:

00XX: Margin Off

0101 : Margin Low (Ignore Fault)

0110 : Margin Low (Act on Fault)

1001 : Margin High (Ignore Fault)

1010 : Margin High (Act on Fault)

#### **Power Management Bus Adjustable Overcurrent Warning**

The SLDN-20D1Ax module can provide an overcurrent warning via the Power Management Bus. The threshold for the overcurrent warning can be set using the parameter IOUT\_OC\_WARN\_LIMIT. This command uses the "Linear" data format with a two byte data word where the upper five bits [7:3] of the high byte represent the exponent and the remaining three bits of the high byte [2:0] and the eight bits in the low byte represent the mantissa. The exponent is fixed at –1 (decimal). The upper five bits of the mantissa are fixed at 0 while the lower six bits are programmable with a default value of 24A. The resolution of this warning limit is 500mA. The value of the IOUT\_OC\_WARN\_LIMIT can be stored to non-volatile memory using the STORE\_DEFAULT\_ALL command.

#### **Temperature Status via Power Management Bus**

The SLDN-20D1Ax module can provide information related to temperature of the module through the STATUS\_TEMPERATURE command. The command returns information about whether the pre-set over temperature fault threshold and/or the warning threshold have been exceeded.

#### **Power Management Bus Adjustable Output Over and Under Voltage Protection**

The SLDN-20D1Ax module has output over and under voltage protection capability. The Power Management Bus command VOUT\_OV\_FAULT\_LIMIT is used to set the output over voltage threshold from four possible values: 108%, 110%, 112% or 115% of the commanded output voltage. The command VOUT\_UV\_FAULT\_LIMIT sets the threshold that causes an output under voltage fault and can also be selected from four possible values: 92%, 90%, 88% or 85%. The default values are 112% and 88% of



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commanded output voltage. Both commands use two data bytes formatted as two's complement binary integers. The "Linear" mode is used with the exponent fixed to –10 (decimal) and the effective over or under voltage trip points given by:

$$\begin{split} V_{OUT(OV\_REQ)} &= (VOUT\_OV\_FAULT\_LIMIT) \times 2^{-10} \\ V_{OUT(UV\_REO)} &= (VOUT\_UV\_FAULT\_LIMIT) \times 2^{-10} \end{split}$$

Values within the supported range for over and undervoltage detection thresholds will be set to the nearest fixed percentage. Note that the correct value for VOUT\_SCALE\_LOOP must be set in the module for the correct over or under voltage trip points to be calculated.

In addition to adjustable output voltage protection, the 12A Digital module can also be programmed for the response to the fault. The VOUT\_OV\_FAULT RESPONSE and VOUT\_UV\_FAULT\_RESPONSE commands specify the response to the fault. Both these commands use a single data byte with the possible options as shown below.

- 1. Continue operation without interruption (Bits [7:6] = 00, Bits [5:3] = xxx).
- 2. Continue for four switching cycles and then shut down if the fault is still present, followed by no restart or continuous restart (Bits [7:6] = 01, Bits [5:3] = 000 means no restart, Bits [5:3] = 111 means continuous restart).
- 3. Immediate shut down followed by no restart or continuous restart (Bits [7:6] = 10, Bits [5:3] = 000 means no restart, Bits [5:3] = 111 means continuous restart).
- 4. Module output is disabled when the fault is present and the output is enabled when the fault no longer exists (Bits [7:6] = 11, Bits [5:3] = xxx).

Note that separate response choices are possible for output over voltage or under voltage faults.

#### Power Management Bus Adjustable Input Undervoltage Lockout

The SLDN-20D1Ax module allows adjustment of the input under voltage lockout and hysteresis. The command VIN\_ON allows setting the input voltage turn on threshold, while the VIN\_OFF command sets the input voltage turn off threshold. For the VIN\_ON command, possible values are 2.75V, and 3V to 14V in 0.5V steps. For the VIN\_OFF command, possible values are 2.5V to 14V in 0.5V steps. If other values are entered for either command, they will be mapped to the closest of the allowed values.

Both the VIN\_ON and VIN\_OFF commands use the "Linear" format with two data bytes. The upper five bits represent the exponent (fixed at -2) and the remaining 11 bits represent the mantissa. For the mantissa, the four most significant bits are fixed at 0.

#### **Power Good**

The SLDN-20D1Ax module provides a Power Good (PGOOD) signal that is implemented with an open-drain output to indicate that the output voltage is within the regulation limits of the power module. The PGOOD signal will be de-asserted to a low state if any condition such as overtemperature, overcurrent or loss of regulation occurs that would result in the output voltage going outside the specified thresholds. The PGOOD thresholds are user selectable via the Power Management Bus (the default values are as shown in the Feature Specifications Section). Each threshold is set up symmetrically above and below the nominal value. The POWER\_GOOD\_ON command sets the output voltage level above which PGOOD is asserted (lower threshold). For example, with a 1.2V nominal output voltage, the POWER\_GOOD\_ON threshold can set the lower threshold to 1.14 or 1.1V. Doing this will automatically set the upper thresholds to 1.26 or 1.3V.

The POWER\_GOOD\_OFF command sets the level below which the PGOOD command is de-asserted. This command also sets two thresholds symmetrically placed around the nominal output voltage. Normally, the POWER\_GOOD\_ON threshold is set higher than the POWER\_GOOD\_OFF threshold.

Both POWER\_GOOD\_ON and POWER\_GOOD\_OFF commands use the "Linear" format with the exponent fixed at -10 (decimal). The two thresholds are given by



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$$\begin{split} V_{OUT(PGOOD\_ON)} &= (POWER\_GOOD\_ON) \times 2^{-10} \\ V_{OUT(PGOOD\_OFF)} &= (POWER\_GOOD\_OFF) \times 2^{-10} \end{split}$$

Both commands use two data bytes with bit [7] of the high byte fixed at 0, while the remaining bits are r/w and used to set the mantissa using two's complement representation. Both commands also use the The VOUT\_SCALE\_LOOP parameter so it must be set correctly. The default value of POWER\_GOOD\_ON is set at 1.1035V and that of the POWER\_GOOD\_OFF is set at 1.08V. The values associated with these commands can be stored in non-volatile memory using the STORE\_DEFAULT\_ALL command.

The PGOOD terminal can be connected through a pullup resistor (suggested value  $100K\Omega$ ) to a source of 5VDC or lower.

#### Measurement of Output Current, Output Voltage and Input Voltage

The SLDN-20D1Ax module is capable of measuring key module parameters such as output current and voltage and input voltage and providing this information through the Power Management Bus interface. Roughly every 200µs, the module makes 16 measurements each of output current, voltage and input voltage. Average values of each of these measurements are then calculated and placed in the appropriate registers. These values in the registers can then be read using the Power Management Bus interface.

#### **Measuring Output Current Using the Power Management Bus**

The module measures current by using the inductor winding resistance as a current sense element. The inductor winding resistance is then the current gain factor used to scale the measured voltage into a current reading. This gain factor is the argument of the IOUT\_CAL\_GAIN command, and consists of two bytes in the linear data format. The exponent uses the upper five bits [7:3] of the high data byte in two-s complement format and is fixed at –15 (decimal). The remaining 11 bits in two's complement binary format represent the mantissa. During manufacture, each module is calibrated by measuring and storing the current gain factor into non-volatile storage.

The current measurement accuracy is also improved by each module being calibrated during manufacture with the offset in the current reading. The IOUT\_CAL\_OFFSET command is used to store and read the current offset. The argument for this command consists of two bytes composed of a 5-bit exponent (fixed at -4d) and a 11-bit mantissa. This command has a resolution of 62.5mA and a range of -4000mA to +3937.5mA.

The READ\_IOUT command provides module average output current information. This command only supports positive or current sourced from the module. If the converter is sinking current a reading of 0 is provided. The READ\_IOUT command returns two bytes of data in the linear data format. The exponent uses the upper five bits [7:3] of the high data byte in two-s complement format and is fixed at –4 (decimal). The remaining 11 bits in two's complement binary format represent the mantissa with the 11th bit fixed at 0 since only positive numbers are considered valid.

Note that the current reading provided by the module is not corrected for temperature. The temperature corrected current reading for module temperature TModule can be estimated using the following equation

$$I_{\text{OUT,CORR}} = \frac{I_{\text{READ}\_OUT}}{1 + [(T_{\text{IND}} - 30) \times 0.00393]}$$

where IOUT\_CORR is the temperature corrected value of the current measurement, IREAD\_OUT is the module current measurement value, TIND is the temperature of the inductor winding on the module. Since it may be difficult to measure TIND, it may be approximated by an estimate of the module temperature.

#### **Measuring Output Voltage Using the Power Management Bus**



The SLDN-20D1Ax module can provide output voltage information using the READ\_VOUT command. The command returns two bytes of data all representing the mantissa while the exponent is fixed at -10 (decimal).

During manufacture of the module, offset and gain correction values are written into the non-volatile memory of the module. The command VOUT\_CAL\_OFFSET can be used to read and/or write the offset (two bytes consisting of a 16-bit mantissa in two's complement format) while the exponent is always fixed at -10 (decimal). The allowed range for this offset correction is -125 to 124mV. The command VOUT\_CAL\_GAIN can be used to read and/or write the gain correction - two bytes consisting of a five-bit exponent (fixed at -8) and a 11-bit mantissa. The range of this correction factor is -0.125 to +0.121, with a resolution of 0.004. The corrected output voltage reading is then given by:

$$V_{OUT}(Final) = [V_{OUT}(Initial) \times (1 + VOUT \_CAL \_GAIN)] + VOUT \_CAL \_OFFSET$$

#### **Measuring Input Voltage Using the Power Management Bus**

The SLDN-20D1Ax module can provide output voltage information using the READ\_VIN command. The command returns two bytes of data in the linear format. The upper five bits [7:3] of the high data form the two's complement representation of the mantissa which is fixed at –5 (decimal). The remaining 11 bits are used for two's complement representation of the mantissa, with the 11th bit fixed at zero since only positive numbers are valid.

During module manufacture, offset and gain correction values are written into the non-volatile memory of the module. The command VIN\_CAL\_OFFSET can be used to read and/or write the offset - two bytes consisting of a five-bit exponent (fixed at -5) and a11-bit mantissa in two's complement format. The allowed range for this offset correction is -2to 1.968V, and the resolution is 32mV. The command VIN\_CAL\_GAIN can be used to read and/or write the gain correction - two bytes consisting of a five-bit exponent (fixed at -8) and a 11-bit mantissa. The range of this correction factor is -0.125 to +0.121, with a resolution of 0.004. The corrected output voltage reading is then given by:

$$V_{IN}(Final) =$$

$$[V_{IN}(Initial) \times (1 + VIN \_CAL \_GAIN)] + VIN \quad CAL \quad OFFSET$$

#### Reading the Status of the Module using the Power Management Bus

The SLDN-20D1Ax module supports a number of status information commands implemented in Power Management Bus. However, not all features are supported in these commands. A 1 in the bit position indicates the fault that is flagged.

STATUS\_BYTE: Returns one byte of information with a summary of the most critical device faults.



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BIT POSITION	FLAG	DEFAULT VALUE
7	X	0
6	OFF	0
5	VOUT Overvoltage	0
4	IOUT Overcurrent	0
3	VIN Undervoltage	0
2	Temperature	0
1	CML (Comm. Memory Fault)	0
0	None of the above	0

Table 6.

STATUS\_WORD: Returns two bytes of information with a summary of the module's fault/warning conditions.

BIT POSITION	FLAG	DEFAULT VALUE
7	X	0
6	OFF	0
5	VOUT Overvoltage	0
4	IOUT Overcurrent	0
3	VIN Undervoltage	0
2	Temperature	0
1	CML (Comm. Memory Fault)	0
0	None of the above	0

Table 7. LOW BYTE

BIT POSITION	FLAG	DEFAULT VALUE
7	VOUT fault or warning	0
6	IOUT fault or warning	0
5	X	0
4	X	0
3	POWER_GOOD# (is negated)	0
2	X	0
1	X	0
0	Χ	0

Table 8. HIGH BYTE

STATUS\_VOUT: Returns one byte of information relating to the status of the module's output voltage related faults.



BIT POSITION	FLAG	DEFAULT VALUE
7	VOUT OV Fault	0
6	X	0
5	Χ	0
4	VOUT UV Fault	0
3	X	0
2	X	0
1	Χ	0
0	X	0

Table 9.

STATUS\_IOUT: Returns one byte of information relating to the status of the module's output voltage related faults.

BIT POSITION	FLAG	DEFAULT VALUE
7	IOUT OC Fault	0
6	X	0
5	IOUT OC Warning	0
4	X	0
3	Χ	0
2	X	0
1	Х	0
0	Χ	0

Table 10.

STATUS\_TEMPERATURE: Returns one byte of information relating to the status of the module's temperature related faults.

BIT POSITION	FLAG	DEFAULT VALUE
7	OT Fault	0
6	OT Warning	0
5	X	0
4	X	0
3	Χ	0
2	X	0
1	X	0
0	X	0

Table 11.

STATUS\_CML: Returns one byte of information relating to the status of the module's communication related faults.



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BIT POSITION	FLAG	DEFAULT VALUE
7	Invalid/Unsupported Command	0
6	Invalid/Unsupported Command	0
5	Packet Error Check Failed	0
4	X	0
3	Χ	0
2	X	0
1	Other Communication Fault	0
0	X	0

Table 12.

MFR\_VIN\_MIN: Returns minimum input voltage as two data bytes of information in Linear format (upper five bits are exponent – fixed at -2, and lower 11 bits are mantissa in two's complement format – fixed at 12)

MFR\_VOUT\_MIN: Returns minimum output voltage as two data bytes of information in Linear format (upper five bits are exponent – fixed at -10, and lower 11 bits are mantissa in two's complement format – fixed at 614)

MFR\_SPECIFIC\_00: Returns information related to the type of module and revision number. Bits [7:2] in the Low Byte indicate the module type (000010 corresponds to the SLDN-20D1Ax series of module), while bits [7:3] indicate the revision number of the module.

BIT POSITION	FLAG	DEFAULT VALUE
7:2	Module Name	000110
1:0	Reserved	10

BIT POSITION	FLAG	DEFAULT VALUE
7:3	Module Revision Number	None
2:0	Reserved	000

Table 14. HIGH BYTE



# **Summary of Supported Power Management Bus Commands**

Please refer to the Power Management Bus 1.1 specification for more details of these commands.

Hex Code	Command	S and the opposition			ef Des			. marrae			Non-Volatile Memory Storage
		Turn Module on or	off. Also	used to	margin	the out	put volt	age			
		Format					d Binary				
l		Bit Position	7	6	5	4	3	2	1	0	
01	OPERATION	Access	r/w	r	r/w	r/w	r/w	r/w	r	r	
		Function	On	Х		Ma	rgin		Х	Х	
		Default Value	0	0	0	0	0	0	Х	Х	
		Configures the ON/									
		PMBus commands									
		Format				Unsigne	d Binary	/			
02	ON_OFF_CONFIG	Bit Position	7	6	5	4	3	2	1	0	YES
		Access	r	r	r	r/w	r/w	r/w	r/w	r	
		Function	Х	Х	Х	BN.	smd	SRC	pol	Spa	
		Default Value	0	0	0	1	0	1	1	1	
	OLEAN FALLETS	Clear any fault bits	Clear any fault bits that may have been set, also releases the SMBALERT# signal if								
03	CLEAR_FAULTS	the device has been	assertii	ng it.						_	
		Used to control writing to the module via PMBus. Copies the current register									
		setting in the modu	le whos	e comm	and cod	le match	nes the v	/alue in	the data	a byte	
		into non-volatile me	into non-volatile memory (EEPROM) on the module								
		Format				Unsigne	d Binary	/			
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r/w	r/w	r/w	X	х	X	X	х	
		Function	bit7	bit6	bit5	Х	Χ	Х	Х	X	
10	WRITE BROTECT	Default Value	0	0	0	X	X	Х	Х	X	YES
10	WRITE_PROTECT										153
		1 – Disables all writes except the WRITE_PROTECT, OPERATION and ON OFF CONFIG (bit 6 and bit7 must be 0)									
		Bit 6: 0 – Enables all writes as permitted in bit5 or bit7									
		1 – Disables all writes as permitted in bits or bit?  1 – Disables all writes except for the WRITE_PROTECT and									
		OPERATION		-		_					
		Bit7: 0 - Enables all	writes a	s permi	tted in I	bit5 or b	it6				
		1 – Disables all writes except for the WRITE_PROTECT command									
		(bit5 and bit	t6 must	be 0)							
11	STORE_DEFAULT_ALL	Copies all current re	_	_							
		(EEPROM) on the m									
12	RESTORE_DEFAULT_ALL	Restores all current	-	setting	s in the	module	from va	lues in	the mod	dule non-	
		volatile memory (EE			n +h	a de de co	han				
		Copies the current of the value in the dat	_	_							
13	STORE_DEFAULT_CODE	Bit Position	a byte ir	6	voiatile 5	memor 4	3	2 2	tne mod	o l	
13	STORE_DEFACET_CODE	Access	w	w	w	w	w	w	w	w	
		Function	- **	W			nd code		- W		
		Restores the curren	t registe	er settin	g in the				nd code	matches	
		the value in the dat									
	DESTORE DESAULT COOP	(EEPROM)									
14	RESTORE_DEFAULT_CODE	Bit Position	7	6	5	4	3	2	1	0	
		Access	w	w	w	w	w	w	w	w	
		Function					nd code				
		The module has MO	DE set 1	to Linea	r and Ex	ponent	set to -1	.0. Thes	e values	cannot	
		be changed		-			-	-	I -		
20	VOUT_MODE	Bit Position	7	6	5	4	3	2	1	0	
20		Access	r	r	r	r	r	r	r	r	
		Function	_	Mode	_	4		xponer		-	
ldot		Default Value	0	0	0	1	0	1	1	0	



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Rev. D1.04.19

Hex Code	Command		Non-Volatile Memory Storage								
		Apply a fixed offset	voltage	to the o	output v	oltage o	omman	d value			
		Format	Tomage		Linear, t				rv		
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r/w	r	r/w	r/w	r/w	r/w	r/w	r/w	
		Function	1,11		.,		Byte	.,	.,	-,	
22	VOUT_TRIM	Default Value	0	0	0	0	0	0	0	0	YES
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function	.,	.,	.,		Byte	.,	.,	.,	
		Default Value	0	0	0	0	0	0	0	0	
					_	_					
		Sets the target volta	age for r	marginir	a the o	itout b	iah				
		Format	ge ioi i		Linear, t		_	nt hina	D/		
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function	<u> </u>	1,00	1/00		Byte	1,00	1,00	1,00	
25	VOUT_MARGIN_HIGH	Default Value	0	0	0	0	0	1	0	1	YES
		Bit Position	7	6	5	4	3	2	1	ō	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function	.,	.,	1,740		Byte	1,11	.,	.,	
		Default Value	0	1	0	0	0	1	1	1	
		Sets the target volta									
		Format Linear, two's complement binary									
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function	<u> </u>	.,	.,		Byte	.,	.,	.,	
26	VOUT_MARGIN_LOW	Default Value	0	0	0	0	0	1	0	0	YES
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function	-,	.,	.,		Byte	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	.,	-,	
		Default Value	0	1	0	1	0	0	0	1	
		Sets the scaling of t	he outp	ut volta	ge – equ	al to th	e feedba	ack resis	stor divi	der ratio	
		Format			Linear, t	wo's co	mpleme	nt bina	гу		
		Bit Position	7	6	5	4	3	2	1	0	
		Access	г	r	r	г	r	г	r/w	r/w	
29	VOUT SCALE LOOP	Function			Exponer	_			Mantiss	a	YES
23	1001_50ALE_E00F	Default Value	1	0	1	1	1	0	0	1	163
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function				Mar	ntissa				
		Default Value	0	0	0	0	0	0	0	0	
1		Sets the value of inp	out volta	age at w	hich the	modul	e turns o	on			
		Format			Linear, t	wo's co	mpleme	nt bina	ry		
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	г	r	r	r	r	
35	VIN ON	Function			Exponer	nt			Mantiss	a	YES
35	VIN_ON	Default Value	1	1	1	1	0	0	0	0	1E3
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function				Mar	ntissa				
		Default Value	0	0	0	0	1	0	1	1	



Hex Code	Command			Bri	ef Des	criptio	1				Non-Volatile Memory Storage
		Sets the value of inp	out volta	age at w	hich the	module	e turns o	off			
		Format			Linear, t	wo's co	mpleme	nt bina	ry		
		Bit Position	7	6	5	4	3	2	1	0	
		Access	г	r	r	r	г	r	r	г	
36	MIN OFF	Function			Exponer	nt			Mantiss	a	YES
36	VIN_OFF	Default Value	1	1	1	1	0	0	0	0	153
		Bit Position	7	6	5	4	3	2	1	0	
		Access	г	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function				Mar	ntissa				
		Default Value	0	0	0	0	1	0	1	0	
		Returns the value of	f the gai	in corre	ction ter	rm used	to corre	ct the r	neasure	d output	
		current									
		Format			Linear, t	wo's co	mpleme	nt binar	ry		
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r/w	
38	IOUT_CAL_GAIN	Function			Exponer	nt			Mantiss	a	YES
		Default Value	1	0	0	0	1	0	0	V	
		Bit Position	7	6	5	4	3	2	1	0	
		Access	cess r/w r/w r/w r/w r/w r/w r/w								
		Function	Mantissa								
		Default Value									
		Returns the value of	Value V: Variable based on factory calibration value of the offset correction term used to correct the measured								
		output current									
		Format			Linear, t	wo's co	mpleme	nt binar	ry		
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r/w	r	г	
39	IOUT_CAL_OFFSET	Function			Exponer	nt			Mantiss	а	YES
		Default Value	1	1	1	0	0	V	0	0	
		Bit Position	7	6	5	4	3	2	1	0	
		Access	г	r	r/w	r/w	r/w	r/w	r/w	r/w	
		Function				Mar	ntissa				
		Default Value	0	0	V: V	ariable	based or	n factor	y calibra	ation	
		Sets the voltage lev	el for ar	output	overvol	ltage fau	ılt. Expo	nent is	fixed at	-10.	
		Suggested value sho	own for	1.2Vo. 5	Should b	e chang	ed for d	ifferent	output	voltage.	
		Values can be 108%	, 110%,	112% o	r 115% (	of outpu	ıt voltag	e			
		Format			Linear, t	wo's co	mpleme	nt bina	ry		
		Bit Position	7	6	5	4	3	2	1	0	
40	VOUT OV FAULT LIMIT	Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w	YES
+0	VOOT_OV_FACET_LIMIT	Function				High	Byte				153
		Default Value	0	0	0	0	0	1	0	1	
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function				Low	Byte			]	
		Default Value	0	1	1	0	0	0	0	0	
		Instructs the modul	e on wh	nat actio				<u> </u>	ut overv	oltage	
		Format		-	_		d Binary		T -	إليا	
41	VOUT_OV_FAULT_RESPONSE	Bit Position	7	6	5	4	3	2	1	0	YES
		Access	r/w	r/w	r/w	r/w	r/w	r	r	r	
		Function	[1]	[0]	<u>RS[</u> 2]	<u>RS[</u> 1]	<u>RS[</u> 0]	X	х	Х	
		Default Value	1	1	1	1	1	1	0	0	



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Hex Code	Command			Bri	ef Desc	cription	1				Non-Volatile Memory Storage
		Sets the voltage lev			*********	*****					
		Suggested value sho						ifferent	output	voltage.	
		Values can be 92%,	90%, 88								
		Format			Linear, t						
		Bit Position	7	-6	5	4	3	2	1	0	
44	VOUT_UV_FAULT_LIMIT	Access Function	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w	YES
		Default Value	0	0	0	0	Byte 0	1	0	0	
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	YES
		Function	-,	.,	.,		Byte	.,	.,	.,	
		Default Value	0	0	1	1	1	0	0	1	
		Instructs the modul		_	_	_	_	_	_	_	
		fault							30000	WOOD OF THE	
		Format				Unsigne	ed Binar	,			
	MONT IN TAXES OFFICE	Bit Position	7	6	5	4	3	2	1	0	1/50
45	VOUT_UV_FAULT_RESPONSE	Access	r/w	r/w	r/w	r/w	r/w	г	г	r	YES
		Function	RSP [1]	RSP [0]	<u>RS[</u> 2]	<u>RS[</u> 1]	<u>RS[</u> 0]	х	Х	х	
		Default Value	0	0	0	0	0	1	0	0	
		Sets the output ove									
		Format			Linear, t				rv		
		Bit Position	7	6	5	4	3	2	1	0	
46		Access	r	r	r	г	r	г	r	r	
	10117 00 511117 11147	Function			Exponen	it			Mantiss	a	
46	IOUT_OC_FAULT_LIMIT	Default Value									YES
		Bit Position	7	6	5	4	3	2	1	0	
		Access	г	г	r	r	r	г	г	R	
		Function				Mar	ntissa				
		Default Value	0	0	1	1	0	0	1	0	
		Sets the output ove	rcurrent								
		Format	-		Linear, t						
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	г	г	r Mantin	r	
4A	IOUT_OC_WARN_LIMIT	Function Default Value	1	1	Exponen 1	1	1	0	Mantiss 0	a 0	YES
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r/w	r/w	r/w	r/w	r/w	r/w	
		Function	<u> </u>	_ '	1/W		ntissa	1/W	1 1/W	.,	
		Default Value	0	0	1	1	0	0	0	0	
		Sets the output volt	tage leve								
		Format	-		Linear, t		_		<del> </del>		
		Bit Position	7	-6	5	4	3	2	1 -/	0	
		Access Function	r	r/w	r/w	r/w High	r/w Puto	r/w	r/w	r/w	
5E	POWER_GOOD_ON	Default Value	0	0	0	High 0	Byte	1	0	0	YES
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function	1/W	1/W	1/W	<u> </u>	Byte	1/W	1/W	1/W	$\dashv$
		Default Value	0	1	1	0	1	0	1	0	
		Delault value	U					U		U	



	-						-		· ·	v	•
Hex Code	Command			Bri	ef Des	criptio	n				Non-Volatile Memory Storage
		Sets the output volt	age lev	el at whi	ich the	PGOOD	pin is de	-asserte	ed low		
		Format		-	Linear, t	wo's co	mpleme	nt binar	у		
		Bit Position	7	6	5	4	3	2	1	0	
		Access	г	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
5F	DOWER COOR OFF	Function				High	Byte				YES
51	POWER_GOOD_OFF	Default Value	0	0	0	0	0	1	0	0	153
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function					Byte				
		Default Value	0	1	0	1	0	0	1	0	
		Sets the rise time of	the ou								
		Format				wo's co					
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r/w	
61	TON_RISE	Function Default Value	4		Expone:				Mantiss		YES
	_	Default Value Bit Position	7	6	1 5	0 4	3	2	0	0	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function	1/1/	1/10	1/W	<u> </u>	ntissa	1/10	1/10	1/10	
		Default Value	0	0	1	0	1	0	1	0	
		Returns one byte of	inform	ation wi	th a sur				al modu	le faults	
		Format					ed Binar	_			
		Bit Position	7	6	5	4	3	2	1	0	
78	STATUS_BYTE	Access	г	r	r	r	r	r	r	r	ts
		Flag	Х	OFF	_OV	OC_	VIN_U V	TEMP	CML	OTHE R	
		Default Value	0	0	0	0	0	0	0	0	
		Returns two bytes of conditions	f inforn	nation w	vith a su	immary	of the m	nodule's	fault/w	arning	
		Format				Unsigne	ed binar	у			
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r	
79	STATUS_WORD	Flag	VOUT	OC_	Х	Х	PGOO D	Х	Х	х	
		Default Value	0	0	0	0	0	0	0	0	
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r	
		Flag	Х	OFF	_OV	OC_	VIN_U V	TEMP	CML	OTHE R	
		Default Value	0	0	0	0	0	0	0	0	
		Returns one byte of related faults	inform	ation wi	th the s	tatus of	the mod	dule's o	utput vo	ltage	
		Format				Unsigne	ed Binar	у			
7A	STATUS_VOUT	Bit Position		7	-	5	4	3	2 1	0	
		Access		r	-	r	r	r	r r	r	
		Flag		r_ov	-	_	UT_UV		X X	X	
		Default Value		)	0 (	0	0	0	0 0	0	
		Returns one byte of related faults	inform	ation wi	th the s	tatus of	the mo	dule's o	utput cu	rrent	
		Format				Unsigne	ed Binar	у			
7B	STATUS_IOUT	Bit Position				$\overline{}$					
		Access			r	r		r r	$\overline{}$	r r	
		Flag					$\overline{}$				
		Default Value	(	)	0	0		0 0	0	0 0	



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Hex Code	Command			E	Brief Des	eriptio	n					Non-Volatile Memory Storage
		Returns one byte of	inform	ation v	with the	status o	fthe	mod	lula's t	emnerat	ture	
		related faults		00.011						empere.		
		Format				Unsign	ad R	inan	,			
7D	STATUS_TEMPERATURE	Bit Position	<del> </del>	7	6		5	4	3	2	1 0	
//	STATOS_TEMPERATORE	Access	_	r r	r		r	r	г		r r	
			_	AULT	OT W		Х	X	x	_	x x	
		Flag	_	AULI )	01_0		ô	0	ô	-	<del>^ ^</del>	
		Default Value					U	U	U	0	0 0	
		Returns one byte of related faults	inform	ation v	with the	status o	fthe	mod	lule's c	ommun	ication	
		Format				Unsign	ned B	inary				
		Bit Position	7		6	5	4	3	2	1	0	
7E	STATUS_CML	Access	r		r	r	г	r	г	r	г	
		Flag	Inva Comn		Invalid Data	PEC Fail	х	х	х	Other Comm Fault	n x	
		Default Value	0 0 0 0 0 0 0							0		
		Returns the value o										
		Format		25 401	Linear,					rv.		
		Bit Position	7	6	5	4		3	2	1	То	
		Access	r	r	r	+ -						
		Function	<u> </u>	'	Expone			•		Mantiss	_	
88	READ_VIN	Default Value	-	1	<del></del>	_	$\overline{}$	1	0	0	$\overline{}$	
		Bit Position	7	6	5	4	_	3	2	1	0	
		Access		_	_	+	-	$\overline{}$		+	-	
		7.00033	г	r	r	r	_	r	r	Г	Г	
		Function	_	_			intiss	_	_	_		
		Default Value	0	0	0	0	_	0	0	0	0	
			of the output voltage of the module									
		Format	_			_	complement binary					
		Bit Position	7	6	5	4	-	3	2	1	0	
		Access	г	г	r	r	_	r	г	r	r	
8B	READ_VOUT	Function		_		_	intiss	_				
	-	Default Value	0	0	0	0	_	0	0	0	0	
		Bit Position	7	6	5	4	+-	3	2	1	0	
		Access	г	г	r	r		r	г	r	r	
		Function		-		_	intiss					
		Default Value	0	0	0	0	_	0	0	0	0	ļ
		Returns the value o	the ou	tput c								
		Format		T -	Linear,	_				<del>-</del>		
		Bit Position	7	6	5	4	_	3	2	1	0	
		Access	r	r	_ r	r		r	r	r	r	
8C	READ_IOUT	Function	<u> </u>		Expone	_	_	_		Mantiss		
	_	Default Value	1	1	1	0	_	0	0	0	0	
		Bit Position	7	6	5	4	+-	3	2	1	0	
		Access	r	r	r	r		r	r	r	г	
		Function	_	-		_	intiss	_				
		Returns one byte in only)	dicating	the m	0 nodule is	compli		o PM	0 Bus Sp	0 ec. 1.1 (	0 read	
		Format Unsigned Binary										
98	PMBUS_REVISION	Bit Position	7	6	5	4	_	3	2	1	Г о	YES
		Access	r	r	r	r	$\overline{}$	r	r	r	r	
	-	Default Value	0	0	0	1	-	0	0	· ·	1	
								_				



Hex Code	Command	Brief Description									Non-Volatile Memory Storage
		Returns the minimu only)	m input	t voltage	the mo	dule is	specifie	d to ope	erate at (	read	
		Format			Linear, t	wo's co	mpleme	nt bina	ry		
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r	
A0	MFR_VIN_MIN	Function			Exponer	nt			Mantiss	3	YES
		Default Value	1	1	1	1	0	0	0	0	
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	г	r	r	
		Function				Mar	ntissa				
		Default Value	0	0	0	0	1	1	0	0	
		Returns the minimum output voltage possible from the module (read only)									
		Format			Linear, t	wo's co	mpleme	nt bina	ry		
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	г	r	r	
A4	MFR_VOUT_MIN	Function			Exponer	nt			Mantiss	a	YES
	WII N_VOOT_WIIIV	Default Value	0	0	0	0	0	0	1	0	123
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	г	r	r	
		Function				_	rtissa				
		Default Value	0	1	1	0	0	1	1	0	
		Returns module nar	name information (read only)								
		Format				Unsigne	d Binar	y			
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	г	r	r	г	г	r	r	
DO	MFR SPECIFIC 00	Function				_	erved		_		YES
		Default Value	1	1	1	0	1	0	0	0	
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	Г	r	r	г	г	r	r	
		Function	_			e Name		_	Rese		
		Default Value Applies an offset to	0 *b= DE/	0	0	0	1	0	1	0	
		in module measurer									1
		Format	nents o		Linear, t					-4111V)	
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r/w	г	r	r	r	r	r	r	
D4	VOUT_CAL_OFFSET	Function	-,	<u> </u>	<u> </u>		ntissa				YES
-		Default Value	V	0	0	0	0	0	0	0	
		Bit Position	7	6	5	4	3	2	1	ō	
		Access	г	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function		, ,	, ,		ntissa	, ,	, ,	,,,,,	
		Default Value	٧	٧	٧	٧	٧	V	V	V	
		Applies a gain corre						sults to	calibrate	out	
		gain errors in modu 0.121)									
		Format			Linear, t	wo's co	mpleme	nt bina	ry		
		Bit Position	7	6	5	4	3	2	1	0	
D5	VOUT_CAL_GAIN	Access	г	г	r	r	г	r/w	r	r	YES
55	roon_ant_aniii	Function			Exponer				Mantiss		
		Default Value	1	1	0	0	0	0	0	V	
		Bit Position	7	6	5	4	3	2	1	0	
		Access	г	Г	г	r/w	r/w	r/w	r/w	r/w	
		Function					ntissa				
		Default Value	V	V	V	V	V	V	V	V	



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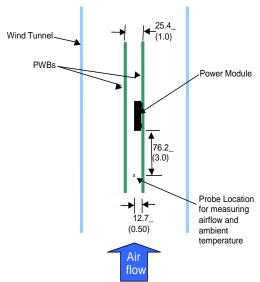
Hex Code	Command		Brief Description									Non-Volatile Memory Storage
		Applies an offset co errors in module me			_						fset	
		Format		ı	Linear, t	wo's co	mpleme	nt binar	у		]	
		Bit Position	7	6	5	4	3	2	1	0	1	
		Access	г	r	r	г	г	г	r/w	г	1	
D6	VIN_CAL_OFFSET	Function			Exponen	nt			Mantiss	а	1	YES
		Default Value	1	1	0	1	V	0	0	V	1	
		Bit Position	7	6	5	4	3	2	1	0	1	
		Access	г	r	r/w	r/w	r/w	r/w	r/w	r/w	1	
		Function	Mantissa							1		
		Default Value	0	0	V	V	V	V	V	V	]	
		Applies a gain corre	Applies a gain correction to the READ_VIN command results to calibrate out gain errors								errors	
		in module measure	ments o	f the inp	put volta	ge (bet	ween -0	.125 an	d 0.121)		_	
		Format		I	Linear, t	wo's co	mpleme	nt binar	у			
		Bit Position	7	6	5	4	3	2	1	0		
		Access	г	r	r	r	r	r/w	r	r		
D7	VIN_CAL_GAIN	Function		ı	Exponen	nt			Mantiss	а		YES
		Default Value	1	1	0	0	V	0	0	V		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	г	г	r	r/w	r/w	r/w	r/w	r/w		
		Function				Mar	itissa				1	
		Default Value	0	0	0	V	V	V	V	V	]	



#### 31. THERMAL CONSIDERATIONS

The SLDN-20D1Ax power modules operate in a variety of thermal environments; however, sufficient cooling should always be provided to help ensure reliable operation.

Considerations include ambient temperature, airflow, module power dissipation, and the need for increased reliability. A reduction in the operating temperature of the module will result in an increase in reliability. The thermal data presented here is based on physical measurements taken in a wind tunnel. The test set-up is shown in Figure 22. The preferred airflow direction for the module is in Figure 23.



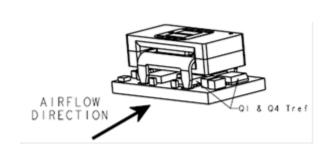


Figure 22. Thermal Test Setup

Figure 23. Preferred airflow direction and location of hot-spot of the module(Tref).

The thermal reference points, Tref used in the specifications are also shown in Figure 49. For reliable operation the temperatures at these points should not exceed 120 oC. The output power of the module should not exceed the rated power of the module (Vo,set x lo,max).

Please refer to the Application Note "Thermal Characterization Process For Open-Frame Board-Mounted Power Modules" for a detailed discussion of thermal aspects including maximum device temperatures.

#### 32. SHOCK AND VIBRATION

The ruggedized (-D version) of the modules are designed to withstand elevated levels of shock and vibration to be able to operate in harsh environments. The ruggedized modules have been successfully tested to the following conditions:

#### Non operating random vibration:

Random vibration tests conducted at 25C, 10 to 2000Hz, for 30 minutes each level, starting from 30Grms (Z axis) and up to 50Grms (Z axis). The units were then subjected to two more tests of 50Grms at 30 minutes each for a total of 90 minutes.

#### Operating shock to 40G per Mil Std. 810F, Method 516.4 Procedure I:

The modules were tested in opposing directions along each of three orthogonal axes, with waveform and amplitude of the shock impulse characteristics as follows:

All shocks were half sine pulses, 11 milliseconds (ms) in duration in all 3 axes.



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Units were tested to the Functional Shock Test of MIL-STD-810, Method 516.4, Procedure I - Figure 516.4-4. A shock magnitude of 40G was utilized. The operational units were subjected to three shocks in each direction along three axes for a total of eighteen shocks.

#### Operating vibration per Mil Std 810F, Method 514.5 Procedure I:

The ruggedized (-D version) modules are designed and tested to vibration levels as outlined in MIL-STD-810F, Method 514.5, and Procedure 1, using the Power Spectral Density (PSD) profiles as shown in Table 1 and Table 2 for all axes. Full compliance with performance specifications was required during the performance test. No damage was allowed to the module and full compliance to performance specifications was required when the endurance environment was removed. The module was tested per MIL-STD-810, Method 514.5, Procedure I, for functional (performance) and endurance random vibration using the performance and endurance levels shown in Table 4 and Table 5 for all axes. The performance test has been split, with one half accomplished before the endurance test and one half after the endurance test (in each axis). The duration of the performance test was at least 16 minutes total per axis and at least 120 minutes total per axis for the endurance test. The endurance test period was 2 hours minimum per axis.

FREQUENCY	PSD LEVEL	FREQUENCY	PSD LEVEL	FREQUENCY	PSD LEVEL
(Hz)	(G2/Hz)	(Hz)	(G2/Hz)	(Hz)	(G2/Hz)
10	1.14E-03	170	2.54E-03	690	1.03E-03
30	5.96E-03	230	3.70E-03	800	7.29E-03
40	9.53E-04	290	7.99E-04	890	1.00E-03
50	2.08E-03	340	1.12E-02	1070	2.67E-03
90	2.08E-03	370	1.12E-02	1240	1.08E-03
110	7.05E-04	430	8.84E-04	1550	2.54E-03
130	5.00E-03	490	1.54E-03	1780	2.88E-03
140	8.20E-04	560	5.62E-04	2000	5.62E-04

Table 15. Performance Vibration Qualification - All Axes

FREQUENCY (Hz)	PSD LEVEL (G2/Hz)	FREQUENCY (Hz)	PSD LEVEL (G2/Hz)	FREQUENCY (Hz)	PSD LEVEL (G2/Hz)
10	0.00803	170	0.01795	690	0.00727
30	0.04216	230	0.02616	800	0.05155
40	0.00674	290	0.00565	890	0.00709
50	0.01468	340	0.07901	1070	0.01887
90	0.01468	370	0.07901	1240	0.00764
110	0.00498	430	0.00625	1550	0.01795
130	0.03536	490	0.01086	1780	0.02035
140	0.0058	560	0.00398	2000	0.00398

Table 16. Endurance Vibration Qualification - All Axes



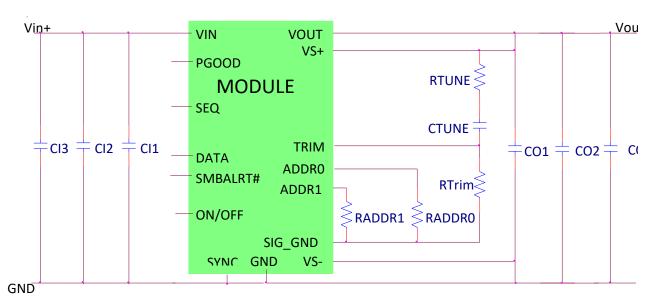
#### 33. EXAMPLE APPLICATION CIRCUIT

#### Requirements:

Vin: 12V Vout: 1.8V

lout: 15A max., worst case load transient is from 10A to 15A  $\Delta$ Vout: 1.5% of Vout (27mV) for worst case load transient

Vin, ripple 1.5% of Vin (180mV, p-p)



CI1 Decoupling cap - 1x0.047μF/16V ceramic capacitor (e.g. Murata LLL185R71C473MA01)

CI2 3x22μF/16V ceramic capacitor (e.g. Murata GRM32ER61C226KE20)

CI3 47µF/16V bulk electrolytic

CO1 Decoupling cap - 1x0.047μF/16V ceramic capacitor (e.g. Murata LLL185R71C473MA01)

CO2 N.A.

CO3 3 x 330 $\mu$ F/6.3V Polymer (e.g. Sanyo Poscap)

CTune 4700pF ceramic capacitor (can be 1206, 0805 or 0603 size)

RTune 330 ohms SMT resistor (can be 1206, 0805 or 0603 size)

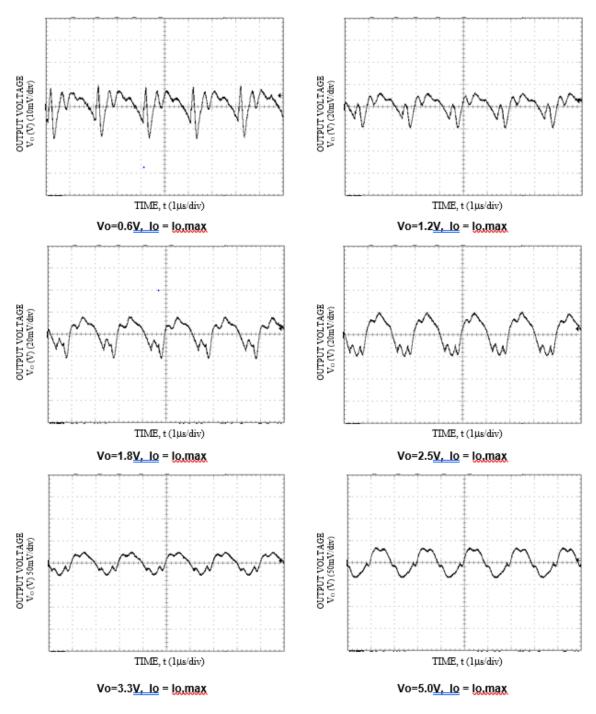
RTrim  $10k\Omega$  SMT resistor (can be 1206, 0805 or 0603 size, recommended tolerance of 0.1%)

Note: The DATA, CLK and SMBALRT pins do not have any pull-up resistors inside the module. Typically, the SMBus master controller will have the pull-up resistors as well as provide the driving source for these signals.



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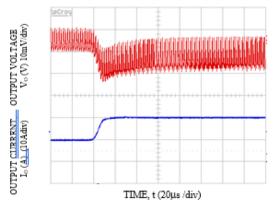
# 34. OUTPUT RIPPLE AND NOISE WAVEFORMS



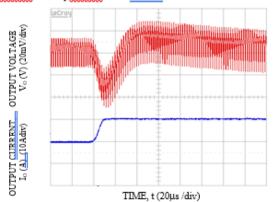
Notes: Co=2×47µF ceramic, VIN = 12V



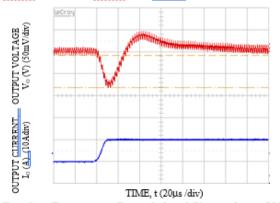
#### **35. TRANSIENT RESPONSE**



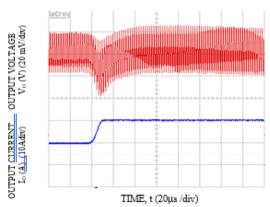
Transient Response to Dynamic Load Change from 50% to 100% at 12Vin, Cout= 1x47µF +11x330µF CTune=47nF, RTune=178 ohms. Vo=0.6V



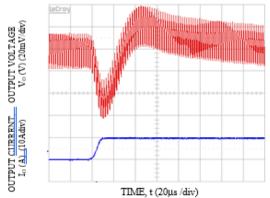
Transient Response to Dynamic Load Change from 50% to 100% at 12Vin, Cout= 2x47µF +3x330µF, CTune=5600pF & RTune=220 ohms., Vo=1.8V



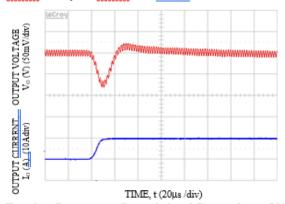
Transient Response to Dynamic Load Change from 50% to 100% at 12Vin, Cout= 5x47µF +1x330µF, CTune=2200pF & RTune=220 ohms. Vo=3.3V



Transient Response to Dynamic Load Change from 50% to 100% at 12Vin, Cout= 1x47µF +5x330µF, CTune=10nF & RTune=178 ohrns 8. Vo=1.2V



Transient Response to Dynamic Load Change from 50% to 100% at 12Vin, Cout= 2x4µF +2x330µF, CTune=3300pF & Trune=220 ohms. Vo=2.5V

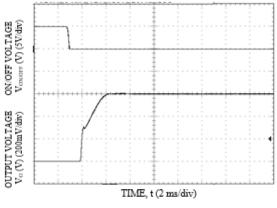


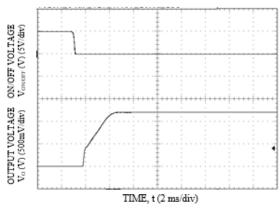
Transient Response to Dynamic Load Change from 50% to 100% at 12Vin, Cout= 8x47µF, CTune=1500pF & RTune=220 ohrns . Vo=5.0V



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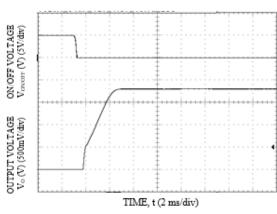
#### **36. STARTUP TIME**

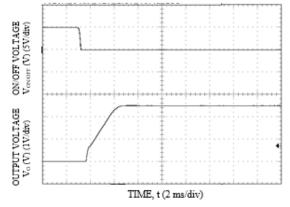






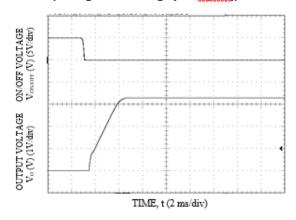


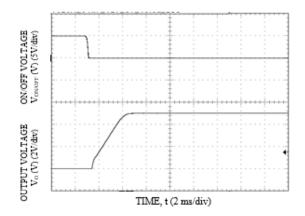




# Start-up Using On/Off Voltage (lo = lo\_max), Vo=1.8V

Start-up Using On/Off Voltage (lo = lo.max), Vo=2.5V

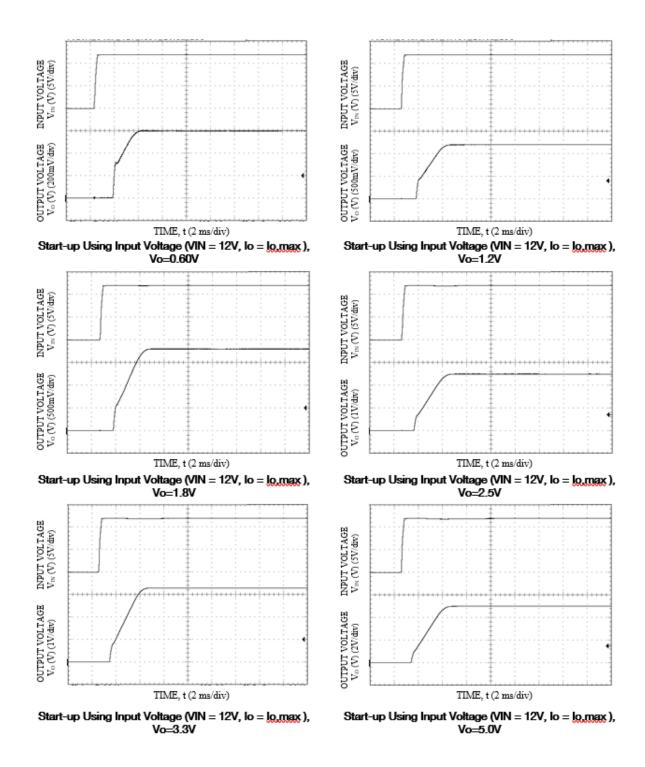




Start-up Using On/Off Voltage (lo = lo.max), Vo=3.3V

Start-up Using On/Off Voltage (lo = lo.max), Vo=5.0V







#### 37. DESIGN CONSIDERATIONS

#### **Input Filtering**

The SLDN-20D1Ax module should be connected to a low ac-impedance source. A highly inductive source can affect the stability of the module. An input capacitance must be placed directly adjacent to the input pin of the module, to minimize input ripple voltage and ensure module stability.

To minimize input voltage ripple, ceramic capacitors are recommended at the input of the module. Figure 24 shows the input ripple voltage for various output voltages at 20A of load current with  $2x22 \, \mu F$  or  $3x22 \, \mu F$  ceramic capacitors and an input of 12V.

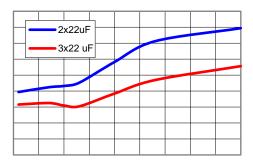


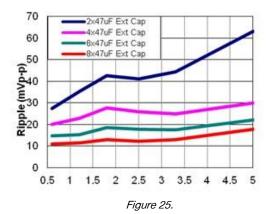
Figure 24. Output Voltage (VDC)

**NOTE**: Input ripple voltage for various output voltages with various external ceramic capacitors at the input (40A load). Input voltage is 12V. Scope Bandwidth limited to 20MHz.

#### **Output Filtering**

These modules are designed for low output ripple voltage and will meet the maximum output ripple specification with 0.1  $\mu$ F ceramic and 2x47  $\mu$ F ceramic capacitors at the output of the module. However, additional output filtering may be required by the system designer for a number of reasons. First, there may be a need to further reduce the output ripple and noise of the module. Second, the dynamic response characteristics may need to be customized to a particular load step change.

To reduce the output ripple and improve the dynamic response to a step load change, additional capacitance at the output can be used. Low ESR polymer and ceramic capacitors are recommended to improve the dynamic response of the module. Figure 25 provides output ripple information for different external capacitance values at various Vo and a full load current of 20A. For stable operation of the module, limit the capacitance to less than the maximum output capacitance as specified in the electrical specification table. Optimal performance of the module can be achieved by using the Tunable Loop<sup>TM</sup> feature described later in this data sheet.



**NOTE:** Output ripple voltage for various output voltages with external 2x47  $\mu$ F, 4x47  $\mu$ F or 6x47  $\mu$ F ceramic capacitors at the output (20A load). Input voltage is 12V.



#### **38. SAFETY CONSIDERATIONS**

For safety agency approval the power module must be installed in compliance with the spacing and separation requirements of the end-use safety agency standards, i.e., UL 60950-1 2nd, CSA C22.2 No. 60950-1-07, DIN EN 60950-1:2006 + A11 (VDE0805 Teil 1 + A11):2009-11; EN 60950-1:2006 + A11:2009-03.

For the converter output to be considered meeting the requirements of safety extra-low voltage (SELV), the input must meet SELV requirements. The power module has extra-low voltage (ELV) outputs when all inputs are ELV.

The SLDN-20D1Ax series were tested using an external fast-acting fuse rated at 30 A, 100 VDC in the ungrounded input.

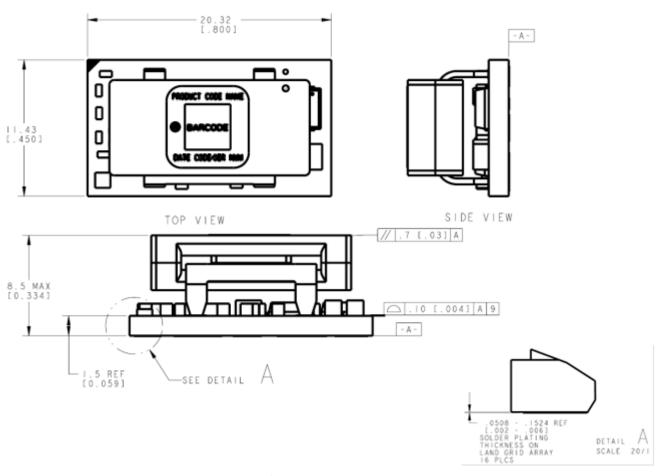


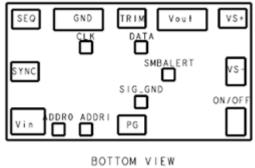
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# 39. MECHANICAL OUTLINE





#### **PIN CONNECTIONS**

PIN	FUNCTION	PIN	FUNCTION
1	ON/OFF	10	SYNC <sup>1</sup>
2	VIN	11	CLK
3	SEQ	12	DATA
4	GND	13	SMBALERT
5	TRIM	14	SIG_GND
6	VOUT	15	ADDR1
7	VS+	16	ADDR0
8	VS-		
9	PG	9	
9	PG	9	

<sup>1</sup>If unused, connect to Ground.

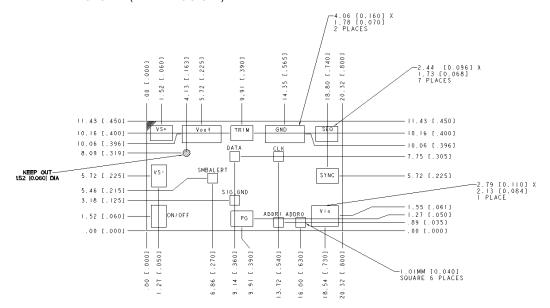


# **40. RECOMMENDED PAD LAYOUT**

Dimensions are in millimeters and (inches).

Tolerances: x.x mm  $\pm$  0.5 mm (x.xx in.  $\pm$  0.02 in.) [unless otherwise indicated]

x.xx mm  $\pm$  0.25 mm (x.xxx in  $\pm$  0.010 in.)



RECOMMENDED FOOTPRINT -THROUGH THE BOARD-

PIN	FUNCTION	PIN	FUNCTION
1	ON/OFF	10	SYNC <sup>2</sup>
2	VIN	11	CLK
3	SEQ	12	DATA
4	GND	13	SMBALERT
5	TRIM	14	SIG_GND
6	VOUT	15	ADDR1
7	VS+	16	ADDR0
8	VS-		
9	PG		

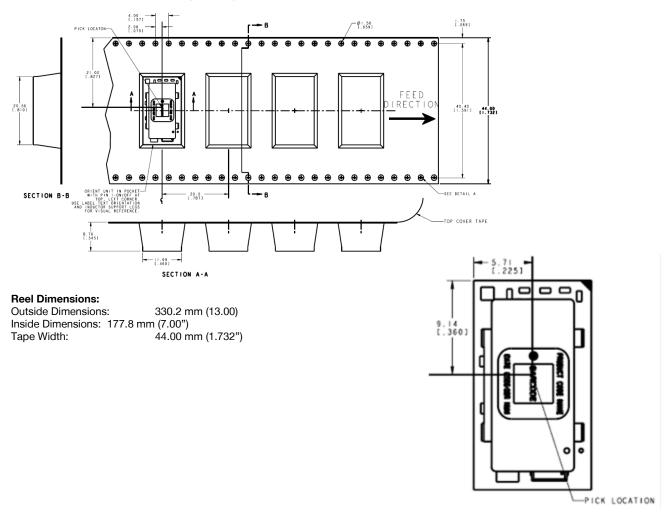
<sup>&</sup>lt;sup>2</sup> If unused, connect to Ground



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#### **41. PACKAGING DETAILS**

The SLDN-20D1Ax modules are supplied in tape & reel as standard. All Dimensions are in millimeters and (in inches)



#### **42. SURFACE MOUNT INFORMATION**

#### **Pick and Place**

The SLDN-20D1Ax modules use an open frame construction and are designed for a fully automated assembly process. The modules are fitted with a label designed to provide a large surface area for pick and place operations. The label meets all the requirements for surface mount processing, as well as safety standards, and is able to withstand reflow temperatures of up to 300oC. The label also carries product information such as product code, serial number and the location of manufacture.

#### **Nozzle Recommendations**

The module weight has been kept to a minimum by using open frame construction. Variables such as nozzle size, tip style, vacuum pressure and placement speed should be considered to optimize this process. The minimum recommended inside nozzle diameter for reliable operation is 3mm. The maximum nozzle outer diameter, which will safely fit within the allowable component spacing, is 7 mm.



#### **Bottom Side / First Side Assembly**

This module is not recommended for assembly on the bottom side of a customer board. If such an assembly is attempted, components may fall off the module during the second reflow process.

#### **Lead Free Soldering**

The modules are lead-free (Pb-free) and RoHS compliant and fully compatible in a Pb-free soldering process. Failure to observe the instructions below may result in the failure of or cause damage to the modules and can adversely affect long-term reliability.

#### **Pb-free Reflow Profile**

Power Systems will comply with J-STD-020 Rev. C (Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices) for both Pb-free solder profiles and MSL classification procedures. This standard provides a recommended forced-air-convection reflow profile based on the volume and thickness of the package (table 4-2). The suggested Pb-free solder paste is Sn/Ag/Cu (SAC). The recommended linear reflow profile using Sn/Ag/Cu solder is shown in Fig. 26. Soldering outside of the recommended profile requires testing to verify results and performance.

#### **MSL** Rating

The SLDN-20D1Ax modules have a MSL rating of 2A.

#### Storage and Handling

The recommended storage environment and handling procedures for moisture-sensitive surface mount packages is detailed in J-STD-033 Rev. A (Handling, Packing, Shipping and Use of Moisture/Reflow Sensitive Surface Mount Devices). Moisture barrier bags (MBB) with desiccant are required for MSL ratings of 2 or greater. These sealed packages should not be broken until time of use. Once the original package is broken, the floor life of the product at conditions of  $\leq 30^{\circ}$ C and 60% relative humidity varies according to the MSL rating (see J-STD-033A). The shelf life for dry packed SMT packages will be a minimum of 12 months from the bag seal date, when stored at the following conditions:  $< 40^{\circ}$  C, < 90% relative humidity.

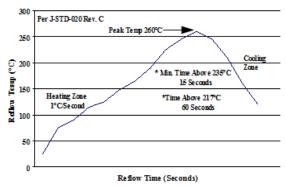


Figure 26. Recommended linear reflow profile using Sn/Ag/Cu solder.

#### **Post Solder Cleaning and Drying Considerations**

Post solder cleaning is usually the final circuit-board assembly process prior to electrical board testing. The result of inadequate cleaning and drying can affect both the reliability of a power module and the testability of the finished circuit-board assembly. For guidance on appropriate soldering, cleaning and drying procedures, refer to Board Mounted Power Modules: Soldering and Cleaning Application Note (AN04-001).



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#### **43. REVISION HISTORY**

DATE	REVISION	CHANGES DETAIL	APPROVAL
2012-03-20	А	First release	HL LU
2012-05-09	В	Adding patent info	HL LU
2015-7-10	С	Update part selection, absolute maximum Ratings, output specifications, general specifications, digital interface specification, safety considerations, analog voltage margining, overtemperature protection, output voltage adjustment using the Power Management Bus, Power Management Bus adjustable overcurrent warning, measuring output current using the Power Management Bus, reading the statues of the Module using the POWER MANAGEMENT BUS, summary of supported Power Management Bus commands, example application circuit, packaging details, MSL Rating.	XF Jiang

# For more information on these products consult: tech.support@psbel.com

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