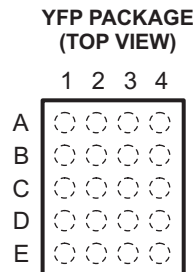


# MMC, SD CARD, Memory Stick™ VOLTAGE-TRANSLATION TRANSCIEVER AND LDO VOLTAGE REGULATOR WITH ESD PROTECTION AND EMI FILTERING

## FEATURES

- **Level Translator**
  - $V_{CCA}$  Range of 1.1 V to 3.6 V
  - Fast Propagation Delay (4 ns Max When Translating Between 1.8 V and 2.9 V)
- **Low-Dropout (LDO) Regulator**
  - 200-mA LDO Regulator With Enable
  - 2.9-V Output Voltage
  - 3.05-V to 5.5-V Input Voltage Range
  - Very Low Dropout: 200 mV at 200 mA
- **ESD Protection Exceeds JESD 22 (A Port)**
  - 2000-V Human-Body Model (A114-B)
  - 1000-V Charged-Device Model (C101)
- **±8-kV Contact Discharge IEC 61000-4-2 ESD (B Port)**



## TERMINAL ASSIGNMENTS

	1	2	3	4
<b>A</b>	DAT2A	$V_{CCA}$	WP/CD	DAT2B
<b>B</b>	DAT3A	$V_{BATT}$	$V_{CCB}$ O/P	DAT3B
<b>C</b>	CMDA	GND	GND	CMDB
<b>D</b>	DAT0A	CLKA	CLKB	DAT0B
<b>E</b>	DAT1A	CLK-f	EN	DAT1B

## DESCRIPTION/ORDERING INFORMATION

The TXS0206-29 is a complete solution for interfacing microprocessors with MultiMediaCards (MMCs), secure digital (SD) cards, and Memory Stick™ cards. It is comprised of a high-speed level translator, a low-dropout (LDO) voltage regulator, IEC level ESD protection, and EMI filtering circuitry.

The voltage-level translator has two supply voltage pins.  $V_{CCA}$  can be operated over the full range of 1.1 V to 3.6 V.  $V_{CCB}$  is set at 2.9 V and is supplied by an internal LDO. The integrated LDO accepts input voltages from 3.05V to as high as 5.5 V and outputs 2.9 V, 200 mA to the B-side circuitry and to the external memory card. The TXS0206-29 enables system designers to easily interface low-voltage microprocessors to memory cards operating at 2.9 V.

Memory card standards recommend high-ESD protection for devices that connect directly to the external memory card. To meet this need, the TXS0206-29 incorporates ±8-kV Contact Discharge protection on the card side.

Since memory cards are widely used in mobile phones, PDAs, digital cameras, personal media players, camcorders, set-top boxes, etc. Low static power consumption and small package size make the TXS0206-29 an ideal choice for these applications. The TXS0206-29 is offered in a 20-bump wafer chip scale package (WCSP). This package has dimensions of 1.96 mm × 1.56 mm, with a 0.4-mm ball pitch for effective board-space savings

## ORDERING INFORMATION<sup>(1)</sup>

$T_A$	PACKAGE <sup>(2)</sup>		ORDERABLE PART NUMBER	TOP-SIDE MARKING <sup>(3)</sup>
–40°C to 85°C	WCSP – YFP (Pb-free)	Tape and reel	TXS0206-29YFPR	__ _ 3 V 2

(1) For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI web site at [www.ti.com](http://www.ti.com).

(2) Package drawings, thermal data, and symbolization are available at [www.ti.com/packaging](http://www.ti.com/packaging).

(3) The actual top-side marking has three preceding characters to denote year, month, and sequence code.



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## REFERENCE DESIGN

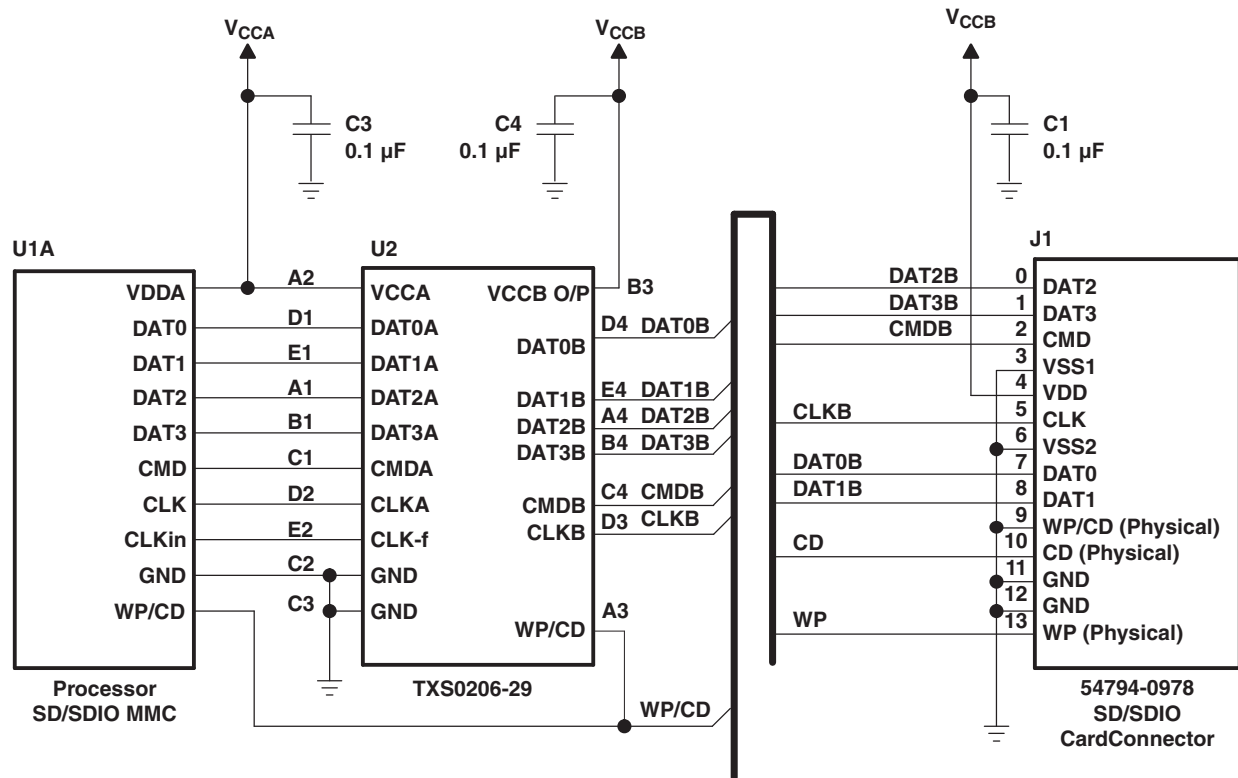


Figure 1. Interfacing With SD/SDIO Card

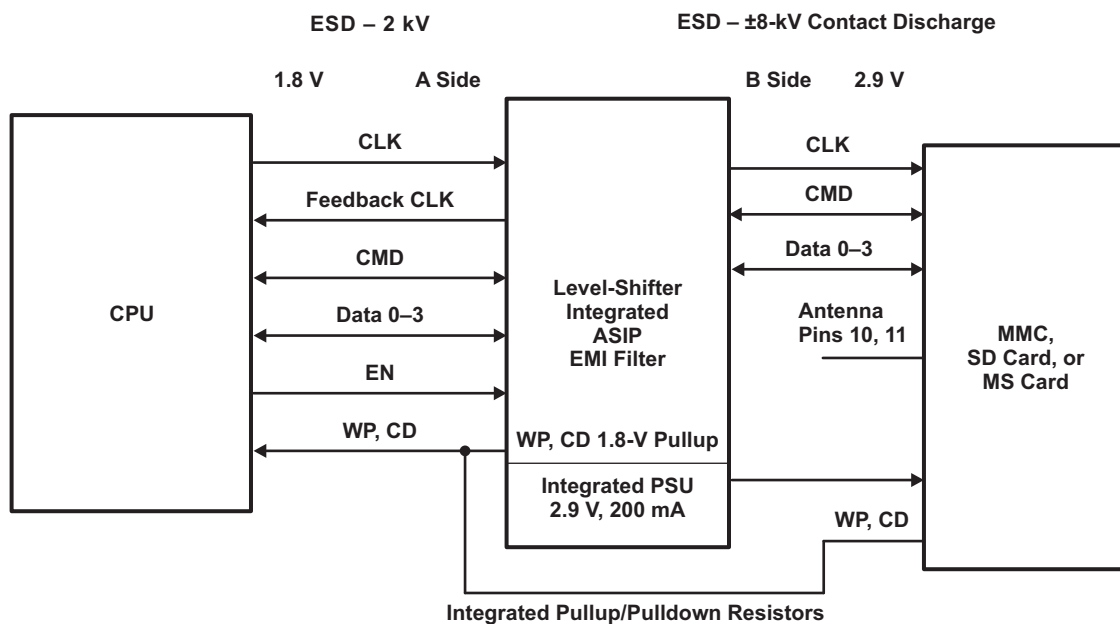


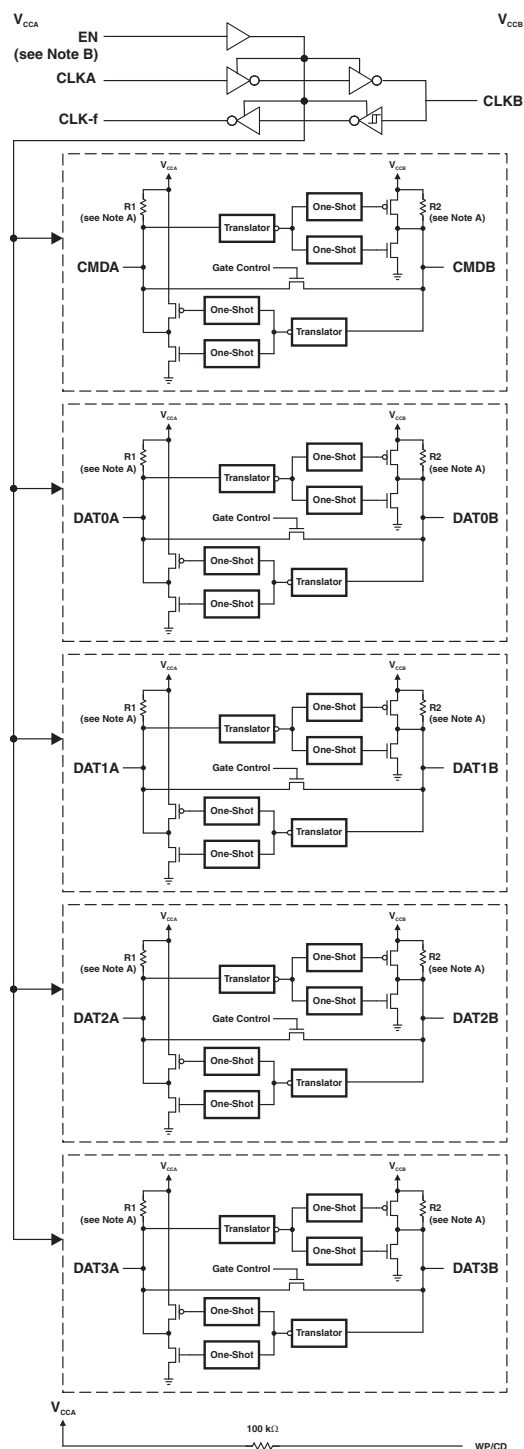
Figure 2. Typical Application Circuit

**Table 1. LOGIC TABLE**

EN	LDO	TRANSLATOR I/Os
L	Disabled	Disabled, pulled to $V_{CCA}$ , $V_{CCB}$ O/P through $R_1$ and $R_2$ at 70k $\Omega$ pullup resistors respectively
H	Active	Active

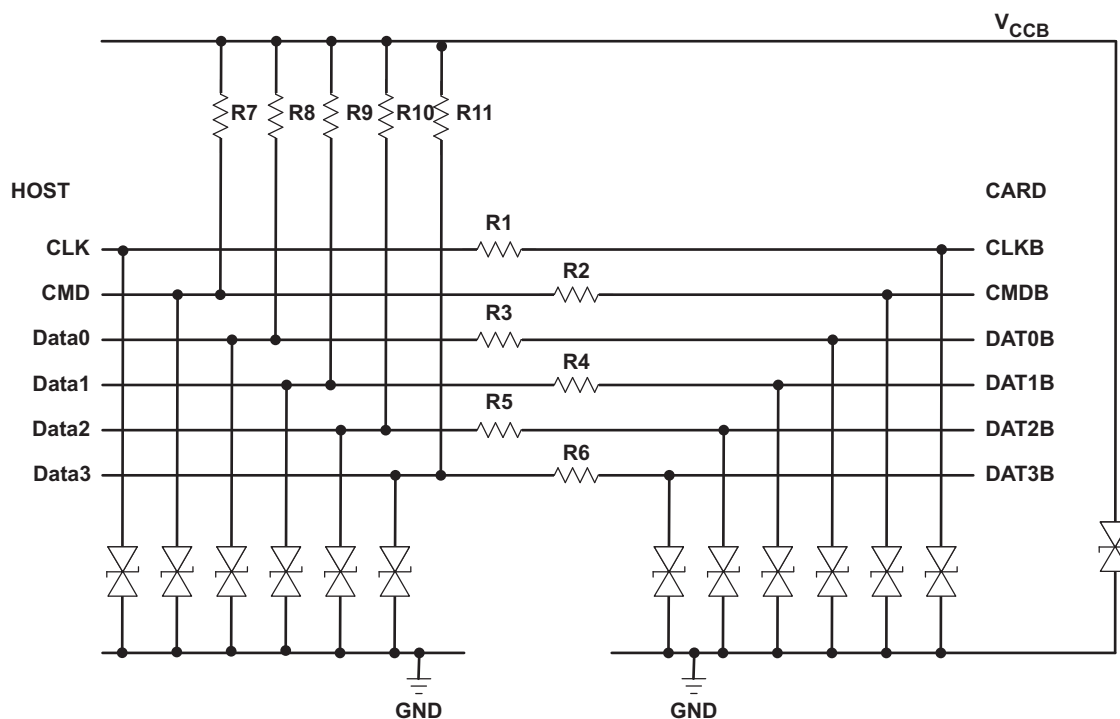
**TERMINAL FUNCTIONS**

TERMINAL		TYPE	DESCRIPTION
NO.	NAME		
A1	DAT2A	I/O	Data bit 2 connected to host. Referenced to $V_{CCA}$ . Includes $R_1$ pullup resistor to $V_{CCA}$ (see Note A).
A2	$V_{CCA}$	Power	A-port supply voltage. $V_{CCA}$ powers all A-port I/Os and control inputs.
A3	WP/CD	Output	Connected to write protect on the mechanical connector. The WP pin has an internal 100-k $\Omega$ pullup resistor to $V_{CCA}$ .
A4	DAT2B	I/O	Data bit 2 connected to memory card. Referenced to $V_{CCB}$ O/P. Includes $R_2$ pullup resistor to $V_{CCB}$ O/P (see Note A).
B1	DAT3A	I/O	Data bit 3 connected to host. Referenced to $V_{CCA}$ . Includes $R_1$ pullup resistor to $V_{CCA}$ (see Note A).
B2	$V_{BATT}$	Input	LDO input voltage from Battery-Supply
B3	$V_{CCB}$ O/P	Output	LDO output voltage and B-port supply voltage. $V_{CCB}$ O/P powers all B-port I/Os.
B4	DAT3B	I/O	Data bit 3 connected to memory card. Referenced to $V_{CCB}$ O/P. Includes $R_2$ pullup resistor to $V_{CCB}$ O/P (see Note A).
C1	CMDA	I/O	Command bit connected to host. Referenced to $V_{CCA}$ . Includes $R_1$ pullup resistor to $V_{CCA}$ (see Note A).
C2, C3	GND		Ground
C4	CMDB	I/O	Command bit connected to memory card. Referenced to $V_{CCB}$ O/P. Includes $R_2$ pullup resistor to $V_{CCB}$ O/P (see Note A).
D1	DAT0A	I/O	Data bit 0 connected to host. Referenced to $V_{CCA}$ . Includes $R_1$ pullup resistor to $V_{CCA}$ (see Note A).
D2	CLKA	Input	Clock signal connected to host. Referenced to $V_{CCA}$ .
D3	CLKB	Output	Clock signal connected to memory card. Referenced to $V_{CCB}$ O/P.
D4	DAT0B	I/O	Data bit 0 connected to memory card. Referenced to $V_{CCB}$ O/P. Includes $R_2$ pullup resistor to $V_{CCB}$ O/P (see Note A).
E1	DAT1A	I/O	Data bit 1 connected to host. Referenced to $V_{CCA}$ . Includes $R_1$ pullup resistor to $V_{CCA}$ (see Note A).
E2	CLK-f	Output	Clock feedback to host for resynchronizing data to a processor. Leave unconnected if not used.
E3	EN	Input	Enable/disable control. Pull EN low to place all outputs in Hi-Z state and to disable the LDO. Referenced to $V_{CCA}$ .
E4	DAT1B	I/O	Data bit 1 connected to memory card. Referenced to $V_{CCB}$ O/P. Includes $R_2$ pullup resistor to $V_{CCB}$ O/P (see Note A).



- A.  $R_1$  and  $R_2$  resistor values are determined based upon the logic level applied to the A port or B port as follows:
- $R_1$  and  $R_2 = 40\text{ k}\Omega$  when a logic level low is applied to the A port or B port.
  - $R_1$  and  $R_2 = 4\text{ k}\Omega$  when a logic level high is applied to the A port or B port.
  - $R_1$  and  $R_2 = 70\text{ k}\Omega$  when the port is deselected (or in High-Z or 3-state).
- B. EN controls all output buffers. When EN = low, all outputs are Hi-Z.

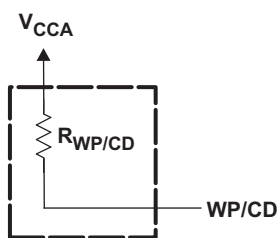
**Figure 3. Logic Diagram**



RESISTORS	
R1, R2, R3, R4, R5, R6	40 Ω
Tolerance	±20%
R7, R8, R9, R10, R11	40 kΩ
Tolerance	±30%

BIDIRECTIONAL ZENER DIODES	
Vbr min	14 V at 1 mA
Line capacitance	<20 pF

Figure 4. ASIP Block Diagram



RESISTORS	
R <sub>WP/CD</sub>	100 kΩ
Tolerance	±30%

Figure 5. WP/CD Pullup Resistor

**ABSOLUTE MAXIMUM RATINGS<sup>(1)</sup>****Level Translator**

over operating free-air temperature range (unless otherwise noted)

		MIN	MAX	UNIT
V <sub>CCA</sub>	Supply voltage range	–0.5	4.6	V
V <sub>I</sub>	Input voltage range	I/O ports (A port)	–0.5	4.6
		I/O ports (B port)	–0.5	4.6
		Control inputs	–0.5	4.6
V <sub>O</sub>	Voltage range applied to any output in the high-impedance or power-off state	A port	–0.5	4.6
		B port	–0.5	4.6
V <sub>O</sub>	Voltage range applied to any output in the high or low state	A port	–0.5	4.6
		B port	–0.5	4.6
I <sub>IK</sub>	Input clamp current	V <sub>I</sub> < 0	–50	mA
I <sub>OK</sub>	Output clamp current	V <sub>O</sub> < 0	–50	mA
I <sub>O</sub>	Continuous output current		±50	mA
	Continuous current through V <sub>CCA</sub> or GND		±100	mA
T <sub>stg</sub>	Storage temperature range	–65	150	°C

- (1) Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

**THERMAL IMPEDANCE RATINGS**

	TYP	UNIT
θ <sub>JA</sub> Package thermal impedance <sup>(1)</sup>	117	°C/W

- (1) The package thermal impedance is calculated in accordance with JESD 51-7.

**ABSOLUTE MAXIMUM RATINGS<sup>(1)</sup>****LDO**

over operating free-air temperature range (unless otherwise noted)

	MIN	MAX	UNIT
V <sub>IN</sub> Input voltage range	2.3	6.5	V
V <sub>OUT</sub> Output voltage range	–0.3	4.6	V
Peak output current		220	mA
Continuous total power dissipation		TBD	mW
T <sub>J</sub> Junction temperature range	–55	150	°C
T <sub>stg</sub> Storage temperature range	–55	150	°C

- (1) Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

## RECOMMENDED OPERATING CONDITIONS<sup>(1)</sup>

### Level Translator

			V <sub>CCA</sub>	V <sub>CCB</sub>	MIN	MAX	UNIT
V <sub>CCA</sub>	Supply voltage				1.1	3.6	V
V <sub>IH</sub>	High-level input voltage	A-Port CMD and DATA I/Os	1.1 V to 1.95 V	2.9 V	V <sub>CCI</sub> – 0.2	V <sub>CCI</sub>	V
			1.95 V to 3.6 V		V <sub>CCI</sub> – 0.4	V <sub>CCI</sub>	
		B-Port and DATA I/Os	1.1 V to 1.95 V	2.9 V	V <sub>CCI</sub> – 0.2	V <sub>CCI</sub>	
			1.95 V to 3.6 V		V <sub>CCI</sub> – 0.4	V <sub>CCI</sub>	
		OE and CLKA	1.1 V to 3.6 V		V <sub>CCI</sub> × 0.65	V <sub>CCI</sub>	
V <sub>IL</sub>	Low-level input voltage	A-Port CMD and DATA I/Os	1.1 V to 1.95 V	2.9 V	0	0.15	V
			1.95 V to 3.6 V		0	0.15	
		B-Port CMD and DATA I/Os	1.1 V to 1.95 V	2.9 V	0	0.15	
			1.95 V to 3.6 V		0	0.15	
		OE and CLKA	1.1 V to 3.6 V		0	V <sub>CCI</sub> × 0.35	
V <sub>O</sub>	Output voltage	Active state			0	V <sub>CCO</sub>	V
		3-state					
I <sub>OH</sub>	High-level output current (CLK-f output)		1.1 V to 1.3 V	2.9 V		–0.5	mA
			1.4 V to 1.6 V			–1	
			1.65 V to 1.95 V			–2	
			2.3 V to 2.7 V			–4	
			3 V to 3.6 V			–8	
I <sub>OL</sub>	Low-level output current (CLK-f output)		1.1 V to 1.3 V	2.9 V		0.5	mA
			1.4 V to 1.6 V			1	
			1.65 V to 1.95 V			2	
			2.3 V to 2.7 V			4	
			3 V to 3.6 V			8	
I <sub>OH</sub>	High-level output current (CLK output)			2.9 V		–8	mA
I <sub>OL</sub>	Low-level output current (CLK output)			2.9 V		8	mA
Δt/Δv	Input transition rise or fall rate					5	ns/V
T <sub>A</sub>	Operating free-air temperature				–40	85	°C

(1) All unused data inputs of the device must be held at V<sub>CCI</sub> or GND to ensure proper device operation. See the TI application report, *Implications of Slow or Floating CMOS Inputs*, literature number [SCBA004](#).

## RECOMMENDED OPERATING CONDITIONS

### LDO

		MIN	MAX	UNIT
I <sub>OUT(PK)</sub>	Peak output current	200		mA
C <sub>OUT</sub>	Output capacitance	1	100	μF
T <sub>J</sub>	Operating junction temperature	–40	125	°C

## ELECTRICAL CHARACTERISTICS

### Level Translator

over recommended operating free-air temperature range (unless otherwise noted)

PARAMETER		TEST CONDITIONS	$V_{CCA}$	$V_{CCB}/P$	MIN	TYP <sup>(1)</sup>	MAX	UNIT
$V_{OH}$	A port (CLK-f output)	$I_{OH} = -100 \mu A$	1.1 V to 3.6 V	2.9 V	$V_{CCA} \times 0.8$			V
		$I_{OH} = -0.5 \text{ mA}$	1.1 V		0.8			
		$I_{OH} = -1 \text{ mA}$	1.4 V		1.05			
		$I_{OH} = -2 \text{ mA}$	1.65 V		1.2			
		$I_{OH} = -4 \text{ mA}$	2.3 V		1.75			
		$I_{OH} = -8 \text{ mA}$	3 V		2.3			
	A port (DAT and CMD outputs)	$I_{OH} = -20 \mu A$	1.1 V to 3.6 V		$V_{CCA} \times 0.8$			
$V_{OL}$	A port (CLK-f output)	$I_{OL} = 100 \mu A$	1.1 V to 3.6 V	2.9 V			$V_{CCA} \times 0.8$	V
		$I_{OL} = 0.5 \text{ mA}$	1.1 V				0.35	
		$I_{OL} = 1 \text{ mA}$	1.4 V				0.35	
		$I_{OL} = 2 \text{ mA}$	1.65 V				0.45	
		$I_{OL} = 4 \text{ mA}$	2.3 V				0.55	
		$I_{OL} = 8 \text{ mA}$	3 V				0.7	
	A port (DAT and CMD outputs)	$I_{OL} = 135 \mu A$	1.1 V to 3.6 V	2.9 V			0.4	V
		$I_{OL} = 180 \mu A$					0.4	
		$I_{OL} = 220 \mu A$					0.4	
		$I_{OL} = 300 \mu A$					0.4	
		$I_{OL} = 400 \mu A$					0.55	
$V_{OH}$	B port (CLK output)	$I_{OH} = -100 \mu A$	1.1 V to 3.6 V	2.9 V	$V_{CCB}/P \times 0.8$			V
		$I_{OH} = -8 \text{ mA}$			2.3			
	B port (DAT output)	$I_{OH} = -20 \mu A$		2.9 V	$V_{CCB}/P \times 0.8$			
$V_{OL}$	CLKB output port	$I_{OL} = 100 \mu A$	1.1 V to 3.6 V	2.9 V			$V_{CCB}/P \times 0.8$	V
		$I_{OL} = 8 \text{ mA}$					0.7	
	B port (DAT and CMD outputs)	$I_{OL} = 135 \mu A$	1.1 V to 3.6 V	2.9 V			0.4	V
		$I_{OL} = 180 \mu A$					0.4	
		$I_{OL} = 220 \mu A$					0.4	
		$I_{OL} = 300 \mu A$					0.4	
		$I_{OL} = 400 \mu A$					0.55	
$I_I$	Control inputs	$V_I = V_{CCA}$ or GND	1.1 V to 3.6 V	2.9 V			$\pm 1$	$\mu A$
$I_{CCA}$		$V_I = V_{CC1}$ or GND, $I_O = 0$	1.1 V to 3.6 V	2.9 V			6	$\mu A$
$I_{CCB}$		$V_I = V_{CC1}$ or GND, $I_O = 0$	1.1 V to 3.6 V	2.9 V			5	$\mu A$
$C_{io}$	A port					5.5	6.5	pF
	B port					15	17.5	
$C_i$	Control inputs	$V_I = V_{CCA}$ or GND				3.5	4.5	pF
	Clock input					3	4	

(1) All typical values are at  $T_A = 25^\circ\text{C}$ .



## ELECTRICAL CHARACTERISTICS

### LDO

over operating free-air temperature range (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP <sup>(1)</sup>	MAX	UNIT
V <sub>BATT</sub>	Input voltage		V <sub>OUT</sub> + V <sub>DO</sub>		5.5	V
V <sub>OUT</sub>	Output voltage	Nominal T <sub>A</sub> = 25°C	2.9			V
		All conditions	2.75		3.05	
ΔV <sub>OUT</sub>	Output voltage tolerance	Nominal T <sub>A</sub> = 25°C	±3			%
V <sub>DO</sub>	Dropout voltage	I <sub>OUT</sub> = 200 mA		200	250	mV
I <sub>GND</sub>	Ground-pin current	I <sub>OUT</sub> = 0	40			μA
		I <sub>OUT</sub> < 100 mA	200			
		100 mA ≤ I <sub>OUT</sub> ≤ 200 mA	400			
I <sub>OUT(SC)</sub>	Short-circuit current	R <sub>L</sub> = 0 Ω	300			mA
PSRR	Power-supply rejection ratio	V <sub>IN</sub> = 3.05 V, V <sub>OUT</sub> = 2.9 V, C <sub>NR</sub> = 0.01 μF, I <sub>OUT</sub> = 200 mA	f = 1 kHz		50	dB
			f = 10 kHz		40	
t <sub>STR</sub>	Start-up time	V <sub>OUT</sub> = 2.9 V, I <sub>OUT</sub> = 200 mA, C <sub>OUT</sub> = 2.2 μF	200			μs

(1) All typical values are at T<sub>A</sub> = 25°C.

## TIMING REQUIREMENTS

over recommended operating free-air temperature range, V<sub>CCB</sub> = 2.9 V ± 5% (unless otherwise noted)

			V <sub>CCA</sub> = 1.2 V ± 0.1 V		V <sub>CCA</sub> = 1.5 V ± 0.1 V		V <sub>CCA</sub> = 1.8 V ± 0.15 V		V <sub>CCA</sub> = 2.5 V ± 0.2 V		V <sub>CCA</sub> = 3.3 V ± 0.3 V		UNIT
			MIN	MAX	MIN	MAX	MIN	MAX	MIN	MAX	MIN	MAX	
Data rate	Command	Push-pull driving	40		60		60		60		60		Mbps
		Open-drain driving	1		1		1		1		1		
	Clock	Push-pull driving	60		60		60		60		60		MHz
	Data		40		60		60		60		60		Mbps
t <sub>w</sub> Pulse duration	Command	Push-pull driving	25		17		17		17		17		ns
		Open-drain driving	1		1		1		1		1		μs
	Clock	Push-pull driving	8.3		8.3		8.3		8.3		8.3		ns
	Data		25		17		17		17		17		ns

## SWITCHING CHARACTERISTICS

over recommended operating free-air temperature range,  $V_{CCB} = 2.9 \text{ V} \pm 5\%$  (unless otherwise noted)

PARAMETER	FROM (INPUT)	TO (OUTPUT)	TEST CONDITIONS	$V_{CCA} = 1.2 \text{ V} \pm 0.1 \text{ V}$		$V_{CCA} = 1.5 \text{ V} \pm 0.1 \text{ V}$		$V_{CCA} = 1.8 \text{ V} \pm 0.15 \text{ V}$		$V_{CCA} = 2.5 \text{ V} \pm 0.2 \text{ V}$		$V_{CCA} = 3.3 \text{ V} \pm 0.3 \text{ V}$		UNIT
				MIN	MAX	MIN	MAX	MIN	MAX	MIN	MAX	MIN	MAX	
$t_{pd}$	CMDA	CMDB	Push-pull driving		10.8		6.1		4.6		3.7		3.8	ns
			Open-drain driving (H-to-L)	3.2	10.6	2.7	6.6	2.4	5.5	2.1	4.4	2	4.1	
			Open-drain driving (L-to-H)	71	175	83	180	89	201	98	249	101	233	
	CMDB	CMDA	Push-pull driving		12		6.8		5.2		4.1		3.4	
			Open-drain driving (H-to-L)	2.9	9.4	2.1	7.3	2	6.4	2	5.7	2.2	4.6	
			Open-drain driving (L-to-H)	77	243	87	214	93	215	99	261	105	248	
	CLKA	CLKB	Push-pull driving		11.7		6.2		4.7		3.7		3.5	
	DATxA	DATxB	Push-pull driving		11.1		6.2		4.7		3.7		3.7	
	DATxB	DATxA			11.5		6.2		5		3.9		6.2	
	CLKA	CLK-f	Push-pull driving		24.7		13		8.9		6.8		4.8	
$t_{en}$	EN	B-port	Push-pull driving		1		1		1		1		1	$\mu\text{s}$
	EN	A-port	Push-pull driving		1		1		1		1		1	
$t_{dis}$	EN	B-port	Push-pull driving		40		39		35		38		34	ns
	EN	A-port	Push-pull driving		40		38		38		38		36	
$t_{rA}$	CMDA rise time		Push-pull driving	1.6	12.2	0.4	8.3	1.1	5.9	1.9	3.3	0.8	4.2	ns
			Open-drain driving	32	120	44	127	52	150	62	201	74	194	
	CLK-f rise time		Push-pull driving	0.6	12.7	0.5	7.2	0.4	4.5	0.7	1.5	0.7	1.4	
	DATxA rise time			1.6	11.6	0.6	8.4	1	6.3	1.8	4.2	1.1	3.3	
$t_{rB}$	CMDB rise time		Push-pull driving	1.7	6.7	0.5	5.6	1	5.2	1.5	5.2	1.9	5	ns
			Open-drain driving	66	214	71	196	73	184	76	214	79	185	
	CLKB rise time		Push-pull driving	1.7	4.8	1.5	4.9	1.5	4.9	1.6	5	1.6	5.1	
	DATxB rise time			0.4	6.8	0.6	5	0.2	5.2	0.9	5.3	1	14	
$t_{fA}$	CMDA fall time		Push-pull driving	0.8	4	0.8	2.3	0.2	3.1	0.3	1.5	1	2.3	ns
			Open-drain driving	1.6	3.9	1.6	3.7	1.6	3.7	1.6	3.7	1.6	3.9	
	CLK-f fall time		Push-pull driving	1	4	0.4	6.8	0.1	1.5	0.3	2.8	0.6	1.3	
	DATxA fall time			1	3.9	0.1	3.8	0.2	2.7	0.3	2.9	0.4	1.8	
$t_{fB}$	CMDB fall time		Push-pull driving	1.5	4.5	1.4	5.4	1.6	5	1.6	5.6	0.8	6.3	ns
			Open-drain driving	1	4.3	1	2.3	0.8	1.9	0.8	1.6	0.9	1.3	
	CLKB fall time		Push-pull driving	1.6	4	1.6	4.1	1.7	4.2	1.7	4.5	0.9	5.1	
	DATxB fall time			1	4.8	2.3	4.3	0.8	4.9	0.2	4.9	0.8	6.9	
$t_{SK(O)}$	Channel-to-channel skew		Push-pull driving		1		1		1		1		1	ns
Max data rate	Command		Push-pull driving		40		60		60		60		60	Mbps
			Open-drain driving		1		1		1		1		1	
	Clock		Push-pull driving		60		60		60		60		60	MHz
	Data				40		60		60		60		60	Mbps

## OPERATING CHARACTERISTICS

 $T_A = 25^{\circ}\text{C}$ ,  $V_{CCB} = 2.9\text{ V}$ 

PARAMETER			TEST CONDITIONS	$V_{CCA}$ TYP						UNIT
				1.2 V	1.5 V	1.8 V	2.5 V	3 V	3.3 V	
$C_{pdA}$ <sup>(1)</sup>	A-port input, B-port output	CLK Enabled	$C_L = 0$ , $f = 10\text{ MHz}$ , $t_r = t_f = 1\text{ ns}$	15	15	15	15.7	17.1	17.1	pF
		DATA Enabled		6.3	6.4	6.5	6.5	6.5	6.5	
	B-port input, A-port output	DATA Enabled		12.5	12.3	12.3	12.5	14	14	
		CLK Disabled		0.2	0.2	0.2	0.3	0.3	0.3	
	A-port input, B-port output	DATA Disabled		1.2	1.2	1.2	1.2	1.2	1.2	
		B-port input, A-port output		0.2	0.2	0.2	0.3	0.3	0.3	
$C_{pdB}$ <sup>(1)</sup>	A-port input, B-port output	DATA Enabled	$C_L = 0$ , $f = 10\text{ MHz}$ , $t_r = t_f = 1\text{ ns}$	31.2	30.6	30.3	29.5	28.5	28.5	pF
		CLK Enabled		28.1	27.2	27	26.9	27	27	
	B-port input, A-port output	DATA Enabled		12.9	12.8	12.9	13.2	13.2	13.2	
		DATA Disabled		0.6	0.5	0.5	0.5	0.5	0.6	
	A-port input, B-port output	CLK Disabled		0.6	0.5	0.5	0.5	0.5	0.6	
		DATA Disabled		1.2	1.2	1.2	1	1	1	

(1) Power dissipation capacitance per transceiver

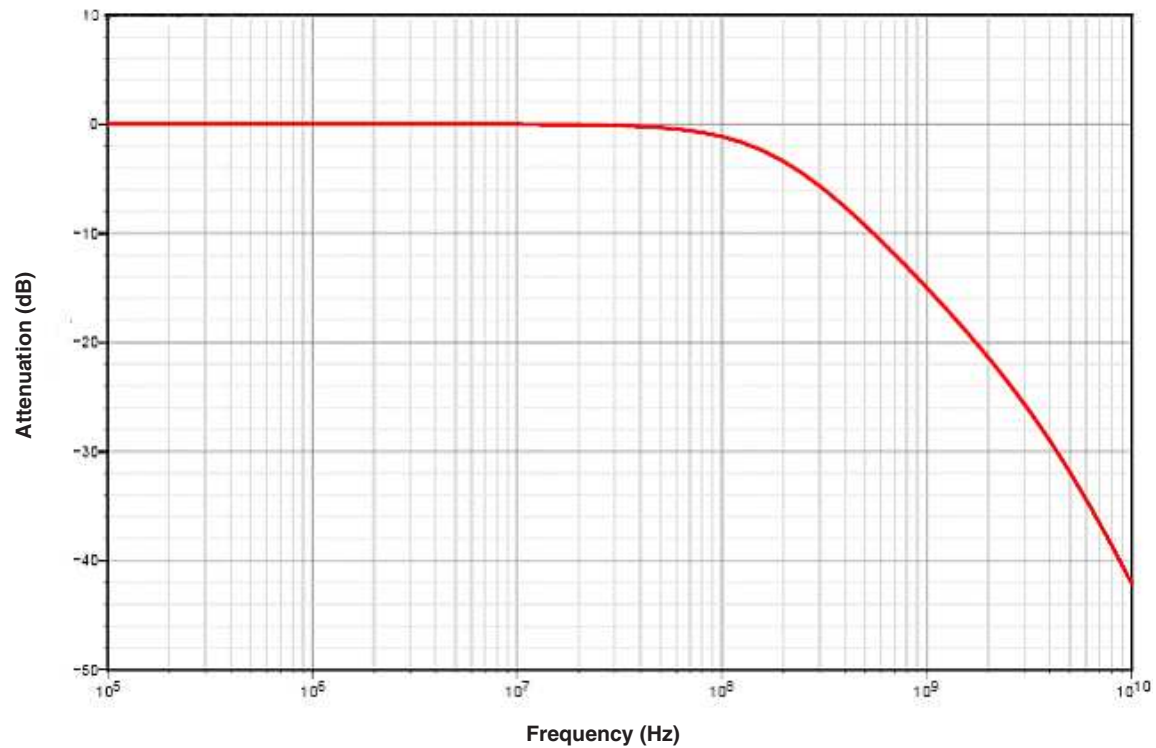


Figure 6. Typical ASIP EMI Filter Frequency Response

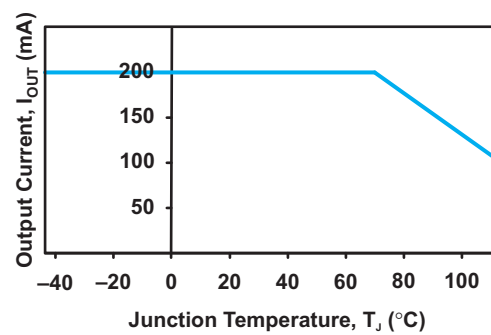
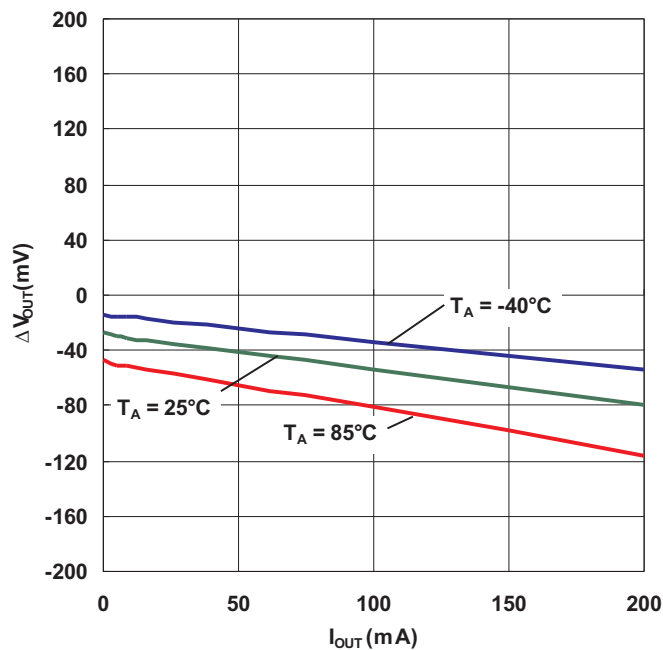


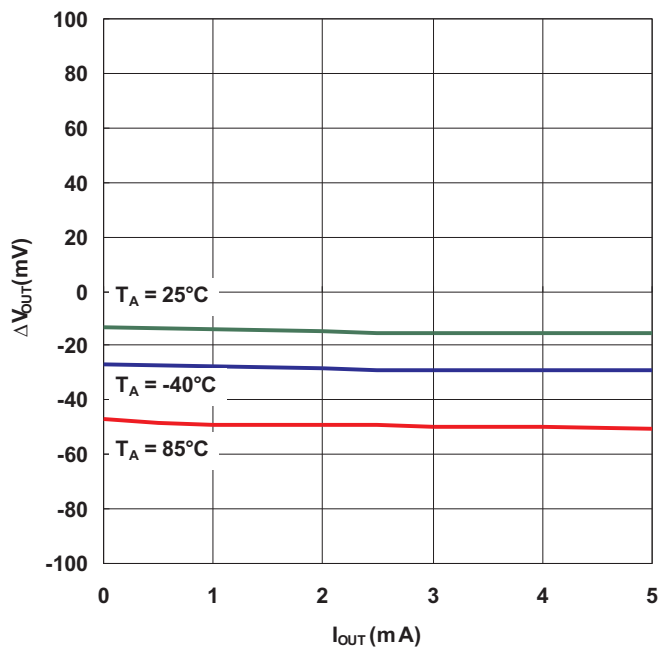
Figure 7. LDO Output Current Derating

## TYPICAL CHARACTERISTICS

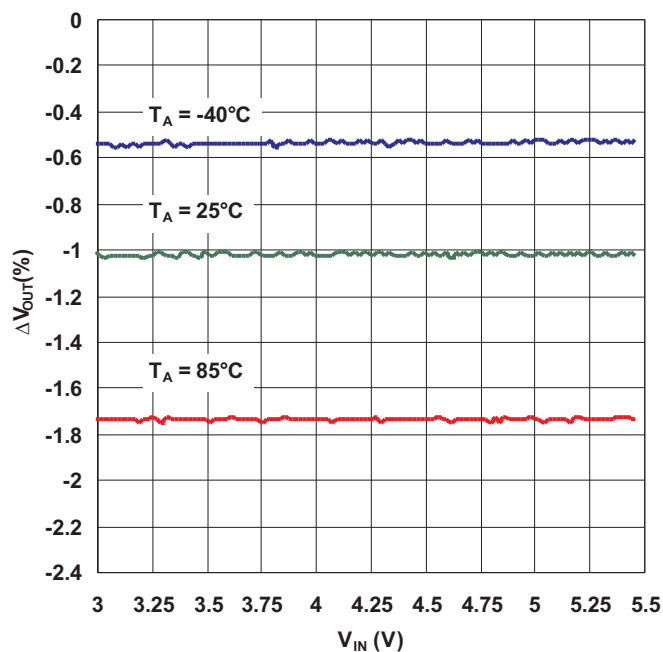
**LOAD REGULATION**



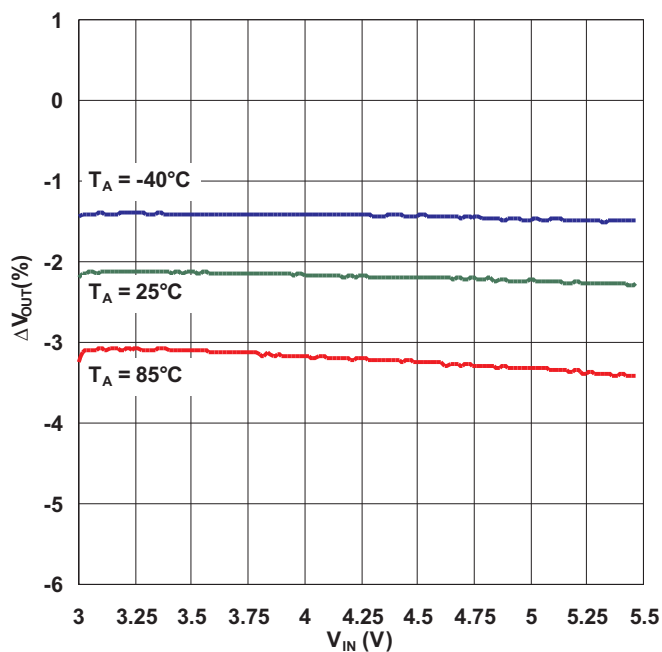
**LOAD REGULATION, LIGHT LOADS**



**LINE REGULATION  
( $I_{OUT} = 5\text{ mA}$ )**

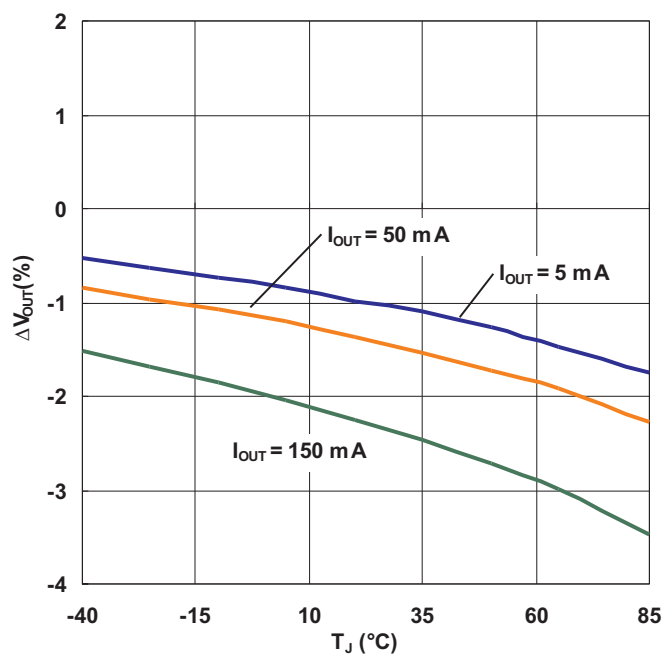


**LINE REGULATION  
( $I_{OUT} = 150\text{ mA}$ )**

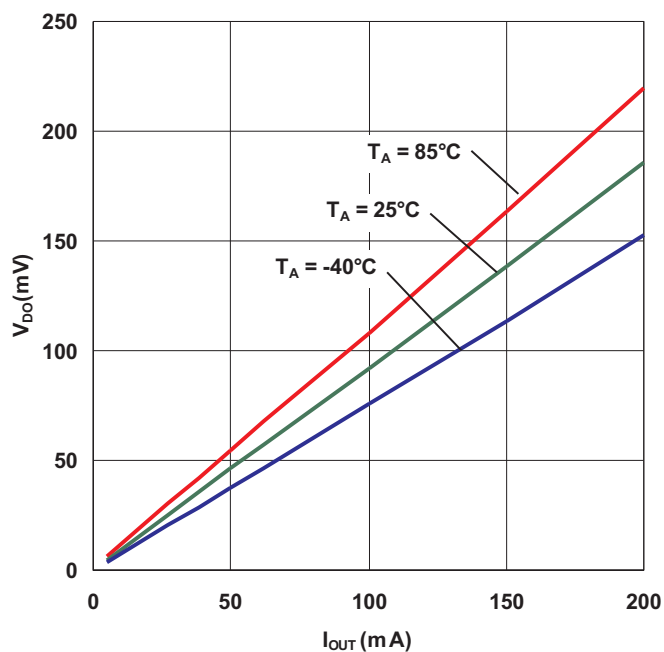


## TYPICAL CHARACTERISTICS (continued)

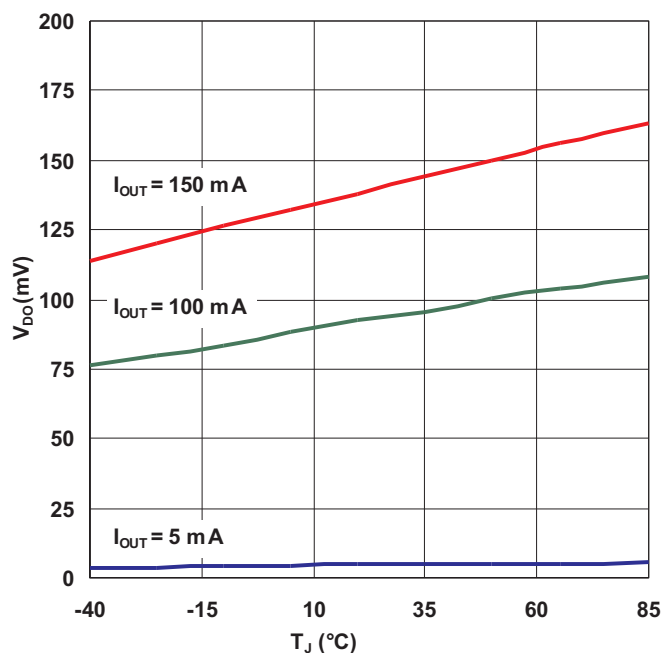
**OUTPUT VOLTAGE  
vs  
TEMPERATURE**



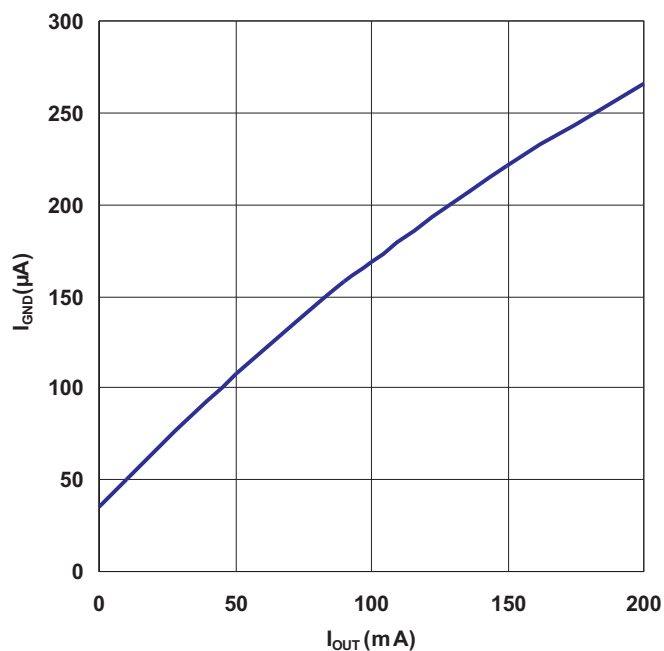
**DROPOUT VOLTAGE  
vs  
OUTPUT CURRENT**



**DROPOUT VOLTAGE  
vs  
TEMPERATURE**

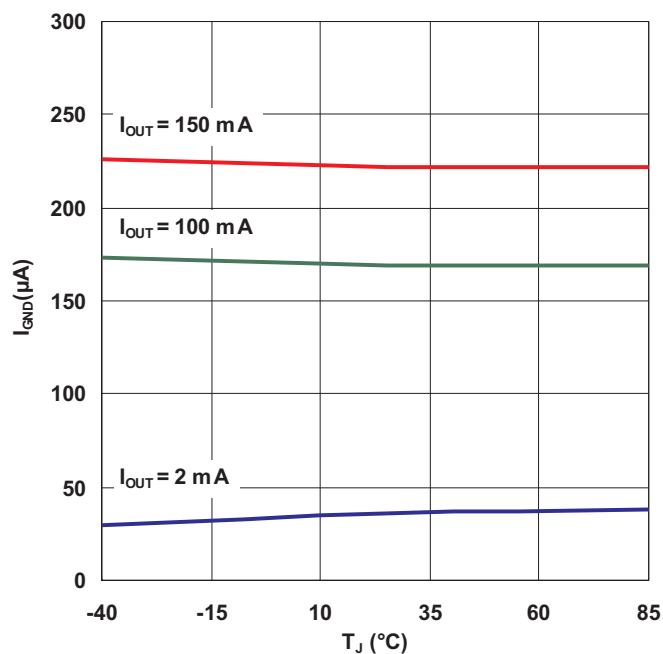


**GROUND PIN CURRENT  
vs  
OUTPUT CURRENT**

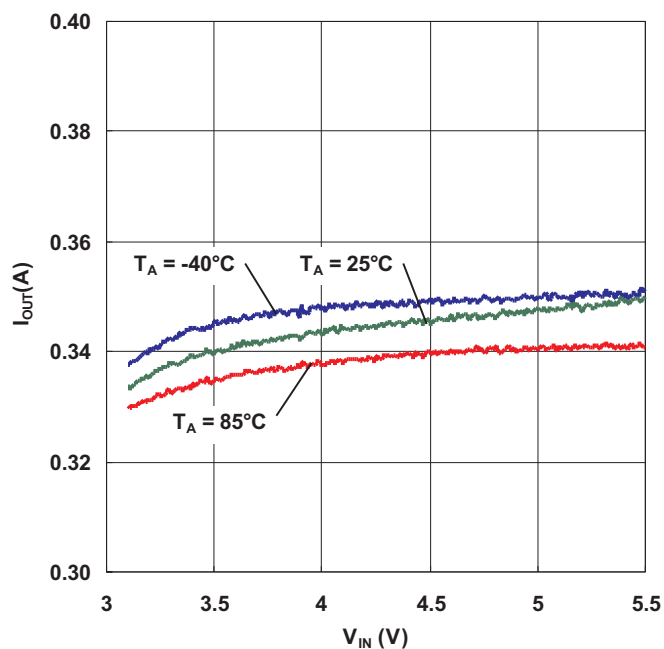


## TYPICAL CHARACTERISTICS (continued)

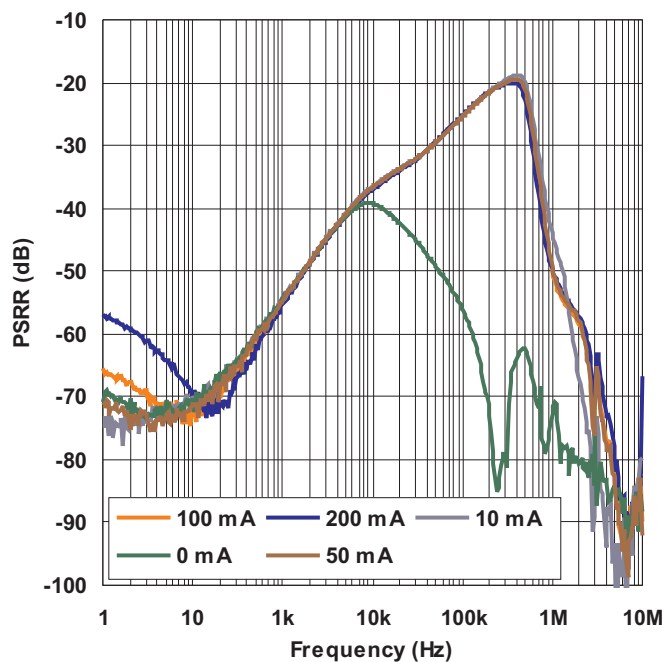
**GROUND PIN CURRENT  
vs  
TEMPERATURE (ENABLE)**



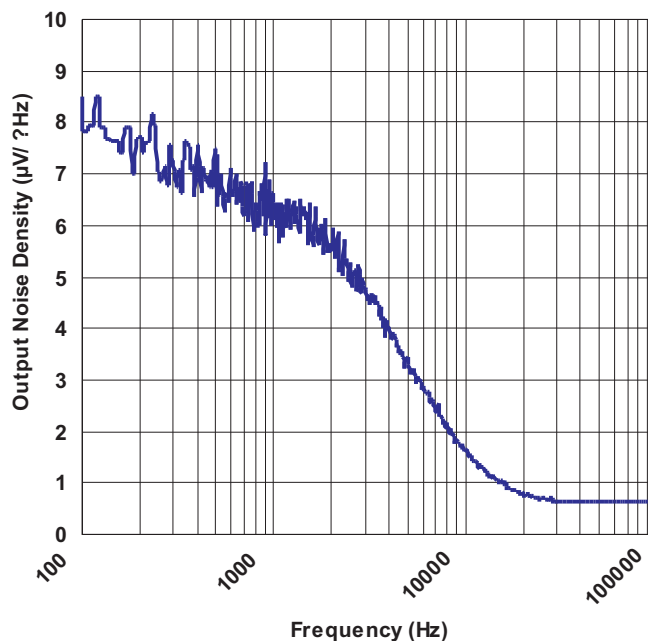
**CURRENT LIMIT  
vs  
INPUT VOLTAGE**



**POWER SUPPLY RIPPLE REJECTION  
vs  
FREQUENCY ( $V_{IN} - V_{OUT} = 1\text{ V}$ )**

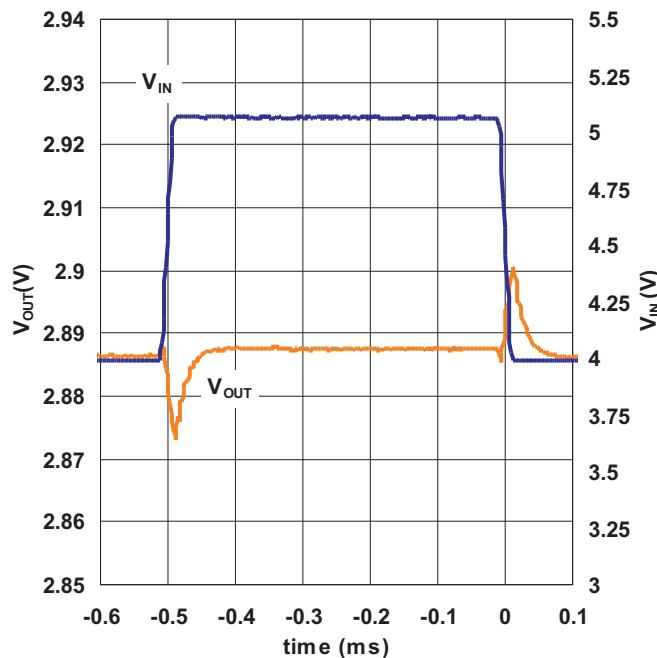


**OUTPUT SPECTRAL NOISE DENSITY  
( $C_{OUT} = 1\text{ }\mu F$ )**

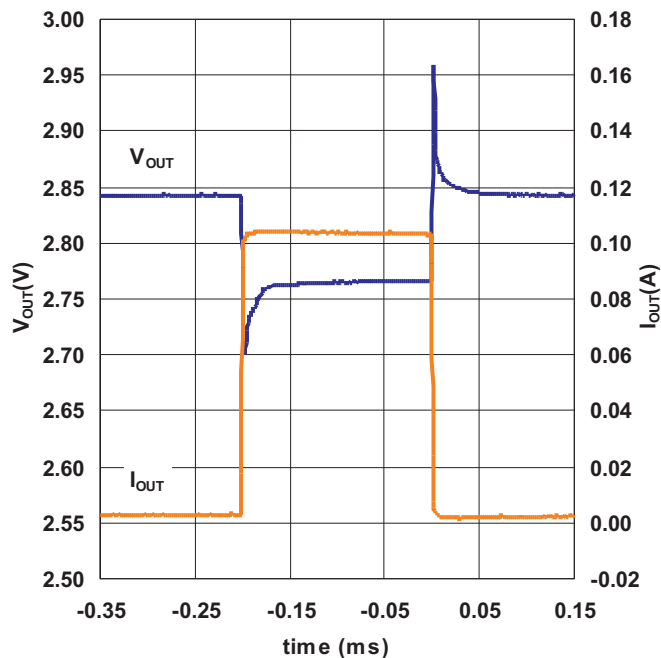


## TYPICAL CHARACTERISTICS (continued)

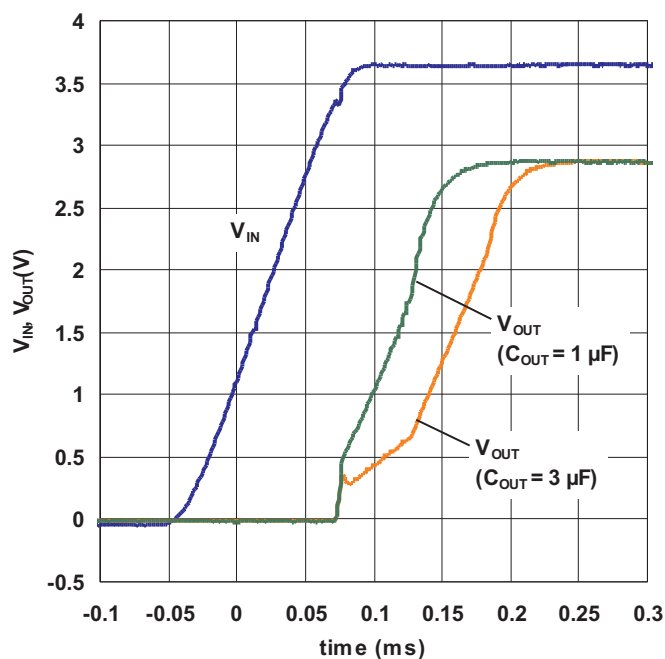
**LINE TRANSIENT RESPONSE**  
( $C_{OUT} = 1\ \mu\text{F}$ )



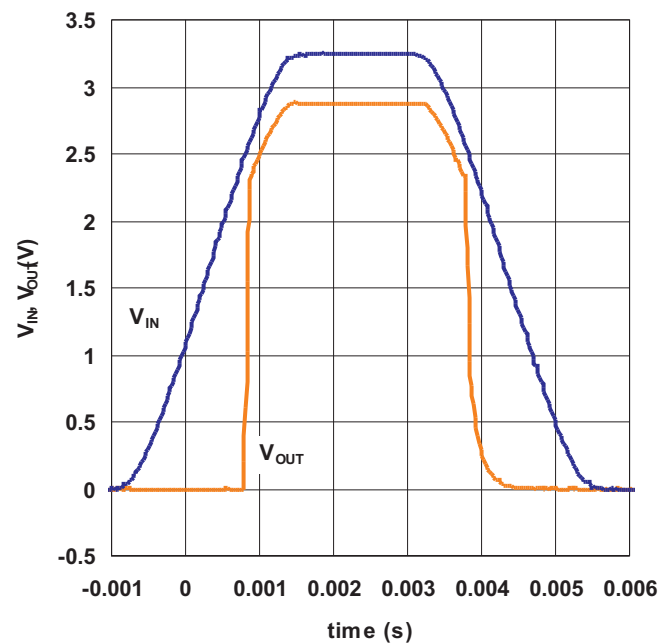
**LOAD TRANSIENT RESPONSE**  
( $C_{OUT} = 1\ \mu\text{F}$ ,  $V_{IN} = 3.3\ \text{V}$ ,  $I_{OUT} = 0$  to  $100\ \text{mA}$ )



**TURN-ON RESPONSE**

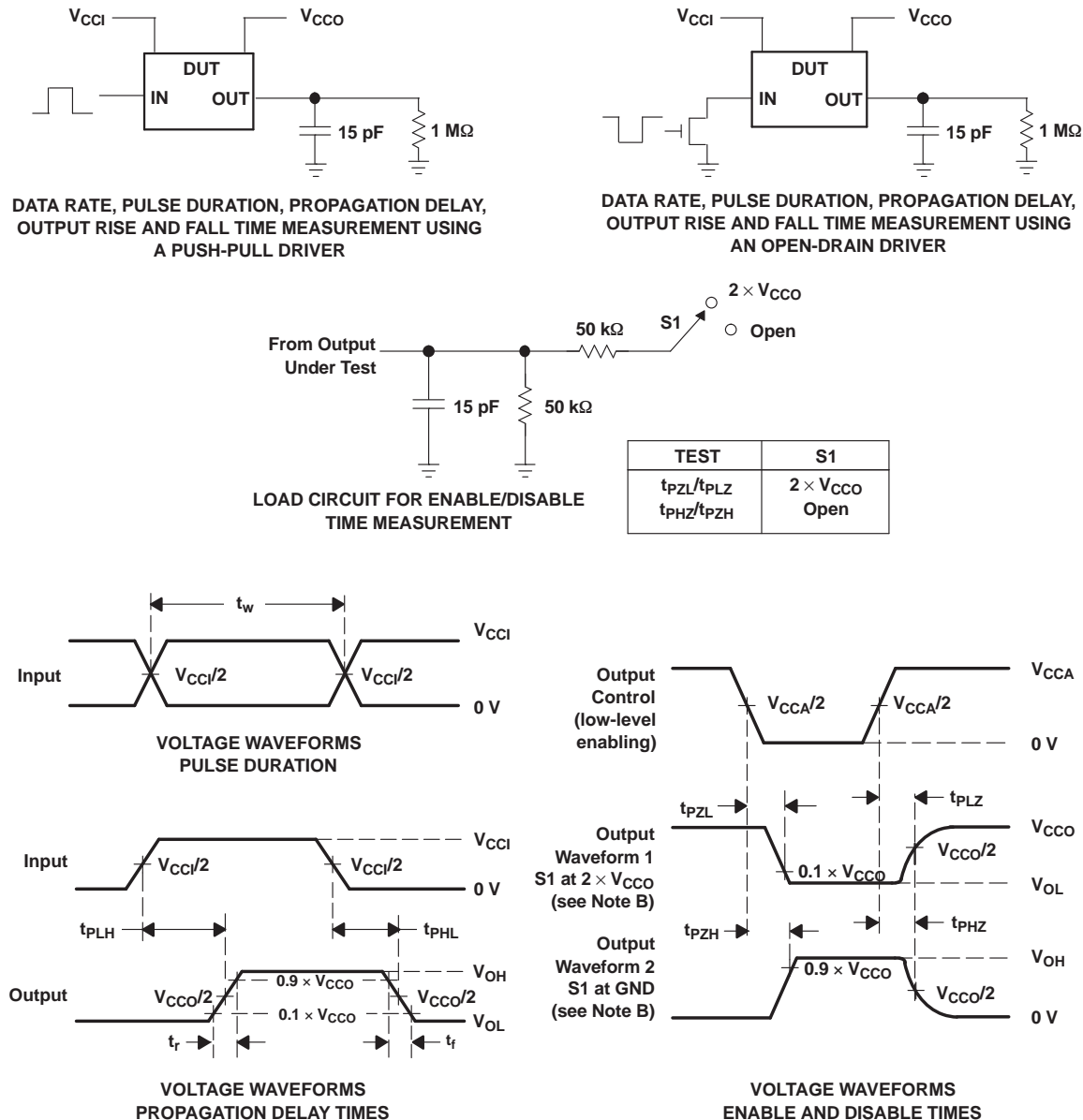


**POWER-UP/POWER-DOWN**  
( $C_{OUT} = 1\ \mu\text{F}$ ,  $I_{OUT} = 150\ \text{mA}$ )





## PARAMETER MEASUREMENT INFORMATION



- $C_L$  includes probe and jig capacitance.
- Waveform 1 is for an output with internal conditions such that the output is low, except when disabled by the output control. Waveform 2 is for an output with internal conditions such that the output is high, except when disabled by the output control.
- All input pulses are supplied by generators having the following characteristics:  $PRR \leq 10$  MHz,  $Z_O = 50 \Omega$ ,  $dv/dt \geq 1$  V/ns.
- The outputs are measured one at a time, with one transition per measurement.
- $t_{PLZ}$  and  $t_{PHZ}$  are the same as  $t_{dis}$ .
- $t_{PZL}$  and  $t_{PZH}$  are the same as  $t_{en}$ .
- $t_{PLH}$  and  $t_{PHL}$  are the same as  $t_{pd}$ .
- $V_{CCI}$  is the  $V_{CC}$  associated with the input port.
- $V_{CCO}$  is the  $V_{CC}$  associated with the output port.
- All parameters and waveforms are not applicable to all devices.

Figure 8. Load Circuit and Voltage WaveformsN

## PRINCIPLES OF OPERATION

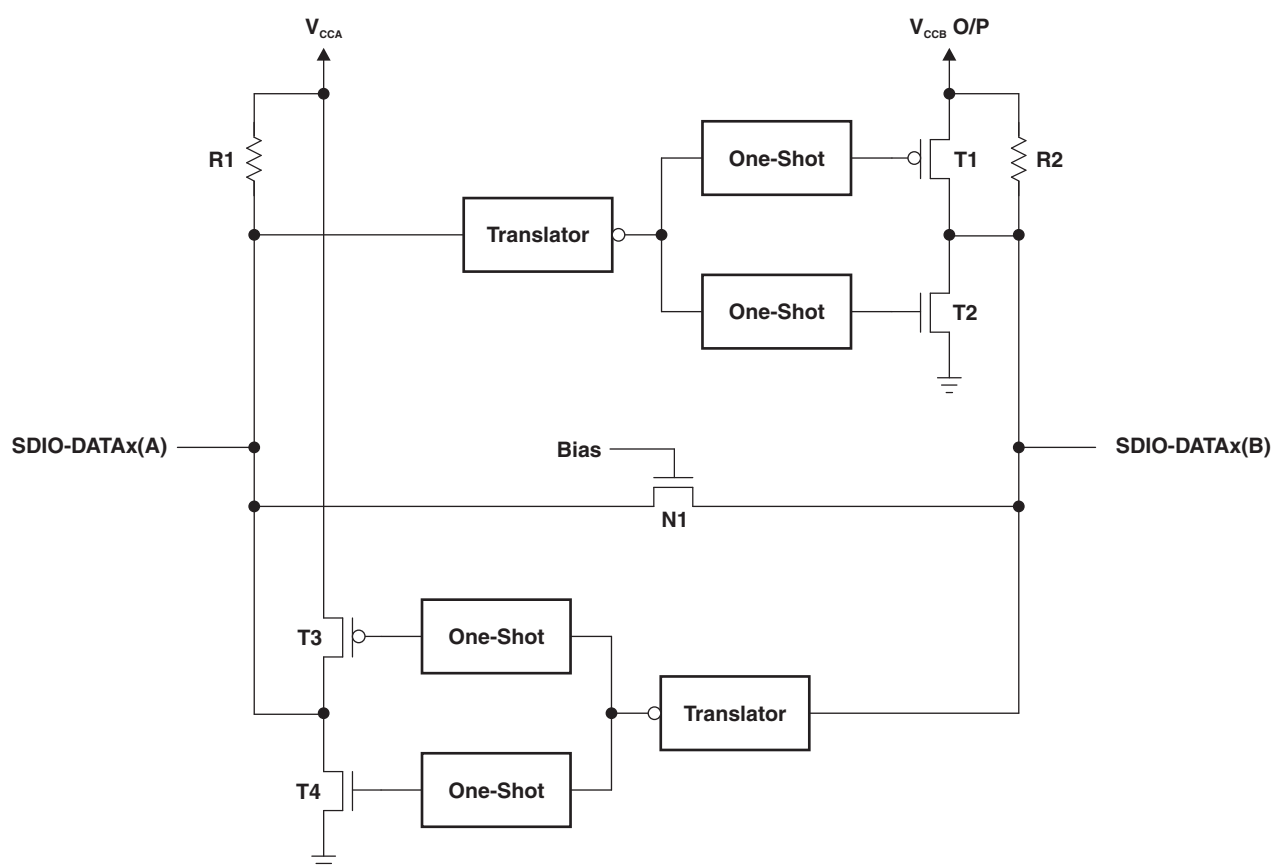
### Applications

The TXS0206-29 device is a complete application-specific voltage-translator designed to bridge the digital-switching compatibility gap and interface logic threshold levels between a microprocessor with MMC, SD, and Memory Stick™ cards. It is intended to be used in a point-to-point topology when interfacing these devices that may or may not be operating at different interface voltages.

### Architecture

The CLKA, CLKB, and CLK-f subsystem interfaces consist of a fully-buffered voltage translator design that has its output transistors to source and sink current optimized for drive strength.

The SDIO lines comprise a semi-buffered auto-direction-sensing based translator architecture (see Figure 9) that does not require a direction-control signal to control the direction of data flow of the A to B ports (or from B to A ports).



**Figure 9. Architecture of an SDIO Switch-Type Cell**

Each of these bidirectional SDIO channels independently determines the direction of data flow without a direction-control signal. Each I/O pin can be automatically reconfigured as either an input or an output, which is how this auto-direction feature is realized.

The following two key circuits are employed to facilitate the "switch-type" voltage translation function:

1. Integrated pullup resistors to provide dc-bias and drive capabilities
2. An N-channel pass-gate transistor topology (with a high  $R_{ON}$  of  $\sim 300\ \Omega$ ) that ties the A-port to the B-port
3. Output one-shot (O.S.) edge-rate accelerator circuitry to detect and accelerate rising edges on the A or B ports

For bidirectional voltage translation, pullup resistors are included on the device for dc current sourcing capability. The  $V_{GATE}$  gate bias of the N-channel pass transistor is set at a level that optimizes the switch characteristics for maximum data rate as well as minimal static supply leakage. Data can flow in either direction without guidance from a control signal.

The edge-rate acceleration circuitry speeds up the output slew rate by monitoring the input edge for transitions, helping maintain the data rate through the device.

During a low-to-high signal rising-edge, the O.S. circuits turn on the PMOS transistors ( $T_1$ ,  $T_3$ ) and its associated driver output resistance of the driver is decreased to approximately 50  $\Omega$  to 70  $\Omega$  during this acceleration phase to increase the current drive capability of the driver for approximately 30 ns or 95% of the input edge, whichever occurs first. This edge-rate acceleration provides high ac drive by bypassing the internal pullup resistors during the low-to-high transition to speed up the rising-edge signal.

During a high-to-low signal falling-edge, the O.S. circuits turn on the NMOS transistors ( $T_2$ ,  $T_4$ ) and its associated driver output resistance of the driver is decreased to approximately 50  $\Omega$  to 70  $\Omega$  during this acceleration phase to increase the current drive capability of the driver for approximately 30 ns or 95% of the input edge, whichever occurs first.

To minimize dynamic  $I_{CC}$  and the possibility of signal contention, the user should wait for the O.S. circuit to turn-off before applying a signal in the opposite direction. The worst-case duration is equal to the minimum pulse-width number provided in the *Timing Requirements* section of this data sheet.

Once the O.S. is triggered and switched off, both the A and B ports must go to the same state (i.e. both High or both Low) for the one-shot to trigger again. In a DC state, the output drivers maintain a Low state through the pass transistor. The output drivers maintain a High through the "smart pullup resistors" that dynamically change value based on whether a Low or a High is being passed through the SDIO lines, as follows:

- $R_{PU1}$  and  $R_{PU2}$  values are a nominal 40 k $\Omega$  when the output is driving a low
- $R_{PU1}$  and  $R_{PU2}$  values are a nominal 4 k $\Omega$  when the output is driving a high
- $R_{PU1}$  and  $R_{PU2}$  values are a nominal 70 k $\Omega$  when the device is disabled via the EN pin or by pulling the either  $V_{CCA}$  or  $V_{CCB}/O/P$  to 0 V.

The reason for using these "smart" pullup resistors is to allow the TXS0206-29 to realize a lower static power consumption (when the I/Os are low), support lower  $V_{OL}$  values for the same size pass-gate transistor, and improved simultaneous switching performance.

## Input Driver Requirements

The continuous dc-current "sinking" capability is determined by the external system-level driver interfaced to the SDIO pins. Since the high bandwidth of these bidirectional SDIO circuits necessitates the need for a port to quickly change from an input to an output (and vice-versa), they have a modest dc-current "sourcing" capability of hundreds of micro-Amps, as determined by the smart pullup resistor values.

The fall time ( $t_{fA}$ ,  $t_{fB}$ ) of a signal depends on the edge rate and output impedance of the external device driving the SDIO I/Os, as well as the capacitive loading on these lines.

Similarly, the  $t_{pd}$  and max data rates also depend on the output impedance of the external driver. The values for  $t_{fA}$ ,  $t_{fB}$ ,  $t_{pd}$ , and maximum data rates in the data sheet assume that the output impedance of the external driver is less than 50  $\Omega$ .

## Output Load Considerations

TI recommends careful PCB layout practices with short PCB trace lengths to avoid excessive capacitive loading and to ensure that proper O.S. triggering takes place. PCB signal trace-lengths should be kept short enough such that the round trip delay of any reflection is less than the one-shot duration. This improves signal integrity by ensuring that any reflection sees a low impedance at the driver. The O.S. circuits have been designed to stay on for approximately 30 ns. The maximum capacitance of the lumped load that can be driven also depends directly on the one-shot duration. With very heavy capacitive loads, the one-shot can time-out before the signal is driven fully to the positive rail. The O.S. duration has been set to best optimize trade-offs between dynamic  $I_{CC}$ , load driving capability, and maximum bit-rate considerations. Both PCB trace length and connectors add to the capacitance that the TXS0206-29 SDIO output sees, so it is recommended that this lumped-load capacitance be considered and kept below 50 pF to avoid O.S. retriggering, bus contention, output signal oscillations, or other adverse system-level affects.

When using the TXS0206-29 device with MMCs, SD, and Memory Stick™ to ensure that a valid receiver input voltage high ( $V_{IH}$ ) is achieved, the value of any pulldown resistors (external or internal to a memory card) must not be  $>10\text{-k}\Omega$  value. The impact of adding too heavy a pulldown resistor (i.e.  $<10\text{-k}\Omega$  value) to the data and command lines of the TXS0206-29 device and the resulting  $4\text{-k}\Omega$  pullup &  $10\text{-k}\Omega$  pulldown voltage divider network has a direct impact on the  $V_{IH}$  of the signal being sent into the memory card and its associated logic.

The resulting  $V_{IH}$  voltage for the  $10\text{-k}\Omega$  pulldown resistor value would be:

$$V_{CC} \times 10\text{ k}\Omega / (10\text{ k}\Omega + 4\text{ k}\Omega) = 0.714 \times V_{CC}$$

This is marginally above a valid input high voltage for a 1.8-V signal (i.e.,  $0.65 \times V_{CC}$ ).

The resulting  $V_{IH}$  voltage for  $20\text{-k}\Omega$  pulldown resistor value would be:

$$V_{CC} \times 20\text{ k}\Omega / (20\text{ k}\Omega + 4\text{ k}\Omega) = 0.833 \times V_{CC}$$

Which is above the valid input high voltage for a 1.8-V signal of  $0.65 \times V_{CC}$ .

.

## PACKAGING INFORMATION

Orderable part number	Status (1)	Material type (2)	Package   Pins	Package qty   Carrier	RoHS (3)	Lead finish/ Ball material (4)	MSL rating/ Peak reflow (5)	Op temp (°C)	Part marking (6)
TXS0206-29YFPRB	Active	Production	DSBGA (YFP)   20	3000   LARGE T&R	Yes	SNAGCU	Level-1-260C-UNLIM	-40 to 85	(3V, 3V2)

<sup>(1)</sup> **Status:** For more details on status, see our [product life cycle](#).

<sup>(2)</sup> **Material type:** When designated, preproduction parts are prototypes/experimental devices, and are not yet approved or released for full production. Testing and final process, including without limitation quality assurance, reliability performance testing, and/or process qualification, may not yet be complete, and this item is subject to further changes or possible discontinuation. If available for ordering, purchases will be subject to an additional waiver at checkout, and are intended for early internal evaluation purposes only. These items are sold without warranties of any kind.

<sup>(3)</sup> **RoHS values:** Yes, No, RoHS Exempt. See the [TI RoHS Statement](#) for additional information and value definition.

<sup>(4)</sup> **Lead finish/Ball material:** Parts may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

<sup>(5)</sup> **MSL rating/Peak reflow:** The moisture sensitivity level ratings and peak solder (reflow) temperatures. In the event that a part has multiple moisture sensitivity ratings, only the lowest level per JEDEC standards is shown. Refer to the shipping label for the actual reflow temperature that will be used to mount the part to the printed circuit board.

<sup>(6)</sup> **Part marking:** There may be an additional marking, which relates to the logo, the lot trace code information, or the environmental category of the part.

Multiple part markings will be inside parentheses. Only one part marking contained in parentheses and separated by a "~" will appear on a part. If a line is indented then it is a continuation of the previous line and the two combined represent the entire part marking for that device.

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In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

**TAPE AND REEL INFORMATION**


\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TXS0206-29YFPRB	DSBGA	YFP	20	3000	180.0	8.4	1.66	2.06	0.56	4.0	8.0	Q1

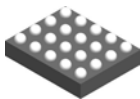
## TAPE AND REEL BOX DIMENSIONS



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TXS0206-29YFPRB	DSBGA	YFP	20	3000	182.0	182.0	20.0

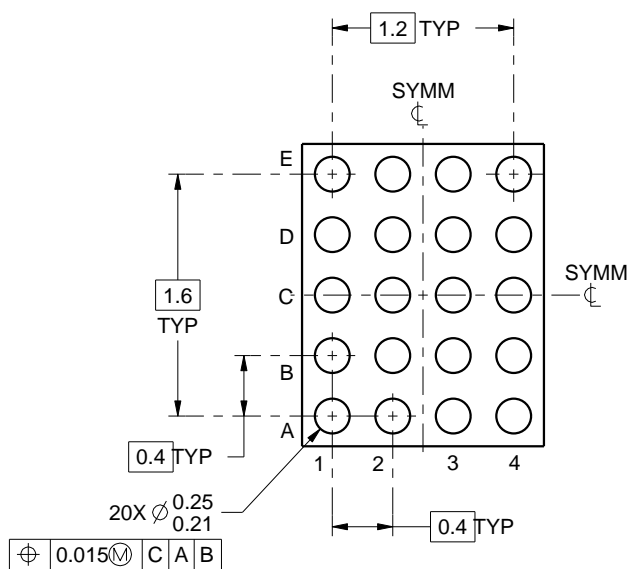
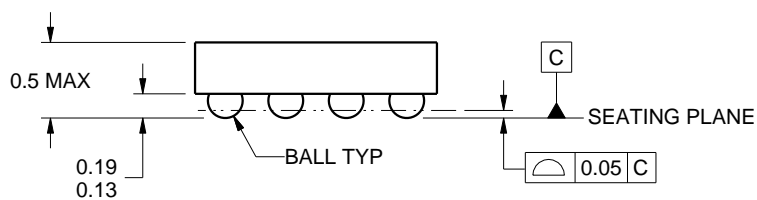
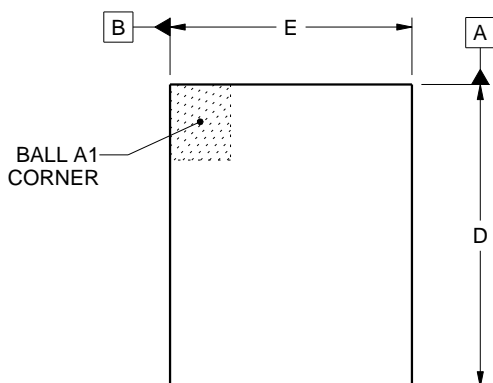
YFP0020



## PACKAGE OUTLINE

DSBGA - 0.5 mm max height

DIE SIZE BALL GRID ARRAY



D: Max = 1.988 mm, Min = 1.928 mm

E: Max = 1.588 mm, Min = 1.527 mm

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## NOTES:

1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.

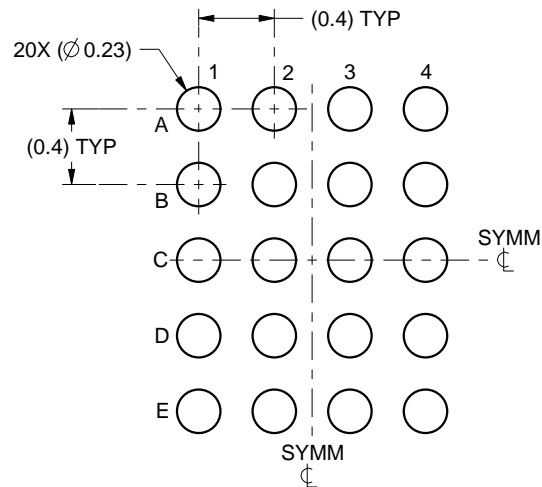


# EXAMPLE BOARD LAYOUT

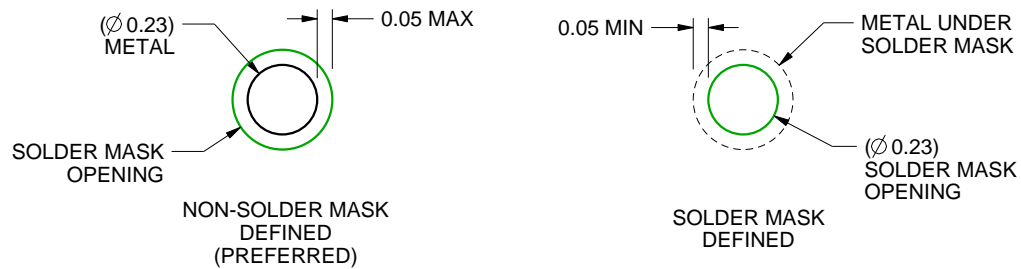
YFP0020

DSBGA - 0.5 mm max height

DIE SIZE BALL GRID ARRAY



LAND PATTERN EXAMPLE  
SCALE:25X



SOLDER MASK DETAILS  
NOT TO SCALE

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NOTES: (continued)

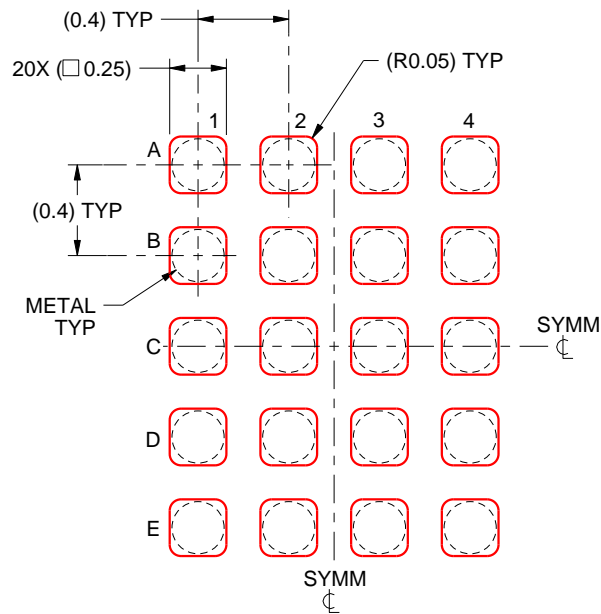
- Final dimensions may vary due to manufacturing tolerance considerations and also routing constraints. For more information, see Texas Instruments literature number SNVA009 ([www.ti.com/lit/snva009](http://www.ti.com/lit/snva009)).

# EXAMPLE STENCIL DESIGN

YFP0020

DSBGA - 0.5 mm max height

DIE SIZE BALL GRID ARRAY



SOLDER PASTE EXAMPLE  
BASED ON 0.1 mm THICK STENCIL  
SCALE:30X

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NOTES: (continued)

4. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release.

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