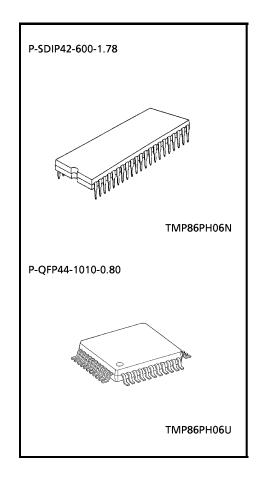
#### CMOS 8-Bit Microcontroller

#### TMP86PH06N / TMP86PH06U

The TMP86PH06 is a OTP type MCU which includes 16 Kbyte One-time PROM. It is a pin compatible with a mask ROM product of the TMP86CH06. Writing the program to built-in PROM, the TMP86PH06 operates as the same way as the TMP86CH06. Using the Adapter socket, you can write and verify the data for the TMP86PH06 with a general-purpose PROM programmer same as TC57100D/AD.

Part No.	OTP	RAM	Package	Adapter Socket
TMP86PH06N	16 K × 8 bit	512 × 8 bit	P-SDIP42-600-1.78	BM11155
TMP86PH06U	16 K × 8 bit	512 × 8 bit	P-QFP44-1010-0.80	BM11156



For a discussion of how the reliability of microcontrollers can be predicted, please refer to Section 1.3 of the chapter entitled Quality and Reliability Assurance / Handling Precautions.

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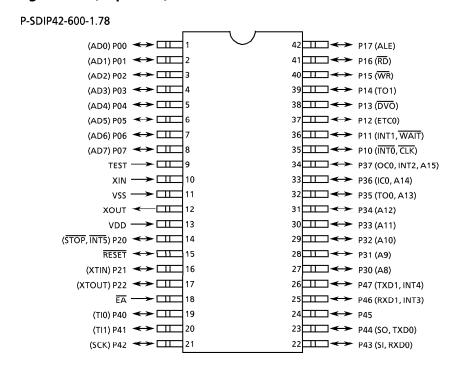
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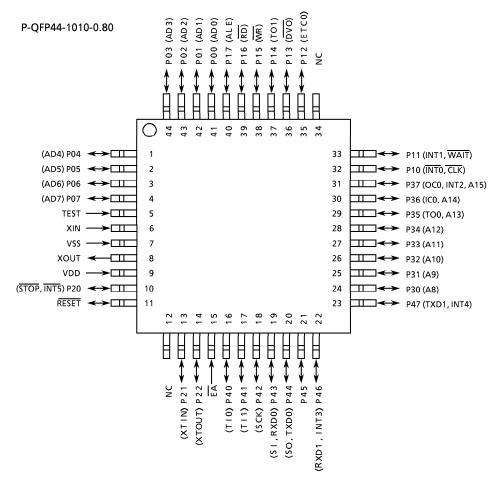
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#### Pin Assignments (Top View)





## **Pin Function**

The TMP86PH06 has MCU mode and PROM mode.

# (1) MCU mode

In the MCU mode, the TMP86PH06 is a pin compatible with the TMP86CH06 (Make sure to fix the TEST pin to low level).

#### (2) PROM mode

Pin Name (PROM mode)	Input/Output	Functions	Pin Name (MCU mode)			
A15 to A8 A7 to A0	Input	Input of Memory address for program	P30 to P37 P40 to P47			
D7 to D0	I/O	Input/Output of Memory data for program	P00 to P07			
CE		Chip enable	P13			
ŌĒ	Input	Output enable	P14			
PGM		Program control	P15			
VPP		+ 12.75 V / 5 V (Power supply of program)	TEST			
vcc	Power supply	+ 6.25 V / 5 V	VDD			
GND		0 V	VSS			
EA, P11, P21 P12, P10, P22, P20 RESET	I/O	PROM mode setting pin. Fix to high.  PROM mode setting pin. Fix to low.				
P16, P17	Output	Output pin for PROM operation test. Open or rele	ase.			
XIN	Input	Solf oscillation with reconstor (9 MHz)				
XOUT	Output	Self oscillation with resonator (8 MHz).				

Note: No pin is applied to A16 input.

## **Operational Description**

This section describes the functions and basic operational blocks of TMP86PH06.

The TMP86PH06 has PROM in place of the mask ROM which is included in the TMP86CH06. The configuration and function are the same as the TMP86CH06. For the functions of TMP86PH06 in details, see the section of TMP86CH06.

In addition, TMP86PH06 operates as the single clock mode when releasing reset.

When using the dual clock mode, oscillate a low-frequency clock by SET. XTEN command at the beginning of program.

#### 1. Operating Mode

The TMP86PH06 has MCU mode and PROM mode.

#### 1.1 MCU mode

The MCU mode is set by fixing the TEST/VPP pin to the low level.

In the MCU mode, the operation is the same as the TMP86CH06 (TEST/VPP pin cannot be used open because it has no built-in pull-down resister).

#### 1.1.1 Program Memory

The TMP86PH06 has a 16-Kbyte built-in one time PROM (addresses C000 to 3FFF<sub>H</sub> in the MCU mode, addresses 0000 to 3FFF<sub>H</sub> in the PROM mode).

When using TMP86PH06 for evaluation of TMP86CH06, the program is written in the program storing area shown in Figure 1-1.

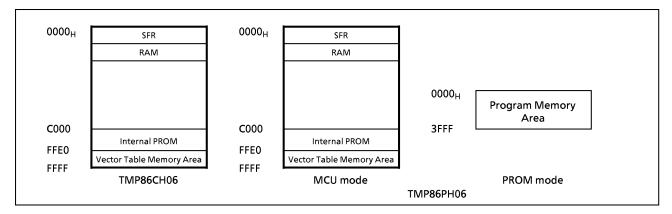


Figure 1-1. Program Memory Area

Note: The area that is not in use should be set data to FFH, or a general-purpose PROM programmer should be set only in the program memory area to access.

## 1.1.2 Data Memory

TMP86PH06 has a built-in 512-byte Data memory (static RAM).

## 1.1.3 Input/Output Circuitry

## (1) Control pins

The control pins of the TMP86PH06 are the same as those of the TMP86CH06 except that the TEST pin does not have a built-in pull-down resister.

#### (2) I/O ports

The I/O circuitries of TMP86PH06 I/O ports are the same as the those of TMP86CH06.

#### 1.2 PROM Mode

The PROM mode is set by setting the  $\overline{\text{RESET}}$  pin, the ports P17 to P10, P22 to P20 and  $\overline{\text{TEST}}$  and  $\overline{\text{EA}}$  as shown in Figure 1-2. The programming and verification for the internal PROM is achieved by using a general-purpose PROM programmer with the adapter socket.

Note: The high-speed program mode can be used. The setting is different according to the type of PROM programmer to use, refer to each description of PROM programmer.

The 86PH06 does not support the electric signature mode, apply the ROM type of PROM programmer to TC571000D/AD.

Always set the switch of Adapter socket to the N side when using TOSHIBA's Adapter socket.

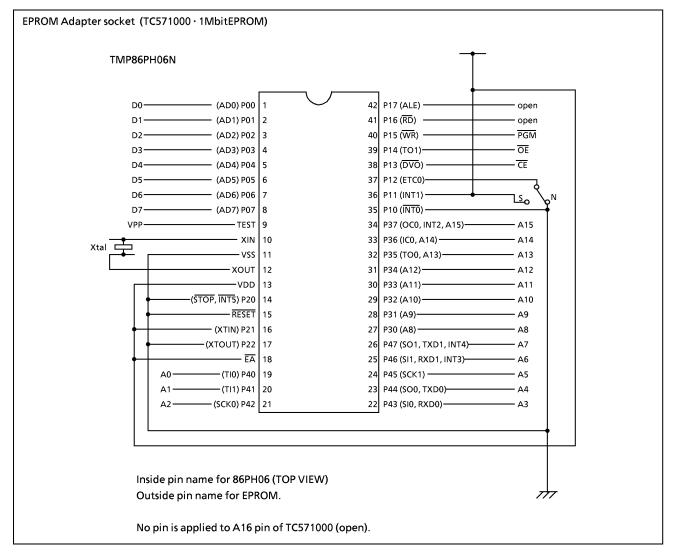


Figure 1-2 (a). PROM Mode Setting

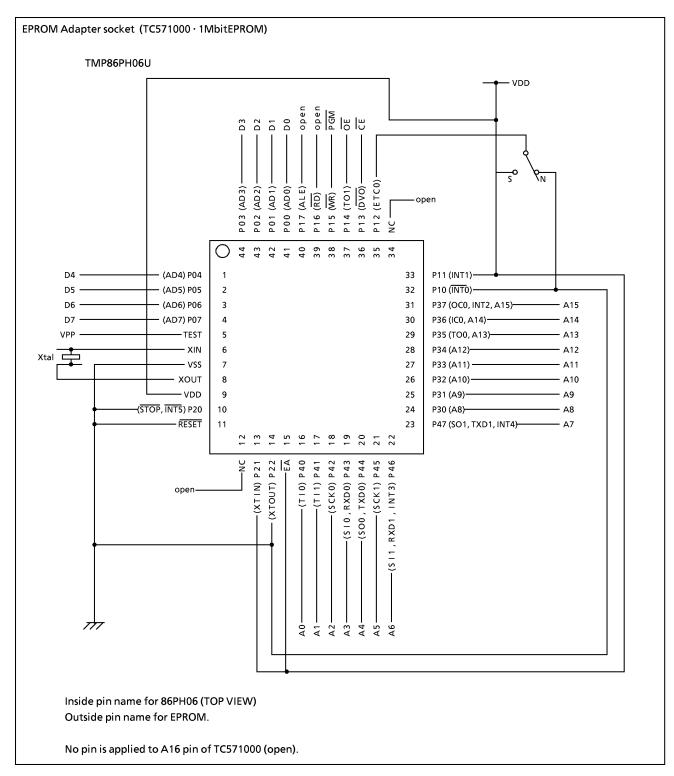


Figure 1-2 (b). PROM Mode Setting

#### 1.2.1 Programming Flowchart (High-speed Program Writing)

The high-speed programming mode is set by applying 12.75 V (programming voltage) to the  $V_{PP}$  pin when the  $V_{CC}$  is 6.25 V. After the address and data are fixed, the data in the address is written by applying 0.1ms of low level program pulse to  $\overline{PGM}$  pin. Then verify if the data is written.

If the programmed data is incorrect, another 0.1ms pulse is applied to PGM pin.

This programming procedure is repeated until correct data is read from the address (maximum of 25 times).

Subsequently, all data are programmed in all addresses.

When all data were written, verify all address under the condition of  $V_{CC} = V_{PP} = 5 \text{ V}$ .

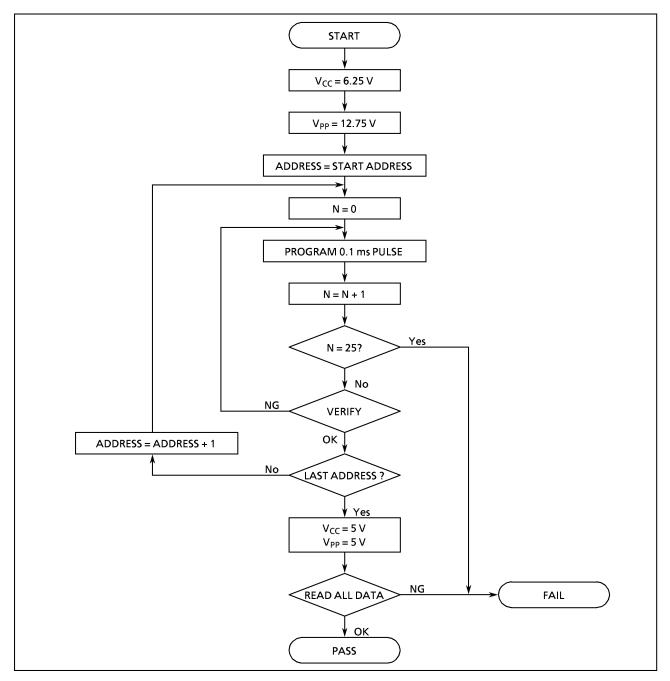


Figure 1-3. Programming Flow Chart

- 1.2.2 Program Writing using a general-purpose PROM programmer
- (1) Recommended OTP Adapter

BM11155: for TMP86PH06N BM11156: for TMP86PH06U

(2) Setting of OTP Adapter

Set the switch (SW1) to N side.

- (3) Setting of PROM programmer
  - i) Set PROM type to TC571000D/AD. VPP: 12.75 V (high-speed program writing)
  - ii) Data transmission (Note 1)

The PROM of TMP86PH06 is located on different addresses; it depends on operating modes: MCU mode and PROM mode. When you write the data of ROM for TMP86CH06, the data should be transferred from the address for MCU mode to that for PROM mode before writing operation is executed. For the applicable program areas of MCU mode and PROM mode are different, refer to Figure 1-1 Program Memory Area.

Example: Execute block Transferring on PROM programmer.

ROM (16 KB): 0C000 to 0FFFF<sub>H</sub>  $\rightarrow$  00000 to 03FFF<sub>H</sub>

iii) Setting of the program address (Note 1)

Start address: 00000<sub>H</sub> End address: 03FFF<sub>H</sub>

(4) Writing program

Write and verify according to the above mentioned "Setting of PROM programmer."

- Note 1: For the setting method, refer to each description of PROM programmer.

  Make sure to set the data of address area that is not in used to FF<sub>H</sub>.
- Note 2: When setting MCU to the adapter or when setting the adapter to the PROM programmer, set the first pin of the adapter and that of PROM programmer socket matched. If the first pin is conversely set, MCU or adapter or programmer would be damaged.
- Note 3: The TMP86PH06 does not support the electric signature mode.

  If PROM programmer uses the signature, the device would be damaged because of applying voltage of 12 ± 0.5 V to pin 9 (A9) of the address.

  Do not use the signature.

## **Electrical Characteristics**

Absolute Maximum Rating (V<sub>ss</sub> = 0 V)

Parameter	Symbol	Pins	Rating	Unit
Supply Voltage	$V_{DD}$		– 0.3 to 6.5	
Input Voltage	V <sub>IN</sub>		– 0.3 to V <sub>DD</sub> + 0.3	V
Output Voltage	V <sub>OUT</sub>		– 0.3 to V <sub>DD</sub> + 0.3	
Outrot Comment	I <sub>OUT1</sub>	P1 to P4	3.2	
Output Current	I <sub>OUT3</sub>	Р0	30	mA
0.1.16	Σ l <sub>OUT1</sub>		80	
Output Current	Σ I <sub>OUT3</sub>		120	
Power Dissipation (Topr = 85°C)	PD		330	mW
Soldering Temperature (Time)	Tsld		260 (10 s)	
Storage Temperature	Tstg		– 55 to 125	°C
Operating Temperature	Topr		– 40 to 85	

Note: The absolute maximum ratings are rated values which must not be exceeded during operation, even for an instant.

Any one of the ratings must not be exceeded. If any absolute maximum rating is exceeded, a device may break down or its performance may be degraded, causing it to catch fire or explode resulting in injury to the user. Thus, when designing products which include this device, ensure that no absolute maximum rating value will ever be exceeded.

**Recommended Operating Conditions** 

 $(V_{SS} = 0 \text{ V, Topr} = -40 \text{ to } 85^{\circ}\text{C})$ 

Parameter	Symbol	Pins		Conditions	Min	Max	Unit		
			fc = 16	NORMAL1, 2 mode					
			MHz	IDLE0, 1, 2 mode	4.5				
			fc = 4.2	NORMAL1, 2 mode					
Supply Voltage	$V_{DD}$		MHz	IDLE0, 1, 2 mode	1.8	5.5	v		
			fs = 32.768	SLOW1, 2 mode	1				
			kHz	SLEEP0, 1, 2 mode					
				STOP mode	1.8				
	V <sub>IH1</sub>	Except hysteresis and TTL input		V >4 EV	V <sub>DD</sub> × 0.70				
	V <sub>IH2</sub>	Hysteresis input	$V_{DD} \ge 4.5 V$		V <sub>DD</sub> × 0.75				
Input High Voltage	V <sub>IH3</sub>	Except TTL input	V <sub>DD</sub> <4.5 V		$V_{DD} \times 0.90$	V <sub>DD</sub>	V		
	V	TTL input	V <sub>DD</sub> = 5 V		2.2	]			
	V <sub>IH4</sub>	(Data bus)	$V_{DD} = 3 V$		V <sub>DD</sub> – 0.2				
	V <sub>IH5</sub>			V <sub>DD</sub> = 1.8 V	TBD				
	V <sub>IL1</sub>	Except hysteresis and TTL input	V >4.5V		V >45V			$V_{DD} \times 0.30$	
	$V_{IL2}$	Hysteresis input		$V_{DD} \ge 4.5 V$		$V_{DD} \times 0.25$			
Input Low Voltage	$V_{IL3}$	Except TLL input		$V_{DD}$ < 4.5 $V$	0	$V_{DD} \times 0.10$	\ v		
	$V_{IL4}$	TTL input		$V_{DD} = 5 V$		0.8			
'	V IL4	(Data bus)	V <sub>DD</sub> = 3 V			0.2			
	V <sub>IL5</sub>			V <sub>DD</sub> = 1.8 V		TBD			
	fc	XIN, XOUT	V <sub>DD</sub> = 4.5 V to 5.5 V		1.0	16	MHz		
Clock Frequency	10	Aliv, AOUT	V <sub>DD</sub> = 1.8 V to 5.5 V		1.0	4.2	IVITZ		
	fs	XTIN, XTOUT			30.0	34.0	kHz		

Note 1: The recommended operating conditions for a device are operating conditions under which it can be guaranteed that the device will operate as specified. If the device is used under operating conditions other than the recommended operating conditions (supply voltage, operating temperature range, specified AC/DC values etc.), malfunction may occur. Thus, when designing products which include this device, ensure that the recommended operating conditions for the device are always adhered to.

Note 2: Clock Frequency fc; The condition of supply voltage range is the value under NORMAL and IDLE mode.

Note 3: The minimum fc with clock gear is calculated as following formula with the ratio on divider n.

 $(Min\ fc) = (ratio\ on\ divider\ n) \times 1\ [MHz]$ 

DC Characteristics

 $(V_{SS} = 0 \text{ V}, \text{ Topr} = -40 \text{ to } 85^{\circ}\text{C})$ 

Parameter	Symbol	Pins	Conditions	Min	Тур.	Max	Unit
Hysteresis Voltage	V <sub>HS</sub>	Hysteresis input		-	0.9	-	V
Input Current	I <sub>IN1</sub> I <sub>IN2</sub> I <sub>IN3</sub>	TEST, EA Sink Open Drain, Tri-state Port RESET, STOP	V <sub>DD</sub> = 5.5 V V <sub>IN</sub> = 5.5 V / 0 V	-	-	± 2	μΑ
Input Resistance	R <sub>IN2</sub>	RESET TEST		100	220 70	450 –	kΩ
OSC. Feedback Resistance	Rfx Rfxt	XIN-XOUT XTIN-XTOUT		-	1.2	-	ΜΩ
Output Leakage Current	I <sub>LO1</sub>	Sink Open Drain Port Tri-state Port	$V_{DD} = 5.5 \text{ V}, V_{OUT} = 5.5 \text{ V}$ $V_{DD} = 5.5 \text{ V}, V_{OUT} = 5.5 \text{ V}/0 \text{ V}$	-	-	2 ± 2	μΑ
"H" Output Voltage	V <sub>OH2</sub>	Tri-state Port P0	$V_{DD} = 4.5 \text{ V}, I_{OH} = -0.7 \text{ mA}$ $V_{DD} = 4.5 \text{ V}, I_{OH} = -0.7 \text{ mA}$	4.1 4.1	-	-	V
"L" Output Voltage  "L" Output Current	V <sub>OL3</sub> I <sub>OL1</sub>	P0 Except P0 and XOUT P0	$V_{DD} = 4.5 \text{ V}, I_{OL} = 1.6 \text{ mA}$ $V_{DD} = 4.5 \text{ V}, V_{OL} = 0.4 \text{ V}$ $V_{DD} = 4.5 \text{ V}, V_{OL} = 1.0 \text{ V}$	_ _ _	- 1.6 20	0.4 _ _	V mA
Supply Current under NORMAL1, 2 mode	·OLS		$V_{DD} = 5.5 \text{ V}$ $V_{IN} = 5.3 \text{ V} / 0.2 \text{ V}$	_	5.5	7	mA
Supply Current under IDLE1, 2 mode			fc = 16 MHz fs = 32.768 kHz	-	2.8	3.5	IIIA
Supply Current under SLOW1 mode	l <sub>DD</sub>		V <sub>DD</sub> = 3.0 V	_	14	25	μΑ
Supply Current under SLEEP1 mode			V <sub>IN</sub> = 2.8 V / 0.2 V fs = 32.768 kHz	_	7	15	μΑ
Supply Current under SLEEP0 mode			13 – 32.700 KIIZ	_	6	15	μΑ
Supply Current under STOP mode			$V_{DD} = 5.5 \text{ V}$ $V_{IN} = 5.3 \text{ V} / 0.2 \text{ V}$	_	0.5	10	μΑ

Note 1: Typical values are shown under  $T_{\rm opr}$  = 25°C,  $V_{\rm DD}$  = 5 V, while conditions are not stated. Note 2: Input current  $I_{\rm IN1}$ ,  $I_{\rm IN3}$ : The current through pull-up or pull-down resistor is not included.

A.C. Characteristics

(1)  $(V_{SS} = 0 \text{ V}, V_{DD} = 4.5 \text{ to } 5.5 \text{ V}, \text{ Topr} = -40 \text{ to } 85^{\circ}\text{C})$ 

#### ① CLOCK

Parameter	Symbol	Conditions	Min	Тур.	Max	Unit
		NORMAL1, 2 mode	0.25		10	
Ma china Cuala Tima	4	IDLE0, 1, 2 mode	0.25	_		
Machine Cycle Time	tcy	SLOW1, 2 mode	117.6		133.3	$\mu$ S
		SLEEP0, 1, 2 mode	117.6	_		
High Level Clock Pulse Width	t <sub>WCH</sub>	External clock operation (XIN input)	50			
Low Level Clock Pulse Width	t <sub>WCL</sub>	fc = 16 MHz	50	_	_	ns
High Level Clock Pulse Width	t <sub>WSH</sub>	External clock operation (XTIN input)	14.7			
Low Level Clock Pulse Width	t <sub>WSL</sub>	fs = 32.768 kHz	14.7	ı		μS

## ② External Memory Interface (Multiplexed Bus) at V<sub>DD</sub> = 4.5 to 5.5

N.a	Comple ed	Danamatan.	Vari	able	16 N	l l a la	
No.	Symbol	Parameter	Min	Max	Min	Max	Unit
1	t <sub>AL</sub>	A7 to 0 effective → ALE	0.5t – 15		16		ns
2	$t_{LA}$	ALE fall → A7 to 0 hold	0.5t - 20		11		ns
3	t <sub>LL</sub>	ALE pulse width	t – 40		22		ns
4	t <sub>LC</sub>	ALE fall $\rightarrow \overline{RD}$ , $\overline{WR}$ fall	0.5t – 25		6		ns
5	t <sub>CL</sub>	$\overline{RD}$ , $\overline{WR}$ rise $\rightarrow$ ALE rise	0.5t – 20		11		ns
6	t <sub>ACL</sub>	A7 to 0 effective $\rightarrow \overline{RD}$ , $\overline{WR}$ fall	t – 25		37		ns
7	t <sub>ACH</sub>	A15 to 8 effective $\rightarrow \overline{RD}$ , $\overline{WR}$ fall	1.5t – 25		68		ns
8	t <sub>CA</sub>	$\overline{RD}$ , $\overline{WR}$ rise $\rightarrow$ A15 to 8 hold	0.5t – 20		11		ns
9	t <sub>ADL</sub>	A7 to 0 effective $\rightarrow$ D7 to 0 input		3t – 55		132	ns
10	t <sub>ADH</sub>	A15 to 8 effective $\rightarrow$ D7 to 0 input		3.5t – 65		153	ns
11	t <sub>RD</sub>	$\overline{RD}$ fall $\rightarrow$ D7 to 0 input		2t – 60		65	ns
12	t <sub>RR</sub>	RD pulse width	2t – 40		85		ns
13	t <sub>HR</sub>	$\overline{RD}$ rise $\rightarrow$ D7 to 0 hold	0		0		ns
14	t <sub>RAE</sub>	$\overline{RD}$ rise $\rightarrow$ A7 to 0 effective	t – 15		47		ns
15	t <sub>WW</sub>	WR pulse width	2t – 40		85		ns
16	t <sub>DW</sub>	D7 to 0 effective $\rightarrow \overline{WR}$ rise	2t – 40		85		ns
17	t <sub>WD</sub>	$\overline{\text{WR}}$ rise $\rightarrow$ D7 to 0 hold	0.5t – 15		16		ns

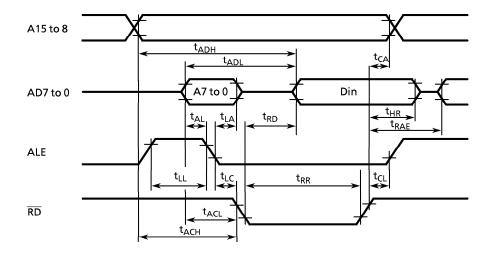
Note: t = tcy/4 (t = 62.5 ns at fcgck = 16 MHz)

A.C.Measurement Condition

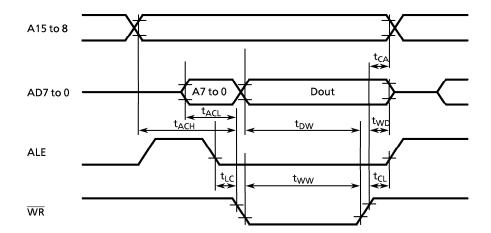
Output Level: High 2.2 V/Low 8.0 V, CL = 50 pFInput Level: High 2.4 V/Low 0.4 V (D7 to D0)

High 0.8 VDD / Low 0.2 VDD (Except D7 to D0)

# Read Cycle



# Write Cycle

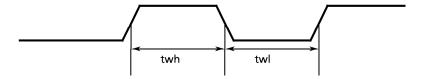


TC0, 1: External Input (Vcc = 4.5 to 5.5)

			_	
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Operating Mode	twh	twl
NORMAL	8fc + 25	8fc + 25
SLOW	8fs + 25	8fs + 25

TIn input



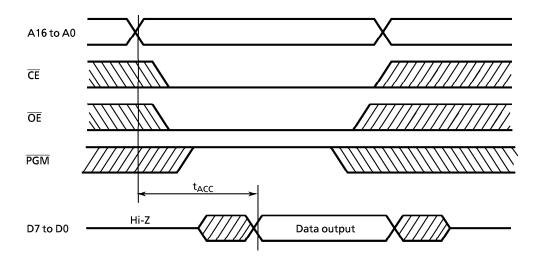
DC Characteristics, AC Characteristics (PROM mode)

 $(V_{SS} = 0 \text{ V, Topr} = -30 \text{ to } 70^{\circ}\text{C})$ 

#### (1) Read operation in PROM mode

Parameter	Symbol	Conditions	Min	Тур.	Max	Unit
High level input voltage (TTL)	V <sub>IH4</sub>		2.2	-	V <sub>CC</sub>	٧
Low leve input voltage (TTL)	V <sub>IL4</sub>		0	-	0.8	>
Power supply	V <sub>CC</sub>		4.75	5.0	5.25	V
Power supply of program	$V_{PP}$		4.75	5.0	3.23	'
Address access time	t <sub>ACC</sub>	V <sub>CC</sub> = 5.0 ± 0.25 V	-	1.5 tcyc + 300	-	ns

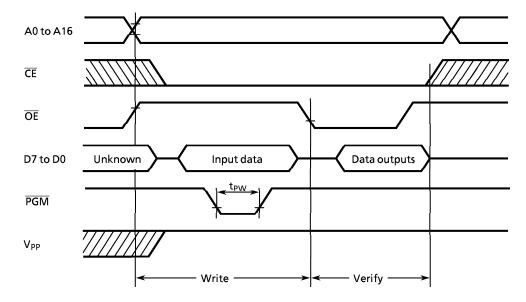
Note: tcyc = 500 ns at 8 MHz



# (2) Program operation (High-speed) (Topr = $25 \pm 5^{\circ}$ C)

Parameter	Symbol	Conditions	Min	Тур.	Max	Unit
High level input voltage (TTL)	V <sub>IH4</sub>		2.2	_	V <sub>CC</sub>	<
Low leve input voltage (TTL)	V <sub>IL4</sub>		0	_	0.8	<b>&gt;</b>
Power supply	V <sub>CC</sub>		6.0	6.25	6.5	V
Power supply of program	V <sub>PP</sub>		12.5	12.75	13.0	V
Pulse width of initializing program	t <sub>PW</sub>	V <sub>CC</sub> = 6.0 V	0.095	0.1	0.105	ms

#### High-speed program writing



- Note 1: The power supply of  $V_{PP}$  (12.75 V) must be set power-on at the same time or the later time for a power supply of  $V_{CC}$  and must be clear power-on at the same time or early time for a power supply of  $V_{CC}$ .
- Note 2: The pulling up/down device on the condition of  $V_{PP} = 12.75 \text{ V} \pm 0.25 \text{ V}$  causes a damage for the device. Do not pull up/down at programming.
- Note 3: Use the recommended adapter (see 1.2.2 (1)) and mode (see 1.2.2 (3) i).
  Using other than the above condition may cause the trouble of the writting.