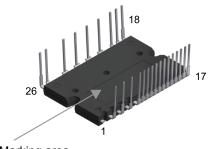
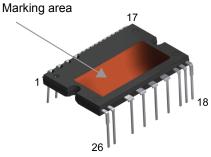


# SLLIMM - 2<sup>nd</sup> series IPM, 3-phase inverter, 35 A, 600 V short-circuit rugged IGBT





SDIP2B-26L type L1



#### Product status link

STGIB30M60TS-L

Product summary				
Order code STGIB30M60TS-L				
Marking GIB30M60TS-L				
Package	SDIP2B-26L type L1			
Packing	Tube			

#### **Features**

- IPM 35 A, 600 V 3-phase IGBT inverter bridge including 2 control ICs for gate driving and freewheeling diodes
- 3.3 V, 5 V TTL/CMOS inputs with hysteresis
- · Internal bootstrap diode
- · Under-voltage lockout of gate drivers
- · Smart shutdown function
- · Short-circuit protection
- Shutdown input/fault output
- · Separate open emitter outputs
- · Built-in temperature sensor
- · Comparator for fault protection
- Short-circuit rugged TFS IGBTs
- Very fast, soft recovery diodes
- 85 kΩ NTC UL 1434 CA 4 recognized
- Fully isolated package
- Isolation rating of 1500 Vrms/min
- UL recognition: UL 1557, file E81734

### **Applications**

- · 3-phase inverters for motor drives
- Home appliances such as washing machines, refrigerators, air conditioners and sewing machines

### **Description**

This second series of SLLIMM (small low-loss intelligent molded module) provides a compact, high-performance AC motor drive in a simple, rugged design. It combines new ST proprietary control ICs (one LS and one HS driver) with an improved short-circuit rugged trench gate field-stop (TFS) IGBT, making it ideal for motor drives operating up to 20 kHz in hard-switching circuitries. SLLIMM is a trademark of STMicroelectronics.



# 1 Internal schematic and pin description

NC(1) (26)T1 VbootU(2) (25)T2 VbootV(3) VbootW(4) (24)P HinU(5) (23)U HinV(6) HinW(7) (22)VVccH(8) (21)W GND(9) H-side LinU(10) LinV(11) LinW(12) (20)NU VccL(13) SD/OD(14) )(19)NV Cin(15) GND(16) )(18)NW TSO(17) L-side

Figure 1. Internal schematic diagram and pin configuration

GIPG120520140842FSR

page 2/24

DS11296 - Rev 6

Downloaded from Arrow.com.



Table 1. Pin description

Pin	Symbol	Description
1	NC	-
2	VBOOTu	Bootstrap voltage for U phase
3	VBOOTv	Bootstrap voltage for V phase
4	VBOOTw	Bootstrap voltage for W phase
5	HINu	High-side logic input for U phase
6	HINv	High-side logic input for V phase
7	HINw	High-side logic input for W phase
8	VCCH	High-side low voltage power supply
9	GND	Ground
10	LINu	Low-side logic input for U phase
11	LINv	Low-side logic input for V phase
12	LINw	Low-side logic input for W phase
13	VCCL	Low-side low voltage power supply
14	SD /OD	Shutdown logic input (active low) / open-drain (comparator output)
15	CIN	Comparator input
16	GND	Ground
17	TSO	Temperature sensor output
18	NW	Negative DC input for W phase
19	NV	Negative DC input for V phase
20	NU	Negative DC input for U phase
21	W	W phase output
22	V	V phase output
23	U	U phase output
24	Р	Positive DC input
25	T2	NTC thermistor terminal 2
26	T1	NTC thermistor terminal 1



# 2 Absolute maximum ratings

 $T_J$  = 25 °C unless otherwise noted.

Table 2. Inverter parts

Symbol	Parameter	Value	Unit
$V_{PN}$	Supply voltage among P -N <sub>U</sub> , -N <sub>V</sub> , -N <sub>W</sub>	450	V
V <sub>PN(surge)</sub>	Supply voltage surge among P -N <sub>U</sub> , -N <sub>V</sub> , -N <sub>W</sub>	500	V
V <sub>CES</sub>	Collector-emitter voltage each IGBT	600	V
ш.	Continuous collector current each IGBT (T <sub>C</sub> = 25 °C)	35	Α
±l <sub>C</sub>	Continuous collector current each IGBT (T <sub>C</sub> = 80 °C)	30	
±l <sub>CP</sub>	Peak collector current each IGBT (less than 1 ms)	70	Α
P <sub>TOT</sub>	Total power dissipation at T <sub>C</sub> =25 °C each IGBT	125	W
t <sub>scw</sub>	Short circuit withstand time, V <sub>CE</sub> = 300 V, T <sub>J</sub> = 125 °C,		μs

Table 3. Control parts

Symbol	Parameter	Min.	Max.	Unit
V <sub>CC</sub>	Supply voltage between V <sub>CCH</sub> -GND, V <sub>CCL</sub> -GND	-0.3	20	V
V <sub>BOOT</sub>	Bootstrap voltage	-0.3	619	V
V <sub>OUT</sub>	Output voltage among U, V, W and GND	V <sub>BOOT</sub> - 21	V <sub>BOOT</sub> + 0.3	V
V <sub>CIN</sub>	Comparator input voltage	-0.3	20	V
V <sub>IN</sub>	Logic input voltage applied among HINx, LINx and GND	-0.3	15	V
V <sub>SD/OD</sub>	Open-drain voltage	-0.3	7	V
I <sub>SD/OD</sub>	Open-drain sink current	-	10	mA
V <sub>TSO</sub>	Temperature sensor output voltage	-0.3	5.5	V
I <sub>TSO</sub>	Temperature sensor output current		7	mA

Table 4. Total system

Symbol	Parameter	Value	Unit
V <sub>ISO</sub>	Isolation withstand voltage applied between each pin and heat sink plate (AC voltage, t = 60 s)	1500	Vrms
TJ	Power chips operating junction temperature range	-40 to 175	°C
T <sub>C</sub>	Module case operation temperature range	-40 to 125	°C

DS11296 - Rev 6 page 4/24



## 2.1 Thermal data

Table 5. Thermal data

Symbol	Parameter	Value	Unit
P.,	Thermal resistance junction-case single IGBT	1.2	°C/W
R <sub>th(j-c)</sub>	Thermal resistance junction-case single diode	2.3	C/VV

DS11296 - Rev 6 page 5/24

## 3 Electrical characteristics

 $T_J$  = 25 °C unless otherwise noted.

### 3.1 Inverter part

Table 6. Static

Symbol	Parameter	Test condition	Min.	Тур.	Max.	Unit
I <sub>CES</sub>	Collector-cut off current	V <sub>CE</sub> = 600 V, V <sub>CC</sub> = V <sub>boot</sub> = 15 V	-		100	μA
V <sub>CE(sat)</sub>	Collector-emitter saturation voltage	$V_{CC} = V_{Boot} = 15 \text{ V}, V_{IN}^{(1)} = 0 \text{ to } 5 \text{ V},$ $I_{C} = 30 \text{ A}$	-	1.55	2.0	V
▼ CE(sat)		$V_{CC} = V_{Boot} = 15 \text{ V}, V_{IN}^{(1)} = 0 \text{ to } 5 \text{ V},$ $I_{C} = 35 \text{ A}$	-	1.65		V
V <sub>F</sub>	Diode forward voltage	$V_{IN}^{(1)} = 0 \text{ V, } I_C = 30 \text{ A}$	-	1.8	2.5	V
٧F		$V_{IN}^{(1)} = 0 \text{ V, } I_C = 35 \text{ A}$	-	1.95		V

<sup>1.</sup> Applied among HINx, LINx and GND for x = U, V, W

Table 7. Inductive load switching time and energy

Symbol	Parameter	Test condition	Min.	Тур.	Max.	Unit
$t_{on}^{(1)}$	Turn-on time		-	464	-	
t <sub>c(on)</sub> (1)	Cross-over time on		-	274	-	
t <sub>off</sub> <sup>(1)</sup>	Turn-off time		-	475	-	ns
t <sub>c(off)</sub> <sup>(1)</sup>	Cross-over time off	$V_{DD} = 300 \text{ V}, V_{CC} = V_{boot} = 15 \text{ V},$	_	169	-	
t <sub>rr</sub>	Reverse recovery time	$V_{IN}^{(2)}$ = 0 to 5 V, $I_C$ = 30 A	_	415	-	
E <sub>on</sub>	Turn-on switching energy		_	1245	-	
E <sub>off</sub>	Turn-off switching energy		-	645	-	μJ
E <sub>rr</sub>	Reverse recovery energy		-	131	-	
$t_{on}^{(1)}$	Turn-on time		-	483	-	
t <sub>c(on)</sub> (1)	Cross-over time on		_	296	-	
t <sub>off</sub> <sup>(1)</sup>	Turn-off time		_	464	-	ns
t <sub>c(off)</sub> <sup>(1)</sup>	Cross-over time off	$V_{DD} = 300 \text{ V}, V_{CC} = V_{boot} = 15 \text{ V},$	-	162	-	
t <sub>rr</sub>	Reverse recovery time	$V_{IN}^{(2)}$ = 0 to 5 V, $I_C$ = 35 A	-	450	-	
E <sub>on</sub>	Turn-on switching energy		-	1580	-	
E <sub>off</sub>	Turn-off switching energy		-	750	-	μJ
E <sub>rr</sub>	Reverse recovery energy		-	153	-	

<sup>1.</sup>  $t_{on}$  and  $t_{off}$  include the propagation delay time of the internal drive.  $t_{C(on)}$  and  $t_{C(off)}$  are the switching times of the IGBT itself under the internally given gate driving condition.

DS11296 - Rev 6 page 6/24

<sup>2.</sup> Applied among HINx, LINx and GND for x = U, V, W

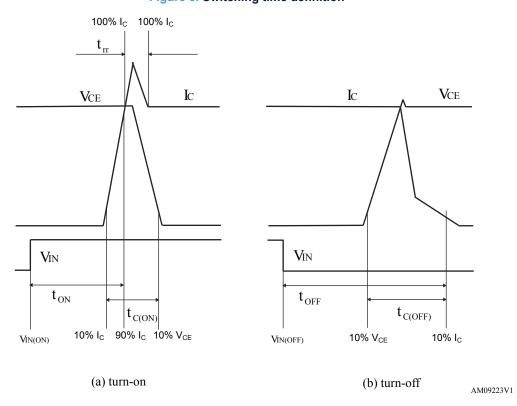


I c Vcc \_ воот VCC HVG HIN GND OUT ——

Vdd VCC LIN Vce Vce Rsd +5V □ SD LVG GND

Figure 2. Switching time test circuit

Figure 3. Switching time definition



DS11296 - Rev 6 page 7/24



# 3.2 Control/protection parts

Table 8. High- and low-side drivers

Symbol	Parameter	Test condition	Min.	Тур.	Max.	Unit
V <sub>il</sub>	Low logic level voltage				0.8	V
V <sub>ih</sub>	High logic level voltage		2			V
I <sub>INh</sub>	IN logic "1" input bias current	IN <sub>x</sub> = 15 V	80	150	200	μA
I <sub>INI</sub>	IN logic "0" input bias current	IN <sub>x</sub> = 0 V			1	μA
		High-side				
V <sub>CC_hys</sub>	V <sub>CC</sub> UV hysteresis		1.2	1.4	1.7	V
V <sub>CCH_th(on)</sub>	V <sub>CCH</sub> UV turn-on threshold		11	11.5	12	V
V <sub>CCH_th(off)</sub>	V <sub>CCH</sub> UV turn-off threshold		9.6	10.1	10.6	V
V <sub>BS_hys</sub>	V <sub>BS</sub> UV hysteresis		0.5	1	1.6	V
V <sub>BS_th(on)</sub>	V <sub>BS</sub> UV turn-on threshold		10.1	11	11.9	V
V <sub>BS_th(off)</sub>	V <sub>BS</sub> UV turn-off threshold		9.1	10	10.9	V
I <sub>QBSU</sub>	Under voltage V <sub>BS</sub> quiescent current	V <sub>BS</sub> = 9 V, HINx <sup>(1)</sup> = 5 V		55	75	μA
I <sub>QBS</sub>	V <sub>BS</sub> quiescent current	V <sub>CC</sub> = 15 V, HINx <sup>(1)</sup> = 5 V		125	170	μA
I <sub>qccu</sub>	Under voltage quiescent supply current	V <sub>CC</sub> = 9 V, HINx <sup>(1)</sup> = 0 V		190	250	μA
I <sub>qcc</sub>	Quiescent current	V <sub>CC</sub> = 15 V, HINx <sup>(1)</sup> = 0 V		560	730	μA
R <sub>DS(on)</sub>	BS driver ON resistance			150		Ω
		Low-side				
V <sub>CC_hys</sub>	V <sub>CC</sub> UV hysteresis		1.1	1.4	1.6	V
V <sub>CCL_th(on)</sub>	V <sub>CCL</sub> UV turn-on threshold		10.4	11.6	12.4	V
V <sub>CCL_th(off)</sub>	V <sub>CCL</sub> UV turn-off threshold		9.0	10.3	11	V
I <sub>qccu</sub>	Under voltage quiescent supply current	$V_{CC}$ = 10 V, $\overline{SD}$ pulled to 5 V through R <sub>SD</sub> = 10 kΩ, CIN = LINx <sup>(1)</sup> = 0		600	800	μA
I <sub>qcc</sub>	Quiescent current	$V_{CC} = 15 \text{ V}, \overline{\text{SD}} = 5 \text{ V},$ $CIN = \text{LINx}^{(1)} = 0$		700	900	μА
V <sub>SSD</sub>	Smart SD unlatch threshold		0.5	0.6	0.75	V
I <sub>SDh</sub>	SD logic "1" input bias current	SD = 5 V	25	50	70	μA
I <sub>SDI</sub>	SD logic "0" input bias current	<u>SD</u> = 0 V			1	μA

<sup>1.</sup> Applied among HINx, LINx and GND for x = U, V, W

Table 9. Temperature sensor output

Symbol	Parameter	Test condition	Min.	Тур.	Max.	Unit
V <sub>TSO</sub>	Temperature sensor output voltage	T <sub>J</sub> = 25 °C	0.974	1.16	1.345	V
I <sub>TSO_SNK</sub>	Temperature sensor sink current capability			0.1		mA
I <sub>TSO_SRC</sub>	Temperature sensor source current capability		4			mA

DS11296 - Rev 6 page 8/24



Table 10. Sense comparator ( $V_{CC}$  = 15 V, unless otherwise is specified)

Symbol	Parameter	Test condition	Min.	Тур.	Max.	Unit
I <sub>CIN</sub>	CIN input bias current	V <sub>CIN</sub> =1 V	-0.2		0.2	μA
V <sub>ref</sub>	Internal reference voltage		460	510	560	mV
V <sub>OD</sub>	Open-drain low level output voltage	I <sub>od</sub> = 5 mA			500	mV
t <sub>CIN_SD</sub>	C <sub>IN</sub> comparator delay to $\overline{SD}$	$\overline{SD}$ pulled to 5 V through R <sub>SD</sub> = 10 k $\Omega$ ; measured applying a voltage step 0-1 V to pin CIN; 50 % CIN to 90 % $\overline{SD}$	240	320	410	ns
SR <sub>SD</sub>	SD fall slew rate	$\overline{SD}$ pulled to 5 V through R <sub>SD</sub> = 10 k $\Omega$ ; C <sub>L</sub> = 1 nF through $\overline{SD}$ and ground; 90 % $\overline{SD}$ to 10 % $\overline{SD}$		25		V/µs

The comparator stays enabled even if  $V_{\text{CC}}$  is in the UVLO condition but higher than 4 V.

DS11296 - Rev 6 page 9/24



## 4 Fault management

The device integrates an open-drain output connected to the  $\overline{SD}$  pin. As soon as a fault occurs, the open-drain is activated and the LVGx outputs are forced low. Two types of fault can be identified:

- Overcurrent (OC) sensed by the internal comparator (see more detail in Section 4.1 Smart shutdown function);
- Undervoltage on supply voltage (V<sub>CC</sub>)

Each fault enables the SD open drain for a different time, as described in the following table.

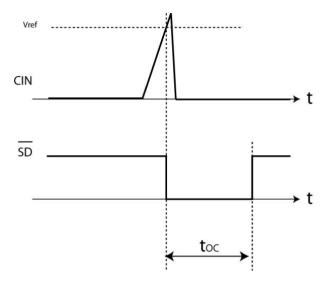
Symbol **Parameter** Event time (1) SD open-drain enable time result (1)(2) ≤ 24 µs 24 µs OC Over-current event OC time > 24 µs ≤ 70 µs 70 µs > 70 µs **UVLO** Under-voltage lockout event **UVLO** time until the VCC LS exceeds the VCC\_LS UV turn ON threshold

Table 11. Fault timing

- 1. Typical value (-40 °C  $\leq$  T<sub>J</sub>  $\leq$  +125 °C)
- 2. Without contribution of the RC network on SD

Actually, the device remains in a fault condition  $(\overline{SD})$  at low logic level and LVGx outputs disabled) for a time also depending on the RC network connected to the  $\overline{SD}$  pin. The network generates a time contribution that is added to the internal value.

Figure 4. Overcurrent timing (without contribution of the RC network on SD)



GIPG120520141638FSR

DS11296 - Rev 6 page 10/24

GIPG120520141644FSR



Vcc
UVLO Vcc ON.
UVLO Vcc OFF

Iower Vcc
threshold

T

tuvlo

 $t > t_{\text{UVLO}}$ 

Figure 5. UVLO timing (without contribution of the RC network on  $\overline{\text{SD}}$ )

6 - Rev 6 page 11/24

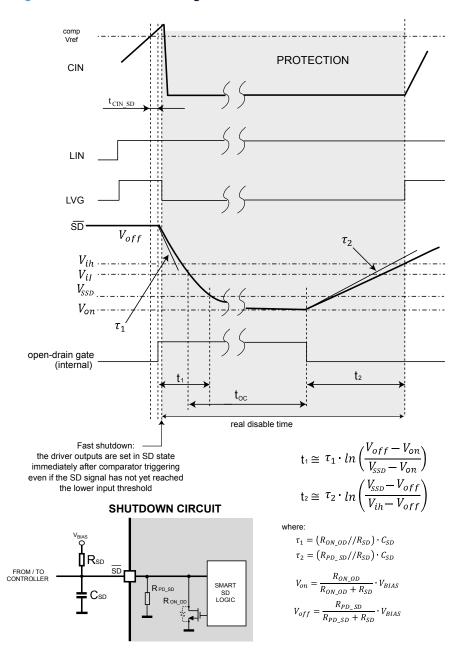


#### 4.1 Smart shutdown function

The device integrates a comparator committed to the fault sensing function. The comparator input can be connected to an external shunt resistor in order to implement a simple overcurrent detection function.

The output signal of the comparator is fed to an integrated MOSFET with the open drain output available on the SD input. When the comparator triggers, the device is set in shutdown state and its outputs are all set to low level.

Figure 6. Smart shutdown timing waveforms in case of overcurrent event



 $R_{ON\_OD}$  =  $V_{OD}/5$  mA, see Table 10. Sense comparator ( $V_{CC}$  = 15 V, unless otherwise is specified);  $R_{PD\ SD}$  (typ.) = 5 V/I<sub>SDh</sub>

In common overcurrent protection designs, the comparator output is usually connected to the  $\overline{SD}$  input and an RC network is connected to this  $\overline{SD}$  line in order to provide a mono-stable circuit which implements a protection time that follows the fault condition.

DS11296 - Rev 6 page 12/24







As opposed to common fault detection systems, the device smart shutdown architecture allows the immediate turn-off of output gates driver in case of fault, by minimizing the propagation delay between the fault detection event and the actual switching off of the outputs. In fact, the time delay between the fault and the turning off of the outputs is no longer dependent on the RC value of the external network connected to the pin.

In the smart shutdown circuitry, the fault signal has a preferential path which directly switches off the outputs after the comparator triggering.

At the same time, the internal logic turns on the open-drain output and holds it on until the  $\overline{SD}$  voltage goes below the  $V_{SSD}$  threshold and the  $t_{oc}$  time is elapsed.

The driver outputs restart following the input pins as soon as the voltage at the  $\overline{SD}$  pin reaches the higher threshold of the  $\overline{SD}$  logic input.

The smart shutdown system provides the possibility to increase the time constant of the external RC network (i.e., the disable time after the fault event) up to very high values without increasing the delay time of the protection.

DS11296 - Rev 6 page 13/24



# 5 Temperature monitoring solutions

## 5.1 TSO output

The device integrates a temperature sensor. A voltage proportional to the die temperature is available on the TSO pin. When this function is not used, the pin can be left floating.

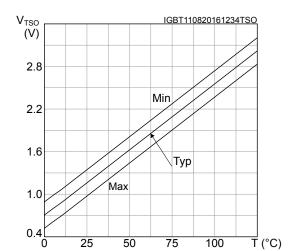


Figure 7. V<sub>TSO</sub> output characteristics vs LVIC temperature

### 5.2 NTC thermistor

Table 12. NTC thermistor

Symbol	Parameter	Test condition	Min.	Тур.	Max.	Unit
R <sub>25</sub>	Resistance	T = 25 °C		85		kΩ
R <sub>125</sub>	Resistance	T = 125 °C		2.6		kΩ
В	B-constant	T = 25 to 100 °C		4092		K
Т	Operating temperature range		-40		125	°C

DS11296 - Rev 6 page 14/24



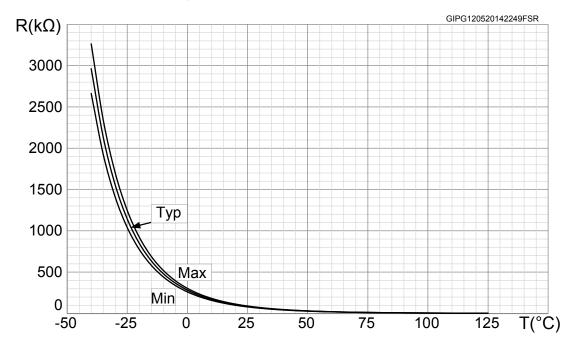
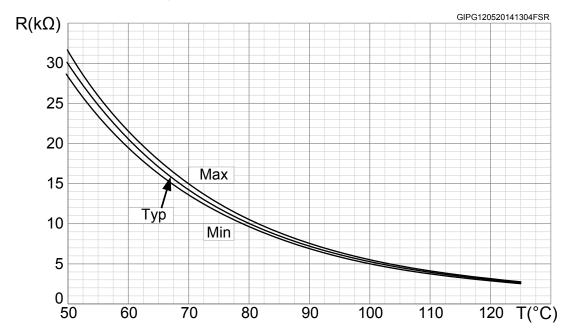


Figure 8. NTC resistance vs temperature





DS11296 - Rev 6 page 15/24



# 6 Application circuit example

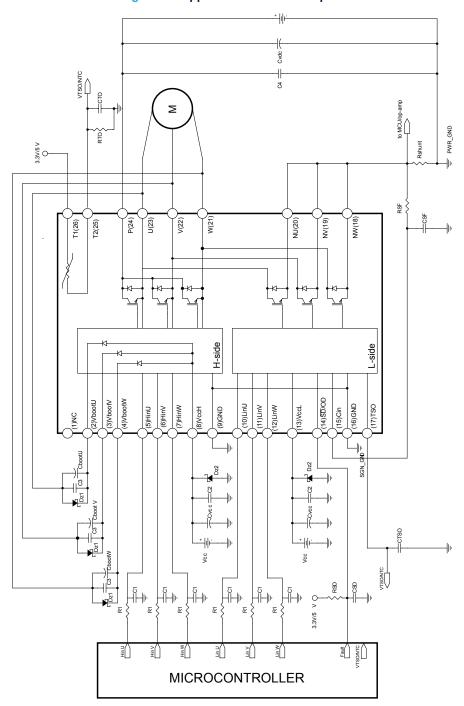


Figure 10. Application circuit example

Application designers are free to use a different scheme according to the device specifications.



#### 6.1 Guidelines

- Input signals HIN, LIN are active-high logic. A 100 k $\Omega$  (typ.) pull-down resistor is built-in for each input pin. To prevent input signal oscillations, the wiring of each input should be as short as possible and the use of RC filters (R<sub>1</sub>, C<sub>1</sub>) on each input signal is suggested. The filters should be with a time constant of about 100 ns and placed as close as possible to the IPM input pins.
- The use of a bypass capacitor C<sub>VCC</sub> (aluminum or tantalum) can reduce the transient circuit demand on the power supply. Besides, to reduce any high-frequency switching noise distributed on the power lines, a decoupling capacitor C2 (100 to 220 nF, with low ESR and low ESL) should be placed as close as possible to each V<sub>cc</sub> pin and in parallel with the bypass capacitor.
- The use of an RC filter (R<sub>SF</sub>, C<sub>SF</sub>) prevents protection circuit malfunctions. The time constant (R<sub>SF</sub> x C<sub>SF</sub>) 3. should be set to 1 µs and the filter must be placed as close as possible to the CIN pin.
- The SD is an input/output pin (open-drain type if it is used as output). It should be pulled up to a power 4. supply (i.e., MCU bias at 3.3/5 V) by a resistor value, which can keep the  $I_{od}$  no higher than 5 mA ( $V_{OD} \le$ 500 mV when open-drain MOSFET is ON). The filter on SD should be sized to get a desired re-starting time after a fault event and placed as close as possible to the SD pin.
- A decoupling capacitor C<sub>TSO</sub> between 1 nF and 10 nF can be used to increase the noise immunity of the TSO thermal sensor; a similar decoupling capacitor COT (between 10 nF and 100 nF) can be implemented if the NTC thermistor is available and used. In both cases, their effectiveness is improved if these capacitors are placed close to the MCU.
- The decoupling capacitor C<sub>3</sub> (100 to 220 nF with low ESR and low ESL) in parallel with each C<sub>boot</sub> filters high-frequency disturbances. Both Cboot and C3 (if present) should be placed as close as possible to the U,V,W and V<sub>boot</sub> pins. Bootstrap negative electrodes should be connected to the U,V,W terminals directly and separated from the main output wires.
- To prevent overvoltage on the V<sub>CC</sub> pin, a Zener diode (Dz1) can be used. Similarly on the V<sub>boot</sub> pin, a Zener 7. diode (Dz2) can be placed in parallel with each Cboot.
- The use of the decoupling capacitor C<sub>4</sub> (100 to 220 nF, with low ESR and low ESL) in parallel with the electrolytic capacitor C<sub>Vdc</sub> prevents surge destruction. Both capacitors C<sub>4</sub> and C<sub>Vdc</sub> should be placed as close as possible to the IPM (C<sub>4</sub> has priority over C<sub>vdc</sub>).
- By integrating an application-specific type HVIC inside the module, direct coupling to the MCU terminals without an optocoupler is possible.
- 10. Low inductance shunt resistors should be used for phase leg current sensing.
- 11. In order to avoid malfunctions, the wiring on N pins, the shunt resistor and PWR GND should be as short as
- 12. The connection of the SGN GND to the PWR GND at one point only (close to the shunt resistor terminal) can reduce the impact of power ground fluctuation.

These guidelines ensure the device specifications for application designs. For further details, please refer to the relevant application note.

Table 13. Recommended operating conditions

Symbol	Parameter	Test conditions	Min.	Тур.	Max.	Unit
V <sub>PN</sub>	Supply voltage	Applied among P-Nu, N <sub>V</sub> , N <sub>w</sub>		300	400	V
V <sub>CC</sub>	Control supply voltage	Applied to V <sub>CC</sub> -GND	13.5	15	18	V
V <sub>BS</sub>	High-side bias voltage	Applied to $V_{BOOTi}$ -OUT <sub>i</sub> for i = U, V, W	13		18	V
t <sub>dead</sub>	Blanking time to prevent arm-short	For each input signal	1.0			μs
f <sub>PWM</sub>	PWM input signal	-40 °C < T <sub>C</sub> < 100 °C			20	kHz
		-40 °C < T <sub>J</sub> < 125 °C				
T <sub>C</sub>	Case operation temperature				100	°C

DS11296 - Rev 6 page 17/24



# 7 Electrical characteristics (curves)

Figure 11. Output characteristics

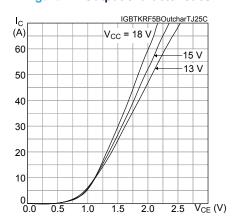


Figure 12. V<sub>CE(sat)</sub> vs collector current

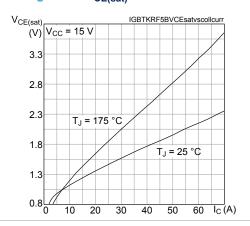


Figure 13. I<sub>C</sub> vs case temperature

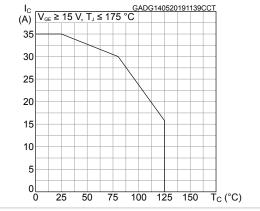


Figure 14. Diode V<sub>F</sub> vs forward current

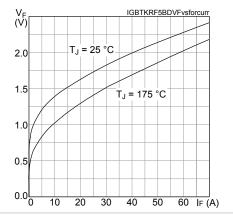


Figure 15. E<sub>ON</sub> switching energy vs collector current

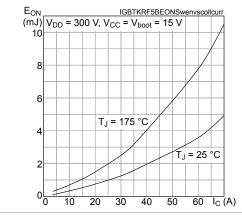
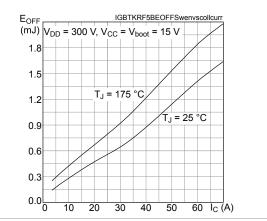
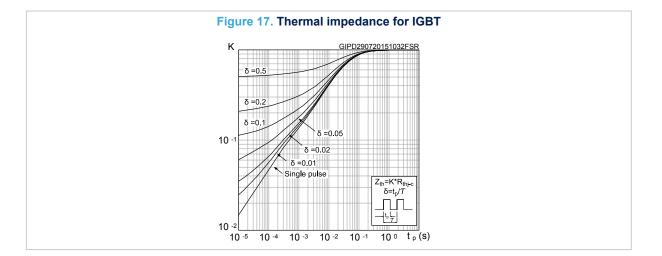


Figure 16. E<sub>OFF</sub> switching energy vs collector current



DS11296 - Rev 6 page 18/24





DS11296 - Rev 6 page 19/24

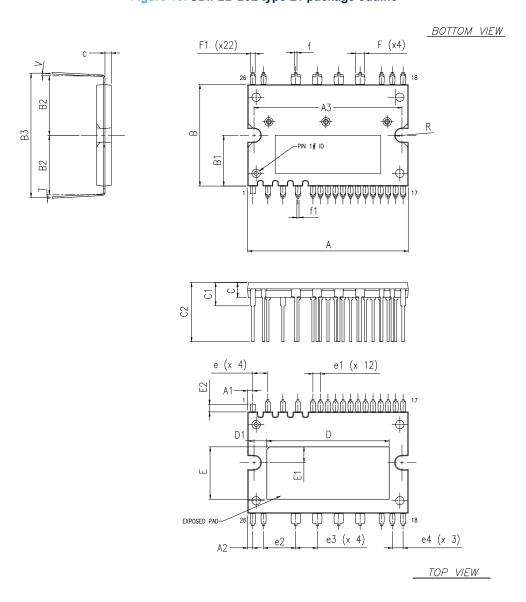


# 8 Package information

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK packages, depending on their level of environmental compliance. ECOPACK specifications, grade definitions and product status are available at: <a href="https://www.st.com">www.st.com</a>. ECOPACK is an ST trademark.

### 8.1 SDIP2B-26L type L1 package information

Figure 18. SDIP2B-26L type L1 package outline



8450802\_5\_type\_L1\_IGBT

DS11296 - Rev 6

Downloaded from Arrow.com.



Table 14. SDIP2B-26L type L1 package mechanical data

D. (	Dimensions (mm)				
Ref.	Min.	Тур.	Max.		
А	37.50	38.00	38.50		
A1	0.97	1.22	1.47		
A2	0.97	1.22	1.47		
A3	34.70	35.00	35.30		
С	1.45	1.50	1.55		
В	23.50	24.00	24.50		
B1		12.00			
B2	13.90	14.40	14.90		
В3	28.90	29.40	29.90		
С	3.30	3.50	3.70		
C1	5.00	5.50	6.00		
C2	13.50	14.00	14.50		
D	28.45	28.95	29.45		
D1	2.725	3.025	3.325		
е	3.356	3.556	3.756		
e1	1.578	1.778	1.978		
e2	7.42	7.62	7.82		
e3	4.88	5.08	5.28		
e4	2.34	2.54	2.74		
Е	11.90	12.40	12.90		
E1	3.45	3.75	4.05		
E2		1.80			
f	0.45	0.60	0.75		
f1	0.35	0.50	0.65		
F	1.95	2.10	2.25		
F1	0.95	1.10	1.25		
R	1.55	1.575	1.60		
Т	0.375	0.40	0.425		
V	0°		5°		

DS11296 - Rev 6 page 21/24



# **Revision history**

Table 15. Document revision history

Date	Revision	Changes
30-Sep-2015	1	Initial release.
	2	Text edits throughout document
16-May-2016		Updated Section 3: "Electrical characteristics"
		Added Section 7: "Electrical characteristics (curves)"
	3	Modified Table 7: "Static", Table 10: "Temperature sensor output" and Table 11: "Sense comparator (VCC = 15 V, unless otherwise is specified)"
08-Nov-2016		Modified Figure 15: "VTSO output characteristics vs. LVIC temperature"
		Updated Section 8.1: "SDIP2B-26L type L package information"
		Minor text changes
	4	Document status promoted from preliminary data to production data.
06-Oct-2017		Updated features in cover page and Table 12: "Fault timing".
		Minor text changes
07-Jun-2018	5	Updated Section 8.1 SDIP2B-26L type L package information.
07 0011 2010		Minor text changes
	6	Added Figure 13. I <sub>C</sub> vs case temperature.
14-May-2019		Updated Section 8.1 SDIP2B-26L type L1 package information.
		Minor text changes.

DS11296 - Rev 6 page 22/24





# **Contents**

1	Inte	rnal schematic and pin description	2	
2	Abs	Absolute maximum ratings		
	2.1	Thermal data	4	
3	Elec	ctrical characteristics	6	
	3.1	Inverter part	6	
	3.2	Control/protection parts	7	
4	Fau	It management	10	
	4.1	Smart shutdown function	12	
5	Tem	perature monitoring solutions	14	
	5.1	TSO output	14	
	5.2	NTC thermistor	14	
6	Арр	olication circuit example	16	
	6.1	Guidelines	17	
7	Elec	ctrical characteristics (curves)	18	
8	Pac	kage information	20	
	8.1	SDIP2B-26L type L1 package information	20	
Rev	/ision	history	22	



#### IMPORTANT NOTICE - PLEASE READ CAREFULLY

STMicroelectronics NV and its subsidiaries ("ST") reserve the right to make changes, corrections, enhancements, modifications, and improvements to ST products and/or to this document at any time without notice. Purchasers should obtain the latest relevant information on ST products before placing orders. ST products are sold pursuant to ST's terms and conditions of sale in place at the time of order acknowledgement.

Purchasers are solely responsible for the choice, selection, and use of ST products and ST assumes no liability for application assistance or the design of Purchasers' products.

No license, express or implied, to any intellectual property right is granted by ST herein.

Resale of ST products with provisions different from the information set forth herein shall void any warranty granted by ST for such product.

ST and the ST logo are trademarks of ST. For additional information about ST trademarks, please refer to <a href="https://www.st.com/trademarks">www.st.com/trademarks</a>. All other product or service names are the property of their respective owners.

Information in this document supersedes and replaces information previously supplied in any prior versions of this document.

© 2019 STMicroelectronics - All rights reserved

DS11296 - Rev 6 page 24/24