DC Brushless Fan Motor Driver

Standard Single-phase Full wave Fan motor driver

BD6964FVM

Description

This is the summary of application for BD6964FVM. BD6964FVM can drive FAN motor silently by BTL soft switching, and it can control rotational speed by PWM signal.

Features

- Compact package (MSOP8)
- BTL soft switching drive
- PWM speed control
- Quick start function
- Lock protection and auto restart (without external capacitor)
- Lock alarm signal (AL) output

Application

- PC, PC peripheral component (Power supply, VGA card, case FAN etc.)
- BD player, Projector etc.

Package

	W(Typ) x D(Typ) x H(Max)
MSOP8	2.90mm x 4.00mm x 0.90m



MSOP8

Absolute Maximum Ratings

Parameter	Symbol	Limit	Unit
Supply Voltage	V_{CC}	15	V
Power Dissipation	Pd	0.58(Note 1)	W
Operating Temperature	Topr	-40～+105	°C
Storage Temperature	Tstg	-55～+150	°C
Output Voltage	V_{OMAX}	15	V
Output Current	I_{OMAX}	800(Note 2)	mA
AL Signal Output Voltage	V_{AL}	15	V
AL Signal Output Current	I_{AL}	10	mA
Junction Temperature	Tjmax	150	°C

(Note 1) Reduce by 4.68mW/°C over 25°C. (On 70.0mm×70.0mm×1.6mm glass epoxy board)
(Note 2) This value is not to exceed Pd.

Caution: Operating the IC over the absolute maximum ratings may damage the IC. The damage can either be a short circuit between pins or an open circuit between pins and the internal circuitry. Therefore, it is important to consider circuit protection measures, such as adding a fuse, in case the IC is operated over the absolute maximum ratings.

© 2012 ROHM Co., Ltd. All rights reserved.

Downloaded from Arrow.com.

Recommended Operating Conditions

Parameter	Symbol	Limit	Unit
Operating supply voltage range	V_{CC}	3.3 to 14	V
Hall input voltage range	V_H	0 to V_{CC}/3	V

Electrical Characteristics (Unless otherwise specified Ta=25°C, Vcc=12V)

Parameter	Symbol	Limits			Unit	Conditions	Characteristics
		Min	Typ	Max			
Circuit Current 1	$I_{CC}1$	1	3	5	mA	PWM=GND	Figure 1
Circuit Current 2	$I_{CC}2$	2	5	8	mA	PWM=OPEN	Figure 2
Input Offset Voltage	V_{HOFS}	-	-	±6	mV		-
PWM Input H Level	V_{PWMH}	2.0	-	Vcc+0.3	V		-
PWM Input L Level	V_{PWML}	-0.3	-	0.8	V		-
PWM Input Current	I_{PWMH}	11	22	33	µA	PWM=5V	Figure 3
	I_{PWML}	-42	-28	-14	µA	PWM=GND	Figure 3
Input Frequency	F_{PWM}	0.02	-	50	kHz		-
Output Voltage	V_O	-	0.4	0.6	V	I_O=300mA Upper and Lower total	Figure 4 to 7
Input-output Gain	G_{IO}	45	48	51	dB		-
AL Low Voltage	V_{ALL}	-	-	0.4	V	I_{AL}=5mA	Figure 8,9
AL Leak Current	I_{ALL}	-	-	20	µA	V_{AL}=15V	Figure 10
Lock Detection ON time	t_{ON}	0.35	0.50	0.65	s		Figure 11
Lock Detection OFF time	t_{OFF}	3.5	5.0	6.5	s		Figure 12

Truth Table

H+	H-	PWM	OUT1	OUT2
H	L	H(OPEN)	H	L
L	H	H(OPEN)	L	H
H	L	L	L	L
L	H	L	L	L

AL normal operation :L(output is ON)

lock detection :H(output is OFF)

© 2012 ROHM Co., Ltd. All rights reserved.

Downloaded from Arrow.com.

Reference Data

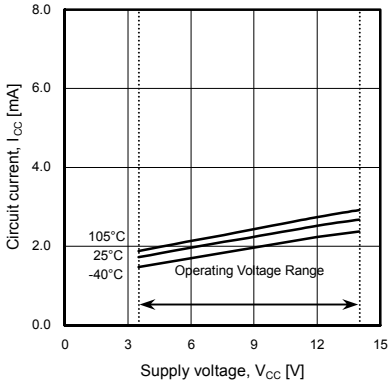


Figure 1. Circuit Current 1

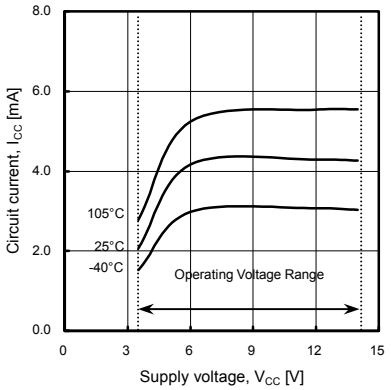


Figure 2. Circuit Current 2

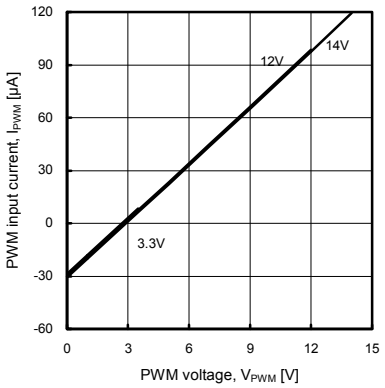


Figure 3. PWM Input Current

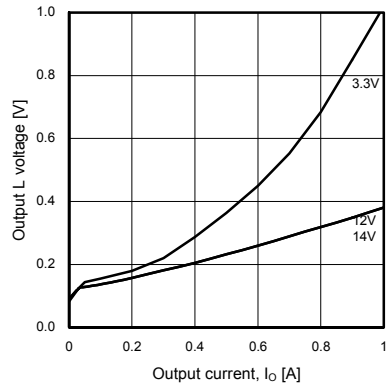


Figure 4. Output L Voltage (Voltage Characteristics)

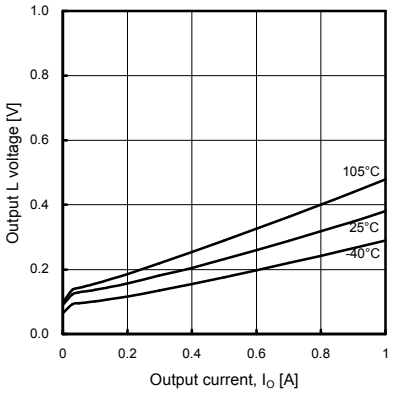


Figure 5. Output L Voltage (Temperature Characteristics)

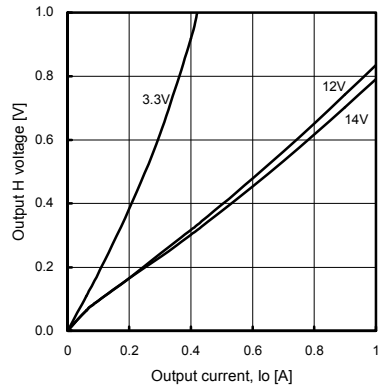


Figure 6. Output H Voltage (Voltage Characteristics)

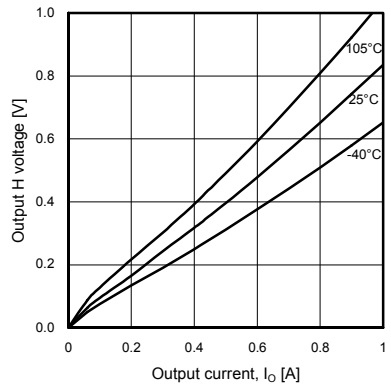


Figure 7. Output H Voltage (Temperature Characteristics)

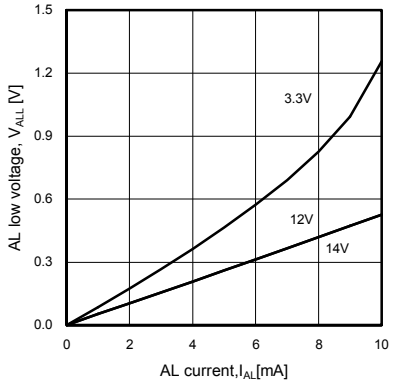


Figure 8. AL L Voltage (Voltage Characteristics)

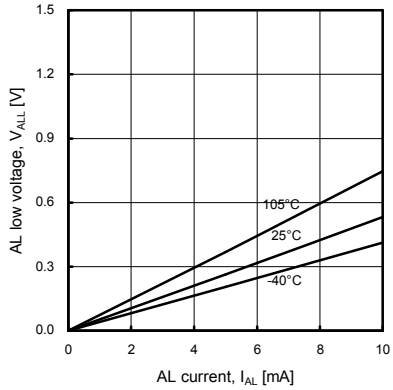


Figure 9. AL L Voltage (Temperature Characteristics)

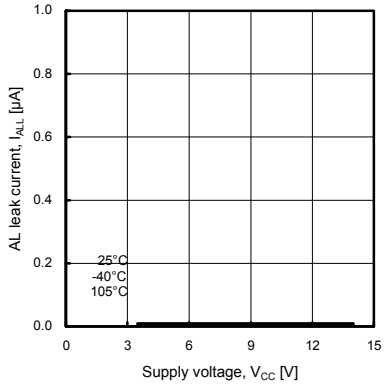


Figure 10. AL Leak Current

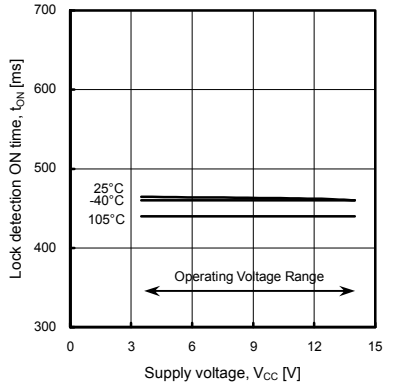


Figure 11. Lock Detection ON time

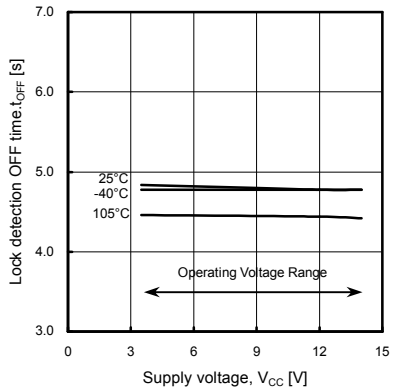
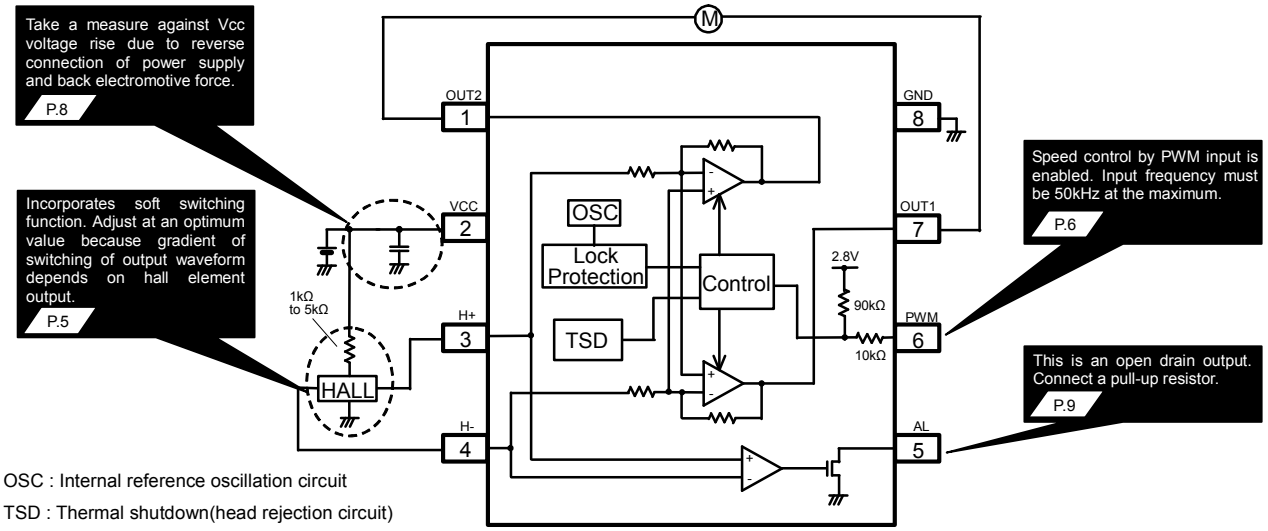


Figure 12. Lock Detection OFF Time

© 2012 ROHM Co., Ltd. All rights reserved.

Downloaded from Arrow.com.

Block Diagram, Application Circuit, and Pin Assignment



Pin No.	Pin Name	Function
1	OUT2	Motor output
2	VCC	Power supply
3	H+	Hall input +
4	H-	Hall input -
5	AL	Lock alarm signal output
6	PWM	PWM signal input
7	OUT1	Motor output
8	GND	GND

© 2012 ROHM Co., Ltd. All rights reserved.

Downloaded from Arrow.com.

Description of Operations

1) Lock Protection and Automatic Restart Circuit

Motor rotation is detected by hall signal, and lock detection ON time (t_{ON}) and lock detection OFF time (t_{OFF}) are set by IC internal counter. External part (C or R) is not required. Timing chart is shown in Figure 13.

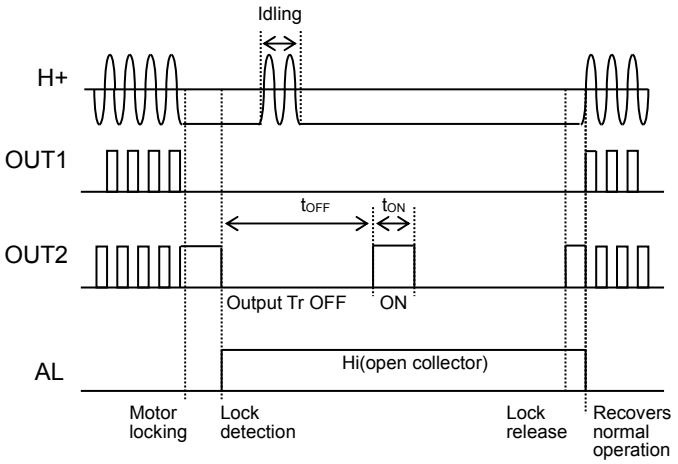


Figure 13. Lock Protection Timing Chart

2) Soft Switching (silent drive setting)

Input signal to hall amplifier is amplified to produce an output signal.

When the hall element output signal is small, the gradient of switching of output waveform is gentle; When it is large, the gradient of switching of output waveform is steep. Enter an appropriate hall element output to IC where output waveform swings sufficiently.

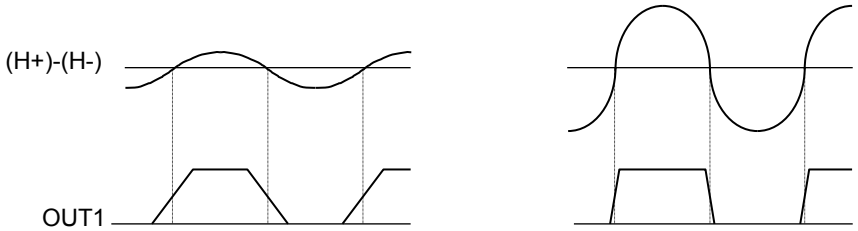


Figure 14. Relation between Hall Element Output Amplitude and Output Waveform

3) Hall Input Setting

Hall input voltage range is shown in operating conditions.

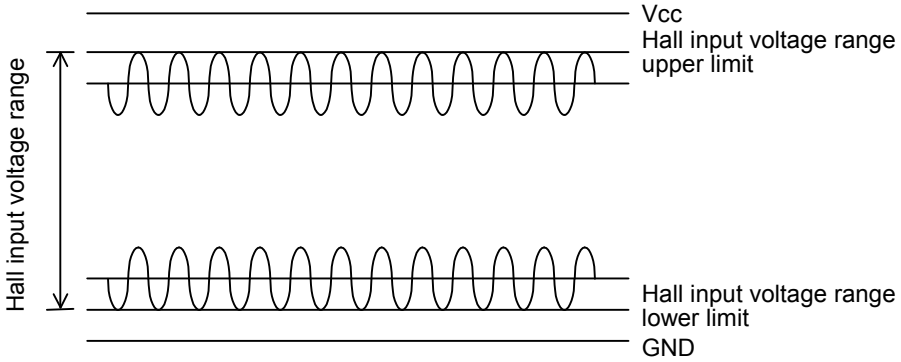


Figure 15. Hall Input Voltage Range

Adjust the value of hall element bias resistor R1 in Figure 16 so that the input voltage of a hall amplifier is input in "Hall Input Voltage Range" including signal amplitude.

© 2012 ROHM Co., Ltd. All rights reserved.

Downloaded from Arrow.com.

○Reducing the Noise of Hall Signal

Hall element may be affected by Vcc noise depending on the wiring pattern of board. In this case, place a capacitor like C1 in Figure 16. In addition, when wiring from the hall element output to IC hall input is long, noise may be loaded on wiring. In this case, place a capacitor like C2 in Figure 16.

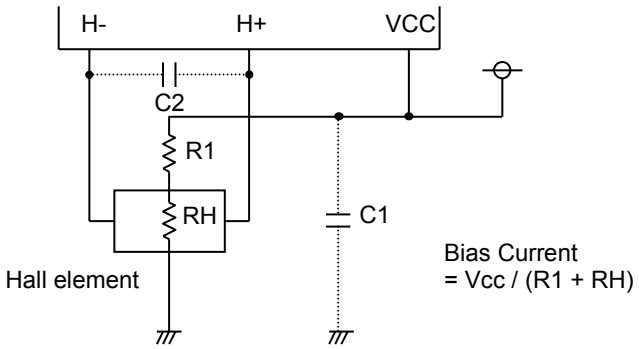


Figure 16. Application near of Hall Signal

4) PWM Input

Rotation speed of motor can be changed by controlling ON/OFF of the upper output depending on duty of the signal input to PWM terminal.

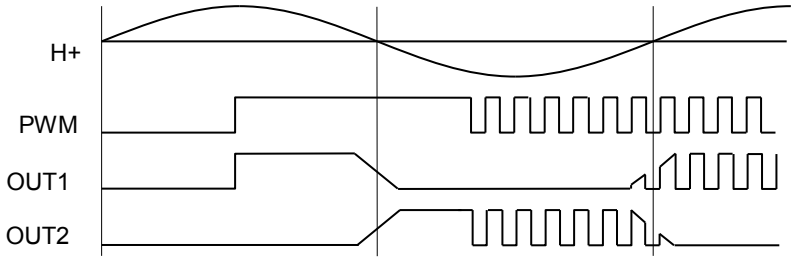


Figure 17. Timing Chart in PWM Control

When the voltage input to PWM terminal applies H logic : normal operation
L logic : H side output is off

When PWM terminal is open, H logic is applied. PWM terminal has hysteresis of 100mV (Typ.).

*If H logic is applied to PWM terminal before VCC voltage is applied to IC, current flows to VCC terminal through ESD protection diode inside PWM terminal, resulting in malfunction may possibly occur.
When VCC voltage is not apply to IC, do not apply voltage to PWM terminal.

5) Quick Start, Stand-by Function

The function can start motor at once regardless of the detection time of lock protection function when the PWM signal is input. Lock protection function is turned off when the time of PWM = L has elapsed more than 66.5 ms in order to disable lock protection function when the motor is stopped by PWM signal.

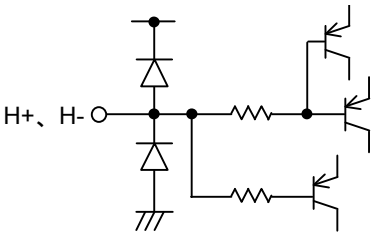
When H level duty of PWM input signal is close to 0%, lock protection function does not work at an input frequency slower than 15Hz, therefore enter a frequency faster than 20Hz.

© 2012 ROHM Co., Ltd. All rights reserved.

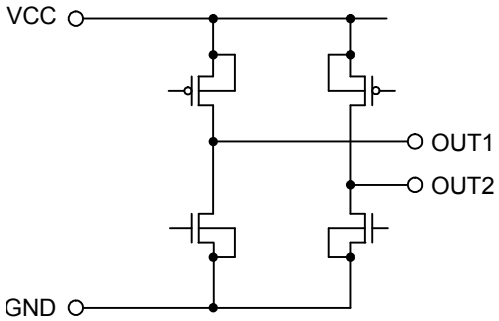
Downloaded from Arrow.com.

Equivalent Circuit

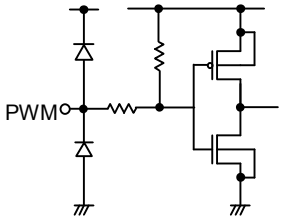
1) Hall Input



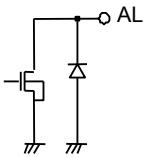
2) Motor Output



3) PWM Signal Input



4) AL Output



© 2012 ROHM Co., Ltd. All rights reserved.

Downloaded from Arrow.com.

Safety Measure

1) Reverse Connection Protection Diode

Reverse connection of power results in IC destruction as shown in Figure 18. When reverse connection is possible, reverse connection destruction preventive diode must be added between power supply and VCC.

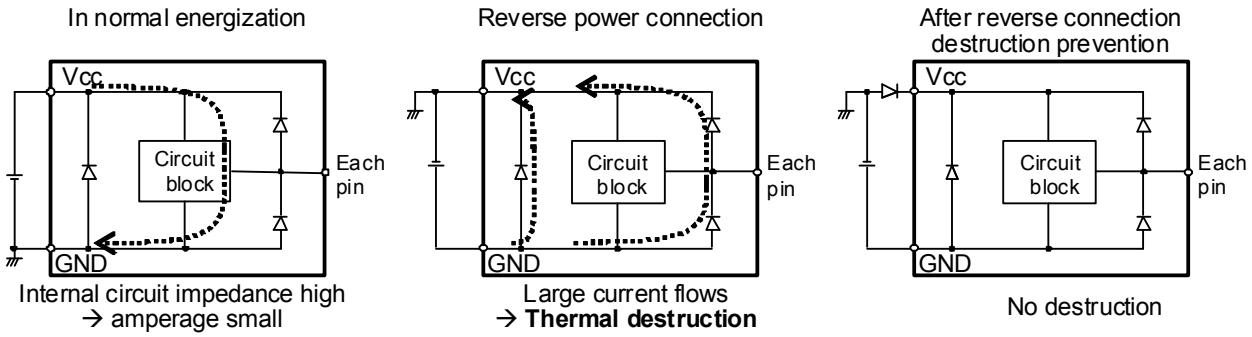


Figure 18. Flow of Current when Power is Connected Reversely

2) Measure against VCC voltage Rise by Back Electromotive Force

Back electromotive force (Back EMF) generates regenerative current to power supply. However, when reverse connection protection diode is connected, VCC voltage rises because the diode prevents current flow to power supply.

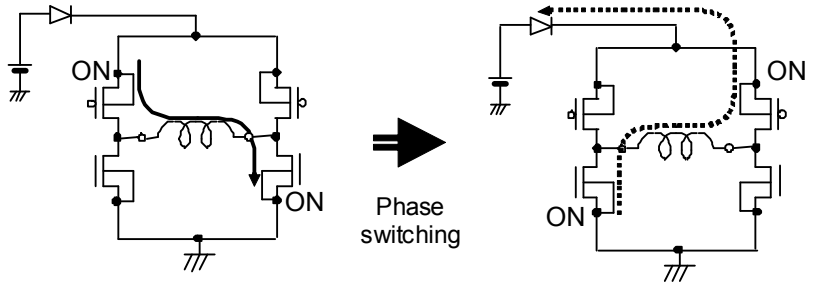


Figure 19. VCC Voltage Rise by Back Electromotive Force

When the absolute maximum rated voltage may be exceeded due to voltage rise by back electromotive force, place (A) Capacitor or (B) Zener diode between VCC and GND. If necessary, add both (C).

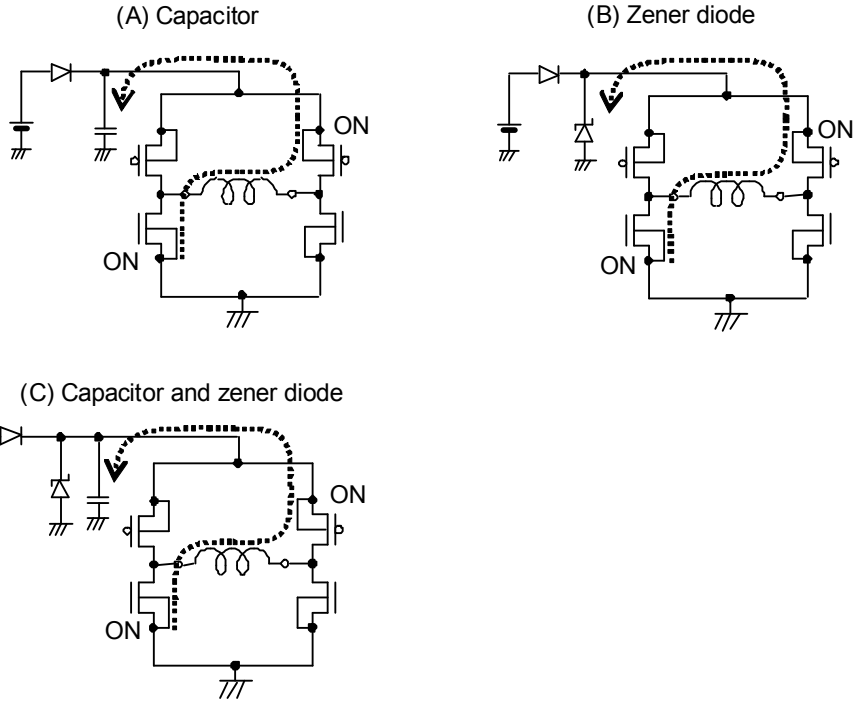


Figure 20. Measure against VCC voltage rise

© 2012 ROHM Co., Ltd. All rights reserved.

Downloaded from Arrow.com.

3) Problem of GND Line PWM Switching

Do not perform PWM switching of GND line because the potential of GND terminal cannot be kept at the minimum.

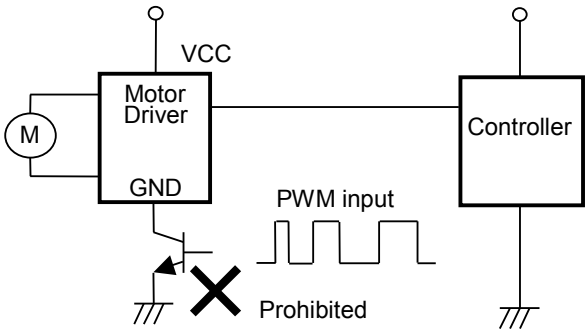


Figure 21. GND Line PWM Switching Prohibited

4) AL Output

AL output is an open drain and requires pull-up resistor.

The IC can be protected by adding resistor R1. An excess of absolute maximum rating, when AL output terminal is directly connected to power supply, could damage the IC.

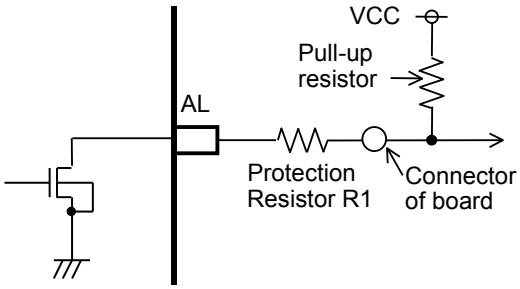


Fig.22 Protection of AL terminal

Thermal derating curve

Thermal derating curve indicates power that can be consumed by IC with reference to ambient temperature. Power that can be consumed by IC begins to attenuate at certain ambient temperature. This gradient is determined by thermal resistance θja.

Thermal resistance θja depends on chip size, power consumption, package ambient temperature, packaging condition, wind velocity, etc., even when the same package is used. Thermal derating curve indicates a reference value measured at a specified condition. Figure 23 shows a thermal derating curve.

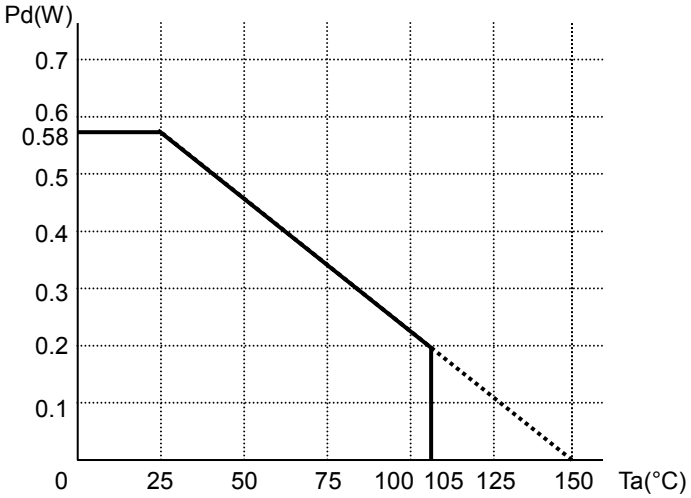


Figure 23. Thermal Derating Curve

© 2012 ROHM Co., Ltd. All rights reserved.

Downloaded from Arrow.com.

Operational Notes

1. **Reverse Connection of Power Supply**
   Connecting the power supply in reverse polarity can damage the IC. Take precautions against reverse polarity when connecting the power supply, such as mounting an external diode between the power supply and the IC's power supply pins.

2. **Power Supply Lines**
   Design the PCB layout pattern to provide low impedance supply lines. Separate the ground and supply lines of the digital and analog blocks to prevent noise in the ground and supply lines of the digital block from affecting the analog block. Furthermore, connect a capacitor to ground at all power supply pins. Consider the effect of temperature and aging on the capacitance value when using electrolytic capacitors.

3. **Ground Voltage**
   Ensure that no pins are at a voltage below that of the ground pin at any time, even during transient condition. However, pins that drive inductive loads (e.g. motor driver outputs, DC-DC converter outputs) may inevitably go below ground due to back EMF or electromotive force. In such cases, the user should make sure that such voltages going below ground will not cause the IC and the system to malfunction by examining carefully all relevant factors and conditions such as motor characteristics, supply voltage, operating frequency and PCB wiring to name a few.

4. **Ground Wiring Pattern**
   When using both small-signal and large-current ground traces, the two ground traces should be routed separately but connected to a single ground at the reference point of the application board to avoid fluctuations in the small-signal ground caused by large currents. Also ensure that the ground traces of external components do not cause variations on the ground voltage. The ground lines must be as short and thick as possible to reduce line impedance.

5. **Thermal Consideration**
   Should by any chance the power dissipation rating be exceeded the rise in temperature of the chip may result in deterioration of the properties of the chip. The absolute maximum rating of the Pd stated in this specification is when the IC is mounted on a 70mm x 70mm x 1.6mm glass epoxy board. In case of exceeding this absolute maximum rating, increase the board size and copper area to prevent exceeding the Pd rating.

6. **Recommended Operating Conditions**
   These conditions represent a range within which the expected characteristics of the IC can be approximately obtained. The electrical characteristics are guaranteed under the conditions of each parameter.

7. **Inrush Current**
   When power is first supplied to the IC, it is possible that the internal logic may be unstable and inrush current may flow instantaneously due to the internal powering sequence and delays, especially if the IC has more than one power supply. Therefore, give special consideration to power coupling capacitance, power wiring, width of ground wiring, and routing of connections.

8. **Operation Under Strong Electromagnetic Field**
   Operating the IC in the presence of a strong electromagnetic field may cause the IC to malfunction.

9. **Testing on Application Boards**
   When testing the IC on an application board, connecting a capacitor directly to a low-impedance output pin may subject the IC to stress. Always discharge capacitors completely after each process or step. The IC's power supply should always be turned off completely before connecting or removing it from the test setup during the inspection process. To prevent damage from static discharge, ground the IC during assembly and use similar precautions during transport and storage.

10. **Inter-pin Short and Mounting Errors**
    Ensure that the direction and position are correct when mounting the IC on the PCB. Incorrect mounting may result in damaging the IC. Avoid nearby pins being shorted to each other especially to ground, power supply and output pin. Inter-pin shorts could be due to many reasons such as metal particles, water droplets (in very humid environment) and unintentional solder bridge deposited in between pins during assembly to name a few.

© 2012 ROHM Co., Ltd. All rights reserved.

Downloaded from Arrow.com.

Operational Notes – continued

11. Unused Input Pins

Input pins of an IC are often connected to the gate of a MOS transistor. The gate has extremely high impedance and extremely low capacitance. If left unconnected, the electric field from the outside can easily charge it. The small charge acquired in this way is enough to produce a significant effect on the conduction through the transistor and cause unexpected operation of the IC. So unless otherwise specified, unused input pins should be connected to the power supply or ground line.

12. Regarding the Input Pin of the IC

This monolithic IC contains P+ isolation and P substrate layers between adjacent elements in order to keep them isolated. P-N junctions are formed at the intersection of the P layers with the N layers of other elements, creating a parasitic diode or transistor. For example (refer to figure below):

When GND > Pin A and GND > Pin B, the P-N junction operates as a parasitic diode.
When GND > Pin B, the P-N junction operates as a parasitic transistor.

Parasitic diodes inevitably occur in the structure of the IC. The operation of parasitic diodes can result in mutual interference among circuits, operational faults, or physical damage. Therefore, conditions that cause these diodes to operate, such as applying a voltage lower than the GND voltage to an input pin (and thus to the P substrate) should be avoided.

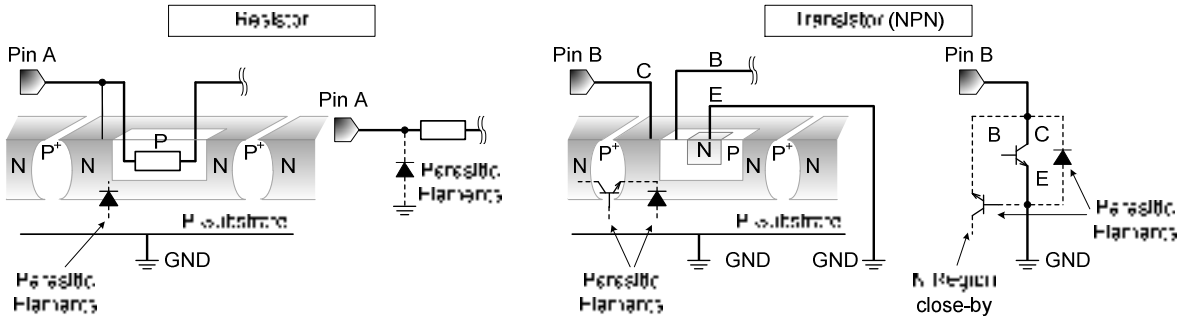


Figure 24. Example of monolithic IC structure

13. Ceramic Capacitor

When using a ceramic capacitor, determine the dielectric constant considering the change of capacitance with temperature and the decrease in nominal capacitance due to DC bias and others.

14. Thermal Shutdown Circuit(TSD)

This IC has a built-in thermal shutdown circuit that prevents heat damage to the IC. Normal operation should always be within the IC's power dissipation rating. If however the rating is exceeded for a continued period, the junction temperature (Tj) will rise which will activate the TSD circuit that will turn OFF all output pins. When the Tj falls below the TSD threshold, the circuits are automatically restored to normal operation.
Note that the TSD circuit operates in a situation that exceeds the absolute maximum ratings and therefore, under no circumstances, should the TSD circuit be used in a set design or for any purpose other than protecting the IC from heat damage.

© 2012 ROHM Co., Ltd. All rights reserved.

Downloaded from Arrow.com.

Ordering Information

B	D	6	9	6	4	F	V	M	-	TR

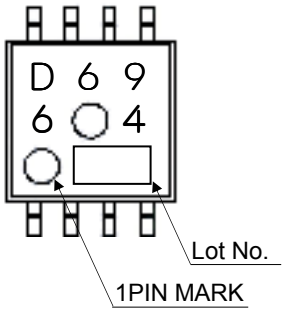
Part Number

Package
F: SOP8

Packaging and forming specification
E2: Embossed tape and reel

Marking Diagram

MSOP8
(TOP VIEW)

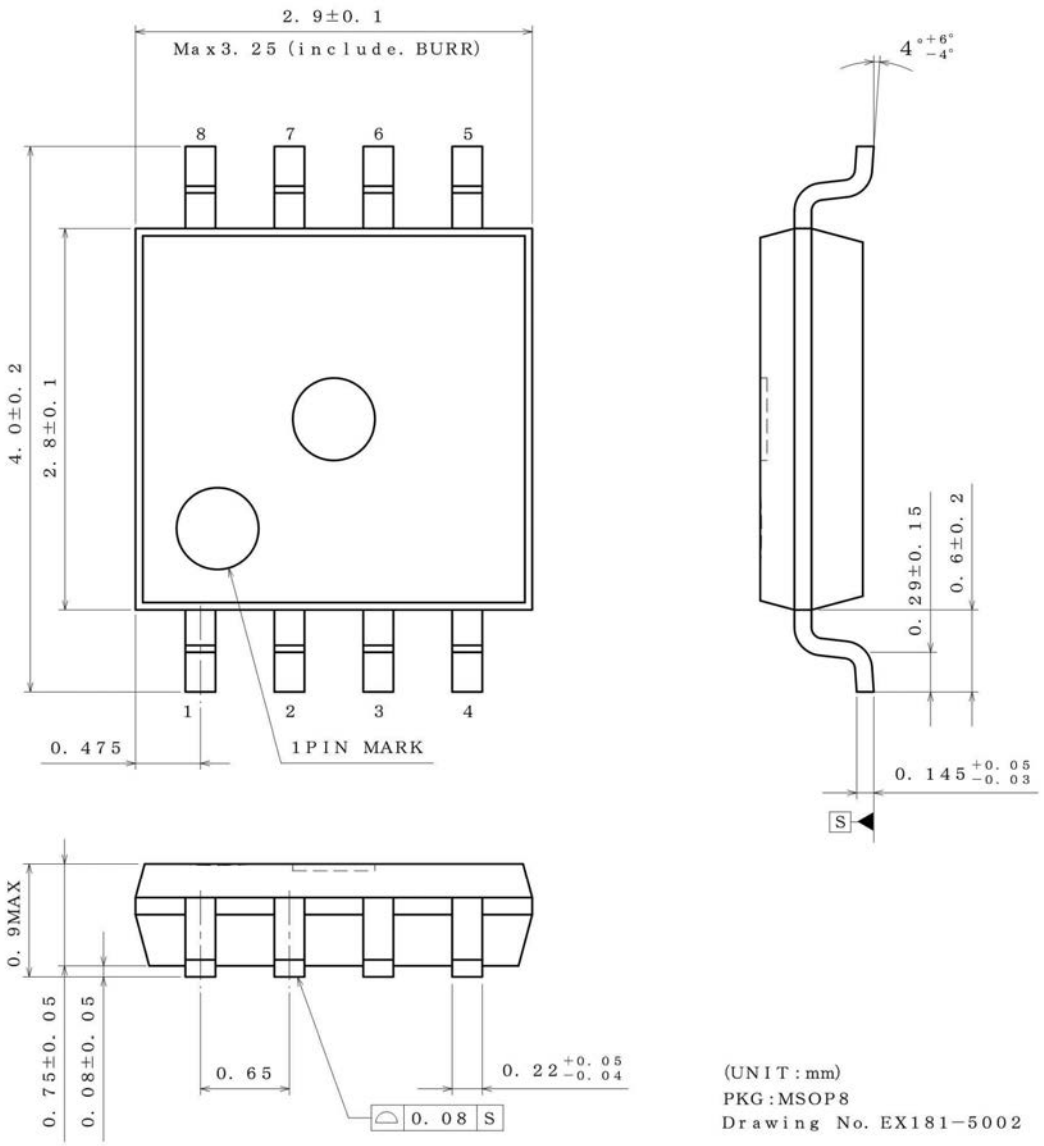


© 2012 ROHM Co., Ltd. All rights reserved.

Downloaded from Arrow.com.

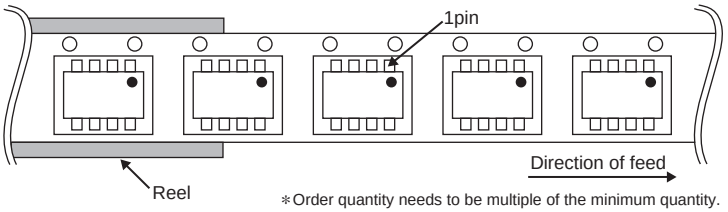
Physical Dimension, Tape and Reel Information

Package Name	MSOP8



<Tape and Reel information>

Tape	Embossed carrier tape
Quantity	3000pcs
Direction of feed	TR (The direction is the 1pin of product is at the upper right when you hold reel on the left hand and you pull out the tape on the right hand)



∗Order quantity needs to be multiple of the minimum quantity.

© 2012 ROHM Co., Ltd. All rights reserved.

Downloaded from Arrow.com.

Notice

Precaution on using ROHM Products

1. Our Products are designed and manufactured for application in ordinary electronic equipments (such as AV equipment, OA equipment, telecommunication equipment, home electronic appliances, amusement equipment, etc.). If you intend to use our Products in devices requiring extremely high reliability (such as medical equipment (Note 1), transport equipment, traffic equipment, aircraft/spacecraft, nuclear power controllers, fuel controllers, car equipment including car accessories, safety devices, etc.) and whose malfunction or failure may cause loss of human life, bodily injury or serious damage to property ("Specific Applications"), please consult with the ROHM sales representative in advance. Unless otherwise agreed in writing by ROHM in advance, ROHM shall not be in any way responsible or liable for any damages, expenses or losses incurred by you or third parties arising from the use of any ROHM's Products for Specific Applications.

(Note1) Medical Equipment Classification of the Specific Applications

JAPAN	USA	EU	CHINA
CLASSⅢ	CLASSⅢ	CLASSⅡb	CLASSⅢ
CLASSⅣ		CLASSⅢ	

2. ROHM designs and manufactures its Products subject to strict quality control system. However, semiconductor products can fail or malfunction at a certain rate. Please be sure to implement, at your own responsibilities, adequate safety measures including but not limited to fail-safe design against the physical injury, damage to any property, which a failure or malfunction of our Products may cause. The following are examples of safety measures:
   [a] Installation of protection circuits or other protective devices to improve system safety
   [b] Installation of redundant circuits to reduce the impact of single or multiple circuit failure

3. Our Products are designed and manufactured for use under standard conditions and not under any special or extraordinary environments or conditions, as exemplified below. Accordingly, ROHM shall not be in any way responsible or liable for any damages, expenses or losses arising from the use of any ROHM's Products under any special or extraordinary environments or conditions. If you intend to use our Products under any special or extraordinary environments or conditions (as exemplified below), your independent verification and confirmation of product performance, reliability, etc, prior to use, must be necessary:
   [a] Use of our Products in any types of liquid, including water, oils, chemicals, and organic solvents
   [b] Use of our Products outdoors or in places where the Products are exposed to direct sunlight or dust
   [c] Use of our Products in places where the Products are exposed to sea wind or corrosive gases, including Cl_2, H_2S, NH_3, SO_2, and NO_2
   [d] Use of our Products in places where the Products are exposed to static electricity or electromagnetic waves
   [e] Use of our Products in proximity to heat-producing components, plastic cords, or other flammable items
   [f] Sealing or coating our Products with resin or other coating materials
   [g] Use of our Products without cleaning residue of flux (even if you use no-clean type fluxes, cleaning residue of flux is recommended); or Washing our Products by using water or water-soluble cleaning agents for cleaning residue after soldering
   [h] Use of the Products in places subject to dew condensation

4. The Products are not subject to radiation-proof design.

5. Please verify and confirm characteristics of the final or mounted products in using the Products.

6. In particular, if a transient load (a large amount of load applied in a short period of time, such as pulse. is applied, confirmation of performance characteristics after on-board mounting is strongly recommended. Avoid applying power exceeding normal rated power; exceeding the power rating under steady-state loading condition may negatively affect product performance and reliability.

7. De-rate Power Dissipation (Pd) depending on Ambient temperature (Ta). When used in sealed area, confirm the actual ambient temperature.

8. Confirm that operation temperature is within the specified range described in the product specification.

9. ROHM shall not be in any way responsible or liable for failure induced under deviant condition from what is defined in this document.

Precaution for Mounting / Circuit board design

1. When a highly active halogenous (chlorine, bromine, etc.) flux is used, the residue of flux may negatively affect product performance and reliability.

2. In principle, the reflow soldering method must be used; if flow soldering method is preferred, please consult with the ROHM representative in advance.

For details, please refer to ROHM Mounting specification

© 2013 ROHM Co., Ltd. All rights reserved.

Downloaded from Arrow.com.

Precautions Regarding Application Examples and External Circuits

1. If change is made to the constant of an external circuit, please allow a sufficient margin considering variations of the characteristics of the Products and external components, including transient characteristics, as well as static characteristics.

2. You agree that application notes, reference designs, and associated data and information contained in this document are presented only as guidance for Products use. Therefore, in case you use such information, you are solely responsible for it and you must exercise your own independent verification and judgment in the use of such information contained in this document. ROHM shall not be in any way responsible or liable for any damages, expenses or losses incurred by you or third parties arising from the use of such information.

Precaution for Electrostatic

This Product is electrostatic sensitive product, which may be damaged due to electrostatic discharge. Please take proper caution in your manufacturing process and storage so that voltage exceeding the Products maximum rating will not be applied to Products. Please take special care under dry condition (e.g. Grounding of human body / equipment / solder iron, isolation from charged objects, setting of Ionizer, friction prevention and temperature / humidity control).

Precaution for Storage / Transportation

1. Product performance and soldered connections may deteriorate if the Products are stored in the places where:
   - [a] the Products are exposed to sea winds or corrosive gases, including Cl2, H2S, NH3, SO2, and NO2
   - [b] the temperature or humidity exceeds those recommended by ROHM
   - [c] the Products are exposed to direct sunshine or condensation
   - [d] the Products are exposed to high Electrostatic

2. Even under ROHM recommended storage condition, solderability of products out of recommended storage time period may be degraded. It is strongly recommended to confirm solderability before using Products of which storage time is exceeding the recommended storage time period.

3. Store / transport cartons in the correct direction, which is indicated on a carton with a symbol. Otherwise bent leads may occur due to excessive stress applied when dropping of a carton.

4. Use Products within the specified time after opening a humidity barrier bag. Baking is required before using Products of which storage time is exceeding the recommended storage time period.

Precaution for Product Label

QR code printed on ROHM Products label is for ROHM's internal use only.

Precaution for Disposition

When disposing Products please dispose them properly using an authorized industry waste company.

Precaution for Foreign Exchange and Foreign Trade act

Since our Products might fall under controlled goods prescribed by the applicable foreign exchange and foreign trade act, please consult with ROHM representative in case of export.

Precaution Regarding Intellectual Property Rights

1. All information and data including but not limited to application example contained in this document is for reference only. ROHM does not warrant that foregoing information or data will not infringe any intellectual property rights or any other rights of any third party regarding such information or data. ROHM shall not be in any way responsible or liable for infringement of any intellectual property rights or other damages arising from use of such information or data.:

2. No license, expressly or implied, is granted hereby under any intellectual property rights or other rights of ROHM or any third parties with respect to the information contained in this document.

Other Precaution

1. This document may not be reprinted or reproduced, in whole or in part, without prior written consent of ROHM.

2. The Products may not be disassembled, converted, modified, reproduced or otherwise changed without prior written consent of ROHM.

3. In no event shall you use in any way whatsoever the Products and the related technical information contained in the Products or this document for any military purposes, including but not limited to, the development of mass-destruction weapons.

4. The proper names of companies or products described in this document are trademarks or registered trademarks of ROHM, its affiliated companies or third parties.

© 2013 ROHM Co., Ltd. All rights reserved.

Downloaded from Arrow.com.

General Precaution

1. Before you use our Products, you are requested to carefully read this document and fully understand its contents. ROHM shall not be in any way responsible or liable for failure, malfunction or accident arising from the use of any ROHM's Products against warning, caution or note contained in this document.

2. All information contained in this document is current as of the issuing date and subject to change without any prior notice. Before purchasing or using ROHM's Products, please confirm the latest information with a ROHM sales representative.

3. The information contained in this document is provided on an "as is" basis and ROHM does not warrant that all information contained in this document is accurate and/or error-free. ROHM shall not be in any way responsible or liable for any damages, expenses or losses incurred by you or third parties resulting from inaccuracy or errors of or concerning such information.

© 2014 ROHM Co., Ltd. All rights reserved.

Downloaded from Arrow.com.