

Please note that Cypress is an Infineon Technologies Company.

The document following this cover page is marked as "Cypress" document as this is the company that originally developed the product. Please note that Infineon will continue to offer the product to new and existing customers as part of the Infineon product portfolio.

Continuity of document content

The fact that Infineon offers the following product as part of the Infineon product portfolio does not lead to any changes to this document. Future revisions will occur when appropriate, and any changes will be set out on the document history page.

Continuity of ordering part numbers

Infineon continues to support existing part numbers. Please continue to use the ordering part numbers listed in the datasheet for ordering.

www.infineon.com



256-Kbit (32 K × 8) Bytewide F-RAM Memory

Features

- 256-Kbit ferroelectric random access memory (F-RAM) logically organized as 32 K × 8
 - ☐ High-endurance 100 trillion (10¹⁴) read/writes
 - □ 151-year data retention (see the Data Retention and Endurance table)
 - □ NoDelay[™] writes
 - Advanced high-reliability ferroelectric process
- SRAM and EEPROM compatible
 - ☐ Industry-standard 32 K × 8 SRAM and EEPROM pinout
 - □ 70-ns access time, 130-ns cycle time
- Superior to battery-backed SRAM modules
 - No battery concerns
 - Monolithic reliability
 - ☐ True surface mount solution, no rework steps
 - □ Superior for moisture, shock, and vibration
 - □ Resistant to negative voltage undershoots
- Low power consumption
 - ☐ Active current 15 mA (max)
 - □ Standby current 25 μA (typ)

- Voltage operation: V_{DD} = 4.5 V to 5.5 V
- Industrial temperature: -40 °C to +85 °C
- 28-pin small outline integrated circuit (SOIC) package
- Restriction of hazardous substances (RoHS) compliant

Functional Description

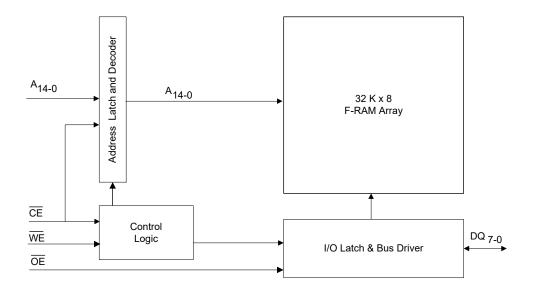
The FM1808B is a 32 K × 8 nonvolatile memory that reads and writes similar to a standard SRAM. A ferroelectric random access memory or F-RAM is nonvolatile, which means that data is retained after power is removed. It provides data retention for over 151 years while eliminating the reliability concerns, functional disadvantages, and system design complexities of battery-backed SRAM (BBSRAM). Fast write timing and high write endurance make the F-RAM superior to other types of memory.

The FM1808B operation is similar to that of other RAM devices and therefore, it can be used as a drop-in replacement for a standard SRAM in a system. Minimum read and write cycle times are equal. The F-RAM memory is nonvolatile due to its unique ferroelectric memory process. These features make the FM1808B ideal for nonvolatile memory applications requiring frequent or rapid writes.

The device is available in a 28-pin SOIC surface mount package. Device specifications are guaranteed over the industrial temperature range –40 °C to +85 °C.

For a complete list of related documentation, click here.

Logic Block Diagram





Contents

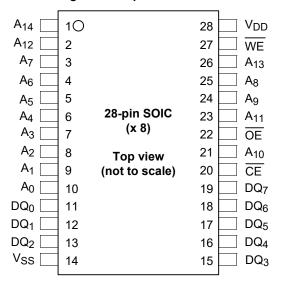
Pinout	3
Pin Definitions	3
Device Operation	
Memory Architecture	4
Memory Operation	
Read Operation	4
Write Operation	4
Pre-charge Operation	4
Endurance	5
F-RAM Design Considerations	5
Maximum Ratings	
Operating Range	
DC Electrical Characteristics	7
Data Retention and Endurance	8
Capacitance	8
Thermal Resistance	8
AC Test Conditions	9

AC Switching Characteristics	9
SRAM Read Cycle	9
SRAM Write Cycle	
Power Cycle Timing	
Functional Truth Table	
Ordering Information	13
Ordering Code Definitions	
Package Diagram	
Acronyms	
Document Conventions	
Units of Measure	15
Document History Page	16
Sales, Solutions, and Legal Information	
Worldwide Sales and Design Support	
Products	
PSoC® Solutions	17
Cypress Developer Community	
Technical Support	



Pinout

Figure 1. 28-pin SOIC Pinout



Pin Definitions

Pin Name	I/O Type	Description
A ₁₄ -A ₀	Input	Address inputs: The 15 address lines select one of 32,768 bytes in the F-RAM array.
DQ ₇ –DQ ₀	Input/Output	Data I/O Lines: 8-bit bidirectional data bus for accessing the F-RAM array.
WE	Input	Write Enable : A write cycle begins when WE is asserted. Asserting WE LOW causes the FM1808B to write the contents of the data bus to the address location latched by the falling edge of CE.
CE	Input	Chip Enable : The device is selected when $\overline{\text{CE}}$ is LOW. Asserting $\overline{\text{CE}}$ LOW causes the address to be latched internally. Address changes that occur after CE goes LOW will be ignored until the next falling edge occurs.
ŌĒ	Input	Output Enable: When OE is LOW, the FM1808B drives the data bus when the valid read data is available. Deasserting OE HIGH tristates the DQ pins.
V _{SS}	Ground	Ground for the device. Must be connected to the ground of the system.
V_{DD}	Power supply	Power supply input to the device.
NC	No connect	No connect. This pin is not connected to the die.

Document Number: 001-86209 Rev. *F Page 3 of 17



Device Operation

The FM1808B is a bytewide F-RAM memory logically organized as 32,768 × 8 and accessed using an industry-standard parallel interface. All data written to the part is immediately nonvolatile with no delay. Functional operation of the F-RAM memory is the same as SRAM type devices, except the FM1808B requires a falling edge of CE to start each memory cycle. See the Functional Truth Table on page 12 for a complete description of read and write modes.

Memory Architecture

Users access 32,768 memory locations, each with 8 data bits through a parallel interface. The complete 15-bit address specifies each of the 32,768 bytes uniquely. The F-RAM array is organized as 4092 rows of 8-bytes each. This row segmentation has no effect on operation, however the user can group data into blocks by its endurance characteristics as explained in the Endurance section.

The cycle time is the same for read and write memory operations. This simplifies memory controller logic and timing circuits. Likewise the access time is the same for read and write memory operations. When \overline{CE} is deasserted HIGH, a pre-charge operation begins, and is required of every memory cycle. Thus unlike SRAM, the access and cycle times are not equal. Writes occur immediately at the end of the access with no delay. Unlike an EEPROM, it is not necessary to poll the device for a ready condition since writes occur at bus speed.

It is the user's responsibility to ensure that V_{DD} remains within datasheet tolerances to prevent incorrect operation. Also proper voltage level and timing relationships between V_{DD} and \overline{CE} must be maintained during power-up and power-down events. See "Power Cycle Timing" on page 12.

Memory Operation

The FM1808B is designed to operate in a manner similar to other bytewide memory products. For users familiar with BBSRAM, the performance is comparable but the bytewide interface operates in a slightly different manner as described below. For users familiar with EEPROM, the differences result from the higher write performance of F-RAM technology including NoDelay writes and much higher write endurance.

Read Operation

A read operation begins on the falling edge of CE. At this time, the address bits are latched and a memory cycle is initiated. Once started, a full memory cycle must be completed internally even if CE goes inactive. Data becomes available on the bus after the access time is met.

After the address has been latched, the address value may be changed upon satisfying the hold time parameter. Unlike an SRAM, changing address values will have no effect on the memory operation after the address is latched.

The FM1808B will drive the data bus when \overline{OE} is asserted LOW and the memory access time is met. If \overline{OE} is asserted after the memory access time is met, the data bus will be driven with valid data. If \overline{OE} is asserted before completing the memory access, the data bus will not be driven until valid data is available. This feature minimizes supply current in the system by eliminating transients caused by invalid data being driven to the bus. When \overline{OE} is deasserted HIGH, the data bus will remain in a HI-Z state.

Write Operation

In the FM1808B, writes o<u>ccu</u>r in th<u>e same</u> interval as reads. The FM1808B supports both $\overline{\text{CE}}$ and $\overline{\text{WE}}$ controlled write cycles. In both cases, the address is latched on the falling edge of $\overline{\text{CE}}$.

In a $\overline{\text{CE}}$ -controlled write, the $\overline{\text{WE}}$ signal is asserted before beginning the memory cycle. That is, $\overline{\text{WE}}$ is LOW when the device is activated with the chip enable. In this case, the device begins the memory cycle as a write. The FM1808B will not drive the data bus regardless of the state of $\overline{\text{OE}}$.

In a WE-<u>controlled wri</u>te, the memory cycle begins on the fa<u>lling</u> edge of CE. The WE signal falls after the falling edge of CE. Therefore, the memory cycle begins as a read. The data <u>bus</u> will <u>be driven</u> according to the state of OE until WE falls. The CE and WE controlled write timing cases are shown in the page 11.

Write access to the array begins asynchronously after the memory cycle <u>is initiated</u>. The write access terminates on the rising edge of WE or CE, whichever comes first. A valid write operation requires the user to meet the access time specification before deasserting WE or CE. The data setup time indicates the interval during which data cannot change before the end of the write access.

Unlike other nonvolatile memory technologies, there is no write delay with F-RAM. Because the read and write access times of the underlying memory are the same, the user experiences no delay through the bus. The entire memory operation occurs in a single bus cycle. Therefore, any operation including read or write can occur immediately following a write. Data polling, a technique used with EEPROMs to determine if a write is complete, is unnecessary.

Pre-charge Operation

The pre-charge operation is an internal condition in which the memory state is prepared for a new access. All memory cycles consist of a memory access and a pre-charge. Pre-charge is user-initiated by driving the CE signal HIGH. It must remain HIGH for at least the minimum pre-charge time, t_{PC}.

The user determines the beginning of this operation since a pre-charge will not begin until CE rises. However, the device has a maximum CE LOW time specification that must be satisfied.

Document Number: 001-86209 Rev. *F Page 4 of 17



Endurance

Internally, a F-RAM operates with a read and restore mechanism. Therefore, each read and write cycle involves a change of state. The memory architecture is based on an array of rows and columns. Each read or write access causes an endurance cycle for an entire row. In the FM1808B, a row is 64 bits wide. Every 8-byte boundary marks the beginning of a new row. Endurance can be optimized by ensuring frequently accessed data is located in different rows. Regardless, F-RAM offers substantially higher write endurance than other nonvolatile memories. The rated endurance limit of 10¹⁴ cycles will allow 150,000 accesses per second to the same row for over 20 years.

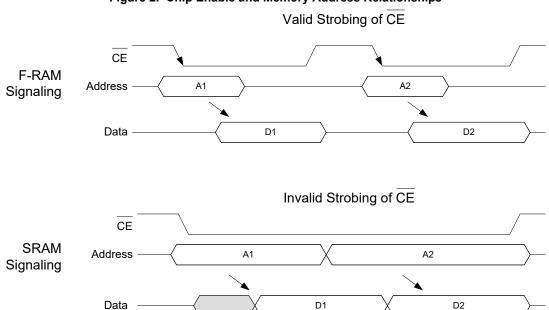
F-RAM Design Considerations

When designing with F-RAM for the first time, users of SRAM will recognize a few minor differences. First, bytewide F-RAM memories latch each address on the falling edge of chip enable. This allows the address bus to change after starting the memory access. Since every access latches the memory address on the falling edge of CE, users cannot ground it as they might with SRAM.

Users who are modifying existing designs to use F-RAM should examine the memory controller for timing compatibility of address and control pins. Each memory access must be qualified with a LOW transition of CE. In many cases, this is the only change required. An example of the signal relationships is shown in Figure 2. Also shown is a common SRAM signal relationship that will not work for the FM1808B.

The reason for CE to strobe for each address is twofold: it latches the new address and creates the necessary pre-charge period while $\overline{\text{CE}}$ is HIGH.

Figure 2. Chip Enable and Memory Address Relationships



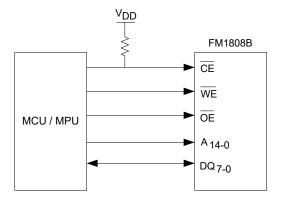
A second design consideration relates to the level of V_{DD} during operation. Battery-backed SRAMs are forced to monitor V_{DD} in order to switch to battery backup. They typically block user access below a certain V_{DD} level in order to prevent loading the battery with current demand from an active SRAM. The user can be abruptly cut off from access to the nonvolatile memory in a power down situation with no warning or indication.

F-RAM memories do not need this system overhead. The memory will not block access at any V_{DD} level that complies with the specified operating range. The user should take measures to prevent the processor from accessing memory when V_{DD} is out-of-tolerance. The common design practice of holding a processor in reset during power-down may be sufficient. It is recommended that chip enable is pulled HIGH and allowed to track V_{DD} during power-up and power-down cycles. It is the user's responsibility to ensure that chip enable is HIGH to prevent accesses below V_{DD} min. (4.5 V).



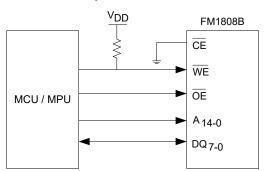
Figure 3 shows a pull-up resistor on $\overline{\text{CE}}$, which will keep the pin HIGH during power cycles, assuming the MCU / MPU pin tristates during the reset condition. The pull-up resistor value should be chosen to ensure the $\overline{\text{CE}}$ pin tracks V_{DD} to a high enough value, so that the current drawn when $\overline{\text{CE}}$ is LOW is not an issue.

Figure 3. Use of Pull-up Resistor on CE



Note that if \overline{CE} is tied to ground, the user must be sure \overline{WE} is not LOW at power-up or power-down events. If the chip is enabled and \overline{WE} is LOW during power cycles, data will be corrupted. Figure 4 shows a pull-up resistor on \overline{WE} , which will keep the pin HIGH during power cycles, assuming the MCU / MPU pin tristates during the reset condition. The pull-up resistor value should be chosen to ensure the \overline{WE} pin tracks V_{DD} to a high enough value, so that the current drawn when \overline{WE} is LOW is not an issue.

Figure 4. Use of Pull-up Resistor on WE





Maximum Ratings

Package power dissipation capability (T _A = 25 °C)
Surface mount Pb soldering temperature (3 seconds)+260 °C
DC output current (1 output at a time, 1s duration) 15 mA
Static discharge voltage Human Body Model (AEC-Q100-002 Rev. E) 4 kV
Charged Device Model (AEC-Q100-011 Rev. B) 1.25 kV
Machine Model (AEC-Q100-003 Rev. E)300 V
Latch-up current > 140 mA

Operating Range

Range	Ambient Temperature (T _A)	V _{DD}
Industrial	–40 °C to +85 °C	4.5 V to 5.5 V

DC Electrical Characteristics

Over the Operating Range

Parameter	Description	Test Conditions		Min	Typ [1]	Max	Unit
V_{DD}	Power supply voltage			4.5	5.0	5.5	V
I _{DD}	V _{DD} supply current	V_{DD} = 5.5 V, \overline{CE} cycling at min. of inputs toggling at CMOS levels (0.2 V or V_{DD} – 0.2 V), all DQ p		-	-	15	mA
		$V_{DD} = 5.5 \text{ V}, \overline{\text{CE}} \text{ at } V_{IH},$	$T_A \ge 25 ^{\circ}C$	_	_	1.8	mA
I _{SB1}	Standby current (TTL)	All other pins are static and at TTL levels (0.8 V or 2.0 V)	T _A < 25 °C	_	-	2.0	mA
I _{SB2}	Standby current (CMOS)	V _{DD} = 5.5 V, $\overline{\text{CE}}$ at V _{IH} , All other I and at CMOS levels (0.2 V or V	pins are static _{DD} – 0.2 V)	_	25	50	μΑ
I _{LI}	Input leakage current	V _{IN} between V _{DD} and V _{SS}		-	_	<u>+</u> 1	μA
I _{LO}	Output leakage current	V _{OUT} between V _{DD} and V _{SS}		-	_	<u>+</u> 1	μA
V _{IH}	Input HIGH voltage	_		2.0	_	V _{DD} + 0.3	V
V _{IL}	Input LOW voltage	-		- 0.3	_	0.8	V
V _{OH1}	Output HIGH voltage	I _{OH} = -2.0 mA		2.4	_	_	V
V _{OH2}	Output HIGH voltage	I _{OH} = -100 μA		V _{DD} – 0.2	_	_	V
V _{OL1}	Output LOW voltage	I _{OL} = 4.2 mA		-	_	0.4	V
V_{OL2}	Output LOW voltage	I _{OL} = 150 μA		_	_	0.2	V

Note

Document Number: 001-86209 Rev. *F Page 7 of 17

^{1.} Typical values are at 25 °C, V_{DD} = V_{DD} (typ). Not 100% tested.



Data Retention and Endurance

Parameter	Description	Test condition	Min	Max	Unit
T _{DR} Data retention		At +85 °C	10	_	Years
	Data retention	At +75 °C	38	_	Years
		At +65 °C	151	_	Years
NV_C	Endurance	Over operating temperature	10 ¹⁴	-	Cycles

Capacitance

Parameter	Description	Test Conditions	Max	Unit
C _{I/O}	Input/Output capacitance (DQ)	$T_A = 25 ^{\circ}\text{C}, f = 1 \text{MHz}, V_{DD} = V_{DD}(\text{Typ})$	8	pF
C _{IN}	Input capacitance	1A - 23 C, 1 - 1 Wil 12, VDD - VDD(1 yp)	6	pF

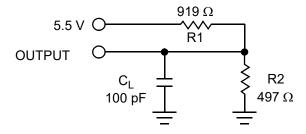
Thermal Resistance

Parameter	Description	Test Conditions	28-pin SOIC	Unit
Θ_{JA}	Thermal resistance (junction to ambient)	Test conditions follow standard test methods and	58	°C/W
Θ _{JC}		procedures for measuring thermal impedance, in accordance with EIA/JESD51.	26	°C/W

AC Test Conditions

Input pulse levels	0 V to 3V
Input rise and fall times (10%–90%)	<u><</u> 10 ns
Input and output timing reference levels	1.5
Output load capacitance	100 pF

Figure 5. AC Test Loads



Document Number: 001-86209 Rev. *F Page 8 of 17



AC Switching Characteristics

Over the Operating Range

Para	meters ^[2]					
Cypress Parameter	Alt Parameter	Description	Min	Max	Unit	
SRAM Read Cycl	le					
t _{CE}	t _{ACE}	Chip enable access time	_	70	ns	
t _{CA}	_	Chip enable active time	70	_	ns	
t _{RC}	_	Read cycle time	130	-	ns	
t _{PC}	_	Pre-charge time	60	-	ns	
t _{AS}	t _{SA}	Address setup time	0	_	ns	
t _{AH}	t _{HA}	Address hold time	15	_	ns	
t _{OE}	t _{DOE}	Output enable access time	_	12	ns	
t _{HZ} ^[3, 5]	t _{HZCE}	Chip Enable to output HI-Z	_	15	ns	
t _{OHZ} [3, 5]	t _{HZOE}	Output enable HIGH to output HI-Z	_	15	ns	
SRAM Write Cycl				1		
t _{WC}	t _{WC}	Write cycle time	130	_	ns	
t _{CA}	_	Chip enable active time	70	_	ns	
t _{CW}	t _{SCE}	Chip enable to write enable HIGH	70	_	ns	
t _{PC}	_	Pre-charge time	60	_	ns	
t _{WP}	t _{PWE}	Write enable pulse width	40	_	ns	
t _{AS}	t _{SA}	Address setup time	0	_	ns	
t _{AH}	t _{HA}	Address hold time	15	_	ns	
t _{DS}	t _{SD}	Data input setup time	30	_	ns	
t _{DH}	t _{HD}	Data input hold time	0	_	ns	
t _{WZ} [4, 4]	t _{HZWE}	Write enable LOW to output HI-Z	_	15	ns	
t _{WX} ^[4]	_	Write enable HIGH to output driven	10	_	ns	
t _{HZ} ^[4]	_	Chip enable to output HI-Z	_	15	ns	
t _{WS} ^[6]	_	Write enable to CE LOW setup time	0	-	ns	
t _{WH} ^[6]	_	Write enable to CE HIGH hold time	0	-	ns	

Notes

2. Test conditions assume a signal transition time of 10 ns or less, timing reference levels of 0.5 × V_{DD}, input pulse levels of 0 to 3 V, output loading of the specified I_{OL}/I_{OH} and load capacitance shown in AC Test Conditions on page 8.

3. t_{HZ} and t_{OHZ} are specified with a load capacitance of 5 pF. Transition is measured when the outputs enter a high impedance state.

4. t_{WZ} and t_{HZ} is specified with a load capacitance of 5 pF. Transition is measured when the outputs enter a high impedance state.

5. This parameter is characterized but not 100% tested.

6. The relationship between CE and WE determines if a CE or WE controlled write occurs. There is no timing specification associated with this relationship.

CE

t_{CA}

t_{RC}

t_{PC}

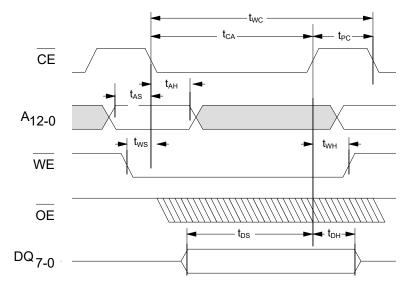
A12-0

OE

DQ₇₋₀

Figure 6. Read Cycle Timing

Figure 7. Write Cycle Timing 1 (CE Controlled)



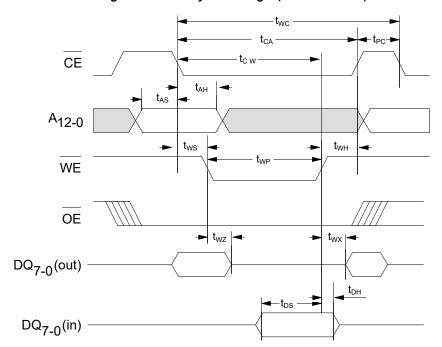


Figure 8. Write Cycle Timing 2 (WE Controlled)

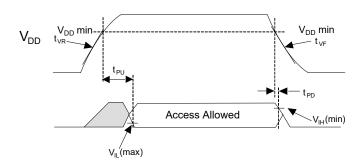


Power Cycle Timing

Over the Operating Range

Parameter	Description		Max	Unit
t _{PU}	ower-up (after V _{DD} min. is reached) to first access time		-	ms
t _{PD}	Last write (WE HIGH) to power down time	0	-	μs
$t_{VR}^{[7]}$	V _{DD} power-up ramp rate	30	-	µs/V
t _{VF} ^[7]	V _{DD} power-down ramp rate	30	-	µs/V

Figure 9. Power Cycle Timing



Functional Truth Table

CE	WE	Operation ^[8, 9]	
Н	Х	Standby/Pre-charge	
↓	Х	Latch Address (and begin write if $\overline{\text{WE}}$ = LOW)	
L	Н	Read	
L	↓	Write	

- Slope measured at any point on the V_{DD} waveform.
 H = Logic HIGH, L = Logic LOW, V = Valid Data, X = Don't Care, ↓ = Toggle LOW, ↑ = Toggle HIGH.
 The OE pin controls only the DQ output buffers.

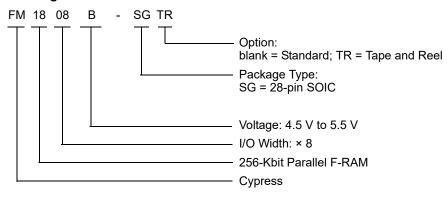


Ordering Information

Ordering Code	Package Diagram	Package Type	Operating Range
FM1808B-SG	51-85026	28-pin SOIC	Industrial
FM1808B-SGTR	51-85026	28-pin SOIC	muustilai

All the above parts are Pb-free.

Ordering Code Definitions

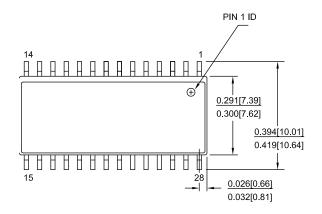


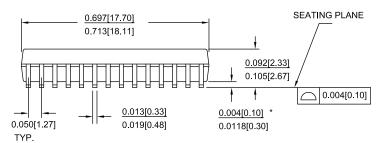


Package Diagram

Figure 10. 28-pin SOIC Package Outline, 51-85026

28 Lead (300 Mil) SOIC - S21

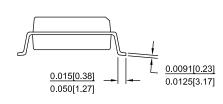




NOTE :

- 1. JEDEC STD REF MO-119
- 2. BODY LENGTH DIMENSION DOES NOT INCLUDE MOLD PROTRUSION/END FLASH,BUT DOES INCLUDE MOLD MISMATCH AND ARE MEASURED AT THE MOLD PARTING LINE. MOLD PROTRUSION/END FLASH SHALL NOT EXCEED 0.010 in (0.254 mm) PER SIDE
- 3. DIMENSIONS IN INCHES MIN. MAX.

PART #		
S28.3	STANDARD PKG.	
SZ28.3	LEAD FREE PKG.	
SX28.3	LEAD FREE PKG.	



51-85026 *H



Acronyms

Table 1. Acronyms Used in this Document

Acronym	Description
CPU	Central Processing Unit
CMOS	Complementary Metal Oxide Semiconductor
JEDEC	Joint Electron Devices Engineering Council
JESD	JEDEC Standards
EIA	Electronic Industries Alliance
F-RAM	Ferroelectric Random Access Memory
I/O	Input/Output
MCU	Microcontroller Unit
MPU	Microprocessor Unit
RoHS	Restriction of Hazardous Substances
R/W	Read and Write
SOIC	Small Outline Integrated Circuit
SRAM	Static Random Access Memory

Document Conventions

Units of Measure

Table 2. Units of Measure

Symbol	Unit of Measure
°C	degree Celsius
Hz	hertz
kHz	kilohertz
kΩ	kilohm
MHz	megahertz
μΑ	microampere
μF	microfarad
μS	microsecond
mA	milliampere
ms	millisecond
ΜΩ	megaohm
ns	nanosecond
Ω	ohm
%	percent
pF	picofarad
V	volt
W	watt



Document History Page

		1-86209 Orig. of	Submission	Description (O)	
Rev.	ECN No.	Change	Date	Description of Change	
**	3912933	GVCH	02/25/2013	New spec	
*A	4000965	GVCH	05/15/2013	Added Appendix A - Errata for FM1808B	
*B	4045491	GVCH	06/30/2013	All errata items are fixed and the errata is removed.	
*C	4274813	GVCH	03/10/2014	Converted to Cypress standard format Changed datasheet status from "Preliminary to Final" Changed endurance value from 10 ¹² to 10 ¹⁴ cycles Updated Maximum Ratings table - Removed Moisture Sensitivity Level (MSL) - Added junction temperature and latch up current Updated Data Retention and Endurance table Added Thermal Resistance table Removed Package Marking Scheme (top mark)	
*D	4562106	GVCH	11/05/2014	Added related documentation hyperlink in page 1. Updated package diagram 51-85026 to current version.	
*E	4881950	ZSK / PSR	09/04/2015	Updated Maximum Ratings: Removed "Maximum junction temperature". Added "Maximum accumulated storage time". Added "Ambient temperature with power applied". Updated to new template.	
*F	6572627	GVCH	06/10/2019	DC Electrical Characteristics: Updated I_{SB1} parameter test condition and added I_{SB1} value for T_A < 25 °C. Updated Copyright information.	

Document Number: 001-86209 Rev. *F Page 16 of 17



Sales, Solutions, and Legal Information

Worldwide Sales and Design Support

Cypress maintains a worldwide network of offices, solution centers, manufacturer's representatives, and distributors. To find the office closest to you, visit us at Cypress Locations.

cypress.com/touch cypress.com/usb

cypress.com/wireless

Products

Touch Sensing

USB Controllers
Wireless Connectivity

Arm® Cortex® Microcontrollers cypress.com/arm Automotive cypress.com/automotive Clocks & Buffers cypress.com/clocks Interface cypress.com/interface Internet of Things cypress.com/iot Memory cypress.com/memory Microcontrollers cypress.com/mcu **PSoC** cypress.com/psoc Power Management ICs cypress.com/pmic

PSoC® Solutions

PSoC 1 | PSoC 3 | PSoC 4 | PSoC 5LP | PSoC 6 MCU

Cypress Developer Community

Community | Projects | Video | Blogs | Training | Components

Technical Support

cypress.com/support

Cypress, the Cypress logo, Spansion, the Spansion logo, and combinations thereof, WICED, PSoC, CapSense, EZ-USB, F-RAM, and Traveo are trademarks or registered trademarks of Cypress in the United States and other countries. For a more complete list of Cypress trademarks, visit cypress.com. Other names and brands may be claimed as property of their respective owners.s in the United States and other countries. For a more complete list of Cypress trademarks, visit cypress.com. Other names and brands may be claimed as property of their respective owners.

[©] Cypress Semiconductor Corporation, 2013-2019. This document is the property of Cypress Semiconductor Corporation and its subsidiaries ("Cypress"). This document, including any software or firmware included or referenced in this document ("Software"), is owned by Cypress under the intellectual property laws and treaties of the United States and other countries worldwide. Cypress reserves all rights under such laws and treaties and does not, except as specifically stated in this paragraph, grant any license under its patents, copyrights, trademarks, or other intellectual property rights. If the Software is not accompanied by a license agreement and you do not otherwise have a written agreement with Cypress governing the use of the Software, then Cypress hereby grants you a personal, non-exclusive, nontransferable license (without the right to sublicense) (1) under its copyright rights in the Software (a) for Software provided in source code form, to modify and reproduce the Software solely for use with Cypress hardware products, only internally within your organization, and (b) to distribute the Software in binary code form externally to end users (either directly or indirectly through resellers and distributors), solely for use on Cypress hardware product units, and (2) under those claims of Cypress's patents that are infringed by the Software (as provided by Cypress, unmodified) to make, use, distribute, and import the Software is prohibited.

TO THE EXTENT PERMITTED BY APPLICABLE LAW, CYPRESS MAKES NO WARRANTY OF ANY KIND, EXPRESS OR IMPLIED, WITH REGARD TO THIS DOCUMENT OR ANY SOFTWARE OR ACCOMPANYING HARDWARE, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE. No computing device can be absolutely secure. Therefore, despite security measures implemented in Cypress hardware or software products, Cypress shall have no liability arising out of any security breach, such as unauthorized access to or use of a Cypress product. CYPRESS DOES NOT REPRESENT, WARRANT, OR GUARANTEE THAT CYPRESS PRODUCTS, OR SYSTEMS CREATED USING CYPRESS PRODUCTS, WILL BE FREE FROM CORRUPTION, ATTACK, VIRUSES, INTERFERENCE, HACKING, DATA LOSS OR THEFT, OR OTHER SECURITY INTRUSION (collectively, "Security Breach"). Cypress disclaims any liability relating to any Security Breach. In addition, the products described in these materials may contain design defects or errors known as errata which may cause the product to deviate from published specifications. To the extent permitted by applicable law, Cypress reserves the right to make changes to this document without further notice. Cypress does not assume any liability arising out of the application or use of any product or circuit described in this document. Any information provided in this document, including any sample design information or programming code, is provided only for reference purposes. It is the responsibility of the user of this document to properly design, program, and test the functionality and safety of any application made of this information and any resulting product. "High-Risk Device" means any device or system whose failure could cause personal injury, death, or property damage. Examples of High-Risk Devices are weapons, nuclear installations, surgical implants, and other medical devices. "Critical Component" means any component of a High-Risk Device whose failure to perform can be reasonably expected to cause, directly or indirectly, the failure of