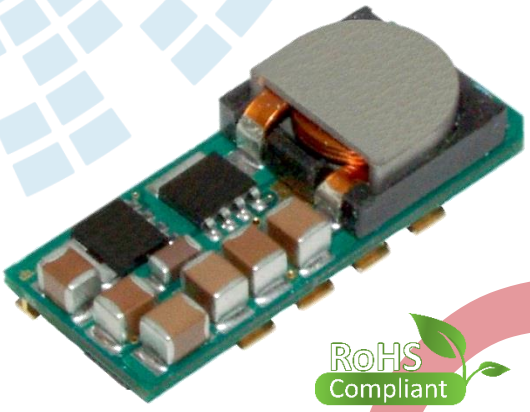
YNC12S20
DC-DC Converter

9.6 – 14 VDC Input; 0.7525 – 5.5 VDC Programmable @ 20 A



RoHS Compliant

ECO

Key Features

- RoHS lead-free solder and lead-solder-exempted products are available
- Delivers up to 20 A (100 W)
- Extended input range 9.6 V – 14 V
- High efficiency (0.94 at 5 V output)
- Surface-mount package
- Industry-standard footprint and pinout
- Small size and low profile: 1.30” x 0.53” x 0.314” (33.02 x 13.46 x 7.98 mm)
- Weight: 0.22 oz [6.12 g]
- Coplanarity less than 0.003”, maximum
- Synchronous Buck Converter topology
- Source and sink capable
- Start-up into pre-biased output
- No minimum load required
- Programmable output voltage via external resistor
- Operating ambient temperature: -40 °C to 85 °C
- Remote output sense
- Remote ON/OFF (Positive or Negative)
- Fixed-frequency operation
- Auto-reset output overcurrent protection
- Auto-reset overtemperature protection
- High reliability, MTBF = TBD Million Hours
- All materials meet UL94, V-0 flammability rating
- Approved to the latest edition and amendment of ITE Safety standards, UL/CSA 60950-1 and IEC60950-1

Bel Power Solutions point-of-load converters are recommended for use with regulated bus converters in an Intermediate Bus Architecture (IBA). The YNC12S20 non-isolated DC-DC converter delivers up to 20 A of output current in an industry-standard surface-mount package. Operating from a 9.6 to 14 VDC input, the YNC12S20 converter is an ideal choice for Intermediate Bus Architectures where point-of-load power delivery is generally a requirement. It provides a resistor-programmable regulated output voltage of 0.7525V to 5.5V.

The Y-Series converters provide exceptional thermal performance, even in high temperature environments with minimal airflow. This is accomplished through the use of circuit, packaging and processing techniques to achieve ultra-high efficiency, excellent thermal management and a very low body profile.

The low body profile and the preclusion of heat sinks minimize impedance to system airflow, thus enhancing cooling for both upstream and downstream devices. The use of 100% automation for assembly, coupled with advanced power electronics and thermal design, results in a product with extremely high reliability.

Applications

- Intermediate Bus Architectures
- Telecommunications
- Data Communications
- Distributed Power Architectures
- Servers, Workstations

Benefits

- High Efficiency – no heat sink required
- Reduces Total Solution Board Area
- Tape and Reel Packing
- Compatible with Pick & Place Equipment
- Minimizes Part Numbers in Inventory

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1. ELECTRICAL SPECIFICATIONS

Conditions: T_A = 25°C, Airflow = 200 LFM (1 m/s), Vin = 12 VDC, Vout = 0.7525 - 5.5 V, unless otherwise specified.

PARAMETER	NOTES	MIN	TYP	MAX	UNITS
Absolute Maximum Ratings					
Input Voltage	Continuous	-0.3		15	VDC
Operating Ambient Temperature		-40		85	°C
Storage Temperature		-55		125	°C
Feature Characteristics					
Switching Frequency			300		kHz
Output Voltage Programming Range[1]	By external resistor, See Trim Table 1	0.7525		5.5	VDC
Remote Sense Compensation[1]				0.5	VDC
Turn-On Delay Time	Full resistive load				
With Vin = (Module Enabled, then Vin applied)	From Vin = Vin(min) to Vo=0.1* Vo(nom)		3		ms
With Enable (Vin = Vin(nom) applied, then enabled)	From enable to Vo= 0.1*Vo(nom)		3		ms
Rise time	From 10% to 90%, full resistive load		4		ms
ON/OFF Control (Positive Logic)[2]	Module Off	-5		0.8	VDC
	Module On	2.4		V_{IN}	VDC
ON/OFF Control (Negative Logic)[2]	Module Off	2.4		V_{IN}	VDC
	Module On	-5		0.8	VDC
Input Characteristics					
Operating Input Voltage Range		9.6	12	14	VDC
Input Under Voltage Lockout	Turn-on Threshold		9		VDC
	Turn-off Threshold		8.5		VDC
Maximum Input Current	20 ADC Out @ 9.6 VDC In				
	V_{OUT} = 5.0 VDC			11.1	ADC
	V_{OUT} = 3.3 VDC			7.6	ADC
	V_{OUT} = 2.5 VDC			5.9	ADC
	V_{OUT} = 2.0 VDC			4.8	ADC
	V_{OUT} = 1.8 VDC			4.4	ADC
	V_{OUT} = 1.5 VDC			3.8	ADC
	V_{OUT} = 1.2 VDC			3.1	ADC
	V_{OUT} = 1.0 VDC			2.7	ADC
	V_{OUT} = 0.7525 VDC			2.2	ADC
Input Stand-by Current (Module disabled)			5		mA
Input No Load Current (Module enabled)	V_{OUT} = 5.0 VDC		80		mA
	V_{OUT} = 3.3 VDC		62		mA
	V_{OUT} = 2.5 VDC		52		mA
	V_{OUT} = 2.0 VDC		47		mA
	V_{OUT} = 1.8 VDC		45		mA
	V_{OUT} = 1.5 VDC		43		mA
	V_{OUT} = 1.2 VDC		41		mA
	V_{OUT} = 1.0 VDC		39		mA
	V_{OUT} = 0.7525 VDC		35		mA
Input Reflected-Ripple Current - i_s	See Fig. F for setup. (BW=20 MHz)		TBD		mA_{P-P}
Input Voltage Ripple Rejection	120 Hz		72		dB

Notes:

1. The output voltage should not exceed 5.5V (taking into account both the programming and remote sense compensation).
2. Converter is on if ON/OFF pin is left open.
3. Note that start-up time is the sum of turn-on delay time and rise time.

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PARAMETER	NOTES	MIN	TYP	MAX	UNITS
Output Characteristics					
Output Voltage Set Point (no load)		-1.5	Vout	+1.5	%Vout
Output Regulation					
Over Line	Full resistive load		2		mV
Over Load	From no load to full load		10		mV
Output Voltage Range	Overall operating input voltage, resistive load and temperature conditions until end of life.	-2.5		+2.5	%Vout
Output Ripple and Noise - 20MHz bandwidth (Fig. F)	Over line, load and temperature				
Peak-to-Peak	V_{OUT} = 0.7525 VDC		10	15	mV_{P-P}
Peak-to-Peak	V_{OUT} = 5.0 VDC		35	50	mV_{P-P}
External Load Capacitance	Plus full load (resistive)				
Min ESR > 1mΩ				1000	µF
Min ESR > 10 mΩ				5000	µF
Output Current Range		0		20	A
Output Current Limit Inception (I_{OUT})			26		A
Output Short-Circuit Current , RMS Value	Short=10 mΩ, continuous		6		A
Dynamic Response					
Load current change from 10A – 20A, di/dt = 5 A/µS	Co = 100µF ceramic + 470 µF POS		140		mV
Settling Time (V_{OUT} < 10% peak deviation)			45		µs
Unloading current change 20A – 10A, di/dt = -5 A/µS	Co = 100 µF ceramic + 470 µF POS		140		mV
Settling Time (V_{OUT} < 10% peak deviation)			45		µs
Efficiency	*Full Load (20a)*				
	V_{OUT} = 5.0 VDC		94		%
	V_{OUT} = 3.3 VDC		91		%
	V_{OUT} = 2.5 VDC		89		%
	V_{OUT} = 2.0 VDC		87		%
	V_{OUT} = 1.8 VDC		86		%
	V_{OUT} = 1.5 VDC		84		%
	V_{OUT} = 1.2 VDC		81.5		%
	V_{OUT} = 1.0 VDC		78		%
	V_{OUT} = 0.7525 VDC		73.5		%

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2. OPERATIONS

2.1. INPUT AND OUTPUT IMPEDANCE

The Y-Series converter should be connected via a low impedance to the DC power source. In many applications, the inductance associated with the distribution from the power source to the input of the converter can affect the stability of the converter. It is recommended to use decoupling capacitors in order to ensure stability of the converter and reduce input ripple voltage. The converter has an internal input capacitance of 40 µF with very low ESR (ceramic capacitors).

In a typical application, low - ESR tantalum or POS capacitors will be sufficient to provide adequate ripple voltage filtering at the input of the converter. However, very low ESR ceramic capacitors 47µF-100 µF are recommended at the input of the converter in order to minimize the input ripple voltage. They should be placed as close as possible to the input pins of the converter.

YNC12S20 has been designed for stable operation with or without external capacitance. Low ESR ceramic capacitors placed as close as possible to the load (Min 47 µF) are recommended for improved transient performance and lower output voltage ripple.

It is important to keep low resistance and low inductance PCB traces for connecting load to the output pins of the converter in order to maintain good load regulation.

2.2. ON/OFF (PIN 1)

The ON/OFF pin is used to turn the power converter on or off remotely via a system signal. There are two remote control options available, positive logic (standard option) and negative logic, and both are referenced to GND. Typical connections are shown in Fig. A.

The positive logic version turns the converter on when the ON/OFF pin is at a logic high or left open, and turns the converter off when at a logic low or shorted to GND.

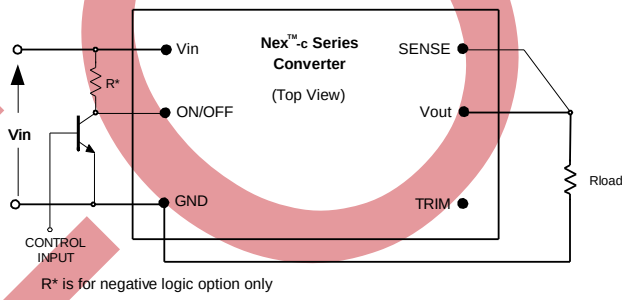


Fig. A: Circuit configuration for ON/OFF function.

The negative logic version turns the converter on when the ON/OFF pin is at logic low or left open, and turns the converter off when the ON/OFF pin is at a logic high or connected to Vin.

ON/OFF pin is internally pulled-up to Vin for a positive logic version, and pulled-down for a negative logic version. A TTL or CMOS logic gate, open collector (open drain) transistor can be used to drive ON/OFF pin. When using open collector (open drain) transistor with a negative logic option, add a pull-up resistor (R*) of 75 kΩ to Vin as shown in Fig. A; This device must be capable of:

- sinking up to 0.2 mA at a low level voltage of ≤ 0.8 V
- sourcing up to 0.25 mA at a high logic level of 2.3V – 5V
- sourcing up to 0.75 mA when connected to Vin.

2.3. REMOTE SENSE (PIN 2)

The remote sense feature of the converter compensates for voltage drops occurring only between Vout pin (Pin 4) of the converter and the load. The SENSE (Pin 2) pin should be connected at the load or at the point where regulation is required (see Fig. B). There is no sense feature on the output GND return pin, where a solid ground plane is recommended to provide low voltage drop.

If remote sensing is not required, the SENSE pin must be connected to the Vout pin (Pin 4) to ensure the converter will regulate at the specified output voltage. If these connections are not made, the converter will deliver an output voltage that is slightly higher than the specified value.

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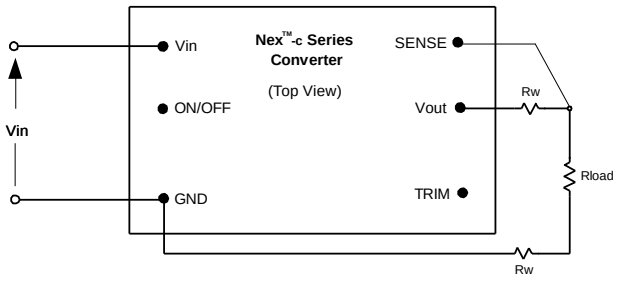


Fig. B: Remote sense circuit configuration.

Because the sense lead carries minimal current, large traces on the end-user board are not required. However, sense traces should be located close to a ground plane to minimize system noise and ensure optimum performance.

When utilizing the remote sense feature, care must be taken not to exceed the maximum allowable output power capability of the converter, equal to the product of the nominal output voltage and the allowable output current for the given conditions.

When using remote sense, the output voltage at the converter can be increased up to 0.5V above the nominal rating in order to maintain the required voltage across the load. Therefore, the designer must, if necessary, decrease the maximum current (originally obtained from the derating curves) by the same percentage to ensure the converter's actual output power remains at or below the maximum allowable output power.

2.4. OUTPUT VOLTAGE PROGRAMMING (PIN 3)

The output voltage can be programmed from 0.7525V to 5.5V by connecting an external resistor between TRIM pin (Pin 3) and GND pin (Pin 5); see Fig. C.

A trim resistor, R_{TRIM}, for a desired output voltage can be calculated using the following equation:

$$R_{TRIM} = \frac{10.5}{(V_{O\text{-}REQ} - 0.7525)} - 1 \quad [k\Omega]$$

where,

R_{TRIM} = Required value of trim resistor [kΩ]

$V_{O\text{-}REQ}$ = Desired (trimmed) output voltage [V]

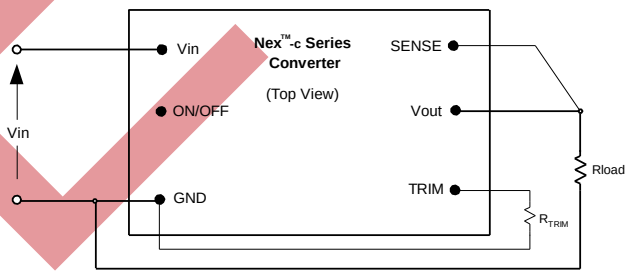


Fig. C: Configuration for programming output voltage.

Note that the tolerance of a trim resistor directly affects the output voltage tolerance. It is recommended to use standard 1% or 0.5% resistors; for tighter tolerance, two resistors in parallel are recommended rather than one standard value from Table 1.

The ground pin of the trim resistor should be connected directly to the converter GND pin (Pin 5) with no voltage drop in between. Table 1 provides the trim resistor values for popular output voltages.

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$V_{O\text{-}REG}$ [V]	R_{TRIM} [kΩ]	The Closest Standard Value [kΩ]
0.7525	open	
1.0	41.2	41.2
1.2	22.46	22.6
1.5	13.0	13.0
1.8	9.0	9.09
2.0	7.4	7.32
2.5	5.0	4.99
3.3	3.12	3.09
5.0	1.47	1.47
5.5	1.21	1.21

Table 1: Trim Resistor Value

The output voltage can be also programmed by external voltage source. To make trimming less sensitive, a series external resistor Rext is recommended between the TRIM pin and the programming voltage source. Control Voltage can be calculated by the formula:

$$V_{CTRL} = 0.7 - \frac{(1+R_{EXT})(V_{O\text{-}REQ} - 0.7525)}{15} \quad [V]$$

where,

V_{CTRL} = Control voltage [V]

R_{EXT} = External resistor between TRIM pin and voltage source; the value can be chosen depending on the required output voltage range [kΩ].

Control voltages with R_{EXT} = 0 and R_{EXT} = 15k are shown in Table 2.

$V_{O\text{-}REG}$ [V]	V_{CTRL} (R_{EXT} = 0)	V_{CTRL}(R_{EXT} = 15k)
0.7525	0.700	0.700
1.0	0.684	0.436
1.2	0.670	0.223
1.5	0.650	-0.097
1.8	0.630	-0.417
2.0	0.617	-0.631
2.5	0.584	-1.164
3.3	0.530	-2.017
5.0	0.417	-3.831
5.5	0.384	-4.364

Table 2: Control Voltage [VDC]

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3. PROTECTION FEATURES

3.1. INPUT UNDERVOLTAGE LOCKOUT

Input undervoltage lockout is standard with this converter. The converter will shut down when the input voltage drops below a pre-determined voltage; it will start automatically when Vin returns to a specified range.

The input voltage must be at least 9.6V (typically 9V) for the converter to turn on. Once the converter has been turned on, it will shut off when the input voltage drops below typically 8.5V.

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3.2. OUTPUT OVERCURRENT PROTECTION (OCP)

The converter is protected against overcurrent and short-circuit conditions. Upon sensing an over-current condition (see Fig. D), the converter will enter hiccup mode. Once the overload or short circuit condition is removed, Vout will return to nominal value.

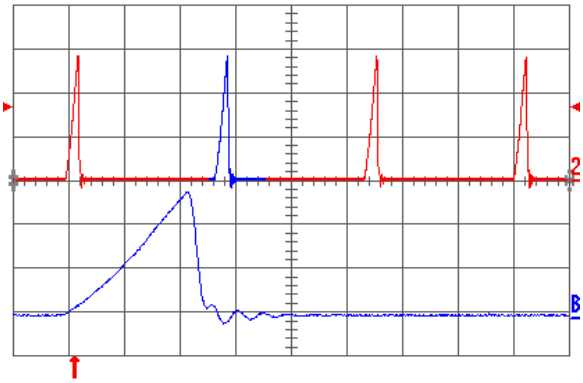


Fig. D: Output short circuit current (10 A/div) (RLOAD= 10 mOhm) for Vout = 5.0 V Time scale: 1 ms/div.; Bottom trace: Zoomed current with time scale 0.1 ms/div.

3.3. OVERTEMPERATURE PROTECTION (OTP)

The converter will shut down under an overtemperature condition to protect itself from overheating caused by operation outside the thermal derating curves, or operation in abnormal conditions such as system fan failure. After the converter has cooled to a safe operating temperature, it will automatically restart.

3.4. SAFETY REQUIREMENTS

The converter meets North American and International safety regulatory requirements per UL60950 and EN60950. The maximum DC voltage between any two pins is Vin under all operating conditions. Therefore, the unit has ELV (extra low voltage) output; it meets SELV requirements under the condition that all input voltages are ELV.

The converter is not internally fused. To comply with safety agencies requirements, a recognized fuse with a maximum rating of 20 Amps must be used in series with the input line.

4. CHARACTERIZATION

4.1. GENERAL INFORMATION

The converter has been characterized for many operational aspects, to include thermal derating (maximum load current as a function of ambient temperature and airflow) for vertical and horizontal mounting, efficiency, start-up and shutdown parameters, output ripple and noise, transient response to load step-change, overload, and short circuit.

The figures are numbered as Fig. x.y, where x indicates the different output voltages, and y associates with specific plots (y = 1 for the vertical thermal derating, …). For example, Fig. x.1 will refer to the vertical thermal derating for all the output voltages in general.

The following pages contain specific plots or waveforms associated with the converter. Additional comments for specific data are provided below.

4.2. TEST CONDITIONS

All thermal and efficiency data presented were taken with the converter soldered to a test board, specifically a 0.060” thick printed wiring board (PWB) with four layers. The top and bottom layers were not metalized. The two inner layers, comprising two-ounce copper, were used to provide traces for connectivity to the converter.

The lack of metalization on the outer layers as well as the limited thermal connection ensured that heat transfer from the converter to the PWB was minimized. This provides a worst-case but consistent scenario for thermal derating purposes.

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All measurements requiring airflow were made in vertical and horizontal wind tunnel facilities using Infrared (IR) thermography and thermocouples for thermometry.

Ensuring components on the converter do not exceed their ratings is important to maintaining high reliability. If one anticipates operating the converter at or close to the maximum loads specified in the derating curves, it is prudent to check actual operating temperatures in the application. Thermographic imaging is preferable; if this capability is not available, then thermocouples may be used. It is recommended to use AWG #40 gauge thermocouples to ensure measurement accuracy. Careful routing of the thermocouple leads will further minimize measurement error. Refer to Fig. E for optimum measuring thermocouple location.

4.3. THERMAL DERATING

Load current vs. ambient temperature and airflow rates are given in Figs. x.1 for maximum temperature of 120 °C. Ambient temperature was varied between 25 °C and 85 °C, with airflow rates from 30 to 500 LFM (0.15m/s to 2.5 m/s), and vertical converter mounting. The airflow during the testing is parallel to the short axis of the converter, going from pin 1 and pin 6 to pins 2 – 5.

For each set of conditions, the maximum load current was defined as the lowest of:

(i) The output current at which either any MOSFET temperature did not exceed a maximum specified temperature (120°C) as indicated by the thermographic image, or

(ii) The maximum current rating of the converter (20 A)

During normal operation, derating curves with maximum FET temperature less than or equal to 120 °C should not be exceeded. Temperature on the PCB at the thermocouple location shown in Fig. E should not exceed 120 °C in order to operate inside the derating curves.

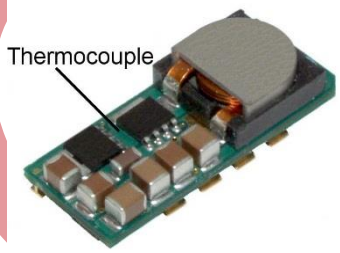


Fig. E: Location of the thermocouple for thermal testing.

4.4. EFFICIENCY

Figure x.2 shows the efficiency vs. load current plot for ambient temperature of 25 °C, airflow rate of 200 LFM (1 m/s) and input voltages of 9.6 V, 12 V, and 14 V.

4.5. POWER DISSIPATION

Fig. x.3 shows the power dissipation vs. load current plot for Ta = 25 °C, airflow rate of 200 LFM (1 m/s) with vertical mounting and input voltages of 9.6 V, 12 V, and 14 V.

4.6. RIPPLE AND NOISE

The output voltage ripple waveform is measured at full rated load current. Note that all output voltage waveforms are measured across a 1 µF ceramic capacitor.

The output voltage ripple and input reflected ripple current waveforms are obtained using the test setup. See Figure F.

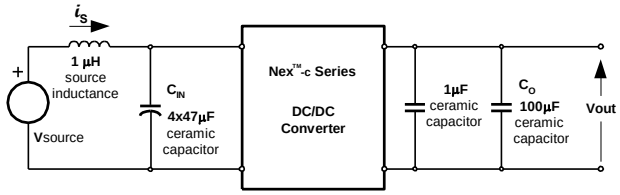


Fig. F: Test setup for measuring input reflected ripple currents, is and output voltage ripple.

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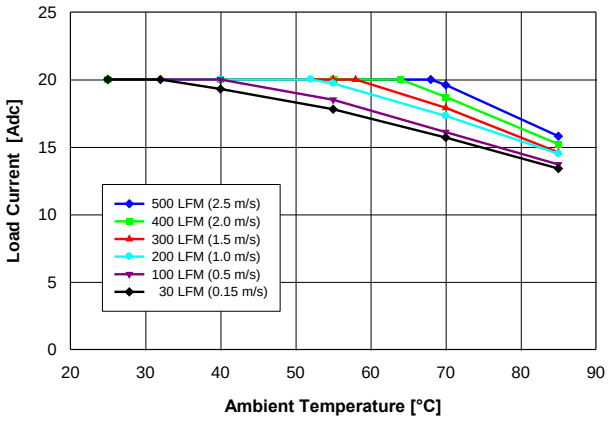


Fig. 5.0V.1: Available load current vs. ambient temperature and airflow rates for Vout = 5.0 V converter mounted vertically with Vin = 12 V, and maximum MOSFET temperature ≤ 120 °C.

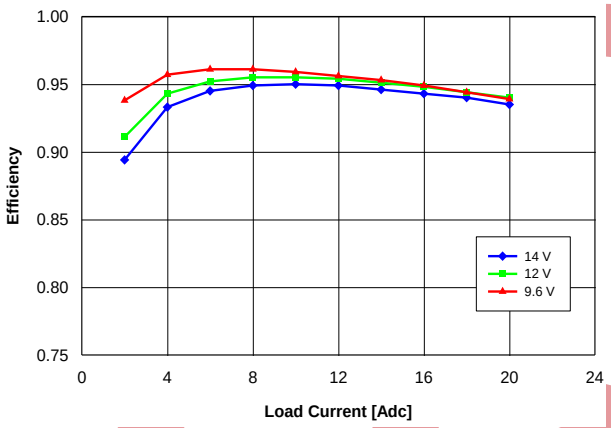


Fig. 5.0V.2: Efficiency vs. load current and input voltage for Vout = 5.0 V converter mounted vertically with air flowing at a rate of 200 LFM (1 m/s) and Ta = 25 °C.

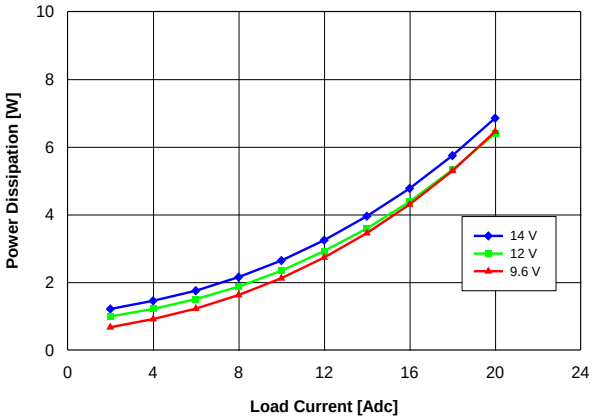


Fig. 5.0V.3: Power loss vs. load current and input voltage for Vout = 5.0 V converter mounted vertically with air flowing at a rate of 200 LFM (1 m/s) and Ta = 25 °C.

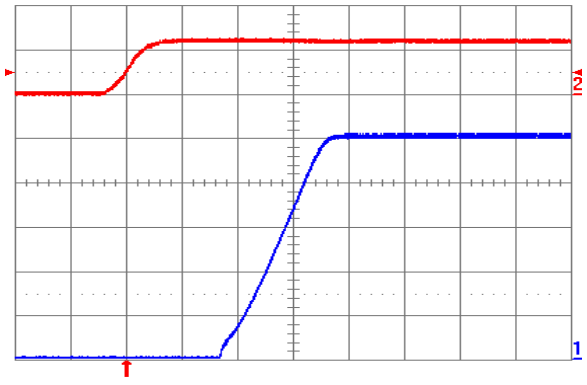


Fig. 5.0V.4: Turn-on transient for Vout = 5.0 V with application of Vin at full rated load current (resistive) and 100 µF external capacitance at Vin = 12 V. Top trace: Vin (10 V/div.); Bottom trace: output voltage (1 V/div.); Time scale: 2 ms/div.

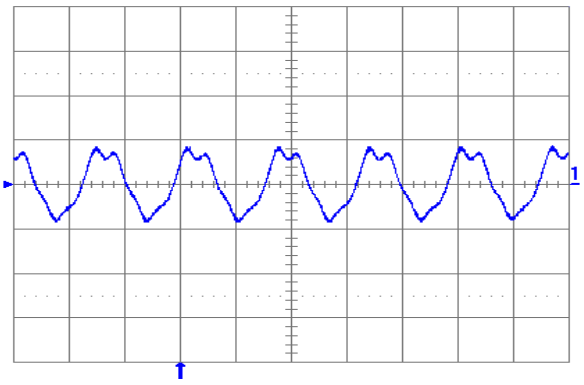


Fig. 5.0V.5: Output voltage ripple (20 mV/div.) at full rated load current into a resistive load with external capacitance 100 µF ceramic + 1 µF ceramic and Vin = 12 V for Vout = 5.0 V. Time scale: 2 µs/div.

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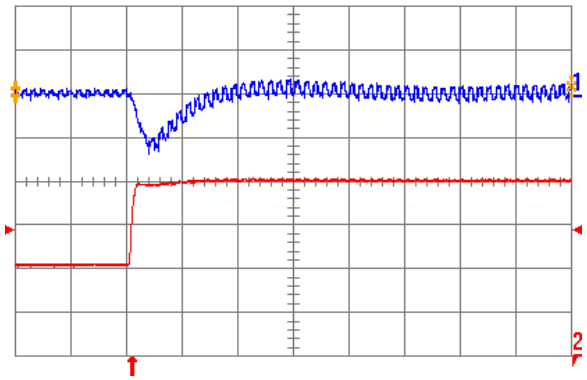


Fig. 5.0V.6: Output voltage response for Vout = 5.0 V to positive load current step change from 10 A to 20 A with slew rate of 5 A/µs at Vin = 12 V. Top trace: output voltage (200 mV/div.); Bottom trace: load current (5 A/div.). Co = 100 µF ceramic. Time scale: 20 µs/div.

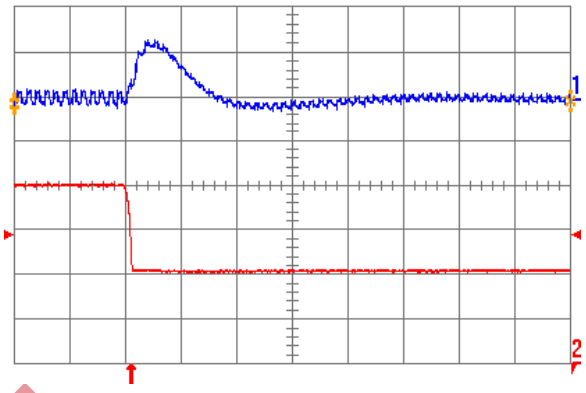


Fig. 5.0V.7: Output voltage response for Vout = 5.0 V to negative load current step change from 20 A to 10 A with slew rate of -5 A/µs at Vin = 12 V. Top trace: output voltage (200 mV/div.); Bottom trace: load current (5 A/div.). Co = 100 µF ceramic. Time scale: 20 µs/div.

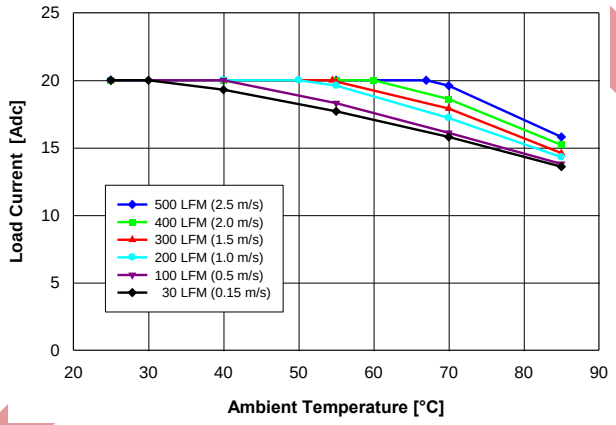


Fig. 3.3V.1: Available load current vs. ambient temperature and airflow rates for Vout = 3.3 V converter mounted vertically with Vin = 12 V, and maximum MOSFET temperature ≤ 120 °C.

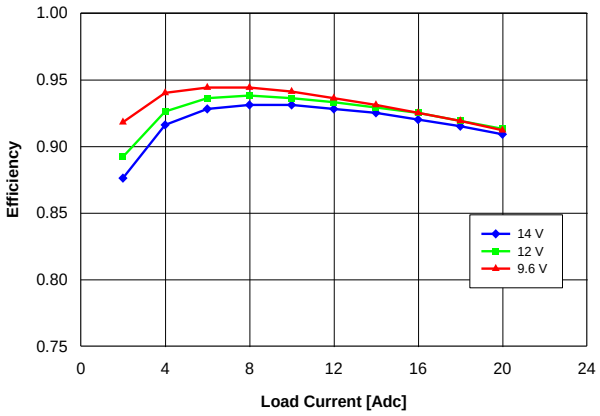


Fig. 3.3V.2: Efficiency vs. load current and input voltage for Vout = 3.3 V converter mounted vertically with air flowing at a rate of 200 LFM (1 m/s) and Ta = 25 °C.

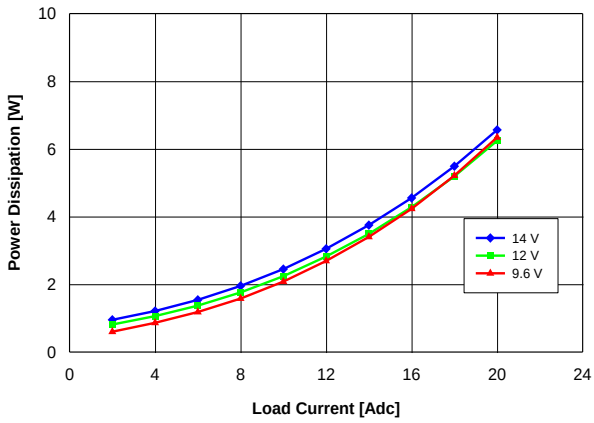


Fig. 3.3V.3: Power loss vs. load current and input voltage for Vout = 3.3 V converter mounted vertically with air flowing at a rate of 200 LFM (1 m/s) and Ta = 25 °C.

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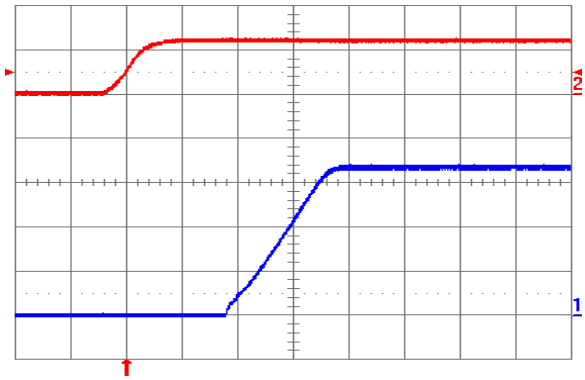


Fig. 3.3V.4: Turn-on transient for Vout = 3.3 V with application of Vin at full rated load current (resistive) and 100 µF external capacitance at Vin = 12 V. Top trace: Vin (10 V/div.); Bottom trace: output voltage (1 V/div.); Time scale: 2 ms/div.

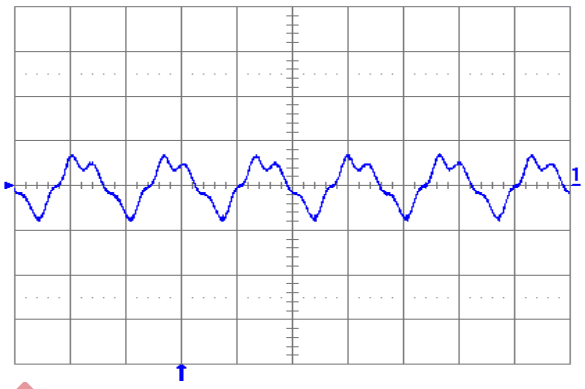


Fig. 3.3V.5: Output voltage ripple (20 mV/div.) at full rated load current into a resistive load with external capacitance 100 µF ceramic + 1 µF ceramic and Vin = 12 V for Vout = 3.3 V. Time scale: 2 µs/div.

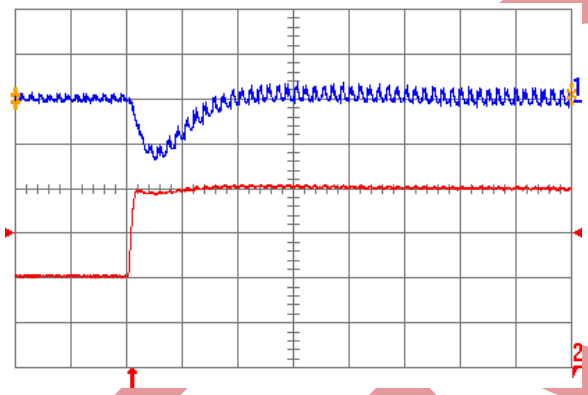


Fig. 3.3V.6: Output voltage response for Vout = 3.3 V to positive load current step change from 10 A to 20 A with slew rate of 5 A/µs at Vin = 12 V. Top trace: output voltage (200 mV/div.); Bottom trace: load current (5 A/div.). Co = 100 µF ceramic. Time scale: 20 µs/div.

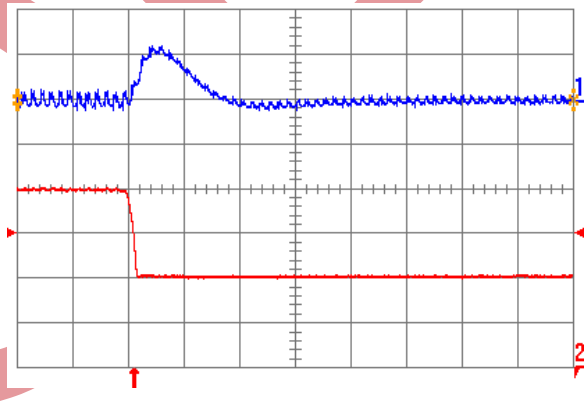


Fig. 3.3V.7: Output voltage response for Vout = 3.3 V to negative load current step change from 20 A to 10 A with slew rate of -5A/µs at Vin = 12 V. Top trace: output voltage (200 mV/div.); Bottom trace: load current (5 A/div.). Co = 100 µF ceramic. Time scale: 20 µs/div.

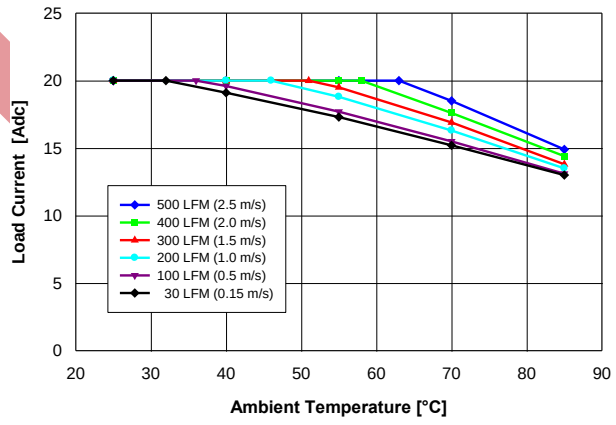


Fig. 2.5V.1: Available load current vs. ambient temperature and airflow rates for Vout = 2.5 V converter mounted vertically with Vin = 12 V, and maximum MOSFET temperature ≤ 120 °C.

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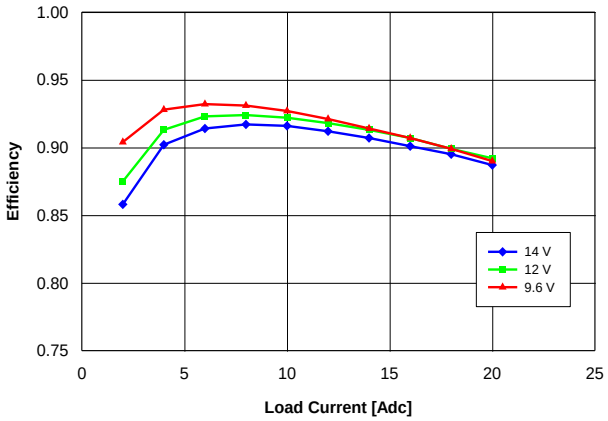


Fig. 2.5V.2: Efficiency vs. load current and input voltage for Vout = 2.5 V converter mounted vertically with air flowing at a rate of 200 LFM (1 m/s) and Ta = 25 °C.

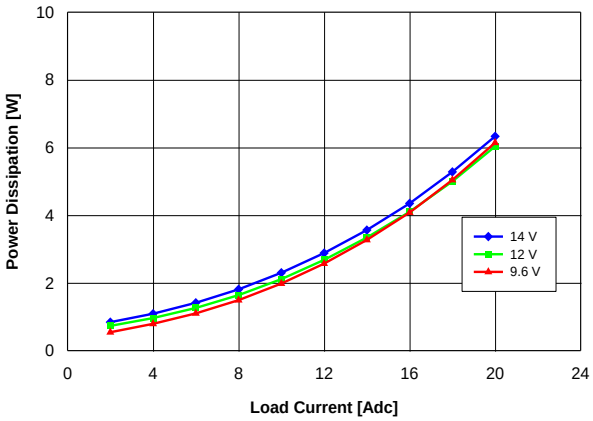


Fig. 2.5V.3: Power loss vs. load current and input voltage for Vout = 2.5 V converter mounted vertically with air flowing at a rate of 200 LFM (1 m/s) and Ta = 25 °C.

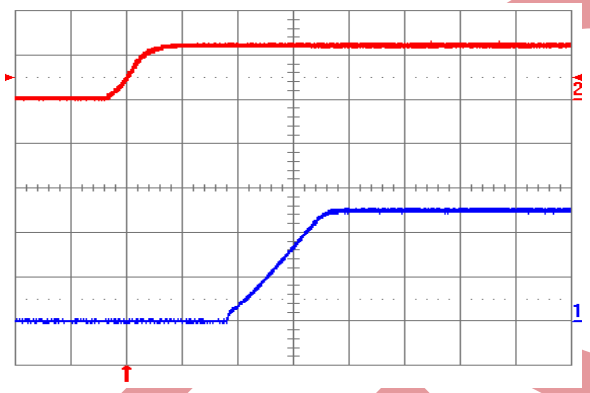


Fig. 2.5V.4: Turn-on transient for Vout = 2.5 V with application of Vin at full rated load current (resistive) and 100 µF external capacitance at Vin = 12V. Top trace: Vin (10 V/div.); Bottom trace: output voltage (1 V/div.); Time scale: 2 ms/div.

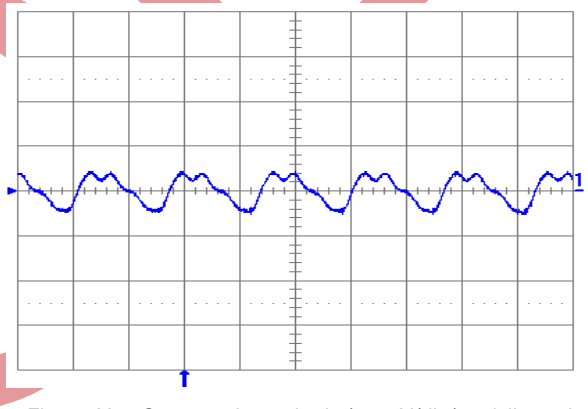


Fig. 2.5V.5: Output voltage ripple (20 mV/div.) at full rated load current into a resistive load with external capacitance 100 µF ceramic + 1 µF ceramic and Vin = 12 V for Vout = 2.5 V. Time scale: 2 µs/div.

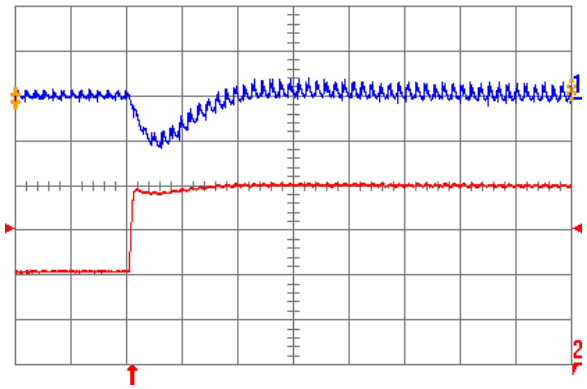


Fig. 2.5V.6: Output voltage response for Vout = 2.5 V to positive load current step change from 10 A to 20 A with slew rate of 5A/µs at Vin = 12 V. Top trace: output voltage (200 mV/div.); Bottom trace: load current (5 A/div.). Co = 100 µF ceramic. Time scale: 20 µs/div.

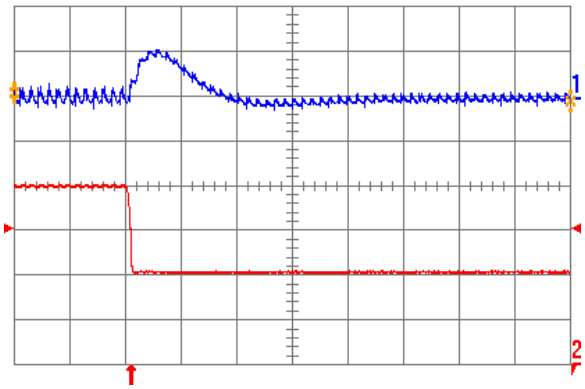


Fig. 2.5V.7: Output voltage response for Vout = 2.5 V to negative load current step change from 20 A to 10 A with slew rate of -5A/µs at Vin = 12 V. Top trace: output voltage (200 mV/div.); Bottom trace: load current (5 A/div.). Co = 100 µF ceramic. Time scale: 20 µs/div.

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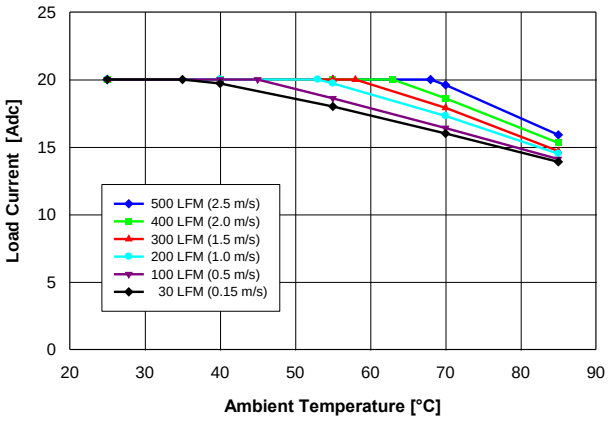


Fig. 2.0V.1: Available load current vs. ambient temperature and airflow rates for Vout = 2.0 V converter mounted vertically with Vin = 12 V, and maximum MOSFET temperature ≤ 120 °C.

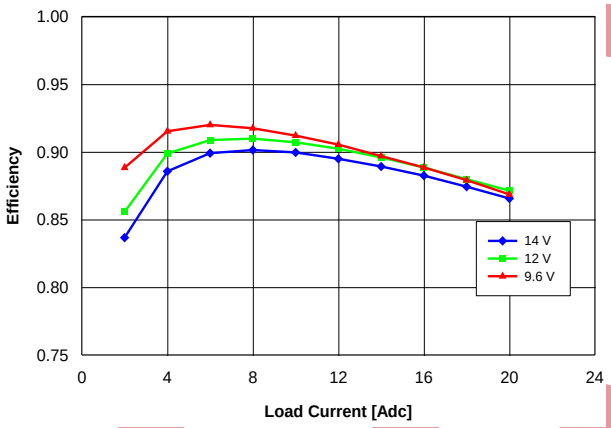


Fig. 2.0V.2: Efficiency vs. load current and input voltage for Vout = 2.0 V converter mounted vertically with air flowing at a rate of 200 LFM (1 m/s) and Ta = 25 °C.

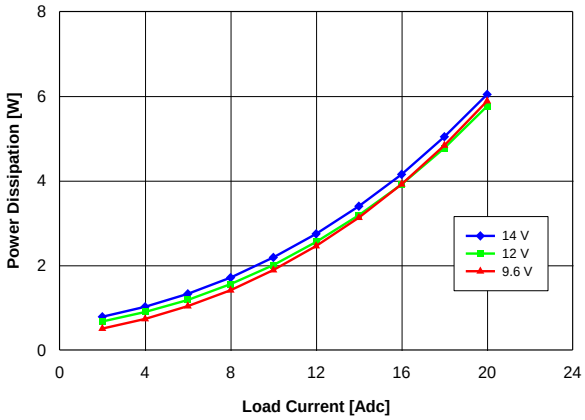


Fig. 2.0V.3: Power loss vs. load current and input voltage for Vout = 2.0 V converter mounted vertically with air flowing at a rate of 200 LFM (1 m/s) and Ta = 25 °C.

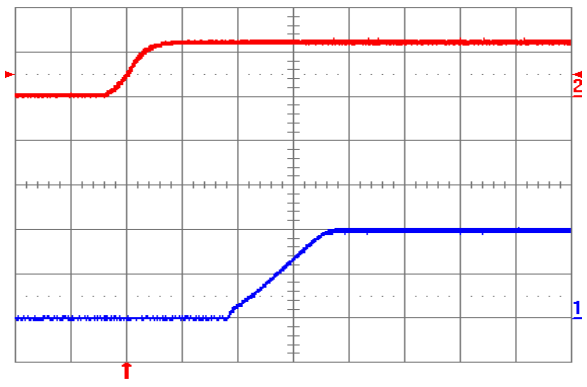


Fig. 2.0V.4: Turn-on transient for Vout = 2.0 V with application of Vin at full rated load current (resistive) and 100 µF external capacitance at Vin = 12 V. Top trace: Vin (10 V/div.); Bottom trace: output voltage (1 V/div.); Time scale: 2 ms/div.

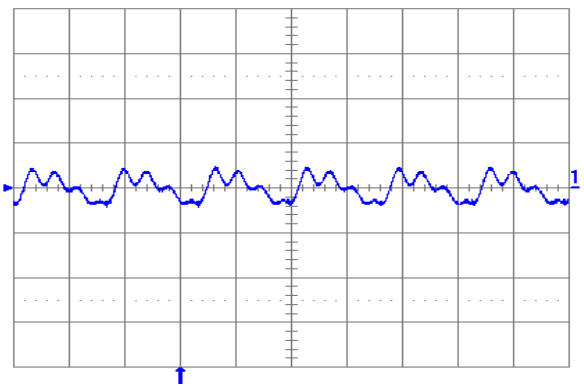


Fig. 2.0V.5: Output voltage ripple (20mV/div.) at full rated load current into a resistive load with external capacitance 100 µF ceramic + 1 µF ceramic and Vin = 12 V for Vout = 2.0 V. Time scale: 2 µs/div.

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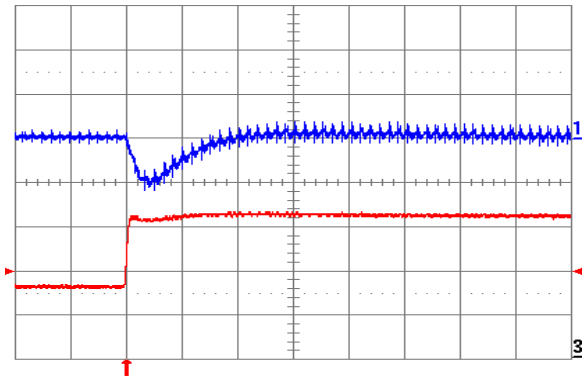


Fig. 2.0V.6: Output voltage response for Vout = 2.0 V to positive load current step change from 10 A to 20 A with slew rate of 5 A/µs at Vin = 12 V. Top trace: output voltage (200 mV/div.); Bottom trace: load current (5 A/div.). Co = 100 µF ceramic. Time scale: 20 µs/div.

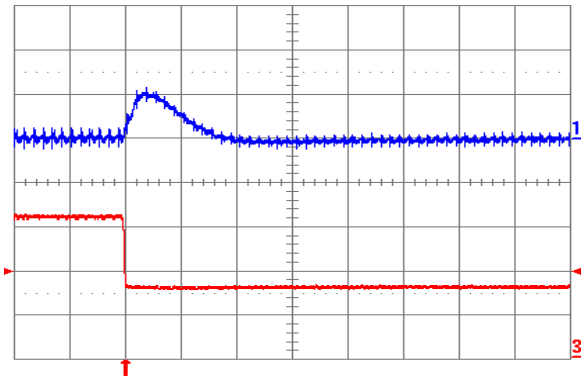


Fig. 2.0V.7: Output voltage response for Vout = 2.0 V to negative load current step change from 20 A to 10 A with slew rate of -5A/µs at Vin = 12 V. Top trace: output voltage (200 mV/div.); Bottom trace: load current (5 A/div.). Co = 100 µF ceramic. Time scale: 20 µs/div.

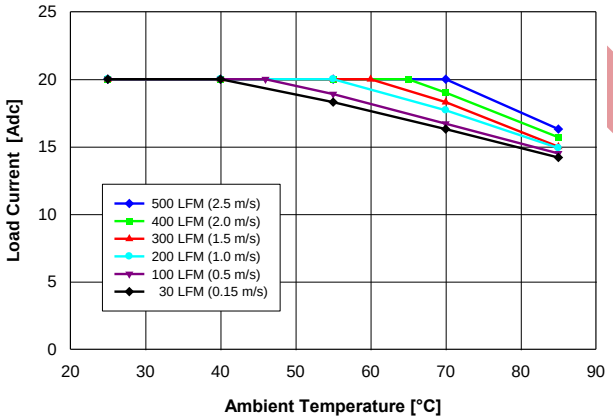


Fig. 1.8V.1: Available load current vs. ambient temperature and airflow rates for Vout = 1.8 V converter mounted vertically with Vin = 12 V, and maximum MOSFET temperature ≤ 120 °C.

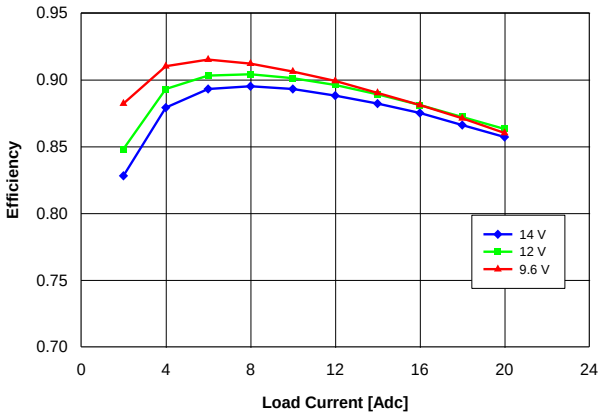


Fig. 1.8V.2: Efficiency vs. load current and input voltage for Vout = 1.8 V converter mounted vertically with air flowing at a rate of 200 LFM (1 m/s) and Ta = 25 °C.

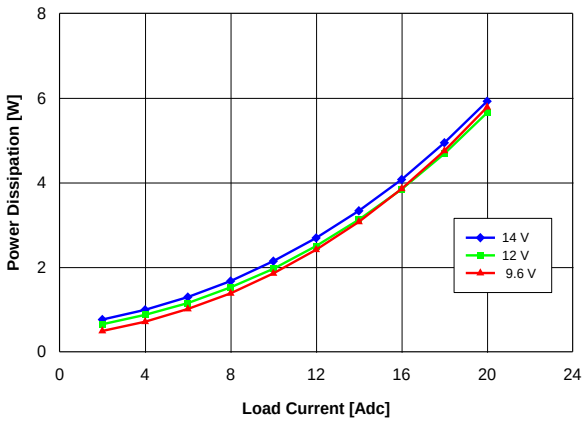


Fig. 1.8V.3: Power loss vs. load current and input voltage for Vout = 1.8 V converter mounted vertically with air flowing at a rate of 200 LFM (1 m/s) and Ta = 25 °C.

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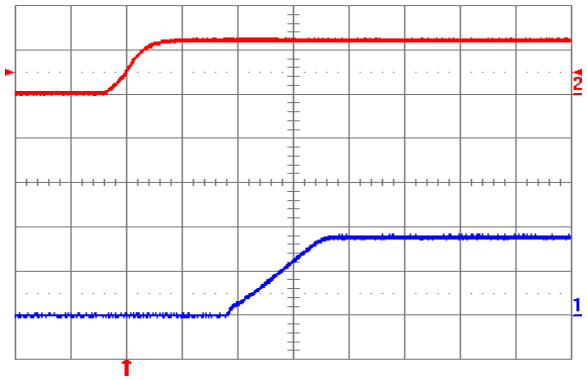


Fig. 1.8V.4: Turn-on transient for Vout = 1.8 V with application of Vin at full rated load current (resistive) and 100 µF external capacitance at Vin = 12 V. Top trace: Vin (10 V/div.); Bottom trace: output voltage (1 V/div.); Time scale: 2 ms/div.

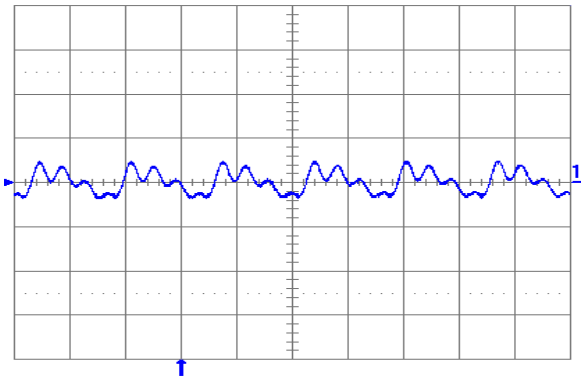


Fig. 1.8V.5: Output voltage ripple (20 mV/div.) at full rated load current into a resistive load with external capacitance 100 µF ceramic + 1 µF ceramic and Vin = 12 V for Vout = 1.8 V. Time scale: 2 µs/div.

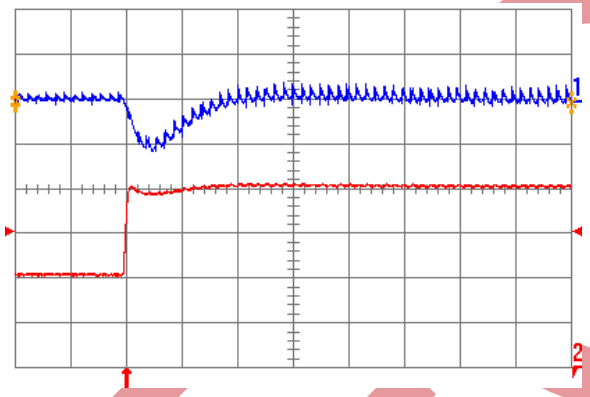


Fig. 1.8V.6: Output voltage response for Vout = 1.8 V to positive load current step change from 10 A to 20 A with slew rate of 5 A/µs at Vin = 12 V. Top trace: output voltage (200 mV/div.); Bottom trace: load current (5 A/div.). Co = 100 µF ceramic. Time scale: 20 µs/div.

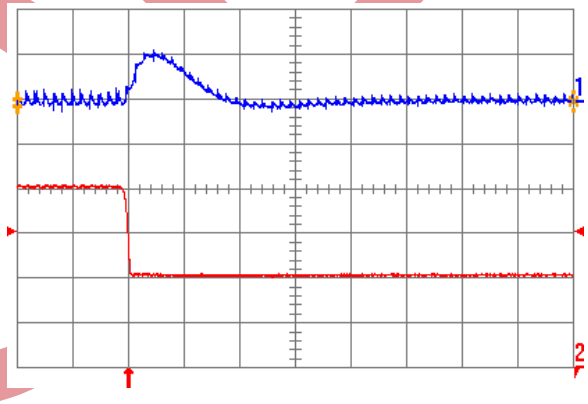


Fig. 1.8V.7: Output voltage response for Vout = 1.8 V to negative load current step change from 20 A to 10 A with slew rate of -5 A/µs at Vin = 12 V. Top trace: output voltage (200 mV/div.); Bottom trace: load current (5 A/div.). Co = 100 µF ceramic. Time scale: 20 µs/div.

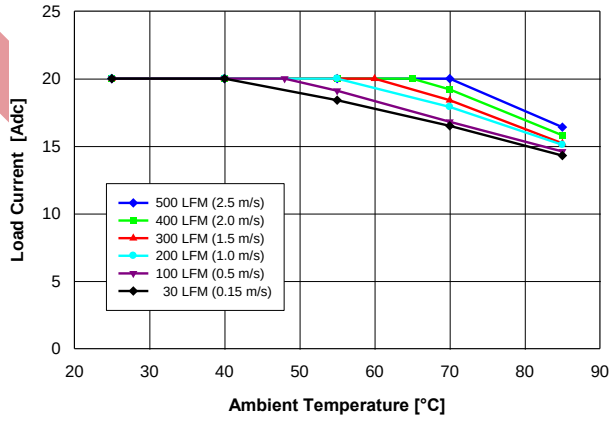


Fig. 1.5V.1: Available load current vs. ambient temperature and airflow rates for Vout = 1.5 V converter mounted vertically with Vin = 12 V, air flowing and maximum MOSFET temperature ≤ 120 °C.

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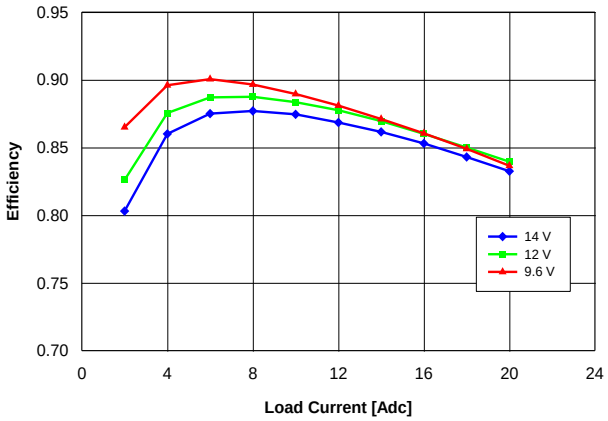


Fig. 1.5V.2: Efficiency vs. load current and input voltage for Vout = 1.5 V converter mounted vertically with air flowing at a rate of 200 LFM (1 m/s) and Ta = 25 °C.

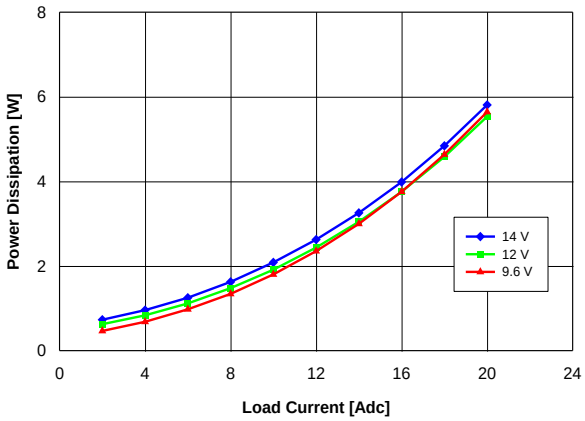


Fig. 1.5V.3: Power loss vs. load current and input voltage for Vout = 1.5V converter mounted vertically with air flowing at a rate of 200 LFM (1 m/s) and Ta = 25 °C.

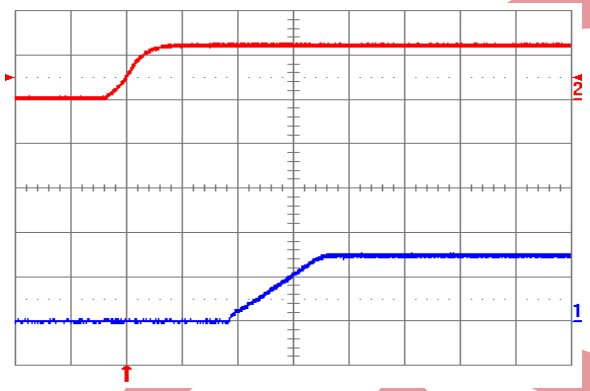


Fig. 1.5V.4: Turn-on transient for Vout = 1.5 V with application of Vin at full rated load current (resistive) and 100 µF external capacitance at Vin = 12 V. Top trace: Vin (10 V/div.); Bottom trace: output voltage (1 V/div.); Time scale: 2 ms/div.

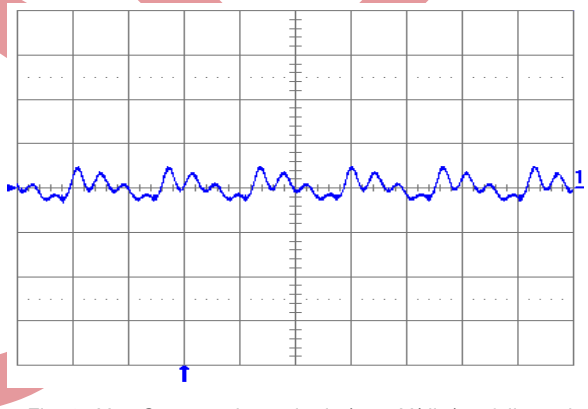


Fig. 1.5V.5: Output voltage ripple (20 mV/div.) at full rated load current into a resistive load with external capacitance 100 µF ceramic + 1 µF ceramic and Vin = 12 V for Vout = 1.5 V. Time scale: 2 µs/div.

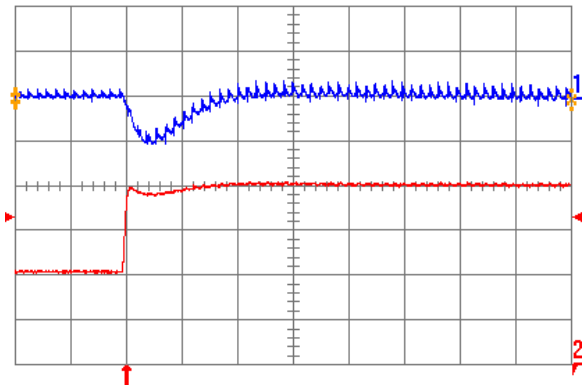


Fig. 1.5V.6: Output voltage response for Vout = 1.5 V to positive load current step change from 10 A to 20 A with slew rate of 5 A/µs at Vin = 12 V. Top trace: output voltage (200 mV/div.); Bottom trace: load current (5 A/div.). Co = 100 µF ceramic. Time scale: 20 µs/div.

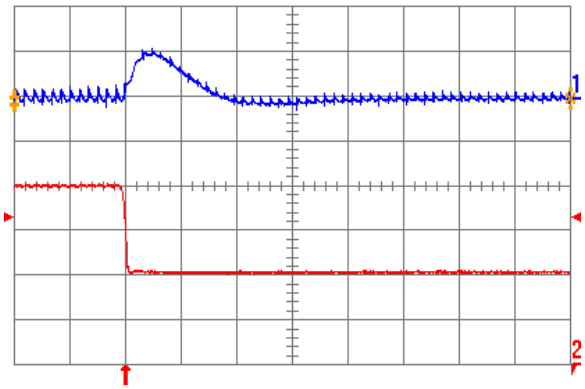


Fig. 1.5V.7: Output voltage response for Vout = 1.5 V to negative load current step change from 20 A to 10 A with slew rate of -5 A/µs at Vin = 12 V. Top trace: output voltage (200 mV/div.); Bottom trace: load current (5 A/div.). Co = 100 µF ceramic. Time scale: 20 µs/div.

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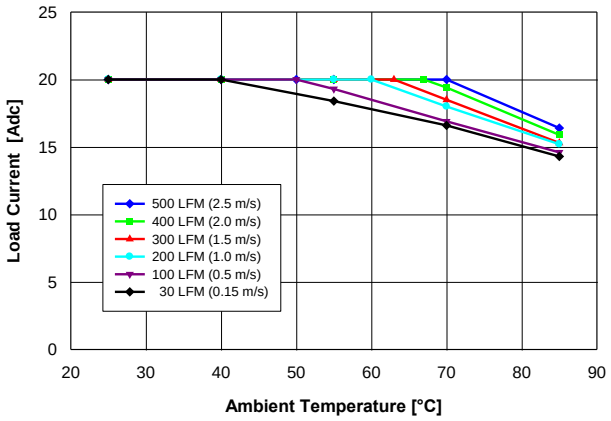


Fig. 1.2V.1: Available load current vs. ambient temperature and airflow rates for Vout = 1.2 V converter mounted vertically with Vin = 12 V, and maximum MOSFET temperature ≤ 120 °C.

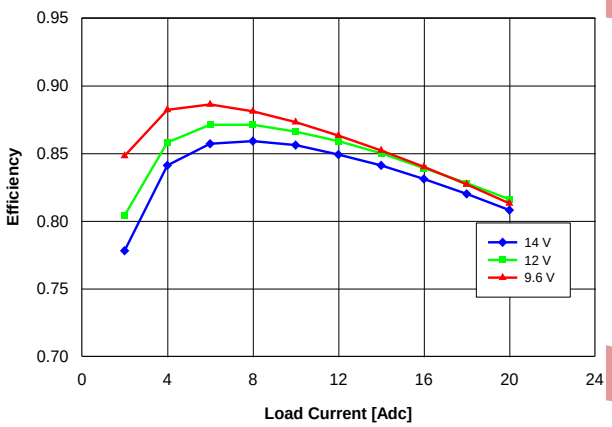


Fig. 1.2V.2: Efficiency vs. load current and input voltage for Vout = 1.2 V converter mounted vertically with air flowing at a rate of 200 LFM (1 m/s) and Ta = 25 °C.

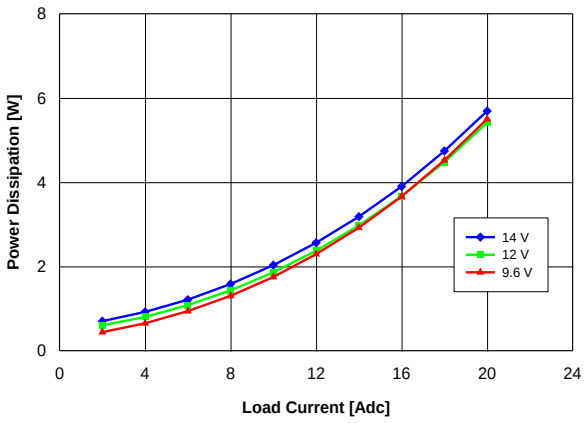


Fig. 1.2V.3: Power loss vs. load current and input voltage for Vout = 1.2 V converter mounted vertically with air flowing at a rate of 200 LFM (1 m/s) and Ta = 25 °C.

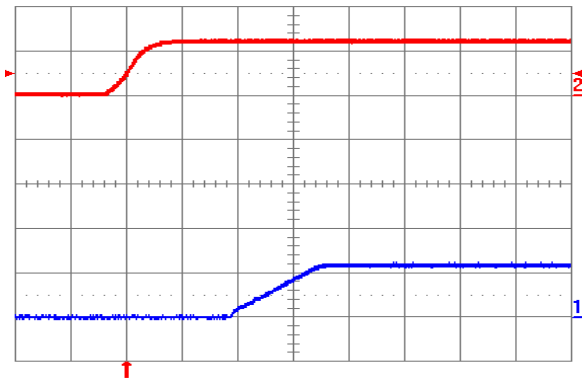


Fig. 1.2V.4: Turn-on transient for Vout = 1.2 V with application of Vin at full rated load current (resistive) and 100 µF external capacitance at Vin = 12 V. Top trace: Vin (10 V/div.); Bottom trace: output voltage (1 V/div.); Time scale: 2 ms/div.

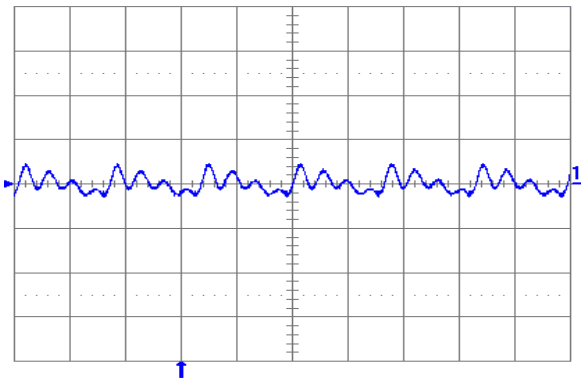


Fig. 1.2V.5: Output voltage ripple (20 mV/div.) at full rated load current into a resistive load with external capacitance 100 µF ceramic + 1 µF ceramic and Vin = 12 V for Vout = 1.2 V. Time scale: 2 µs/div.

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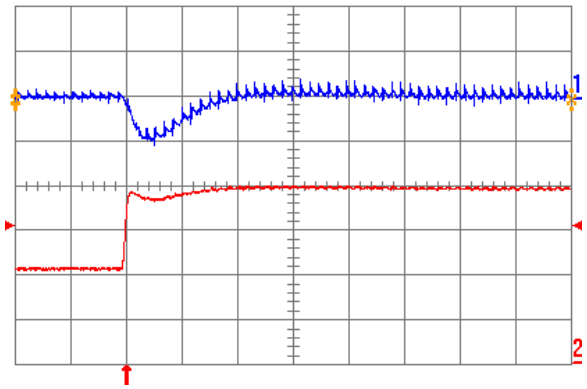


Fig. 1.2V.6: Output voltage response for Vout = 1.2 V to positive load current step change from 10 A to 20 A with slew rate of 5 A/µs at Vin = 12 V. Top trace: output voltage (200 mV/div.); Bottom trace: load current (5 A/div.). Co = 100 µF ceramic. Time scale: 20 µs/div.

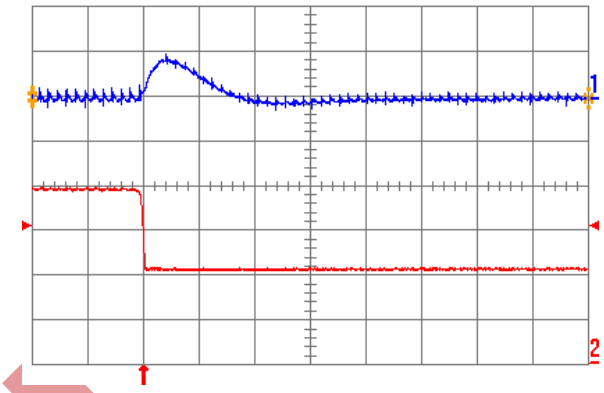


Fig. 1.2V.7: Output voltage response for Vout = 1.2 V to negative load current step change from 20 A to 108 A with slew rate of -5 A/µs at Vin = 12 V. Top trace: output voltage (200 mV/div.); Bottom trace: load current (5 A/div.). Co = 100 µF ceramic. Time scale: 20 µs/div.

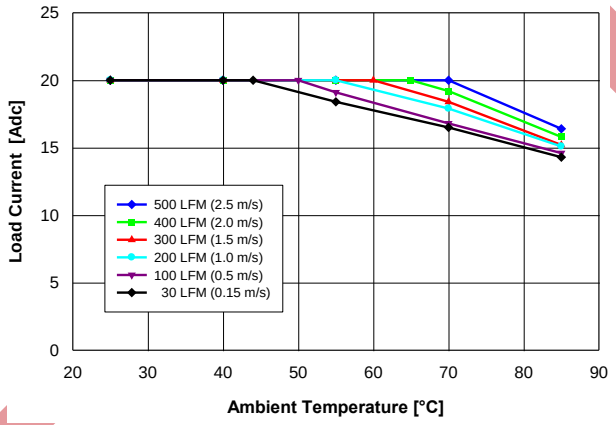


Fig. 1.0V.1: Available load current vs. ambient temperature and airflow rates for Vout = 1.0 V converter mounted vertically with Vin = 12 V, and maximum MOSFET temperature ≤ 120 °C.

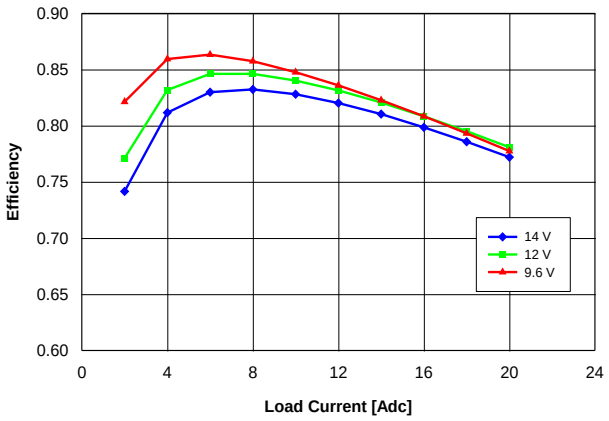


Fig. 1.0V.2: Efficiency vs. load current and input voltage for Vout = 1.0 V converter mounted vertically with air flowing at a rate of 200 LFM (1 m/s) and Ta = 25 °C.

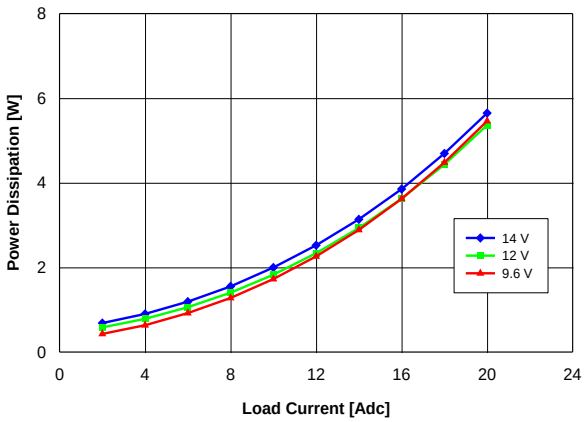


Fig. 1.0V.3: Power loss vs. load current and input voltage for Vout = 1.0 V converter mounted vertically with air flowing at a rate of 200 LFM (1 m/s) and Ta = 25 °C.

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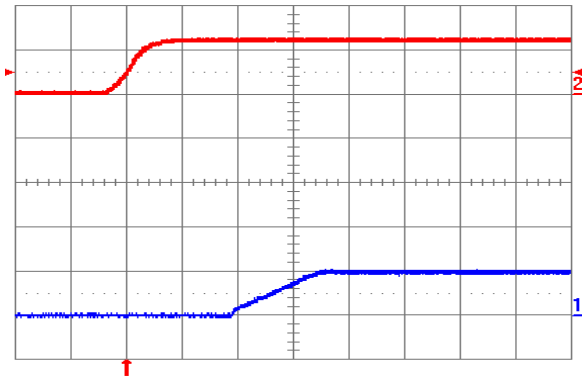


Fig. 1.0V.4: Turn-on transient for Vout = 1.0 V with application of Vin at full rated load current (resistive) and 100 µF external capacitance at Vin = 12 V. Top trace: Vin (10 V/div.); Bottom trace: output voltage (1 V/div.); Time scale: 2 ms/div.

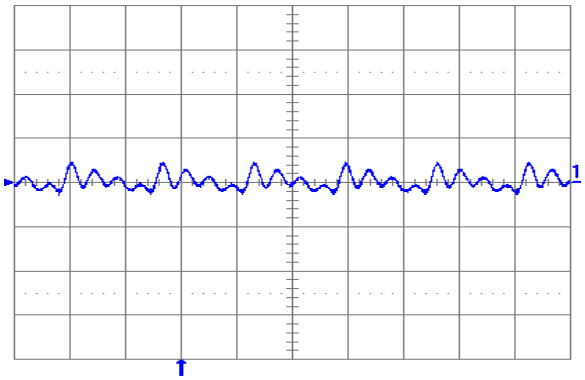


Fig. 1.0V.5: Output voltage ripple (20 mV/div.) at full rated load current into a resistive load with external capacitance 100 µF ceramic + 1 µF ceramic and Vin = 12 V for Vout = 1.0 V. Time scale: 2 µs/div.

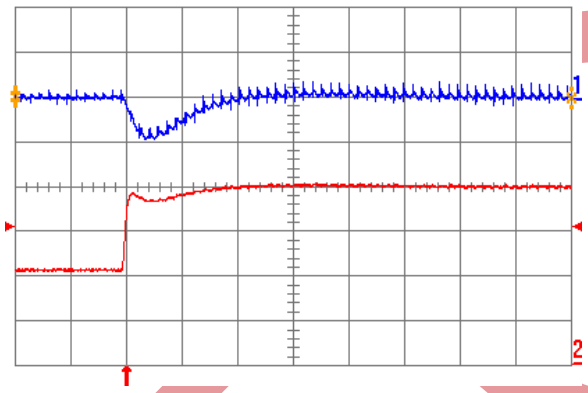


Fig. 1.0V.6: Output voltage response for Vout = 1.0 V to positive load current step change from 10 A to 20 A with slew rate of 5A/µs at Vin = 12 V. Top trace: output voltage (200 mV/div.); Bottom trace: load current (5 A/div.). Co = 100 µF ceramic. Time scale: 20 µs/div.

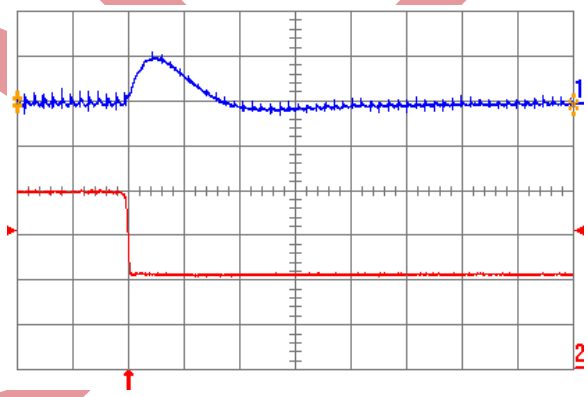


Fig. 1.0V.7: Output voltage response for Vout = 1.0 V to negative load current step change from 20 A to 10 A with slew rate of -5A/µs at Vin = 12 V. Top trace: output voltage (200 mV/div.); Bottom trace: load current (5 A/div.). Co = 100 µF ceramic. Time scale: 20 µs/div.

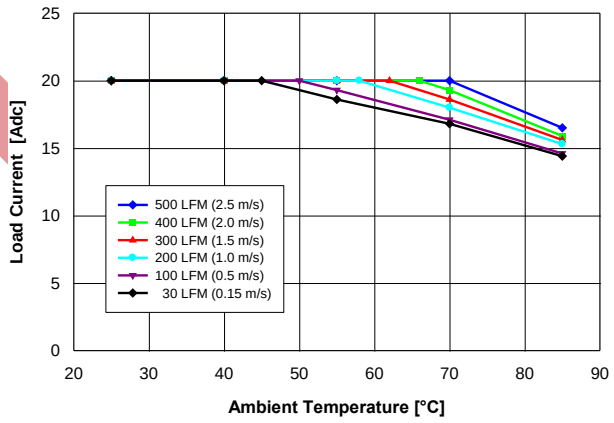


Fig. 0.7525V.1: Available load current vs. ambient temperature and airflow rates for Vout = 1.0 V converter mounted vertically with Vin = 12 V, and maximum MOSFET temperature ≤ 120 °C.

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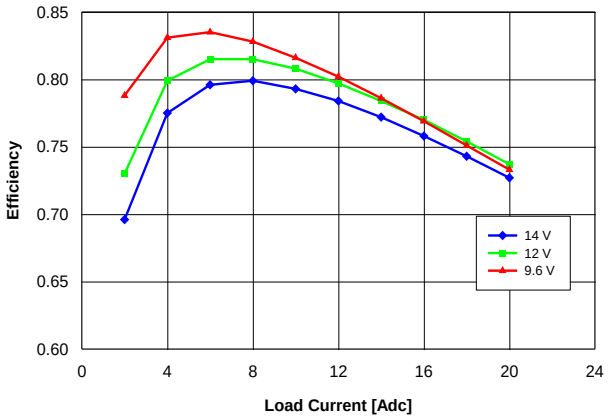


Fig. 0.7525V.2: Efficiency vs. load current and input voltage for Vout = 0.7525V converter mounted vertically with air flowing at a rate of 200 LFM (1 m/s) and Ta = 25 °C.

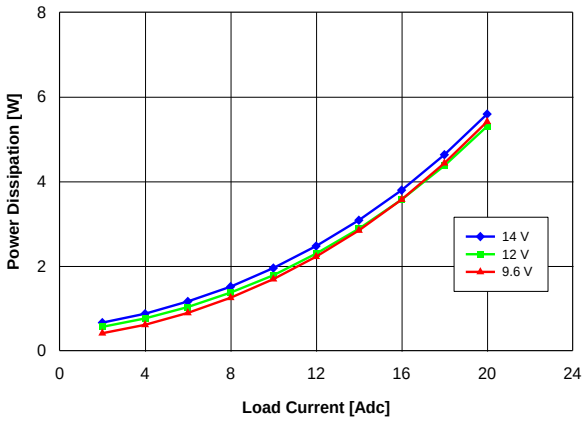


Fig. 0.7525V.3: Power loss vs. load current and input voltage for Vout = 0.7525V converter mounted vertically with air flowing at a rate of 200 LFM (1 m/s) and Ta = 25 °C.

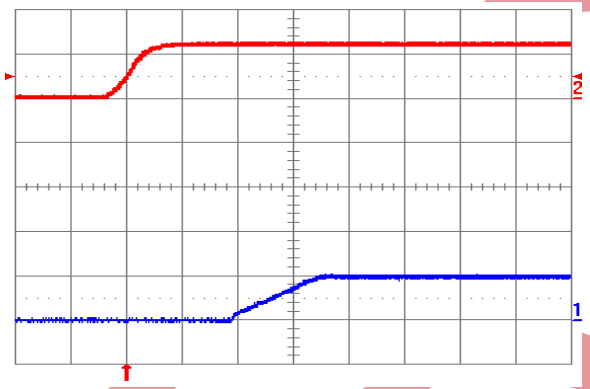


Fig. 0.7525V.4: Turn-on transient for Vout = 0.7525 V with application of Vin at full rated load current (resistive) and 100 µF external capacitance at Vin = 12 V. Top trace: Vin (10 V/div.); Bottom trace: output voltage (1 V/div.); Time scale: 2 ms/div.

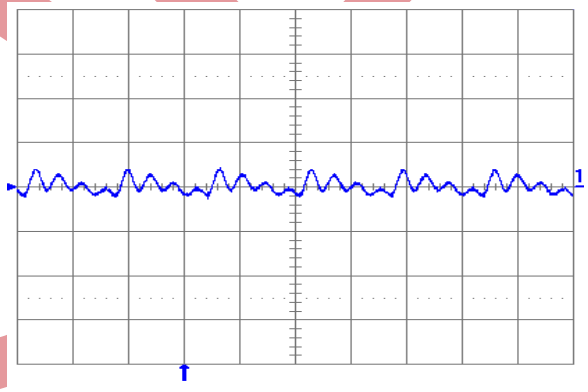


Fig. 0.7525V.5: Output voltage ripple (20 mV/div.) at full rated load current into a resistive load with external capacitance 100 µF ceramic + 1 µF ceramic and Vin = 12 V for Vout = 0.7525V. Time scale: 2 µs/div.

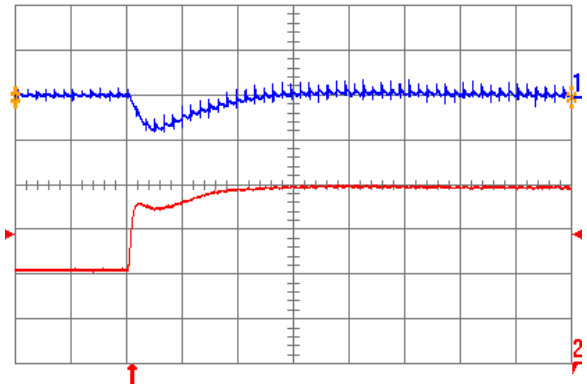


Fig. 0.7525V.6: Output voltage response for Vout = 0.7525 V to positive load current step change from 10 A to 20 A with slew rate of 5A/µs at Vin = 12 V. Top trace: output voltage (200 mV/div.); Bottom trace: load current (5 A/div.). Co = 100 µF ceramic. Time scale: 20 µs/div.

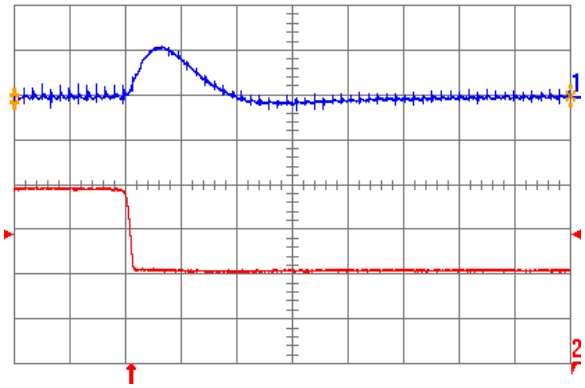


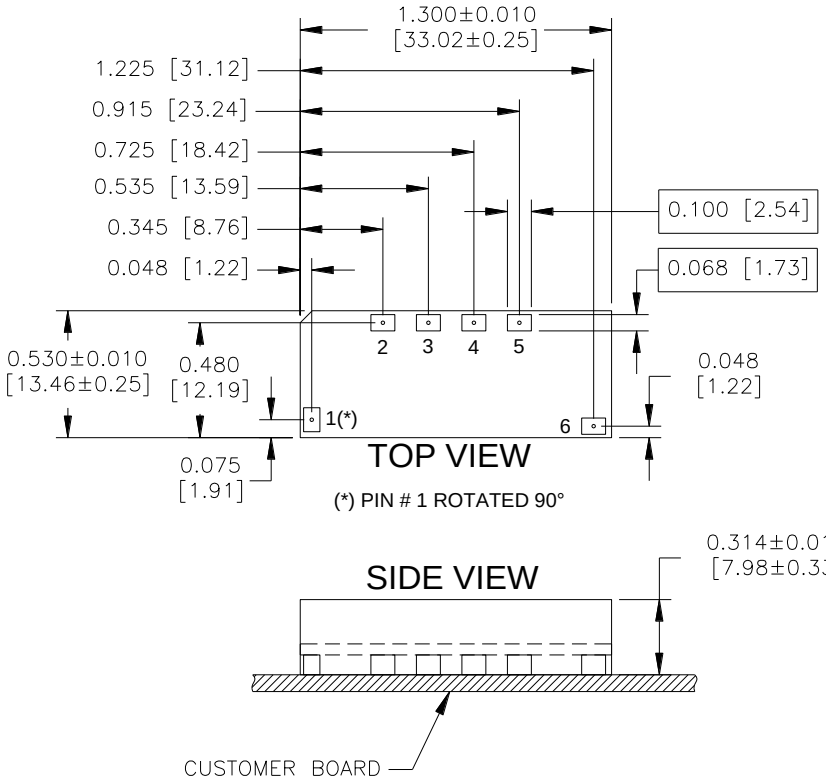
Fig. 0.7525V.7: Output voltage response for Vout = 0.7525 V to negative load current step change from 20 A to 10 A with slew rate of -5 A/µs at Vin = 12 V. Top trace: output voltage (200 mV/div.); Bottom trace: load current (5 A/div.). Co = 100 µF ceramic. Time scale: 20 µs/div.

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5. PHYSICAL INFORMATION



YNC12S20 Pinout (Surface Mount)

PAD/PIN CONNECTIONS	
Pad/Pin #	*Function*
1	ON/OFF
2	SENSE
3	TRIM
4	Vout
5	GND
6	Vin

YNC12S20 Platform Notes

- All dimensions are in inches [mm]
- Connector Material: Copper
- Connector Finish: Gold over Nickel
- Module Weight: 0.22 oz [6.12 g]
- Module Height: 0.327” Max., 0.301” Min.
- Recommended Surface-Mount Pads: Min. 0.080” X 0.112” [2.03 x 2.84]

6. ORDERING INFORMATION

PRODUCT SERIES	INPUT VOLTAGE	MOUNTING SCHEME	RATED LOAD CURRENT		ENABLE LOGIC	ROHS COMPATIBLE
YNC	**12**	**S**	**20**	**–**	**0**	
Y-Series	9.6 – 14 VDC	S ⇒ Surface-Mount	20 A (0.7525 V to 5.5 V)		0 ⇒ Standard (Positive Logic) D ⇒ Opposite of Standard (Negative Logic)	No Suffix ⇒ RoHS lead-solder-exempt compliant G ⇒ RoHS compliant for all six substances

The example above describes P/N YNC12S20-0S1G: 9.6V – 14V input, surface mount, 20A at 0.7525V to 5.5V output, standard enable logic, 25A for 300µs during start up capability, and RoHS lead solder exemption compliant. Please consult factory regarding availability of a specific version.

For more information on these products consult: tech.support@psbel.com

NUCLEAR AND MEDICAL APPLICATIONS - Products are not designed or intended for use as critical components in life support systems, equipment used in hazardous environments, or nuclear control systems.
TECHNICAL REVISIONS - The appearance of products, including safety agency certifications pictured on labels, may change depending on the date manufactured. Specifications are subject to change without notice.

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