



18-CHANNEL LINEAR LED DRIVER

Description

The AL58818Q is comprised of 18 programmable LED current channels each with internal 12-bit PWM and 6-bit global current dimming for color and brightness control through I2C or SPI digital interface. AL58818Q is ideal for up to 6 RGB LED lighting modules with 3 programmable banks (A, B, C) for software control of each color or 18 Single Color LEDs with independent dimming for each channel. An external resistor can set up the global output current of all 18 channels. Each channel current can digitally be configured up to the thermal limitation of the package.

Features of the AL58818Q are controlled via I2C/SPI digital interface. Using a dedicated pin INT_SEL to select either I2C or SPI serial interface protocols. The AL58818Q has an internal 30kHz, 12-bit PWM generator for each channel, as well as channel/module independent color mixing and brightness control registers to enable PWM phase shift staggered delay out to achieve vivid LED effects without audible noise and meet EMC CISPR 25 Class 5 requirements. Users can benefit from the device's ultra-low shutdown IQ Power Saving Mode and easy software programming.

The device operates over -40°C to +125°C ambient temperature range. The AL58818Q is available in W-QFN5050-40/SWP (Type A1) MSL level 1 package.

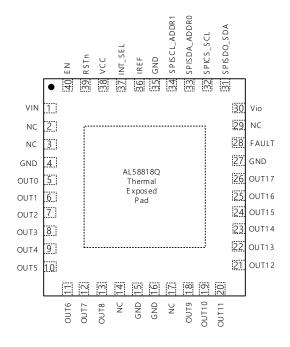
Features

- AEC-Q100 (Grade 1) Qualification
- Input Voltage 2.7V to 5.5V
- 18 Precision LED Current Sinks
 - OUT Pins Voltage max 5.5V
 - 70mA per Channel Current
 - 12-Bit PWM Register with 30kHz Internal PWM Generator
 - PWM Phase Shifting
 - 6-Bit Global Current Dimming
 - Independent Color-Mixing Registers
 - Independent Brightness Control Registers
 - Logarithmic or Linear-Scale Brightness Control
 - Three Programmable Banks (A, B, C)
 - Low-Dropout VSAT 200mV Typical at 70mA
- Hardware-Selectable I2C or SPI Digital Interface
 - Support 400kHz I2C Interface and 4MHz SPI
- Diagnosis and Protections
 - Open-Drain Fault Indication Pin and Registers
 - Individual Fault Mask Registers for Each Channel
 - Overtemperature Protection (OTP) with Pre-OTP Warning
 - LED Open/Short, Undervoltage
- Ultra-Low Quiescent Shutdown 1µA:
 - Power-Saving Mode: 15µA (max)
- Totally Lead-Free & Fully RoHS Compliant (Notes 1 & 2)
- Halogen and Antimony Free. "Green" Device (Note 3)
- The AL58818Q is suitable for automotive applications requiring specific change control; this part is AEC-Q100 qualified, PPAP capable, and manufactured in IATF16949 certified facilities.

https://www.diodes.com/quality/product-definitions/

Pin Assignments

(Top View - Not to Scale)



W-QFN5050-40/SWP (Type A1)

Applications

- Automotive interior and exterior lighting
- Infotainment displays
- Automotive status indicator lights
- Touch panels and LCD displays

Device Information

Orderable Part Number	Package	Body Size
AL58818QFRZW40-13	W-QFN5050-40/SWP (Type A1)	5mm x 5mm

Notes:

1. No purposely added lead. Fully EU Directive 2002/95/EC (RoHS), 2011/65/EU (RoHS 2) & 2015/863/EU (RoHS 3) compliant.

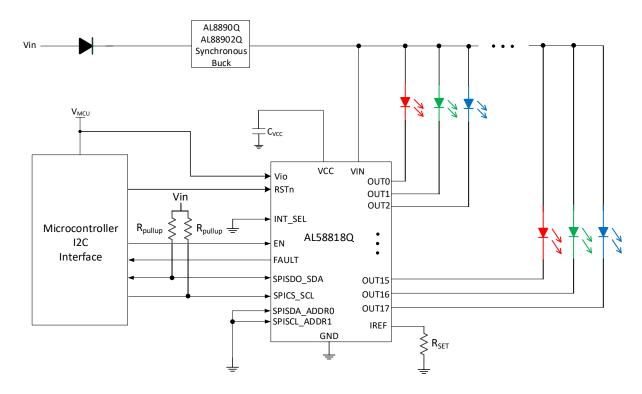
2. See https://www.diodes.com/quality/lead-free/ for more information about Diodes Incorporated's definitions of Halogen- and Antimony-free, "Green" and Lead-free.

3. Halogen- and Antimony-free "Green" products are defined as those which contain <900ppm bromine, <900ppm chlorine (<1500ppm total Br + Cl) and <1000ppm antimony compounds.

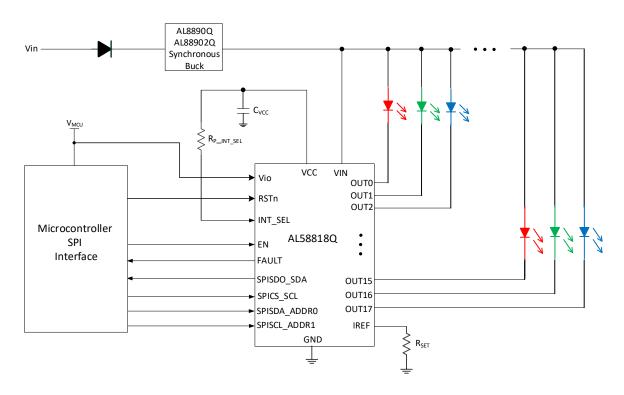


Typical Applications Circuit

1) For I2C Interface



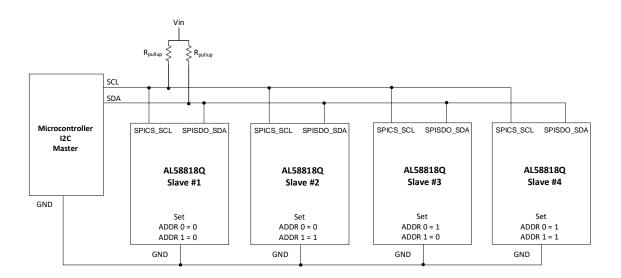
2) For SPI Interface



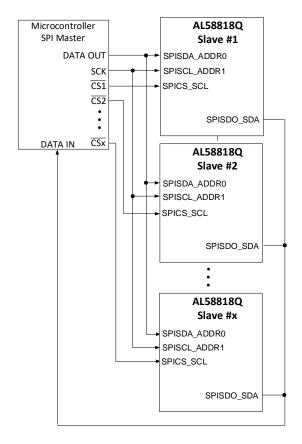


Typical Applications Circuit (continued)

3) Four AL58818Q connected together with external hardware pins setup



4) AL58818Q (SPI interface) connected in parallel



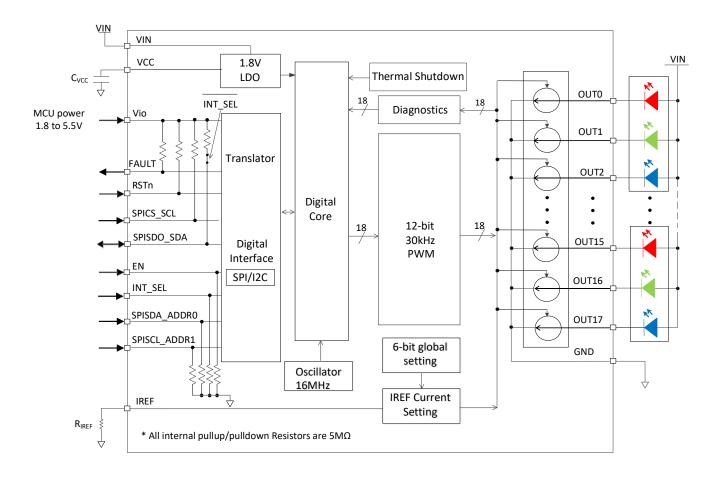


Pin Descriptions

Pin Name	Pin Number	Туре	Function
VIN	1	Power	Input power supply
NC	2, 3, 14, 17, 29	_	No connect
GND	4, 15, 16, 27, 35	GND	Ground
OUT0 to OUT8	5 to 13	0	Current sink output for LED 0 to LED 8
OUT9 to OUT17	18 to 26	0	Current sink output for LED 9 to LED 17
FAULT	28	0	Analog output with open-drain internal pullup $5M\Omega$ resistor to VLDO for fault indication
Vio	30	1	Input power from MCU power rail
SPISDO_SDA	31	I/O	INT_SEL = HIGH, SPI Master input slave output, serial data line selected. INT_SEL = LOW, I2C Data line selected. If not used, this pin must be connected to GND or VIN. (Default HIGH with an internal pullup when I2C mode selected from INT_SEL pin)
SPICS_SCL	32	I	INT_SEL = HIGH, SPI Active low chip selected. INT_SEL = LOW, I2C bus clock line selected. If not used, this pin must be connected to GND or VIN. (Default high with an internal pullup)
SPISDA_ADDR0	33	I	INT_SEL = HIGH, SPI Master output slave input, serial data line selected. INT_SEL = LOW, I2C slave-address selection pin selected. This pin must not be left floating. (Default LOW with an internal pulldown)
SPISCL_ADDR1	34	I	INT_SEL = HIGH, SPI Serial clock line from SPI master (FPGA). INT_SEL = LOW, I2C slave-address pin selected. This pin must not be left floating. (Default LOW with an internal pulldown)
IREF	36	0	Connect an external resistor to regulate all channel output current.
INT_SEL	37	I	Selects the required communication interface. INT_SEL = LOW selects I2C and INT_SEL = HIGH selects SPI. This pin must not be left floating. (Default LOW with an internal pulldown)
VCC	38	0	Internal LDO 1.8V output pin, this pin must be connected to a 1µF capacitor to GND.
RSTn	39	I	Resets digital interface only but retains other register values if pulled down for time between 1ms to 20ms. Resets all register values if pulled down for time more than 20ms. Needs to be pulled high for powering up the internal digital block. (Default HIGH with an internal pullup)
EN	40	1	Active low to shut down the chip. (Default LOW with an internal pulldown)
	Thermal Exposed Pad	GND	Thermal exposed pad also serves as a ground for the device.



Functional Block Diagram





Absolute Maximum Ratings (TA = +25°C, unless otherwise specified.) (Note 4)

Symbol	Parameter	Rating	Unit
V _{IN}	Input Voltage, Voltage Relative to GND	-0.3 to 6	V
І _{ОИТх}	OUTx Output Current	160	mA
V _{OUTX} , EN, FAULT, RSTn, Vio, INT_SEL, SPICS_SCL, SPISDO_SDA, SPISDA_ADDR0, SPISCL_ADDR1, IREF	High-Voltage Pins	-0.3 to 6V	V
VCC	Low-Voltage Output Pin	-0.3 to 2V	V
TJ	Junction Temperature	-40 to +150	°C
Тѕтс	Storage Temperature	-65 to +150	°C
Leb	НВМ	2000	V
ESD	CDM	1000	V

Note:

and transporting these devices.

Package Thermal Information (Note 5)

Symbol	Thermal Resistance	Value	Unit
RөJA	Junction-to-Ambient Thermal Resistance	36.0	°C/W
ReJC(top)	Junction-to-Case (Top) Thermal Resistance	18.7	°C/W
RөJв	Junction-to-Board Thermal Resistance	6.4	°C/W
Ψ_{JT}	Junction-to-Top Characterization Parameter	0.2	°C/W
Ψ_{JB}	Junction-to-Board Characterization Parameter	6.4	°C/W
ReJC(bot)	Junction-to-Case (Bottom) Thermal Resistance	1.1	°C/W

Note:

Recommended Operating Conditions (TA = -40°C to +125°C, unless otherwise specified.)

Symbol	Parameter	Min	Тур	Max	Unit
V _{IN}	Device Supply Voltage	2.7		5.5	V
Vio	Input Power from MCU Rail	1.8	3.3	5.5	V
Іоитх	OUTx Output Current (Note 6)	_	70	-	mA
T _A	Ambient Temperature (Note 6)	-40	_	+125	°C

Note: 6. Dependent on ambient temperature, LED voltage, package thermal limitation, and PCB layout. Set Max_Current_Option = 1 for 70mA.

^{4.} Stresses greater than those listed under Absolute Maximum Ratings can cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions is not implied. Exposure to Absolute Maximum Ratings for extended periods can affect device reliability. Semiconductor devices are ESD sensitive and may be damaged by exposure to ESD events. Suitable ESD precautions should be taken when handling

^{5.} Test condition: device mounted on FR-4 PCB (51mm x 51mm 2oz copper, minimum recommended pad layout on top layer and thermal vias to bottom layer with maximum area ground plane. For better thermal performance, a larger copper pad for heatsink is needed



Electrical Characteristics ($V_{IN} = 3.3V$, -40°C < T_A < +125°C, unless otherwise specified.)

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
POWER SUPPL	_Y					
VCC	Internal 1.8V LDO Output	_	1.74	1.8	1.86	V
	Shutdown Supply Current	VEN = 0V	_	0.2	6	μΑ
	Standby Supply Current	V _{EN} = 3.3V, Chip_EN = 0 (bit)	_	12	33	μA
Ivin	Normal-Mode Supply Current	With 39mA LED current per OUTx	-	7	9	mA
	Power-Save Mode Supply Current	V _{EN} = 3.3V, Chip_EN = 1 (bit) Power_Save_EN = 1 (Bit) All LEDs turned off for time > 30ms	l	12	33	μΑ
UVLO+	VIN UVLO Rising	_	2	2.36	2.5	V
UVLO-	VIN UVLO Falling	_	1.8	2.16	2.4	V
UVLO_Hys	_	_	_	0.2	_	V
Viref	Output Voltage of IREF Pin	_	0.68	0.7	0.72	V
CURRENT SIN	K (Note 7), Max_Current_Optio	n set in Device Config 1 Register, G5:G0 set in LED	Global Dim	nming Regis	ter (See pa	ge 24)
		V_{IN} in full range, $R_{IREF} = 2.1k\Omega$ Max_Current_Option = 0, G5:G0 = 000000		29.25	_	mA
	Maximum Global Output Current (Channel average current, Color Register = FF, Brightness Register = FF)	V _{IN} in full range, R _{IREF} = 2.1kΩ Max_Current_Option = 1, G5:G0 = 100000 (Note 10)	l	7		mA
I _{MAX}		V_{IN} in full range, R_{IREF} = 2.1k Ω Max_Current_Option = 1 G5:G0 = 000000	_	39	_	mA
		V_{IN} in full range, $R_{IREF} = 2.1k\Omega$ $Max_Current_Option = 1$ G5:G0 = 011111 (Note 10)	_	70	_	mA
Ішм	Internal Current Limit	V _{IN} = 3.3V Max_Current_Option = 1, V _{IREF} = 0V G5:G0 = 011111	_	75	155	mA
I _{D2D} (Note 8)	Device to Device (lavg-lset)/lset x 100	$V_{IN} = 2.7V$ to 5.5V. RIREF = $2.1k\Omega$ All channels' current set to 10mA. PWM = 100%. G5:G0 = 100011 (I _{MAX} = 10mA)	_	±3	_	%
I _{C2C} (Note 9)	Channel to Channel (loutx-lavg)/lavg x 100	V_{IN} = 2.7V to 5.5V. R_{IREF} = 2.1k Ω All channels' current set to 10mA. PWM = 100%. G5:G0 = 100011 (I_{MAX} = 10mA)	_	±3	_	%
I _{lkg}	LEDx Leakage Current	PWM = 0%	_	0.01	2.2	μA
VSAT	Output Saturation Voltage	V_{IN} in full range, Max_Current_Option = 1 (bit), RIREF = $2.1k\Omega$, PWM = 100% , the voltage when the LED current has dropped 5% , G5:G0 = 000000	_	0.2	0.6	V
VOPEN_th_rising	LED Open Threshold	VIN = 3.3V, VOUTx < VOPEN_th_rising	0.10	0.2	0.35	V
VSC_th_rising	LED Short Threshold (V _{IN} - V _{OUTx})	VIN = 3.3V, VIN - VOUTx < VSC_th_rising	0.31	0.62	0.9	V

Notes:

^{7.} For understanding of PWM generation process, please refer to Section 2.1.3.

^{8.} I_{D2D}: accuracy of average of all 18 channels current with respect to design target.

^{9.} ICZC: accuracy of individual channel current with respect to the average of all 18 channels current within a device. Channel current: average or mean current (not RMS current) on a channel. Not production tested, guaranteed by design.

10. Not production tested, guaranteed by design.



Symbol	Parameter	Conditions	Min	Тур	Max	Unit	
PWM GROUP DIMMING							
fpWM	PWM Frequency	_	25	30	36	kHz	
fosc	Internal Oscillator Frequency (Note 10)	_	_	15.5	_	MHz	
tIOUTx_rise	IOUTx Rise Time (Note 10)	Time for 0% to 90% rise of IOUTx	_	8	_	ns	
PROTECTION (N	ote 10)						
T(PRETSD)	Pre-Thermal Warning Threshold	_	_	+145	_	°C	
T(PRETSD_HYS)	Pre-Thermal Warning Hysteresis	_	_	+20	_	°C	
T _{SD}	Thermal Shutdown Temperature	_	_	+165	_	°C	
Thys	Thermal Shutdown Temperature Hysteresis	_	_	+20	_	°C	

Note:

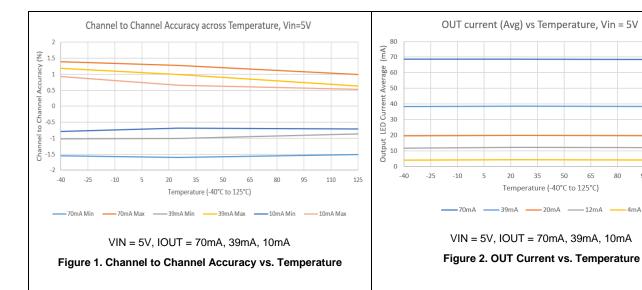
10. Not production tested, guaranteed by design.

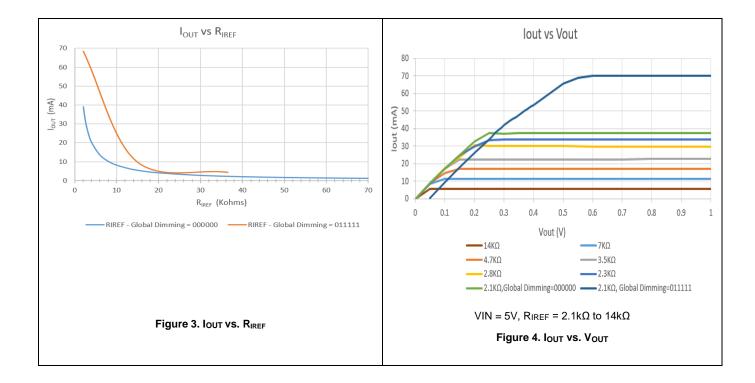
110



Typical Performance Characteristics

 $(V_{IN} = 5V, -40 ^{\circ}C < T_{A} < +125 ^{\circ}C. \ Max_Current_Option = 1 \ for \ 70 mA, \ unless \ otherwise \ specified.)$







Functional Descriptions

1. General Operation

One of the I2C or SPI protocols can be selected using INT_SEL pin. Using I2C/SPI interface, AL58818Q controls LED's color and brightness through 4 primary mechanisms:

- 1. Use R_{IREF} to set full range for LED current I_{MAX} (up to 70mA).
- 2. Set I_{MAX} by using 6-bit global dimming register, which is termed as LED GLOBAL DIMMING in the registers map.
- 3. Set color/brightness registers for LED color and brightness (see Registers Map Description).
- 4. Further select various dimming and protection features described in Registers Map Description.

2. Feature Description

2.1 Each Channel PWM Control

The AL58818Q device is designed with independent color mixing and brightness control, which makes it easier to achieve the RGB LED color effects needed. With the inputs of the color-mixing register and the brightness-control register, the final PWM generator output for each channel is 12-bit resolution and 30kHz dimming frequency, which helps achieve a smooth dimming effect and eliminates audible noise. See Figure 5.

For example, yellow color has the red, green and blue components as 255, 255 and 0 respectively. So to get the color yellow for the first RGB LED module, the color registers at the addresses 14h, 15h and 16h need to be configured with the values 255, 255 and 0 respectively. And then the brightness register for first RGB LED module at the address 8h can be configured based on the amount of brightness needed, 255 being the maximum brightness.

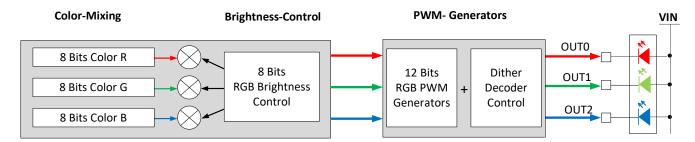


Figure 5. PWM Control Scheme for Each Channel

2.1.1 Independent Color Mixing per RGB LED Module

Each output channel has its own individual 8-bit color-setting register (OUTx_COLOR). The device allows every RGB LED module to achieve > 16 million ($256 \times 256 \times 256$) color-mixing.

2.1.2 Independent Brightness Control per RGB LED Module

When color is fixed, the independent brightness-control is used to achieve accurate and flexible dimming control for every RGB LED module.

2.1.2.1 Brightness-Control Register Configuration

Every three consecutive output channels are assigned to their respective brightness-control register (RGBx_BRIGHTNESS). For example, LED0, LED1, and LED2 are assigned to RGB0_BRIGHTNESS, so it is recommended to connect the RGB LEDs in the sequence as shown in Table 1. The AL58818Q device allows 256-step brightness control for each RGB LED module, which helps achieve a smooth dimming effect.

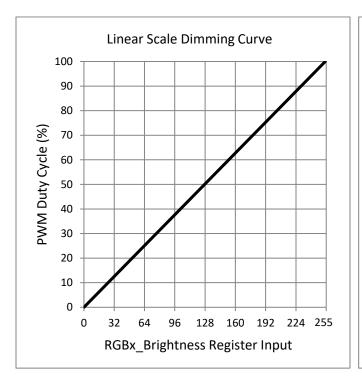
Keeping FFh (default value) in the RGB0_BRIGHTNESS register results in 100% dimming brightness. With this setting, the users can just configure the color mixing register by channel to achieve the target dimming effect in a single-color LED application.

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2.1.2.2 Logarithmic- or Linear-Scale Brightness Control

For human-eye-friendly visual performance, a logarithmic-scale dimming curve is usually implemented in LED drivers. However, for RGB LEDs, if using a single register to achieve both color mixing and brightness control, color distortion can be observed easily when using a logarithmic scale. The AL58818Q device, with independent color-mixing and brightness-control registers, implements the logarithmic scale dimming control inside the brightness control function, which solves the color distortion issue effectively (See Figure 6). Also, the AL58818Q device allows users to configure the dimming scale either logarithmically or linearly through the global Log_Scale_EN register bit. If a special dimming curve is desired, using the linear scale with software correction is the most flexible approach.



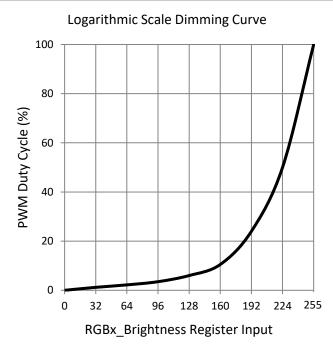


Figure 6. Logarithmic vs Linear Dimming Curve

2.1.3 12-Bit, 30kHz PWM Generator per Channel

With the inputs of the color mixing and the brightness control, the final output PWM duty cycle is defined as the product obtained by multiplying the color-mixing register value by the related brightness-control register value. The final output PWM duty cycle has 12 bits of control resolution, which is achieved by 9 bits of pure PWM resolution and 3 bits of dithering digital control. The AL58818Q device allows the users to enable or disable the dithering function through the PWM_Dithering_EN register. When enabled (default), the output PWM duty-cycle resolution is 12 bits. When disabled, the output PWM duty-cycle resolution is 9 bits. More details about dithering are mentioned in the following paragraph.

When 3-bit dithering is enabled, dither effect is generated with 8 ($2^3 = 8$) possible dither values: "0", "1", "2",..."7", where 0 means no dithering; "1" means every 8th PWM pulse is made 1 LSB longer to increase the final average duty cycle by 1 LSB/8 (duty cycle is termed as DT); "2" means in every group of 8 PWM pulses, the 7th and 8th PWM pulses are both made 1 LSB longer to increase DT by 2 LSB/8, etc. AL58818Q uses 512 clocks in a 100% PWM DT period to achieve 9-bit pure PWM resolution ($2^9 = 512$), thus 1 LSB PWM DT is 1/512. Therefore dither value "1" adds 1/(8 x 512) = 0.0244% additional DT to pure PWM DT. For example, combining with dither value "1", the pure PWM DT of 25% will actually generate DT = 25.0244% for LED current regulation; while with dither value "2", pure PWM DT of 25% will actually generate DT = 25.05%. Though AL58818Q pure PWM resolution is 1/512 = 0.195%, the 3-bit dither scheme enhances PWM resolution to 0.0244%.



2.1.4 PWM Phase-Shifting

A PWM phase-shifting scheme allows delaying the time when each LED driver is active. When the LED drivers are not activated simultaneously, the peak load current from the pre-stage power supply is significantly decreased. The scheme also reduces input-current ripple and ceramic-capacitor audible ringing. LED drivers are grouped into three different phases.

- Phase 1 The rising edge of the PWM pulse is fixed. The falling edge of the pulse is changed when the duty cycle changes. Phase 1 is applied to LED0, LED3, ..., LED[3 × (n 1)].
- Phase 2 The middle point of the PWM pulse is fixed. The pulse spreads in both directions when the PWM duty cycle is increased. Phase 2 is applied to LED1, LED4, ..., LED[3 × (n − 1) + 1].
- Phase 3 The falling edge of the PWM pulse is fixed. The rising edge of the pulse is changed when the duty cycle changes. Phase 3 is applied to LED2, LED5, ..., LED[3 × (n − 1) + 2].

2.2 LED Bank Control

For most LED-animation effects, like blinking and breathing, all the RGB LEDs have the same lighting pattern. Instead of controlling the individual LED separately, which occupies the microcontroller resources heavily, the AL58818Q device provides an easy coding approach, the LED bank control. Each channel can be configured as either independent control or bank control through the RGBx_Bank_EN register. When RGBx_Bank_EN = 0 (default), the LED is controlled independently by the related color-mixing and brightness-control registers. When RGBx_Bank_EN = 1, the AL58818Q device drives the LED in LED bank-control mode. The LED bank has its own independent PWM control scheme, which is the same structure as the PWM scheme of each channel. When a channel configured as LED bank-control mode, the related color mixing and brightness control is governed by the bank control registers (BANK_A_COLOR, BANK_B_COLOR, BANK_C_COLOR, and BANK_BRIGHTNESS) regardless of the inputs on its own color-mixing and brightness-control registers.

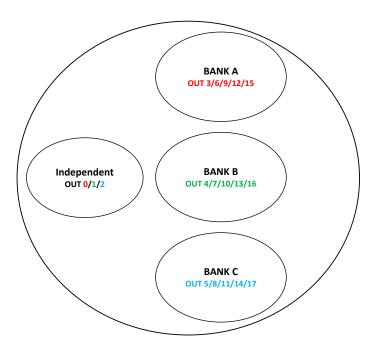
Out Number	Bank Number	RGB Module Number	Register		
OUT0	Bank A				
OUT1	Bank B	RGB0	RGB0_Bank_EN		
OUT2	Bank C				
OUT3	Bank A				
OUT4	Bank B	RGB1	RGB1_Bank_EN		
OUT5	Bank C				
OUT6	Bank A				
OUT7	Bank B	RGB2	RGB2_Bank_EN		
OUT8	Bank C				
OUT9	Bank A				
OUT10	Bank B	RGB3	RGB3_Bank_EN		
OUT11	Bank C				
OUT12	Bank A				
OUT13	Bank B	RGB4	RGB4_Bank_EN		
OUT14	Bank C				
OUT15	Bank A				
OUT16	Bank B	RGB5	RGB5_Bank_EN		
OUT17	Bank C				

Table 1. Bank Number and RGB Number Assignment

With the bank control configuration, the AL58818Q device enables users to achieve smooth and live LED effects globally with an ultra-simple software effort.

For example (as shown in Figure 7), say if we want to configure RGB0 in independent mode and rest of RGB1 to RGB5 in BANK mode, we can do that by configuring LED_CONFIG0 register to FEh and LED_CONFIG1 register to 0Fh. By doing this, the RGB0 module operating in independent mode will be using RGB0_BRIGHTNESS for brightness and R0_COLOR, G0_COLOR and B0_COLOR for R, G and B colors respectively, while the other RGB modules in bank mode would use BANK_BRIGHTNESS for brightness and BANK A, BANK B and BANKC for R, G and B colors respectively.





(RGB0 is independent, RGB1 to RGB5 is bank mode)

Figure 7. Bank PWM Control Example

2.3 Automatic Power-Save Mode

When all the LED outputs are inactive, the AL58818Q device is able to enter power-save mode automatically, thus lowering idle-current consumption down to 25µA (maximum). Automatic power-save mode is enabled when register bit Power_Save_EN = 1 (default) and all the LEDs are off (both color and brightness registers = 00H) for a duration of > 30ms. Almost all analog blocks are powered down in power-save mode. If any I2C/SPI command to the device occurs, the AL58818Q device returns to NORMAL mode.

2.4 Protection Features

2.4.1 LED Open-Circuit Diagnostics

The AL58818Q integrates LED open-circuit diagnostics to allow users to monitor LED status real time. The device monitors OUTx voltage to determine if there is any open-circuit failure.

If the voltage V_{OUTx} for any of the channels goes below threshold V_{OPEN_th_rising} and if the open persists for more than t_{FAULT_WAIT}, the AL58818Q pulls the FAULT pin low to report fault and also sets flag register Open_Fault_CHx and FLAG_OPEN to 1. Once the open-circuit failure is removed, the controller needs to send CLR_FAULT to clear the FLAG_OPEN after fault removal. The fault delay is decided based on below table.

 FW1
 FW0
 tFAULT_WAIT

 0
 0
 8 PWM clock count

 0
 1
 16 PWM clock count

 1
 0
 24 PWM clock count

 1
 1
 32 PWM clock count

Table 2. Fault Wait Time

2.4.2 LED Short-circuit Diagnostics

AL58818Q monitors voltage difference between SUPPLY (VIN) and OUTx to determine if there is any short-circuit failure. If the difference voltage (VIN - VOUTx) for any of the channel falls below threshold (VSC_th_rising) and if the short persists for more than tFAULT_WAIT, the AL58818Q pulls the FAULT pin low to report fault and also sets flag register Short_Fault_CHx and FLAG_SHORT to 1. The MCU should turn off the channel that detects a short fault to avoid overstressing device. Once the short-circuit failure is removed, the controller needs to send CLR_FAULT to clear the FLAG_SHORT after fault removal.



2.4.3 Pre-OTP Warning &Thermal Shutdown

The AL58818Q has pre-thermal warning threshold of +145°C (typical) and thermal shutdown threshold of +160°C (typical).

When the AL58818Q junction temperature rises above pre-thermal warning threshold of +145°C (typical) and if it persists for more than 33µs, the device reports pre-thermal warning by pulling FAULT pin low and sets the flag register FLAG_PREOTP to 1. The device releases pre-OTP warning once the temperature goes below +125°C. Once the fault is removed, the controller needs to send CLR_FAULT to clear the flag register after fault removal.

The AL58818Q device also implements a thermal shutdown mechanism to protect the device from damage due to overheating. When the junction temperature further rises to +165°C (typical), the device shuts down all output drivers and pulls the FAULT pin low. The AL58818Q device releases thermal shutdown when the junction temperature of the device is reduced to +145°C (typical).

2.4.4 Pre-UVLO Warning

The AL58818Q provides Pre-UVLO feature that warns the MCU about supply (VIN) being low and soon UVLO might be triggered. When V_{IN} goes below Pre-UVLO- threshold and if it persists for more than 33 μ s, FAULT pin is pulled low and the flag register FLAG_PREUVLO is set to 1. The device releases Pre-UVLO warning once the V_{IN} goes above Pre-UVLO+ threshold. Once the fault is cleared, the controller needs to send CLR_FAULT to clear the flag register after fault removal.

2.4.5 UVLO

The AL58818Q device has an internal comparator that monitors the voltage at VIN. When V_{IN} is below UVLO-, reset is active and the AL58818Q device is in the INITIALIZATION state. When V_{IN} supply goes below the UVLO- threshold, FAULT pin is pulled low to indicate the fault.

2.4.6 Digital POR Indicator

The AL58818Q device has a digital bit FLAG_POR to indicate the power-on reset. The default value of this bit is high to indicate the power-on reset of digital block. The controller can set CLR_POR during the start of the operation to reset FLAG_POR so that the next power-on reset to digital block can be captured.

2.5 Interface Selection

Interface selection between I2C or SPI is done using an external pin INT_SEL. When tied low, I2C is selected while when connected to high, SPI is selected.

2.6 Digital Communication Enhancements

Pulling the external pin RSTn high enables the internal digital block. Pulling down for time duration between 1ms to 20ms resets only the digital interface and would keep other register values unaltered. Pulling down for time duration more than 20ms would reset all the registers. There is an internal pullup resistor that would by default pull up this pin to HIGH.

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2.7 Current Setting for All Channels

The maximum global output current for all 18 channels can be adjusted by the external resistor, RIREF, as described below. IMAX = KIREF x VIREF/RIREF x [(Max_Current_Option/4)+(3/4)]

where,

I_{MAX} = Channel average current, Color Register = FF, Brightness Register = FF

 R_{IREF} = External dimming resistor (2.1k Ω recommended)

Max_Current_Option = 1 (default) or 0, see Register Map

KIREF = 21 + (N x 3), is the current multiplication factor which can be programmed using 6-bit global dimming register G5:G0 (Address = 66H), which is analog dimming register and N is the decimal equivalent of $\overline{\text{G5}}$ G4 G3 G2 G1 G0.

For example, if all global dimming register bits are 0, the N will be decimal equivalent of 100000 which is 32. Hence, KIREF = 21 + (32 x 3) = 117.

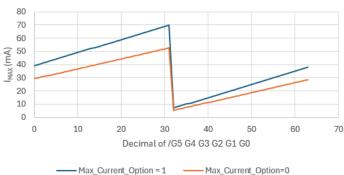
Using equation (1) above, for RIREF = 2.1kΩ and Max Current Option = 1, below is the table that shows IMAX variation with respect to the global dimming register bits. From Table 3, we can see that the default value = 39mA, minimum value = 7mA and maximum value = 70mA.

IMAX (mA) IMAX (mA) G5 G4 G3 G2 G1 G0 Ν **K**IREF Max_Current_Option = 1 Max_Current_Option = 0 39 (Default) 29.25 117 (Default) 30.75 31.5 50.25 51.75 70 (max) 52.5 (max) 210 (max) 7 (min) 5.25 (min) 21 (min) 6.75 7.5 27.75

Table 3. I_{MAX} vs. Global Dimming @ R_{IREF} = 2.1 $k\Omega$



28.5





Similarly, using equation (1) above, for global dimming register setting of 000000H and Max_Current_Option = 1, below is the table that shows I_{MAX} variation with respect to the R_{IREF} .

Table 4. IMAX vs. RIREF @ G5 G4 G3 G2 G1 G0 = 100000

R _{IREF} (kΩ)	I _{MAX} (mA)	Kiref
2.1 (Recommended)	39	117
14.7	5.57	117
36.5	2.24	117

Table 5 shows I_{MAX} range using global dimming at different R_{IREF} values.

Table 5. IMAX vs. Global Dimming Bits @ Various RIREF

D (I-O)	I _{MAX} (mA)					
R _{IREF} (kΩ)	Min	Default	Max			
2.1 (Recommended)	7	39	70			
14.7	1	5.57	10			
36.5	0.4	2.24	4			

2.7.1 Thermal Considerations

As V_{INMAX} increases to 5.5V, the voltage on OUTx nodes can go as high as 3V for RED LEDs and 2V for GREEN and BLUE LEDs. In such situation if the user configures G0:G5 or Rext for higher currents, the device would get overheated and might hit the thermal shutdown voltage.

Hence the V_{IN} and I_{OUTx} for the channels should be chosen in such a way that the device junction temperature does not exceed its thermal shutdown temperature. Below is the formula relating the power dissipation and θ_{JA} that can be used to avoid device thermal shutdown.

$$T_J = T_A + (\theta_{JA} \times P_{TOTAL})$$

Where, T_J is the junction temperature.

 $T_{\mbox{\scriptsize A}}$ is the ambient temperature.

 θ_{JA} is the junction to ambient thermal resistance. Ptotal is the device's total power dissipation.

Example: if all the 18 channels are turned on and carry the same current IMAX, then the device total power dissipation is given by,

PTOTAL = $(6 \times V(OUT0) \times IMAX) + (6 \times V(OUT1) \times IMAX) + (6 \times V(OUT2) \times IMAX)$

2.8 Microcontroller (MCU) Supply

The AL58818Q can recognize interface logic levels from 1.8V to 5.5V. So MCU interacting with the AL58818Q can operate in the range 1.8V to 5.5V. However, the information of the supply used by MCU is required to be shared with the AL58818Q by connecting the MCU supply to Vio pin of the AL58818Q.



2.9 Device Functional Modes

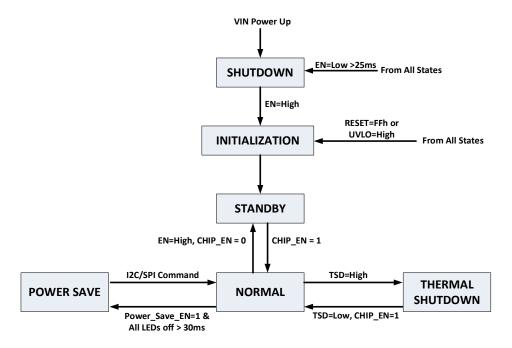


Figure 8. Functional Mode

- **INITIALIZATION**: The device enters INITIALIZATION mode when EN = High. In this mode, all the registers are reset. Entry can also be from any state, if the RESET (register) = FFh or UVLO is active.
- NORMAL: The device enters the NORMAL mode when Chip_EN (register) = 1. IVIN is 7mA (typical).
- **POWER SAVE**: The device automatically enters the POWER SAVE mode when Power_Save_EN (register) = 1 and all the LEDs are off for a duration of > 30ms. In POWER SAVE mode, analog blocks are disabled to minimize power consumption, but the registers retain the data and keep it available via I2C/SPI. IVIN is 25µA (max). In case of any I2C/SPI command to this device, it goes back to the NORMAL mode.
- SHUTDOWN: The device enters SHUTDOWN mode from all states on VIN power down or when EN = Low > 25ms. IVIN is < 6µA (max).
- STANDBY: The device enters the STANDBY mode when Chip_EN (register bit) = 0. In this mode, all the OUTx are shut down, but the registers retain the data and keep it available via I2C/SPI. STANDBY is the low-power-consumption mode, when all circuit functions are disabled. IVIN is 25μA (max).
- THERMAL SHUTDOWN: The device automatically enters THERMAL SHUTDOWN mode when the junction temperature exceeds +160°C (typical). In this mode, the FAULT pin state will change to LOW, Flag register (65h), and the default value 10h will change to 14h. All OUTx outputs will shut down.

Addr.	Name	BIT7	BIT6	BIT5	BIT4	BIT3	BIT2	BIT1	BIT0	FDV
65h	FLAG		Reserved		FLAG_POR	FLAG_ PREUVLO	FLAG_ PREOTP	FLAG_SHORT	FLAG_OPEN	10h

RETURN TO NORMAL MODE: Write 02h to Mask and CLR register (68h) to clear the Fault bit.

Addr.	Name	BIT7	BIT6	BIT5	BIT4	BIT3	BIT2	BIT1	BIT0	FDV
68h	MASK and CLR	Reserved	POR_Mask	PreUVLO_ Mask	PreOTP_ Mask	Short_Mask	Open_ Mask	CLR_Fault	CLR_POR	00h

Write 40h to DEVICE_CONFIG0 register (00h) to enable the device back to normal mode, then decrease the junction temperature below +150°C (typical). FAULT pin state will change to HIGH, then the device returns to NORMAL mode.

Addr.	Name	BIT7	BIT6	BIT5	BIT4	BIT3	BIT2	BIT1	BIT0	FDV
00h	DEVICE_CONFIG0	Reserved	CHIP_EN	Reserved						00h

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3. Programming (SPI)

3.1 SPI-Compatible Interface

The AL58818Q is compatible with SPI serial-bus specification and it operates as a slave.

3.1.1 SPI Initialization

Upon the release of power-on-reset (POR), the SPI peripheral in Digital Block waits for the chip selection signal (SPICS_SCL) from the SPI Controller. The output SPISDA_ADDR0 of the AL58818Q is at high impedance until the reception of an active low on the select line.

The duration of the select line (SPICS_SCL) should be compliant with the lead and lag time requirements.

Lead time: 1) The time from SPICS_SCL low to SPISCL_ADDR1 high.

2) Least lead time is half clock period.

Lag time: 1) The time from SPISCL_ADDR1 low to SPICS_SCL high.

2) Least lag time is one clock period.

AL58818Q is configured to communicate in Mode 0. Data read on rising edge. Clock Polarity in Idle State is Logic Low.

3.1.2 Write Operation

A '1' on bit (R/W) of the SPI request frame indicates a write request from the SPI Controller. Bits A6 to A0 provide the address of the register to which the data is to be written. The contents of the frame from bit D7 to D0 is written into the respective register with last positive edge of the SPISCL_ADDR1 in the current SPI frame.

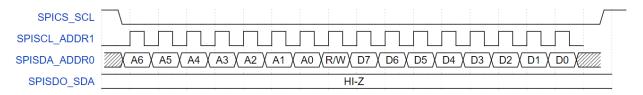


Figure 9. SPI Write Transaction

3.1.3 Read Operation

A read request from the SPI Controller is decoded with the read/write enable bit (R/W). A '0' on bit (R/W) of the frame indicates a read request from the Controller.

Bits A6 to A0 provide the address of the register. For a valid address, the 8-bit contents of the respective register are read out. For invalid addresses (out-of range/unused addresses) the response will be a default value (zero). The peripheral responds to the read request one clock cycle later by setting up data on falling edge and Controller reads data on rising edge. The peripheral responds to the read request one clock cycle later by setting up data on falling edge and Controller reads data on rising edge.

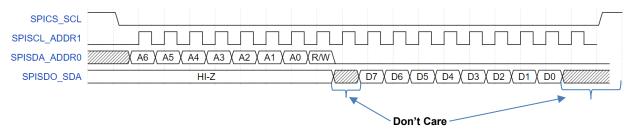


Figure 10. SPI Read Transaction



4. Programming (I2C)

4.1 I2C Interface

The I2C-compatible two-wire serial interface provides access to the programmable functions and registers on the device. This protocol uses a two-wire interface for bi-directional communications between the devices connected to the bus. The two interface lines are the serial data line (SDA) and the serial clock line (SCL). Every device on the bus is assigned a unique address and acts as either a master or a slave depending on whether it generates or receives the serial clock, SCL. The SCL and SDA lines should each have a pullup resistor placed somewhere on the line and remain HIGH even when the bus is idle.

4.1.1 Data Validity

The data on SDA line must be stable during the HIGH period of the clock signal (SCL). In other words, the state of the data line can only be changed when the clock signal is LOW.

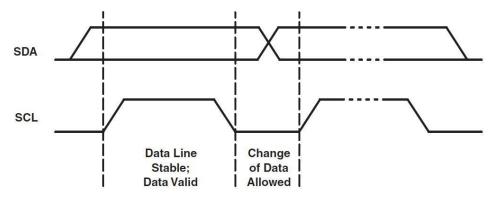


Figure 11. Data Validity

4.1.2 Start and Stop Conditions

START and STOP conditions classify the beginning and the end of the data transfer session. A START condition is defined as the SDA signal transitioning from HIGH to LOW while the SCL line is HIGH. A STOP condition is defined as the SDA transitioning from LOW to HIGH while SCL is HIGH. The bus master always generates START and STOP conditions. The bus is considered to be busy after a START condition and free after a STOP condition. During data transmission, the bus master can generate repeated START conditions. First START and repeated START conditions are functionally equivalent.

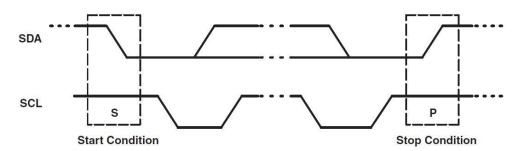


Figure 12. Start and Stop Conditions



4.1.3 Transferring Data

Every byte put on the SDA line must be eight bits long, with the most-significant bit (MSB) being transferred first. Each byte of data must be followed by an acknowledge bit. The acknowledge-related clock pulse is generated by the master. The master releases the SDA line (HIGH) during the acknowledge clock pulse. The device pulls down the SDA line during the 9th clock pulse, signifying an acknowledge. The device generates an acknowledge after each byte has been received.

There is one exception to the acknowledge-after-every-byte rule. When the master is the receiver, it must indicate to the transmitter an end of data by not acknowledging (negative acknowledge) the last byte clocked out of the slave. This negative acknowledge still includes the acknowledge clock pulse (generated by the master), but the SDA line is not pulled down.

After the START condition, the bus master sends a chip address. This address is seven bits long followed by an eighth bit, which is a data direction bit (READ or WRITE). For the eighth bit, a 0 indicates a WRITE, and a 1 indicates a READ. The second byte selects the register to which the data is written. The third byte contains data to write to the selected register.

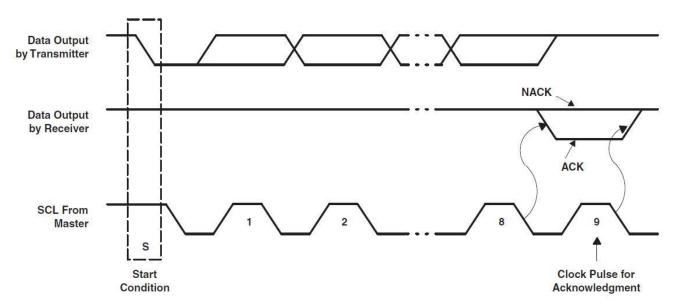


Figure 13. Acknowledge and Not Acknowledge on I2C Bus

Downloaded from **Arrow.com**.



4.1.4 I2C Slave Addressing

The device slave address is defined by connecting GND or Vio to the SPISDA_ADDR0 and SPISCL_ADDR1 pins. A total of 4 independent slave addresses can be realized by combinations when GND or Vio is connected to the SPISDA_ADDR0 and SPISCL_ADDR1 pins (see Table 6 and Table 7).

The device responds to a broadcast slave address regardless of the setting of the SPISDA_ADDR0 and SPISCL_ADDR1 pins. Global writes to the broadcast address can be used for configuring all devices simultaneously. The device supports global read using a broadcast address; however, the data read is only valid if all devices on the I2C bus contain the same value in the addressed register.

Table 6. Slave-Address Combinations

CDICCI ADDD4	eniena anno	Slave Address				
SPISCL_ADDR1	SPISDA_ADDR0	Independent	Broadcast			
GND	GND	011 0000				
GND	Vio	011 0001	001 1100			
Vio	GND	011 0010				
Vio	Vio	011 0011				

Table 7. Chip Address

		Slave Address										
	BIT7	BIT6	BIT5	BIT4	ВІТ3	BIT2	BIT1	BIT0				
Independent	0	1	1	0	0	SPISCL_ADDR1	SPISDA_ADDR0	1 or 0				
Broadcast	0	0	1	1	1	0	0	1 or 0				

4.1.5 Control-Register Write Cycle

- The master device generates a start condition.
- The master device sends the slave address (7 bits) and the data direction bit (R/W = 0).
- The slave device sends an acknowledge signal if the slave address is correct.
- The master device sends the control register address (8 bits).
- The slave device sends an acknowledge signal.
- The master device sends the data byte to be written to the addressed register.
- The slave device sends an acknowledge signal.
- If the master device sends further data bytes, the control register address of the slave is incremented by 1 after the acknowledge signal. To reduce program load time, the device supports address auto incrementation. The register address is incremented after each 8 data bits.
- The write cycle ends when the master device creates a stop condition.



Figure 14. Write Cycle

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4.1.6 Control-Register Read Cycle

- The master device generates a start condition.
- The master device sends the slave address (7 bits) and the data direction bit (R/W = 0).
- The slave device sends an acknowledge signal if the slave address is correct.
- The master device sends the control register address (8 bits).
- The slave device sends an acknowledge signal.
- The master device generates a repeated-start condition.
- The master device sends the slave address (7 bits) and the data direction bit (R/W = 1).
- The slave device sends an acknowledge signal if the slave address is correct.
- The slave device sends the data byte from the addressed register.
- If the master device sends an acknowledge signal, the control-register address is incremented by 1. The slave device sends the data byte from the addressed register. To reduce program load time, the device supports address auto incrementation. The register address is incremented after each 8 data bits.
- The read cycle ends when the master device does not generate an acknowledge signal after a data byte and generates a stop condition.

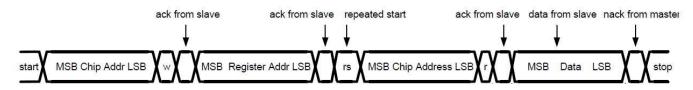


Figure 15. Read Cycle

4.2 FAULT Output

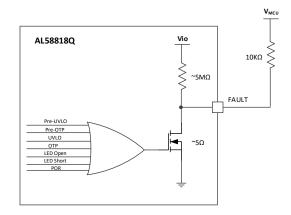


Figure 16. FAULT Internal Block Diagram

The FAULT pin is a fault indicator pin. It can be used as an interrupt output to master controller in case of any fault. The FAULT pin is an nMOS open-drain output with an internal $5M\Omega$ pullup resistor, pulled to Vio and if additionally, this pin can also be pulled up externally to MCU supply using a smaller resistor like $10k\Omega$, as shown in figure above. When one or any of the faults are triggered such as UVLO, OTP, pre-UVLO, pre-OTP, LED open, LED short is detected, FAULT pin is pulled low continuously. Once the FAULT pin output is triggered, the controller needs to take necessary action and to deal with the fault and reset the fault flag. The AL58818Q takes action only for UVLO and OTP faults. For any other fault, the AL58818Q only reports the fault and the controller needs to take the action.

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Protection	Detection	FAULT Pin	Action
Pre-UVLO	V _{IN} < 2.5V	Low	When V _{IN} goes below Pre-UVLO- threshold and if it persists for more than 33µs, FAULT pin is pulled low and sets the flag register FLAG_PREUVLO to 1. Once the V _{IN} goes above Pre-UVLO+ threshold, the fault is cleared. The controller needs to send CLR_FAULT to clear the flag register after fault removal.
Pre-OTP	T _J > +145°C	Low	When the junction temperature > +145°C (typical) and if it persists for more than 33µs, the device pulls FAULT pin low and sets the flag register FLAG_PREOTP to 1. Once the temperature < +125°C, the fault is removed. The controller needs to send CLR_FAULT to clear the flag register after fault removal.
UVLO	Vin < 1.8V	Low	When V_{IN} is below UVLO-, reset is active and the device is in the INITIALIZATION state. When V_{IN} supply goes below the UVLO-threshold, FAULT pin is pulled low to indicate the fault.
OTP - Thermal Protection	T _J > +165°C	Low	When the junction temperature > +165°C (typical), the device shuts down all output drivers and pulls the FAULT pin low. The AL58818Q device releases thermal shutdown when the junction temperature < +145°C (typical).
LED Open	VOUTx < VOPEN_th_rising	Low	If the voltage Voutx for any of the channels goes below threshold Vopen_th_rising and if the open persists for more than tfault_wait, the FAULT pin is pulled low and sets flag register Open_Fault_CHx and FLAG_OPEN to 1. Once the open-circuit failure is removed, the controller needs to send CLR_FAULT to clear the FLAG_OPEN after fault removal.
LED Short	VIN - VOUTx < VSC_th_rising	Low	If the difference voltage (VIN - VOUTX) for any of the channel falls below threshold (VSC_th_rising) and if the short persists for more than tFAULT_WAIT, the FAULT pin is pulled low and sets flag register Short_Fault_CHx and FLAG_SHORT to 1. The MCU should turn off the channel that detects a short fault to avoid overstressing the device. Once the short-circuit failure is removed, the controller needs to send CLR_FAULT to clear the FLAG_SHORT after fault removal.
POR	Software Reset	Low	The default value of this bit is high to indicate the power-on reset of digital block. The controller can set CLR_POR during the start of the operation to reset FLAG_POR so that the next power-on reset to digital block can be captured.

4.3 Unused Channel Masking

Write a "1" to all the reserved bits in the Open Mask registers located in addresses 6Ah/6Bh/6Ch/6Dh/6Eh.

Any unused channels from the 18 channels need the fault masked so it will not be reported to FAULT pin. OUTx pins of those unused channels can be left floating or grounded.

4.4 Fault Masking

Open_Mask_CHx prevents the output open-circuit fault of individual channels from being reported to FAULT pin while Open_Mask prevents any of the channels open fault from being reported to FAULT pin.

Short_Mask_CHx prevents the output short-circuit fault of individual channels from being reported to FAULT pin while Short_Mask prevents any of the channels short fault from being reported to FAULT pin.

Pre_OTP_Mask prevents the Pre_OTP fault from being reported to FAULT pin.

Pre_UVLOMask prevents the Pre_UVLO fault from being reported to FAULT pin.

 $\ensuremath{\mathsf{POR}}\xspace_{-}\xspace\ensuremath{\mathsf{Mask}}\xspace$ prevents the POR event from being reported to FAULT pin.



Registers Map Description

5. Registers Map

Addr.	Name	BIT7	BIT6	BIT5	BIT4	BIT3	BIT2	BIT1	BIT0	FDV
00h	DEVICE_CONFIG0	Reserved	CHIP_EN			Rese	rved			00h
01h	DEVICE_CONFIG1	Phase_Shift_ EN	Reserved	Log_Scale _EN	Power_Save_ _EN	Reserved	Dither_ EN	Max_Current _Option	LED_Global _Off	AEh
02h	LED_CONFIG0	RGB3_Bank_ EN	Rese	erved	RGB2_Bank_ EN	RGB1_ Bank_EN	RGB0_ Bank_EN	Reserved	Reserved	00h
03h	LED_CONFIG1			Rese	rved			RGB5_Bank_ EN	RGB4_Bank _EN	00h
04h	BANK_BRIGHTNESS				Bank_Brig	htness				FFh
05h	BANK_A_COLOR				Bank_A_	Color				00h
06h	BANK_B_COLOR				Bank_B_	Color				00h
07h	BANK_C_COLOR				Bank_C_	Color				00h
08h to 09h	Reserved				Reserv	/ed				00h
0Ah	RGB0_BRIGHTNESS				RGB0_Brio	htness				FFh
0Bh	RGB1_BRIGHTNESS				RGB1_Brig	htness				FFh
0Ch	RGB2_BRIGHTNESS				RGB2_Brig	htness				FFh
0Dh to 0Eh	Reserved				Reserv	/ed				00h
0Fh	RGB3_BRIGHTNESS		RGB3_Brightness							FFh
10h	RGB4_BRIGHTNESS				RGB4_Briq	htness				FFh
11h	RGB5_BRIGHTNESS				RGB5_Briq	htness				FFh
12h to 19h	Reserved		Reserved							00h
1Ah	R0_COLOR				R0_Cd	olor				00h
1Bh	G0_COLOR				G0_Cd	olor				00h
1Ch	B0_COLOR				B0_Cc	olor				00h
1Dh	R1_COLOR				R1_Cd	olor				00h
1Eh	G1_COLOR				G1_C	olor				00h
1Fh	B1_COLOR				B1_Cc	olor				00h
20h	R2_COLOR				R2_C	olor				00h
21h	G2_COLOR				G2_C	olor				00h
22h	B2_COLOR				B2_Cc	olor				00h
23h to 28h	Reserved				Reserv	/ed				00h
29h	R3_COLOR				R3_C	olor				00h
2Ah	G3_COLOR				G3_C	olor				00h
2Bh	B3_COLOR				B3_Cc	olor				00h
2Ch	R4_COLOR				R4_C	olor				00h
2Dh	G4_COLOR				G4_C	olor				00h
2Eh	B4_COLOR				B4_Cc	olor				00h
2Fh	R5_COLOR				R5_Cc	olor				00h
30h	G5_COLOR				G5_C	olor				00h
31h	B5_COLOR				B5_Cc	olor				00h
32h to 37h	Reserved		Reserved							
38h	RESET		RESET							00h
65h	FLAG		Reserved FLAG_POR FLAG_FLAG_FLAG_ FLAG_OPEN							10h
66h	LED_GLOBAL_DIMMING	Reser	ved	G5	G4	G3	G2	G1	G0	00h
67h	FAULT WAIT			Rese	rved			FW1	FW0	00h
68h	MASK and CLR	Reserved	POR_Mask	PreUVLO_ Mask	PreOTP_ Mask	Short_ Mask	Open_ Mask	CLR_Fault	CLR_POR	00h

^{*} FDV = Factory Default Value



5. Registers Map (continued)

Addr.	Name	BIT7	BIT6	BIT5	BIT4	BIT3	BIT2	BIT1	BIT0	FDV
6Ah	OM0	OM_OUT1	OM_OUT0			Rese	rved			00h
6Bh	OM1	Reserved	OM_OUT8	OM_OUT7	OM_OUT6	OM_OUT5	OM_OUT4	OM_OUT3	OM_OUT2	00h
6Ch	OM2	OM_OUT11	OM_OUT10	OM_OUT9			Reserved			00h
6Dh	OM3	Res	served	OM_OUT17	OM_OUT16	OM_OUT15	OM_OUT14	OM_OUT13	OM_OUT12	00h
6Eh	Reserved				Rese	rved				00h
6Fh	SM0	SM_OUT1	SM_OUT0			Rese	rved			00h
70h	SM1	Reserved	SM_OUT8	SM_OUT7	SM_OUT6	SM_OUT5	SM_OUT4	SM_OUT3	SM_OUT2	00h
71h	SM2	SM_OUT11	SM_OUT10	SM_OUT9	SM_OUT9 Reserved					
74h	SM3	Res	served	SM_OUT17	SM_OUT16	SM_OUT15	SM_OUT14	SM_OUT13	SM_OUT12	00h
75h	Reserved				Rese	rved				00h
76h	OF0	OF_OUT1	OF_OUT0			Rese	rved			00h
77h	OF1	Reserved	OF_OUT8	OF_OUT7	OF_OUT6	OF_OUT5	OF_OUT4	OF_OUT3	OF_OUT2	00h
78h	OF2	OF_OUT11	OF_OUT10	OF_OUT9			Reserved			00h
79h	OF3	Res	served	OF_OUT17	OF_OUT16	OF_OUT15	OF_OUT14	OF_OUT13	OF_OUT12	00h
7Ah	Reserved				Rese	rved				00h
7Bh	SF0	SF_OUT1	SF_OUT0			Rese	rved			00h
7Ch	SF1	Reserved	SF_OUT8	SF_OUT7	SF_OUT6	SF_OUT5	SF_OUT4	SF_OUT3	SF_OUT2	00h
7Dh	SF2	SF_OUT11	SF_OUT10	SF_OUT9 Reserved						00h
7Eh	SF3	Res	served	SF_OUT17	SF_OUT16	SF_OUT15	SF_OUT14	SF_OUT13	SF_OUT12	00h
7Fh	Reserved	_			Rese	rved				00h

^{*} OMx = Open_Maskx

^{*} SMx = Short_Maskx

^{*} OFx = Open Faultx

^{*} SFx = Short Faultx

^{*} FDV = Factory Default Value



Table 8. Access Type Codes

Access Type	Code	Description
Read Type		
R	R	Read
Write Type		
$\overline{\mathbb{W}}$	W	Write
Power On Reset or Default value		
(xxh)	(xxh)	Value after POR or default value

5.1 DEVICE_CONFIG0 (Address = 00h) [default = 00h]

Table 9. DEVICE_CONFIG0 Register

7	6	5	4	3	2	1	0		
Reserved	Chip_EN	Reserved							
Reserved	R/W-(00h)	Reserved							
Reserved	0 = Disabled 1 = Enabled	Reserved							

5.2 DEVICE_CONFIG1 (Address = 01h) [default = AEh]

Table 10. DEVICE_CONFIG1 Register

7	6	5	4	3	2	1	0
Phase_Shift_EN	Reserved	Log_Scale_EN	Power_Save_EN	Reserved	Dither_EN	Max_Current _Option	LED_Global_Off
R/W̄-(01h)	R/W-(00h)	R/W-(01h)	R/W-(00h)	R/W̄-(01h)	R/W-(01h)	R/W-(01h)	R/W-(00h)
0 = Disabled 1 = Enabled	_	0 = Linear curve Enabled 1 = Logarithmic curve Enabled	0 = Power Save Mode Disabled 1 = Power Save Mode Enabled	_	0 = Disabled 1 = Enabled	0 = 29.25mA 1 = 39mA	0 = Normal Operation 1 = Shutdown all LEDs

5.3 LED_CONFIG0 (Address = 02h) [default = 00h]

Table 11. LED_CONFIG0 Register

7	6	5	4	3	2	1	0					
LED3_Bank_ EN	Reserved		LED2_Bank_ EN	LED1_Bank_ EN	LED0_Bank_ EN	Reserved	Reserved					
	R/\(\bar{W}\)-(00h)											
0 = Disabled			0 = Disabled	0 = Disabled	0 = Disabled							
1 = Enabled	_		1 = Enabled	1 = Enabled	1 = Enabled	_	_					

^{* 0 =} Independent Mode Enabled

5.4 LED_CONFIG1 (Address = 03h) [default = 00h]

Table 12. LED_CONFIG1 Register

7	6	5	4	3	2	1	0					
		LED5_Bank_ EN	LED4_Bank_ EN									
	R/W̄-(00h)											
Reserved 0 = Disabled 1 = Enabled 1 =												

^{* 1 =} Bank Mode Enabled



5.5 BANK_BRIGHTNESS (Address = 04h) [default = FFh]

Table 13. BANK_BRIGHTNESS Register

7	7 6 5 4 3 2 1 0											
	BANK_BRIGHTNESS											
R/W̄-(FFh)												
			00h = 0% of f	ull brightness								
	80h = 50% of full brightness											
			FFh = 100 % o	 f full brightness								

5.6 BANK_A_COLOR (Address = 05h) [default = 00h]

Table 14. BANK_A_COLOR Register

7	7 6 5 4 3 2 1 0										
BANK_A_COLOR											
R/W̄-(00h)											
	00h = The color mixing percentage is 0%										
	80h = The color mixing percentage is 50%										
	FFh = The color mixing percentage is 100%										

5.7 BANK_B_COLOR (Address = 06h) [default = 00h]

Table 15. BANK_B_COLOR Register

7	7 6 5 4 3 2 1 0										
BANK_B_COLOR											
R/W-(00h)											
	00h = The color mixing percentage is 0%										
	80h = The color mixing percentage is 50%										
	FFh = The color mixing percentage is 100%										

5.8 BANK_C_COLOR (Address = 07h) [default = 00h]

Table 16. BANK_C_COLOR Register

7	7 6 5 4 3 2 1 0										
BANK_C_COLOR											
R/W̄-(00h)											
	00h = The color mixing percentage is 0%										
	 80h = The color mixing percentage is 50%										
	FFh = The color mixing percentage is 100%										



5.9 RGB0 to RGB5_BRIGHTNESS (Address = 0Ah, 0Bh, 0Ch, 0Fh, 10h, and 11h) [default = FFh]

Table 17. RGB0 to RGB5_BRIGHTNESS Register

7	7 6 5 4 3 2 1 0												
RGB0 to RGB5_BRIGHTNESS													
	R/W̄-(FFh)												
00h = 0% of full brightness													
	 80h = 50% of full brightness												
				 FFh = 100 % of full brightness									

5.10 Rx_COLORx = 0 to 5 (Address = 1Ah, 1Dh, 20h, 29h, 2Ch, and 2Fh) [default = 00h]

Table 18. Rx_COLOR Register

7	7 6 5 4 3 2 1 0										
Rx_COLOR											
R/W̄-(00h)											
00h = The color mixing percentage is 0%											
	 80h = The color mixing percentage is 50%										
	FFh = The color mixing percentage is 100%										

5.11 Gx_COLORx = 0 to 5 (Address = 1Bh, 1Eh, 21h, 2Ah, 2Dh, and 30h) [default = 00h]

Table 19. Gx_COLOR Register

7 6 5 4 3 2 1 0											
Gx_COLOR											
R/W̄-(00h)											
	00h = The color mixing percentage is 0%										
	 80h = The color mixing percentage is 50%										
	FFh = The color mixing percentage is 100%										

5.12 Bx_COLORx = 0 to 5 (Address = 1Ch, 1Fh, 22h, 2Bh, 2Eh, and 31h) [default = 00h]

Table 20. Bx_COLOR Register

7	7 6 5 4 3 2 1 0										
Bx_COLOR											
R/W̄-(00h)											
	00h = The color mixing percentage is 0%										
	80h = The color mixing percentage is 50%										
	FFh = The color mixing percentage is 100%										

5.13 RESET (Address = 38h) [default = 00h]

Table 21. RESET Register

7	6	5	4	3	2	1	0				
RESET											
	W̄-(00h)										
	FFh = Resets all the registers to default value.										



5.14 FLAG (Address = 65h) [default = 00h]

Table 22. FLAG Register

7	6	5	4	3	2	1	0				
F	Reserve	d	FLAG_POR	FLAG_PREUVLO	FLAG_PREOTP	FLAG_SHORT	FLAG_OPEN				
	R/W̄-(00h)										
F	Reserve	d	0 = No POR fault reported. 1 = POR fault reported.	0 = No Pre_UVLO fault reported. 1 = Pre_UVLO fault reported.	0 = No Pre_OTP fault reported. 1 = Pre_OTP fault reported.	0 = No short fault reported on any channel. 1 = Short fault reported on any of the channels.	0 = No open fault reported on any channel. 1 = Open fault reported on any of the channels.				

5.15 LED_GLOBAL_DIMMING (Address = 66h) [default = 00h]

Table 23. LED_GLOBAL_DIMMING Register

7	6	5	4	3	2	1	0				
Reserved		G5	G4	G3	G2	G1	G0				
	R/W̄-(00h)										
Rese	Reserved 6-bit LED Global current setting. See <u>Table 3</u> for details.										

5.16 FAULT_WAIT (Address = 67h) [default = 00h]

Table 24. FAULT_WAIT Register

7	6	5	4	3	2	1	0				
		FW1	FW0								
	R/W̄-(00h)										
		0 = as per <u>Table 2</u> 1 = as per <u>Table 2</u>	0 = as per <u>Table 2</u> 1 = as per <u>Table 2</u>								

5.17 MASK and CLR (Address = 68h) [default = 00h]

Table 25. MASK and CLR Register

7	6	5	4	3	2	1	0			
Reserved	POR_Mask	PreUVLOMask	PreOTP_Mask	Short_Mask	Open_Mask	CLR_Fault	CLR_POR			
R/W̄-(00h)										
	0 = POR mask	0 = Pre-UVLO	0 = Pre-OTP	0 = Short Detection	0 = Open Detection	0 = Clearing	0 = Clearing			
Reserved	turned off	mask turned off	mask turned off	Mask off	Mask off	faults turned off	POR turned off			
Reserved	1 = POR mask	1 = Pre-UVLO	1 = Pre-OTP	1 = Short Detection	1 = Open Detection	1 = Clears the	1 = Clears the			
	turned on	mask turned on	mask turned on	Mask on	Mask on	faults	POR faults			

5.18 OM0 (Address = 6Ah) [default = 00h]

Table 26. OM0 Register

7	6	5 4 3 2 1 0							
OM_OUT1	OM_OUT0		Reserved						
			R/W-	(00h)					
0 = Off 1 = On									

OM = Open_Maskx



5.19 OM1 (Address = 6Bh) [default = 00h]

Table 27. OM1 Register

7	6	5	4	3	2	1	0			
Reserved	OM_OUT8	OM_OUT7	OM_OUT6	OM_OUT5	OM_OUT4	OM_OUT3	OM_OUT2			
	R/W̄-(00h)									
_	0 = Off 1 = On									

 $OM = Open_Maskx$

5.20 OM2 (Address = 6Ch) [default = 00h]

Table 28. OM2 Register

7	6	5	4 3 2 1 0							
OM_OUT11	OM_OUT10	OM_OUT9	Reserved							
	R/W̄-(00h)									
0 = Off	0 = Off									
1 = On	1 = On	1 = On			_ _					

OM = Open_Maskx

5.21 OM3 (Address = 6Dh) [default = 00h]

Table 29. OM3 Register

7	6	5	4	3	2	1	0			
Reserved	Reserved	OM_OUT17	OM_OUT16	OM_OUT15	OM_OUT14	OM_OUT13	OM_OUT12			
	R/W̄-(00h)									
Reserved	Reserved	0 = Off 1 = On								

OM = Open_Maskx

5.22 SM0 (Address = 6Fh) [default = 00h]

Table 30. SM0 Register

7	6	5	4	3	2	1	0			
SM_OUT1	SM_OUT0		Reserved							
			R/W̄-	(00h)						
0 = Off 1 = On	0 = Off		_							
1 = On	1 = On									

SM = Short_Maskx

5.23 SM1 (Address = 70h) [default = 00h]

Table 31. SM1 Register

7	6	5	4	3	2	1	0			
Reserved	SM_OUT8	SM_OUT7	SM_OUT6	SM_OUT5	SM_OUT4	SM_OUT3	SM_OUT2			
	R/W-(00h)									
_	0 = Off 1 = On									

 $SM = Short_Maskx$



5.24 SM2 (Address = 71h) [default = 00h]

Table 32. SM2 Register

7	6	5	4 3 2 1 0							
SM_OUT11	SM_OUT10	SM_OUT9	Reserved							
	R/W̄-(00h)									
0 = Off	_									
1 = On	1 = On	1 = On								

 $SM = Short_Maskx$

5.25 SM3 (Address = 74h) [default = 00h]

Table 33. SM3 Register

7	6	5	4	3	2	1	0			
Reserved		SM_OUT17	SM_OUT16	SM_OUT15	SM_OUT14	SM_OUT13	SM_OUT12			
	R/W̄-(00h)									
_	_	0 = Off 1 = On								

 $SM = Short_Maskx$

5.26 OF0 (Address = 76h) [default = 00h]

Table 34. OF0 Register

7	6	5 4 3 2 1 0								
OF_OUT1	OF_OUT0		Reserved							
	R/W̄-(00h)									
0 = Off										

OFx = Open_Faultx

5.27 OF1 (Address = 77h) [default = 00h]

Table 35. OF1 Register

7	6	5	4	3	2	1	0				
Reserved	OF_OUT8	OF_OUT7	OF_OUT6	OF_OUT5	OF_OUT4	OF_OUT3	OF_OUT2				
	R/\(\bar{W}\)-(00h)										
	0 = Off	0 = Off	0 = Off	0 = Off	0 = Off	0 = Off	0 = Off				
_	1 = On	1 = On	1 = On	1 = On	1 = On	1 = On	1 = On				

 $OFx = Open_Faultx$

5.28 OF2 (Address = 78h) [default = 00h]

Table 36. OF2 Register

7	6	5	4	3	2	1	0		
OF_OUT11	OF_OUT10	OF_OUT9	Reserved						
			R/W-	(00h)					
0 = Off	0 = Off	0 = Off							
1 = On	1 = On	1 = On			_				

 $OFx = Open_Faultx$



5.29 OF3 (Address = 79h) [default = 00h]

Table 37. OF3 Register

7	6	5	4	3	2	1	0			
Reserved	Reserved	OF_OUT17	OF_OUT16	OF_OUT15	OF_OUT14	OF_OUT13	OF_OUT12			
	R/W̄-(00h)									
Reserved	Reserved	0 = Off 1 = On								

OFx = Open_Faultx

5.30 SF0 (Address = 7Bh) [default = 00h]

Table 38. SF0 Register

7	6	5	4	3	2	1	0
SF_OUT1	SF_OUT0	Reserved					
	R/W̄-(00h)						
0 = Off 1 = On	0 = Off 1 = On	0 = Off 1 = On					

 $SFx = Short_Faultx$

5.31 SF1 (Address = 7Ch) [default = 00h]

Table 39. SF1 Register

7	6	5	4	3	2	1	0
Reserved	SF_OUT8	SF_OUT7	SF_OUT6	SF_OUT5	SF_OUT4	SF_OUT3	SF_OUT2
	R/\(\bar{W}\)-(00h)						
_	0 = Off 1 = On	0 = Off 1 = On	0 = Off 1 = On	0 = Off 1 = On	0 = Off 1 = On	0 = Off 1 = On	0 = Off 1 = On

 $SFx = Short_Faultx$

5.32 SF2 (Address = 7Dh) [default = 00h]

Table 40. SF2 Register

6	5	4	3	2	1	0
SF_OUT10	SF_OUT9	Reserved				
R/W̄-(00h)						
0 = Off 1 = Op	0 = Off 1 = Op			_		
_	SF_OUT10	SF_OUT10 SF_OUT9 0 = Off 0 = Off	SF_OUT10 SF_OUT9 R/W- 0 = Off 0 = Off	SF_OUT10 SF_OUT9 R/W-(00h) 0 = Off	SF_OUT10 SF_OUT9 Reserved R/W-(00h) 0 = Off 0 = Off	SF_OUT10 SF_OUT9 Reserved R/W̄-(00h) 0 = Off 0 = Off

SFx = Short_Faultx

5.33 SF3 (Address = 7Eh) [default = 00h]

Table 41. SF3 Register

7	6	5	4	3	2	1	0
Reserved	Reserved	SF_OUT17	SF_OUT16	SF_OUT15	SF_OUT14	SF_OUT13	SF_OUT12
	R/\(\bar{W}\)-(00h)						
Reserved	Reserved	0 = Off 1 = On					

 $SFx = Short_Faultx$



Application Information

Timing Requirements for I2C Interface (Note 11)

Symbol	Parameter	Min	Тур	Max	Unit
fscL	I2C clock frequency	_	1	400	kHz
ten_H	EN first rising edge until first I2C access	_	_	500	μs
ten_L	EN first falling edge until first I2C reset	_	_	3	μs
1	Hold time (repeated) START condition	0.6	_	_	μs
2	Clock low time	1.3	_	_	μs
3	Clock high time	600	_	_	ns
4	Setup time for a repeated START condition	600	_	_	ns
5	Data hold time	0	_	_	ns
6	Data setup time	100	_	_	ns
7	Rise time of SDA and SCL	20 + 0.1 Cb	_	300	ns
8	Fall time of SDA and SCL	15 + 0.1 Cb	_	300	ns
9	Setup time for STOP condition	600	_	_	ns
10	Bus free time between a STOP and a START condition	1.3	_	_	ns
Cb	Capacitive load parameter for each bus line. Load of 1pF corresponds to one nanosecond.	_	_	200	pF

Note:

11. Specified by design & ATE characterized.

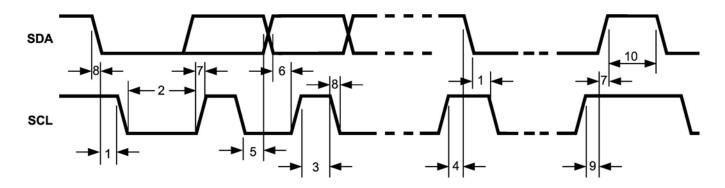


Figure 17. I2C Timing Parameters

Table 42. Input and Output Logic Levels

Symbol	Parameter	Conditions	Min	Тур	Max	Unit		
DIGITAL INPUT	DIGITAL INPUT LOGIC LEVELS (EN, RSTn, INT_SEL)							
VIL	Input logic low	Vio = 1.8V	_		0.35	V		
VIH	Input logic high	VIO = 1.0V	1.4	_	_	V		
DIGITAL INTER	DIGITAL INTERFACE LOGIC LEVELS (SPICS_SCL, SPISDO_SDA, SPISDA_ADDR0, SPISCL_ADDR1)							
VIL	Input logic low	Vio = 1.8V	_		0.4	V		
Vih	Input logic high	VIO = 1.0V	1.4			V		
Vsda	SDA output low level	IPULLUP = 5mA	_		0.4	V		



Application Information (continued)

Timing Requirements for SPI Interface (Note 11)

Symbol	Parameter	Condition	Min	Тур	Max	Unit
fsclk	SPI clock frequency	_	_	_	4	MHz
tcss	The time from SPICS_SCL low to SPISCL_ADDR1 high	_	250	_	_	ns
tсsн	The time from SPISCL_ADDR1 low to SPICS_SCL high	_	250	_	_	ns
tos	Data setup time	_	10	_	_	ns
tрн	Data hold time		0	_	_	ns
tcs_нı	Minimum chip select de-asserted HIGH time		250	_	_	ns
tD(SDO)	SDO delay time	C _L = 50pF	_	_	20	ns
t _{LOW}	LOW period of SCLK clock	_	125	_	_	ns
tніgн	HIGH period of SCLK clock	_	125	_	_	ns

Note:

11. Specified by design & ATE characterized.

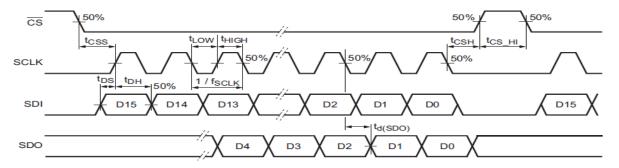


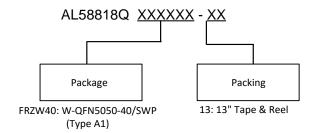
Figure 18. SPI Timing Parameters

Design Tools - from Diodes Incorporated's Website https://www.diodes.com/design/tools/

- RGB 3 in 1 Demo Board AL58818QEV1
- Arduino Sample Code
- Demo Board Gerber File for PCB Layout Reference



Ordering Information

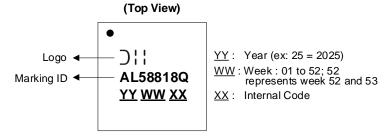


Orderable Part Number	Part Number Suffix	Package Code	Package (Note 12)	Packing	
Orderable Part Number	Part Number Sumx	Fackage Code	Package (Note 12)	Qty.	Carrier
AL58818QFRZW40-13	-13	FRZW40	W-QFN5050-40/SWP (Type A1)	5000	Tape & Reel

Note: 12. For packaging details, go to our website at https://www.diodes.com/design/support/packaging/diodes-packaging/.

Marking Information

W-QFN5050-40/SWP (Type A1)

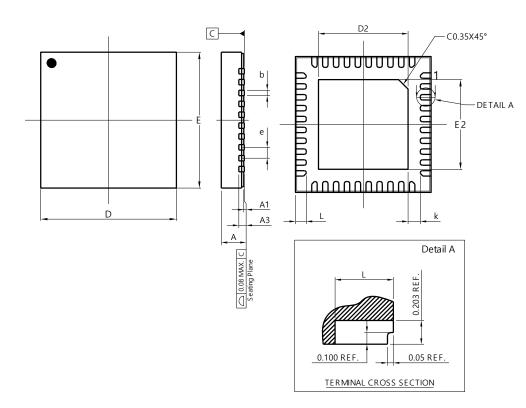




Package Outline Dimensions

Please see http://www.diodes.com/package-outlines.html for the latest version.

W-QFN5050-40/SWP (Type A1)

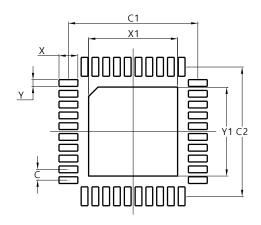


W-	W-QFN5050-40/SWP					
	(Type A1)					
Dim	Min	Max	Тур			
Α	0.70	0.80	0.75			
A1	0.00	0.05	0.02			
А3	().203 R	REF			
b	0.15	0.25	0.20			
D	4.90	5.10	5.00			
D2	3.25	3.35	3.30			
Е	4.90	5.10	5.00			
E2	3.25	3.35	3.30			
е		0.40 B	SC			
k	0.20					
L	0.35	0.45	0.40			
All	All Dimensions in mm					

Suggested Pad Layout

Please see http://www.diodes.com/package-outlines.html for the latest version.

W-QFN5050-40/SWP (Type A1)



Dimensions	Value		
Dilliensions	(in mm)		
С	0.400		
C1	4.800		
C2	4.800		
X	0.700		
X1	3.300		
Y	0.250		
Y1	3.300		



Tape and Reel Information

Please see https://www.diodes.com/assets/Packaging-Support-Docs/AP02007.pdf for tape and reel details.

Mechanical Data

Package W-QFN5050-40/SWP (Type A1)

- Moisture Sensitivity: Level 1 per J-STD-020
- Terminals: Finish Matte Tin Plated Leads, Solderable per JESD22-B102 @3
- Weight: 0.0091 grams (Approximate)

April 2025



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