

Non-Isolated DC-DC Converter

The SLDN-03D1A modules are non-isolated DC-DC converters that can deliver up to 3 A of output current. These modules operate over a wide range of input voltage 3 to 14.4 VDC and provide a precisely regulated output voltage from 0.45 to 5.5 VDC, programmable via an external resistor and power management bus control.

Features include a digital interface using the power management bus protocol, remote on/off, adjustable output voltage, over current and over temperature protection. The power management bus interface supports a range of commands to both control and monitor the module. These modules also include the Tunable LoopTM feature that allows the user to optimize the dynamic response of the converter to match the load with reduced amount of output capacitance leading to savings on cost and PWB area.



Key Features & Benefits

- Wide Input Voltage Range (3 14.4 VDC)
- Cost Efficient Open Frame Design
- Non-Isolated
- DOSA Based
- Power Good Signal, Remote On/Off
- Over Temperature Protection
- Output Voltage Programmable from 0.6 VDC to 5.5 VDC via External Resistor. Digitally adjustable down to 0.45 VDC
- Digital Interface through the Power Management Bus Protocol
- Ability to Sink and Source Current
- Tunable LoopTM to Optimize Dynamic Output Voltage Response
- Flexible Output Voltage Sequencing EZ-SEQUENCE
- Fixed Switching Frequency with Capability of External Synchronization
- Output Over Current Protection (non-latching)
- Certificated to IEC/EN 62368-1
- Class II, Category 2, Non-Isolated DC/DC Converter (refer to IPC-9592B)



Applications

- Distributed Power Architectures
- Intermediate Bus Voltage Applications
- Telecommunications Equipment
- Servers and Storage Applications
- Networking Equipment
- Industrial Equipment



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1. MODEL SELECTION

MODEL NUMBER	OUTPUT VOLTAGE	INPUT VOLTAGE	MAX. OUTPUT CURRENT	MAX. OUTPUT POWER	TYPICAL EFFICIENCY
SLDN-03D1A0G					
SLDN-03D1A0R	0.45 551/00	0 44.41/00	0.4	40 5 14/	0.40/
SLDN-03D1ALG	0.45 - 5.5 VDC	3 – 14.4 VDC	3 A	16.5 W	94%
SLDN-03D1ALR					

PART NUMBER EXPLANATION

s	LDN	- ()3 D	1A	х	У
Mounting Type	Series Code		tput Input Voltage Range	e Sequencing or not	Active Logic	Package Type
Surface Mount	SLDN Series	3	A 3 – 14.4 V	With Sequencing	L – Active Low 0 – Active High	G – Tray Package R – Tape and Reel Package

2. ABSOLUTE MAXIMUM RATINGS

PARAMETER	DESCRIPTION	MIN	TYP	MAX	UNITS
Continuous Input Voltage		-0.3	-	15	V
Voltage on SEQ, SYNC, VS+ terminal		-	-	7	V
Voltage on CLK, DATA, SMBALERT Terminal		-	-	3.6	V
Operating Ambient Temperature	See Thermal Considerations section	-40	-	85	°C
Storage Temperature		-55	-	125	°C
Altitude		-	-	4000	m

NOTE: Stresses in excess of the absolute maximum ratings can cause permanent damage to the device. These are absolute stress ratings only, functional operation of the device is not implied at these or any other conditions in excess of those given in the operations sections of the data sheet. Exposure to absolute maximum ratings for extended periods can adversely affect the device reliability.

3. INPUT SPECIFICATIONS

All specifications are typical at 25°C unless otherwise stated.

PARAMETER		DESCRIPTION	MIN	TYP	MAX	UNIT
Operating Input Voltage			3	-	14.4	V
Input Current (full loa	ad)	$V_{IN} = 3$ to 14.4 V	-	-	2.8	Α
Input Current V _{o, set} = 0.6 V		$V_{IN} = 12 \text{ VDC}, I_O = 0, \text{ module enabled}$	-	17.5	-	mA
(no load)	$V_{o, set} = 5 V$	VIN = 12 VDC, IO = 0, Module enabled	-	43	-	mA
Input Stand-by Curre	ent	$V_{\text{IN}} = 12 \text{ VDC}$, module disabled	-	6.4	-	mA
Input Reflected Ripple Current (pk-pk)		 5 Hz to 20 MHz, 1 µH source impedance; V_{IN} =0 to 14 V, I_O = I_{O, max} See Test Configurations 	-	100	-	mA
I ² t Inrush Current Transient			-	-	1	A^2s
Input Ripple Rejection	on (120 Hz)		-	-57	-	dB

Note: Unless otherwise indicated, specifications apply over entire operating input voltage range, resistive load, and temperature conditions.



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4. OUTPUT SPECIFICATIONS

PARAMETER		DESCRIPTION	MIN	TYP	MAX	UNIT
Output Voltage Set Point		With 0.1% tolerance for external resistor used to set output voltage	-1.0	-	1.0	%V _{o, set}
Output Voltage		Over entire operating input voltage range, resistive load, and temperature conditions until end of life	-3.0	-	3.0	$\%V_{o,set}$
Output Voltage Overshoot			-	-	3.0	%V _{o, set}
Power Management Bus A Output Voltage Range	•		-25	0	25	$%V_{o,set}$
Power Management Bus O Voltage Adjustment Step S	•		-	0.4	-	$%V_{o, set}$
Adjustment Range		Selected by an external resistor Some output voltages may not be possible depending on the input voltage – see Feature Descriptions Section	0.6	-	5.5	V
Remote Sense Range			-	-	0.5	V
Load Description	$V_{O} \geq 2.5 \text{ V}$	l l tol	-	-	10	mV
Load Regulation	$V_{\text{O}} < 2.5 \; \text{V}$	Io=Io, min to Io, max	-	-	10	mV
1: B 1:	V _O ≥ 2.5 V	V _{IN} =V _{IN} , min to V _{IN} , max	-	-	0.4	%V _{o, set}
Line Regulation	$V_{\text{O}} < 2.5 \text{ V}$	VIN=VIN, min tO VIN, max		-	5	mV
Temperature Regulation		T _{ref} =T _{A, min} to T _{A, max}	-	-	0.4	%V _{o, set}
Ripple and Noise (Pk-Pk)		5 Hz to 20 MHz BW, $V_{IN} = V_{IN}$, nom and $I_O = I_{O, min}$ to	-	50	100	mV
Ripple and Noise (RMS)		$I_{O,max,}$ Co = 0.1 μF // 22 μF ceramic capacitors	-	20	38	mV
Output Current		In either sink or source mode	0	-	3	Α
Output Current Limit Incept	tion	Current limit does not operate in sink mode	-	270	-	%I _{o, max}
Output Short-Circuit Currer	nt	Vo ≤ 250 mV, Hiccup Mode	-	268	-	mArms
	ESR ≥ 1 mΩ	Without the Tunable Loop™	10	-	22	μF
Output Capacitance	ESR ≥ 0.15 mΩ	With the Tunable Loop TM	22	-	1000	μF
	ESR ≥ 10 mΩ	With the Tunable Loop TM	22	-	3000	μF
Turn-On Delay Times		Case 1: On/Off input is enabled and then input power is applied (delay from instant at which $V_{IN}=V_{IN,\ min}$ until $V_o=10\%$ of $V_{o,\ set}$)	-	0.4	-	ms
$(V_{IN} = V_{IN}, nom, I_O = I_{O, max}, V_{Steady state})$	∕o to within ±1% of	Case 2: Input power is applied for at least one second and then the On/Off input is enabled (delay from instant at which Von/Off is enabled until $V_o = 10\%$ of $V_{o,\rm set}$)	-	0.4	-	ms
Output Voltage Rise Time		Time for Vo to rise from 10% of $V_{o,set}$ to 90% of $V_{o,set}$	-	2.4	-	ms

Notes:

- 1. External capacitors may require using the new Tunable LoopTM feature to ensure that the module is stable as well as getting the best transient response (See the Tunable LoopTM section for details).
- 2. Unless otherwise indicated, specifications apply over entire operating input voltage range, resistive load, and temperature conditions.



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5. GENERAL SPECIFICATIONS

Vo = 0.8 V Vo = 1.2 V Vo = 0.2 V Vo = 0.3 3 V Vo = 0.5 V Vo = 0.3 3 V Vo = 0.5 V	PARAMETER		DESCRIPTION	MIN	TYP	MAX	UNIT
March Marc		Vo = 0.6 V		-	72.4	-	%
Female		Vo = 1.2 V		-	83.2	-	%
Vo = 2.5 V Vo = 3.0 V Vo = 5.0 V Vo	T#ining av	Vo = 1.8 V	V _{in} = 12 VDC, T _A = 25 °C	-	87.5	-	%
Vo = 5.0 V Vo	Efficiency	Vo = 2.5 V	$I_o = I_{o, \; max, \;} V_o = V_{o, \; set}$	-	90.1	-	%
Switching Frequency Since		Vo = 3.3 V		-	91.9	-	%
Synchronization Frequency Range 510 - 720 kHz High-Level Input Voltage 2.0 - 0 V Low-Level Input Voltage - 0 0.4 V Input Current, SYNC - 0 0.0 - 0 0.0 Power Management Bus Over Temperature Warning Threshold stockout Thresholds Power Management Bus Adjustable Input Under Voltage Lockout Thresholds Preshold for PGOOD Application of Adjustable Input Under Voltage Input Under-voltage Lockout Hysteresis - 0 0.3 - 0 Turn-off Threshold Hysteresis - 0 0.3 - 0 Turn-off Threshold Hysteresis - 0 0.3 - 0 Power-Up: 2 V/ms Power-Up: 2 V/ms Power-Down: 2 V/ms Over-voltage Threshold for PGOOD OFF Under-voltage Threshold for PGOOD OFF PGOOD ON Over-voltage Threshold for PGOOD OFF Pulldown Resistance of PGOOD pin Sink Current Capability into PGOOD pin Sink Current Capability into PGOOD pin - 0 0.96 - 0 Weight Calculated MTBF (Io = 0.8 Io, ms, Ta = 40°C) Telecordia 19,508,839 - 0 hours Dimensions (L × W × H) Dimen		Vo = 5.0 V		-	94.0	-	%
High-Level Input Voltage	Switching Frequency			-	600	-	kHz
Low-Level Input Voltage	Synchronization Freq	uency Range		510	-	720	kHz
Input Current, SYNC	High-Level Input Volta	age		2.0	-	-	V
Minimum Pulse Width, SYNC 100 - - ns	Low-Level Input Volta	age		-	-	0.4	V
Maximum SYNC Rise Time 100 - - ns Over Temperature Protection - 150 - °C Power Management Bus Over Temperature Warning Threshold Over temperature Warning – Warning may not activate before alarm and unit may shutdown before warning - 130 - °C Power Management Bus Adjustable Input Under Voltage Total Cloud Thresholds 2.5 - 14 V Resolution of Adjustable Input Under Voltage Threshold Hysteresis - - 2.71 - V Input Under-voltage Lockout Turn-on Threshold Hysteresis - - 2.41 - V Input Under-voltage Threshold Hysteresis - - 2.41 - V Tracking Accuracy Power-Down: 2 V/ms Power-Down: 2 V/ms V _{in, min} to V _{in, maxi} I _{o, min} to I _{o, max} , V _{seq} < V _o - - 100 mV PGOOD ON Over-voltage Threshold for PGOOD ON Under-voltage Threshold for PGOOD OFF Pulldown Resistance of PGOOD off PGOOD OFF Pulldown Resistance of PGOOD pin Sink Current Capability into PGOOD pin Signal Interface Open Drain, Vsupply ≤ 5 VDC - 90 - %Vo, set MTBF Calculated MTBF (lo = 0	Input Current, SYNC			-	-	100	nA
Over Temperature Protection - 150 - °C Power Management Bus Over Temperature Warning Threshold Over temperature Warning – Warning may not activate before alarm and unit may shutdown before warning - 130 - °C Power Management Bus Adjustable Input Under Voltage Threshold's Resolution of Adjustable Input Under Voltage Threshold 2.5 - 14 V Turn-on Threshold Input Under Voltage Threshold Hysteresis - 2.71 - V Input Under-voltage Lockout Power-Up: 2 V/ms - 2.41 - V Input Under-voltage Threshold for Power-Down: 2 V/ms - 0.3 - V Over-voltage Threshold for PGOOD ON Over-voltage Threshold for PGOOD OFF Under-voltage Threshold for PGOOD OFF Pulldown Resistance of PGOOD DOFF Pulldown Resistance of PGOOD pin Sink Current Capability into PGOOD pin Signal Interface Open Drain, Vsupply ≤ 5 VDC - 90 - %Vo. set Weight MTBF Calculated MTBF (loc 0.8 lo. mas, Ta=40°C) Telecordia Issue 2 Method 1 Case 3 - 19,508,839 - hours	Minimum Pulse Width	n, SYNC		100	-	-	ns
Power Management Bus Over Temperature Warning Threshold Very Temperature Warning Threshold Power Management Bus Adjustable Input Under Voltage Lockout Thresholds Resolution of Adjustable Input Under Voltage Lockout Thresholds Power Management Bus Adjustable Input Under Voltage Lockout Thresholds Power Management Bus Adjustable Input Under Voltage Cockout Thresholds Power Management Bus Adjustable Input Under Voltage Threshold Power Management Bus Adjustable Input Voltage In	Maximum SYNC Rise	Time		100	-	-	ns
Power Management Bus Over Temperature Warning Threshold may not activate before alarm and unit may shutdown before warning - 130 - °C Power Management Bus Adjustable Input Under Voltage Lockout Thresholds 2.5 - 14 V Resolution of Adjustable Input Under Voltage Threshold - 2.71 - V Input Under-voltage Lockout Turn-off Threshold Hysteresis - 2.71 - V Lockout Turn-off Threshold Hysteresis - 0.3 - V Lockout Power-Up: 2 V/ms - 0.3 - V Power-Up: 2 V/ms Power-Down: 2 V/ms - 0.3 - V Power-Up: 2 V/ms Power-Down: 2 V/ms Powe	Over Temperature Pro	otection		-	150	-	°C
Voltage Lockout Thresholds 2.5 - 14 V Resolution of Adjustable Input Under Voltage Threshold Input Under-voltage Lockout Turn-on Threshold - - - 500 mV Tracking Accuracy Power-Up: 2 V/ms Power-Up: 2 V/ms - 0.3 - V Power-Up: 2 V/ms Power-Down: 2 V/ms Over-voltage Threshold for PGOOD ON Under-voltage Threshold for PGOOD OFF Under-voltage Threshold for PGOOD OFF Under-voltage Threshold for PGOOD ON Under-voltage Threshold for PGOOD ON Under-voltage Threshold for PGOOD OFF Pulldown Resistance of PGOOD pin Sink Current Capability into PGOOD pin Signal Interface Open Drain, Vsupply ≤ 5 VDC - - 110 - %Vo, set Weight - - - - 5 mA Dimensions (L × W × H) Calculated MTBF (lo = 0.8 lo, max, Ta = 40°C) Telecordia Issue 2 Method 1 Case 3 - - 19,508,839 - hours		Bus Over Temperature	may not activate before alarm and unit	-	130	-	°C
Turn-on Threshold Turn-on Threshold Turn-on Threshold Turn-off	Voltage Lockout Thre	sholds	,	2.5	-	14	V
Turn-off Threshold Hysteresis -				-	-		
Lockout Furn-ort Threshold - 2.41 - V Tracking Accuracy Power-Up: 2 V/ms Power-Up: 2 V/ms Vin, min to Vin, max; Io, min to Io, max, Vseq < Vo	Input Under-voltage			-		-	
Tracking Accuracy $ \begin{array}{c} $				-		-	
Tracking Accuracy Power-Down: 2 V/ms Over-voltage Threshold for PGOOD ON Over-voltage Threshold for PGOOD OFF Under-voltage Threshold for PGOOD ON Over-voltage Threshold for PGOOD OFF Under-voltage Threshold for PGOOD ON Under-voltage Threshold for PGOOD OFF Pulldown Resistance of PGOOD pin Sink Current Capability into PGOOD pin Weight MTBF Calculated MTBF ($lo = 0.8 lo, max, TA = 40^{\circ}C$) Telecordia lssue 2 Method 1 Case 3 O.48 x 0.48 x 0.246 inch		•		-	0.3		
$PGOOD (Power Good) \begin{tabular}{l l l l l l l l l l l l l l l l l l l $	Tracking Accuracy	·	$V_{\text{in, min}}$ to $V_{\text{in, max}};I_{\text{o, min}}$ to $I_{\text{o, max}},V_{\text{seq}} < V_{\text{o}}$	-	-		
For PGOOD ON Over-voltage Threshold for PGOOD OFF Under-voltage Threshold for PGOOD OFF Under-voltage Threshold for PGOOD ON Under-voltage Threshold for PGOOD ON Under-voltage Threshold for PGOOD ON Under-voltage Threshold for PGOOD OFF Pulldown Resistance of PGOOD pin Sink Current Capability into PGOOD pin Weight Calculated MTBF (Io = 0.8 Io, max, TA = 40°C) Telecordia Issue 2 Method 1 Case 3 0.48 x 0.48 x 0.246 inch				-	-	100	mV
PGOOD (Power Good) OFF Under-voltage Threshold for PGOOD ON Under-voltage Threshold for PGOOD ON Under-voltage Threshold for PGOOD OFF Pulldown Resistance of PGOOD pin Sink Current Capability into PGOOD pin Sink Current Capability		for PGOOD ON		-	108	-	%V _{o, set}
PGOOD (Power Good) Inder-voltage Threshold for PGOOD ON Under-voltage Threshold for PGOOD OFF Pulldown Resistance of PGOOD pin Sink Current Capability into PGOOD pin Weight Calculated MTBF (lo = 0.8 lo, max, TA = 40°C) Telecordia Issue 2 Method 1 Case 3 O.48 x 0.48 x 0.246 PGOOD ON Signal Interface Open Drain, Vsupply \leq 5 VDC - 90 - 90 - %Vo, set PVo, set PVo, set PVo, set PGOOD on PGOOD pin - 190 -				-	110	-	$\text{\%V}_{o, set}$
Good) Under-voltage Threshold for PGOOD OFF Pulldown Resistance of PGOOD pin Sink Current Capability into PGOOD pin Weight Calculated MTBF (lo = 0.8 lo, max, TA = 40°C) Telecordia Issue 2 Method 1 Case 3 O.48 x 0.48 x 0.246 inch	PGOOD (Power	9	Signal Interface Open Drain.	-	92	-	$%V_{o,set}$
PGOOD pin Sink Current Capability into PGOOD pin Weight - 0.96 - g Calculated MTBF (lo = 0.8 lo, max, T _A = 40°C) Telecordia Issue 2 Method 1 Case 3 Dimensions (L × W × H)		Under-voltage Threshold	1 ,	-	90	-	%V _{o, set}
into PGOOD pin - 5 mA Weight - 0.96 - g MTBF Calculated MTBF (Io = 0.8 Io, max, TA = 40°C) Telecordia Issue 2 Method 1 Case 3 - 19,508,839 - hours Dimensions (L × W × H) 0.48 x 0.48 x 0.246 inch				-	-	50	Ω
Calculated MTBF $ (lo = 0.8 \ lo, _{max}, T_A = 40^{\circ}C) \ Telecordia \\ lssue 2 \ Method 1 \ Case 3 $ - $19,508,839$ - hours $ 0.48 \times 0.48 \times 0.246 $ inch		Sink Current Capability		-		5	mA
MTBF	Weight			-	0.96	-	g
Dimensions (L × W × H)	MTBF		($I_O = 0.8 I_{O, max}$, $T_A = 40$ °C) Telecordia	-	19,508,839	-	hours
	Dimensions (L., W.,	LI\			0.48 x 0.48 x 0.2	46	inch
	Dimensions (L x W x	П)		1	2.19 x 12.19 x 6	.25	mm

Note: Unless otherwise indicated, specifications apply over entire operating input voltage range, resistive load, and temperature conditions.



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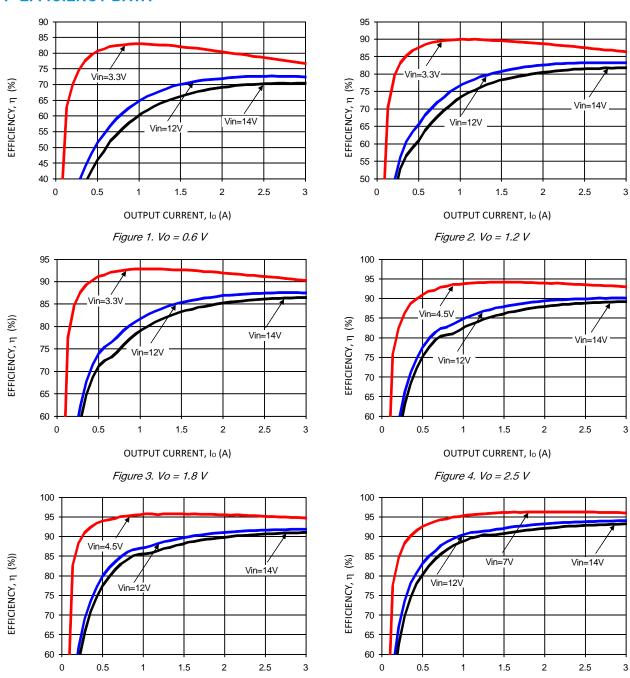
6. DIGITAL INTERFACE SPECIFICATIONS

PARAMETER	DESCRIPTION	MIN	TYP	MAX	UNIT
Power Management Bus Signal Inte	rface Characteristics				
Input High Voltage (CLK, DATA)		2.1	-	3.6	V
Input Low Voltage (CLK, DATA)		-	-	0.8	V
Input High Level Current (CLK, DATA)		-10	-	10	μΑ
Input Low Level Current (CLK, DATA)		-10	-	10	μΑ
Output Low Voltage (CLK, DATA, SMBALERT#)	I _{out} = 2 mA	-	-	0.4	V
Output High Level Open Drain Leakage Current (DATA, SMBALERT#)	$V_{out} = 3.6 \text{ V}$	0	-	10	μΑ
Pin Capacitance		-	0.7	-	pF
Power Management Bus Operating Frequency Range		10	-	400	kHz
Data Setup Time		250	-	-	ns
Data Hold Time	Receive Mode	0	-	-	ns
Data Florid Time	Transmit Mode	300	-	-	ns
Measurement System Characteristic	cs				
Read Delay Time		153	192	231	μs
Output Current Measurement Range		0	-	18	Α
Output Current Measurement Resolution		62.5	-	-	mA
Output Current Measurement Gain Accuracy		-	-	±5	%
Output Current Measurement Offset		-	-	0.1	Α
Vout Measurement Range		0	-	5.5	V
Vout Measurement Resolution		-	15.625	-	mV
Vout Measurement Gain Accuracy		-15	-	15	%
V _{OUT} Measurement Offset		-3	-	3	%
V _{IN} Measurement Range		3	-	14.4	V
V _{IN} Measurement Resolution		-	32.5	-	mV
V _{IN} Measurement Gain Accuracy		-15	-	15	%
V _{IN} Measurement Offset		-5.5	-	1.4	LSB



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7. EFFICIENCY DATA





OUTPUT CURRENT, Io (A)

Figure 5. Vo = 3.3 V

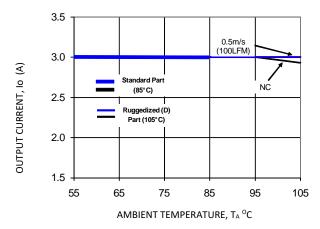
OUTPUT CURRENT, Io (A)

Figure 6. Vo = 5.0 V

OUTPUT CURRENT, Io (A)

OUTPUT CURRENT, Io (A)

8. THERMAL DERATING CURVE





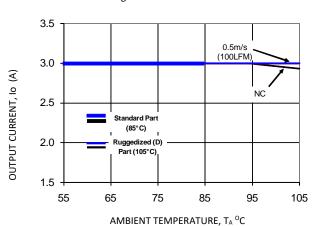


Figure 9. Vo = 1.8 V

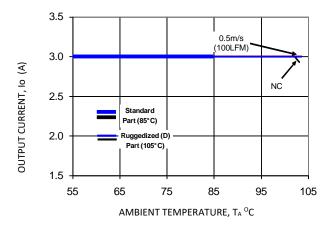


Figure 11. Vo = 3.3 V

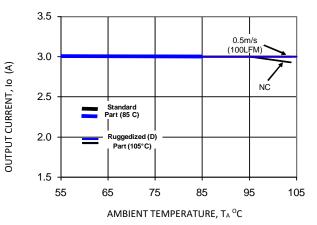


Figure 8. Vo = 1.2 V

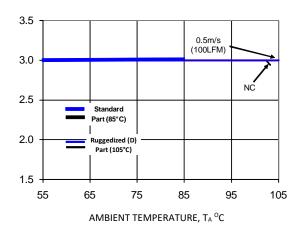


Figure 10. Vo = 2.5 V

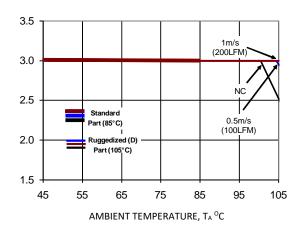


Figure 12. Vo = 5.0 V



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9. RIPPLE AND NOISE WAVEFORM

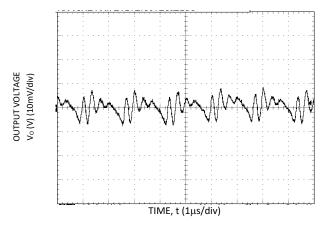


Figure 13. Vo = 0.6 V, Io = Io, max

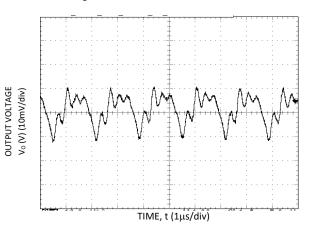


Figure 15. Vo = 1.8 V, Io = Io, max

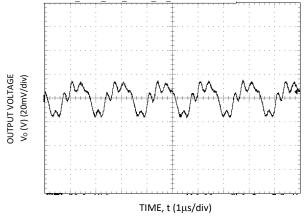


Figure 17. Vo = 3.3 V, Io = Io, max

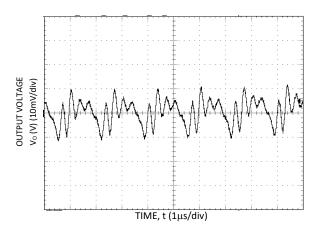


Figure 14. Vo = 1.2 V, Io = Io, max

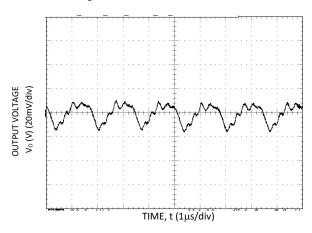


Figure 16. Vo = 2.5 V, Io = Io, max

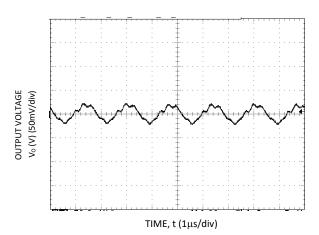


Figure 18. Vo = 5.0 V, Io = Io, max

Note: $Co = 10 \mu F$ ceramic, $V_{IN} = 12 V$.



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10. TRANSIENT RESPONSE WAVEFORMS

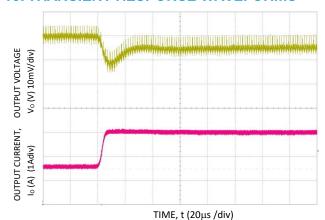
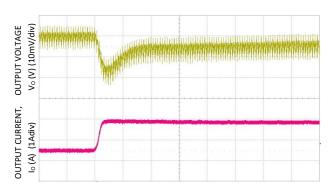


Figure 19. Transient Response to Dynamic Load Change from 50% to 100% at 12 Vin, Cout = 1x 47 μF + 2x 330 μF, CTune = 27 nF, RTune = 180 Ω. Vo = 0.6 V



TIME, t (20µs /div)

Figure 21. Transient Response to Dynamic Load Change from 50% to 100% at 12 Vin, Cout= 1x 47 μ F +1x 330 μ F, CTune = 10 nF & RTune = 267 Ω . Vo = 1.8 V

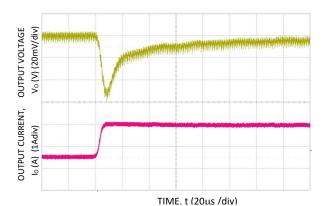
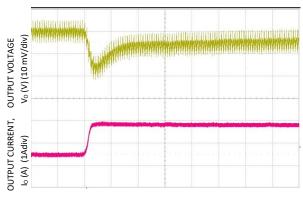


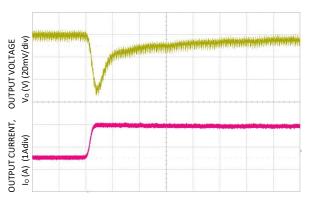
Figure 23. Transient Response to Dynamic Load Change from 50% to 100% at 12 Vin, Cout = 2x 47 μF, CTune = 2200 pF & RTune = 267 Ω. Vo = 3.3 V





TIME, t (20µs /div)

Figure 20. Transient Response to Dynamic Load Change from 50% to 100% at 12 Vin, Cout = 1x 47 μF+1x 330 μF, CTune = 10 nF & RTune = 267 Ω. Vo = 1.2 V



TIME, t (20µs /div)

Figure 22. Transient Response to Dynamic Load Change from 50% to 100% at 12 Vin, Cout = 2x 47 μ F, CTune = 2700 pF & RTune = 267Ω . Vo = 2.5 V

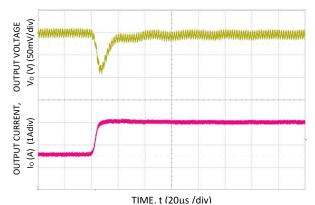


Figure 24. Transient Response to Dynamic Load Change from 50% to 100% at 12 Vin, Cout= 1x 47 μ F, CTune = 820 pF & RTune = 267 Ω . Vo = 5.0 V

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11. STARTUP & TIME

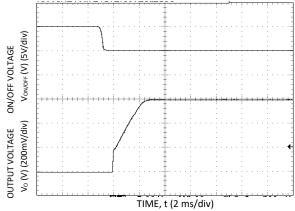


Figure 25. Start-up Using On/Off Voltage (lo = lo,max), Vo = 0.6 V

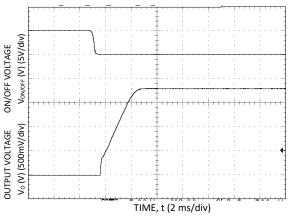


Figure 27. Start-up Using On/Off Voltage (Io = Io,max), Vo = 1.8 V

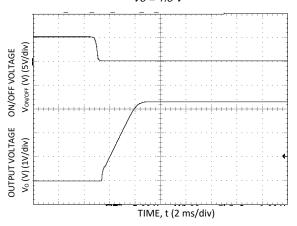


Figure 29. Start-up Using On/Off Voltage (Io = Io,max), Vo = 3.3 V

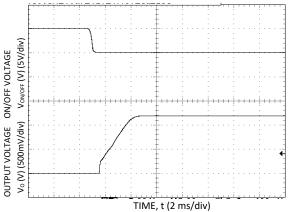


Figure 26. Start-up Using On/Off Voltage (lo = lo,max), Vo = 1.2 V

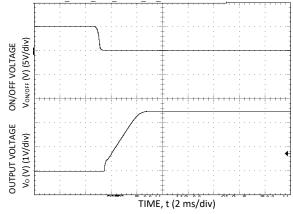


Figure 28. Start-up Using On/Off Voltage (lo = lo, max), Vo = 2.5 V

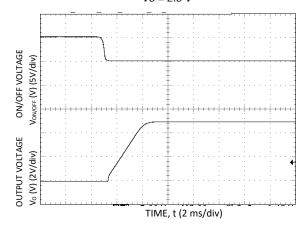
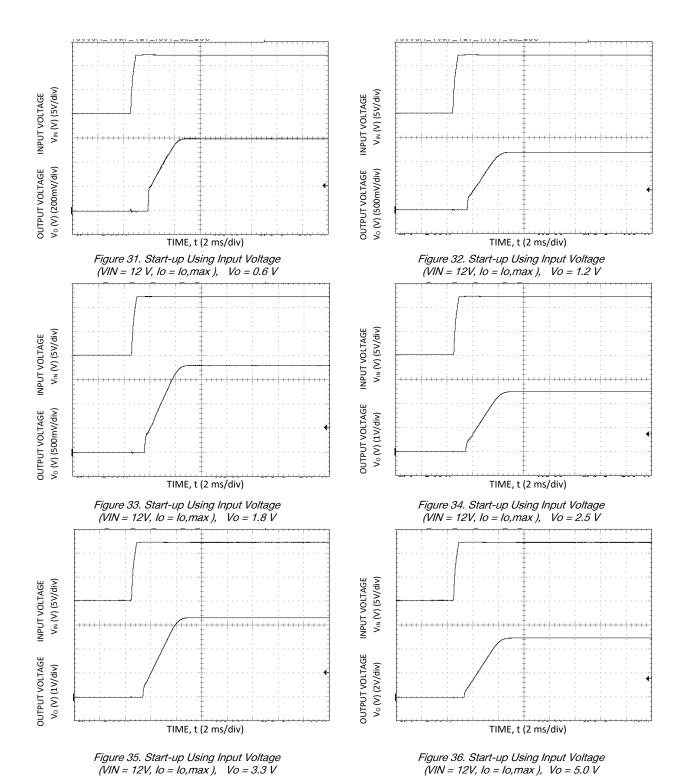


Figure 30. Start-up Using On/Off Voltage (lo = lo,max), Vo = 5.0 V



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12. INPUT FILTERING

The SLDN-03D1Ax module should be connected to a low ac-impedance source. A highly inductive source can affect the stability of the module. An input capacitance must be placed directly adjacent to the input pin of the module, to minimize input ripple voltage and ensure module stability. High frequency switching noise can be reduced by using suitable decoupling ceramic caps. Refer to AN04-006 and AN04-002 for more guidelines.

To minimize input voltage ripple, ceramic capacitors are recommended at the input of the module. Figure 37 shows the input ripple voltage for various output voltages at 3A of load current with $1x22 \mu F$ or $2x22 \mu F$ ceramic capacitors and an input of 12V.

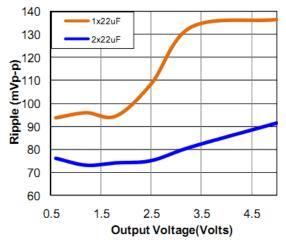


Figure 37.

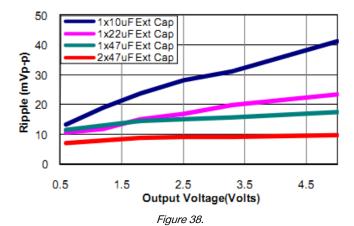
Note: Input ripple voltage for various output voltages with 2x22 μF or 3x22 μF ceramic capacitors at the input (3 A load). Input voltage is 12 V.



13. OUTPUT FILTERING

These modules are designed for low output ripple voltage and will meet the maximum output ripple specification with $0.1~\mu F$ ceramic and $22~\mu F$ ceramic capacitors at the output of the module. However, additional output filtering may be required by the system designer for a number of reasons. First, there may be a need to further reduce the output ripple and noise of the module. Second, the dynamic response characteristics may need to be customized to a particular load step change.

To reduce the output ripple and improve the dynamic response to a step load change, additional capacitance at the output can be used. Low ESR polymer and ceramic capacitors are recommended to improve the dynamic response of the module. Figure 38 provides output ripple information for different external capacitance values at various Vo and a full load current of 3 A. For stable operation of the module, limit the capacitance to less than the maximum output capacitance as specified in the electrical specification table. Optimal performance of the module can be achieved by using the Tunable LoopTM feature described later in this data sheet.



Note: Output ripple voltage for various output voltages with external 1x10 μ F, 1x22 μ F, 1x47 μ F or 2x47 μ F ceramic capacitors at the output (3 A load). Input voltage is 12 V.

14. SAFETY CONSIDERATIONS

For safety agency approval the power module must be installed in compliance with the spacing and separation requirements of the end-use safety agency standards, i.e., IEC/EN 62368-1.

For the converter output to be considered meeting the requirements of electrical energy source class 1 (ES1), the input must meet ES1 requirements.

The input to these units is to be provided with a slow-blow fuse with a maximum rating of 5 A in the positive input lead.



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15. REMOTE ON/OFF

PARAMETER		DESCRIPTION	MIN	TYP	MAX	UNIT
Signal Low (Unit On)	Active Low	The remote on/off pin open Unit on	-0.2	-	0.6	V
Signal High (Unit Off)	Active Low	The remote on/off pin open, Unit on	2.0	-	Vin, max	V
Signal Low (Unit Off)	Activo Lligh	The remote on/off pin open Unit on	-0.2	-	0.6	V
Signal High (Unit On)	Active High	The remote on/off pin open, Unit on	2.0	-	Vin, max	V

The SLDN-03D1Ax module can be turned ON and OFF either by using the ON/OFF pin or through the Power management bus interface (Digital). The module can be configured in a number of ways through the Power management bus interface to react to the two ON/OFF inputs:

- · Module ON/OFF can be controlled only through the analog interface (digital interface ON/OFF commands are ignored).
- · Module ON/OFF can be controlled only through the Power management bus interface (analog interface is ignored).
- Module ON/OFF can be controlled by either the analog or digital interface.

The default state of the module (as shipped from the factory) is to be controlled by the analog interface only. If the digital interface is to be enabled, or the module is to be controlled only through the digital interface, this change must be made through the Power management bus. These changes can be made and written to non-volatile memory on the module so that it is remembered for subsequent use.



16. ANALOG ON/OFF

The SLDN-03D1Ax modules feature an On/Off pin for remote On/Off operation. Two On/Off logic options are available. In the Positive Logic On/Off option, (device code suffix "0" – see Ordering Information), the module turns ON during a logic High on the On/Off pin and turns OFF during a logic Low. With the Negative Logic On/Off option, (device code suffix "L" – see Ordering Information), the module turns OFF during logic High and ON during logic Low. The On/Off signal should be always referenced to ground. For either On/Off logic option, leaving the On/Off pin disconnected will turn the module ON when input voltage is present. For positive logic modules, the circuit configuration for using the On/Off pin is shown in Figure 39. When the external transistor Q2 is in the OFF state, the internal transistor Q1 is turned ON, and the internal PWM #Enable signal is pulled low causing the module to be ON. When transistor Q2 is turned ON, the On/Off pin is pulled low and the module is OFF. A suggested value for Rpullup is 20kO.

For negative logic On/Off modules, the circuit configuration is shown in Fig. 40. The On/Off pin should be pulled high with an external pull-up resistor (suggested value for the 3V to 14V input range is $20~\text{k}\Omega$). When transistor Q2 is in the OFF state, the On/Off pin is pulled high, transistor Q1 is turned ON and the module is OFF. To turn the module ON, Q2 is turned ON pulling the On/Off pin low, turning transistor Q1 OFF resulting in the PWM Enable pin going high.

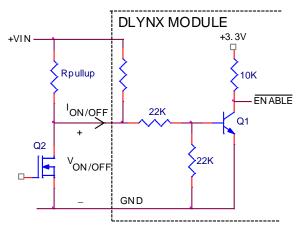


Figure 39.
Circuit configuration for using positive On/Off logic

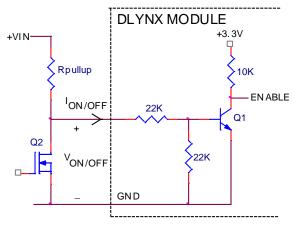


Figure 40.
Circuit configuration for using negative On/Off logic



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17. DIGITAL ON/OFF

Please see the Digital Feature Descriptions section.

18. MONOTONIC START-UP AND SHUTDOWN

The SLDN-03D1Ax module has monotonic start-up and shutdown behavior for any combination of rated input voltage, output current and operating temperature range.

19. STARTUP INTO PRE-BIASED OUTPUT

The SLDN-03D1Ax module can start into a pre-biased output as long as the pre-bias voltage is 0.5 V less than the set output voltage.

20. ANALOG OUTPUT VOLTAGE PROGRAMMING

The output voltage of the module is programmable to any voltage from 0.6 VDC to 5.5 VDC by connecting a resistor between the Trim and SIG_GND pins of the module. Certain restrictions apply on the output voltage set point depending on the input voltage. These are shown in the Output Voltage vs. Input Voltage Set Point Area plot in Fig. 41. The Upper Limit curve shows that for output voltages lower than 1 V, the input voltage must be lower than the maximum of 14.4 V. The Lower Limit curve shows that for output voltages higher than 0.6 V, the input voltage needs to be larger than the minimum of 3 V.

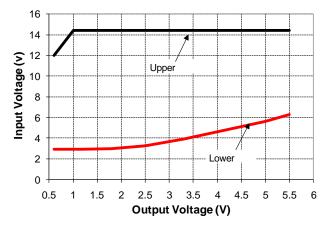


Figure 41.

Output Voltage vs. Input Voltage Set Point Area plot showing limits where the output voltage can be set for different input voltages.



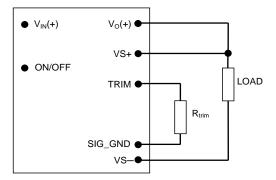


Figure 42.

CAUTION: Do not connect SIG_GND to GND elsewhere in the layout.

Circuit configuration for programming output voltage using an external resistor.

21. OUTPUT TRIM EQUATIONS

Without an external resistor between Trim and SIG_GND pins, the output of the module will be 0. 6 VDC.To calculate the value of the trim resistor, Rtrim for a desired output voltage, should be as per the following equation:

$$Rtrim = \left\lceil \frac{12}{(Vo - 0.6)} \right\rceil k\Omega$$

Rtrim is the external resistor in $k\boldsymbol{\Omega}$

Vo is the desired output voltage.

Table 1 provides Rtrim values required for some common output voltages.

VO, SET (V)	RTRIM (KΩ)
0.6	Open
0.9	40
1.0	30
1.2	20
1.5	13.33
1.8	10
2.5	6.316
3.3	4.444
5.0	2.727

Table 1



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22. DIGITAL OUTPUT VOLTAGE ADJUSTMENT

Please see the Digital Feature Descriptions section.

23. REMOTE SENSE

The SLDN-03D1Ax power module has a Remote Sense feature to minimize the effects of distribution losses by regulating the voltage between the sense pins (VS+ and VS-). The voltage drops between the sense pins and the VOUT and GND pins of the module should not exceed 0.5V.

24. ANALOG VOLTAGE MARGINING

Output voltage margining can be implemented in the module by connecting a resistor, Rmargin-up, from the Trim pin to the ground pin for margining-up the output voltage and by connecting a resistor, Rmargin-down, from the Trim pin to output pin for margining-down. Figure 43 shows the circuit configuration for output voltage margining. Please consult your local Bel Power technical representative for additional details.

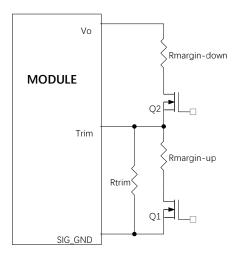


Figure 43.
Circuit Configuration for margining Output voltage

25. DIGITAL OUTPUT VOLTAGE MARGINING

Please see the Digital Feature Descriptions section.



26. OUTPUT VOLTAGE SEQUENCING

The SLDN-03D1Ax module includes a sequencing feature, EZ-SEQUENCE that enables users to implement various types of output voltage sequencing in their applications. This is accomplished via an additional sequencing pin. When not using the sequencing feature, leave it unconnected.

The voltage applied to the SEQ pin should be scaled down by the same ratio as used to scale the output voltage down to the reference voltage of the module. This is accomplished by an external resistive divider connected across the sequencing voltage before it is fed to the SEQ pin as shown in Fig. 44. In addition, a small capacitor (suggested value 100pF) should be connected across the lower resistor R1.

For SLDN-03D1Ax modules, the minimum recommended delay between the ON/OFF signal and the sequencing signal is 10ms to ensure that the module output is ramped up according to the sequencing signal. This ensures that the module soft-start routine is completed before the sequencing signal is allowed to ramp up.

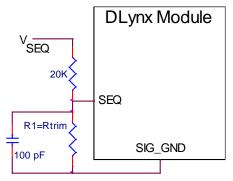


Figure 44.
Circuit showing connection of the sequencing signal to the SEQ pin

When the scaled down sequencing voltage is applied to the SEQ pin, the output voltage tracks this voltage until the output reaches the set-point voltage. The final value of the sequencing voltage must be set higher than the set-point voltage of the module. The output voltage follows the sequencing voltage on a one-to-one basis. By connecting multiple modules together, multiple modules can track their output voltages to the voltage applied on the SEQ pin.

To initiate simultaneous shutdown of the modules, the SEQ pin voltage is lowered in a controlled manner. The output voltage of the modules tracks the voltages below their set-point voltages on a one-to-one basis. A valid input voltage must be maintained until the tracking and output voltages reach ground potential. Note that in all digital Bel series of modules, the Power management bus Output Undervoltage Fault will be tripped when sequencing is employed. This will be detected using the STATUS_WORD and STATUS_VOUT Power management bus commands. In addition, the SMBALERT# signal will be asserted low as occurs for all faults and warnings. To avoid the module shutting down due to the Output Undervoltage Fault, the module must be set to continue operation without interruption as the response to this fault (see the description of the power management bus command VOUT_UV_FAULT_RESPONSE for additional information).



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27. OVER CURRENT PROTECTION

To provide protection in a fault (output overload) condition, the unit is equipped with internal current limiting circuitry and can endure current limiting continuously. At the point of current limit inception, the unit enters hiccup mode. The unit operates normally once the output current is brought back into its specified range.

28. DIGITAL ADJUSTABLE OVERCURRENT WARNING

Please see the Digital Feature Descriptions section.

29. OVER TEMPERATURE PROTECTION

To provide protection in a fault condition, the unit is equipped with a thermal shutdown circuit. The unit will shut down if the overtemperature threshold of 150°C (typ) is exceeded at the thermal reference point Tref. Once the unit goes into thermal shutdown it will then wait to cool before attempting to restart.

30. DIGITAL TEMPERATURE STATUS VIA POWER MANAGEMENT BUS

Please see the Digital Feature Descriptions section.

31. DIGITAL ADJUSTABLE OUTPUT OVER AND UNDER VOLTAGE PROTECTION

Please see the Digital Feature Descriptions section.

32. INPUT UNDERVOLTAGE LOCKOUT

At input voltages below the input undervoltage lockout limit, the module operation is disabled. The module will begin to operate at an input voltage above the undervoltage lockout turn-on threshold.

33. DIGITAL ADJUSTABLE INPUT UNDERVOLTAGE LOCKOUT

Please see the Digital Feature Descriptions section.

34. DIGITAL ADJUSTABLE POWER GOOD THERSHOLDS

Please see the Digital Feature Descriptions section.



35. SYNCHRONIZATION

The SLDN-03D1Ax module switching frequency can be synchronized to a signal with an external frequency within a specified range. Synchronization can be done by using the external signal applied to the SYNC pin of the module as shown in Fig. 45, with the converter being synchronized by the rising edge of the external signal. The Electrical Specifications table specifies the requirements of the external SYNC signal. If the SYNC pin is not used, the module should free run at the default switching frequency.

If synchronization is not being used, connect the SYNC pin to GND.

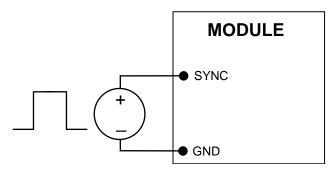


Figure 45.

External source connections to synchronize switching frequency of the module.

36. MEASURING OUTPUT CURRENT, OUTPUT VOLTAGE AND INPUT VOLTAGE

Please see the Digital Feature Descriptions section.

37. DUAL LAYOUT

Identical dimensions and pin layout of Analog and Digital modules permit migration from one to the other without needing to change the layout. To support this, 2 separate Trim Resistor locations have to be provided in the layout. As shown in Fig. 46, for the digital modules, the resistor is connected between the TRIM pad and SGND and in the case of the analog module it is connected between TRIM and GND.

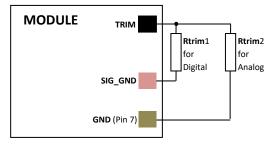


Figure 46.

Caution – For digital modules, do not connect SIG_GND to GND elsewhere in the layout. Layout to support either Analog or Digital on the same pad.



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38. TUNABLE LOOP™

The SLDN-03D1Ax module has a feature that optimizes transient response of the module called Tunable Loop™.

External capacitors are usually added to the output of the module for two reasons: to reduce output ripple and noise (see Figure 38) and to reduce output voltage deviations from the steady-state value in the presence of dynamic load current changes. Adding external capacitance however affects the voltage control loop of the module, typically causing the loop to slow down with sluggish response. Larger values of external capacitance could also cause the module to become unstable.

The Tunable Loop[™] allows the user to externally adjust the voltage control loop to match the filter network connected to the output of the module. The Tunable Loop[™] is implemented by connecting a series R-C between the VS+ and TRIM pins of the module, as shown in Fig. 47. This R-C allows the user to externally adjust the voltage loop feedback compensation of the module.

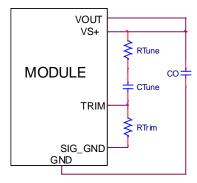


Figure 47.

Circuit diagram showing connection of R_{TUNE} and C_{TUNE} to tune the control loop of the module

Recommended values of R_{TUNE} and C_{TUNE} for different output capacitor combinations are given in Tables 2 and 3. Table 2 shows the recommended values of R_{TUNE} and C_{TUNE} for different values of ceramic output capacitors up to $1000\mu\text{F}$ that might be needed for an application to meet output ripple and noise requirements. Selecting R_{TUNE} and C_{TUNE} according to Table 2 will ensure stable operation of the module. In applications with tight output voltage limits in the presence of dynamic current loading, additional output capacitance will be required. Table 3 lists recommended values of R_{TUNE} and C_{TUNE} in order to meet 2% output voltage deviation limits for some common output voltages in the presence of a 0A to 1.5A step change (50% of full load), with an input voltage of 12V.

Please contact your Bel Power technical representative to obtain more details of this feature as well as for guidelines on how to select the right value of external R-C to tune the module for best transient performance and stable operation for other output capacitance values.

Со	1x47 μF	2x47 μF	4x47 μF	6x47 μF	10x47 μF
R _{TUNE}	270 Ω	220 Ω	180 Ω	180 Ω	180 Ω
CTUNE	1500 pF	1800 pF	3300 pF	4700 pF	4700 pF

Table 2. General recommended values of of R_{TUNE} and C_{TUNE} for Vin = 12 V and various external ceramic capacitor combinations

Vo	5 V	3.3 V	2.5 V	1.8 V	1.2 V	0.6 V
Со	1x47 μF	1x47 μF	2x47 μF	1x330 μF Polymer	1x330 μF Polymer	2x330 μF Polymer
R _{TUNE}	270 Ω	220 Ω	180 Ω	180 Ω	180 Ω	180 Ω
C _{TUNE}	1500 pF	1800 pF	3300 pF	8200 pF	8200 pF	33 nF
ΔV	68 mV	60 mV	37 mV	18 mV	18 mV	10 mV

Table 3. Recommended values of R_{TUNE} and C_{TUNE} to obtain transient deviation of 2% of Vout for a 1.5 A step load with Vin = 12 V

Note: The capacitors used in the Tunable Loop tables are 47 μ F/3 m Ω ESR ceramic and 330 μ F/12 m Ω ESR polymer capacitors.



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39. POWER MANAGEMENT BUS INTERFACE CAPABILITY

The SLDN-03D1Ax modules have a Power management bus interface that supports both communication and control. The modules support a subset of version 1.1 of the specification (see Table 6 for a list of the specific commands supported). Most module parameters can be programmed using Power management bus and stored as defaults for later use.

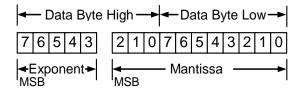
All communication over the module Power management bus interface must support the Packet Error Checking (PEC) scheme. The Power management bus master must generate the correct PEC byte for all transactions, and check the PEC byte returned by the module.

The module also supports the SMBALERT response protocol whereby the module can alert the bus master if it wants to talk. For more information on the SMBus alert response protocol, see the System Management Bus (SMBus) specification.

The module has non-volatile memory that is used to store configuration settings. Not all settings programmed into the device are automatically saved into this non-volatile memory, only those specifically identified as capable of being stored can be saved (see Table 6 for which command parameters can be saved to non-volatile storage).

40. POWER MANAGEMENT BUS DATA FORMAT

For commands that set thresholds, voltages or report such quantities, the module supports the "Linear" data format among the three data formats supported by Power management bus. The Linear Data Format is a two byte value with an 11-bit, two's complement mantissa and a 5-bit, two's complement exponent. The format of the two data bytes is shown below:



The value of the number is then given by Value = Mantissa x 2 Exponent



41. POWER MANAGEMENT BUS ADDRESSING

The SLDN-03D1Ax module can be addressed through the Power management bus using a device address. The module has 64 possible addresses (0 to 63 in decimal) which can be set using resistors connected from the ADDR0 and ADDR1 pins to SIG_GND. Note that some of these addresses (0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11 12, 40, 44, 45, 55 in decimal) are reserved according to the SMBus specifications and may not be useable. The address is set in the form of two octal (0 to 7) digits, with each pin setting one digit. The ADDR1 pin sets the high order digit and ADDR0 sets the low order digit. The resistor values suggested for each digit are shown in Table 4 (1% tolerance resistors are recommended). Note that if either address resistor value is outside the range specified in Table 4, the module will respond to address 127.

DIGIT	RESISTOR VALUE (ΚΩ)
0	10
1	15.4
2	23.7
3	36.5
4	54.9
5	84.5
6	130
7	200

Table 4

The user must know which I2C addresses are reserved in a system for special functions and set the address of the module to avoid interfering with other system operations. Both 100kHz and 400kHz bus speeds are supported by the module. Connection for the Power management bus interface should follow the High Power DC specifications given in section 3.1.3 in the SMBus specification V2.0 for the 400kHz bus speed or the Low Power DC specifications in section 3.1.2. The complete SMBus specification is available from the SMBus web site, smbus.org.

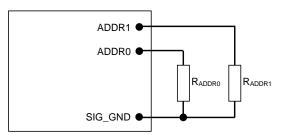


Figure 48.

Circuit showing connection of resistors used to set the Power Management Bus address of the module.



42. POWER MANAGEMENT BUS ENABLE ON/OFF

The SLDN-03D1Ax module can also be turned on and off via the Power management bus interface. The OPERATION command is used to actually turn the module on and off via the Power management bus, while the ON_OFF_CONFIG command configures the combination of analog ON/OFF pin input and Power management bus commands needed to turn the module on and off. Bit [7] in the OPERATION command data byte enables the module, with the following functions:

0 : Output is disabled1 : Output is enabled

This module uses the lower five bits of the ON_OFF_CONFIG data byte to set various ON/OFF options as follows:

BIT POSITION	4	3	2	1	0
Access	r/w	r/w	r/w	r/w	r
Function	PU	CMD	CPR	POL	CPA
Default Value	1	0	1	1	1

PU: Sets the default to either operate any time input power is present or for the ON/OFF to be controlled by the analog ON/OFF input and the Power management bus OPERATION command. This bit is used together with the CP, CMD and ON bits to determine startup.

BIT VALUE	ACTION
0	Module powers up any time power is present regardless of state of the analog ON/OFF pin
1	Module does not power up until commanded by the analog ON/OFF pin and the OPERATION command as programmed in bits [2:0] of the ON_OFF_CONFIG register.

CMD: The CMD bit controls how the device responds to the OPERATION command.

BIT VALUE	ACTION
0	Module ignores the ON bit in the OPERATION command
1	Module responds to the ON bit in the OPERATION command

CPR: Sets the response of the analog ON/OFF pin. This bit is used together with the CMD, PU and ON bits to determine startup.

BIT VALUE	ACTION
0	Module ignores the analog ON/OFF pin, i.e. ON/OFF is only controlled through the POWER MANAGEMENT BUS via the OPERATION command
1	Module requires the analog ON/OFF pin to be asserted to start the unit



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43. POWER MANAGEMENT BUS ADJUSTABLE SOFT START RISE TIME

The soft start rise time can be adjusted in the module via Power management bus. When setting this parameter, make sure that the charging current for output capacitors can be delivered by the module in addition to any load current to avoid nuisance tripping of the overcurrent protection circuitry during startup. The TON_RISE command sets the rise time in ms, and allows choosing soft start times between $600\mu s$ and 9ms, with possible values listed in Table 5. Note that the exponent is fixed at -4 (decimal) and the upper two bits of the mantissa are also fixed at 0.

RISE TIME	EXPONENT	MANTISSA
600µs	11100	0000001010
900μs	11100	0000001110
1.2ms	11100	00000010011
1.8ms	11100	00000011101
2.7ms	11100	00000101011
4.2ms	11100	00001000011
6.0ms	11100	00001100000
9.0ms	11100	00010010000

Table 5



44. OUTPUT VOLTAGE ADJUSTMENT USING THE POWER MANAGEMENT BUS

The VOUT_SCALE_LOOP parameter is important for a number of Power management bus commands related to output voltage trimming, margining, over/under voltage protection and the PGOOD thresholds. The output voltage of the module is set as the combination of the voltage divider formed by RTrim and a $20k\Omega$ upper divider resistor inside the module, and the internal reference voltage of the module. The reference voltage VREF is nominally set at 600mV, and the output regulation voltage is then given by.

$$V_{\scriptscriptstyle OUT} = \left\lceil \frac{20000 + RTrim}{RTrim} \right\rceil \times V_{\scriptscriptstyle REF}$$

Hence the module output voltage is dependent on the value of RTrim which is connected external to the module. The information on the output voltage divider ratio is conveyed to the module through the VOUT_SCALE_LOOP parameter which is calculated as follows:

$$VOUT _SCALE _LOOP = \frac{RTrim}{20000 + RTrim}$$

The VOUT_SCALE_LOOP parameter is specified using the "Linear" format and two bytes. The upper five bits [7:3] of the high byte are used to set the exponent which is fixed at -9 (decimal). The remaining three bits of the high byte [2:0] and the eight bits of the lower byte are used for the mantissa. The default value of the mantissa is 00100000000 corresponding to 256 (decimal), corresponding to a divider ratio of 0.5. The maximum value of the mantissa is 512 corresponding to a divider ratio of 1. Note that the resolution of the VOUT_SCALE_LOOP command is 0.2%.

When Power management bus commands are used to trim or margin the output voltage, the value of VREF is what is changed inside the module, which in turn changes the regulated output voltage of the module.

The nominal output voltage of the module can be adjusted with a minimum step size of 0.4% over a $\pm 25\%$ range from nominal using the VOUT_TRIM command over the Power management bus.

The VOUT_TRIM command is used to apply a fixed offset voltage to the output voltage command value using the "Linear" mode with the exponent fixed at -10 (decimal). The value of the offset voltage is given by

$$V_{OUT(offset)} = VOUT _TRIM \times 2^{-10}$$

This offset voltage is added to the voltage set through the divider ratio and nominal VREF to produce the trimmed output voltage. The valid range in two's complement for this command is —4000h to 3FFFh. The high order two bits of the high byte must both be either 0 or 1. If a value outside of the +/-25% adjustment range is given with this command, the module will set its output voltage to the nominal value (as if VOUT_TRIM had been set to 0), assert SMBALRT#, set the CML bit in STATUS_BYTE and the invalid data bit in STATUS_CML.



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45. OUTPUT VOLTAGE MARGINING USING THE POWER MANAGEMENT BUS

The SLDN-03D1Ax module can also have its output voltage margined via Power management bus commands. The command VOUT_MARGIN_HIGH sets the margin high voltage, while the command VOUT_MARGIN_LOW sets the margin low voltage. Both the VOUT_MARGIN_HIGH and VOUT_MARGIN_LOW commands use the "Linear" mode with the exponent fixed at -10 (decimal). Two bytes are used for the mantissa with the upper bit [7] of the high byte fixed at 0. The actual margined output voltage is a combination of the VOUT_MARGIN_HIGH or VOUT_MARGIN_LOW and the VOUT_TRIM values as shown below:

$$\begin{split} V_{OUT(MH)} &= \\ & (VOUT_MARGIN_HIGH + VOUT_TRIM) \times 2^{-10} \\ V_{OUT(ML)} &= \\ & (VOUT_MARGIN_LOW + VOUT_TRIM) \times 2^{-10} \end{split}$$

Note that the sum of the margin and trim voltages cannot be outside the ±25% window around the nominal output voltage. The data associated with VOUT_MARGIN_HIGH and VOUT_MARGIN_LOW can be stored to non-volatile memory using the STORE_DEFAULT_ALL command.

The module is commanded to go to the margined high or low voltages using the OPERATION command. Bits [5:2] are used to enable margining as follows:

00XX : Margin Off

0101 : Margin Low (Ignore Fault)
0110 : Margin Low (Act on Fault)
1001 : Margin High (Ignore Fault)
1010 : Margin High (Act on Fault)

46. POWER MANAGEMENT BUS ADJUSTABLE OVERCURRENT WARNING

The SLDN-03D1Ax module can provide an overcurrent warning via the Power management bus. The threshold for the overcurrent warning can be set using the parameter IOUT_OC_WARN_LIMIT. This command uses the "Linear" data format with a two byte data word where the upper five bits [7:3] of the high byte represent the exponent and the remaining three bits of the high byte [2:0] and the eight bits in the low byte represent the mantissa. The exponent is fixed at – 1(decimal). The upper six bits of the mantissa are fixed at 0 while the lower five bits are programmable with a default value of 5A. The resolution of this warning limit is 500mA. The value of the IOUT_OC_WARN_LIMIT can be stored to non-volatile memory using the STORE_DEFAULT_ALL command.

47. TEMPERATURE STATUS VIA POWER MANAGEMENT BUS

The SLDN-03D1Ax module can provide information related to temperature of the module through the STATUS_TEMPERATURE command. The command returns information about whether the pre-set over temperature fault threshold and/or the warning threshold have been exceeded.



48. POWER MANAGEMENT BUS ADJUSTABLE OUTPUT OVER AND UNDER VOLTAGE PROTECTION

The SLDN-03D1Ax module has output over and under voltage protection capability. The Power management bus command VOUT_OV_FAULT_LIMIT is used to set the output over voltage threshold from four possible values: 108%, 110%, 112% or 115% of the commanded output voltage. The command VOUT_UV_FAULT_LIMIT sets the threshold that causes an output under voltage fault and can also be selected from four possible values: 92%, 90%, 88% or 85%. The default values are 112% and 88% of commanded output voltage. Both commands use two data bytes formatted as two's complement binary integers. The "Linear" mode is used with the exponent fixed to -10 (decimal) and the effective over or under voltage trip points given by

$$\begin{split} V_{OUT(OV_REQ)} &= (VOUT_OV_FAULT_LIMIT) \times 2^{-10} \\ V_{OUT(UV_REO)} &= (VOUT_UV_FAULT_LIMIT) \times 2^{-10} \end{split}$$

Values within the supported range for over and undervoltage detection thresholds will be set to the nearest fixed percentage. Note that the correct value for VOUT_SCALE_LOOP must be set in the module for the correct over or under voltage trip points to be calculated.

In addition to adjustable output voltage protection, the 3A Digital module can also be programmed for the response to the fault. The VOUT_OV_FAULT RESPONSE and VOUT_UV_FAULT_RESPONSE commands specify the response to the fault. Both these commands use a single data byte with the possible options as shown below.:

- 1. Continue operation without interruption (Bits [7:6] = 00, Bits [5:3] = xxx).
- 2. Continue for four switching cycles and then shut down if the fault is still present, followed by no restart or continuous restart (Bits [7:6] = 01, Bits [5:3] = 000 means no restart, Bits [5:3] = 111 means continuous restart).
- 3. Immediate shut down followed by no restart or continuous restart (Bits [7:6] = 10, Bits [5:3] = 000 means no restart, Bits [5:3] = 111 means continuous restart).
- 4. Module output is disabled when the fault is present and the output is enabled when the fault no longer exists (Bits [7:6] = 11, Bits [5:3] = xxx)

Note that separate response choices are possible for output over voltage or under voltage faults.

49. POWER MANAGEMENT BUS ADJUSTABLE INPUT UNDERVOLTAGE LOCKOUT

The SLDN-03D1Ax module allows adjustment of the input under voltage lockout and hysteresis. The command VIN_ON allows setting the input voltage turn on threshold, while the VIN_OFF command sets the input voltage turn off threshold. For the VIN_ON command, possible values are 2.75V, and 3V to 14V in 0.5V steps. For the VIN_OFF command, possible values are 2.5V to 14V in 0.5V steps. If other values are entered for either command, they will be mapped to the closest of the allowed values.

VIN_ON must be set higher than VIN_OFF. Attempting to write either VIN_ON lower than VIN_OFF or VIN_OFF higher than VIN_ON results in the new value being rejected, SMBALERT being asserted along with the CML bit in STATUS_BYTE and the invalid data bit in STATUS_CML.

Both the VIN_ON and VIN_OFF commands use the "Linear" format with two data bytes. The upper five bits represent the exponent (fixed at -2) and the remaining 11 bits represent the mantissa. For the mantissa, the four most significant bits are fixed at 0.



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50. POWER GOOD

The SLDN-03D1Ax module provides a Power Good (PGOOD) signal that is implemented with an open-drain output to indicate that the output voltage is within the regulation limits of the power module. The PGOOD signal will be de-asserted to a low state if any condition such as overtemperature, overcurrent or loss of regulation occurs that would result in the output voltage going outside the specified thresholds. The PGOOD thresholds are user selectable via the Power management bus (the default values are as shown in the Feature Specifications Section). Each threshold is set up symmetrically above and below the nominal value. The POWER_GOOD_ON command sets the output voltage level above which PGOOD is asserted (lower threshold). For example, with a 1.2V nominal output voltage, the POWER_GOOD_ON threshold can set the lower threshold to 1.14 or 1.1V. Doing this will automatically set the upper thresholds to 1.26 or 1.3V.

The POWER_GOOD_OFF command sets the level below which the PGOOD command is de-asserted. This command also sets two thresholds symmetrically placed around the nominal output voltage. Normally, the POWER_GOOD_ON threshold is set higher than the POWER_GOOD_OFF threshold.

Both POWER_GOOD_ON and POWER_GOOD_OFF commands use the "Linear" format with the exponent fixed at -10 (decimal). The two thresholds are given by

$$V_{OUT(PGOOD_ON)} = (POWER_GOOD_ON) \times 2^{-10}$$

$$V_{OUT(PGOOD_OFF)} = (POWER_GOOD_OFF) \times 2^{-10}$$

Both commands use two data bytes with bit [7] of the high byte fixed at 0, while the remaining bits are r/w and used to set the mantissa using two's complement representation. Both commands also use the VOUT_SCALE_LOOP parameter so it must be set correctly. The default value of POWER_GOOD_ON is set at 1.1035V and that of the POWER_GOOD_OFF is set at 1.08V. The values associated with these commands can be stored in non-volatile memory using the STORE_DEFAULT_ALL command.

The PGOOD terminal can be connected through a pullup resistor (suggested value 100 K Ω) to a source of 5VDC or lower.

51. MEASURREMENT OF OUTPUT CURRENT, OUTPUT VOLTAGE AND INPUT VOLTAGE

The SLDN-03D1Ax module is capable of measuring key module parameters such as output current and voltage and input voltage and providing this information through the Power management bus interface. Roughly every 200µs, the module makes 16 measurements each of output current, voltage and input voltage. Average values of of these 16 measurements are then calculated and placed in the appropriate registers. The values in the registers can then be read using the Power management bus interface.



52. MEASURING OUTPUT CURRENT USING THE POWER MANAGEMENT BUS

The SLDN-03D1Ax module measures current by using the inductor winding resistance as a current sense element. The inductor winding resistance is then the current gain factor used to scale the measured voltage into a current reading. This gain factor is the argument of the IOUT_CAL_GAIN command, and consists of two bytes in the linear data format. The exponent uses the upper five bits [7:3] of the high data byte in two-s complement format and is fixed at –15 (decimal). The remaining 11 bits in two's complement binary format represent the mantissa.

The current measurement accuracy is also improved by each module being calibrated during manufacture with the offset in the current reading. The IOUT_CAL_OFFSET command is used to store and read the current offset. The argument for this command consists of two bytes composed of a 5-bit exponent (fixed at -4d) and a 11-bit mantissa. This command has a resolution of 62.5mA and a range of -4000mA to +3937.5mA.

The READ_IOUT command provides module average output current information. This command only supports positive or current sourced from the module. If the converter is sinking current a reading of 0 is provided. The READ_IOUT command returns two bytes of data in the linear data format. The exponent uses the upper five bits [7:3] of the high data byte in two-s complement format and is fixed at –4 (decimal). The remaining 11 bits in two's complement binary format represent the mantissa with the 11th bit fixed at 0 since only positive numbers are considered valid.

Note that the current reading provided by the module is not corrected for temperature. The temperature corrected current reading for module temperature T_{Module} can be estimated using the following equation

$$I_{OUT,CORR} = \frac{I_{READ_OUT}}{1 + [(T_{IND} - 30) \times 0.00393]}$$

where IOUT_CORR is the temperature corrected value of the current measurement, I¬READ_OUT is the module current measurement value, TIND is the temperature of the inductor winding on the module. Since it may be difficult to measure TIND, it may be approximated by an estimate of the module temperature.

The SLDN-03D1Ax module can provide output voltage information using the READ_VOUT command. The command returns two bytes of data all representing the mantissa while the exponent is fixed at -10 (decimal).

During manufacture of the module, offset and gain correction values are written into the non-volatile memory of the module. The command VOUT_CAL_OFFSET can be used to read and/or write the offset (two bytes consisting of a 16-bit mantissa in two's complement format) while the exponent is always fixed at -10 (decimal). The allowed range for this offset correction is -125 to 124mV. The command VOUT_CAL_GAIN can be used to read and/or write the gain correction - two bytes consisting of a five-bit exponent (fixed at -8) and a 11-bit mantissa. The range of this correction factor is -0.125V to +0.121V, with a resolution of 0.004V. The corrected output voltage reading is then given by:

$$V_{OUT}(Final) = \ [V_{OUT}(Initial) \times (1 + VOUT_CAL_GAIN)] \ + VOUT_CAL_OFFSET$$



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53. MEASURING INPPUT VOLTAGE USING THE POWER MANAGEMENT BUS

The SLDN-03D1Ax module can provide output voltage information using the READ_VIN command. The command returns two bytes of data in the linear format. The upper five bits [7:3] of the high data form the two's complement representation of the mantissa which is fixed at –5 (decimal). The remaining 11 bits are used for two's complement representation of the mantissa, with the 11th bit fixed at zero since only positive numbers are valid.

During module manufacture, offset and gain correction values are written into the non-volatile memory of the module. The command VIN_CAL_OFFSET can be used to read and/or write the offset - two bytes consisting of a five-bit exponent (fixed at -5) and a11-bit mantissa in two's complement format. The allowed range for this offset correction is -2 to 1.968V, and the resolution is 32mV. The command VIN_CAL_GAIN can be used to read and/or write the gain correction - two bytes consisting of a five-bit exponent (fixed at -8) and a 11-bit mantissa. The range of this correction factor is -0.125V to +0.121V, with a resolution of 0.004V. The corrected output voltage reading is then given by:

$$V_{IN}(Final) =$$

$$[V_{IN}(Initial) \times (1 + VIN _CAL _GAIN)] + VIN _CAL _OFFSET$$



54. READING THE STATUS OF THE MODULE USING THE POWER MANAGEMENT BUS

The SLDN-03D1Ax module supports a number of status information commands implemented in Power management bus. However, not all features are supported in these commands. A 1 in the bit position indicates the fault that is flagged.

STATUS_BYTE: Returns one byte of information with a summary of the most critical device faults.

BIT POSITION	FLAG	DEFAULT VALUE
7	X	0
6	OFF	0
5	VOUT Overvoltage	0
4	IOUT Overcurrent	0
3	VIN Undervoltage	0
2	Temperature	0
1	CML (Comm. Memory Fault)	0
0	None of the above	0

STATUS_WORD: Returns two bytes of information with a summary of the module's fault/warning conditions.

Low Byte

BIT POSITION	FLAG	DEFAULT VALUE
7	X	0
6	OFF	0
5	VOUT Overvoltage	0
4	IOUT Overcurrent	0
3	VIN Undervoltage	0
2	Temperature	0
1	CML (Comm. Memory Fault)	0
0	None of the above	0

High Byte

BIT POSITION	FLAG	DEFAULT VALUE
7	VOUT fault or warning	0
6	IOUT fault or warning	0
5	X	0
4	X	0
3	POWER_GOOD# (is negated)	0
2	X	0
1	X	0
0	X	0



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STATUS_VOUT: Returns one byte of information relating to the status of the module's output voltage related faults.

BIT POSITION	FLAG	DEFAULT VALUE
7	VOUT OV Fault	0
6	X	0
5	X	0
4	VOUT UV Fault	0
3	X	0
2	X	0
1	X	0
0	X	0

STATUS_IOUT: Returns one byte of information relating to the status of the module's output voltage related faults.

BIT POSITION	FLAG	DEFAULT VALUE
7	IOUT OC Fault	0
6	X	0
5	IOUT OC Warning	0
4	X	0
3	X	0
2	X	0
1	X	0
0	X	0

STATUS_TEMPERATURE: Returns one byte of information relating to the status of the module's temperature related faults.

BIT POSITION	FLAG	DEFAULT VALUE
7	OT Fault	0
6	OT Warning	0
5	X	0
4	X	0
3	X	0
2	X	0
1	X	0
0	X	0



STATUS_CML: Returns one byte of information relating to the status of the module's communication related faults.

BIT POSITION	FLAG	DEFAULT VALUE
7	Invalid/Unsupported Command	0
6	Invalid/Unsupported Command	0
5	Packet Error Check Failed	0
4	X	0
3	X	0
2	X	0
1	Other Communication Fault	0
0	X	0

MFR_VIN_MIN: Returns minimum input voltage as two data bytes of information in Linear format (upper five bits are exponent – fixed at -2, and lower 11 bits are mantissa in two's complement format – fixed at 12).

MFR_VOUT_MIN: Returns minimum output voltage as two data bytes of information in Linear format (upper five bits are exponent – fixed at -10, and lower 11 bits are mantissa in two's complement format – fixed at 614).

MFR_SPECIFIC_00: Returns information related to the type of module and revision number. Bits [7:2] in the Low Byte indicate the module type (001000 corresponds to the SLDN-03D1Ax series of module), while bits [7:3] indicate the revision number of the module.

Low Byte

BIT POSITION	FLAG	DEFAULT VALUE
7:2	Module Name	001000
1:0	Reserved	10

High Byte

BIT POSITION	FLAG	DEFAULT VALUE			
7:3	Module Revision Number	None			
2:0	Reserved	000			



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55. SUMMARY OF SUPPORTED POWER MANAGEMENT BUS COMMANDS

Please refer to the Power Management Bus 1.1 specification for more details of these commands.

Table 6

Hex Code	Command	Brief Description						Non-Volatile Memory Storage			
	Turn Module on or off. Also used to margin the output vo								je		
	OPERATION	Format					d Binar				
01		Bit Position	7	6	5	4	3	2	1	0	
		Access	r/w	r	r/w	r/w	r/w	r/w	r	r	
		Function	On	Х		Ma	rgin		Х	Х	
		Default Value	0	0	0	0	0	0	Х	Х	
		Configures the ON/OFF functionality as a combination of analog ON/OFF pin and Power management bus commands									
	ON_OFF_CONFIG	Format Unsigned Binary									
02		Bit Position	7	6	5	4	3	2	1	0	YES
02	014_011_001411d	Access	r	r	r	r/w	r/w	r/w	r/w	r	
		Function	X	X	X	pu	cmd	cpr	pol	сра	
		Default Value	0	0	0	1	0	1	1	1	
03	CLEAR_FAULTS	Clear any fault bits signal if the device	e has b	een ass	erting i	t.					
	WRITE_PROTECT	Used to control writing to the module via Power management bus. Copies the current register setting in the module whose command code matches the value in the data byte into non-volatile memory (EEPROM) on the module						atches			
		Format	Format Unsigned Binary								
		Bit Position	7	6	5	4	3	2	1	0	YES
		Access	r/w	r/w	r/w	х	х	х	х	Х	
10		Function	bit7	bit6	bit5	Х	Х	Х	Х	Х	
		Default Value	0	0	0	Х	Х	Х	Х	Х	
.0		Bit5: 0 – Enables all writes as permitted in bit6 or bit7 1 – Disables all writes except the WRITE_PROTECT, OPERATION and ON_OFF_CONFIG (bit 6 and bit7 must be 0) Bit 6: 0 – Enables all writes as permitted in bit5 or bit7 1 – Disables all writes except for the WRITE_PROTECT and OPERATION commands (bit5 and bit7 must be 0) Bit7: 0 – Enables all writes as permitted in bit5 or bit6 1 – Disables all writes except for the WRITE_PROTECT command (bit5 and bit6 must be 0)					120				
11	STORE_DEFAULT_ALL	Copies all current register settings in the module into non-volatile memory (EEPROM) on the module. Takes about 50ms for the command to execute.									
											
12	RESTORE_DEFAULT_ALL	Restores all currer					uule iro	ını valu	es in tr	ie	
13	STORE_DEFAULT_CODE	module non-volatile memory (EEPROM) Copies the current register setting in the module whose command code matches the value in the data byte into non-volatile memory (EEPROM) on the module									
13		Bit Position	7	6	5	4	3	2	1	0	
		Access	w	W	w	w	w	W	W	W	
		Function					nd cod				
14	RESTORE_DEFAULT_CODE	Restores the current register setting in the module whose command code matches the value in the data byte from the value in the module non-volatile memory (EEPROM) Bit Position 7 6 5 4 3 2 1 0									
		Access	7					2	1		
		Function	W	W	W	W Commo	W nd cod	W	W	W	
		Function				JUITINA	nd cod	C			



Hex Code	Command			Brid	ef Desc	cription	1				Non-Volatile Memory Storage
		The module has M		et to Li	near an	d Expo	nent se	et to -10	0. Thes	e values	
		cannot be change	1		-						
20	VOUT_MODE	Bit Position Access	7	6	5	4	3	2	1	0	
	_	Function	r	r Mode	r	r	r	r	r	r	
		Default Value	0	0	0	1	0	xponer	1	0	
									<u>' ' ' ' ' ' ' ' ' ' ' ' ' ' ' ' ' ' ' </u>	U	
		Apply a fixed offse	et volta								
		Format Dit Decition	7	6		/o's coi					
		Bit Position Access	r/w	r	5 r/w	4 r/w	3 r/w	2 r/w	r/w	0 r/w	
		Function	17 VV	<u> </u>	17 VV		Byte	17 VV	17 VV	17 VV	
22	VOUT_TRIM	Default Value	0	0	0	0	0	0	0	0	YES
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function				Low					
		Default Value	0	0	0	0	0	0	0	0	
		Cata the target ve	ltomo fo		nina th	o outou	+ biab				
		Sets the target vo	lage io			o's co		ant hins	an/		
		Bit Position	7	6	5	4	3	2	1 1	0	
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
	25 VOLIT MARGIN HIGH	Function		17 VV	17 VV		Byte	17 00	17 VV	17 VV	
25	VOUT_MARGIN_HIGH	Default Value	0	0	0	0	0	1	0	1	YES
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function				Low	Byte				
		Default Value	0	1	0	0	0	1	1	1	
		Sets the target voltage for margining the output low Format Linear, two's complement binary									
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
00	VOLIT MADOIN LOW	Function		•		High	Byte	•	•		VEC
26	VOUT_MARGIN_LOW	Default Value	0	0	0	0	0	1	0	0	YES
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function					Byte	· -	-		
		Default Value	0	1	0	1	0	0	0	1	
		Sets the scaling of divider ratio	f the ou	ıtput vo	ltage –	equal t	o the f	eedbac	k resist	or	
		Format		Li	near, tv	o's co	mpleme	ent bina	ary		
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r/w	r/w	
29	VOUT_SCALE_LOOP	Function			xponer				Mantiss		YES
		Default Value	1	0	1	1	1	0	0	1	
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function Default Value	0	0	0		tissa	0	0		
		Default Value	0	U	U	0	0	U		0	



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Hex Code	Command	Brief Description								Non-Volatile Memory Storage	
		Sets the value of i	nput vo	ltage a	t which	the mo	odule tu	ırns on			
		Format		Li	near, tv	o's co	mpleme	ent bina	ary		
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r	
35	VIN_ON	Function		E	xponer	nt		N	Mantiss	а	YES
55	VIIV_OIV	Default Value	1	1	1	1	0	0	0	0	120
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function					tissa			1	
		Default Value	0	0	0	0	1	0	1	1	
		Sets the value of i	nput vo	ltage a	t which	the mo	odule tu	ırns off			
		Format			near, tw						
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r	
36	VIN_OFF	Function Exponent Mantissa							YES		
50	VIIV_011	Default Value	1	1	1	1	0	0	0	0	120
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function					tissa				
		Default Value	0	0	0	0	1	0	1	0	
		Returns the value of the gain correction term used to correct the measured output current									
		Format		Liı	near, tw	o's co	mpleme	ent bina	ary		
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r/w	
38	IOUT_CAL_GAIN	Function		E	xponer	nt		N	√antiss	а	YES
		Default Value	1	0	0	0	1	0	0	V	
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function				Man					
		Default Value		V: Va	riable b	ased o	n facto	ry calib	ration		
Returns the value of the offset correction term used to correct the measured output current											
		Format	Current	l is	near, tw	io's co	mnleme	ant hins	arv/		
		Bit Position	7	6	5	4	3	2	1 1	0	
		Access	r	r	r	r	r	r/w	r	r	
39	IOUT_CAL_OFFSET	Function	- '		xponer		_ '		/⊿ntiss		YES
33	IOUI_OAL_OITOLI	Default Value	1	1	1	0	0	V	0	0	123
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r/w	r/w	r/w	r/w	r/w	r/w	
		Function	<u> </u>	<u>'</u>	., .,		tissa	, .,	, **	., **	
		Default Value	0	0	V: Va		ased o	n facto	rv calih	ration	
		Doladit Value	U	U	v. va	i abic b	asca 0	iuoto	, ouil	iation	



Hex Code	Command			Bri	ef Desc	cription	1				Non-Volatile Memory Storage
		Sets the voltage le	evel for	an out	out ove	rvoltage	e fault.	Expon	ent is f	ixed at	
		-10. Suggested value s	shown f	or 1.2\	/o Shoi	ıld be d	hange	d for di	fferent	outout	
		voltage. Values ca									
		Format			near, tv	o's co	mpleme	ent bina	ary		
		Bit Position	7	6	5	4	3	2	1	0	
40	VOUT_OV_FAULT_LIMIT	Access Function	r	r/w	r/w	r/w High	r/w	r/w	r/w	r/w	YES
		Default Value	0	0	0	0	0 0	1	0	1	
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function	0	_		Low					
		Default Value	0	1	1	0	0	0	0	0	
41	VOUT_OV_FAULT_RESPONSE	Instructs the mode overvoltage fault Format Bit Position Access	7 r/w RSP	what ac	5 r/w	Jnsigne 4 r/w	d Binar 3 r/w		output	0 r	YES
		Function	[1]	[0]	RS[2]	RS[1]	RS[0]	Х	Х	X	
		Default Value	1	1	1	1	1	1	0	0	
44	VOUT_UV_FAULT_LIMIT	Sets the voltage le- 10. Suggested values cavoltage. Values Function Cavoltage. Value Cavoltage. Value Cavoltage. Value Cavoltage. Values	shown f	or 1.2V 2%, 90	o. Sho	uld be o	changed for our formplement for a changed fo	d for di	fferent oltage		YES
		Default Value	0	0	1	1	1	0	0	1	
		Instructs the mode undervoltage fault Format		vhat ac		take in Insigne			output		
45	VOUT_UV_FAULT_RESPONSE	Bit Position	7	6	5	4	3	2	1	0	YES
.0	1 2 3 3	Access	r/w	r/w	r/w	r/w	r/w	r	r	r	
		Function Default Value	RSP [1] 0	RSP [0] 0	RS[2]	RS[1]	RS[0]	X 1	X 0	X 0	
		Sets the output ov						l			
		Format	/ercurre		near, tv						
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r	
46	IOUT_OC_FAULT_LIMIT	Function	-		xponer		4		Mantiss		YES
		Default Value Bit Position	7	1 6	5	4	3	2	0	0	
		Access	r	r	r	r	r	r	r	R	
		Function					tissa				
		Default Value	0	0	0	0	1	1	0	0	



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Hex Code	Command			Bri	ef Desc	cription	1				Non-Volatile Memory Storage
		Sets the output ov	vercurre	ent war	nina lev	el in A					
		Format			near, tw		mpleme	ent bina	arv		
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r	
		Function			xponer				Mantiss		
4A	IOUT_OC_WARN_LIMIT	Default Value	1	1	1	1	1	0	0	0	YES
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r/w	r/w	r/w	r/w	r/w	r/w	
		Function				Man	tissa				
		Default Value	0	0	0	0	1	0	1	0	
			oltogo la	avol et i	which th	20 DCC	OD nin	io ooo	ortod bi	iah	
		Sets the output vo	ntage 16		wnich tr near, tw					ign	
		Bit Position	7	6	5 5	4	3	2	1 1	0	
			r	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Access	r	I/W	I/W		Byte	I/W	I/W	I/W	
5E	POWER_GOOD_ON	Function Default Value	0	0	0	nign 0	- Буtе 0	1	0	0	YES
		Bit Position	7	6	5	4	3	2	1	0	
						r/w			<u> </u>		
		Access	r/w	r/w	r/w		r/w	r/w	r/w	r/w	
		Function Default Value	0	1	1	0	Byte	0	1	0	
		<u> </u>				_	ı		-		
		Sets the output vo	oltage le							d low	
		Format		<u>Li</u>	near, tw	o's co	mpleme	ent bina	ary		
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
5F	POWER_GOOD_OFF	Function		•			Byte	•			YES
51	TOWEN_GOOD_OFF	Default Value	0	0	0	0	0	1	0	0	ILO
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function		•		Low	Byte	•			
		Default Value	0	1	0	1	0	0	1	0	
		Sets the rise time	of the	output v	voltage	during	startup)			
		Format		Li	near, tw	o's co	mpleme	ent bina	ary		
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r/w	
61	TON DISE	Function		E	xponer	nt		- 1	Mantiss	a	VEC
61	TON_RISE	Default Value	1	1	1	0	0	0	0	0	YES
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function				Man	tissa				
		Default Value	0	0	1	0	1	0	1	0	
		Returns one byte faults	of infor	mation					critical	module	
		Format			L	Jnsigne	d Binar	γ			
78	STATUS_BYTE	Bit Position	7	6	5	4	3	2	1	0	
10	SIMIUS_BITE	Access	r	r	r	r	r	r	r	r	
		Flag	Х	OFF	VOUT _OV	_OC	VIN_ UV	TEMP		OTHE R	
		Default Value	0	0	0	0	0	0	0	0	



Hex Code	Command			Bri	ef De	script	ion					Non-Volatile Memory Storage
		Returns two bytes	of info	rmatio	n with	a sun	nmar	y of th	ne mod	dule's		
		fault/warning cond	ditions									
		Format				Unsig	gned	Binar	У			
		Bit Position	7	6	5	4		3	2	1	0	
		Access	r	r	r	r		r	r	r	r	
79	STATUS_WORD	Flag	VOUT	_00	Х	Х	`	PGO OD	Х	Х	Х	
		Default Value	0	0	0	0		0	0	0	0	
		Bit Position	7	6	5	4		3	2	1	0	
		Access	r	r	r	r		r	r	r	r	
		Flag	Х	OFF	_OV	_0	С	VIN_ UV	TEMP		R	
		Default Value	0	0	0	0)	0	0	0	0	
		voltage related fau	leturns one byte of information with the status of the module's output oltage related faults Format Unsigned Binary									
		Format					_					
7A	STATUS_VOUT	Bit Position										
		Access	r		r	r	r		r			
		Flag	VOU	_				Γ_UV		X >	_	
		Default Value	C)	0	0	0)	0	0 (0	
		Returns one byte current related fau										
		Format				Unsig	gned	Binar	У			
7B	STATUS IOUT	Bit Position	7	7	6		5		4 3	2	1 0	
/ 6	31A103_1001	Access	r		r		r		r r	r	r r	
		Flag	IOUT		^	OUT_	N	WAR	х		хх	
		Default Value	C)	0		0		0 0	0	0 0	
		Returns one byte temperature relate								e's		
		Format						Binar				
7D	STATUS_TEMPERATURE	Bit Position	7			3	5		3	2	1 0	
		Access	r			<u>r</u>	r		r	r	r R	
		Flag	OT_F		OT_V				Х		X X	
		Default Value	C)	()	0	0	0	0	0 0	
		Returns one byte communication re								e's		
		Format	-					Binar				
7-	CTATUC CMI	Bit Position	7		6	5	4	-	2	1	0	
7E	STATUS_CML	Access	r		r	r	r	r	r	r	r	
		Flag	Inva Comn	nand	nvalid Data	Fail	X		Х	Othe Com Fau	m X lt	
		Default Value	0		0	0	0	0	0	0	0	



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READ_VIN Format			Non-Volatile Memory Storage								
Bit Position 7 6 5 4 3 Access r r r r r Function Exponent Default Value 1 1 0 1 1 Bit Position 7 6 5 4 3 Access r r r r r Function Exponent Default Value 1 1 0 1 1 Bit Position 7 6 5 4 3 Access r r r r r Function Mantissa Default Value 0 0 0 0 0 Returns the value of the output voltage of the module Format Linear, two's compleme Bit Position 7 6 5 4 3 Access r r r r r Function Mantissa Default Value 0 0 0 0 0 Bit Position 7 6 5 4 3 Access r r r r r Function Mantissa Default Value 0 0 0 0 0 Returns the value of the output current of the module Format Linear, two's compleme Bit Position 7 6 5 4 3 Access r r r r r Function Exponent Default Value 1 1 1 0 0 Bit Position 7 6 5 4 3 Access r r r r r Function Exponent Default Value 1 1 1 0 0 Bit Position 7 6 5 4 3 Access r r r r r Function Exponent Default Value 1 1 1 0 0 Bit Position 7 6 5 4 3 Access r r r r r Function Exponent Default Value 1 1 1 0 0 Bit Position 7 6 5 4 3 Access r r r r r Function Exponent Default Value 1 1 1 0 0 Bit Position 7 6 5 4 3 Access r r r r r Function Exponent	Returns the value of the input voltage applied to the module										
READ_VIN	nt binary	nary									
READ_VIN Function Exponent	2	1)								
Bit Position Total Total	r	r	•								
Bit Position 7 6 5 4 3 Access r r r r r Function Mantissa Default Value 0 0 0 0 0 0 Bit Position 7 6 5 4 3 Access r r r r r r r r r	Mar	Mantissa									
Returns the value of the output voltage of the module Format	0	0)								
Returns the value O O O O O O	2	1)								
Returns the value of the output voltage of the module Format	r	r	·								
Returns the value of the output voltage of the module Format											
READ_VOUT Format	0	0)								
Bit Position 7 6 5 4 3 Access r r r r r Function	Returns the value of the output voltage of the module										
READ_VOUT READ_VOUT Read_vour Read	nt binary	nary									
READ_VOUT Function Mantissa	2	1)								
Default Value	r	r									
Bit Position 7 6 5 4 3 Access r r r r r Function											
Access r r r r r	0	0)								
Function Mantissa	2	1)								
Default Value	r	r	·								
Returns the value of the output current of the module Format											
READ_IOUT Format Linear, two's complement	0	0)								
Bit Position 7 6 5 4 3 Access r r r r Function Exponent Default Value 1 1 1 0 0 Bit Position 7 6 5 4 3 Access r r r r Function Mantissa	of the output current of the module										
Access r r r r r Function Exponent Default Value 1 1 1 0 0	mat Linear, two's complement binary										
Function Exponent Default Value 1 1 1 0 0	2	1)								
Default Value	r	r	•								
Default Value	Mar	Mantissa									
Access r r r r r Function Mantissa	0	0)								
Function Mantissa	2	1)								
	r	r	•								
	0	0)								
Returns one byte indicating the module is compliant to bus Spec. 1.1 (read only) POWER MANAGEMENT Returns one byte indicating the module is compliant to bus Spec. 1.1 (read only) Format Unsigned Binary		wer manage	nent								
98 BUS_REVISION Bit Position 7 6 5 4 3		1	YES								
Access r r r r r			<u></u>								
Default Value 0 0 0 1 0											



Hex Code	Command			Bri	ef Desc	cription	1				Non-Volatile Memory Storage
		Returns the minim	ium inp	ut volta	ge the	module	e is spe	cified to	o opera	te at	
		(read only)	1								
		Format		1	near, tv			1			
		Bit Position	7	6	5	4	3	2	1	0	
4.0	MED VIN MIN	Access	r	r	r	r	r	r	r Mantiss	r	V/F0
A0	MFR_VIN_MIN	Function Default Value	1	1	xponer 1	1 1	0	0	0	a 0	YES
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r	
		Function	<u> </u>	· · · · ·			itissa	· · · · ·	<u> </u>		
		Default Value	0	0	0	0	1	1	0	0	
		Returns the minim	um out	put vol	tage po	ssible	from the	e modu	ıle (read	only)	
		Format			near, tv					- //	
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r	
A4	MFR_VOUT_MIN	Function				Man	tissa				YES
A4	IVIFH_VOOT_IVIIIV	Default Value	0	0	0	0	0	0	1	0	1 E3
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r	
		Function	_				tissa				
		Default Value	0	1	1	0	0	1	1	0	
		Returns module na	ame inf	ormatio							
		Format					d Binar				
	MFR_SPECIFIC_00	Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r	r	r	r	r	
D0		Function	-				erved		1 0	-	YES
		Default Value	0	0	0	0	0	0	0	0	
		Bit Position	7	6	5	4	3	2	1	0	
		Access Function	r	r	r Module	Namo	r	r	r Rese	r	
		Default Value	0	0	1	0	0	0	1	0	
		Applies an offset t	o the R	EAD_V		omman	d result	s to ca		out	
		125mV and +124n							`		
		Format		1	near, tv						
		Bit Position	7	6	5	4	3	2	1	0	
D4	VOUT_CAL_OFFSET	Access	r/w	r	r	r	r	r	r	r	YES
57	1001_0/1C_0110E1	Function	\ , <i>,</i>				tissa				1.20
		Default Value	V	0	0	0	0	0	0	0	
		Bit Position	7	6 r/w	5 r/w	4	3	2	1	0	
		Access	r	r/W	I/W	r/w Man	r/w itissa	r/w	r/w	r/w	
		Function Default Value	V	V	V	Wan	V	V	V	V	
		Applies a gain cor		_		V		•	_	-	1
		out gain errors in r 0.125 and 0.121)		measu	rement	s of the	output	t voltag	e (betw		
		Format		Li	near, tv	vo's co	mpleme	ent bina	ary		
		Bit Position	7	6	5	4	3	2	1	0	
D5	VOUT_CAL_GAIN	Access	r	r	r	r	r	r/w	r	r	YES
טט	VOOT_CAL_GAIN	Function		1	xponer				Mantiss		IES
		Default Value	1	1	0	0	0	0	0	V	
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	r	r/w	r/w	r/w	r/w	r/w]
		Function	\ , <i>,</i>	٠,,			tissa	٠,,	1 1		
		Default Value	V	V	V	V	V	V	V	V	



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Hex Code	Command		Brief Description									Non-Volatile Memory Storage
			Applies an offset correction to the READ_VIN command results to calibrate offset errors in module measurements of the input voltage (between -2V and -1.968V)									
		Format		Li	near, tv	vo's co	mpleme	ent bina	ary			
		Bit Position	7	6	5	4	3	2	1	0		
D0	VIN ON OFFORT	Access	r	r	r	r	r	r/w	r	r		\/F0
D6	VIN_CAL_OFFSET Function Exponent Mantissa										YES	
		Default Value	1	1	0	1	V	0	0	V		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				Man	tissa					
		Default Value	0	0	V	V	V	V	V	V		
		Applies a gain cor gain errors in mod 0.121)		asurem	ents of	the inp	out volta	age (be	tween			
		Format		Li	near, tv	vo's co	mpleme	ent bina	ary			
		Bit Position	7	6	5	4	3	2	1	0		
D7	VINI CAL CAINI	Access	r	r	r	r	r	r/w	r	r		YES
וט	VIN_CAL_GAIN	Function		E	xpone	nt		N	√antiss	а		169
		Default Value	1	1	0	0	V	0	0	V		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r/w	r/w	r/w	r/w	r/w		
		Function				Man	tissa					
		Default Value	0	0	0	V	V	V	V	V		



56. THERMAL CONSIDERATIONS

The SLDN-03D1Ax power modules operate in a variety of thermal environments; however, sufficient cooling should always be provided to help ensure reliable operation.

Considerations include ambient temperature, airflow, module power dissipation, and the need for increased reliability. A reduction in the operating temperature of the module will result in an increase in reliability. The thermal data presented here is based on physical measurements taken in a wind tunnel. The test set-up is shown in Figure 49. The preferred airflow direction for the module is in Figure 50.

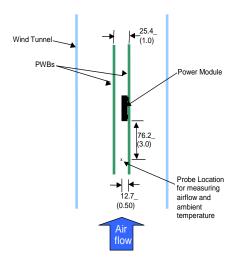


Figure 49. Thermal Test Setup

The thermal reference points, Tref used in the specifications are also shown in Figure 50. For reliable operation the temperatures at these points should not exceed 120° C. The output power of the module should not exceed the rated power of the module (Vo,set x Io,max).

Please refer to the Application Note "Thermal Characterization Process For Open-Frame Board-Mounted Power Modules" for a detailed discussion of thermal aspects including maximum device temperatures.

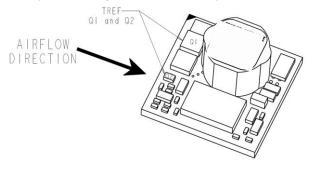


Figure 50.

Preferred airflow direction and location of hot spot of the module (Tref)



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57. EXAMPLE APPLICATION CIRCUIT

Requirements:

Vin: 12 V Vout: 1.8 V

lout: 2.25 A max., worst case load transient is from 1.5 A to 2.25 A

ΔVout: 1.5% of Vout (27 mV) for worst case load transient

Vin, ripple 1.5% of Vin (180 mV, p-p)

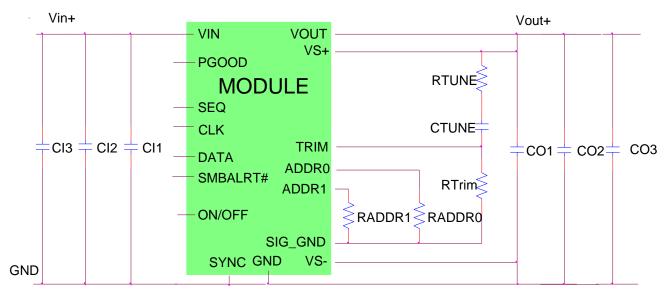


Figure 51.

CI1	Decoupling cap - 1x0.047 μF/16 V ceramic capacitor (e.g. Murata LLL185R71C473MA01)
CI2	1x22 μF/16 V ceramic capacitor (e.g. Murata GRM32ER61C226KE20)
CI3	470 μF/16 V bulk electrolytic
CO1	Decoupling cap - 1x0.047μF/16V ceramic capacitor (e.g. Murata LLL185R71C473MA01)
CO2	-

CO3 1 x 330 μF

CTune 2200 pF ceramic capacitor (can be 1206, 0805 or 0603 size) RTune 220 Ω SMT resistor (can be 1206, 0805 or 0603 size)

RTrim 10 k Ω SMT resistor (can be 1206, 0805 or 0603 size, recommended tolerance of 0.1%)

Note: The DATA, CLK and SMBALRT pins do not have any pull-up resistors inside the module. Typically, the SMBus master controller will have the pull-up resistors as well as provide the driving source for these signals.



58. MECHANICAL DIMENSIONS OUTLINE

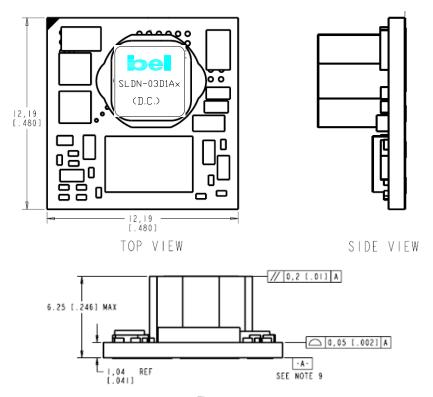


Figure 52.

Dimensions are in mm [inch].

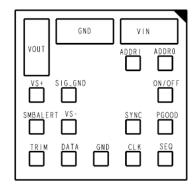
Tolerances: $x.x \pm 0.5$ mm [± 0.02 inch] [unless otherwise indicated].

 $x.xx \pm 0.25 \text{ mm } [\pm 0.010 \text{ inch}].$



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PIN DEFINITIONS



BOTTOM VIEW
Figure 53. Pins

PIN	FUNCTION	PIN	FUNCTION
1	ON/OFF	10	PGOOD
2	VIN	11	SYNC ¹
3	GND	12	VS-
4	VOUT	13	SIG. GND
5	VS+ (SENSE)	14	SMBALERT
6	TRIM	15	DATA
7	GND	16	ADDR0
8	CLK	17	ADDR1
9	SEQ		

¹ If unused, connect to Ground.

RECOMMENDED PAD LAYOUT

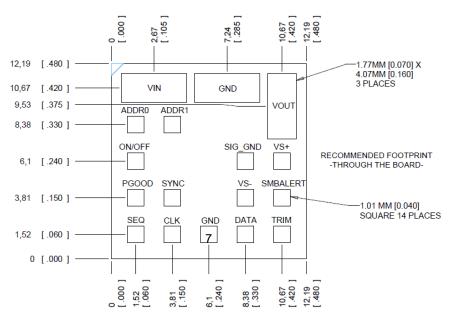


Figure 54. Recommended pad layout



tech.support@psbel.com belfuse.com/power-solutions

59. PACKAGING DETAILS

The SLDN-03D1Ax modules are supplied in tape & reel as standard.

All Dimensions are in mm [inch].

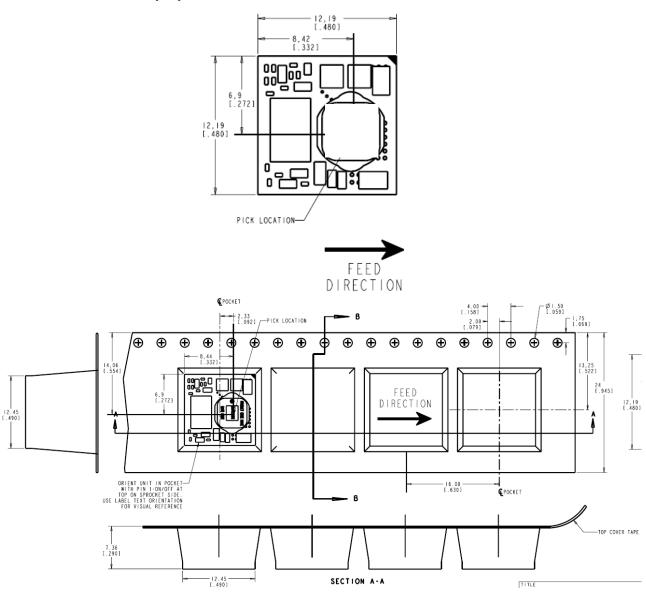


Figure 55.

Reel Dimensions:

Outside Dimensions: 330.2 mm [13.00 inch]
Inside Dimensions: 177.8 mm [7.00 inch]
Tape Width: 24.00 mm [0.945 inch]



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60. SURFACE MOUNT INFORMATION

Pick and Place

The SLDN-03D1Ax modules use an open frame construction and are designed for a fully automated assembly process. The modules are fitted with a label designed to provide a large surface area for pick and place operations. The label meets all the requirements for surface mount processing, as well as safety standards, and is able to withstand reflow temperatures of up to 300°C. The label also carries product information such as product code, serial number and the location of manufacture.

Nozzle Recommendations

The weight has been kept to a minimum by using open frame construction. Variables such as nozzle size, tip style, vacuum pressure and placement speed should be considered to optimize this process. The minimum recommended inside nozzle diameter for reliable operation is 3mm. The maximum nozzle outer diameter, which will safely fit within the allowable component spacing, is 7 mm

Bottom Side / First Side Assembly

This SLDN-03D1Ax module is not recommended for assembly on the bottom side of a customer board. If such an assembly is attempted, components may fall off the module during the second reflow process.

Lead Free Soldering

The SLDN-03D1Ax modules are lead-free (Pb-free) and RoHS compliant and are both forward and backward compatible in a Pb-free and a SnPb soldering process. Failure to observe the instructions below may result in the failure of or cause damage to the modules and can adversely affect long-term reliability.

Pb-free Reflow Profile

Power Systems will comply with J-STD-020 Rev. C (Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices) for both Pb-free solder profiles and MSL classification procedures. This standard provides a recommended forced-air-convection reflow profile based on the volume and thickness of the package (table 5-2). The suggested Pb-free solder paste is Sn/Ag/Cu (SAC). The recommended linear reflow profile using Sn/Ag/Cu solder is shown in Fig. 56. Soldering outside of the recommended profile requires testing to verify results and performance.

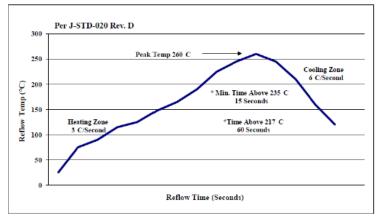
It is recommended that the pad layout include a test pad where the output pin is in the ground plane. The thermocouple should be attached to this test pad since this will be the coolest solder joints. The temperature of this point should be:

Maximum peak temperature is 260 °C.

Minimum temperature is 235 °C.

Dwell time above 217 °C: 60 seconds minimum

Dwell time above 235 °C: 5 to 15 second.





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Figure 56. Recommended linear reflow profile using Sn/Ag/Cu solder

MSL Rating

The SLDN-03D1Ax modules have a MSL rating of 2A.

Storage and Handling

The recommended storage environment and handling procedures for moisture-sensitive surface mount packages is detailed in J-STD-033 Rev. B (Handling, Packing, Shipping and Use of Moisture/Reflow Sensitive Surface Mount Devices). Moisture barrier bags (MBB) with desiccant are required for MSL ratings of 2 or greater. These sealed packages should not be broken until time of use. Once the original package is broken, the floor life of the product at conditions of $\leq 30^{\circ}$ C and 60% relative humidity varies according to the MSL rating (see J-STD-033A). The shelf life for dry packed SMT packages will be a minimum of 12 months from the bag seal date, when stored at the following conditions: $< 40^{\circ}$ C, $< 90^{\circ}$ C relative humidity.

Post Solder Cleaning and Drying Considerations

Post solder cleaning is usually the final circuit board assembly process prior to electrical board testing. The result of inadequate cleaning and drying can affect both the reliability of a power module and the testability of the finished circuit board assembly. For guidance on appropriate soldering, cleaning and drying procedures, refer to Board Mounted Power Modules: Soldering and Cleaning Application Note (AN04-001).



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61. REVISION HISTORY

DATE	REVISION	CHANGES DETAIL	APPROVAL
2012-03-20	А	First release.	HL.Lu
2012-05-03	В	Adding the patent info.	HL.Lu
2015-07-02	С	Update part selection, output specifications, general specifications, safety considerations, analog voltage margining, output voltage adjustment using the power management bus, power management bus adjustable overcurrent warning, power management bus adjustable input undervoltage lockout, measuring output current using the power management bus, summary of supported power management bus commands, thermal considerations, example application circuit, packaging details, MSL rating.	XF.Jiang
2021-07-23	AD	Add object ID and module photo. Update to new form. Update safety certificate and altitude.	XF.Jiang

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