DC Brushless Fan Motor Driver

5V Single-phase Full-wave Fan motor driver

BD6966NUX

●Description

This is the summary of application for BD6966NUX that suit for notebook PC cooling fan motor. They employ Bi-CMOS process and realize low ON resistor, and low power consumption and quiet drive.

●Features

- Small and thin package (VSON10　thickness:0.6mm)
- BTL soft switching drive
- PWM speed control
- Low duty start up function and enable/disable selectable
- Quick start function
- Stand-by function
- Constant voltage output for hall element
- Lock protection and auto restart (without external capacitor)
- Rotating speed pulse signal (FG) output

●Package(s)

	W(Typ.) x D(Typ.) x H(Max.)
VSON010X3030	3.00mm x 3.00mm x 0.60mm



VSON010X3030

●Applications

- Compact 5V fan such as notebook PC cooling fan

●Absolute maximum ratings

Parameter	Symbol	Limit	Unit
Supply voltage	Vcc	7	V
Power dissipation	Pd	580*	mW
Operating temperature	Topr	-40 to +105	ºC
Storage temperature	Tstg	-55 to +150	ºC
Output voltage	Vomax	7	V
Output current	Iomax	1000**	mA
FG signal output voltage	Vfg	7	V
FG signal output current	Ifg	10	mA
Hall bias output current	Ihb	10	mA
Junction temperature	Tjmax	150	ºC

* Reduce by 4.64mW/ºC over Ta=25ºC(On 74.2mm×74.2mm×1.6mm glass epoxy board, Copper foil area 6.28mm^2)

** This value is not to exceed Pd

●Operating conditions

Parameter	Symbol	Limit	Unit
Operating supply voltage range	Vcc	1.8 to 5.5	V
Hall input voltage range	Vh	0.4 to Vcc-1.1	V

○Product structure：Silicon monolithic integrated circuit　○This product is not designed protection against radioactive rays

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●**Electrical characteristics**(Unless otherwise specified Ta=25℃,Vcc=5V)

Parameter	Symbol	Limits			Unit	Conditions	Characteristics
		Min.	Typ.	Max.			
Circuit current 1	Icc1	1	3	6	mA	PWM=OPEN	Fig.1
Circuit current 2 (Stand-by mode)	Icc2	15	25	35	uA	PWM=GND	Fig.2
Hall bias voltage	Vhb	0.9	1.0	1.1	V	Ihb=-3mA	Fig.3
Input offset voltage	Vofs	0	-	±6	mV		
PWM input H level	Vpwmh	2.5	-	Vcc+0.3	V		
PWM input L level	Vpwml	-0.3	-	0.8	V		-
PWM input current	Ipwmh	-	0	-	μA	PWM=Vcc	-
	Ipwml	-33	-25	-17	μA	PWM=GND	-
PWM input frequency	Fpwm	2	-	50	kHz		-
SEL input L level	Vsell	-0.3	-	0.8	V	SEL=L Start duty assist ON	-
Output voltage	Vo	-	0.4	0.6	V	Io=300mA Upper and Lower total	Fig.4 to 7
Input-output Gain	Gio	43	44.5	46	dB		-
FG hysteresis voltage	Vhys	±5	±10	±15	mV		Fig.8
FG low voltage	Vfgl	-	0.12	0.3	V	Ifg=5mA	Fig.9,10
FG leak current	Ifgl	-	-	10	μA	Vfg=7V	-
Lock detection ON time	Ton	0.35	0.50	0.65	s		Fig.11
Lock detection OFF time	Toff	3.5	5.0	6.5	s		Fig.12

●**Truth table**

H+	H-	PWM	OUT1	OUT2	FG
H	L	H(OPEN)	H	L	H(Output Tr：OFF)
L	H	H(OPEN)	L	H	L(Output Tr：ON)
H	L	L	L	L	H(Output Tr：OFF)
L	H	L	L	L	L(Output Tr：ON)

* FG=H at stand-by mode

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●Reference data

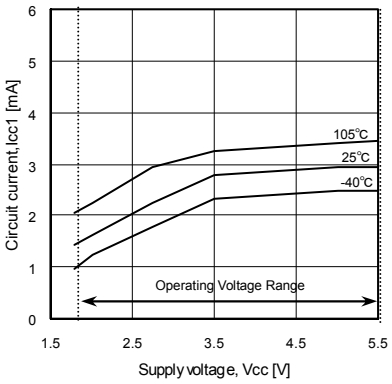


Fig.1 Circuit current 1

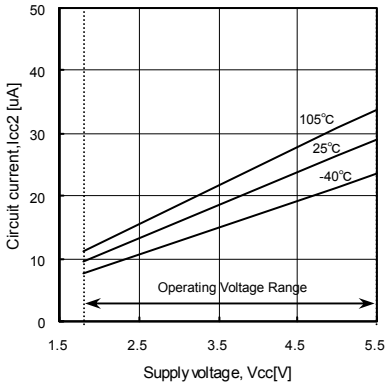


Fig.2 Circuit current 2

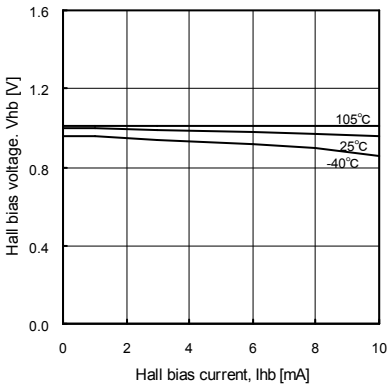


Fig.3 Hall bias voltage

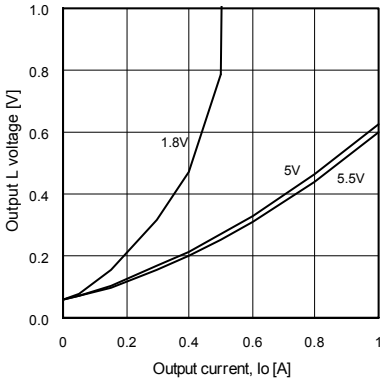


Fig.4 Output L voltage
(Voltage characteristics)

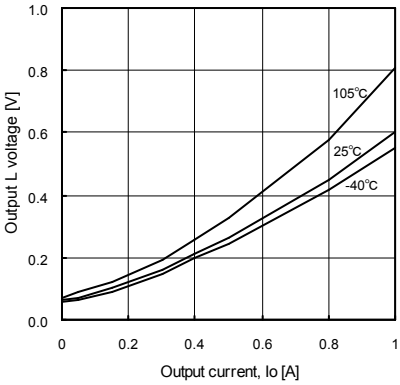


Fig.5 Output L voltage
(Temperature characteristics)

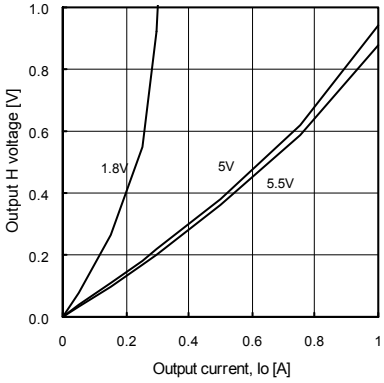


Fig.6 Output H voltage
(Voltage characteristics)

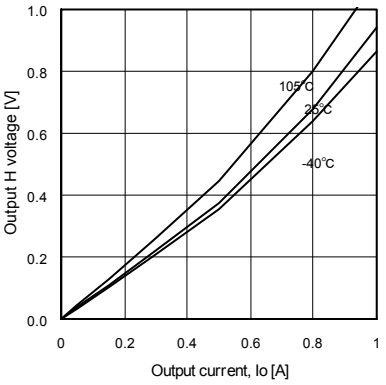


Fig.7 Output H voltage
(Temperature characteristics)

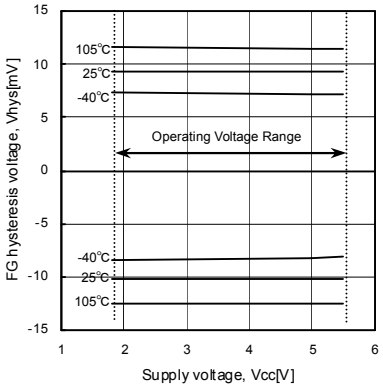


Fig.8 FG hysteresis voltage

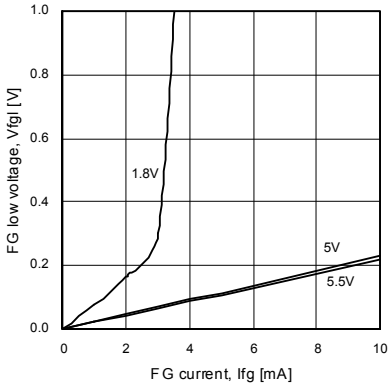


Fig.9 FG output L voltage
(Voltage characteristics)

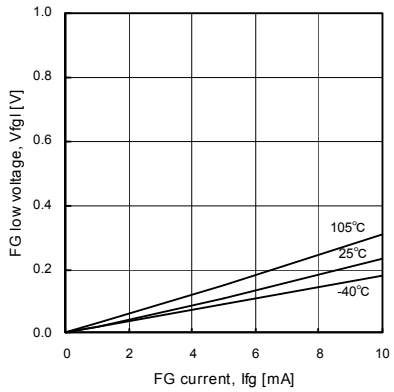


Fig.10 FG output L voltage
(Temperature characteristics)

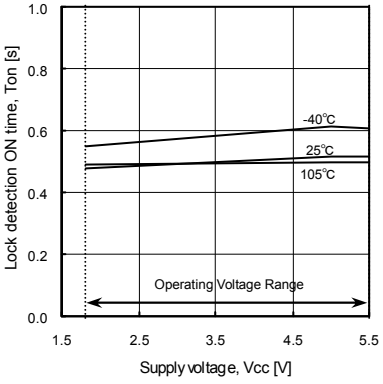


Fig.11 Lock detection ON time

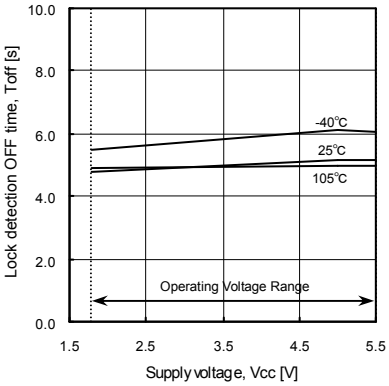
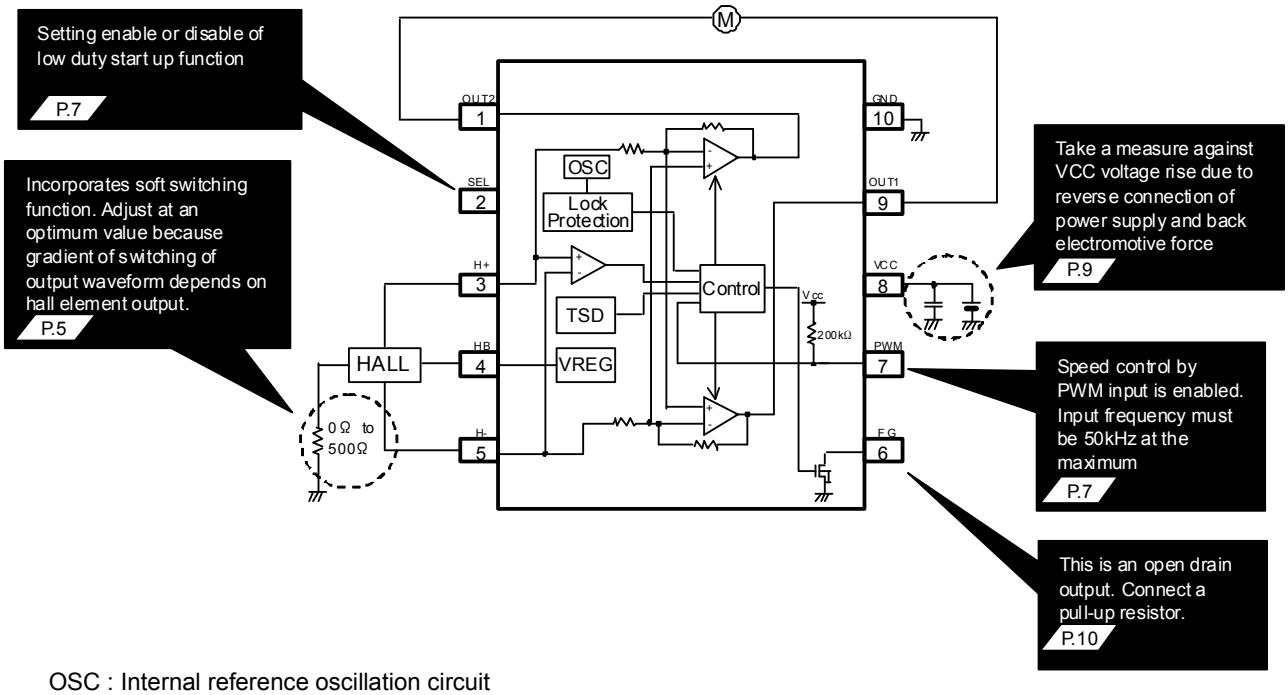


Fig.12 Lock detection OFF time

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●Block diagram, application circuit, and pin assignment



OSC : Internal reference oscillation circuit
TSD : Thermal shut down(heat rejection circuit)

PIN No.	Terminal name	Function
1	OUT2	Motor output terminal 2
2	SEL	Low duty start up function selecting terminal
3	H+	Hall input terminal+
4	HB	Hall bias terminal
5	H-	Hall input terminal-
6	FG	FG signal output terminal
7	PWM	PWM signal input terminal
8	Vcc	Power supply terminal
9	OUT1	Motor output terminal 1
10	GND	GND terminal

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●Description of operations

1) Lock protection and automatic restart circuit

Motor rotation is detected by hall signal, and lock detection ON time (Ton) and lock detection OFF time (Toff) are set by IC internal counter. External part (C or R) is not required. Timing chart is shown in Fig.13.

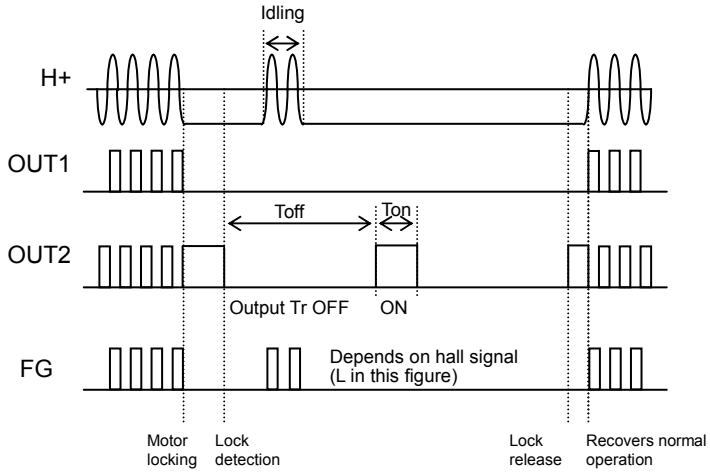


Fig.13 Lock protection timing chart

2) Soft switching function (silent drive setting)

Input signal to hall amplifier is amplified to produce an output signal.

When the hall element output signal is small, the gradient of switching of output waveform is gentle; When it is large, the gradient of switching of output waveform is steep. Gain of 44.5dB (170 times) is provided between input and output, therefore enter an appropriate hall element output to IC where output waveform swings sufficiently.

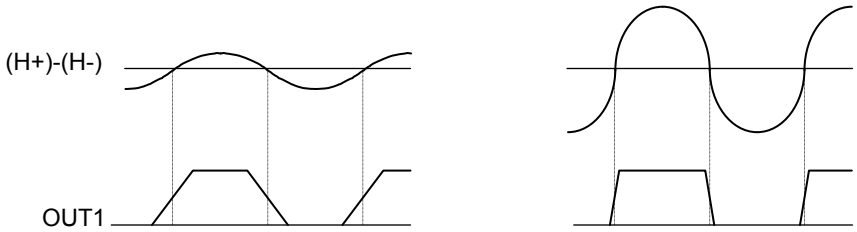


Fig.14 Relation between hall element output amplitude and output waveform

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3) Hall input setting

Hall input voltage range is shown in operating conditions.

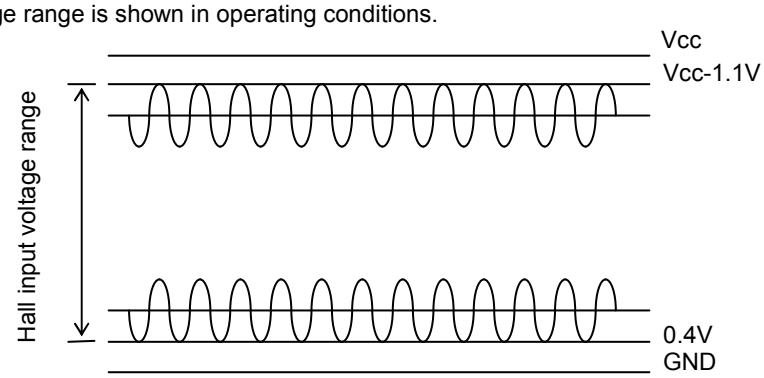


Fig.15 Hall input voltage range

Adjust the value of hall element bias resistor R1 in Fig.16 so that the input voltage of a hall amplifier is input in "hall input voltage range" including signal amplitude.

○Reducing the noise of hall signal

Hall element may be affected by Vcc noise or the like depending on the wiring pattern of board. In this case, place a capacitor like C1 in Fig.16. In addition, when wiring from the hall element output to IC hall input is long, noise may be loaded on wiring. In this case, place a capacitor like C2 in Fig.16.

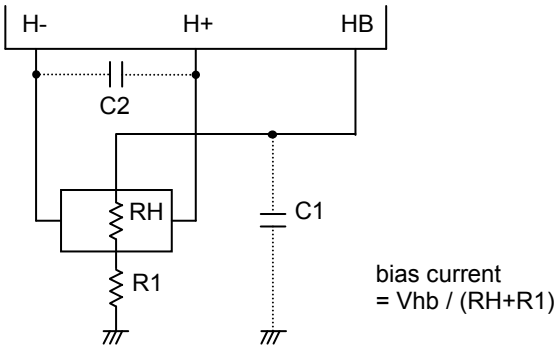


Fig.16 Application near of hall signal

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4) PWM input

Rotation speed of motor can be changed by controlling ON/OFF of the upper output depending on duty of the signal input to PWM terminal.

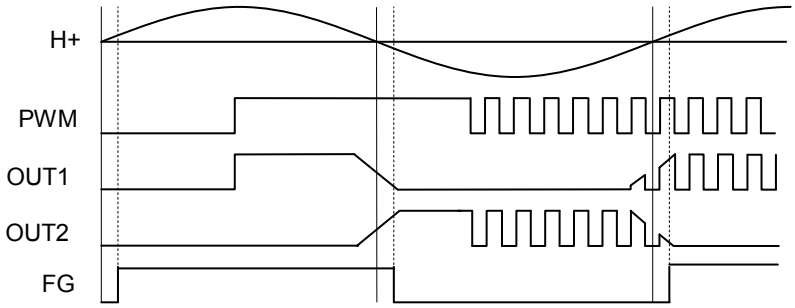


Fig.17 Timing chart in PWM control

When the voltage input to PWM terminal applies H logic : normal operation
L logic : H side output is off, L side output is ON

When PWM terminal is open, H logic is applied. PWM input has hysteresis of 200mV.

5) Quick start, stand-by function

The quick start function is built into this IC. The function can start motor at once regardless of the detection time of the lock protection function when PWM signal is input. Lock protection function is turned off when the time of PWM=L has elapsed more than 1ms in order to disable lock protection function when the motor is stopped by PWM signal.

When H level duty of PWM input signal is close to 0%, lock protection function does not work at input frequency is slower than 1kHz, therefore enter a frequency faster than 2kHz.

In stand-by mode, BD6966NUX cuts the voltage supply of HB terminal off, and fix the FG output state H (output Tr. is off), so that the power consumption of the motor unit is suppressed.

6) Low duty start up function

When motor start-up from stop condition, outputs are driven in PWM 50% duty until detecting motor rotation (33kHz, max 250ms). It doesn't depend on input PWM signal (except 0% duty). Even if input duty of PWM signal is low, the motor can be started by this function.

Connecting SEL terminal to GND enables low duty start up function.
If you don’t need this function, leave SEL terminal open. Low duty start up function is disabled.

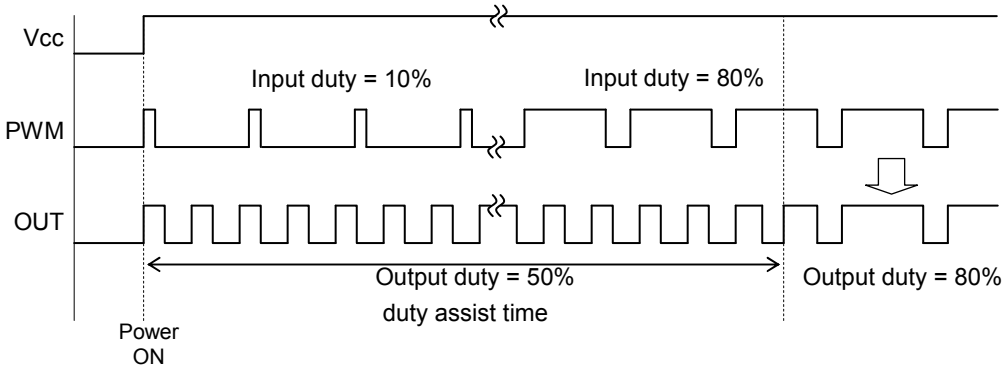


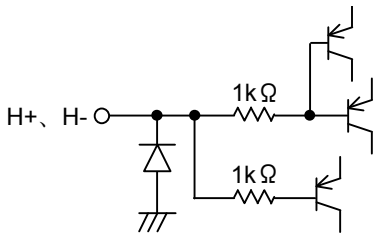
Fig.18 Low duty start up function

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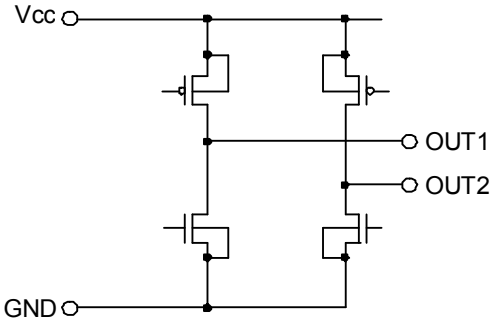
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●Equivalent circuit

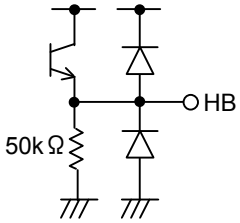
1) Hall input terminal



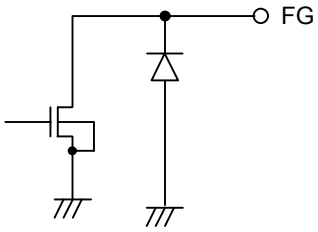
2) Motor output terminal



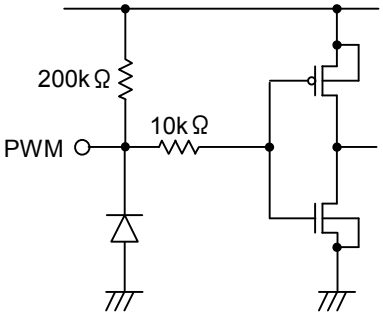
3) Hall bias terminal



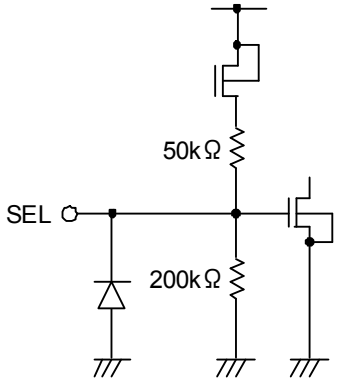
4) FG output terminal



5) PWM signal input terminal



6) SEL terminal



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●**Safety measure**

1) Reverse connection protection diode

Reverse connection of power results in IC destruction as shown in Fig.19. When reverse connection is possible, reverse connection destruction preventive diode must be added between power supply and Vcc.

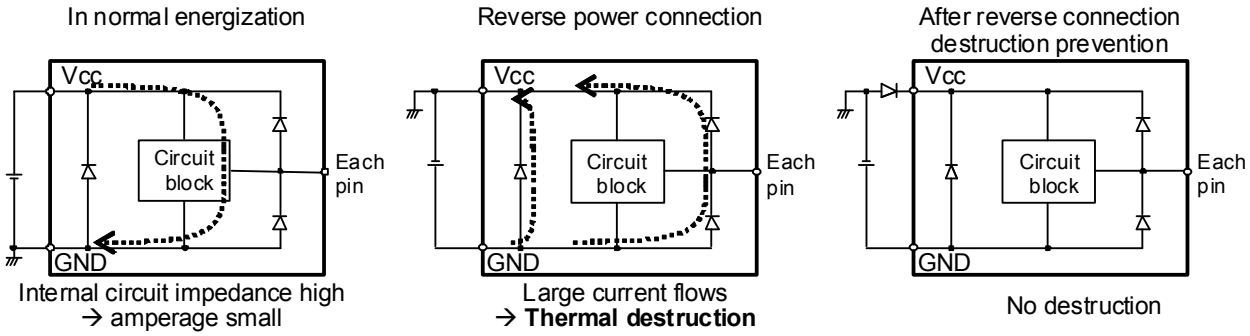


Fig.19 Flow of current when power is connected reversely

2) Measure against Vcc voltage rise by back electromotive force

Back electromotive force (Back EMF) generates regenerative current to power supply. However, when reverse connection protection diode is connected, Vcc voltage rises because no route is available for regenerating to power.

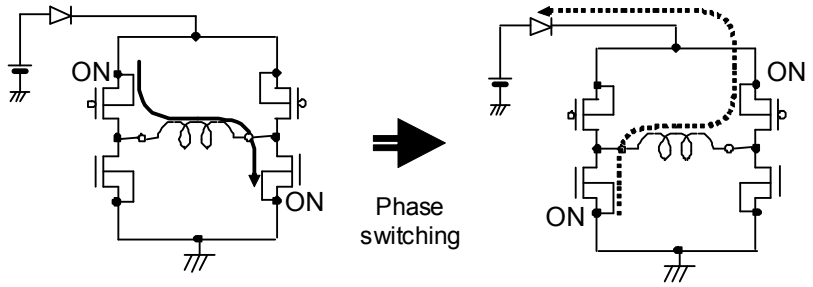
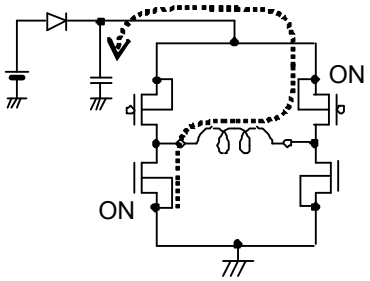


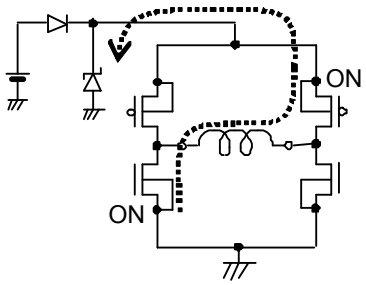
Fig.20 Vcc voltage rise by back electromotive force

When the absolute maximum rated voltage may be exceeded due to voltage rise by back electromotive force, place (A) Capacitor or (B) Zener diode between Vcc and GND. In addition, also take the measure (A) and (B) as shown in (C) if required.

(A) Capacitor



(B) Zener diode



(C) Capacitor and zener diode

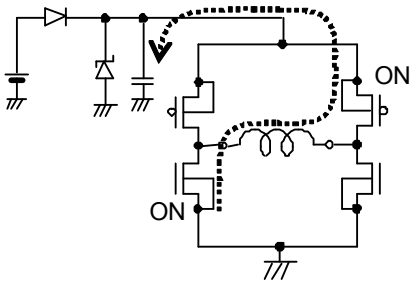


Fig.21 Measure against Vcc voltage rise

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3) Problem of GND line PWM switching
Do not perform PWM switching of GND line because the potential of GND terminal cannot be kept at the minimum.

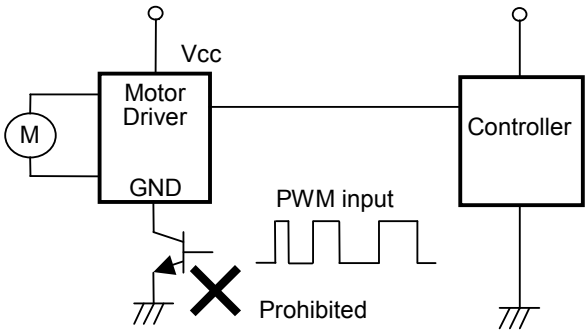


Fig.22 GND Line PWM switching prohibited

4) FG output
FG output is an open drain and requires pull-up resistor.
The IC can be protected by adding resistor R1. An excess of absolute maximum rating, when FG output terminal is directly connected to power supply, could damage the IC.

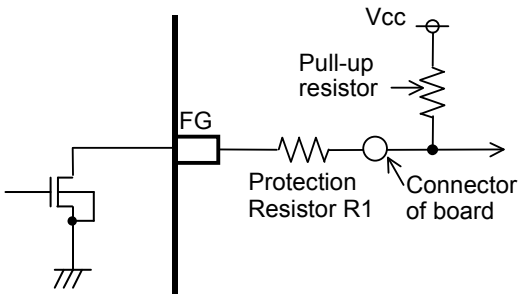
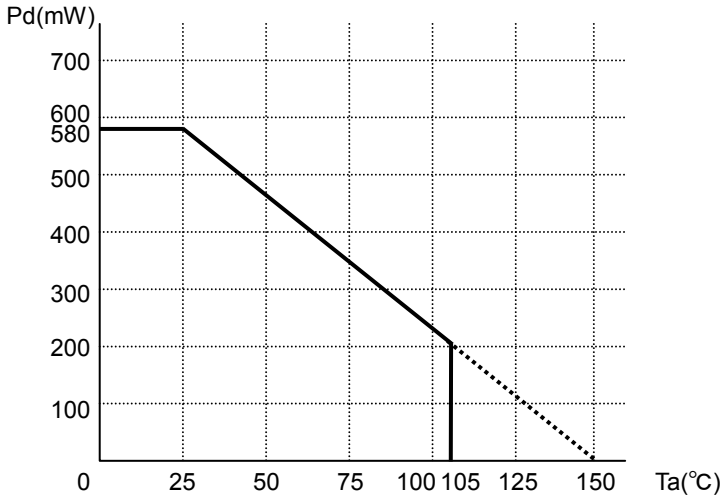


Fig.23 Protection of FG terminal

●Thermal derating curve

Thermal derating curve indicates power that can be consumed by IC with reference to ambient temperature. Power that can be consumed by IC begins to attenuate at certain ambient temperature. this gradient is determined by thermal resistance θja.
Thermal resistance θja depends on chip size, power consumption, package ambient temperature, packaging condition, wind velocity, etc., even when the same package is used. Thermal derating curve indicates a reference value measured at a specified condition. Fig.24 shows a thermal derating curve (Value when mounting FR4 glass epoxy board 74.2 [mm] x 74.2 [mm] x 1.6 [mm] (copper foil area 6.28mm2))



＊ Reduce by 4.64 mW/℃ over 25℃.
(74.2mm x 74.2mm x 1.6mm glass epoxy board (copper foil area 6.28mm^2))

Fig.24 Thermal derating curve

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●Notes for use

1) Absolute maximum ratings
Devices may be destroyed when supply voltage or operating temperature exceeds the absolute maximum ratings. Because the cause of this damage cannot be identified as a short circuit or an open circuit, if any over rated values will expect to exceed the absolute maximum ratings, consider adding circuit protection devices, such as fuses.
2) Connecting the power supply connector backward
Connecting of the power supply in reverse polarity can damage IC. Take precautions when connecting the power supply lines. An external direction diode can be added.
3) Power supply line
Back electromotive force causes regenerated current to power supply line, therefore take a measure such as placing a capacitor between power supply and GND for routing regenerated current. And fully ensure that the capacitor characteristics have no problem before determine a capacitor value. (when applying electrolytic capacitors, capacitance characteristic values are reduced at low temperatures)
4) GND potential
It is possible that the motor output terminal may deflect below GND terminal because of influence by back electromotive force of motor. The potential of GND terminal must be minimum potential in all operating conditions, except that the levels of the motor outputs terminals are under GND level by the back electromotive force of the motor coil. Also ensure that all terminals except GND and motor output terminals do not fall below GND voltage including transient characteristics. Malfunction may possibly occur depending on use condition, environment, and property of individual motor. Please make fully confirmation that no problem is found on operation of IC.
5) Thermal design
Use a thermal design that allows for a sufficient margin in light of the power dissipation(Pd) in actual operating conditions.
6) Inter-pin shorts and mounting errors
Use caution when positioning the IC for mounting on printed circuit boards. The IC may be damaged if there is any connection error or if pins are shorted together.
7) Actions in strong electromagnetic field
Use caution when using the IC in the presence of a strong electromagnetic field as doing so may cause the IC to malfunction.
8) ASO
When using the IC, set the output transistor so that it does not exceed absolute maximum rations or ASO.
9) Thermal shut down circuit
The IC incorporates a built-in thermal shutdown circuit (TSD circuit). Operation temperature is 175ºC (typ.) and has a hysteresis width of 25ºC (typ.). When IC chip temperature rises and TSD circuit works, the output terminal becomes an open state. TSD circuit is designed only to shut the IC off to prevent thermal runaway. It is not designed to protect the IC or guarantee its operation. Do not continue to use the IC after operation this circuit or use the IC in an environment where the operation of this circuit is assumed.
10) Testing on application boards
When testing the IC on an application board, connecting a capacitor to a pin with low impedance subjects the IC to stress. Always discharge capacitors after each process or step. Always turn the IC's power supply off before connecting it to or removing it from a jig or fixture during the inspection process. Ground the IC during assembly steps as an antistatic measure. Use similar precaution when transporting or storing the IC.
11) GND wiring pattern
When using both small signal and large current GND patterns, it is recommended to isolate the two ground patterns, placing a single ground point at the ground potential of application so that the pattern wiring resistance and voltage variations caused by large currents do not cause variations in the small signal ground voltage. Be careful not to change the GND wiring pattern of any external components, either.
12) Capacitor between output and GND
When a large capacitor is connected between output and GND, if Vcc is shorted with 0V or GND for some cause, it is possible that the current charged in the capacitor may flow into the output resulting in destruction. Keep the capacitor between output and GND below 100uF.
13) IC terminal input
When Vcc voltage is not applied to IC, do not apply voltage to each input terminal. When voltage above Vcc or below GND is applied to the input terminal, parasitic element is actuated due to the structure of IC. Operation of parasitic element causes mutual interference between circuits, resulting in malfunction as well as destruction in the last. Do not use in a manner where parasitic element is actuated.
14) In use
We are sure that the example of application circuit is preferable, but please check the character further more in application to a part which requires high precision. In using the unit with external circuit constant changed, consider the variation of externally equipped parts and our IC including not only static character but also transient character and allow sufficient margin in determining.

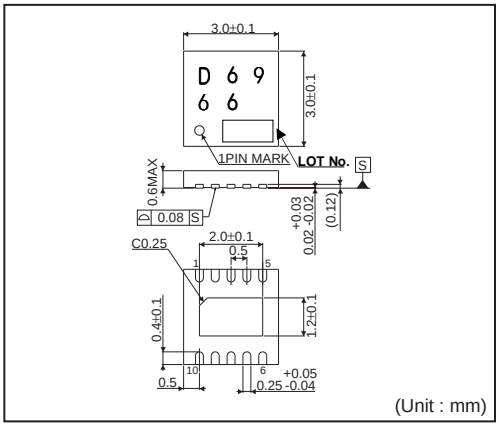
Status of this document
The Japanese version of this document is formal specification. A customer may use this translation version only for a reference to help reading the formal version.
If there are any differences in translation version of this document formal version takes priority

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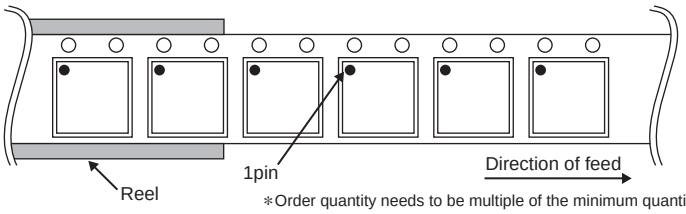
●Physical Dimension

VSON010X3030



<Tape and Reel information>

Tape	Embossed carrier tape
Quantity	4000pcs
Direction of feed	E2 (The direction is the 1pin of product is at the upper left when you hold reel on the left hand and you pull out the tape on the right hand)



∗Order quantity needs to be multiple of the minimum quantity.

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Notice

Precaution on using ROHM Products

1. Our Products are designed and manufactured for application in ordinary electronic equipments (such as AV equipment, OA equipment, telecommunication equipment, home electronic appliances, amusement equipment, etc.). If you intend to use our Products in devices requiring extremely high reliability (such as medical equipment (Note 1), transport equipment, traffic equipment, aircraft/spacecraft, nuclear power controllers, fuel controllers, car equipment including car accessories, safety devices, etc.) and whose malfunction or failure may cause loss of human life, bodily injury or serious damage to property ("Specific Applications"), please consult with the ROHM sales representative in advance. Unless otherwise agreed in writing by ROHM in advance, ROHM shall not be in any way responsible or liable for any damages, expenses or losses incurred by you or third parties arising from the use of any ROHM's Products for Specific Applications.

(Note1) Medical Equipment Classification of the Specific Applications

JAPAN	USA	EU	CHINA
CLASSⅢ	CLASSⅢ	CLASSⅡb	CLASSⅢ
CLASSⅣ		CLASSⅢ	

2. ROHM designs and manufactures its Products subject to strict quality control system. However, semiconductor products can fail or malfunction at a certain rate. Please be sure to implement, at your own responsibilities, adequate safety measures including but not limited to fail-safe design against the physical injury, damage to any property, which a failure or malfunction of our Products may cause. The following are examples of safety measures:
   [a] Installation of protection circuits or other protective devices to improve system safety
   [b] Installation of redundant circuits to reduce the impact of single or multiple circuit failure

3. Our Products are designed and manufactured for use under standard conditions and not under any special or extraordinary environments or conditions, as exemplified below. Accordingly, ROHM shall not be in any way responsible or liable for any damages, expenses or losses arising from the use of any ROHM's Products under any special or extraordinary environments or conditions. If you intend to use our Products under any special or extraordinary environments or conditions (as exemplified below), your independent verification and confirmation of product performance, reliability, etc, prior to use, must be necessary:
   [a] Use of our Products in any types of liquid, including water, oils, chemicals, and organic solvents
   [b] Use of our Products outdoors or in places where the Products are exposed to direct sunlight or dust
   [c] Use of our Products in places where the Products are exposed to sea wind or corrosive gases, including Cl_2, H_2S, NH_3, SO_2, and NO_2
   [d] Use of our Products in places where the Products are exposed to static electricity or electromagnetic waves
   [e] Use of our Products in proximity to heat-producing components, plastic cords, or other flammable items
   [f] Sealing or coating our Products with resin or other coating materials
   [g] Use of our Products without cleaning residue of flux (even if you use no-clean type fluxes, cleaning residue of flux is recommended); or Washing our Products by using water or water-soluble cleaning agents for cleaning residue after soldering
   [h] Use of the Products in places subject to dew condensation

4. The Products are not subject to radiation-proof design.

5. Please verify and confirm characteristics of the final or mounted products in using the Products.

6. In particular, if a transient load (a large amount of load applied in a short period of time, such as pulse. is applied, confirmation of performance characteristics after on-board mounting is strongly recommended. Avoid applying power exceeding normal rated power; exceeding the power rating under steady-state loading condition may negatively affect product performance and reliability.

7. De-rate Power Dissipation (Pd) depending on Ambient temperature (Ta). When used in sealed area, confirm the actual ambient temperature.

8. Confirm that operation temperature is within the specified range described in the product specification.

9. ROHM shall not be in any way responsible or liable for failure induced under deviant condition from what is defined in this document.

Precaution for Mounting / Circuit board design

1. When a highly active halogenous (chlorine, bromine, etc.) flux is used, the residue of flux may negatively affect product performance and reliability.

2. In principle, the reflow soldering method must be used; if flow soldering method is preferred, please consult with the ROHM representative in advance.

For details, please refer to ROHM Mounting specification

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Precautions Regarding Application Examples and External Circuits

1. If change is made to the constant of an external circuit, please allow a sufficient margin considering variations of the characteristics of the Products and external components, including transient characteristics, as well as static characteristics.

2. You agree that application notes, reference designs, and associated data and information contained in this document are presented only as guidance for Products use. Therefore, in case you use such information, you are solely responsible for it and you must exercise your own independent verification and judgment in the use of such information contained in this document. ROHM shall not be in any way responsible or liable for any damages, expenses or losses incurred by you or third parties arising from the use of such information.

Precaution for Electrostatic

This Product is electrostatic sensitive product, which may be damaged due to electrostatic discharge. Please take proper caution in your manufacturing process and storage so that voltage exceeding the Products maximum rating will not be applied to Products. Please take special care under dry condition (e.g. Grounding of human body / equipment / solder iron, isolation from charged objects, setting of Ionizer, friction prevention and temperature / humidity control).

Precaution for Storage / Transportation

1. Product performance and soldered connections may deteriorate if the Products are stored in the places where:
   - [a] the Products are exposed to sea winds or corrosive gases, including Cl2, H2S, NH3, SO2, and NO2
   - [b] the temperature or humidity exceeds those recommended by ROHM
   - [c] the Products are exposed to direct sunshine or condensation
   - [d] the Products are exposed to high Electrostatic

2. Even under ROHM recommended storage condition, solderability of products out of recommended storage time period may be degraded. It is strongly recommended to confirm solderability before using Products of which storage time is exceeding the recommended storage time period.

3. Store / transport cartons in the correct direction, which is indicated on a carton with a symbol. Otherwise bent leads may occur due to excessive stress applied when dropping of a carton.

4. Use Products within the specified time after opening a humidity barrier bag. Baking is required before using Products of which storage time is exceeding the recommended storage time period.

Precaution for Product Label

QR code printed on ROHM Products label is for ROHM's internal use only.

Precaution for Disposition

When disposing Products please dispose them properly using an authorized industry waste company.

Precaution for Foreign Exchange and Foreign Trade act

Since our Products might fall under controlled goods prescribed by the applicable foreign exchange and foreign trade act, please consult with ROHM representative in case of export.

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bd6966nux - Web Page

Buy

Distribution Inventory

Part Number	bd6966nux
Package	VSON010X3030
Unit Quantity	4000
Minimum Package Quantity	4000
Packing Type	Taping
Constitution Materials List	inquiry
RoHS	Yes

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