To our customers,

Old Company Name in Catalogs and Other Documents

On April 1st, 2010, NEC Electronics Corporation merged with Renesas Technology Corporation, and Renesas Electronics Corporation took over all the business of both companies. Therefore, although the old company name remains in this document, it is a valid Renesas Electronics document. We appreciate your understanding.

Renesas Electronics website: http://www.renesas.com

April 1st, 2010
Renesas Electronics Corporation

Issued by: Renesas Electronics Corporation (http://www.renesas.com)

Send any inquiries to http://www.renesas.com/inquiry.

Downloaded from Arrow.com.

Notice

1. All information included in this document is current as of the date this document is issued. Such information, however, is subject to change without any prior notice. Before purchasing or using any Renesas Electronics products listed herein, please confirm the latest product information with a Renesas Electronics sales office. Also, please pay regular and careful attention to additional and different information to be disclosed by Renesas Electronics such as that disclosed through our website.
2. Renesas Electronics does not assume any liability for infringement of patents, copyrights, or other intellectual property rights of third parties by or arising from the use of Renesas Electronics products or technical information described in this document. No license, express, implied or otherwise, is granted hereby under any patents, copyrights or other intellectual property rights of Renesas Electronics or others.
3. You should not alter, modify, copy, or otherwise misappropriate any Renesas Electronics product, whether in whole or in part.
4. Descriptions of circuits, software and other related information in this document are provided only to illustrate the operation of semiconductor products and application examples. You are fully responsible for the incorporation of these circuits, software, and information in the design of your equipment. Renesas Electronics assumes no responsibility for any losses incurred by you or third parties arising from the use of these circuits, software, or information.
5. When exporting the products or technology described in this document, you should comply with the applicable export control laws and regulations and follow the procedures required by such laws and regulations. You should not use Renesas Electronics products or the technology described in this document for any purpose relating to military applications or use by the military, including but not limited to the development of weapons of mass destruction. Renesas Electronics products and technology may not be used for or incorporated into any products or systems whose manufacture, use, or sale is prohibited under any applicable domestic or foreign laws or regulations.
6. Renesas Electronics has used reasonable care in preparing the information included in this document, but Renesas Electronics does not warrant that such information is error free. Renesas Electronics assumes no liability whatsoever for any damages incurred by you resulting from errors in or omissions from the information included herein.
7. Renesas Electronics products are classified according to the following three quality grades: "Standard", "High Quality", and "Specific". The recommended applications for each Renesas Electronics product depends on the product's quality grade, as indicated below. You must check the quality grade of each Renesas Electronics product before using it in a particular application. You may not use any Renesas Electronics product for any application categorized as "Specific" without the prior written consent of Renesas Electronics. Further, you may not use any Renesas Electronics product for any application for which it is not intended without the prior written consent of Renesas Electronics. Renesas Electronics shall not be in any way liable for any damages or losses incurred by you or third parties arising from the use of any Renesas Electronics product for an application categorized as "Specific" or for which the product is not intended where you have failed to obtain the prior written consent of Renesas Electronics. The quality grade of each Renesas Electronics product is "Standard" unless otherwise expressly specified in a Renesas Electronics data sheets or data books, etc.

   "Standard": Computers; office equipment; communications equipment; test and measurement equipment; audio and visual equipment; home electronic appliances; machine tools; personal electronic equipment; and industrial robots.

   "High Quality": Transportation equipment (automobiles, trains, ships, etc.); traffic control systems; anti-disaster systems; anti-crime systems; safety equipment; and medical equipment not specifically designed for life support.

   "Specific": Aircraft; aerospace equipment; submersible repeaters; nuclear reactor control systems; medical equipment or systems for life support (e.g. artificial life support devices or systems), surgical implantations, or healthcare intervention (e.g. excision, etc.), and any other applications or purposes that pose a direct threat to human life.
8. You should use the Renesas Electronics products described in this document within the range specified by Renesas Electronics, especially with respect to the maximum rating, operating supply voltage range, movement power voltage range, heat radiation characteristics, installation and other product characteristics. Renesas Electronics shall have no liability for malfunctions or damages arising out of the use of Renesas Electronics products beyond such specified ranges.
9. Although Renesas Electronics endeavors to improve the quality and reliability of its products, semiconductor products have specific characteristics such as the occurrence of failure at a certain rate and malfunctions under certain use conditions. Further, Renesas Electronics products are not subject to radiation resistance design. Please be sure to implement safety measures to guard them against the possibility of physical injury, and injury or damage caused by fire in the event of the failure of a Renesas Electronics product, such as safety design for hardware and software including but not limited to redundancy, fire control and malfunction prevention, appropriate treatment for aging degradation or any other appropriate measures. Because the evaluation of microcomputer software alone is very difficult, please evaluate the safety of the final products or system manufactured by you.
10. Please contact a Renesas Electronics sales office for details as to environmental matters such as the environmental compatibility of each Renesas Electronics product. Please use Renesas Electronics products in compliance with all applicable laws and regulations that regulate the inclusion or use of controlled substances, including without limitation, the EU RoHS Directive. Renesas Electronics assumes no liability for damages or losses occurring as a result of your noncompliance with applicable laws and regulations.
11. This document may not be reproduced or duplicated, in any form, in whole or in part, without prior written consent of Renesas Electronics.
12. Please contact a Renesas Electronics sales office if you have any questions regarding the information contained in this document or Renesas Electronics products, or if you have any other inquiries.

(Note 1) "Renesas Electronics" as used in this document means Renesas Electronics Corporation and also includes its majority-owned subsidiaries.

(Note 2) "Renesas Electronics product(s)" means any product developed or manufactured by or for Renesas Electronics.

Downloaded from Arrow.com.

3858 Group

SINGLE-CHIP 8-BIT CMOS MICROCOMPUTER

REJ03B0139-0111
Rev.1.11
Dec 18, 2008

DESCRIPTION

The 3858 group is the 8-bit microcomputer based on the 740 family core technology.
The 3858 group is designed for the household products and office automation equipment and includes serial interface functions, 8-bit timer, 16-bit timer, and A/D converter.

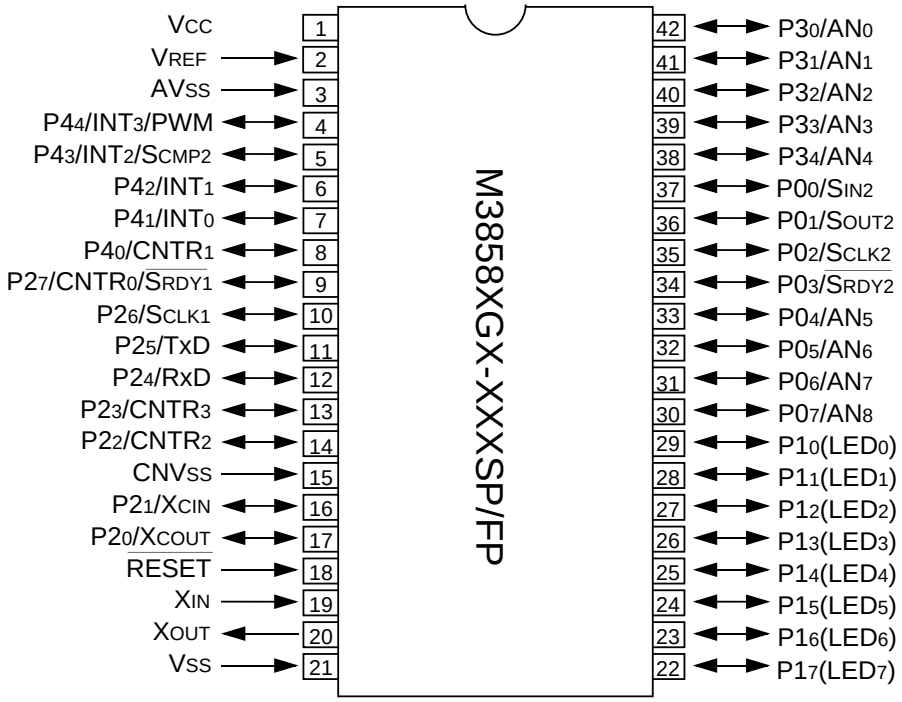
FEATURES

- Basic machine-language instructions 71
- Minimum instruction execution time ..... 0.32 µs
  (at 12.5 MHz oscillation frequency)
- Memory size
  ROM ..... 48 K bytes
  RAM ..... 1.5 K bytes
- Programmable input/output ports 34
- On-chip software pull-up resistor ..... Built-in
- Interrupts ..... 19 sources, 16 vectors
  (external 8, internal 10, software 1)
- Timers ..... 8-bit × 4
  ..... 16-bit × 2
- Serial interface
  Serial I/O1 ..... 8-bit × 1 (UART or Clock-synchronized)
  Serial I/O2 ..... 8-bit × 1 (Clock-synchronized)
- PWM ..... 8-bit × 1
- A/D converter ..... 8-bit × 9 channels
- Clock generating circuit ..... Built-in 2 circuits
  (connect to external ceramic resonator or quartz-crystal oscillator)
- Watchdog timer ..... 16-bit × 1
- Power source voltage
  In high-speed mode ..... 4.0 to 5.5 V
  (at 12.5 MHz oscillation frequency)
  In high-speed mode ..... 2.7 to 5.5 V
  (at 6 MHz oscillation frequency)
  In middle-speed mode ..... 2.7 to 5.5 V
  (at 12.5 MHz oscillation frequency, at middle-speed mode)
  In low-speed mode ..... 2.7 to 5.5 V
  (at 32 kHz oscillation frequency)
- Operating temperature range ..... –20 to 85°C

APPLICATION

Office automation equipment, Factory automation equipment, Household products, Consumer electronics, etc.

PIN CONFIGURATION (TOP VIEW)



Package type : PRDP0042BA-A (42P4B)
PRSP0042GA-A/B (42P2R-A/E)

Fig. 1 Pin configuration of M3858XGX-XXXSP/FP

Downloaded from Arrow.com.

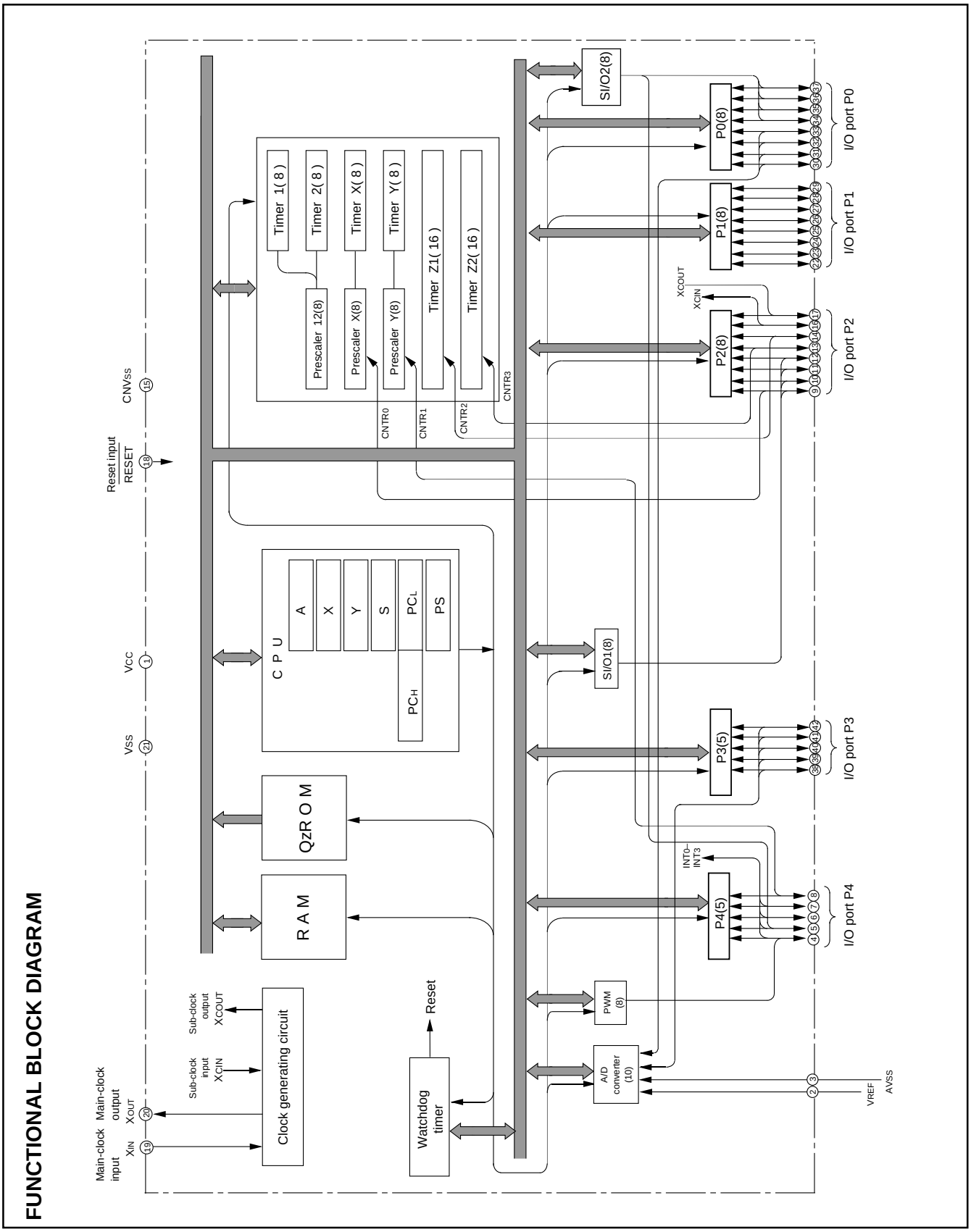


Fig. 2 Functional block diagram

Downloaded from Arrow.com.

PIN DESCRIPTION

Table 1 Pin description

Pin	Name	Functions	Function except a port function
VCC, VSS	Power source	•Apply voltage of 2.7 V – 5.5 V to Vcc, and 0 V to Vss.	
CNVSS	CNVSS input	•This pin controls the operation mode of the chip and is shared with the VPP pin which is the power source input pin for programming the built-in QzROM. •Normally connected to VSS.	
VREF	Reference voltage	•Reference voltage input pin for A/D converter.	
AVss	Analog power source	•Analog power source input pin for A/D converter. •Connect to Vss.	
$\overline{\text{RESET}}$	Reset input	•Reset input pin for active “L”.	
XIN	Clock input	•Input and output pins for the clock generating circuit. •Connect a ceramic resonator or quartz-crystal oscillator between the XIN and XOUT pins to set the oscillation frequency. •When an external clock is used, connect the clock source to the XIN pin and leave the XOUT pin open.	
XOUT	Clock output		
P00/SIN2 P01/SOUT2 P02/SCLK2 P03/$\overline{\text{SRDY2}}$	I/O port P0	•8-bit I/O port. •I/O direction register allows each pin to be individually programmed as either input or output. •CMOS compatible input level. •CMOS 3-state output structure. •Pull-up control is enabled in a bit unit.	• Serial I/O2 function pin
P04/AN5–P07/AN8			• A/D converter input pin
P10–P17	I/O port P1	•P10 to P17 (8 bits) are enabled to output large current for LED drive.	
P20/XCOUT P21/XCIN	I/O port P2	•8-bit I/O port. •I/O direction register allows each pin to be individually programmed as either input or output. •CMOS compatible input level. •CMOS3-state output structure. •Pull-up control is enabled in a bit unit.	• Sub-clock generating circuit I/O pins (connect a resonator)
P22/CNTR2			• Timer Z1 function pin
P23/CNTR3			• Timer Z2 function pin
P24/RxD P25/TxD P26/SCLK1			• Serial I/O1 function pin
P27/CNTR0/$\overline{\text{SRDY1}}$			• Timer X function pin/ Serial I/O1 function pin
P30/AN0– P34/AN4	I/O port P3	•5-bit I/O port with the same function as port P0. •CMOS compatible input level. •CMOS 3-state output structure. •Pull-up control is enabled in a bit unit.	• A/D converter input pin
P40/CNTR1	I/O port P4	•5-bit I/O port with the same function as port P0. •CMOS compatible input level. •CMOS 3-state output structure. •Pull-up control is enabled in a bit unit.	• Timer Y function pin
P41/INT0 P42/INT1			• Interrupt input pins
P43/INT2/SCMP2			• Interrupt input pin • SCMP2 output pin
P44/INT3/PWM			• Interrupt input pin • PWM output pin

Downloaded from Arrow.com.

PART NUMBERING

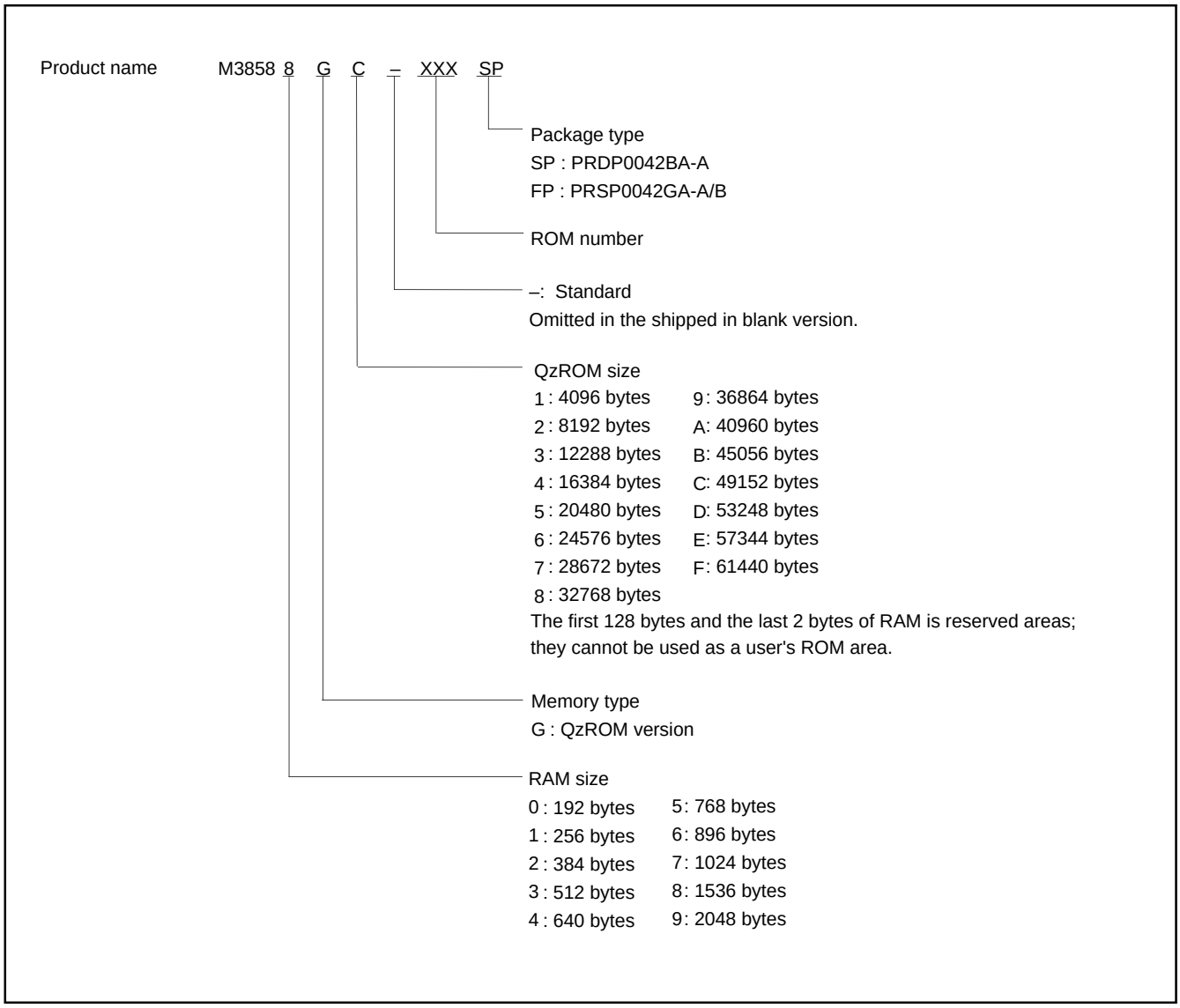


Fig. 3 Part numbering

Downloaded from Arrow.com.

GROUP EXPANSION

Renesas Technology plans to expand the 3858 group as follows.

Memory Type

Support for QzROM version.

Memory Size

QzROM size ..... 48 K bytes
RAM size ..... 1.5 K bytes

Packages

PRDP0042BA-A ..... 42-pin shrink plastic-molded SDIP
PRSP0042GA-A/B ..... 42-pin plastic-molded SSOP

Memory Expansion Plan

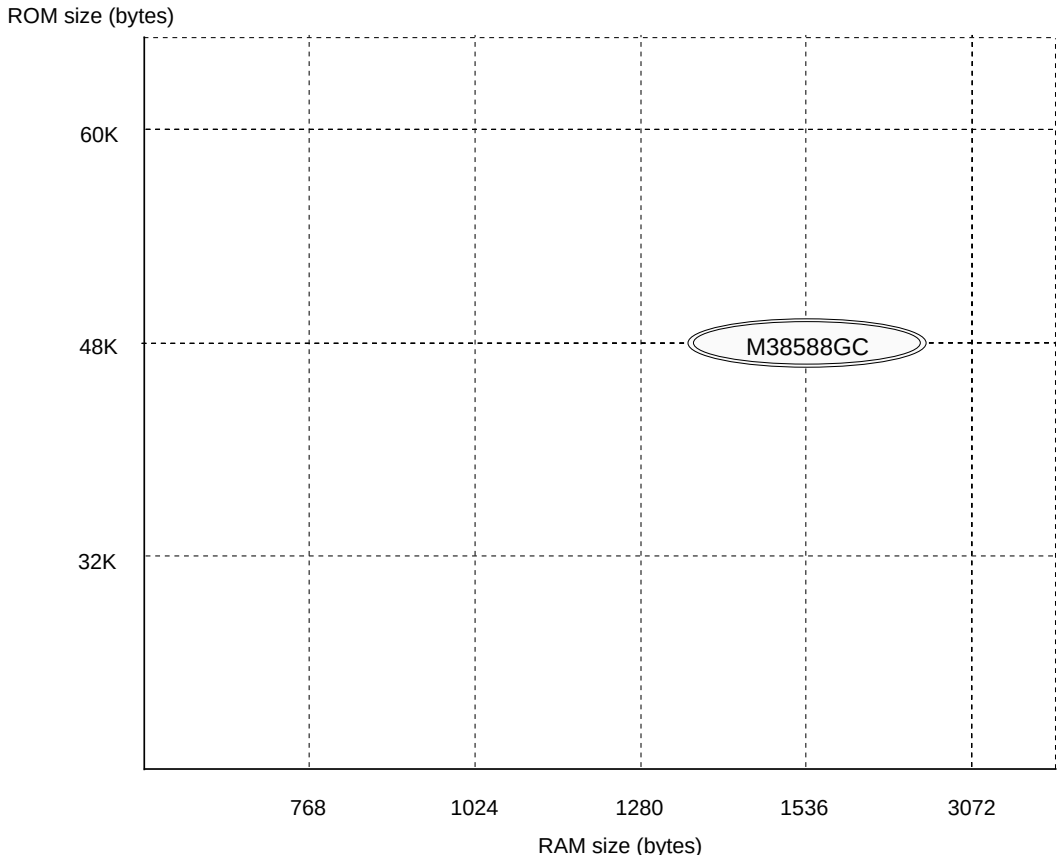


Fig. 4 Memory expansion plan

Table 2 List of products

Part number	ROM size (bytes) ROM size for User in ( )	RAM size (bytes)	Package	Remarks
M38588GC-XXXSP	49152 (49021)	1536	PRDP0042BA-A	
M38588GC-XXXFP			PRSP0042GA-A/B	
M38588GCSP	49152 (49021)	1536	PRDP0042BA-A	Blank
M38588GCFP			PRSP0042GA-A/B	

Downloaded from Arrow.com.

FUNCTIONAL DESCRIPTION
CENTRAL PROCESSING UNIT (CPU)

The 3858 group uses the standard 740 Family instruction set. Refer to the table of 740 Family addressing modes and machine instructions or the 740 Family Software Manual for details on the instruction set.

Machine-resident 740 Family instructions are as follows:

The FST and SLW instructions cannot be used.

The STP, WIT, MUL, and DIV instructions can be used.

[Accumulator (A)]

The accumulator is an 8-bit register. Data operations such as data transfer, etc., are executed mainly through the accumulator.

[Index Register X (X)]

The index register X is an 8-bit register. In the index addressing modes, the value of the OPERAND is added to the contents of register X and specifies the real address.

[Index Register Y (Y)]

The index register Y is an 8-bit register. In partial instruction, the value of the OPERAND is added to the contents of register Y and specifies the real address.

[Stack Pointer (S)]

The stack pointer is an 8-bit register used during subroutine calls and interrupts. This register indicates start address of stored area (stack) for storing registers during subroutine calls and interrupts.

The low-order 8 bits of the stack address are determined by the contents of the stack pointer. The high-order 8 bits of the stack address are determined by the stack page selection bit. If the stack page selection bit is “0” , the high-order 8 bits becomes “00_{16}”. If the stack page selection bit is “1”, the high-order 8 bits becomes “01_{16}”.

The operations of pushing register contents onto the stack and popping them from the stack are shown in Figure 6.

Store registers other than those described in Figure 6 with program when the user needs them during interrupts or subroutine calls (see Table 3).

[Program Counter (PC)]

The program counter is a 16-bit counter consisting of two 8-bit registers PC_H and PC_L. It is used to indicate the address of the next instruction to be executed.

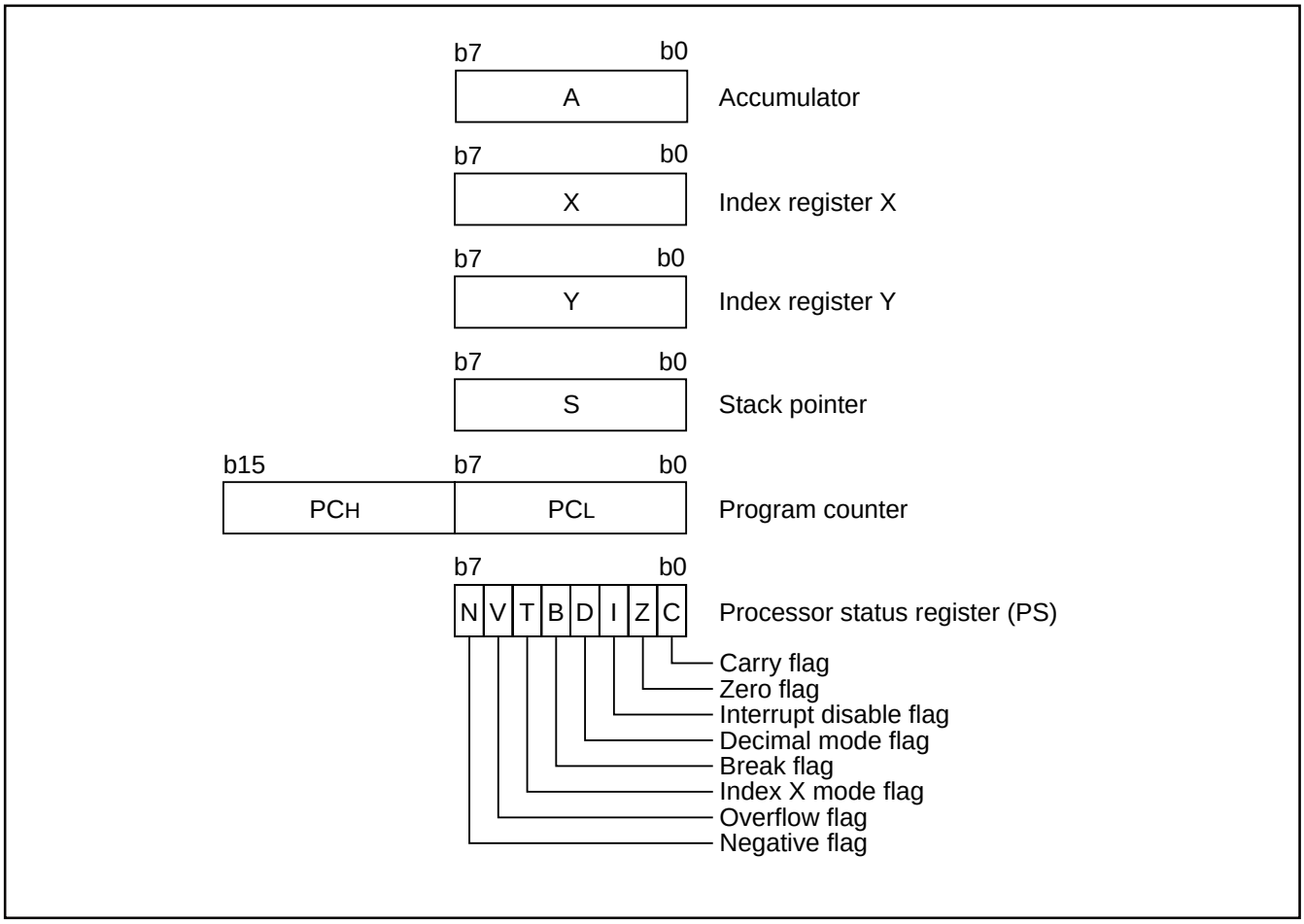


Fig. 5 740 Family CPU register structure

Downloaded from Arrow.com.

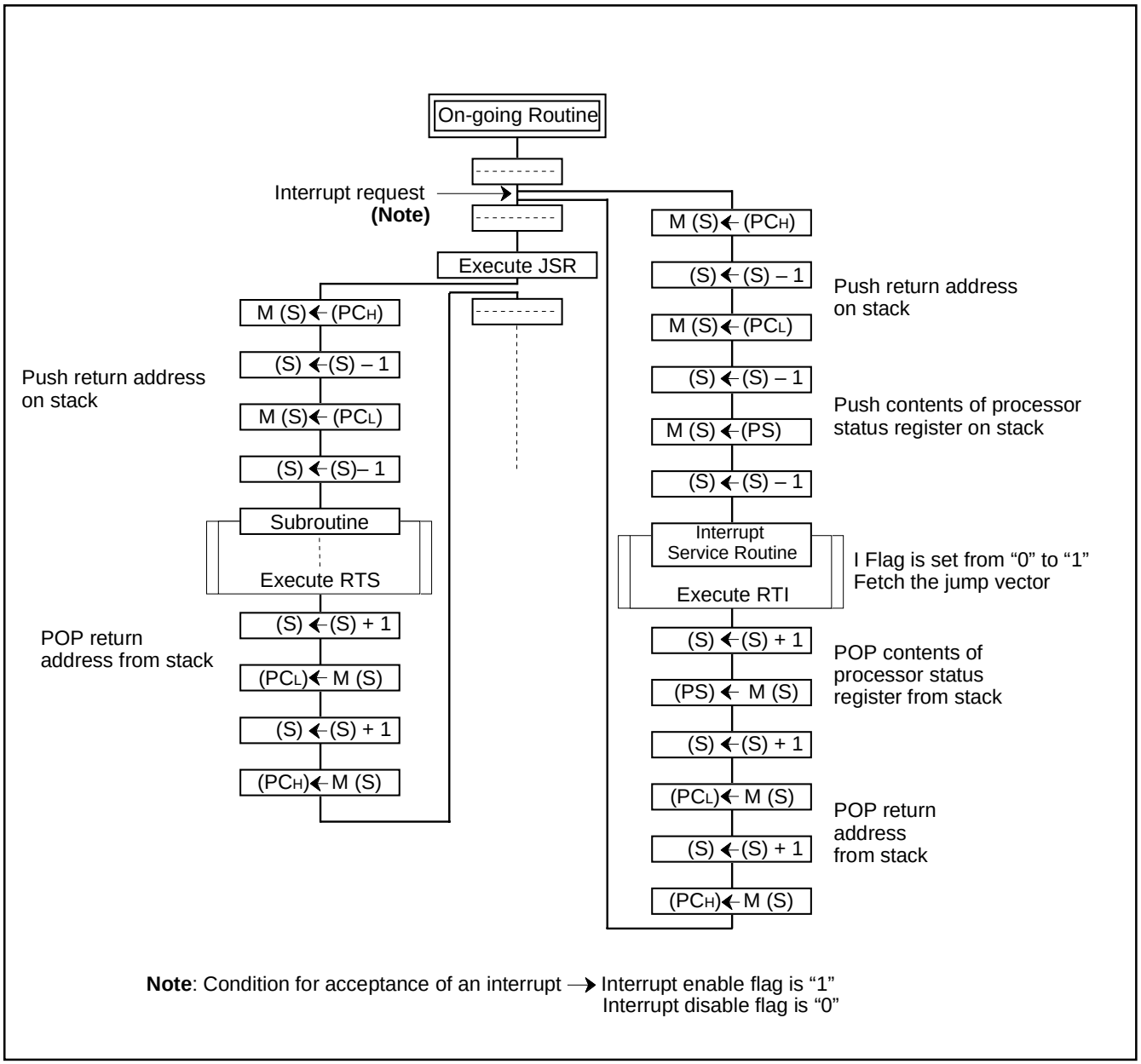


Fig. 6 Register push and pop at interrupt generation and subroutine call

Table 3 Push and pop instructions of accumulator or processor status register

	Push instruction to stack	Pop instruction from stack
Accumulator	PHA	PLA
Processor status register	PHP	PLP

Downloaded from Arrow.com.

[Processor status register (PS)]

The processor status register is an 8-bit register consisting of 5 flags which indicate the status of the processor after an arithmetic operation and 3 flags which decide MCU operation. Branch operations can be performed by testing the Carry (C) flag , Zero (Z) flag, Overflow (V) flag, or the Negative (N) flag. In decimal mode, the Z, V, N flags are not valid.

•Bit 0: Carry flag (C)

The C flag contains a carry or borrow generated by the arithmetic logic unit (ALU) immediately after an arithmetic operation. It can also be changed by a shift or rotate instruction.

•Bit 1: Zero flag (Z)

The Z flag is set if the result of an immediate arithmetic operation or a data transfer is “0”, and cleared if the result is anything other than “0”.

•Bit 2: Interrupt disable flag (I)

The I flag disables all interrupts except for the interrupt generated by the BRK instruction.

Interrupts are disabled when the I flag is “1”.

•Bit 3: Decimal mode flag (D)

The D flag determines whether additions and subtractions are executed in binary or decimal. Binary arithmetic is executed when this flag is “0”; decimal arithmetic is executed when it is “1”. Decimal correction is automatic in decimal mode. Only the ADC and SBC instructions can be used for decimal arithmetic.

•Bit 4: Break flag (B)

The B flag is used to indicate that the current interrupt was generated by the BRK instruction. The BRK flag in the processor status register is always “0”. When the BRK instruction is used to generate an interrupt, the processor status register is pushed onto the stack with the break flag set to “1”.

•Bit 5: Index X mode flag (T)

When the T flag is “0”, arithmetic operations are performed between accumulator and memory. When the T flag is “1”, direct arithmetic operations and direct data transfers are enabled between memory locations.

•Bit 6: Overflow flag (V)

The V flag is used during the addition or subtraction of one byte of signed data. It is set if the result exceeds +127 to -128. When the BIT instruction is executed, bit 6 of the memory location operated on by the BIT instruction is stored in the overflow flag.

•Bit 7: Negative flag (N)

The N flag is set if the result of an arithmetic operation or data transfer is negative. When the BIT instruction is executed, bit 7 of the memory location operated on by the BIT instruction is stored in the negative flag.

Table 4 Set and clear instructions of each bit of processor status register

	C flag	Z flag	I flag	D flag	B flag	T flag	V flag	N flag
Set instruction	SEC	–	SEI	SED	–	SET	–	–
Clear instruction	CLC	–	CLI	CLD	–	CLT	CLV	–

Downloaded from Arrow.com.

[CPU Mode Register (CPUM)] 003B16

The CPU mode register contains the stack page selection bit, etc.
The CPU mode register is allocated at address 003B16.

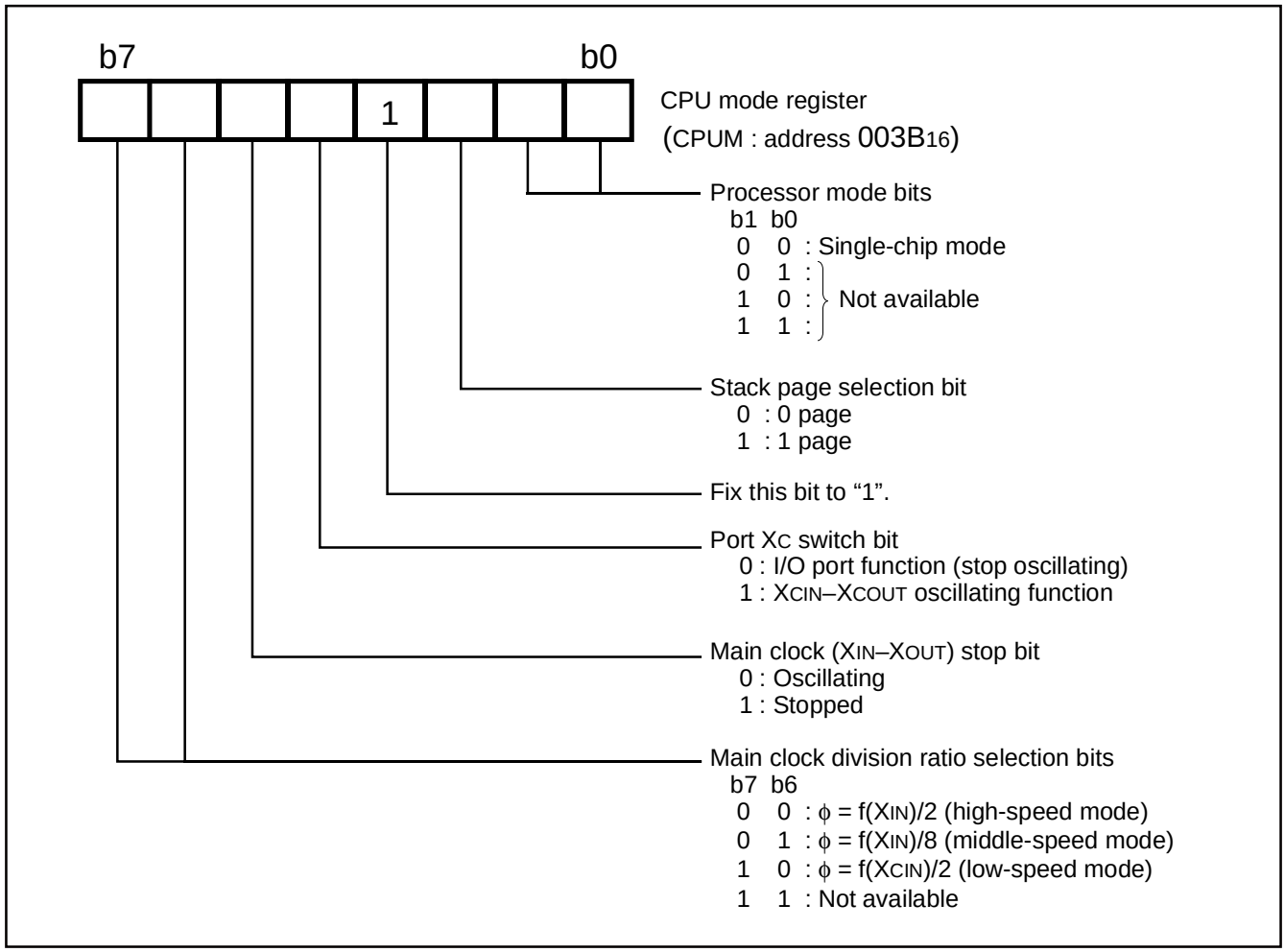


Fig. 7 Structure of CPU mode register

Downloaded from Arrow.com.

MEMORY

Special Function Register (SFR) Area

The Special Function Register area in the zero page contains control registers such as I/O ports and timers.

RAM

RAM is used for data storage and for stack area of subroutine calls and interrupts.

ROM

The first 128 bytes and the last 2 bytes of ROM are reserved for device testing and the rest is user area for storing programs.

Interrupt Vector Area

The interrupt vector area contains reset and interrupt vectors.

Zero Page

Access to this area with only 2 bytes is possible in the zero page addressing mode.

Special Page

Access to this area with only 2 bytes is possible in the special page addressing mode.

ROM Code Protect Address (address FFDB16)

Address FFDB16, which is the reserved ROM area of QzROM, is the ROM code protect address. "0016" is written into this address when selecting the protect bit write by using a serial programmer or selecting protect enabled for writing shipment by Renesas Technology corp.. When "0016" is set to the ROM code protect address, the protect function is enabled, so that reading or writing from/to QzROM is disabled by a serial programmer.

As for the QzROM product in blank, the ROM code is protected by selecting the protect bit write at ROM writing with a serial programmer.

As for the QzROM product shipped after writing, "0016" (protect enabled) or "FF16" (protect disabled) is written into the ROM code protect address when Renesas Technology corp. performs writing. The writing of "0016" or "FF16" can be selected as ROM option setup ("MASK option" written in the mask file converter) when ordering.

■ Notes

Because the contents of RAM are indefinite at reset, set initial values before using.

RAM area

RAM size (bytes)	Address XXXX16
192	00FF16
256	013F16
384	01BF16
512	023F16
640	02BF16
768	033F16
896	03BF16
1024	043F16
1536	063F16
2048	083F16

ROM area

ROM size (bytes)	Address YYYY16	Address ZZZZ16
4096	F00016	F08016
8192	E00016	E08016
12288	D00016	D08016
16384	C00016	C08016
20480	B00016	B08016
24576	A00016	A08016
28672	900016	908016
32768	800016	808016
36864	700016	708016
40960	600016	608016
45056	500016	508016
49152	400016	408016
53248	300016	308016
57344	200016	208016
61440	100016	108016

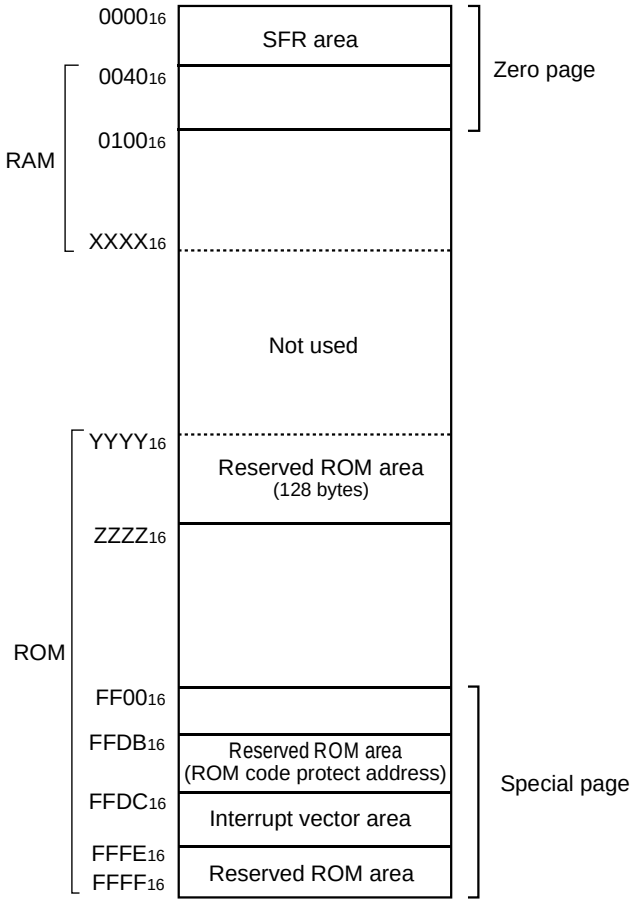


Fig. 8 Memory map diagram

Downloaded from Arrow.com.

000016	Port P0 (P0)	002016	Prescaler 12 (PRE12)
000116	Port P0 direction register (P0D)	002116	Timer 1 (T1)
000216	Port P1 (P1)	002216	Timer 2 (T2)
000316	Port P1 direction register (P1D)	002316	Timer XY mode register (TM)
000416	Port P2 (P2)	002416	Prescaler X (PREX)
000516	Port P2 direction register (P2D)	002516	Timer X (TX)
000616	Port P3 (P3)	002616	Prescaler Y (PREY)
000716	Port P3 direction register (P3D)	002716	Timer Y (TY)
000816	Port P4 (P4)	002816	Timer Z1 mode register (TZ1M)
000916	Port P4 direction register (P4D)	002916	Timer Z1 low-order (TZ1L)
000A16		002A16	Timer Z1 high-order (TZ1H)
000B16		002B16	Timer Z2 mode register (TZ2M)
000C16		002C16	Timer Z2 low-order (TZ2L)
000D16		002D16	Timer Z2 high-order (TZ2H)
000E16		002E16	Timer 12, X count source selection register (T12XCSS)
000F16		002F16	Timer Y, Z1 count source selection register (TYZ1CSS)
001016	Port P0 pull-up control register (PULL0)	003016	Timer Z2 count source selection register (TZ2CSS)
001116	Port P1 pull-up control register (PULL1)	003116	
001216	Port P2 pull-up control register (PULL2)	003216	
001316	Port P3 pull-up control register (PULL3)	003316	
001416	Port P4 pull-up control register (PULL4)	003416	AD control register (ADCON)
001516	Serial I/O2 control register 1 (SIO2CON1)	003516	AD conversion register (AD)
001616	Serial I/O2 control register 2 (SIO2CON2)	003616	Interrupt source selection register (INTSEL)
001716	Serial I/O2 register (SIO2)	003716	Reserved ✻
001816	Transmit/Receive buffer register (TB/RB)	003816	MISRG
001916	Serial I/O1 status register (SIOSTS)	003916	Watchdog timer control register (WDTCON)
001A16	Serial I/O1 control register (SIOCON)	003A16	Interrupt edge selection register (INTEDGE)
001B16	UART control register (UARTCON)	003B16	CPU mode register (CPUM)
001C16	Baud rate generator (BRG)	003C16	Interrupt request register 1 (IREQ1)
001D16	PWM control register (PWMCON)	003D16	Interrupt request register 2 (IREQ2)
001E16	PWM prescaler (PREPWM)	003E16	Interrupt control register 1 (ICON1)
001F16	PWM register (PWM)	003F16	Interrupt control register 2 (ICON2)

✻ Reserved : Do not write any data to this addresses, because these areas are reserved.

Fig. 9 Memory map of special function register (SFR)

Downloaded from Arrow.com.

I/O PORTS

The I/O ports have direction registers which determine the input/output direction of each individual pin. Each bit in a direction register corresponds to one pin, and each pin can be set to be input port or output port.

When "0" is written to the bit corresponding to a pin, that pin becomes an input pin. When "1" is written to that bit, that pin becomes an output pin.

If data is read from a pin which is set to output, the value of the port output latch is read, not the value of the pin itself. Pins set to input are floating. If a pin set to input is written to, only the port output latch is written to and the pin remains floating.

By setting the port P0 pull-up control register (address 0010_{16}), the port P1 pull-up control register (address 0011_{16}), the port P2 pull-up control register (address 0012_{16}), the port P3 pull-up control register (address 0013_{16}), or the port P4 pull-up control register (address 0014_{16}), ports can control pull-up with a program. However, the contents of these registers do not affect ports programmed as the output ports.

Table 5 I/O port function

Pin	Name	Input/Output	I/O Structure	Non-Port Function	Related SFRs	Ref.No.
P0$_0$/SIN$_2$ P0$_1$/SOUT$_2$ P0$_2$/SCLK$_2$ P0$_3$/$\overline{\text{SRDY}_2}$	Port P0	Input/output, individual bits	CMOS compatible input level CMOS 3-state output	Serial I/O2 function I/O	Serial I/O2 control register	(1) (2) (3) (4)
P0$_4$/AN$_5$–P0$_7$AN$_8$				A/D converter input	AD control register AD input selection register	(13)
P1$_0$–P1$_7$	Port P1					(5)
P2$_0$/XCOUT P2$_1$/XCIN	Port P2			Sub-clock generating circuit	CPU mode register	(6) (7)
P2$_2$/CNTR$_2$				Timer Z1 function I/O	Timer Z1 mode register	(8)
P2$_3$/CNTR$_3$				Timer Z2 function I/O	Timer Z2 mode register	(8)
P2$_4$/RxD P2$_5$/TxD P2$_6$/SCLK$_1$				Serial I/O1 function I/O	Serial I/O1 control register	(9) (10) (11)
P2$_7$/CNTR$_0$/$\overline{\text{SRDY}_1}$				Timer X function I/O Serial I/O1 function I/O	Timer XY mode register Serial I/O1 control register	(12)
P3$_0$/AN$_0$– P3$_4$/AN$_4$	Port P3 **(Note)**			A/D converter input	AD control register AD input selection register	(13)
P4$_0$/CNTR$_1$	Port P4 **(Note)**			Timer Y function I/O	Timer XY mode register	(14)
P4$_1$/INT$_0$ P4$_2$/INT$_1$				External interrupt input	Interrupt edge selection register	(15)
P4$_3$/INT$_2$/SCMP$_2$				External interrupt input SCMP$_2$ output	Interrupt edge selection register Serial I/O2 control register	(16)
P4$_4$/INT$_3$/PWM				External interrupt input PWM output	Interrupt edge selection register PWM control register	(17)

Note: When bits 5 to 7 of Ports P3 and P4 are read out, the contents are undefined.

Downloaded from Arrow.com.

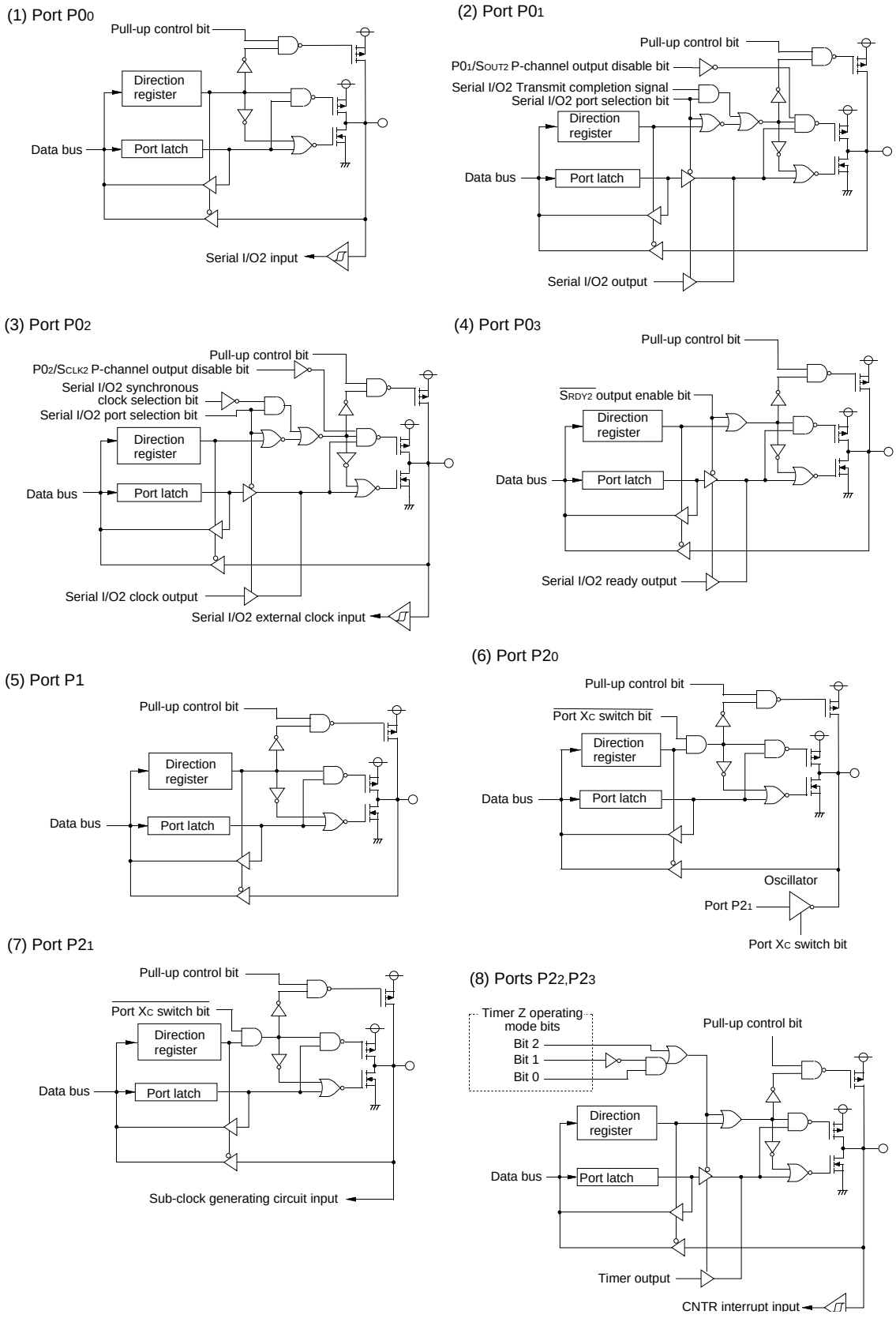


Fig. 10 Port block diagram (1)

Downloaded from Arrow.com.

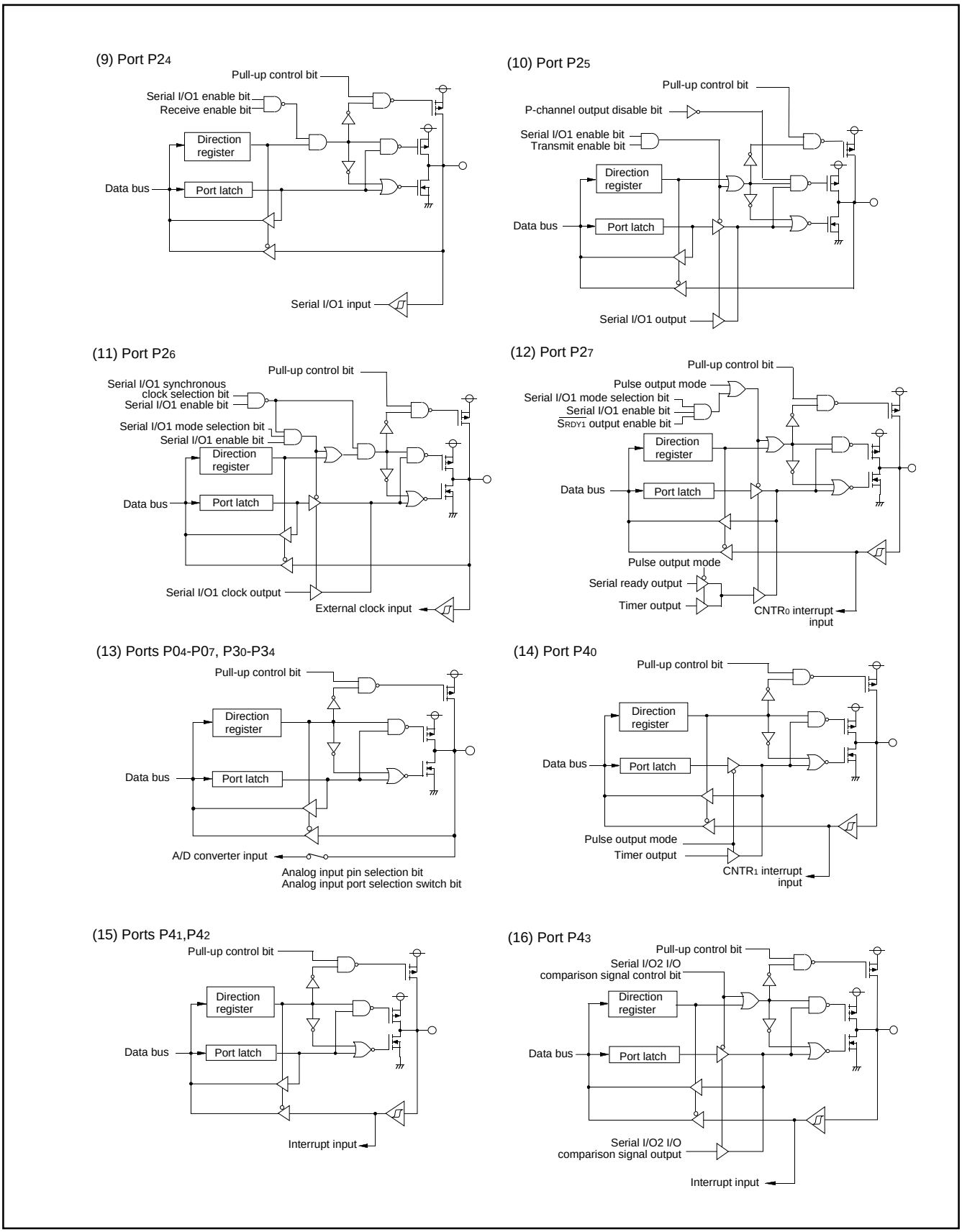


Fig. 11 Port block diagram (2)

Downloaded from Arrow.com.

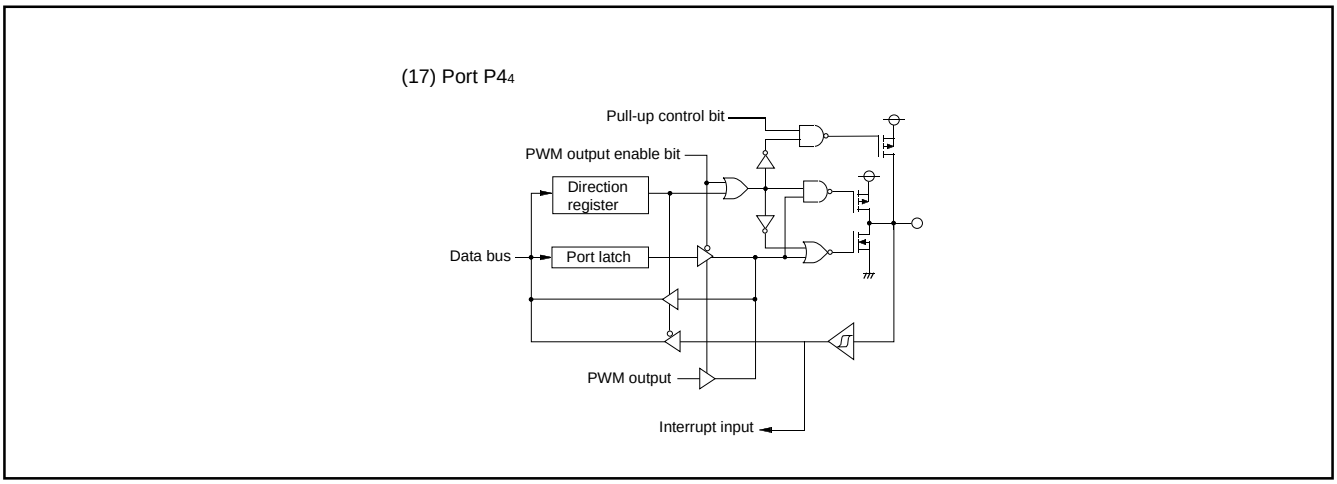
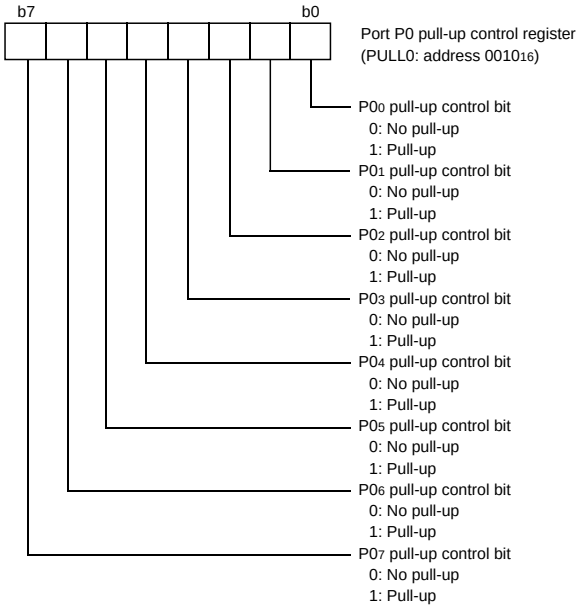
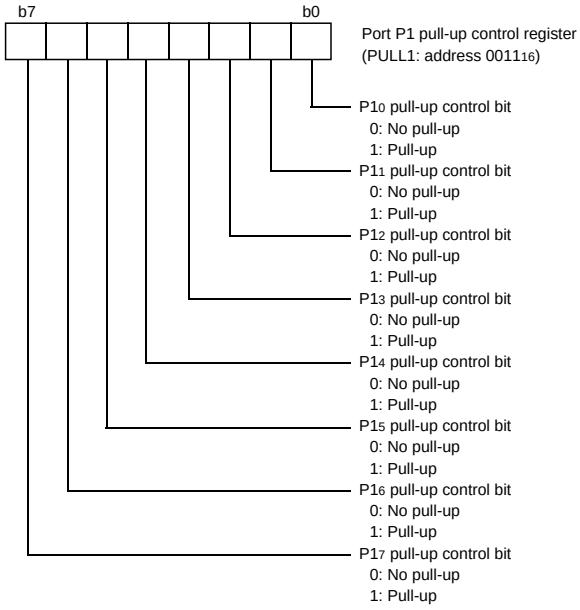


Fig. 12 Port block diagram (3)

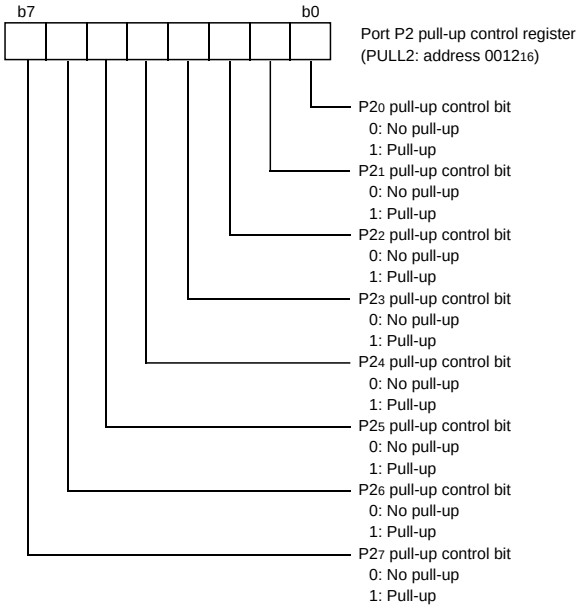
Downloaded from Arrow.com.



Note: Pull-up control is valid when the corresponding bit of the port direction register is "0" (input).
When that bit is "1" (output), pull-up cannot be set to the port of which pull-up is selected.



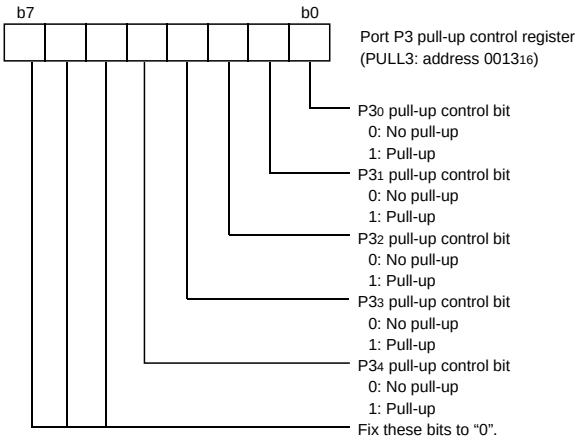
Note: Pull-up control is valid when the corresponding bit of the port direction register is "0" (input).
When that bit is "1" (output), pull-up cannot be set to the port of which pull-up is selected.



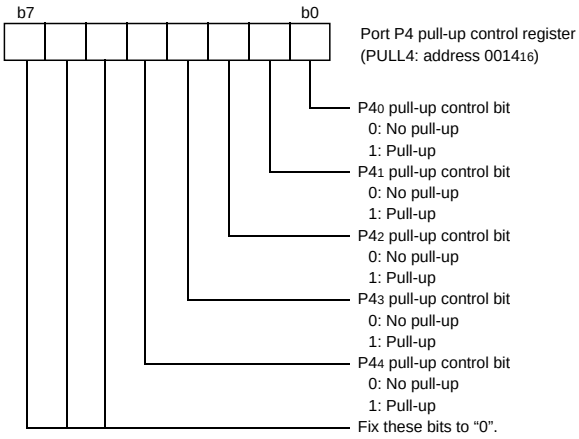
Note: Pull-up control is valid when the corresponding bit of the port direction register is "0" (input).
When that bit is "1" (output), pull-up cannot be set to the port of which pull-up is selected.

Fig. 13 Structure of port registers (1)

Downloaded from Arrow.com.



Note: Pull-up control is valid when the corresponding bit of the port direction register is “0” (input).
When that bit is “1” (output), pull-up cannot be set to the port of which pull-up is selected.



Note: Pull-up control is valid when the corresponding bit of the port direction register is “0” (input).
When that bit is “1” (output), pull-up cannot be set to the port of which pull-up is selected.

Fig. 14 Structure of port registers (2)

Downloaded from Arrow.com.

INTERRUPTS

The 3858 group's interrupts are a type of vector and occur by 16 sources among 19 sources: eight external, ten internal, and one software.

Interrupt Control

Each interrupt is controlled by an interrupt request bit, an interrupt enable bit, and the interrupt disable flag except for the software interrupt set by the BRK instruction. An interrupt occurs if the corresponding interrupt request and enable bits are “1” and the interrupt disable flag is “0”.

Interrupt enable bits can be set or cleared by software.

Interrupt request bits can be cleared by software, but cannot be set by software.

The reset and the BRK instruction cannot be disabled with any flag or bit. The I (interrupt disable) flag disables all interrupts except the reset and the BRK instruction interrupt.

When several interrupt requests occur at the same time, the interrupts are received according to priority.

Interrupt Operation

By acceptance of an interrupt, the following operations are automatically performed:

1. The contents of the program counter and the processor status register are automatically pushed onto the stack.
2. The interrupt disable flag is set and the corresponding interrupt request bit is cleared.
3. The interrupt jump destination address is read from the vector table into the program counter.

Interrupt Source Selection

Which of each combination of the following interrupt sources can be selected by the interrupt source selection register (address 0039_{16}).

1. INT_3 or Serial I/O2
2. Timer Z1 or $CNTR_2$
3. Timer Z2 or $CNTR_3$
4. $CNTR_0$ or $CNTR_2$
5. $CNTR_1$ or $CNTR_3$

Downloaded from Arrow.com.

Table 6 Interrupt vector addresses and priority

Interrupt Source	Priority	Vector Addresses (Note 1)		Interrupt Request Generating Conditions	Remarks
		High	Low		
Reset (Note 2)	1	FFFD16	FFFC16	At reset	Non-maskable
INT0	2	FFFB16	FFFA16	At detection of either rising or falling edge of INT0 input	External interrupt (active edge selectable)
Timer Z1	3	FFF916	FFF816	At timer Z1 underflow	
CNTR2				At detection of either rising or falling edge of CNTR2 input	External interrupt (active edge selectable)
INT1	4	FFF716	FFF616	At detection of either rising or falling edge of INT1 input	External interrupt (active edge selectable)
INT2	5	FFF516	FFF416	At detection of either rising or falling edge of INT2 input	External interrupt (active edge selectable)
INT3	6	FFF316	FFF216	At detection of either rising or falling edge of INT3 input	External interrupt (active edge selectable)
Serial I/O2				At completion of serial I/O2 data transmission or reception	Valid when serial I/O2 is selected
Timer Z2	7	FFF116	FFF016	At timer Z2 underflow	
CNTR3				At detection of either rising or falling edge of CNTR3 input	External interrupt (active edge selectable)
Timer X	8	FFEF16	FFEE16	At timer X underflow	
Timer Y	9	FFED16	FFEC16	At timer Y underflow	
Timer 1	10	FFEB16	FFEA16	At timer 1 underflow	STP release timer underflow
Timer 2	11	FFE916	FFE816	At timer 2 underflow	
Serial I/O1 reception	12	FFE716	FFE616	At completion of serial I/O1 data reception	Valid when serial I/O1 is selected
Serial I/O1 transmission	13	FFE516	FFE416	At completion of serial I/O1 transmission shift or when transmission buffer is empty	Valid when serial I/O1 is selected
CNTR0	14	FFE316	FFE216	At detection of either rising or falling edge of CNTR0 input	External interrupt (active edge selectable)
CNTR2				At detection of either rising or falling edge of CNTR2 input	
CNTR1	15	FFE116	FFE016	At detection of either rising or falling edge of CNTR1 input	External interrupt (active edge selectable)
CNTR3				At detection of either rising or falling edge of CNTR3 input	
A/D converter	16	FFDF16	FFDE16	At completion of A/D conversion	
BRK instruction	17	FFDD16	FFDC16	At BRK instruction execution	Non-maskable software interrupt

Notes 1: Vector addresses contain interrupt jump destination addresses.
2: Reset function in the same way as an interrupt with the highest priority.

Downloaded from Arrow.com.

■ Notes

When setting the followings, the interrupt request bit may be set to "1".

•When setting external interrupt active edge
Related register: Interrupt edge selection register (address 003A16)
Timer XY mode register (address 002316)
Timer Z1 mode register (address 002816)
Timer Z2 mode register (address 002B16)

•When switching interrupt sources of an interrupt vector address where two or more interrupt sources are allocated
Related register: Interrupt source selection register (address 003616)

When not requiring for the interrupt occurrence synchronized with these setting, take the following sequence.

①Set the corresponding interrupt enable bit to "0" (disabled).
②Set the interrupt edge select bit or the interrupt source select bit to "1".
③Set the corresponding interrupt request bit to "0" after 1 or more instructions have been executed.
④Set the corresponding interrupt enable bit to "1" (enabled).

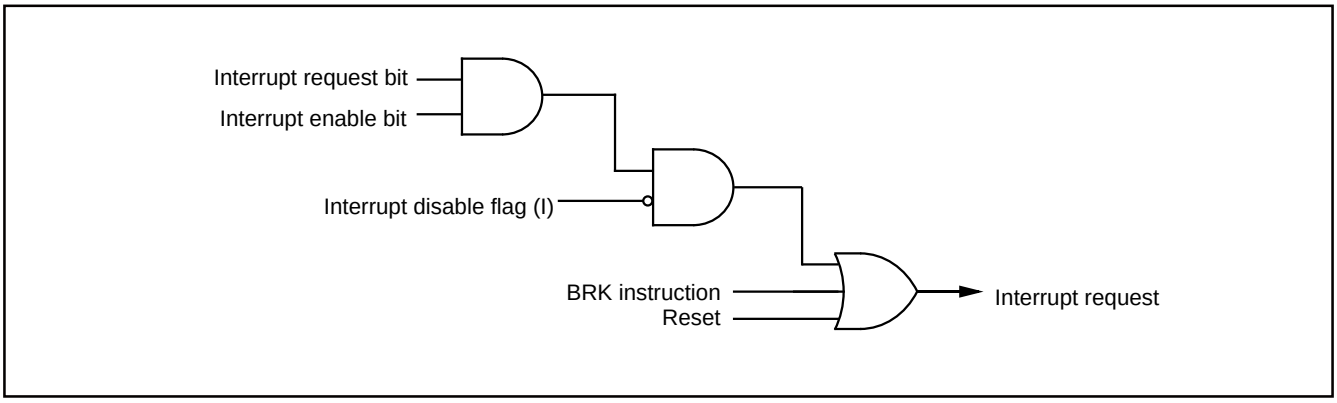


Fig. 15 Interrupt control

Downloaded from Arrow.com.

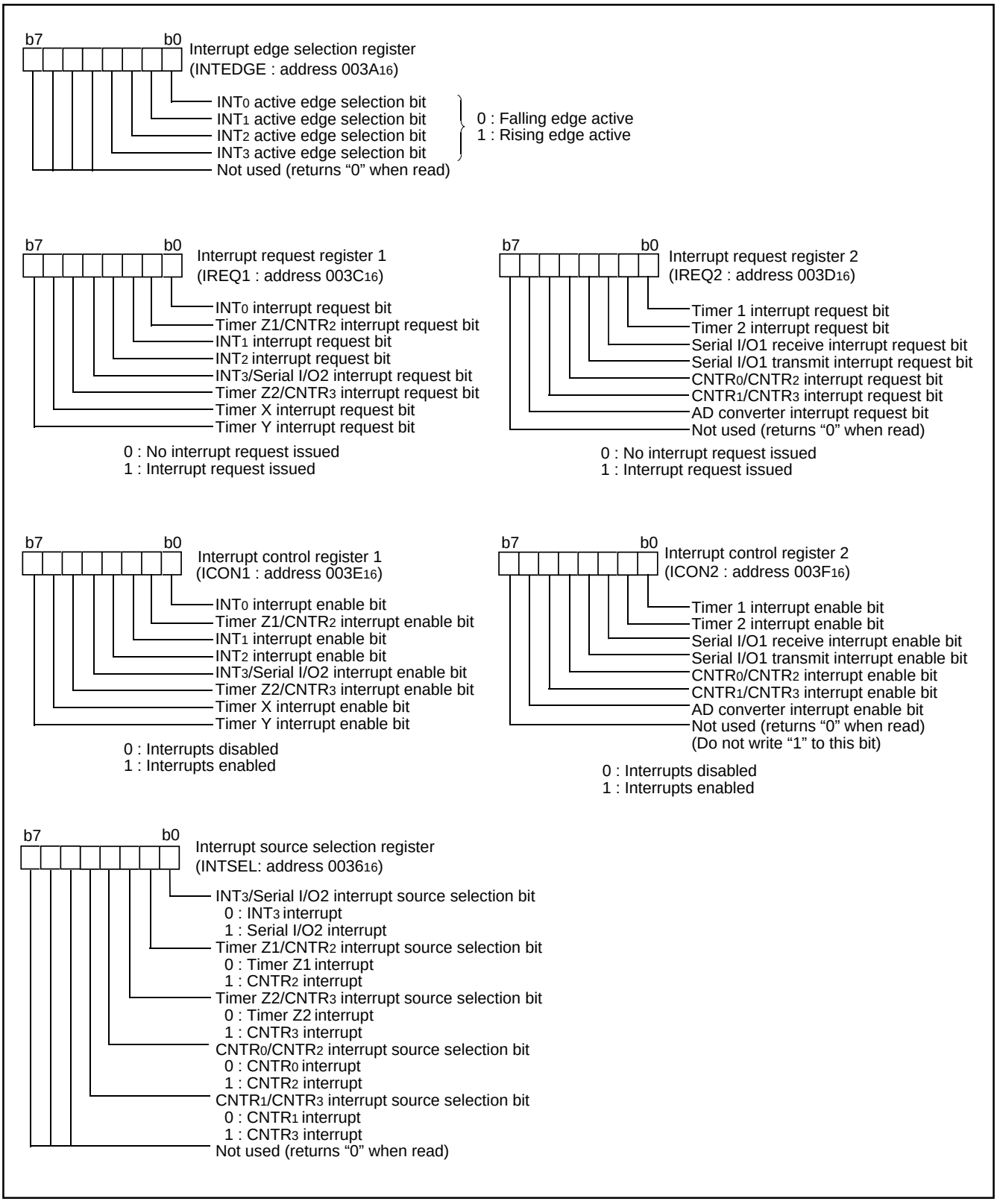


Fig. 16 Structure of interrupt-related registers

Downloaded from Arrow.com.

TIMERS

●8-bit Timers

The 3858 group has four 8-bit timers: timer 1, timer 2, timer X, and timer Y.

The timer 1 and timer 2 use one prescaler in common, and the timer X and timer Y use each prescaler. Those are 8-bit prescalers. Each of the timers and prescalers has a timer latch or a prescaler latch.

The division ratio of each timer or prescaler is given by 1/(n + 1), where n is the value in the corresponding timer or prescaler latch.

All timers are down-counters. When the timer reaches "00$_{16}$", an underflow occurs at the next count pulse and the contents of the corresponding timer latch are reloaded into the timer and the count is continued. When the timer underflows, the interrupt request bit corresponding to that timer is set to "1".

●Timer divider

The divider count source is switched by the main clock division ratio selection bits of CPU mode register (bits 7 and 6 at address 003B$_{16}$). When these bits are "00" (high-speed mode) or "01" (middle-speed mode), X_{IN} is selected. When these bits are "10" (low-speed mode), X_{CIN} is selected.

●Prescaler 12

The prescaler 12 counts the output of the timer divider. The count source is selected by the timer 12, X count source selection register (address 002E$_{16}$) among 1/2, 1/4, 1/8, 1/16, 1/32, 1/64, 1/128, 1/256, 1/512, 1/1024 of f(X_{IN}) or f(X_{CIN}).

Timer 1 and Timer 2

The timer 1 and timer 2 counts the output of prescaler 12 and periodically set the interrupt request bit.

●Prescaler X and prescaler Y

The prescaler X and prescaler Y count the output of the timer divider or f(X_{CIN}). The count source is selected by the timer 12, X count source selection register (address 002E$_{16}$) and the timer Y, Z1 count source selection register (address 002F$_{16}$) among 1/2, 1/4, 1/8, 1/16, 1/32, 1/64, 1/128, 1/256, 1/512, and 1/1024 of f(X_{IN}) or f(X_{CIN}); and f(X_{CIN}).

Timer X and Timer Y

The timer X and timer Y can each select one of four operating modes by setting the timer XY mode register (address 0023$_{16}$).

(1) Timer mode

●Mode selection

This mode can be selected by setting "00" to the timer X operating mode bits (bits 1 and 0) and the timer Y operating mode bits (bits 5 and 4) of the timer XY mode register (address 0023$_{16}$).

●Explanation of operation

The timer count operation is started by setting "0" to the timer X count stop bit (bit 3) and the timer Y count stop bit (bit 7) of the timer XY mode register (address 0023$_{16}$).

When the timer reaches "00$_{16}$", an underflow occurs at the next count pulse and the contents of timer latch are reloaded into the timer and the count is continued.

(2) Pulse output mode

●Mode selection

This mode can be selected by setting "01" to the timer X operating mode bits (bits 1 and 0) and the timer Y operating mode bits (bits 5 and 4) of the timer XY mode register (address 0023$_{16}$).

●Explanation of operation

The operation is the same as the timer mode's. Moreover the pulse which is inverted each time the timer underflows is output from $CNTR_0$/$CNTR_1$ pin. Regardless of the timer counting or not the output of $CNTR_0$/$CNTR_1$ pin is initialized to the level of specified by their active edge switch bits when writing to the timer. When the $CNTR_0$ active edge switch bit (bit 2) and the $CNTR_1$ active edge switch bit (bit 6) of the timer XY mode register (address 0023$_{16}$) is "0", the output starts with "H" level. When it is "1", the output starts with "L" level.

Switching the $CNTR_0$ or $CNTR_1$ active edge switch bit will reverse the output level of the corresponding $CNTR_0$ or CNTR1 pin.

■Precautions

Set the double-function port of $CNTR_0$/$CNTR_1$ pin and port $P2_7$/$P4_0$ to output in this mode.

Downloaded from Arrow.com.

(3) Event counter mode

●Mode selection

This mode can be selected by setting “10” to the timer X operating mode bits (bits 1 and 0) and the timer Y operating mode bits (bits 5 and 4) of the timer XY mode register (address 0023_{16}).

●Explanation of operation

The operation is the same as the timer mode’s except that the timer counts signals input from the $CNTR_0$ or $CNTR_1$ pin. The valid edge for the count operation depends on the $CNTR_0$ active edge switch bit (bit 2) or the $CNTR_1$ active edge switch bit (bit 6) of the timer XY mode register (address 0023_{16}). When it is “0”, the rising edge is valid. When it is “1”, the falling edge is valid.

■Precautions

Set the double-function port of $CNTR_0$/$CNTR_1$ pin and port $P2_7$/$P4_0$ to input in this mode.

(4) Pulse width measurement mode

●Mode selection

This mode can be selected by setting “11” to the timer X operating mode bits (bits 1 and 0) and the timer Y operating mode bits (bits 5 and 4) of the timer XY mode register (address 0023_{16}).

●Explanation of operation

When the $CNTR_0$ active edge switch bit (bit 2) or the $CNTR_1$ active edge switch bit (bit 6) of the timer XY mode register (address 0023_{16}) is “1”, the timer counts during the term of one falling edge of $CNTR_0$/$CNTR_1$ pin input until the next rising edge of input (“L” term). When it is “0”, the timer counts during the term of one rising edge input until the next falling edge input (“H” term).

■Precautions

Set the double-function port of $CNTR_0$/$CNTR_1$ pin and port $P2_7$/$P4_0$ to input in this mode.

The count operation can be stopped by setting “1” to the timer X count stop bit (bit 3) and the timer Y count stop bit (bit 7) of the timer XY mode register (address 0023_{16}). The interrupt request bit is set to “1” each time the timer underflows.

•Precautions when switching count source

When switching the count source by the timer 12, X and Y count source selection bits, the value of timer count is altered in inconsiderable amount owing to generating of thin pulses on the count input signals.

Therefore, select the timer count source before setting the value to the prescaler and the timer.

Downloaded from Arrow.com.

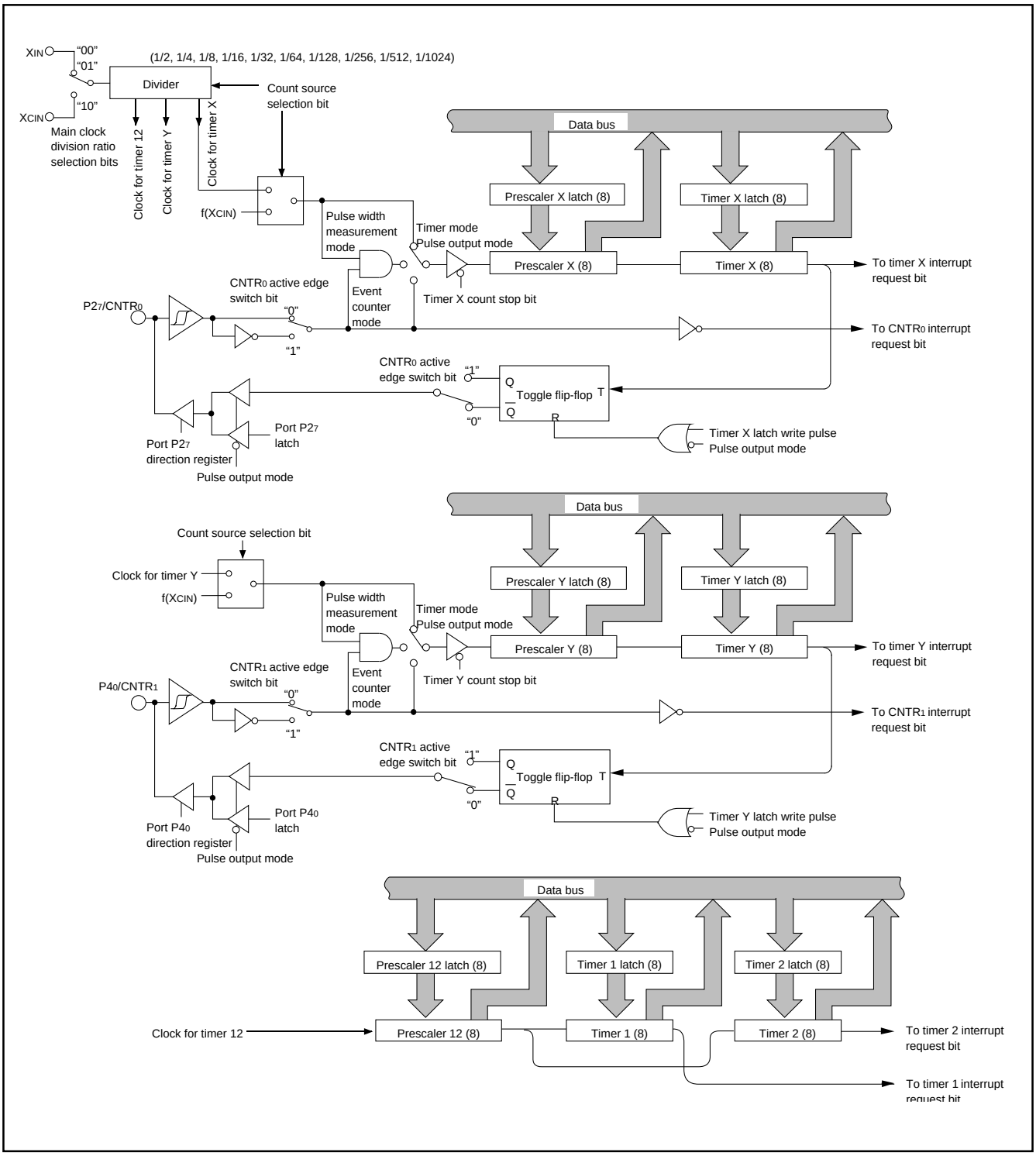


Fig. 17 Block diagram of timer X, timer Y, timer 1, and timer 2

Downloaded from Arrow.com.

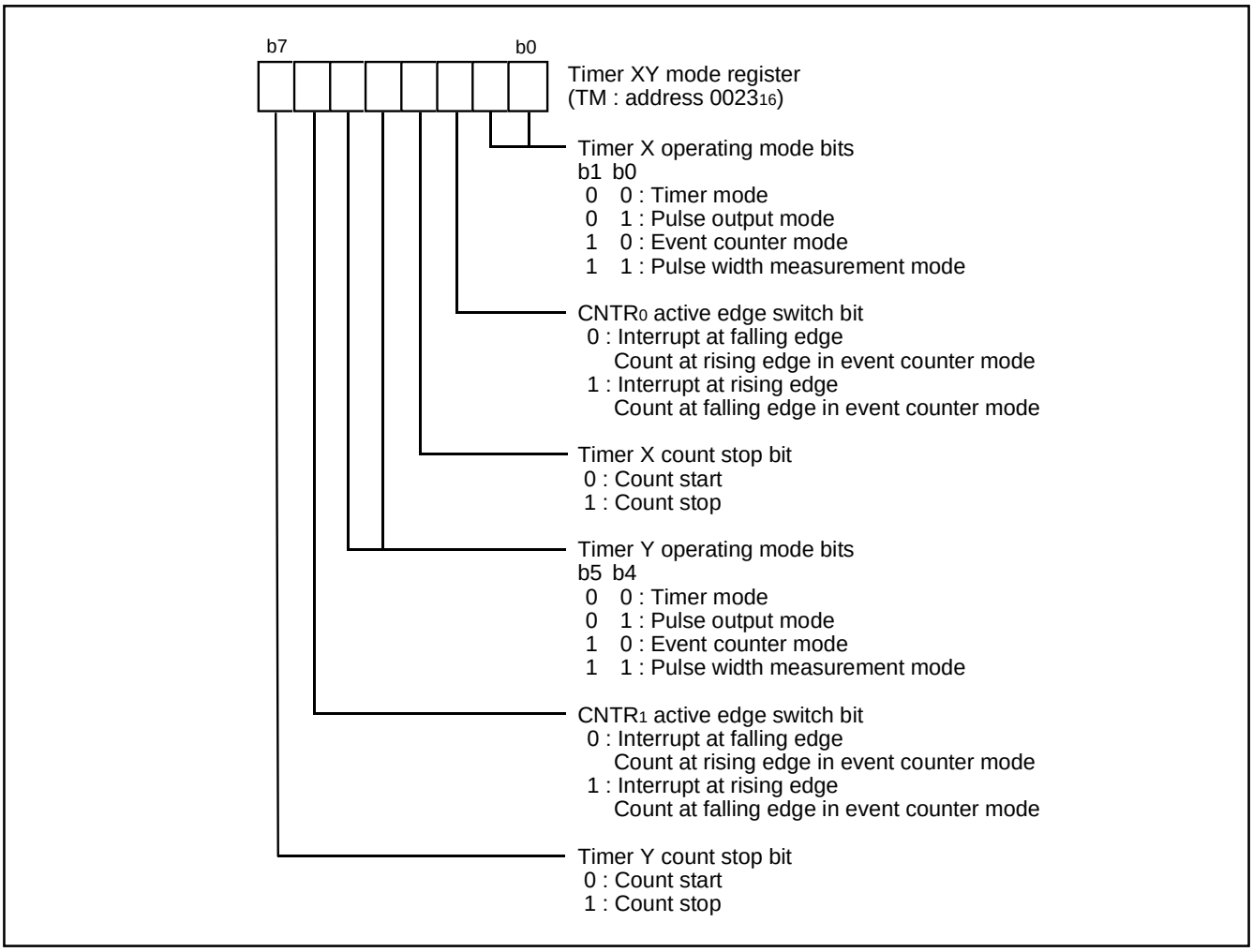


Fig. 18 Structure of timer XY mode register

Downloaded from Arrow.com.

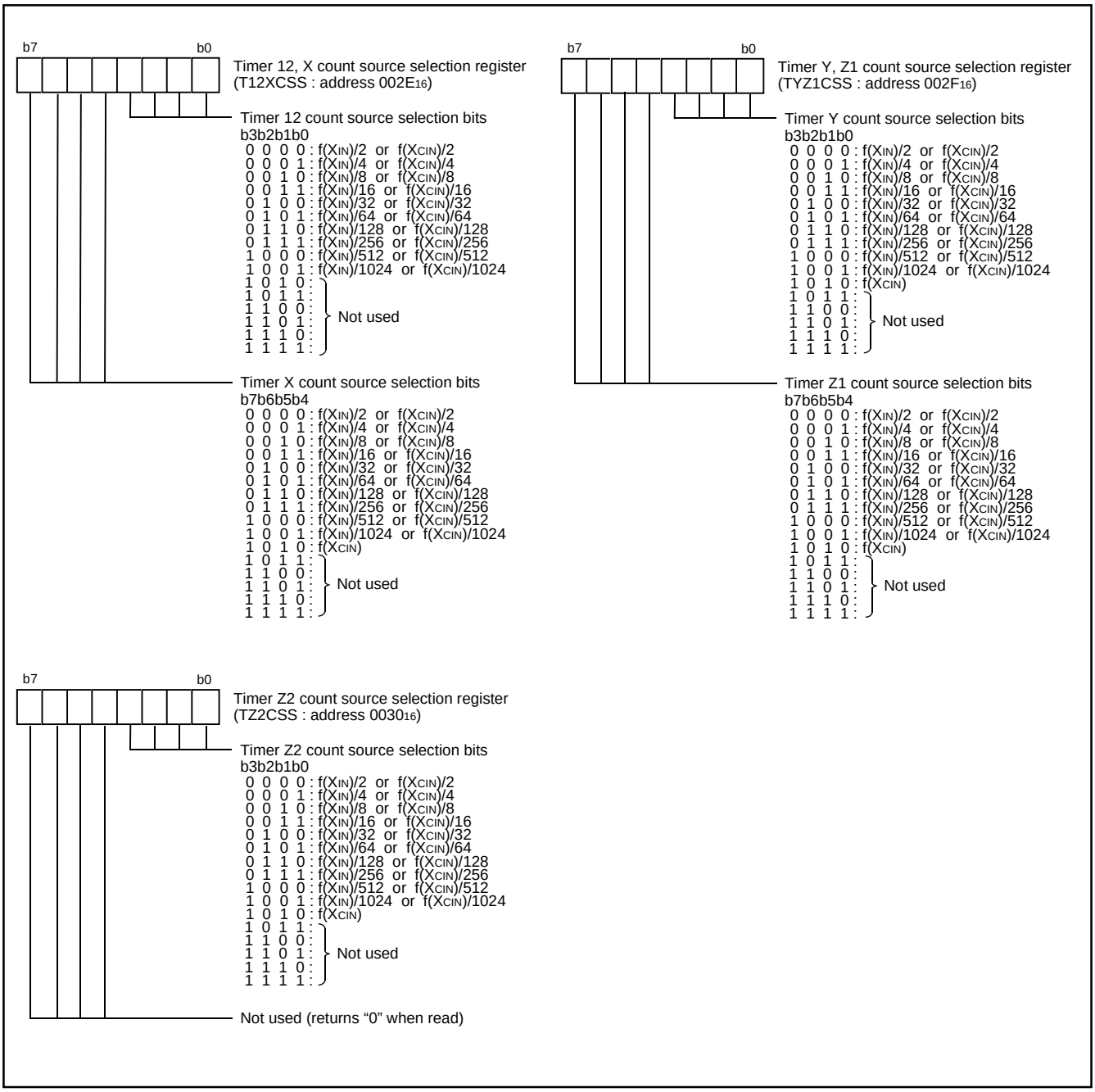


Fig. 19 Structure of timer 12, X, timer Y, Z1 and timer Z2 count source selection registers

Downloaded from Arrow.com.

Timer Z1
●16-bit Timer

The timer Z1 is a 16-bit timer. When the timer reaches "0000$_{16}$", an underflow occurs at the next count pulse and the corresponding timer latch is reloaded into the timer and the count is continued. When the timer underflows, the interrupt request bit corresponding to the timer Z1 is set to "1".

When reading/writing to the timer Z1, perform reading/writing to both the high-order byte and the low-order byte. When reading the timer Z1, read from the high-order byte first, followed by the low-order byte. Do not perform the writing to the timer Z1 between read operation of the high-order byte and read operation of the low-order byte. When writing to the timer Z1, write to the low-order byte first, followed by the high-order byte. Do not perform the reading to the timer Z1 between write operation of the low-order byte and write operation of the high-order byte.

The timer Z1 can select the count source by the timer Z1 count source selection bits of timer Y, Z count source selection register (bits 7 to 4 at address 000F$_{16}$).

Timer Z1 can select one of seven operating modes by setting the timer Z1 mode register (address 0028$_{16}$).

(1) Timer mode

●Mode selection

This mode can be selected by setting "000" to the timer Z1 operating mode bits (bits 2 to 0) and setting "0" to the timer/event counter mode switch bit (b7) of the timer Z1 mode register (address 0028$_{16}$).

●Count source selection

In high-, or middle-speed mode, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64, 1/128, 1/256, 1/512 or 1/1024 of f(XIN); or f(XCIN) can be selected as the count source.

In low-speed mode, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64, 1/128, 1/256, 1/512 or 1/1024 of f(XCIN); or f(XCIN) can be selected as the count source.

●Interrupt

When an underflow occurs, the timer Z1/CNTR$_2$ interrupt request bit (bit 0) of the interrupt request register 1 (address 003C$_{16}$) is set to "1".

●Explanation of operation

During timer stop, usually write data to a latch and a timer at the same time to set the timer value.

The timer count operation is started by setting "0" to the timer Z1 count stop bit (bit 6) of the timer Z1 mode register (address 0028$_{16}$).

When the timer reaches "0000$_{16}$", an underflow occurs at the next count pulse and the contents of timer latch are reloaded into the timer and the count is continued.

When writing data to the timer during operation, the data is written only into the latch. Then the new latch value is reloaded into the timer at the next underflow.

(2) Event counter mode

●Mode selection

This mode can be selected by setting "000" to the timer Z1 operating mode bits (bits 2 to 0) and setting "1" to the timer/event counter mode switch bit (bit 7) of the timer Z1 mode register (address 0028$_{16}$).

The valid edge for the count operation depends on the CNTR$_2$ active edge switch bit (bit 5) of the timer Z1 mode register (address 0028$_{16}$). When it is "0", the rising edge is valid. When it is "1", the falling edge is valid.

●Interrupt

The interrupt at an underflow is the same as the timer mode's.

●Explanation of operation

The operation is the same as the timer mode's.

Set the double-function port of CNTR$_2$ pin and port P2$_2$ to input in this mode.

Figure 22 shows the timing chart of the timer/event counter mode.

(3) Pulse output mode

●Mode selection

This mode can be selected by setting "001" to the timer Z1 operating mode bits (bits 2 to 0) and setting "0" to the timer/event counter mode switch bit (b7) of the timer Z1 mode register (address 0028$_{16}$).

●Count source selection

In high-, or middle-speed mode, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64, 1/128, 1/256, 1/512 or 1/1024 of f(XIN); or f(XCIN) can be selected as the count source.

In low-speed mode, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64, 1/128, 1/256, 1/512 or 1/1024 of f(XCIN); or f(XCIN) can be selected as the count source.

●Interrupt

The interrupt at an underflow is the same as the timer mode's.

●Explanation of operation

The operation is the same as the timer mode's. Moreover the pulse which is inverted each time the timer underflows is output from CNTR$_2$ pin. When the CNTR$_2$ active edge switch bit (bit 5) of the timer Z1 mode register (address 0028$_{16}$) is "0", the output starts with "H" level. When it is "1", the output starts with "L" level.

■Precautions

The double-function port of CNTR$_2$ pin and port P2$_2$ is automatically set to the timer pulse output port in this mode.

The output from CNTR$_2$ pin is initialized to the level depending on CNTR$_2$ active edge switch bit by writing to the timer.

When the value of the CNTR$_2$ active edge switch bit is changed, the output level of CNTR$_2$ pin is inverted.

Figure 23 shows the timing chart of the pulse output mode.

Downloaded from Arrow.com.

(4) Pulse period measurement mode

●Mode selection

This mode can be selected by setting “010” to the timer Z1 operating mode bits (bits 2 to 0) and setting “0” to the timer/event counter mode switch bit (b7) of the timer Z1 mode register (address 0028_{16}).

●Count source selection

In high-, or middle-speed mode, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64, 1/128, 1/256, 1/512 or 1/1024 of f(XIN); or f(XCIN) can be selected as the count source.

In low-speed mode, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64, 1/128, 1/256, 1/512 or 1/1024 of f(XCIN); or f(XCIN) can be selected as the count source.

●Interrupt

The interrupt at an underflow is the same as the timer mode’s. When the pulse period measurement is completed, the timer Z1/CNTR2 interrupt request bit (bit 1) of the interrupt request register 1 (address $003C_{16}$) is set to “1”.

●Explanation of operation

The cycle of the pulse which is input from the CNTR2 pin is measured. When the CNTR2 active edge switch bit (bit 5) of the timer Z1 mode register (address 0028_{16}) is “0”, the timer counts during the term from one falling edge of CNTR2 pin input to the next falling edge. When it is “1”, the timer counts during the term from one rising edge input to the next rising edge input.

When the valid edge of measurement completion/start is detected, the 1’s complement of the timer value is written to the timer latch and “$FFFF_{16}$” is set to the timer.

Furthermore when the timer underflows, the timer Z1 interrupt request occurs and “$FFFF_{16}$” is set to the timer. When reading the timer Z1, the value of the timer latch (measured value) is read. The measured value is retained until the next measurement completion.

■Precautions

Set the double-function port of CNTR2 pin and port P22 to input in this mode.

A read-out of timer value is impossible in this mode. The timer can be written to only during timer stop (no measurement of pulse period).

Since the timer latch in this mode is specialized for the read-out of measured values, do not perform any write operation during measurement.

“$FFFF_{16}$” is set to the timer when the timer underflows or when the valid edge of measurement start/completion is detected. Consequently, the timer value at start of pulse period measurement depends on the timer value just before measurement start.

Figure 24 shows the timing chart of the pulse period measurement mode.

(5) Pulse width measurement mode

●Mode selection

This mode can be selected by setting “011” to the timer Z1 operating mode bits (bits 2 to 0) and setting “0” to the timer/event counter mode switch bit (b7) of the timer Z1 mode register (address 0028_{16}).

●Count source selection

In high-, or middle-speed mode, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64, 1/128, 1/256, 1/512 or 1/1024 of f(XIN); or f(XCIN) can be selected as the count source.

In low-speed mode, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64, 1/128, 1/256, 1/512 or 1/1024 of f(XCIN); or f(XCIN) can be selected as the count source.

●Interrupt

The interrupt at an underflow is the same as the timer mode’s. When the pulse widths measurement is completed, the timer Z1/CNTR2 interrupt request bit (bit 1) of the interrupt request register 2 (address $003C_{16}$) is set to “1”.

●Explanation of operation

The pulse width which is input from the CNTR2 pin is measured. When the CNTR2 active edge switch bit (bit 5) of the timer Z1 mode register (address 0028_{16}) is “0”, the timer counts during the term from one rising edge input to the next falling edge input (“H” term). When it is “1”, the timer counts during the term from one falling edge of CNTR2 pin input to the next rising edge of input (“L” term).

When the valid edge of measurement completion is detected, the 1’s complement of the timer value is written to the timer latch.

When the valid edge of measurement completion/start is detected, “$FFFF_{16}$” is set to the timer.

When the timer Z1 underflows, the timer Z1 interrupt occurs and “$FFFF_{16}$” is set to the timer Z1. When reading the timer Z1, the value of the timer latch (measured value) is read. The measured value is retained until the next measurement completion.

■Precautions

Set the double-function port of CNTR2 pin and port P22 to input in this mode.

A read-out of timer value is impossible in this mode. The timer can be written to only during timer stop (no measurement of pulse widths).

Since the timer latch in this mode is specialized for the read-out of measured values, do not perform any write operation during measurement.

“$FFFF_{16}$” is set to the timer when the timer underflows or when the valid edge of measurement start/completion is detected. Consequently, the timer value at start of pulse width measurement depends on the timer value just before measurement start.

Figure 25 shows the timing chart of the pulse width measurement mode.

Downloaded from Arrow.com.

(6) Programmable waveform generating mode

●Mode selection

This mode can be selected by setting "100" to the timer Z1 operating mode bits (bits 2 to 0) and setting "0" to the timer/event counter mode switch bit (b7) of the timer Z1 mode register (address 0028_{16}).

●Count source selection

In high-, or middle-speed mode, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64, 1/128, 1/256, 1/512 or 1/1024 of f(XIN); or f(XCIN) can be selected as the count source.

In low-speed mode, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64, 1/128, 1/256, 1/512 or 1/1024 of f(XCIN); or f(XCIN) can be selected as the count source.

●Interrupt

The interrupt at an underflow is the same as the timer mode's.

●Explanation of operation

The operation is the same as the timer mode's. Moreover the timer outputs the data set in the output level latch (bit 4) of the timer Z1 mode register (address 0028_{16}) from the $CNTR_2$ pin each time the timer underflows.

Changing the value of the output level latch and the timer latch after an underflow makes it possible to output an optional waveform from the $CNTR_2$ pin.

■Precautions

The double-function port of $CNTR_2$ pin and port $P2_2$ is automatically set to the programmable waveform generating port in this mode.

Figure 26 shows the timing chart of the programmable waveform generating mode.

(7) Programmable one-shot generating mode

●Mode selection

This mode can be selected by setting "101" to the timer Z1 operating mode bits (bits 2 to 0) and setting "0" to the timer/event counter mode switch bit (b7) of the timer Z1 mode register (address 0028_{16}).

●Count source selection

In high-, or middle-speed mode, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64, 1/128, 1/256, 1/512 or 1/1024 of f(XIN); or f(XCIN) can be selected as the count source.

●Interrupt

The interrupt at an underflow is the same as the timer mode's.

The trigger to generate one-shot pulse can be selected by the INT_1 active edge selection bit (bit 1) of the interrupt edge selection register (address $003A_{16}$). When it is "0", the falling edge active is selected; when it is "1", the rising edge active is selected.

When the valid edge of the INT_1 pin is detected, the INT_1 interrupt request bit (bit 1) of the interrupt request register 1 (address $003C_{16}$) is set to "1".

●Explanation of operation

•"H" one-shot pulse; Bit 5 of timer Z1 mode register = "0"

The output level of the $CNTR_2$ pin is initialized to "L" at mode selection. When trigger generation (input signal to INT_1 pin) is detected, "H" is output from the $CNTR_2$ pin. When an underflow occurs, "L" is output. The "H" one-shot pulse width is set by the setting value to the timer Z1 register low-order and high-order. When trigger generating is detected during timer count stop, although "H" is output from the $CNTR_2$ pin, "H" output state continues because an underflow does not occur.

•"L" one-shot pulse; Bit 5 of timer Z1 mode register = "1"

The output level of the $CNTR_2$ pin is initialized to "H" at mode selection. When trigger generation (input signal to INT_1 pin) is detected, "L" is output from the $CNTR_2$ pin. When an underflow occurs, "H" is output. The "L" one-shot pulse width is set by the setting value to the timer Z1 low-order and high-order. When trigger generating is detected during timer count stop, although "L" is output from the $CNTR_2$ pin, "L" output state continues because an underflow does not occur.

■Precautions

Set the double-function port of INT_1 pin and port $P4_2$ to input in this mode.

Set the double function port of $CNTR_2$ pin and port $P2_2$ is automatically set to the programmable one-shot generating port in this mode.

This mode cannot be used in low-speed mode.

If the value of the $CNTR_2$ active edge switch bit is changed during one-shot generating enabled or generating one-shot pulse, then the output level from $CNTR_2$ pin changes.

Figure 27 shows the timing chart of the programmable one-shot generating mode.

■Notes regarding all modes

●Timer Z1 write control

Which write control can be selected by the timer Z1 write control bit (bit 3) of the timer Z1 mode register (address 0028_{16}), writing data to both the latch and the timer at the same time or writing data only to the latch.

When the operation "writing data only to the latch" is selected, the value is set to the timer latch by writing data to the address of timer Z1 and the timer is updated at next underflow. After reset release, the operation "writing data to both the latch and the timer at the same time" is selected, and the value is set to both the latch and the timer at the same time by writing data to the address of timer Z1.

In the case of writing data only to the latch, if writing data to the latch and an underflow are performed almost at the same time, the timer value may become undefined.

●Timer Z1 read control

A read-out of timer value is impossible in pulse period measurement mode and pulse width measurement mode. In the other modes, a read-out of timer value is possible regardless of count operating or stopped.

However, a read-out of timer latch value is impossible.

●Switch of interrupt active edge of $CNTR_2$ and INT_1

Each interrupt active edge depends on setting of the $CNTR_2$ active edge switch bit and the INT_1 active edge selection bit.

●Switch of count source

When switching the count source by the timer Z1 count source selection bits, the value of timer count is altered in inconsiderable amount owing to generating of thin pulses on the count input signals.

Therefore, select the timer count source before setting the value to the prescaler and the timer.

●Usage of $CNTR_2$ pin as normal I/O port $P2_2$

To use the $CNTR_2$ pin as normal I/O port $P2_2$, set timer Z1 operating mode bits (b2, b1, b0) of timer Z1 mode register (address 0028_{16}) to "000".

Downloaded from Arrow.com.

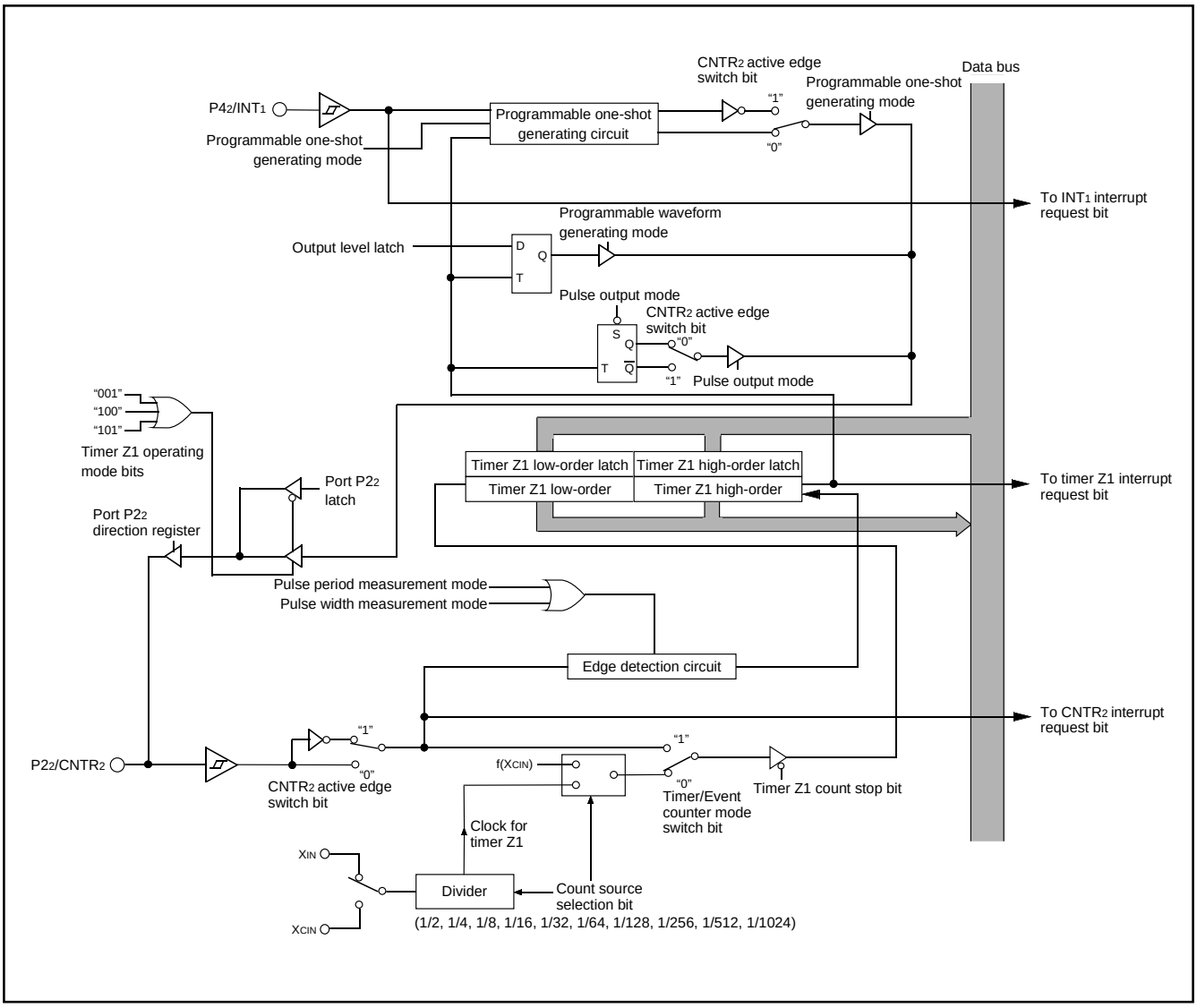


Fig. 20 Block diagram of timer Z1

Downloaded from Arrow.com.

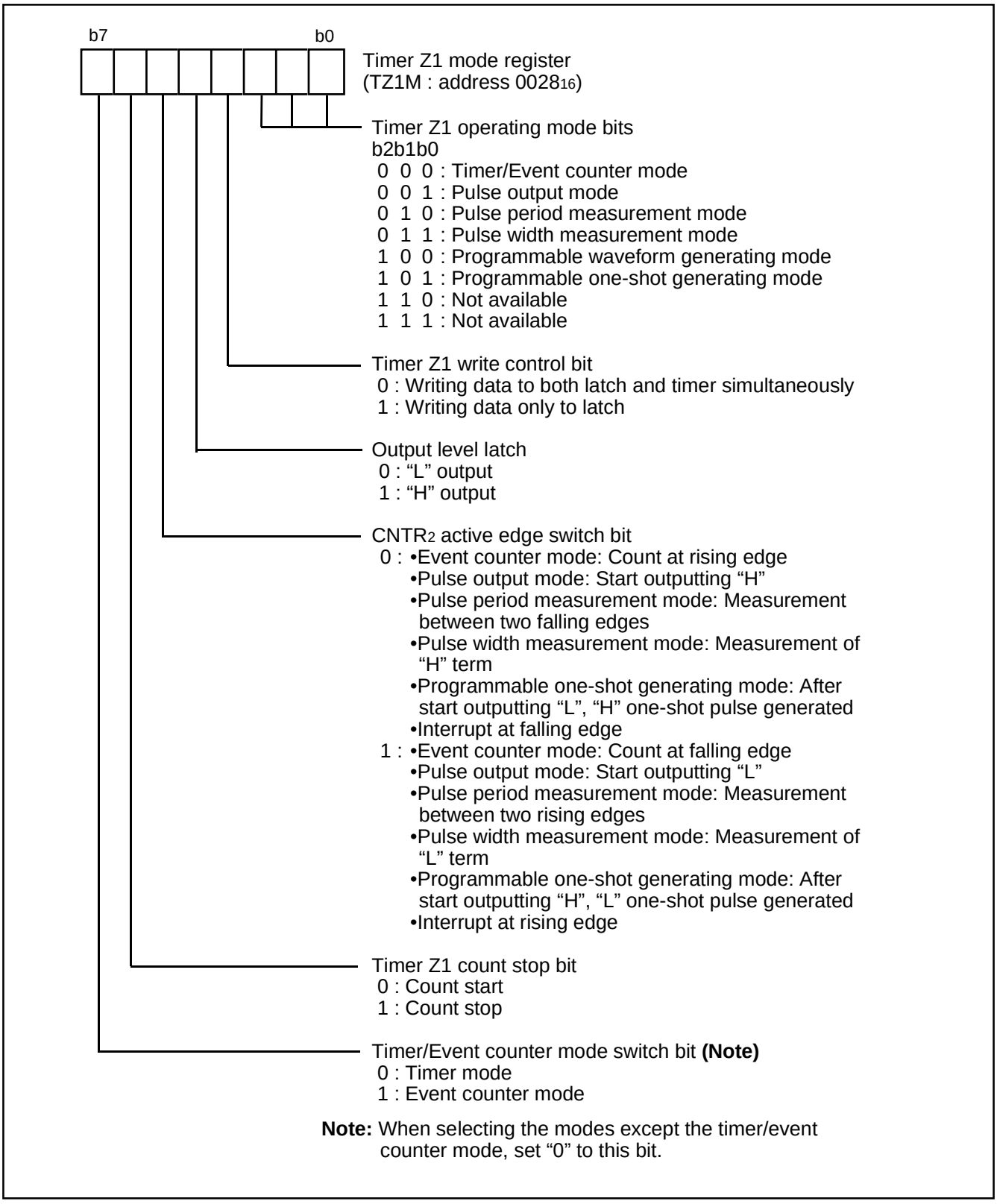
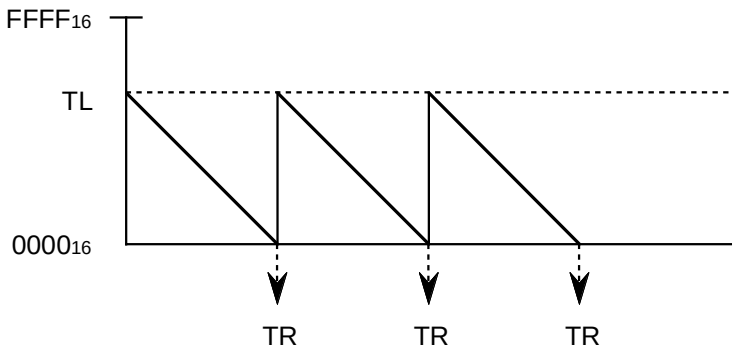


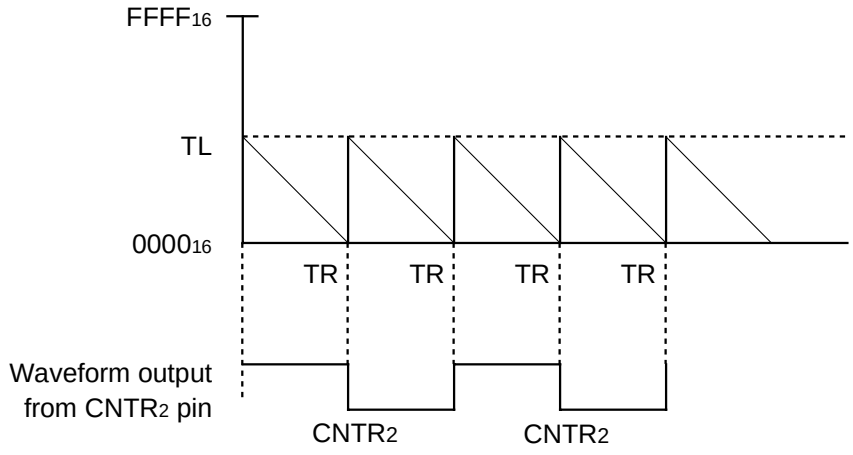
Fig. 21 Structure of timer Z1 mode register

Downloaded from Arrow.com.



TL : Value set to timer latch
TR : Timer interrupt request

Fig. 22 Timing chart of timer/event counter mode



TL : Value set to timer latch
TR : Timer interrupt request
CNTR2 : CNTR2 interrupt request
(CNTR2 active edge switch bit = “0”; Falling edge active)

Fig. 23 Timing chart of pulse output mode

Downloaded from Arrow.com.

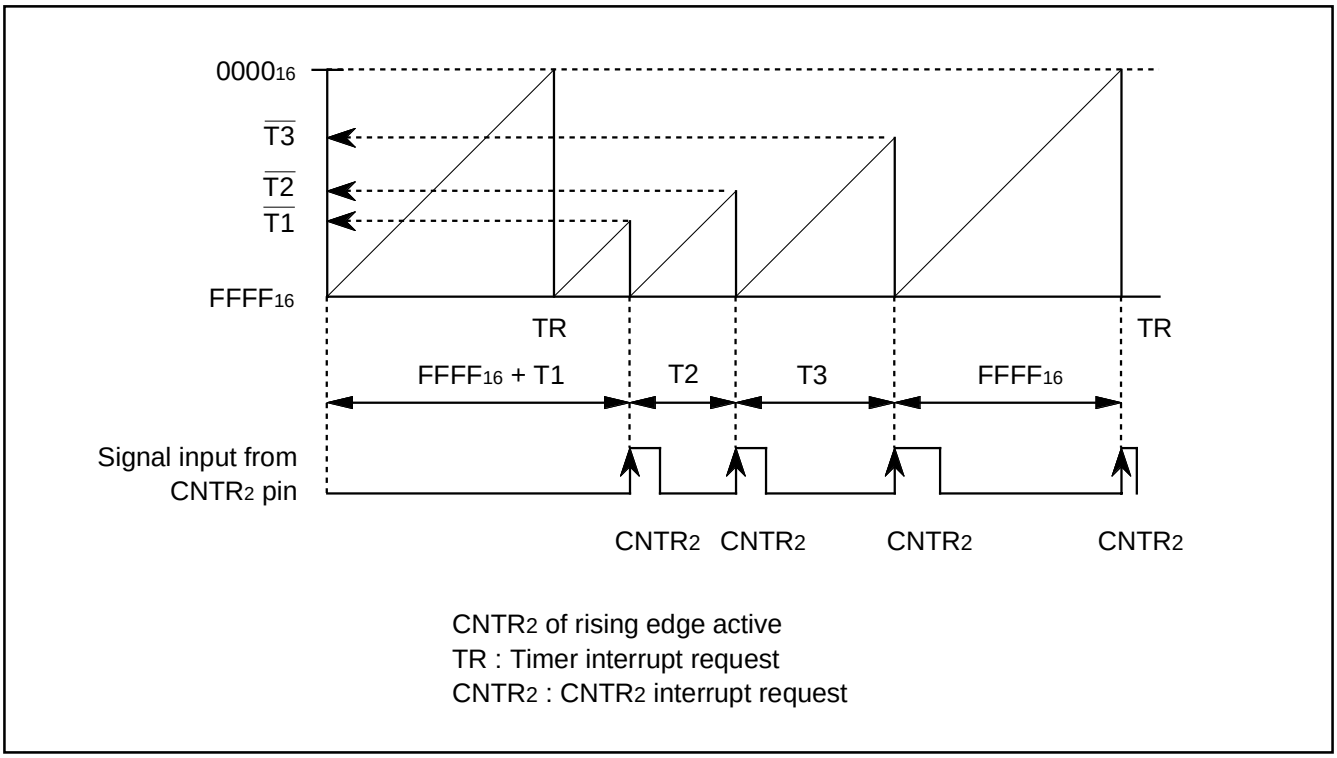


Fig. 24 Timing chart of pulse period measurement mode (Measuring term between two rising edges)

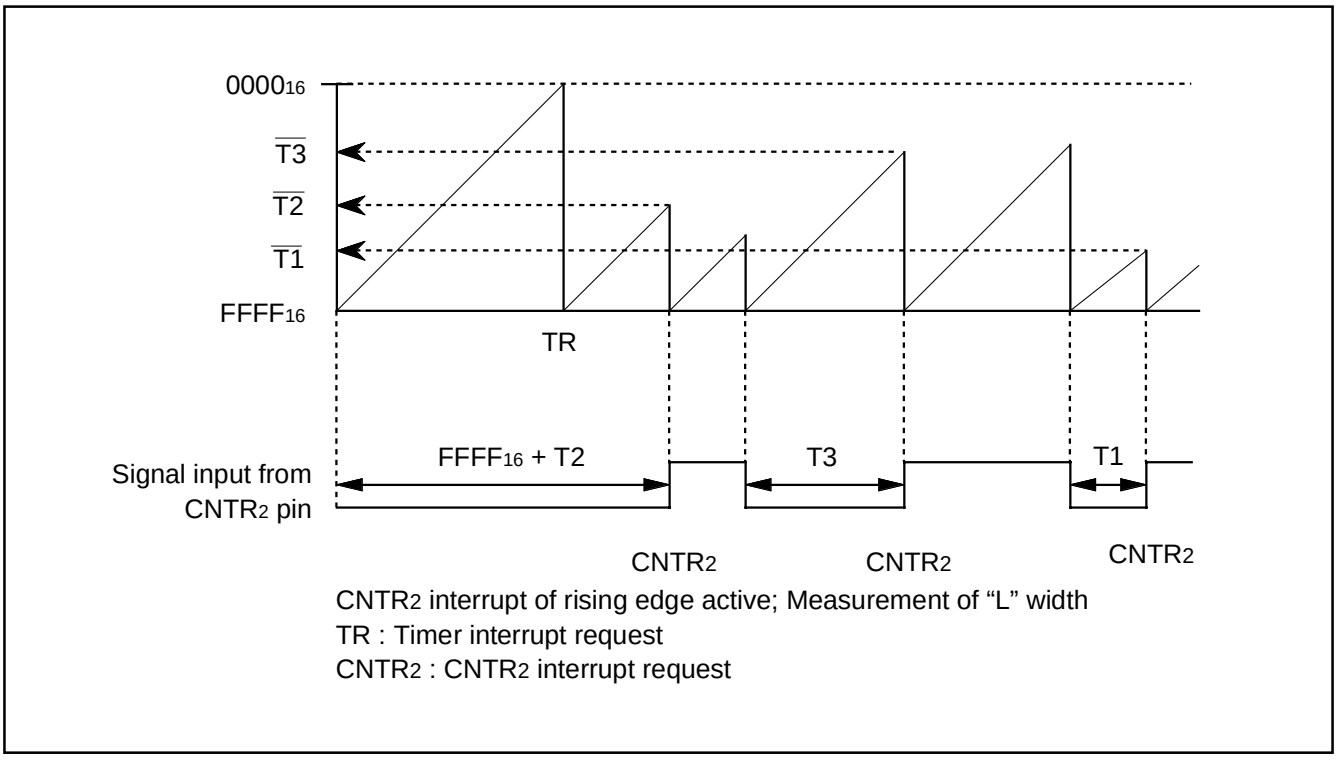
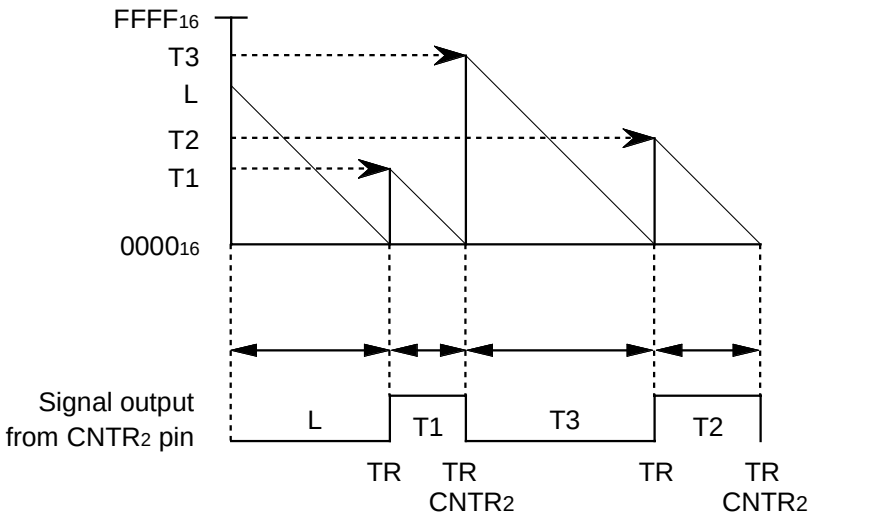


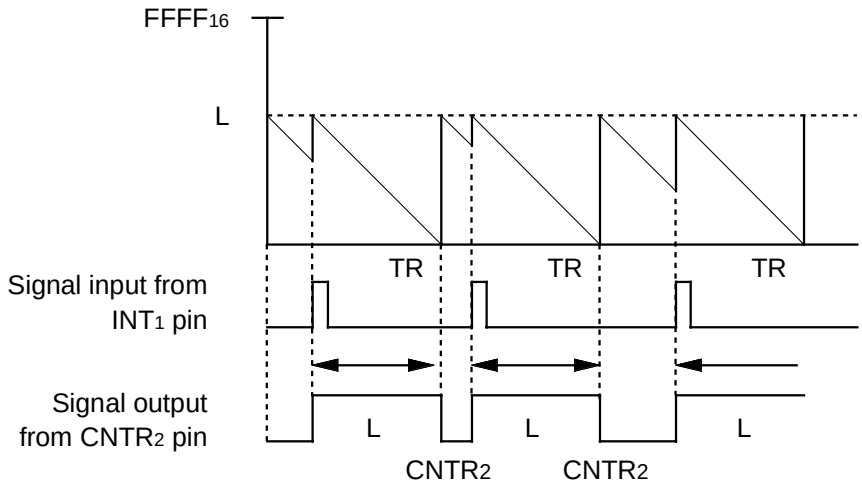
Fig. 25 Timing chart of pulse width measurement mode (Measuring “L” term)

Downloaded from Arrow.com.



L : Timer initial value
TR : Timer interrupt request
CNTR2 : CNTR2 interrupt request
(CNTR2 active edge switch bit = “0”; Falling edge active)

Fig. 26 Timing chart of programmable waveform generating mode



L : One-shot pulse width
TR : Timer interrupt request
CNTR2 : CNTR2 interrupt request
(CNTR2 active edge switch bit = “0”; Falling edge active)

Fig. 27 Timing chart of programmable one-shot generating mode (“H” one-shot pulse generating)

Downloaded from Arrow.com.

Timer Z2
●16-bit Timer

The timer Z2 is a 16-bit timer. When the timer reaches "0000$_{16}$", an underflow occurs at the next count pulse and the corresponding timer latch is reloaded into the timer and the count is continued. When the timer underflows, the interrupt request bit corresponding to the timer Z2 is set to "1".

When reading/writing to the timer Z2, perform reading/writing to both the high-order byte and the low-order byte. When reading the timer Z2, read from the high-order byte first, followed by the low-order byte. Do not perform the writing to the timer Z2 between read operation of the high-order byte and read operation of the low-order byte. When writing to the timer Z2, write to the low-order byte first, followed by the high-order byte. Do not perform the reading to the timer Z2 between write operation of the low-order byte and write operation of the high-order byte.

The timer Z2 can select the count source by the timer Z2 count source selection bits of timer Z2 count source selection register (bits 7 to 4 at address 0030$_{16}$).

Timer Z2 can select one of seven operating modes by setting the timer Z2 mode register (address 002B$_{16}$).

(1) Timer mode

●Mode selection

This mode can be selected by setting "000" to the timer Z2 operating mode bits (bits 2 to 0) and setting "0" to the timer/event counter mode switch bit (b7) of the timer Z2 mode register (address 002B$_{16}$).

●Count source selection

In high-, or middle-speed mode, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64, 1/128, 1/256, 1/512 or 1/1024 of f(XIN); or f(XCIN) can be selected as the count source.

In low-speed mode, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64, 1/128, 1/256, 1/512 or 1/1024 of f(XCIN); or f(XCIN) can be selected as the count source.

●Interrupt

When an underflow occurs, the timer Z2/CNTR$_3$ interrupt request bit (bit 5) of the interrupt request register 1 (address 003C$_{16}$) is set to "1".

●Explanation of operation

During timer stop, usually write data to a latch and a timer at the same time to set the timer value.

The timer count operation is started by setting "0" to the timer Z2 count stop bit (bit 6) of the timer Z2 mode register (address 002B$_{16}$).

When the timer reaches "0000$_{16}$", an underflow occurs at the next count pulse and the contents of timer latch are reloaded into the timer and the count is continued.

When writing data to the timer during operation, the data is written only into the latch. Then the new latch value is reloaded into the timer at the next underflow.

(2) Event counter mode

●Mode selection

This mode can be selected by setting "000" to the timer Z2 operating mode bits (bits 2 to 0) and setting "1" to the timer/event counter mode switch bit (bit 7) of the timer Z2 mode register (address 002B$_{16}$).

The valid edge for the count operation depends on the CNTR$_3$ active edge switch bit (bit 5) of the timer Z2 mode register (address 002B$_{16}$). When it is "0", the rising edge is valid. When it is "1", the falling edge is valid.

●Interrupt

The interrupt at an underflow is the same as the timer mode's.

●Explanation of operation

The operation is the same as the timer mode's.

Set the double-function port of CNTR$_3$ pin and port P2$_3$ to input in this mode.

Figure 30 shows the timing chart of the timer/event counter mode.

(3) Pulse output mode

●Mode selection

This mode can be selected by setting "001" to the timer Z2 operating mode bits (bits 2 to 0) and setting "0" to the timer/event counter mode switch bit (b7) of the timer Z2 mode register (address 002B$_{16}$).

●Count source selection

In high-, or middle-speed mode, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64, 1/128, 1/256, 1/512 or 1/1024 of f(XIN); or f(XCIN) can be selected as the count source.

In low-speed mode, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64, 1/128, 1/256, 1/512 or 1/1024 of f(XCIN); or f(XCIN) can be selected as the count source.

●Interrupt

The interrupt at an underflow is the same as the timer mode's.

●Explanation of operation

The operation is the same as the timer mode's. Moreover the pulse which is inverted each time the timer underflows is output from CNTR$_3$ pin. When the CNTR$_3$ active edge switch bit (bit 5) of the timer Z2 mode register (address 002B$_{16}$) is "0", the output starts with "H" level. When it is "1", the output starts with "L" level.

■Precautions

The double-function port of CNTR$_3$ pin and port P2$_3$ is automatically set to the timer pulse output port in this mode.

The output from CNTR$_3$ pin is initialized to the level depending on CNTR$_3$ active edge switch bit by writing to the timer.

When the value of the CNTR$_3$ active edge switch bit is changed, the output level of CNTR$_3$ pin is inverted.

Figure 31 shows the timing chart of the pulse output mode.

Downloaded from Arrow.com.

(4) Pulse period measurement mode

●Mode selection

This mode can be selected by setting “010” to the timer Z2 operating mode bits (bits 2 to 0) and setting “0” to the timer/event counter mode switch bit (b7) of the timer Z2 mode register (address $002B_{16}$).

●Count source selection

In high-, or middle-speed mode, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64, 1/128, 1/256, 1/512 or 1/1024 of f(XIN); or f(XCIN) can be selected as the count source.

In low-speed mode, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64, 1/128, 1/256, 1/512 or 1/1024 of f(XCIN); or f(XCIN) can be selected as the count source.

●Interrupt

The interrupt at an underflow is the same as the timer mode’s. When the pulse period measurement is completed, the timer Z2/CNTR3 interrupt request bit (bit 1) of the interrupt request register 1 (address $003C_{16}$) is set to “1”.

●Explanation of operation

The cycle of the pulse which is input from the CNTR3 pin is measured. When the CNTR3 active edge switch bit (bit 5) of the timer Z2 mode register (address $002B_{16}$) is “0”, the timer counts during the term from one falling edge of CNTR3 pin input to the next falling edge. When it is “1”, the timer counts during the term from one rising edge input to the next rising edge input.

When the valid edge of measurement completion/start is detected, the 1’s complement of the timer value is written to the timer latch and “$FFFF_{16}$” is set to the timer.

Furthermore when the timer underflows, the timer Z2 interrupt request occurs and “$FFFF_{16}$” is set to the timer. When reading the timer Z2, the value of the timer latch (measured value) is read. The measured value is retained until the next measurement completion.

■Precautions

Set the double-function port of CNTR3 pin and port P23 to input in this mode.

A read-out of timer value is impossible in this mode. The timer can be written to only during timer stop (no measurement of pulse period).

Since the timer latch in this mode is specialized for the read-out of measured values, do not perform any write operation during measurement.

“$FFFF_{16}$” is set to the timer when the timer underflows or when the valid edge of measurement start/completion is detected. Consequently, the timer value at start of pulse period measurement depends on the timer value just before measurement start.

Figure 32 shows the timing chart of the pulse period measurement mode.

(5) Pulse width measurement mode

●Mode selection

This mode can be selected by setting “011” to the timer Z2 operating mode bits (bits 2 to 0) and setting “0” to the timer/event counter mode switch bit (b7) of the timer Z2 mode register (address $002B_{16}$).

●Count source selection

In high-, or middle-speed mode, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64, 1/128, 1/256, 1/512 or 1/1024 of f(XIN); or f(XCIN) can be selected as the count source.

In low-speed mode, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64, 1/128, 1/256, 1/512 or 1/1024 of f(XCIN); or f(XCIN) can be selected as the count source.

●Interrupt

The interrupt at an underflow is the same as the timer mode’s. When the pulse widths measurement is completed, the timer Z2/CNTR3 interrupt request bit (bit 1) of the interrupt request register 1 (address $003C_{16}$) is set to “1”.

●Explanation of operation

The pulse width which is input from the CNTR3 pin is measured. When the CNTR3 active edge switch bit (bit 5) of the timer Z2 mode register (address $002B_{16}$) is “0”, the timer counts during the term from one rising edge input to the next falling edge input (“H” term). When it is “1”, the timer counts during the term from one falling edge of CNTR3 pin input to the next rising edge of input (“L” term).

When the valid edge of measurement completion is detected, the 1’s complement of the timer value is written to the timer latch.

When the valid edge of measurement completion/start is detected, “$FFFF_{16}$” is set to the timer.

When the timer Z2 underflows, the timer Z2 interrupt occurs and “$FFFF_{16}$” is set to the timer Z2. When reading the timer Z2, the value of the timer latch (measured value) is read. The measured value is retained until the next measurement completion.

■Precautions

Set the double-function port of CNTR3 pin and port P23 to input in this mode.

A read-out of timer value is impossible in this mode. The timer can be written to only during timer stop (no measurement of pulse widths).

Since the timer latch in this mode is specialized for the read-out of measured values, do not perform any write operation during measurement.

“$FFFF_{16}$” is set to the timer when the timer underflows or when the valid edge of measurement start/completion is detected. Consequently, the timer value at start of pulse width measurement depends on the timer value just before measurement start.

Figure 33 shows the timing chart of the pulse width measurement mode.

Downloaded from Arrow.com.

(6) Programmable waveform generating mode

●Mode selection

This mode can be selected by setting “100” to the timer Z2 operating mode bits (bits 2 to 0) and setting “0” to the timer/event counter mode switch bit (b7) of the timer Z2 mode register (address 002B16).

●Count source selection

In high-, or middle-speed mode, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64, 1/128, 1/256, 1/512 or 1/1024 of f(XIN); or f(XCIN) can be selected as the count source.

In low-speed mode, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64, 1/128, 1/256, 1/512 or 1/1024 of f(XCIN); or f(XCIN) can be selected as the count source.

●Interrupt

The interrupt at an underflow is the same as the timer mode’s.

●Explanation of operation

The operation is the same as the timer mode’s. Moreover the timer outputs the data set in the output level latch (bit 4) of the timer Z2 mode register (address 002B16) from the CNTR3 pin each time the timer underflows.

Changing the value of the output level latch and the timer latch after an underflow makes it possible to output an optional waveform from the CNTR3 pin.

■Precautions

The double-function port of CNTR3 pin and port P23 is automatically set to the programmable waveform generating port in this mode.

Figure 34 shows the timing chart of the programmable waveform generating mode.

(7) Programmable one-shot generating mode

●Mode selection

This mode can be selected by setting “101” to the timer Z2 operating mode bits (bits 2 to 0) and setting “0” to the timer/event counter mode switch bit (b7) of the timer Z2 mode register (address 002B16).

●Count source selection

In high-, or middle-speed mode, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64, 1/128, 1/256, 1/512 or 1/1024 of f(XIN); or f(XCIN) can be selected as the count source.

●Interrupt

The interrupt at an underflow is the same as the timer mode’s.

The trigger to generate one-shot pulse can be selected by the INT2 active edge selection bit (bit 2) of the interrupt edge selection register (address 003A16). When it is “0”, the falling edge active is selected; when it is “1”, the rising edge active is selected.

When the valid edge of the INT2 pin is detected, the INT2 interrupt request bit (bit 2) of the interrupt request register 1 (address 003C16) is set to “1”.

●Explanation of operation

•“H” one-shot pulse; Bit 5 of timer Z2 mode register = “0”

The output level of the CNTR3 pin is initialized to “L” at mode selection. When trigger generation (input signal to INT2 pin) is detected, “H” is output from the CNTR3 pin. When an underflow occurs, “L” is output. The “H” one-shot pulse width is set by the setting value to the timer Z2 register low-order and high-order. When trigger generating is detected during timer count stop, although “H” is output from the CNTR3 pin, “H” output state continues because an underflow does not occur.

•“L” one-shot pulse; Bit 5 of timer Z2 mode register = “1”

The output level of the CNTR3 pin is initialized to “H” at mode selection. When trigger generation (input signal to INT2 pin) is detected, “L” is output from the CNTR3 pin. When an underflow occurs, “H” is output. The “L” one-shot pulse width is set by the setting value to the timer Z2 low-order and high-order. When trigger generating is detected during timer count stop, although “L” is output from the CNTR3 pin, “L” output state continues because an underflow does not occur.

■Precautions

Set the double-function port of INT2 pin and port P43 to input in this mode.

Set the double function port of CNTR3 pin and port P23 is automatically set to the programmable one-shot generating port in this mode.

This mode cannot be used in low-speed mode.

If the value of the CNTR3 active edge switch bit is changed during one-shot generating enabled or generating one-shot pulse, then the output level from CNTR3 pin changes.

Figure 35 shows the timing chart of the programmable one-shot generating mode.

■Notes regarding all modes

●Timer Z2 write control

Which write control can be selected by the timer Z2 write control bit (bit 3) of the timer Z2 mode register (address 002B16), writing data to both the latch and the timer at the same time or writing data only to the latch.

When the operation “writing data only to the latch” is selected, the value is set to the timer latch by writing data to the address of timer Z2 and the timer is updated at next underflow. After reset release, the operation “writing data to both the latch and the timer at the same time” is selected, and the value is set to both the latch and the timer at the same time by writing data to the address of timer Z2.

In the case of writing data only to the latch, if writing data to the latch and an underflow are performed almost at the same time, the timer value may become undefined.

●Timer Z2 read control

A read-out of timer value is impossible in pulse period measurement mode and pulse width measurement mode. In the other modes, a read-out of timer value is possible regardless of count operating or stopped.

However, a read-out of timer latch value is impossible.

●Switch of interrupt active edge of CNTR3 and INT2

Each interrupt active edge depends on setting of the CNTR3 active edge switch bit and the INT2 active edge selection bit.

●Switch of count source

When switching the count source by the timer Z2 count source selection bits, the value of timer count is altered in inconsiderable amount owing to generating of thin pulses on the count input signals.

Therefore, select the timer count source before setting the value to the prescaler and the timer.

●Usage of CNTR3 pin as normal I/O port P23

To use the CNTR3 pin as normal I/O port P23, set timer Z2 operating mode bits (b2, b1, b0) of timer Z2 mode register (address 002B16) to “000”.

Downloaded from Arrow.com.

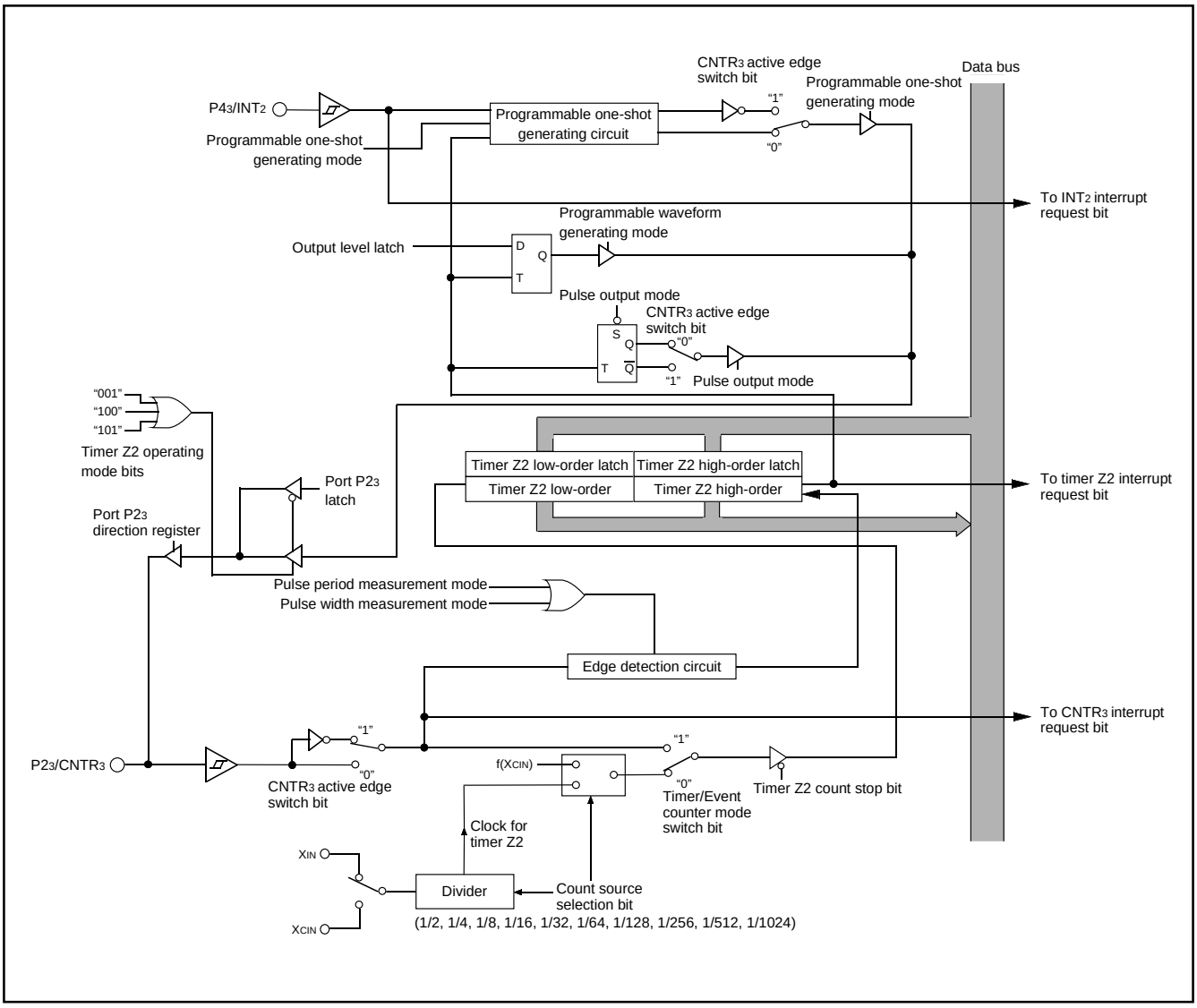


Fig. 28 Block diagram of timer Z2

Downloaded from Arrow.com.

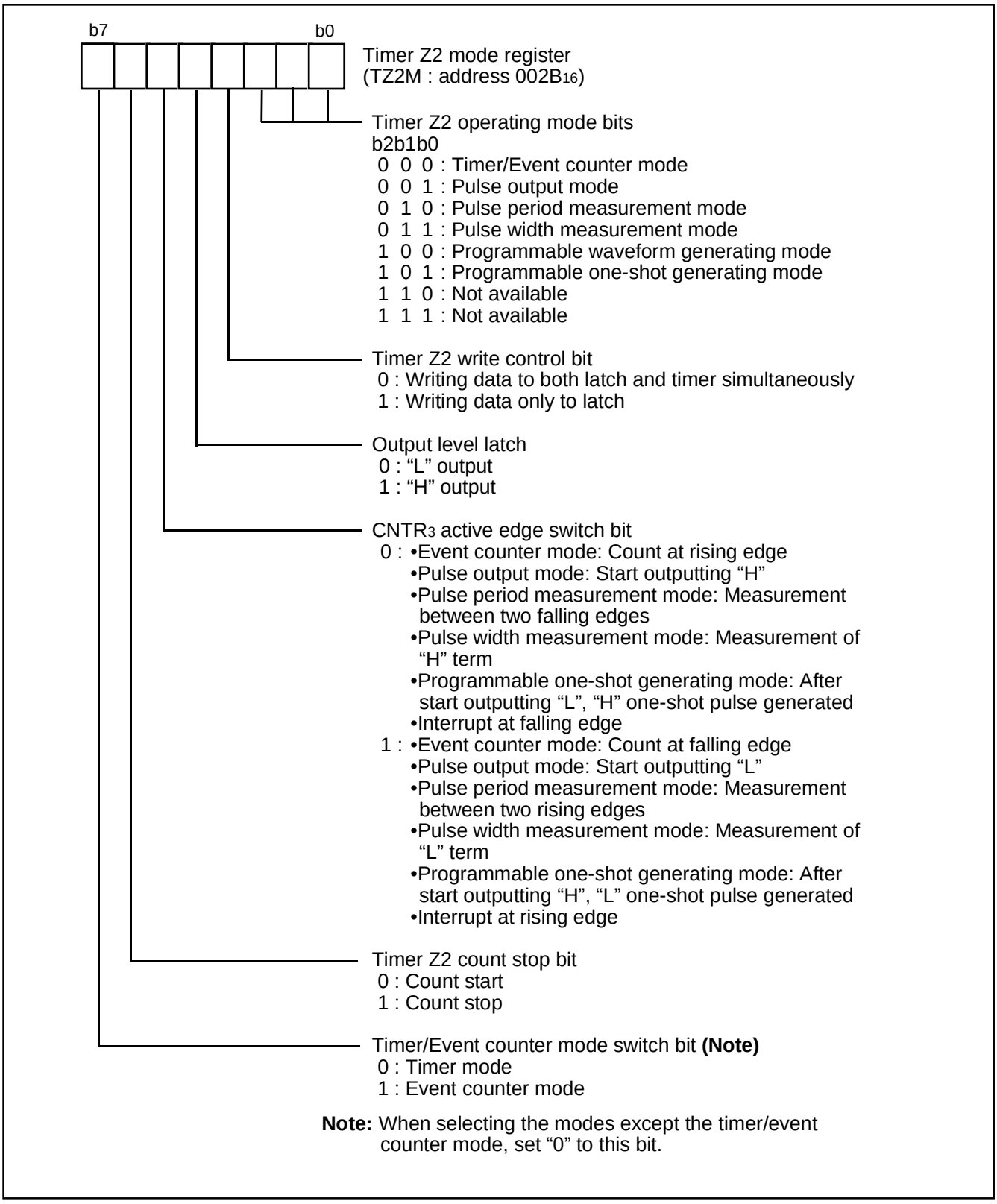
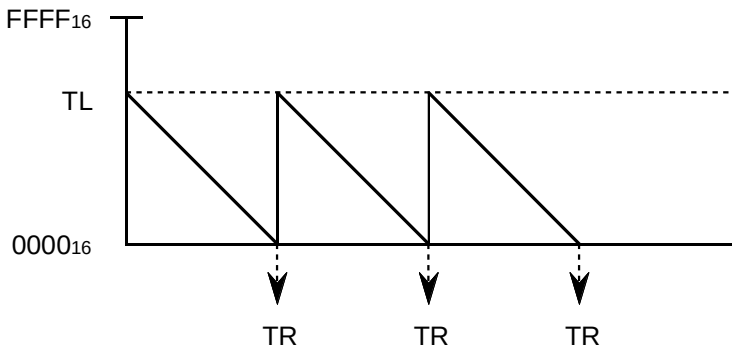


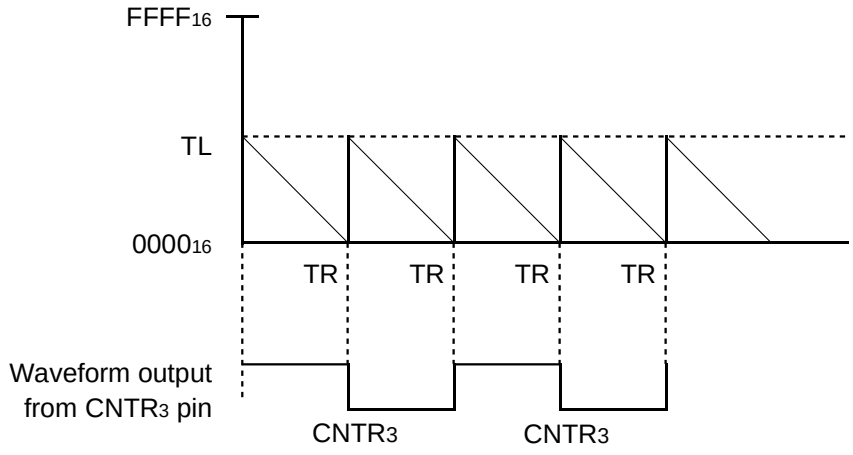
Fig. 29 Structure of timer Z2 mode register

Downloaded from Arrow.com.



TL : Value set to timer latch
TR : Timer interrupt request

Fig. 30 Timing chart of timer/event counter mode



TL : Value set to timer latch
TR : Timer interrupt request
CNTR3 : CNTR3 interrupt request
(CNTR3 active edge switch bit = “0”; Falling edge active)

Fig. 31 Timing chart of pulse output mode

Downloaded from Arrow.com.

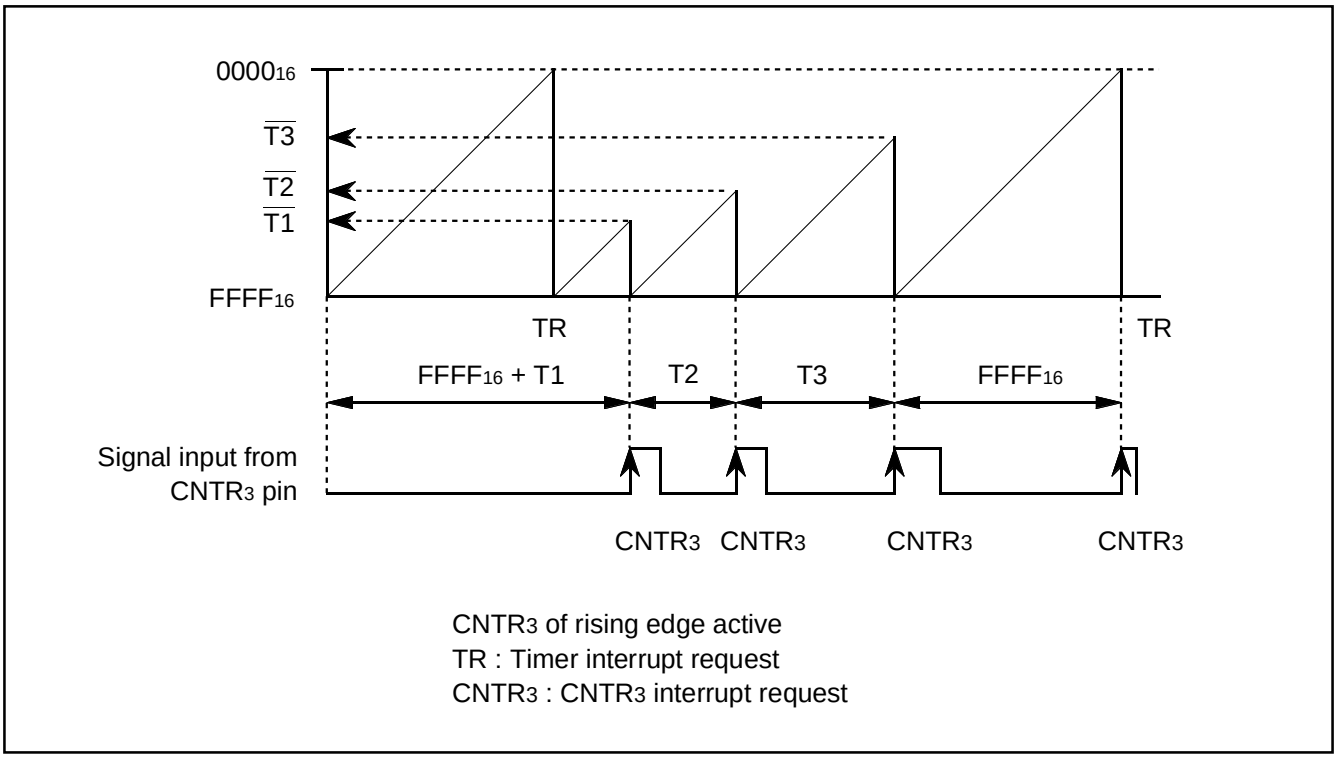


Fig. 32 Timing chart of pulse period measurement mode (Measuring term between two rising edges)

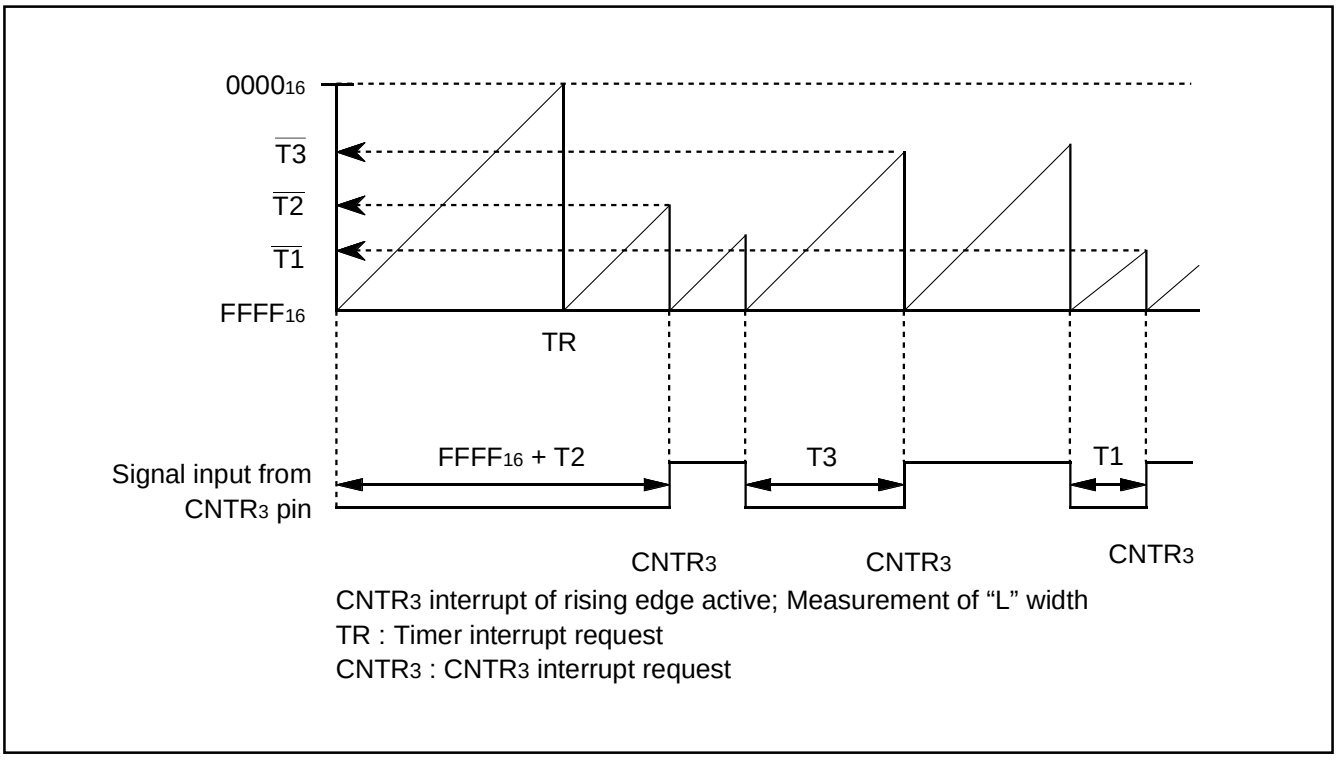
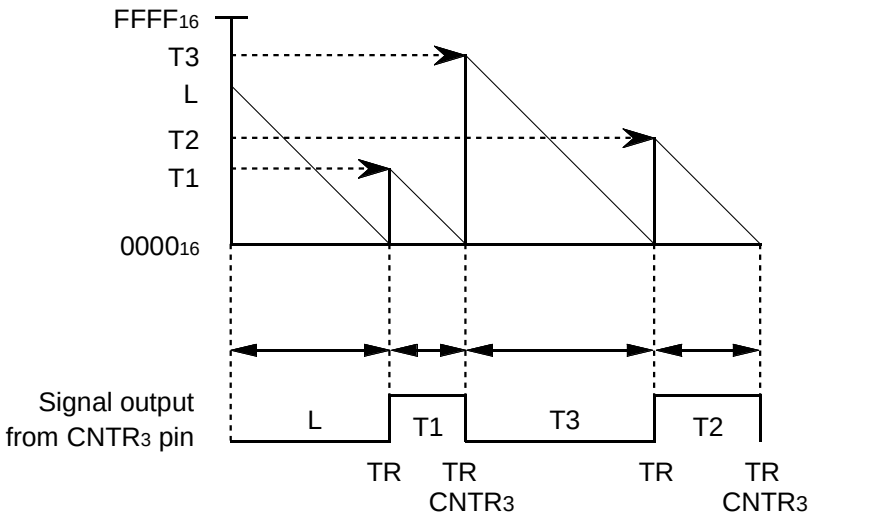


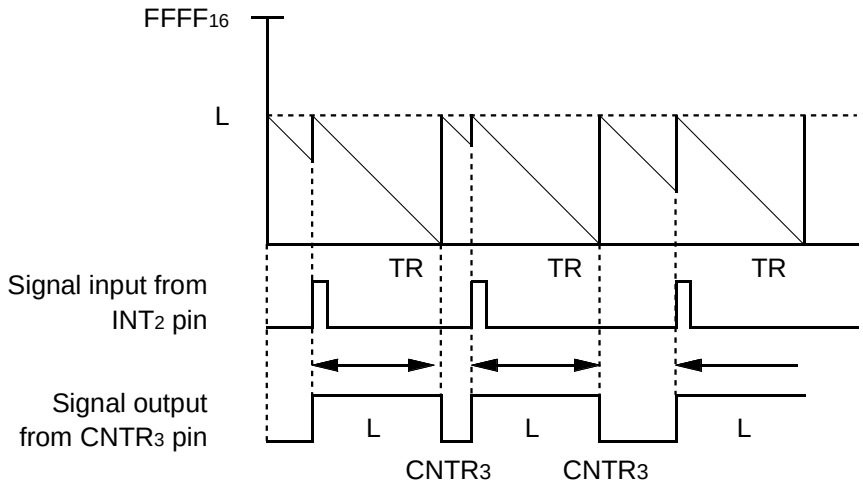
Fig. 33 Timing chart of pulse width measurement mode (Measuring “L” term)

Downloaded from Arrow.com.



L : Timer initial value
TR : Timer interrupt request
CNTR3 : CNTR3 interrupt request
(CNTR3 active edge switch bit = “0”; Falling edge active)

Fig. 34 Timing chart of programmable waveform generating mode



L : One-shot pulse width
TR : Timer interrupt request
CNTR3 : CNTR3 interrupt request
(CNTR3 active edge switch bit = “0”; Falling edge active)

Fig. 35 Timing chart of programmable one-shot generating mode (“H” one-shot pulse generating)

Downloaded from Arrow.com.

SERIAL INTERFACE
●SERIAL I/O1

Serial I/O1 can be used as either clock synchronous or asynchronous (UART) serial I/O1. A dedicated timer is also provided for baud rate generation.

(1) Clock Synchronous Serial I/O Mode

Clock synchronous serial I/O mode can be selected by setting the serial I/O1 mode selection bit of the serial I/O1 control register (bit 6 of address 001A16) to "1".

For clock synchronous serial I/O, the transmitter and the receiver must use the same clock. If an internal clock is used, transfer is started by a write signal to the TB/RB.

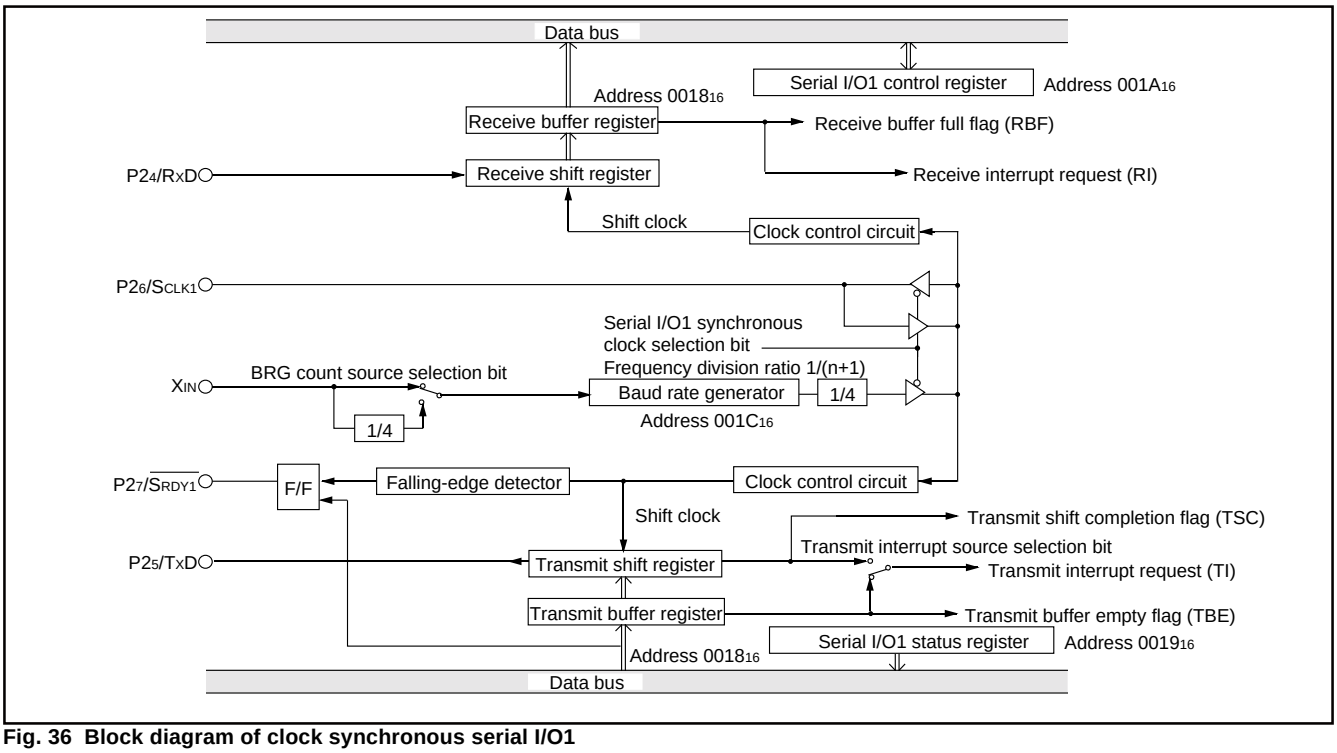
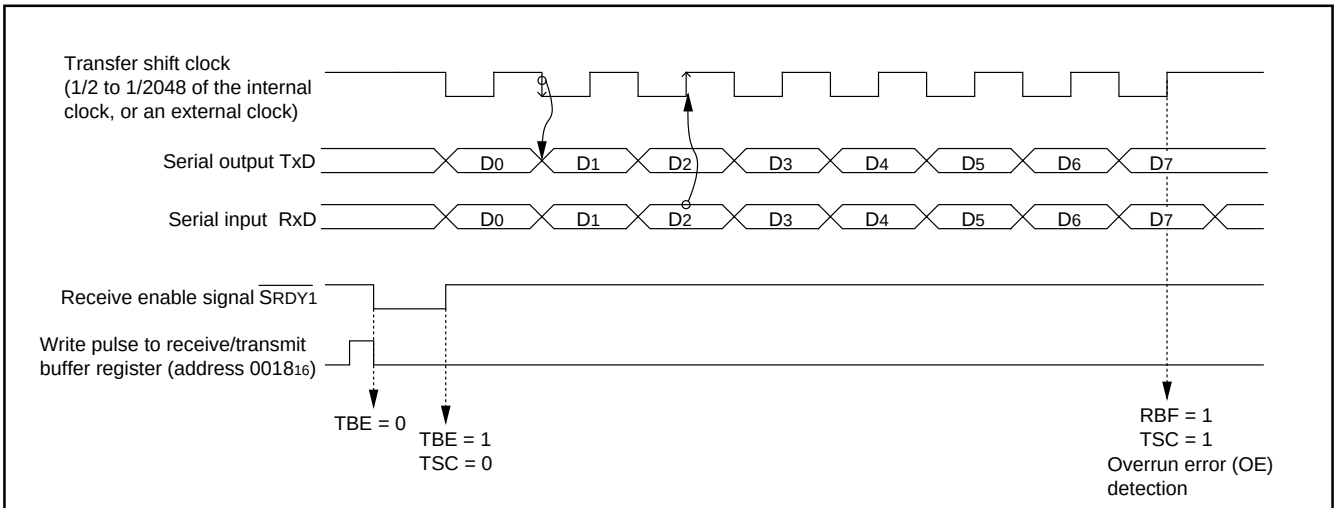


Fig. 36 Block diagram of clock synchronous serial I/O1



Notes 1: As the transmit interrupt (TI), either when the transmit buffer has emptied (TBE=1) or after the transmit shift operation has ended (TSC=1), by setting the transmit interrupt source selection bit (TIC) of the serial I/O1 control register.
2: If data is written to the transmit buffer register when TSC=0, the transmit clock is generated continuously and serial data is output continuously from the TxD pin.
3: The receive interrupt (RI) is set when the receive buffer full flag (RBF) becomes "1" .

Fig. 37 Operation of clock synchronous serial I/O1 function

Downloaded from Arrow.com.

(2) Asynchronous Serial I/O (UART) Mode

Clock asynchronous serial I/O mode (UART) can be selected by clearing the serial I/O1 mode selection bit (b6) of the serial I/O1 control register to “0”.

Eight serial data transfer formats can be selected, and the transfer formats used by a transmitter and receiver must be identical.

The transmit and receive shift registers each have a buffer, but the two buffers have the same address in memory. Since the shift register cannot be written to or read from directly, transmit data is written to the transmit buffer register, and receive data is read from the receive buffer register.

The transmit buffer register can also hold the next data to be transmitted, and the receive buffer register can hold a character while the next character is being received.

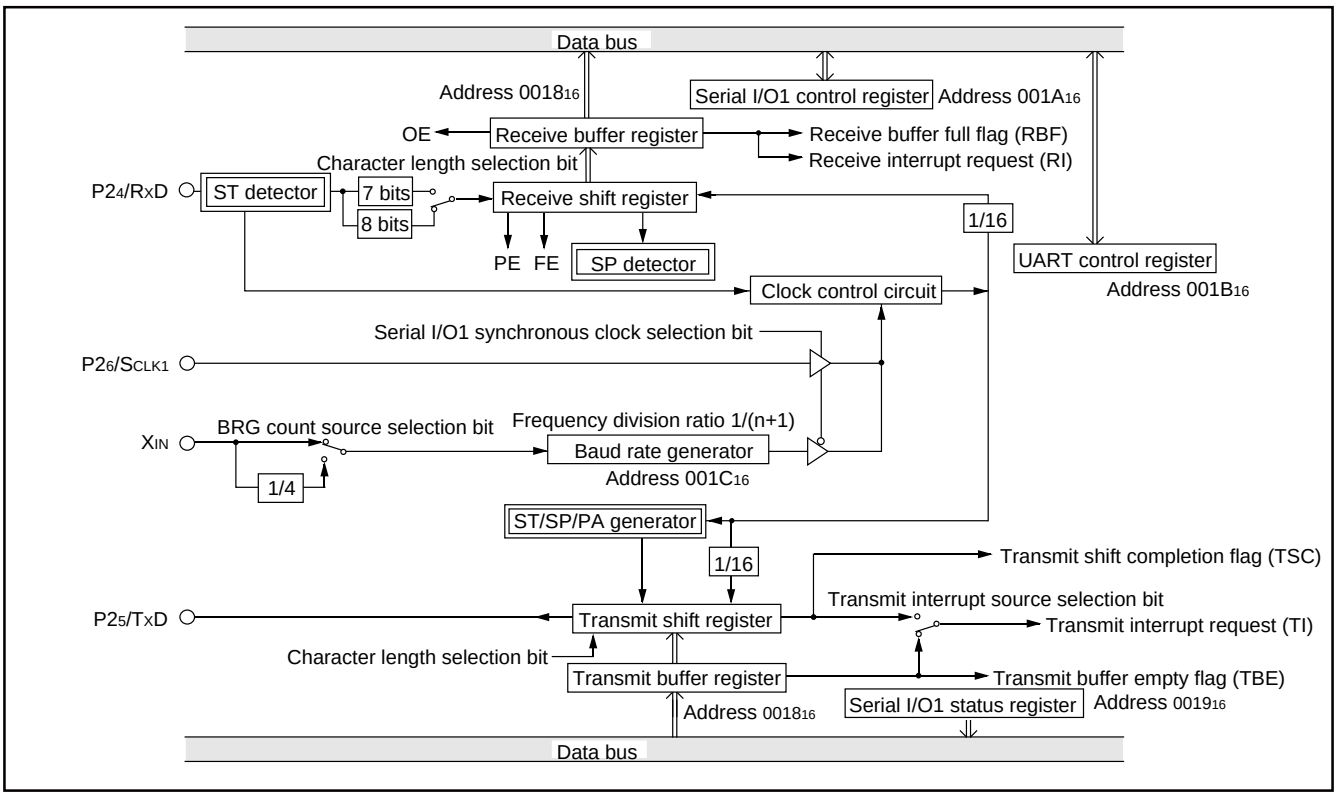
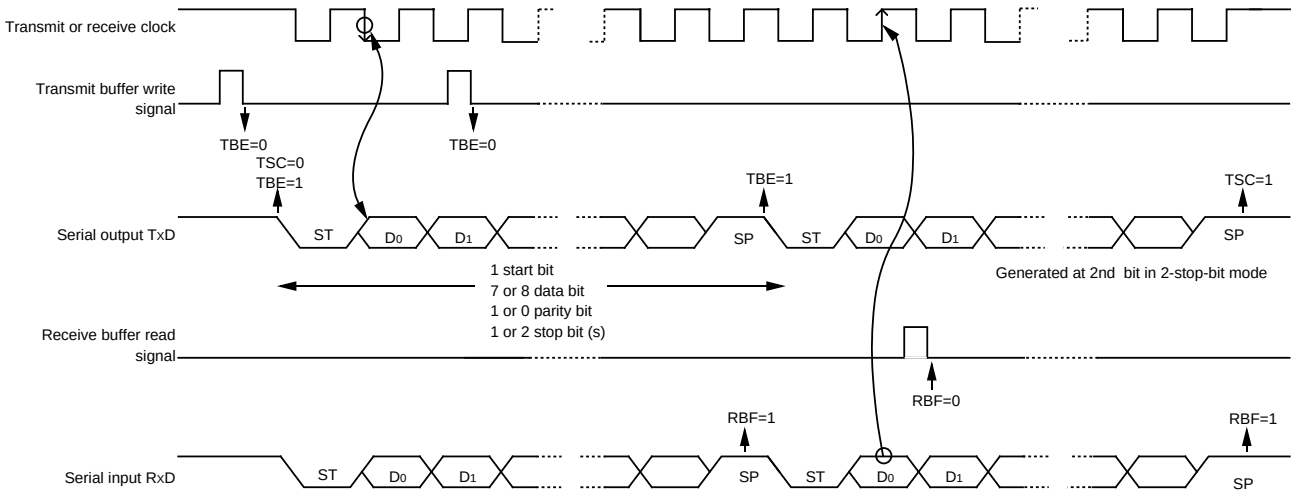


Fig. 38 Block diagram of UART serial I/O1

Downloaded from Arrow.com.



Notes
1: Error flag detection occurs at the same time that the RBF flag becomes "1" (at 1st stop bit, during reception).
2: As the transmit interrupt (TI), when either the TBE or TSC flag becomes "1", can be selected to occur depending on the setting of the transmit interrupt source selection bit (TIC) of the serial I/O1 control register.
3: The receive interrupt (RI) is set when the RBF flag becomes "1".
4: After data is written to the transmit buffer when TSC=1, 0.5 to 1.5 cycles of the data shift cycle is necessary until changing to TSC=0.

Fig. 39 Operation of UART serial I/O1 function

[Transmit Buffer Register/Receive Buffer Register (TB/RB)] 0018$_{16}$

The transmit buffer register and the receive buffer register are located at the same address. The transmit buffer is write-only and the receive buffer is read-only. If a character bit length is 7 bits, the MSB of data stored in the receive buffer is "0".

[Serial I/O1 Status Register (SIOSTS)] 0019$_{16}$

The read-only serial I/O1 status register consists of seven flags (bits 0 to 6) which indicate the operating status of the serial I/O1 function and various errors.

Three of the flags (bits 4 to 6) are valid only in UART mode.

The receive buffer full flag (bit 1) is cleared to "0" when the receive buffer register is read.

If there is an error, it is detected at the same time that data is transferred from the receive shift register to the receive buffer register, and the receive buffer full flag is set. A write to the serial I/O1 status register clears all the error flags OE, PE, FE, and SE (bit 3 to bit 6, respectively). Writing "0" to the serial I/O1 enable bit SIOE (bit 7 of the serial I/O1 control register) also clears all the status flags, including the error flags.

Bits 0 to 6 of the serial I/O1 status register are initialized to "0" at reset, but if the transmit enable bit (bit 4) of the serial I/O1 control register has been set to "1", the transmit shift completion flag (bit 2) and the transmit buffer empty flag (bit 0) become "1".

[Serial I/O1 Control Register (SIOCON)] 001A$_{16}$

The serial I/O1 control register consists of eight control bits for the serial I/O1 function.

[UART Control Register (UARTCON)] 001B$_{16}$

The UART control register consists of four control bits (bits 0 to 3) which are valid when asynchronous serial I/O is selected and set the data format of an data transfer and one bit (bit 4) which is always valid and sets the output structure of the P25/TxD pin.

[Baud Rate Generator (BRG)] 001C$_{16}$

The baud rate generator determines the baud rate for serial transfer.

The baud rate generator divides the frequency of the count source by 1/(n + 1), where n is the value written to the baud rate generator.

Downloaded from Arrow.com.

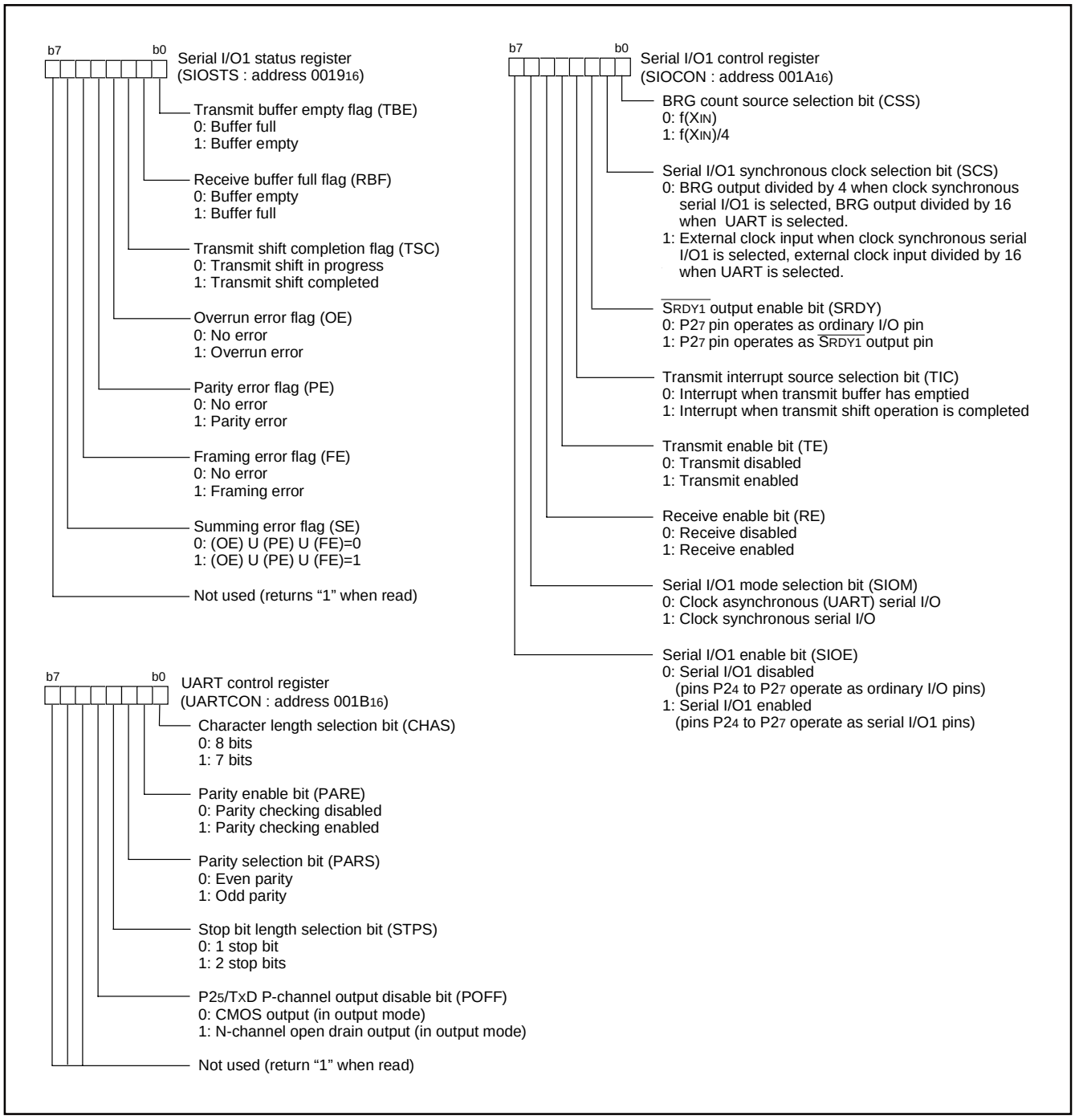


Fig. 40 Structure of serial I/O1 control registers

■Notes on serial interface

When setting the transmit enable bit of serial I/O1 to “1”, the serial I/O1 transmit interrupt request bit is automatically set to “1”. When not requiring the interrupt occurrence synchronized with the transmission enabled, take the following sequence.

(1) Set the serial I/O1 transmit interrupt enable bit to “0” (disabled).
(2) Set the transmit enable bit to “1”.
(3) Set the serial I/O1 transmit interrupt request bit to “0” after 1 or more instructions have been executed.
(4) Set the serial I/O1 transmit interrupt enable bit to “1” (enabled).

Downloaded from Arrow.com.

●SERIAL I/O2

The serial I/O2 can be operated only as the clock synchronous type. As a synchronous clock for serial transfer, either internal clock or external clock can be selected by the serial I/O2 synchronous clock selection bit (b6) of serial I/O2 control register 1.

The internal clock incorporates a dedicated divider and permits selecting 6 types of clock by the internal synchronous clock selection bits (b2, b1, b0) of serial I/O2 control register 1.

Regarding S_{OUT2} and S_{CLK2} being output pins, either CMOS output format or N-channel open-drain output format can be selected by the $P0_1/S_{OUT2}$, $P0_2/S_{CLK2}$ P-channel output disable bit (b7) of serial I/O2 control register 1.

When the internal clock has been selected, a transfer starts by a write signal to the serial I/O2 register (address 0017_{16}). After completion of data transfer, the level of the S_{OUT2} pin goes to high impedance automatically but bit 7 of the serial I/O2 control register 2 is not set to "1" automatically.

When the external clock has been selected, the contents of the serial I/O2 register is continuously sifted while transfer clocks are input. Accordingly, control the clock externally. Note that the S_{OUT2} pin does not go to high impedance after completion of data transfer.

To cause the S_{OUT2} pin to go to high impedance in the case where the external clock is selected, set bit 7 of the serial I/O2 control register 2 to "1" when S_{CLK2} is "H" after completion of data transfer. After the next data transfer is started (the transfer clock falls), bit 7 of the serial I/O2 control register 2 is set to "0" and the S_{OUT2} pin is put into the active state.

Regardless of the internal clock to external clock, the interrupt request bit is set after the number of bits (1 to 8 bits) selected by the optional transfer bit is transferred. In case of a fractional number of bits less than 8 bits as the last data, the received data to be stored in the serial I/O2 register becomes a fractional number of bits close to MSB if the transfer direction selection bit of serial I/O2 control register 1 is LSB first, or a fractional number of bits close to LSB if the transfer direction selection bit is MSB first. For the remaining bits, the previously received data is shifted.

At transmit operation using the clock synchronous serial I/O, the S_{CMP2} signal can be output by comparing the state of the transmit pin S_{OUT2} with the state of the receive pin S_{IN2} in synchronization with a rise of the transfer clock. If the output level of the S_{OUT2} pin is equal to the input level to the S_{IN2} pin, "L" is output from the S_{CMP2} pin. If not, "H" is output. At this time, an INT_2 interrupt request can also be generated. Select a valid edge by bit 2 of the interrupt edge selection register (address $003A_{16}$).

[Serial I/O2 Control Registers 1, 2 (SIO2CON1 / SIO2CON2)] 0015_{16}, 0016_{16}

The serial I/O2 control registers 1 and 2 are containing various selection bits for serial I/O2 control as shown in Figure 41.

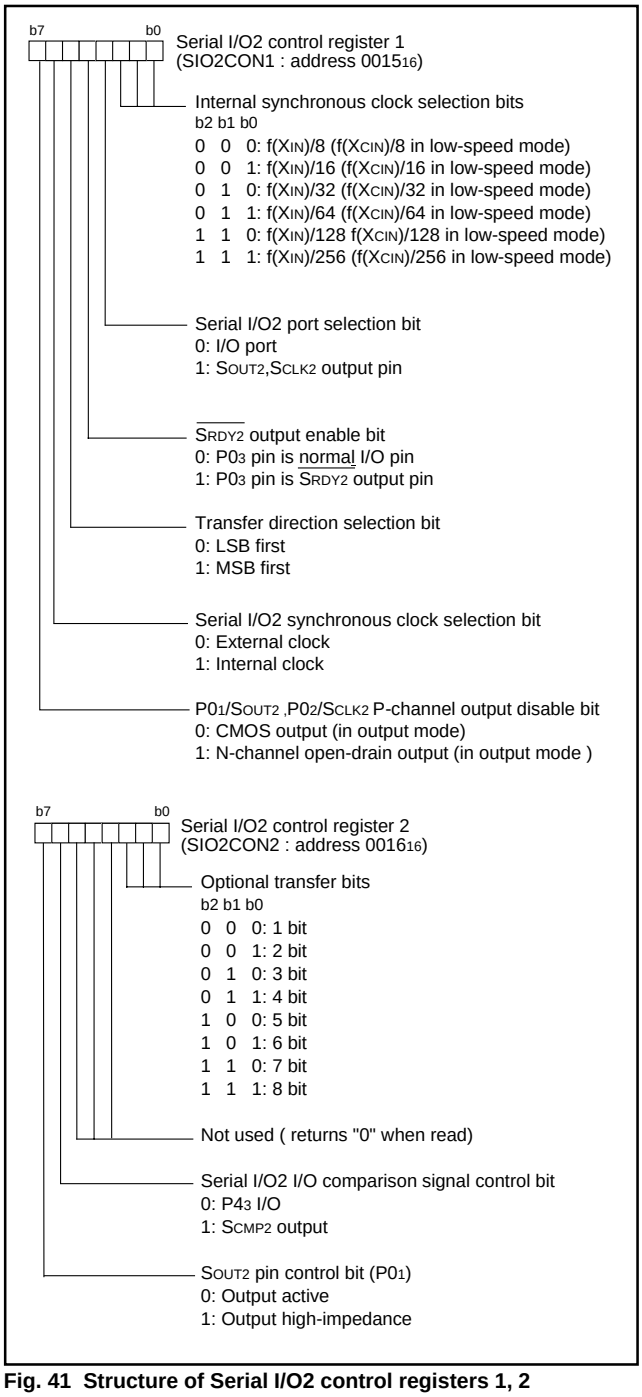
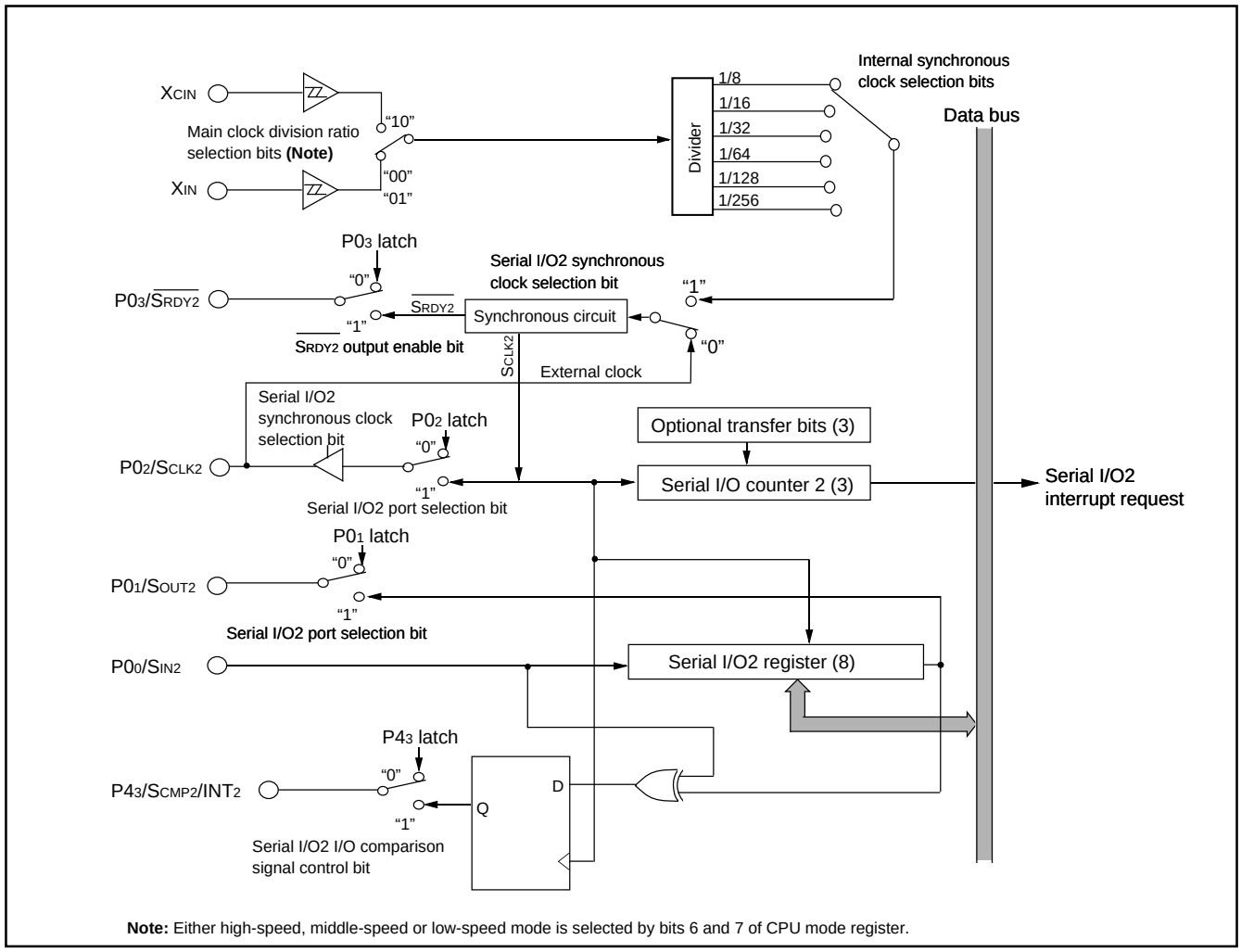


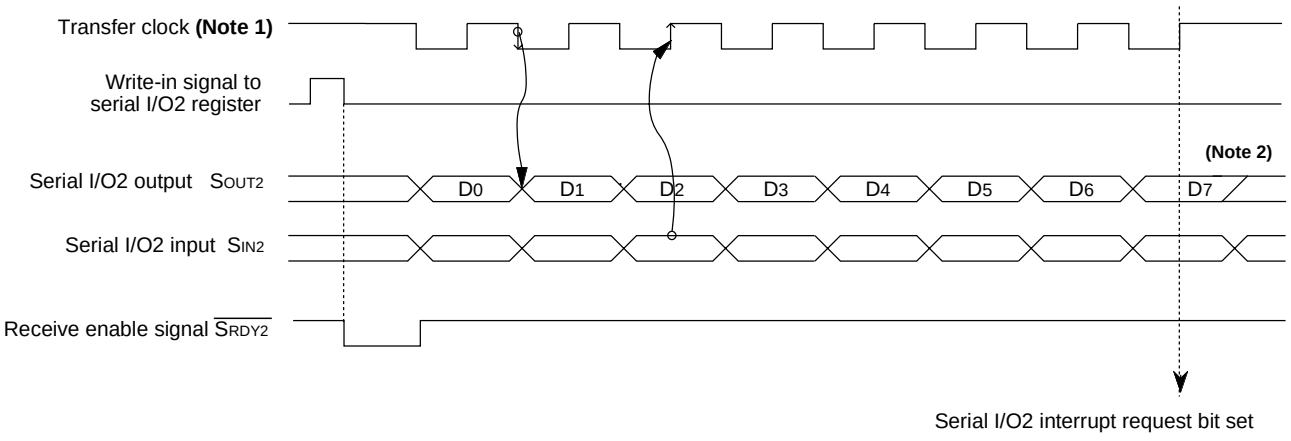
Fig. 41 Structure of Serial I/O2 control registers 1, 2

Downloaded from Arrow.com.



Note: Either high-speed, middle-speed or low-speed mode is selected by bits 6 and 7 of CPU mode register.

Fig. 42 Block diagram of Serial I/O2



Notes 1: When the internal clock is selected as a transfer clock, the f(XIN) clock division (f(XCIN) in low-speed mode) can be selected by setting bits 0 to 2 of serial I/O2 control register 1.
2: When the internal clock is selected as a transfer clock, the SOUT2 pin has high impedance after transfer completion.

Fig. 43 Timing chart of Serial I/O2

Downloaded from Arrow.com.

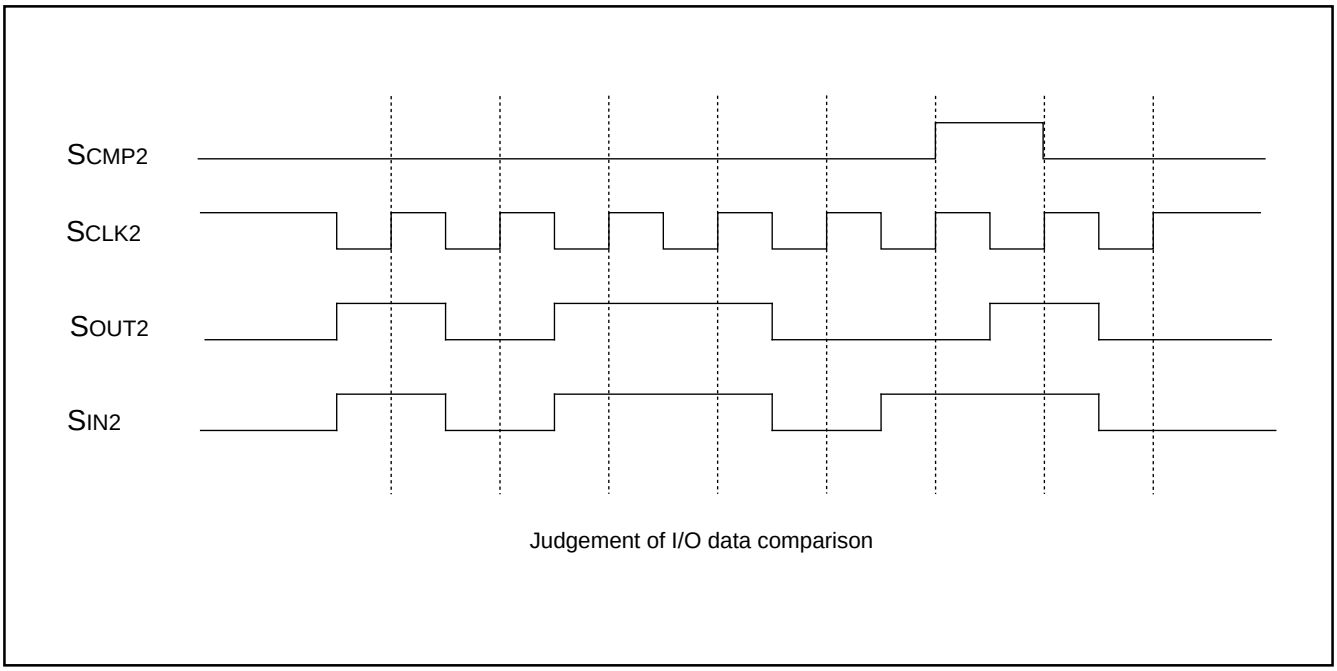


Fig. 44 SCMP2 output operation

Downloaded from Arrow.com.

PWM (PWM: Pulse Width Modulation)

The 3858 group has a PWM function with an 8-bit resolution, based on a signal that is the clock input XIN or that clock input divided by 2.

Data Setting

The PWM output pin also functions as port P44. Set the PWM period by the PWM prescaler, and set the "H" term of output pulse by the PWM register.

If the value in the PWM prescaler is n and the value in the PWM register is m (where n = 0 to 255 and m = 0 to 255) :

PWM period = 255 × (n+1) / f(XIN)

= 31.875 × (n+1) µs

(when f(XIN) = 8 MHz, count source selection bit = "0")

Output pulse "H" term = PWM period × m / 255

= 0.125 × (n+1) × m µs

(when f(XIN) = 8 MHz, count source selection bit = "0")

PWM Operation

When bit 0 (PWM enable bit) of the PWM control register is set to "1", operation starts by initializing the PWM output circuit, and pulses are output starting at an "H".

If the PWM register or PWM prescaler is updated during PWM output, the pulses will change in the cycle after the one in which the change was made.

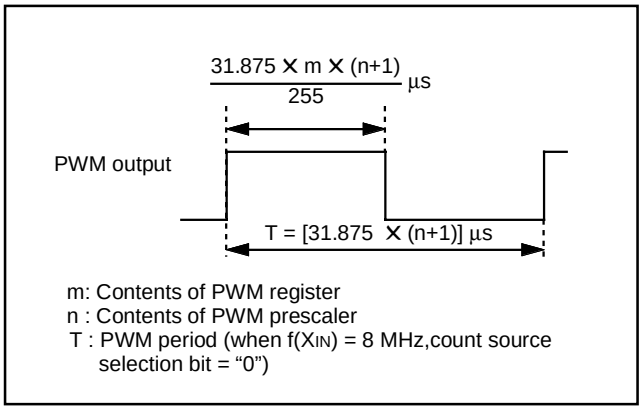


Fig. 45 Timing of PWM period

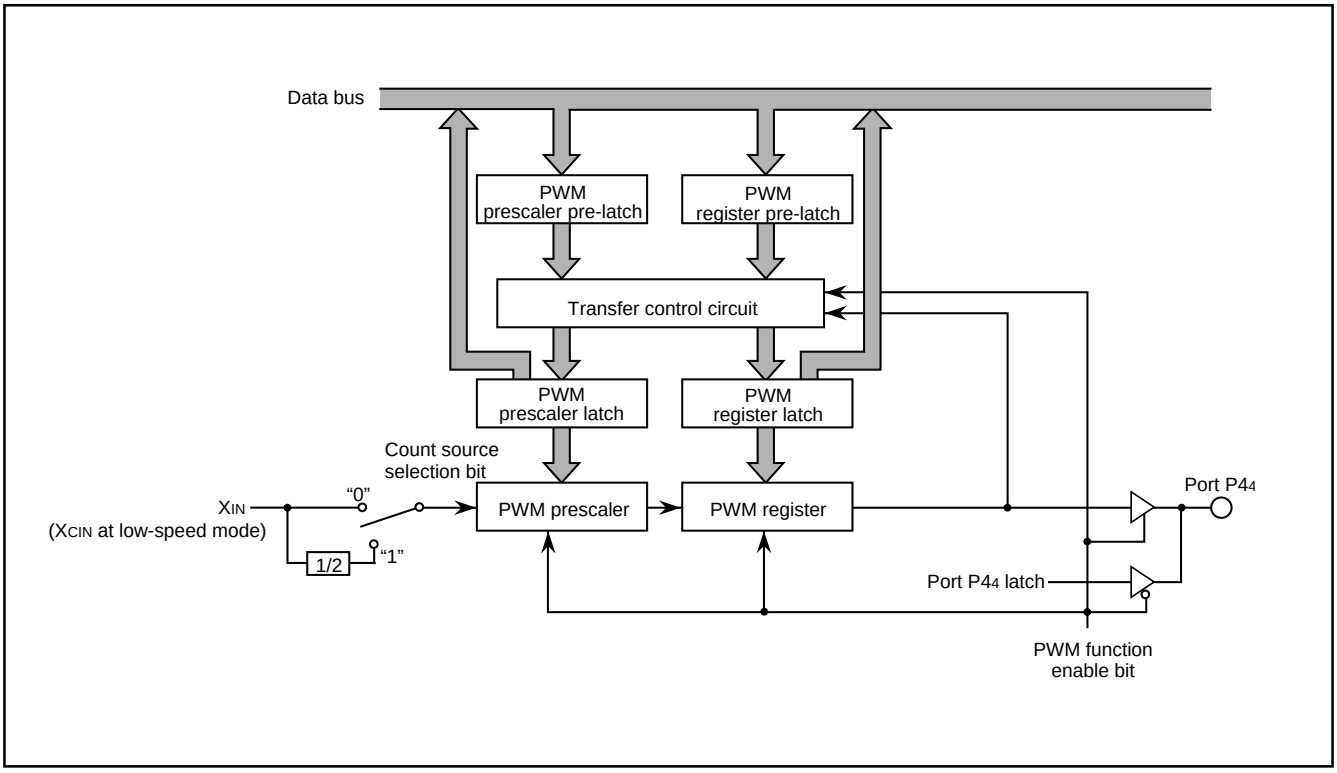


Fig. 46 Block diagram of PWM function

Downloaded from Arrow.com.

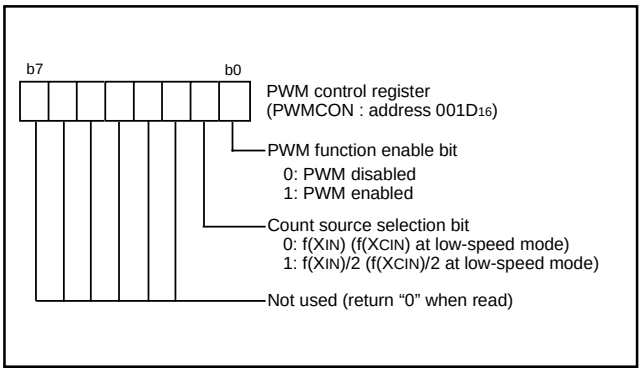


Fig. 47 Structure of PWM control register

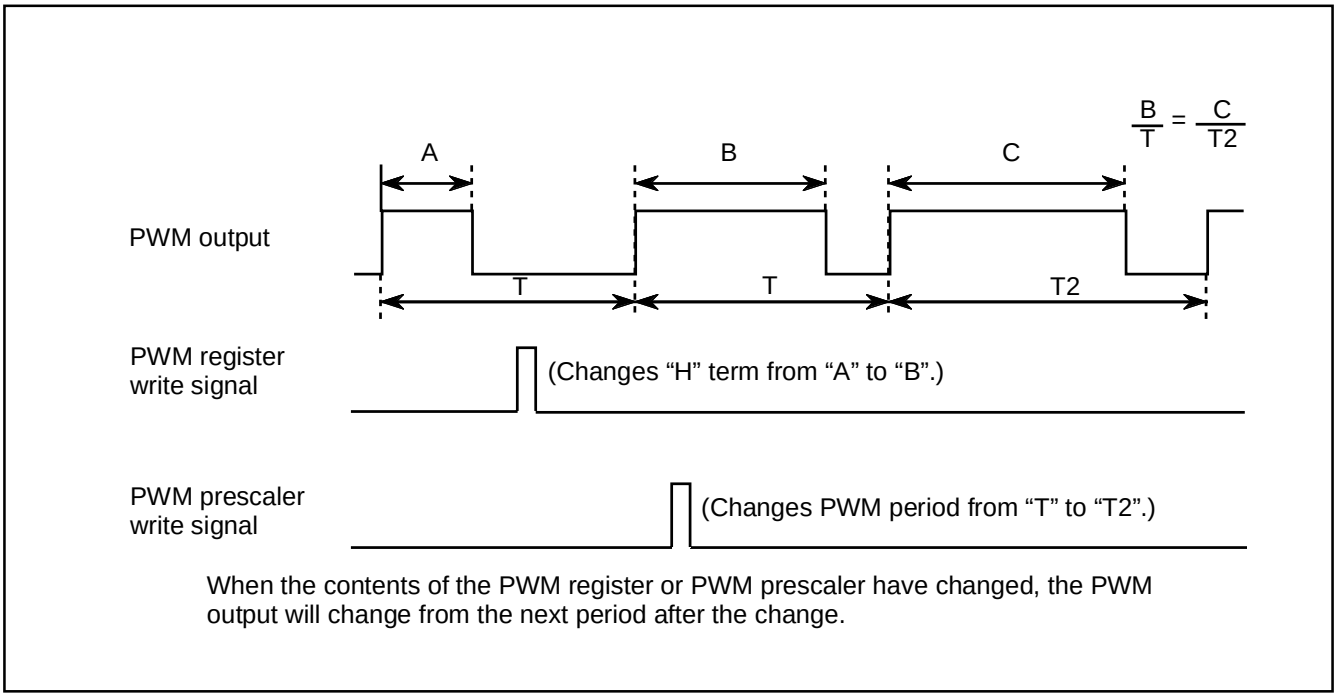


Fig. 48 PWM output timing when PWM register or PWM prescaler is changed

■Note

The PWM starts after the PWM function enable bit is set to enable and “L” level is output from the PWM pin.
The length of this “L” level output is as follows:

$$\frac{n+1}{2 \times f(X_{IN})} \text{ sec} \quad \text{(Count source selection bit = 0, where n is the value set in the prescaler)}$$

$$\frac{n+1}{f(X_{IN})} \text{ sec} \quad \text{(Count source selection bit = 1, where n is the value set in the prescaler)}$$

Downloaded from Arrow.com.

A/D CONVERTER
[AD Conversion Register (ADL)] 0035$_{16}$

The A/D conversion register is a read-only register that stores the result of A/D conversion. Do not read out this register during an A/D conversion.

[AD Control Register (ADCON)] 0034$_{16}$

The A/D control register controls the A/D converter. Bit 3 to 0 are analog input pin selection bits. Bit 4 is the AD conversion completion bit. The value of this bit remains at “0” during A/D conversion, and changes to “1” at completion of A/D conversion.
A/D conversion is started by setting this bit to “0”.

Comparison Voltage Generator

The comparison voltage generator divides the voltage between AVSS and VREF by 256, and outputs the divided voltages.

Channel Selector

The channel selector selects one of ports P3$_0$/AN$_0$ to P3$_4$/AN$_4$, P0$_4$/AN$_5$ to P0$_7$/AN$_8$ and inputs the voltage to the comparator.

Comparator and Control Circuit

The comparator and control circuit compare an analog input voltage with the comparison voltage, and the result is stored in the AD conversion registers. When an A/D conversion is completed, the control circuit sets the AD conversion completion bit and the AD interrupt request bit to “1”.
Note that because the comparator consists of a capacitor coupling, set f(XIN) to 500 kHz or more during an A/D conversion.

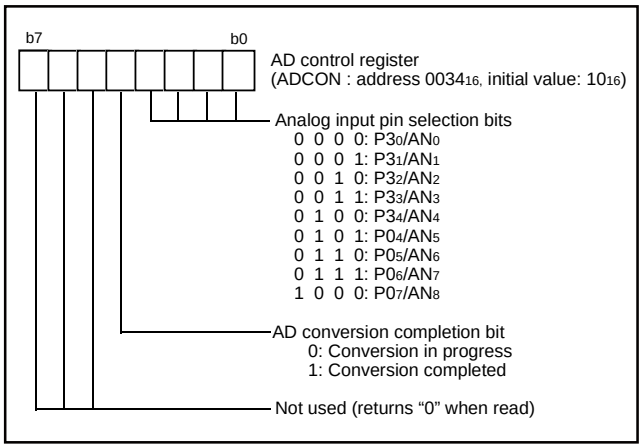


Fig. 49 Structure of AD control register

■Note on A/D converter

The comparator uses internal capacitors whose charge will be lost if the clock frequency is too low.
Make sure that f(XIN) is 500 kHz or more during A/D conversion.
As for AD translation accuracy, on the following operating conditions, accuracy may become low.
(1) Since the analog circuit inside a microcomputer becomes sensitive to noise when VREF voltage is set up lower than Vcc voltage, accuracy may become low rather than the case where VREF voltage and Vcc voltage are set up to the same value..
(2) When VREF voltage is lower than [3.0 V], the accuracy at the low temperature may become extremely low compared with that at room temperature. When the system would be used at low temperature, the use at VREF=3.0 V or more is recommended.

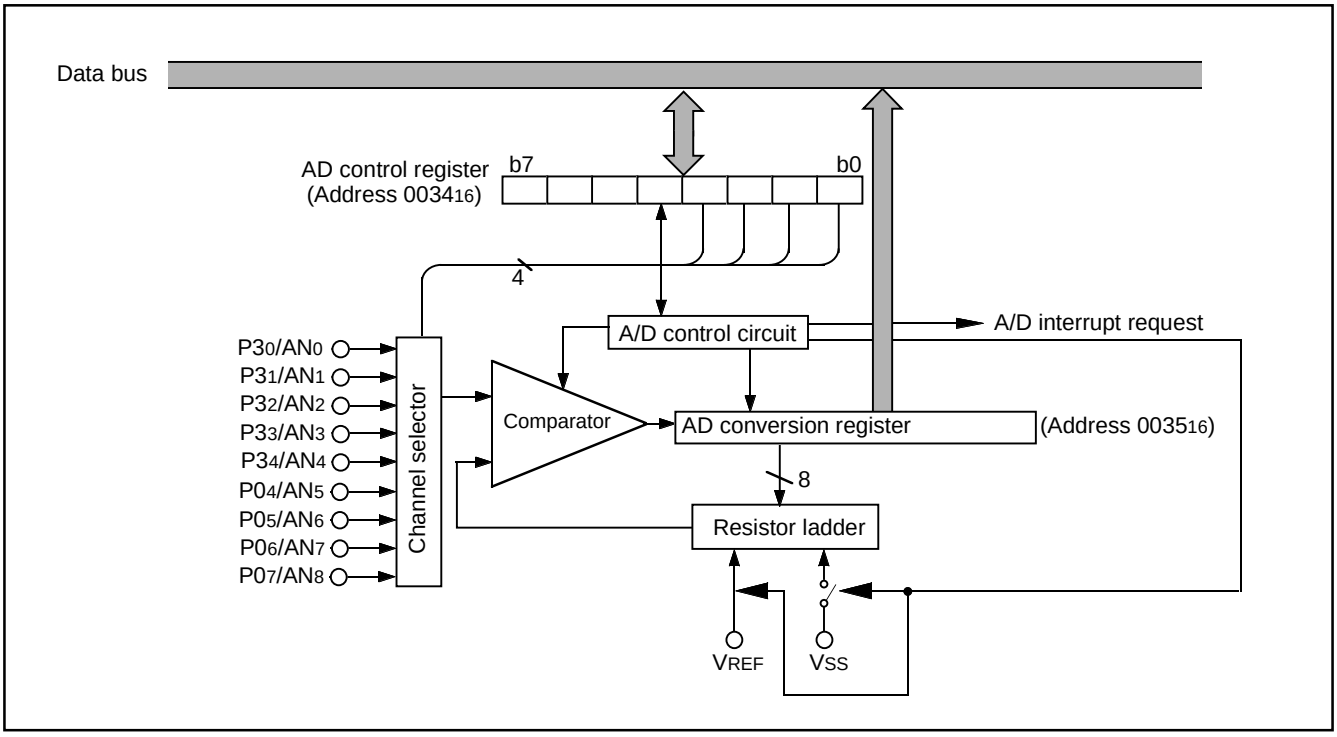


Fig. 50 Block diagram of A/D converter

Downloaded from Arrow.com.

WATCHDOG TIMER

The watchdog timer gives a mean of returning to the reset status when a program cannot run on a normal loop (for example, because of a software run-away). The watchdog timer consists of an 8-bit watchdog timer L and an 8-bit watchdog timer H.

Initial Value of Watchdog Timer

At reset or writing to the watchdog timer control register (address 0039_{16}), each of watchdog timer H and L is set to "FF_{16}". Any instruction which generates a write signal such as the instructions of STA, LDM, CLB and others can be used to write. The data of bits 6 and 7 are only valid when writing to the watchdog timer control register. Each of watchdog timer is set to "FF_{16}" regardless of the written data of bits 0 to 5.

Bit 6 can be written to only once after reset release. After this bit is written, it cannot rewritten because it is locked.

Operation of Watchdog Timer

The watchdog timer stops at reset and starts to count down by writing to the watchdog timer control register. An internal reset occurs at an underflow of the watchdog timer H. The reset is released after waiting for a reset release time and the program is processed from the reset vector address. Accordingly, programming is usually performed so that writing to the watchdog timer control register may be started before an underflow of the watchdog timer H. If writing to the watchdog timer control register is not performed once, the watchdog timer does not function.

Bit 6 of Watchdog Timer Control Register

When bit 6 of the watchdog timer control register is "0", the MCU enters the stop mode by execution of STP instruction. Just after releasing the stop mode, the watchdog timer restarts counting (Note). When executing the WIT instruction, the watchdog timer does not stop.

When bit 6 is "1", execution of STP instruction causes an internal reset. When this bit is set to "1" once, it cannot be rewritten to "0" by program. Bit 6 is "0" at reset.

The necessary time after writing to the watchdog timer control register to an underflow of the watchdog timer H is shown as follows.

When bit 7 of the watchdog timer control register is "0":

32 s at X_{CIN} = 32.768 kHz frequency and

131.072 ms at X_{IN} = 8 MHz frequency.

When bit 7 of the watchdog timer control register is "1":

125 ms at X_{CIN} = 32.768 kHz frequency and

512 µs at X_{IN} = 8 MHz frequency.

Note: The watchdog timer continues to count for waiting for a stop mode release time. Do not generate an underflow of the watchdog timer H during that time.

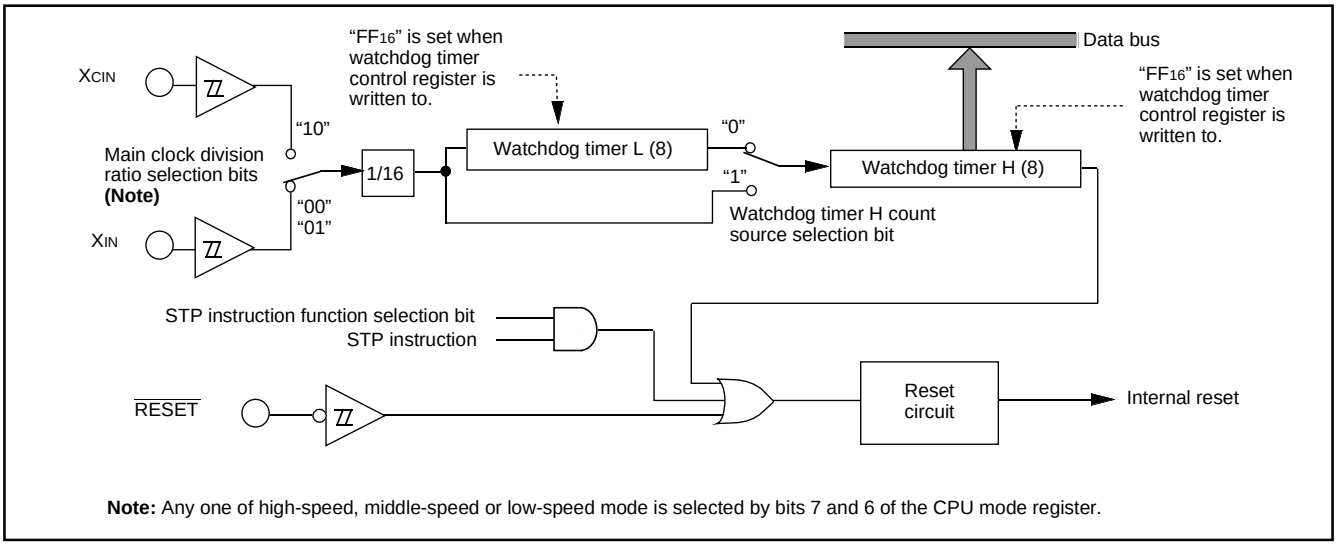


Fig. 51 Block diagram of Watchdog timer

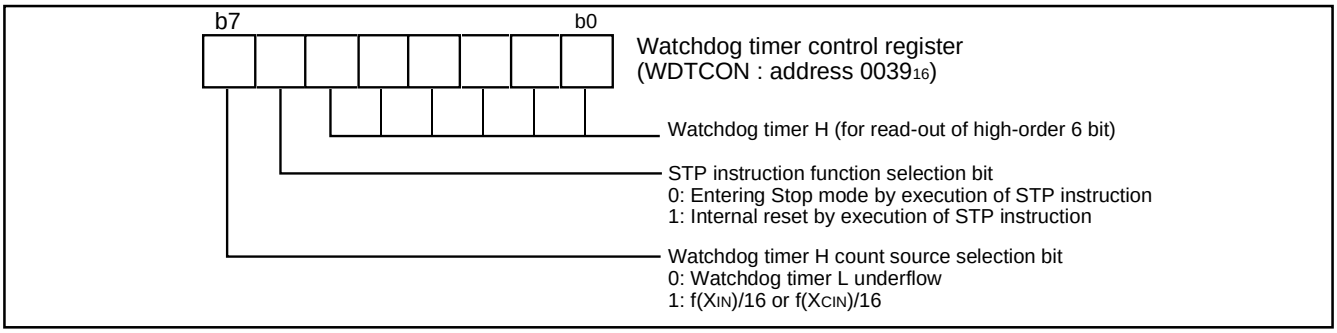


Fig. 52 Structure of Watchdog timer control register

Downloaded from Arrow.com.

RESET CIRCUIT

To reset the microcomputer, $\overline{\text{RESET}}$ pin must be held at an “L” level for 20 cycles or more of X_{IN}. Then the $\overline{\text{RESET}}$ pin is returned to an “H” level (the power source voltage must be between 2.7 V and 5.5 V, and the oscillation must be stable), reset is released. After the reset is completed, the program starts from the address contained in address $FFFD_{16}$ (high-order byte) and address $FFFC_{16}$ (low-order byte). Make sure that the reset input voltage is less than 0.54 V for V_{CC} of 2.7 V.

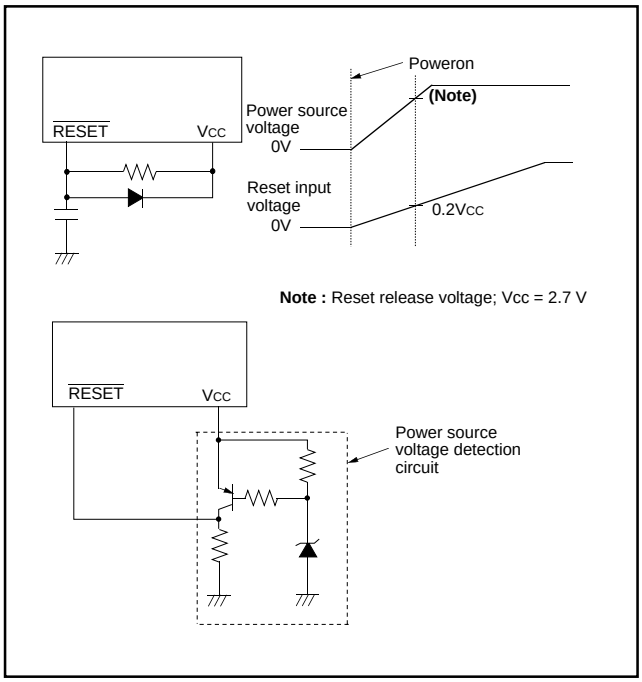


Fig. 53 Reset circuit example

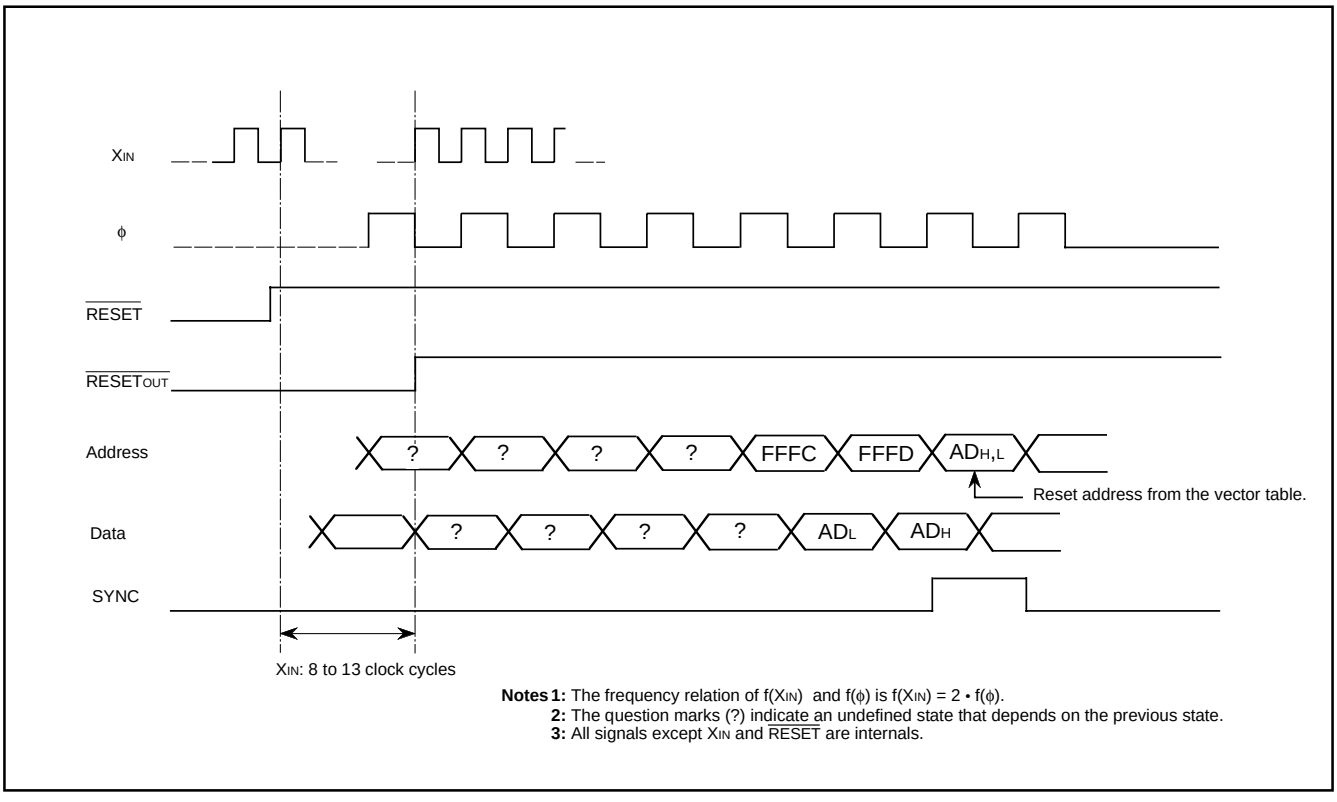


Fig. 54 Reset sequence

Downloaded from Arrow.com.

		Address	Register contents
(1)	Port P0 (P0)	0000_{16}	00_{16}
(2)	Port P0 direction register (P0D)	0001_{16}	00_{16}
(3)	Port P1 (P1)	0002_{16}	00_{16}
(4)	Port P1 direction register (P1D)	0003_{16}	00_{16}
(5)	Port P2 (P2)	0004_{16}	00_{16}
(6)	Port P2 direction register (P2D)	0005_{16}	00_{16}
(7)	Port P3 (P3)	0006_{16}	00_{16}
(8)	Port P3 direction register (P3D)	0007_{16}	00_{16}
(9)	Port P4 (P4)	0008_{16}	00_{16}
(10)	Port P4 direction register (P4D)	0009_{16}	00_{16}
(11)	Port P0 pull-up control register (PULL0)	0010_{16}	00_{16}
(12)	Port P1 pull-up control register (PULL1)	0011_{16}	00_{16}
(13)	Port P2 pull-up control register (PULL2)	0012_{16}	00_{16}
(14)	Port P3 pull-up control register (PULL3)	0013_{16}	00_{16}
(15)	Port P4 pull-up control register (PULL4)	0014_{16}	00_{16}
(16)	Serial I/O2 control register 1 (SIO2CON1)	0015_{16}	00_{16}
(17)	Serial I/O2 control register 2 (SIO2CON2)	0016_{16}	0 0 0 0 0 1 1 1
(18)	Serial I/O2 register (SIO2)	0017_{16}	X X X X X X X X
(19)	Transmit/Receive buffer register (TB/RB)	0018_{16}	X X X X X X X X
(20)	Serial I/O1 status register (SIOSTS)	0019_{16}	1 0 0 0 0 0 0 0
(21)	Serial I/O1 control register (SIOCON)	$001A_{16}$	00_{16}
(22)	UART control register (UARTCON)	$001B_{16}$	1 1 1 0 0 0 0 0
(23)	Baud rate generator (BRG)	$001C_{16}$	X X X X X X X X
(24)	PWM control register (PWMCON)	$001D_{16}$	00_{16}
(25)	PWM prescaler (PREPWM)	$001E_{16}$	X X X X X X X X
(26)	PWM register (PWM)	$001F_{16}$	X X X X X X X X
(27)	Prescaler 12 (PRE12)	0020_{16}	FF_{16}
(28)	Timer 1 (T1)	0021_{16}	01_{16}
(29)	Timer 2 (T2)	0022_{16}	FF_{16}
(30)	Timer XY mode register (TM)	0023_{16}	00_{16}
(31)	Prescaler X (PREX)	0024_{16}	FF_{16}
(32)	Timer X (TX)	0025_{16}	FF_{16}
(33)	Prescaler Y (PREY)	0026_{16}	FF_{16}
(34)	Timer Y (TY)	0027_{16}	FF_{16}

		Address	Register contents
(35)	Timer Z1 mode register (TZ1M)	0028_{16}	00_{16}
(36)	Timer Z1 low-order (TZ1L)	0029_{16}	FF_{16}
(37)	Timer Z1 high-order (TZ1H)	$002A_{16}$	FF_{16}
(38)	Timer Z2 mode register (TZ2M)	$002B_{16}$	00_{16}
(39)	Timer Z2 low-order (TZ2L)	$002C_{16}$	FF_{16}
(40)	Timer Z2 high-order (TZ2H)	$002D_{16}$	FF_{16}
(41)	Timer 12, X count source selection register (T12XCSS)	$002E_{16}$	0 0 1 1 0 0 1 1
(42)	Timer Y, Z1 count source selection register (TYZ1CSS)	$002F_{16}$	0 0 1 1 0 0 1 1
(43)	Timer Z2 count source selection register (TZ2CSS)	0030_{16}	0 0 0 0 0 0 1 1
(44)	AD control register (ADCON)	0034_{16}	0 0 0 1 0 0 0 0
(45)	AD conversion register (AD)	0035_{16}	X X X X X X X X
(46)	Interrupt source selection register (INTSEL)	0036_{16}	00_{16}
(47)	MISRG	0038_{16}	00_{16}
(48)	Watchdog timer control register (WDTCON)	0039_{16}	0 0 1 1 1 1 1 1
(49)	Interrupt edge selection register (INTEDGE)	$003A_{16}$	00_{16}
(50)	CPU mode register (CPUM)	$003B_{16}$	0 1 0 0 1 0 0 0
(51)	Interrupt request register 1 (IREQ1)	$003C_{16}$	00_{16}
(52)	Interrupt request register 2 (IREQ2)	$003D_{16}$	00_{16}
(53)	Interrupt control register 1 (ICON1)	$003E_{16}$	00_{16}
(54)	Interrupt control register 2 (ICON2)	$003F_{16}$	00_{16}
	Processor status register	(PS)	X X X X X 1 X X
	Program counter	(PC_H)	$FFFD_{16}$ contents
		(PC_L)	$FFFC_{16}$ contents

Note : X : Not fixed
Since the initial values for other than above mentioned registers and RAM contents are indefinite at reset, they must be set.

Fig. 55 Internal status at reset

Downloaded from Arrow.com.

CLOCK GENERATING CIRCUIT

The 3858 group has two built-in oscillation circuits. An oscillation circuit can be formed by connecting a resonator between XIN and XOUT (XCIN and XCOUT). Use the circuit constants in accordance with the resonator manufacturer's recommended values. No external resistor is needed between XIN and XOUT since a feed-back resistor exists on-chip. (An external feed-back resistor may be needed depending on conditions.) However, an external feed-back resistor is needed between XCIN and XCOUT.

Immediately after power on, only the XIN oscillation circuit starts oscillating, and XCIN and XCOUT pins function as I/O ports.

●Frequency Control

(1) Middle-speed mode

The internal clock ϕ is the frequency of XIN divided by 8. After reset is released, this mode is selected.

(2) High-speed mode

The internal clock ϕ is half the frequency of XIN.

(3) Low-speed mode

The internal clock ϕ is half the frequency of XCIN.

(4) Low power dissipation mode

The low power consumption operation can be realized by stopping the main clock XIN in low-speed mode. To stop the main clock, set bit 5 of the CPU mode register to "1". When the main clock XIN is restarted (by setting the main clock stop bit to "0"), set sufficient time for oscillation to stabilize.

The sub-clock XCIN-XCOUT oscillating circuit can not directly input clocks that are generated externally. Accordingly, make sure to cause an external resonator to oscillate.

●Oscillation Control

(1) Stop mode

If the STP instruction is executed, the internal clock ϕ stops at an "H" level, and XIN and XCIN oscillation stops. When the oscillation stabilizing time set after STP instruction released bit (bit 0 of address 003816) is "0", the prescaler 12 is set to "FF_{16}" and timer 1 is set to "01_{16}". When the oscillation stabilizing time set after STP instruction released bit is "1", set the sufficient time for oscillation of used oscillator to stabilize since nothing is set to the prescaler 12 and timer 1.

After STP instruction is released, the input of the prescaler 12 is connected to count source which had set at executing the STP instruction, and the output of the prescaler 12 is connected to timer 1. Oscillator restarts when an external interrupt is received, but the internal clock ϕ is not supplied to the CPU (remains at "H") until timer 1 underflows. The internal clock ϕ is supplied for the first time, when timer 1 underflows. This ensures time for the clock oscillation using the ceramic resonators to be stabilized. When the oscillator is restarted by reset, apply "L" level to the $\overline{\text{RESET}}$ pin until the oscillation is stable since a wait time will not be generated.

(2) Wait mode

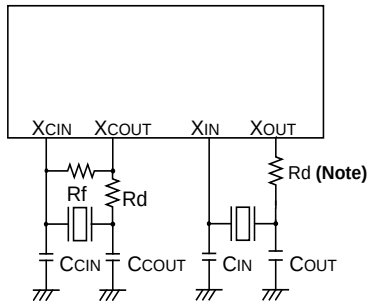
If the WIT instruction is executed, the internal clock ϕ stops at an "H" level, but the oscillator does not stop. The internal clock ϕ restarts at reset or when an interrupt is received. Since the oscillator does not stop, normal operation can be started immediately after the clock is restarted.

To ensure that the interrupts will be received to release the STP or WIT state, their interrupt enable bits must be set to "1" before executing of the STP or WIT instruction.

When releasing the STP state, the input of the prescaler 12 and timer 1 is connected to the count source which had set at executing the STP instruction and the prescaler 12 and timer 1 will start counting. Set the timer 1 interrupt enable bit to "0" before executing the STP instruction.

■Notes

- If you switch the mode between middle/high-speed and low-speed, stabilize both XIN and XCIN oscillations. The sufficient time is required for the sub-clock to stabilize, especially immediately after power on and at returning from the stop mode. When switching the mode between middle/high-speed and low-speed, set the frequency on condition that f(XIN) > 3 × f(XCIN).
- When using the oscillation stabilizing time set after STP instruction released bit set to "1", evaluate time to stabilize oscillation of the used oscillator and set the value to the timer 1 and prescaler 12.



Notes : Insert a damping resistor if required.
The resistance will vary depending on the oscillator and the oscillation drive capacity setting.
Use the value recommended by the maker of the oscillator.
Also, if the oscillator manufacturer's data sheet specifies that a feedback resistor be added external to the chip though a feedback resistor exists on-chip, insert a feedback resistor between XIN and XOUT following the instruction.

Fig. 56 Ceramic resonator circuit

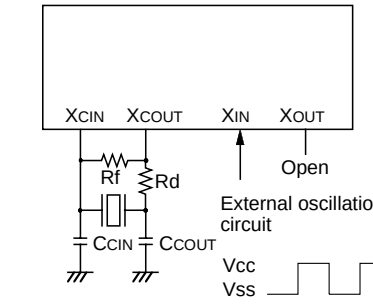


Fig. 57 External clock input circuit

Downloaded from Arrow.com.

[MISRG (MISRG)] 0038$_{16}$

MISRG consists of three control bits (bits 1 to 3) for middle-speed mode automatic switch and one control bit (bit 0) for oscillation stabilizing time set after STP instruction released.

By setting the middle-speed mode automatic switch start bit to “1” while operating in the low-speed mode and setting the middle-speed mode automatic switch set bit to “1”, XIN oscillation automatically starts and the mode is automatically switched to the middle-speed mode.

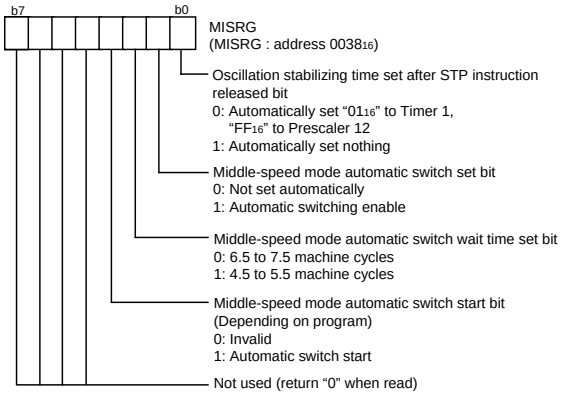
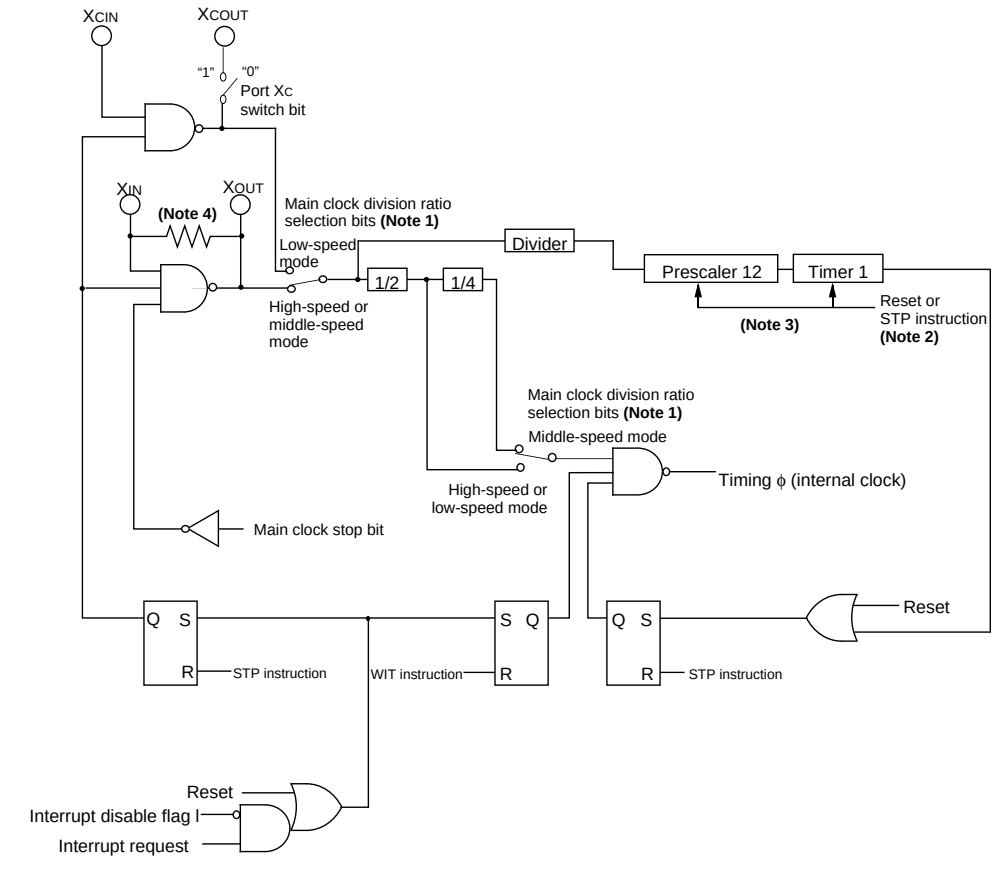


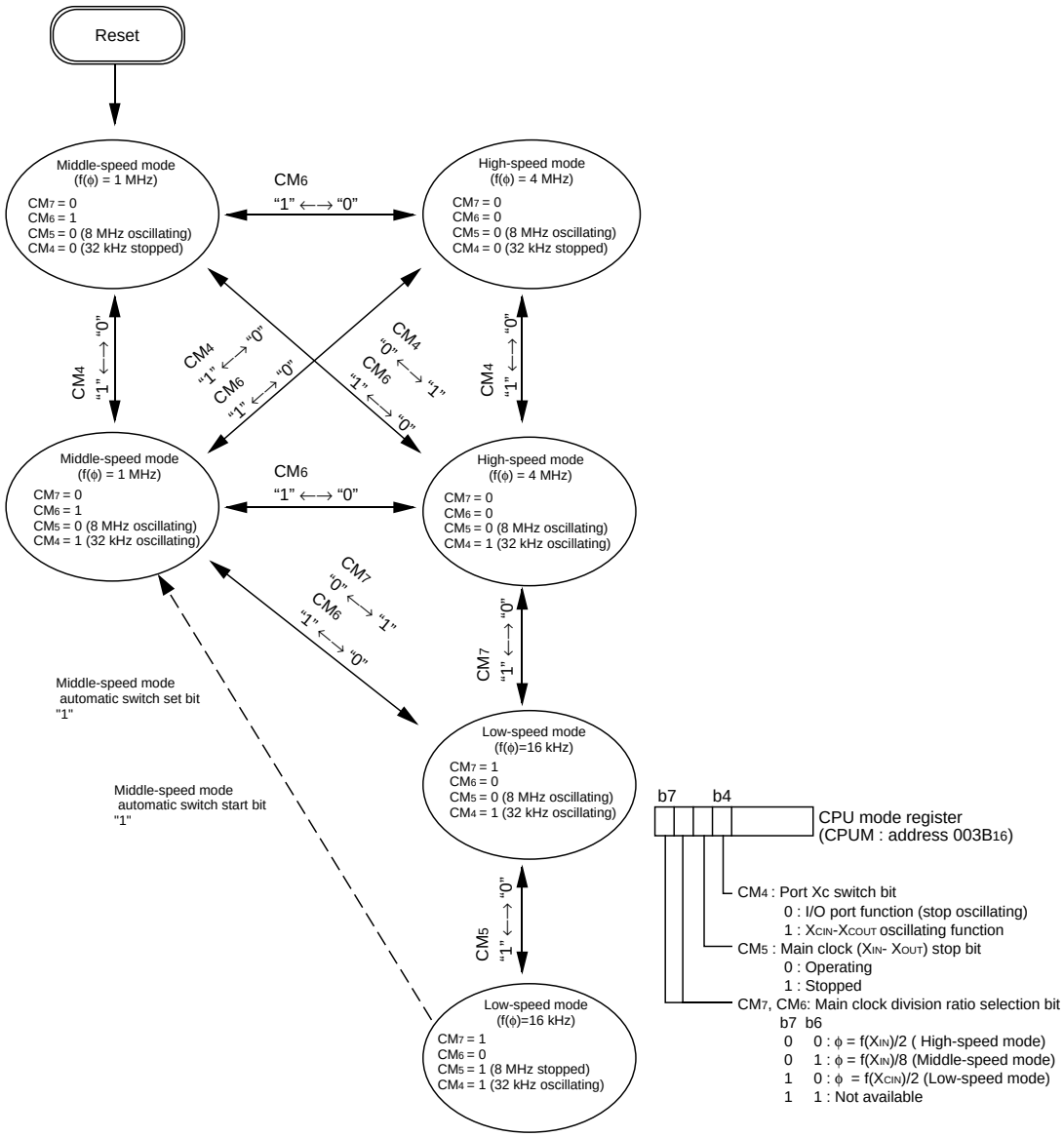
Fig. 58 Structure of MISRG



Notes 1: Any one of high-speed, middle-speed or low-speed mode is selected by bits 7 and 6 of the CPU mode register. When low-speed mode is selected, set port Xc switch bit (b4) to “1”.
2: f(XIN)/16 is supplied as the count source to the prescaler 12 at reset, the count source before executing the STP instruction is supplied as the count source at executing STP instruction.
3: When bit 0 of MISRG = “0”, the prescaler 12 is set to "FF$_{16}$" and timer 1 is set to "01$_{16}$". When bit 0 of MISRG = “1”, set the sufficient time for oscillation of used oscillator to stabilize since nothing is set to the prescaler 12 and timer 1.
4: Although a feed-back resistor exists on-chip, an external feed-back resistor may be needed depending on conditions.

Fig. 59 System clock generating circuit block diagram (Single-chip mode)

Downloaded from Arrow.com.



Notes 1 : Switch the mode by the allows shown between the mode blocks. (Do not switch between the modes directly without an allow.)

2 : The all modes can be switched to the stop mode or the wait mode and return to the source mode when the stop mode or the wait mode is ended.

3 : Timer operates in the wait mode.

4 : After STP instruction is released, the count source which had set by bit 2 (timer 12 count source selection bit) of the timer count source set register at executing the STP instruction is supplied to timer 1. Accordingly, when bit 0 of MISRG is "0" and the timer 12 count source selection bit is "0" (f(XIN)/16 or f(XCIN)/16), a delay of approximately 1 ms occurs automatically in the high/middle-speed mode. A delay of approximately 256 ms occurs automatically in the low-speed mode (at f(XIN) = 8 MHz, f(XCIN) = 32 kHz). When the timer 12 count source selection bit is "1" (f(XCIN)), a delay of approximately 16 ms occurs regardless of the operation mode.

5 : Wait until oscillation stabilizes after oscillating the main clock XIN before the switching from the low-speed mode to middle/high-speed mode.

6 : When the mode is switched to the middle-speed mode by the middle-speed mode automatic switch set bit of MISRG, the waiting time set by the middle-speed mode automatic switch wait time set bit is automatically generated, and then the mode is switched to the middle-speed mode.

7 : The example assumes that 8 MHz is being applied to the XIN pin and 32 kHz to the XCIN pin. φ indicates the internal clock.

Fig. 60 State transitions of system clock

Downloaded from Arrow.com.

Electrical characteristics

Absolute maximum ratings

Table 7 Absolute maximum ratings

Symbol	Parameter	Conditions	Ratings	Unit
V_{CC}	Power source voltage	All voltages are based on V_{SS}.	–0.3 to 6.5	V
V_I	Input voltage $P0_0$–$P0_7$, $P1_0$–$P1_7$, $P2_0$, $P2_1$, $P2_4$–$P2_7$, $P3_0$–$P3_4$, $P4_0$–$P4_4$, V_{REF}	When an input voltage is measured, output transistors are cut off.	–0.3 to V_{CC} +0.3	V
V_I	Input voltage $P2_2$, $P2_3$		–0.3 to V_{CC} +0.3	V
V_I	Input voltage $\overline{RESET}$, X_{IN}		–0.3 to V_{CC} +0.3	V
V_I	Input voltage CNV$_{SS}$		–0.3 to 8.0	V
V_O	Output voltage $P0_0$–$P0_7$, $P1_0$–$P1_7$, $P2_0$, $P2_1$, $P2_4$–$P2_7$, $P3_0$–$P3_4$, $P4_0$–$P4_4$, X_{OUT}		–0.3 to V_{CC} +0.3	V
V_O	Output voltage $P2_2$, $P2_3$		–0.3 to 5.8	V
P_d	Power dissipation	T_a = 25 °C	1000 **(Note)**	mW
T_{opr}	Operating temperature	–	–20 to 85	°C
T_{stg}	Storage temperature	–	–40 to 125	°C

Note : The rating becomes 300mW at the PRSP0042GA-A/B (42P2R-A/E) package.

Downloaded from Arrow.com.

Recommended operating conditions

Table 8 Recommended operating conditions

(V_{CC} = 2.7 to 5.5 V, T_a = –20 to 85 °C, unless otherwise noted)

Symbol	Parameter		Limits			Unit
			Min.	Typ.	Max.	
V_{CC}	Power source voltage	At 12.5 MHz (High-speed mode)	4.0	5.0	5.5	V
		At 12.5 MHz (Middle-speed mode), 6 MHz (High-speed mode) 32 kHz (Low-speed mode)	2.7	5.0	5.5	V
V_{SS}	Power source voltage			0		V
V_{REF}	A/D convert reference voltage		2.0		V_{CC}	V
AV_{SS}	Analog power source voltage			0		V
V_{IA}	Analog input voltage	AN_0–AN_8	AV_{SS}		V_{CC}	V
V_{IH}	“H” input voltage	$P0_0$–$P0_7$, $P1_0$–$P1_7$, $P2_0$–$P2_7$, $P3_0$–$P3_4$, $P4_0$–$P4_4$	0.8V_{CC}		V_{CC}	V
V_{IH}	“H” input voltage	$\overline{RESET}$, X_{IN}, CNV_{SS}	0.8V_{CC}		V_{CC}	V
V_{IL}	“L” input voltage	$P0_0$–$P0_7$, $P1_0$–$P1_7$, $P2_0$–$P2_7$, $P3_0$–$P3_4$, $P4_0$–$P4_4$	0		0.2V_{CC}	V
V_{IL}	“L” input voltage	$\overline{RESET}$, CNV_{SS}	0		0.2V_{CC}	V
V_{IL}	“L” input voltage	X_{IN}	0		0.16V_{CC}	V
$\Sigma I_{OH(peak)}$	“H” total peak output current **(Note 1)**	$P0_0$–$P0_7$, $P1_0$–$P1_7$, $P3_0$–$P3_4$			–80	mA
$\Sigma I_{OH(peak)}$	“H” total peak output current **(Note 1)**	$P2_0$, $P2_1$, $P2_4$–$P2_7$, $P4_0$–$P4_4$			–80	mA
$\Sigma I_{OL(peak)}$	“L” total peak output current **(Note 1)**	$P0_0$–$P0_7$, $P3_0$–$P3_4$			80	mA
$\Sigma I_{OL(peak)}$	“L” total peak output current **(Note 1)**	$P1_0$–$P1_7$			120	mA
$\Sigma I_{OL(peak)}$	“L” total peak output current **(Note 1)**	$P2_0$–$P2_7$, $P4_0$–$P4_4$			80	mA
$\Sigma I_{OH(avg)}$	“H” total average output current **(Note 1)**	$P0_0$–$P0_7$, $P1_0$–$P1_7$, $P3_0$–$P3_4$			–40	mA
$\Sigma I_{OH(avg)}$	“H” total average output current **(Note 1)**	$P2_0$, $P2_1$, $P2_4$–$P2_7$, $P4_0$–$P4_4$			–40	mA
$\Sigma I_{OL(avg)}$	“L” total average output current **(Note 1)**	$P0_0$–$P0_7$, $P3_0$–$P3_4$			40	mA
$\Sigma I_{OL(avg)}$	“L” total average output current **(Note 1)**	$P1_0$–$P1_7$			60	mA
$\Sigma I_{OL(avg)}$	“L” total average output current **(Note 1)**	$P2_0$–$P2_7$, $P4_0$–$P4_4$			40	mA
$I_{OH(peak)}$	“H” output voltage **(Note 2)**	$P0_0$–$P0_7$, $P1_0$–$P1_7$, $P2_0$, $P2_1$, $P2_4$–$P2_7$, $P3_0$–$P3_4$, $P4_0$–$P4_4$			–10	mA
$I_{OL(peak)}$	“L” output voltage **(Note 2)**	$P0_0$–$P0_7$, $P2_0$–$P2_7$, $P3_0$–$P3_4$, $P4_0$–$P4_4$			10	mA
$I_{OL(peak)}$	“L” output voltage **(Note 2)**	$P1_0$–$P1_7$			20	mA
$I_{OH(avg)}$	“H” average output current **(Note 3)**	$P0_0$–$P0_7$, $P1_0$–$P1_7$, $P2_0$, $P2_1$, $P2_4$–$P2_7$, $P3_0$–$P3_4$, $P4_0$–$P4_4$			–5	mA
$I_{OL(avg)}$	“L” average output current **(Note 3)**	$P0_0$–$P0_7$, $P2_0$–$P2_7$, $P3_0$–$P3_4$, $P4_0$–$P4_4$			5	mA
$I_{OL(avg)}$	“L” average output current **(Note 3)**	$P1_0$–$P1_7$			15	mA
$f(X_{IN})$	Internal clock oscillation frequency (V_{CC} = 4.0 to 5.5V) **(Note 4)**				12.5	MHz
$f(X_{IN})$	Internal clock oscillation frequency (V_{CC} = 2.7 to 4.0V) **(Note 4)**				5V_{CC}–7.5	MHz
$f(X_{CIN})$	Sub-clock input oscillation frequency **(Note 4, 5)**			32.768	50	kHz

Note 1: The total output current is the sum of all the currents flowing through all the applicable ports. The total average current is an average value measured over 100 ms. The total peak current is the peak value of all the currents.

2: The peak output current is the peak current flowing in each port.

3: The average output current I_{OL} (avg), I_{OH} (avg) in an average value measured over 100 ms.

4: When the oscillation frequency has a duty cycle of 50 %.

5: When using the microcomputer in low-speed mode, set the sub-clock input oscillation frequency on condition that $f(X_{CIN}) < f(X_{IN})/3$.

Downloaded from Arrow.com.

Electrical characteristics

Table 9 Electrical characteristics (1)

(V_{CC} = 2.7 to 5.5 V, V_{SS} = 0 V, T_a = –20 to 85 °C, unless otherwise noted)

Symbol	Parameter	Test conditions	Limits			Unit
			Min.	Typ.	Max.	
V_{OH}	"H" output voltage **(Note)** $P0_0$–$P0_7$, $P1_0$–$P1_7$, $P2_0$,$P2_1$ $P2_4$–$P2_7$, $P3_0$–$P3_4$, $P4_0$–$P4_4$	I_{OH} = –10mA V_{CC}=4.0–5.5V	V_{CC} – 2.0			V
		I_{OH} = –1.0mA V_{CC}=2.7–5.5V	V_{CC} – 1.0			V
V_{OL}	"L" output voltage $P0_0$–$P0_7$, $P2_0$–$P2_7$, $P3_0$–$P3_4$ $P4_0$–$P4_4$	I_{OL} = 10mA V_{CC}=4.0–5.5V			2.0	V
		I_{OL} = 1.0mA V_{CC}=2.7–5.5V			1.0	V
V_{OL}	"L" output voltage $P1_0$–$P1_7$	I_{OL} = 20mA V_{CC}=4.0–5.5V			2.0	V
		I_{OL} = 10mA V_{CC}=2.7–5.5V			1.0	V
V_{T+} – V_{T-}	Hysteresis $CNTR_0$, $CNTR_1$, INT_0–INT_3			0.4		V
V_{T+} – V_{T-}	Hysteresis RxD, S_{CLK1}, S_{CLK2}, S_{IN2}			0.5		V
V_{T+} – V_{T-}	Hysteresis $\overline{RESET}$			0.5		V
I_{IH}	"H" input current $P0_0$–$P0_7$, $P1_0$–$P1_7$, $P2_0$, $P2_1$, $P2_4$–$P2_7$, $P3_0$–$P3_4$, $P4_0$–$P4_4$	V_I=V_{CC} Pin floating, Pull-up Transistor "off"			5.0	µA
I_{IH}	"H" input current $\overline{RESET}$, CNV_{SS}	V_I=V_{CC}			5.0	µA
I_{IH}	"H" input current X_{IN}	V_I=V_{CC}		4		µA
I_{IL}	"L" input current $P0_0$–$P0_7$, $P1_0$–$P1_7$, $P2_0$–$P2_7$ $P3_0$–$P3_4$, $P4_0$–$P4_4$	V_I=V_{SS} Pin floating, Pull-up Transistor "off"			–5.0	µA
I_{IL}	"L" input current $\overline{RESET}$,CNV_{SS}	V_I=V_{SS}			–5.0	µA
I_{IL}	"L" input current X_{IN}	V_I=V_{SS}		–4		µA
I_{IL}	"L" input current (at Pull-up) $P0_0$–$P0_7$, $P1_0$–$P1_7$, $P2_0$–$P2_7$, $P3_0$–$P3_4$, $P4_0$–$P4_4$	V_I=V_{SS} V_{CC}=5.0V	–25	–65	–120	µA
		V_I=V_{SS} V_{CC}=3.0V	–8	–22	–40	µA
V_{RAM}	RAM hold voltage	When clock stopped	2.0		5.5	V

Note: $P2_5$ is measured when the $P2_5$/TxD P-channel output disable bit of the UART control register (bit 4 of address $001B_{16}$) is "0".

Downloaded from Arrow.com.

Table 10 Electrical characteristics (2)
(V_{CC} = 2.7 to 5.5 V, V_{SS} = 0 V, T_a = –20 to 85 °C, unless otherwise noted)

Symbol	Parameter	Test conditions	Limits			Unit
			Min.	Typ.	Max.	
I_{CC}	Power source current	High-speed mode $f(X_{IN})$ = 12.5 MHz $f(X_{CIN})$ = 32.768 kHz Output transistors “off”		6.0	12.0	mA
		High-speed mode $f(X_{IN})$ = 8 MHz $f(X_{CIN})$ = 32.768 kHz Output transistors “off”		4.0	8.0	mA
		High-speed mode $f(X_{IN})$ = 12.5 MHz (in WIT state) $f(X_{CIN})$ = 32.768 kHz Output transistors “off”		1.75	4.5	mA
		High-speed mode $f(X_{IN})$ = 8 MHz (in WIT state) $f(X_{CIN})$ = 32.768 kHz Output transistors “off”		1.35	4.2	mA
		Middle-speed mode $f(X_{IN})$ = 12.5 MHz $f(X_{CIN})$ = stopped Output transistors “off”		2.7	6.0	mA
		Middle-speed mode $f(X_{IN})$ = 8 MHz $f(X_{CIN})$ = stopped Output transistors “off”		2.0	4.5	mA
		Middle-speed mode $f(X_{IN})$ = 12.5 MHz (in WIT state) $f(X_{CIN})$ = stopped Output transistors “off”		1.65	4.2	mA
		Middle-speed mode $f(X_{IN})$ = 8 MHz (in WIT state) $f(X_{CIN})$ = stopped Output transistors “off”		1.3	4.0	mA
		Low-speed mode $f(X_{IN})$ = stopped $f(X_{CIN})$ = 32.768 kHz Output transistors “off”		40	150	µA
		Low-speed mode $f(X_{IN})$ = stopped $f(X_{CIN})$ = 32.768 kHz (in WIT state) Output transistors “off”		30	100	µA
		Low-speed mode (V_{CC}=3V) $f(X_{IN})$ = stopped $f(X_{CIN})$ = 32.768 kHz Output transistors “off”		10	40	µA
		Low-speed mode (V_{CC}=3V) $f(X_{IN})$ = stopped $f(X_{CIN})$ = 32.768 kHz (in WIT state) Output transistors “off”		5.5	11	µA
		Increment when A/D conversion is executed $f(X_{IN})$ = 8 MHz		600		µA
		All oscillation stopped (in STP state) Output transistors “off” — Ta=25°C		0.1	1.0	µA
		Output transistors “off” — Ta=85°C			10	µA

Downloaded from Arrow.com.

A/D converter characteristics

Table 11 A/D converter characteristics

(V_{CC} = 2.7 to 5.5 V, V_{SS} = 0 V, T_a = –20 to 85 °C, unless otherwise noted)

Symbol	Parameter	Test conditions	Limits			Unit
			Min.	Typ.	Max.	
–	Resolution				8	bit
ABS	Absolute accuracy	V_{CC}=V_{REF}			±3	LSB
t_{CONV}	Conversion time				109	tc(X_{IN})
R_{LADDER}	Ladder resistor			37		kΩ
I_{VREF}	Reference power source input current	V_{REF}=5.0V	50	135	200	µA
		V_{REF}=3.0V	30	80	120	
$I_{I(AD)}$	A/D port input current				5.0	µA

Note : As for AD translation accuracy, on the following operating conditions, accuracy may become low.

(1) Since the analog circuit inside a microcomputer becomes sensitive to noise when V_{REF} voltage is set up lower than Vcc voltage, accuracy may become low rather than the case where V_{REF} voltage and Vcc voltage are set up to the same value.

(2) When V_{REF} voltage is less than [3.0V], the accuracy at the time of low temperature may become extremely low compared with the time of room temperature. The use beyond V_{REF}=3.0V is recommended in the system the use by the side of low temperature is assumed to be.

Downloaded from Arrow.com.

Timing requirements

Table 12 Timing requirements (1)

(Vcc = 4.0 to 5.5 V, Vss = 0 V, Ta = –20 to 85 °C, unless otherwise noted)

Symbol	Parameter	Limits			Unit
		Min.	Typ.	Max.	
tw($\overline{\text{RESET}}$)	Reset input “L” pulse width	20			XIN cycle
tc(XIN)	External clock input cycle time	80			ns
twH(XIN)	External clock input “H” pulse width	32			ns
twL(XIN)	External clock input “L” pulse width	32			ns
tc(CNTR)	CNTR0, CNTR1 input cycle time	200			ns
twH(CNTR)	CNTR0, CNTR1 input “H” pulse width	80			ns
twL(CNTR)	CNTR0, CNTR1 input “L” pulse width	80			ns
twH(INT)	INT0 to INT3 input “H” pulse width	80			ns
twL(INT)	INT0 to INT3 input “L” pulse width	80			ns
tc(SCLK1)	Serial I/O1 clock input cycle time **(Note)**	800			ns
twH(SCLK1)	Serial I/O1 clock input “H” pulse width **(Note)**	370			ns
twL(SCLK1)	Serial I/O1 clock input “L” pulse width **(Note)**	370			ns
tsu(RxD-SCLK1)	Serial I/O1 input setup time	220			ns
th(SCLK1-RxD)	Serial I/O1 input hold time	100			ns
tc(SCLK2)	Serial I/O2 clock input cycle time	1000			ns
twH(SCLK2)	Serial I/O2 clock input “H” pulse width	400			ns
twL(SCLK2)	Serial I/O2 clock input “L” pulse width	400			ns
tsu(SIN2-SCLK2)	Serial I/O2 clock input setup time	200			ns
th(SCLK2-SIN2)	Serial I/O2 clock input hold time	200			ns

Note : When f(XIN) = 8 MHz and bit 6 of address 001A16 is “1” (clock synchronous).
Divide this value by four when f(XIN) = 8 MHz and bit 6 of address 001A16 is “0” (UART).

Table13 Timing requirements (2)

(Vcc = 2.7 to 5.5 V, Vss = 0 V, Ta = –20 to 85 °C, unless otherwise noted)

Symbol	Parameter	Limits			Unit
		Min.	Typ.	Max.	
tw($\overline{\text{RESET}}$)	Reset input “L” pulse width	20			XIN cycle
tc(XIN)	External clock input cycle time	166			ns
twH(XIN)	External clock input “H” pulse width	66			ns
twL(XIN)	External clock input “L” pulse width	66			ns
tc(CNTR)	CNTR0, CNTR1 input cycle time	500			ns
twH(CNTR)	CNTR0, CNTR1 input “H” pulse width	230			ns
twL(CNTR)	CNTR0, CNTR1 input “L” pulse width	230			ns
twH(INT)	INT0 to INT3 input “H” pulse width	230			ns
twL(INT)	INT0 to INT3 input “L” pulse width	230			ns
tc(SCLK1)	Serial I/O1 clock input cycle time **(Note)**	2000			ns
twH(SCLK1)	Serial I/O1 clock input “H” pulse width **(Note)**	950			ns
twL(SCLK1)	Serial I/O1 clock input “L” pulse width **(Note)**	950			ns
tsu(RxD-SCLK1)	Serial I/O1 input setup time	400			ns
th(SCLK1-RxD)	Serial I/O1 input hold time	200			ns
tc(SCLK2)	Serial I/O2 clock input cycle time	2000			ns
twH(SCLK2)	Serial I/O2 clock input “H” pulse width	950			ns
twL(SCLK2)	Serial I/O2 clock input “L” pulse width	950			ns
tsu(SIN2-SCLK2)	Serial I/O2 clock input setup time	400			ns
th(SCLK2-SIN2)	Serial I/O2 clock input hold time	300			ns

Note : When f(XIN) = 4 MHz and bit 6 of address 001A16 is “1” (clock synchronous).
Divide this value by four when f(XIN) = 4 MHz and bit 6 of address 001A16 is “0” (UART).

Downloaded from Arrow.com.

Switching characteristics

Table 14 Switching characteristics (1)

(Vcc = 4.0 to 5.5 V, Vss = 0 V, Ta = –20 to 85 °C, unless otherwise noted)

Symbol	Parameter	Test conditions	Limits			Unit
			Min.	Typ.	Max.	
tWH (SCLK1)	Serial I/O1 clock output “H” pulse width	Fig. 61	tc(SCLK1)/2–30			ns
tWL (SCLK1)	Serial I/O1 clock output “L” pulse width		tc(SCLK1)/2–30			ns
td (SCLK1-TXD)	Serial I/O1 output delay time **(Note 1)**				140	ns
tv (SCLK1-TXD)	Serial I/O1 output valid time **(Note 1)**		–30			ns
tr (SCLK1)	Serial I/O1 clock output rising time				30	ns
tf (SCLK1)	Serial I/O1 clock output falling time				30	ns
tWH (SCLK2)	Serial I/O2 clock output “H” pulse width		tc(SCLK2)/2–160			ns
tWL (SCLK2)	Serial I/O2 clock output “L” pulse width		tc(SCLK2)/2–160			ns
td (SCLK2-SOUT2)	Serial I/O2 output delay time **(Note 2)**				200	ns
tv (SCLK2-SOUT2)	Serial I/O2 output valid time **(Note 2)**		0			ns
tf (SCLK2)	Serial I/O2 clock output falling time				30	ns
tr (CMOS)	CMOS output rising time **(Note 3)**			10	30	ns
tf (CMOS)	CMOS output falling time **(Note 3)**			10	30	ns

Notes 1: When the P25/TXD P-channel output disable bit of the UART control register (bit 4 of address 001B16) is “0”.
2: When the P01/SOUT2 and P02/SCLK2 P-channel output disable bit of the Serial I/O2 control register 1 (bit 7 of address 001516) is “0”.
3: The XOUT pin is excluded.

Table 15 Switching characteristics (2)

(Vcc = 2.7 to 5.5 V, Vss = 0 V, Ta = –20 to 85 °C, unless otherwise noted)

Symbol	Parameter	Test conditions	Limits			Unit
			Min.	Typ.	Max.	
tWH (SCLK1)	Serial I/O1 clock output “H” pulse width	Fig. 61	tc(SCLK1)/2–50			ns
tWL (SCLK1)	Serial I/O1 clock output “L” pulse width		tc(SCLK1)/2–50			ns
td (SCLK1-TXD)	Serial I/O1 output delay time **(Note 1)**				350	ns
tv (SCLK1-TXD)	Serial I/O1 output valid time **(Note 1)**		–30			ns
tr (SCLK1)	Serial I/O1 clock output rising time				50	ns
tf (SCLK1)	Serial I/O1 clock output falling time				50	ns
tWH (SCLK2)	Serial I/O2 clock output “H” pulse width		tc(SCLK2)/2–240			ns
tWL (SCLK2)	Serial I/O2 clock output “L” pulse width		tc(SCLK2)/2–240			ns
td (SCLK2-SOUT2)	Serial I/O2 output delay time **(Note 2)**				400	ns
tv (SCLK2-SOUT2)	Serial I/O2 output valid time **(Note 2)**		0			ns
tf (SCLK2)	Serial I/O2 clock output falling time				50	ns
tr (CMOS)	CMOS output rising time **(Note 3)**			20	50	ns
tf (CMOS)	CMOS output falling time **(Note 3)**			20	50	ns

Notes 1: When the P25/TXD P-channel output disable bit of the UART control register (bit 4 of address 001B16) is “0”.
2: When the P01/SOUT2 and P02/SCLK2 P-channel output disable bit of the Serial I/O2 control register 1 (bit 7 of address 001516) is “0”.
3: The XOUT pin is excluded.

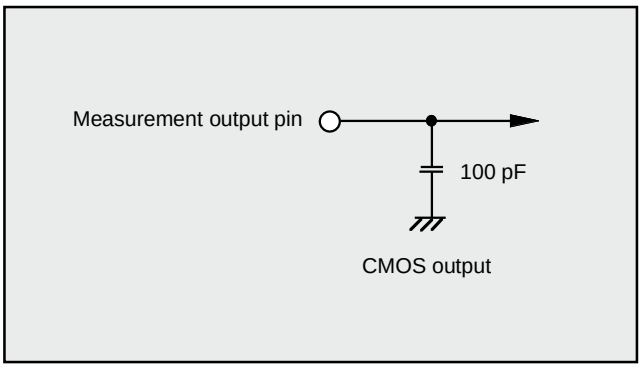


Fig. 61 Circuit for measuring output switching characteristics

Downloaded from Arrow.com.

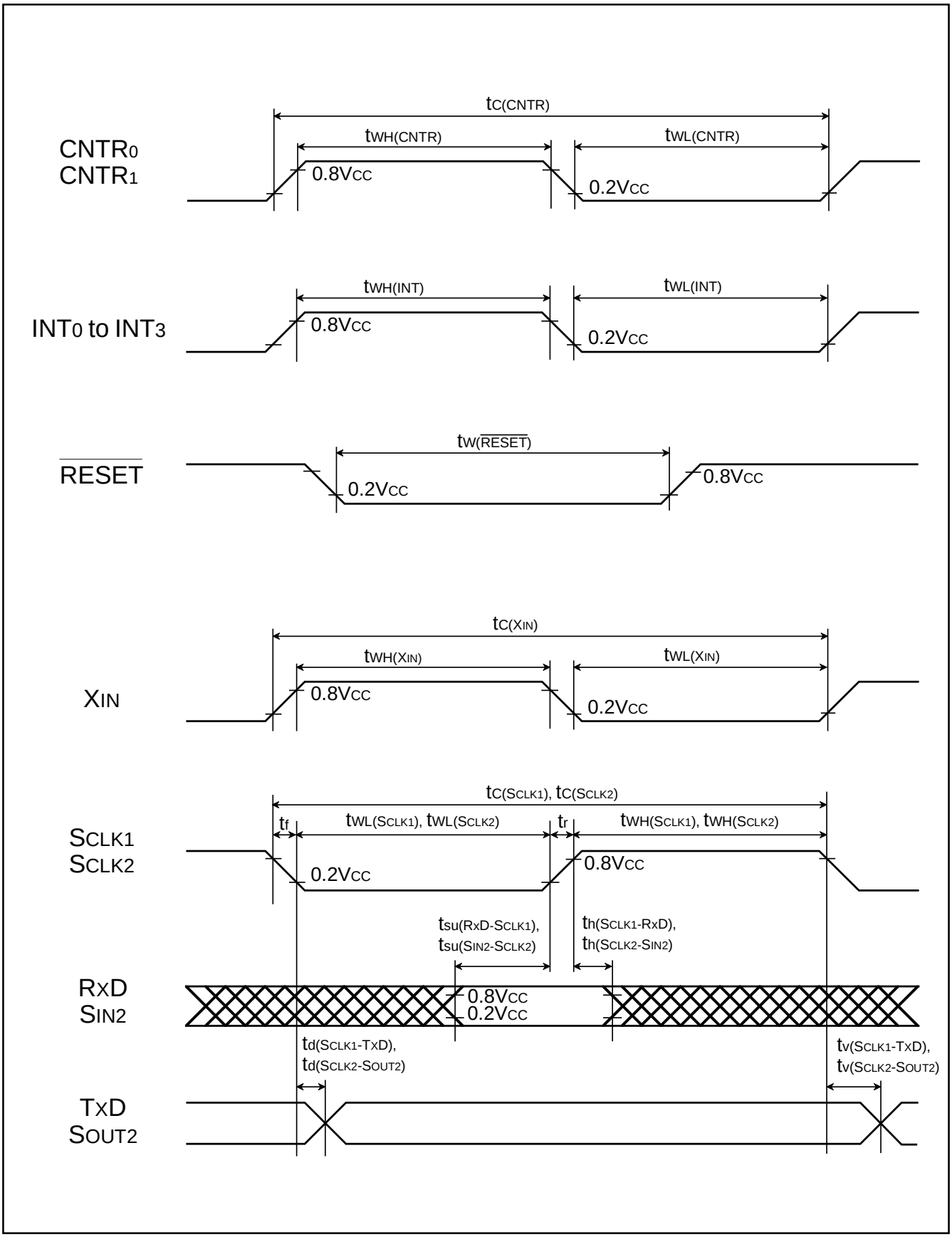


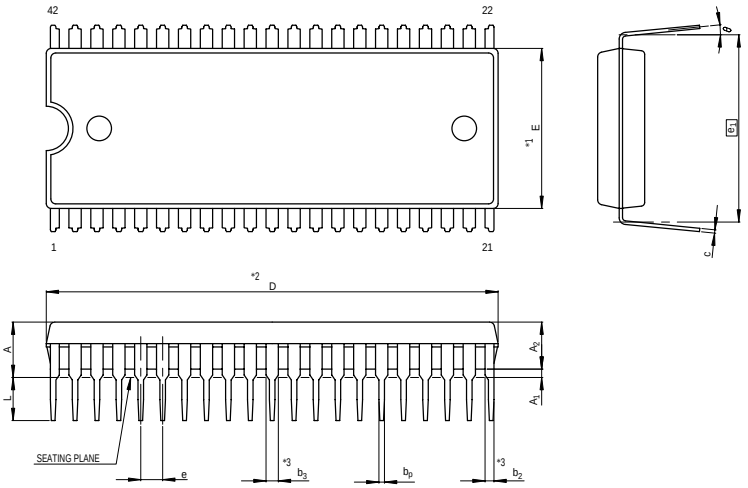
Fig. 62 Timing diagram

Downloaded from Arrow.com.

PACKAGE OUTLINE

Diagrams showing the latest package dimensions and mounting information are available in the “Packages” section of the Renesas Technology website.

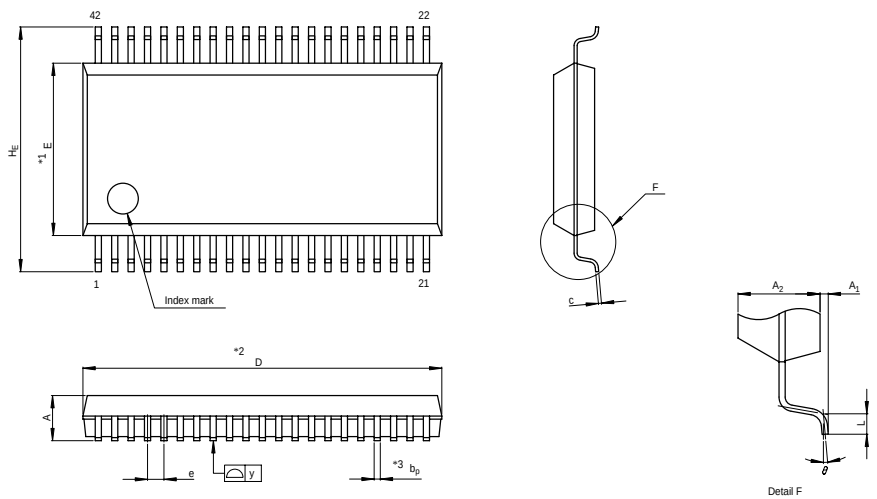
JEITA Package Code	RENESAS Code	Previous Code	MASS[Typ.]
P-SDIP42-13x36.72-1.78	PRDP0042BA-A	42P4B	4.1g



NOTE)
1. DIMENSIONS "*1" AND "*2" DO NOT INCLUDE MOLD FLASH.
2. DIMENSION "*3" DOES NOT INCLUDE TRIM OFFSET.

Reference Symbol	Dimension in Millimeters		
	Min	Nom	Max
e_1	14.94	15.24	15.54
D	36.5	36.7	36.9
E	12.85	13.0	13.15
A	—	—	5.5
A_1	0.51	—	—
A_2	—	3.8	—
b_p	0.35	0.45	0.55
b_2	0.63	0.73	1.03
b_3	0.9	1.0	1.3
c	0.22	0.27	0.34
θ	0°	—	15°
e	1.528	1.778	2.028
L	3.0	—	—

JEITA Package Code	RENESAS Code	Previous Code	MASS[Typ.]
P-SSOP42-8.4x17.5-0.80	PRSP0042GA-B	42P2R-E	0.6g



NOTE)
1. DIMENSIONS "*1" AND "*2" DO NOT INCLUDE MOLD FLASH.
2. DIMENSION "*3" DOES NOT INCLUDE TRIM OFFSET.

Reference Symbol	Dimension in Millimeters		
	Min	Nom	Max
D	17.3	17.5	17.7
E	8.2	8.4	8.6
A_2	—	2.0	—
A	—	—	2.4
A_1	0.05	—	—
b_p	0.25	0.3	0.4
c	0.13	0.15	0.2
θ	0°	—	10°
H_E	11.63	11.93	12.23
e	0.65	0.8	0.95
y	—	—	0.15
L	0.3	0.5	0.7

Downloaded from Arrow.com.

NOTES

NOTES ON PROGRAMMING

1. Processor Status Register

(1) Initializing of processor status register

Flags which affect program execution must be initialized after a reset. In particular, it is essential to initialize the T and D flags because they have an important effect on calculations.

<Reason>

After a reset, the contents of the processor status register (PS) are undefined except for the I flag which is “1”.

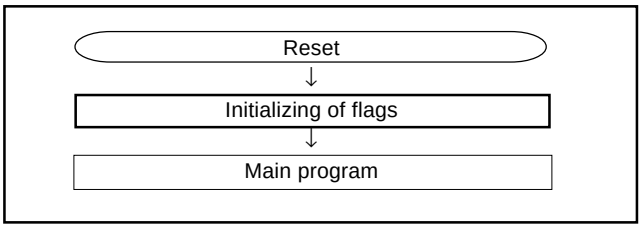


Fig 63. Initialization of processor status register

(2) How to reference the processor status register

To reference the contents of the processor status register (PS), execute the PHP instruction once then read the contents of (S+1). If necessary, execute the PLP instruction to return the PS to its original status.

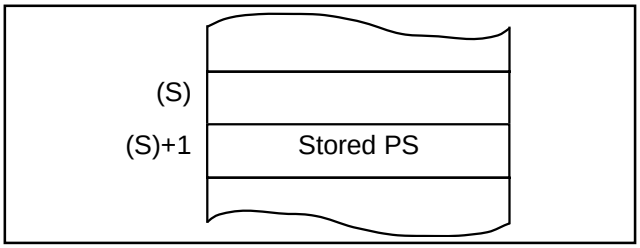


Fig 64. Stack memory contents after PHP instruction execution

2. BRK instruction

(1) Interrupt priority level

When the BRK instruction is executed with the following conditions satisfied, the interrupt execution is started from the address of interrupt vector which has the highest priority.

- Interrupt request bit and interrupt enable bit are set to “1”.
- Interrupt disable flag (I) is set to “1” to disable interrupt.

3. Decimal calculations

(1) Execution of decimal calculations

The ADC and SBC are the only instructions which will yield proper decimal notation, set the decimal mode flag (D) to “1” with the SED instruction. After executing the ADC or SBC instruction, execute another instruction before executing the SEC, CLC, or CLD instruction.

(2) Notes on status flag in decimal mode

When decimal mode is selected, the values of three of the flags in the status register (the N, V, and Z flags) are invalid after a ADC or SBC instruction is executed.

The carry flag (C) is set to “1” if a carry is generated as a result of the calculation, or is cleared to “0” if a borrow is generated. To determine whether a calculation has generated a carry, the C flag must be initialized to “0” before each calculation. To check for a borrow, the C flag must be initialized to “1” before each calculation.

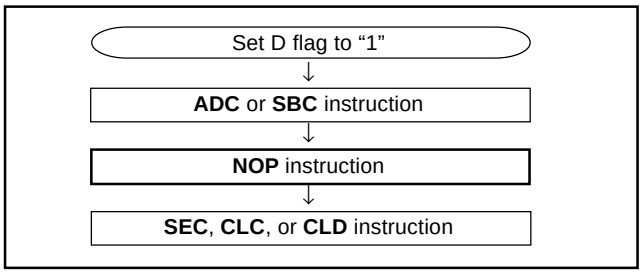


Fig 65. Execution of decimal calculations

4. JMP instruction

When using the JMP instruction in indirect addressing mode, do not specify the last address on a page as an indirect address.

5. Multiplication and Division Instructions

- The index X mode (T) and the decimal mode (D) flags do not affect the MUL and DIV instruction.
- The execution of these instructions does not change the contents of the processor status register.

6. Ports

The contents of the port direction registers cannot be read. The following cannot be used:

- The data transfer instruction (LDA, etc.)
- The operation instruction when the index X mode flag (T) is “1”
- The addressing mode which uses the value of a direction register as an index
- The bit-test instruction (BBC or BBS, etc.) to a direction register
- The read-modify-write instructions (ROR, CLB, or SEB, etc.) to a direction register.

Use instructions such as LDM and STA, etc., to set the port direction registers.

7. Instruction Execution Time

The instruction execution time can be obtained by multiplying the frequency of the internal clock ϕ by the number of cycles mentioned in the 740 Family Software Manual.

The frequency of the internal clock ϕ is the twice the XIN cycle in high-speed mode, 8 times the XIN cycle in middle-speed mode, and the twice the XCIN in low-speed mode.

8. Reserved Area, Reserved Bit

Do not write any data to the reserved area in the SFR area and the special page. (Do not change the contents after reset.)

9. CPU Mode Register

Be sure to fix bit 3 of the CPU mode register (address $003B_{16}$) to “1”.

Downloaded from Arrow.com.

NOTES ON PERIPHERAL FUNCTIONS

Notes on Input and Output Ports

1. Notes in standby state

In standby state[*1] , do not make input levels of an I/O port "undefined", especially for I/O ports of the N-channel open-drain. When setting the N-channel open-drain port as an output, do not make input levels of an I/O port "undefined", too.

Pull-up (connect the port to VCC) or pull-down (connect the port to VSS) these ports through a resistor.

When determining a resistance value, note the following points:

- External circuit
- Variation of output levels during the ordinary operation

<Reason>

When setting as an input port with its direction register, the transistor becomes the OFF state, which causes the ports to be the high-impedance state.

Accordingly, the potential which is input to the input buffer in a microcomputer is unstable in the state that input levels of an I/O port are "undefined". This may cause power source current.

In I/O ports of N-channel open-drain, when the contents of the port latch are "1", even if it is set as an output port with its direction register, it becomes the same phenomenon as the case of an input port.

[*1] Standby state : stop mode by executing STP instruction
wait mode by executing WIT instruction

2. Modifying output data with bit managing instruction

When the port latch of an I/O port is modified with the bit managing instruction[*2] , the value of the unspecified bit may be changed.

<Reason>

The bit managing instructions are read-modify-write form instructions for reading and writing data by a byte unit.

Accordingly, when these instructions are executed on a bit of the port latch of an I/O port, the following is executed to all bits of the port latch.

- As for bit which is set for input port:
  The pin state is read in the CPU, and is written to this bit after bit managing.
- As for bit which is set for output port:
  The bit value is read in the CPU, and is written to this bit after bit managing.

Note the following:

- Even when a port which is set as an output port is changed for an input port, its port latch holds the output data.
- As for a bit of which is set for an input port, its value may be changed even when not specified with a bit managing instruction in case where the pin state differs from its port latch contents.

[*2] Bit managing instructions : SEB and CLB instructions

Termination of Unused Pins

1. Terminate unused pins

(1) I/O ports :

- Set the I/O ports for the input mode and connect them to VCC or VSS through each resistor of 1 kΩ to 10 kΩ. In the port which can select a internal pull-up resistor, the internal pull-up resistor can be used.
  Set the I/O ports for the output mode and open them at "L" or "H".
- When opening them in the output mode, the input mode of the initial status remains until the mode of the ports is switched over to the output mode by the program after reset. Thus, the potential at these pins is undefined and the power source current may increase in the input mode. With regard to an effects on the system, thoroughly perform system evaluation on the user side.
- Since the direction register setup may be changed because of a program runaway or noise, set direction registers by program periodically to increase the reliability of program.

(2) The AVSS pin when not using the A/D converter :

- When not using the A/D converter, handle a power source pin for the A/D converter, AVSS pin as follows:
  AVSS: Connect to the VSS pin.

2. Termination remarks

(1) Input ports and I/O ports :

Do not open in the input mode.

<Reason>

- The power source current may increase depending on the firststage circuit.
- An effect due to noise may be easily produced as compared with proper termination (1) in 1 shown on the above.

(2) I/O ports :

When setting for the input mode, do not connect to VCC or VSS directly.

<Reason>

If the direction register setup changes for the output mode because of a program runaway or noise, a short circuit may occur between a port and VCC (or VSS).

(3) I/O ports :

When setting for the input mode, do not connect multiple ports in a lump to VCC or VSS through a resistor.

<Reason>

If the direction register setup changes for the output mode because of a program runaway or noise, a short circuit may occur between ports.

- At the termination of unused pins, perform wiring at the shortest possible distance (20 mm or less) from microcomputer pins.

Downloaded from Arrow.com.

Notes on Interrupts

1. Change of relevant register settings

When the setting of the following registers or bits is changed, the interrupt request bit may be set to “1”. When not requiring the interrupt occurrence synchronized with these setting, take the following sequence.

- Interrupt edge selection register (address 003A16)
- Timer XY mode register (address 002316)

Set the above listed registers or bits as the following sequence.

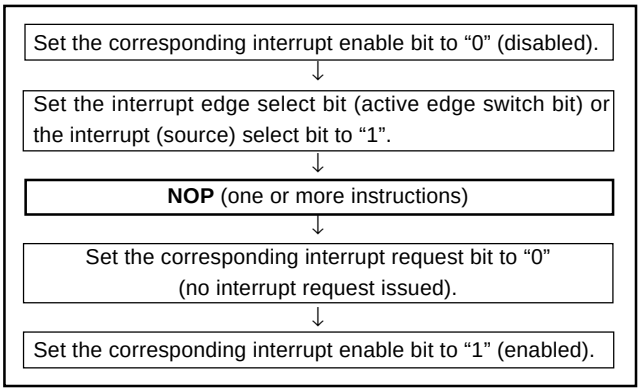


Fig 66. Sequence of changing relevant register

<Reason>
When setting the followings, the interrupt request bit may be set to “1”.

- When setting external interrupt active edge
  Concerned register: Interrupt edge selection register (address 003A16)
  Timer XY mode register (address 002316)
- When switching interrupt sources of an interrupt vector address where two or more interrupt sources are allocated.
  Concerned register: Interrupt edge selection register (address 003A16)

2. Check of interrupt request bit

When executing the BBC or BBS instruction to an interrupt request bit of an interrupt request register immediately after this bit is set to “0” by using a data transfer instruction, execute one or more instructions before executing the BBC or BBS instruction.

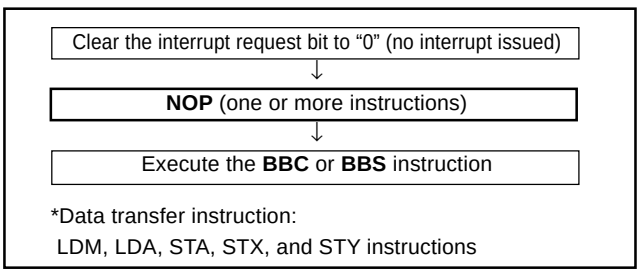


Fig 67. Sequence of check of interrupt request bit

<Reason>
If the BBC or BBS instruction is executed immediately after an interrupt request bit of an interrupt request register is cleared to “0”, the value of the interrupt request bit before being cleared to “0” is read.

Notes on Timer

- If a value n (between 0 and 255) is written to a timer latch, the frequency division ratio is 1/(n+1).
- When switching the count source by the timer 12, X and Y count source selection bits, the value of timer count is altered in unconsiderable amount owing to generating of thin pulses in the count input signals.
  Therefore, select the timer count source before set the value to the prescaler and the timer.

Notes on Serial Interface

1. Notes when selecting clock synchronous serial I/O (Serial I/O1)

(1) Stop of transmission operation
Clear the serial I/O1 enable bit and the transmit enable bit to “0” (Serial I/O1 and transmit disabled).
<Reason>
Since transmission is not stopped and the transmission circuit is not initialized even if only the serial I/O1 enable bit is cleared to “0” (Serial I/O1 disabled), the internal transmission is running (in this case, since pins TxD, RxD, SCLK1, and $\overline{\text{SRDY1}}$ function as I/O ports, the transmission data is not output). When data is written to the transmit buffer register in this state, data starts to be shifted to the transmit shift register. When the serial I/O1 enable bit is set to “1” at this time, the data during internally shifting is output to the TxD pin and an operation failure occurs.

(2) Stop of receive operation
Clear the receive enable bit to “0” (receive disabled), or clear the serial I/O1 enable bit to “0” (Serial I/O1 disabled).

(3) Stop of transmit/receive operation
Clear the transmit enable bit and receive enable bit to “0” simultaneously (transmit and receive disabled).
(when data is transmitted and received in the clock synchronous serial I/O mode, any one of data transmission and reception cannot be stopped.)
<Reason>
In the clock synchronous serial I/O mode, the same clock is used for transmission and reception. If any one of transmission and reception is disabled, a bit error occurs because transmission and reception cannot be synchronized.
In this mode, the clock circuit of the transmission circuit also operates for data reception. Accordingly, the transmission circuit does not stop by clearing only the transmit enable bit to “0” (transmit disabled). Also, the transmission circuit is not initialized by clearing the serial I/O1 enable bit to “0” (Serial I/O1 disabled) (refer to (1) in 1).

(4) $\overline{\text{SRDY1}}$ output of reception side (Serial I/O1)
When signals are output from the $\overline{\text{SRDY1}}$ pin on the reception side by using an external clock in the clock synchronous serial I/O mode, set all of the receive enable bit, the $\overline{\text{SRDY1}}$ output enable bit, and the transmit enable bit to “1” (transmit enabled).

Downloaded from Arrow.com.

2. Notes when selecting clock asynchronous serial I/O (Serial I/O1)

(1) Stop of transmission operation

Clear the transmit enable bit to “0” (transmit disabled).

<Reason>

Since transmission is not stopped and the transmission circuit is not initialized even if only the serial I/O1 enable bit is cleared to “0” (Serial I/O1 disabled), the internal transmission is running (in this case, since pins TxD, RxD, SCLK1, and $\overline{\text{SRDY1}}$ function as I/O ports, the transmission data is not output). When data is written to the transmit buffer register in this state, data starts to be shifted to the transmit shift register. When the serial I/O1 enable bit is set to “1” at this time, the data during internally shifting is output to the TxD pin and an operation failure occurs.

(2) Stop of receive operation

Clear the receive enable bit to “0” (receive disabled).

(3) Stop of transmit/receive operation

Only transmission operation is stopped.

Clear the transmit enable bit to “0” (transmit disabled).

<Reason>

Since transmission is not stopped and the transmission circuit is not initialized even if only the serial I/O1 enable bit is cleared to “0” (Serial I/O1 disabled), the internal transmission is running (in this case, since pins TxD, RxD, SCLK1, and $\overline{\text{SRDY1}}$ function as I/O ports, the transmission data is not output). When data is written to the transmit buffer register in this state, data starts to be shifted to the transmit shift register. When the serial I/O1 enable bit is set to “1” at this time, the data during internally shifting is output to the TxD pin and an operation failure occurs.

Only receive operation is stopped.

Clear the receive enable bit to “0” (receive disabled).

3. Setting serial I/O1 control register again (Serial I/O1)

Set the serial I/O1 control register again after the transmission and the reception circuits are reset by clearing both the transmit enable bit and the receive enable bit to “0”.

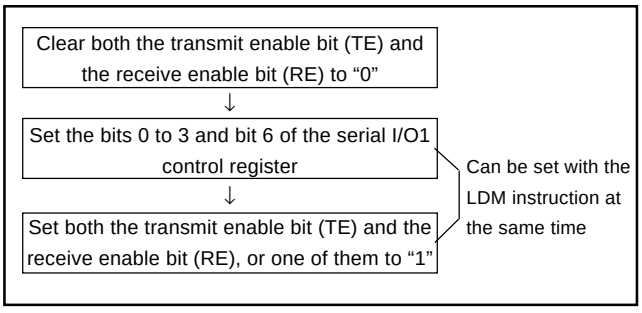


Fig 68. Sequence of setting serial I/O1 control register again

4. Data transmission control with referring to transmit shift register completion flag (Serial I/O1)

The transmit shift register completion flag changes from “1” to “0” with a delay of 0.5 to 1.5 shift clocks. When data transmission is controlled with referring to the flag after writing the data to the transmit buffer register, note the delay.

5. Transmit interrupt request when transmit enable bit is set (SeriaII/O1)

When the transmit interrupt is used, set the transmit interrupt enable bit to transmit enabled as shown in the following sequence.

(1) Set the interrupt enable bit to “0” (disabled) with CLB instruction.

(2) Prepare serial I/O for transmission/reception.

(3) Set the interrupt request bit to “0” with CLB instruction after 1 or more instruction has been executed.

(4) Set the interrupt enable bit to “1” (enabled).

<Reason>

When the transmission enable bit is set to “1”, the transmit buffer empty flag and transmit shift register completion flag are set to “1”. The interrupt request is generated and the transmission interrupt request bit is set regardless of which of the two timings listed below is selected as the timing for the transmission interrupt to be generated.

- Transmit buffer empty flag is set to “1”
- Transmit shift register completion flag is set to “1”

6. Transmission control when external clock is selected (Serial I/O1 clock synchronous mode)

When an external clock is used as the synchronous clock for data transmission, set the transmit enable bit to “1” at “H” of the SCLK1 input level. Also, write the transmit data to the transmit buffer register (serial I/O shift register) at “H” of the SCLK1 input level.

7. Transmit data writing (Serial I/O2)

In the clock synchronous serial I/O, when selecting an external clock as synchronous clock, write the transmit data to the serial I/O2 register (serial I/O shift register) at “H” of the transfer clock input level.

Notes on PWM

The PWM starts after the PWM enable bit is set to enable and “L” level is output from the PWM pin.

The length of this “L” level output is as follows:

$\frac{n+1}{2 \times f(X_{IN})}$ (s) (Count source selection bit = “0”, where n is the value set in the prescaler)

$\frac{n+1}{f(X_{IN})}$ (s) (Count source selection bit = “1”, where n is the value set in the prescaler)

Downloaded from Arrow.com.

Notes on A/D Converter

1. Analog input pin

Make the signal source impedance for analog input low, or equip an analog input pin with an external capacitor of 0.01 μF to 1 μF. Further, be sure to verify the operation of application products on the user side.

<Reason>

An analog input pin includes the capacitor for analog voltage comparison. Accordingly, when signals from signal source with high impedance are input to an analog input pin, charge and discharge noise generates. This may cause the A/D conversion precision to be worse.

2. A/D converter power source pin

The AVSS pin is A/D converter power source pin. Regardless of using the A/D conversion function or not, connect it as following :

•AVSS : Connect to the VSS line

<Reason>

If the AVSS pin is opened, the microcomputer may have a failure because of noise or others.

3. Clock frequency during A/D conversion

The comparator consists of a capacity coupling, and a charge of the capacity will be lost if the clock frequency is too low. Thus, make sure the following during an A/D conversion.

- f(XIN) is 500 kHz or more in middle-/high-speed mode.
- Do not execute the STP instruction.
- When the A/D converter is operated at low-speed mode, f(XIN) do not have the lower limit of frequency, because of the A/D converter has a built-in self-oscillation circuit.

Notes on Watchdog Timer

- Make sure that the watchdog timer does not underflow while waiting Stop release, because the watchdog timer keeps counting during that term.
- When the STP instruction function selection bit has been set to "1", it is impossible to switch it to "0" by a program.

Notes on $\overline{\text{RESET}}$ Pin

1. Connecting capacitor

In case where the $\overline{\text{RESET}}$ signal rise time is long, connect a ceramic capacitor or others across the $\overline{\text{RESET}}$ pin and the VSS pin. Use a 1000 pF or more capacitor for high frequency use. When connecting the capacitor, note the following :

- Make the length of the wiring which is connected to a capacitor as short as possible.
- Be sure to verify the operation of application products on the user side.

<Reason>

If the several nanosecond or several ten nanosecond impulse noise enters the $\overline{\text{RESET}}$ pin, it may cause a microcomputer failure.

2. Reset release after power on

When releasing the reset after power on, such as power-on reset, release reset after XIN passes more than 20 cycles in the state where the power supply voltage is 2.7 V or more and the XIN oscillation is stable.

<Reason>

To release reset, the $\overline{\text{RESET}}$ pin must be held at an "L" level for 20 cycles or more of XIN in the state where the power source voltage is between 2.7 V and 5.5 V, and XIN oscillation is stable.

Notes on Using Stop Mode

1. Register setting

Since values of the prescaler 12 and Timer 1 are automatically reloaded when returning from the stop mode, set them again, respectively. (When the oscillation stabilizing time set after STP instruction released bit is "0")

When using the oscillation stabilizing time set after STP instruction released bit set to "1", evaluate time to stabilize oscillation of the used oscillator and set the value to the timer 1 and prescaler 12.

2. Clock restoration

After restoration from the stop mode to the normal mode by an interrupt request, the contents of the CPU mode register previous to the STP instruction execution are retained. Accordingly, if both main clock and sub clock were oscillating before execution of the STP instruction, the oscillation of both clocks is resumed at restoration.

In the above case, when the main clock side is set as a system clock, the oscillation stabilizing time for approximately 8,000 cycles of the XIN input is reserved at restoration from the stop mode. At this time, note that the oscillation on the sub clock side may not be stabilized even after the lapse of the oscillation stabilizing time of the main clock side.

Notes on Wait Mode

• Clock restoration

If the wait mode is released by a reset when XCIN is set as the system clock and XIN oscillation is stopped during execution of the WIT instruction, XCIN oscillation stops, XIN oscillations starts, and XIN is set as the system clock.

In the above case, the RESET pin should be held at "L" until the oscillation is stabilized.

Notes on Restarting Oscillation

• Restarting oscillation

Usually, when the MCU stops the clock oscillation by STP instruction and the STP instruction has been released by an external interrupt source, the fixed values of Timer 1 and Prescaler 12 (Timer 1 = "01_{16}", Prescaler 12 = "FF_{16}") are automatically reloaded in order for the oscillation to stabilize.

The user can inhibit the automatic setting by writing "1" to bit 0 of MISRG (address 0038_{16}).

However, by setting this bit to "1", the previous values, set just before the STP instruction was executed, will remain in Timer 1 and Prescaler 12. Therefore, you will need to set an appropriate value to each register, in accordance with the oscillation stabilizing time, before executing the STP instruction.

<Reason>

Oscillation will restart when an external interrupt is received.

However, internal clock ϕ is supplied to the CPU only when Timer 1 starts to underflow. This ensures time for the clock oscillation using the ceramic resonators to be stabilized.

Downloaded from Arrow.com.

Handling of Source Pins

In order to avoid a latch-up occurrence, connect a capacitor suitable for high frequencies as bypass capacitor between power source pin (V_{CC} pin) and GND pin (V_{SS} pin) and between power source pin (V_{CC} pin) and analog power source input pin (AV_{SS} pin). Besides, connect the capacitor to as close as possible. For bypass capacitor which should not be located too far from the pins to be connected, a ceramic capacitor of 0.01 µF–0.1 µF is recommended.

Power Source Voltage

When the power source voltage value of a microcomputer is less than the value which is indicated as the recommended operating conditions, the microcomputer does not operate normally and may perform unstable operation.

In a system where the power source voltage drops slowly when the power source voltage drops or the power supply is turned off, reset a microcomputer when the power source voltage is less than the recommended operating conditions and design a system not to cause errors to the system by this unstable operation.

Product Shipped in Blank

As for the product shipped in blank, Renesas does not perform the writing test to user ROM area after the assembly process though the QzROM writing test is performed enough before the assembly process. Therefore, a writing error of approx.0.1 % may occur. Moreover, please note the contact of cables and foreign bodies on a socket, etc. because a writing environment may cause some writing errors.

QzROM Version

Connect the CNV_{SS}/V_{PP} pin the shortest possible to the GND pattern which is supplied to the V_{SS} pin of the microcomputer.

In addition connecting an approximately 5 kΩ resistor in series to the GND could improve noise immunity. In this case as well as the above mention, connect the pin the shortest possible to the GND pattern which is supplied to the V_{SS} pin of the microcomputer.

<Reason>

The CNV_{SS}/V_{PP} pin is the power source input pin for the built-in QzROM. When programming in the QzROM, the impedance of the V_{PP} pin is low to allow the electric current for writing to flow into the built-in QzROM. Because of this, noise can enter easily. If noise enters the V_{PP} pin, abnormal instruction codes or data are read from the QzROM, which may cause a program runaway.

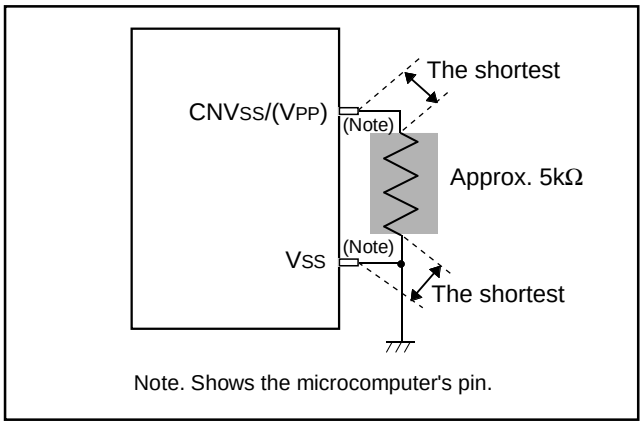


Fig 68. Wiring for the CNV_{SS}/V_{PP}

Notes On QzROM Writing Orders

When ordering the QzROM product shipped after writing, submit the mask file (extension: .msk) which is made by the mask file converter MM.

- Be sure to set the ROM option data* setup when making the mask file by using the mask file converter MM.. The ROM code protect is specified according to the ROM option data* in the mask file which is submitted at ordering. Note that the mask file which has nothing at the ROM option data* or has the data other than "00_{16}" and "FF_{16}" can not be accepted.
- Set "FF_{16}" to the ROM code protect address in ROM data regardless of the presence or absence of a protect. When data other than "FF_{16}" is set, we may ask that the ROM data be submitted again.

* ROM option data: mask option noted in MM

DATA REQUIRED FOR QzROM WRITING ORDERS

The following are necessary when ordering a QzROM product shipped after writing:

1. QzROM Writing Confirmation Form*
2. Mark Specification Form*
3. ROM data.....Mask file

* For the QzROM writing confirmation form and the mark specification form, refer to the "Renesas Technology Corp." Homepage (http://www.renesas.com/homepage.jsp).

Note that we cannot deal with special font marking (customer's trademark etc.) in QzROM microcomputer.

Downloaded from Arrow.com.

REVISION HISTORY	3858 Group Data Sheet

Rev.	Date	Description	
		Page	Summary
1.00	Jan.28, 2005	–	First edition issued
1.01	May.11, 2005	5	Table 2 added
		10	ROM code protect address, Notes added
			Fig. 8 partly revised
		60	QzROM Version, Notes On QzROM Writing Orders, Notes On ROM Code Protect, DATA REQUIRED FOR QzROM WRITING ORDERS added
		61	Table 7 partly revised
		65	Table 12 partly revised
1.10	Apr.3, 2006	–	"Under development" deleted
		–	Package name is revised "42P2R-A/E" → "PRSP0042GA-B"
		3	Table 1; CNVSS Functions: "and is shared with ..... the built-in QzROM" added
			P3, P4 Functions: "•8-bit I/O port" → "•5-bit I/O port"
		10	ROM Code Protect Address; "the Mask option set up when ordering." →
			"ROM option setup ..... when ordering." revised
		12	Table 5 "A/D converter input" → "A/D conversion input"
		15	Fig. 12 revised
		17	Fig. 14; b7 to b5 of registers PULL3 and PULL4 revised
		53	WATCHDOG TIMER revised
		56	CLOCK GENERATING CIRCUIT revised
		57	Fig. 59 revised
		59	Table 7; Input voltage $P2_2$, $P2_3$ Ratings: "5.8" → "V_{CC} +0.3"
			Input voltage CNV_{SS} Ratings: "V_{CC} +0.3" → "8.0"
		61	Table 9; f(X_{CIN}), Note 4 added
		64	Table 13 "V_{CC} = 4.0 to 5.5 V" → "V_{CC} = 2.7 to 5.5 V"
		69	PACKAGE OUTLINE revised
		70 to 75	NOTES added (The last NOTES ON PROGRAMMING and NOTES ON USAGE deleted)
1.11	Dec.18,2008	1,4,5,59	PRSP0042GA-B → PRSP0042GA-A/B
		23	Fig. 17: Main clock division ration selection bit X_{IN} "1" deleted
		52	"Initial Value of Watchdog Timer" partly added
			When bit 7 of the watchdog timer control register is
			"0": 65.536 ms at X_{IN} = 16 MHz frequency → 131.072 ms at X_{IN} = 8 MHz frequency
			"1": 256 µs at X_{IN} = 16 MHz frequency → 512 µs at X_{IN} = 8 MHz frequency
		55	(2) Wait mode partly revised: "When releasing the STP state, the input of the prescaler 12 and timer 1 is connected to the count source which had set at executing the STP instruction and the prescaler 12 and timer 1 will start counting"
		63	Table 11 A/D converter characteristics: "Ta = 25°C " deleted from the test conditions of absolute accuracy
		72	Notes on Watchdog Timer:
			"STP instruction disable bit" → "STP instruction function selection bit"
		73	Notes on QzROM Writing Orders revised

Downloaded from Arrow.com.

Renesas Technology Corp. Sales Strategic Planning Div. Nippon Bldg., 2-6-2, Ohte-machi, Chiyoda-ku, Tokyo 100-0004, Japan

Notes:
1. This document is provided for reference purposes only so that Renesas customers may select the appropriate Renesas products for their use. Renesas neither makes warranties or representations with respect to the accuracy or completeness of the information contained in this document nor grants any license to any intellectual property rights or any other rights of Renesas or any third party with respect to the information in this document.
2. Renesas shall have no liability for damages or infringement of any intellectual property or other rights arising out of the use of any information in this document, including, but not limited to, product data, diagrams, charts, programs, algorithms, and application circuit examples.
3. You should not use the products or the technology described in this document for the purpose of military applications such as the development of weapons of mass destruction or for the purpose of any other military use. When exporting the products or technology described herein, you should follow the applicable export control laws and regulations, and procedures required by such laws and regulations.
4. All information included in this document such as product data, diagrams, charts, programs, algorithms, and application circuit examples, is current as of the date this document is issued. Such information, however, is subject to change without any prior notice. Before purchasing or using any Renesas products listed in this document, please confirm the latest product information with a Renesas sales office. Also, please pay regular and careful attention to additional and different information to be disclosed by Renesas such as that disclosed through our website. (http://www.renesas.com)
5. Renesas has used reasonable care in compiling the information included in this document, but Renesas assumes no liability whatsoever for any damages incurred as a result of errors or omissions in the information included in this document.
6. When using or otherwise relying on the information in this document, you should evaluate the information in light of the total system before deciding about the applicability of such information to the intended application. Renesas makes no representations, warranties or guaranties regarding the suitability of its products for any particular application and specifically disclaims any liability arising out of the application and use of the information in this document or Renesas products.
7. With the exception of products specified by Renesas as suitable for automobile applications, Renesas products are not designed, manufactured or tested for applications or otherwise in systems the failure or malfunction of which may cause a direct threat to human life or create a risk of human injury or which require especially high quality and reliability such as safety systems, or equipment or systems for transportation and traffic, healthcare, combustion control, aerospace and aeronautics, nuclear power, or undersea communication transmission. If you are considering the use of our products for such purposes, please contact a Renesas sales office beforehand. Renesas shall have no liability for damages arising out of the uses set forth above.
8. Notwithstanding the preceding paragraph, you should not use Renesas products for the purposes listed below:
   (1) artificial life support devices or systems
   (2) surgical implantations
   (3) healthcare intervention (e.g., excision, administration of medication, etc.)
   (4) any other purposes that pose a direct threat to human life
   Renesas shall have no liability for damages arising out of the uses set forth in the above and purchasers who elect to use Renesas products in any of the foregoing applications shall indemnify and hold harmless Renesas Technology Corp., its affiliated companies and their officers, directors, and employees against any and all damages arising out of such applications.
9. You should use the products described herein within the range specified by Renesas, especially with respect to the maximum rating, operating supply voltage range, movement power voltage range, heat radiation characteristics, installation and other product characteristics. Renesas shall have no liability for malfunctions or damages arising out of the use of Renesas products beyond such specified ranges.
10. Although Renesas endeavors to improve the quality and reliability of its products, IC products have specific characteristics such as the occurrence of failure at a certain rate and malfunctions under certain use conditions. Please be sure to implement safety measures to guard against the possibility of physical injury, and injury or damage caused by fire in the event of the failure of a Renesas product, such as safety design for hardware and software including but not limited to redundancy, fire control and malfunction prevention, appropriate treatment for aging degradation or any other applicable measures. Among others, since the evaluation of microcomputer software alone is very difficult, please evaluate the safety of the final products or system manufactured by you.
11. In case Renesas products listed in this document are detached from the products to which the Renesas products are attached or affixed, the risk of accident such as swallowing by infants and small children is very high. You should implement safety measures so that Renesas products may not be easily detached from your products. Renesas shall have no liability for damages arising out of such detachment.
12. This document may not be reproduced or duplicated, in any form, in whole or in part, without prior written approval from Renesas.
13. Please contact a Renesas sales office if you have any questions regarding the information contained in this document, Renesas semiconductor products, or if you have any other inquiries.

RENESAS SALES OFFICES

http://www.renesas.com

Refer to "**http://www.renesas.com/en/network**" for the latest and detailed information.

Renesas Technology America, Inc.
450 Holger Way, San Jose, CA 95134-1368, U.S.A
Tel: <1> (408) 382-7500, Fax: <1> (408) 382-7501

Renesas Technology Europe Limited
Dukes Meadow, Millboard Road, Bourne End, Buckinghamshire, SL8 5FH, U.K.
Tel: <44> (1628) 585-100, Fax: <44> (1628) 585-900

Renesas Technology (Shanghai) Co., Ltd.
Unit 204, 205, AZIACenter, No.1233 Lujiazui Ring Rd, Pudong District, Shanghai, China 200120
Tel: <86> (21) 5877-1818, Fax: <86> (21) 6887-7858/7898

Renesas Technology Hong Kong Ltd.
7th Floor, North Tower, World Finance Centre, Harbour City, Canton Road, Tsimshatsui, Kowloon, Hong Kong
Tel: <852> 2265-6688, Fax: <852> 2377-3473

Renesas Technology Taiwan Co., Ltd.
10th Floor, No.99, Fushing North Road, Taipei, Taiwan
Tel: <886> (2) 2715-2888, Fax: <886> (2) 3518-3399

Renesas Technology Singapore Pte. Ltd.
1 Harbour Front Avenue, #06-10, Keppel Bay Tower, Singapore 098632
Tel: <65> 6213-0200, Fax: <65> 6278-8001

Renesas Technology Korea Co., Ltd.
Kukje Center Bldg. 18th Fl., 191, 2-ka, Hangang-ro, Yongsan-ku, Seoul 140-702, Korea
Tel: <82> (2) 796-3115, Fax: <82> (2) 796-2145

Renesas Technology Malaysia Sdn. Bhd
Unit 906, Block B, Menara Amcorp, Amcorp Trade Centre, No.18, Jln Persiaran Barat, 46050 Petaling Jaya, Selangor Darul Ehsan, Malaysia
Tel: <603> 7955-9390, Fax: <603> 7955-9510

© 2008. Renesas Technology Corp., All rights reserved. Printed in Japan.

Colophon .7.2

Downloaded from Arrow.com.