Multifunction LCD Segment Driver

BU97930MUV MAX 108 segments (SEG27×COM4)

●Features

- Integrated RAM for display data (DDRAM): 27 x 4 bit (Max 108 Segment)
- LCD drive output: 4 Common output, Max 27 Segment output
- Integrated 1ch LED driver circuit
- Segment /GPO(Max 4port) output mode selectable
- Support PWM generation from ext. or internal clock (Resolution: 8bit)
- Support standby mode
- Integrated Power-on-Reset circuit (POR)
- Integrated Oscillator circuit
- No external component
- Low power consumption design
- Independent power supply for LCD driving
- Support Blink function (Blink frequency 1.6, 2.0, 2.6, 4.0Hz selectable)

●Applications

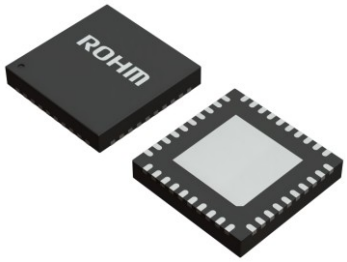
- Telephone
- FAX
- Portable equipment (POS, ECR, PDA etc.)
- DSC
- DVC
- Car audio
- Home electrical appliance
- Meter equipment

etc.

●Key Specifications

- Supply Voltage Range: +1.8V to +3.6V
- LCD drive power supply Range: +2.7V to +5.5V
- Operating Temperature Range: -40°C to +85°C
- Max Segments: 108 Segments
- Display Duty: Static, 1/3, 1/4 selectable
- Bias: Static, 1/3
- Interface: 3wire serial interface

●Package W (Typ.) x D (Typ.) x H (Max.)



VQFN040V6060
6.00mm x 6.00mm x 1.00mm

●Typical Application Circuit

LED/GPO using case

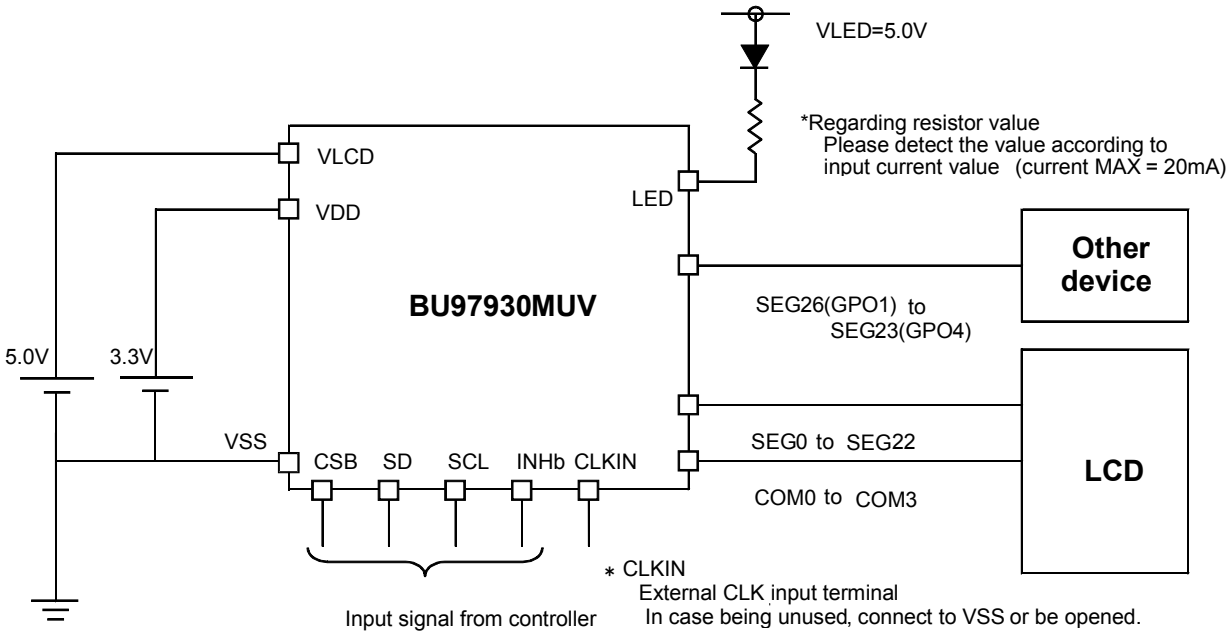


Figure 1. Typical application circuit

○Product structure : Silicon monolithic integrated circuit ○This product is not designed for protection against radioactive rays.

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●Block Diagram / Pin Configuration / Pin Description

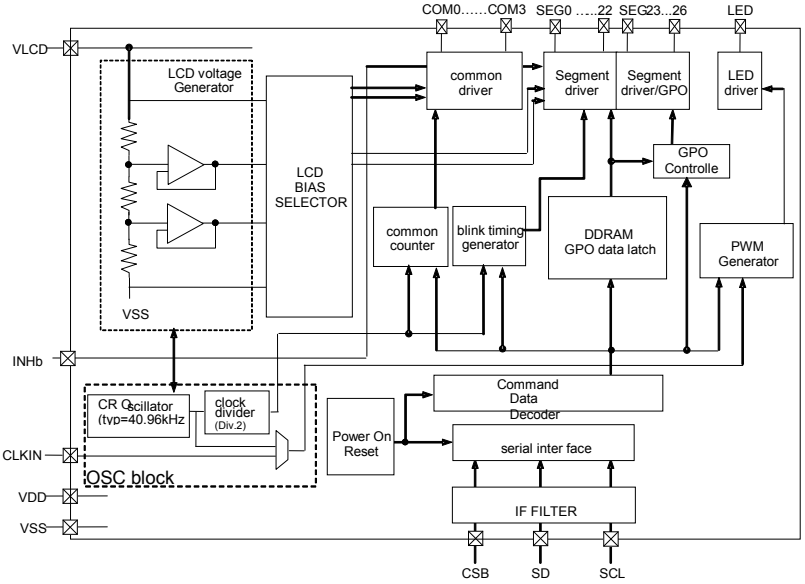


Figure 2. Block Diagram

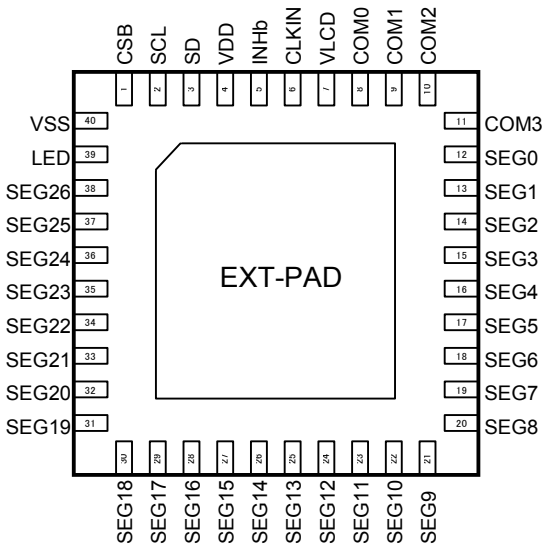


Figure 3. Pin Configuration (BOTTOM VIEW)

Table 1 Pin Description

Terminal	Terminal number	I/O	unused case	Function
CSB	1	I	-	Chip select: "L" active
SCL	2	I	-	Serial data transfer clock
SD	3	I	-	Input serial data
VDD	4	-	-	Power supply for LOGIC
CLKIN	6	I	OPEN / VSS	External clock input terminal (for display/PWM using selectable); Support Hi-Z input mode at internal clock mode
VSS	40	-	-	GND
VLCD	7	-	-	Power supply for LCD
INHb	5	I	VDD	Display turning on/off select terminal H: turning on display, L: turning off display INHb = “L”: All SEG/COM terminals : output VSS level GPO terminal : output VSS level LED drive terminal : output Hi-Z
COM0 to 3	8 to 11	O	OPEN	COMMON output for LCD
SEG0 to 22	12 to 34	O	OPEN	SEGMENT output for LCD
SEG23 to 26	35 to 38	O	OPEN	SEGMENT output for LCD/GPO
LED	39	O	OPEN	LED driver output
EXT-PAD	-	-	VSS	substrate

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●Absolute Maximum Ratings (VSS=0V)

Parameter	Symbol	Ratings	Unit	Remarks
Power supply voltage 1	VDD	-0.3 to +4.5	V	Power supply
Power supply voltage 2	VLCD	-0.5 to +7.0	V	Power supply for LCD
Power Dissipation	Pd	0.8*1	W	
Input voltage range	VIN	-0.5 to VDD+0.5	V	
Operational temperature range	Topr	-40 to +85	℃	
Storage temperature range	Tstg	-55 to +125	℃	
Output current	Iout1	5	mA	SEG output
	Iout2	5	mA	COM output
	Iout3	10	mA	GPO output
	Iout4	50	mA	LED output

*1 When operated higher than Ta=25℃, subtract 8.0mW per degree. (using ROHM standard board)
(board size: 74.2mm×74.2mm×1.6mm material: FR4 board copper foil: land pattern only).

●Recommended Operating Ratings(Ta=-40°C to +85°C,VSS=0V)

Parameter	Symbol	Ratings			Unit	Remarks
		MIN	TYP	MAX		
Power supply voltage 1	VDD	1.8	-	3.6	V	Power supply
Power supply voltage 2	VLCD	2.7	-	5.5	V	Power supply for LCD
Output current	Iout4	-	-	20	mA	Per LED port 1ch

●Electrical Characteristics

DC characteristics (Ta=-40°C to +85°C, VDD=1.8V to 3.6V, VLCD=2.7V to 5.5V, VSS=0)

Parameter	Symbol	Limit			Unit	Condition
		MIN	TYP	MAX		
“H” level input voltage	VIH	0.8VDD	-	VDD	V	SD, SCL, CSB, CLKIN, INHb
“L” level input voltage	VIL	VSS	-	0.2VDD	V	SD, SCL, CSB, CLKIN, INHb
Hysteresis width	VH	-	0.2	-	V	SCL, INHb, VDD=3.3V, Ta=25°C
“H” level input current	IIH1	-	-	5	μA	SD, SCL, CSB, CLKIN, INHb, VI=3.6V
“L” level input current	IIL1	-5	-	-	μA	SD, SCL, CSB, CLKIN, INHb, VI=0V
“H” level output voltage (*2)	VOH1	VLCD -0.4	-	-	V	Iload=-50μA, VLCD=5.0V SEG0 to SEG26
	VOH2	VLCD -0.4	-	-	V	Iload=-50μA, VLCD=5.0V, COM0 to COM3
	VOH3	VLCD -0.6	-	-	V	Iload=-1mA,VLCD=5.0V, SEG23 to SEG26(GPO mode)
“L” level output voltage (*2)	VOL1	-	-	0.4	V	Iload= 50μA, VLCD=5.0V, SEG0 to SEG26
	VOL2	-	-	0.4	V	Iload= 50μA, VLCD=5.0V, COM0 to COM3
	VOL3	-	-	0.5	V	Iload=1mA, VLCD=5.0V, SEG23 to SEG26(GPO mode)
	VOL4	-	0.11	0.5	V	Iload=20mA, VLCD=5.0V, LED
Current consumption (*1)	IstVDD	-	3	10	μA	Input terminal ALL’L’, Display off, Oscillation off
	IstVLCD	-	0.5	5	μA	Input terminal ALL’L’, Display off, Oscillation off
	IVDD1	-	8	15	μA	VDD=3.3V, Ta=25°C, 1/3bias, fFR=64Hz, PWM generate off, All output pin open
	IVDD2	-	30	45	μA	VDD=3.3V, Ta=25°C, 1/3bias, fFR=64Hz, PWM Frequency=500Hz setting, All output pin open
	IVLCD1	-	10	15	μA	VLCD=5.0V, Ta=25°C, 1/3bias, fFR=64Hz, LED generate off, All output pin open
	IVLCD2	-	30	48	μA	VLCD=5.0V, Ta=25℃, 1/3bias, fFR=64Hz, PWM Frequency=500Hz setting, All output pin open

*1 Power save mode 1 and frame inversion setting *2 Iload: In this case, load current from only one port

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●**Electrical Characteristics – continued**

Oscillation Frequency Characteristics (Ta=-40°C to +85°C, VDD=1.8V to 3.6V, VLCD=2.7V to 5.5V, VSS=0)

Parameter	Symbol	Limit			Unit	Condition
		MIN	MIN	MIN		
Frame frequency 1	fFR1	57.6	64	70.4	Hz	VDD=3.3V, Ta=25°C, fFR=64Hz setting
Frame frequency 2	fFR2	51.2	64	73.0	Hz	VDD=2.5 to 3.6V fFR=64Hz setting
Frame frequency 3	fFR3	45.0	-	64	Hz	VDD=1.8 to 2.5V fFR=64Hz setting

MPU interface Characteristics (Ta=-40°C to +85°C, VDD=1.8V to 3.6V, VLCD=2.7V to 5.5V, VSS=0)

Parameter	Symbol	Limit			unit	Condition
		MIN	TYP	MAX		
Input rise time	tr	-	-	50	ns	
Input fall time	tf	-	-	50	ns	
SCL cycle time	tSCYC	250	-	-	ns	
“H” SCL pulse width	tSHW	50	-	-	ns	
“L” SCL pulse width	tSLW	50	-	-	ns	
SD setup time	tSDS	50	-	-	ns	
SD hold time	tSDH	50	-	-	ns	
CSB setup time	tCSS	50	-	-	ns	
CSB hold time	tCSH	50	-	-	ns	
“H” CSB pulse width	tCHW	50	-	-	ns	

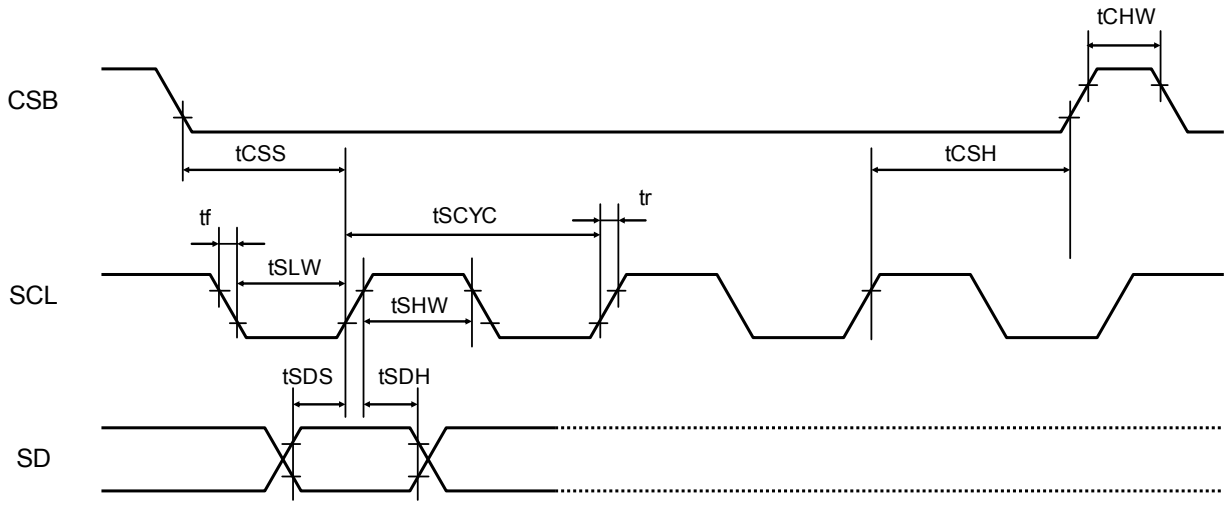


Figure 4. Serial interface timing

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●I/O equivalent circuit

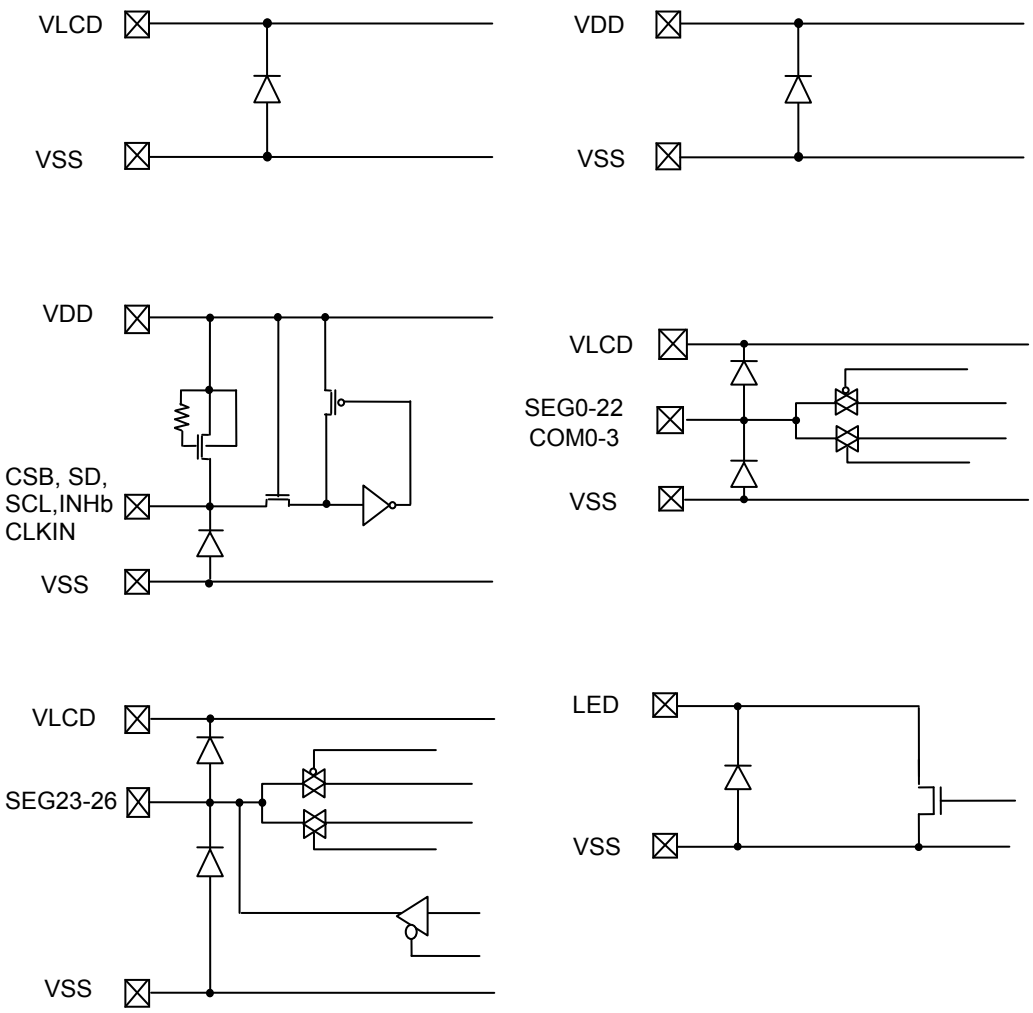


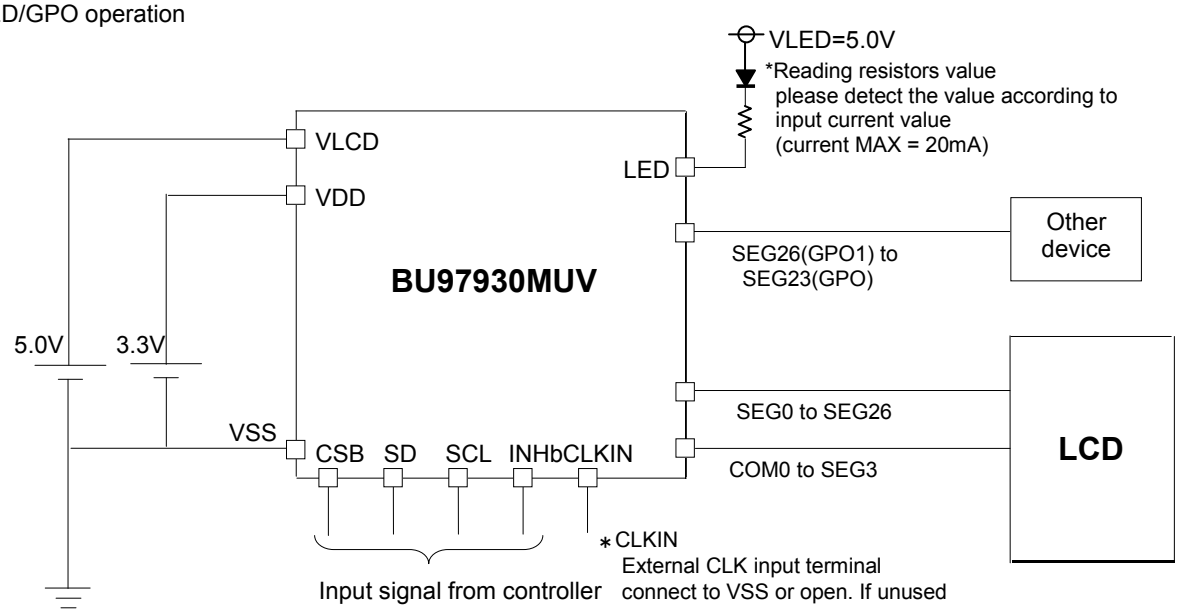
Figure 5. I/O equivalent circuit

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●**Example of recommended circuit**

1) LED/GPO operation



2) SEG output only operation

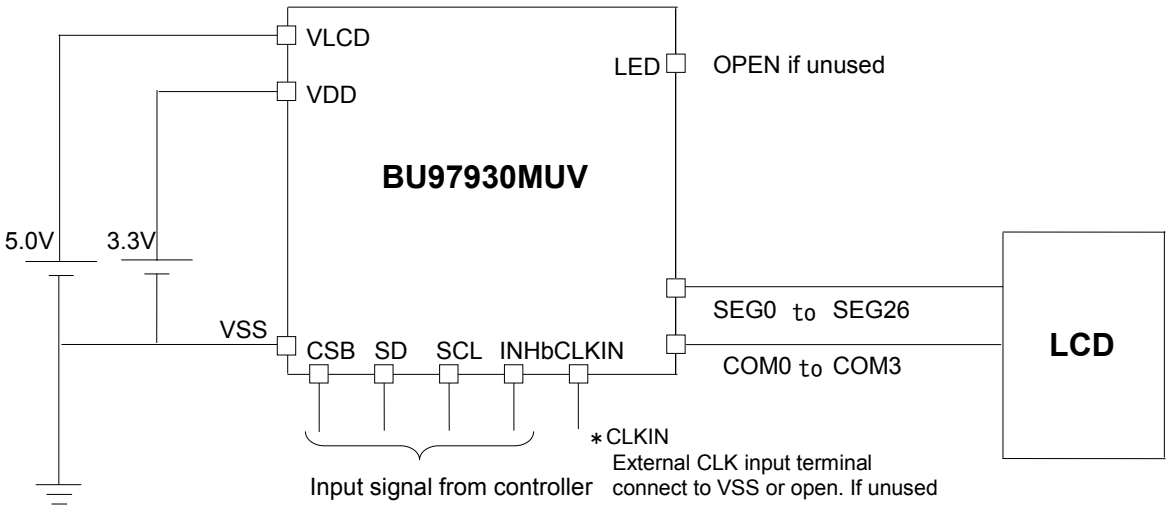


Figure 6. Example of Recommended Circuit

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●Function description

○Command and data transfer method

○3-SPI (3-wire serial interface)

This device is controlled by a 3-wire signal (CSB, SCL, and SD).
First, Interface counter is initialized with CSB="H".
Setting CSB="L", enables SD and SCL inputs.
The protocol of 3-SPI transfer is as follows.
Each command starts with Command or Data judgment bit (D/C) as MSB data,
followed by data D6 to D0 (this is when CSB ="L").
(Internal data is latched at the rising edge of SCL, serial data is converted to an 8-bit parallel data at the falling edge of the 8th CLK.)

When CSB changes from "L" to "H", and at this time serial commands are less than 8 bits, command and data transfers are cancelled. To start sending command again, please set CSB="L" and send command continuously.

After sending RAMWR or BLKWR or GPOSET command, this device is in the RAM data input mode. Under this mode, device can not accept new commands.

In this case, execute a "H" to "L" transition at CSB, after this sequence, the device is released from RAM data input mode, and can accept new command.

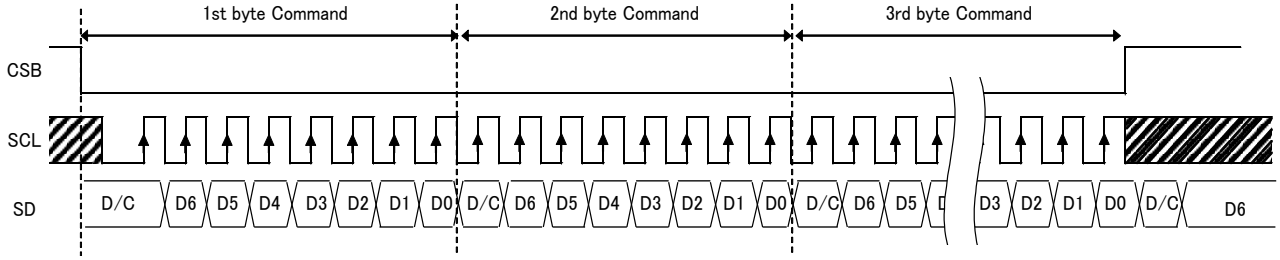


Figure 7. 3-SPI Data transfer Format

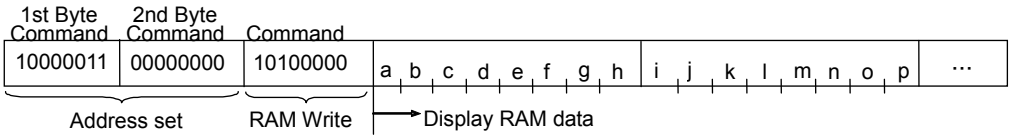
* 8-bit data, sending after RAMWR command, are display RAM data
* 8-bit data, sending after BLKWR command, are blink RAM data
* SCL and SD can be set to "H" or cleared to "L" during CSB="H".

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○Write display data and transfer method

This device has Display Data RAM (DDRAM) of 28×4=112bit.
The relationship between data input and display data, DDRAM data and address are as follows.

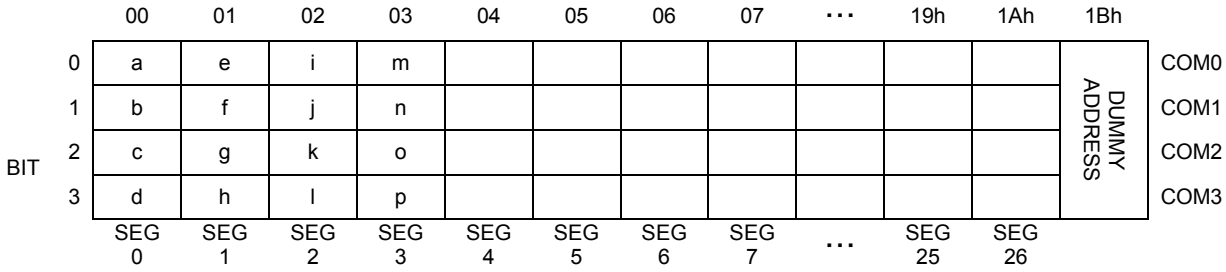


According to this command, an 8-bit binary data will be written to the DDRAM. The starting address of the DDRAM where data will be written is specified by “ADSET” command, and is automatically incremented for every 4 bits of data received..

Writing data to DDRAM can be done by continuously sending data.
(In case data is sent continuously after write date at 1Ah (SEG26), RAM data will be written to 1Bh (dummy address) and return to address 00h (SEG0) automatically.)

In case SEG port assigned to GPO port by OUTSET command, corresponding SEG address do not change and used as dummy address.

DDRAM address



Display data write to DDRAM every 4 bits.
In case CSB changes from ”L” to ”H” before 4 bits of data transfer was finished, RAM write is cancelled.

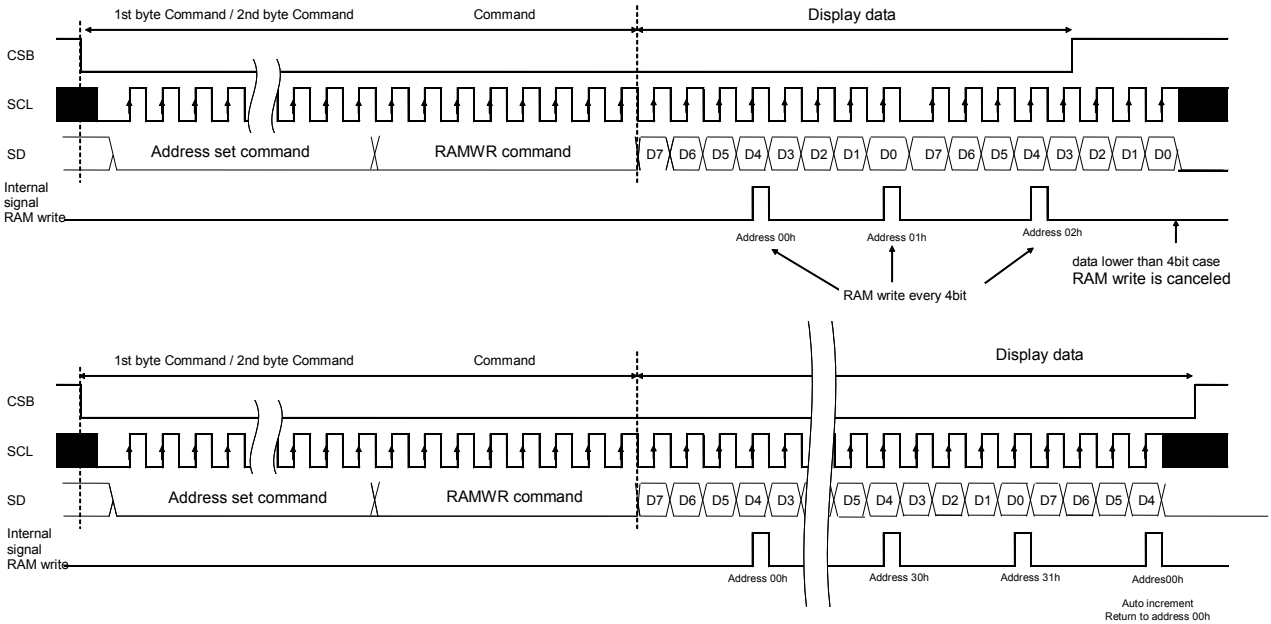


Figure 8. Display Data Transfer Method

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○Blink function

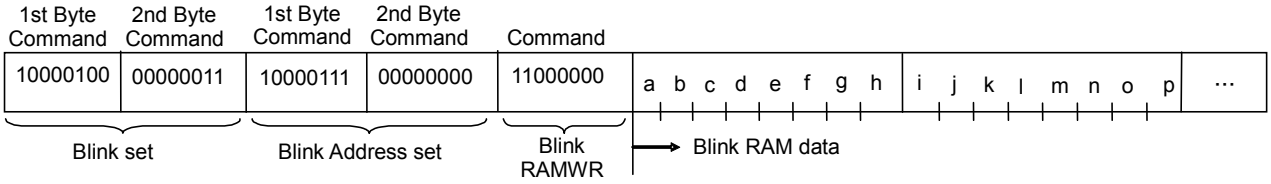
This device has Blink function. Blink function can set each segment port individually.
Blink ON/OFF and Blink frequency are set by the BLKSET command.
Blink frequency varies according to fCLK characteristics.
Blink setup of each segment is controlled by BLKWR command.

The write start address is specified by “BLKADSET” command. And this address will automatically increment every 4 bits of blink data received. The relation of BLKWR command, blink ram data, and blinking segment port is below.

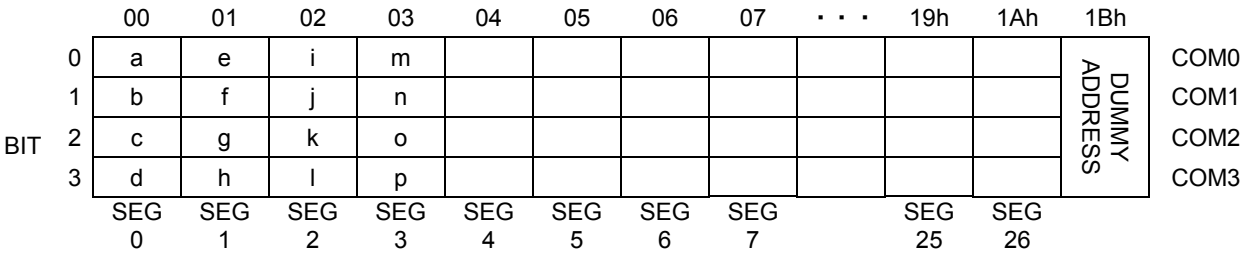
In case data is “1”, segment will blink, on the other hand when data is “0”, segment will not blink.
(In case data is written continuously after write data at 1Ah (SEG26), RAM data will be written to 1Bh (dummy address) and return to address 00h (SEG0) automatically.)

Please refer to the following figures about Blink operation of each segment.

In case SEG port assigned to GPO port by OUTSET command, corresponding SEG address does not change and used as dummy address.



Blink RAM address



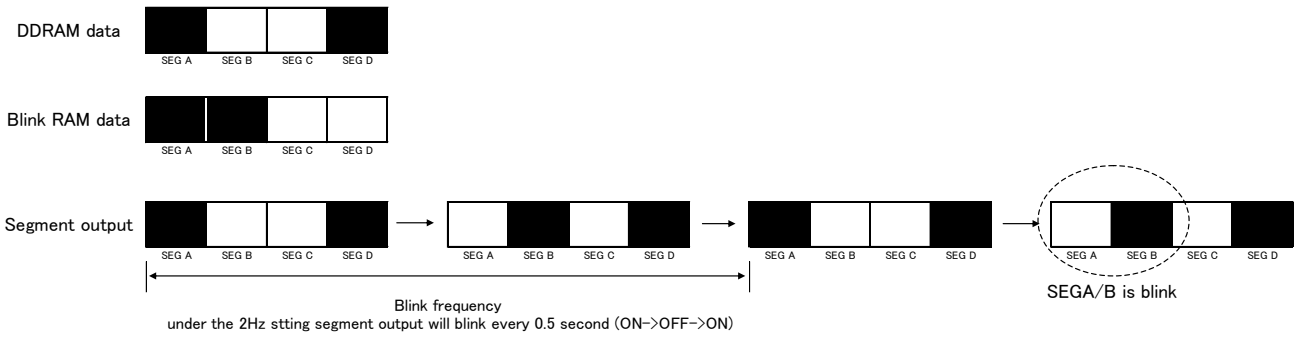


Figure 9. Blink Operation

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○LCD Driver Bias/Duty Circuit

BU97930MUV generates LCD driving voltage using an on-chip Buffer AMP.
Also, it can drive LCD with low power consumption
*Line and frame inversion can be set by MODESET command.
*1/4duty, 1/3duty and static mode can be set by DISCTL command.
About each LCD driving waveform, please refer to “LCD driving waveform” descriptions.

○Initial state

Initial state after SWRST command input
○Display off
○All command register values are in Reset state.
○DDRAM address data and Blink address data are initialized
(DDRAM data and Blink RAM data are not initializing.
Please write DDRAM data and Blink RAM data before Display on.)

●Command / Function list

Function description table

NO	Command	Function
1	Mode Set (MODESET)	Sets LCD drive mode (display on/off, current mode)
2	Display control (DISCTL)	Sets LCD drive mode (frame freq., line/frame inversion)
3	Address set (ADSET)	Sets display data RAM address for RAMWR command
4	Blink set (BLKSET)	Sets Blink mode on/off
5	Blink address set (BLKADSET)	Sets Blink data RAM address for BLKWR command
6	SEG/GPO port change (OUTSET)	Selects segment output/general purpose output (GPO)
7	LED drive control (PWMSET) (H piece adjustment of PWM)	Sets PWM1 signal “H” width for LED driving
8	RAM WRITE (RAMWR)	Writes display data to display data RAM
9	Blink RAM WRITE (BLKWR)	Writes Blink data to BLINK data RAM
10	All Pixel ON (APON)	Sets all Pixel display on
11	All Pixel OFF (APOFF)	Sets all Pixel display off
12	All Pixel On/Off mode off (NORON)	Sets normal display mode (APON/APOFF cancel)
13	Software Reset (SWRST)	Software Reset
14	OSC external input (OSCSET)	Enables External clock input
15	GPO output set (GPOSET)	Sets GPO output data

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●Command Descriptions

D/C, Data / Command judgment bit (MSB)
For more details, please refer to 3wire serial I/F

○Mode Set (MODESET)

	MSB							LSB		
	D/C	D6	D5	D4	D3	D2	D1	D0	Hex	Reset
1st byte command	1	0	0	0	0	0	0	1	81h	-
2nd byte command	0	0	0	0	P3	P2	P1	P0	-	00h

Display Set

Condition	P3	Reset state
Display OFF	0	○
Display ON	1	

Display OFF : No LCD driving mode (Output: VSS Level)
Turn off OSC circuit and LCD power supply circuit. (Synchronized with frame freq)
Display ON : LCD driving mode
Turn on OSC circuit and LCD power supply circuit.
Read data from DDRAM and display to LCD.

LED port and GPO port output states are not affected by a Display on/off state
Output state is determined by command setup (OUTSET GPOSET, PWMSET) and INHb terminal state, respectively. For more details, please refer to each command description.

LCD drive mode set

Condition	P2	Reset state
Frame inversion	0	○
Line inversion	1	

Current mode set

Condition	P1	P0	Reset state
Power save mode1	0	0	○
Power save mode2	0	1	
Normal mode	1	0	
High power mode	1	1	

* Please supply the VLCD voltage larger than 3V at High power mode.

(Reference data of consumption current)

Condition	Current consumption
Power save mode 1	×1.0
Power save mode 2	×1.7
Normal mode	×2.7
High power mode	×5.0

* The value changes according to the panel load.

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○Display control (DISCTL)

	MSB							LSB		
	D/C	D6	D5	D4	D3	D2	D1	D0	Hex	Reset
1st byte Command	1	0	0	0	0	0	1	0	82h	-
2nd byte Command	0	0	0	0	P3	P2	P1	P0	-	02h

Duty set

Condition	P3	P2	Reset state
1/4duty (1/3bias)	0	0	○
1/3duty (1/3bias)	0	1	
Static (1/1bias)	1	*	

*: Don't care

In 1/3 duty, Display data and Blink data of COM3 are ineffective.
COM1 and COM3 output are same data.

Please be careful in transmitting display data and blink data.
The examples of SEG/COM output waveform, under each Bias/Duty set up, are shown at "LCD Driver Bias/Duty Circuit" description.

Frame frequency set

Condition (1/4,1/3,1/1duty)	P1	P0	Reset state
(128Hz, 130Hz, 128Hz)	0	0	
(85Hz, 86hz, 64Hz)	0	1	
(64Hz, 65Hz, 48Hz)	1	0	○
(51Hz, 52Hz, 32Hz)	1	1	

Relation table, between Frame frequencies (FR), integrated oscillator circuit (OSC) and Divide number.

DISCTL (P1,P0)	Divide			FR [Hz] (* 1)		
	Duty set (P3,P2)			Duty set (P3,P2)		
	(0,0) 1/4duty	(0,1) 1/3duty	(1, *) 1/1duty	(0,0) 1/4duty	(0,1) 1/3duty	(1, *) 1/1duty
(0,0)	160	156	160	128	131.3	128
(0,1)	240	237	320	85.3	86.4	64
(1,0)	320	315	428	64	65	47.9
(1,1)	400	393	640	51.2	52.1	32

*1: FR is frame frequency, in case OSC frequency = 20.48KHz (typ).

The Formula, to calculate OSC frequency from Frame frequency is shown below.

" OSC frequency = Frame frequency (measurement value) x Divide number "
Divide number : Please determine by using the value of Frame Frequency Set (P1,P0) and duty setting (P3,P2).

Ex) (P1,P0) = (0,1) ,(P3,P2) = (0,1) => Divide number= 237

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○Address set (ADSET)

MSB LSB

MSB	D/C	D6	D5	D4	D3	D2	D1	D0	Hex	Reset
1st byte Command	1	0	0	0	0	0	1	1	83h	-
2nd byte Command	0	0	0	P4	P3	P2	P1	P0	-	00h

Set start address to write DDRAM data.
The address can be set from 00h to 1Ah. (Address 1Bh is used at dummy address)
Do not set other addresses. (Except 00h to 1Bh address is not acceptable.)
In case writing data to DDRAM, make sure to send RAMWR command.

○Blink set (BLKSET)

MSB LSB

	D/C	D6	D5	D4	D3	D2	D1	D0	Hex	Reset
1st byte Command	1	0	0	0	0	1	0	0	84h	-
2nd byte Command	0	0	0	0	0	P2	P1	P0	-	00h

Set Blink ON/OFF.
For more details, please refer to "Blink function".

Blink set

Blink mode(Hz)	P2	P1	P0	Reset state
OFF	0	0 / *	0 / *	○
1.6	1	0	0	
2.0	1	0	1	
2.6	1	1	0	
4.0	1	1	1	

*: Don’t care

○Blink address set (BLKADSET)

MSB LSB

	D/C	D6	D5	D4	D3	D2	D1	D0	Hex	Reset
1st byte Command	1	0	0	0	0	1	1	1	87h	-
2nd byte Command	0	0	0	P4	P3	P2	P1	P0	-	00h

Set Blink data RAM start write address.
The address can be set from 00h to 1Ah. (Address 1Bh is used at dummy address)
Do not set other addresses. (Except 00h to 1Bh address is not acceptable.)
In case writing data to Blink RAM, make sure to send BLKWR command

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○SEG/GPO port change (OUTSET)

	MSB							LSB		
	D/C	D6	D5	D4	D3	D2	D1	D0	Hex	Reset
1st byte Command	1	0	0	0	1	0	0	0	88h	-
2nd byte Command	0	0	0	0	0	P2	P1	*	-	00h

Set output mode, Segment output or GPO output.
P2 to P0: Select changing port number. (SEG23 to SEG26 ports are SEG mode/GPO mode selectable)

In case GPO output is selected, Terminal output data is set by GPOSET command.

Ex) In case SEG 26 port assigned to GPO,
If GPO1 data is "H", GPO1 (SEG26) port outputs "H" (VLCD Level).
If GPO1 data is "L", GPO1 (SEG26) port outputs "L" (VSS level).

Output terminal state under the P2 to P0 set condition is listed below

Output Terminal state

Condition			SEG Terminal state (SEG output/GPO output)			
P2	P1	P0	SEG23 port	SEG24 port	SEG25 port	SEG26 port
0	0	*	SEG23	SEG24	SEG25	SEG26
0	1	0	SEG23	SEG24	SEG25	GPO1
0	1	1	SEG23	SEG24	GPO2	GPO1
1	0	0	SEG23	GPO3	GPO2	GPO1
1	0	1	GPO4	GPO3	GPO2	GPO1
1	1	*	(OUTSET command will be canceled)			

In case SEG port is switched to the GPO port, DDRAM address and Blink RAM address do not change.
In this case DDRAM address and Blink RAM address, selected GPO output mode is dummy address.

The output state of GPO and LED port under the INHb H/L, display on/off, and RESET state are listed below.

Control port	INHb		DISPLAY		RESET state
	H	L	ON	OFF	
GPO	According to GPOSET command	Low Fix	According to GPOSET command	According to GPOSET command	GPO unselected (All SEG output)
LED	According to PWMSET command	Hi-Z	According to PWMSET command	According to PWMSET command	LED unselected (All SEG output)

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○LED drive-control (PWM “H” width control) command (PWMSET)

	MSB							LSB		
	D/C	D6	D5	D4	D3	D2	D1	D0	Hex	Reset
1st byte Command	1	0	0	0	1	0	1	0	8Ah	-
2nd byte Command	0	0	0	0	0	0	P7	P6	-	00h
3rd byte Command	0	0	P5	P4	P3	P2	P1	P0	-	00h

2nd and 3rd byte command data are able to set from 00h to 3Fh (described as 8bit binary data).
In case other value is selected, sending command is ignored, and 2nd and 3rd byte command data is set to 3Fh.
In default state, 2nd and 3rd byte command data are set to 00h.
In case command is less than 3 bytes, sending command is cancelled.

According to PWMSET command, LED driving signal is adjustable. PWM “H” width is adjustable by 8-bit resolution.

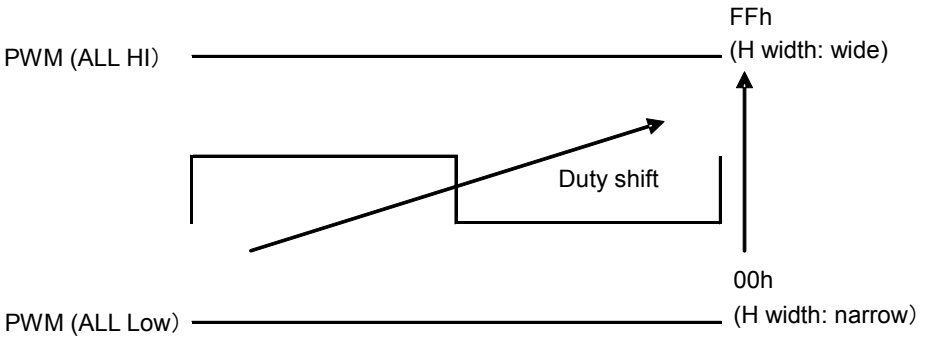
Explanation about P7 to P6 data of 2nd byte command and P5 to P0 data of 3rd byte command are as follows:
(The 2nd byte data are used as upper 2bit, and 3rd byte data are used as lower 6 bits.)

8bit mode: P7 data is used as MSB of 8 bits, and P0 data is used LSB.

LED driving period is decided by the “H” width of PWM signal, generated by PWM generator circuit (resolution: 8 bits).

Ex)
In case, external PWM clock 125KHz, parameter setting value is 127 (7Fh)
1-bit resolution: 8us
ALL HI set: PWM signal frequency about 500Hz, H width about 2.00msec
ALL LOW set: PWM signal frequency about 500Hz, H width 0usec (in case 8-bit resolution)

This command is reflected, synchronizing with a next PWM frame head.
And, LED port output is as follows. LED port operation does not affect Display ON/OFF state.



(*) About the PWM frequency and PWM “H” width calculation.

PWM cycle and PWM “H” width, decided by PWM clock cycle are described as follows:
(PWM clock cycle is a minimum unit of PWM “H” width)

PWM frequency = PWM clock cycle × (Number of the steps (8bit =256) - 1)
PWM H width = PWM clock cycle × Parameter set value (8bit: 0 to 255)
PWM Duty = PWM H width/PWM cycle = Parameter set value / Number of the steps

In case PWM is generated from internal clock, the PWM cycle varies according to OSC frequency.

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○RAM WRITE (RAMWR)

	MSB							LSB		
	D/C	D6	D5	D4	D3	D2	D1	D0	Hex	Reset
1st byte Command	1	0	1	0	0	0	0	0	A0h	-
2nd byte Command	Display data									Random
	....									
n byte Command	Display data									Random

Input data, sending after 1st byte command, are used as Display data. And display data are sent every 4 bits. Please set this command after the ADSET command.

○Blink RAM WRITE (BLKWR)

	MSB							LSB		
	D/C	D6	D5	D4	D3	D2	D1	D0	Hex	Reset
1st byte Command	1	1	0	0	0	0	0	0	C0h	-
2nd byte Command	Blink data									Random
	....									
n byte Command	Blink data									Random

Input data, sending after 1st byte command, are used as Display data. And display data are sent every 4 bits. Please set this command after the BLKADSET command.

○All Pixel ON (APON)

	MSB							LSB		
	D/C	D6	D5	D4	D3	D2	D1	D0	Hex	Reset
1st byte Command	1	0	0	1	0	0	0	1	91h	-

After sending the command, all SEG outputs set display on state regardless of the DDRAM data.
(This command affects the SEG output terminals only (except GPO and LED output)

○All Pixel OFF (APOFF)

	MSB							LSB		
	D/C	D6	D5	D4	D3	D2	D1	D0	Hex	Reset
1st byte Command	1	0	0	1	0	0	0	0	90h	-

After sending the command, all SEG outputs set display off state regardless of the DDRAM data.
(This command affects the SEG output terminals only (except GPO and LED output)

○All Pixel ON/OFF mode off (NORON)

	MSB							LSB		
	D/C	D6	D5	D4	D3	D2	D1	D0	Hex	Reset
1st byte Command	1	0	0	1	0	0	1	1	93h	-

After sending the command, all SEG outputs are released from APON/APOFF state.
And SEG port output signal follows DDRAM data.
(This command affects the SEG output terminals only (except GPO and LED output)
After reset sequence or SWRESET, all outputs set NORON state.

○Software Reset (SWRST)

	MSB							LSB		
	D/C	D6	D5	D4	D3	D2	D1	D0	Hex	Reset
1st byte Command	1	0	0	1	0	0	1	0	92h	-

After sending the command, device is set to default state.

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○OSC external input command (OSCSET)

	MSB							LSB		
	D/C	D6	D5	D4	D3	D2	D1	D0	Hex	Reset
1st byte Command	1	0	0	1	1	0	0	0	98h	-
2nd byte Command	0	0	0	0	0	P2	P1	P0	-	00h

Sets the type of clock mode. There are 4 selectable modes including external clock input mode.
Details of this command function are as follows.

Condition	P2	P1	P0	Reset state
Internal CLK (PWM generation OFF)	0	0	0	○
External CLK input for PWM (PWM generation OFF)	0	0	1	
Internal CLK (PWM generation ON)	0	1	0	
External CLK input for PWM (PWM generation ON)	0	1	1	
External CLK input for Display (ROHM use only)	1	*	*	

(*: Don't care)

(P2,P1,P0)=(0,0,1) : External PWM input mode
CLKIN：external PWM input available.
PWMOUT: "L" Output
*under the (P2,P1,P0)=(0,0,0) condition PWMOUT into same state

(P2,P1,P0)=(0,1,0) : PWM is generated from an internal oscillating frequency

(P2,P1,P0)=(0,1,1) : PWM is generated from an External CLK input CLKIN
PWM width is set by PWMSET command.

The relation of OSC function control by each command is as follows:

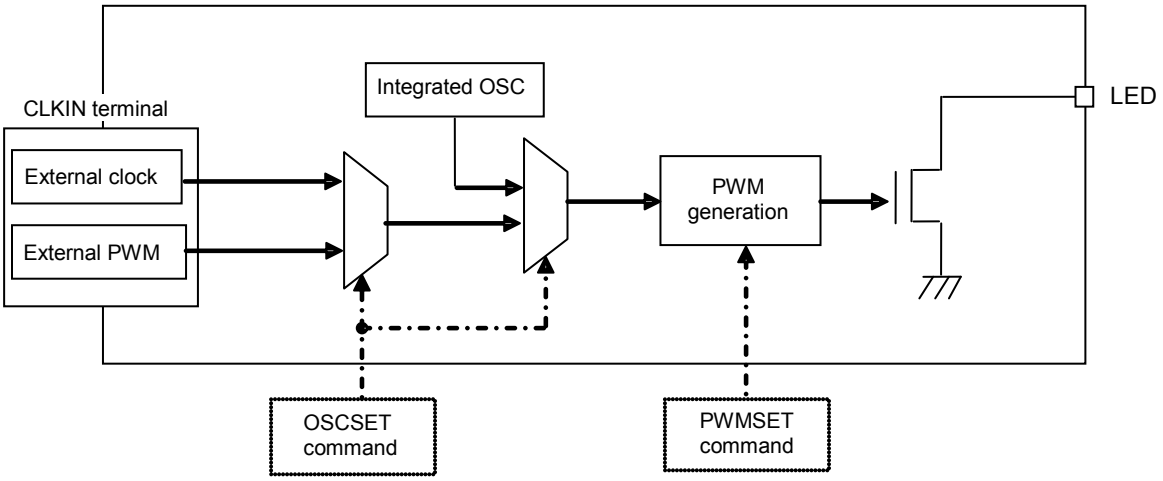


Figure 10. OSC External Input

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○GPO output set command (GPOSET)

	MSB							LSB		
	D/C	D6	D5	D4	D3	D2	D1	D0	Hex	Reset
1st byte Command	1	0	0	1	1	0	1	0	9Ah	-
2nd byte Command	0	0	0	P4	P3	P2	P1	0	-	00h

(*: Don't care)

Set GPO output data. The relation between SEG port (GPO port) and data is shown below.

GPOSET data	GPO port	SEG port
P1	GPO1	SEG26
P2	GPO2	SEG25
P3	GPO3	SEG24
P4	GPO4	SEG23

GPO data output is asynchronous from frame cycle.
In case INHb="H", GPO output signal follows GPOSET data, on the other hand, in case INHb="L" GPO output is GND level. GPO output is not affected by Display ON/OFF state.

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●LCD driving waveform

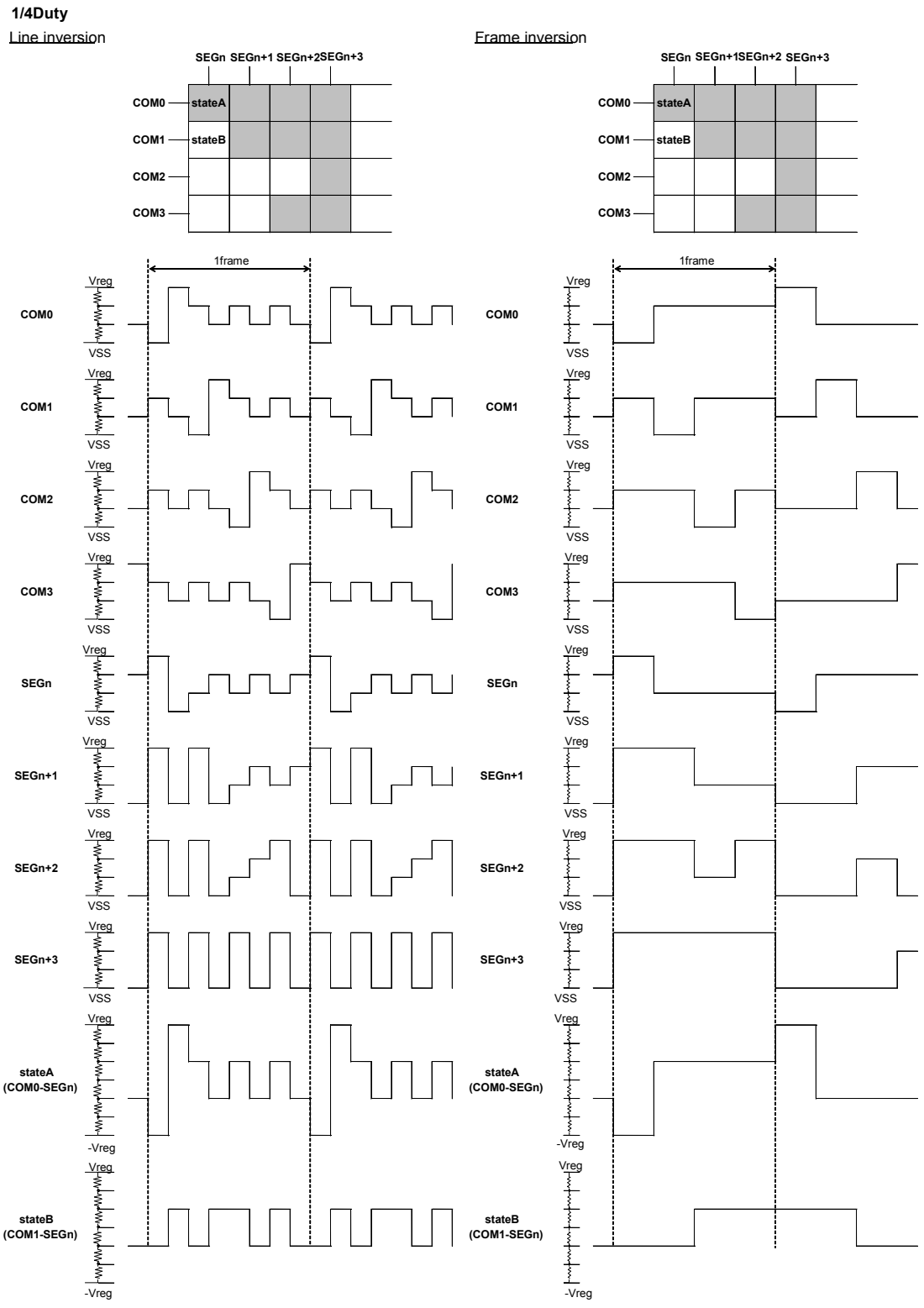


Figure 11. Waveform of Line Inversion

Figure12. Waveform of Frame Inversion

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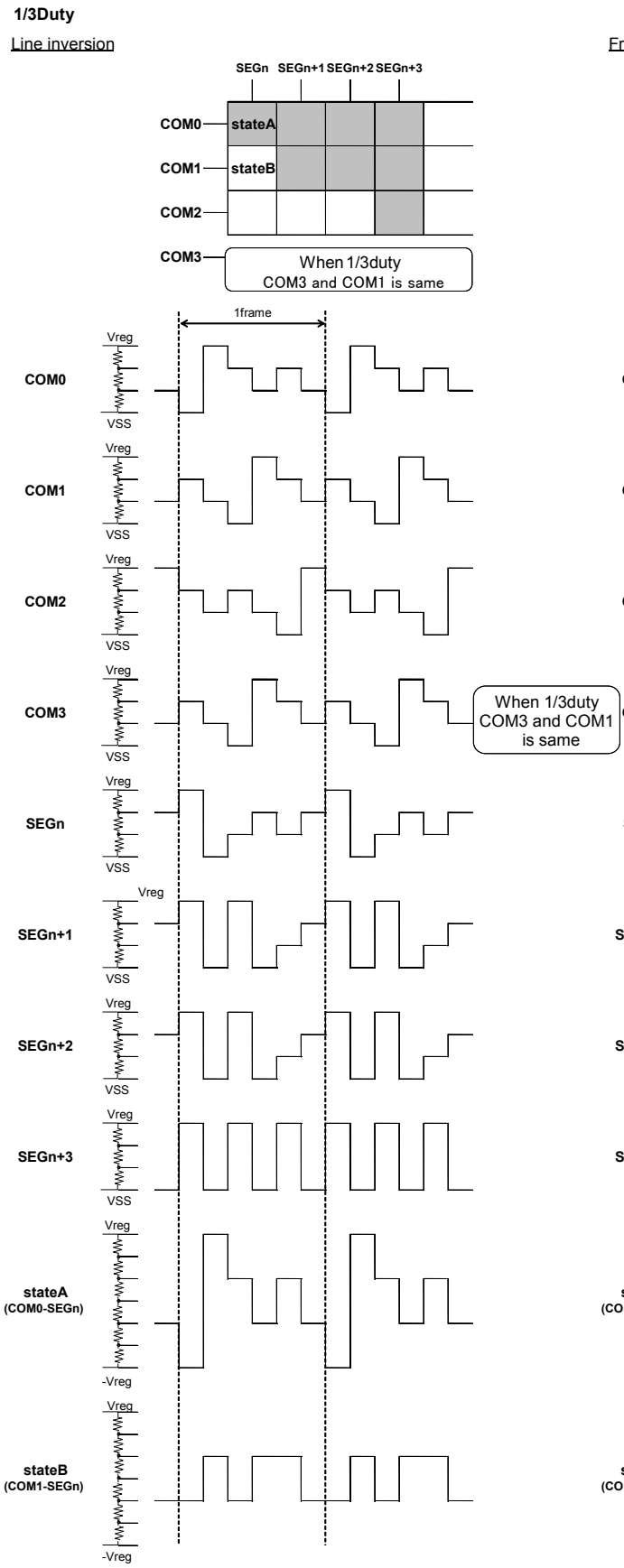


Figure 13. Waveform of Line Inversion

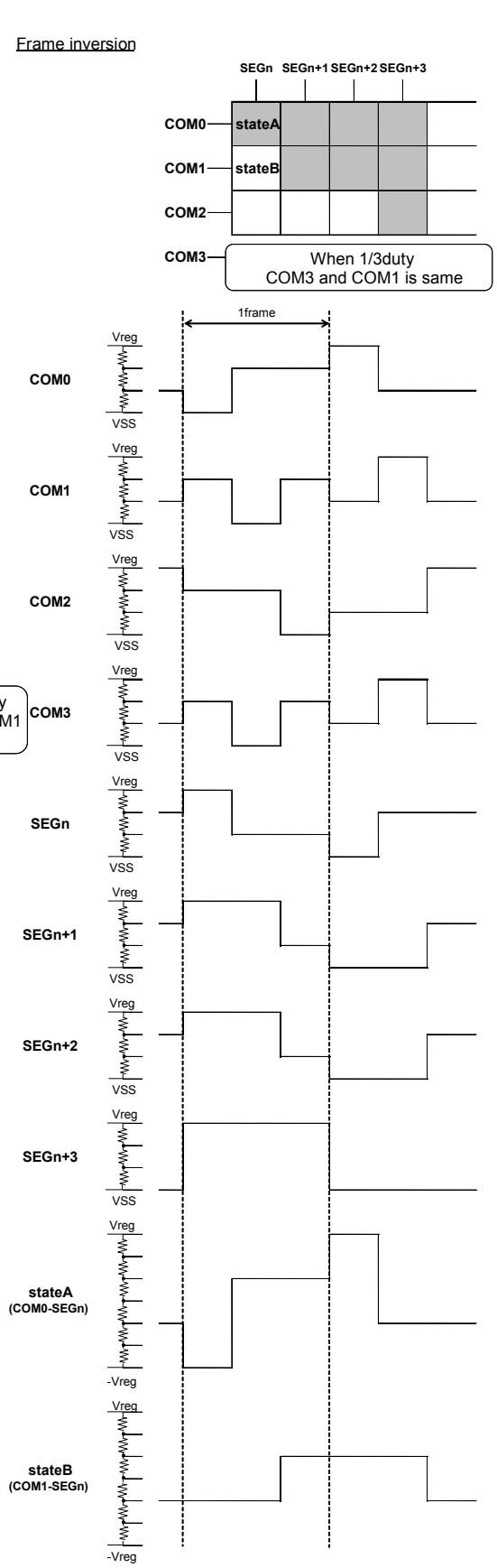


Figure 14. Waveform of Frame Inversion

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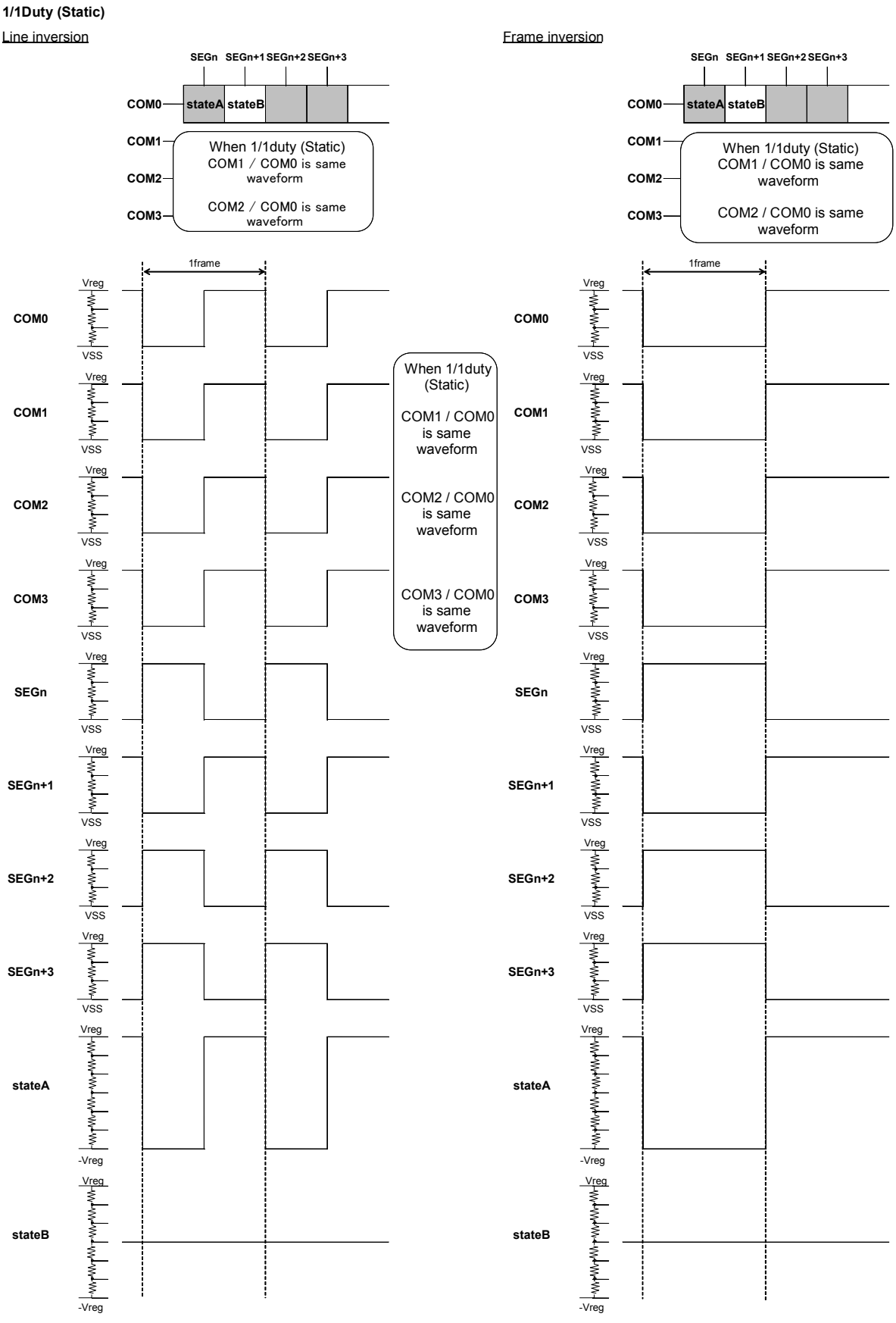


Figure 15. Waveform of Line Inversion

Figure 16. Waveform of Frame Inversion

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●Initialize Sequence

Recommended input sequence is listed below, before starting LCD driving.
(Refer to Power ON/OFF sequence)

Input voltage supply
↓
CSB 'H' …interface initializing
↓
CSB 'L' …interface command sending
↓
SWRESET …software reset
↓
MODESET …Display off
↓
Various commands setting
↓
RAM WRITE
↓
Blink RAM WRITE
↓
MODESET …Display on
↓
Start LCD driving

*Before initializing sequence, DDRAM address, DDRAM data, Blink address and Blink data are random.

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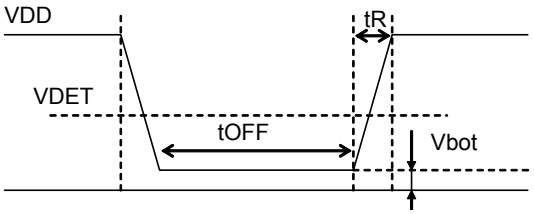
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●Cautions on Power-On/ Power-Off condition

○POR circuit

BU97930MUV has “P.O.R” (Power-On Reset) circuit and Software Reset function.
Please follow the recommended Power-On conditions in order to power up properly.

1, Please set power up conditions, follow the recommended tR, tF, tOFF, and Vbot specification below in order to ensure P.O.R operation.
(*The detection voltage of POR varies because of environment, etc. To operate POR, please satisfy Vbot lower than 0.5V condition.)



Recommended condition of tR, tF, tOFF, Vbot

tR	tOFF	Vbot	VDET
less than 10ms	Over 1ms	less than 0.5V	TYP 1.2V

* VDET : POR detect level

Figure 17. Power ON/OFF Waveform

2, If it is difficult to meet the above conditions, execute the following sequence after Power-On.
(1) CSB=”L”→”H” condition
(2) After CSB”H”→“L”, execute SWRST command.

In addition, in order to the SWRST command certainly, please wait 1ms after a VDD level reaches to 90% and CSB=”L”→”H”.

*Before SWRST command, input device will be in unstable state, since SWRST command does not operate perfect substitution of a POR function.

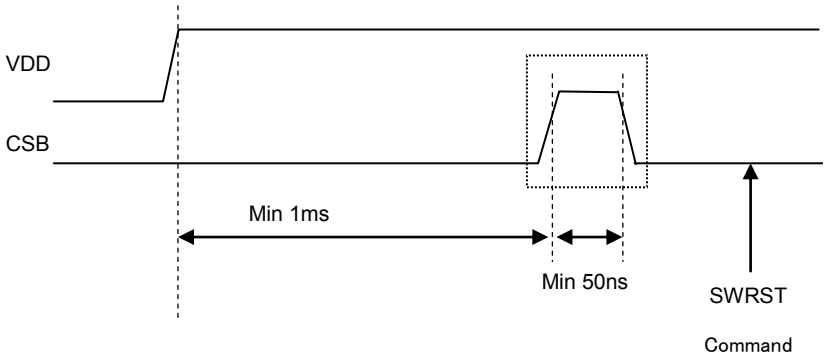


Figure 18. SWRST Command Sequence

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●Power ON / OFF sequence

Display ON/OFF control by INHb terminal is not asynchronous with frame cycle.
To prevent incorrect display, malfunction and abnormal current,
VDD must be turned on before VLCD in power up sequence.
VDD must be turned off after VLCD in power down sequence.
Please set INHb terminal ="L" during Power ON/OFF sequence.
Please satisfies VLCD Please satisfies VLCD≥VDD, t1>0ns, t2>0ns

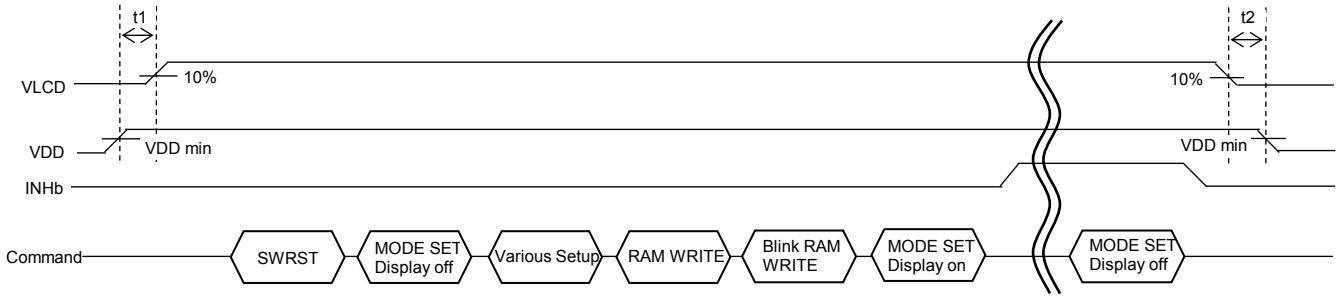


Figure 19. Power On/Off Sequence

●Notes on pull down resistor usage

Satisfy the following sequence if input terminals are pulled down by external resistors (In case MPU output Hi-Z).

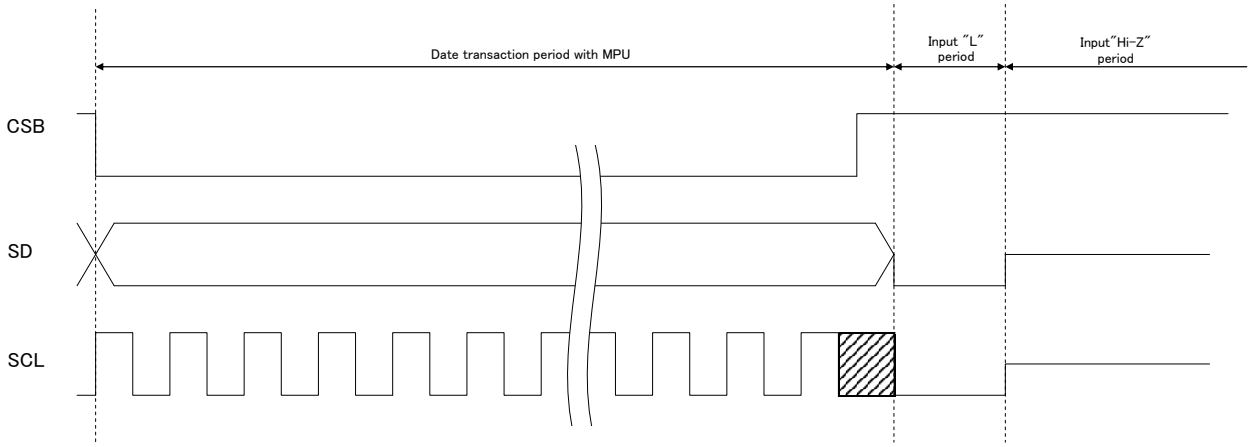


Figure 20. Recommended sequence when input ports are pulled down

BU97930MUV adopts a 5V tolerant I/O for the digital input. This circuit includes a bus-hold function to keep HIGH level. A pull down resistor of below 10KΩshall be connected to the input terminals for transitions from HIGH to LOW because the bus-hold transistor turns on during the input's HIGH level. (Refer to the Figure 5; I/O Equivalent Circuit)
A higher resistor than 10KΩ (approximate) causes input terminals being steady by intermediate potential between HIGH and LOW level so unexpected current is consumed by the system.
The potential depends on the pull down resistance and bus-hold transistor's resistance.
As the bus-hold transistor turns off upon the input level is cleared to LOW, a higher resistor can be used as a pull down resistor if MPU sets SD and SCL lines to LOW before it releases the lines.

The LOW period preceding MPU's bus release shall be at least 50ns as same as a minimum CLK width (tSLW).

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●Operational Notes

(1) Absolute maximum ratings
Operating the IC over the absolute maximum ratings may damage the IC. The damage can either be a short circuit between pins or an open circuit between pins. Therefore, it is important to consider circuit protection measures, such as adding a fuse, in case the IC is operated over the absolute maximum ratings.

(2) Recommended operating conditions
These conditions represent a range within which the expected characteristics of the IC can be approximately obtained. The electrical characteristics are guaranteed under the conditions of each parameter.

(3) Reverse connection of power supply
Connecting the power supply in reverse polarity can damage the IC. Take precautions against reverse polarity when connecting the power supply, such as mounting an external diode between the power supply and the IC's power supply terminals

(4) Power supply lines
Design the PCB layout pattern to provide low impedance ground and supply lines. Separate the ground and supply lines of the digital and analog blocks to prevent noise in the ground and supply lines of the digital block from affecting the analog block. Furthermore, connect a capacitor to ground at all power supply pins. Consider the effect of temperature and aging on the capacitance value when using electrolytic capacitors.

(5) Ground Voltage
The voltage of the ground pin must be the lowest voltage of all pins of the IC at all operating conditions. Ensure that no pins are at a voltage below the ground pin at any time, even during transient condition.

(6) Short between pins and mounting errors
Be careful when mounting the IC on printed circuit boards. The IC may be damaged if it is mounted in a wrong orientation or if pins are shorted together. Short circuit may be caused by conductive particles caught between the pins.

(7) Operation under strong electromagnetic field
Operating the IC in the presence of a strong electromagnetic field may cause the IC to malfunction.

(8) Testing on application boards
When testing the IC on an application board, connecting a capacitor directly to a low-impedance output pin may subject the IC to stress. Always discharge capacitors completely after each process or step. The IC's power supply should always be turned off completely before connecting or removing it from the test setup during the inspection process. To prevent damage from static discharge, ground the IC during assembly and use similar precautions during transport and storage.

(9) Regarding input pins of the IC
In the construction of this IC, P-N junctions are inevitably formed creating parasitic diodes or transistors. The operation of these parasitic elements can result in mutual interference among circuits, operational faults, or physical damage. Therefore, conditions which cause these parasitic elements to operate, such as applying a voltage to an input pin lower than the GND voltage should be avoided. Furthermore, do not apply a voltage to the input terminals when no power supply voltage is applied to the IC. Even if the power supply voltage is applied, make sure that the input terminals have voltages within the values specified in the electrical characteristics of this IC.

(10) GND wiring pattern
When using both small-signal and large-current GND traces, the two ground traces should be routed separately but connected to a single ground at the reference point of the application board to avoid fluctuations in the small-signal ground caused by large currents. Also ensure that the GND traces of external components do not cause variations on the GND voltage. The power supply and ground lines must be as short and thick as possible to reduce line impedance.

(11) External Capacitor
When using a ceramic capacitor, determine the dielectric constant considering the change of capacitance with temperature and the decrease in nominal capacitance due to DC bias and others.

(12) Unused input terminals
Input terminals of an IC are often connected to the gate of a CMOS transistor. The gate has extremely high impedance and extremely low capacitance. If left unconnected, the electric field from the outside can easily charge it. The small charge acquired in this way is enough to produce a significant effect on the conduction through the transistor and cause unexpected operation of IC. So unless otherwise specified, input terminals not being used should be connected to the power supply or ground line.

(13) Rush current
When power is first supplied to the IC, rush current may flow instantaneously. It is possible that the charge current to the parasitic capacitance of internal photo diode or the internal logic may be unstable. Therefore, give special consideration to power coupling capacitance, power wiring, width of GND wiring, and routing of connections.

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●Ordering Information

B U 9 7 9 3 0 M U V	-	E 2

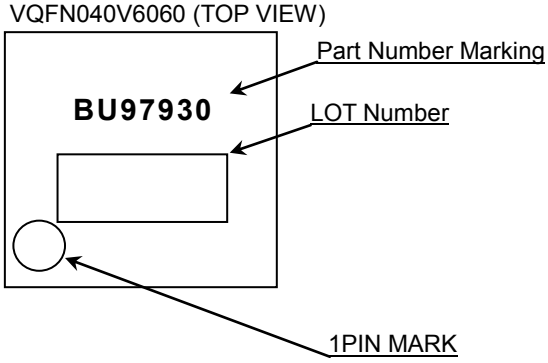
Part Number

Package
MUV :VQFN040V6060

Packaging and forming specification
E2: Embossed tape and reel
(VQFN040V6060)

●Marking Diagram

VQFN040V6060 (TOP VIEW)

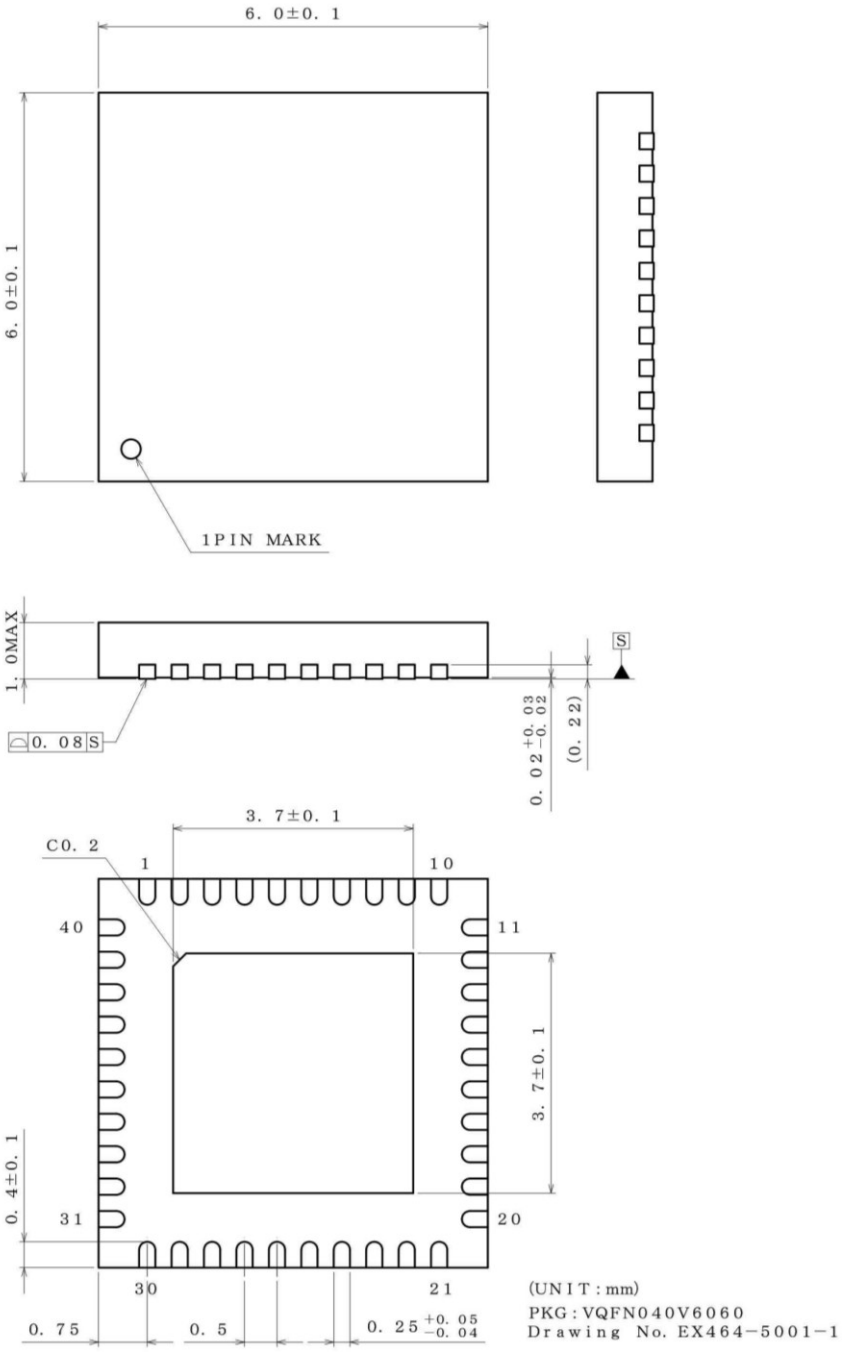


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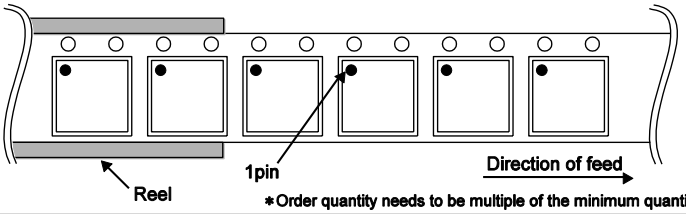
●**Physical Dimension, Tape and Reel Information**

Package Name	VQFN040V6060



<Tape and Reel information>

Tape	Embossed carrier tape
Quantity	2000pcs
Direction of feed	E2 (The direction is the 1pin of product is at the upper left when you hold reel on the left hand and you pull out the tape on the right hand)



*Order quantity needs to be multiple of the minimum quantity.

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●**Revision History**

Date	Revision	Changes
14.Mar.2012	001	New Release
8.Jan.2013	002	Improved the statement in all pages. Deleted “Status of this document” in page 26. Changed format of Physical Dimension, Tape and Reel Information.
26.Jan.2015	003	Add the condition when power supply in page 24.
10.Apr.2015	004	Modified figure of Power On/Off Sequence in page 24.

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Notice

Precaution on using ROHM Products

1. Our Products are designed and manufactured for application in ordinary electronic equipments (such as AV equipment, OA equipment, telecommunication equipment, home electronic appliances, amusement equipment, etc.). If you intend to use our Products in devices requiring extremely high reliability (such as medical equipment (Note 1), transport equipment, traffic equipment, aircraft/spacecraft, nuclear power controllers, fuel controllers, car equipment including car accessories, safety devices, etc.) and whose malfunction or failure may cause loss of human life, bodily injury or serious damage to property ("Specific Applications"), please consult with the ROHM sales representative in advance. Unless otherwise agreed in writing by ROHM in advance, ROHM shall not be in any way responsible or liable for any damages, expenses or losses incurred by you or third parties arising from the use of any ROHM's Products for Specific Applications.

(Note1) Medical Equipment Classification of the Specific Applications

JAPAN	USA	EU	CHINA
CLASSⅢ	CLASSⅢ	CLASSⅡb	CLASSⅢ
CLASSⅣ		CLASSⅢ	

2. ROHM designs and manufactures its Products subject to strict quality control system. However, semiconductor products can fail or malfunction at a certain rate. Please be sure to implement, at your own responsibilities, adequate safety measures including but not limited to fail-safe design against the physical injury, damage to any property, which a failure or malfunction of our Products may cause. The following are examples of safety measures:
   [a] Installation of protection circuits or other protective devices to improve system safety
   [b] Installation of redundant circuits to reduce the impact of single or multiple circuit failure

3. Our Products are designed and manufactured for use under standard conditions and not under any special or extraordinary environments or conditions, as exemplified below. Accordingly, ROHM shall not be in any way responsible or liable for any damages, expenses or losses arising from the use of any ROHM's Products under any special or extraordinary environments or conditions. If you intend to use our Products under any special or extraordinary environments or conditions (as exemplified below), your independent verification and confirmation of product performance, reliability, etc, prior to use, must be necessary:
   [a] Use of our Products in any types of liquid, including water, oils, chemicals, and organic solvents
   [b] Use of our Products outdoors or in places where the Products are exposed to direct sunlight or dust
   [c] Use of our Products in places where the Products are exposed to sea wind or corrosive gases, including Cl_2, H_2S, NH_3, SO_2, and NO_2
   [d] Use of our Products in places where the Products are exposed to static electricity or electromagnetic waves
   [e] Use of our Products in proximity to heat-producing components, plastic cords, or other flammable items
   [f] Sealing or coating our Products with resin or other coating materials
   [g] Use of our Products without cleaning residue of flux (even if you use no-clean type fluxes, cleaning residue of flux is recommended); or Washing our Products by using water or water-soluble cleaning agents for cleaning residue after soldering
   [h] Use of the Products in places subject to dew condensation

4. The Products are not subject to radiation-proof design.

5. Please verify and confirm characteristics of the final or mounted products in using the Products.

6. In particular, if a transient load (a large amount of load applied in a short period of time, such as pulse. is applied, confirmation of performance characteristics after on-board mounting is strongly recommended. Avoid applying power exceeding normal rated power; exceeding the power rating under steady-state loading condition may negatively affect product performance and reliability.

7. De-rate Power Dissipation (Pd) depending on Ambient temperature (Ta). When used in sealed area, confirm the actual ambient temperature.

8. Confirm that operation temperature is within the specified range described in the product specification.

9. ROHM shall not be in any way responsible or liable for failure induced under deviant condition from what is defined in this document.

Precaution for Mounting / Circuit board design

1. When a highly active halogenous (chlorine, bromine, etc.) flux is used, the residue of flux may negatively affect product performance and reliability.

2. In principle, the reflow soldering method must be used on a surface-mount products, the flow soldering method must be used on a through hole mount products. If the flow soldering method is preferred on a surface-mount products, please consult with the ROHM representative in advance.

For details, please refer to ROHM Mounting specification

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Precautions Regarding Application Examples and External Circuits

1. If change is made to the constant of an external circuit, please allow a sufficient margin considering variations of the characteristics of the Products and external components, including transient characteristics, as well as static characteristics.

2. You agree that application notes, reference designs, and associated data and information contained in this document are presented only as guidance for Products use. Therefore, in case you use such information, you are solely responsible for it and you must exercise your own independent verification and judgment in the use of such information contained in this document. ROHM shall not be in any way responsible or liable for any damages, expenses or losses incurred by you or third parties arising from the use of such information.

Precaution for Electrostatic

This Product is electrostatic sensitive product, which may be damaged due to electrostatic discharge. Please take proper caution in your manufacturing process and storage so that voltage exceeding the Products maximum rating will not be applied to Products. Please take special care under dry condition (e.g. Grounding of human body / equipment / solder iron, isolation from charged objects, setting of Ionizer, friction prevention and temperature / humidity control).

Precaution for Storage / Transportation

1. Product performance and soldered connections may deteriorate if the Products are stored in the places where:
   - [a] the Products are exposed to sea winds or corrosive gases, including Cl2, H2S, NH3, SO2, and NO2
   - [b] the temperature or humidity exceeds those recommended by ROHM
   - [c] the Products are exposed to direct sunshine or condensation
   - [d] the Products are exposed to high Electrostatic

2. Even under ROHM recommended storage condition, solderability of products out of recommended storage time period may be degraded. It is strongly recommended to confirm solderability before using Products of which storage time is exceeding the recommended storage time period.

3. Store / transport cartons in the correct direction, which is indicated on a carton with a symbol. Otherwise bent leads may occur due to excessive stress applied when dropping of a carton.

4. Use Products within the specified time after opening a humidity barrier bag. Baking is required before using Products of which storage time is exceeding the recommended storage time period.

Precaution for Product Label

QR code printed on ROHM Products label is for ROHM's internal use only.

Precaution for Disposition

When disposing Products please dispose them properly using an authorized industry waste company.

Precaution for Foreign Exchange and Foreign Trade act

Since concerned goods might be fallen under listed items of export control prescribed by Foreign exchange and Foreign trade act, please consult with ROHM in case of export.

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