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# **DIGI POT 4 Click**

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PID: MIKROE-2873

**DIGI POT 4 click** is a digitally controlled dual potentiometer, with the resistance of  $10K\Omega$ . It has a 10bit resolution which allows for a very smooth linear wiper positioning through 1024 steps. Digital wiper position can be controlled via SPI interface. DIGI POT 4 click also features a non-volatile durable EEPROM memory for storing the wiper position, which means that the device can restore its last position after the power on - just like its mechanical counterpart.

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The main advantage of the digital potentiometers over the mechanical ones is that they can never wear out. The wiper position can be precisely programmed, and the wiper contact with the resistive coating can never be compromised by the influence of the dirt or moisture. Due to its low THD and good bandwidth, it can be used for digital volume control or a precise gain and offset adjustment. It can also be used as the LCD digital contrast control, and generally - whenever a precise dual digital potentiometer is required.

#### How does the click work?

DIGI POT 4 click carries <u>MAX5494</u>, a 10bit dual, non-volatile, linear taper, digital potentiometer, from <u>Analog Devices</u>. This IC consists of the control logic and a resistors stream (i.e. 1024

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ISO 27001: 2013 certification of informational security management system.
ISO 14001: 2015 certification of environmental management system.
OHSAS 18001: 2008 certification of occupational health and safety management system.



ISO 9001: 2015 certification of quality management system (QMS).

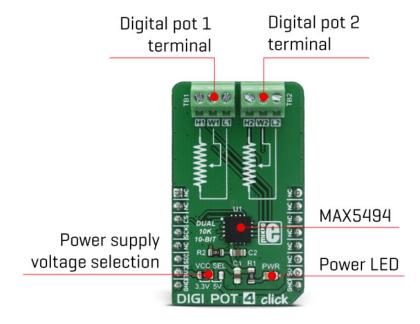


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equal resistors serially connected) through which the wiper is moving. The end-to-end resistance of the resistors on the used IC is  $10K\Omega$ . The wiper movement is done by writing 10bit data into the wiper registers, resulting in 1024 discrete positions the wiper can take. All three terminals of the digital pot are routed to the IC terminals and further to the onboard connectors, for easy and secure connecting to the rest of the circuit. The MAX5494 contains two such potentiometers, routed to the click board screw terminals. Depending on the output impedance to which the wiper is connected, it is possible that the voltage drop may occur while switching positions, therefore it is not recommended to use it as the variable resistor.

After the power on, the content of the EEPROM NV memory will be copied to the volatile RAM, used as the shift register for the wiper position. This volatile memory register directly controls the wiper position. The wiper can be positioned by writing data into this register. The EEPROM NV registers are only written if requested, by using the specific write command. This way, the EEPROM lifecycle is prolonged, although it can withstand up to 200000 read/write cycles.



All the communication with the control logic of the MAX5494 is done through the SPI, so all the SPI signals are routed to the appropriate mikroBUS $^{\text{m}}$  pins. The CS pin is held high, preventing the SPI communication, so as always - to initialize the SPI communication, the CS pin needs to be pulled LOW by the MCU.

Besides two connectors used to connect the potentiometer terminals, the click board  $^{\text{m}}$  is equipped with the SMD jumper, used to choose between the 3.3V or 5V operating voltage.

## **Specifications**

Туре	Digital potentiometer
Applications	It can be used for digital volume control or a precise gain and offset adjustment. It can also be used as the LCD digital contrast control, and generally - whenever a precise dual digital potentiometer is required

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On-board modules	MAX5494, a 10bit dual, non-volatile, linear taper, digital potentiometer, from Maxim Integrated
Key Features	Accurate positioning of the wiper, via the 1024 different steps, non-volatile EEPROM memory used for recalling the wiper positions after the power on, very good bandwidth and low THD on input signals
Interface	SPI
Feature	No ClickID
Compatibility	mikroBUS™
Click board size	M (42.9 x 25.4 mm)
Input Voltage	3.3V or 5V

## **Pinout diagram**

This table shows how the pinout on **DIGI POT 4 click** corresponds to the pinout on the mikroBUS<sup>m</sup> socket (the latter shown in the two middle columns).

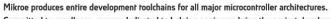
Notes	Pin	mikro™ BUS				Pin	Notes
	NC	1	AN	PWM	16	NC	
	NC	2	RST	INT	15	NC	
SPI Chip Select	CS	3	CS	RX	14	NC	
SPI Clock	SCK	4	SCK	TX	13	NC	
	NC	5	MISO	SCL	12	NC	
SPI Data In	SDI	6	MOSI	SDA	11	NC	
Power Supply	+3.3V	7	3.3V	5V	10	+5V	Power Supply
Ground	GND	8	GND	GND	9	GND	Ground

## **Onboard settings and indicators**

Label	Name	Default	Description
LD1	PWR	-	Power LED indicator
J1	VCC SEL	Left	Power supply voltage selection: left position 3V3, right position 5V
CN1	TB1	-	Digital potentiometer 1 terminal (H1,W1,L1) connection
CN2	TB2	-	Digital potentiometer 2 terminal (H2,W2,L2) connection

### **Software support**

We provide a library for DIGI POT 4 click on our <u>LibStock</u> page, as well as a demo application (example), developed using MikroElektronika <u>compilers</u> and <u>mikroSDK</u>. The provided click



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library is mikroSDK standard compliant. The demo application can run on all the main MikroElektronika <u>development boards</u>.

#### Library description

The library carries two functions which are sufficient to have complete control over DIGI POT 4 click.

Key functions:

void digipot4\_writeReg(uint8\_t Reg, uint16\_t value);- Write data to wiper register void digipot4\_copyReg(uint8\_t Reg);- Copy data to NV memory

#### **Example description**

The application is composed of three sections :

- System Initialization Initializes SPI module and sets CS pin as OUTPUT
- Application Initialization DIGI POT 4 Driver initialization
- Application Task (code snippet) Sequentially sets the wiper position every second.

```
void applicationTask()
{
    digipot4_writeReg(_DIGIPOT4_WIPER_REG_1, 0);
    digipot4_writeReg(_DIGIPOT4_WIPER_REG_2, 0);
    Delay_lsec();
    digipot4_writeReg(_DIGIPOT4_WIPER_REG_1, 512);
    digipot4_writeReg(_DIGIPOT4_WIPER_REG_2, 512);
    Delay_lsec();
    digipot4_writeReg(_DIGIPOT4_WIPER_REG_1, 1023);
    digipot4_writeReg(_DIGIPOT4_WIPER_REG_1, 1023);
    digipot4_writeReg(_DIGIPOT4_WIPER_REG_2, 1023);
    Delay_lsec();
}
```

The full application code, and ready to use projects can be found on our <u>LibStock</u> page.

#### Additional notes and information

Depending on the development board you are using, you may need <u>USB UART click</u>, <u>USB UART 2 click</u> or <u>RS232 click</u> to connect to your PC, for development systems with no UART to USB interface available on the board. The terminal available in all MikroElektronika <u>compilers</u>, or any other terminal application of your choice, can be used to read the message.

#### mikroSDK

This click board is supported with <u>mikroSDK</u> - MikroElektronika Software Development Kit. To ensure proper operation of mikroSDK compliant click board demo applications, mikroSDK

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should be downloaded from the <u>LibStock</u> and installed for the compiler you are using.

For more information about mikroSDK, visit the official page.

#### Resources

mikroBUS™ standard specifications

mikroSDK

Click board™ Catalog

Click Boards™

#### **Downloads**

**DIGI POT 4 click example on Libstock** 

**DIGI POT 4 click schematic** 

MAX5494 datasheet

DIGI POT 4 click 2D and 3D files





