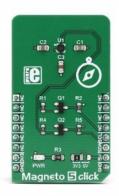


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# Magneto 5 Click





PID: MIKROE-3050

**Magneto 5 click** is a very accurate and reliable magnetic sensor device, which features the MEMSIC MMC34160PJ, a 3-axis magnetic sensor IC. MMC34160PJ IC features an onboard signal processing and I2C communication, simplifying the application development and reducing the host MCU load. It is a very accurate sensor, which can sense the heading direction with the precision of  $\pm 1^{\circ}$ , with the full scale magnetic field detection of  $\pm 16$  G. The device also has a RESET function, which eliminates measurement offset errors and restores the internal magnetic field orientation.

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Featuring onboard signal processing, fast I2C communication, RESET function which restores the sensor accuracy, low power consumption, and high precision with the low noise, this Click board  $^{\text{\tiny M}}$  is an ideal solution for developing portable electronic compass applications, but it is not limited only to directional measurement. It can be also used for the detection of a magnetic field, vehicle detection, and similar applications that rely on an accurate magnetic field sensing in all three axes.

## How does it work?

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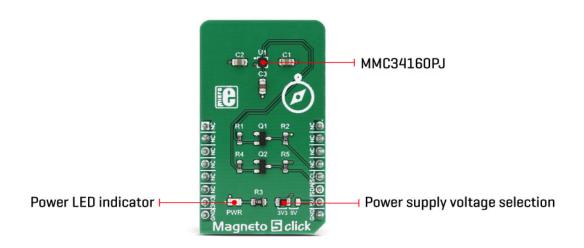




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This Click board™ uses the MMC34160PJ, a 3-axis magnetic sensor IC from MEMSIC Inc. This integrated anisotropic magneto-resistive (AMR) sensor consists of permalloy film, deposited on a silicon wafer. One of the important characteristics of the permalloy (a nickel-iron alloy) is that it can be easily magnetized and demagnetized under the influence of the magnetic field. A strong field is applied during the manufacture, so that the permalloy film becomes magnetized, with the magnetic vector established in a specific direction. When the sensor is affected by an external magnetic field applied perpendicularly to the existing magnetic vector, it will rotate this vector and change its orientation. This will result in a change of the resistance of the permalloy, which varies with the intensity of the applied field. The MEMSIC AMR sensor is incorporated into a Wheatstone bridge configuration to maximize Signal to Noise ratio. This way, the influence of the external field can be measured.



The resulting characteristics of this sensor IC, are impressive: it can sense the heading direction with the accuracy of  $\pm 1^{\circ}$ , it has a high SNR with only 1.5 mG of total RMS noise, a resolution of  $\pm 0.5$  mG when using 16 bit ADC mode, and  $\pm 16$  G full-scale reading.

There are two internal configuration registers, used to set up the device and its working parameters. They allow the sampling resolution to be set (12bit, 14bit, or 16bit), sampling mode (continuous or single shot), the sampling frequency when working in continuous mode, and more. Among other options, these control registers offer a way to trigger SET and RESET event. Before SET or RESET pulses are triggered, an external capacitor connected to the CAP pin has to be recharged. This is also done by setting an appropriate bit in the control register.

The Status register offers the status indication for various events. It signalizes whether the integrated charge pump completed external capacitor recharging process, or if the reading of the internal register was successful, if the measurement was completed successfully, and it indicates the result of the self-test command.

The complete description of the internal registers can be found in the datasheet of the MMC34160PJ sensor IC. However, the included software library offers functions that simplify working with this device, taking care of the proper order of actions that needs to be followed, before reading the X, Y and Z position from the appropriate output registers. It also simplifies

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the reading process itself, providing the measurement values, directly.

To overcome situations where the external field might be too strong (more than 25 G) and disturb the internal magnetic vector of the permalloy film, a SET/RESET function is employed to restore the magnetic vector, by applying a high current pulse to an internal magnetically coupled strap.

The MMC34160PJ uses I2C communication, with the appropriate pins routed to the mikroBUS $^{\rm m}$ . This ensures a reliable operation of the device. In addition, this device uses an SMD jumper, used to select the logic voltage level, allowing interfacing to both 3.3V and 5V MCUs. Two level shifting MOSFETs are used on I2C lines to allow both 3.3V and 5V operation since the sensor IC itself is not 5V tolerant.

## **Specifications**

Туре	Magnetic
Applications	It is an ideal solution for developing portable electronic compass applications, but it can be also used for the detection of a magnetic field, vehicle detection, and similar applications that rely on an accurate magnetic field sensing in all three axes.
On-board modules	MMC34160PJ, a 3-axis magnetic sensor
Key Features	Accurate sensing of the magnetic field in all three axes, SET and RESET functions for the internal magnetic field restoration, on-chip processing functions, can be interfaced with the wide range of both 3.3V and 5V MCUs
Interface	I2C
Feature	No ClickID
Compatibility	mikroBUS™
Click board size	M (42.9 x 25.4 mm)
Input Voltage	3.3V or 5V

## **Pinout diagram**

This table shows how the pinout on **Magneto 5 click** corresponds to the pinout on the mikroBUS $^{\text{m}}$  socket (the latter shown in the two middle columns).

Notes	Pin	of mikro™ BUS				Pin	Notes
	NC	1	AN	PWM	16	NC	
	NC	2	RST	INT	15	NC	
	NC	3	CS	RX	14	NC	
	NC	4	SCK	TX	13	NC	
	NC	5	MISO	SCL	12	SCL	I2C Clock
	NC	6	MOSI	SDA	11	SDA	I2C Data

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Power Supply	+3V3	7	3.3V	5V	10	+5V	Power Supply
Ground	GND	8	GND	GND	9	GND	Ground

## **Onboard settings and indicators**

Label	Name	Default	Description
LD1	PWR	-	Power LED indicator
JP1	3V3, 5V		Logic voltage level
			selection: left position
			3.3V, right position 5V

## Magneto 5 click electrical specifications

Description	Min	Тур	Max	Unit
Magnetic field	-16	-	16	G
measurement				
range on each				
axis				
External	-25	-	25	G
disturbing field				
intensity				
Heading accuracy	-1	-	1	Deg (°)

# Software support

We provide a library for Magneto 5 click on our <u>Libstock page</u>, as well as a demo application (example), developed using MikroElektronika compilers and mikroSDK. The provided click library is mikroSDK standard compliant. The demo application can run on all the main MikroElektronika development boards.

#### **Library Description**

This library provides generic functions for working with the Click board™.

#### Key functions:

- void magneto5 reset( void ); Used to software reset the sensor.
- float magneto5\_getAxisValue(uint8\_t axis, uint8\_t maxResolution); The function returns the calculated Gauss value.
- void magneto5 getAxisData( int16 t \*axisBuffer, uint8 t maxResolution ); Used for the reading of the raw axis data from registers.

#### **Examples Description**

The application is composed of three sections:

- System Initialization Initializes I2C module
- · Application Initialization Initializes driver init and set measurement mode and channel
- Application Task (code snippet) Reads X / Y / Z data axis and logs to USBUART every 1 sec.

The full application code, and ready to use projects can be found on our Libstock page.

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Other mikroE Libraries used in the example:

- Conversions
- I2C
- UART
- C\_String Library

### **Additional notes and information**

Depending on the development board you are using, you may need <u>USB UART click</u>, <u>USB UART 2 click</u> or <u>RS232 click</u> to connect to your PC, for development systems with no UART to USB interface available on the board. The terminal available in all MikroElektronika <u>compilers</u>, or any other terminal application of your choice, can be used to read the message.

#### mikroSDK

This click board is supported by <u>mikroSDK</u> - MikroElektronika Software Development Kit. To ensure proper operation of mikroSDK compliant click board demo applications, mikroSDK should be downloaded from the <u>LibStock</u> and installed for the compiler you are using.

For more information about mikroSDK, visit the official page.

#### Resources

mikroBUS™

mikroSDK

Click board™ Catalog

Click Boards™

#### **Downloads**

Magneto 5 click 2D and 3D files

MMC3416xPJ datasheet

Magneto 5 click schematic

Magneto 5 click example on Libstock

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