SPM 49 Series
Smart Power Module (SPM)
Inverter, 1200 V, 50 A

NFAL5012L5BT

ON Semiconductor®

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General Description

The NFAL5012L5BT is a smart power module providing a fully−featured, high−performance inverter output stage for AC induction, BLDC, and PMSM motors. These modules integrate optimized gate drive of the built−in IGBTs to minimize EMI and losses, while also providing multiple on−module protection features: under−voltage lockouts, over−current shutdown, temperature sensing, and fault reporting. The built−in, high−speed HVIC requires only a single supply voltage and translates the incoming logic−level gate inputs to high−voltage, high−current drive signals to properly drive the module's internal IGBTs. Separate negative IGBT terminals are available for each phase to support the widest variety of control algorithms.

Features

- 1200 V – 50 A 3-Phase IGBT Inverter, Including Control ICs for Gate Drive and Protections
- Low−Loss, Short−Circuit−Rated IGBTs
- Very Low Thermal Resistance Using Al_2O_3 DBC Substrate
- Built−In Bootstrap Diodes/Resistors
- Separate Open−Emitter Pins from Low−Side IGBTs for Three−Phase Current Sensing
- Built−In NTC Thermistor for Temperature Monitoring and Management
- Adjustable Over−Current Protection via Integrated Sense−IGBTs
- Isolation Rating of 2500 Vrms/1 min
- These Devices are RoHS Compliant

Typical Applications

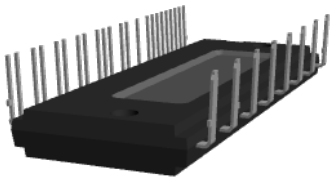
- Motion Control − Industrial Motor (AC 400 V Class)

Integrated Power Functions

- 1200 V – 50 A IGBT Inverter for Three−Phase DC/AC Power Conversion (Refer to Figure 2)

Integrated Drive, Protection, and System Control Functions

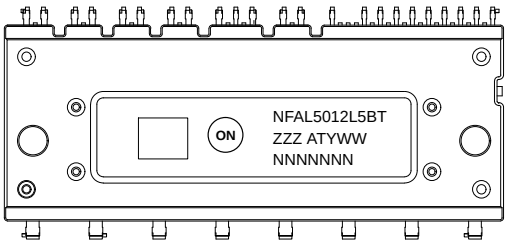
- For Inverter High−Side IGBTs: gate−drive circuit, high−voltage isolated high−speed level−shifting control circuit, Under−Voltage Lock−Out protection (UVLO), available bootstrap circuit example is given in Figures 4 and 16
- For Inverter Low−Side IGBTs: gate-drive circuit, Short−Circuit Protection (SCP) control circuit, Under−Voltage Lock−Out protection (UVLO)
- Fault Signaling: corresponding to UV (low−side supply) and SC faults
- Input Interface: active−HIGH interface, works with 3.3 V/5 V logic, Schmitt−trigger input



3D Package Drawing
(Click to Activate 3D Content)

SPM49−CAB
CASE MODGQ

MARKING DIAGRAM



NFAL5012L5BT	= Specific Device Code
ZZZ	= Lot ID
AT	= Assembly & Test Location
Y	= Year
WW	= Work Week
NNNNNNN	= Serial Number

ORDERING INFORMATION

See detailed ordering and shipping information on page 10 of this data sheet.

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PIN CONFIGURATION

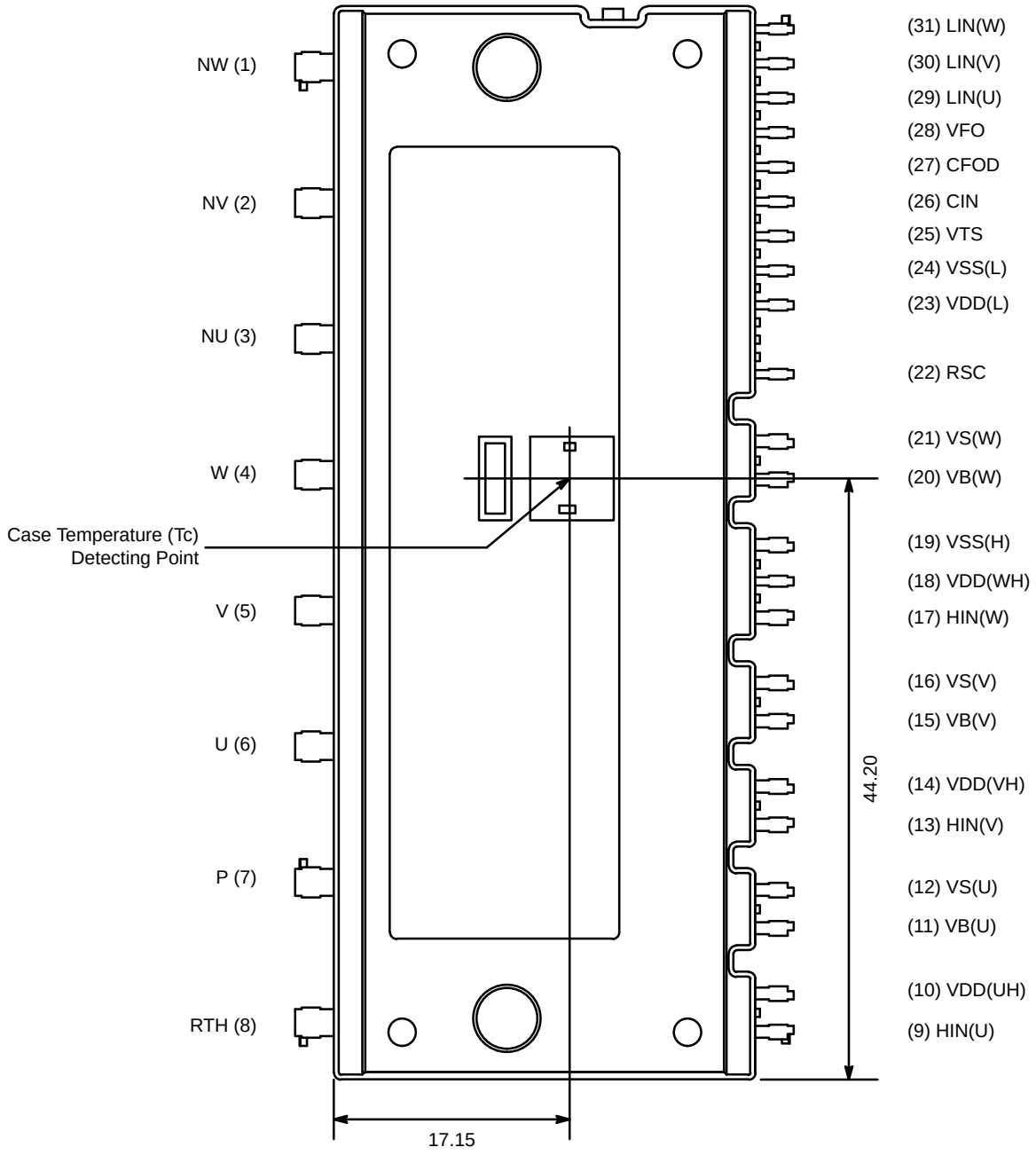


Figure 1. Pin Configuration − Top View

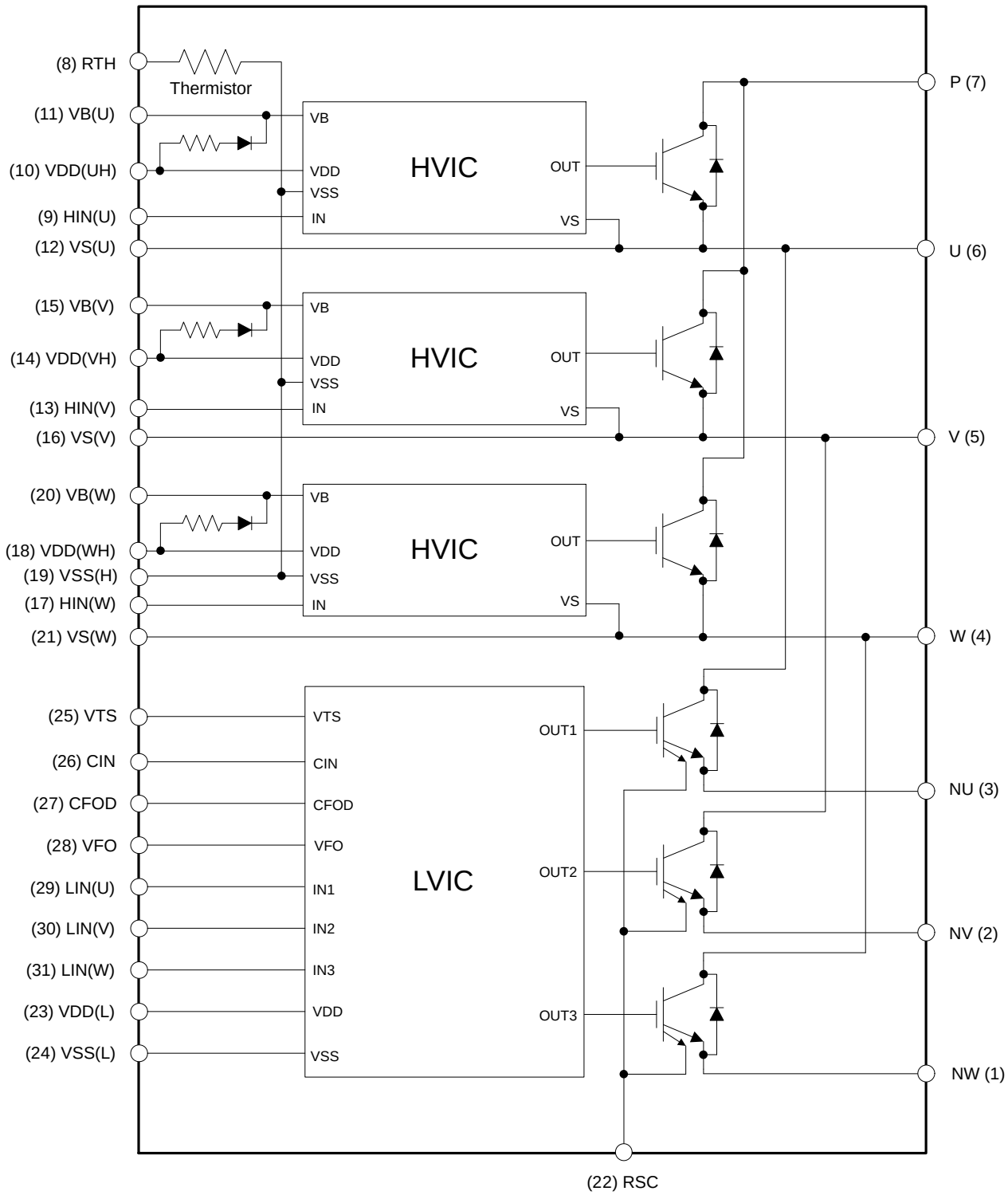
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PIN DESCRIPTION

Pin Number	Pin Name	Pin Description
1	NW	Negative DC−Link Input for W Phase
2	NV	Negative DC−Link Input for V Phase
3	NU	Negative DC−Link Input for U Phase
4	W	Output for W Phase
5	V	Output for V Phase
6	U	Output for U Phase
7	P	Positive DC−Link Input
8	RTH	Series Resistor for Thermistor (Temperature Detection)
9	HIN(U)	Signal Input for High−Side U Phase
10	VDD(UH)	High−Side Bias Voltage for U Phase IC
11	VB(U)	High−Side Bias Voltage for U Phase IGBT Driving
12	VS(U)	High−Side Bias Voltage GND for U Phase IGBT Driving
13	HIN(V)	Signal Input for High−Side V Phase
14	VDD(VH)	High−Side Bias Voltage for V Phase IC
15	VB(V)	High−Side Bias Voltage for V Phase IGBT Driving
16	VS(V)	High−Side Bias Voltage GND for V Phase IGBT Driving
17	HIN(W)	Signal Input for High−Side W Phase
18	VDD(WH)	High−Side Bias Voltage for W Phase IC
19	VSS(H)	High−Side Common Supply Ground, Connected to HVIC
20	VB(W)	High−Side Bias Voltage for W Phase IGBT Driving
21	VS(W)	High−Side Bias Voltage GND for W Phase IGBT Driving
22	RSC	Resistor for Over and Short−Circuit Current Detection
23	VDD(L)	Low−Side Bias Voltage for IC and IGBTs Driving
24	VSS(L)	Low−Side Common Supply Ground, Connected to LVIC
25	VTS	Voltage Output for LVIC Temperature Sensing Unit
26	CIN	Input for Current Protection
27	CFOD	Capacitor for Fault Output Duration Selection
28	VFO	Fault Output
29	LIN(U)	Signal Input for Low−Side U Phase
30	LIN(V)	Signal Input for Low−Side V Phase
31	LIN(W)	Signal Input for Low−Side W Phase

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INTERNAL EQUIVALENT CIRCUIT AND INPUT/OUTPUT PINS



NOTES:

1. Inverter high−side is composed of three normal−IGBTs, freewheeling diodes, and one control IC for each IGBT.
2. Inverter low−side is composed of three sense−IGBTs, freewheeling diodes, and one control IC for each IGBT. It has gate drive and protection functions.
3. Inverter power side is composed of four inverter DC−link input terminals and three inverter output terminals.

Figure 2. Internal Block Diagram

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ABSOLUTE MAXIMUM RATINGS (Tj = 25°C unless otherwise noted)

Symbol	Rating	Conditions	Rating	Unit
INVERTER PART				
VPN	Supply Voltage	Applied between P − NU, NV, NW	900	V
VPN(surge)	Supply Voltage (Surge)	Applied between P − NU, NV, NW	1000	V
Vces	Collector−Emitter Voltage		1200	V
±Ic	Each IGBT Collector Current	Tc = 25°C, Tj ≤ 150°C	50	A
±Icp	Each IGBT Collector Current (Peak)	Tc = 25°C, Tj ≤ 150°C, Under 1 ms Pulse Width (Note 4)	100	A
Pc	Collector Dissipation	Tc = 25°C per One Chip (Note 4)	219	W
Tj	Operating Junction Temperature		−40~150	°C
CONTROL PART				
VDD	Control Supply Voltage	Applied between VDD(H), VDD(L) − VSS	20	V
VBS	High−Side Control Bias Voltage	Applied between VB(U) − VS(U), VB(V) − VS(V), VB(W) − VS(W)	20	V
VIN	Input Signal Voltage	Applied between HIN(U), HIN(V), HIN(W), LIN(U), LIN(V), LIN(W) − VSS	−0.5~VDD+0.5	V
VFO	Fault Output Supply Voltage	Applied between VFO − VSS	−0.5~VDD+0.5	V
IFO	Fault Output Current	Sink Current at VFO pin	5	mA
VCIN	Current Sensing Input Voltage	Applied between CIN − VSS	−0.5~VDD+0.5	V
Tj	Operating Junction Temperature		−40~150	°C
BOOSTSTRAP DIODE PART				
VRRM	Maximum Repetitive Reverse Voltage		1200	V
Tj	Operating Junction Temperature		−40~150	°C
TOTAL SYSTEM				
VPN(PROT)	Self−Protection Supply Voltage Limit (Short−Circuit Protection Capability)	VDD = VBS = 13.5~16.5 V, Tj = 150°C, Vces < 1200 V, Non-Repetitive, < 2 μs	800	V
Tc	Module Case Operation Temperature	See Figure 1	−40~125	°C
Tstg	Storage Temperature		−40~125	°C
Viso	Isolation Voltage	60 Hz, Sinusoidal, AC 1 Minute, Connection Pins to Heat Sink Plate	2500	Vrms

Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

4. These values had been made an acquisition by the calculation considered to design factor.

THERMAL RESISTANCE

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
Rth(j-c)Q	Junction−to−Case Thermal Resistance (Note 5)	Inverter IGBT Part (per 1/6 module)	−	−	0.57	°C/W
Rth(j-c)F		Inverter FWDi Part (per 1/6 module)	−	−	1.15	°C/W

5. For the measurement point of case temperature (Tc), please refer to Figure 1. DBC discoloration and Picker Circle Printing allowed, please refer to application note AN−9190 (Impact of DBC Oxidation on SPM® Module Performance).

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ELECTRICAL CHARACTERISTICS (Tj = 25°C unless otherwise specified.)

Symbol		Parameter	Conditions		Min	Typ	Max	Unit
INVERTER PART								
VCE(sat)		Collector−Emitter Saturation Voltage	VDD = VBS = 15 V IN = 5 V	Ic = 50 A, Tj = 25°C	−	2.00	2.50	V
VF		FWDi Forward Voltage	IN = 0 V	Ic = −50 A, Tj = 25°C	−	2.30	2.90	V
HS	ton	Switching Times	VPN = 600 V, VDD = 15 V, Ic = 50 A Tj = 25°C IN = 0 V ↔ 5 V, Inductive Load See Figure 3 (Note 6)		1.10	1.70	2.30	μs
	tc(on)				−	0.25	0.55	μs
	toff				−	1.50	2.10	μs
	tc(off)				−	0.15	0.45	μs
	trr				−	0.25	−	μs
LS	ton		VPN = 600 V, VDD = 15 V, Ic = 50 A Tj = 25°C IN = 0 V ↔ 5 V, Inductive Load See Figure 3 (Note 6)		1.00	1.60	2.20	μs
	tc(on)				−	0.25	0.55	μs
	toff				−	1.40	2.00	μs
	tc(off)				−	0.15	0.45	μs
	trr				−	0.25	−	μs
Ices		Collector−Emitter Leakage Current	Vce = Vces		−	−	1	mA
CONTROL PART								
IQDDH		Quiescent VDD Supply Current	VDD(UH,VH,WH) = 15 V, HIN(U,V,W) = 0 V	VDD(UH) − VSS(H), VDD(VH) − VSS(H), VDD(WH) − VSS(H)	−	−	0.30	mA
IQDDL			VDD(L) = 15 V, LIN(U,V,W) = 0 V	VDD(L) − VSS(L)	−	−	3.50	mA
IPDDH		Operating VDD Supply Current	VDD(UH,VH,WH) = 15 V, FPWM = 20 kHz, Duty = 50%, Applied to one PWM Signal Input for High−Side	VDD(UH) − VSS(H), VDD(VH) − VSS(H), VDD(WH) − VSS(H)	−	−	0.40	mA
IPDDL			VDD(L) = 15 V, FPWM = 20 kHz, Duty = 50%, Applied to one PWM Signal Input for Low−Side	VDD(L) − VSS(L)	−	−	7.50	mA
IQBS		Quiescent VBS Supply Current	VDD = VBS = 15 V, HIN(U,V,W) = 0 V	VB(U) − VS(U), VB(V) − VS(V), VB(W) − VS(W)	−	−	0.30	mA
IPBS		Operating VBS Supply Current	VDD = VBS = 15 V, FPWM = 20 kHz, Duty = 50%, Applied to one PWM Signal Input for High−Side	VB(U) − VS(U), VB(V) − VS(V), VB(W) − VS(W)	−	−	6.50	mA
VFOH		Fault Output Voltage	VDD = 15 V, CIN = 0 V, VFO Circuit: 10 kΩ to 5 V Pull−up		4.90	−	−	V
VFOL			VDD = 15 V, CIN = 1 V, IFO = 1 mA		−	−	0.95	V
ISEN		Sensing Current of Each Sense IGBT	VDD = 15 V, LIN = 5 V, Rsc = 0 Ω, No Connection of Shunt Resistor at NU, NV, NW Terminal	Ic = 50 A	−	22	−	mA
VSC(ref)		Short Circuit Trip Level	VDD = 15 V	CIN − VSS(L)	0.46	0.48	0.50	V
ISC		Short Circuit Current Level for Trip	Rsc = 18 Ω (±1%), No Connection of Shunt Resistor at NU, NV, NW Terminal (Note 7)		75	−	−	A

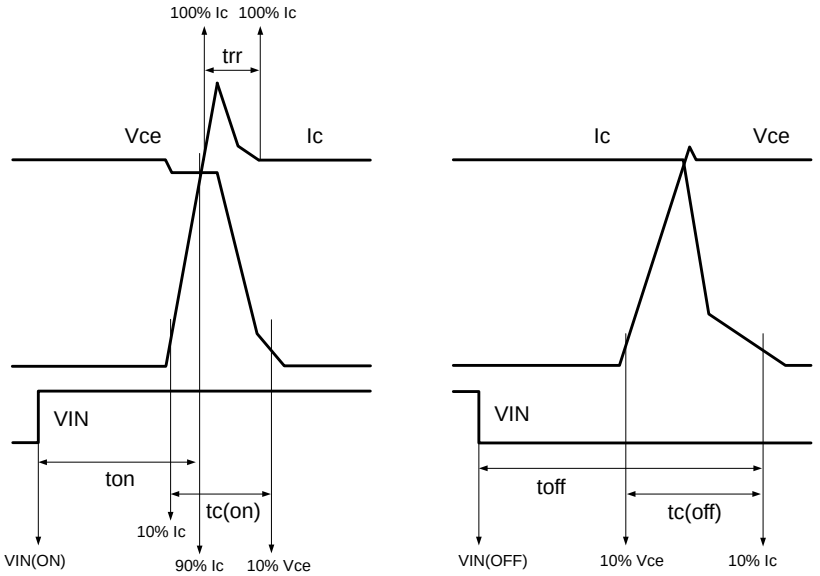
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ELECTRICAL CHARACTERISTICS (Tj = 25°C unless otherwise specified.) (continued)

Symbol	Parameter	Conditions		Min	Typ	Max	Unit
CONTROL PART							
UVDDD	Supply Circuit Under-Voltage Protection	Detection Level		10.3	−	12.5	V
UVDDR		Reset Level		10.8	−	13.0	V
UVBSD		Detection Level		10.0	−	12.0	V
UVBSR		Reset Level		10.5	−	12.5	V
VIN(ON)	ON Threshold Voltage	Applied between HIN(U,V,W) − VSS(H), LIN(U,V,W) − VSS(L)		−	−	2.6	V
VIN(OFF)	OFF Threshold Voltage			0.8	−	−	V
VTS	Voltage Output for LVIC Temperature Sensing Unit	VDD(L) = 15 V, TLVIC = 25°C See Figure 6 and 7 (Note 8)		0.909	1.030	1.151	V
tFOD	Fault-Out Pulse Width	CFOD = 22 nF (Note 9)		1.6	−	−	ms
RTH	Resistance of Thermistor	At TTH = 25°C	See Figure 8 (Note 10)	−	47	−	kΩ
		At TTH = 100°C		−	2.9	−	kΩ
BOOTSTRAP DIODE/RESISTOR PART							
VF	Forward Voltage	If = 0.1 A, Tj = 25°C	See Figure 9	2.1	2.5	2.9	V
RBOOT	Bootstrap Resistor			12.5	15.5	18.5	Ω

Product parametric performance is indicated in the Electrical Characteristics for the listed test conditions, unless otherwise noted. Product performance may not be indicated by the Electrical Characteristics if operated under different conditions.

6. ton and toff include the propagation delay of the internal drive IC. tc(on) and tc(off) are the switching times of IGBT under the given gate−driving condition internally. For the detailed information, please see Figure 3.
7. Short−circuit current protection functions only at the low−sides because the sense current is divided from main current at low−side IGBTs. Inserting the shunt resistor for monitoring the phase current at NU, NV, NW terminal, the trip level of the short−circuit current is changed.
8. TLVIC is the temperature of LVIC itself. VTS is only for sensing temperature of LVIC and cannot shutdown IGBTs automatically. The relationship between VTS voltage output and LVIC temperature is described in Figure 6. It is recommended to add a ceramic capacitor of 10 nF or more between VTS and VSS (Signal Ground) to make the VTS more stable as described in Figure 7. Refer to the application note for this products about usage of VTS.
9. The fault−out pulse width tFOD depends on the capacitance value of CFOD according to the following approximate equation: $tFOD = 0.1 \times 10^6 \times CFOD$ [s].
10. TTH is the temperature of thermistor itself. To know case temperature (Tc), conduct experiments considering the application.



(a) turn-on **(b) turn-off**

Figure 3. Switching Time Definition

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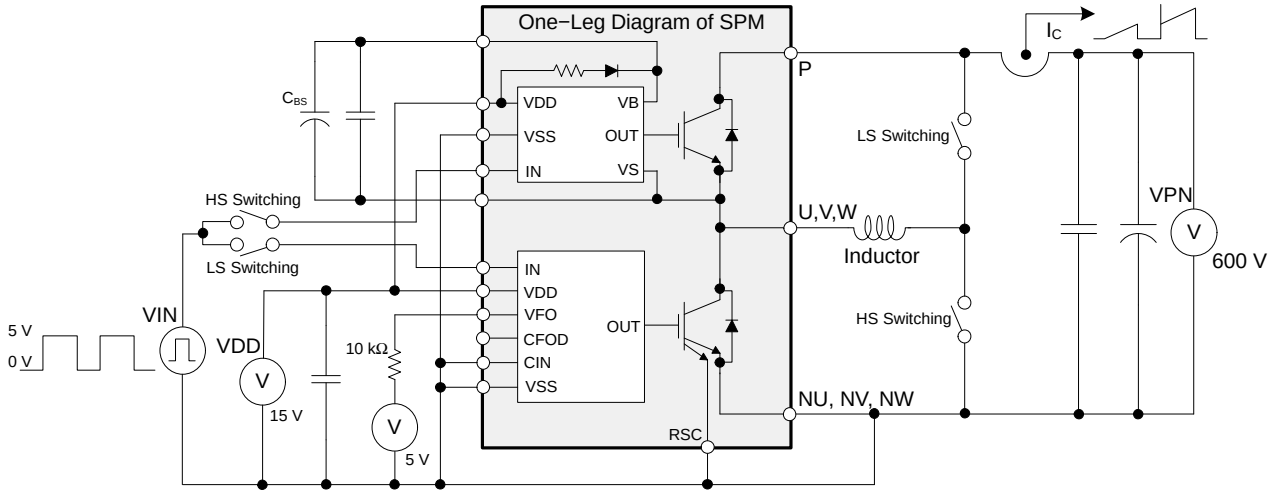


Figure 4. Example Circuit of Switching Test

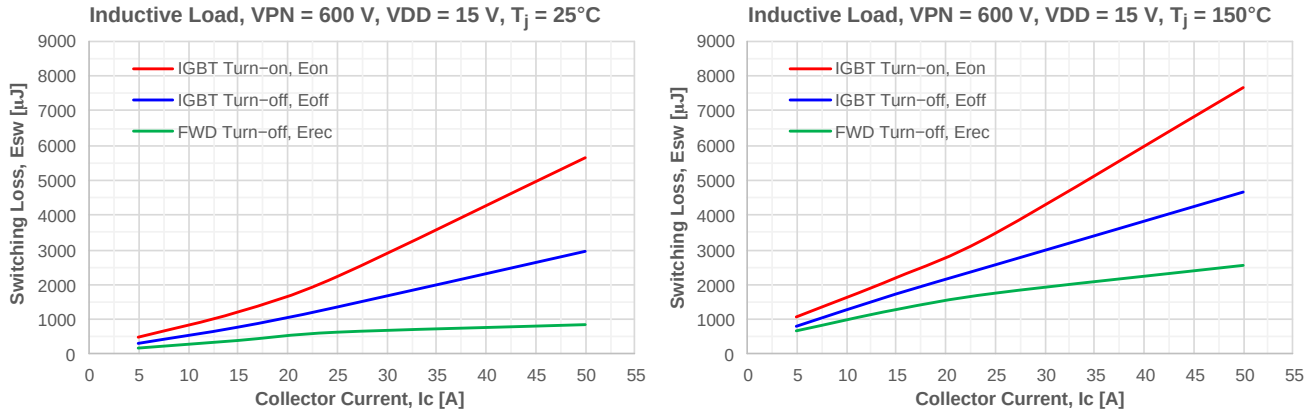


Figure 5. Switching Loss Characteristics

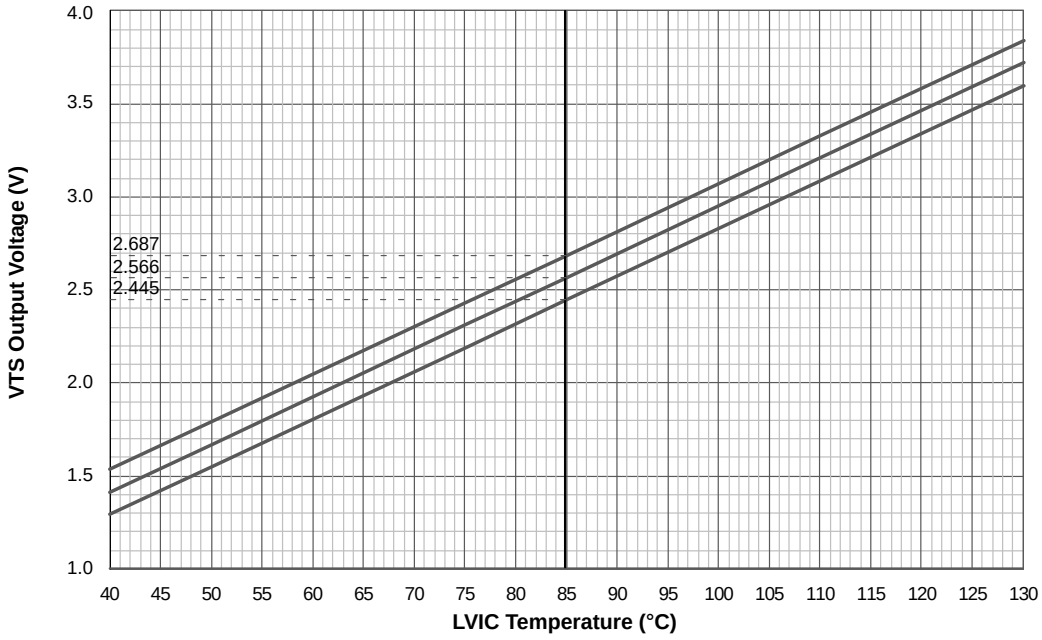


Figure 6. Temperature Profile of VTS

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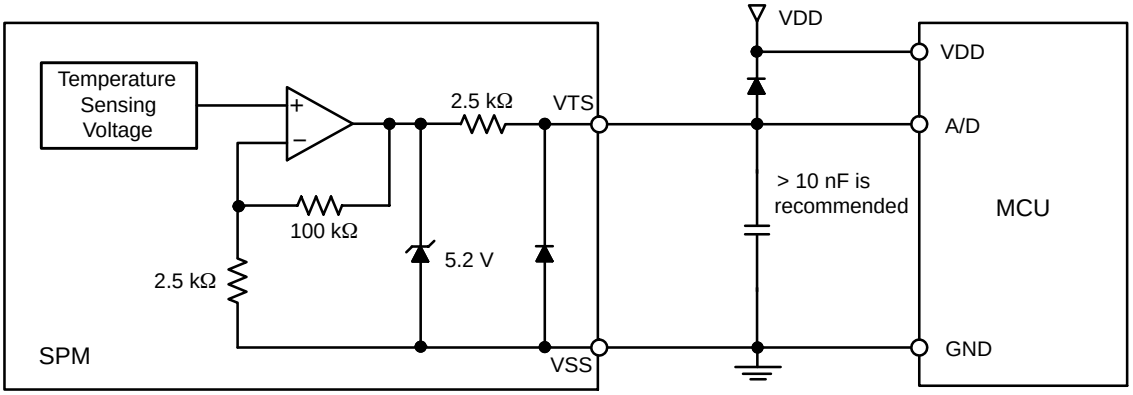


Figure 7. Internal Block Diagram and Interface Circuit of VTS

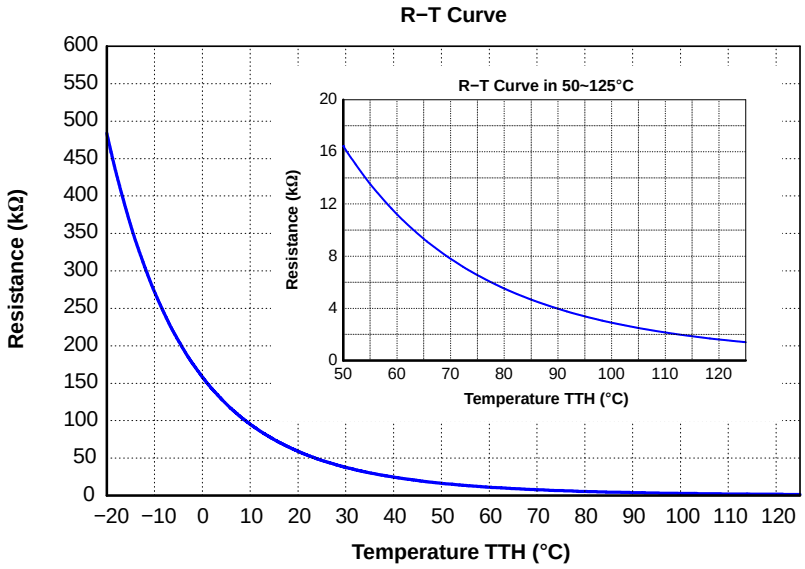


Figure 8. R−T Curve of Built-in Thermistor

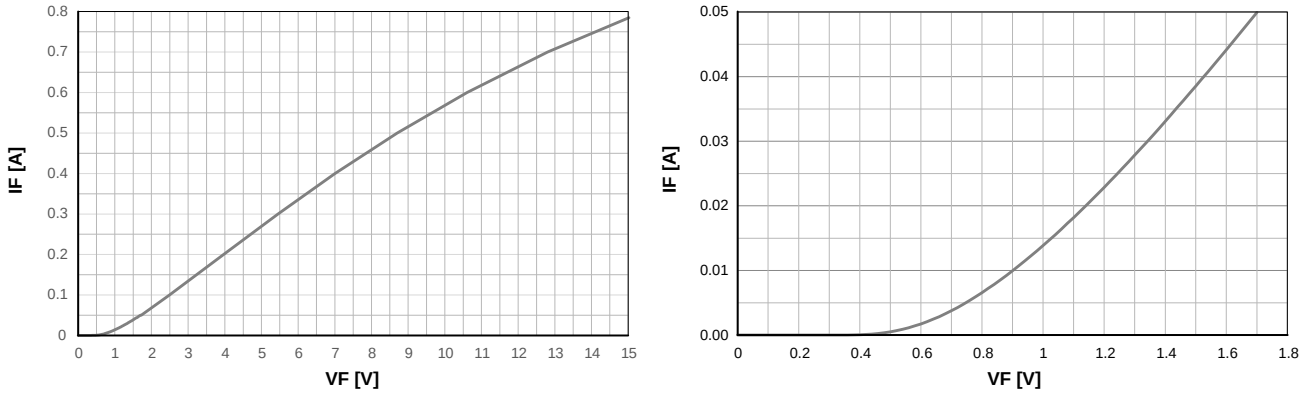


Figure 9. Characteristics of Bootstrap Diode/Resistor (Right Figure is Enlarged Figure)

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RECOMMENDED OPERATING RANGES

Symbol	Parameter	Conditions		Min	Typ	Max	Unit
VPN	Supply Voltage	Applied between P−NU, NV, NW		350	600	800	V
VDD	Control Supply Voltage	Applied between VDD(UH,VH,WH)−VSS(H), VDD(L)−VSS(L)		13.5	15.0	16.5	V
VBS	High−Side Control Bias Voltage	Applied between VB(U)−VS(U), VB(V)−VS(V), VB(W)−VS(W)		13.0	15.0	18.5	V
dVDD/dt, dVBS/dt	Control Supply Variation			−1	−	+1	V/μs
tdead	Blanking Time for Preventing Arm − Short	For Each Input Signal		2.0	−	−	μs
FPWM	PWM Input Signal	−40°C ≤ Tc ≤ 125°C, −40°C ≤ Tj ≤ 150°C		−	−	20	kHz
Io	Allowable r.m.s. Output Current	VPN = 600 V, VDD = VBS = 15 V, P.F = 0.8, Sinusoidal PWM Tc ≤ 125°C, Tj ≤ 150°C (Note 11)	FPWM = 5 kHz	−	−	25	Arms
			FPWM = 15 kHz	−	−	14	
VSEN	Voltage for Current Sensing	Applied between NU, NV, NW−VSS (Including Surge Voltage)		−5.0	−	+5.0	V
PWIN(ON)	Minimum Input Pulse Width	(Note 12)		1.5	−	−	μs
PWIN(OFF)		VDD = VBS = 15 V, I_C ≤ 100 A, Wiring Inductance between NU, NV, NW and DC Link N < 10 nH (Note 12)		2.0	−	−	
Tj	Junction Temperature			−40	−	+150	°C

Functional operation above the stresses listed in the Recommended Operating Ranges is not implied. Extended exposure to stresses beyond the Recommended Operating Ranges limits may affect device reliability.

11. This allowable output current value is the reference data for the safe operation of this product. This may be different from the actual application and operating condition.
12. This product might not make output response if input pulse width is less than the recommended value.

PACKAGE MARKING AND ORDERING INFORMATION

Device	Device Marking	Package	Shipping
NFAL5012L5BT	NFAL5012L5BT	SPM49−CAB	6 Units/Tube

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MECHANICAL CHARACTERISTICS AND RATINGS

Parameter	Conditions		Min	Typ	Max	Unit
Device Flatness	See Figure 10		−50	−	100	μm
Mounting Torque	Mounting Screw: M4 See Figure 11	Recommended 1.18 N · m	0.98	1.18	1.47	N · m
		Recommended 12.03 kg · cm	10.00	12.03	14.98	kg · cm
Terminal Pulling Strength	Load 19.6 N		10	−	−	s
Terminal Bending Strength	Load 9.8 N, 90 degrees Bend		2	−	−	times
Weight			−	44.5	−	g

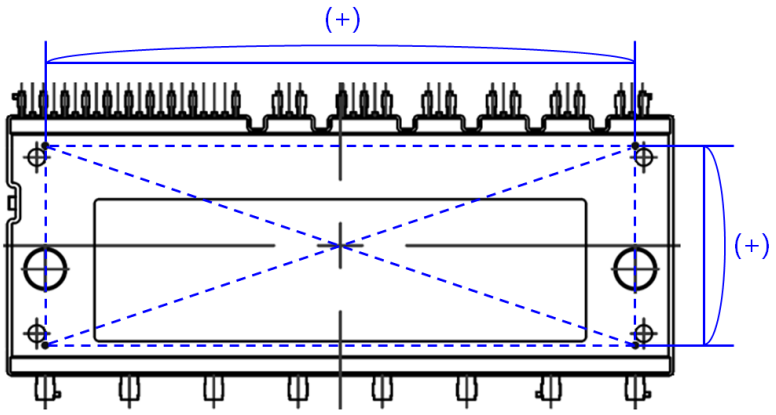
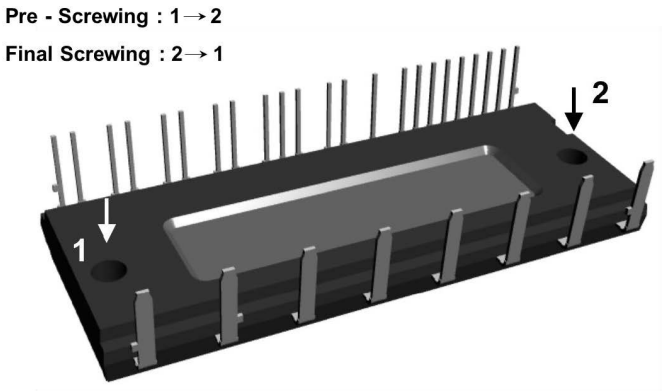


Figure 10. Flatness Measurement Position



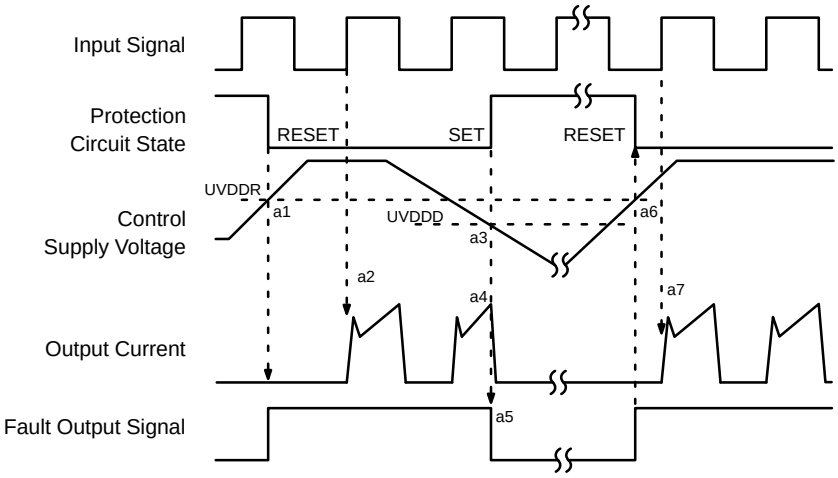
NOTES:

13. Do not over torque when mounting screws. Too much mounting torque may cause DBC cracks, as well as bolts and Al heat-sink destruction.
14. Avoid one−sided tightening stress. Figure 11 shows the recommended torque order for the mounting screws. Uneven mounting can cause the DBC substrate of package to be damaged. The pre−screwing torque is set to 20~30% of maximum torque rating.

Figure 11. Mounting Screws Torque Order

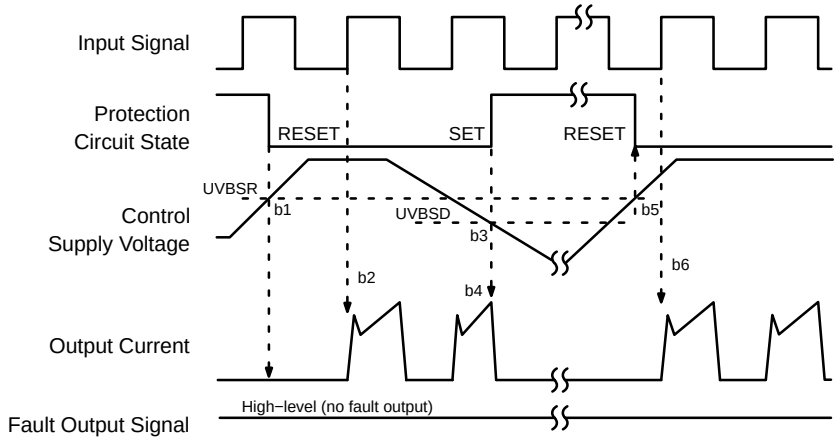
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TIME CHARTS OF SPMs PROTECTIVE FUNCTION



a1: Control supply voltage rises: after the voltage rises UVDDR, the circuits start to operate when the next input is applied.
a2: Normal operation: IGBT ON and carrying current.
a3: Under−voltage detection (UVDDD).
a4: IGBT OFF in spite of control input condition.
a5: Fault output operation starts with a fixed pulse width according to the condition of the external capacitor CFOD.
a6: Under−voltage reset (UVDDR).
a7: Normal operation: IGBT ON and carrying current by triggering next signal from LOW to HIGH.

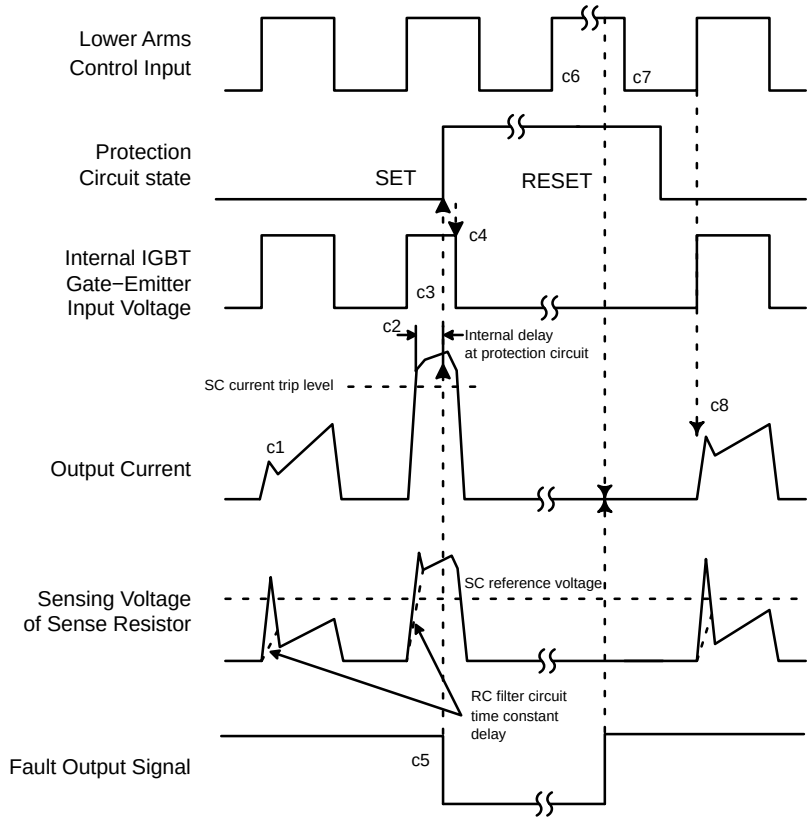
Figure 12. Under-voltage Protection (Low-side)



b1: Control supply voltage rises: after the voltage reaches UVBSR, the circuits start to operate when the next input is applied.
b2: Normal operation: IGBT ON and carrying current.
b3: Under−voltage detection (UVBSD).
b4: IGBT OFF in spite of control input condition, but there is no fault output signal.
b5: Under−voltage reset (UVBSR).
b6: Normal operation: IGBT ON and carrying current by triggering next signal from LOW to HIGH.

Figure 13. Under-voltage Protection (High-side)

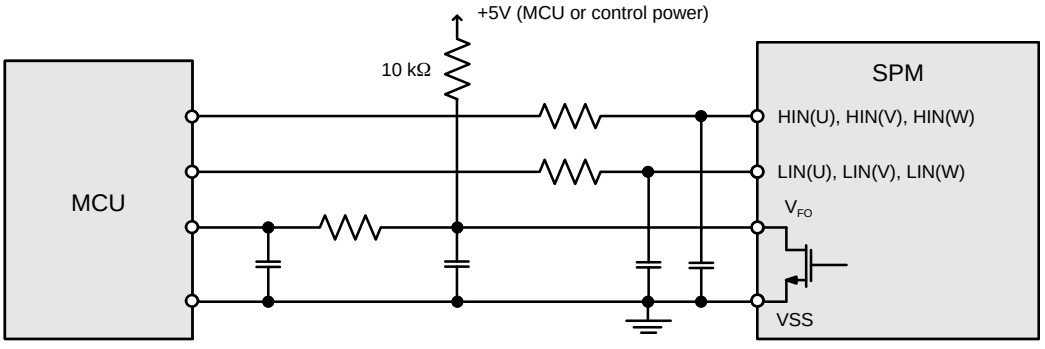
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(With the external sense resistance and RC filter connection)
c1: Normal operation: IGBT ON and carrying current.
c2: Short−circuit current detection (SC trigger).
c3: All low−side IGBTs gate are hard interrupted.
c4: All low−side IGBTs turn OFF.
c5: Fault output operation starts with a fixed pulse width according to the condition of the external capacitor CFOD.
c6: Input HIGH − IGBT ON state, but during the active period of fault output, the IGBT doesn't turn ON.
c7: Fault output operation finishes, but IGBT doesn't turn on until triggering the next signal from LOW to HIGH.
c8: Normal operation: IGBT ON and carrying current.

Figure 14. Short−circuit Current Protection (Low−side Operation Only)

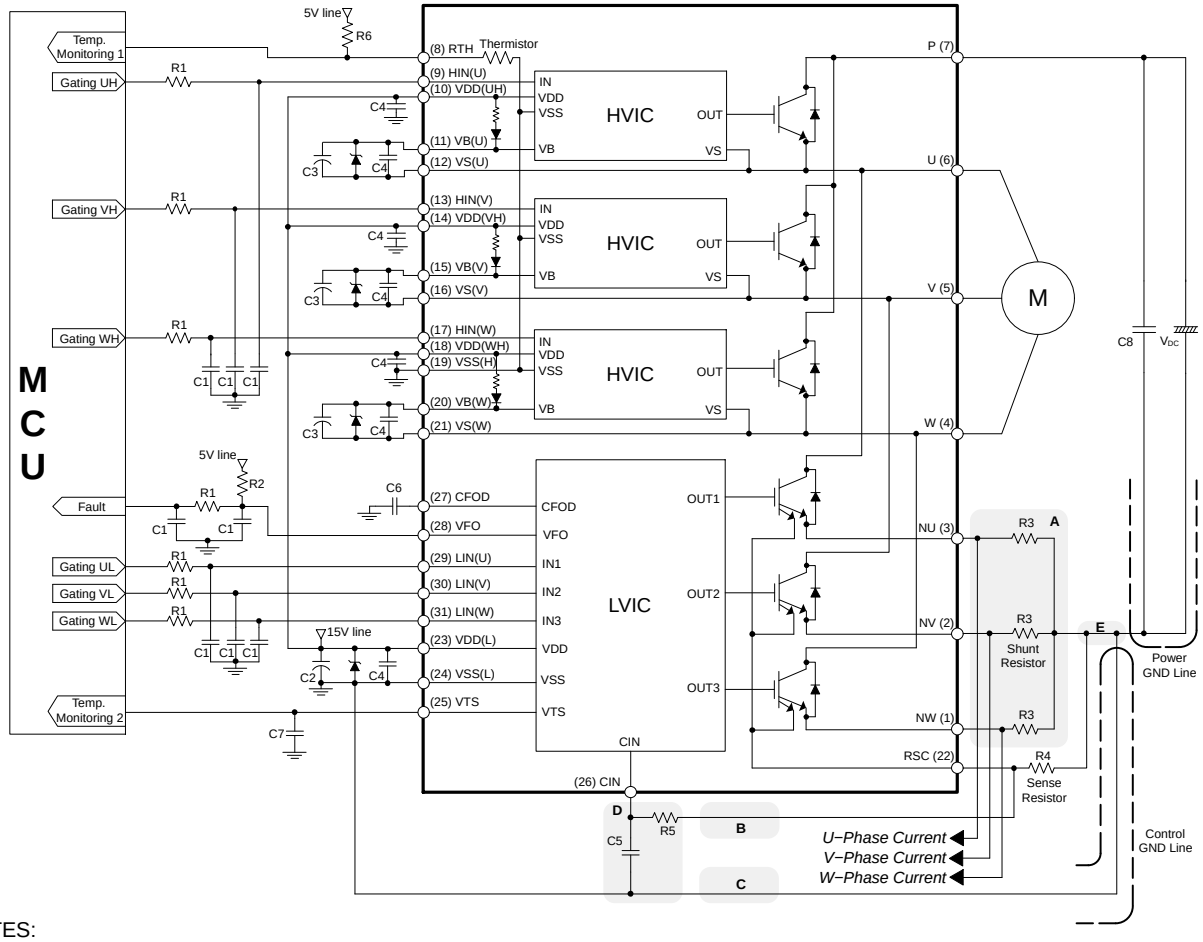
INPUT/OUTPUT INTERFACE CIRCUIT



NOTE:
15. RC coupling at each input might change depending on the PWM control scheme used in the application and the wiring impedance of the application's printed circuit board. The input signal section of the SPM49 product integrates 5 kΩ (typ.) pull−down resistor. Therefore, when using an external filtering resistor, please pay attention to the signal voltage drop at input terminal.

Figure 15. Recommended MCU I/O Interface Circuit

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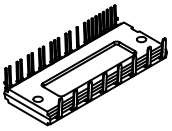
NOTES:

16. To avoid malfunction, the wiring of each input should be as short as possible (less than 2−3 cm).
17. VFO output is an open−drain type. This signal line should be pulled up to the positive side of the MCU or control power supply with a resistor that makes IFO up to 1 mA. Please refer to Figure 15.
18. Fault out pulse width can be adjusted by capacitor C6 connected to the CFOD terminal.
19. Input signal is active−HIGH type. There is a 5 kΩ resistor inside the IC to pull−down each input signal line to GND. RC coupling circuits should be adopted for the prevention of input signal oscillation. R1C1 time constant should be selected in the range 50~150 ns (recommended R1 = 100 Ω, C1 = 1 nF).
20. Each wiring pattern inductance of point A should be minimized (recommend less than 10 nH). Use the shunt resistor R3 of surface mounted (SMD) type to reduce wiring inductance. To prevent malfunction, wiring of point E should be connected to the terminal of the shunt resistor R3 as close as possible.
21. To insert the shunt resistor to measure each phase current at NU, NV, NW terminal, it makes to change the trip level ISC about the short-circuit current.
22. To prevent errors of the protection function, the wiring of points B, C, and D should be as short as possible. The wiring of B between CIN filter and RSC terminal should be divided at the point that is close to the terminal of sense resistor R4.
23. For stable protection function, use the sense resistor R4 with resistance variation within 1% and low inductance value.
24. In the short−circuit protection circuit, select the R5C5 time constant in the range 1.5~2.0 μs. R5 should be selected with a minimum of 10 times larger resistance than sense resistor R4. Do enough evaluation on the real system because short-circuit protection time may vary wiring pattern layout and value of the R5C5 time constant.
25. Each capacitor should be mounted as close to the pins of the SPM product as possible.
26. To prevent surge destruction, the wiring between the smoothing capacitor C8 and the P & GND pins should be as short as possible. The use of a high−frequency non−inductive capacitor of around 0.1~0.22 μF between the P & GND pins is recommended.
27. Relays are used in most systems of electrical equipment in industrial application. In these cases, there should be sufficient distance between the MCU and the relays.
28. The Zener diode or transient voltage suppressor should be adopted for the protection of ICs from the surge destruction between each pair of control supply terminals (recommended Zener diode is 20~22 V/1 W, which has the lower Zener impedance characteristic than about 15 Ω).
29. C2 of around seven times larger than bootstrap capacitor C3 is recommended.
30. Please choose the electrolytic capacitor with good temperature characteristic in C3. Choose 0.1~0.2 μF R−category ceramic capacitors with good temperature and frequency characteristics in C4.

Figure 16. Typical Application Circuit

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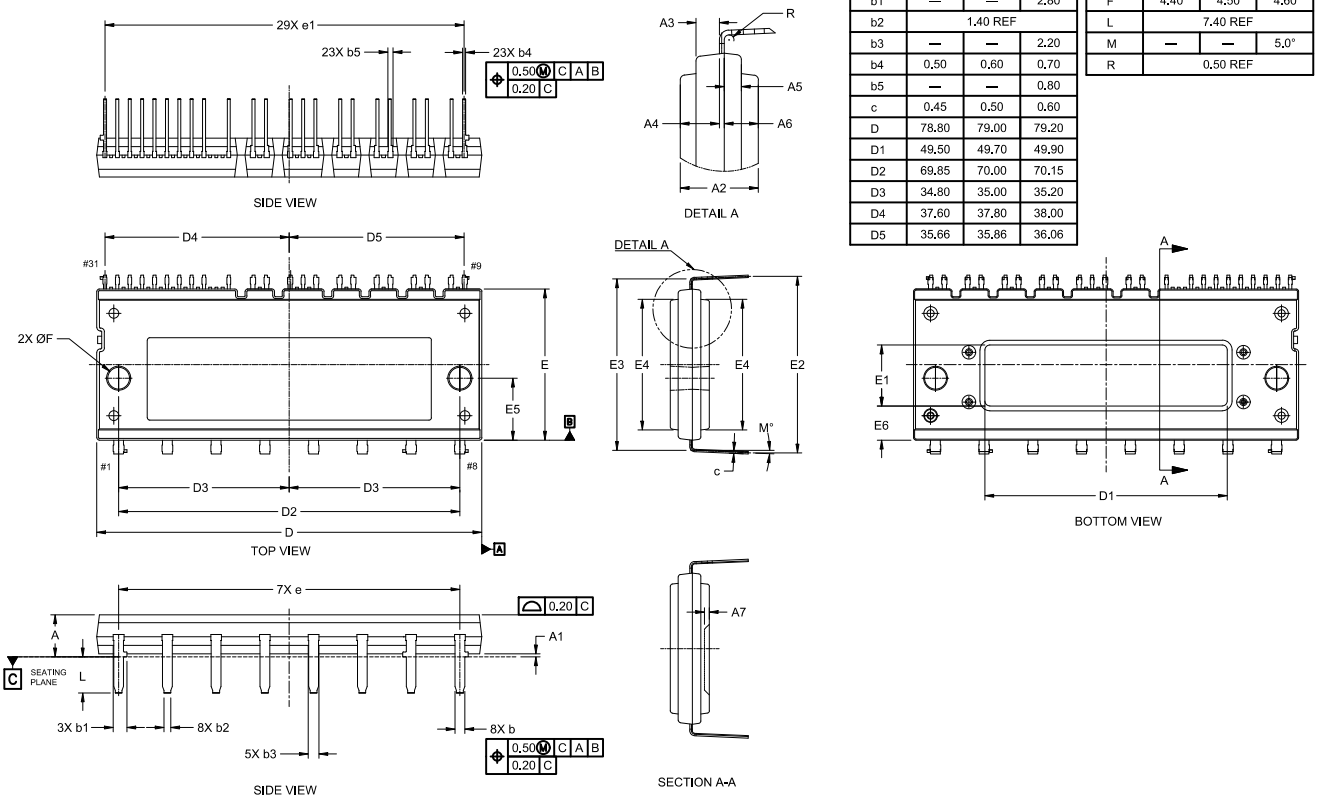
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CASE MODGQ
ISSUE O

DATE 06 DEC 2018

NOTES:
1. DIMENSIONING AND TOLERANCING PER. ASME Y14.5M, 2009.
2. CONTROLLING DIMENSION: MILLIMETERS
3. DIMENSION b and c APPLY TO THE PLATED LEADS AND ARE MEASURED BETWEEN 1.00 AND 2.00 FROM THE LEAD TIP.
4. POSITION OF THE LEAD IS DETERMINED AT THE BASE OF THE LEAD WHERE IT EXITS THE PACKAGE BODY.

DIM	MILLIMETERS		
	MIN.	NOM.	MAX.
A	8.40	8.60	8.80
A1	0.40	0.60	0.80
A2	7.90	8.00	8.10
A3	2.30	2.40	2.50
A4	3.90	4.00	4.10
A5	1.65	1.75	1.85
A6	3.40	3.50	3.60
A7	1.00 REF		
b	1.90	2.00	2.10
b1	—	—	2.80
b2	1.40 REF		
b3	—	—	2.20
b4	0.50	0.60	0.70
b5	—	—	0.80
c	0.45	0.50	0.60
D	78.80	79.00	79.20
D1	49.50	49.70	49.90
D2	69.85	70.00	70.15
D3	34.80	35.00	35.20
D4	37.60	37.80	38.00
D5	35.66	35.86	36.06

DIM	MILLIMETERS		
	MIN.	NOM.	MAX.
E	30.80	31.00	31.20
E1	12.30	12.50	12.70
E2	35.75	36.20	36.65
E3	35.17 REF		
E4	26.60	26.80	27.00
E5	12.55	12.70	12.85
E6	6.80	7.00	7.20
e	10.00 BSC		
e1	2.54 BSC		
F	4.40	4.50	4.60
L	7.40 REF		
M	—	—	5.0°
R	0.50 REF		



GENERIC MARKING DIAGRAM*

XXXXXXXXXXX
ZZZ ATYWW
NNNNNNN

XXXX = Specific Device Code
ZZZ = Assembly Lot Code
AT = Assembly & Test Location
Y = Year
W = Work Week
NNN = Serial Number

*This information is generic. Please refer to device data sheet for actual part marking. Pb−Free indicator, “G” or microdot “▪”, may or may not be present. Some products may not follow the Generic Marking.

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