

SYNCHRONOUS-BUCK PWM CONTROLLER WITH NMOS LDO CONTROLLER

FEATURES

- Switching Mode Step-Down dc-to-dc Controller With Fast LDO Controller
- Input Voltage Range
Switcher: 4.5 V to 28 V
LDO: 1.1 V to 3.6 V
- Output Voltage Range
Switcher: 0.9 V to 3.5 V
LDO: 0.9 V to 2.5 V
- Synchronous for High Efficiency
- Precision V_{REF} ($\pm 1\%$)
- PWM Mode Control: Max. 500-kHz Operation
- High-Speed Error Amplifier
- Overcurrent Protection With Temperature Compensation Circuit
- Overvoltage and Undervoltage Protection
- Programmable Short-Circuit Protection

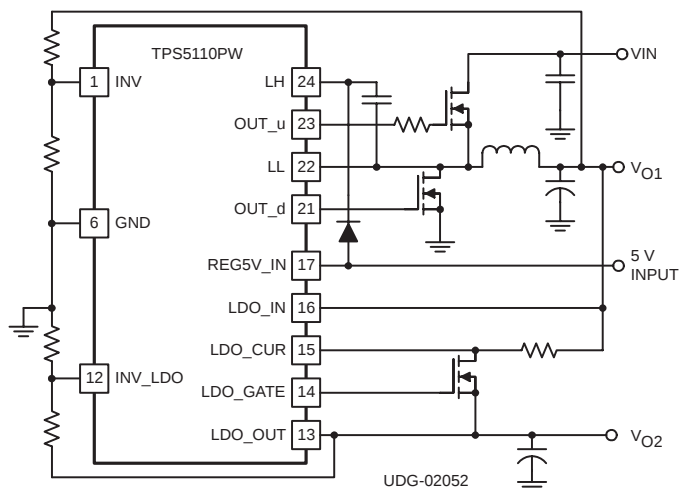
APPLICATIONS

- Notebook PCs, PDAs
- Consumer Game Systems
- DSP Application

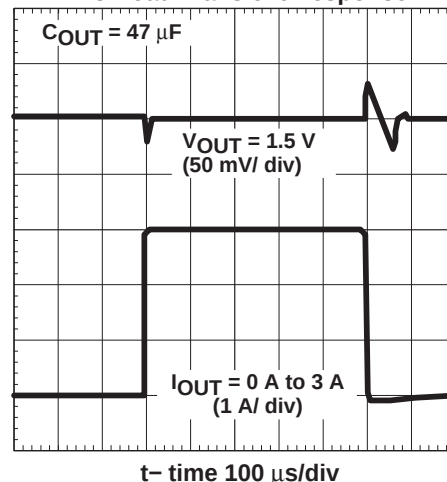
DESCRIPTION

The TPS5110 provides one PWM-mode synchronous buck regulator controller (SBRC) and one low drop-out (LDO) regulator controller. The TPS5110 supports a low-voltage/high-current power supply for I/O and other peripherals in modern digital systems. The SBRC of the TPS5110 automatically adjusts from PWM mode to SKIP mode to maintain high efficiency under all load conditions. The LDO controller drives an external N-channel power MOSFET that realizes fast response and ultra-low dropout voltage. A unique overshoot protection circuit prevents a voltage hump at fast load decreasing transients. The current protection circuit for SBRC detects the drain-to-source voltage drop across the low-side and high-side power MOSFET while it is conducting. Also, the current protection circuit has a temperature coefficient to compensate for the $R_{DS(on)}$ variation of the MOSFET. This resistor-less current protection simplifies the system design and reduces the external parts count. The LDO controller includes current-limit protection. Other features, such as undervoltage lockout, power good, overvoltage, undervoltage, and programmable short-circuit protection promote system reliability.

SIMPLIFIED APPLICATION



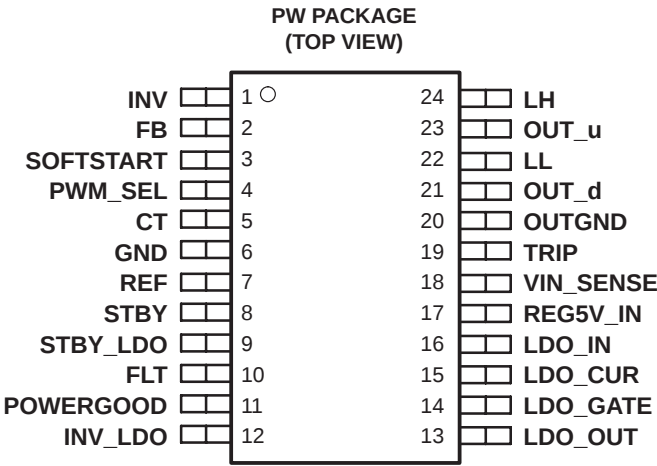
LDO Load Transient Response



ORDERING INFORMATION

T _A	PACKAGED DEVICES ⁽¹⁾
	PLASTIC TSSOP (PW)
–40°C to 85°C	TPS5110PW (24)

(1) The PW package is also available taped and reeled. Add an R suffix to the device type (i.e. TPS5110PWR)



ABSOLUTE MAXIMUM RATINGS

over operating free-air temperature range unless otherwise noted⁽¹⁾

		TPS5110	UNIT
Input voltage range, V_I	VIN_SENSE, STBY, STBY_LDO, TRIP, LL	-0.3 to 30	V
	INV, SOFTSTART, PWM_SEL, CT, FLT, INV_LDO, LDO_OUT, LDO_CUR, LDO_IN, REG5V_IN	-0.3 to 7	
	LH	-0.3 to 35	
Output voltage range, V_O	REF	-0.3 to 3	V
	FB, POWERGOOD, OUT_d	-0.3 to 7	V
	LDO_GATE	-0.3 to 9	V
	OUT_u	-0.3 to 35	V
Continuous total power dissipation		See dissipation rating table	
Operating ambient temperature range, T_A		-40 to 85	°C
Storage temperature range, T_{stg}		-55 to 150	

(1) Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability. All voltages are with respect to GND.

RECOMMENDED OPERATING CONDITIONS

		MIN	NOM	MAX	UNIT
Supply voltage	REG5V_IN	4.5		5.5	V
Supply voltage	LDO_IN	1.1		3.6	
Input voltage, V_I	VIN_SENSE	4.5		28	
	INV, INV_LDO, CT, PWM_SEL, SOFTSTART, FLT	-0.1		6	
	POWERGOOD, FB, OUT_d	-0.1		5.5	
	LDO_CUR, LDO_OUT	-0.1		3.5	
	STBY, STBY_LDO, LL	-0.1		28	
	OUT_u, LH	-0.1		33	
	TRIP	-0.1		28	
	LDO_GATE	-0.1		8	
Oscillator frequency, f_{OSC}			300	500	kHz
Operating free-air temperature, T_A		-40		85	°C

DISSIPATION RATINGS (THERMAL RESISTANCE = °C/W)

PACKAGE(1)	DERATING FACTOR ABOVE $T_A = 25^\circ\text{C}$	$T_A \leq 25^\circ\text{C}$ POWER RATING	$T_A = 85^\circ\text{C}$ POWER RATING
24-PW	11.24 mW/°C	1404 mW	730 mW

(2) These devices are mounted on a JEDEC high-k board (2 oz. traces on surface, 2-layer 1-oz plane inside).
(Assume the maximum junction temperature is 150°C)

ELECTRICAL CHARACTERISTICS

Over recommended free-air temperature range, $V_{VIN_SENSE} = 12\text{ V}$ and $V_{REG5V_IN} = 5\text{ V}$ (unless otherwise specified).

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
SUPPLY CURRENT SECTION					
I _{CC} Supply current	REG5V_IN current, T _A = 25°C, V _{LDO_IN} = 3.6 V, V _{CT} = V _{INV} = V _{INV_LDO} = V _{PWM_SEL} = 0 V		0.9	1.4	mA
I _{CC(S)} Shutdown current	REG5V_IN current, V _{STBY} = V _{STBY_LDO} = 0 V		0.001	10.00	μA
UNDERVOLTAGE LOCKOUT SECTION					
V _(TLH) Low-to-high threshold voltage	REG5V_IN voltage		3.6	4.2	V
V _(TLL) High-to-low threshold voltage	REG5V_IN voltage		3.5	4.1	
V _{HYS} Hysteresis	REG5V_IN voltage		30	200	mV
REFERENCE VOLTAGE SECTION					
V _{REF} Reference voltage			0.85		V
V _{REF(tol)} Reference voltage tolerance	T _A = 25°C, I _{REF} = 50 μA		−1%	1%	
	0°C ≤ T _A ≤ 85°C, I _{REF} = 50 μA		−1.5%	1.5%	
	−40°C ≤ T _A ≤ 85°C, I _{REF} = 50 μA		−2%	2%	
Reg(line) Line regulation	I _{REF} = 50 μA, 4.5 V ≤ V _(REG5V_IN) ≤ 5.5 V		0.05	5	mV
Reg(load) Load regulation	0.1 μA ≤ I _{REF} ≤ 1 mA		0.15	5	mV
CONTROL SECTION					
V _{IH} High-level input voltage	STBY, STBY_LDO, PWM_SEL		2.2		V
V _{IL} Low-level input voltage	STBY, STBY_LDO, PWM_SEL			0.3	
OUTPUT VOLTAGE MONITOR SECTION					
OVP comparator threshold voltage	SBRC, LDO		0.91	0.95 0.99	V
UVP comparator threshold voltage	SBRC, LDO		0.51	0.55 0.59	
Powergood comparator 1, 4 threshold voltage			0.75	0.79 0.81	
Powergood comparator 2, 3 threshold voltage			0.88	0.91 0.94	
Powergood propagation delay from INV and INV_LDO to POWERGOOD	POWERGOOD high-to-low		1.2		μs
	POWERGOOD low-to-high		4		
Timer latch current source	UVP protection		−1.5	−2.3 −3.1	μA
	OVP protection		−80	−125 −180	
OSCILLATOR SECTION					
f _{OSC} Oscillator frequency	PWM mode, C _{CT} = 44 pF T _A = 25°C		300		kHz
V _{OH} CT high-level output voltage	dc		1.0	1.1 1.2	V
	f _{OSC} = 300 kHz		1.17		
V _{OL} CT low-level output voltage	dc		0.4	0.5 0.6	
	f _{OSC} = 300 kHz		0.43		

ELECTRICAL CHARACTERISTICS

Over recommended free-air temperature range, $V_{VIN_SENSE} = 12\text{ V}$ and $V_{REG5V_IN} = 5\text{ V}$ (unless otherwise specified).

SBRC ERROR AMPLIFIER SECTION						
V _{IO} Input offset voltage	T _A = 25°C	2	10	mV		
Open loop voltage gain		50	dB			
Unity gain bandwidth		2.5	MHz			
I _{SNK} Output sink current	V _{FB} = 1 V	0.2	0.7	mA		
I _{SRC} Output source current	V _{FB} = 1 V	−0.2	−0.9			
DUTY CONTROL SECTION						
DUTY Maximum duty control	f _{OSC} = 300 kHz, V _{INV} = 0 V	82%				
OUTPUT DRIVERS SECTION						
OUT_u sink current	V _{OUT_u} − V _{LL} = 3 V	1.2	A			
OUT_u source current	V _{LH} − V _{OUT_u} = 3 V	−1.2				
OUT_d sink current	V _{OUT_d} = 3 V	1.5				
OUT_d source current	V _{OUT_d} = 2 V	−1.5				
LDO_GATE sink current	V _{LDO_GATE} = 2 V	1.5	mA			
LDO_GATE source current	V _{LDO_GATE} = 2 V	−1.4				
I _{TRIP} TRIP current	T _A = 25°C	11.5	13.0	14.5	μA	
SOFT-START SECTION						
I _{SOFT} Soft-start current		−1.6	−2.3	−2.9	μA	
LDO ERROR AMPLIFIER SECTION						
V _{IO} Input offset voltage	T _A = 25°C, V _{LDO_IN} = 3.3 V	2	10	mV		
Open loop voltage gain	V _{LDO_IN} = 3.3 V	50	dB			
Unity-gain bandwidth	V _{LDO_IN} = 3.3 V, C _{LOAD} = 2000 pF	1.4	MHz			
LDO CURRENT LIMIT SECTION						
Current limit comparator threshold voltage	V _{LDO_IN} = 3.3 V	40	50	60	mV	
LDO OVERSHOOT PROTECTION SECTION						
LDO_OUT sink current	V _{LDO_OUT} = V _{LDO_GATE} = 1.5 V	25	mA			

Terminal Functions

TERMINAL		I/O	DESCRIPTION
NAME	NO.		
CT	5	I/O	External capacitor from CT to GND adjusts frequency of the triangle oscillator.
FB	2	O	Feedback output of error amplifier
FLT	10	I/O	Fault latch timer pin. An external capacitor is connected between FLT and GND to set the FLT enable time up.
GND	6	–	Signal GND
INV	1	I	Inverting input of the SBRC error amplifier, skip comparator, OVP/UVLP comparators and POWERGOOD comparator
INV_LDO	12	I	Inverting input of the LDO regulator, OVP/UVLP comparators and POWERGOOD comparator
LDO_CUR	15	I	Current sense input of the LDO regulator.
LDO_GATE	14	O	Gate control output of an external MOSFET for LDO
LDO_OUT	13	I/O	LDO regulator's output connection. If output voltage causes an over shoot at output current changes high to low quickly, it pulls out electrical charge from this pin.
LDO_IN	16	I	Input of LDO regulator and current sense input of LDO regulator
LH	24	I/O	Bootstrap capacitor connection for high-side gate driver
LL	22	I/O	High side gate driving return. Connect this pin to the junction of the high side and low side MOSFET(s) for floating drive configuration. This pin also is an input terminal for current comparator.
OUT_d	21	O	Gate drive output for low-side MOSFET(s)
OUT_u	23	O	Gate drive output for high-side MOSFET(s).
OUTGND	20	–	Ground for FET drivers. It is connected to the current limiting comparator's negative input.
POWERGOOD	11	O	Power good open-drain output. PG comparators monitor both SBRC's and LDO's over voltage and under voltage. The threshold is $\pm 7\%$. When either output is beyond this condition, POWERGOOD output goes low. When STBY or STBY_LDO goes high, the POWERGOOD pin's output starts with high. POWERGOOD also monitors REG5V_IN's UVLO output.
PWM_SEL	4	I	PWM or auto PWM/SKIP modes select. H: auto PWM/SKIP L: PWM fixed
REF	7	O	0.85-V reference voltage output. This 0.85-V reference voltage is used for setting the output voltage and the voltage protections. This reference voltage is regulated from REG5V_IN power supply.
REG5V_IN	17	I	External 5-V input. This input is a supply voltage for internal circuits.
SOFTSTART	3	I/O	External capacitor between SOFTSTART and GND sets SBRC soft-start time.
STBY	8	I	Standby control input for SBRC. SBRC can be switched into standby mode by grounding the STBY pin.
STBY_LDO	9	I	Standby control input for LDO regulator. LDO regulator can be switched into standby mode by grounding the STBY_LDO pin.
TRIP	19	I	External resistor connection for SBRC's output current protection control.
VIN_SENSE	18	I	SBRC supply voltage monitor. Input range is 4.5 V to 28 V. This pin is for reference of current limit.

FUNCTIONAL BLOCK DIAGRAM

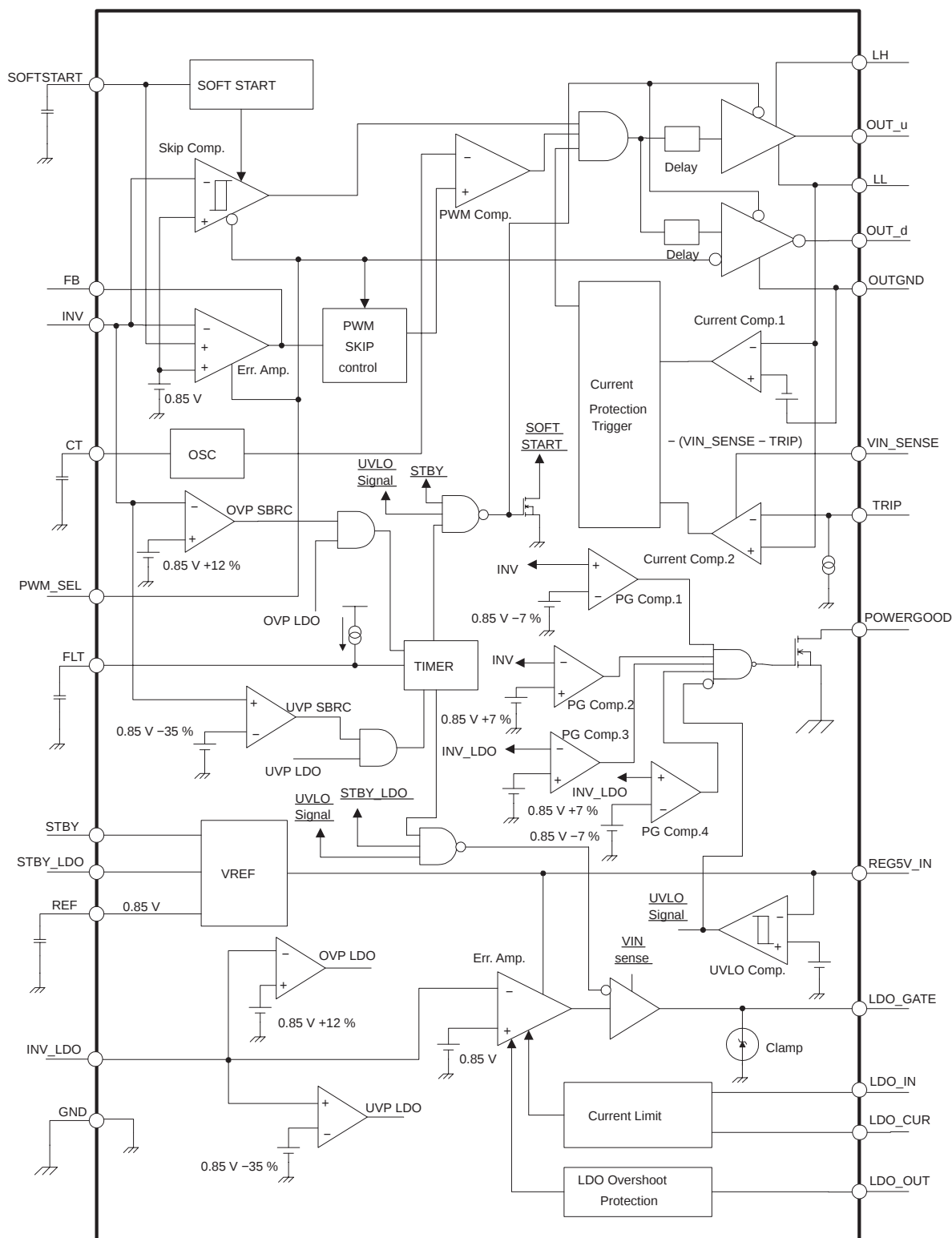


Figure 1. Block Diagram

DETAILED DESCRIPTION

PWM operation

The SBRC block has a high-speed error amplifier to regulate the output voltage of the synchronous buck converter. The output voltage of the SBRC is fed back to the inverting input (INV) of the error amplifier. The noninverting input is internally connected to a 0.85 V precise band gap reference circuit. The unity-gain bandwidth of the amplifier is 2.5 MHz. This decreases the amplifier delay during fast-load transients and contributes to a fast response. Loop gain and phase compensation is programmable by an external C, R network between the FB and INV pins. The output signal of the error amplifier is compared with a triangular wave to achieve the PWM control signal. The oscillation frequency of this triangular wave sets the switching frequency of the SBRC and is determined by the capacitor connected between the CT and GND pins. The PWM mode is used for the entire load range if the PWM_SEL pin is set LOW, or used in high-output current condition if auto PWM/SKIP mode is selected by setting the same pin to HIGH.

SKIP mode operation

The PWM_SEL pin selects either the auto PWM/SKIP mode or fixed PWM mode. If this pin is lower than 0.3 V, the SBRC operates in the fixed PWM mode. If 2.5 V (min.) or higher is applied, it operates in auto PWM/SKIP mode. In the auto PWM/SKIP mode, the operation changes from constant frequency PWM mode to an energy-saving SKIP mode automatically in accordance with load conditions. Using a MOSFET with ultra-low $R_{DS(on)}$ if the auto SKIP function is implemented is not recommended. The SBRC block has a hysteretic comparator to regulate the output voltage of the synchronous buck converter during SKIP mode. The delay from the comparator input to the driver output is typically 1.2 μ s. In the SKIP mode, the frequency varies with load current and input voltage.

high-side driver

The high-side driver is designed to drive high current and low $R_{DS(on)}$ N-channel MOSFET(s). The current rating of the driver is 1.2 A at source and sink. When configured as a floating driver a 5-V bias voltage is delivered from external REG5V_IN supply. The instantaneous-drive current is supplied by the flying capacitor between the LH and LL pins since a 5-V power supply does not usually have low impedance. It is recommended to add a 5- Ω to 10- Ω resistor between the gate of the high-side MOSFET(s) and the OUT_u pin to suppress noise. The maximum voltage that can be applied between the LH and OUTGND pins is 33 V. When selecting the high-current rating MOSFET(s), it is important to pay attention to both gate-drive power dissipation and the rise/fall time against the dead-time between high-side and low-side drivers. The gate-drive power is dissipated from the controller device and it is proportional to the gate charge at $V_{gs} = 5$ V, PWM switching frequency and the numbers of all MOSFETs used for low-side and high-side switches. This gate drive loss should not exceed the maximum power dissipation of the device.

low-side driver

The low-side driver is designed to drive high-current and low $R_{DS(on)}$ N-channel MOSFET(s). The maximum drive voltage is 5 V from REG5V_IN pin. The current rating of the driver is typically 1.5 A at source and sink. Gate resistance is not necessary for the low-side MOSFET for switching noise suppression since it turns on after the parallel diode is turned on (ZVS). It needs the same dissipation consideration when using high-current rating MOSFET(s). Another issue that needs precaution is the gate threshold voltage. Even though the OUT_d pin is shorted to the OUTGND pin with low resistance when the low-side MOSFET(s) is OFF, high dv/dt at the LL pin during turnon of the high side arm generates voltage peak at the OUT_d pin through the drain to gate capacitance, C_{dg} , of the low-side MOSFET(s). To prevent a short period shoot-through during this switching event, the application designer should select MOSFET(s) with adequate threshold voltage.

DETAILED DESCRIPTION

dead time

The internally defined dead-time prevents shoot-through current flowing through the main power MOSFETs during switching transitions. Typical value of the dead-time is 100 ns.

standby

The SBRC and the LDO controller can be switched into standby mode separately by grounding the STBY pin and/or SYBY_LDO pins. The standby-mode current, when both controllers are off, can be as low as 1 nA.

Table 1. Standby Logic ($V_{REG5V_IN} > 4\text{ V}$)†

STBY	STBY_LDO	SBRC	LDO	POWERGOOD
L	L	OFF	OFF	OFF
L	H	OFF	ON	OFF
H	L	ON	OFF	OFF
H	H	ON	ON	ON

soft start

Soft-start ramp up of the SBRC is controlled by the SOFTSTART pin voltage. After the STBY pin is raised to a HIGH level, an internal current source charges up an external capacitor connected between the SOFTSTART and GND pins. The output voltage ramps up as the SOFTSTART pin voltage increases from 0 V to 0.85 V. The soft-start time is easily calculated by the supply current and the capacitance value (see application information). The soft-start timing circuit for the LDO is integrated into the device. The soft-start time is fixed and can be as short as 600 μs . This is observed when the LDO is turned on separately from the SBRC. Simultaneous start up of the two outputs is also possible. Tie the LDO input to the SBRC's output and let both STBY_LDO and STBY voltages rise to the HIGH level simultaneously, then the LDO's output follows the ramp of the SBRC's output.

over current protection

Over current protection (OCP) is achieved by comparing the drain-to-source voltage of the high-side and low-side MOSFET to a set-point voltage, which is defined by both the internal current source, I_{TRIP} , and the external resistor connected between the VIN_SENSE and TRIP pins. I_{TRIP} has a typical value of 13 μA at 25°C. When the drain-to-source voltage exceeds the set-point voltage during low-side conduction, the high-side current comparator becomes active, and the low-side pulse is extended until this voltage comes back below the threshold. If the set-point voltage is exceeded during high-side conduction in the following cycle, the current-limit circuit terminates the high-side driver pulse. Together this action has the effect of decreasing the output voltage until the under voltage protection circuit is activated to latch both the high-side and low-side drivers OFF. In the TPS5110, trip current I_{TRIP} also has a temperature coefficient of 3400 ppm/°C in order to compensate for temperature drift of the MOSFET on-resistance.

DETAILED DESCRIPTION

OCP for the LDO

To achieve the LDO current limit, a sense resistor must be placed in series with the N-channel MOSFET drain, connected between the LDO_IN and LDO_CUR pins (see reference schematic). If the voltage drop across this sense resistor exceeds 50 mV, the output voltage is reduced to approximately 22% of the nominal value, thus activates UVP to start the FLT latch timer. When the time is up, the LDO_GATE pin is pulled LOW to makes the LDO regulator shutdown. Note that the SBRC is also latched OFF at the same time since the LDO and the SBRC share the same FLT capacitor.

overvoltage protection

For over voltage protection (OVP), the TPS5110 monitors the INV and INV_LDO pin voltages. When the INV or INV_LDO pin voltage is higher than 0.95 V (0.85 V +12%), the OVP comparator output goes low and the FLT timer starts to charge an external capacitor connected to FLT pin. After a set time, the FLT circuit latches the high-side and low-side MOSFET drivers and the LDO. The latched state of each block is summarized in Table 2. The timer-source current for the OVP latch is 125 μ A(typ.), and the time-up voltage is 1.185 V (typ.). The OVP timer is designed to be 50 times faster than the undervoltage protection timer described below.

Table 2. Overvoltage Protection Logic

OVP OCCURS AT	HIGH-SIDE MOSFET DRIVER	LOW-SIDE MOSFET DRIVER	LDO
SBRC	OFF	ON	OFF
LDO	OFF	OFF	OFF

undervoltage protection

For under voltage protection (UVP), the TPS5110 monitors the INV and INV_LDO pin voltages. When the INV or INV_LDO pin voltage is lower than 0.55 V (0.85 V – 35 %), the UVP comparator output goes low, and the FLT timer starts to charge the external capacitor connected to FLT pin. Also, when the current comparator triggers the OCP, the UVP comparator detects the under-voltage output and starts the FLT capacitor charge, too. After a set time, the FLT circuit latches all of the MOSFET drivers to the OFF state. The timer-latch source current for UVP is 2.3 μ A (typ.), and the time-up voltage is also 1.185 V (typ.). The UVP function of the LDO controller is disabled when voltage across the pass transistor is less than 0.23 V (typ.).

FLT

When an OVP or UVP comparator output goes low, the FLT circuit starts to charge the FLT capacitor. If the FLT pin voltage goes beyond a constant level, the TPS5110 latches the MOSFET drivers. At this time, the state of MOSFET is different depending on the OVP alert and the UVP alert, see Table 2. The enable time used to latch the MOSFET drivers is decided by the value of the FLT capacitor. The charging constant current value depends on whether it is an OVP alert or a UVP alert as shown in the following equation:

$$\text{FLTsource current (OVP)} = \text{FLTsource current (UVP)} \times 50$$

DETAILED DESCRIPTION

undervoltage lockout (UVLO)

When the REG5V_IN voltage decreases below about 4 V, the output stages of both the SBRC and the LDO are turned off. This state is not latched and the operation recovers immediately after the input voltage becomes higher than the turn-on value again. The typical hysteresis voltage is 100 mV.

UVLO for LDO

The LDO_IN voltage is monitored with a hysteretic comparator. When this voltage is less than 1 V, the UVLO circuit disables the UVP/OVP comparators that monitor the INV_LDO voltage. In case the SBRC over current protection is activated prior to that of the LDO's, this protection function may also be observed.

LDO control

The LDO controller can drive an external N-channel MOSFET. This realizes a fast response as well as an ultra-low dropout voltage regulator. For example, it is easy to configure both a 1.8-V and a 1.5-V high-current power supply for core and I/O of modern digital processors, one from the SBRC and the other from the LDO. The LDO_IN voltage range is from 1.1 V to 3.6 V, and the output voltage is adjustable from 0.9 V to 2.5 V by an external resistor divider. Gain and phase of the high-speed error amplifier for this LDO control is internally compensated and is connected to the 0.85-V band-gap reference circuit. The gate driver buffer is supplied by VIN_SENSE voltage. In the relatively high-output voltage applications, make sure that output voltage plus threshold voltage of the pass transistor is less than the minimum VIN. More precisely,

$$V_{\text{VIN_SENSE}} - 0.7 \text{ V} \geq V_{\text{THN}} + V_{\text{LDO_OUT}}$$

where V_{THN} is the threshold voltage of N-channel MOSFET.

The LDO controller is also equipped with OVP, UVP, over current limit and overshoot protection functions.

overshoot protection – LDO

In the event that load current changes from high to low very quickly, the LDO regulator output voltage may start to overshoot. In order to resist this phenomenon, the LDO controller has an overshoot protection function. If the LDO regulator output overshoots, the controller draws electrical charge out from LDO_OUT pin to hold it stable.

DETAILED DESCRIPTION

powergood

A single powergood circuit monitors the SBRC output voltage, LDO output voltage and REF5V_IN voltage. The POWERGOOD pin is an open-drain output. When INV or INV_LDO voltage go beyond $\pm 7\%$ of 0.85 V or the REG5V_IN voltage is lower than 4 V, the POWERGOOD pin is pulled down to the LOW level. POWERGOOD propagation delay is minimal, 1 μs to 4 μs .

Table 3. Powergood Logic†

STBY	STBY_LDO	$0.79\text{ V} \leq V_{\text{INV}} \leq 0.91\text{ V}$	$0.79\text{ V} \leq V_{\text{INV_LDO}} \leq 0.91\text{ V}$	$V_{\text{REG5V_IN}} > 4\text{ V}$	POWER GOOD
L	L	X	X	X	L
H	L	X	X	X	L
L	H	X	X	X	L
H	H	FALSE	X	X	L
H	H	X	FALSE	X	L
H	H	X	X	FALSE‡	L
H	H	TRUE	TRUE	TRUE	H

† X = True OR False

‡ The logic circuit is under normal operation

TYPICAL CHARACTERISTICS

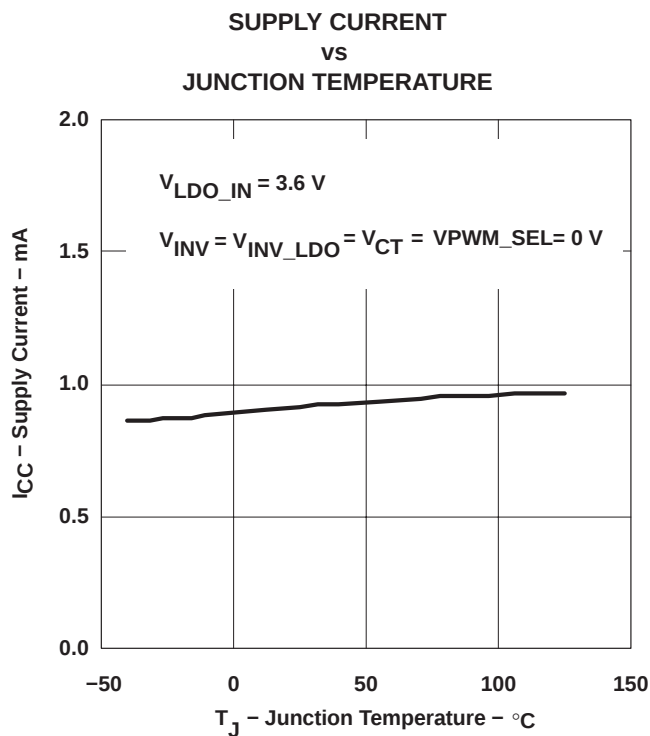


Figure 2

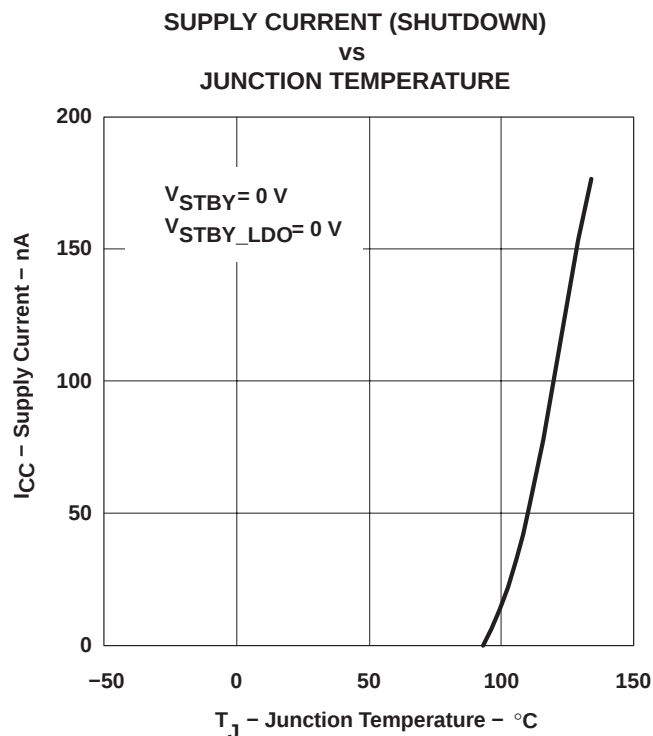
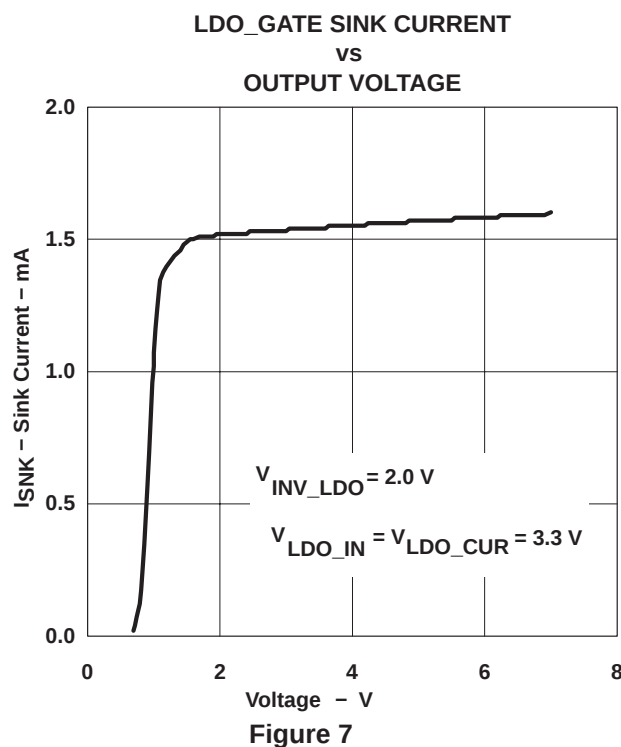
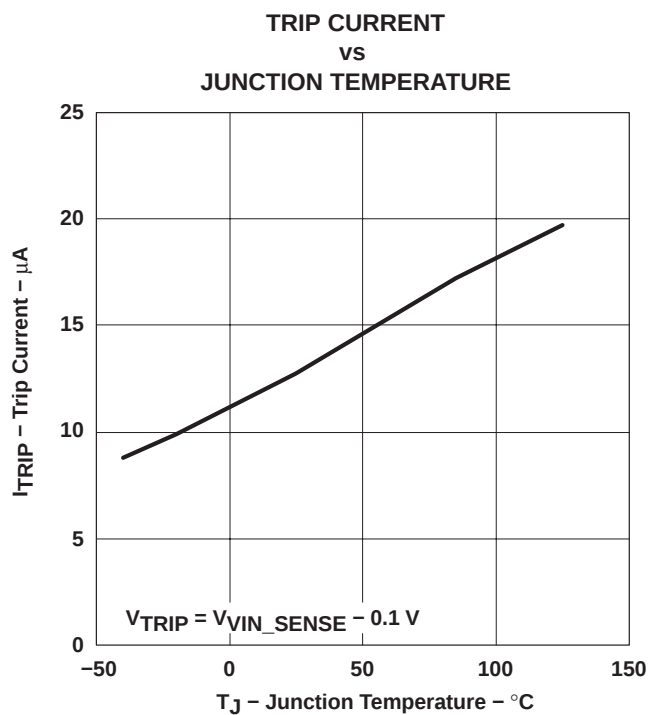
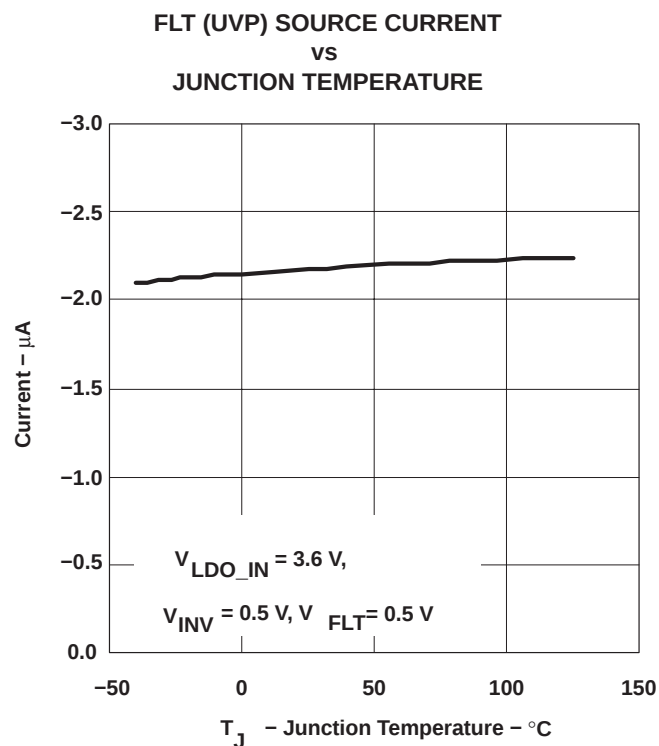
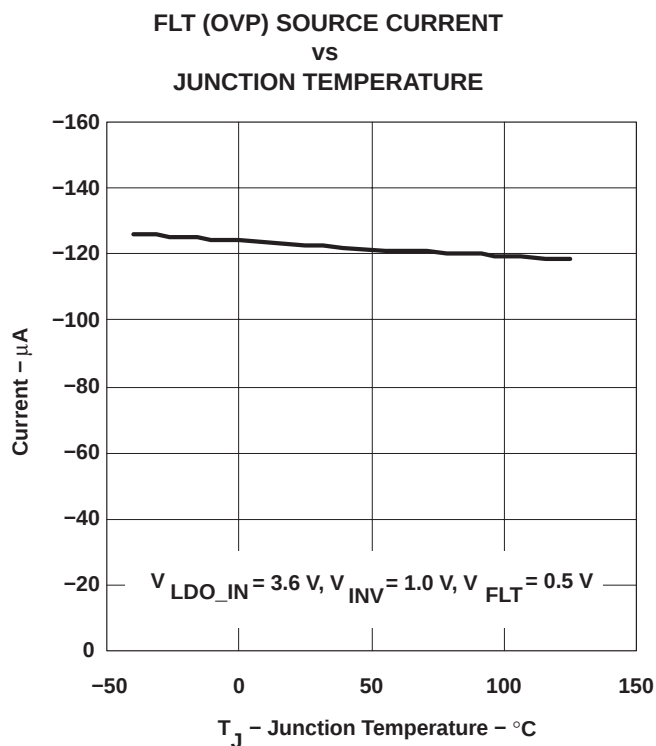


Figure 3

NOTE: $V_{\text{VIN_SENSE}} = 12\text{ V}$, $V_{\text{REG5V_IN}} = 5\text{ V}$ unless otherwise noted.

TYPICAL CHARACTERISTICS



NOTE: $V_{VIN_SENSE} = 12 V$, $V_{REG5V_IN} = 5 V$ unless otherwise noted.

TYPICAL CHARACTERISTICS

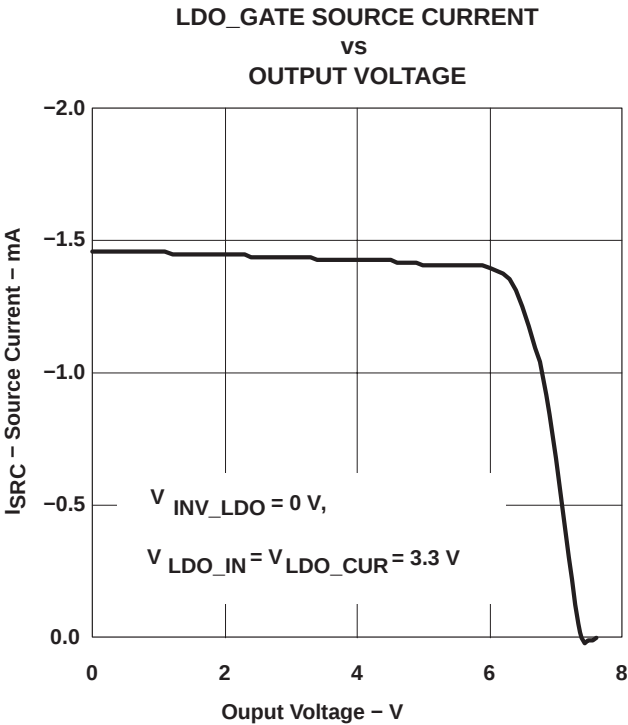


Figure 8

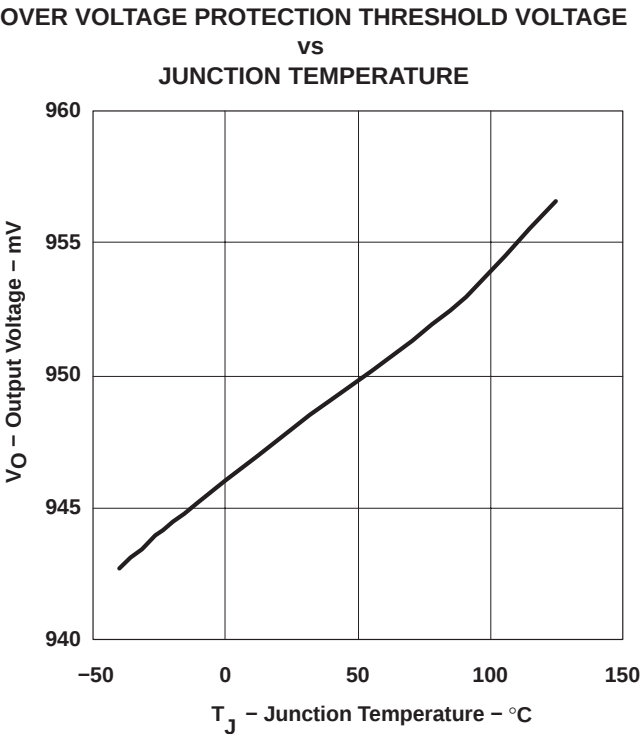


Figure 9

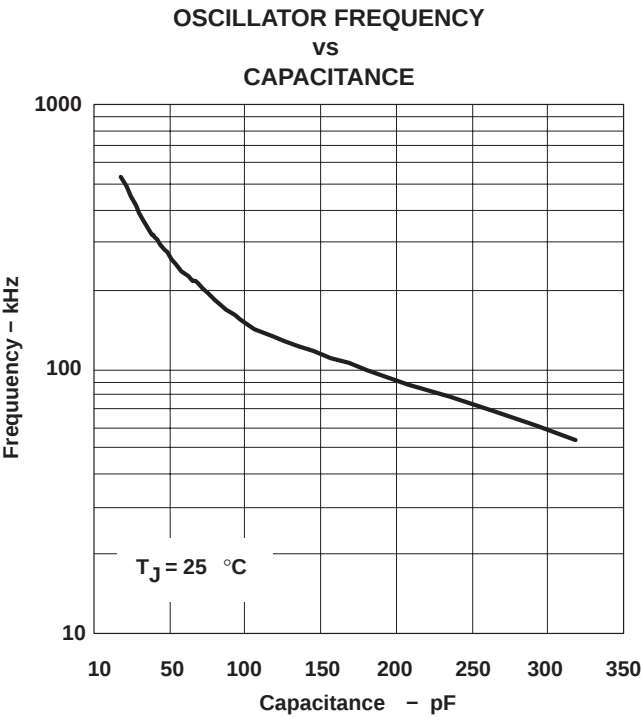


Figure 10

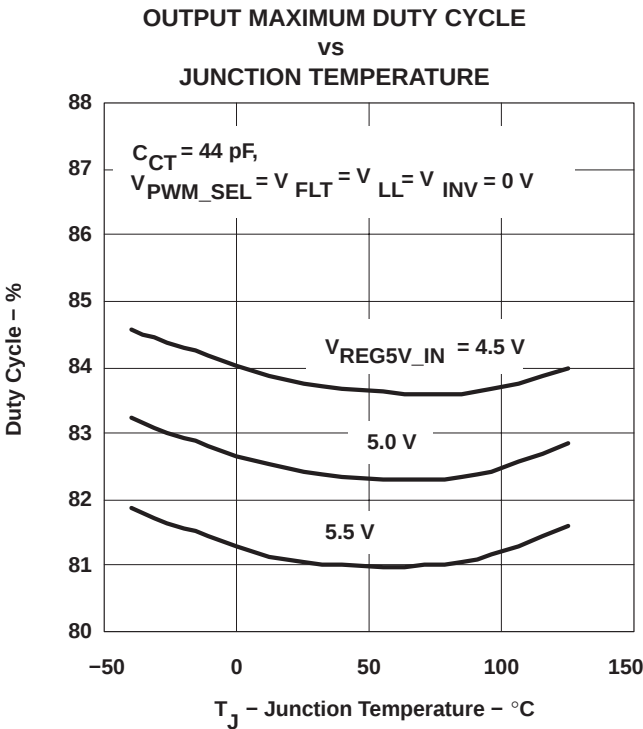


Figure 11

NOTE: $V_{VIN_SENSE} = 12\text{ V}$, $V_{REG5V_IN} = 5\text{ V}$ unless otherwise noted.

TYPICAL CHARACTERISTICS

FLT DELAY TIME (OVP)
vs
CAPACITANCE

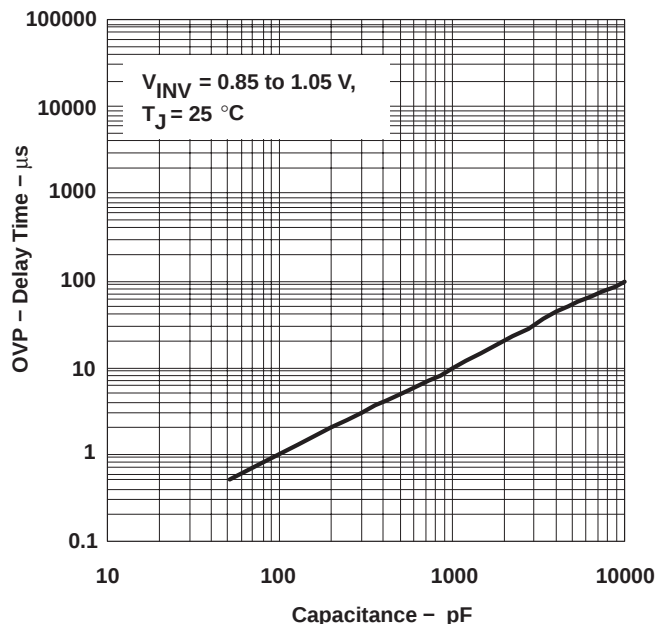


Figure 12

FLT DELAY TIME (UVP)
vs
CAPACITANCE

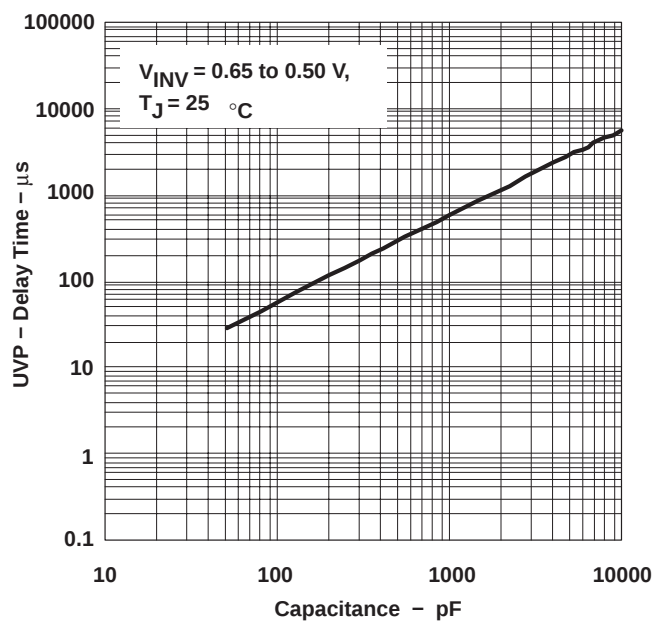


Figure 13

SOFT-START TIME
vs
CAPACITANCE

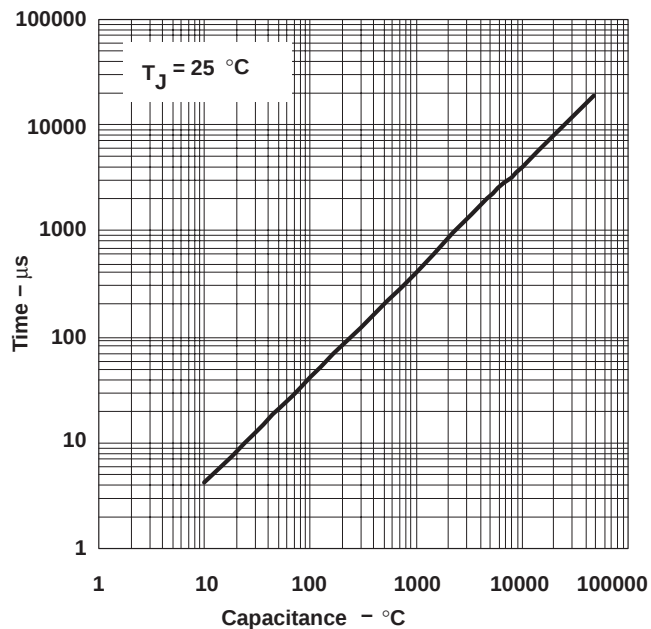


Figure 14

LDO CURRENT LIMIT THRESHOLD VOLTAGE
vs
JUNCTION TEMPERATURE

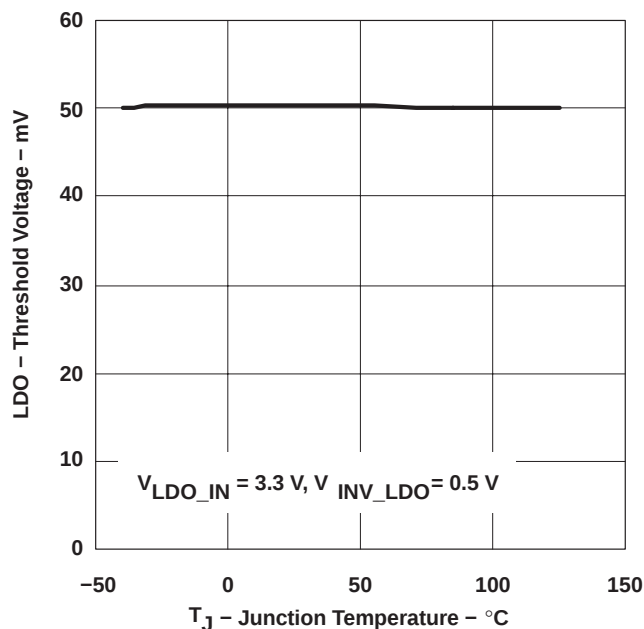
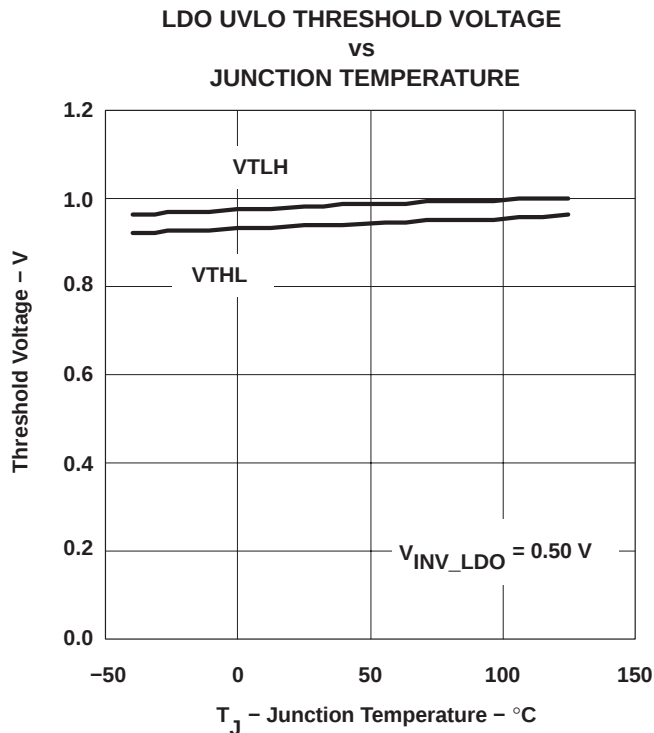


Figure 15

NOTE: $V_{VIN_SENSE} = 12 \text{ V}$, $V_{REG5V_IN} = 5 \text{ V}$ unless otherwise noted.

TYPICAL CHARACTERISTICS

**Figure 16**

NOTE: $V_{VIN_SENSE} = 12\text{ V}$, $V_{REG5V_IN} = 5\text{ V}$ unless otherwise noted.

APPLICATION INFORMATION

The design shown in this application information is a reference design for a notebook PC application. An evaluation module (EVM) is available for customer testing and evaluation. This information allows a customer to fully evaluate the given design using the plug-in EVM shown in Figure17. For subsequent board revisions, the EVM design can be copied onto the system PCB to shorten the design cycle.

The following key design procedures aid in the design of the notebook PC power supply using TPS5110. An optional circuit composed of Q04, R16, R22 and R24 can be used to increase temperature coefficient of the trip current, which is at the top in the page 18.

APPLICATION INFORMATION

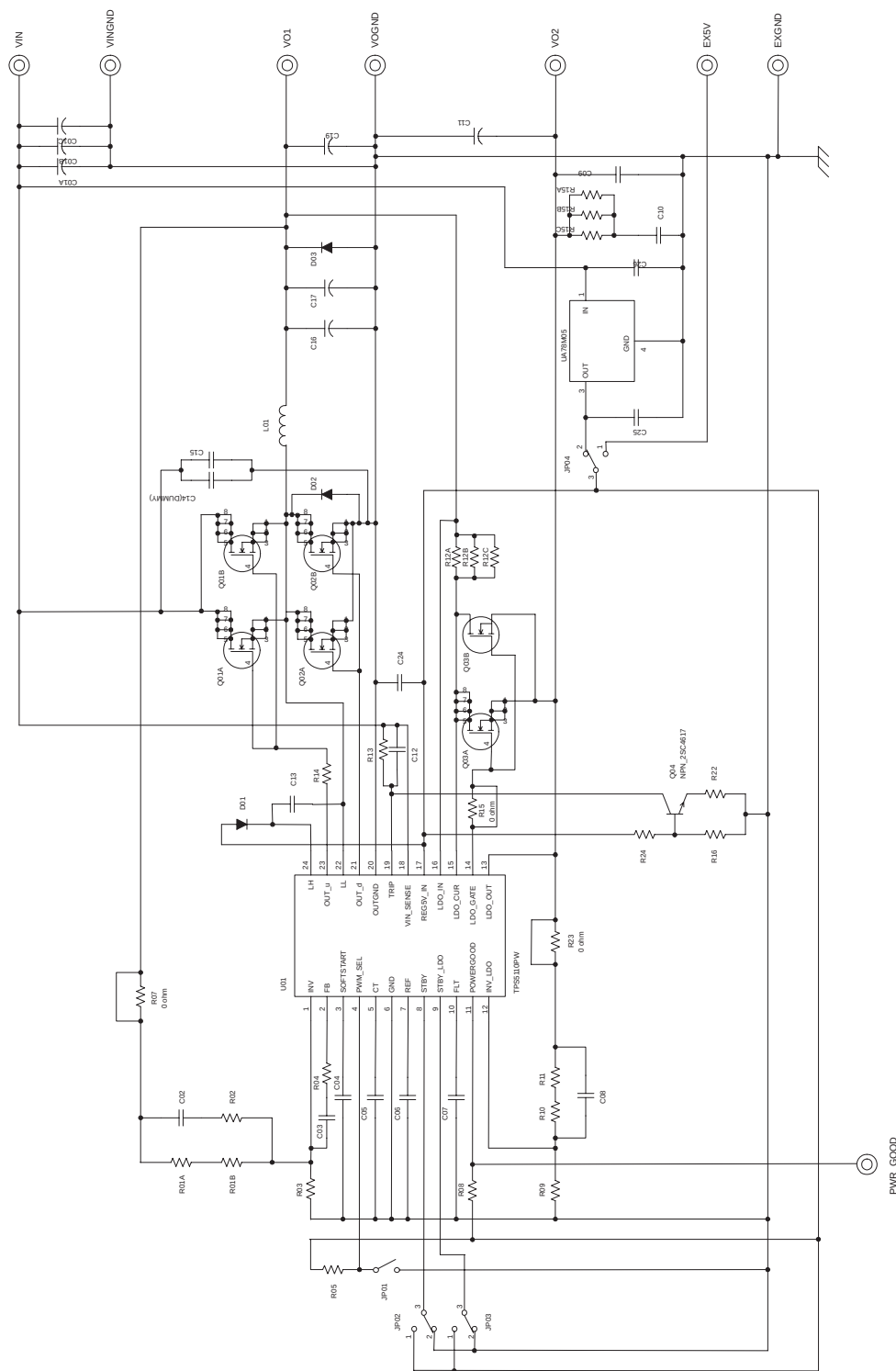


Figure 17. EVM Typical Design

APPLICATION INFORMATION

Table 4. EVM Input and Outputs

VIN†	REG5V_IN	Vo1 (SBRC)	Io1 (SBRC)	Vo2 (LDO)	Io2 (LDO)
8 V to 20 V	5 V	1.8 V	6 A	1.5 V	3 A

† Recommended operation voltage for the EVM

output voltage setpoint calculation

The reference voltage and the voltage divider set the output voltage. In the TPS5110, the reference voltage is 0.85 V, and the divider is composed of three resistors in the EVM design that are R01A, R01B and R03 for switching regulator output; R10, R11 and R09 for LDO regulator output.

$$V_O = \frac{R1 \times V_{REF}}{R2} + V_{REF} \quad \text{or} \quad R2 = \frac{R1 \times V_{REF}}{V_O - V_{REF}}$$

where R1 is the top resistor (kΩ) (R01A + R01B or R10 + R11); R2 is the bottom resistor (kΩ) (R03 or R09); V_O is the required output voltage (V); V_{REF} is the reference voltage (0.85 V in TPS5110). The value for R1 is set as a part of the compensation circuit and the value of R2 may be calculated to achieve the desired output voltage. In the EVM design, the value of R1 was determined as R01A = R01B = 10 kΩ for V_{O1}, and R10 = 6.8 kΩ and R11 = 820 Ω for V_{O2} considering stability. For V_{O1}:

$$R03 = \frac{20 \text{ k}\Omega \times 0.85}{1.8 - 0.85} = 17.89 \text{ k}\Omega$$

Use 18 kΩ.

For V_{O2}:

$$R09 = \frac{(6.8 \text{ k}\Omega + 820) \times 0.85}{1.5 - 0.85} = 9.96 \text{ k}\Omega$$

Use 10 kΩ.

The values of R01A, R01B, R10 and R11 are chosen so that the calculated values of R03 and R09 are those of standard value resistor and the V_O setpoint maintains the highest precision. This can be best accomplished by combining two resistor values. If a standard value resistor can not be applied such as R10 and R11, use a value for R10 that is just slightly less than the desired total. A small value resistor in the range of tens or hundreds of ohms for R11 can then be added to generate the desired final value.

APPLICATION INFORMATION

output inductor selection

The required value for the output-filter inductor can be calculated by using the equation:

$$L_{OUT} = \frac{(V_{IN} - V_O)}{k \times I_{OUT}} \times \frac{V_O}{V_{IN}} \times \frac{1}{f_S}$$

Where L_{OUT} is output filter inductor value (H), V_{IN} is the input voltage (V), I_{OUT} is the maximum output current (A), f_S is the switching frequency (Hz). Constant value k , a ratio of ripple current to output current, is typically in the range 0.2 to 0.3. For V_{O1} , the calculation for the maximum input voltage of 20 V, yields a value for L_{O1} of 3.03 μ H, and for minimum input voltage of 8 V, 2.58 μ H. For the EVM, a value of 2.8 μ H is used for L_{O1} .

output inductor ripple current

The output-inductor current can affect not only the efficiency, but also the output voltage ripple. The equation is exhibited below:

$$I_{RIPPLE} = \frac{V_{IN} - V_O - I_O \times (R_{DS(on)} + R_L)}{L_{OUT}} \times \frac{V_O}{V_{IN}} \times \frac{1}{f_S}$$

where I_{RIPPLE} is the peak-to-peak ripple current (A) through the inductor; I_O is the output current; $R_{DS(on)}$ is the on-time resistance of MOSFET (Ω); R_L is the inductor dc resistance (Ω). From the equation, it can be seen that the current ripple can be adjusted by changing the output inductor value. For the EVM design, the worst-case output ripple occurs with $V_{IN} = 20$ V:

Example: $V_{IN} = 20$ V; $V_O = 1.8$ V; $I_O = 6$ A; $R_{DS(on)} = 25$ m Ω ; $R_L = 10$ m Ω ; $F_s = 300$ kHz; $L_{OUT} = 2.8$ μ H.

Then, the ripple current $I_{RIPPLE} = 1.93$ A

output capacitor selection (SBRC)

Selection of the output capacitor is basically dependent on the amount of peak-to-peak ripple voltage allowed on the output and the ability of the capacitor to dissipate the RMS ripple current. Assuming that the ESR of the output filter sees the entire inductor-ripple current then:

$$V_{PP} = I_{RIPPLE} \times R_{ESR}$$

And a suitable capacitor must be chosen so that the peak-to-peak output ripple is within the limits allowable for the application.

APPLICATION INFORMATION

output capacitor RMS current (SBRC)

Assuming the inductor-ripple current totally goes through the output capacitor to ground, the RMS current in the output capacitor can be calculated as:

$$I_{O(rms)} = \frac{I_{RIPPLE}}{\sqrt{12}}$$

where $I_{O(rms)}$ is maximum RMS current in the output capacitor (A); I_{RIPPLE} is the peak-to-peak inductor-ripple current (A).

Example: $I_{RIPPLE} = 1.93$ A, therefore, $I_{O(rms)} = 0.56$ A

input capacitor RMS current (SBRC)

Assuming the input current totally goes into the input capacitor to the power ground, the RMS current in the input capacitor can be calculated as:

$$I_{i(rms)} = \sqrt{I_O^2 \times D \times (1 - D) + \frac{1}{12} D \times I_{RIPPLE}^2}$$

where $I_{i(rms)}$ is the input RMS current in the input capacitor (A); I_O is the output current (A); I_{RIPPLE} is the peak-to-peak output inductor-ripple current; D is the duty cycle and defined as V_O/V_I in this case. From the equation, it can be seen that the highest input RMS current usually occurs at the lowest input voltage, so it is the worst case design for input capacitor ripple current.

Example: $I_O = 6$ A; $D = 22.5\%$; $I_{RIPPLE} = 1.6$ A then, $I_{i(rms)} = 2.5$ A

The input capacitors must be chosen so that together they can safely handle the input-ripple current. Depending on the input filtering and the dc input voltage source, not all the ripple current flows through the input capacitors, but some may be present on the input leads to the EVM.

soft start

The soft-start timing can be adjusted by selecting the soft-start capacitor value. The equation is;

$$C_{SOFT} = 2.3 \times 10^{-6} \times \frac{T_{SOFT}}{0.85}$$

where C_{SOFT} is the soft-start capacitor (μ F) (C04 in EVM design); T_{SOFT} is the start-up time (s).

Example: $T_{SOFT} = 5$ ms, therefore, $C_{SOFT} = 0.0135$ μ F.

APPLICATION INFORMATION

current protection (SBRC)

The current limit in TPS5110 is set using an internal current source and an external resistor (R13). The current limit protection circuit compares the drain-to-source voltage of the high-side and low-side drivers with respect to the set-point voltage. If the voltage up exceeds the limit during high-side conduction, the current-limit circuit terminates the high-side driver pulse. If the set point voltage is exceeded during low-side conduction, the low-side pulse is extended through the next cycle. Together this action has the effect of decreasing the output voltage until the under voltage protection circuit is activated and the fault latch is set and both the high and low-side MOSFET drivers are shut off. The equation below should be used for calculating the external resistor value for current protection set point:

$$R_{CL} = \frac{R_{DS(on)} \times \left(I_{TRIP} + \frac{I_{RIPPLE}}{2} \right)}{13 \times 10^{-6}}$$

where R_{CL} is the external current limit resistor (R13); $R_{DS(on)}$ is the low-side MOSFET(Q02) on-time resistance. I_{TRIP} is the required current limit.

Example: $R_{DS(on)} = 25 \text{ m}\Omega$, $I_{TRIP} = 6 \text{ A}$, $I_{RIPPLE} = 1.93 \text{ A}$, therefore, $R_{CL} = 13.4 \text{ k}\Omega$.

It should be noted that $R_{DS(on)}$ of a FET is highly dependent on temperature, so to insure full output at maximum operating temperature, the value of $R_{DS(on)}$ in the above equation should be adjusted. For maximum stability, it is recommended that the high-side MOSFET(s) has same, or slightly higher $R_{DS(on)}$ than the low-side MOSFET(s). If the low-side MOSFET(s) has a higher $R_{DS(on)}$, in certain low duty cycle applications it may be possible for the device to regulate at an output current higher than that set by the above equation by increasing the high side conduction time to compensate for the missed conduction cycle caused by the extension of the previous low-side pulse.

timer latch

The TPS5110 includes fault latch function with a user adjustable timer to latch the MOSFET drivers in case of a fault condition. When either the OVP or UVP comparator detect a fault condition, the timer starts to charge FLT capacitor (C07), which is connected with FLT pin 10. The circuit is designed so that for any value of FLT capacitor, the under-voltage latch time $t_{(uvplatch)}$ is about 50 times larger than the over-voltage latch time $t_{(ovplatch)}$. The equations needed to calculate the required value of the FLT capacitor for the desired over and under-voltage latch delay times are:

$$C_{LAT} = 2.3 \times 10^{-6} \times \frac{t_{(uvplatch)}}{1.185} \quad \text{and} \quad C_{LAT} = 125 \times 10^{-6} \times \frac{t_{(ovplatch)}}{1.185}$$

where C_{LAT} is the external capacitor, $t_{(uvplatch)}$ is the time from UVP detection to latch. $t_{(ovplatch)}$ is the time from OVP detection to latch.

For the EVM, $t_{(uvplatch)} = 5 \text{ ms}$ and $t_{(ovplatch)} = 0.1 \text{ ms}$, so $C_{LAT} = 0.01 \text{ }\mu\text{F}$

If the voltage on the FLT pin reaches 1.185 V, the fault latch is set, and the MOSFET drivers are set as follows:

under-voltage protection

The under-voltage comparator circuit continually monitors the voltage at the INV and INV_LDO pins. If the voltage at either pin falls below 65% of the 0.85-V reference, the timer begins to charge the FLT capacitor. If the fault condition persists beyond the time $t_{(uvplatch)}$, the fault latch is set and both the high side and low-side drivers, and LDO regulator drivers are forced OFF.

APPLICATION INFORMATION

short circuit protection

The short circuit protection circuitry uses the UVP circuit to latch the MOSFET drivers. When the current-limit circuit limits the output current, then the output voltage goes below the target-output voltage and UVP comparator detects a fault condition as described above.

over voltage protection

The over-voltage comparator circuit continually monitors the voltage at the INV and INV_LDO pins. If the voltage at either pin rises above 112% of the 0.85-V reference, the timer begins to charge the FLT capacitor. If the fault condition persists beyond the time $t_{(ovplatch)}$, the fault latch is set and the high-side drivers are forced OFF, while the low-side drivers are forced ON, and LDO regulator drivers are forced OFF.

CAUTION: Do not set the FLT pin to a lower voltage (or GND) while the device is timing out an OVP or UVP event. If the FLT pin is manually set to a lower voltage during this time, output overshoot may occur. The TPS5110 must be reset by grounding STBY and STBY_LDO, or dropping down REG5V_IN.

disablement of the protection function

If it is necessary to inhibit the protection functions of the TPS5110 for troubleshooting or other purposes, the OCP, OVP and UVP circuits may be disabled.

- OCP(SBRC): Remove the current-limit resistors R13 to disable the current limit function.
- OCP(LDO): Short-circuit R12 to disable the current limit function.
- OVP, UVP: Grounding the FLT pin can disable OVP and UVP.

output capacitor selection for LDO

To keep stable operation of the LDO, capacitance of more than 33 μ F and R_{ESR} of more than 30 m Ω are recommended for the output capacitor.

power MOSFET selection for LDO

Also, to keep stable operation of the LDO, lower input capacitance is recommended for the external power MOSFET. However, too small input capacitance may lead the feedback loop into unstable region. In such a case, the gate resistor of several hundred ohms keeps the LDO operation in the stable state.

current protection for LDO

If excess output current flows through sense resistor (R12) and the voltage drop exceeds 50 mV, the output voltage is reduced to approximately 22% of the nominal value, thus activates UVP to start the FLT latch timer.

When the set current is 4 A, the value of R12 is 12.5 m Ω .

APPLICATION INFORMATION

layout guidelines

Good power supply results only occur when care is given to proper design and layout. Layout affects noise pickup and generation and can cause a good design to perform with less than expected results. With a range of currents from milli-amps to tens of amps, good power supply layout is much more difficult than most general PCB designs. The general design should proceed from the switching node to the output, then back to the driver section and, finally, parallel the low-level components. Below are specific points to consider before the layout of a TPS5110 design begins.

- A four-layer PCB design is recommended for design using the TPS5110. For the EVM design, the top layer contains the interconnection to the TPS5110, plus some additional signal traces. Layer 2 is fully devoted to the DRVGN plane. Layer 3 mainly has wide VIN and VO1 pattern. The bottom layer is almost devoted to other GND plane including ANAGND, and the rest is to wide signal trace for VO2.
- All sensitive analog components such as INV, REF, CT, GND, FLT and SOFTSTART should be reference to ANAGND.
- Ideally, all of the area directly under the TPS5110 chip should also be ANAGND.
- ANAGND and DRVGN should be isolated as much as possible, with a single point connection between them.

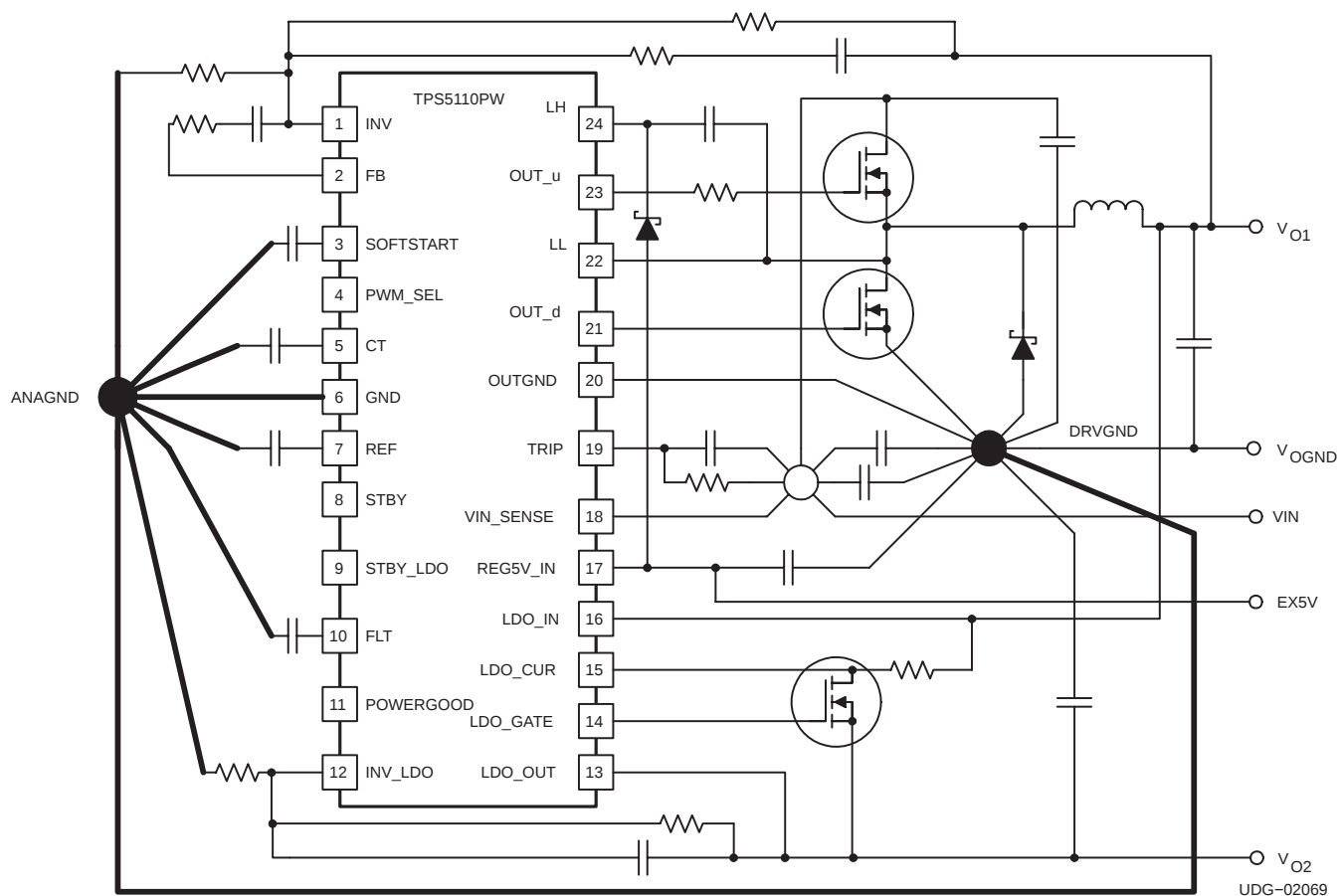


Figure 18. Four-Layer PCB Diagram

low-side MOSFET(s)

- The source of low-side MOSFET(s) should be referenced to DRVGNL, otherwise ANAGND is subject to the noise of the outputs.
- DRVGNL should be connected to the main ground plane close to the source of the low-side FET.
- OUTGND should be placed close to the source of low-side MOSFET(s).
- The Schottky diode anode, the returns for the high-frequency bypass capacitor for the MOSFETs, and the source of the low-side MOSFET(s) traces should be routed as close together as possible.

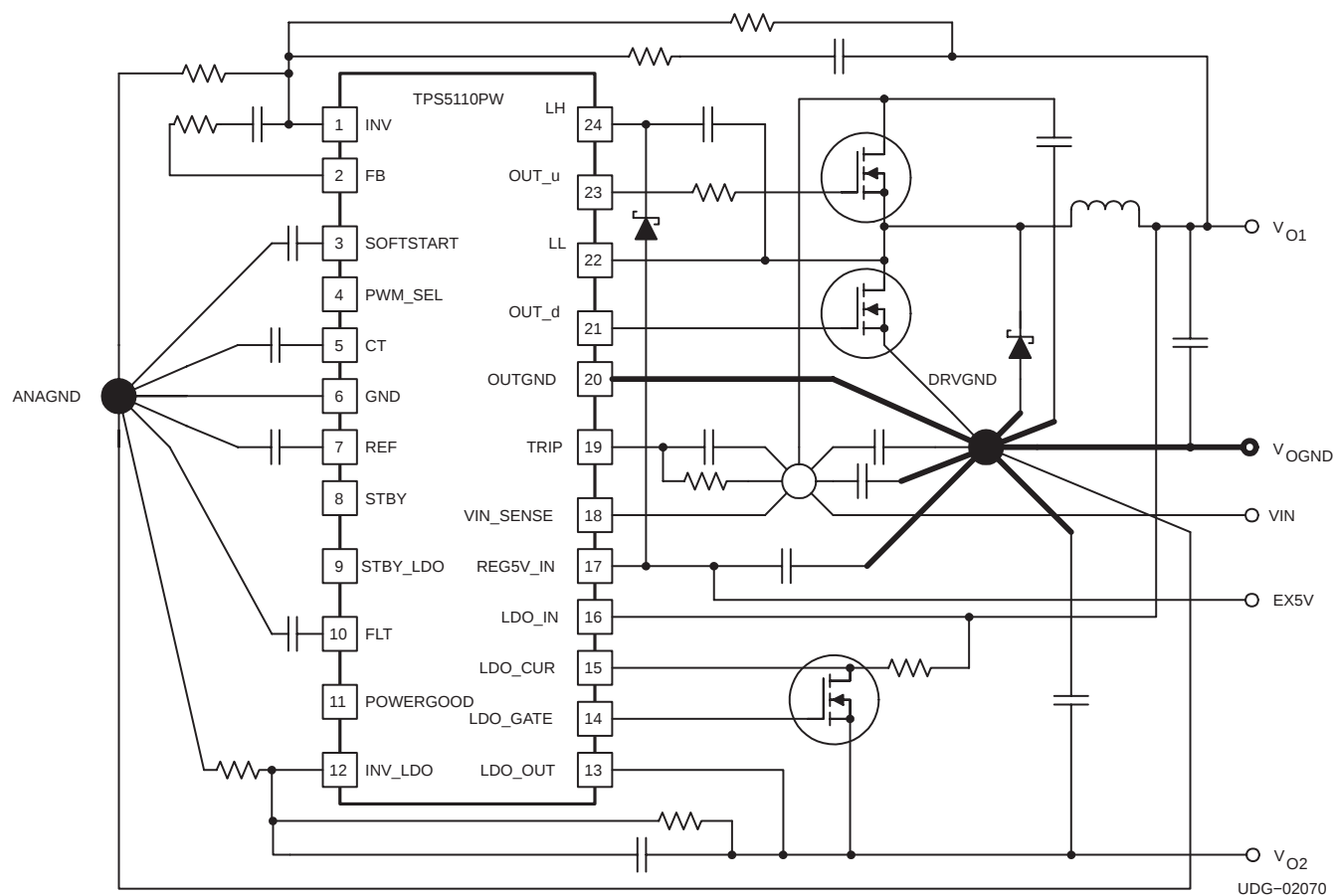


Figure 19. Low-Side MOSFETs Diagram

connections

- Connections from the drivers to the gate of the power MOSFETs should be as short and wide as possible to reduce stray inductance. This becomes more critical if external gate resistors are not being used. In addition, as for the current limit noise issue, use of a gate resistor on the high-side MOSFET(s) considerably reduce the noise at the LL node, improving the performance of the current limit function.
- The connection from LL to the power MOSFETs should be as short and wide as possible.

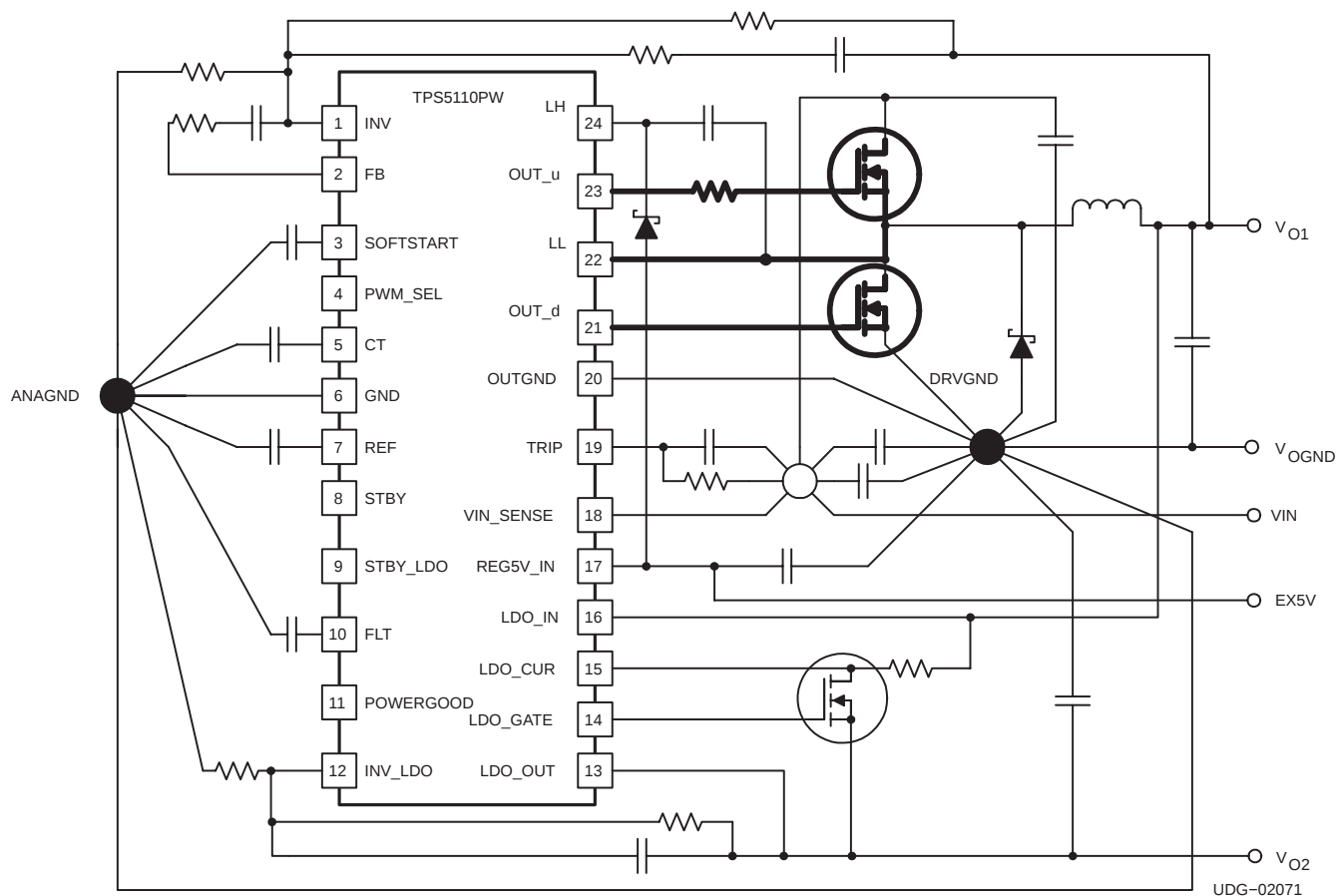


Figure 20. Connections From the Drivers to the Gate Diagram

APPLICATION INFORMATION

bypass capacitor

- The bypass capacitor for VIN_SENSE should be placed close to the TPS5110.
- The bulk-storage capacitors across VIN should be placed close to the power MOSFETs. High-frequency bypass capacitors should be placed in parallel with the bulk capacitors and connected close to the drain of the high-side MOSFET(s) and to the source of the low-side MOSFET(s).
- For aligning phase between the drain of high-side MOSFET(s) and the TRIP pin, and for noise reduction, a 0.1- μ F capacitor should be placed in parallel with the trip resistor.

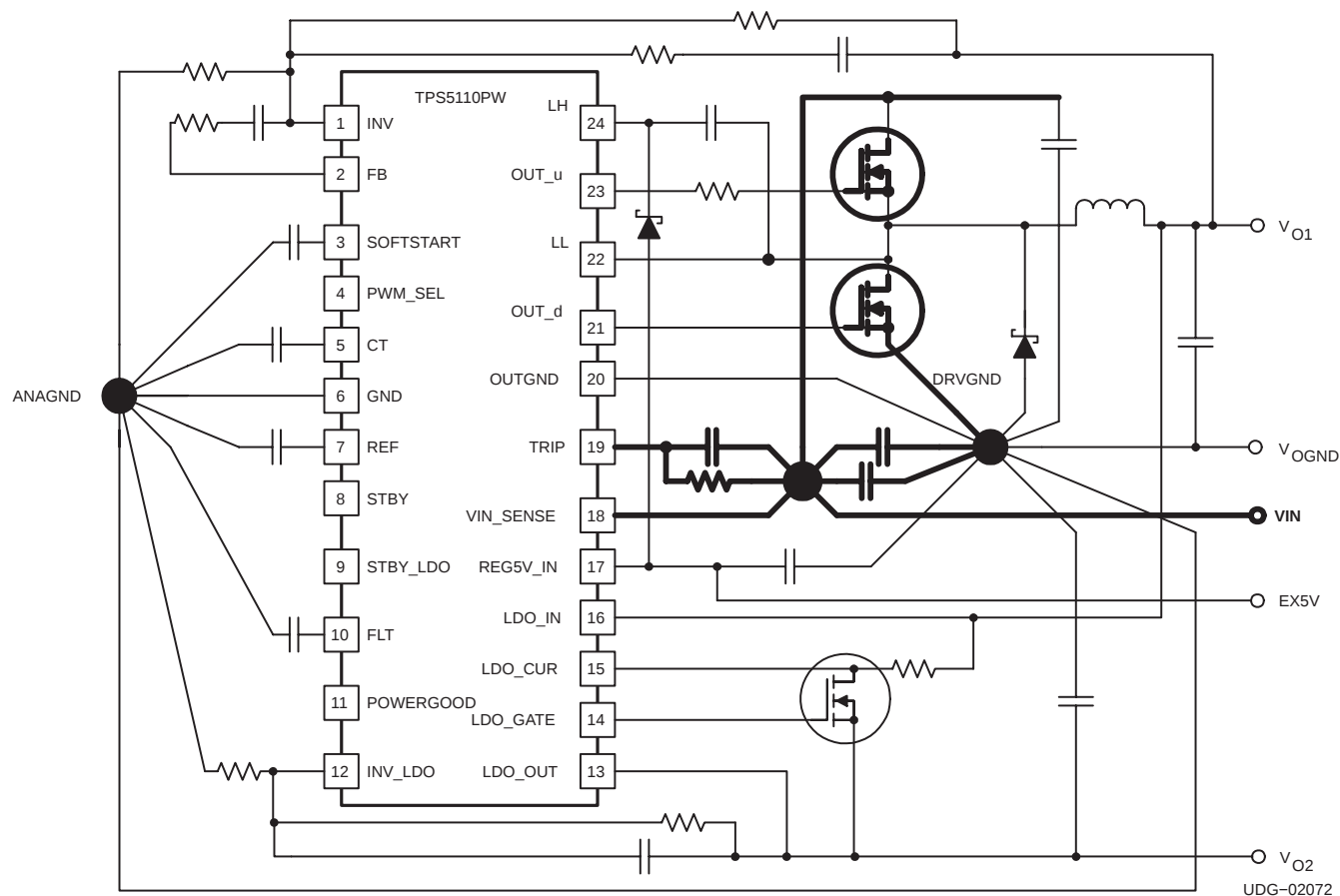


Figure 21. Bypass Capacitor Diagram

bootstrap capacitor

- The bootstrap capacitor (connected from LH to LL) should be placed close to the TPS5110.
- LH and LL should be routed close to each other to minimize differential-mode noise coupling to these traces.
- LH and LL should not be routed near the control pin area (ex. INV, FB, REF, etc.).

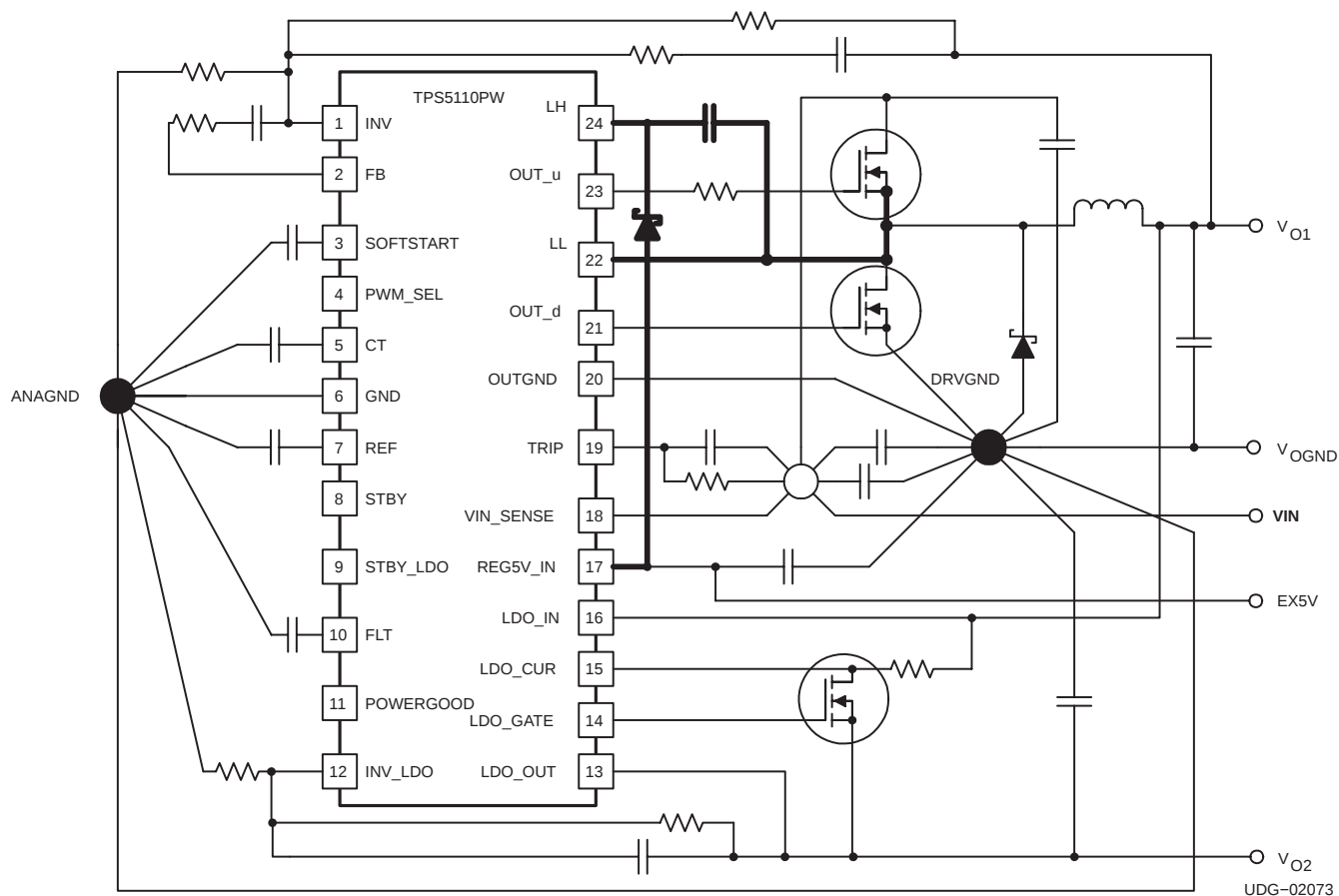


Figure 22. Bootstrap Capacitor Diagram

APPLICATION INFORMATION

output voltage

- The output voltage sensing trace should be isolated by either ground plane.
- The output voltage sensing trace should not be placed under the inductors on same layer.
- The feedback components should be isolated from output components, such as, MOSFETs, inductors, and output capacitors. Otherwise the feedback signal line is susceptible to output noise.
- The resistors for set up output voltage should be referenced to ANAGND.
- The INV trace should be as short as possible.

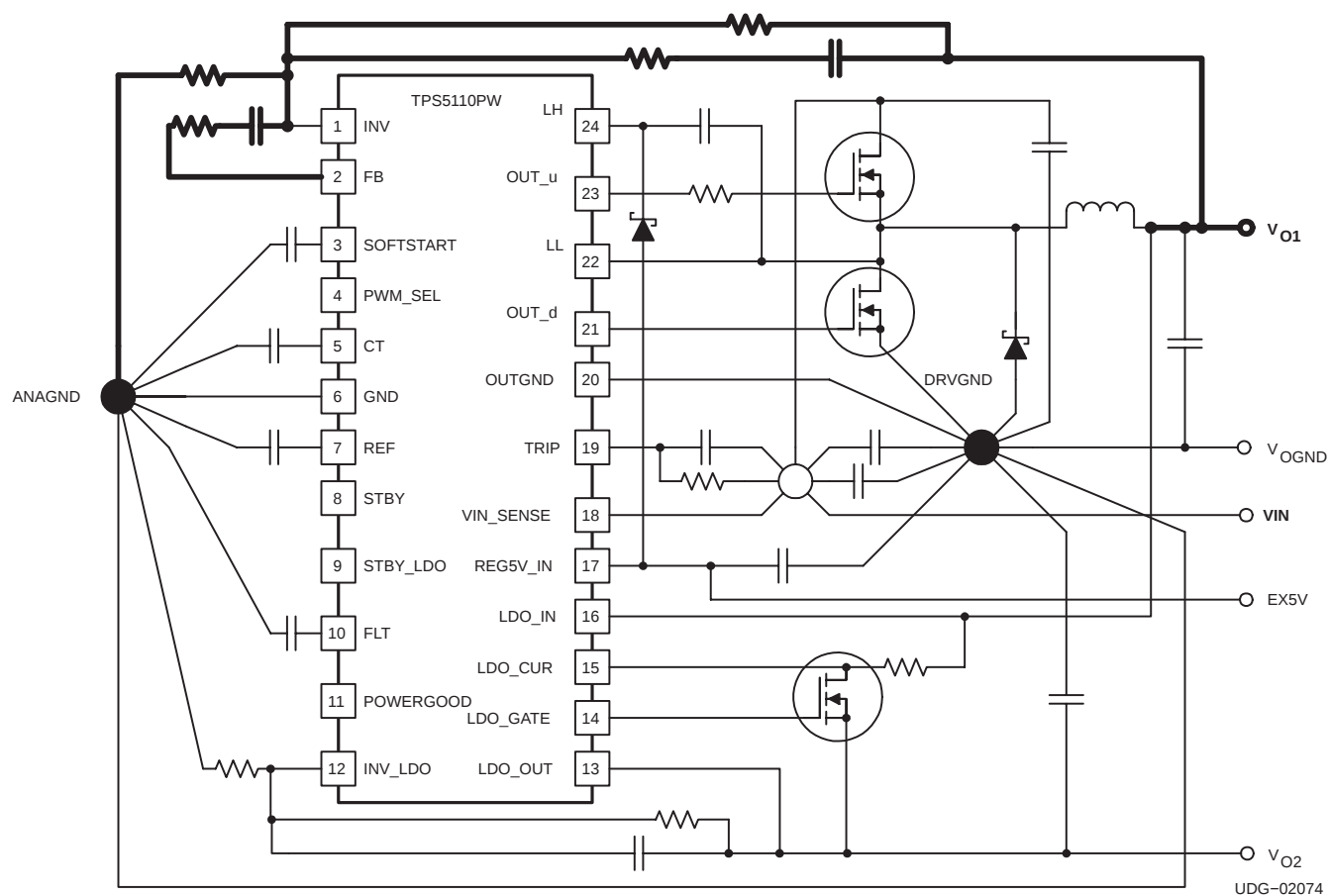


Figure 23. Output Voltage Diagram

APPLICATION INFORMATION

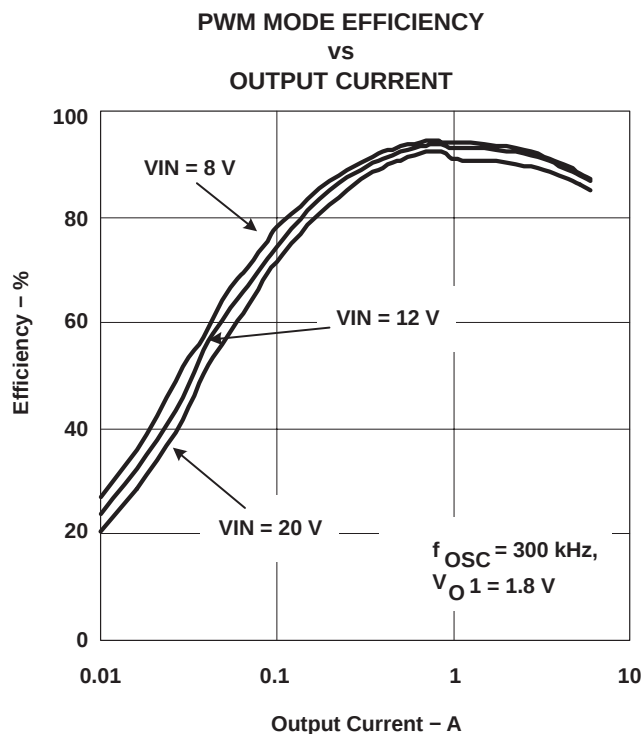


Figure 24

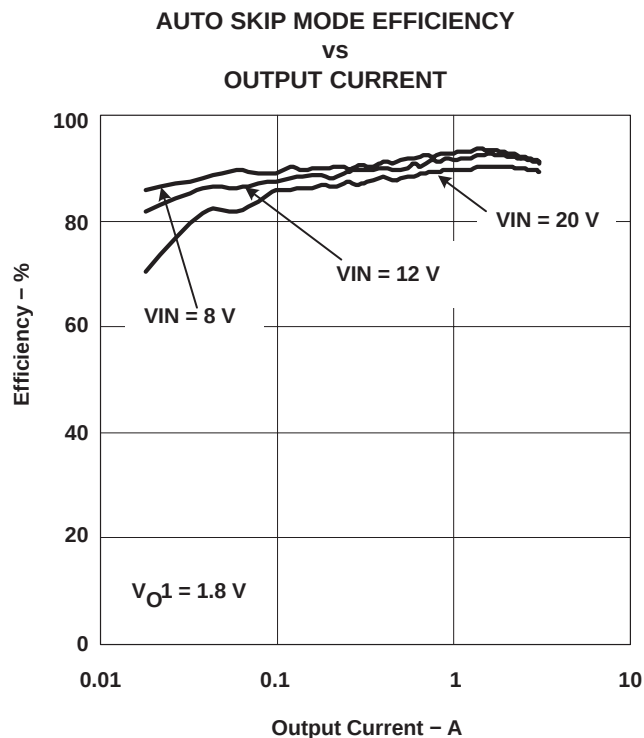


Figure 25

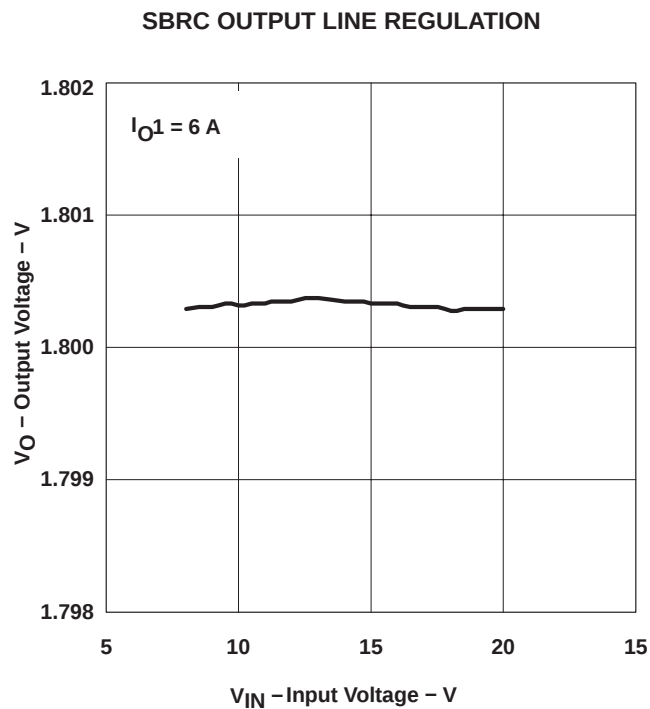


Figure 26

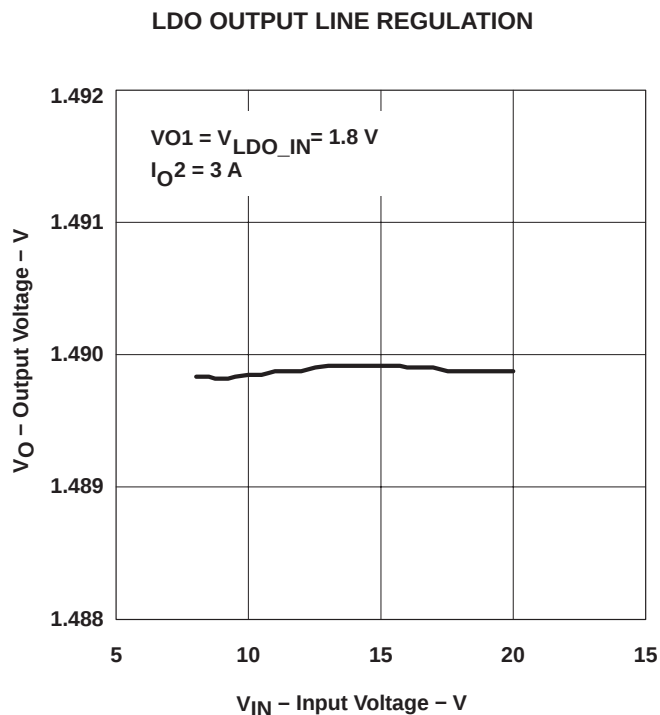


Figure 27

APPLICATION INFORMATION

SBRC OUTPUT LOAD REGULATION

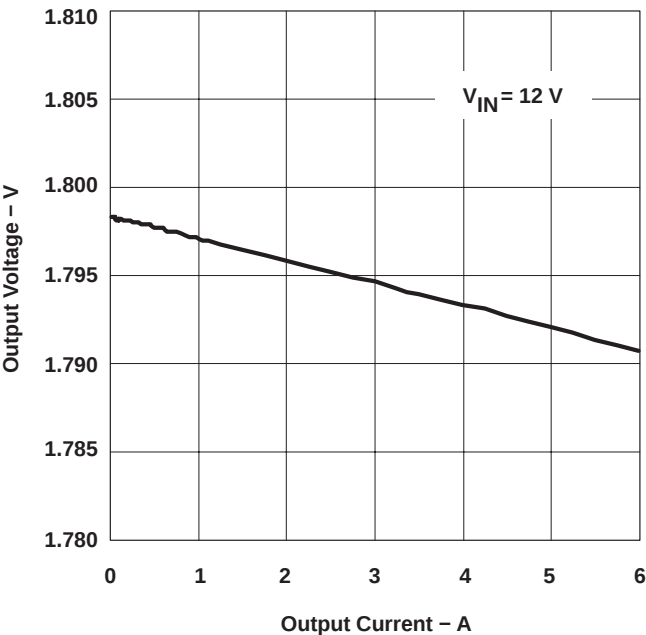


Figure 28

LDO OUTPUT LOAD REGULATION

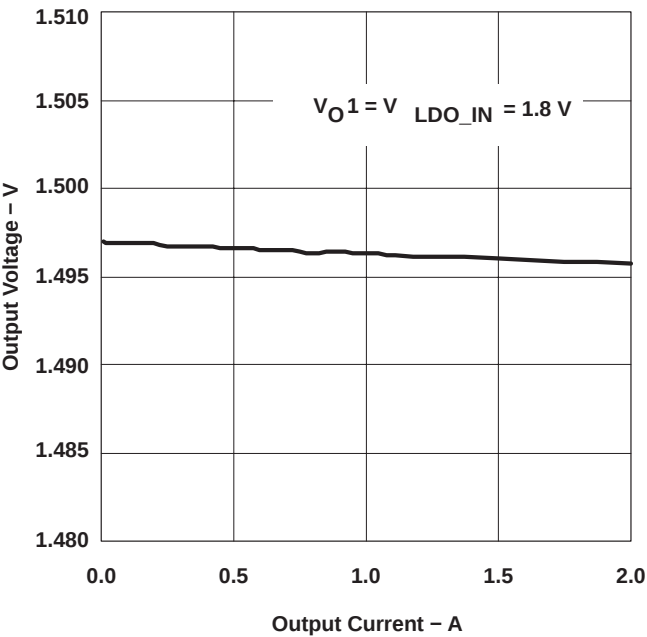


Figure 29

SBRC OUTPUT VOLTAGE RIPPLE

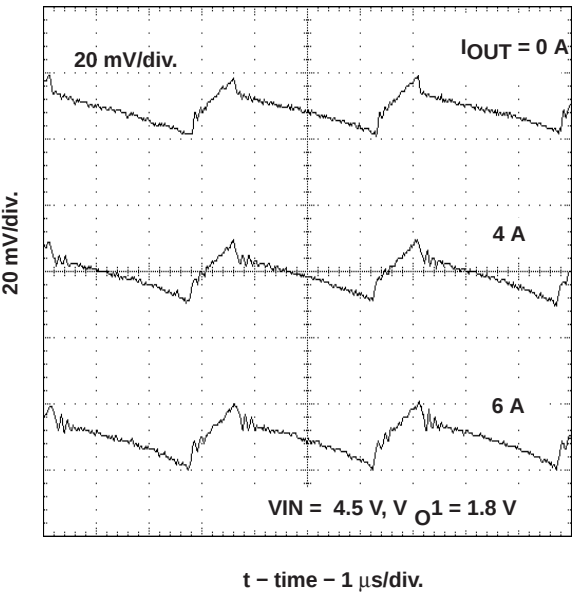


Figure 30

SBRC OUTPUT VOLTAGE RIPPLE

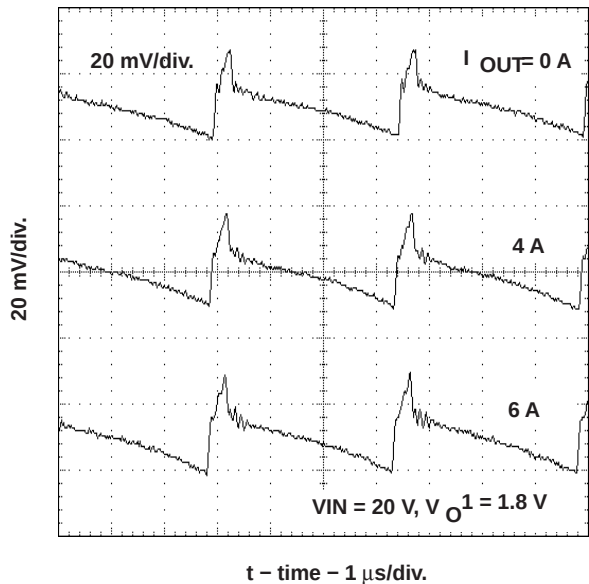


Figure 31

APPLICATION INFORMATION

LDO OUTPUT VOLTAGE RIPPLE

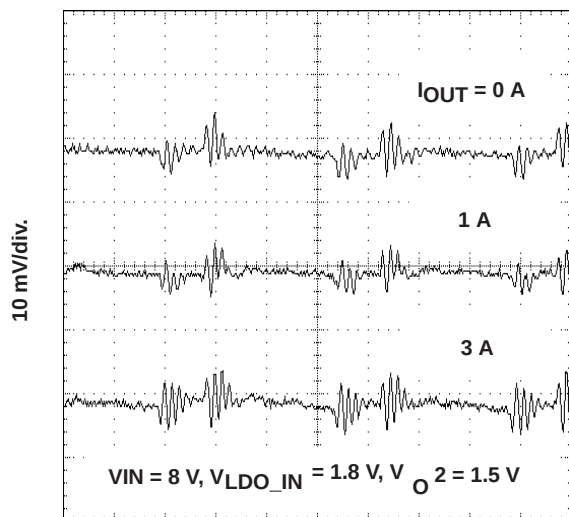
t – time – 1 $\mu\text{s}/\text{div.}$

Figure 32

LDO OUTPUT VOLTAGE RIPPLE

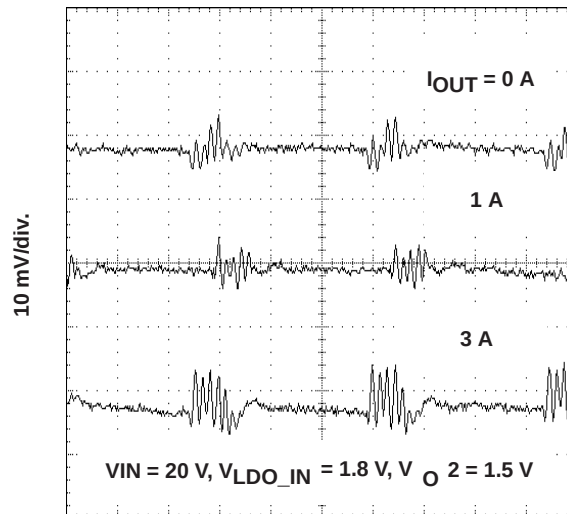
t – time – 1 $\mu\text{s}/\text{div.}$

Figure 33

SBRC LOAD TRANSIENT RESPONSE

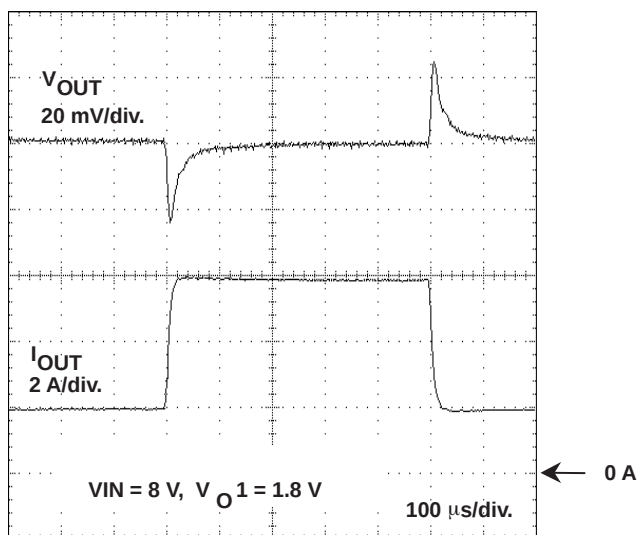
t – time – 100 $\mu\text{s}/\text{div.}$

Figure 34

SBRC LOAD TRANSIENT RESPONSE

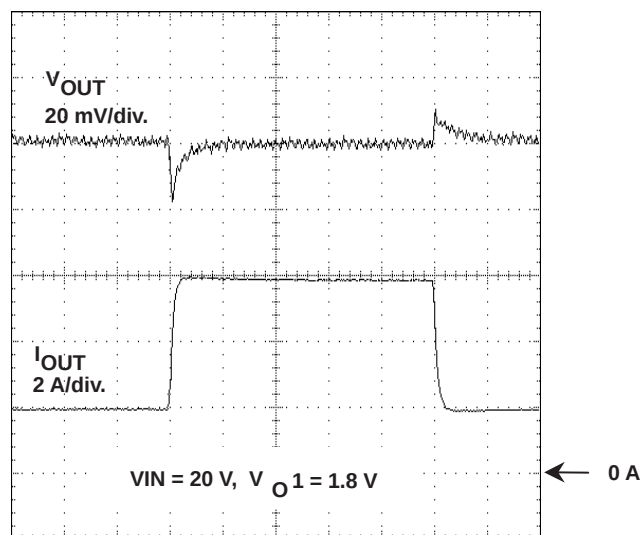
t – time – 100 $\mu\text{s}/\text{div.}$

Figure 35

APPLICATION INFORMATION

LDO LOAD TRANSIENT RESPONSE

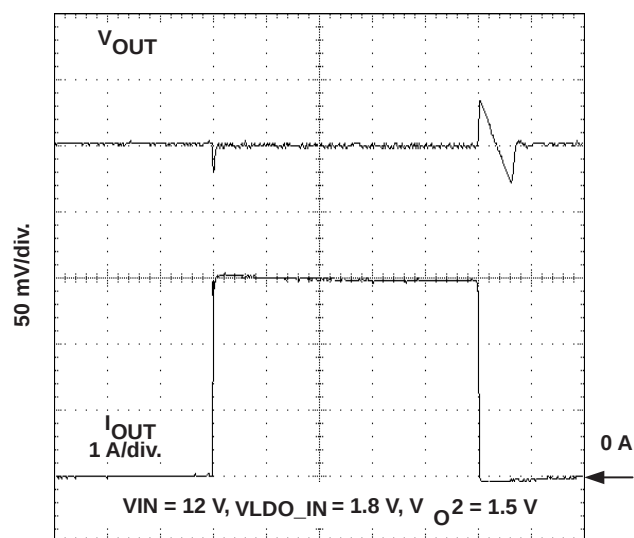
t – time – 100 $\mu\text{s}/\text{div.}$

Figure 36

SBRC-LDO SIMULTANEOUS START-UP

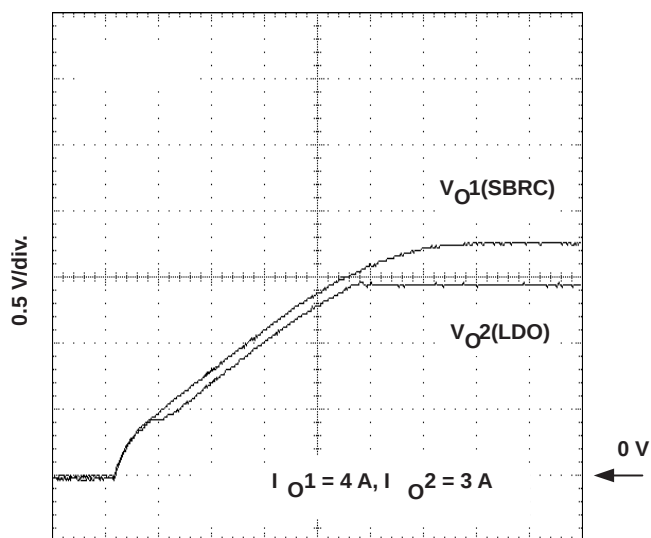
t – time – 1 $\mu\text{s}/\text{div.}$

Figure 37

SBRC GAIN AND PHASE

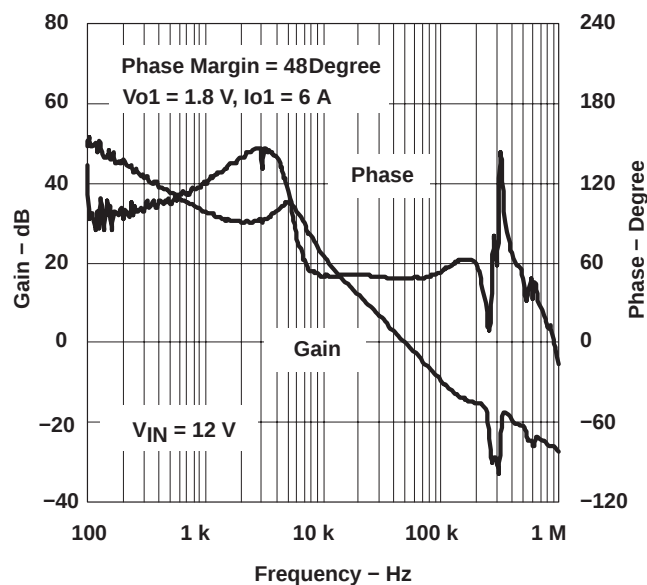


Figure 38

LDO GAIN AND PHASE

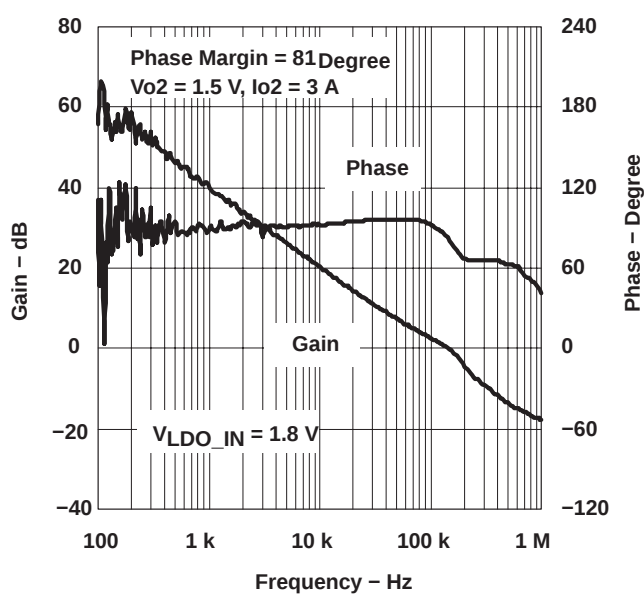


Figure 39

APPLICATION INFORMATION

Table 5. Bill of Materials

	Reference	Qty	Description	Manufacturer	Part Number
Capacitor	C01A	1	SP-VCAP, 22 μ F, 27 V, 8.3x8.3mm	Panasonic	EEFWA27220P
	C02, C03	2	Ceramic, 4700 pF, 10%, 2.0x1.25mm		
	C05	1	Ceramic, 47 pF, 5%, 2.0x1.25mm		
	C04, C07	2	Ceramic, 0.01 μ F, 2.0x1.25mm		
	C09	1	SPCAP, 47 μ F, 6.3 V, 7.3x4.3mm	Panasonic	EEFCD0J470R
	C01B, C06, C11, C12, C13, C19	6	Ceramic, 0.1 μ F, 2.0x1.25mm		
	C15	1	2.2 μ F, 35 V, 3.2x2.5mm	Taiyo-Yuden	GMK325BJ225MN-B
	C16, C17	2	SPCAP, 150 μ F, 2.5 V, 7.4x4.3mm	Panasonic	EEFUD0E151R
	C24	1	Ceramic, 10 μ F, 25 V	Taiyo-Yuden	TMK325BJ106MM
	C01C, C08, C10, C14, C25, C26		Removed		
Resistor	R01A, R01B, R09	1	10 k Ω , 1%, 2.0x1.25mm		
	R02	1	1.2 k Ω , 2.0x1.25mm		
	R03	1	18 k Ω , 1%, 2.0x1.25mm		
	R04	1	4.7 k Ω , 2.0x1.25mm		
	R05, R08	2	100 k Ω , 2.0x1.25mm		
	R10	1	6.8 k Ω , 1%, 2.0x1.25mm		
	R11	1	820 Ω , 1%, 2.0x1.25mm		
	R12A, R12B	2	22 m, 5%, 2.0x1.25mm	Susumu	RL1220T-R022-J
	R13	1	10 k Ω , 2.0x1.25mm		
	R14	1	10 Ω , 2.0x1.25mm		
	R12C, R15A, R15B, R15C, R16, R22, R24		Removed		
Inductor	L01	1	2.8 μ H, 12.5x12.5mm	Sumida	CEP125-2R8MC-H
Diode	D01	1	2.5x1.25mm	Hitachi	HSU119
	D02		Removed		
	D03	1	2.6x4.5mm	Rohm	RB160L-40
Nch MOSFET	Q01B	1	30 V, SOT-8	Fairchild	FDS6612A
	Q02B	1	30 V, SOT-8		FDS6690S*
	Q03A	1	30 V, SOT-8		FD6612A
	Q01A, Q02A, Q03B, Q04		Removed		

APPLICATION INFORMATION

Bill of Materials (continued)

IC	IC01	1	SSOP-24	TI	TPS5110PW
	IC02		Removed		
Jumper	JP01	1	Header, straight, 2-pin	Morex	22-28-4023
			Jumper, shunt		15-29-1025
	JP02, JP03	2	SW, 7x4.5mm	Nikkai	G-12AP
	JP04	1	Header, straight, 3-pin	Morex	22-28-4033
			Jumper, shunt		15-29-1025
Contact	EX5V, EXGND	4		Phoenix	MKDS1.5/2-5.08
	VIN, VINGND				
	VO1, VO2, VOGND	3			MKDS1.5/3-5.08

NOTE: Since the FDS6690S (Q02B) includes an integrated Schottky diode, D02 can be removed.

test setup

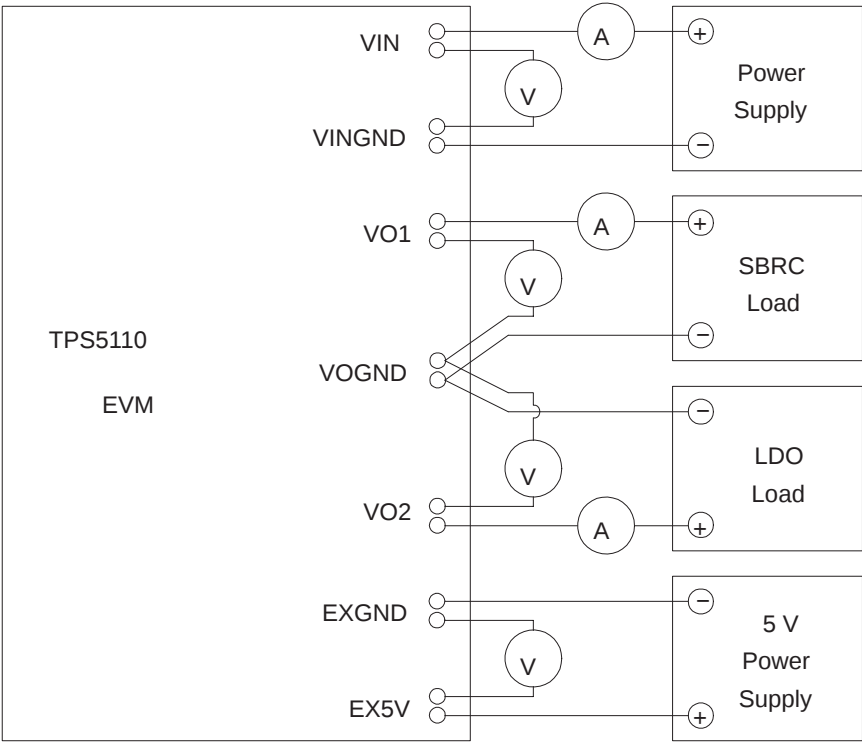


Figure 40. Schematic Diagram of the Test Setup

APPLICATION INFORMATION

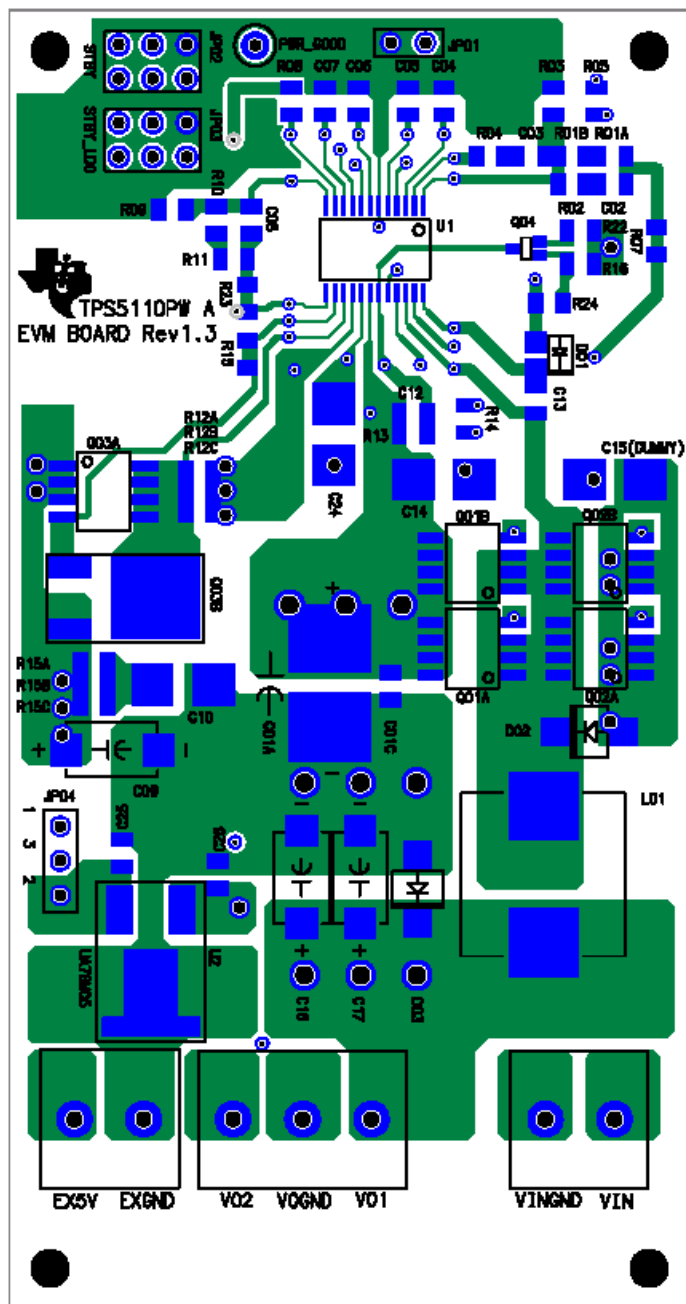


Figure 41. EVM Board Top Layer

APPLICATION INFORMATION

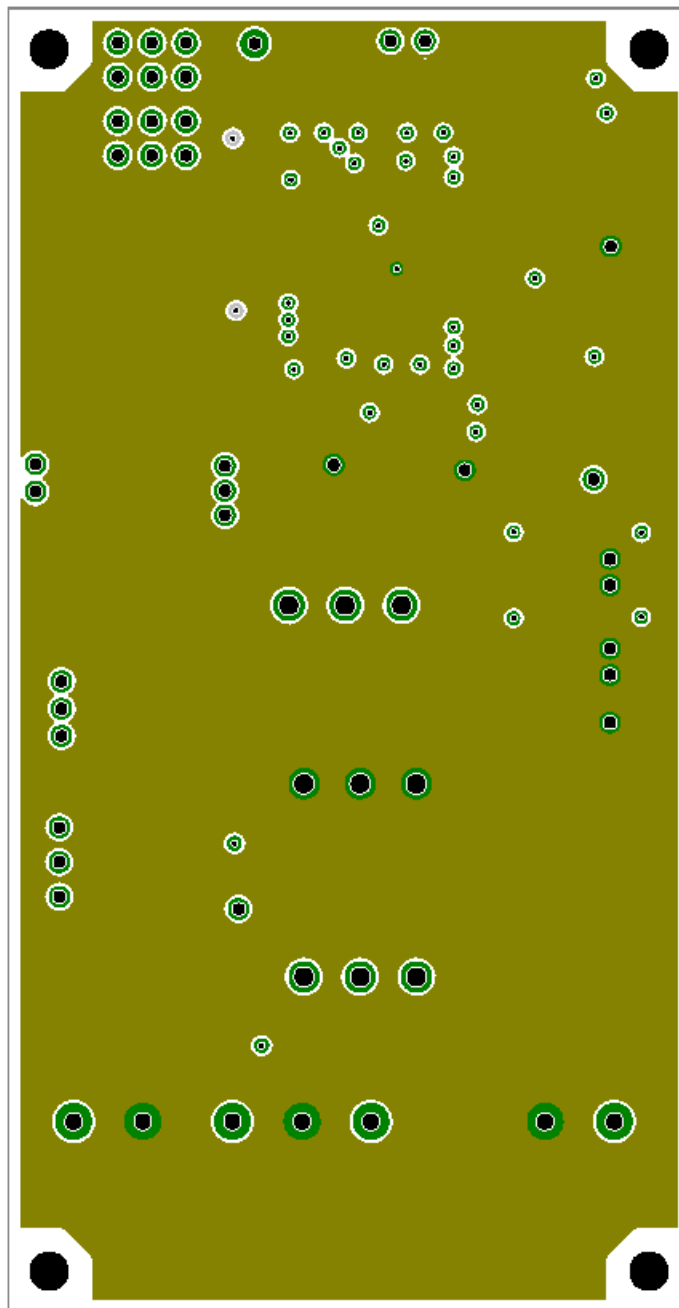


Figure 42. EVM Board Second Layer

APPLICATION INFORMATION

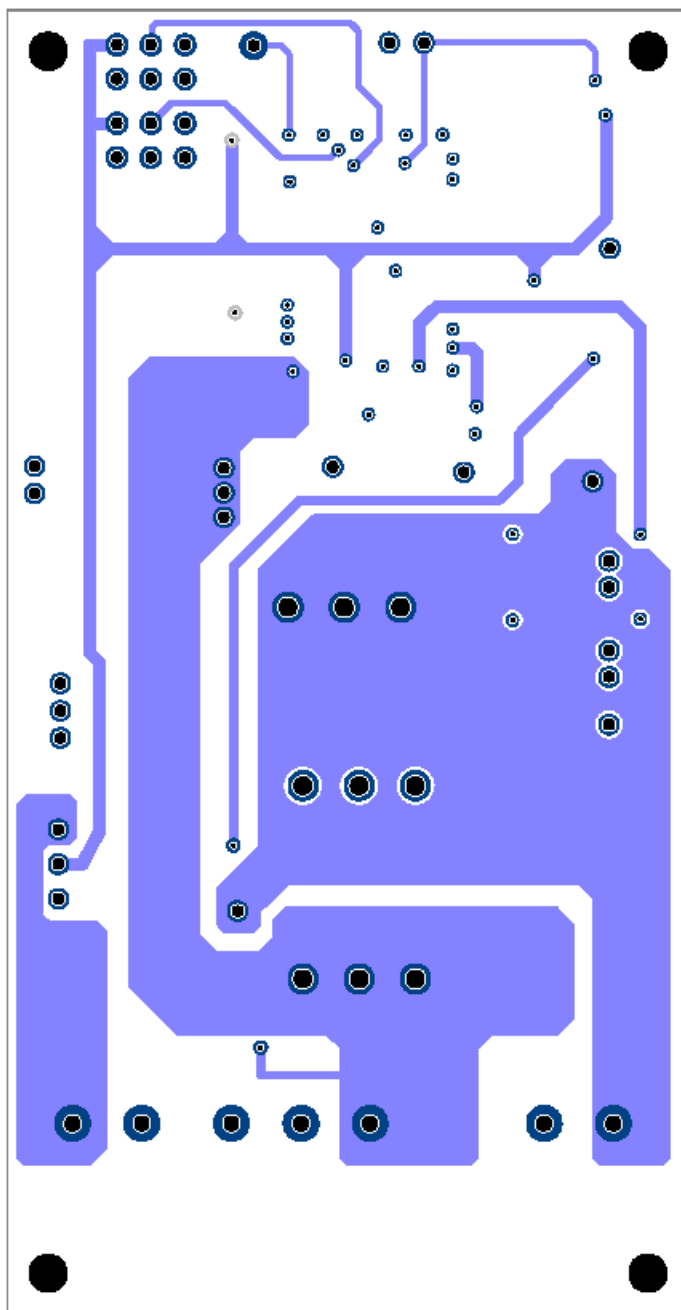


Figure 43. EVM Board Third Layer

APPLICATION INFORMATION

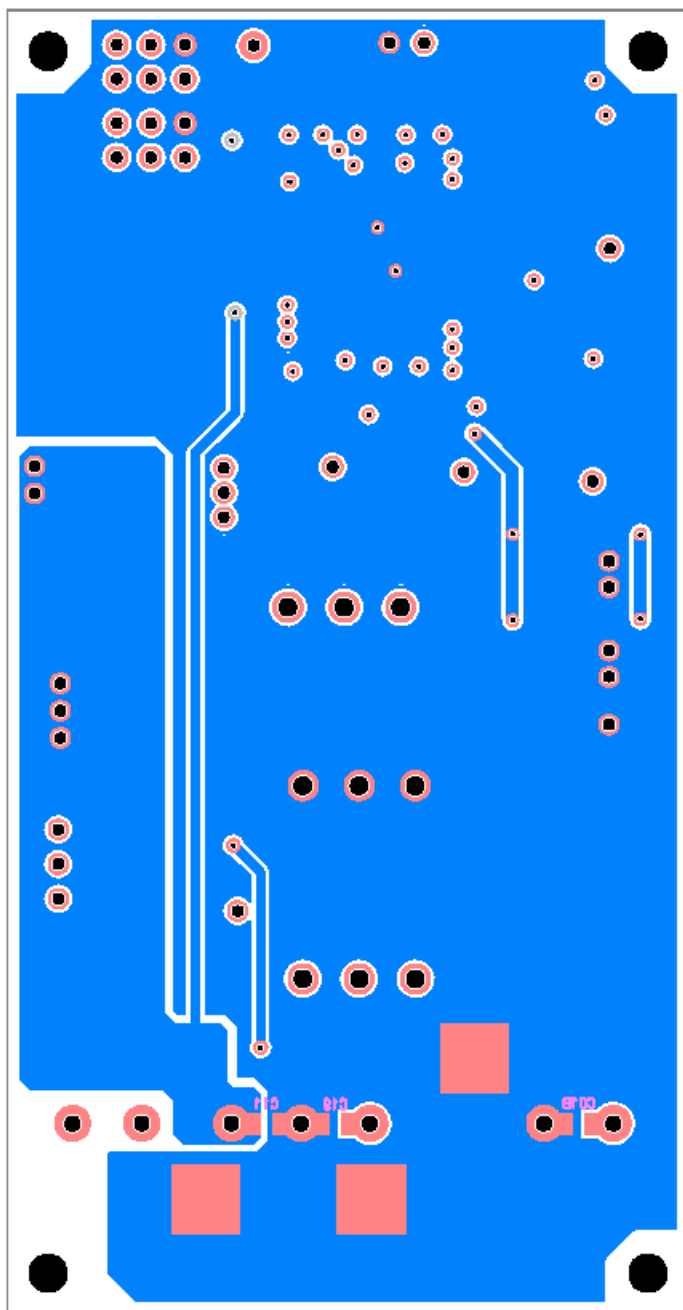


Figure 44. EVM Board Bottom Layer

PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package Pins	Package qty Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
TPS5110PW	Active	Production	TSSOP (PW) 24	60 TUBE	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	PS5110
TPS5110PWR	Active	Production	TSSOP (PW) 24	2000 LARGE T&R	Yes	NIPDAU	Level-1-260C-UNLIM	-40 to 85	PS5110

⁽¹⁾ **Status:** For more details on status, see our [product life cycle](#).

⁽²⁾ **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

⁽³⁾ **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

⁽⁴⁾ **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

⁽⁵⁾ **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

⁽⁶⁾ **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "-" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

Important Information and Disclaimer: The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

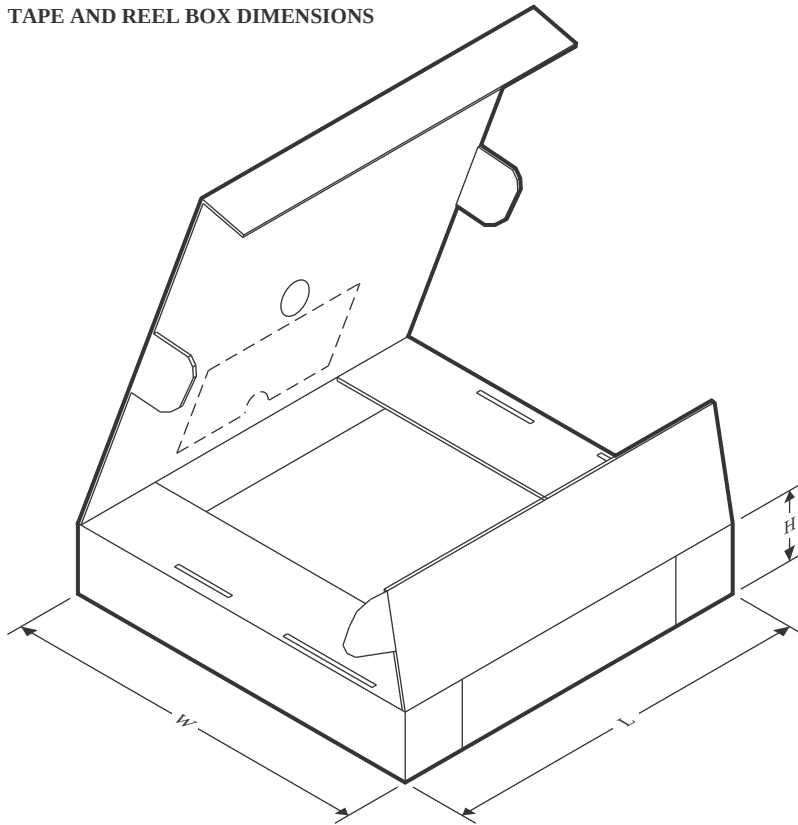
TAPE AND REEL INFORMATION



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TPS5110PWR	TSSOP	PW	24	2000	330.0	16.4	6.95	8.3	1.6	8.0	16.0	Q1

TAPE AND REEL BOX DIMENSIONS



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TPS5110PWR	TSSOP	PW	24	2000	356.0	356.0	35.0

TUBE

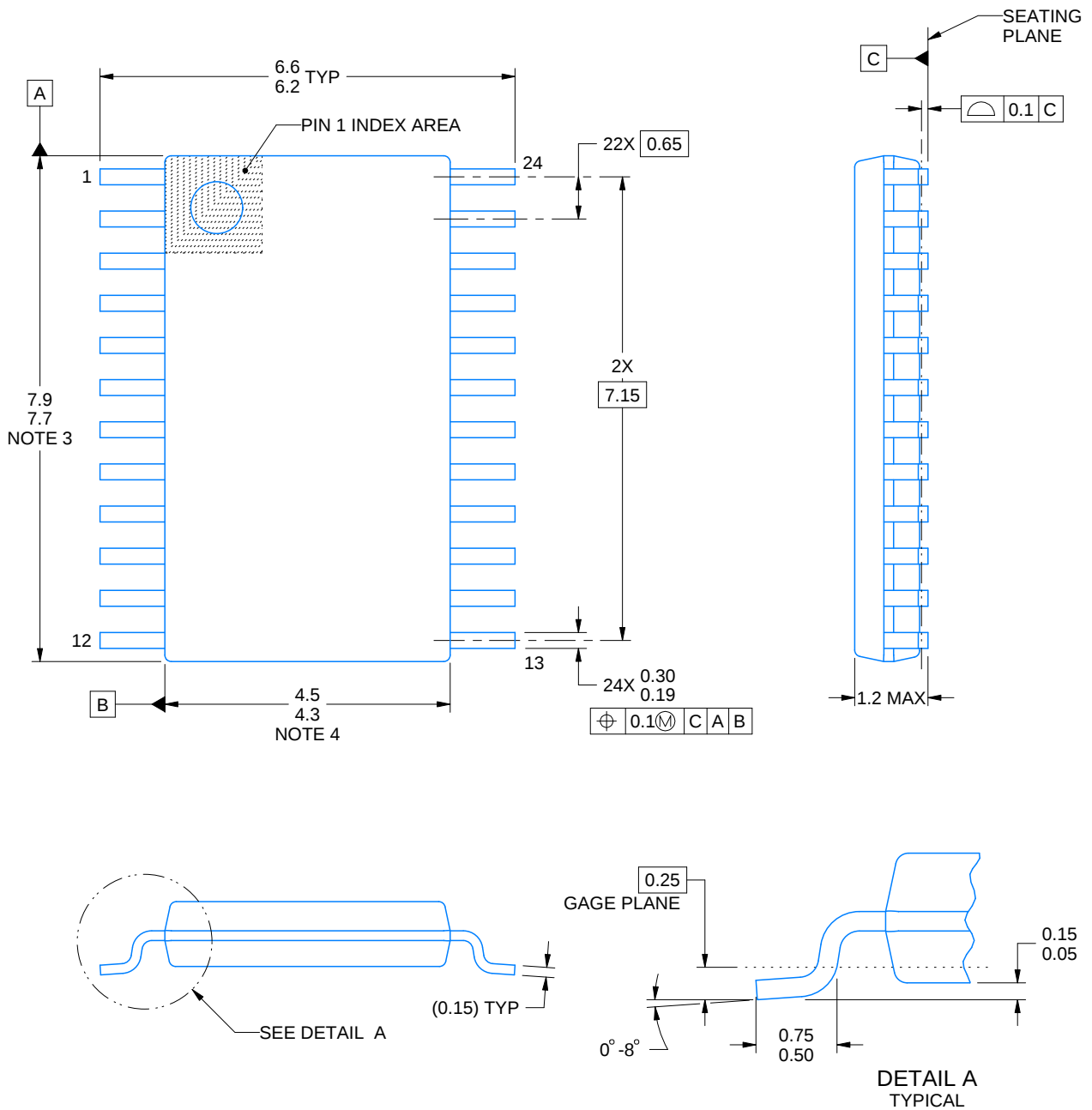


*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	L (mm)	W (mm)	T (μm)	B (mm)
TPS5110PW	PW	TSSOP	24	60	530	10.2	3600	3.5



TSSOP - 1.2 mm max height

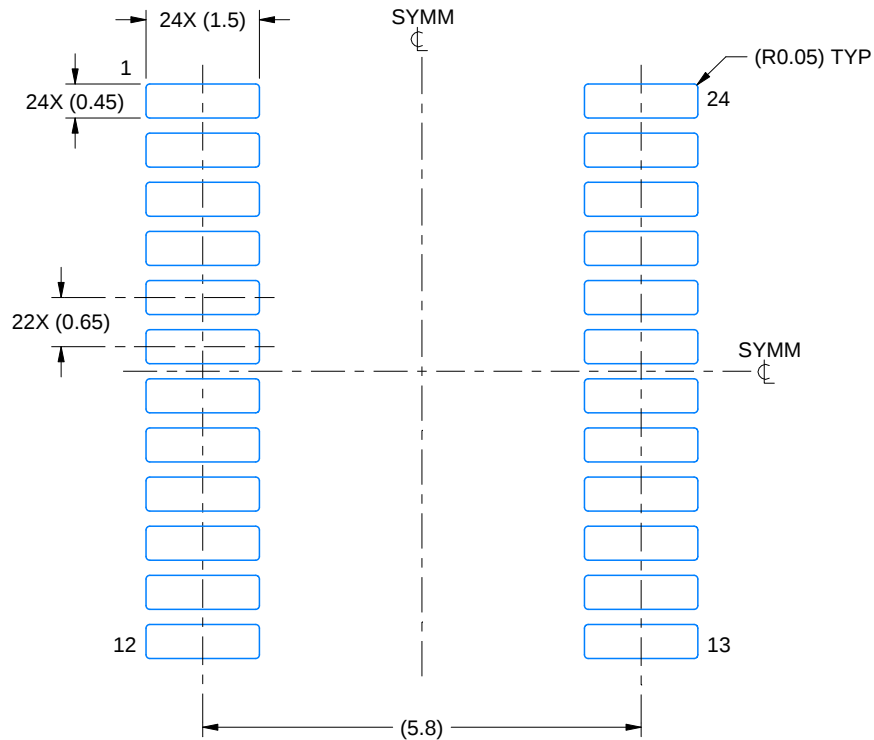


EXAMPLE BOARD LAYOUT

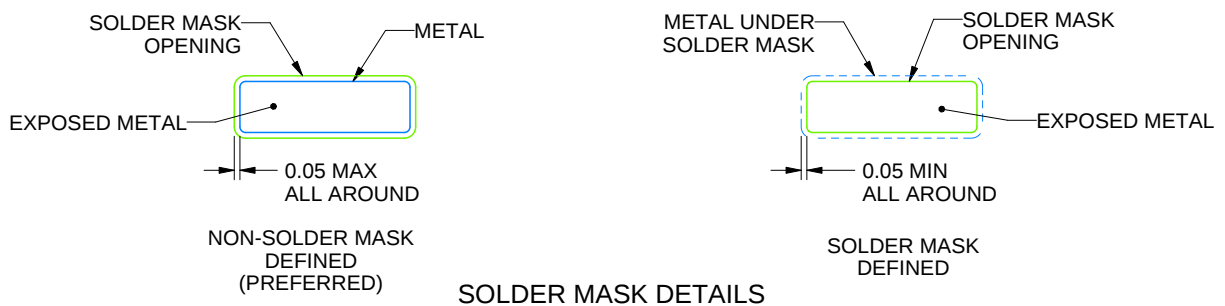
PW0024A

TSSOP - 1.2 mm max height

SMALL OUTLINE PACKAGE



LAND PATTERN EXAMPLE
EXPOSED METAL SHOWN
SCALE: 10X



SOLDER MASK DETAILS

4220208/A 02/2017

NOTES: (continued)

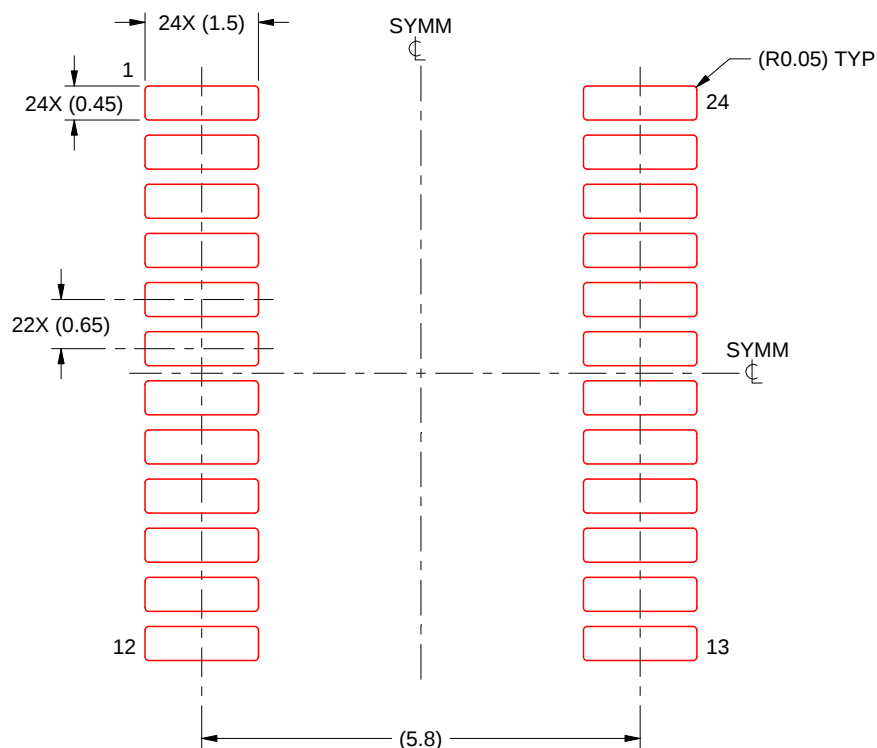
6. Publication IPC-7351 may have alternate designs.
7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

EXAMPLE STENCIL DESIGN

PW0024A

TSSOP - 1.2 mm max height

SMALL OUTLINE PACKAGE



SOLDER PASTE EXAMPLE
BASED ON 0.125 mm THICK STENCIL
SCALE: 10X

4220208/A 02/2017

NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATA SHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES "AS IS" AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, regulatory or other requirements.

These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you will fully indemnify TI and its representatives against, any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI's products are provided subject to [TI's Terms of Sale](#) or other applicable terms available either on [ti.com](https://www.ti.com) or provided in conjunction with such TI products. TI's provision of these resources does not expand or otherwise alter TI's applicable warranties or warranty disclaimers for TI products.

TI objects to and rejects any additional or different terms you may have proposed.

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265
Copyright © 2025, Texas Instruments Incorporated